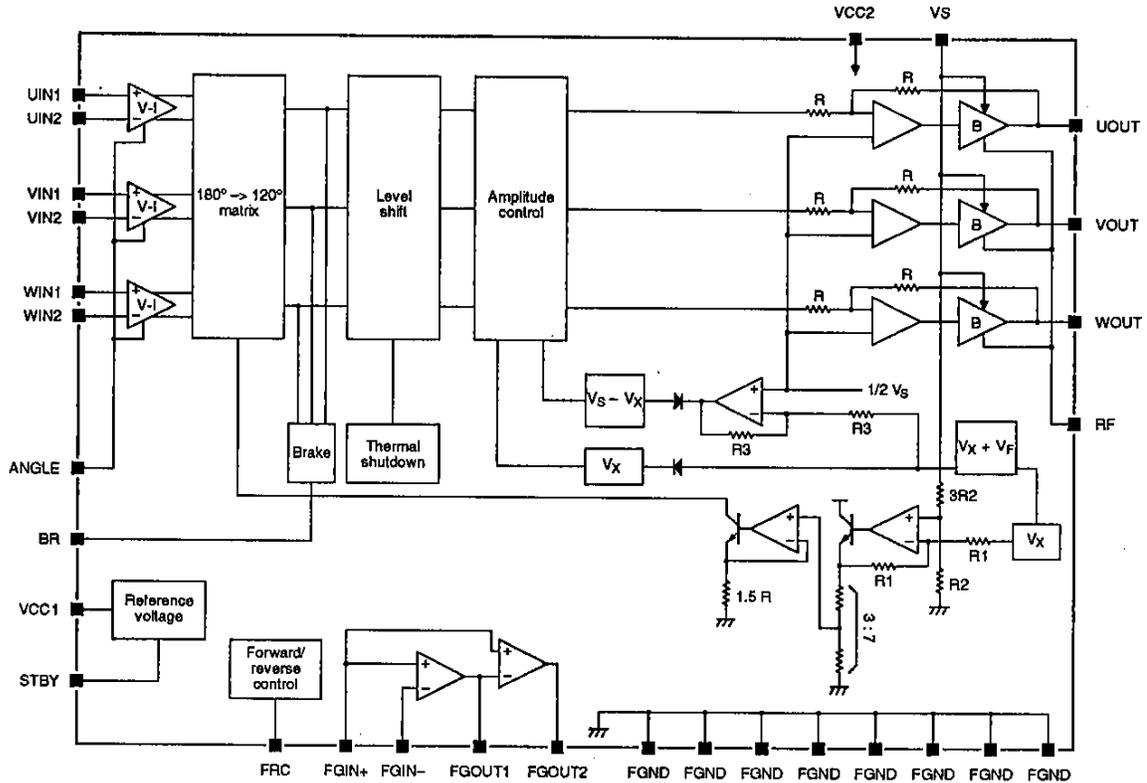


BLOCK DIAGRAM



PIN DESCRIPTION

| Number | Name | Equivalent circuit | Description |
|------------------------|------|--------------------|---|
| 1, 2, 14 to 17, 29, 30 | FGND | | Frame ground. Ground for all circuits other than output transistors |
| 3 | WOUT | | Motor phase outputs |
| 27 | UOUT | | |
| 28 | VOUT | | |
| 4 | VS | | 0 V to VCC2 output transistor supply |
| 5 | VCC2 | | 4 to 14 V supply for circuits other than output transistors and circuits supplied by VCC1 |
| 6 | VCC1 | | 4 to 6 V input amplifier, forward/reverse control, FG amplifier and thermal shutdown circuit supply |

LB1857M

| Number | Name | Equivalent circuit | Description |
|--------|--------|--------------------|--|
| 7 | STBY | | Standby mode set input |
| 8 | ANGLE | | Input amplifier gain set resistor connection |
| 9 | NC | | No connection |
| 10 | FGIN- | | FG signal inputs |
| 11 | FGIN+ | | |
| 12 | FGOUT1 | | FG amplifier 1 output |
| 13 | FGOUT2 | | FG Schmitt-trigger input amplifier 2 output |

LB1857M

| Number | Name | Equivalent circuit | Description |
|--------|------|--------------------|--|
| 18 | FRC | | Motor forward/reverse control input |
| 19 | BR | | Motor braking control input |
| 20 | WIN2 | | W-phase, Hall-effect transducer amplifier inputs |
| 21 | WIN1 | | V-phase, Hall-effect transducer amplifier inputs |
| 22 | VIN2 | | |
| 23 | VIN1 | | |
| 24 | UIN2 | | U-phase, Hall-effect transducer amplifier inputs |
| 25 | UIN1 | | |
| 26 | RF | | Output transistor ground |

SPECIFICATIONS

Absolute Maximum Ratings

| Parameter | Symbol | Rating | Unit |
|-----------------------------------|-----------|------------|------|
| Control supply voltage | V_{CC1} | 7 | V |
| Power amplifier supply voltage | V_{CC2} | 16 | V |
| Output transistor supply voltage | V_S | V_{CC2} | V |
| U-, V- and W-phase output voltage | V_O | $V_S + 2$ | V |
| Output current | I_O | 1.5 | A |
| Power dissipation | P_D | 1 | W |
| Operating temperature range | T_{opr} | -20 to 75 | °C |
| Storage temperature range | T_{stg} | -55 to 125 | °C |

Recommended Operating Conditions

 $T_a = 25\text{ }^\circ\text{C}$

| Parameter | Symbol | Rating | Unit |
|--|-----------|----------------|------|
| Control supply voltage range | V_{CC1} | 4 to 6 | V |
| Power amplifier supply voltage range | V_{CC2} | 4 to 14 | V |
| Output transistor supply voltage range | V_S | 0 to V_{CC2} | V |

Electrical Characteristics

 $V_{CC1} = 5\text{ V}$, $V_{CC2} = 7\text{ V}$, $V_S = 3\text{ V}$, $T_a = 25\text{ }^\circ\text{C}$ unless otherwise noted

| Parameter | Symbol | Condition | Rating | | | Unit |
|--|-----------------|--|--------|-----|------|------------------|
| | | | min | typ | max | |
| Control supply current | I_{CC1} | $V_{BR} = 5\text{ V}$ | – | 4.5 | 6.5 | mA |
| Power amplifier supply current | I_{CC2} | $V_{BR} = 5\text{ V}$ | – | 15 | 20 | mA |
| Output transistor supply current | I_S | $V_{BR} = 0\text{ V}$, $R_L = \infty$ | – | 6.5 | 9.0 | mA |
| Power amplifier quiescent supply current | I_{CCOQ} | $V_{STBY} = 0\text{ V}$ | – | – | 180 | μA |
| Output transistor quiescent supply current | I_{SOQ} | $V_{STBY} = 0\text{ V}$, $R_L = \infty$ | – | – | 150 | μA |
| BR LOW-level input voltage | V_{IL1} | | – | – | 0.8 | V |
| FRC LOW-level input voltage | V_{IL2} | | – | – | 1.2 | V |
| STBY LOW-level input voltage | V_{IL3} | | –0.2 | – | 0.1 | V |
| BR HIGH-level input voltage | V_{IH1} | | 2 | – | – | V |
| FRC HIGH-level input voltage | V_{IH2} | | 2.8 | – | – | V |
| STBY HIGH-level input voltage | V_{IH3} | | 2 | – | 5 | V |
| Output saturation voltage | V_{Osat} | $I_O = 0.5\text{ A}$ | – | – | 2.3 | V |
| Output TRS sustaining voltage | V_{Ostus} | $I_O = 20\text{ mA}$. See note. | 16 | – | – | V |
| Quiescent output voltage | V_{OQ} | $V_{BR} = 5\text{ V}$ | 1.4 | 1.5 | 1.6 | V |
| Hall-effect transducer amplifier input offset voltage | V_{Hoff} | See note. | –5 | – | 5 | mV |
| Hall-effect transducer amplifier common-mode input voltage | V_{Hch} | | 1.4 | – | 2.8 | V |
| Hall-effect transducer amplifier gain | G_{VHO} | $R_{ANGLE} = 8.2\text{ k}\Omega$ | 32 | 35 | 38 | dB |
| Upper-side residual voltage | V_{XH} | $I_O = 100\text{ mA}$, $V_{CC2} = 6\text{ V}$, $V_S = 2\text{ V}$. | 0.32 | – | 0.49 | V |
| Lower-side residual voltage | V_{XL} | $I_O = 100\text{ mA}$, $V_{CC2} = 6\text{ V}$, $V_S = 2\text{ V}$ | 0.39 | – | 0.48 | V |
| Overlap capacity | Over | $V_{CC2} = 6\text{ V}$, $V_S = 3\text{ V}$ | 60 | 70 | 80 | % |
| BR and FRC input current | I_i | | – | – | 100 | μA |
| BR and FRC leakage current | I_{leak} | | – | – | –30 | μA |
| STBY input bias current | I_{BIAS} | $V_{STBY} = 0\text{ V}$ | – | – | 10 | μA |
| Thermal shutdown temperature | T_{SD} | See note. | 150 | 180 | 210 | $^\circ\text{C}$ |
| Thermal shutdown hysteresis | ΔT_{SD} | See note. | – | 15 | – | $^\circ\text{C}$ |

Note

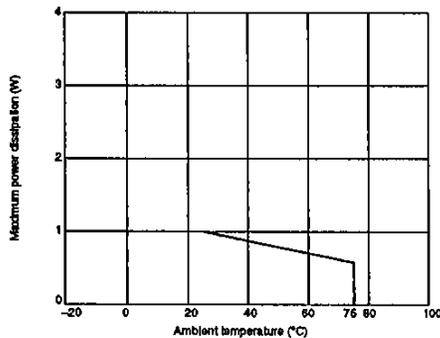
Estimated values

FG amplifier $V_{CC1} = 5\text{ V}$, $V_{CC2} = 7\text{ V}$, $V_S = 3\text{ V}$, $T_a = 25\text{ }^\circ\text{C}$

| Parameter | Symbol | Condition | Rating | | | Unit |
|--|-------------|--|--------|------|------|----------|
| | | | min | typ | max | |
| Input offset voltage | V_{FGoff} | | -8 | - | 8 | mV |
| Open-loop voltage gain | G_{VFG} | $f = 1\text{ kHz}$ | - | 60 | - | dB |
| Output saturation voltage (source) | V_{FGOU} | $I_o = 2\text{ mA}$ | 3.7 | - | - | V |
| Output saturation voltage (sink) | V_{FGOD} | $I_o = -2\text{ mA}$ | - | - | 1.3 | V |
| Common-mode rejection ratio | CHR | See note. | - | 80 | - | dB |
| Common-mode input voltage | V_{FGCH} | | 0 | - | 3.5 | V |
| Phase margin | Φ_{FG} | See note. | - | 20 | - | $^\circ$ |
| Schmitt-trigger input threshold voltage | V_{TH} | $V_{FGIN+} = 2.5\text{ V}$, V_{FGOUT2} HIGH to LOW transition | 2.45 | 2.50 | 2.55 | V |
| Schmitt-trigger input hysteresis voltage | V_H | $V_{FGIN+} = 2.5\text{ V}$ | 20 | 40 | 60 | mV |

Note

Estimated values

Typical Performance Characteristics**Maximum power dissipation vs. ambient temperature****FUNCTIONAL DESCRIPTION****Inputs**

Motor driver operation is determined by the levels on STBY, BR and FRC. Standby mode is ON when STBY is LOW, and OFF when STBY is HIGH or open. Motor braking is ON when BR is HIGH. the motor is forward mode when FRC is LOW, and in reverse mode, when FRC is HIGH.

A Hall-effect transducer amplifier input is HIGH when input 1 is more than 0.2 V above input 2, and LOW when input 1 is more than 0.2 V below input 2. The resistor connected between ANGLE and GND determines the Hall-effect transducer amplifier V-I characteristic and gain.

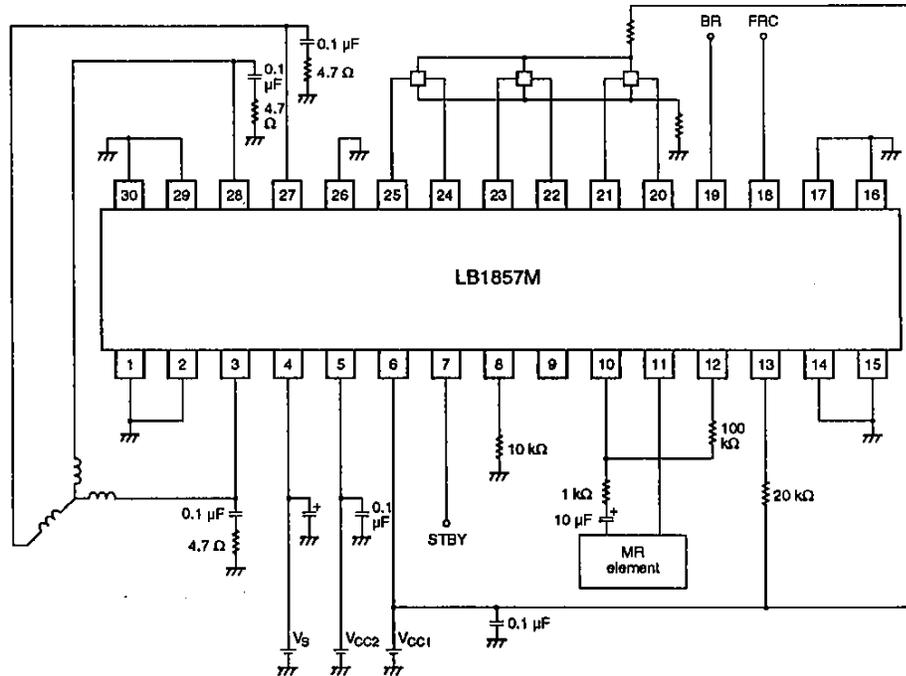
Outputs

The motor driver output source and sink phases are selected by the voltages at the amplifier inputs and FRC as shown in table 1.

Table 1. Output phase control

| Source phase | Sink phase | FRC | Hall-effect transducer amplifier inputs | | |
|--------------|------------|------|---|------|------|
| | | | U | V | W |
| W | V | LOW | HIGH | HIGH | LOW |
| V | W | HIGH | | | |
| W | U | LOW | HIGH | LOW | LOW |
| U | W | HIGH | | | |
| V | W | LOW | LOW | LOW | HIGH |
| W | V | HIGH | | | |
| U | V | LOW | LOW | HIGH | LOW |
| V | U | HIGH | | | |
| V | U | LOW | HIGH | LOW | HIGH |
| U | V | HIGH | | | |
| U | W | LOW | LOW | HIGH | HIGH |
| W | U | HIGH | | | |

TYPICAL APPLICATION



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