

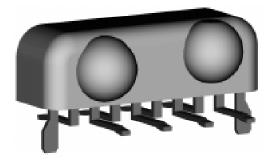
IBM31T1100A Integrated Infrared Transceiver Module

Highlights

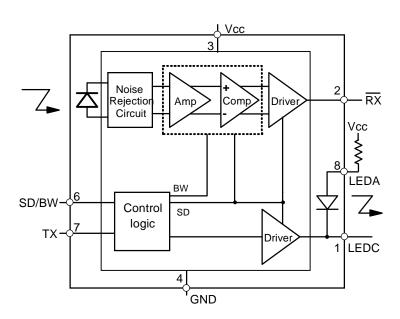
- IrDA 1.1, HP-SIR and Sharp ASK compliant
- Supports IrDA data rates up to 4 Mbps
- Low profile (height = 5.6 mm max.)
- Minimum external components
- On-chip LED protection circuit
- Low power consumption
- 5 V Supply Voltage
- Complete differential receiver design
- · Ambient light and noise rejection circuitry
- Shutdown pin for power management
- Programmable bandwidth control
- Compatible with all major Super I/Os

General Description

The IBM31T1100A is a multi-mode integrated infrared (IR) transceiver module for data communication systems. The transceiver supports IrDA speeds up to 4 Mbps, HP-SIR and Sharp ASK modes. Integrated into this tiny package is a photodiode, LED and analog transceiver ASIC to provide a total solution in a single package. A current limiting resistor in series with the LED and a Vcc bypass capacitor are the only external components required to implement a complete transceiver.

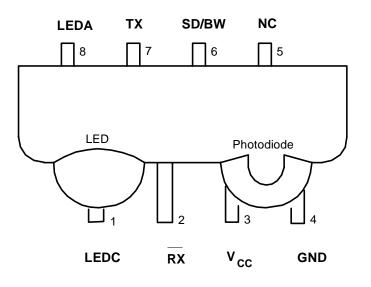


Package



Block Diagram

Pin Assignments and Descriptions



| Pin | Pin Name | Description | I/O | Active |
|-----|--|--|-----|--------|
| 1 | LEDC | Indicates the state of the internal LED cathode. Normally not connected. | 0 | Low |
| 2 | RX | Indicates received serial data. It is a push-pull CMOS driver capable of driving a standard CMOS or TTL load. No external pull-up or pull-down resistor is required. May switch indeterminately when the IBM31T1100A is transmitting. | 0 | Low |
| 3 | V_{cc} Connect to +5 V power supply. Place a 1.0-10 μ F ceramic bypass capacitor as close as possible to this pin. | | | |
| 4 | GND | Connect to ground of the power supply. A solid ground plane is recommended for proper operation. | | |
| 5 | NC | This pin is reserved for special application use only. No signal should be connected to this pin. | | |
| 6 | SD/BW | This CMOS input is used to put the IBM31T1100A in shutdown mode. Nominal supply current draw in this mode is 35 μ A versus 5 mA in normal mode. Together with the TX input, this pin also sets the receiver bandwidth. If TX is low when SD/BW transitions from high to low, the receiver bandwidth is optimized for operation up to 1.2 Mbps. If TX is high when SD/BW transitions from high to low, the receiver bandwidth is optimized for operation at 4 Mbps. | Ι | High |
| 7 | ТХ | Used to transmit serial data when SD/BW is low. This CMOS input controls the LED driver. An on-chip protection circuit disables the LED driver if TX is high for more than 60 µsec. This pin is also used to program the bandwidth of the receiver. See SD/BW pin description. | Ι | High |
| 8 | LEDA | Connect this input to Vcc through a resistor to set the proper LED current. Add an external LED in series to increase output intensity if required. | Ι | |
| | Guide Pins (not shown above) | Two through-hole guide pins provide mechanical stability during board mounting. They also improve heat conduction when the part is in operation. | | |

NOTE: The IBM31T1100A is pin and plug compatible with the Temic TFDS6000D.

IBM31T1100A

Electrical and Timing Specifications

Absolute Maximum Ratings

| Symbol | Parameter | Min | Тур | Max | Unit | Condition |
|------------------|---------------------------|-------|-----|-----------------------|------|-----------------------------|
| Vcc | Supply Voltage Range | - 0.5 | | 6 | V | |
| PD | Power Dissipation | | | 450 | mW | |
| TJ | Junction Temperature | | | 125 | °C | |
| | Storage Temperature Range | - 25 | | 85 | °C | |
| | Soldering Temperature | | | 240 | °C | See application notes |
| I _{LED} | LED Current | | | 0.8 | А | <2 µs, t _{on} <10% |
| | Voltage at Any Pin | - 0.5 | | V _{cc} + 0.5 | V | |

Recommended Operating Conditions

| Symbol | Parameter | Min | Тур | Max | Unit | Condition |
|-----------------|-----------------------------|-----|-----|-----|------|-----------|
| V _{CC} | Supply Voltage | 4.5 | 5 | 5.5 | V | |
| T _A | Operating Temperature Range | 0 | | 70 | °C | |

DC Electrical Characteristics

 $T_A\!=\!0$ - 70 °C, $V_{CC}\!=\!5$ V $\pm\,10$ %, unless otherwise specified

| Symbol | Parameter | Min | Тур | Max | Unit | Condition |
|-----------------|---|----------------------|-----|------|------|------------------------------------|
| Icc | Dynamic Supply Current | | 5 | 7 | mA | SD = 0 V |
| I _{CC} | Standby Supply Current | | 35 | 100 | uA | $SD = V_{CC} - 0.5, SC = NC$ |
| ILED | Repetitive Pulsed LED Current | | | 0.55 | А | $< 60 \ \mu s, t_{on} \le 25 \ \%$ |
| Vol | \overrightarrow{RX} Output Voltage Low @ $I_{OL} = 2.5 \text{ mA}$ | | 0.3 | 0.5 | V | |
| V _{OH} | \overrightarrow{RX} Output Voltage High @ -I _{OH} = 2.5 mA | V _{CC} -0.5 | | | V | |
| V _{IL} | Input Voltage Low (TX, SD/BW) | 0 | | 0.8 | V | |
| V _{IH} | Input Voltage High (TX) | 3.0 | | | V | |
| V _{IH} | Input Voltage High (SD/BW) | V _{CC} -0.5 | | | V | |
| IL | Input Leakage Current | -10 | | +10 | uA | |
| CI | Input Capacitance | | | 5 | pF | |

AC Electrical Characteristics

$T_A\!=\!0$ - 70 °C, $V_{CC}\!=\!5$ V \pm 10 %, unless otherwise specified

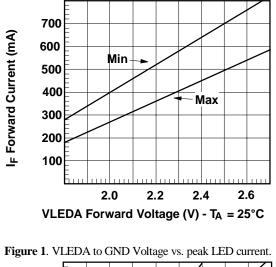
| Symbol | Parameter | Min | Тур | Max | Unit | Condition |
|----------------------|---|-----|-----|-----|------|--|
| t _R | RX Rise Time | 10 | | 40 | ns | $R_{LED} = 2.0 \text{ K}\Omega, C = 50 \text{ pF}$ |
| t _F | RX Fall Time | 10 | | 40 | ns | $R_{LED} = 2.0 \text{ K}\Omega, C = 50 \text{ pF}$ |
| ts | TX Setup Time to SD/BW Low | 200 | | | ns | |
| t _H | TX Hold Time from SD/BW Low | 200 | | | ns | |
| $t_{\rm PW}$ | RX Pulse Width | 0.8 | | 20 | us | 9.6 kbps |
| $t_{\rm PW}$ | RX Pulse Width | 100 | | 500 | ns | 1.2 Mbps |
| $t_{\rm PW}$ | RX Pulse Width | 60 | | 165 | ns | 4 Mbps |
| $t_{\rm PW}$ | RX Pulse Width | 185 | | 290 | ns | 4 Mbps double pulse |
| t _D | Output Delay @ $E_e = 40 \text{ mW/cm}^2$ | | 1 | 2 | us | \leq 1.2 Mbps |
| t _L | Latency | | | 120 | us | |
| t _{RXEN} | RX Valid After Shutdown | | | 60 | us | |
| t _{DIS_LED} | LEDC Inactive After TX High | | | 60 | us | |

Optical Characteristics

 $T_A = 0$ - 70 °C, $V_{CC} = 5 V \pm 10\%$, unless otherwise specified

| Symbol | Parameter | Min | Тур | Max | Unit | Condition |
|-------------------|---|------|-------|--------|------------------|---|
| E _{emin} | Minimum Detection Irradiance (SIR mode) | | 0.025 | 0.035 | Wm ⁻² | 9.6 - 115 kbps |
| E _{emin} | Minimum Detection Irradiance | | 0.035 | 0.05 | Wm ⁻² | 1.2 Mbps |
| E _{emin} | Minimum Detection Irradiance | | 0.07 | 0.08 | Wm ⁻² | 4 Mbps |
| E _{emax} | Maximum Detection Irradiance | 5000 | | | Wm ⁻² | All speeds |
| | | 100 | 140 | 320(1) | mW/sr | Tx = High, SD = Low, R_{LED} = 5.6 Ω |
| Ie | Output Radiant Intensity | | | | | V _{CC} =5.0, α=0 °, α=±15 °, T _A =25 °C |
| | | | | 0.4 | uW/sr | Tx=Low or SD=High, R_{LED} =5.6 Ω |
| | | | | | | V _{CC} =5.0, α=0 °, α=±15 °, T _A =25 °C |
| α | Output Radiant Intensity Half Angle | | ±24 | | 0 | |
| λ_{P} | Peak Wavelength | 880 | | 900 | nm | |
| | Optical Overshoot | | | 25 | % | |

1. Maximum intensity specified for class 1 operation of IEC 825-1



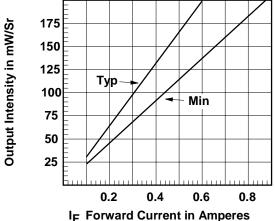


Figure 3. Output Intensity vs. Current

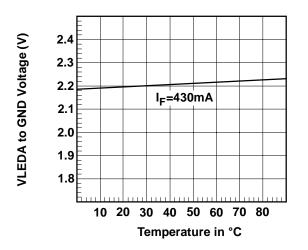


Figure 5. VLEDA to GND Voltage vs. Temperature.

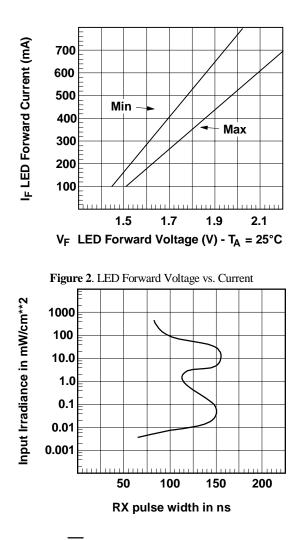


Figure 4. RX pulse width vs. Irradiance - 4 Mbps mode.

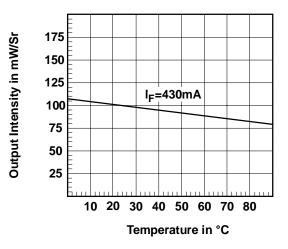


Figure 6. Output Intensity vs. Temperature

Timing Diagrams

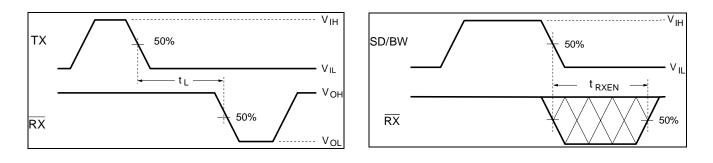


Figure 7. Latency Timing

Figure 8. RX valid after Shutdown.

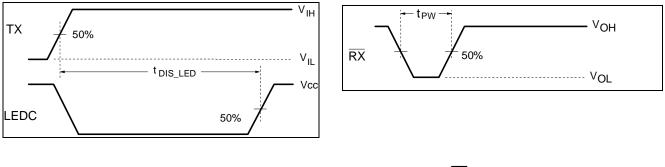
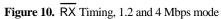
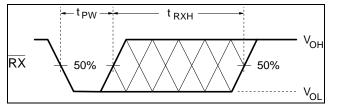
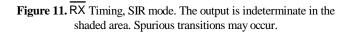


Figure 9. LED Protection Timing







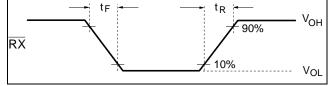


Figure 12. RX Rise and Fall timing measurements.

Programming the Receiver Bandwidth

The IBM31T1100A powers on with the upper limit of the receiver bandwidth set to 1.2 Mbps operation. To set the bandwidth for operation at 4 Mbps, apply timings as shown in Figure 14 to the SD/BW and the TX inputs. Note that the internal LED driver is disabled when SD/BW is active and is not enabled until the next rising edge of TX. This ensures that the LED(s) will not be active during bandwidth adjustment. It is recommended that the SD/BW pin be connected to GND if bandwidth adjustment and shutdown mode are not used.

To switch the IBM31T1100A from the default state to 4 Mbps and vice versa, the programming specifications are as follows:

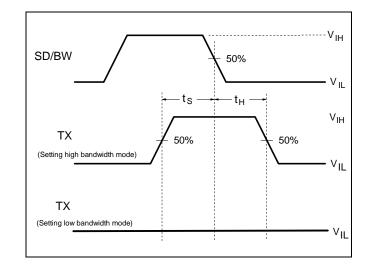


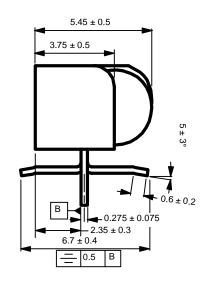
Figure 13. Bandwidth Programming

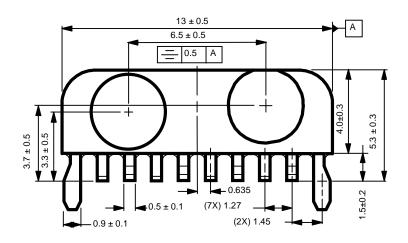
Setting the receiver to 9.6 kbps-to-1.2 Mbps mode

- 1. Set the SD/BW input to logic high.
- 2. Ensure that the TX input is at logic low. Wait $t_S \ge 200$ ns.
- Set the SD/BW to logic low. (This high-to-low transition latches the state of TX, which determines the receiver bandwidth.)
- 4. Ensure that the TX input remains low for $t_H \ge 200$ ns. The receiver is now in low bandwidth mode, which is the optimal setting for data rates from 9.6 kbps to 1.2 Mbps.

Setting the receiver to 4 Mbps mode

- 1. Set the SD/BW input to logic high.
- 2. Set the TX input to logic high. Wait $t_S \ge 200$ ns.
- Set the SD/BW to logic low. (This high-to-low transition latches the state of TX, which determines the receiver bandwidth.)
- 4. After waiting $t_H \ge 200$ ns, set the TX input to logic low. The receiver is now in high bandwidth mode, the optimal setting for 4 Mbps operation.





Dimensions in mm.

Package Dimensions

Revision History

The following changes have been made in the specifications from the IBM31T1100 data sheet.

- 1. Improved Irradiance values have been updated.
- 2. LED protection circuit has been added.
- 3. The $\overline{\mathsf{RX}}$ rise time specification is 40 ns instead of 35 ns.
- 4. 200K internal pull-down resistor has been removed from the SD/BW pin.
- 5. Output Intensity and $\overline{\mathsf{RX}}$ pulse width graphs have been updated.

Ordering Information

Order Part Number IBM31T1100A

Qty/Reel 750 Pieces

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GH45-5286-01