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LM1577/LM2577 Series SIMPLE SWITCHER Step-Up Voltage Regulator

# National Semiconductor

# LM1577/LM2577 Series SIMPLE SWITCHER<sup>®</sup> Step-Up Voltage Regulator

# **General Description**

The LM1577/LM2577 are monolithic integrated circuits that provide all of the power and control functions for step-up (boost), flyback, and forward converter switching regulators. The device is available in three different output voltage versions: 12V, 15V, and adjustable.

Requiring a minimum number of external components, these regulators are cost effective, and simple to use. Listed in this data sheet are a family of standard inductors and flyback transformers designed to work with these switching regulators.

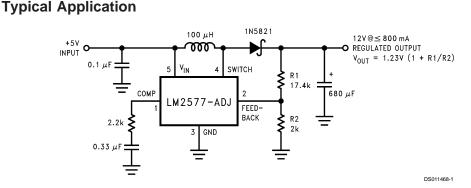
Included on the chip is a 3.0A NPN switch and its associated protection circuitry, consisting of current and thermal limiting, and undervoltage lockout. Other features include a 52 kHz fixed-frequency oscillator that requires no external components, a soft start mode to reduce in-rush current during start-up, and current mode control for improved rejection of input voltage and output load transients.

# Features

- Requires few external components
- NPN output switches 3.0A, can stand off 65V
- Wide input voltage range: 3.5V to 40V
- Current-mode operation for improved transient response, line regulation, and current limit
- 52 kHz internal oscillator
- Soft-start function reduces in-rush current during start-up
- Output switch protected by current limit, under-voltage lockout, and thermal shutdown

# **Typical Applications**

- Simple boost regulator
- Flyback and forward regulators
- Multiple-output regulator



# Note: Pin numbers shown are for TO-220 (T) package

# Ordering Information

Temperature	Package		Output Voltage		NSC	
Range	Туре	12V	15V	ADJ	Package	Package
					Drawing	
$-40^{\circ}C \le T_A \le +125^{\circ}C$	24-Pin Surface Mount	LM2577M-12	LM2577M-15	LM2577M-ADJ	M24B	SO
	16-Pin Molded DIP	LM2577N-12	LM2577N-15	LM2577N-ADJ	N16A	N
	5-Lead Surface Mount	LM2577S-12	LM2577S-15	LM2577S-ADJ	TS5B	TO-263
	5-Straight Leads	LM2577T-12	LM2577T-15	LM2577T-ADJ	T05A	TO-220
	5-Bent Staggered	LM2577T-12	LM2577T-15	LM2577T-ADJ	T05D	TO-220
	Leads	Flow LB03	Flow LB03	Flow LB03		
$-55^{\circ}C \le T_A \le +150^{\circ}C$	4-Pin TO-3	LM1577K-12/883	LM1577K-15/883	LM1577K- ADJ/883	K04A	TO-3

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# Absolute Maximum Ratings (Note 1)

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If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage	45V
Output Switch Voltage	65V
Output Switch Current (Note 2)	6.0A
Power Dissipation	Internally Limited
Storage Temperature Range	-65°C to +150°C
Lead Temperature	
(Soldering, 10 sec.)	260°C
Maximum Junction Temperature	150°C

Minimum ESD Rating

(C = 100 pF, R = 1.5 k $\Omega$ )

# **Operating Ratings**

Supply Voltage	3
Output Switch Voltage	0V ≤
Output Switch Current	
Junction Temperature Range	
LM1577	–55°C
LM2577	-40°C

 $\begin{array}{l} 3.5 \text{V} \leq \text{V}_{\text{IN}} \leq 40 \text{V} \\ \text{V} \leq \text{V}_{\text{SWITCH}} \leq 60 \text{V} \\ \text{I}_{\text{SWITCH}} \leq 3.0 \text{A} \end{array}$ 

2 kV

 $\begin{array}{l} -55^{\circ}C \leq T_{J} \leq +150^{\circ}C \\ -40^{\circ}C \leq T_{J} \leq +125^{\circ}C \end{array}$ 

# Electrical Characteristics—LM1577-12, LM2577-12

Specifications with standard type face are for  $T_J = 25^{\circ}C$ , and those in **bold type face** apply over full **Operating Temperature Range**. Unless otherwise specified,  $V_{IN} = 5V$ , and  $I_{SWITCH} = 0$ .

				LM1577-12	LM2577-12	Units
Symbol	Parameter	Conditions	Typical	Limit	Limit	(Limits)
				(Notes 3, 4)	(Note 5)	
SYSTEM PA	RAMETERS Circuit of Figu	<i>Ire 1</i> (Note 6)				
V <sub>OUT</sub>	Output Voltage	$V_{IN} = 5V$ to 10V	12.0			V
		$I_{LOAD}$ = 100 mA to 800 mA		11.60/ <b>11.40</b>	11.60/ <b>11.40</b>	V(min)
		(Note 3)		12.40/ <b>12.60</b>	12.40/ <b>12.60</b>	V(max)
$\Delta V_{OUT}$	Line Regulation	$V_{IN} = 3.5V$ to 10V	20			mV
$\Delta V_{IN}$		I <sub>LOAD</sub> = 300 mA		50/ <b>100</b>	50/ <b>100</b>	mV(max)
ΔV <sub>OUT</sub>	Load Regulation	V <sub>IN</sub> = 5V	20			mV
$\Delta_{LOAD}$		I <sub>LOAD</sub> = 100 mA to 800 mA		50/ <b>100</b>	50/ <b>100</b>	mV(max)
η	Efficiency	V <sub>IN</sub> = 5V, I <sub>LOAD</sub> = 800 mA	80			%
DEVICE PAR	AMETERS			r		
ls	Input Supply Current	V <sub>FEEDBACK</sub> = 14V (Switch Off)	7.5			mA
				10.0/ <b>14.0</b>	10.0/ <b>14.0</b>	mA(max)
		I <sub>SWITCH</sub> = 2.0A	25			mA
		V <sub>COMP</sub> = 2.0V (Max Duty Cycle)		50/ <b>85</b>	50/ <b>85</b>	mA(max)
V <sub>UV</sub>	Input Supply	I <sub>SWITCH</sub> = 100 mA	2.90			V
Und	Undervoltage Lockout			2.70/ <b>2.65</b>	2.70/ <b>2.65</b>	V(min)
				3.10/ <b>3.15</b>	3.10/ <b>3.15</b>	V(max)
f <sub>o</sub>	Oscillator Frequency	Measured at Switch Pin	52			kHz
		I <sub>SWITCH</sub> = 100 mA		48/ <b>42</b>	48/ <b>42</b>	kHz(min)
				56/ <b>62</b>	56/ <b>62</b>	kHz(max)
V <sub>REF</sub>	Output Reference	Measured at Feedback Pin				V
	Voltage	$V_{IN} = 3.5V$ to 40V	12	11.76/ <b>11.64</b>	11.76/ <b>11.64</b>	V(min)
		$V_{COMP} = 1.0V$		12.24/ <b>12.36</b>	12.24/ <b>12.36</b>	V(max)
$\Delta V_{REF}$	Output Reference	$V_{IN} = 3.5V$ to 40V	7			mV
$\Delta V_{IN}$	Voltage Line Regulator					
R <sub>FB</sub>	Feedback Pin Input		9.7			kΩ
	Resistance					
G <sub>M</sub>	Error Amp	I <sub>COMP</sub> = -30 μA to +30 μA	370			µmho
	Transconductance	$V_{COMP} = 1.0V$		225/ <b>145</b>	225/ <b>145</b>	µmho(min
				515/ <b>615</b>	515/ <b>615</b>	µmho(max
A <sub>VOL</sub>	Error Amp	$V_{COMP}$ = 1.1V to 1.9V	80			V/V
	Voltage Gain	$R_{COMP} = 1.0 M\Omega$		50/ <b>25</b>	50/ <b>25</b>	V/V(min)
		(Note 7)				

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				LM1577-12	LM2577-12	Units
Symbol	Parameter	Conditions	Typical	Limit	Limit	(Limits)
				(Notes 3, 4)	(Note 5)	
DEVICE PAR	AMETERS					
	Error Amplifier	Upper Limit	2.4			V
	Output Swing	V <sub>FEEDBACK</sub> = 10.0V		2.2/ <b>2.0</b>	2.2/ <b>2.0</b>	V(min)
		Lower Limit	0.3			V
		V <sub>FEEDBACK</sub> = 15.0V		0.40/ <b>0.55</b>	0.40/ <b>0.55</b>	V(max)
	Error Amplifier	$V_{\text{FEEDBACK}}$ = 10.0V to 15.0V	±200			μΑ
	Output Current	$V_{COMP} = 1.0V$		±130/ <b>±90</b>	±130/ <b>±90</b>	µA(min)
				±300/ <b>±400</b>	±300/ <b>±400</b>	µA(max)
I <sub>SS</sub>	Soft Start Current	V <sub>FEEDBACK</sub> = 10.0V	5.0			μA
		$V_{COMP} = 0V$		2.5/ <b>1.5</b>	2.5/ <b>1.5</b>	µA(min)
				7.5/ <b>9.5</b>	7.5/ <b>9.5</b>	µA(max)
D	Maximum Duty Cycle	$V_{COMP} = 1.5V$	95			%
		I <sub>SWITCH</sub> = 100 mA		93/ <b>90</b>	93/ <b>90</b>	%(min)
$\frac{\Delta I_{SWITCH}}{\Delta V_{COMP}}$	Switch Transconductance		12.5			A/V
l,	Switch Leakage	V <sub>SWITCH</sub> = 65V	10			μA
	Current	V <sub>FEEDBACK</sub> = 15V (Switch Off)		300/ <b>600</b>	300/600	µA(max)
V <sub>SAT</sub>	Switch Saturation	I <sub>SWITCH</sub> = 2.0A	0.5			V
	Voltage	V <sub>COMP</sub> = 2.0V (Max Duty Cycle)		0.7/ <b>0.9</b>	0.7/ <b>0.9</b>	V(max)
	NPN Switch		4.5			А
	Current Limit			3.7/ <b>3.0</b>	3.7/ <b>3.0</b>	A(min)
				5.3/ <b>6.0</b>	5.3/ <b>6.0</b>	A(max)

**Electrical Characteristics**— LM1577-15, LM2577-15 Specifications with standard type face are for  $T_J = 25$ °C, and those in **bold type face** apply over full **Operating Temperature** Range. Unless otherwise specified,  $V_{IN} = 5V$ , and  $I_{SWITCH} = 0$ .

				LM1577-15	LM2577-15	Units
Symbol	Parameter	Conditions	Typical	Limit	Limit	(Limits)
				(Notes 3, 4)	(Note 5)	
SYSTEM PAR	AMETERS Circuit of Figure	e 2 (Note 6)				
V <sub>OUT</sub>	Output Voltage	$V_{IN} = 5V$ to 12V	15.0			V
		$I_{LOAD}$ = 100 mA to 600 mA		14.50/ <b>14.25</b>	14.50/ <b>14.25</b>	V(min)
		(Note 3)		15.50/ <b>15.75</b>	15.50/ <b>15.75</b>	V(max)
ΔV <sub>OUT</sub>	Line Regulation	V <sub>IN</sub> = 3.5V to 12V	20	50/400	50/400	mV
$\Delta V_{IN}$		$I_{LOAD} = 300 \text{ mA}$		50/ <b>100</b>	50/ <b>100</b>	mV(max)
ΔV <sub>OUT</sub>	Load Regulation	V <sub>IN</sub> = 5V	20			mV
$\Delta_{LOAD}$		$I_{LOAD}$ = 100 mA to 600 mA		50/ <b>100</b> 50/ <b>100</b>		mV(max)
η	Efficiency	V <sub>IN</sub> = 5V, I <sub>LOAD</sub> = 600 mA	80			%
DEVICE PAR	AMETERS		·			
ls	Input Supply Current	V <sub>FEEDBACK</sub> = 18.0V	7.5			mA
		(Switch Off)		10.0/ <b>14.0</b>	10.0/ <b>14.0</b>	mA(max)
		I <sub>SWITCH</sub> = 2.0A	25			mA
		$V_{COMP} = 2.0V$		50/ <b>85</b>	50/ <b>85</b>	mA(max)
		(Max Duty Cycle)				
V <sub>UV</sub>	Input Supply	I <sub>SWITCH</sub> = 100 mA	2.90			V

Symbol	Parameter	Conditions	Typical	LM1577-15 Limit (Notes 3, 4)	LM2577-15 Limit (Note 5)	Units (Limits)
DEVICE PARA	METERS			(110185 3, 4)	(NOLE 3)	
	Undervoltage			2.70/ <b>2.65</b>	2.70/ <b>2.65</b>	V(min)
	Lockout			3.10/ <b>3.15</b>	3.10/ <b>3.15</b>	V(max)
fo	Oscillator Frequency	Measured at Switch Pin	52			kHz
0		I <sub>SWITCH</sub> = 100 mA		48/ <b>42</b>	48/ <b>42</b>	kHz(min)
				56/ <b>62</b>	56/ <b>62</b>	kHz(max)
V <sub>REF</sub>	Output Reference	Measured at Feedback Pin				V
	Voltage	$V_{IN} = 3.5V$ to 40V	15	14.70/ <b>14.55</b>	14.70/ <b>14.55</b>	V(min)
		$V_{COMP} = 1.0V$		15.30/ <b>15.45</b>	15.30/ <b>15.45</b>	V(max)
$\Delta V_{REF}$	Output Reference	V <sub>IN</sub> = 3.5V to 40V	10			mV
ΔVIN	Voltage Line Regulation					
R <sub>FB</sub>	Feedback Pin Input		12.2			kΩ
· ·FB	Voltage Line Regulator					
G <sub>M</sub>	Error Amp	$I_{COMP} = -30 \ \mu A \text{ to } +30 \ \mu A$	300			µmho
СM	Transconductance	$V_{\text{COMP}} = 1.0V$		170/ <b>110</b>	170/ <b>110</b>	µmho(min)
				420/500	420/500	µmho(max)
A <sub>VOL</sub>	Error Amp	V <sub>COMP</sub> = 1.1V to 1.9V	65			V/V
VOL	Voltage Gain	$R_{COMP} = 1.0 M\Omega$		40/ <b>20</b>	40/ <b>20</b>	V/V(min)
		(Note 7)				., . ()
	Error Amplifier	Upper Limit	2.4			V
	Output Swing	V <sub>FEEDBACK</sub> = 12.0V		2.2/ <b>2.0</b>	2.2/ <b>2.0</b>	V(min)
		Lower Limit	0.3			V
		V <sub>FEEDBACK</sub> = 18.0V		0.4/ <b>0.55</b>	0.40/ <b>0.55</b>	V(max)
	Error Amp	V <sub>FEEDBACK</sub> = 12.0V to 18.0V	±200			μA
	Output Current	$V_{COMP} = 1.0V$		±130/ <b>±90</b>	±130/ <b>±90</b>	µA(min)
				±300/ <b>±400</b>	±300/ <b>±400</b>	µA(max)
I <sub>ss</sub>	Soft Start Current	V <sub>FEEDBACK</sub> = 12.0V	5.0			μA
		$V_{COMP} = 0V$		2.5/ <b>1.5</b>	2.5/ <b>1.5</b>	µA(min)
				7.5/ <b>9.5</b>	7.5/ <b>9.5</b>	µA(max)
D	Maximum Duty	$V_{COMP} = 1.5V$	95			%
	Cycle	I <sub>SWITCH</sub> = 100 mA		93/ <b>90</b>	93/ <b>90</b>	%(min)
$\frac{\Delta I_{SWITCH}}{\Delta V_{COMP}}$	Switch Transconductance		12.5			A/V
I <sub>L</sub>	Switch Leakage	V <sub>SWITCH</sub> = 65V	10			μA
L	Current	V <sub>FEEDBACK</sub> = 18.0V		300/ <b>600</b>	300/600	μA(max)
		(Switch Off)				F ( )
V <sub>SAT</sub>	Switch Saturation	I <sub>SWITCH</sub> = 2.0A	0.5			V
	Voltage	$V_{COMP} = 2.0V$		0.7/ <b>0.9</b>	0.7/ <b>0.9</b>	V(max)
		(Max Duty Cycle)				. /
	NPN Switch	$V_{COMP} = 2.0V$	4.3			А
	Current Limit			3.7/ <b>3.0</b>	3.7/ <b>3.0</b>	A(min)
				5.3/ <b>6.0</b>	5.3/ <b>6.0</b>	A(max)

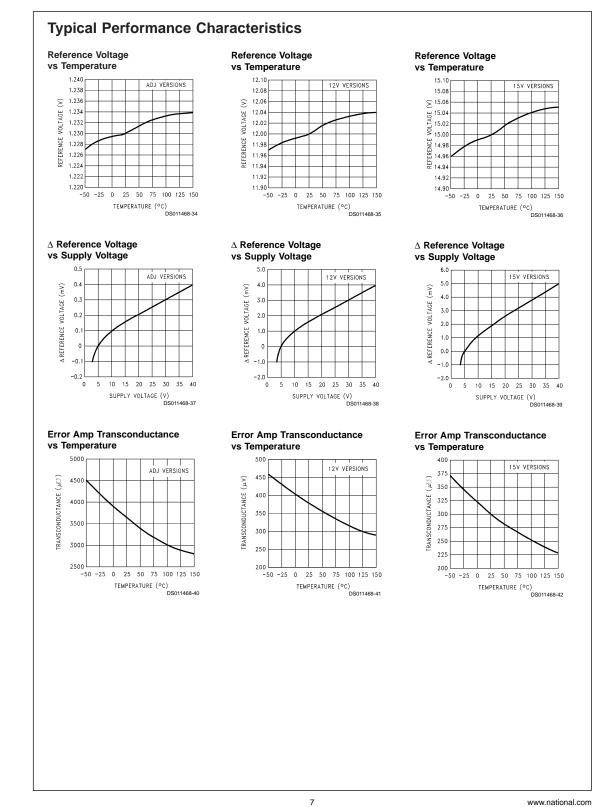
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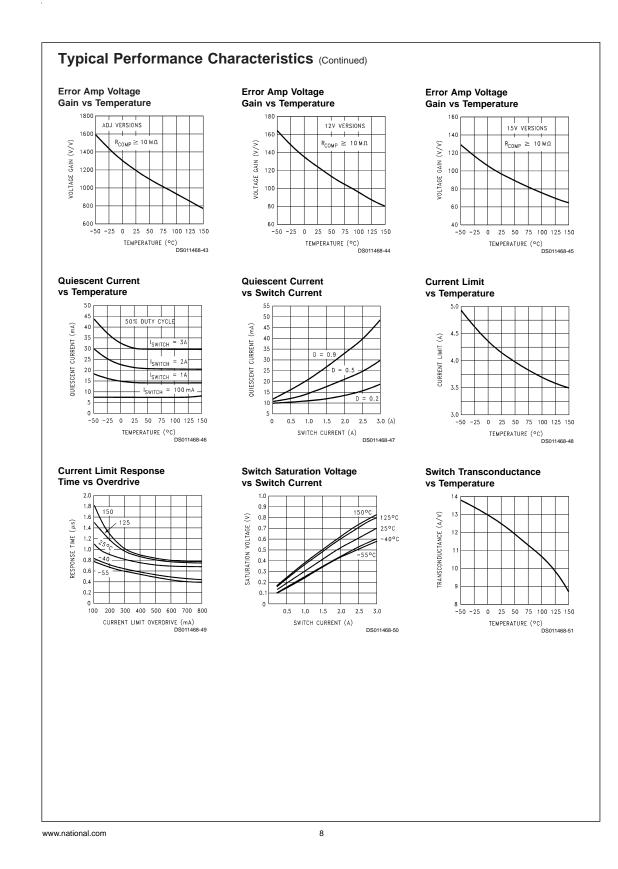
		e are for T <sub>J</sub> = 25°C, and those in <b>bo</b> $V_{IN} = 5V$ , $V_{FEEDBACK} = V_{REF}$ , and $I_{S}$		LM1577-ADJ	LM2577-ADJ	Units
Symbol	Parameter	Conditions	Typical	Limit	Limit	(Limits)
Symbol	Falanielei	Conditions	Typical	(Notes 3, 4)	(Note 5)	(Linnes)
SYSTEM P	ARAMETERS Circuit of <i>Fi</i>	aure 3 (Note 6)		(10103-0, 4)	(1010-0)	
/ <sub>OUT</sub>	Output Voltage	$V_{IN} = 5V \text{ to } 10V$	12.0			V
OUT	Oulput Voltage	$I_{1,OAD} = 100 \text{ mA to } 800 \text{ mA}$	12.0	11.60/ <b>11.40</b>	11.60/ <b>11.40</b>	V(min)
		(Note 3)		12.40/ <b>12.60</b>	12.40/ <b>12.60</b>	V(max)
ΔV <sub>OUT</sub> /	Line Regulation	$V_{IN} = 3.5V \text{ to } 10V$	20	12.40/12.00	12.40/12.00	mV
ΔV <sub>IN</sub>	Line Regulation	$I_{I,OAD} = 300 \text{ mA}$	20	50/ <b>100</b>	50/ <b>100</b>	mV(max)
$\Delta V_{OUT}$	Load Regulation	$V_{IN} = 5V$	20	00/100	30/100	mV
ΔI <sub>LOAD</sub>	Loud Rogulation	$I_{LOAD} = 100 \text{ mA to } 800 \text{ mA}$	20	50/ <b>100</b>	50/ <b>100</b>	mV(max)
<u>η</u>	Efficiency	$V_{IN} = 5V, I_{LOAD} = 800 \text{ mA}$	80	00,100	00/100	%
	RAMETERS		00			70
-	Input Supply Current	$V_{\text{FEEDBACK}} = 1.5V$ (Switch Off)	7.5			mA
I <sub>S</sub> Input Su		FEEDBACK 1.00 (Ownon On)	1.0	10.0/ <b>14.0</b>	10.0/ <b>14.0</b>	mA(max)
		I <sub>SWITCH</sub> = 2.0A	25	10.0/14.0	10.0/14.0	mA
		$V_{COMP} = 2.0V$ (Max Duty Cycle)	20	50/ <b>85</b>	50/ <b>85</b>	mA(max)
V <sub>UV</sub>	Input Supply	$I_{SWITCH} = 100 \text{ mA}$	2.90	00/00	30/00	V
• 00	Undervoltage Lockout	ISWITCH TOO TIME	2.00	2.70/ <b>2.65</b>	2.70/ <b>2.65</b>	V(min)
	Chaorvonago Econoar			3.10/ <b>3.15</b>	3.10/ <b>3.15</b>	V(max)
0	Oscillator Frequency	Measured at Switch Pin	52	0.10/0.10	0.10/0.10	kHz
	Coolinator r roquonoy	$I_{SWITCH} = 100 \text{ mA}$	02	48/ <b>42</b>	48/ <b>42</b>	kHz(min)
		ISWITCH TOO TIME		56/62	56/ <b>62</b>	kHz(max)
V <sub>RFF</sub>	Reference	Measured at Feedback Pin		00,02	00,02	V
* REF	Voltage	$V_{IN} = 3.5V$ to 40V	1.230	1.214/ <b>1.206</b>	1.214/ <b>1.206</b>	V(min)
	Voltago	$V_{COMP} = 1.0V$	1.200	1.246/ <b>1.254</b>	1.246/ <b>1.254</b>	V(max)
ΔV <sub>REE</sub> /	Reference Voltage	$V_{IN} = 3.5V \text{ to } 40V$	0.5			mV
ΔV <sub>IN</sub>	Line Regulation					
I <sub>B</sub>	Error Amp	$V_{COMP} = 1.0V$	100			nA
5	Input Bias Current			300/ <b>800</b>	300/ <b>800</b>	nA(max)
G <sub>M</sub>	Error Amp	$I_{COMP} = -30 \ \mu A \text{ to } +30 \ \mu A$	3700			µmho
	Transconductance	$V_{\text{COMP}} = 1.0V$		2400/ <b>1600</b>	2400/ <b>1600</b>	µmho(min
				4800/ <b>5800</b>	4800/ <b>5800</b>	µmho(ma)
A <sub>VOL</sub>	Error Amp	V <sub>COMP</sub> = 1.1V to 1.9V	800			V/V
	Voltage Gain	$R_{COMP} = 1.0 M\Omega$ (Note 7)		500/ <b>250</b>	500/ <b>250</b>	V/V(min)
	Error Amplifier	Upper Limit	2.4			V
	Output Swing	V <sub>FEEDBACK</sub> = 1.0V		2.2/ <b>2.0</b>	2.2/ <b>2.0</b>	V(min)
		Lower Limit	0.3			V
		V <sub>FEEDBACK</sub> = 1.5V		0.40/ <b>0.55</b>	0.40/ <b>0.55</b>	V(max)
	Error Amp	V <sub>FEEDBACK</sub> = 1.0V to 1.5V	±200			μA
	Output Current	$V_{COMP} = 1.0V$		±130/ <b>±90</b>	±130/ <b>±90</b>	μA(min)
				±300/ <b>±400</b>	±300/ <b>±400</b>	µA(max)
SS	Soft Start Current	V <sub>FEEDBACK</sub> = 1.0V	5.0			μA
		$V_{COMP} = 0V$		2.5/ <b>1.5</b>	2.5/ <b>1.5</b>	μA(min)
				7.5/ <b>9.5</b>	7.5/ <b>9.5</b>	µA(max)
D	Maximum Duty Cycle	V <sub>COMP</sub> = 1.5V	95			%
		I <sub>SWITCH</sub> = 100 mA		93/ <b>90</b>	93/ <b>90</b>	%(min)
∆l <sub>switch</sub> /	Switch		12.5			A/V
V <sub>COMP</sub>	Transconductance					

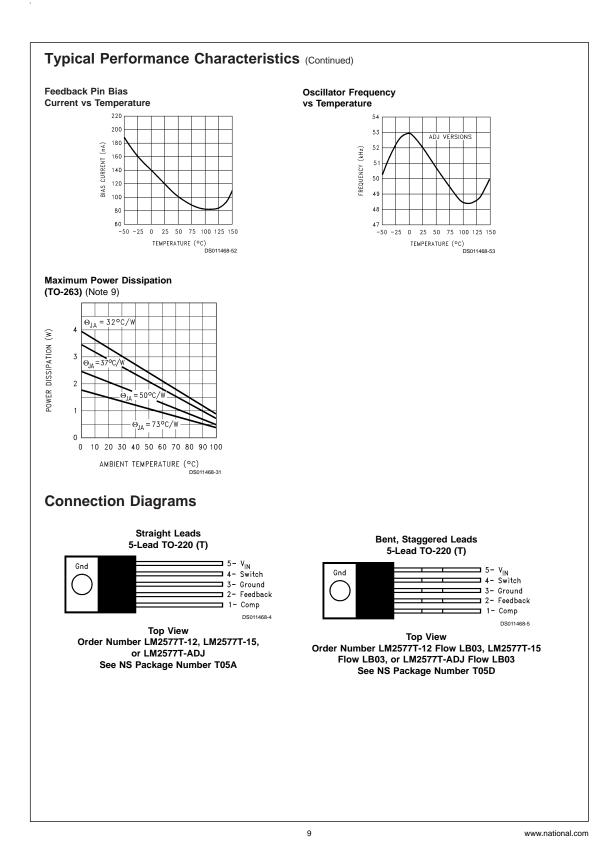
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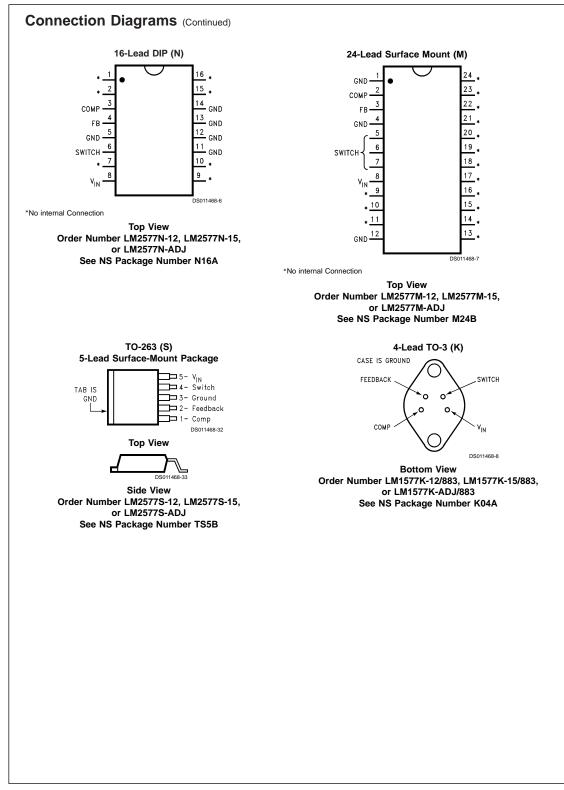
Curr V <sub>SAT</sub> Swit Volta NPN Curr THERMAL PARA	rch Leakage rent rch Saturation	K Package, Junction to Ambient	10 0.5 4.3	300/ <b>600</b> 0.7/ <b>0.9</b> 3.7/ <b>3.0</b>	300/ <b>600</b> 0.7/ <b>0.9</b>	μA(m V
Curr           V <sub>SAT</sub> Swit           Volt         NPN           Curr         Curr           THERMAL PARA         Para           θ <sub>JA</sub> The           θ <sub>JA</sub> θ <sub>JC</sub>	rent ch Saturation age J Switch rent Limit METERS (All Vers	$V_{\text{FEEDBACK}} = 1.5V \text{ (Switch Off)}$ $I_{\text{SWITCH}} = 2.0A$ $V_{\text{COMP}} = 2.0V \text{ (Max Duty Cycle)}$ $V_{\text{COMP}} = 2.0V$ ions) K Package, Junction to Ambient	0.5	0.7/ <b>0.9</b>	0.7/ <b>0.9</b>	V V(ma
V <sub>SAT</sub> Switt Volt:           NPN Curr           THERMAL PARAL           θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JA</sub>	ch Saturation age I Switch rent Limit METERS (All Vers	$I_{SWITCH} = 2.0A$ $V_{COMP} = 2.0V (Max Duty Cycle)$ $V_{COMP} = 2.0V$ ions) K Package, Junction to Ambient		0.7/ <b>0.9</b>	0.7/ <b>0.9</b>	V(ma
Volt           NPN           Curr           THERMAL PARA           θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JC</sub>	age I Switch rent Limit METERS (All Vers	V <sub>COMP</sub> = 2.0V (Max Duty Cycle) V <sub>COMP</sub> = 2.0V				V(ma
NPN           Curr           THERMAL PARA           θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JA</sub> θ <sub>JC</sub>	J Switch rent Limit METERS (All Vers	V <sub>COMP</sub> = 2.0V ions) K Package, Junction to Ambient	4.3			V(ma A
$\begin{array}{c} & Curr \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \\ \hline \\ \\ \\ \\ \\ \\$	rent Limit METERS (All Vers	ions) K Package, Junction to Ambient	4.3	3.7/ <b>3.0</b>	0.7/0.0	А
$\begin{array}{c c} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \\ \hline \\ \\ \\ \\ \\ \\ \\ $	METERS (All Vers	K Package, Junction to Ambient		3.7/ <b>3.0</b>	0 7/0 0	
$ \begin{array}{c} \theta_{JA} & \\ \theta_{JC} & \\ \theta_{JA} & \\ \theta_{JC} & \\ \end{array}                                 $		K Package, Junction to Ambient			3.7/ <b>3.0</b>	A(mii
$ \begin{array}{c} \theta_{JA} & \\ \theta_{JC} & \\ \theta_{JA} & \\ \theta_{JC} & \\ \end{array}                                 $		K Package, Junction to Ambient		5.3/ <b>6.0</b>	5.3/ <b>6.0</b>	A(ma
θ <sub>JC</sub> θ <sub>JA</sub> θ <sub>JC</sub>	rmal Resistance		<del></del>		,	
θ <sub>JA</sub> θ <sub>JC</sub>			35			
θ <sub>JC</sub>		K Package, Junction to Case	1.5		ļ	
-		T Package, Junction to Ambient	65			
θ <sub>JA</sub>		T Package, Junction to Case	2	<b></b>	<u> </u>	
		N Package, Junction to	85			°C/V
-		Ambient (Note 8)	<u> </u>			
θ <sub>JA</sub>		M Package, Junction	100			
		to Ambient (Note 8)				
θ <sub>JA</sub>		S Package, Junction to Ambient (Note 9)	37			
RETS specifications of to Standard Military I Note 5: All limits gua tion tested. All limits a Note 6: External com as shown in the Test	complied fully with the bo Drawing specifications. Irranteed at room temper at temperature extremes apponents such as the dio Circuit, system perform	ication is available on request. At the time of prin oldface limits in these columns. The LM1577K-12 ature (standard type face) and at temperature ex s are guaranteed via correlation using standard t ide, inductor, input and output capacitors can affer ance will be as specified by the system paramet a compensation pin (which is the error amplifier's	/883, LM1577K ktremes (boldfa Statistical Qual ct switching reg ters.	C-15/883, and LM157 ice type). All room te ity Control (SQC) m gulator performance.	77K-ADJ/883 may als mperature limits are ethods. When the LM1577/LI	so be procu 100% prod M2577 is us
this pin's load resista Note 8: Junction to a	nce should be ≥10 MΩ, Imbient thermal resistan	resulting in A <sub>VOL</sub> that is typically twice the guara ce with approximately 1 square inch of pc board o itchers Made Simple" software.	anteed minimu	m limit.		
Note 9: If the TO-26	3 package is used, the t	hermal resistance can be reduced by increasing W; with 1 square inch of copper area, $\theta_{JA}$ is 37°C				

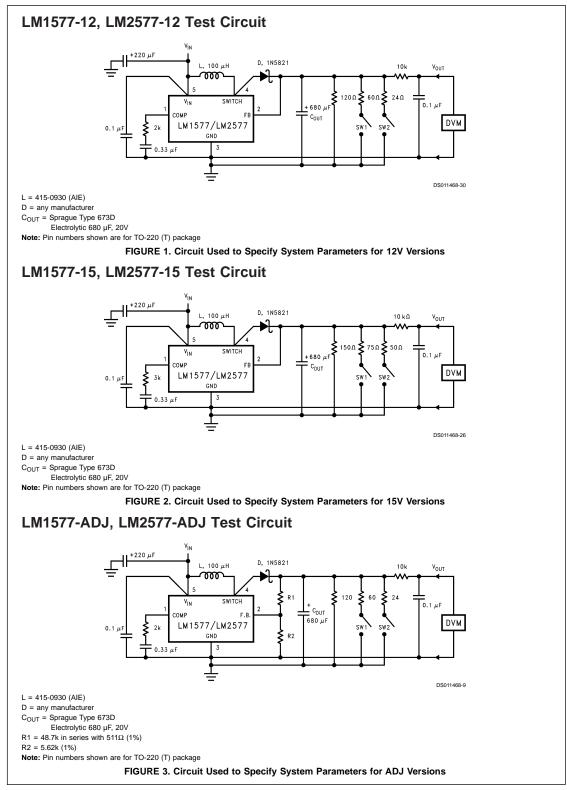
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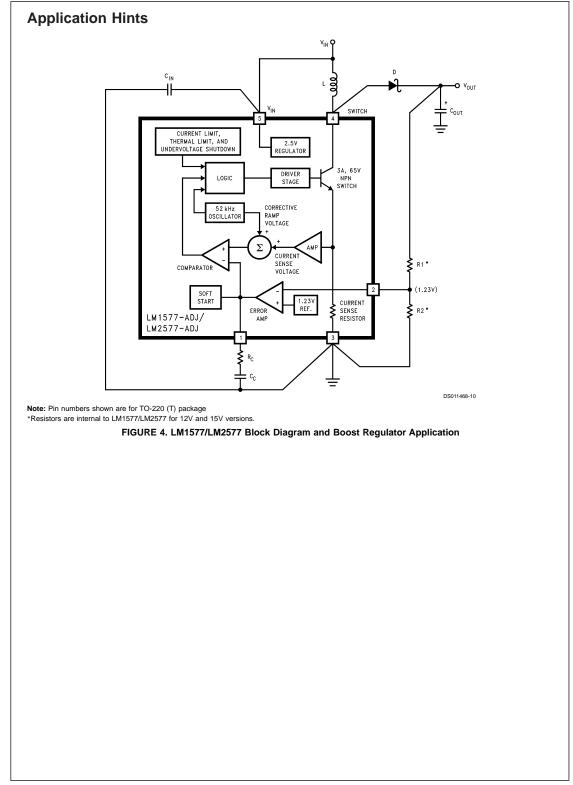












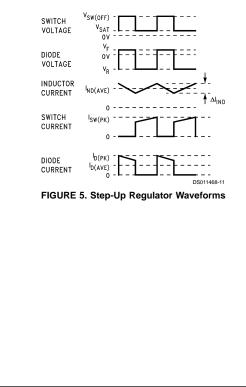
#### STEP-UP (BOOST) REGULATOR

*Figure 4* shows the LM1577-ADJ/LM2577-ADJ used as a Step-Up Regulator. This is a switching regulator used for producing an output voltage greater than the input supply voltage. The LM1577-12/LM2577-12 and LM1577-15/LM2577-15 can also be used for step-up regulators with 12V or 15V outputs (respectively), by tying the feedback pin directly to the regulator output.

A basic explanation of how it works is as follows. The LM1577/LM2577 turns its output switch on and off at a frequency of 52 kHz, and this creates energy in the inductor (L). When the NPN switch turns on, the inductor current charges up at a rate of V<sub>IN</sub>/L, storing current in the inductor. When the switch turns off, the lower end of the inductor flies above VIN, discharging its current through diode (D) into the output capacitor (C<sub>OUT</sub>) at a rate of (V<sub>OUT</sub> - V<sub>IN</sub>)/L. Thus, energy stored in the inductor during the switch on time is transferred to the output during the switch off time. The output voltage is controlled by the amount of energy transferred which, in turn, is controlled by modulating the peak inductor current. This is done by feeding back a portion of the output voltage to the error amp, which amplifies the difference between the feedback voltage and a 1.230V reference. The error amp output voltage is compared to a voltage proportional to the switch current (i.e., inductor current during the switch on time).

The comparator terminates the switch on time when the two voltages are equal, thereby controlling the peak switch current to maintain a constant output voltage.

Voltage and current waveforms for this circuit are shown in *Figure 5*, and formulas for calculating them are given in *Figure 6*.



Duty Cycle	D	$\frac{V_{\text{OUT}} + V_{\text{F}} - V_{\text{IN}}}{V_{\text{OUT}} + V_{\text{F}} - V_{\text{SAT}}} \approx \frac{V_{\text{OUT}} - V_{\text{IN}}}{V_{\text{OUT}}}$
Average Inductor Current	I <sub>IND(AVE)</sub>	l <sub>LOAD</sub> 1 — D
Inductor Current Ripple	$\Delta I_{IND}$	<u>VIN - V<sub>SAT</sub> D</u> L 52,000
Peak Inductor Current	I <sub>IND(PK)</sub>	$\frac{I_{LOAD(max)}}{1 - D_{(max)}} + \frac{\Delta I_{IND}}{2}$
Peak Switch Current	I <sub>SW(PK)</sub>	$\frac{I_{LOAD(max)}}{1 - D_{(max)}} + \frac{\Delta I_{IND}}{2}$
Switch Voltage When Off	V <sub>SW(OFF)</sub>	V <sub>OUT</sub> + V <sub>F</sub>
Diode Reverse Voltage	V <sub>R</sub>	V <sub>OUT</sub> – V <sub>SAT</sub>
Average Diode Current	I <sub>D(AVE)</sub>	I <sub>LOAD</sub>
Peak Diode Current	I <sub>D(PK)</sub>	$\frac{I_{LOAD}}{1-D_{(max)}} + \frac{\Delta I_{IND}}{2}$
Power Dissipation of LM1577/2577	P <sub>D</sub>	$0.25\Omega \left(\frac{I_{LOAD}}{1-D}\right)^2 D + \frac{I_{LOAD} D V_{IN}}{50 (1-D)}$

V<sub>F</sub> = Forward Biased Diode Voltage

ILOAD = Output Load Current

FIGURE 6. Step-Up Regulator Formulas

#### STEP-UP REGULATOR DESIGN PROCEDURE

The following design procedure can be used to select the appropriate external components for the circuit in *Figure 4*, based on these system requirements.

## Given:

 $V_{IN (min)}$  = Minimum input supply voltage

 $V_{OUT}$  = Regulated output voltage

I<sub>LOAD(max)</sub> = Maximum output load current

Before proceeding any further, determine if the LM1577/ LM2577 can provide these values of V<sub>OUT</sub> and I<sub>LOAD(max)</sub> when operating with the minimum value of V<sub>IN</sub>. The upper limits for V<sub>OUT</sub> and I<sub>LOAD(max)</sub> are given by the following equations.

 $V_{OUT} \le 60V$ 

and 
$$V_{OUT} \le 10 \text{ x } V_{IN(min)}$$

$$I_{LOAD(max)} \le \frac{2.1A \times V_{IN(min)}}{V_{OUT}}$$

These limits must be greater than or equal to the values specified in this application.

- 1. Inductor Selection (L) A. Voltage Options:
  - 1. For 12V or 15V output

1. For 12V or 15V output

From Figure 7 (for 12V output) or Figure 8 (for 15V output), identify inductor code for region indicated by  $V_{\rm IN~(min)}$  and I<sub>LOAD (max)</sub>. The shaded region indicates conditions for which the LM1577/LM2577 output switch would be operating beyond its switch current rating. The minimum operating voltage for the LM1577/LM2577 is 3.5V.

From here, proceed to step C.

#### 2. For Adjustable version

#### Preliminary calculations:

The inductor selection is based on the calculation of the following three parameters:

 $D_{(max)},$  the maximum switch duty cycle (0  $\leq$  D  $\leq$  0.9):

$$D_{(max)} = \frac{V_{OUT} + V_F - V_{IN(min)}}{V_{OUT} + V_F - 0.6V}$$

where  $V_{\text{F}}$  = 0.5V for Schottky diodes and 0.8V for fast recovery diodes (typically);

 $E \bullet T$ , the product of volts x time that charges the inductor:

$$\mathsf{E} \bullet \mathsf{T} = \frac{\mathsf{D}_{(\text{max})} \, (\mathsf{V}_{\text{IN}(\text{min})} - 0.6\mathsf{V}) 10^6}{52,000 \, \text{Hz}} \qquad (\mathsf{V} \bullet \mu s)$$

I<sub>IND,DC</sub>, the average inductor current under full load;

$$I_{\text{IND,DC}} = \frac{1.05 \times I_{\text{LOAD(max)}}}{1 - D_{\text{(max)}}}$$

B. Identify Inductor Value:

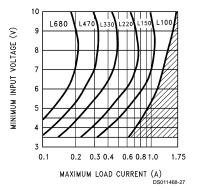
1. From *Figure 9*, identify the inductor code for the region indicated by the intersection of E•T and I<sub>IND,DC</sub>. This code gives the inductor value in microhenries. The L or H prefix signifies whether the inductor is rated for a maximum E•T of 90 V•µs (L) or 250 V•µs (H).

2. If D < 0.85, go on to step C. If D  $\ge$  0.85, then calculate the minimum inductance needed to ensure the switching regulator's stability:

$$L_{\text{MIN}} = \frac{6.4 \left( V_{\text{IN}(\text{min})} - 0.6V \right) \left( 2D_{(\text{max})} - 1 \right)}{1 - D_{(\text{max})}} \qquad (\mu \text{H})$$

If  $L_{\rm MIN}$  is smaller than the inductor value found in step B1, go on to step C. Otherwise, the inductor value found in step B1 is too low; an appropriate inductor code should be obtained from the graph as follows:

1. Find the lowest value inductor that is greater than  $L_{MIN}$ . 2. Find where E•T intersects this inductor value to determine if it has an L or H prefix. If E•T intersects both the L and H regions, select the inductor with an H prefix.





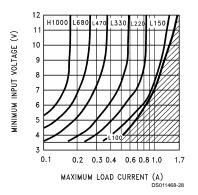
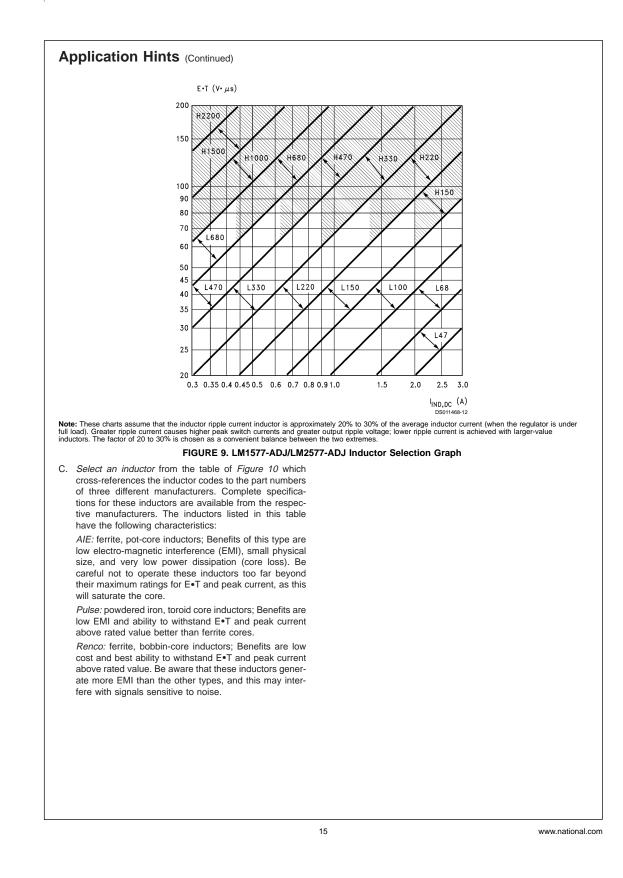


FIGURE 8. LM2577-15 Inductor Selection Guide



.

Inductor	Manufa	cturer's Part Nu	Imber
Code	Schott	Pulse	Renco
L47	67126980	PE - 53112	RL2442
L68	67126990	PE - 92114	RL2443
L100	67127000	PE - 92108	RL2444
L150	67127010	PE - 53113	RL1954
L220	67127020	PE - 52626	RL1953
L330	67127030	PE - 52627	RL1952
L470	67127040	PE - 53114	RL1951
L680	67127050	PE - 52629	RL1950
H150	67127060	PE - 53115	RL2445
H220	67127070	PE - 53116	RL2446
H330	67127080	PE - 53117	RL2447
H470	67127090	PE - 53118	RL1961
H680	67127100	PE - 53119	RL1960
H1000	67127110	PE - 53120	RL1959
H1500	67127120	PE - 53121	RL1958
H2200	67127130	PE - 53122	RL2448

Schott Corp., (612) 475-1173

1000 Parkers Lake Rd., Wayzata, MN 55391 **Pulse Engineering**, (619) 268-2400 P.O. Box 12235, San Diego, CA 92112

Renco Electronics Inc., (516) 586-5566 60 Jeffryn Blvd. East, Deer Park, NY 11729

#### FIGURE 10. Table of Standardized Inductors and Manufacturer's Part Numbers

#### 2. Compensation Network (R<sub>c</sub>, C<sub>c</sub>) and Output Capacitor (C<sub>OUT</sub>) Selection

R<sub>C</sub> and C<sub>C</sub> form a pole-zero compensation network that stabilizes the regulator. The values of R<sub>C</sub> and C<sub>C</sub> are mainly dependant on the regulator voltage gain,  $I_{LOAD(max)}$ , L and C<sub>OUT</sub>. The following procedure calculates values for R<sub>C</sub>, C<sub>C</sub>, and  $C_{\mbox{\scriptsize OUT}}$  that ensure regulator stability. Be aware that this procedure doesn't necessarily result in R<sub>c</sub> and C<sub>c</sub> that provide optimum compensation. In order to guarantee optimum compensation, one of the standard procedures for testing loop stability must be used, such as measuring  $V_{\mbox{\scriptsize OUT}}$  transient response when pulsing ILOAD (see Figure 15).

A. First, calculate the maximum value for R<sub>C</sub>.

$$R_C \leq \frac{750 \times I_{LOAD(max)} \times V_{OUT}^2}{V_{IN(min)}^2}$$

Select a resistor less than or equal to this value, and it should also be no greater than 3 k $\Omega$ .

B. Calculate the minimum value for COUT using the following two equations.

$$C_{OUT} \geq \frac{0.19 \times L \times R_{C} \times I_{LOAD(max)}}{V_{IN(min)} \times V_{OUT}}$$

and

$$C_{\text{OUT}} \geq \frac{V_{\text{IN(min)}} \times \text{R}_{\text{C}} \times (V_{\text{IN(min)}} + (3.74 \times 10^{5} \times \text{L}))}{487,800 \times V_{\text{OUT}}^{3}}$$

The larger of these two values is the minimum value that ensures stability.

C. Calculate the minimum value of  $C_C$ .

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The compensation capacitor is also part of the soft start circuitry. When power to the regulator is turned on, the switch duty cycle is allowed to rise at a rate controlled by this capacitor (with no control on the duty cycle, it would immediately rise to 90%, drawing huge currents from the input power supply). In order to operate properly, the soft start circuit requires  $C_C \geq 0.22~\mu\text{F}.$ 

The value of the output filter capacitor is normally large enough to require the use of aluminum electrolytic capacitors. Figure 11 lists several different types that are recommended for switching regulators, and the following parameters are used to select the proper capacitor.

Working Voltage (WVDC): Choose a capacitor with a working voltage at least 20% higher than the regulator output voltage

Ripple Current: This is the maximum RMS value of current that charges the capacitor during each switching cycle. For step-up and flyback regulators, the formula for ripple current is

$$I_{\text{RIPPLE}(\text{RMS})} = \frac{I_{\text{LOAD}(\text{max})} \times D_{(\text{max})}}{1 - D_{(\text{max})}}$$

Choose a capacitor that is rated at least 50% higher than this value at 52 kHz.

Equivalent Series Resistance (ESR) : This is the primary cause of output ripple voltage, and it also affects the values of R<sub>C</sub> and C<sub>C</sub> needed to stabilize the regulator. As a result, the preceding calculations for C<sub>C</sub> and R<sub>C</sub> are only valid if ESR doesn't exceed the maximum value specified by the following equations.

$$\text{ESR} \leq \frac{0.01 \times \text{V}_{\text{OUT}}}{\text{I}_{\text{RIPPI F(P,P)}}} \text{ and } \leq \frac{8.7 \times (10) - 3 \times \text{V}_{\text{IN}}}{\text{I}_{\text{I}} \text{ OAD(max)}}$$

where

$$I_{\text{RIPPLE}(\text{P-P})} = \frac{1.15 \times I_{\text{LOAD(max)}}}{1 - D_{(\text{max})}}$$

Select a capacitor with ESR, at 52 kHz, that is less than or equal to the lower value calculated. Most electrolytic capacitors specify ESR at 120 Hz which is 15% to 30% higher than at 52 kHz. Also, be aware that ESR increases by a factor of 2 when operating at -20°C.

In general, low values of ESR are achieved by using large value capacitors (C  $\geq$  470  $\mu\text{F}),$  and capacitors with high WVDC, or by paralleling smaller-value capacitors.

#### 3. Output Voltage Selection (R1 and R2)

This section is for applications using the LM1577-ADJ/ LM2577-ADJ. Skip this section if the LM1577-12/LM2577-12 or LM1577-15/LM2577-15 is being used.

With the LM1577-ADJ/LM2577-ADJ, the output voltage is given by

$$V_{OUT} = 1.23V (1 + R1/R2)$$

Resistors R1 and R2 divide the output down so it can be compared with the LM1577-ADJ/LM2577-ADJ internal 1.23V reference. For a given desired output voltage  $V_{OUT}$ , select R1 and R2 so that

$$\frac{\text{R1}}{\text{R2}} = \frac{\text{V}_{\text{OUT}}}{1.23\text{V}} - 1$$

#### 4. Input Capacitor Selection (CIN)

The switching action in the step-up regulator causes a triangular ripple current to be drawn from the supply source. This in turn causes noise to appear on the supply voltage. For proper operation of the LM1577, the input voltage should be decoupled. Bypassing the Input Voltage pin directly to ground with a good quality, low ESR, 0.1  $\mu$ F capacitor (leads as short as possible) is normally sufficient.

Cornell Dublier — Types 239, 250, 251, UFT,			
300, or 350			
P.O. Box 128, Pickens, SC 29671 (803) 878-6311			
Nichicon — Types PF, PX, or PZ			
927 East Parkway,			
Schaumburg, IL 60173			
(708) 843-7500			

Sprague — Types 672D, 673D, or 674D Box 1, Sprague Road, Lansing, NC 28643

(919) 384-2551

United Chemi-Con — Types LX, SXF, or SXJ 9801 West Higgins Road, Rosemont, IL 60018 (708) 696-2000

#### FIGURE 11. Aluminum Electrolytic Capacitors Recommended for Switching Regulators

If the LM1577 is located far from the supply source filter capacitors, an additional large electrolytic capacitor (e.g. 47  $\mu F)$  is often required.

#### 5. Diode Selection (D)

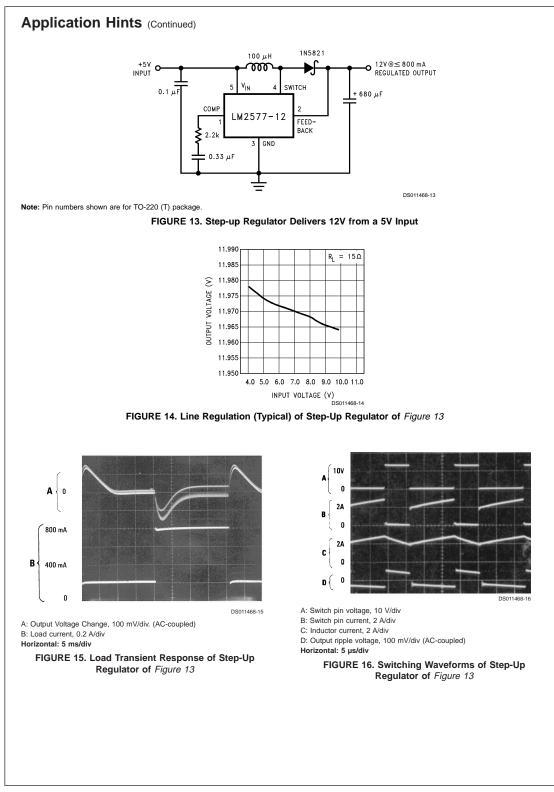
The switching diode used in the boost regulator must withstand a reverse voltage equal to the circuit output voltage, and must conduct the peak output current of the LM2577. A suitable diode must have a minimum reverse breakdown voltage greater than the circuit output voltage, and should be rated for average and peak current greater than I<sub>LOAD</sub>(max) and I<sub>D(PK)</sub>. Schottky barrier diodes are often favored for use in switching regulators. Their low forward voltage drop allows higher regulator efficiency than if a (less expensive) fast recovery diode was used. See *Figure 12* for recommended part numbers and voltage ratings of 1A and 3A diodes.

Vout	Schottky		Fast Recovery	
(max)	1A	3A	1A	3A
20V	1N5817	1N5820		
	MBR120P	MBR320P		
	1N5818	1N5821		
30V	MBR130P	MBR330P		
	11DQ03	31DQ03		
	1N5819	1N5822		
40V	MBR140P	MBR340P		
	11DQ04	31DQ04		
	MBR150	MBR350	1N4933	
50V	11DQ05	31DQ05	MUR105	
			1N4934	MR851
100V			HER102	30DL1
			MUR110	MR831
			10DL1	HER302

FIGURE 12. Diode Selection Chart

#### BOOST REGULATOR CIRCUIT EXAMPLE

By adding a few external components (as shown in *Figure 13*), the LM2577 can be used to produce a regulated output voltage that is greater than the applied input voltage. Typical performance of this regulator is shown in *Figure 14* and *Figure 15*. The switching waveforms observed during the operation of this circuit are shown in *Figure 16*.



### FLYBACK REGULATOR

A Flyback regulator can produce single or multiple output voltages that are lower or greater than the input supply voltage. *Figure 18* shows the LM1577/LM2577 used as a flyback regulator with positive and negative regulated outputs. Its operation is similar to a step-up regulator, except the output switch contols the primary current of a flyback transformer. Note that the primary and secondary windings are out of phase, so no current flows through secondary when current flows through the primary. This allows the primary to charge up the transformer core when the switch is on. When the switch turns off, the core discharges by sending current through the secondary, and this produces voltage at the outputs. The output voltages are controlled by adjusting the peak primary current, as described in the step-up regulator section.

Voltage and current waveforms for this circuit are shown in *Figure 17*, and formulas for calculating them are given in *Figure 19*.

#### FLYBACK REGULATOR DESIGN PROCEDURE

#### 1. Transformer Selection

A family of standardized flyback transformers is available for creating flyback regulators that produce dual output voltages, from  $\pm 10V$  to  $\pm 15V$ , as shown in *Figure 18. Figure 20* lists these transformers with the input voltage, output voltages and maximum load current they are designed for.

# 2. Compensation Network (C<sub>c</sub>, R<sub>c</sub>) and Output Capacitor (C<sub>OUT</sub>) Selection

As explained in the Step-Up Regulator Design Procedure,  $C_{\rm C}, R_{\rm C}$  and  $C_{\rm OUT}$  must be selected as a group. The following procedure is for a dual output flyback regulator with equal turns ratios for each secondary (i.e., both output voltages have the same magnitude). The equations can be used for a single output regulator by changing  $\Sigma I_{\rm LOAD(max)}$  to  $I_{\rm LOAD(max)}$  in the following equations.

$$\mathsf{R}_C \leq \frac{750 \times \Sigma \mathsf{I}_{\mathsf{LOAD}(\mathsf{max})} \times (15\mathsf{V} + \mathsf{V}_{\mathsf{IN}(\mathsf{min})}\mathsf{N})^2}{\mathsf{V}_{\mathsf{IN}(\mathsf{min})}^2}$$

Where  $\Sigma I_{\text{LOAD}(\text{max})}$  is the sum of the load current (magnitude) required from both outputs. Select a resistor less than or equal to this value, and no greater than 3 k $\Omega$ .

B. Calculate the minimum value for  $\Sigma C_{OUT}$  (sum of  $C_{OUT}$  at both outputs) using the following two equations.

$$C_{OUT} \geq \frac{0.19 \times R_C \times L_P \times \Sigma I_{LOAD(max)}}{15V \times V_{IN(min)}}$$

and

$$C_{OUT} {\geq} \frac{V_{IN(min)} {\times} R_C {\times} N^2 {\times} (V_{IN(min)} + (3.74 {\times} 10^5 {\times} L_p))}{487,800 {\times} (15V)^2 {\times} (15V {+} V_{IN(min)} {\times} N)}$$

The larger of these two values must be used to ensure regulator stability.

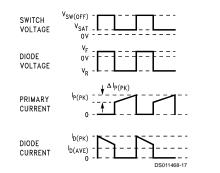
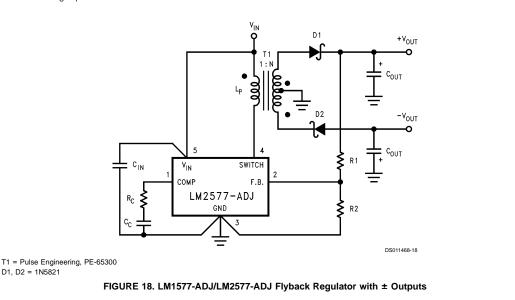


FIGURE 17. Flyback Regulator Waveforms



Duty Cycle	D	$\frac{\frac{V_{OUT} + V_{F}}{N (V_{IN} - V_{SAT}) + V_{OUT} + V_{F}} \approx \frac{V_{OUT}}{\frac{V_{OUT}}{N (V_{IN}) + V_{OUT}}}$	
Primary Current Variation	Δl <sub>P</sub>	$\frac{D\left(V_{IN}-V_{SAT}\right)}{L_{P}\times52,000}$	
Peak Primary Current	I <sub>P(PK)</sub>	$\frac{N}{\eta} \times \frac{\SigmaI_{LOAD}}{1-D} + \frac{\DeltaI_{PK}}{2}$	
Switch Voltage when Off	V <sub>SW(OFF)</sub>	$V_{IN} + rac{V_{OUT} + V_F}{N}$	
Diode Reverse Voltage	V <sub>R</sub>	V <sub>OUT</sub> <sup>+</sup> N (V <sub>IN</sub> <sup>-</sup> V <sub>SAT</sub> )	
Average Diode Current	I <sub>D(AVE)</sub>	I <sub>LOAD</sub>	
Peak Diode Current	I <sub>D(PK)</sub>	$\frac{I_{\text{LOAD}}}{1-D} + \frac{\Delta I_{\text{IND}}}{2}$	
Short Circuit Diode Current		$\approx \frac{6A}{N}$	
Power Dissipation of LM1577/LM2577	P <sub>D</sub>	$0.25\Omega \left(\frac{N \Sigma I_{LOAD}}{1 - D}\right)^2 + \frac{N I_{LOAD}}{50 (1 - D)} V_{IN}$	

N = Transformer Turns Ratio = number of secondary turns

 $\eta$  = Transformer Efficiency (typically 0.95)

 $\Sigma I_{\text{LOAD}} = |+I_{\text{LOAD}}|+|-I_{\text{LOAD}}|$ 

#### FIGURE 19. Flyback Regulator Formulas

C. Calculate the minimum value of  $C_C$ 

$$C_{C} \geq \frac{58.5 \times C_{OUT} \times V_{OUT} \times (V_{OUT} + (V_{IN(min)} \times N))}{R_{C}^{2} \times V_{IN(min)} \times N}$$

D. Calculate the maximum ESR of the  $+V_{OUT}$  and  $-V_{OUT}$  output capacitors in parallel.

$$\mathsf{ESR} + \|\mathsf{ESR}_{-} \leq \frac{8.7 \times 10^{-3} \times \mathsf{V}_{\mathsf{IN}(\mathsf{min})} \times \mathsf{V}_{\mathsf{OUT}} \times \mathsf{N}}{\Sigma \mathsf{I}_{\mathsf{LOAD}(\mathsf{max})} \times (\mathsf{V}_{\mathsf{OUT}}^{+} (\mathsf{V}_{\mathsf{IN}(\mathsf{min})} \times \mathsf{N}))}$$

This formula can also be used to calculate the maximum ESR of a single output regulator.

At this point, refer to this same section in the **Step-Up Regulator Design Procedure** for more information regarding the selection of  $C_{\text{OUT}}$ .

#### 3. Output Voltage Selection

This section is for applications using the LM1577-ADJ/ LM2577-ADJ. Skip this section if the LM1577-12/LM2577-12 or LM1577-15/LM2577-15 is being used.

With the LM1577-ADJ/LM2577-ADJ, the output voltage is given by

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Resistors R1 and R2 divide the output voltage down so it can be compared with the LM1577-ADJ/LM2577-ADJ internal 1.23V reference. For a desired output voltage  $V_{OUT}$ , select R1 and R2 so that

$$\frac{\mathrm{R1}}{\mathrm{R2}} = \frac{\mathrm{V}_{\mathrm{OUT}}}{\mathrm{1.23V}} - 1$$

#### 4. Diode Selection

DS011468-78

The switching diode in a flyback converter must withstand the reverse voltage specified by the following equation.

$$v_{\mathsf{R}} = v_{\mathsf{OUT}} + \frac{v_{\mathsf{IN}}}{\mathsf{N}}$$

A suitable diode must have a reverse voltage rating greater than this. In addition it must be rated for more than the average and peak diode currents listed in *Figure 19*.

#### 5. Input Capacitor Selection

The primary of a flyback transformer draws discontinuous pulses of current from the input supply. As a result, a flyback regulator generates more noise at the input supply than a step-up regulator, and this requires a larger bypass capacitor to decouple the LM1577/LM2577  $V_{\rm IN}$  pin from this noise. For most applications, a low ESR,  $1.0~\mu{\rm F}$  cap will be sufficient, if it is connected very close to the  $V_{\rm IN}$  and Ground pins.

Transformer Type		Input Voltage	Dual	Maxi- mum
			Output	Output
			Voltage	Current
	L <sub>P</sub> = 100 µH	5V	±10V	325 mA
1	N = 1	5V	±12V	275 mA
		5V	±15V	225 mA
		10V	±10V	700 mA
		10V	±12V	575 mA
2	L <sub>P</sub> = 200 μH	10V	±15V	500 mA
	N = 0.5	12V	±10V	800 mA
		12V	±12V	700 mA
		12V	±15V	575 mA
3	L <sub>P</sub> = 250 μH	15V	±10V	900 mA
	N = 0.5	15V	±12V	825 mA
		15V	±15V	700 mA

Transformer	Manufacturers' Part Numbers			
Туре	AIE	Pulse	Renco	
1	326-0637	PE-65300	RL-2580	
2	330-0202	PE-65301	RL-2581	
3	330-0203	PE-65302	RL-2582	

FIGURE 20. Flyback Transformer Selection Guide

In addition to this bypass cap, a larger capacitor ( $\geq$  47  $\mu\text{F})$  should be used where the flyback transformer connects to the input supply. This will attenuate noise which may interfere with other circuits connected to the same input supply voltage.

#### 6. Snubber Circuit

A "snubber" circuit is required when operating from input voltages greater than 10V, or when using a transformer with  $L_P \ge 200 \ \mu$ H. This circuit clamps a voltage spike from the transformer primary that occurs immediately after the output switch turns off. Without it, the switch voltage may exceed the 65V maximum rating. As shown in *Figure 21*, the snubber consists of a fast recovery diode, and a parallel RC. The

RC values are selected for switch clamp voltage (V<sub>CLAMP</sub>) that is 5V to 10V greater than V<sub>SW(OFF)</sub>. Use the following equations to calculate R and C;

$$\begin{split} C &\geq \frac{0.02 \times L_P \times I_{P(PK)}^2}{\left(V_{CLAMP}\right)^2 - \left(VSW_{(OFF)}\right)^2} \\ R &\leq \left(\frac{V_{CLAMP} + V_{SW(OFF)} - V_{IN}}{2}\right)^2 \times \left(\frac{19.2 \times 10^{-4}}{L_P \times I_{P(PK)}^2}\right) \end{split}$$

Power dissipation (and power rating) of the resistor is;

$$\mathsf{P} = \left(\frac{\mathsf{V}_{\mathsf{CLAMP}} + \mathsf{V}_{\mathsf{SW}(\mathsf{OFF})} - \mathsf{V}_{\mathsf{IN}}}{2}\right)^2 / \mathsf{R}$$

The fast recovery diode must have a reverse voltage rating greater than  $V_{\text{CLAMP}}.$ 

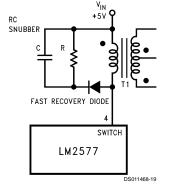
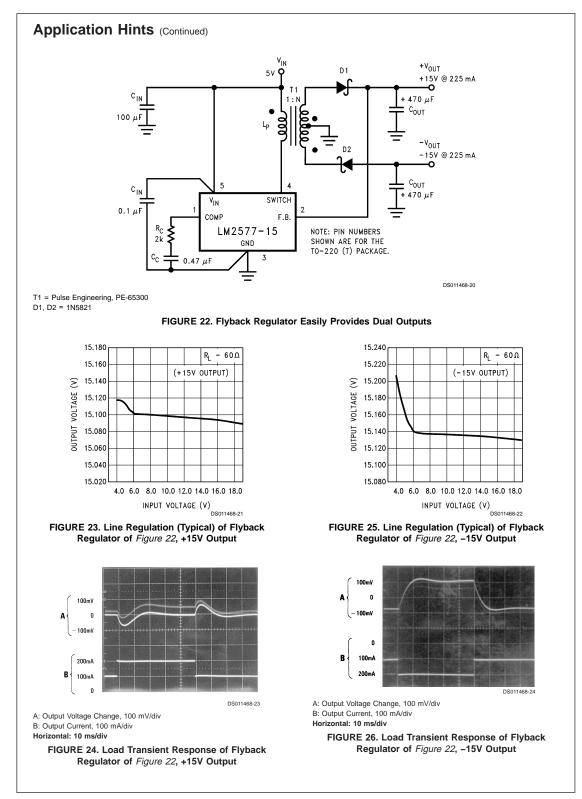
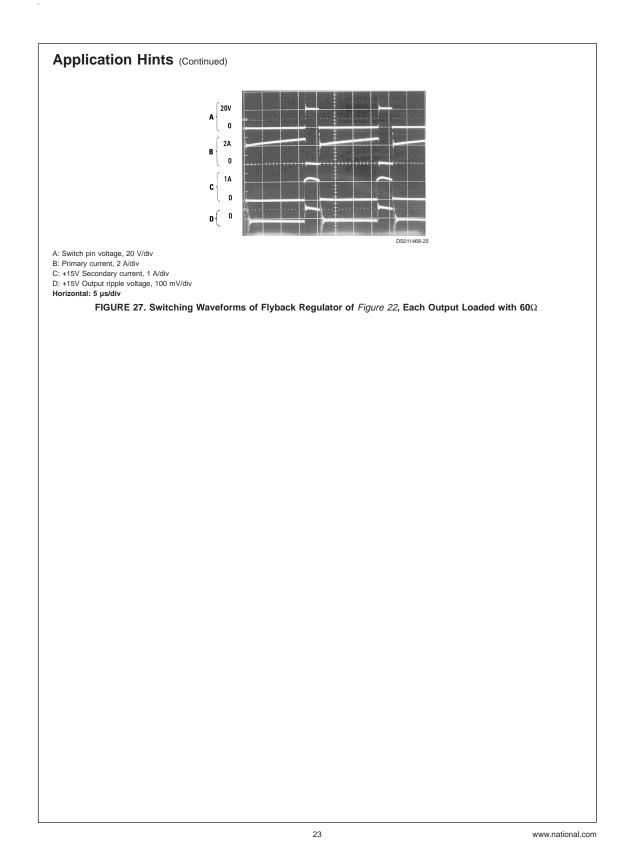


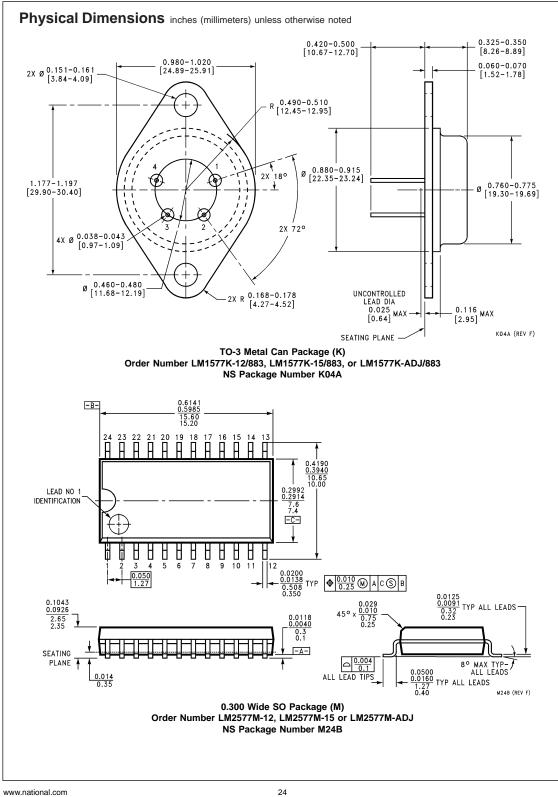
FIGURE 21. Snubber Circuit

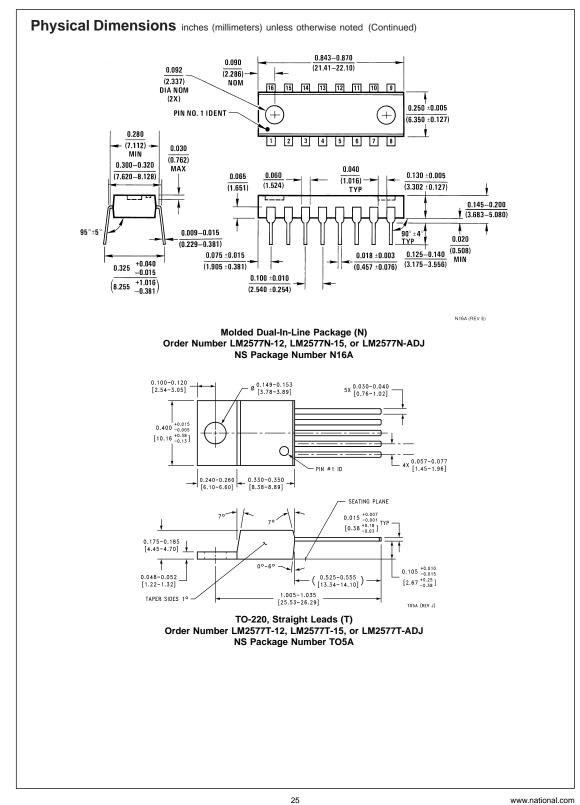
#### FLYBACK REGULATOR CIRCUIT EXAMPLE

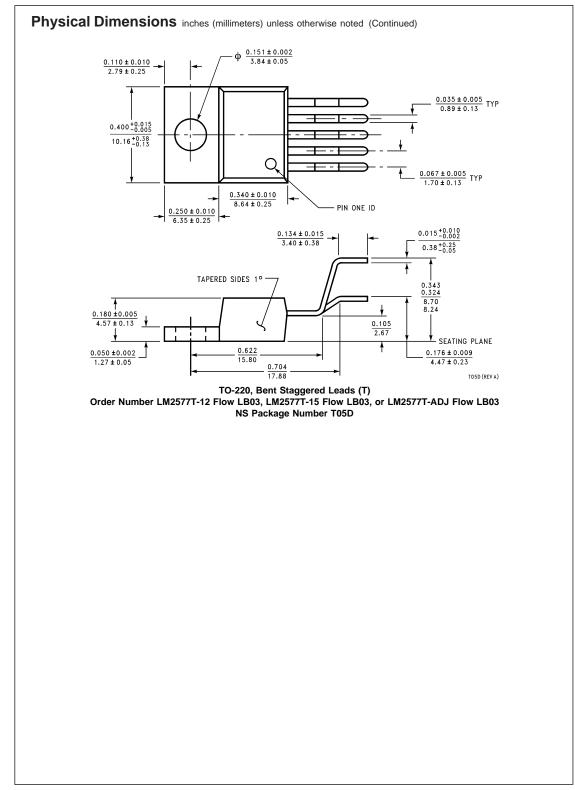
The circuit of *Figure 22* produces  $\pm$ 15V (at 225 mA each) from a single 5V input. The output regulation of this circuit is shown in *Figure 23* and *Figure 25*, while the load transient response is shown in *Figure 24* and *Figure 26*. Switching waveforms seen in this circuit are shown in *Figure 27*.

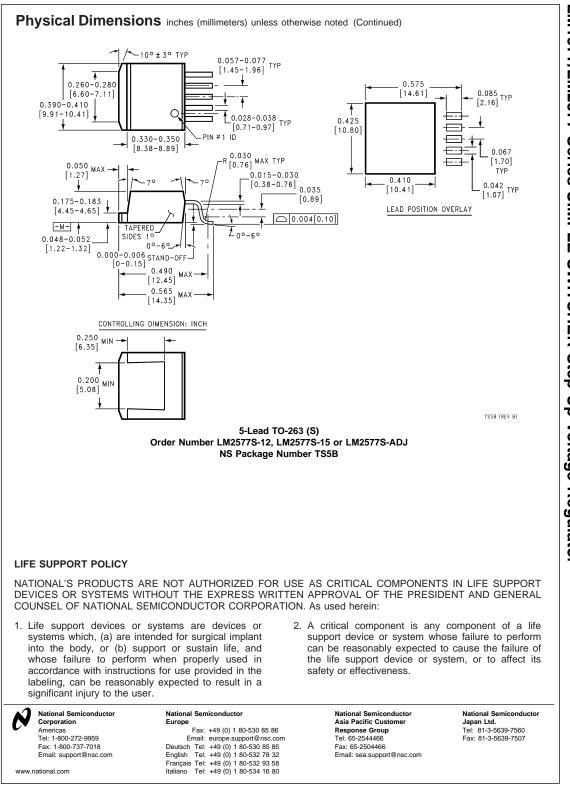












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