Phase-Locked Loop High-Performance Silicon-Gate CMOS

The device inputs are compatible with standard CMOS outputs; with pullup resistors, they are compatible with LS/ALSTTL outputs.

The SL74HC4046 phase-locked loop contains three phase comparators, a voltage-controlled oscillator (VCO) and unity gain opamp DEM_{OUT} . The comparators have two common signal inputs, $COMP_{IN}$, and SIG_{IN} . Input SIG_{IN} and $COMP_{IN}$ can be used directly coupled to large voltage signals, or indirectly coupled (with a series capacitor to small voltage signals). The self-bias circuit adjusts small voltage signals in the linear region of the amplifier. Phase comparator 1 (an exclusive OR gate) provides a digital error signal $PC1_{OUT}$ and maintains 90 degrees phase shift at the center frequency between SIG_{IN} and $COMP_{IN}$ signals (both at 50% duty cycle). Phase comparator 2 (with leading-edge sensing logic) provides digital error signals $PC2_{OUT}$ and PCP_{OUT} and maintains a 0 degree phase shift between SIG_{IN} and $COMP_{IN}$ signals (duty cycle is immaterial). The linear VCO produces an output signal VCO_{OUT} whose frequency is determined by the voltage of input VCO_{IN} signal and the capacitor and resistors connected to pins

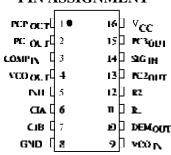


C1A, C1B, R1 and R2. The unity gain op-amp output DEM_{OUT} with an external resistor is used where the VCO_{IN} signal is needed but no loading can be tolerated. The inhibit input, when high, disables the VCO and all on-amps to minimize standby power consumption.

Applications include FM and FSK modulation and demodulation, frequency synthesis and multiplication, frequency discrimination, tone decoding, data synchronization and conditioning, voltage-to-frequency conversion and motor speed control.

- Low Power Consumption Characteristic of CMOS Device
- Operating Speeds Similary to LS/ALSTTL
- Wide Operating Voltage Range: 3.0 to 6.0 V
- Low Input Current: 1.0 μA Maximum (except SIG_{IN} and COMP_{IN})
- Low Quiescent Current: 80 µA Maximum (VCO disabled)
- High Noise Immunity Characteristic of CMOS Devices
- Diode Protection on all Inputs

PIN ASSIGNMENT



Pin No.	Symbol	Name and Function
1	PCP_{OUT}	Phase Comparator Pulse Output
2	PC1 _{OUT}	Phase Comparator 1 Output
3	$COMP_{IN}$	Comparator Input
4	VCO_{OUT}	VCO Output
5	INH	Inhibit Input
6	C1A	Capacitor C1 Connection A
7	C1B	Capacitor C1 Connection B
8	GND	Ground (0 V) V _{SS}
9	VCO_{IN}	VCO Input
10	DEM_{OUT}	Demodulator Output
11	R1	Resistor R1 Connection
12	R2	Resistor R2 Connection
13	PC2 _{OUT}	Phase Comparator 2 Output
14	$\mathrm{SIG}_{\mathrm{IN}}$	Signal Input
15	PC3 _{OUT}	Phase Comparator 3 Output
16	V_{CC}	Positive Supply Voltage

MAXIMUM RATINGS*

Symbol	Parameter	Value	Unit
V_{CC}	DC Supply Voltage (Referenced to GND)	-0.5 to +7.0	V
V_{IN}	DC Input Voltage (Referenced to GND)	-1.5 to V_{CC} +1.5	V
V _{OUT}	DC Output Voltage (Referenced to GND)	-0.5 to V _{CC} +0.5	V
I_{IN}	DC Input Current, per Pin	±20	mA
I_{OUT}	DC Output Current, per Pin	±25	mA
I_{CC}	DC Supply Current, V _{CC} and GND Pins	±50	mA
P_{D}	Power Dissipation in Still Air, Plastic DIP+ SOIC Package+	750 500	mW
Tstg	Storage Temperature	-65 to +150	°C
T_{L}	Lead Temperature, 1 mm from Case for 10 Seconds (Plastic DIP or SOIC Package)	260	°C

^{*}Maximum Ratings are those values beyond which damage to the device may occur. Functional operation should be restricted to the Recommended Operating Conditions.

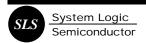
SOIC Package: : - 7 mW/°C from 65° to 125°C

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Min	Max	Unit
V_{CC}	DC Supply Voltage (Referenced to GND) VCO only	3.0	6.0	V
V _{CC}	DC Supply Voltage (Referenced to GND) NON-VCO	2.0	6.0	V
$V_{\rm IN}, V_{\rm OUT}$	DC Input Voltage, Output Voltage (Referenced to GND)	0	V_{CC}	V
T_{A}	Operating Temperature, All Package Types	-55	+125	°C
t _r , t _f	Input Rise and Fall Time (Figure 1) $V_{CC} = 2.0 \text{ V} $ $V_{CC} = 4.5 \text{ V} $ $V_{CC} = 6.0 \text{ V} $	0 0 0	1000 500 400	ns

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, V_{IN} and V_{OUT} should be constrained to the range $GND \leq (V_{IN} \text{ or } V_{OUT}) \leq V_{CC}$.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., either GND or V_{CC}). Unused outputs must be left open.



⁺Derating - Plastic DIP: - 10 mW/°C from 65° to 125°C

[Phase Comparator Section] DC ELECTRICAL CHARACTERISTICS(Voltages Referenced to GND)

				Gua			
Symbol	Parameter	Test Conditions	V	25 °C to -55°C	≤85 °C	≤125 °C	Unit
V _{IH}	Minimum High-Level Input Voltage DC Coupled SIG _{IN} , COMP _{IN}	$V_{OUT} = 0.1 \text{ V or } V_{CC} - 0.1 \text{ V}$ $ I_{OUT} \le 20 \mu\text{A}$	2.0 4.5 6.0	1.5 3.15 4.2	1.5 3.15 4.2	1.5 3.15 4.2	V
V _{IL}	Maximum Low -Level Input Voltage DC Coupled SIG _{IN} , COMP _{IN}	V_{OUT} =0.1 V or V_{CC} -0.1 V $ I_{OUT} \le 20 \mu A$	2.0 4.5 6.0	0.5 1.35 1.8	0.5 1.35 1.8	0.5 1.35 1.8	V
V_{OH}	Minimum High-Level Output Voltage PCP _{OUT} , PCn _{OUT}	$V_{\rm IN} = V_{\rm IH}$ or $V_{\rm IL}$ $\mid I_{\rm OUT} \mid \le 20~\mu A$	2.0 4.5 6.0	1.9 4.4 5.9	1.9 4.4 5.9	1.9 4.4 5.9	V
		$V_{IN} = V_{IH} \text{ or } V_{IL}$ $\mid I_{OUT} \mid \le 4.0 \text{ mA}$ $\mid I_{OUT} \mid \le 5.2 \text{ mA}$	4.5 6.0	3.98 5.48	3.84 5.34	3.7 5.2	
$V_{ m OL}$	Maximum Low-Level Output Voltage Q _a -Q _h PCP _{OUT} , PCn _{OUT}	$V_{\rm IN} = V_{\rm IH}$ or $V_{\rm IL}$ $ I_{\rm OUT} \le 20 \mu\text{A}$	2.0 4.5 6.0	0.1 0.1 0.1	0.1 0.1 0.1	0.1 0.1 0.1	V
		$V_{IN} = V_{IH} \text{ or } V_{IL}$ $\mid I_{OUT} \mid \leq 4.0 \text{ mA}$ $\mid I_{OUT} \mid \leq 5.2 \text{ mA}$	4.5 6.0	0.26 0.26	0.33 0.33	0.4 0.4	
I_{IN}	Maximum Input Leakage Current SIG _{IN} , COMP _{IN}	V_{IN} = V_{CC} or GND	2.0 3.0 4.5 6.0	±3.0 ±7.0 ±18.0 ±30.0	±4.0 ±9.0 ±23.0 ±38.0	±5.0 ±11.0 ±27.0 ±45.0	μА
I_{OZ}	Maximum Three-State Leakage Current PC2 _{OUT}	Output in High-Impedance State $V_{IN}{=}V_{IL} or V_{IH} \\ V_{OUT}{=}V_{CC} or GND$	6.0	±0.5	±5.0	±10	μΑ
I _{cc}	Maximum Quiescent Supply Current (per Package) (VCO disabled) Pins 3,5 and 14 at V _{CC} Pin 9 at GND; Input Leacage at Pin 3 and 14 to be excluded	$V_{IN}=V_{CC}$ or GND $I_{OUT}=0\mu A$	6.0	4.0	40	160	μА

[Phase Comparator Section]

$\textbf{AC ELECTRICAL CHARACTERISTICS}(C_L = 50 pF, Input \ t_r = t_f = 6.0 \ ns)$

		V_{CC}	Gu	Guaranteed Limit		
Symbol	Parameter	V	25 °C to -55°C	≤85°C	≤125°C	Unit
$t_{\rm PLH}, t_{\rm PHL}$	Maximum Propagation Delay, $SIG_{IN}/COMP_{IN}$ to $PC1_{OUT}$ (Figure 1)	2.0 4.5 6.0	175 35 30	220 44 37	265 53 45	ns
$t_{\rm PLH}, t_{\rm PHL}$	Maximum Propagation Delay, SIG _{IN} /COMP _{IN} to PCP _{OUT} (Figure 1)	2.0 4.5 6.0	340 68 58	425 85 72	510 102 87	ns
$t_{\rm PLH}, t_{\rm PHL}$	Maximum Propagation Delay , $SIG_{IN}/COMP_{IN}$ to $PC3_{OUT}$ (Figure 1)	2.0 4.5 6.0	270 54 46	340 68 58	405 81 69	ns
t_{PLZ}, t_{PHZ}	$\label{eq:maximum} \begin{array}{l} \text{Maximum Propagation Delay , SIG}_{\text{IN}}/\text{COMP}_{\text{IN}} \\ \text{Output Disable Time to PC2}_{\text{OUT}} \\ \text{(Figures 2 and 3)} \end{array}$	2.0 4.5 6.0	200 40 34	250 50 43	300 60 51	ns
t_{PZL}, t_{PZH}	$\begin{array}{c} \text{Maximum Propagation Delay , SIG}_{\text{IN}}/\text{COMP}_{\text{IN}} \\ \text{Output Enable Time to PC2}_{\text{OUT}} \\ \text{(Figures 2 and 3)} \end{array}$	2.0 4.5 6.0	230 46 39	290 58 49	345 69 59	ns
t_{TLH}, t_{THL}	Maximum Output Transition Time (Figure 1)	2.0 4.5 6.0	75 15 13	95 19 16	110 22 19	ns

[VCO Section]

DC ELECTRICAL CHARACTERISTICS (Voltages Referenced to GND)

			V_{CC}	Guar			
Symbol	Parameter	Test Conditions	V	25 °C to-55°C	≤85°C	≤125°C	Unit
V _{IH}	Minimum High-Level Input Voltage INH	$V_{OUT} = 0.1 \text{ V or}$ $V_{CC} = 0.1 \text{ V}$ $ I_{OUT} \le 20 \mu\text{A}$	3.0 4.5 6.0	2.1 3.15 4.2	2.1 3.15 4.2	2.1 3.15 4.2	V
V_{IL}	Maximum Low -Level Input Voltage INH	V_{OUT} =0.1 V or V_{CC} - 0.1 V $ I_{OUT} \le 20 \mu\text{A}$	3.0 4.5 6.0	0.90 1.35 1.8	0.90 1.35 1.8	0.90 1.35 1.8	V
V _{OH}	Minimum High-Level Output Voltage VCO _{OUT}	$V_{IN}=V_{IH} \text{ or } V_{IL}$ $ I_{OUT} \le 20 \mu\text{A}$	3.0 4.5 6.0	1.9 4.4 5.9	1.9 4.4 5.9	1.9 4.4 5.9	V
		$\begin{aligned} & V_{\text{IN}} = V_{\text{IH}} \text{ or } V_{\text{IL}} \\ & \mid I_{\text{OUT}} \mid \leq 4.0 \text{ mA} \\ & \mid I_{\text{OUT}} \mid \leq 5.2 \text{ mA} \end{aligned}$	4.5 6.0	3.98 5.48	3.84 5.34	3.7 5.2	
$V_{ m OL}$	Maximum Low-Level Output Voltage VCO _{OUT}	$V_{IN}=V_{IH} \text{ or } V_{IL}$ $\mid I_{OUT} \mid \leq 20 \mu\text{A}$	3.0 4.5 6.0	0.1 0.1 0.1	0.1 0.1 0.1	0.1 0.1 0.1	V
		$\begin{aligned} &V_{\text{IN}} = V_{\text{IH}} \text{ or } V_{\text{IL}} \\ & I_{\text{OUT}} \leq 4.0 \text{ mA} \\ & I_{\text{OUT}} \leq 5.2 \text{ mA} \end{aligned}$	4.5 6.0	0.26 0.26	0.33 0.33	0.4 0.4	

(continued)

[VCO Section]

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			V_{CC}	Guaranteed Limit												
Symbol	Parameter	Test Conditions	V	25 °C to -55°C						≤85°C		≤85°C		≤12	25°C	Unit
I_{IN}	Maximum Input Leakage Current INH, VCO _{IN}	$V_{\rm IN}$ = $V_{\rm cc}$ or GND	6.0	0.1		0.1		1	.0	1	.0	μА				
				Min	Max	Min	Max	Min	Max							
V _{vcoin}	Operating Voltage Range at VCO _{IN} over the range specified for R1; For linearity see Fig.13A, Parallel value of R1 and R2 should be $>2.7 \text{ k}\Omega$	INH= V _{IL}	3.0 4.5 6.0	0.1 0.1 0.1	1.0 2.5 4.0	0.1 0.1 0.1	1.0 2.5 4.0	0.1 0.1 0.1	1.0 2.5 4.0	V						
R1	Resistor Range		3.0 4.5 6.0	3.0 3.0 3.0	300 300 300	3.0 3.0 3.0	300 300 300	3.0 3.0 3.0	300 300 300	kΩ						
R2			3.0 4.5 6.0	3.0 3.0 3.0	300 300 300	3.0 3.0 3.0	300 300 300	3.0 3.0 3.0	300 300 300							
C1	Capacitor Range		3.0 4.5 6.0	40 40 40	No Li- mit					pF						

[VCO Section]

$\textbf{AC ELECTRICAL CHARACTERISTICS}(C_L = 50 pF, Input \ t_r = t_f = 6.0 \ ns)$

		V_{CC}		(Guarante												
Symbol	Parameter	V	25 °C to -55°C										≤8.	5°C	≤12	25°C	Unit
			Min	Max	Min	Max	Min	Max									
Δf/T	Frequency Stability with Temperature Changes (Figures 11A,B,C)	3.0 4.5 6.0							%/K								
fo	VCO Center Frequency (Duty Factor = 50%) (Figures 12A,B,C)	3.0 4.5 6.0	3 11 13						MHz								
ΔfVCO	VCO Frequency Linearity	3.0 4.5 6.0	See Figures 13A,B						%								
∂VCO	Duty Factor at VCO _{OUT}	3.0 4.5 6.0	Typical 50%						%								

[Demodulator Section]

DC ELECTRICAL CHARACTERISTICS

			V_{CC}	G		Guarante										
Symbol	Parameter	Test Conditions	V	25 °C to -55°C								≤8.5	5°C	≤12	25°C	Unit
				Min	Max	Min	Max	Min	Max							
RS	Resistor Range	$At RS > 300 k\Omega$ the Leakage Current can Influence $VDEM_{OUT}$	3.0 4.5 6.0	50 50 50	300 300 300					kΩ						
V _{OFF}	Offset Voltage VCO _{IN} to VDEM _{OUT}	V _I = VVCO _{IN} = 1/2 V _{CC} ; Values taken over RS Range	3.0 4.5 6.0	See Figure 10					mV							
RD	Dynamic Output Resistance at DEM _{OUT}	$VDEM_{OUT} = 1/2 V_{CC}$	3.0 4.5 6.0	Typical 25 Ω					Ω							

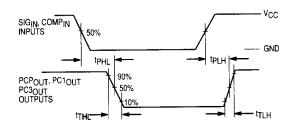


Figure 1. Switching Waveforms

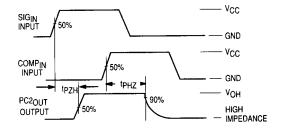


Figure 2. Switching Waveforms

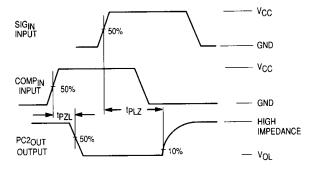
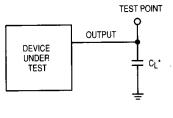


Figure 3. Switching Waveforms



*INCLUDES ALL PROBE AND JIG CAPACITANCE

Figure 4. Test Circuit

DETAILED CIRCUIT DESCRIPTION

Voltage Controlled Oscillator/Demodulator Output

The VCO requires two or three external components to operate. These are R1, R2, C1. Resistor R1 and Capacitor C1 are selected to determine the center frequency of the VCO (see typical performance curves Figure 12). R2 can be used to set the offset frequency with 0 volts at VCO input. For example, if R2 is decreased, the offset frequency is increased. If R2 is omitted the VCO range is from 0 Hz. By increasing the value of R2 the lock range of the PLL is increased and the gain (volts/Hz) is decreased. Thus, for a narrow lock range, large swings on the VCO input will cause less frequency variation.

Internally, the resistors set a current in a current mirror, as shown in Figure 5. The mirrored current drives one side of the capacitor. Once the voltage across the capacitor charges up to $V_{\rm ref}$ of the comparators, the oscillator logic flips the capacitor which causes the mirror to change the opposite side of

the capacitor. The output from the internal logic is then taken to VCO output (Pin4).

The input to the VCO is a very high impedance CMOS input and thus will not load down the loop filter, easing the filters design. In order to make signals at the VCO input accessible without degrading the loop performance, the VCO input voltage is buffered through a unity gain Op-amp, to Demod Output. This Op-amp can drive loads of 50K ohms or more and provides no loading effects to the VCO input voltage (see Figure 10).

An inhibit input is provided to allow disabling of the VCO and all Op-amps (see Figure 5). This is useful if the internal VCO is not being used. A logic high on inhibit disables the VCO and all Op-amps, minimizing standby power consumption.

The output of the VCO is a standard high speed CMOS output with an equivalent LS-TTL fan out of 10. The VCO output is approximately a square wave. This output can either directly feed the $COMP_{IN}$ of the phase comparators or feed external prescalers (counters) to enable frequency synthesis.

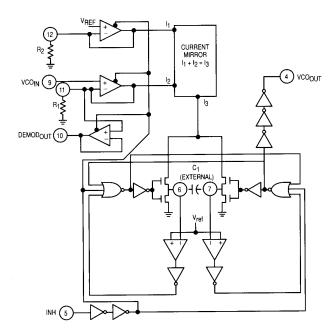


Figure 5. Logic Diagram for VCO

Phase Comparators

All three phase comparators have two inputs, SIG_{IN} and $COMP_{IN}$. The SIG_{IN} and $COMP_{IN}$ have a special DC bias network that enables AC coupling of input signals. If the signals are not AC coupled, standard SL74HC input levels are required. Both input structures are shown in Figure 6. The outputs of these

comparators are essentially standard SL74HC outputs (comparator 2 is TRI-STATEABLE). In normal operation $V_{\rm CC}$ and ground voltage levels are fed to the loop filter. This differs from some phase detectors which supply a current to the loop filter and should be considered in the design.

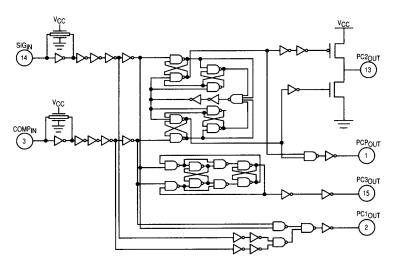


Figure 6. Logic Diagram for Phase Comparators

Phase Comparator 1

This comparator is a simple XOR gate similar to the SL74HC86. Its operation is similar to an overdriven balanced modulator. To maximize lock range the input frequencies must have a 50% duty cycle. Typical input and output waveforms are shown in Figure 7. The output of the phase detector feeds the loop filter which averages the output voltage. The frequency range upon which the PLL will lock onto if initially out of lock is defined as the capture range. The capture range for phase detector 1 is dependent on the loop filter design. The capture range can be as large as the lock range, which is equal to the VCO frequency range.

To see how the detector operates, refer to Figure 7. When two square wave signals are applied to this comparator, an output waveform (whose duty cycle is dependent on the phase difference between the two signals) results. As the phase difference increases, the output duty cycle increases and the voltage after the loop filter increases. In order to achieve lock when the PLL input frequency increases, the VCO input voltage must increase and the phase difference between COMP $_{\rm IN}$ and SIG $_{\rm IN}$ will increase. At an input frequency equal to $f_{\rm min}$, the VCO input is at 0 V

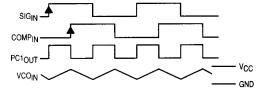


Figure 7. Typical Waveforms for PLL Using Phase Comparator 1

This requires the phase detector output to be grounded; hence, the two input signals must be in phase. When the input frequency is f_{max} , the VCO input must be V_{CC} and the phase detector inputs must be 180 degrees out of phase.

The XOR is more susceptible to locking onto harmonics of the $SIG_{\rm IN}$ than the digital phase detector 2. For instance, a signal 2 times the VCO frequency results in the same output duty cycle as a signal equal to the VCO frequency. The difference is hat the output frequency of the 2f example is twice that of the other example. The loop filter and VCO range should be designed to prevent locking on to harmonics.

Phase Comparator 2

This detector is a digital memory network. It consists of four flip-flops and some gating logic, a three state output and a phase pulse output as shown in Figure 6. This comparator acts only on the positive edges of the input signals and is independent of duty cycle.

Phase comparator 2 operates in such a way as to force the PLL into lock with 0 phase difference between the VCO output and the signal input positive waveform edges. Figure 8 shows some typical loop waveforms. First assume that SIG_{IN} is leading the $COMP_{IN}$. This means that the VCO's frequency must be increased to bring its leding edge into proper phase alignment. Thus the phase detector 2 output is set high. This will cause the loop filter to charge up the VCO input, increasing the VCO frequency. Once the leading edge of the $COMP_{IN}$ is detected, the output goes TRI-STATE holding the VCO input at the loop filter voltage. If the VCO still lags the SIG_{IN} then the phase detector will again charge up the VCO input for the time between the leading edges of both waveforms.

If the VCO leads the SIG_{IN} then when the leading edge of the VCO is seen; the output of the phase comparator goes low. This discharges the loop filter until the leading edge of the SIG_{IN} is detected at which time the output disables itself again. This has the effect of slowing down the VCO to again make the rising edges of both waveforms coincidental.

When the PLL is out of lock, the VCO will be running either slower or faster than the SIG_{IN} . If it is running slower the phase detector will see more SIG_{IN} rising edges and so the output of the phase comparator will be high a majority of the time, raising the VCO's frequency. Conversely, if the VCO is running faster than the SIG_{IN} , the output of the detector will be low most of the time and the VCO's output frequency will be decreased.

As one can see, when the PLL is locked, the output of phase comparator 2 will be disabled except for minor corrections at the leading edge of the waveforms. When PC_2 is TRI-STATED, the PCP output is high. This output can be used to determine when the PLL is in the locked condition.

This detector has several interesting characteristics. Over the entire VCO frequency range there is no phase difference between the $COMP_{IN}$ and the SIG_{IN} . The lock range of the PLL is the same as the capture range. Minimal power was consumed in the loop filter since in lock the detector output is a high impedance. When no SIG_{IN} is present, the detector will

see only VCO leading edges, so the comparator output will stay low, forcing the VCO to f_{\min} .

Phase comparator 2 is more susceptible to noise, causing the PLL to unlock. If a noise pulse is seen on the $SIG_{\rm IN}$, the comparator treats it as another positive edge of the $SIG_{\rm IN}$ and will cause the output to go high until the VCO leding edge is see, potentially for an entire $SIG_{\rm IN}$ period. This would cause the VCO to speed up during that time. When using PC_1 , the output of that phase detector would be disturbed for only the short duration of the noise spike and would cause less upset.

Phase Comparator 3

This is positive edge-triggered sequential phase detector using an RS flip-flop as shown in Figure 6. When the PLL is using this comparator, the loop is controlled by positive signal transitions and the duty factors of SIG_{IN} and $COMP_{IN}$ are not important. It has some similar characteristics to the edge sensitive comparator. To see how this detector works, assume input pulses are applied to the SIGN_{IN} and COMP_{IN}'s as shown in Figure 9. When the SIGN_{IN} leads the COMP_{IN}, the flop is set. This will charge the loop filter and cause the VCO to speed up, bringing the comparator into phase with the SIG_{IN} . The phase angle between SIG_{IN} and COMP_{IN} varies from 0° to 360° and is 180° at f_o. The voltage swing for PC₃ is greater than for PC₂ but consequently has more ripple in the signal to the VCO . When no SIG_{IN} is present the VCO will be forced to f_{max} as opposed to fmin when PC₂ is used.

The operating characteristics of all three phase comparators tors should be compared to the requirement of the system design and the appropriate one should be used.

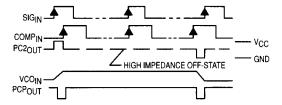


Figure 8. Typical Waveforms for PLL Using Phase Comparator 2

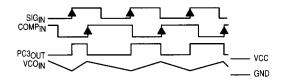


Figure 9. Typical Waveforms for PLL Using Phase Comparator 3



INTEGRAL

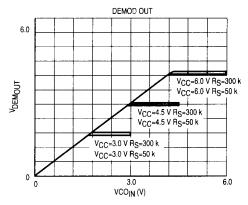


Figure 10. Offset Voltage at Demodulator Output as a Function of $VCO_{\rm IN}$ and $R_{\rm S}$

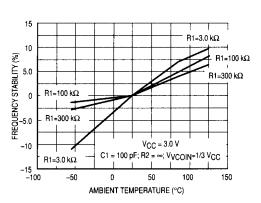


Figure 11A. Frequency Stability versus Ambient Temperature: $V_{\rm CC}$ = 3.0 V

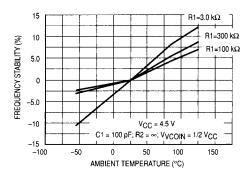


Figure 11B. Frequency Stability versus Ambient Temperature: $V_{\rm CC}$ = 4.5 V

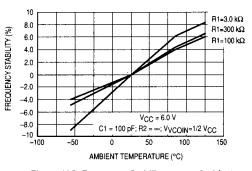
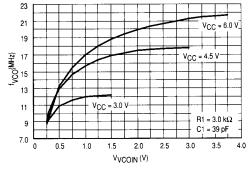


Figure 11C. Frequency Stability versus Ambient Temperature: $V_{\rm CC}$ = 6.0 V



 $\label{eq:Figure 12A.VCO} Frequency \left(f_{VCO}\right) as \ a \ Function \ of \\ the \ VCO \ Input \ Voltage \left(V_{VCOIN}\right)$

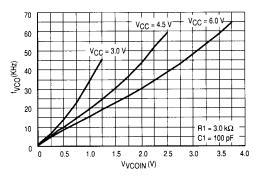


Figure 12B. VCO Frequency (f_{VCO}) as a Function of the VCO Input Voltage (V_{VCOIN})

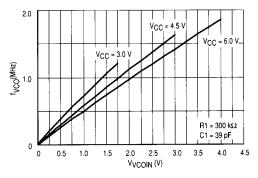
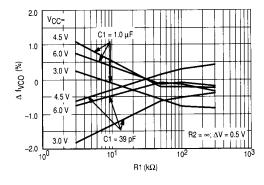


Figure 12C. VCO Frequency (f_{VCO}) as a Function of the VCO Input Voltage (V_{VCOIN})

Figure 12D. VCO Frequency (f_{VCO}) as a Function of the VCO Input Voltage (V_{VCOIN})



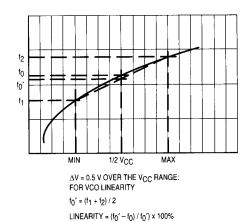


Figure 13A. Frequency Linearity versus R1,C1 and $$V_{\rm CC}$$

Figure~13B.~Definition~of~VCO~Frequency~Linearity)

