

### Dual 300MHz Current Feedback Amplifier

### **Features**

- 300MHz -3dB bandwidth
- 4mA supply current (per amplifier)
- Single and dual supply operation, from 5V to 10V
- Single (EL5193C) and triple (EL5393C) available
- High speed, 1GHz product available (EL5191C)
- High speed, 6mA, 600MHz product available (EL5192C, EL5292C, and EL5392C

### **Applications**

- Battery-powered Equipment
- Hand-held, Portable Devices
- Video Amplifiers
- Cable Drivers
- RGB Amplifiers
- Test Equipment
- Instrumentation
- Current to Voltage Converters

## **Ordering Information**

| Part No      | Package  | Tape &<br>Reel | Outline # |
|--------------|----------|----------------|-----------|
| EL5293CS     | 8-Pin SO | -              | MDP0027   |
| EL5293CS-T7  | 8-Pin SO | 7"             | MDP0027   |
| EL5293CS-T13 | 8-Pin SO | 13"            | MDP0027   |

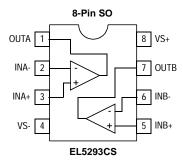
## **General Description**

The EL5293C is a dual current feedback amplifier with a bandwidth of 300MHz. This makes these amplifiers ideal for today's high speed video and monitor applications.

With a supply current of just 4mA per amplifier and the ability to run from a single supply voltage from 5V to 10V, these amplifiers are also ideal for hand held, portable or battery powered equipment.

The EL5293C is offered in the industry standard 8-pin SO. The EL5293C operates over the industrial temperature range of -40°C to +85°C.

## **Pin Configurations**



Note: All information contained in this data sheet has been carefully checked and is believed to be accurate as of the date of publication; however, this data sheet cannot be a "controlled document". Current revisions, if any, to these specifications are maintained at the factory and are available upon your request. We recommend checking the revision level before finalization of your design documentation.

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# Absolute Maximum Ratings (T<sub>A</sub> = 25°C)

Values beyond absolute maximum ratings can cause the device to be prematurely damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

Supply Voltage between  $V_{S^+}$  and  $V_{S^-}$  11V Maximum Continuous Output Current 50mA

 $\begin{array}{lll} \text{Operating Junction Temperature} & 125^{\circ}\text{C} \\ \text{Power Dissipation} & \text{See Curves} \\ \text{Pin Voltages} & \text{V}_{S^{-}}\text{--}0.5\text{V to V}_{S^{+}}\text{+-}0.5\text{V} \\ \text{Storage Temperature} & -65^{\circ}\text{C to +}150^{\circ}\text{C} \\ \text{Operating Temperature} & -40^{\circ}\text{C to +}85^{\circ}\text{C} \\ \end{array}$ 

#### **Important Note:**

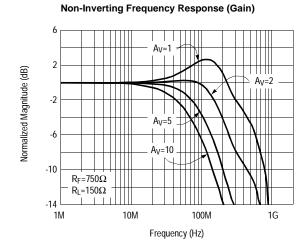
All parameters having Min/Max specifications are guaranteed. Typ values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore:  $T_J = T_C = T_A$ .

### **Electrical Characteristics**

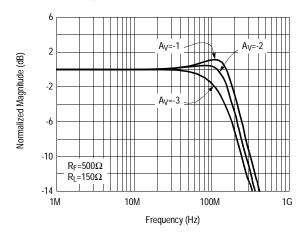
 $V_S+=+5V, V_{S^*}=-5V, R_F=750\Omega \ for \ A_V=1, R_F=375\Omega \ for \ A_V=2, R_L=150\Omega, T_A=25^{\circ}C \ unless \ otherwise \ specified.$ 

| Parameter            | Description                                  | Conditions   | Min  | Тур  | Max | Unit      |
|----------------------|--|--|------|------|-----|-----------|
| AC Performa          | nnce   |  |      |      |     | _         |
| BW                   | -3dB Bandwidth                               | $A_V = +1$   |      | 300  |     | MHz       |
|                      |  | $A_V = +2$   |      | 200  |     | MHz       |
| BW1                  | 0.1dB Bandwidth                              |  |      | 20   |     | MHz       |
| SR                   | Slew Rate                                    | $V_O = -2.5 V$ to $+2.5 V$ , $A_V = +2$            | 2000 | 2200 |     | V/µs      |
| ts                   | 0.1% Settling Time                           | $V_{OUT} = -2.5V$ to $+2.5V$ , $A_V = -1$          |      | 12   |     | ns        |
| C <sub>S</sub>       | Channel Separation                           | f = 5MHz   |      | 60   |     | dB        |
| e <sub>n</sub>       | Input Voltage Noise                          |  |      | 4.4  |     | nV/√Hz    |
| i <sub>n</sub> -     | IN- input current noise                      |  |      | 17   |     | pA/√Hz    |
| i <sub>n</sub> +     | IN+ input current noise                      |  |      | 50   |     | pA/√Hz    |
| dG                   | Differential Gain Error [1]                  | $A_V = +2$   |      | 0.03 |     | %         |
| dP                   | Differential Phase Error [1]                 | $A_V = +2$   |      | 0.04 |     | 0         |
| DC Performa          | nnce   |  | •    | •    | •   | <u>'I</u> |
| V <sub>OS</sub>      | Offset Voltage                               |  | -10  | 1    | 10  | mV        |
| $T_{\rm C}V_{ m OS}$ | Input Offset Voltage Temperature Coefficient | Measured from T <sub>MIN</sub> to T <sub>MAX</sub> |      | 5    |     | μV/°C     |
| R <sub>OL</sub>      | Transimpediance                              |  | 300  | 600  |     | kΩ        |
| Input Charac         | teristics                                    |  | -    | •    | •   |           |
| CMIR                 | Common Mode Input Range                      |  | ±3   | ±3.3 |     | V         |
| CMRR                 | Common Mode Rejection Ratio                  |  | 42   | 50   |     | dB        |
| +I <sub>IN</sub>     | + Input Current                              |  | -60  | 1    | 60  | μΑ        |
| -I <sub>IN</sub>     | - Input Current                              |  | -35  | 1    | 35  | μΑ        |
| R <sub>IN</sub>      | Input Resistance                             |  |      | 45   |     | kΩ        |
| C <sub>IN</sub>      | Input Capacitance                            |  |      | 0.5  |     | pF        |
| Output Char          | acteristics                                  |  | -    | •    | •   |           |
| Vo                   | Output Voltage Swing                         | $R_L = 150\Omega$ to GND                           | ±3.4 | ±3.7 |     | V         |
|                      |  | $R_L = 1k\Omega$ to GND                            | ±3.8 | ±4.0 |     | V         |
| I <sub>OUT</sub>     | Output Current                               | $R_L = 10\Omega$ to GND                            | 95   | 120  |     | mA        |
| Supply               |  |  |      | •    | •   |           |
| Ison                 | Supply Current - Enabled (per amplifier)     | No Load, V <sub>IN</sub> = 0V                      | 3    | 4    | 5   | mA        |
| PSRR                 | Power Supply Rejection Ratio                 | DC, $V_S = \pm 4.75V$ to $\pm 5.25V$               | 55   | 75   |     | dB        |
| -IPSR                | - Input Current Power Supply Rejection       | DC, $V_S = \pm 4.75V$ to $\pm 5.25V$               | -2   |      | 2   | μA/V      |

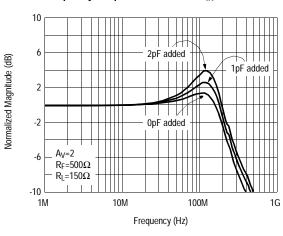
 $<sup>1. \</sup>quad Standard \ NTSC \ test, \ AC \ signal \ amplitude = 286mV_{p\text{-}p}, \ f = 3.58MHz$ 



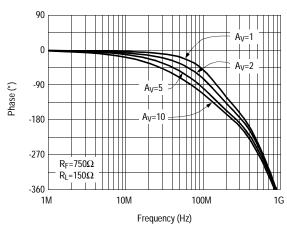
#### **Inverting Frequency Response (Gain)**



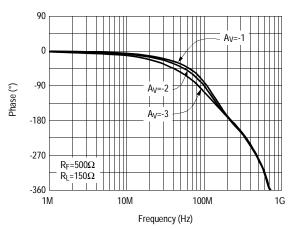
#### Frequency Response for Various CIN-



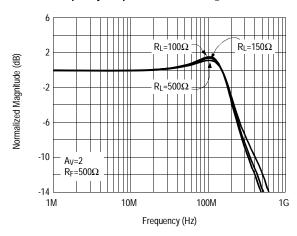
#### Non-Inverting Frequency Response (Phase)



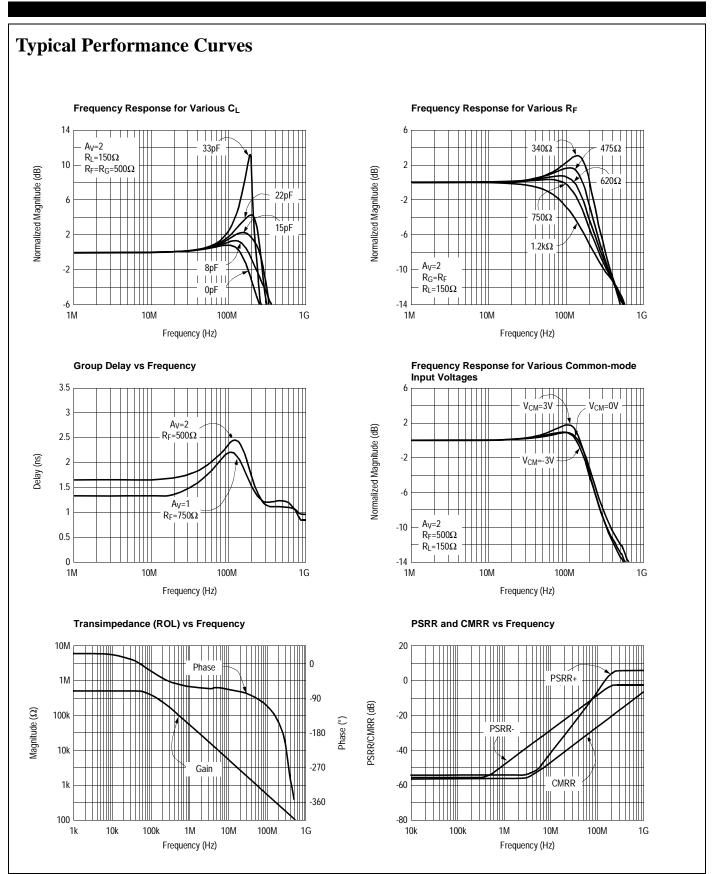
#### Inverting Frequency Response (Phase)

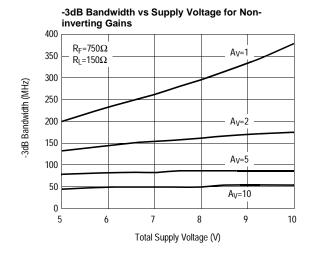


#### Frequency Response for Various R<sub>L</sub>

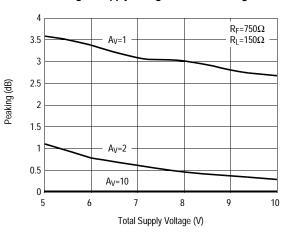


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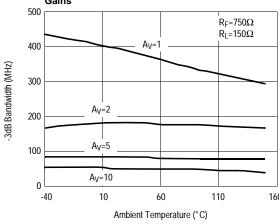




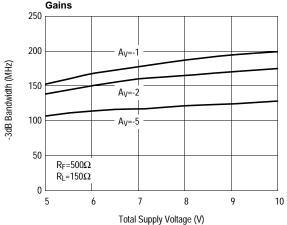
#### Peaking vs Supply Voltage for Non-inverting Gains



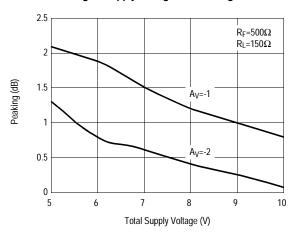
-3dB Bandwidth vs Temperature for Non-inverting Gains



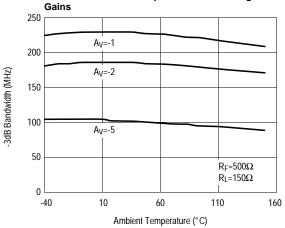
-3dB Bandwidth vs Supply Voltage for Inverting



#### Peaking vs Supply Voltage for Inverting Gains



-3dB Bandwidth vs Temperature for Inverting



## Dual 300MHz Current Feedback Amplifier

#### **Typical Performance Curves** Peaking vs Temperature Voltage and Current Noise vs Frequency 1000 $R_L$ =150 $\Omega$ $A_V=1$ Voltage Noise (nV/√Hz) Current Noise (pA/√Hz) 100 1.5 Peaking (dB) 0.5 10 A<sub>V</sub>=-1 -0.5 110 160 100 1000 100k 10M -40 Frequency () Ambient Temperature (°C) Closed Loop Output Impedance vs Frequency Supply Current vs Supply Voltage 100 10 10 8 Output Impedance (\Omega) Supply Current (mA) 0.1 0.01 0.001 0 100 12 Frequency (Hz) Supply Voltage (V) 2nd and 3rd Harmonic Distortion vs Frequency Two-tone 3rd Order Input Referred Intermodulation Intercept (IIP3) 25 -20 $A_V=+2$ -30 V<sub>OUT</sub>=2V<sub>P-P</sub> $R_L=150\Omega$ R<sub>L</sub>=100Ω Input Power Intercept (dBm) Harmonic Distortion (dBc) -40 15 2nd Order -50 10 Distortion -60 3rd Order -70 Distortion -80 $R_L$ =100 $\Omega$

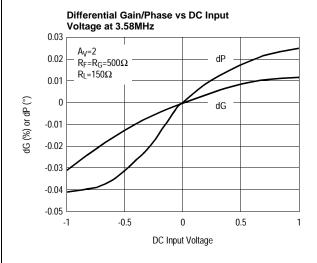
100

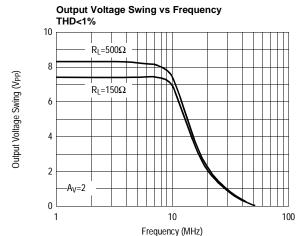
-10

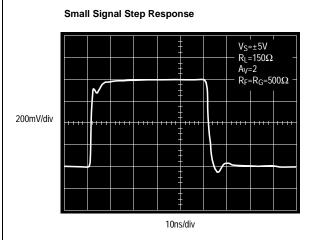
10

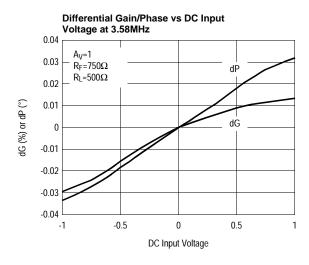
1

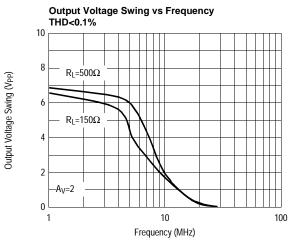
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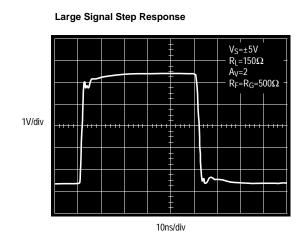




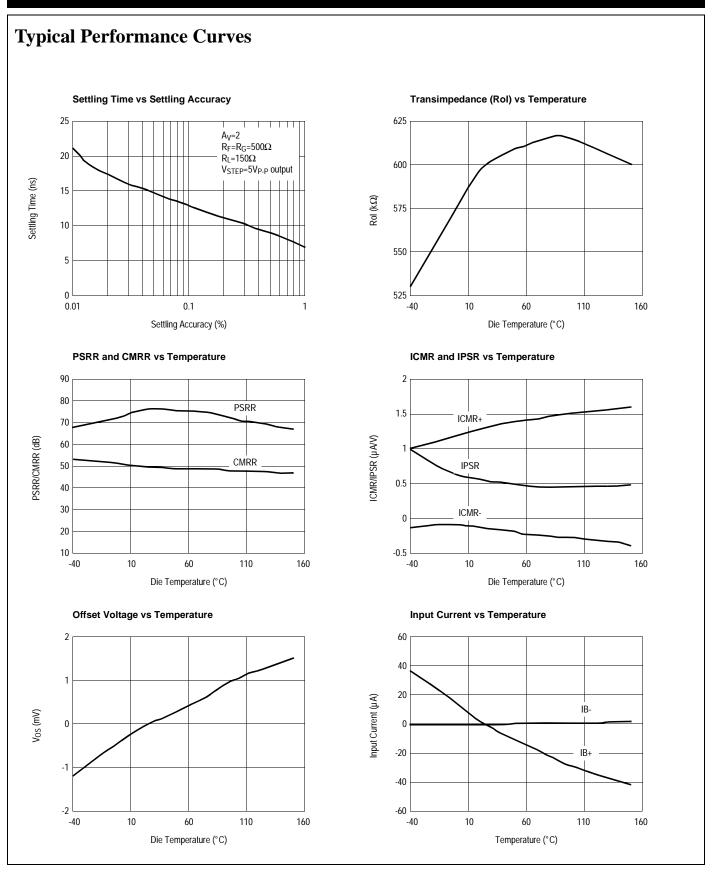




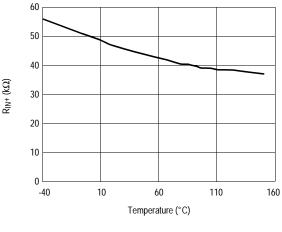


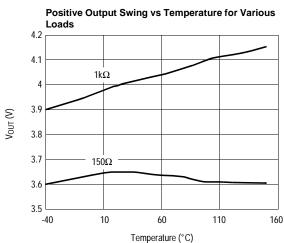


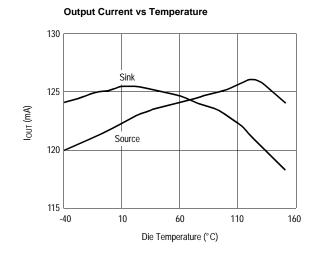
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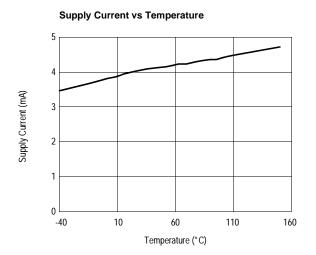


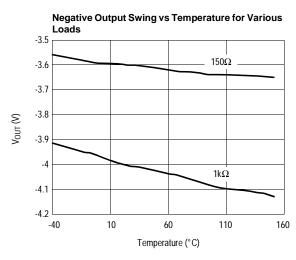
# Positive Input Resistance vs Temperature 40 30 20 10 -40 10 110 160

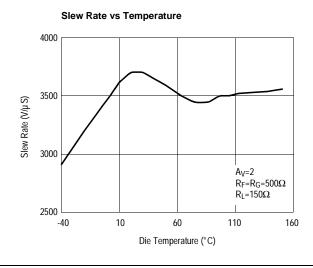








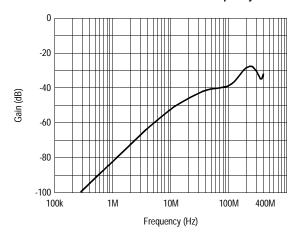




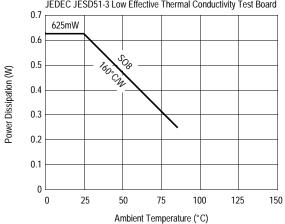
# Dual 300MHz Current Feedback Amplifier

# **Typical Performance Curves**

#### Channel-to-Channel Isolation vs Frequency



# Package Power Dissipation vs Ambient Temp. JEDEC JESD51-3 Low Effective Thermal Conductivity Test Board



# **Pin Descriptions**

| EL5293C  |                  |                                |  |
|----------|------------------|--------------------------------|--|
| 8-Pin SO | Pin Name         | Function                       | Equivalent Circuit   |
| 1        | OUTA             | Output, channel A              | V <sub>S</sub> + OUT V <sub>S</sub> - Circuit 1                |
|          |                  |                                | Circuit 1  |
| 2        | INA-             | Inverting input, channel A     | V <sub>S</sub> +  V <sub>S</sub> +  V <sub>S</sub> -  Circuit2 |
| 3        | INA+             | Non-inverting input, channel A | (See circuit 2)  |
| 4        | V <sub>S</sub> - | Negative supply                |  |
| 5        | INB+             | Non-inverting input, channel B | (See circuit 2)  |
| 6        | INB-             | Inverting input, channel B     | (See circuit 2)  |
| 7        | OUTB             | Output, channel B              | (See circuit 1)  |
| 8        | V <sub>S</sub> + | Positive supply                |  |

## Dual 300MHz Current Feedback Amplifier

## **Applications Information**

### **Product Description**

The EL5293C is a current-feedback operational amplifier that offers a wide -3dB bandwidth of 300MHz and a low supply current of 4mA per amplifier. The EL5293C works with supply voltages ranging from a single 5V to 10V and they are also capable of swinging to within 1V of either supply on the output. Because of their current-feedback topology, the EL5293C does not have the normal gain-bandwidth product associated with voltage-feedback operational amplifiers. Instead, its -3dB bandwidth to remain relatively constant as closed-loop gain is increased. This combination of high bandwidth and low power, together with aggressive pricing make the EL5293C the ideal choice for many low-power/high-bandwidth applications such as portable, handheld, or battery-powered equipment.

For varying bandwidth needs, consider the EL5191C with 1GHz on a 9mA supply current or the EL5192C with 600MHz on a 6mA supply current. Versions include single, dual, and triple amp packages with 5-pin SOT23, 16-pin QSOP, and 8-pin or 16-pin SO outlines.

### **Power Supply Bypassing and Printed Circuit Board Layout**

As with any high frequency device, good printed circuit board layout is necessary for optimum performance. Low impedance ground plane construction is essential. Surface mount components are recommended, but if leaded components are used, lead lengths should be as short as possible. The power supply pins must be well bypassed to reduce the risk of oscillation. The combination of a  $4.7\mu F$  tantalum capacitor in parallel with a  $0.01\mu F$  capacitor has been shown to work well when placed at each supply pin.

For good AC performance, parasitic capacitance should be kept to a minimum, especially at the inverting input. (See the Capacitance at the Inverting Input section) Even when ground plane construction is used, it should be removed from the area near the inverting input to minimize any stray capacitance at that node. Carbon or Metal-Film resistors are acceptable with the Metal-Film resistors giving slightly less peaking and bandwidth because of additional series inductance. Use of sockets, particularly for the SO package, should be avoided if possible. Sockets add parasitic inductance and capacitance which will result in additional peaking and overshoot.

### **Capacitance at the Inverting Input**

Any manufacturer's high-speed voltage- or current-feedback amplifier can be affected by stray capacitance at the inverting input. For inverting gains, this parasitic capacitance has little effect because the inverting input is a virtual ground, but for non-inverting gains, this capacitance (in conjunction with the feedback and gain resistors) creates a pole in the feedback path of the amplifier. This pole, if low enough in frequency, has the same destabilizing effect as a zero in the forward open-loop response. The use of large-value feedback and gain resistors exacerbates the problem by further lowering the pole frequency (increasing the possibility of oscillation.)

The EL5293C has been optimized with a  $475\Omega$  feedback resistor. With the high bandwidth of these amplifiers, these resistor values might cause stability problems when combined with parasitic capacitance, thus ground plane is not recommended around the inverting input pin of the amplifier.

### **Feedback Resistor Values**

The EL5293C has been designed and specified at a gain of +2 with  $R_F$  approximately  $500\Omega$ . This value of feedback resistor gives 200 MHz of -3dB bandwidth at  $A_V=2$  with 2dB of peaking. With  $A_V=-2$ , an  $R_F$  of approximately  $500\Omega$  gives 175 MHz of bandwidth with 0.2 dB of peaking. Since the EL5293C is a current-feedback amplifier, it is also possible to change the value of  $R_F$  to get more bandwidth. As seen in the curve of Frequency Response for Various  $R_F$  and  $R_G$ , bandwidth and peaking can be easily modified by varying the value of the feedback resistor.

Because the EL5293C is a current-feedback amplifier, its gain-bandwidth product is not a constant for different closed-loop gains. This feature actually allows the EL5293C to maintain about the same -3dB bandwidth. As gain is increased, bandwidth decreases slightly while

stability increases. Since the loop stability is improving with higher closed-loop gains, it becomes possible to reduce the value of  $R_{\rm F}$  below the specified 475 $\Omega$  and still retain stability, resulting in only a slight loss of bandwidth with increased closed-loop gain.

# **Supply Voltage Range and Single-Supply Operation**

The EL5293C has been designed to operate with supply voltages having a span of greater than 5V and less than 10V. In practical terms, this means that the EL5293C will operate on dual supplies ranging from  $\pm 2.5$ V to  $\pm 5$ V. With single-supply, the EL5293C will operate from 5V to 10V.

As supply voltages continue to decrease, it becomes necessary to provide input and output voltage ranges that can get as close as possible to the supply voltages. The EL5293C has an input range which extends to within 2V of either supply. So, for example, on +5V supplies, the EL5293C has an input range which spans ±3V. The output range of the EL5293C is also quite large, extending to within 1V of the supply rail. On a ±5V supply, the output is therefore capable of swinging from -4V to +4V. Single-supply output range is larger because of the increased negative swing due to the external pull-down resistor to ground.

#### Video Performance

For good video performance, an amplifier is required to maintain the same output impedance and the same frequency response as DC levels are changed at the output. This is especially difficult when driving a standard video load of  $150\Omega$ , because of the change in output current with DC level. Previously, good differential gain could only be achieved by running high idle currents through the output transistors (to reduce variations in output impedance.) These currents were typically comparable to the entire 4mA supply current of each EL5293C amplifier. Special circuitry has been incorporated in the EL5293C to reduce the variation of output impedance with current output. This results in dG and dP specifications of 0.03% and  $0.04^{\circ}$ , while driving  $150\Omega$  at a gain of 2.

Video performance has also been measured with a  $500\Omega$  load at a gain of +1. Under these conditions, the EL5293C has dG and dP specifications of 0.03% and 0.04°.

### **Output Drive Capability**

In spite of its low 4mA of supply current, the EL5293C is capable of providing a minimum of  $\pm 95$ mA of output current. With a minimum of  $\pm 95$ mA of output drive, the EL5293C is capable of driving  $50\Omega$  loads to both rails, making it an excellent choice for driving isolation transformers in telecommunications applications.

### **Driving Cables and Capacitive Loads**

When used as a cable driver, double termination is always recommended for reflection-free performance. For those applications, the back-termination series resistor will decouple the EL5293C from the cable and allow extensive capacitive drive. However, other applications may have high capacitive loads without a back-termination resistor. In these applications, a small series resistor (usually between  $5\Omega$  and  $50\Omega$ ) can be placed in series with the output to eliminate most peaking. The gain resistor ( $R_G$ ) can then be chosen to make up for any gain loss which may be created by this additional resistor at the output. In many cases it is also possible to simply increase the value of the feedback resistor ( $R_F$ ) to reduce the peaking.

### **Current Limiting**

The EL5293C has no internal current-limiting circuitry. If the output is shorted, it is possible to exceed the Absolute Maximum Rating for output current or power dissipation, potentially resulting in the destruction of the device.

### **Power Dissipation**

With the high output drive capability of the EL5293C, it is possible to exceed the 125°C Absolute Maximum junction temperature under certain very high load current conditions. Generally speaking when  $R_L$  falls below about 25 $\Omega$ , it is important to calculate the maximum junction temperature ( $T_{JMAX}$ ) for the application to determine if power supply voltages, load conditions, or package type need to be modified for the EL5293C to

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remain in the safe operating area. These parameters are calculated as follows:

$$T_{JMAX} = T_{MAX} + (\theta_{JA} \times n \times PD_{MAX})$$

where:

 $T_{MAX} = Maximum Ambient Temperature$ 

 $\theta_{\mathrm{JA}}$  = Thermal Resistance of the Package

n = Number of Amplifiers in the Package

 $PD_{MAX}$  = Maximum Power Dissipation of Each Amplifier in the Package

PD<sub>MAX</sub> for each amplifier can be calculated as follows:

$$PD_{MAX} = (2 \times V_S \times I_{SMAX}) + \left[ (V_S - V_{OUTMAX}) \times \frac{V_{OUTMAX}}{R_L} \right]$$

where:

 $V_S$  = Supply Voltage

I<sub>SMAX</sub> = Maximum Supply Current of 1A

V<sub>OUTMAX</sub> = Maximum Output Voltage (Required)

 $R_{\rm L}$  = Load Resistance

Fax:

# EL5293C

Dual 300MHz Current Feedback Amplifier

#### **General Disclaimer**

Specifications contained in this data sheet are in effect as of the publication date shown. Elantec, Inc. reserves the right to make changes in the circuitry or specifications contained herein at any time without notice. Elantec, Inc. assumes no responsibility for the use of any circuits described herein and makes no representations that they are free from patent infringement.



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