

UHF ASK/FSK Receiver

Description

The T5760/T5761 is a multi-chip PLL receiver device supplied in an SO20 package. It has been especially developed for the demands of RF low-cost data transmission systems with data rates from 1 kBaud to 10 kBaud in Manchester or Bi-phase code. The receiver is well suited to operate with the Atmel Wireless & Microcontrollers' PLL RF transmitter T5750. Its main applications are in

the areas of telemetry, security technology and key-less-entry systems. It can be used in the frequency receiving range of $f_0 = 868$ to 870 MHz or $f_0 = 902$ to 928 MHz for ASK or FSK data transmission. All the statements made below refer to 868.3 MHz and 915.0 MHz applications.

Features

- Fully integrated LC-VCO and PLL loop filter
- Very high sensitivity with power matched LNA
- 30 dB image rejection
- High system IIP3 (-16 dBm), system 1-dB compression point (-25 dBm)
- High large-signal capability at GSM band (blocking -30 dBm @ +20 MHz, IIP3 = -12 dBm @ +20 MHz)
- 5 V to 20 V automotive compatible data interface
- Data clock available for Manchester- and Bi-phase-coded signals
- Programmable digital noise suppression
- Receiving bandwidth $B_{IF} = 600$ kHz for low cost 90-ppm crystals
- Low power consumption due to configurable polling
- Temperature range -40°C to 105°C
- ESD protection 2 kV HBM, 200 V MM
- Communication to μC possible via a single bi-directional data line
- Low-cost solution due to high integration level with minimum external circuitry requirements

System Block Diagram

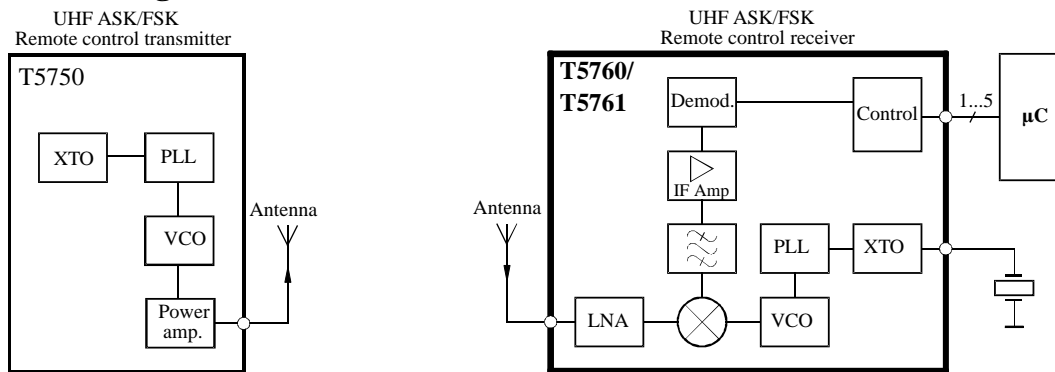


Figure 1. System block diagram

Ordering Information

| Extended Type Number | Package | Remarks |
|----------------------|---------|--|
| T5760-TG | SO20 | Tube, for 868 MHz ISM band |
| T5760-TGQ | SO20 | Taped and reeled, for 868 MHz ISM band |
| T5761-TG | SO20 | Tube, for 915 MHz ISM band |
| T5761-TGQ | SO20 | Taped and reeled, for 915 MHz ISM band |

Pin Description

| Pin | Symbol | Function |
|-----|-------------|--|
| 1 | SENS | Sensitivity-control resistor |
| 2 | IC_ACTIVE | IC condition indicator Low = sleep mode High = active mode |
| 3 | CDEM | Lower cut-off frequency data filter |
| 4 | AVCC | Analog power supply |
| 5 | TEST 1 | Test pin, during operation at GND |
| 6 | AGND | Analog ground |
| 7 | n.c. | Not connected, connect to GND |
| 8 | LNAREF | High-frequency reference node LNA and mixer |
| 9 | LNA_IN | RF input |
| 10 | LNAGND | DC ground LNA and mixer |
| 11 | TEST 2 | Do not connect during operating |
| 12 | TEST 3 | Test pin, during operation at GND |
| 13 | n.c. | Not connected, connect to GND |
| 14 | XTAL | Crystal oscillator XTAL connection |
| 15 | DVCC | Digital power supply |
| 16 | TEST 4 | Test pin, during operation at DVCC |
| 17 | DATA_CLK | Bit clock of data stream |
| 18 | DGND | Digital ground |
| 19 | POLLING/_ON | Selects polling or receiving mode Low: receiving mode High: polling mode |
| 20 | DATA | Data output / configuration input |

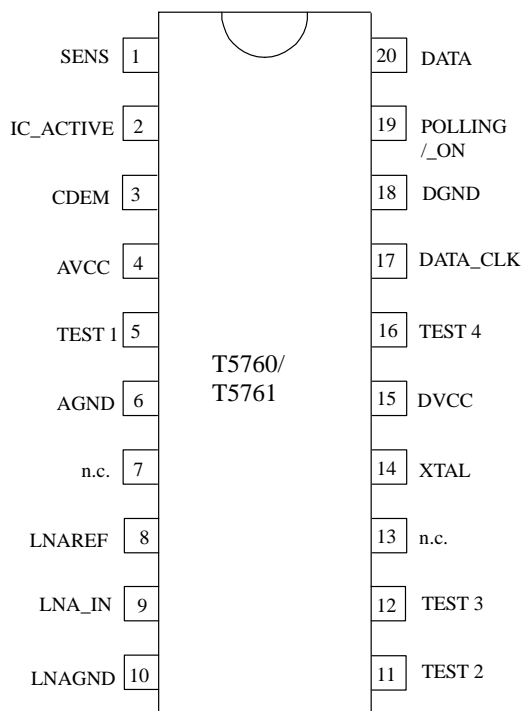


Figure 2. Pinning SO20

Block Diagram

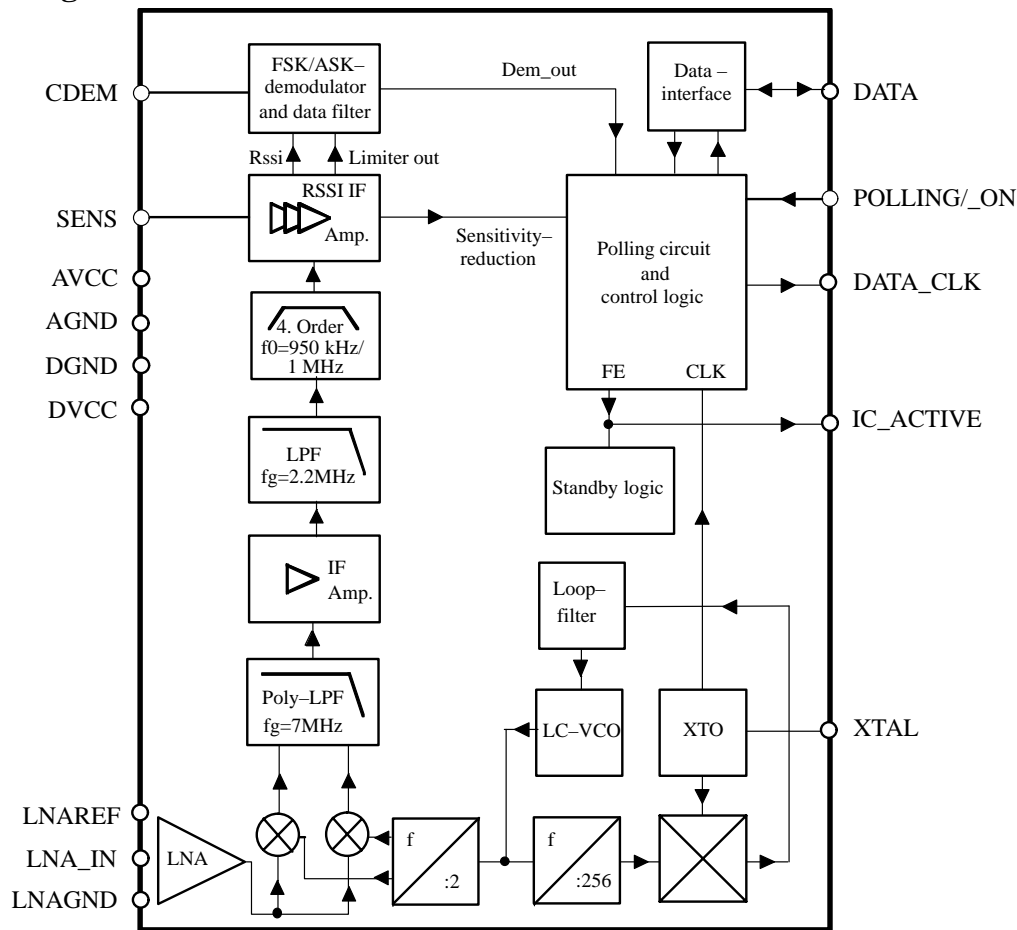


Figure 3. Block diagram

RF Front End

The RF front end of the receiver is a low-IF heterodyne configuration that converts the input signal into a 950-kHz/ 1-MHz IF signal with an image rejection of typical 30dB. According to figure 3 the front end consists of an LNA (low noise amplifier), LO (local oscillator), I/Q mixer, polyphase lowpass filter and an IF amplifier.

The PLL generates the carrier frequency for the mixer via a full integrated synthesizer with integrated low noise LC-VCO (voltage controlled oscillator) and PLL-loop-filter. The XTO (crystal oscillator) generates the reference frequency f_{XTO} . The integrated LC-VCO generates two times the mixer drive frequency f_{VCO} . The I/Q signals for the mixer are generated with a divide by two circuit ($f_{LO} = f_{VCO}/2$). f_{VCO} is divided by a factor of 256 and feed into a phase frequency detector and compared

with f_{XTO} . The output of the phase frequency detector is feed into an integrated loopfilter and thereby generates the control voltage for the VCO. If f_{LO} is determined, f_{XTO} can be calculated using the following formula:

$$f_{XTO} = f_{LO} / 128$$

The XTO is a one-pin oscillator that operates at the series resonance of the quartz crystal with high current but low voltage signal, so that there is only a small voltage at the crystal oscillator frequency at Pin XTAL. According to figure 4, the crystal should be connected to GND with a series capacitor C_L . The value of that capacitor is recommended by the crystal supplier. Due to a somewhat inductive impedance at steady state oscillation and some PCB parasitics a lower value of C_L is normally necessary.

The value of C_L should be optimized for the individual board layout to achieve the exact value of f_{XTO} (the best way is to use a crystal with known load resonance frequency to find the right value for this capacitor) and hereby of f_{LO} . When designing the system in terms of receiving bandwidth and local oscillator accuracy, the accuracy of the crystal and the XTO must be considered.

If a crystal with ± 30 ppm adjustment tolerance at 25°C , ± 50 ppm over Temperature -40°C to 105°C , ± 10 ppm of total aging and a CM (motional capacitance) of 7 fF is used, an additional XTO pulling of ± 30 ppm has to be added.

The resulting total LO tolerance of ± 120 ppm agrees with the receiving bandwidth specification of the T5760/T5761 if the T5750 has also a total LO tolerance of ± 120 ppm.

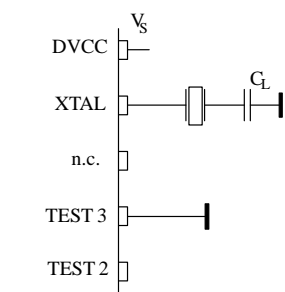


Figure 4. XTO peripherals

The nominal frequency f_{LO} is determined by the RF input frequency f_{RF} and the IF frequency f_{IF} using the following formula (low side injection):

$$f_{LO} = f_{RF} - f_{IF}$$

To determine f_{LO} , the construction of the IF filter must be considered at this point. The nominal IF frequency is $f_{IF} = 950$ kHz. To achieve a good accuracy of the filter corner frequencies, the filter is tuned by the crystal frequency f_{XTO} . This means that there is a fixed relation between f_{IF} and f_{LO} .

$$f_{IF} = f_{LO} / 915$$

The relation is designed to achieve the nominal IF frequency of $f_{IF} = 950$ kHz for the 868.3 MHz version. For the 915 MHz version an IF frequency of $f_{IF} = 1.0$ MHz results.

The RF input either from an antenna or from a RF generator must be transformed to the RF input Pin LNA_IN. The input impedance of that pin is provided in the electrical parameters. The parasitic board inductances and capacitances influence the input matching. The RF receiver T5760/T5761 exhibits its highest sensitivity if the LNA is power matched. This makes the matching to an SAW filter as well as to 50Ω or an antenna more easy.

Figure 33 shows a typical input matching network for $f_{RF} = 868.3$ MHz to 50Ω . Figure 34 illustrates an according input matching for 868.3 MHz to an SAW. The input matching network shown in Figure 33 is the reference network for the parameters given in the electrical characteristics.

Analog Signal Processing

IF Filter

The signals coming from the RF front end are filtered by the fully integrated 4th-order IF filter. The IF center frequency is $f_{IF} = 950$ kHz for applications where $f_{RF} = 868.3$ MHz and $f_{IF} = 1.0$ MHz for $f_{RF} = 915$ MHz. The nominal bandwidth is 600 kHz.

Limiting RSSI Amplifier

The subsequent RSSI amplifier enhances the output signal of the IF amplifier before it is fed into the demodulator. The dynamic range of this amplifier is $DR_{RSSI} = 60$ dB. If the RSSI amplifier is operated within its linear range, the best S/N ratio is maintained in ASK mode. If the dynamic range is exceeded by the transmitter signal, the S/N ratio is defined by the ratio of the maximum RSSI output voltage and the RSSI output voltage due to a disturber. The dynamic range of the RSSI amplifier is exceeded if the RF input signal is about 60 dB higher compared to the RF input signal at full sensitivity.

In FSK mode the S/N ratio is not affected by the dynamic range of the RSSI amplifier, because only the hard limited signal from a high gain limiting amplifier is used by the demodulator.

The output voltage of the RSSI amplifier is internally compared to a threshold voltage V_{Th_red} . V_{Th_red} is determined by the value of the external resistor R_{Sens} . R_{Sens} is connected between Pin SENS and GND or V_S . The output of the comparator is fed into the digital control logic. By this means it is possible to operate the receiver at a lower sensitivity.

If R_{Sens} is connected to GND, the receiver switches to full sensitivity. It is also possible to connect the Pin SENS directly to GND to get the maximum sensitivity.

If R_{Sens} is connected to V_S , the receiver operates at a lower sensitivity. The reduced sensitivity is defined by the value of R_{Sens} , the maximum sensitivity by the signal-to-noise ratio of the LNA input. The reduced sensitivity depends on the signal strength at the output of the RSSI amplifier.

Since different RF input networks may exhibit slightly different values for the LNA gain, the sensitivity values given in the electrical characteristics refer to a specific input matching. This matching is illustrated in figure 33

and exhibits the best possible sensitivity and at the same time power matching at RF_IN.

R_{Sens} can be connected to V_S or GND via a μC. The receiver can be switched from full sensitivity to reduced sensitivity or vice versa at any time. In polling mode, the receiver will not wake up if the RF input signal does not exceed the selected sensitivity. If the receiver is already active, the data stream at Pin DATA will disappear when the input signal is lower than defined by the reduced sensitivity. Instead of the data stream, the pattern according to figure 5 is issued at Pin DATA to indicate that the receiver is still active (see also figure 32).



Figure 5. Steady L state limited DATA output pattern

FSK/ASK Demodulator and Data Filter

The signal coming from the RSSI amplifier is converted into the raw data signal by the ASK/FSK demodulator. The operating mode of the demodulator is set via the bit ASK/_FSK in the OPMODE register. Logic 'L' sets the demodulator to FSK, applying 'H' to ASK mode.

In ASK mode an automatic threshold control circuit (ATC) is employed to set the detection reference voltage to a value where a good signal to noise ratio is achieved. This circuit also implies the effective suppression of any kind of in-band noise signals or competing transmitters. If the S/N (ratio to suppress in-band noise signals) exceeds about 10 dB the data signal can be detected properly, but better values are found for many modulation schemes of the competing transmitter.

The FSK demodulator is intended to be used for an FSK deviation of $10 \text{ kHz} \leq \Delta f \leq 100 \text{ kHz}$. In FSK mode the data signal can be detected if the S/N (ratio to suppress inband noise signals) exceeds about 2 dB. This value is valid for all modulation schemes of a disturber signal.

The output signal of the demodulator is filtered by the data filter before it is fed into the digital signal processing circuit. The data filter improves the S/N ratio as its pass-band can be adopted to the characteristics of the data signal. The data filter consists of a 1st-order highpass and a 2nd-order lowpass filter

The highpass filter cut-off frequency is defined by an external capacitor connected to Pin CDEM. The cut-off frequency of the highpass filter is defined by the following formula:

$$f_{cu_DF} = \frac{1}{2 \times \pi \times 30 \text{ k}\Omega \times \text{CDEM}}$$

In self-polling mode, the data filter must settle very rapidly to achieve a low current consumption. Therefore, CDEM cannot be increased to very high values if self-polling is used. On the other hand CDEM must be large enough to meet the data filter requirements according to the data signal. Recommended values for CDEM are given in the electrical characteristics.

The cut-off frequency of the lowpass filter is defined by the selected baud-rate range (BR_Range). The BR_Range is defined in the OPMODE register (refer to chapter 'Configuration of the Receiver'). The BR_Range must be set in accordance to the used baud-rate.

The T5760/T5761 is designed to operate with data coding where the DC level of the data signal is 50%. This is valid for Manchester and Bi-phase coding. If other modulation schemes are used, the DC level should always remain within the range of $V_{DC_min} = 33\%$ and $V_{DC_max} = 66\%$. The sensitivity may be reduced by up to 2 dB in that condition.

Each BR_Range is also defined by a minimum and a maximum edge-to-edge time (t_{ee_sig}). These limits are defined in the electrical characteristics. They should not be exceeded to maintain full sensitivity of the receiver.

Receiving Characteristics

The RF receiver T5760/T5761 can be operated with and without a SAW front-end filter. In a typical automotive application, a SAW filter is used to achieve better selectivity and large signal capability. The receiving frequency response without a SAW front-end filter is illustrated in figures 6 and 7. This example relates to ASK mode. FSK mode exhibit similar behavior. The plots are printed relatively to the maximum sensitivity. If a SAW filter is used, an insertion loss of about 3 dB must be considered, but the over all selectivity is much better.

When designing the system in terms of receiving bandwidth, the LO deviation must be considered as it also determines the IF center frequency. The total LO deviation is calculated to be the sum of the deviation of the crystal and the XTO deviation of the T5760/T5761. Low-cost crystals are specified to be within ± 90 ppm over tolerance, temperature and aging. The XTO deviation of the T5760/T5761 is an additional deviation due to the XTO circuit. This deviation is specified to be ± 30 ppm worst case for a crystal with $CM = 7 \text{ fF}$. If a crystal of ± 90 ppm is used, the total deviation is ± 120 ppm in that case. Note that the receiving bandwidth and the IF-filter bandwidth are equivalent in ASK mode but not in FSK mode.

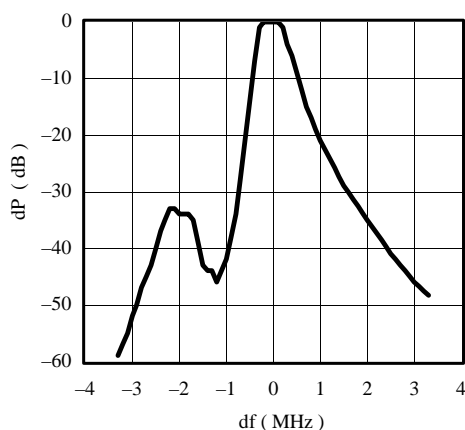


Figure 6. Narrow band receiving frequency response

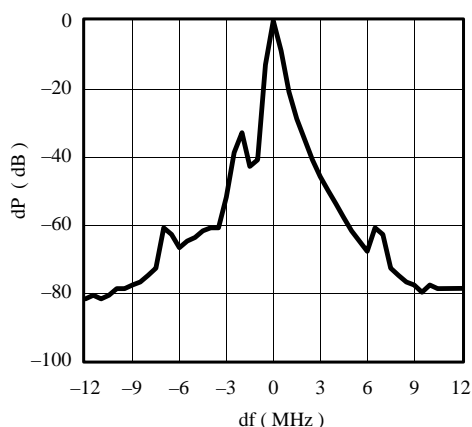


Figure 7. Wide band receiving frequency response

Polling Circuit and Control Logic

The receiver is designed to consume less than 1 mA while being sensitive to signals from a corresponding transmitter. This is achieved via the polling circuit. This circuit enables the signal path periodically for a short time. During this time the bit-check logic verifies the presence of a valid transmitter signal. Only if a valid signal is detected the receiver remains active and transfers the data to the connected μC . If there is no valid signal present the receiver is in sleep mode most of the time resulting in low current consumption. This condition is called polling mode. A connected μC is disabled during that time.

All relevant parameters of the polling logic can be configured by the connected μC . This flexibility enables the user to meet the specifications in terms of current consumption, system response time, data rate etc.

Regarding the number of connection wires to the μC , the receiver is very flexible. It can be either operated by a

single bi-directional line to save ports to the connected μC or it can be operated by up to five uni-directional ports.

Basic Clock Cycle of the Digital Circuitry

The complete timing of the digital circuitry and the analog filtering is derived from one clock. This clock cycle T_{Clk} is derived from the crystal oscillator (XTO) in combination with a divide by 14 circuit. According to chapter 'RF Front End', the frequency of the crystal oscillator (f_{XTO}) is defined by the RF input signal (f_{RFIn}) which also defines the operating frequency of the local oscillator (f_{LO}). The basic clock cycle is $T_{\text{Clk}} = 14 / f_{\text{XTO}}$ giving $T_{\text{Clk}} = 2.066 \mu\text{s}$ for $f_{\text{RF}} = 868.3 \text{ MHz}$ and $T_{\text{Clk}} = 1.961 \mu\text{s}$ for $f_{\text{RF}} = 915 \text{ MHz}$

T_{Clk} controls the following application-relevant parameters:

- Timing of the polling circuit including bit check
- Timing of the analog and digital signal processing
- Timing of the register programming
- Frequency of the reset marker
- IF filter center frequency (f_{IF0})

Most applications are dominated by two transmission frequencies: $f_{\text{Transmit}} = 915 \text{ MHz}$ is mainly used in USA, $f_{\text{Transmit}} = 868.3 \text{ MHz}$ in Europe. In order to ease the usage of all T_{Clk} -dependent parameters on this electrical characteristics display three conditions for each parameter.

- Application USA
($f_{\text{XTO}} = 7.14063 \text{ MHz}$, $T_{\text{Clk}} = 1.961 \mu\text{s}$)
- Application Europe
($f_{\text{XTO}} = 6.77617 \text{ MHz}$, $T_{\text{Clk}} = 2.066 \mu\text{s}$)
- Other applications
The electrical characteristic is given as a function of T_{Clk} .

The clock cycle of some function blocks depends on the selected baud-rate range (BR_Range) which is defined in the OPMODE register. This clock cycle T_{XClk} is defined by the following formulas for further reference:

$$\begin{aligned} \text{BR_Range} = \text{BR_Range0: } T_{\text{XClk}} &= 8 \times T_{\text{Clk}} \\ \text{BR_Range1: } T_{\text{XClk}} &= 4 \times T_{\text{Clk}} \\ \text{BR_Range2: } T_{\text{XClk}} &= 2 \times T_{\text{Clk}} \\ \text{BR_Range3: } T_{\text{XClk}} &= 1 \times T_{\text{Clk}} \end{aligned}$$

Polling Mode

According to figure 11, the receiver stays in polling mode in a continuous cycle of three different modes. In sleep mode the signal processing circuitry is disabled for the time period T_{Sleep} while consuming low current of $I_{\text{S}} = I_{\text{Soff}}$. During the start-up period, T_{Startup} , all signal processing circuits are enabled and settled. In the follow-

ing bit-check mode, the incoming data stream is analyzed bit by bit contra a valid transmitter signal. If no valid signal is present, the receiver is set back to sleep mode after the period $T_{\text{Bit-check}}$. This period varies check by check as it is a statistical process. An average value for $T_{\text{Bit-check}}$ is given in the electrical characteristics. During T_{Startup} and $T_{\text{Bit-check}}$ the current consumption is $I_S = I_{\text{Son}}$. The condition of the receiver is indicated on Pin IC_ACTIVE. The average current consumption in polling mode is dependent on the duty cycle of the active mode and can be calculated as:

$$I_{\text{Spoll}} = \frac{I_{\text{Soff}} \times T_{\text{Sleep}} + I_{\text{Son}} \times (T_{\text{Startup}} + T_{\text{Bitcheck}})}{T_{\text{Sleep}} + T_{\text{Startup}} + T_{\text{Bitcheck}}}$$

During T_{Sleep} and T_{Startup} the receiver is not sensitive to a transmitter signal. To guarantee the reception of a transmitted command the transmitter must start the telegram with an adequate preburst. The required length of the preburst depends on the polling parameters T_{Sleep} , T_{Startup} , $T_{\text{Bit-check}}$ and the start-up time of a connected μC ($T_{\text{Start},\mu\text{C}}$). Thus, $T_{\text{Bit-check}}$ depends on the actual bit rate and the number of bits ($N_{\text{Bit-check}}$) to be tested.

The following formula indicates how to calculate the preburst length.

$$T_{\text{Purburst}} \geq T_{\text{Sleep}} + T_{\text{Startup}} + T_{\text{Bit-check}} + T_{\text{Start},\mu\text{C}}$$

Sleep Mode

The length of period T_{Sleep} is defined by the 5-bit word Sleep of the OPMODE register, the extension factor X_{Sleep} (according to table 9), and the basic clock cycle T_{Clk} . It is calculated to be:

$$T_{\text{Sleep}} = \text{Sleep} \times X_{\text{Sleep}} \times 1024 \times T_{\text{Clk}}$$

In US- and European applications, the maximum value of T_{Sleep} is about 60 ms if X_{Sleep} is set to 1. The time resolution is about 2 ms in that case. The sleep time can be extended to almost half a second by setting X_{Sleep} to 8. X_{Sleep} can be set to 8 by bit X_{SleepStd} to '1'.

According to table 8, the highest register value of sleep sets the receiver into a permanent sleep condition. The receiver remains in that condition until another value for Sleep is programmed into the OPMODE register. This function is desirable where several devices share a single data line and may also be used for μC polling – via Pin POLLING/_ON, the receiver can be switched on and off.

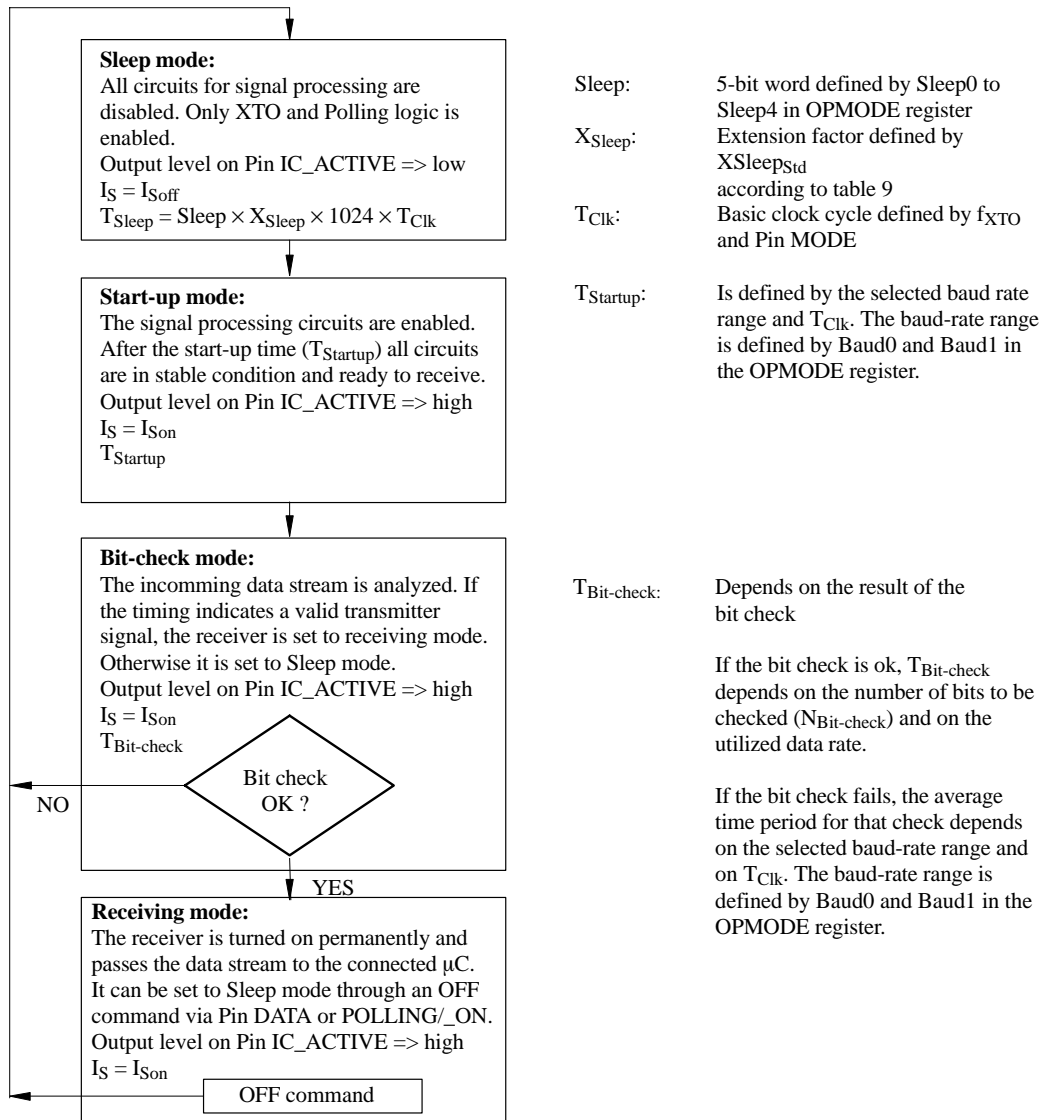


Figure 8. Polling mode flow chart

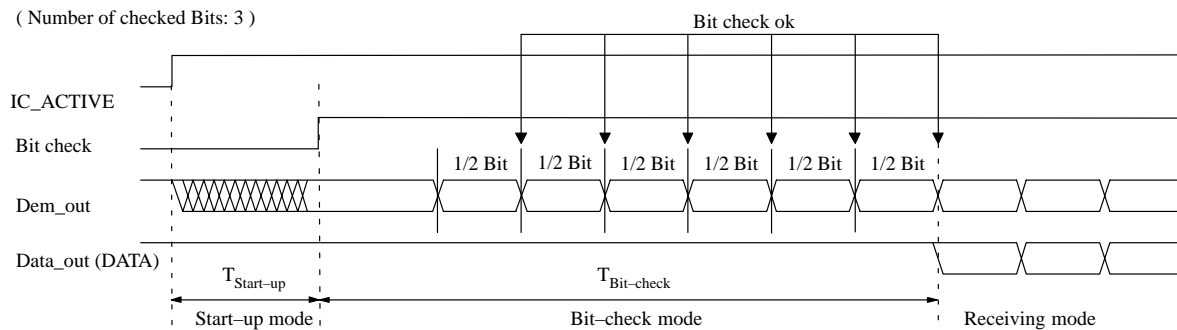


Figure 9. Timing diagram for complete successful bit check

Bit-Check Mode

In bit-check mode the incoming data stream is examined to distinguish between a valid signal from a corresponding transmitter and signals due to noise. This is done by subsequent time frame checks where the distances between 2 signal edges are continuously compared to a programmable time window. The maximum count of this edge-to-edge tests before the receiver switches to receiving mode is also programmable.

Configuring the Bit Check

Assuming a modulation scheme that contains 2 edges per bit, two time frame checks are verifying one bit. This is valid for Manchester, Bi-phase and most other modulation schemes. The maximum count of bits to be checked can be set to 0, 3, 6 or 9 bits via the variable $N_{\text{Bit-check}}$ in the OPMODE register. This implies 0, 6, 12 and 18 edge to edge checks respectively. If $N_{\text{Bit-check}}$ is set to a higher value, the receiver is less likely to switch to receiving mode due to noise. In the presence of a valid transmitter signal, the bit check takes less time if $N_{\text{Bit-check}}$ is set to a lower value. In polling mode, the bit-check time is not dependent on $N_{\text{Bit-check}}$. Figure 12 shows an example where 3 bits are tested successfully and the data signal is transferred to Pin DATA.

According to figure 13, the time window for the bit check is defined by two separate time limits. If the edge-to-edge time t_{ee} is in between the lower bit-check limit $T_{\text{Lim_min}}$ and the upper bit-check limit $T_{\text{Lim_max}}$, the check will be continued. If t_{ee} is smaller than $T_{\text{Lim_min}}$ or t_{ee} exceeds $T_{\text{Lim_max}}$, the bit check will be terminated and the receiver switches to sleep mode.

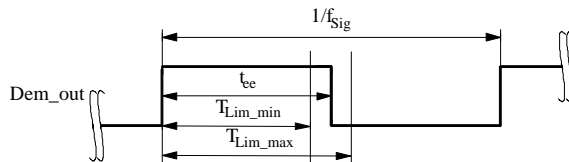


Figure 10. Valid time window for bit check

For best noise immunity it is recommended to use a low span between $T_{\text{Lim_min}}$ and $T_{\text{Lim_max}}$. This is achieved us-

ing a fixed frequency at a 50% duty cycle for the transmitter preburst. A '11111...' or a '10101...' sequence in Manchester or Bi-phase is a good choice concerning that advice. A good compromise between receiver sensitivity and susceptibility to noise is a time window of $\pm 25\%$ regarding the expected edge-to-edge time t_{ee} . Using pre-burst patterns that contain various edge-to-edge time periods, the bit-check limits must be programmed according to the required span.

The bit-check limits are determined by means of the formula below.

$$T_{\text{Lim_min}} = \text{Lim_min} \times T_{\text{XClk}}$$

$$T_{\text{Lim_max}} = (\text{Lim_max} - 1) \times T_{\text{XClk}}$$

Lim_min and Lim_max are defined by a 5-bit word each within the LIMIT register.

Using above formulas, Lim_min and Lim_max can be determined according to the required $T_{\text{Lim_min}}$, $T_{\text{Lim_max}}$ and T_{XClk} . The time resolution defining $T_{\text{Lim_min}}$ and $T_{\text{Lim_max}}$ is T_{XClk} . The minimum edge-to-edge time t_{ee} ($t_{\text{DATA_L_min}}$, $t_{\text{DATA_H_min}}$) is defined according to the chapter 'Receiving Mode'. The lower limit should be set to $\text{Lim_min} \geq 10$. The maximum value of the upper limit is $\text{Lim_max} = 63$.

If the calculated value for Lim_min is < 19 , it is recommended to check 6 or 9 bits ($N_{\text{Bit-check}}$) to prevent switching to receiving mode due to noise.

Figures 14, 15 and 16 illustrate the bit check for the bit-check limits $\text{Lim_min} = 14$ and $\text{Lim_max} = 24$. When the IC is enabled, the signal processing circuits are enabled during T_{Startup} . The output of the ASK/FSK demodulator (Dem_out) is undefined during that period. When the bit check becomes active, the bit-check counter is clocked with the cycle T_{XClk} .

Figure 14 shows how the bit check proceeds if the bit-check counter value CV_Lim is within the limits defined by Lim_min and Lim_max at the occurrence of a signal edge. In figure 15 the bit check fails as the value CV_lim is lower than the limit Lim_min. The bit check also fails if CV_Lim reaches Lim_max. This is illustrated in figure 16.

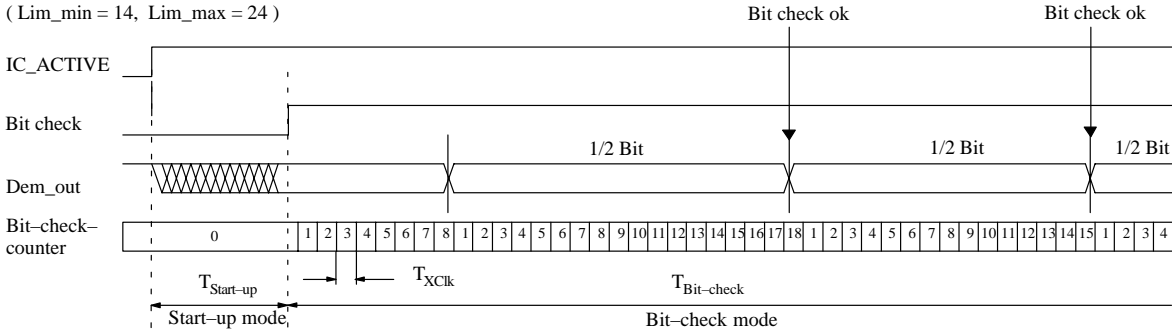


Figure 11. Timing diagram during bit check

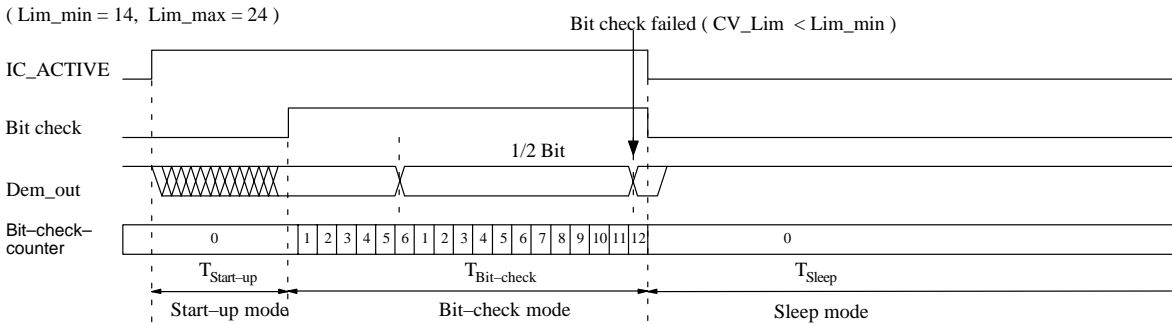


Figure 12. Timing diagram for failed bit check (condition: $CV_Lim < Lim_min$)

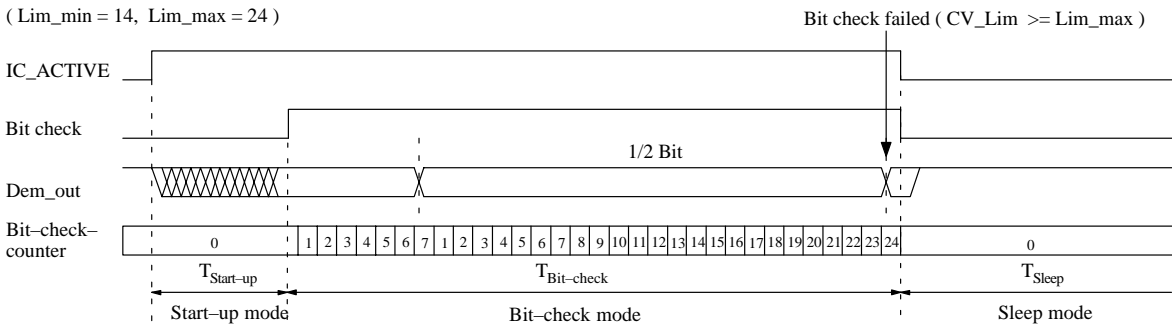


Figure 13. Timing diagram for failed bit check (condition: $CV_Lim \geq Lim_max$)

Duration of the Bit Check

If no transmitter signal is present during the bit check, the output of the ASK/FSK demodulator delivers random signals. The bit check is a statistical process and $T_{Bit-check}$ varies for each check. Therefore, an average value for $T_{Bit-check}$ is given in the electrical characteristics. $T_{Bit-check}$ depends on the selected baud-rate range and on T_{Clk} . A higher baud-rate range causes a lower value for $T_{Bit-check}$ resulting in a lower current consumption in polling mode.

In the presence of a valid transmitter signal, $T_{Bit-check}$ is dependent on the frequency of that signal, f_{Sig} , and the count of the checked bits, $N_{Bit-check}$. A higher value for

$N_{Bit-check}$ thereby results in a longer period for $T_{Bit-check}$ requiring a higher value for the transmitter pre-burst $T_{Preburst}$.

Receiving Mode

If the bit check was successful for all bits specified by $N_{Bit-check}$, the receiver switches to receiving mode. According to figure 9, the internal data signal is switched to Pin DATA in that case and the data clock is available after the start bit has been detected (figure 20). A connected μC can be woken up by the negative edge at Pin DATA or by the data clock at Pin DATA_CLK. The receiver stays in that condition until it is switched back to polling mode explicitly.

Digital Signal Processing

The data from the ASK/FSK demodulator (Dem_out) is digitally processed in different ways and as a result converted into the output signal data. This processing depends on the selected baud-rate range (BR_Range). Figure 14 illustrates how Dem_out is synchronized by the extended clock cycle T_{XCik} . This clock is also used for the bit-check counter. Data can change its state only after T_{XCik} has elapsed. The edge-to-edge time period t_{ee} of the Data signal as a result is always an integral multiple of T_{XCik} .

The minimum time period between two edges of the data

signal is limited to $t_{ee} \geq T_{DATA_min}$. This implies an efficient suppression of spikes at the DATA output. At the same time it limits the maximum frequency of edges at DATA. This eases the interrupt handling of a connected μ C.

The maximum time period for DATA to stay Low is limited to $T_{DATA_L_max}$. This function is employed to ensure a finite response time in programming or switching off the receiver via Pin DATA. $T_{DATA_L_max}$ is thereby longer than the maximum time period indicated by the transmitter data stream. Figure 16 gives an example where Dem_out remains Low after the receiver has switched to receiving mode.

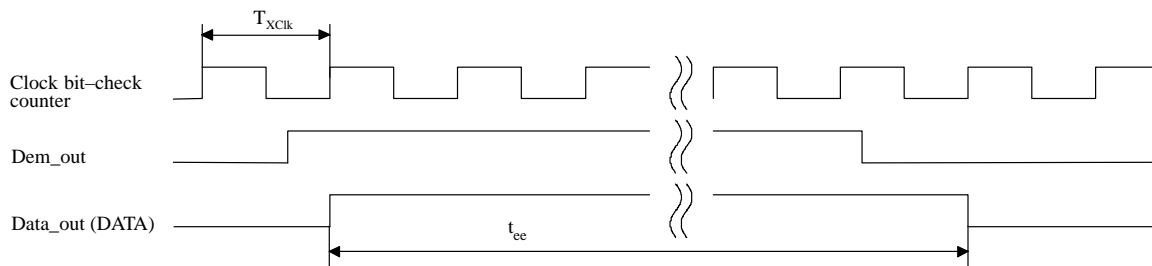


Figure 14. Synchronization of the demodulator output

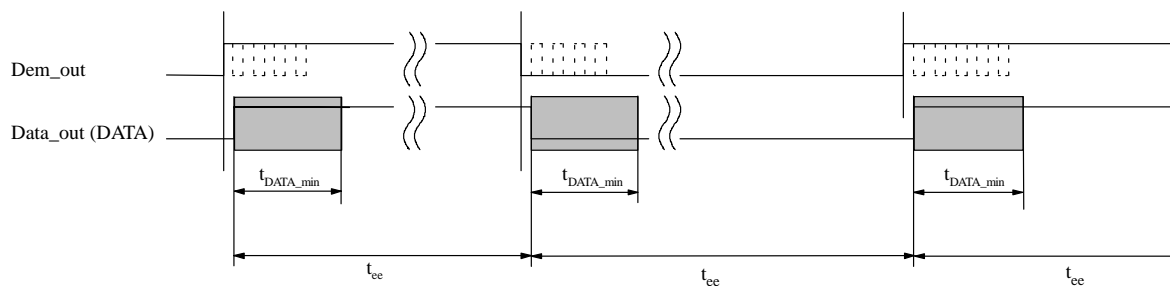


Figure 15. Debouncing of the demodulator output

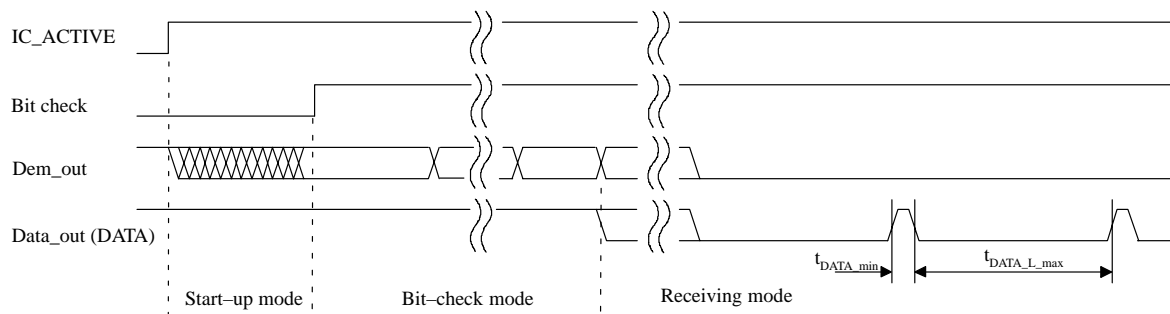


Figure 16. Steady L state limited DATA output pattern after transmission

After the end of a data transmission, the receiver remains active. Depending of the bit Noise_Disable in the OP-MODE register, the output signal at Pin DATA is high or random noise pulses appear at Pin DATA (see chapter 'Digital Noise Suppression'). The edge-to-edge time period t_{ee} of the majority of these noise pulses is equal or slightly higher than T_{DATA_min} .

Switching the Receiver Back to Sleep Mode

The receiver can be set back to polling mode via Pin DATA or via Pin POLLING/_ON.

When using Pin DATA, this pin must be pulled to Low for the period t_1 by the connected μC . Figure 17 illustrates the timing of the OFF command (see also figure 32). The

minimum value of t_1 depends on BR_Range. The maximum value for t_1 is not limited but it is recommended not to exceed the specified value to prevent erasing the reset marker. Note also that an internal reset for the OPMODE and the LIMIT register will be generated if t_1 exceeds the specified values. This item is explained in more detail in the chapter 'Configuration of the Receiver'. Setting the receiver to sleep mode via DATA is achieved by programming bit 1 to be '1' during the register configuration. Only one sync pulse (t_3) is issued.

The duration of the OFF command is determined by the sum of t_1 , t_2 and t_{10} . After the OFF command the sleep time T_{Sleep} elapses. Note that the capacitive load at Pin DATA is limited (see chapter 'Data Interface').

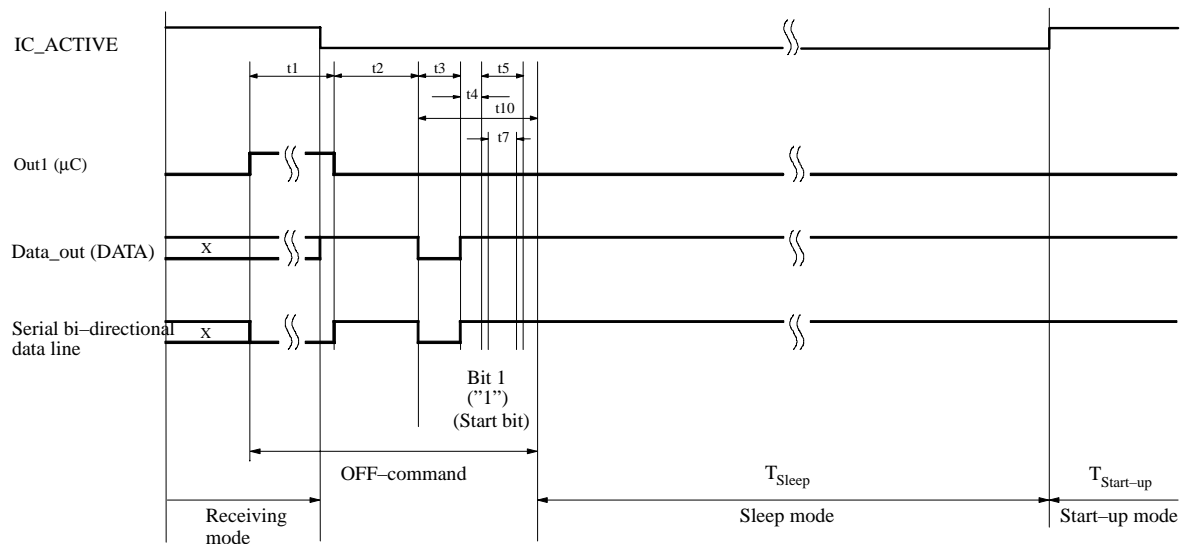


Figure 17. Timing diagram of the OFF-command via Pin DATA

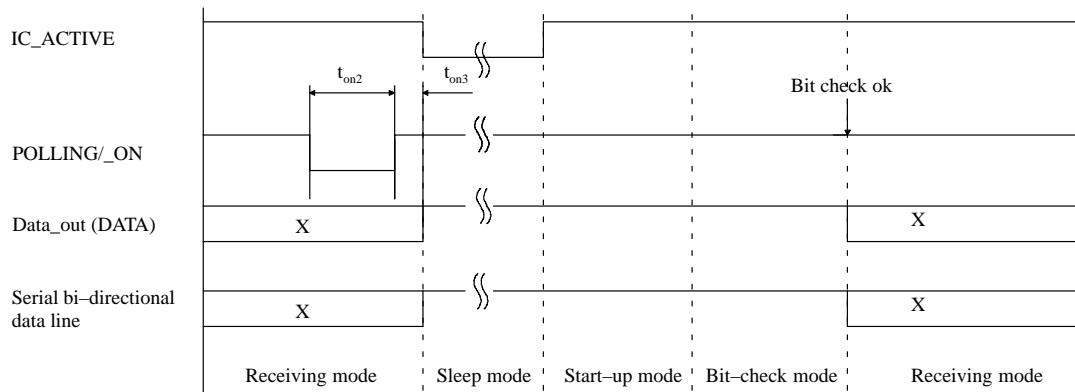


Figure 18. Timing diagram of the OFF-command via Pin POLLING/_ON

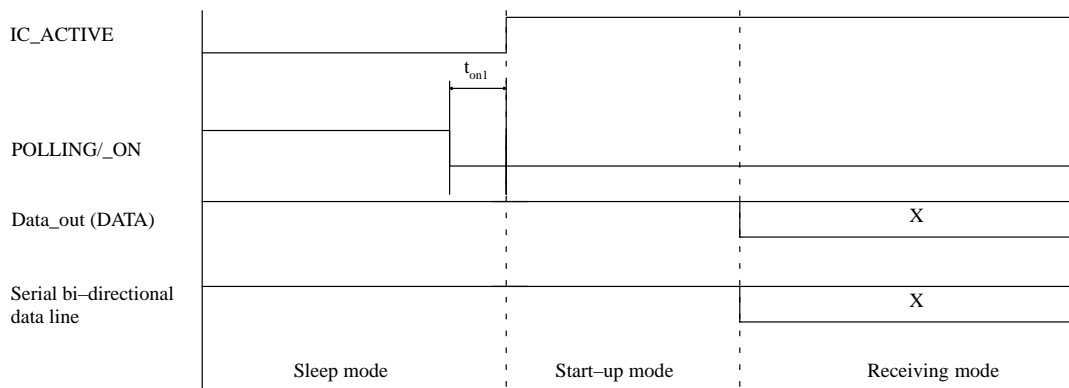


Figure 19. Activating the receiving mode via Pin POLLING/_ON

Figure 18 illustrates how to set the receiver back to polling mode via Pin POLLING/_ON. The Pin POLLING/_ON must be held to low for the time period t_{on2} . After the positive edge on Pin POLLING/_ON and the delay t_{on3} , the polling mode is active and the sleep time T_{Sleep} elapses.

This command is faster than using Pin DATA at the cost of an additional connection to the μC .

Figure 19 illustrates how to set the receiver to receiving mode via the Pin POLLING/_ON. The Pin POLLING/_ON must be held to Low. After the delay t_{on1} , the receiver changes from sleep mode to start-up mode regardless the programmed values for T_{Sleep} and $N_{Bit-check}$. As long as POLLING/_ON is held to Low, the values for T_{Sleep} and $N_{Bit-check}$ will be ignored, but not deleted (see also chapter 'Digital Noise Suppression').

If the receiver is polled exclusively by a μC , T_{Sleep} must be programmed to 31 (permanent sleep mode). In this case the receiver remains in sleep mode as long as POLLING/_ON is held to High.

Data Clock

The Pin DATA_CLK makes a data shift clock available to sample the data stream into a shift register. Using this data clock, a μC can easily synchronize the data stream. This clock can only be used for **Manchester and Bi-phase** coded signals.

Generation of the data clock:

After a successful bit check, the receiver switches from polling mode to receiving mode and the data stream is available at Pin DATA. In receiving mode, the data clock control logic (Manchester/Bi-phase demodulator) is active and examines the incoming data stream. This is done, like in the bit check, by subsequent time frame checks where the distance between two edges is continuously

compared to a programmable time window. As illustrated in figure 20, only two distances between two edges in Manchester and Bi-phase coded signals are valid (T and $2T$).

The limits for T are the same as used for the bit check. They can be programmed in the LIMIT-register (Lim_min and Lim_max , see tables 10 and 11).

The limits for $2T$ are calculated as follows:

Lower limit of $2T$:

$$Lim_min_2T = (Lim_min + Lim_max) - (Lim_max - Lim_min) / 2$$

Upper limit of $2T$:

$$Lim_max_2T = (Lim_min + Lim_max) + (Lim_max - Lim_min) / 2$$

(If the result for 'Lim_min_2T' or 'Lim_max_2T' is not an integer value, it will be round up)

The data clock is available, after the data clock control logic has detected the distance $2T$ (Start bit) and is issued with the delay t_{Delay} after the edge on Pin DATA (see figure 20).

If the data clock control logic detects a timing or logical error (Manchester code violation), like illustrated in figures 21 and 22, it stops the output of the data clock. The receiver remains in receiving mode and starts with the bit check. If the bit check was successful and the start bit has been detected, the data clock control logic starts again with the generation of the data clock (see figure 23).

It is recommended to use the function of the data clock only in conjunction with the bit check 3, 6 or 9. If the bit check is set to 0 or the receiver is set to receiving mode via the Pin POLLING/_ON, the data clock is available if the data clock control logic has detected the distance $2T$ (Start bit).

Note that for Bi-phase-coded signals, the data clock is issued at the end of the bit.

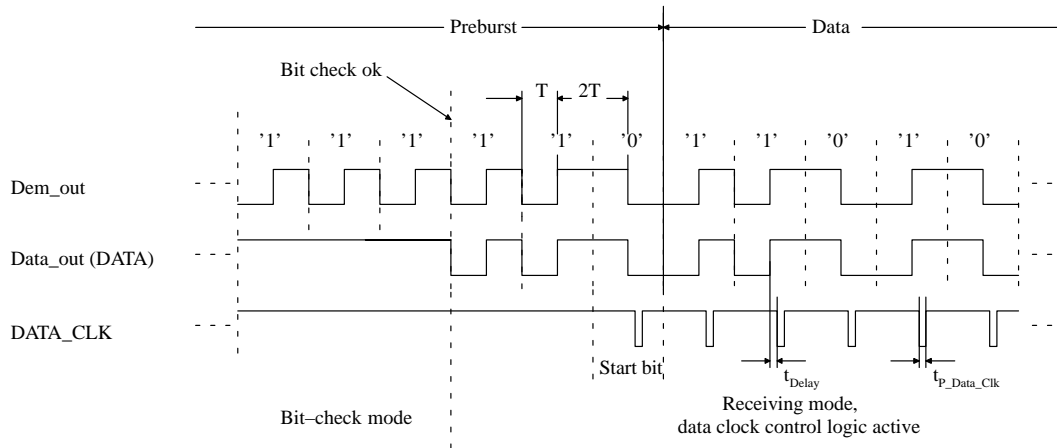


Figure 20. Timing diagram of the data clock

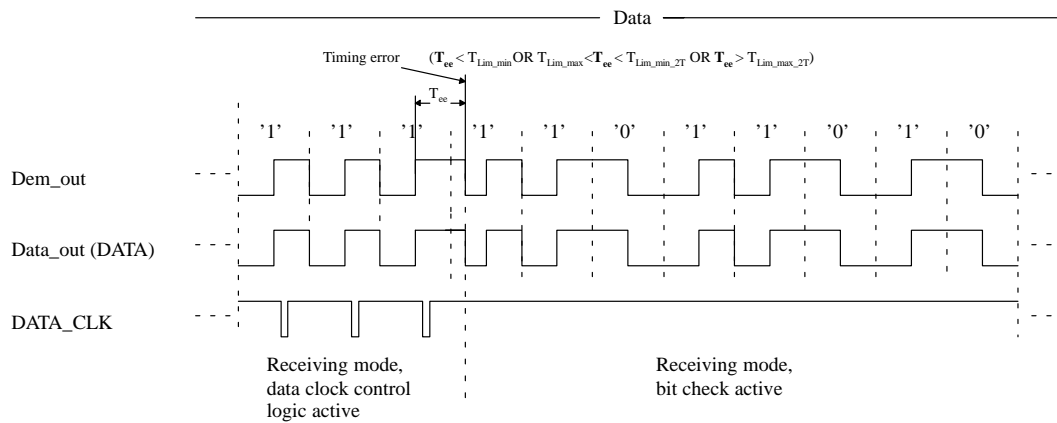


Figure 21. Data clock disappears because of a timing error

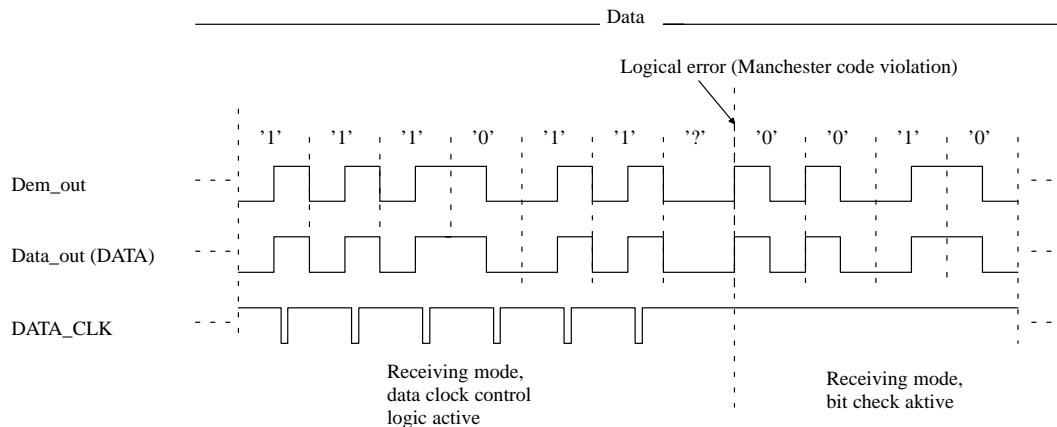


Figure 22. Data clock disappears because of a logical error

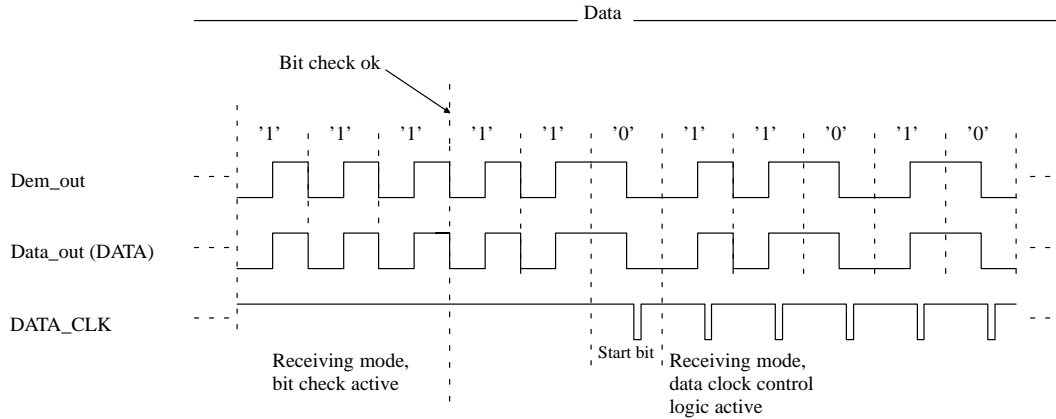


Figure 23. Output of the data clock after a successful bit check

The delay of the data clock is calculated as follows:

$$t_{\text{Delay}} = t_{\text{Delay1}} + t_{\text{Delay2}}$$

t_{Delay1} is the delay between the internal signals Data_Out and Data_In. For the rising edge, t_{Delay1} depends on the capacitive load C_L at Pin DATA and the external pull-up resistor R_{pup} . For the falling edge, t_{Delay1} depends additionally on the external voltage V_X (see figures 24, 25 and

32). When the level of Data_In is equal to the level of Data_Out, the data clock is issued after an additional delay t_{Delay2} .

Note that the capacitive load at Pin DATA is limited. If the maximum tolerated capacitive load at Pin DATA is exceeded, the data clock disappears (see chapter 'Data Interface').

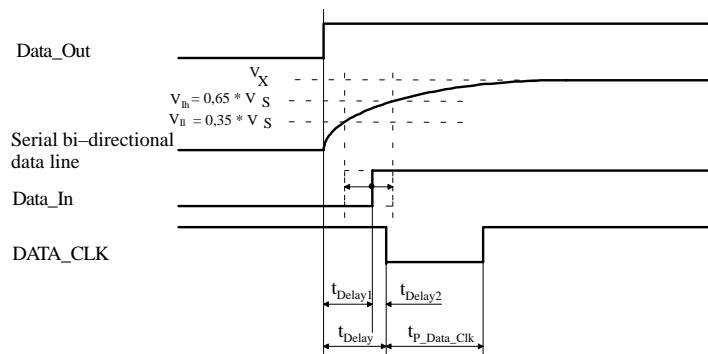


Figure 24. Timing characteristic of the data clock (rising edge on Pin DATA)

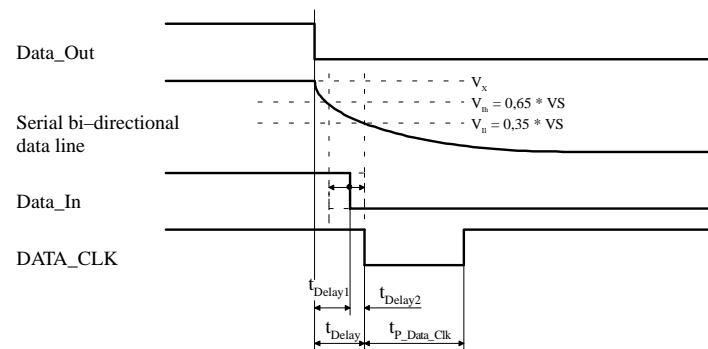


Figure 25. Timing characteristic of the data clock (falling edge of the Pin DATA)

Digital Noise Suppression

After a data transmission, digital noise appears on the data output (see figure 26). To prevent that digital noise keeps the connected μC busy, it can be suppressed in two different ways.

1. Automatic noise suppression:

If the bit Noise_Disable (table 9) in the OPMODE register is set to 1 (default), the receiver changes to bit-check mode at the end of a valid data stream. The digital noise

is suppressed and the level at Pin DATA is High in that case. The receiver changes back to receiving mode, if the bit check was successful.

This way to suppress the noise is recommended if the data stream is Manchester or Bi-phase coded and is active after power on.

Figure 28 illustrates the behavior of the data output at the end of a data stream. Note that if the last period of the data stream is a high period (rising edge to falling edge), a pulse occurs on Pin DATA. The length of the pulse depends on the selected baud-rate range.

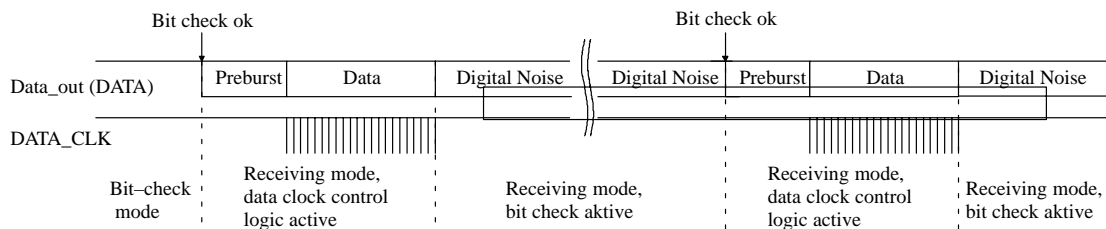


Figure 26. Output of digital noise at the end of the data stream

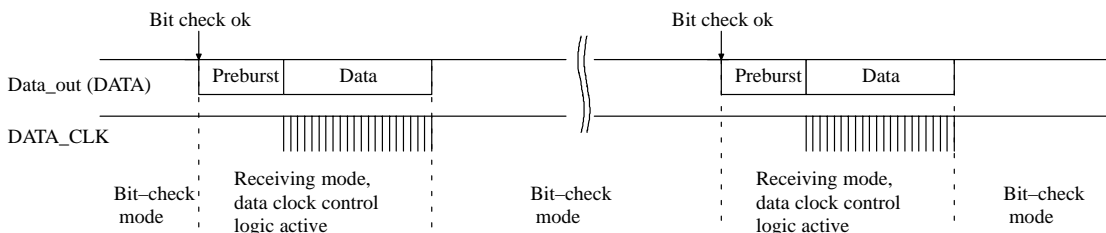


Figure 27. Automatic noise suppression

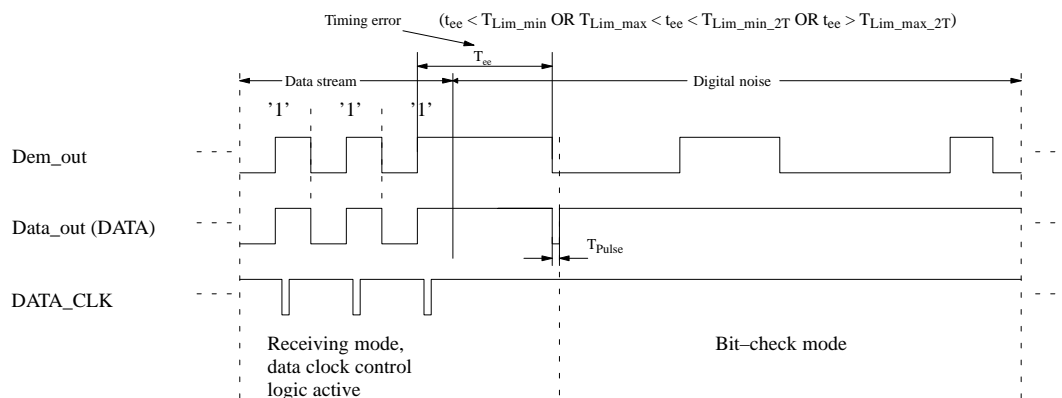


Figure 28. Occurrence of a pulse at the end of the data stream

2. Controlled noise suppression by the μC:

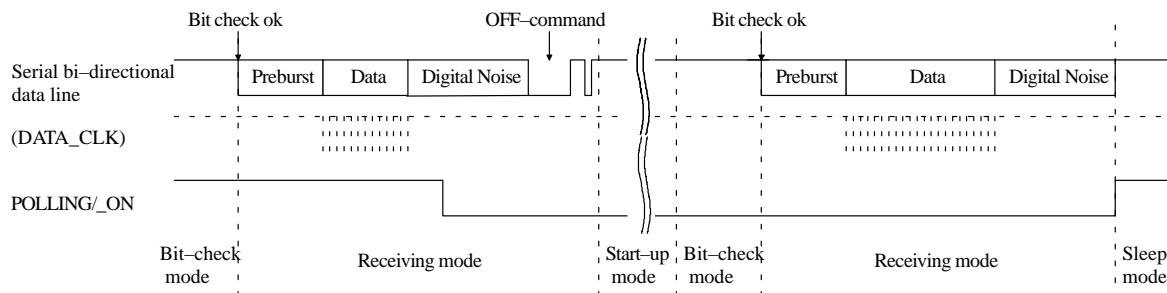


Figure 29. Controlled noise suppression

If the bit Noise_Disable (see table 9) in the OPMODE register is set to 0, digital noise appears at the end of a valid data stream. To suppress the noise, the Pin POLLING/_ON must be set to Low. The receiver remains in receiving mode. Then, the OFF-command causes the change to the start-up mode. The programmed sleep time (see table 7) will not be executed because the level at Pin POLLING/_ON is low, but the bit check is active in that case. The OFF-command activates the bit check also if the Pin POLLING/_ON is held to Low. The receiver changes back to receiving mode if the bit check was successful. To activate the polling mode at the end of the data transmission, the Pin POLLING/_ON must be set to High.

This way to suppress the noise is recommended if the data stream is not Manchester or Bi-phase coded.

Configuration of the Receiver

The T5760/T5761 receiver is configured via two 12-bit RAM registers called OPMODE and LIMIT. The registers can be programmed by means of the bidirectional DATA port. If the register contents have changed due to a voltage drop, this condition is indicated by a certain output pattern called reset marker (RM). The receiver must be reprogrammed in that case. After a power-on reset (POR), the registers are set to default mode. If the receiver

is operated in default mode, there is no need to program the registers. Table 3 shows the structure of the registers. According to table 2 bit 1 defines if the receiver is set back to polling mode via the OFF command (see chapter 'Receiving Mode') or if it is programmed. Bit 2 represents the register address. It selects the appropriate register to be programmed. To get a high programming reliability, Bit15 (Stop bit), at the end of the programming operation, must be set to 0.

Table 1 Effect of Bit 1 and Bit 2 on programming the registers

| Bit 1 | Bit 2 | Action |
|-------|-------|--|
| 1 | x | The receiver is set back to polling mode (OFF command) |
| 0 | 1 | The OPMODE register is programmed |
| 0 | 0 | The LIMIT register is programmed |

Table 2 Effect of Bit 15 on programming the register

| Bit 15 | Action |
|--------|--|
| 0 | The values will be written into the register (OPMODE or LIMIT) |
| 1 | The values will not be written into the register |

Table 3 Effect of the configuration words within the registers

| Bit 1 | Bit 2 | Bit 3 | Bit 4 | Bit 5 | Bit 6 | Bit 7 | Bit 8 | Bit 9 | Bit 10 | Bit 11 | Bit 12 | Bit 13 | Bit 14 | Bit 15 |
|------------------------------|-------|----------|----------|------------------------|----------|------------|----------|----------|----------|----------|----------|------------------------|-------------------|--------|
| OFF-command | | | | | | | | | | | | | | |
| 1 | | | | | | | | | | | | | | |
| OPMODE register | | | | | | | | | | | | | | |
| | | BR_Range | | N _{Bit-check} | | Modulation | Sleep | | | | | X Sleep | Noise Suppression | |
| 0 | 1 | Baud1 | Baud0 | BitChk1 | BitChk0 | ASK/_FSK | Sleep4 | Sleep3 | Sleep2 | Sleep1 | Sleep0 | X _{Sleep} Std | Noise_Disable | 0 |
| Default values of Bit 3...14 | | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | |
| LIMIT register | | | | | | | | | | | | | | |
| | | Lim_min | | | | | | Lim_max | | | | | | |
| 0 | 0 | Lim_min5 | Lim_min4 | Lim_min3 | Lim_min2 | Lim_min1 | Lim_min0 | Lim_max5 | Lim_max4 | Lim_max3 | Lim_max2 | Lim_max1 | Lim_max0 | 0 |
| Default values of Bit 3...14 | | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | |

The following tables illustrate the effect of the individual configuration words. The default configuration is highlighted for each word.

BR_Range sets the appropriate baud-rate range and simultaneously defines XLim. XLim is used to define the bit-check limits T_{Lim_min} and T_{Lim_max} as shown in table 10 and table 11.

Table 4 Effect of the configuration word BR_Range

| BR_Range | | Baud-Rate Range / Extension Factor for Bit-Check Limits (XLim) |
|----------|-------|--|
| Baud1 | Baud0 | |
| 0 | 0 | BR_Range0 (application USA / Europe: BR_Range0 = 1.0 kBaud to 1.8 kBaud) (Default) XLim = 8 (Default) |
| 0 | 1 | BR_Range1 (application USA / Europe: BR_Range1 = 1.8 kBaud to 3.2 kBaud) XLim = 4 |
| 1 | 0 | BR_Range2 (application USA / Europe: BR_Range2 = 3.2 kBaud to 5.6 kBaud) XLim = 2 |
| 1 | 1 | BR_Range3 (Application USA / Europe: BR_Range3 = 5.6 kBaud to 10 kBaud) XLim = 1 |

Table 5 Effect of the configuration word N_{Bit-check}

| N _{Bit-check} | | Number of Bits to be Checked |
|------------------------|---------|------------------------------|
| BitChk1 | BitChk0 | |
| 0 | 0 | 0 |
| 0 | 1 | 3 (Default) |
| 1 | 0 | 6 |
| 1 | 1 | 9 |

Table 6 Effect of the configuration bit Modulation

| Modulation | Selected Modulation |
|------------|---------------------|
| ASK/_FSK | |
| 0 | FSK |
| 1 | ASK |

Table 7 Effect of the configuration word Sleep

| Sleep | | | | | Start Value for Sleep Counter ($T_{Sleep} = Sleep \times X_{sleep} \times 1024 \times T_{CLK}$) |
|--------|--------|--------|--------|--------|--|
| Sleep4 | Sleep3 | Sleep2 | Sleep1 | Sleep0 | |
| 0 | 0 | 0 | 0 | 0 | 0 (Receiver is continuously polling until a valid signal occurs) |
| 0 | 0 | 0 | 0 | 1 | 1 ($T_{Sleep} \approx 2.1$ ms for $X_{Sleep}=1$ and $f_{RF} = 868.3$ MHz, 1.96 ms for $f_{RF} = 915$ MHz) |
| 0 | 0 | 0 | 1 | 0 | 2 |
| 0 | 0 | 0 | 1 | 1 | 3 |
| . | . | . | . | . | . |
| . | . | . | . | . | . |
| . | . | . | . | . | . |
| 0 | 0 | 1 | 0 | 0 | 6 ($T_{Sleep} = 12.098$ ms for $f_{RF} = 868.3$ MHz, 11.76 ms for $f_{RF} = 915$ MHz) |
| . | . | . | . | . | . |
| . | . | . | . | . | . |
| . | . | . | . | . | . |
| 1 | 1 | 1 | 0 | 1 | 29 |
| 1 | 1 | 1 | 1 | 0 | 30 |
| 1 | 1 | 1 | 1 | 1 | 31 (Permanent sleep mode) |

Table 8 Effect of the configuration bit XSleep

| XSleep | Extension Factor for Sleep Time ($T_{Sleep} = Sleep \times X_{sleep} \times 1024 \times T_{CLK}$) |
|-----------|---|
| XSleepStd | |
| 0 | 1 (Default) |
| 1 | 8 |

Table 9 Effect of the configuration bit Noise Suppression

| Noise Suppression | Suppression of the Digital Noise at Pin DATA |
|-------------------|--|
| Noise_Disable | |
| 0 | Noise suppression is inactive |
| 1 | Noise suppression is active (default) |

Table 10 Effect of the configuration word Lim_min

| Lim_min *) (Lim_min < 10 is not applicable) | | | | | | Lower Limit Value for Bit Check |
|---|----------|----------|----------|----------|----------|---|
| Lim_min5 | Lim_min4 | Lim_min3 | Lim_min2 | Lim_min1 | Lim_min0 | ($T_{Lim_min} = Lim_min \times XLim \times T_{Cik}$) |
| 0 | 0 | 1 | 0 | 1 | 0 | 10 |
| 0 | 0 | 1 | 0 | 1 | 1 | 11 |
| 0 | 0 | 1 | 1 | 0 | 0 | 12 |
| . | . | . | . | . | . | |
| . | . | . | . | . | . | |
| 0 | 1 | 0 | 1 | 0 | 1 | 21 (Default) ($T_{Lim_min} = 347 \mu s$ for $f_{RF} = 868.3$ MHz and BR_Range0 $T_{Lim_min} = 329 \mu s$ for $f_{RF} = 915$ MHz and BR_Range0) |
| . | . | . | . | . | . | |
| . | . | . | . | . | . | |
| 1 | 1 | 1 | 1 | 0 | 1 | 61 |
| 1 | 1 | 1 | 1 | 1 | 0 | 62 |
| 1 | 1 | 1 | 1 | 1 | 1 | 63 |

*) Lim_min is also be used to determine the margins of the data clock control logic (see chapter 'Data Clock')

Table 11 Effect of the configuration word Lim_max

| Lim_max *) (Lim_max < 12 is not applicable) | | | | | | Upper Limit Value for Bit Check |
|---|----------|----------|----------|----------|----------|--|
| Lim_max5 | Lim_max4 | Lim_max3 | Lim_max2 | Lim_max1 | Lim_max0 | ($T_{Lim_max} = (Lim_max - 1) \times XLim \times T_{Cik}$) |
| 0 | 0 | 1 | 1 | 0 | 0 | 12 |
| 0 | 0 | 1 | 1 | 0 | 1 | 13 |
| 0 | 0 | 1 | 1 | 1 | 0 | 14 |
| . | . | . | . | . | . | |
| . | . | . | . | . | . | |
| 1 | 0 | 1 | 0 | 0 | 1 | 41 (Default) ($T_{Lim_max} = 677 \mu s$ for $f_{RF} = 868.3$ MHz and BR_Range0, $T_{Lim_max} = 642 \mu s$ for $f_{RF} = 915$ MHz and BR_Range0) |
| . | . | . | . | . | . | |
| . | . | . | . | . | . | |
| 1 | 1 | 1 | 1 | 0 | 1 | 61 |
| 1 | 1 | 1 | 1 | 1 | 0 | 62 |
| 1 | 1 | 1 | 1 | 1 | 1 | 63 |

*) Lim_max is also be used to determine the margins of the data clock control logic (see chapter 'Data Clock')

Conservation of the Register Information

The T5760/T5761 implies an integrated power-on reset and brown-out detection circuitry to provide a mechanism to preserve the RAM register information.

According to figure 30, a power-on reset (POR) is generated if the supply voltage V_S drops below the threshold voltage $V_{ThReset}$. The default parameters are programmed into the configuration registers in that condition. Once V_S exceeds $V_{ThReset}$ the POR is canceled after the minimum reset period t_{Rst} . A POR is also generated when the supply voltage of the receiver is turned on.

To indicate that condition, the receiver displays a reset marker (RM) at Pin DATA after a reset. The RM is repre-

sented by the fixed frequency f_{RM} at a 50% duty-cycle. RM can be canceled via a Low pulse t_1 at Pin DATA. The RM implies the following characteristics:

- f_{RM} is lower than the lowest feasible frequency of a data signal. By this means, RM cannot be misinterpreted by the connected μC .
- If the receiver is set back to polling mode via Pin DATA, RM cannot be canceled by accident if t_1 is applied according to the proposal in the section 'Programming the Configuration Registers'.

By means of that mechanism the receiver cannot lose its register information without communicating that condition via the reset marker RM.

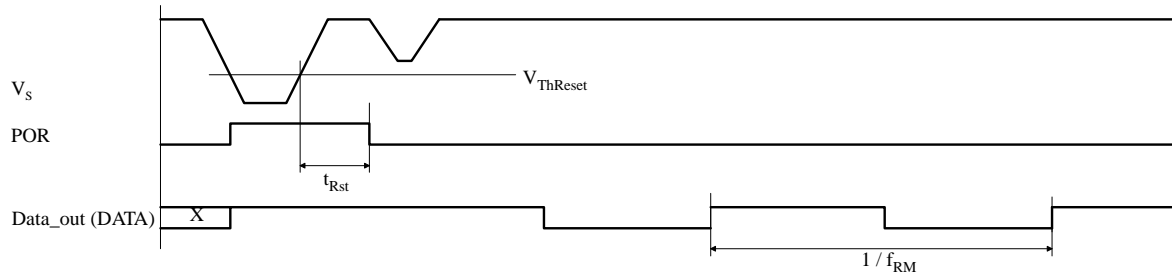


Figure 30. Generation of the power-on reset

Programming the Configuration Register

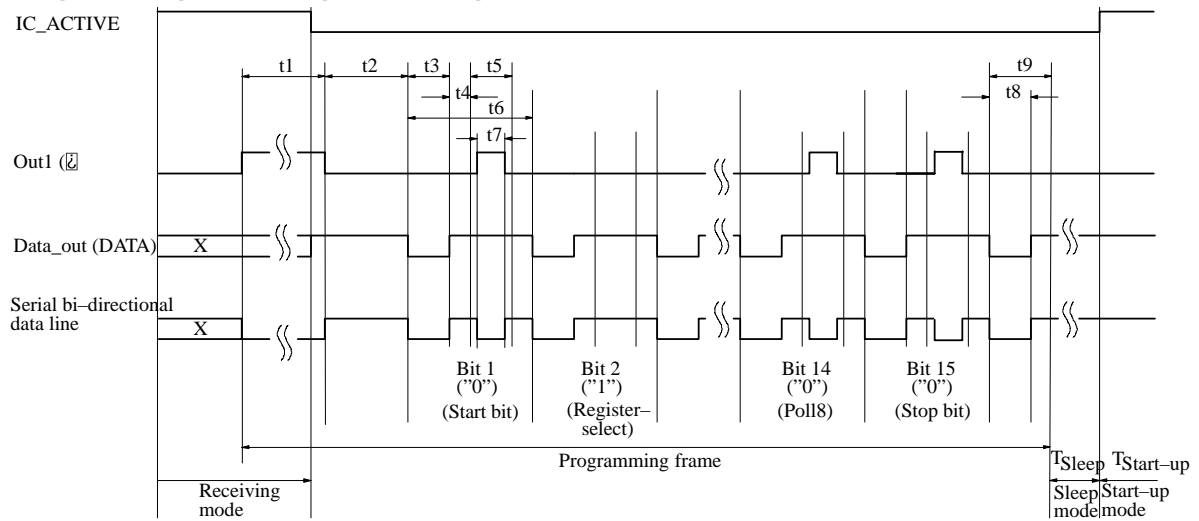


Figure 31. Timing of the register programming

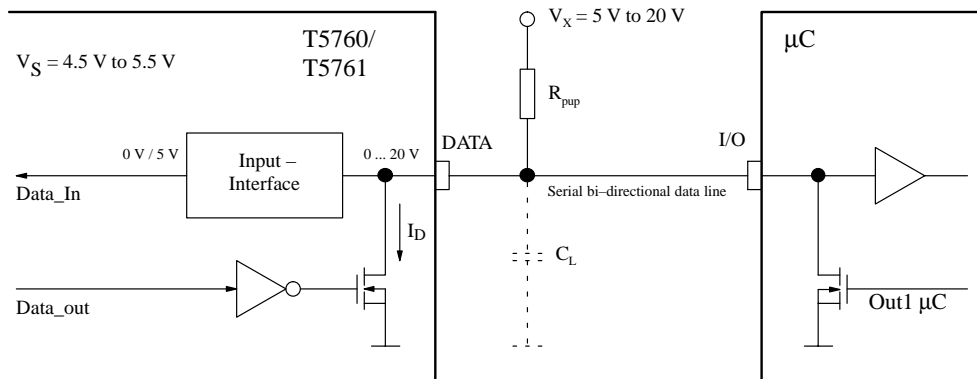


Figure 32. Data interface

The configuration registers are programmed serially via the bi-directional data line according to figure 31 and figure 32.

To start programming, the serial data line DATA is pulled to Low for the time period t_1 by the μC . When DATA has been released, the receiver becomes the master device. When the programming delay period t_2 has elapsed, it emits 15 subsequent synchronization pulses with the pulse length t_3 . After each of these pulses, a programming window occurs. The delay until the program window starts is determined by t_4 , the duration is defined by t_5 . Within the programming window, the individual bits are set. If the μC pulls down Pin DATA for the time period t_7 during t_5 , the according bit is set to '0'. If no programming pulse t_7 is issued, this bit is set to '1'. All 15 bits are subsequently programmed this way. The time frame to program a bit is defined by t_6 .

Bit 15 is followed by the equivalent time window t_9 . During this window, the equivalence acknowledge pulse t_8 (E_Ack) occurs if the just programmed mode word is equivalent to the mode word that was already stored in that register. E_Ack should be used to verify that the mode word was correctly transferred to the register. The register must be programmed twice in that case.

Programming of a register is possible both in sleep- and in active-mode of the receiver.

During programming, the LNA, LO, lowpass filter IF-amplifier and the FSK/ASK Manchester demodulator are disabled.

The programming start pulse t_1 initiates the programming of the configuration registers. If bit 1 is set to '1', it represents the OFF-command to set the receiver back to polling mode at the same time. For the length of the pro-

gramming start pulse t_1 , the following convention should be considered:

- $t_1(\text{min}) < t_1 < 5632 \times T_{\text{CLK}}$: $t_1(\text{min})$ is the minimum specified value for the relevant BR_Range

Programming respectively OFF-command is initiated if the receiver is not in reset mode. If the receiver is in reset mode, programming respectively Off-command is not initiated and the reset marker RM is still present at Pin DATA.

This period is generally used to switch the receiver to polling mode or to start the programming of a register. In reset condition, RM is not cancelled by accident.

- $t_1 > 7936 \times T_{\text{CLK}}$

Programming respectively OFF-command is initiated in any case. The registers OPMODE and LIMIT are set to the default values. RM is cancelled if present.

This period is used if the connected μC detected RM. If the receiver operates in default mode, this time period for t_1 can generally be used.

Note that the capacitive load at Pin DATA is limited.

Data Interface

The data interface (see figure 32) is designed for automotive requirements. It can be connected via the pull-up resistor R_{pup} up to 20V and is short-circuit-protected.

The applicable pull-up resistor R_{pup} depends on the load capacity C_L at Pin DATA and the selected BR_range (see table 12). More detailed information about the calculation of the maximum load capacity at Pin DATA is given in the 'Application Hints T5743N'.

Table 12 Applicable R_{pup}

| | BR_range | Applicable R_{pup} |
|-------------------------|----------|----------------------------------|
| $C_L \leq 1\text{nF}$ | B0 | 1.6 k Ω to 47 k Ω |
| | B1 | 1.6 k Ω to 22 k Ω |
| | B2 | 1.6 k Ω to 12 k Ω |
| | B3 | 1.6 k Ω to 5.6 k Ω |
| $C_L \leq 100\text{pF}$ | B0 | 1.6 k Ω to 470 k Ω |
| | B1 | 1.6 k Ω to 220 k Ω |
| | B2 | 1.6 k Ω to 120 k Ω |
| | B3 | 1.6 k Ω to 56 k Ω |

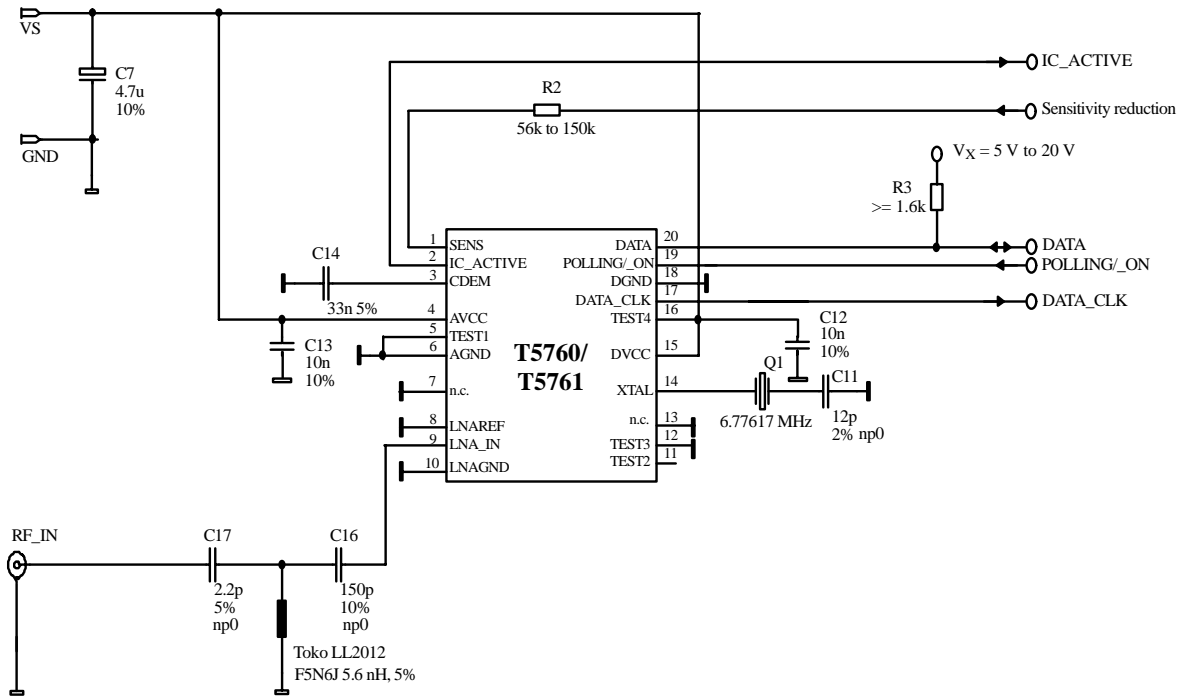


Figure 33. Application circuit: $f_{RF} = 868.3$ MHz without SAW filter

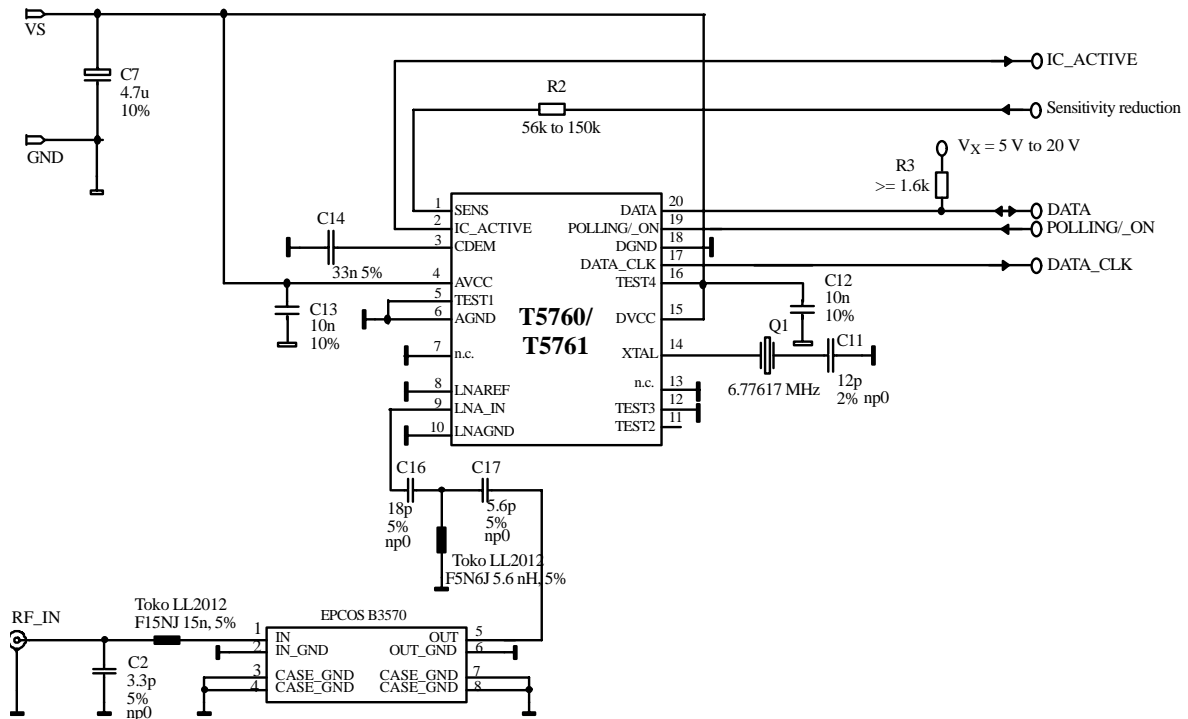


Figure 34. Application circuit: $f_{RF} = 868.3$ MHz with SAW filter

Absolute Maximum Ratings

| Parameter | Symbol | Min. | Max. | Unit |
|---|---------------|------|------|------|
| Supply voltage | V_S | | 6 | V |
| Power dissipation | P_{tot} | | 1000 | mW |
| Junction temperature | T_j | | 150 | °C |
| Storage temperature | T_{stg} | -55 | +125 | °C |
| Ambient temperature | T_{amb} | -40 | +105 | °C |
| Maximum input level, input matched to 50 Ω | P_{in_max} | | 10 | dBm |

Thermal Resistance

| Parameter | Symbol | Value | Unit |
|------------------|------------|-------|------|
| Junction ambient | R_{thJA} | 100 | K/W |

Electrical Characteristics

All parameters refer to GND, $T_{amb} = -40^\circ\text{C}$ to $+105^\circ\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^\circ\text{C}$)

| Parameter | Test Conditions | Symbol | $f_{RF} = 868.3\text{ MHz}$ 6.77617 MHz Osc. | | | $f_{RF} = 915\text{ MHz}$ 7.14063 MHz Osc. | | | Variable Oscillator | | | Unit | |
|---|---|-----------------|--|---|--|--|---|--|---|--|---|---|----------------------|
| | | | Min. | Typ. | Max. | Min. | Typ. | Max. | Min. | Typ. | Max. | | |
| Basic clock cycle of the digital circuitry | | | | | | | | | | | | | |
| Basic clock cycle | | T_{Clk} | 2.0662 | | 2.0662 | 1.9607 | | 1.9607 | $1/f_{XTO}/14$ | | $1/f_{XTO}/14$ | μs | |
| Extended basic clock cycle | BR_Range0 | T_{XClk} | 16.53 | | 16.53 | 15.69 | | 15.69 | $8 \times T_{Clk}$ | | $8 \times T_{Clk}$ | μs | |
| | BR_Range1 | | 8.26 | | 8.26 | 7.84 | | 7.84 | $4 \times T_{Clk}$ | | $4 \times T_{Clk}$ | μs | |
| | BR_Range2 | | 4.13 | | 4.13 | 3.92 | | 3.92 | $2 \times T_{Clk}$ | | $2 \times T_{Clk}$ | μs | |
| | BR_Range3 | | 2.07 | | 2.07 | 1.96 | | 1.96 | $1 \times T_{Clk}$ | | $1 \times T_{Clk}$ | μs | |
| Polling mode | | | | | | | | | | | | | |
| Sleep time see figures 11, 20 and 33 | Sleep and XSleep are defined in the OPMODE register | T_{Sleep} | $Sleep \times X_{Sleep} \times 1024 \times 2.0662$ | | $Sleep \times X_{Sleep} \times 1024 \times 2.0662$ | $Sleep \times X_{Sleep} \times 1024 \times 1.9607$ | | $Sleep \times X_{Sleep} \times 1024 \times 1.9607$ | $Sleep \times X_{Sleep} \times 1024 \times T_{Clk}$ | | $Sleep \times X_{Sleep} \times 1024 \times T_{Clk}$ | ms | |
| Start-up time see figures 11 and 12 | BR_Range0 | $T_{Startup}$ | 1852 | | 1852 | 1758 | | 1758 | 896.5 | | 896.5 | μs | |
| | BR_Range1 | | 1059 | | 1059 | 1049 | | 1049 | 512.5 | | 512.5 | μs | |
| | BR_Range2 | | 1059 | | 1059 | 1049 | | 1049 | 512.5 | | 512.5 | μs | |
| | BR_Range3 | | 662 | | 662 | 628 | | 628 | $320.5 \times T_{Clk}$ | | $320.5 \times T_{Clk}$ | μs | |
| Time for bit check see figure 11 | Average bit-check time while polling, no RF applied, see figures 15 and 16 BR_Range0 BR_Range1 BR_Range2 BR_Range3 | $T_{Bit-check}$ | | 0.45 | | | 0.45 | | | | | ms | |
| | | | | 0.24 | | | 0.24 | | | | | ms | |
| | | | | 0.14 | | | 0.14 | | | | | | ms |
| | | | | 0.08 | | | 0.08 | | | | | | ms |
| | Bit-check time for a valid input signal f_{sig} , see figure 12 NBit-check = 0 NBit-check = 3 NBit-check = 6 NBit-check = 9 | $T_{Bit-check}$ | | $3/f_{sig}$ $6/f_{sig}$ $9/f_{sig}$ | | $3.5/f_{sig}$ $6.5/f_{sig}$ $9.5/f_{sig}$ | $3/f_{sig}$ $6/f_{sig}$ $9/f_{sig}$ | | $3.5/f_{sig}$ $6.5/f_{sig}$ $9.5/f_{sig}$ | $1 \times T_{XClk}$ $3/f_{sig}$ $6/f_{sig}$ $9/f_{sig}$ | | $1 \times T_{Clk}$ $3.5/f_{sig}$ $6.5/f_{sig}$ $9.5/f_{sig}$ | ms ms ms ms |

Electrical Characteristics (continued)

All parameters refer to GND, $T_{amb} = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$)

| Parameter | Test Conditions | Symbol | $f_{RF} = 868.3\text{ MHz}$ 6.77617 MHz Osc. | | | $f_{RF} = 915\text{ MHz}$ 7.14063 MHz Osc. | | | Variable Oscillator | | | Unit |
|--|--|--------------------|---|-------|-------------------------------|---|-------|-------------------------------|--|------|--|--|
| | | | Min. | Typ. | Max. | Min. | Typ. | Max. | Min. | Typ. | Max. | |
| Receiving mode | | | | | | | | | | | | |
| Intermediate frequency | | f_{IF} | | 1.000 | | | 1.054 | | $f_{XTO} \times 128 / 867.3$ | | | MHz |
| Baud-rate range | BR_Range0 BR_Range1 BR_Range2 BR_Range3 | BR_Range | 1.0 1.8 3.2 5.6 | | 1.8 3.2 5.6 10.0 | 1.054 1.89 3.38 5.9 | | 1.89 3.38 5.9 10.5 | BR_Range0 $\times 2\ \mu\text{s} / T_{Clk}$ BR_Range1 $\times 2\ \mu\text{s} / T_{Clk}$ BR_Range2 $\times 2\ \mu\text{s} / T_{Clk}$ BR_Range3 $\times 2\ \mu\text{s} / T_{Clk}$ | | | kBaud kBaud kBaud kBaud |
| Minimum time period between edges at Pin DATA See figures 18 and 19 (With the exception of parameter T_{Pulse}) | BR_Range = BR_Range0 BR_Range1 BR_Range2 BR_Range3 | t_{DATA_min} | 165.3 82.6 41.3 20.7 | | 165.3 82.6 41.3 20.7 | 156.8 78.4 39.2 19.6 | | 156.8 78.4 39.2 19.6 | $10 \times T_{XClk}$ $10 \times T_{XClk}$ $10 \times T_{XClk}$ $10 \times T_{XClk}$ | | $10 \times T_{XClk}$ $10 \times T_{XClk}$ $10 \times T_{XClk}$ $10 \times T_{XClk}$ | μs μs μs μs |
| Maximum Low period at Pin DATA See figure 16 | BR_Range = BR_Range0 BR_Range1 BR_Range2 BR_Range3 | $t_{DATA_L_max}$ | 2149 1074 537 269 | | 2149 1074 537 269 | 2139 1020 510 255 | | 2139 1020 510 255 | $130 \times T_{XClk}$ $130 \times T_{XClk}$ $130 \times T_{XClk}$ $130 \times T_{XClk}$ | | $130 \times T_{XClk}$ $130 \times T_{XClk}$ $130 \times T_{XClk}$ $130 \times T_{XClk}$ | μs μs μs μs |
| Delay to activate the start-up mode See figure 22 | | Ton1 | 19.6 | | 21.7 | 18.6 | | 20.6 | $9.5 \times T_{Clk}$ | | $10.5 \times T_{Clk}$ | μs |
| OFF-command at Pin POLLING/_ON See figure 21 | | Ton2 | 16.5 | | | 15.6 | | | $8 \times T_{Clk}$ | | | μs |
| Delay to activate the sleep mode See figure 21 | | Ton3 | 17.6 | | 19.6 | 16.6 | | 18.6 | $8.5 \times T_{Clk}$ | | $9.5 \times T_{Clk}$ | μs |
| Pulse on Pin DATA at the end of a data stream See figure 30 | BR_Range = BR_Range0 BR_Range1 BR_Range2 BR_Range3 | T_{Pulse} | 16.5 8.3 4.1 2.1 | | 16.5 8.3 4.1 2.1 | 15.69 7.84 3.92 1.96 | | 15.69 7.84 3.92 1.96 | $8 \times T_{Clk}$ $4 \times T_{Clk}$ $2 \times T_{Clk}$ $1 \times T_{Clk}$ | | $8 \times T_{Clk}$ $4 \times T_{Clk}$ $2 \times T_{Clk}$ $1 \times T_{Clk}$ | μs μs μs μs |

Electrical Characteristics (continued)

All parameters refer to GND, $T_{amb} = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$)

| Parameter | Test Conditions | Symbol | $f_{RF} = 868.3\text{ MHz}$ 6.77617 MHz Osc. | | | $f_{RF} = 915\text{ MHz}$ 7.14063 MHz Osc. | | | Variable Oscillator | | | Unit |
|--|--|--------------------|---|------|-------|---|------|-----------------------|---------------------------------|------|---------------------------------|---------------|
| | | | Min. | Typ. | Max. | Min. | Typ. | Max. | Min. | Typ. | Max. | |
| Configuration of the receiver (see figures 17 and 33) | | | | | | | | | | | | |
| Frequency of the reset marker | Frequency is stable within 50 ms after POR | f_{RM} | 118.2 | | 118.2 | 124.5 | | 124.5 | $\frac{1}{4096 \times T_{Clk}}$ | | $\frac{1}{4096 \times T_{Clk}}$ | Hz |
| Programming start pulse | BR_Range = | t1 | | | | | | | | | | |
| | BR_Range0 | | 3355 | | 11637 | 3184 | | 11043 | $1624 \times T_{Clk}$ | | $5632 \times T_{Clk}$ | μs |
| | BR_Range1 | | 2273 | | 11637 | 2168 | | 11043 | $1100 \times T_{Clk}$ | | $5632 \times T_{Clk}$ | μs |
| | BR_Range2 | | 1731 | | 11637 | 1643 | | 11043 | $838 \times T_{Clk}$ | | $5632 \times T_{Clk}$ | μs |
| | BR_Range3 | | 1461 | | 11637 | 1386 | | 11043 | $707 \times T_{Clk}$ | | $5632 \times T_{Clk}$ | μs |
| Programming delay period | after POR | | 16397 | | | 15560 | | $7936 \times T_{Clk}$ | | | μs | |
| Programming delay period | | t2 | 795 | | 797 | 754 | | 756 | $384.5 \times T_{Clk}$ | | $385.5 \times T_{Clk}$ | μs |
| Synchronization pulse | | t3 | 264 | | 264 | 251 | | 251 | $128 \times T_{Clk}$ | | $128 \times T_{Clk}$ | μs |
| Delay until of the program window starts | | t4 | 131 | | 131 | 125 | | 125 | $63.5 \times T_{Clk}$ | | $63.5 \times T_{Clk}$ | μs |
| Programming window | | t5 | 529 | | 529 | 502 | | 502 | $256 \times T_{Clk}$ | | $256 \times T_{Clk}$ | μs |
| Time frame of a bit | | t6 | 1058 | | 1058 | 1004 | | 1004 | $512 \times T_{Clk}$ | | $512 \times T_{Clk}$ | μs |
| Programming pulse | | t7 | 132 | | 529 | 125 | | 502 | $64 \times T_{Clk}$ | | $256 \times T_{Clk}$ | μs |
| Equivalent acknowledge pulse: E_Ack | | t8 | 264 | | 264 | 251 | | 251 | $128 \times T_{Clk}$ | | $128 \times T_{Clk}$ | μs |
| Equivalent time window | | t9 | 533 | | 533 | 506 | | 506 | $258 \times T_{Clk}$ | | $258 \times T_{Clk}$ | μs |
| OFF-bit programming window | | t10 | 929 | | 929 | 881 | | 881 | $449.5 \times T_{Clk}$ | | $449.5 \times T_{Clk}$ | μs |
| Data clock (see figures 27 and 28) | | | | | | | | | | | | |
| Minimum delay time between edge @ DATA and DATA_CLK | BR_Range = | t_{Delay2} | | | | | | | | | | |
| | BR_Range0 | | 0 | | 16.5 | 0 | | 16.7 | 0 | | $1 \times T_{XClk}$ | μs |
| | BR_Range1 | | 0 | | 8.3 | 0 | | 7.8 | 0 | | $1 \times T_{XClk}$ | μs |
| | BR_Range2 | | 0 | | 4.1 | 0 | | 3.9 | 0 | | $1 \times T_{XClk}$ | μs |
| | BR_Range3 | | 0 | | 2.1 | 0 | | 1.96 | 0 | | $1 \times T_{XClk}$ | μs |
| Pulswidth of negative pulse @ Pin DATA_CLK | BR_Range = | $t_{p_DATA_CLK}$ | | | | | | | | | | |
| | BR_Range0 | | 66.1 | | 66.1 | 63 | | 63 | $4 \times T_{XClk}$ | | $4 \times T_{XClk}$ | μs |
| | BR_Range1 | | 33.0 | | 33.0 | 31 | | 31 | $4 \times T_{XClk}$ | | $4 \times T_{XClk}$ | μs |
| | BR_Range2 | | 16.5 | | 16.5 | 15.7 | | 15.7 | $4 \times T_{XClk}$ | | $4 \times T_{XClk}$ | μs |
| | BR_Range3 | | 8.3 | | 8.3 | 7.8 | | 7.8 | $4 \times T_{XClk}$ | | $4 \times T_{XClk}$ | μs |

Electrical Characteristics (continued)

All parameters refer to GND, $T_{amb} = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$)

| Parameters | Test Conditions / Pins | Symbol | Min. | Typ. | Max. | Unit |
|---|---|-------------------|---------|--|------------|--|
| Current consumption | Sleep mode (XTO and polling logic active) | $I_{S_{off}}$ | | 170 | 276 | μA |
| | IC active (start-up-, bit check-, receiving mode) Pin DATA = H | $I_{S_{on}}$ | | 7.8 | 9.9 | mA |
| | FSK ASK | | | 7.4 | 9.6 | mA |
| LNA, mixer, polyphase lowpass and IF amplifier (input matched according to figure 33 referred to RF_{IN}) | | | | | | |
| Third-order intercept point | LNA/ mixer/ IF amplifier | IIP3 | | -16 | | dBm |
| LO spurious emission | Required according to I-ETS 300220 | $I_{S_{LORF}}$ | | -70 | -57 | dBm |
| System noise figure | With power matching $ S_{11} < -10\text{ dB}$ | NF | | 5 | | dB |
| LNA_IN input impedance | @ 868.3 MHz @ 915 MHz | $Z_{i_{LNA_IN}}$ | | $200 \parallel 3.2$ $200 \parallel 3.2$ | | $\Omega \parallel \text{pF}$ $\Omega \parallel \text{pF}$ |
| 1 dB compression point | | $IP_{1\text{dB}}$ | | -25 | | dBm |
| Image rejection | Within the complete image band | | | 30 | 20 | dB |
| Maximum input level | $BER \leq 10^{-3}$, FSK mode ASK mode | P_{in_max} | | | -10 -10 | dBm dBm |
| Local oscillator | | | | | | |
| Operating frequency range VCO | T5760 | f_{VCO} | 866 | | 871 | MHz |
| | T5761 | f_{VCO} | 900 | | 929 | MHz |
| Phase noise local oscillator | $f_{osc} = 867.3\text{ MHz}$ @ 10 MHz | L (fm) | | -140 | -130 | dBc/Hz |
| Spurious of the VCO | @ $\pm f_{XTO}$ | | | -55 | -45 | dBc |
| XTO pulling | XTO pulling, appropriate load capacitance must be connected to XTAL, crystal $C_M = 7\text{ fF}$ $f_{XTAL} = 6.77617\text{ MHz}$ (EU) $f_{XTAL} = 7.14063\text{ MHz}$ (US) | f_{XTO} | -30 ppm | f_{XTAL} | +30 ppm | MHz |
| Series resonance resistor of the crystal | Parameter of the supplied crystal | R_S | | | 120 | Ω |
| Static capacitance at Pin XTAL to GND | Parameter of the supplied crystal and board parasitics | C_0 | | | 6.5 | pF |

Electrical Characteristics (continued)

All parameters refer to GND, $T_{amb} = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$)

| Parameters | Test Conditions / Pins | Symbol | Min. | Typ. | Max. | Unit |
|--|---|--|---|--------------------------------|--|--|
| Analog signal processing (input matched according to figure 33 referred to RF _{IN}) | | | | | | |
| Input sensitivity ASK | ASK (level of carrier) BER $\leq 10^{-3}$, 100% Mod $f_{in} = 868.3\text{ MHz} / 915\text{ MHz}$ $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$ $f_{IF} = 950\text{ kHz} / 1\text{ MHz}$ BR_Range0 BR_Range1 BR_Range2 BR_Range3 | P_{Ref_ASK} | -110 -108.5 -108 -106 | -112 -100.5 -110 -108 | -114 -112.5 -108 -110 | dBm dBm dBm dBm |
| Sensitivity variation ASK for the full operating range compared to $T_{amb} = 25^{\circ}\text{C}$, $V_S = 5\text{ V}$ | $f_{in} = 868.3\text{ MHz} / 915\text{ MHz}$ $f_{IF} = 950\text{ kHz} / 1\text{ MHz}$ $P_{ASK} = P_{Ref_ASK} + \Delta P_{Ref}$ | ΔP_{Ref} | +2.5 | | -1.0 | dB |
| Sensitivity variation ASK for full operating range including IF filter compared to $T_{amb} = 25^{\circ}\text{C}$, $V_S = 5\text{ V}$, | $f_{in} = 868.3\text{ MHz} / 915\text{ MHz}$ $f_{IF} = 950\text{ kHz} / 1\text{ MHz}$ $f_{IF} - 210\text{ kHz}$ to $+210\text{ kHz}$ $f_{IF} - 270\text{ kHz}$ to $+270\text{ kHz}$ $P_{ASK} = P_{Ref_ASK} + \Delta P_{Ref}$, | ΔP_{Ref} | +5.5 +7.5 | | -1.5 -1.5 | dB dB |
| Input sensitivity FSK | BER $\leq 10^{-3}$ $f_{in} = 868.3\text{ MHz} / 915\text{ MHz}$ $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$ $f_{IF} = 950\text{ kHz} / 1\text{ MHz}$ BR_Range0 df = +/- 16 kHz to 28 kHz df = +/- 10 kHz to +/- 100 kHz BR_Range1 df = +/- 16 kHz to 28 kHz df = +/- 10 kHz to +/- 100 kHz BR_Range2 df = +/- 18 kHz to 31 kHz df = +/- 13 kHz to +/- 100 kHz BR_Range3 df = +/- 25 kHz to 44 kHz df = +/- 20 kHz to +/- 100 kHz | P_{Ref_FSK} P_{Ref_FSK} P_{Ref_FSK} P_{Ref_FSK} | -103 -101 -101 -99 -99.5 -97.5 -97.5 -95.5 | -106 -104 -102.5 | -107.5 -107.5 -105.5 -105.5 -104 | dBm dBm dBm dBm dBm dBm |
| Sensitivity variation FSK for the full operating range compared to $T_{amb} = 25^{\circ}\text{C}$, $V_S = 5\text{ V}$ | $f_{in} = 868.3\text{ MHz} / 915\text{ MHz}$ $f_{IF} = 950\text{ kHz} / 1\text{ MHz}$ $P_{FSK} = P_{Ref_FSK} + \Delta P_{Ref}$ | ΔP_{Ref} | +3 | | -1.5 | dB |
| Sensitivity variation FSK for the full operating range including IF filter compared to $T_{amb} = 25^{\circ}\text{C}$, $V_S = 5\text{ V}$ | $f_{in} = 868.3\text{ MHz} / 915\text{ MHz}$ $f_{IF} = 950\text{ kHz} / 1\text{ MHz}$ $f_{IF} - 150\text{ kHz}$ to $+150\text{ kHz}$ $f_{IF} - 200\text{ kHz}$ to $+200\text{ kHz}$ $f_{IF} - 260\text{ kHz}$ to $+260\text{ kHz}$ $P_{FSK} = P_{Ref_FSK} + \Delta P_{Ref}$ | ΔP_{Ref} | +6 +8 +11 | | -2 -2 -2 | dB dB dB |

Electrical Characteristics (continued)

All parameters refer to GND, $T_{amb} = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$)

| Parameters | Test Conditions / Pins | Symbol | Min. | Typ. | Max. | Unit | |
|--|---|------------------|-----------|-------|------|------------------|-----|
| S/N ratio to suppress inband noise signals. Noise signals may have any modulation scheme | ASK mode | SNR_{ASK} | | 10 | 12 | dB | |
| | FSK mode | SNR_{FSK} | | 2 | 3 | dB | |
| Dynamic range RSSI ampl. | | DR_{RSSI} | | 60 | | dB | |
| Lower cut-off frequency of the data filter | $f_{cu_DF} = \frac{1}{2 \times \pi \times 30\text{k}\Omega \times \text{CDEM}}$ CDEM = 33 nF | f_{cu_DF} | 0.11 | 0.16 | 0.20 | kHz | |
| Recommended CDEM for best performance | BR_Range0 (default) | CDEM | | 39 | | nF | |
| | BR_Range1 | | 22 | | nF | | |
| | BR_Range2 | | 12 | | nF | | |
| | BR_Range3 | | 8.2 | | nF | | |
| Edge-to-edge time period of the input data signal for full sensitivity | BR_Range0 (default) | t_{ee_sig} | 270 | | 1000 | μs | |
| | BR_Range1 | | 156 | | 560 | μs | |
| | BR_Range2 | | 89 | | 320 | μs | |
| | BR_Range3 | | 50 | | 180 | μs | |
| Upper cut-off frequency data filter | Upper cut-off frequency programmable in 4 ranges via a serial mode word BR_Range0 (default) | f_u | 2.8 | 3.4 | 4.0 | kHz | |
| | | | BR_Range1 | 4.8 | 6.0 | 7.2 | kHz |
| | | | BR_Range2 | 8.0 | 10.0 | 12.0 | kHz |
| | | | BR_Range3 | 15.0 | 19.0 | 23.0 | kHz |
| Reduced sensitivity | R_{Sense} connected from Pin Sens to V_S , input matched according to figure 33, $f_{IN} = 868.3\text{ MHz}/915\text{ MHz}$ | | | | | dBm (peak level) | |
| | $R_{Sense} = 56\text{ k}\Omega$ | P_{Ref_Red} | -63 | -68 | -73 | dBm | |
| | $R_{Sense} = 100\text{ k}\Omega$ | P_{Ref_Red} | -72 | -77 | -82 | dBm | |
| Reduced sensitivity variation over full operating range | $R_{Sense} = 56\text{ k}\Omega$ | ΔP_{Red} | 5 | 0 | 0 | dB | |
| | $R_{Sense} = 100\text{ k}\Omega$ | | 5 | 0 | 0 | dB | |
| | $P_{Red} = P_{Ref_Red} + \Delta P_{Red}$ | | | | | | |
| Reduced sensitivity variation for different values of R_{Sense} | Values relative to $R_{Sense} = 56\text{ k}\Omega$ | | | | | | |
| | $R_{Sense} = 56\text{ k}\Omega$ | ΔP_{Red} | | 0 | | dB | |
| | $R_{Sense} = 68\text{ k}\Omega$ | ΔP_{Red} | | -3.5 | | dB | |
| | $R_{Sense} = 82\text{ k}\Omega$ | ΔP_{Red} | | -6.0 | | dB | |
| | $R_{Sense} = 100\text{ k}\Omega$ | ΔP_{Red} | | -9.0 | | dB | |
| | $R_{Sense} = 120\text{ k}\Omega$ | ΔP_{Red} | | -11.0 | | dB | |
| | $R_{Sense} = 150\text{ k}\Omega$ | ΔP_{Red} | | -13.5 | | dB | |
| $P_{Red} = P_{Ref_Red} + \Delta P_{Red}$ | | | | | | | |
| Threshold voltage for reset | | $V_{ThRESET}$ | 1.95 | 2.8 | 3.75 | V | |

Electrical Characteristics (continued)

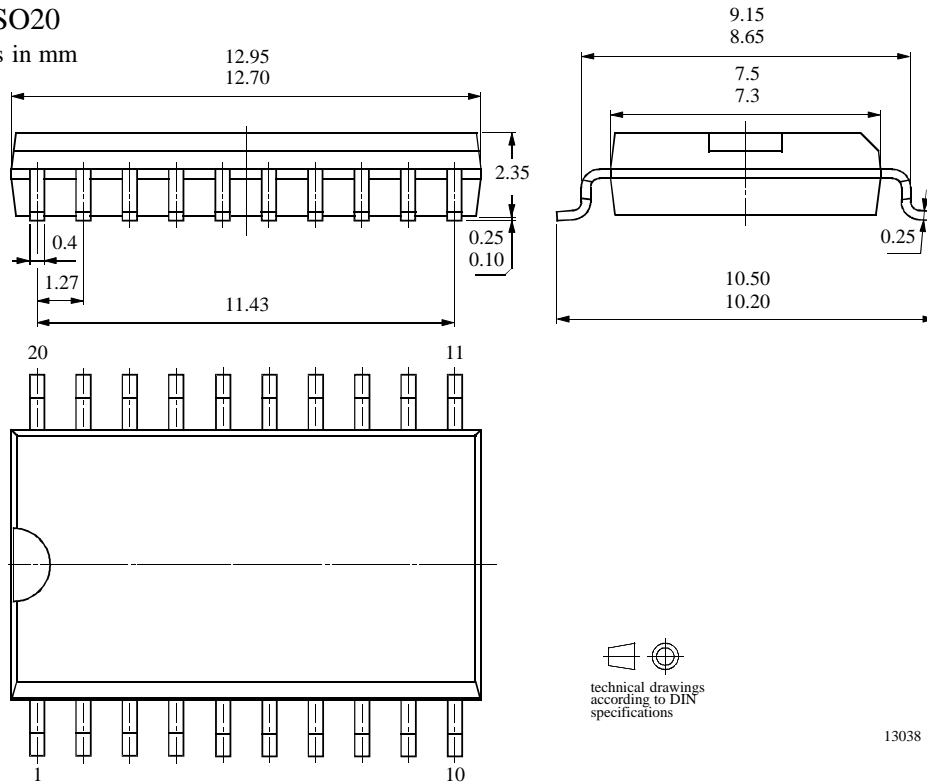
All parameters refer to GND, $T_{amb} = -40^{\circ}\text{C}$ to $+105^{\circ}\text{C}$, $V_S = 4.5\text{ V}$ to 5.5 V , $f_0 = 868.3\text{ MHz}$ and $f_0 = 915\text{ MHz}$, unless otherwise specified. (For typical values: $V_S = 5\text{ V}$, $T_{amb} = 25^{\circ}\text{C}$)

| Parameters | Test Conditions / Pins | Symbol | Min. | Typ. | Max. | Unit |
|--|--------------------------------------|---------------|----------------------|-----------------------|-------------------|--------------------|
| Digital ports | | | | | | |
| Data output | | | | | | |
| – Saturation voltage Low | $I_{ol} \leq 12\text{ mA}$ | V_{ol} | | 0.35 | 0.8 | V |
| | $I_{ol} = 2\text{ mA}$ | V_{ol} | | 0.08 | 0.3 | V |
| – max voltage @ Pin DATA | | V_{oh} | | | 20 | V |
| – quiescent current | $V_{oh} = 20\text{ V}$ | I_{qu} | | | 20 | μA |
| – short-circuit current | $V_{ol} = 0.8\text{ to }20\text{ V}$ | I_{ol_lim} | 13 | 30 | 45 | mA |
| – ambient temp. in case of permanent short-circuit | $V_{oh} = 0\text{V to }20\text{ V}$ | t_{amb_sc} | | | 85 | $^{\circ}\text{C}$ |
| Data input | | | | | | |
| – Input voltage Low | | V_{ll} | | | $0.35 \times V_S$ | V |
| – Input voltage High | | V_{ich} | $0.65 \times V_S$ | | | V |
| DATA_CLK output | | | | | | |
| – Saturation voltage Low | IDATA_CLK = 1mA | V_{ol} | $V_S - 0.4\text{ V}$ | 0.1 | 0.4 | V |
| – Saturation voltage High | IDATA_CLK = -1mA | V_{oh} | | $V_S - 0.15\text{ V}$ | | V |
| IC_ACTIVE output | | | | | | |
| – Saturation voltage Low | IIC_ACTIVE = 1mA | V_{ol} | $V_S - 0.4\text{ V}$ | 0.1 | 0.4 | V |
| – Saturation voltage High | IIC_ACTIVE = -1mA | V_{oh} | | $V_S - 0.15\text{ V}$ | | V |
| POLLING/_ON input | | | | | | |
| – Low level input voltage | Receiving mode | V_{ll} | | | $0.2 \times V_S$ | V |
| – High level input voltage | Polling mode | V_{lh} | $0.8 \times V_S$ | | | V |
| MODE input | | | | | | |
| – Low level input voltage | Division factor = 10 | V_{ll} | | | $0.2 \times V_S$ | V |
| – High level input voltage | Division factor = 14 | V_{lh} | $0.8 \times V_S$ | | | V |
| TEST input | | | | | | |
| – Low level input voltage | Test input must always be set to Low | V_{ll} | | | $0.2 \times V_S$ | V |

Package Information

Package SO20

Dimensions in mm



technical drawings
according to DIN
specifications

13038

Ozone Depleting Substances Policy Statement

It is the policy of **Atmel Germany GmbH** to

1. Meet all present and future national and international statutory requirements.
2. Regularly and continuously improve the performance of our products, processes, distribution and operating systems with respect to their impact on the health and safety of our employees and the public, as well as their impact on the environment.

It is particular concern to control or eliminate releases of those substances into the atmosphere which are known as ozone depleting substances (ODSs).

The Montreal Protocol (1987) and its London Amendments (1990) intend to severely restrict the use of ODSs and forbid their use within the next ten years. Various national and international initiatives are pressing for an earlier ban on these substances.

Atmel Germany GmbH has been able to use its policy of continuous improvements to eliminate the use of ODSs listed in the following documents.

1. Annex A, B and list of transitional substances of the Montreal Protocol and the London Amendments respectively
2. Class I and II ozone depleting substances in the Clean Air Act Amendments of 1990 by the Environmental Protection Agency (EPA) in the USA
3. Council Decision 88/540/EEC and 91/690/EEC Annex A, B and C (transitional substances) respectively.

Atmel Germany GmbH can certify that our semiconductors are not manufactured with ozone depleting substances and do not contain such substances.

We reserve the right to make changes to improve technical design and may do so without further notice.

Parameters can vary in different applications. All operating parameters must be validated for each customer application by the customer. Should the buyer use Atmel Wireless & Microcontrollers products for any unintended or unauthorized application, the buyer shall indemnify Atmel Wireless & Microcontrollers against all claims, costs, damages, and expenses, arising out of, directly or indirectly, any claim of personal damage, injury or death associated with such unintended or unauthorized use.

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