

# **Dual S-Video Lowpass Filter with Phase and Sinx/x Equalization**

## **GENERAL DESCRIPTION**

The ML6423 monolithic BiCMOS 6th-order filter provides a two-channel fixed frequency lowpass filtering for video applications. This dual phase equalized filter with sinx/x correction is designed for reconstruction filtering at the output of a Video DAC. A composite sum output eliminates the need for a third DAC.

Cutoff frequencies are either 5.5MHz or 9.6MHz. Each channel incorporates a 6th-order lowpass filter, a first order allpass filter, a gain boost circuit, and a  $75\Omega$  coax cable driver. A control pin (RANGE) is provided to allow the inputs to swing from 0 to 1V, or 0.5 to 1.5V, by providing a 0.5V offset to the input.

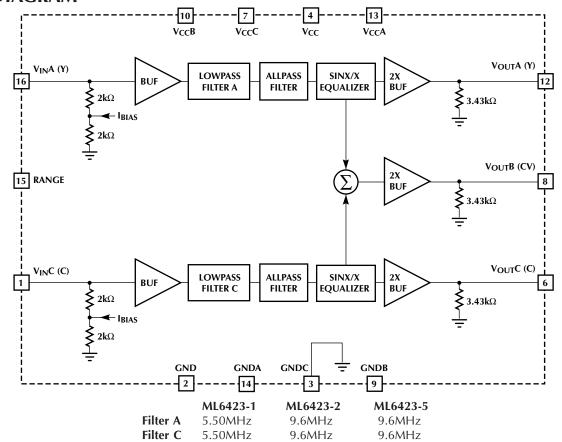
The 2X gain filters are powered from a single 5V supply, and can drive  $1V_{P-P}$  into  $75\Omega$  (0.5V to 1.5V), or  $2V_{P-P}$  into  $150\Omega$  (0.5V to 2.5V) with the internal coax drivers.

#### **FEATURES**

- 5.5 or 9.6MHz bandwidth with 6dB gain
- >40dB stopband rejection
- No external components or clocks
- ±10% frequency accuracy over maximum supply and temperature variation
- <2% differential gain, <2° differential phase
- <20ns group delay variation
- 5V ±10% operation
- Composite (sum) output
- High sink current for AC coupled loads, ML6423-5

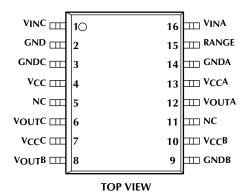
\* This Product Is End Of Life As Of August 1, 2000

#### **BLOCK DIAGRAM**



# **PIN CONFIGURATION**

ML6423 16-Pin Wide SOIC (\$16W)



# **PIN DESCRIPTION**

PIN	NAME	FUNCTION	PIN	NAME	FUNCTION
1	$V_{IN}C$	Signal input to filter C. Input impedance is $4k\Omega$ .	10	$V_{CC}B$	Power supply voltage for output B.
		•	11	NC	No Connect
2	GND	Power and logic ground.	10	\ / A	Output of filter A. Drive is 1V.
3	GNDC	Ground pin for filter C.	12	V <sub>OUT</sub> A	Output of filter A. Drive is $1V_{P-P}$ into $75\Omega$ (0.5V to 1.5V) or $2V_{P-P}$ into $150\Omega$ (0.5V to 2.5V).
4	$V_{CC}$	Positive supply: 4.5V to 5.5V.			(613 ) (6 213 ))
		,	13	$V_{CC}A$	Power supply voltage for filter A.
5	NC	No Connect	1.4	CNDA	
6	VC	Output of filter C. Drive is $1V_{P-P}$ into	14	GNDA	Ground pin for filter A.
O	V <sub>OUT</sub> C	75 $\Omega$ (0.5V to 1.5V) or 2V <sub>P-P</sub> into 150 $\Omega$ (0.5V to 2.5V).	15	range	Input signal range select. When RANGE is low (0), the input signal range is 0.5V to 1.5V, with an output
7	$V_{CC}C$	Power supply voltage for filter C.			range of 0.5V to 2.5V. When RANGE is high (1) the input signal range is 0V
8	$V_{OUT}B$	Sum of Filter A and Filter C. Drive is $1V_{P-P}$ into $75\Omega$ (0.5V to 1.5V) or $2V_{P-P}$ into $150\Omega$ (0.5V to 2.5V).			to 1V, while the output range is 0.5V to 2.5V.
			16	$V_{IN}A$	Signal input to filter A. Input
9	GNDB	Ground pin for output B.			impedance is $4k\Omega$ .

# **ABSOLUTE MAXIMUM RATINGS**

Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

Supply Voltage (V <sub>CC</sub> )	0.3 to 7V
GND	
Logic Inputs	$-0.3$ to $V_{CC} + 0.3V$
Input Current per Pin	±25mA

Storage Temperature	–65° to 150°C
Lead Temperature (Soldering 10 sec)	150°C
Thermal Resistance $(\theta_{IA})$	65°C/W

# **OPERATING CONDITIONS**

Supply Voltage	5V ±10%
Temperature Range	

# **ELECTRICAL CHARACTERISTICS**

Unless otherwise specified  $V_{CC}$  = 5V  $\pm$  10%,  $R_L$  =75 $\Omega$  or 150 $\Omega$ ,  $V_{OUT}$  = 2 $V_{P-P}$  for 150 $\Omega$  Load and  $V_{OUT}$  = 1 $V_{P-P}$  for 75 $\Omega$  Load,  $T_A$  = Operating Temperature Range (Notes 1, 2, 3)

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
GENERAL		,	•	•	•	
R <sub>IN</sub>	Input Impedance		3k	4	5	kΩ
DR/R <sub>IN</sub>	Input R Matching				±2	%
I <sub>BIAS</sub>	Input Current	$V_{IN} = 0.5V$ , RANGE = low		45		μΑ
		V <sub>IN</sub> = 0.0V, RANGE = high	-210		μΑ	
	Differential Gain	V <sub>IN</sub> = 0.8V to 1.5V at 3.58 & 4.43 MHz		1		%
	Differential Phase	V <sub>IN</sub> = 0.8V to 1.5V at 3.58 & 4.43 MHz		1		deg
V <sub>IN</sub>	Input Range	RANGE = Low	0.5		1.5	V
		RANGE = High	3k  IN = 0.5V, RANGE = low  IN = 0.8V to 1.5V		1.0	V
	Peak Overshoot	2T, 0.7V <sub>P-P</sub> pulse		2.0		%
	Crosstalk Rejection	$f_{IN} = 3.58$ , $f_{IN} = 4.43$ MHz	45			dB
	Channel to Channel Group Delay Matching (f <sub>C</sub> = 5.5MHz)	f <sub>IN</sub> = 100kHz		±3		ns
	Channel to Channel Gain Matching	f <sub>IN</sub> = 100kHz		±1.5		%
	Output Current	R <sub>L</sub> = 0 (short circuit)		75		mA
C <sub>L</sub>	Load Capacitance				35	pF
	Composite Chroma/Luma delay	$f_C = 5.5MHz$		±15		ns
		$f_C = 9.6MHz$		±8		ns
5.50MHz l	FILTER					
	Bandwidth (monotonic passband)	-0.55dB (Note 4)	4.95	5.50	6.05	MHz
	Subcarrier Frequency Gain	$f_{IN} = 3.58MHz$	0.9	1.4	2.3	dB
	ML6423-1	$f_{IN} = 4.43MHz$	1.1	1.6	2.5	dB
	Attenuation	$f_{IN} = 10MHz$	20	25		dB
		$f_{IN} = 50MHz$	45	55		dB
	Output Noise	BW = 30MHz			1	mV <sub>RMS</sub>
	Group Delay			180		ns

# **ELECTRICAL CHARACTERISTICS** (Continued)

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
5.50MHz I	FILTER (Continued)				_	
	Small Signal Gain	$V_{IN} = 100 \text{mV}_{P-P}$ at $100 \text{kHz}$ , Filter A or C	5.5	6	6.5	dB
	Composite (CV) Small Signal Gain	$V_{IN}A$ , $C = 100 \text{mV}_{P-P}$ at $100 \text{kHz}$	11	12	13	dB
9.6MHz FI	LTER				_	
	Bandwidth (monotonic passband)	-2dB (Note 4)	8.6	9.6	10.6	MHz
	Subcarrier Frequency Gain	$f_{IN} = 3.58MHz$	-0.1	0.4	1.1	dB
	ML6423-2	$f_{IN} = 4.43MHz$	-0.1	0.6	1.3	dB
	Subcarrier Frequncy Gain	$f_{IN} = 3.58MHz$	-0.1	0.4	1.9	dB
	ML6423-5	$f_{IN} = 4.43MHz$	-0.1	0.6	1.1	dB
	Attenuation	$f_{IN} = 17MHz$	20	25		dB
		$f_{IN} = 85MHz$	45	55		dB
	Output Noise	BW = 30MHz			1	mV <sub>RMS</sub>
	Group Delay				100	ns
	Composite (CV) Small Signal Gain	$V_{IN}A$ , $C = 100 \text{mV}_{P-P}$ at $100 \text{kHz}$	11	12	13	dB
I <sub>CC</sub>	ML6423-5 Supply Current $R_L = 150\Omega$	V <sub>IN</sub> = 0.5V (Note 5)		140	175	mA
		V <sub>IN</sub> = 1.5V		170	215	mA
	ML6423-5 V <sub>OUT</sub> A, V <sub>OUT</sub> B sink current	$V_{IN} = 0.5V$	8.3	11.5		mA
	ML6423-5 V <sub>OUT</sub> C sink current	$V_{IN} = 0.5V$	4.3	6.5		mA
	ML6423-5 Output DC Level	V <sub>IN</sub> = 0.5V, Range = Low		0.5		V
DIGITAL A	AND DC		'		•	•
V <sub>IL</sub>	Logic Input Low	Range			0.8	V
V <sub>IH</sub>	Logic Input High	Range	V <sub>CC</sub> - 0.8			V
I <sub>IL</sub>	Logic Input Low	V <sub>IN</sub> = GND	-1			μA
I <sub>IL</sub>	Logic Input High	$V_{IN} = V_{CC}$			1	μΑ
I <sub>CC</sub>	Supply Current $R_L = 150\Omega$	V <sub>IN</sub> = 0.5V (Note 5)		110	135	mA
		V <sub>IN</sub> = 1.5V		140	175	mA

**Note 1:** Limits are guaranteed by 100% testing, sampling or correlation with worst case test conditions.

Note 2: Maximum resistance on the outputs is  $500\Omega$  in order to improve step response.

**Note 3:** Connect all ground pins to the ground plane via the shortest path.

Note 4: The bandwidth is the -3dB frequency of the unboosted filter. This represents the attenuation that results from boosting the gain from the -3dB point at the specified frequency.

**Note 5:** Power dissipation:  $P_D = (I_{CC} \times V_{CC}) - [3(V_{OUT}^2/RL)]$ 

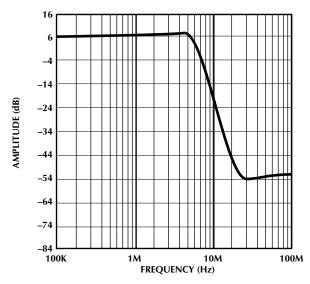


Figure 1a. Stop-Band Amplitude vs. Frequency  $(f_C = 5.5MHz)$ 

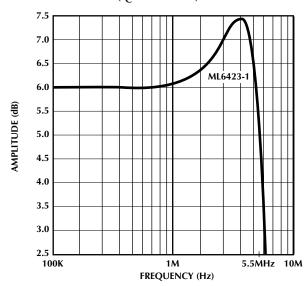


Figure 2a. Pass-Band Amplitude vs. Frequency  $(f_C = 5.5MHz)$ 

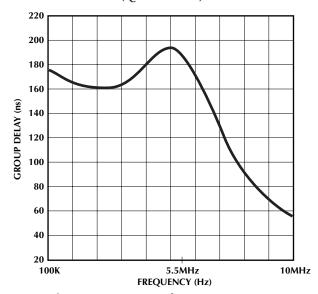


Figure 3a. Group Delay vs. Frequency (f<sub>C</sub> = 5.5MHz)

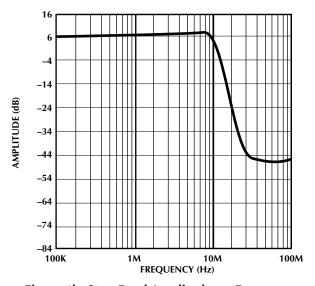


Figure 1b. Stop-Band Amplitude vs. Frequency  $(f_C = 9.6MHz)$ 

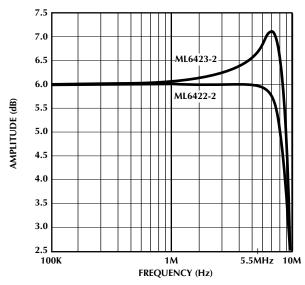


Figure 2b. Pass-Band Amplitude vs. Frequency  $(f_C = 9.6MHz)$ 

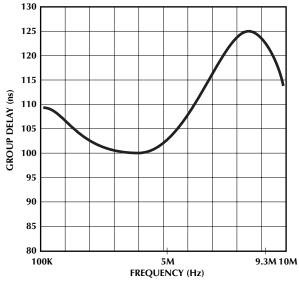


Figure 3b. Group Delay vs. Frequency  $(f_C = 9.6MHz)$ 

## **FUNCTIONAL DESCRIPTION**

The ML6423 single-chip dual video filter is intended for low cost professional and consumer video applications. Each of the two channels incorporates an input buffer amplifier, a 6th-order lowpass filter, a 1st-order allpass equalizer, sinx/x equalizer and an output 2X gain amplifier capable of driving 75 $\Omega$  to ground. A third output (B) is the sum of the A and C inputs and have the identical output amplifier as the A and C channels.

The ML6423 can be driven by a DAC with RANGE down to 0V. When RANGE is low the input range is 0.5V to 1.5V. When the input signal range is 0V to 0.1V, RANGE should be tied high. In this case, an offset is added to the input so that the output swing is kept between 0.5V to 2.5V. The output amplifier is capable of driving up to 24mA of peak current; therefore the output voltage should not exceed 1.8V when driving 75 $\Omega$  to ground.

## **APPLICATION GUIDELINES**

#### **OUTPUT & INPUT CONSIDERATIONS**

The dual filters have 2X gain. The circuit has 2X gain (6dB) when connected to a 150W load, and 0dB gain when driving a  $75\Omega$  load via a  $75\Omega$  series output resistor. The output may be either AC or DC coupled. For AC coupling, the -3dB point should be 5Hz or less. There must also be a DC path of  $\leq 500\Omega$  to ground for output biasing. The ML6423-5 provides higher sink current to better drive AC coupled loads.

The input resistance is  $4k\Omega$ . The input may be either DC or AC coupled. (Note that each input sources 80 to  $125\mu A$  of bias current). The ML6423 is designed to be directly driven by a DAC. For current output video DACs, a  $75\Omega$  or  $150\Omega$  resistor to ground may need to be added to the DAC output (filter input).

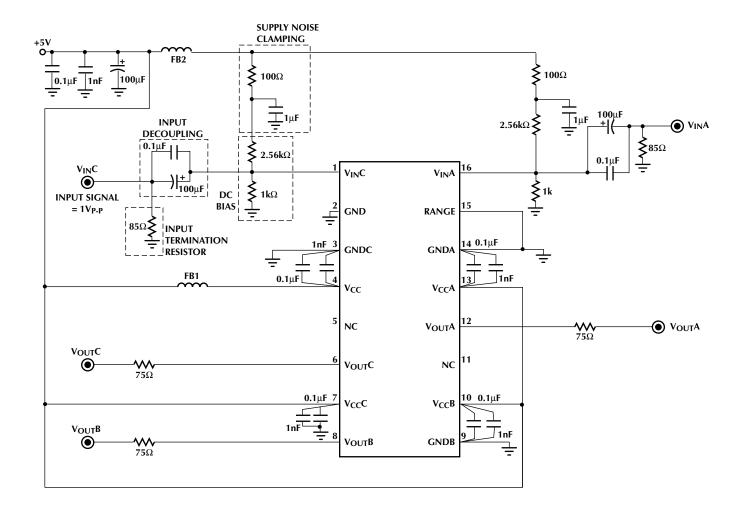


Figure 4. ML6423 AC Coupled DC Bias Test Circuit

#### **APPLICATION GUIDELINES** (Continued)

#### LAYOUT CONSIDERATIONS

In order to obtain full performance from these dual filters, layout is very important. Good high frequency decoupling is required between each power supply and ground. Otherwise, oscillations and/or excessive crosstalk may occur. A ground plane is recommended.

Each filter has its own supply and ground pins. In the test circuit,  $0.1\mu F$  capacitors are connected in parallel with 1nF capacitors on all  $V_{CC}$  pins for maximum noise rejection (Figure 4).

Further noise reduction is achieved by using series ferrite beads. In typical applications, this degree of bypassing may not be necessary.

Since there are two filters and a sum output driver in one package, space the signal leads away from each other as much as possible.

#### **POWER CONSIDERATIONS**

The ML6423 power dissipation follows the formula:

$$P_{D} = (I_{CC} \times V_{CC}) - \left[ \left( \frac{V_{OUT}^{2}}{RL} \times 3 \right) \right]$$

This is a measure of the amount of current the part sinks (current in – current out to the load).

Under worst case conditions:

$$P_D = (0.175 \times 5.5) - \left[ \left( \frac{1.5^2}{75} \times 3 \right) \right] = 872.5 \text{mW}$$

#### **FILTER SELECTION**

The ML6423 provides several choices in filter cutoff frequencies depending on the application.

**S-Video:** For Y/C (S-video) and Y/C + CV (Composite Video) systems the 5.5MHz or 9.6MHz filters are appropriate. In NTSC the C signal occupies the bandwidth from about 2.6MHz to about 4.6MHz, while in PAL the C signal occupies the bandwidth from about 3.4MHz to about 5.4MHz. In both cases, a 5.5MHz lowpass filter provides adequate rejection for both sampling and reconstruction. In addition, using the same filter for both Y/C and CV maintains identical signal timing without adjustments.

**Composite:** When one or more composite signals need to be filtered, then the 5.5MHz and 9.6MHz filters permit filtering of one, two, or three composite signals.

Over Sampling: While the ML6423 filters can eliminate the need for over sampling combined with digital filtering, there are times when over sampling is used. For these situations, 9.3MHz could be used in place of 5.5MHz

NTSC/PAL: A 5.5MHz cutoff frequency provides good filtering for 4.2MHz, 5.0MHz and 5.5MHz signals without the need to change filters on a production basis.

Sinx/x: For digital video system with output D/A converters, there is a fall off in response with frequency due to discrete sampling. The fall off follows a sinx/x response (Figure 5a). The ML6423 filters have a complementary boost to provide a flatter overall response. The boost is designed for 13.5MHz Y/C and CV sampling and 6.75MHz U/V sampling.

In a typical application (Figure 5b) the ML6423 is used as the final output device in a video processing chain. In this case, inputs to the ML6423 are supplied by DAC outputs with their associated load resistors (typically  $75\Omega$  or  $150\Omega$ ). Resistance values should be adjusted to provide  $1V_{P-P}$  at the input of the ML6423. The ML6423 will drive  $75\Omega$  source termination resistors (making the total load  $150\Omega$ ) so that no external drivers or amplifiers are required.

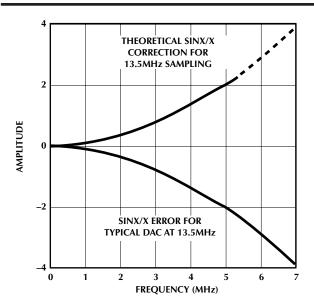


Figure 5a. Sinx/x Frequency Response

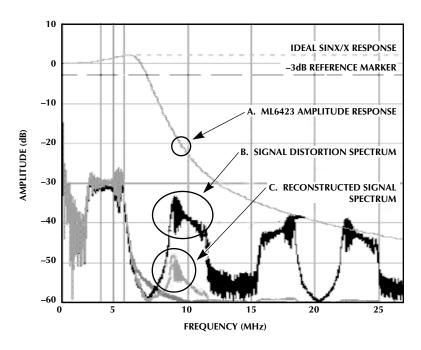


Figure 6. ML6423 Reconstruction Performance in the Frequency Domain

#### **FILTER PERFORMANCE**

The reconstruction performance of a filter is based on its ability to remove the high band spectral artifacts that result from the sampling process without distorting the valid signal spectral contents within the passband. For video signals, the effect of these artifacts is a variation of the amplitude of small detail elements in the picture (such as highlights or fine pattern details) as the elements move relative to the sampling clock. The result is similar to the aliasing problem and causes a "winking" of details as they move in the picture.

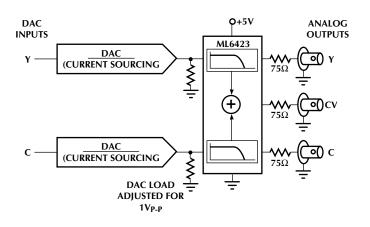


Figure 5b. Typical ML6423 Reconstruction Application

Figure 6 shows the problem in the frequency domain. Curve A shows the amplitude response of the ML6423 filter, while curve B shows the signal spectrum as it is distorted by the sampling process. Curve C shows the composite of the two curves which is the result of passing the sampled waveform through the ML6423. It is clear that the distortion artifacts are reduced significantly.

Ultimately it is the time domain signal that is viewed on a TV monitor, so the effect of the reconstruction filter on the time domain signal is important. Figure 7 shows the sampling artifacts in the time domain. Curve A is the original signal, curve B is the result of CCIR601 sampling, and curve C is the same signal filtered through the ML6423. Again the distortions in the signal are essentially removed by the filter.

In an effort to measure the time domain effectiveness of a reconstruction filter, Figure 8 was generated from a swept frequency waveform. Curves A, B, and C are generated as in Figure 7, but additional curves D and E help quantify the effect of filtering in the time domain. Curves D and E represent the envelopes (instantaneous amplitudes) of curves B and C. Again, it is evident in curve D that the envelope varies significantly due to the sampling process. In curve E, filtering with the ML6423 removes these artifacts and generates an analog output signal that rivals the oversampled (and more ideal) signal waveforms. The ML6423 reduces the amplitude variation from over 6% to less than 1%.

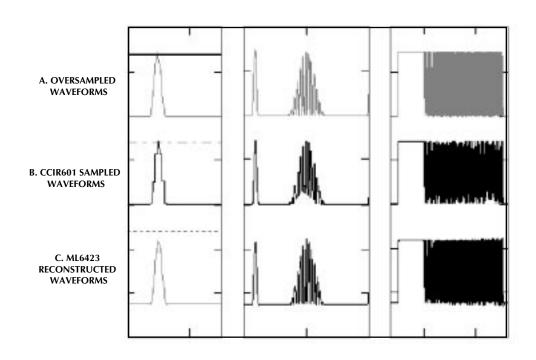


Figure 7. ML6423 Reconstruction Performance in the Time Domain

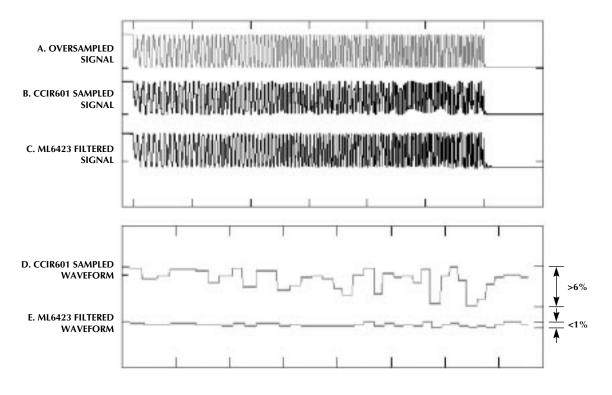
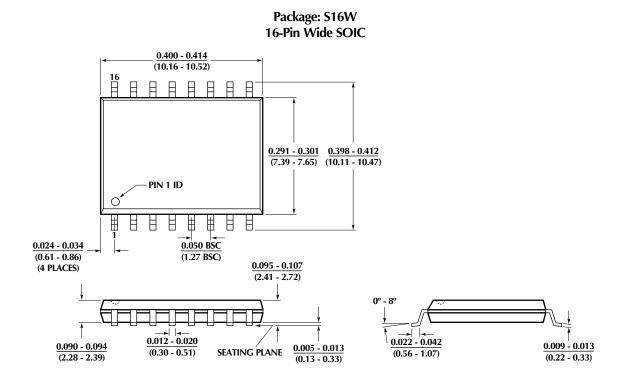


Figure 8. Amplitude Ripple of Reconstructed Swept Pulses

#### PHYSICAL DIMENSIONS inches (millimeters)



#### ORDERING INFORMATION

PART NUMBER	BW (MHz)	TEMPERATURE RANGE	PACKAGE
ML6423CS-1 (EOL)	5.5/5.5	0°C to 70°C	16-pin Wide SOIC (S16W)
ML6423CS-2 (EOL)	9.6/9.6	0°C to 70°C	16-pin Wide SOIC (S16W)
ML6423CS-5 (Obsolete)	<mark>9.6/9.6</mark>	0°C to 70°C	16-pin Wide SOIC (S16W)

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