This version: Aug. 1998

# **OKI** Semiconductor **ML7000-01/02/03 ML7001-01/02/03**

Single Rail CODEC

## **GENERAL DESCRIPTION**

The ML7000/ML7001 are single-channel CMOS CODEC LSI devices for voice signals ranging from 300 to 3400 Hz with filters for A/D and D/A conversion.

Designed especially for a single-power supply and low-power applications, the devices are optimized for ISDN terminals, digital wireless systems, and digital PBXs.

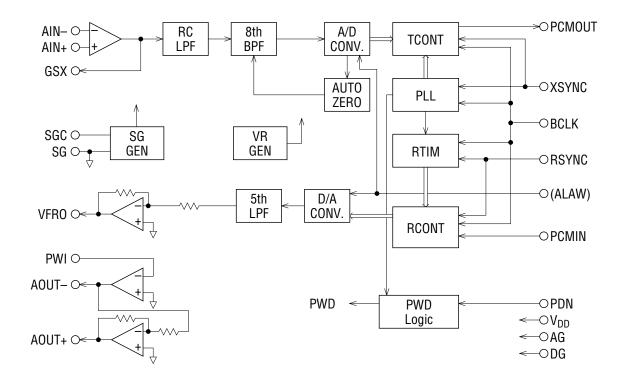
The devices use the same transmission clocks as those used in the MSM7507.

With the differential analog signal outputs which can drive 60  $\Omega$  load, the devices can directly drive a handset receiver.

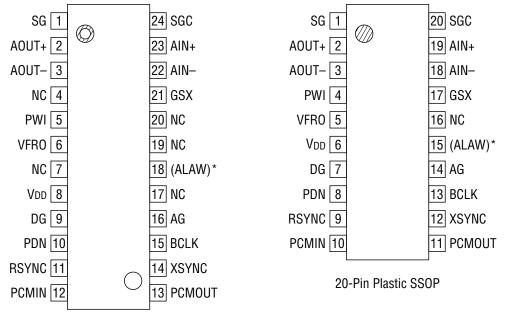
## FEATURES

- Single power supply: +5 V (ML7000-xx)
  - +3 V (ML7001-xx)
- Low power consumption Operating mode: 25 mW Typ.  $V_{DD} = 5.0 \text{ V} (\text{ML7000-xx})$ 20 mW Typ.  $V_{DD} = 3.0 \text{ V} (\text{ML7001-xx})$ Power-down mode: 0.05 mW Typ.  $V_{DD} = 5.0 \text{ V} (\text{ML7000-xx})$ 0.03 mW Typ.  $V_{DD} = 3.0 \text{ V} (\text{ML7001-xx})$
- Conforms to ITU-T Companding law ML7000-01/ML7001-01: μ/A-law pin selectable ML7000-02/ML7001-02: μ-law ML7000-03/ML7001-03: A-law
- Transmission characteristics conform to ITU-T G.714
- Short frame sync timing operation
- Built-in PLL eliminates a master clock
- Serial data rate: 64/96/128/192/200/256/384/512/ 768/1024/1536/1544/2048 kHz
- Adjustable transmit gain
- Adjustable receive gain
- Built-in reference voltage supply
- Package options: 24-pin plastic SOP (SOP24-P-430-1.27-K) (Product name: ML7000-01MA/ML7001-01MA) (Product name: ML7000-02MA/ML7001-02MA)
   20-pin plastic SSOP (SSOP20-P-250-0.95-K) (Product name: ML7000-01MB/ML7001-03MA) (Product name: ML7000-02MB/ML7001-01MB) (Product name: ML7000-02MB/ML7001-02MB) (Product name: ML7000-03MB/ML7001-03MB)

# **BLOCK DIAGRAM**



# **PIN CONFIGURATION (TOP VIEW)**



24-Pin Plastic SOP

\* The ALAW pin is only supported by the ML7000-01MA/ML7000-01MB/ML7001-01MA/ML7001-01MB.

NC : No connect pin

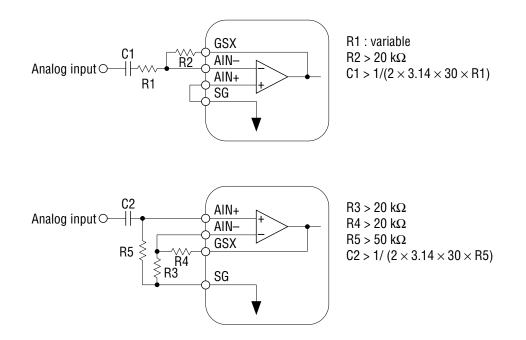
## PIN FUNCTIONAL DESCRIPTION

#### AIN+, AIN-, GSX

Transmit analog input and transmit level adjustment.

AIN+ is a non-inverting input to the op-amp; AIN– is an inverting input to the op-amp; GSX is connected to the output of the op-amp.

The level adjustment should be performed using any of the methods shown below. During power-saving and power-down modes, the GSX output is at AG voltage.



#### AG

Analog ground.

#### VFRO

Receive filter output.

The output signal has an amplitude of 2.4  $V_{PP}$  for ML7000-xx and 2.0  $V_{PP}$  for ML7001-xx above and below the signal ground voltage (SG) when the digital signal of +3 dBm0 is input to PCMIN and can drive a load of 20 k $\Omega$  or more.

For driving a load of less than 20 k $\Omega$ , connect a resistor of 20 k $\Omega$  or more between the pins VFRO and PWI.

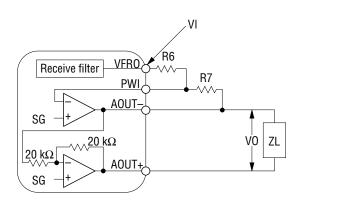
During power-saving or power-down mode, the VFRO output is at an SG level.

When adjusting the receive signal on the basis of frequency characteristics, refer to the Frequency Characteristics Adjustment Circuit.

## PWI, AOUT+, AOUT-

PWI is connected to the inverting input of the receive driver.

The receive driver output is connected to the AOUT– pin. Therefore, the receive level can be adjusted with the pins VFRO, PWI, and AOUT–. During power-saving or power down-mode, the outputs of AOUT+ and AOUT– are in a high impedance state. The output of AOUT+ is inverted with respect to the output of AOUT–. Since these outputs provide differential drive of an impedance of 1.2 k $\Omega$ , they can directly be connected to a handset using a piezoelectric earphone or a line transformer. Refer to the application example.



 $\begin{array}{l} \mathsf{R6} > 20 \; \mathsf{k}\Omega \\ \mathsf{ZL} > 1.2 \; \mathsf{k}\Omega \end{array}$ 

Gain = V0/VI =  $2 \times R7/R6 \le 2$ 

#### $V_{DD}$

Power supply for +5 V (ML7000-xx) or +3 V (ML7001-xx)

## PCMIN

PCM data input.

A serial PCM data input to this pin is converted to an analog signal in synchronization with the RSYNC signal and BCLK signal.

The data rate of PCM is equal to the frequency of the BCLK signal.

PCM signal is shifted in at the falling edge of the BCLK signal and latched into the internal register when shifted by eight bits.

The start of the PCM data (MSD) is identified at the rising edge of RSYNC.

#### BCLK

Shift clock signal input for the PCMIN and PCMOUT signals.

The frequency, equal to the data rate, is 64, 96, 128, 192, 256, 384, 512, 768, 1024, 1536, 1544, or 2048 kHz. Setting this signal to logic "1" or "0" drives both transmit and receive circuits to the power saving state.

## RSYNC

Receive synchronizing signal input.

Eight required bits are selected from serial PCM signals on the PCMIN pin by the receive synchronizing signal.

Signals in the receive section are synchronized by this synchronizing signal. This signal must be synchronized in phase with the BCLK. The frequency should be  $8 \text{ kHz} \pm 50 \text{ ppm}$  to guarantee the AC characteristics which are mainly the frequency characteristics of the receive section.

However, if the frequency characteristic of an applied system is not specified exactly, this device can operate in the range of 6 to 9 kHz, but the electrical characteristics in this specification are not guaranteed.

## XSYNC

Transmit synchronizing signal input.

The PCM output signal from the PCMOUT pin is output in synchronization with this signal. This synchronizing signal triggers the PLL and synchronizes all timing signals of the transmit section. This synchronizing signal must be synchronized in phase with BCLK.

The frequency should be 8 kHz ±50 ppm to guarantee the AC characteristics which are mainly the frequency characteristics of the transmit section. However, if the frequency characteristic of an applied system is not specified exactly, this device operates in the range of 6 to 9 kHz, but the electrical characteristics in this specification are not guaranteed.

Setting this signal to logic "1" or "0" drives both transmit and receive circuits to the power saving state.

#### DG

Ground for the digital signal circuits.

This ground is separate from the analog signal ground AG. The DG pin must be connected to the AG pin on the printed circuit board to make a common analog ground AG.

## PDN

Power down control signal.

A logic "0" level drives both transmit and receive circuits to a power down state.

## PCMOUT

PCM signal output.

Synchronizing with the rising edge of the BCLK signal, the PCM output signal is output from MSD in a sequential order.

MSD may be output at the rising edge of the XSYNC signal, based on the timing between BCLK and XSYNC.

This pin is in a high impedance state except during 8-bit PCM output. It is also in a high impedance state during power saving or power down mode.

A pull-up resistor must be connected to this pin because its output is configured as an open drain. This device is compatible with the ITU-T recommendation on coding law and output coding format.

The ML7000-03 (A-law) and ML7001-03 (A-law) output the character signal, inverting the even bits.

		PCMIN/PCMOUT														
Input/Output Level		N	1L7(	000-	<b>02 (</b> μ	-lav	N)		ML7000-03 (A-law)							
		<b>ML7001-02 (</b> μ-law)					ML7001-03 (A-law)									
+Full scale	MSD							LSD	MSD							LSD
+ruii scale	1	0	0	0	0	0	0	0	1	0	1	0	1	0	1	0
+0	1	1	1	1	1	1	1	1	1	1	0	1	0	1	0	1
-0	0	1	1	1	1	1	1	1	0	1	0	1	0	1	0	1
–Full scale	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0

## SG

Signal ground voltage output. The output voltage is 1/2 of the power supply voltage. The output drive current capability is  $\pm 300 \,\mu\text{A}$  for ML7000-xx and  $\pm 200 \,\mu\text{A}$  for ML7001-xx. This pin provides the SG level for CODEC peripherals. This output voltage level is undefined during power-saving or power-down mode.

## SGC

Used to generate the signal ground voltage level by connecting a bypass capacitor. Connect a  $0.1 \,\mu\text{F}$  capacitor with excellent high frequency characteristics between the AG pin and the SGC pin.

#### ALAW

Control signal input of the companding law selection.

Only the ML7000-01MA/ML7000-01MB/ML7001-01MA/ML7001-01MB have this pin. The CODEC will operate in the  $\mu$ -law when this pin is at a logic "0" level and the CODEC will operate in the A-law when this pin is at a logic "1" level. The CODEC operates in the  $\mu$ -law if the pin is left open, since the pin is internally pulled down.

## **ABSOLUTE MAXIMUM RATINGS**

Parameter	Symbol	Condition	Rating	Unit
Power Supply Voltage	V <sub>DD</sub>	—	-0.3 to +7	V
Analog Input Voltage	V <sub>AIN</sub>	—	-0.3 to V <sub>DD</sub> + 0.3	V
Digital Input Voltage	V <sub>DIN</sub>	—	-0.3 to V <sub>DD</sub> + 0.3	V

## **RECOMMENDED OPERATING CONDITIONS**

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit	
Power Supply Voltage	V		4.75	5.00	5.25	V	
Power Supply voltage	V <sub>DD</sub>		2.70	3.00	3.30	v	
Operating Temperature	Та	—	-30	+25	+85	°C	
Analog Input Voltage	V	Connect AIN– and GSX	—	—	2.4	V	
Analog Input Voltage	V <sub>AIN</sub>	Connect AIN- and GSA	—		1.2	V <sub>PP</sub>	
High Level Input Voltage	V		2.2	—	V <sub>DD</sub>	V	
nigh Level niput voltage	V <sub>IH</sub>	XSYNC, RSYNC, BCLK,	$0.45 \times V_{DD}$	—	V <sub>DD</sub>	v	
Low Level Input Voltage	VIL	PCMIN, PDN, ALAW	0	—	0.8	V	
Low Level input voltage	VIL		0		0.16×V <sub>DD</sub>	V	
			64, 96, 12	28, 192, 20	00, 256,		
Clock Frequency	F <sub>C</sub>	BCLK	384, 512,	768, 1024	, 1536,	kHz	
			1544, 204	18			
	г		6.0	8.0	9.0	kHz	
Sync Pulse Frequency	F <sub>S</sub>	XSYNC, RSYNC (-40 to +75 °C)	6.0	8.0	10.0		
Clock Duty Ratio	D <sub>C</sub>	BCLK	40	50	60	%	
Digital Input Rise Time	t <sub>lr</sub>	XSYNC, RSYNC, BCLK,	_		50	ns	
Digital Input Fall Time	t <sub>lf</sub>	PCMIN, PDN	—	_	50	ns	
Transmit Sync Pulse Setting Time	t <sub>CX</sub>	BCLK $\rightarrow$ XSYNC, See Fig. 1	50	—	_	ns	
	t <sub>XC</sub>	XSYNC→BCLK, See Fig. 1	50	_	—	ns	
XSYNC Setup Time	t <sub>XS</sub>	—	50	_	—	ns	
XSYNC Hold Time	t <sub>XH</sub>	—	50	—	—	ns	
Pagaiya Suna Dulag Satting Tima	t <sub>CR</sub>	BCLK $\rightarrow$ RSYNC, See Fig. 1	50	_	_	ns	
Receive Sync Pulse Setting Time	t <sub>RC</sub>	RSYNC $\rightarrow$ BCLK, See Fig. 1	50	_	—	ns	
RSYNC Setup Time	t <sub>RS</sub>	—	50	_	—	ns	
RSYNC Hold Time	t <sub>RH</sub>	—	50	_	—	ns	
PCMIN Setup Time	t <sub>DS</sub>	—	50	—	—	ns	
PCMIN Hold Time	t <sub>DH</sub>	_	50		—	ns	
Digital Output Load	R <sub>DL</sub>	Pull-up resistor	0.5	—	_	kΩ	
Digital Output Load	C <sub>DL</sub>				100	pF	
Applog Input Allowable DC Offect	V	Transmit gain stage, Gain = 0 dB	-10		+10	mV	
Analog Input Allowable DC Offset	V <sub>off</sub>	Transmit gain stage, Gain = +20 dB	-100		+100	mV	
Allowable Jitter Width	_	XSYNC, RSYNC, BCLK			1000	ns	

# **ELECTRICAL CHARACTERISTICS**

## **DC** and Digital Interface Characteristics

(ML7001-xx: $V_{DD} = 2.7 V \text{ to } 3.3 V$ , Ta = -30 to +85°C)
(ML7000-xx: $V_{DD} = +5.0 \text{ V} \pm 5\%$ , Ta = -30 to +85°C)

$(\text{IVIL} / 000-XX: V_{\text{DD}} = +5.0 \text{ V} \pm 5\%, \text{ Ia} = -30 \text{ to} +85^{\circ}\text{C})$										
Parameter	Symbol	Condition		Min.	Тур.	Max.	Unit			
	1	Operating mode $V_{DD} = 5.0 V$ — 5.0		5.0	12.0	m۸				
	I <sub>DD1</sub>	No signal	V <sub>DD</sub> = 3.0 V	—	6.5	10.0	mA			
Power Supply Current		Power-saving mo	de, PDN = 1,	<u> </u>	1.5	4.0	mA			
Fower Supply Current	I <sub>DD2</sub>	$\text{XSYNC} \rightarrow \text{OFF}$	—	2.0	8.0	IIIA				
	I <sub>DD3</sub>	Power-down moo BCLK OFF	—	0.01	0.05	mA				
Lligh Lovel Input Veltage	V		2.2	—	V <sub>DD</sub>	V				
High Level Input Voltage	VIH		$0.45 \times V_{DD}$		V <sub>DD</sub>					
Low Level Input Voltage	V		0.0		0.8	V				
	V <sub>IL</sub>		0.0		0.16×V <sub>DD</sub>					
High Level Input Leakage Current	I <sub>IH</sub>			—		2.0	μA			
High Level Input Leakage Current	I <sub>IH2</sub>	ALAW		—	—	30.0	μA			
Low Level Input Leakage Current	١ <sub>١L</sub>			_		0.5	μA			
Digital Output Low Voltage	V <sub>OL</sub>	Pull-up resistor =	500 Ω	0.0	0.2	0.4	V			
Digital Output Leakage Current	I <sub>0</sub>				10	μA				
Input Capacitance	CIN				5		рF			

(ML7001-xx:  $V_{DD} = 2.7 V \text{ to } 3.3 V$ , Ta = -30 to +85°C)

## **Transmit Analog Interface Characteristics**

(ML7000-xx: V <sub>DD</sub> = +5.0 V ±5%, Ta = -30 to +									
Symbol	Condition	Min.	Тур.	Max.	Unit				
R <sub>INX</sub>	AIN+, AIN–	10	_		MΩ				
R <sub>LGX</sub>	GSX with respect to SG	20	_		kΩ				
C <sub>LGX</sub>		_	_	30	pF				
V		-1.2	_	+1.2	VOn				
VOGX		-0.7	—	+0.7	V0p				
V <sub>OSGX</sub>	Gain = 1	-20	_	+20	mV				
	R <sub>INX</sub> R <sub>LGX</sub> C <sub>LGX</sub> V <sub>OGX</sub>	Symbol  Condition    RINX  AIN+, AIN–    RLGX  GSX with respect to SG    CLGX  VOGX	Symbol  Condition  Min.    R <sub>INX</sub> AIN+, AIN-  10    R <sub>LGX</sub> GSX with respect to SG  20    C <sub>LGX</sub> V <sub>OGX</sub> 1.2	SymbolConditionMin.Typ. $R_{INX}$ AIN+, AIN-10 $R_{LGX}$ GSX with respect to SG20 $C_{LGX}$ $$ $V_{0GX}$ $-0.7$	$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$				

Values above the dotted line are for ML7000-xx; those below, for ML7001-xx.

#### **Receive Analog Interface Characteristics**

(ML7001-xx:  $V_{DD} = 2.7 V \text{ to } 3.3 V$ , Ta = -30 to +85°C) (ML7000-xx:  $V_{DD} = +5.0 V \pm 5\%$ , Ta = -30 to +85°C)

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit	
Input Resistance	RINPW	PWI	10	_		MΩ	
	R <sub>LVF</sub>	VFRO with respect to SG	20	_	—	kΩ	
Output Load Resistance	D	AOUT+, AOUT- (each) with	0.6			ko	
	R <sub>LAO</sub>	respect to SG	0.6			kΩ	
Output Lood Consolitopoo	CLVF	vf VFRO			30	pF	
Output Load Capacitance	CLAO	AOUT+, AOUT-	—	_	50	pF	
	V	VFR0, $R_L$ = 20 k $\Omega$ with	-1.2	—	+1.2		
Qutaut Appalituda	V <sub>OVF</sub>	respect to SG	-1.0		+1.0		
Output Amplitude	V	AOUT+, AOUT-, $R_L$ = 0.6 k $\Omega$	-1.3		+1.3	V0p	
	V <sub>OAO</sub>	with respect to SG	-1.0		+1.0	1	
	V <sub>OSVF</sub>	VFRO with respect to SG	-100		+100	mV	
Offset Voltage	N	AOUT+, AOUT-, Gain = 1 with	100		. 100		
	Vosao	respect to SG	-100		+100	mV	

#### **AC Characteristics**

			I	$\frac{1}{1} = 0 \text{ KHZ},$	$v_{DD} = +5.$	0 V ±5%, T	a = -30 10	+03 0)
Parameter	Symbol	Freq. (Hz)	Level (dBm0)	Condition	Min.	Тур.	Max.	Unit
	Loss T1	60			20	26		_
	Loss T2	300	_		-0.15	+0.07	+0.2	
Transmit Frequency Response	Loss T3	1020	0			Reference		dB
	Loss T4	2020			-0.15	-0.04	+0.2	UD
	Loss T5	3000			-0.15	+0.07	+0.2	
	Loss T6	3400			0	0.4	0.8	
	Loss R1	300		-	-0.15	-0.03	+0.2	
	Loss R2	1020				Reference		
Receive Frequency Response	Loss R3	2020	0		-0.15	0.00	+0.2	dB
	Loss R4	3000			-0.15	+0.05	+0.2	
	Loss R5	3400			0	0.54	0.8	
	SD T1		3		35	43		
Transmit Signal to Distortion Ratio	SD T2		0	-	35	41		- - - dB
	с <b>т</b> то	1020	-30		35.0	38.0	_	
	SD T3			*4	34.0	38.0		
	сп т <i>1</i>		40	*1	26.0	31.0	_	
	SD T4		-40		26.0	30.0		1
			45	]	24.0	25.0	_	1
	SD T5		-45			25.0		1
	SD R1		3		36	43		- - - dB -
	SD R2		0		36	41		
			20		36.0	40.0	_	
Descrive Circulate Distantian Datis	SD R3	1000	-30	*1	35.0	40.0		
Receive Signal to Distortion Ratio		1020	-40		25.0	32.0		
	SD R4				26.0	32.0		
			45	] [	25.0	27.0		
	SD R5		-45			27.0		
	GT T1		3		-0.3	+0.01	+0.3	
	GT T2		-10	]		Reference		]
Transmit Gain Tracking	GT T3	1020	-40	]	-0.3	-0.05	+0.3	dB
	GT T4		-50	]	-0.6	-0.05	+0.6	
	GT T5		-55		-1.2	-0.08	+1.2	
	GT R1		3		-0.3	-0.06	+0.3	
	GT R2		-10	1		Reference		1
Receive Gain Tracking	GT R3	1020	-40	1	-0.3	+0.08	+0.3	dB
	GT R4		-50		-0.6	+0.12	+0.6	-
	GT R5		-55		-1.2	+0.15	+1.2	1

 $\begin{array}{ll} (ML7001\text{-}xx: \ F_S = 8 \ \text{kHz}, \ V_{DD} = 2.7 \ \text{V to } 3.3 \ \text{V}, \ Ta = -30 \ \text{to } +85^\circ\text{C}) \\ (ML7000\text{-}xx: \ F_S = 8 \ \text{kHz}, \ V_{DD} = +5.0 \ \text{V} \ \pm5\%, \ Ta = -30 \ \text{to } +85^\circ\text{C}) \end{array}$ 

\*1 Psophometric filter is used.

<b>AC Characteristics</b>	(Continued)
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(ML7001-xx: $F_S = 8 \text{ kHz}$ , $V_{DD} = 2.7 \text{ V}$ to 3.3 V, $Ta = -30 \text{ to } +85^{\circ}\text{C}$ )	
(ML7000-xx: $F_S = 8 \text{ kHz}$ , $V_{DD} = +5.0 \text{ V} \pm 5\%$ , $Ta = -30 \text{ to } +85^{\circ}\text{C}$ )	

		· · ·		0		,		/
Parameter	Symbol	Freq. (Hz)	Level (dBm0)	Condition	Min.	Тур.	Max.	Unit
				AIN = SG		-73.0	-66.0	
	Nidle T	_	_	*1 *2	—	-69.5	-65.0	
Idle Channel Noise				*1 *2	_	-78.0	-71.0	dBm0p
	NidleR	_		^1^2		-75.0	-65.0	
Absolute Level (Initial Difference)				V <sub>DD</sub> = 5.0 V, Ta = 25°C	0.58	0.6007	0.622	
	AV T	1020	0	V <sub>DD</sub> = 3.0 V, Ta = 25°C	0.338	0.35	0.362	Vrms
				*0	0.58	0.6007	0.622	1
	AV R			*3	0.483	0.5	0.518	
Absolute Level	AV Tt	V <sub>DD</sub> = 5 V ±5	5%, Ta = -30	to 85°C *3	-0.2	_	0.2	
(Deviation of Temperature and Power)	AV Rt	V <sub>DD</sub> = 2.7 to	3.3 V, Ta = –	30 to 85°C *3	-0.2	_	0.2	dB
Absolute Delay	Td	1020	0	A to A BCLK = 64 kHz	_	_	0.6	ms
	t <sub>GD</sub> T1	500				0.19	0.75	ms
	t <sub>GD</sub> T2	600			_	0.11	0.35	
Transmit Group Delay	t <sub>GD</sub> T3	1000	0	*4	_	0.02	0.125	
	t <sub>GD</sub> T4	2600			_	0.05	0.125	
	t <sub>GD</sub> T5	2800			_	0.07	0.75	
	t <sub>GD</sub> R1	500			_	0.00	0.75	
	t <sub>GD</sub> R2	600	]			0.00	0.35	ms
Receive Group Delay	t <sub>GD</sub> R3	1000	0	*4		0.00	0.125	
	t <sub>GD</sub> R4	2600				0.09	0.125	
	t <sub>GD</sub> R5	2800				0.12	0.75	
Crosstalk Attenuation	CR T	1020	0	$TRANS \to RECV$		-85	-75	dB
orosolalit Attonuation	CR R	1020	U	$\text{RECV} \rightarrow \text{TRANS}$	—	-76	-70	UD

\*1 Psophometric filter is used.

\*2 Input "0" code to PCMIN.

\*3 AVR is defined at VFRO output.

\*4 With respect to minimum value of the group delay distortion.

## **AC Characteristics (Continued)**

 $\begin{array}{ll} (ML7001\text{-}xx: \ F_S = 8 \ \text{kHz}, \ V_{DD} = 2.7 \ \text{V to } 3.3 \ \text{V}, \ Ta = -30 \ \text{to } +85^\circ\text{C}) \\ (ML7000\text{-}xx: \ F_S = 8 \ \text{kHz}, \ V_{DD} = +5.0 \ \text{V} \ \pm5\%, \ Ta = -30 \ \text{to } +85^\circ\text{C}) \end{array}$ 

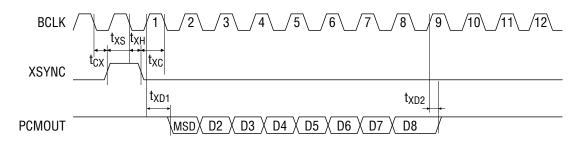
Parameter	Symbol	Freq. (Hz)	Level (dBm0)	Condition	Min.	Тур.	Max.	Unit
Discrimination	DIS	4.6 kHz to	0	0 to	30	32	_	dB
		72 kHz		4000 Hz				
Out-of-band Spurious	S	300 to		4.6 kHz to	—	-37.5	-35	dBm0
	0	3400		100 kHz			-00	UDIIIO
Intermodulation Distortion	IMD	fa = 470	-4	2fa – fb		-52	-35	dBm0
Intermodulation Distortion		fd = 320			—			
Dower Supply Noise Dejection Date	PSR T	0 to	50  m/c	Measured		30		dB
Power Supply Noise Rejection Ratio	PSR R	50 kHz	50 mV <sub>PP</sub>	inband *5	—	30		UD
Digital Output Delay Time	t <sub>XD1</sub>	C <sub>L</sub> = 100 p	F + 1 LST	TL	20	_	200	n
	t <sub>XD2</sub>	Pull-up re	sistor = 50	0 Ω	20	—	200	ns

\*5 Measured under idle channel noise.

## TIMING DIAGRAM

## PCM Data Input/Output Timing

Transmit Timing



**Receive Timing** 

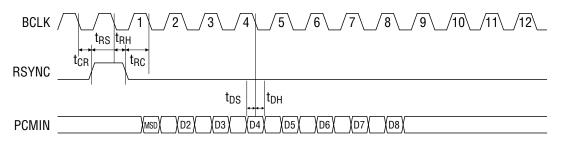
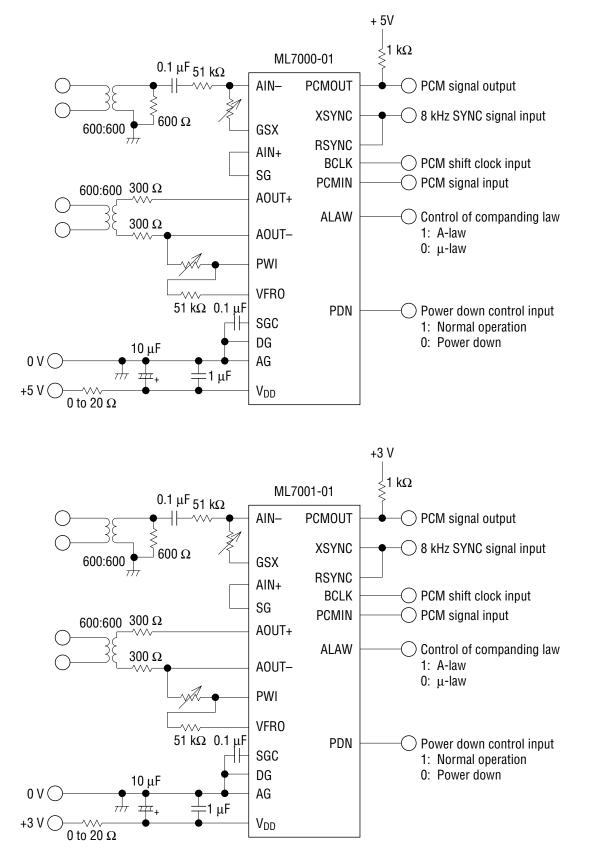


Figure 1 Basic Timing

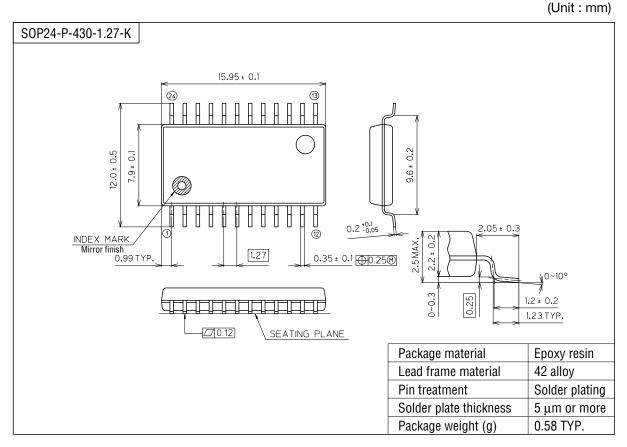
# **APPLICATION CIRCUIT**



## NOTES ON USE

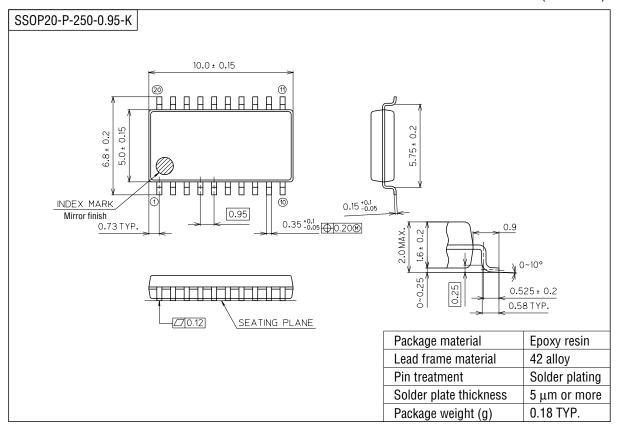
- To ensure proper electrical characteristics, use by pass capacitors with excellent high frequency characteristics for the power supply and keep them as close as possible to the device pins.
- Connect the AG pin and the DG pin as closely as possible. Connect to the system ground with low impedance.
- Mount the device directly on the board when mounted on PCBs. Do not use IC sockets. If the use of IC socket is unavoidable, use the short lead type socket.
- When mounted on a frame, use electromagnetic shielding if any electromagnetic wave sources such as power supply transformers surrounds the device.
- Keep the voltage on the V<sub>DD</sub> pin not lower than –0.3 V even instantaneously to avoid latchup that may otherwise occur when power is turned on.
- Use a low noise (particularly, low level type of high frequency spike noise or pulse noise) power supply to avoid erroneous operation and the degradation of the characteristics of these devices.

# PACKAGE DIMENSIONS



Notes for Mounting the Surface Mount Type Package

The SOP, QFP, TSOP, SOJ, QFJ (PLCC), SHP and BGA are surface mount type packages, which are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).



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(Unit : mm)