

# Motor Driver Monolithic IC MM1036

## Outline

This is a motor driver IC developed for video movie use. It has four modes : open, forward, reverse and brake. It can be used with power supply voltages of 4~16V.

## Features

- |   |               |
|---|---------------|
| 1. Operating voltage range                    | 4~16V         |
| 2. Current consumption during standby         | 2 $\mu$ A max |
| 3. Built-in 2.2V stable power supply          |               |
| 4. Can operate on single power supply         |               |
| 5. Control pins D0 and D1 have TTL interface  |               |
| 6. Built-in thermal shutdown                  |               |
| 7. Built-in counter-electromotive clamp diode |               |

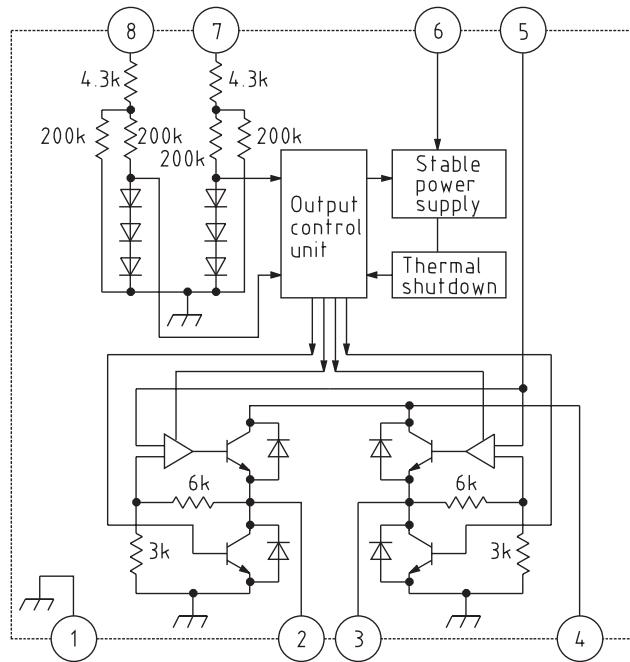
## Package

SOP-8B (MM1036XF)

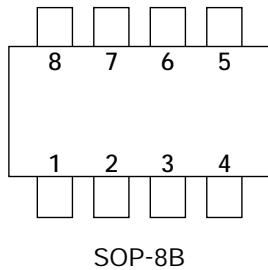
## Applications

Video movies (auto-focus, zoom)

## Equivalent Circuit Diagram



## Pin Description



Pin no.	Pin name	Function
1	GND	GND
2	M0	M0 output pin
3	M1	M1 output pin
4	Vcc	Vcc
5	Vc	Output voltage control
6	V <sub>REF</sub>	Stable power supply
7	D0	D0 control pin
8	D1	D1 control pin

## Mode Settings

D0	D1	Mode	M0	M1
L	L	Open	L	L
H	L	Forward	H	L
L	H	Reverse	L	H
H	H	Brake	L	L

## Absolute Maximum Ratings (Ta=25°C)

Item	Symbol	Ratings	Units	Conditions
Storage temperature	T <sub>STG</sub>	-40~+125	°C	
Operating temperature	T <sub>OPR</sub>	-15~+75	°C	
Power supply voltage	V <sub>CC</sub>	20	V	
Stable power supply	Pd	350 *1	mW	
		470 *2		
Output current	I <sub>O</sub>	100 *3	mA	
D0, D1 applied voltages	V <sub>DIN</sub>	-0.3~+7.0	V	V <sub>DIN</sub> ≤ V <sub>CC</sub> +0.7
Voltage applied to VC	V <sub>CIN</sub>	-0.3~+7.0	V	

Notes :

\*1 Loss tolerance for unit of C

\*2 Loss tolerance when mounted on 20×38×1 [mm] glass epoxy board

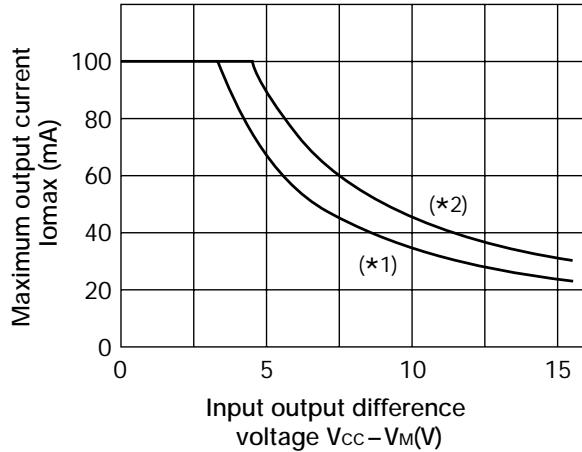
\*3 Within 100ms [Refer to materials]

## Electrical Characteristics

(Except where noted otherwise,  $T_a=25^\circ\text{C}$ ,  $V_{CC}=6.0\text{V}$ ,  $V_M=4.5\text{V}$ )

Item	Symbol	Measurement conditions	Min.	Typ.	Max.	Units
Operating voltage	$V_{CC}$		4.0		16	V
Consumption current 1	$I_{CC1}$	$VD_0, VD_1=0\text{V}, V_{CC}=16\text{V}$			2.0	$\mu\text{A}$
Consumption current 2	$I_{CC2}$	$VD_0, VD_1=2.4\text{V}, V_{CC}=16\text{V}$		9.5	15	mA
Output saturation voltage (L)	$V_{SAT}$	$IM=60\text{mA}$			250	mV
Output voltage (L) Load fluctuation 1	$L_{REG1}(L)$	$IM=10\text{--}60\text{mA}$			200	mV
Output voltage (L) Load fluctuation 2	$L_{REG2}(L)$	$IM=10\text{--}100\text{mA}$			350	mV
$M_0, M_1$ I/O ratio	$K$	$K=V_M/V_C, IM=0\text{mA}$	2.85	3.00	3.15	
Output voltage range	$V_M$	$IM=-60\text{mA}$	2.0		$V_{CC}-1.1$	V
Output voltage (H) Load fluctuation 1	$L_{REG1}(H)$	$IM=0\text{--}65\text{mA}$			100	mV
Output voltage (H) Load fluctuation 2	$L_{REG2}(H)$	$IM=-10\text{--}100\text{mA}$			200	mV
Reference voltage	$V_{REF}$	$I_{REF}=1\text{mA}$	2.10	2.20	2.30	V
$D_0, D_1$ threshold voltages	$V_{TH}$		0.6		2.4	V
$D_0, D_1$ input currents	$I_D$	$VD_0, VD_1=5\text{V}$		40	100	$\mu\text{A}$
Thermal shutdown operating temperature				150		$^\circ\text{C}$
Thermal shutdown hysteresis temperature				50		$^\circ\text{C}$

■ Maximum output current-Input/output difference voltage characteristics ( $25^\circ\text{C}$ )



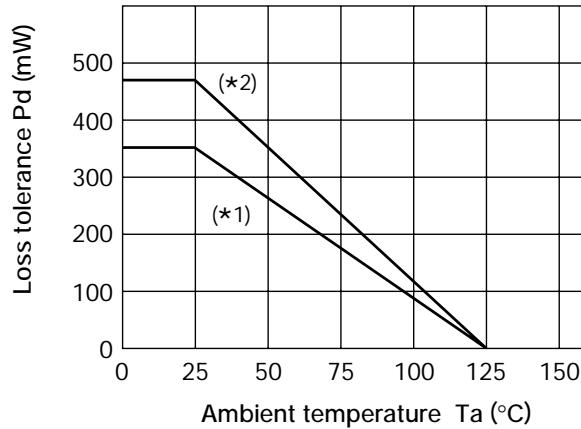
Note : Calculate from  $I_{O \text{ max.}} = P_d / (V_{CC} - V_M + 0.3)$

\*1 Unit : IC

\*2 When mounted on glass epoxy board

20×38×1 [mm]

■ Loss tolerance-Temperature characteristics



\*1 Unit : IC

\*2 When mounted on glass epoxy board

20×38×1 [mm]

## Measuring Circuit

