

SANYO	No. 5131	LB1889/1889M/1889D
		3-phase Brushless Motor Driver for VTR Capstans

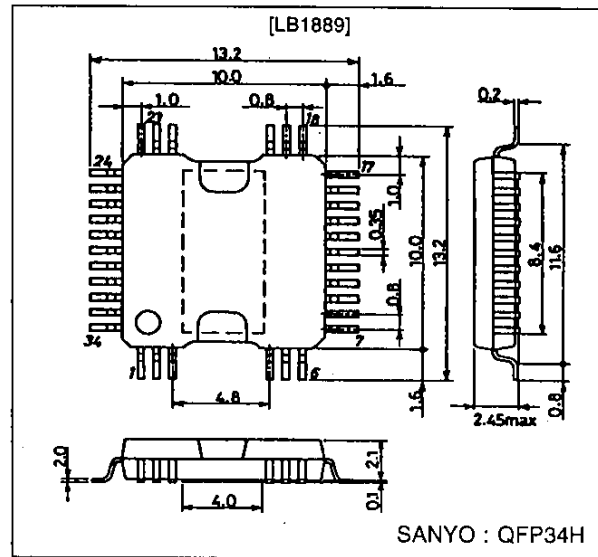
Functions

- 3-phase full-wave current linear drive system
- Torque ripple correction circuit built in (variable compensation ratio)
- Current limiting circuit built in/with control characteristic gain switch
- Output stage upper/lower oversaturation prevention circuit built in (no external capacitor required)
- FG amplifier built in
- Thermal shutdown circuit built in

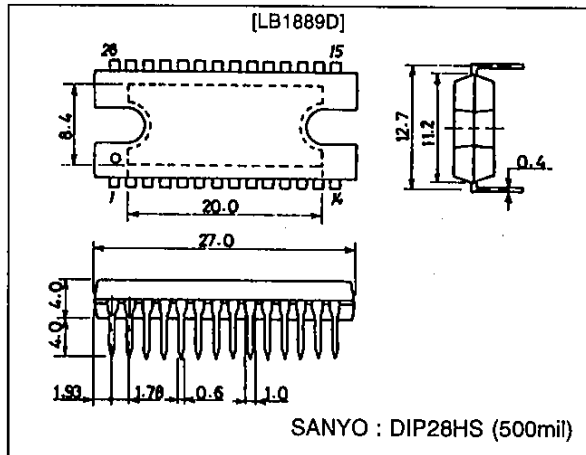
Package Dimensions

unit : mm

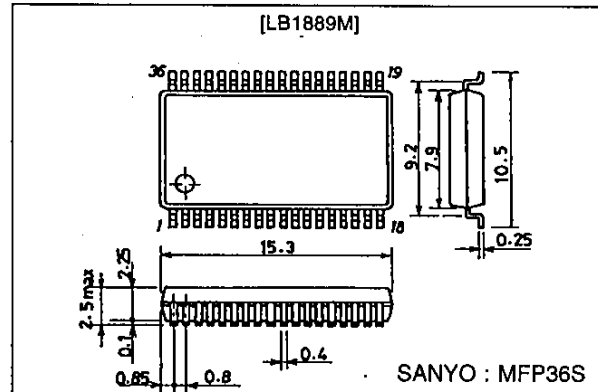
3206-QFP34H



3147A-DIP28HS



3129-MFP36S



Specifications

Absolute Maximum Ratings at Ta = 25 °C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V _{CC} max		7	V
	V _S max		24	V
Maximum output current	I _O max		1.3	A
Allowable power dissipation	Pd max	Arbitrarily large heat sink LB1889	12.5	W
		Arbitrarily large heat sink LB1889D	15.0	W
		Independent IC LB1889	0.77	W
		Independent IC LB1889M	0.95	W
		Independent IC LB1889D	3.0	W
Operating temperature	T _{opr}		-20 to +75	°C
Storage temperature	T _{stg}		-55 to +150	°C

Allowable Operating Ranges at Ta = 25 °C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V _S		5 to 22	V
	V _{CC}		4.5 to 5.5	V
Hall input amplitude	V _{HALL}	Between Hall Inputs	±30 to ±80	mV _{O-P}
GSENSE input range	V _{GSENSE}	Relative to control system GND	-0.20 to +0.20	V

Electrical Characteristics at Ta = 25 °C, V_{CC} = 5 V, V_S = 15 V

Parameter	Symbol	Conditions	min	typ	max	Unit
V _{CC} supply current	I _{CC}	R _L = ∞ (when stopped), V _{CTL} = 0 V, V _{LIM} = 0 V		12	18	mA
[Output]						
Output saturation voltage	V _{Osat1}	I _O = 500 mA, R _f = 0.5 Ω, Sink + Source V _{CTL} = V _{LIM} = 5 V (with saturation prevention)		2.1	2.6	V
	V _{Osat2}	I _O = 1.0 A, R _f = 0.5 Ω, Sink + Source V _{CTL} = V _{LIM} = 5 V (with saturation prevention)		2.6	3.5	V
Output leakage current	I _{oleak}				1.0	mA
[FR]						
FR pin input threshold voltage	V _{FSR}		2.25	2.50	2.75	V
FR pin input bias current	I _b (FSR)		-5.0			μA
[Control]						
CTLREF pin voltage	V _{CREF}		2.37	2.50	2.63	V
CTLREF pin input range	V _{CREFIN}		1.70		3.50	V
CTL pin input bias current	I _b (CTL)	V _{CTL} = 5 V, CTLREF : Open			8.0	μA
CTL pin control start voltage	V _{CTL} (ST)	With R _f = 0.5 Ω, V _{LIM} = 5 V, I _O ≥ 10 mA, Hall input logic fixed, (u, v, w = H, H, L)	2.20	2.35	2.50	V
CTL pin control switch voltage	V _{CTL} (ST2)	R _f = 0.5 Ω, V _{LIM} = 5 V	3.00	3.15	3.30	V
CTL pin control Gm1	Gm1 (CTL)	With R _f = 0.5 Ω, ΔI _O = 200 mA, Hall input logic fixed, (u, v, w = H, H, L)	0.52	0.65	0.78	A/V
CTL pin control Gm2	Gm2 (CTL)	With R _f = 0.5 Ω, ΔV _{CTL} = 200 mV, Hall input logic fixed, (u, v, w = H, H, L)	1.20	1.50	1.80	A/V
[Current Limit]						
LIM current limit offset voltage	V _{off} (LIM)	With R _f = 0.5 Ω, V _{CTL} = 5 V, I _O ≥ 10 mA, Hall input logic fixed, (u, v, w = H, H, L)	140	200	260	mV
LIM pin input bias current	I _b (LIM)	With V _{CTL} = 5 V, CTLREF : Open, V _{LIM} = 0 V	-2.5			μA
LIM pin current limit level	I _{lim}	With R _f = 0.5 Ω, V _{CTL} = 5 V, V _{LIM} = 2.06 V, Hall input logic fixed, (u, v, w = H, H, L)	830	900	970	mA
[Hall Amplifier]						
Hall amplifier input offset voltage	V _{off} (HALL)		-6		+6	mV
Hall amplifier input bias current	I _b (HALL)			1.0	3.0	μA
Hall amplifier common-mode input voltage	V _{cm} (HALL)		1.3		3.3	V

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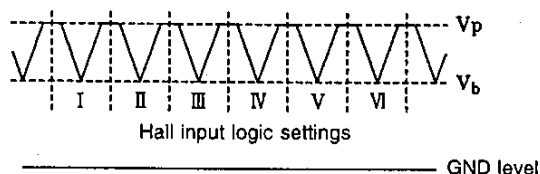
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Parameter	Symbol	Conditions	min	typ	max	Unit
[TRC]						
Torque ripple correction factor	T_{RC}	At bottom and peak in R_f waveform at $I_O = 200$ mA ($R_f = 0.5 \Omega$, ADJ-OPEN) Note 2		9		%
ADJ pin voltage	V_{adj}		2.37	2.50	2.63	V
[FG Amplifier]						
FG amplifier input offset voltage	V_{off} (FG)		-8		+8	mV
FG amplifier input bias current	I_b (FG)		-100			nA
FG amplifier output saturation voltage	V_{Osat} (FG)	At internal pull-up resistor load on sink side			0.5	V
FG amplifier common-mode input voltage	V_{CM} (FG)		0.5		4.0	V
[Saturation]						
Saturation prevention circuit lower set voltage	V_{Osat} (DET)	Voltage between each OUT and R_f at $I_O = 10$ mA, $R_f = 0.5 \Omega$, $V_{CTL} = V_{LIM} = 5$ V	0.175	0.25	0.325	V
[TSD]						
TSD operation temperature	T-TSD	(Design target) Note 1		180		°C
TSD temperature hysteresis width	ΔTSD	(Design target) Note 1		20		°C

Note 1: No measurements are performed for any values listed in the conditions column as design targets.

Note 2: The torque ripple correction factor is calculated using the R_f voltage waveform as follows.



$$\text{Correction factor} = \frac{2 \times (V_p - V_b)}{V_p + V_b} \times 100 (\%)$$

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Truth Table & Control Function

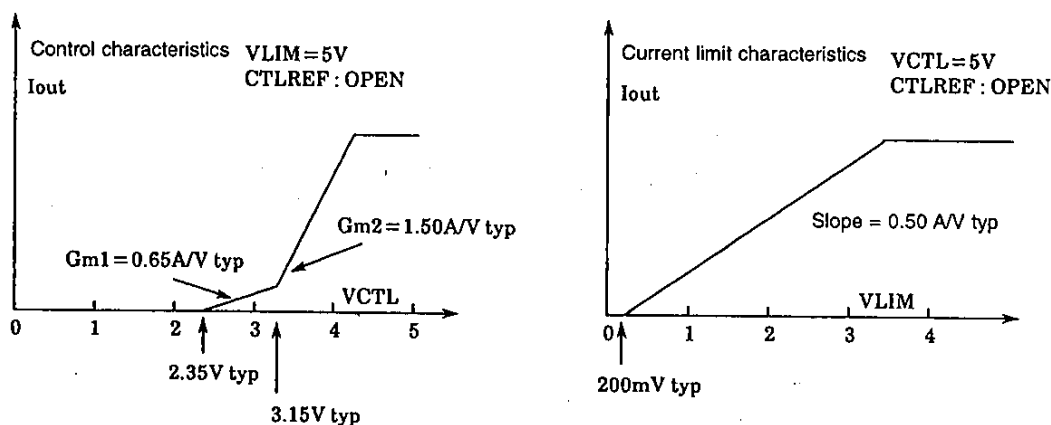
	Source → Sink	Hall input			FR
		U	V	W	
1	V → W	H	H	L	H
	W → V	H	H	L	L
2	U → W	H	L	L	H
	W → U	H	L	L	L
3	U → V	H	L	H	H
	V → U	H	L	H	L
4	W → V	L	L	H	H
	V → W	L	L	H	L
5	W → U	L	H	H	H
	U → W	L	H	H	L
6	V → U	L	H	L	H
	U → V	L	H	L	L

Note: "H" in the FR column represents a voltage of 2.75 V or more; "L" represents a voltage of 2.25 V or less.
(At $V_{CC} = 5$ V)

Note: "H" in the Hall input columns represents a state in which "+" has a potential which is higher by 0.01 V or more than that of the "-" phase inputs.
Conversely, "L" represents a state in which "+" has a potential which is lower by 0.01 V or more than that of the "-" phase input.

Note: Since 180° energized system is used as the drive system, other phases than the sink and source phases are turned off.

Control Function & Current Limit Function

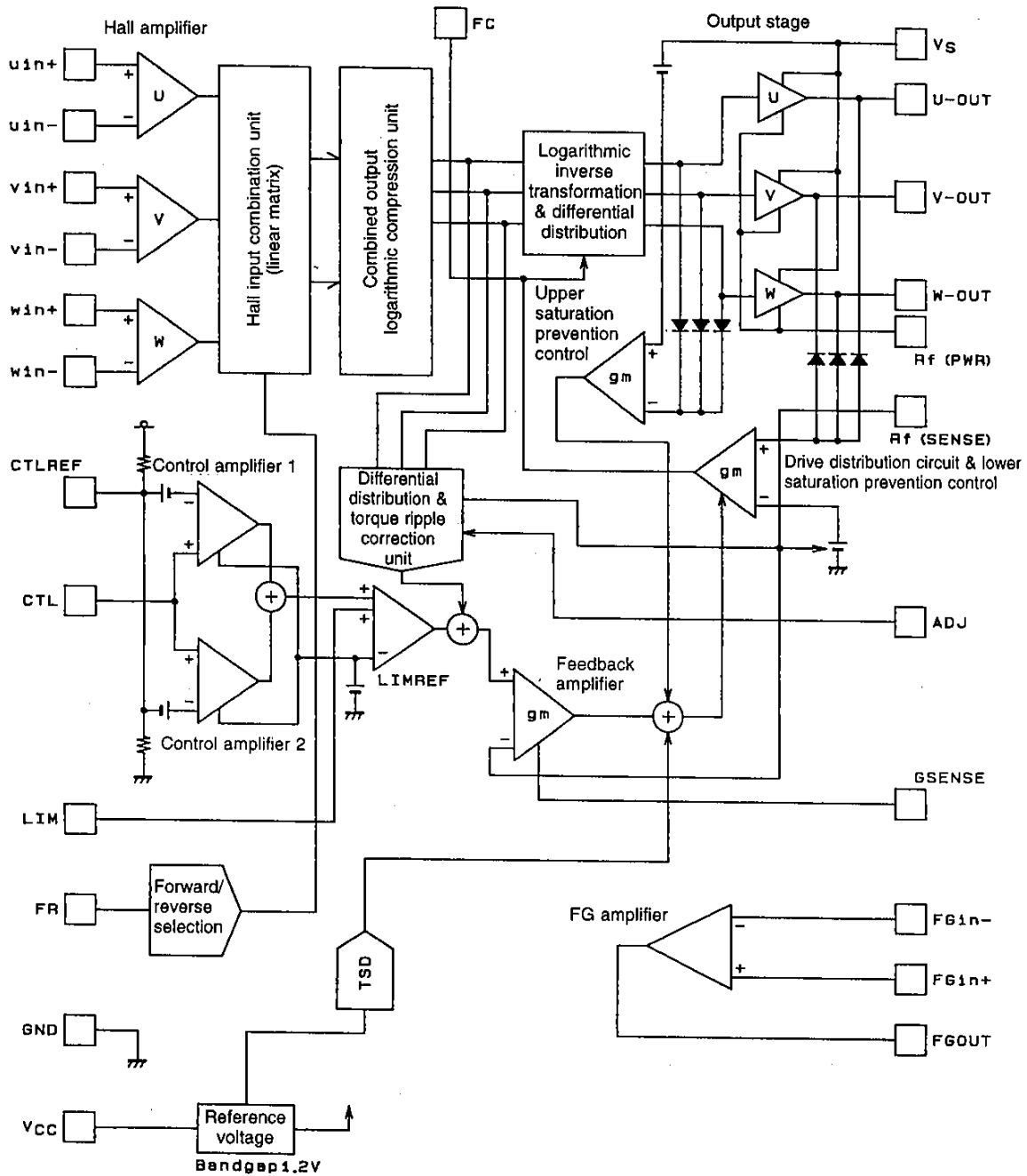


Pin Functions

The pin number in () is for MFP, that in < > is for DIP, and other than these is for QFP.

Pin name	Pin No.	Function
FR	1 (33) <26>	Forward/reverse select pin. The pin voltage selects forward/reverse. ($V_{th} = 2.5 V$ typ at $V_{CC} = 5 V$)
GND	2 (34) <27>	GND for other than output transistor. Minimum potential of output transistor is at Rf pin.
FGin (-)	5 (3) <28>	Input pin when FG amplifier is used with inverted input. Feedback resistor is connected between this pin and FG-OUT.
FGin (+)	6 (4) <1>	Noninverting input pin when FG amplifier is used with differential input. Internal bias is not applied.
FG-OUT	8 (5) <3>	FG amplifier output pin. Resistive load provided internally.
CTL	9 (6) <4>	Speed control pin. Control is exercised by constant-current drive with current feedback applied from Rf. $G_m = 0.65 A/V$ & $1.50 A/V$ typ at $R_f = 0.5 \Omega$
CTLREF	10 (7) <5>	Control reference voltage pin. The voltage is set internally to approx. $V_{CC}/2$ but this can be varied by applying voltage through a low impedance (input impedance = approx. $2.5 k\Omega$).
LIM	11 (8) <6>	Current limiting function control pin. The output current is varied linearly by this pin voltage; slope = $0.5 A/V$ typ at $R_f = 0.5 \Omega$.
FC	12 (9) <7>	Speed control loop frequency characteristic correction pin
Uin*, Uin- Vin*, Vin- Win*, Win-	13, 14 (10, 11) <8, 9> 15, 16 (12, 13) <10, 11> 17, 18 (14, 15) <12, 13>	U-phase Hall device input pin; logic "H" represents $IN+ > IN-$. V-phase Hall device input pin; logic "H" represents $IN+ > IN-$. W-phase Hall device input pin; logic "H" represents $IN+ > IN-$.
VCC	19 (16) <14>	Power supply pin for supplying power to all circuits except output section in IC; this voltage must be stabilized so as to eliminate ripple and noise.
Vs	22 (21) <15>	Output selection power supply pin
ADJ	23 (22) <16>	Pin for external adjustment of torque ripple correction factor. When this factor is to be adjusted, a voltage is externally applied to the ADJ pin through a low impedance. If the voltage applied is increased, the factor drops; conversely, if it is reduced, the factor rises. The factor varies between 0 and 2 times that of the open state. (The voltage is set inside to approx. $V_{CC}/2$ internally, and the input impedance is approx. $5 k\Omega$.)
Rf (PWR) Rf (SNS)	24 (23) <17> 33 (31) <24>	Output current detection pin. Current feedback is applied to the control section by connecting Rf between this pin and GND. The lower oversaturation prevention circuit and torque ripple correction circuit are activated in accordance with this pin voltage. Since the oversaturation prevention level is set with this voltage, the lower oversaturation prevention effect may deteriorate in the high current range if the Rf value is reduced to an extremely low level. The PWR and SENSE pins must always be connected.
Uout Vout Wout	27 (26) <21> 29 (27) <22> 31 (28) <23>	U-phase output pin V-phase output pin W-phase output pin (Built-in spark killer diode)
GSENSE	34 (32) <25>	GND sensing pin. By connecting this pin to the neighboring GND on the Rf resistor side of the motor GND wire which contains Rf, the effect that GND common impedance exerts on Rf can be eliminated. (This pin must not be left open.)

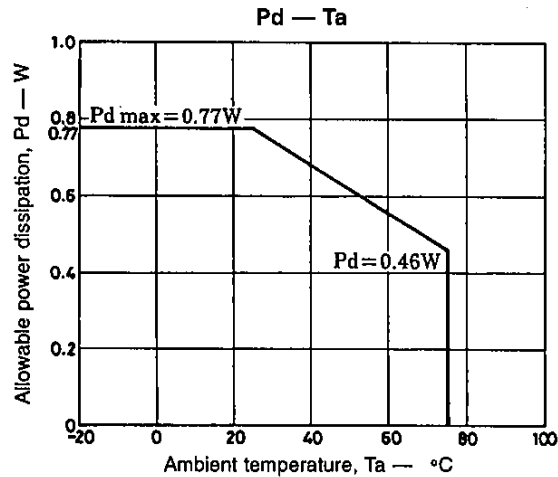
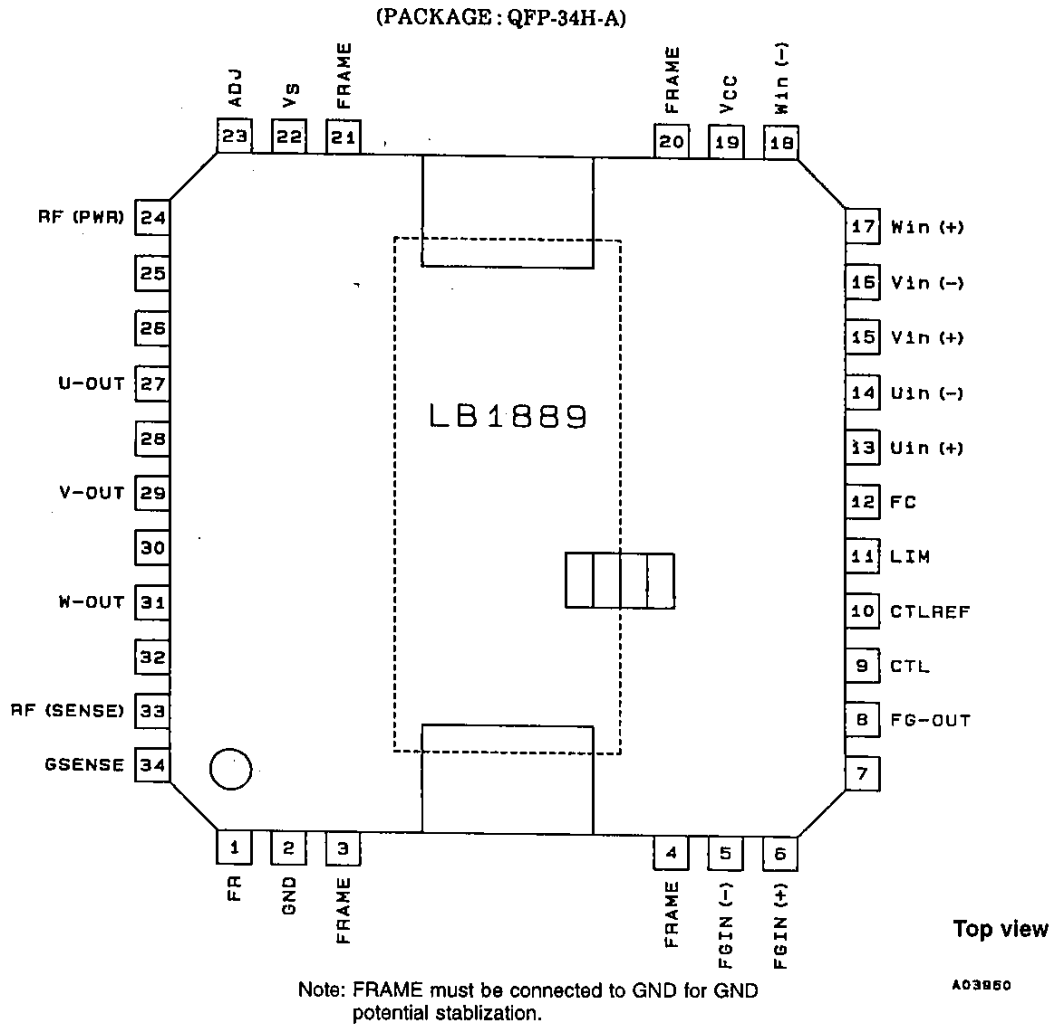
Block Diagram



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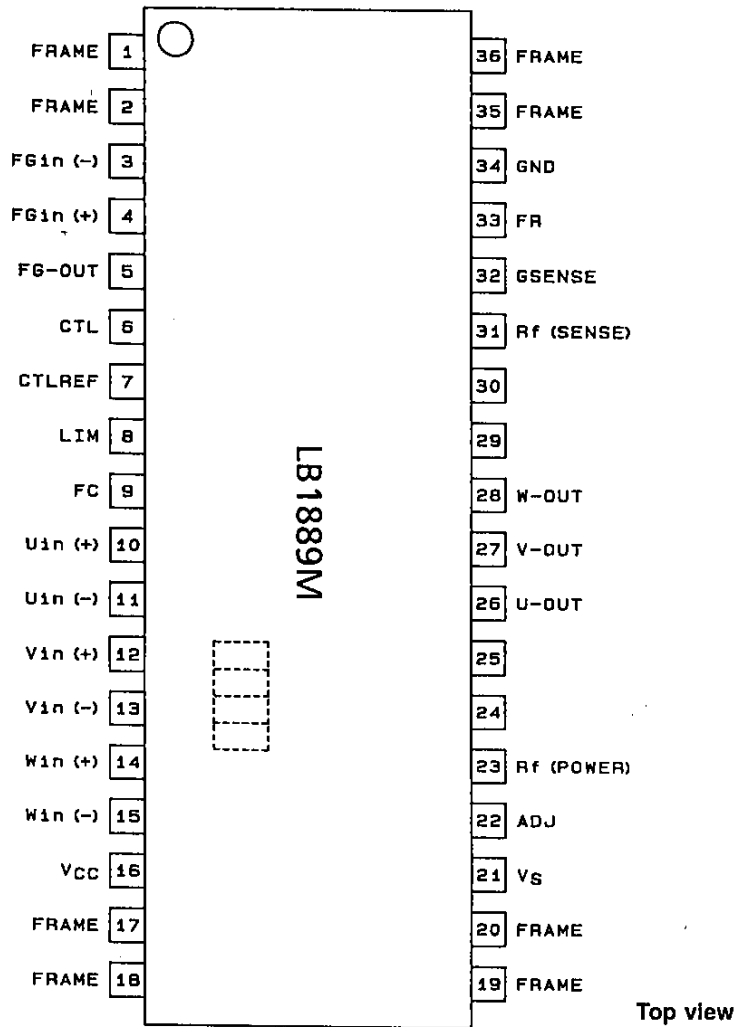
Pin Assignment [LB1889]



LB1889/M/D

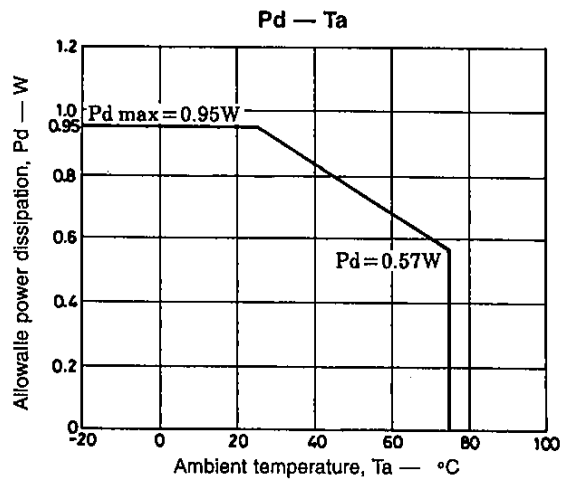
Pin Assignment [LB1889M]

(PACKAGE : MFP-36S-LF)



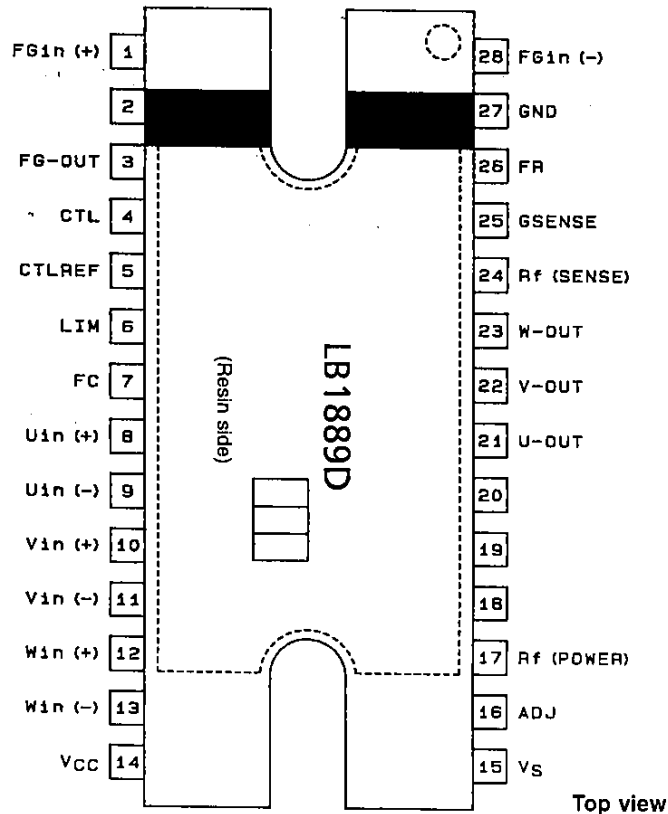
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Note: Although there is no internal connection between the FRAME pin and GND, FRAME must be connected to GND externally for GND potential stabilization.



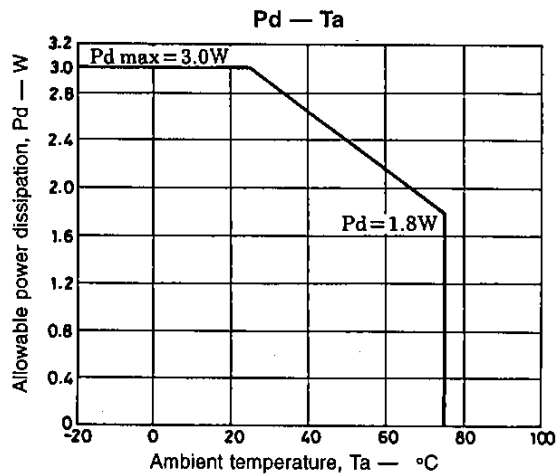
Pin Assignment [LB1889D]

DIP-28HS bent opposite

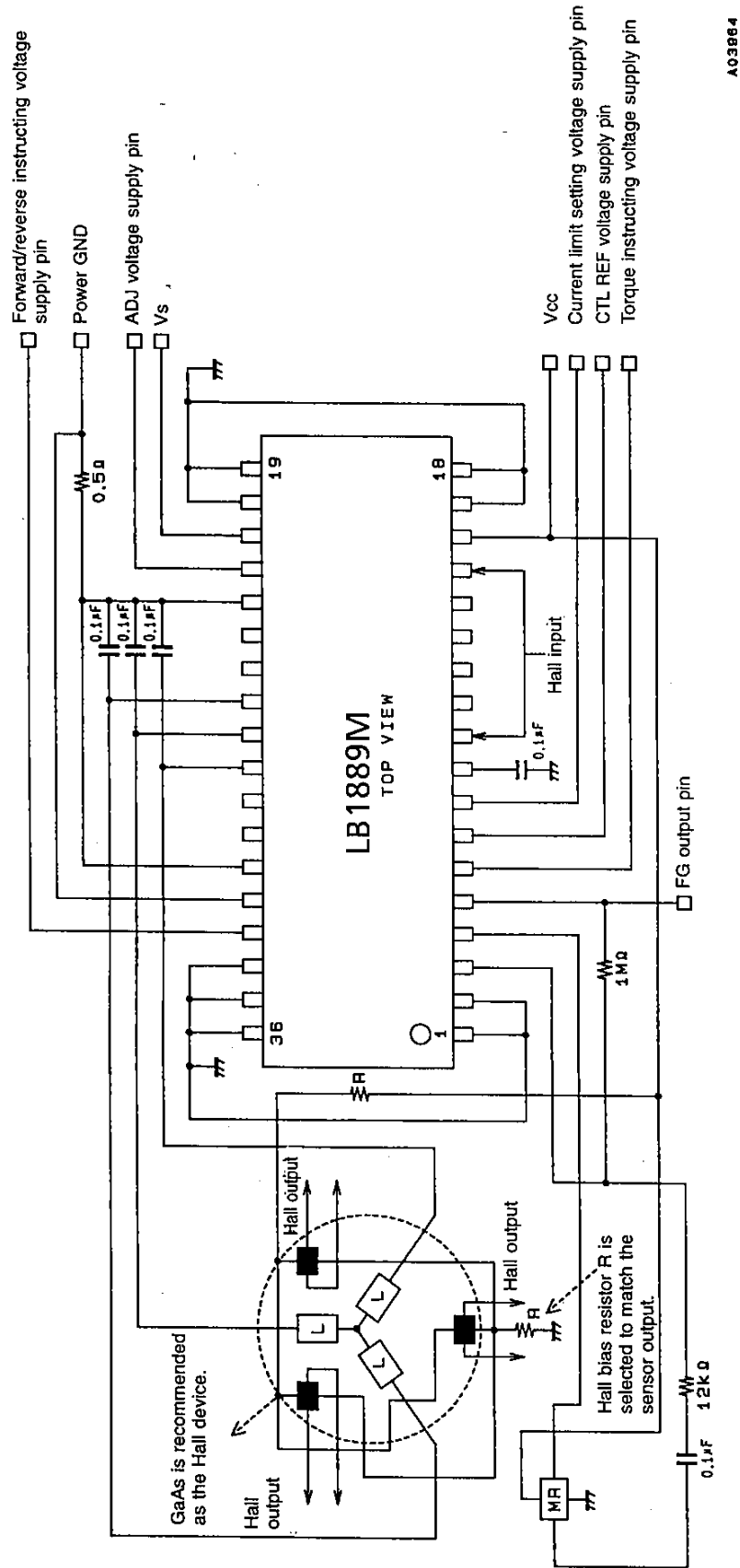


Top view

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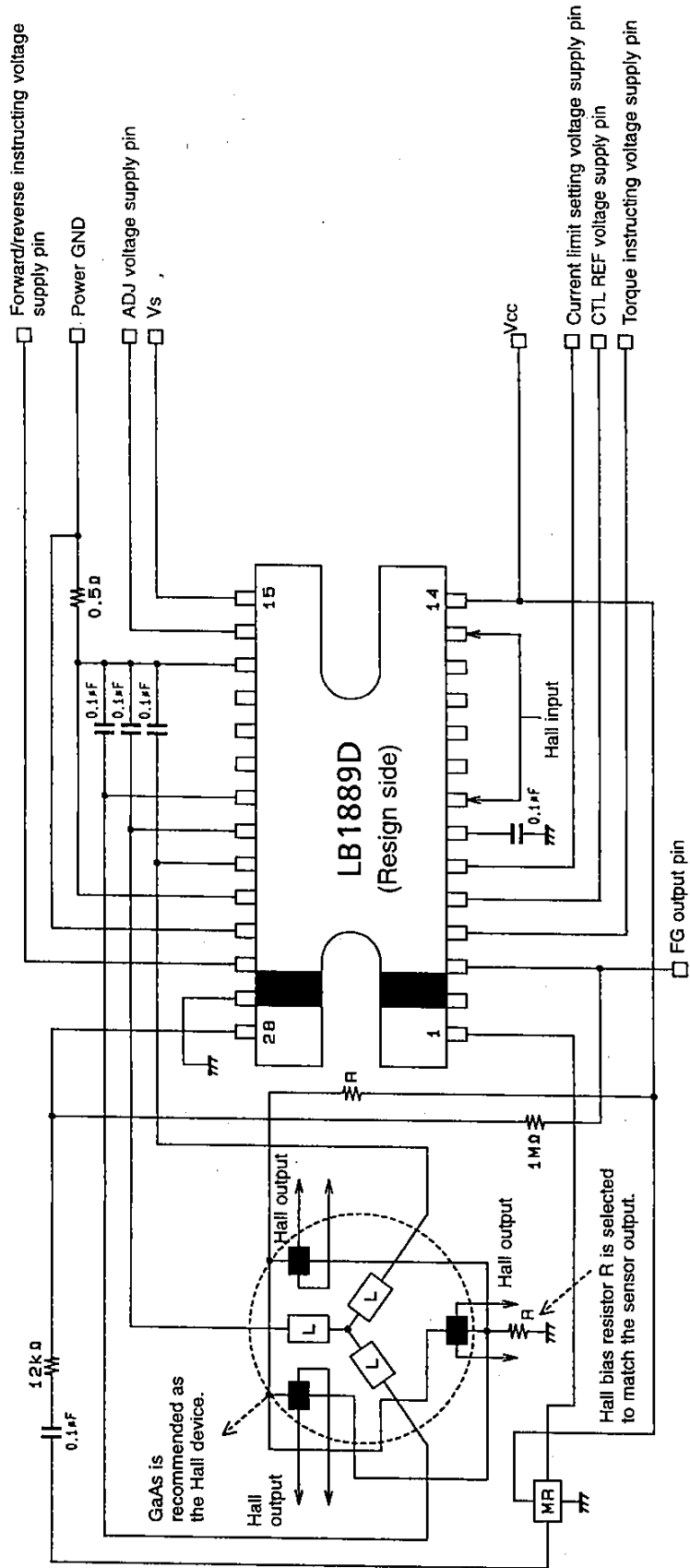
Sample Application Circuit [LB1889M]



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Note: The constants provided in this sample application circuit are provided by way of example and are not intended to guarantee the characteristics.

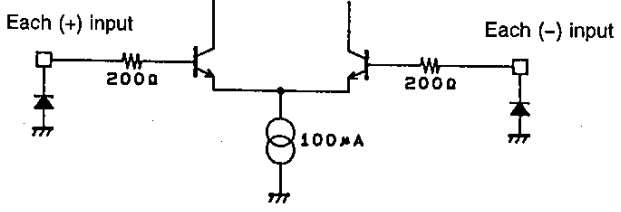
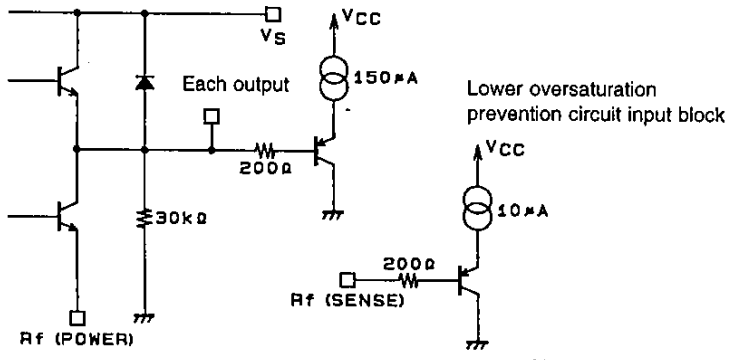
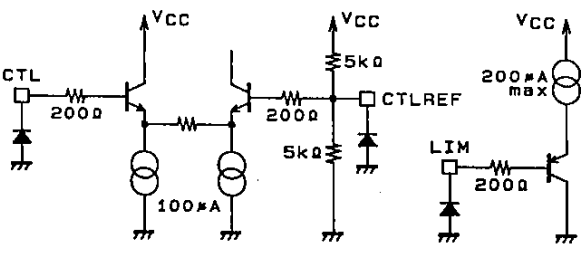
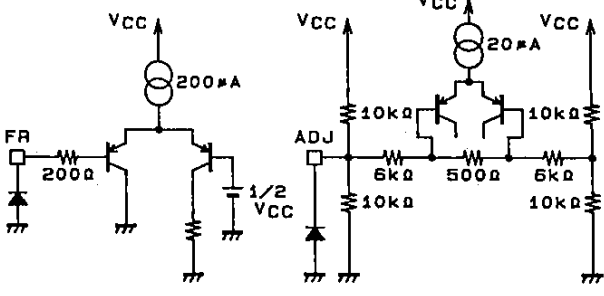
Sample Application Circuit [LB1889D]



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Note: The constants provided in this sample application circuit are provided by way of example and are not intended to guarantee the characteristics.

Pin Input/Output Equivalent Circuit

Pin name	Input/Output Equivalent Circuit
Uin (+) Uin (-) Vin (+) Vin (-) Win (+) Win (-)	 <p style="text-align: right;">A03956</p>
U-OUT V-OUT W-OUT Vs Rf (POWER) Rf (SENSE)	 <p style="text-align: right;">A03957</p>
CTL LIM CTLREF	 <p style="text-align: right;">A03958</p>
FR ADJ	 <p style="text-align: right;">A03959</p>

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Pin name	Input/Output Equivalent Circuit
FGIn (-) FGIn (+)	<p style="text-align: right;">A03970</p>
FGOUT FC	<p style="text-align: right;">A03971</p>

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