Features

- High-performance, Low-power AVR® 8-bit Microcontroller
- Advanced RISC Architecture
 - 130 Powerful Instructions Most Single-clock Cycle Execution
 - 32 x 8 General Purpose Working Registers
 - Fully Static Operation
 - Up to 16 MIPS Throughput at 16 MHz
 - On-chip 2-cycle Multiplier
- High Endurance Non-volatile Memory segments
 - 8K Bytes of In-System Self-programmable Flash program memory
 - 512 Bytes EEPROM
 - 1K Byte Internal SRAM
 - Write/Erase Cycles: 10,000 Flash/100,000 EEPROM
 - Data retention: 20 years at 85°C/100 years at 25°C⁽¹⁾
 - Optional Boot Code Section with Independent Lock Bits
 - In-System Programming by On-chip Boot Program
 - True Read-While-Write Operation
 - Programming Lock for Software Security
- Peripheral Features
 - Two 8-bit Timer/Counters with Separate Prescaler, one Compare Mode
 - One 16-bit Timer/Counter with Separate Prescaler, Compare Mode, and Capture Mode
 - Real Time Counter with Separate Oscillator
 - Three PWM Channels
 - 8-channel ADC in TQFP and QFN/MLF package
 - Eight Channels 10-bit Accuracy
 - 6-channel ADC in PDIP package
 - Six Channels 10-bit Accuracy
 - Byte-oriented Two-wire Serial Interface
 - Programmable Serial USART
 - Master/Slave SPI Serial Interface
 - Programmable Watchdog Timer with Separate On-chip Oscillator
 - On-chip Analog Comparator
- Special Microcontroller Features
 - Power-on Reset and Programmable Brown-out Detection
 - Internal Calibrated RC Oscillator
 - External and Internal Interrupt Sources
 - Five Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down, and Standby
- I/O and Packages
 - 23 Programmable I/O Lines
 - 28-lead PDIP, 32-lead TQFP, and 32-pad QFN/MLF
- Operating Voltages
 - 2.7 5.5V for ATmega8A
- Speed Grades
 - 0 16 MHz for ATmega8A
- Power Consumption at 4 Mhz, 3V, 25°C
 - Active: 3.6 mAIdle Mode: 1.0 mA
 - Power-down Mode: 0.5 μA



8-bit AVR®
with 8K Bytes
In-System
Programmable
Flash

ATmega8A

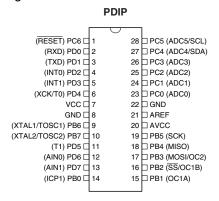
Summary

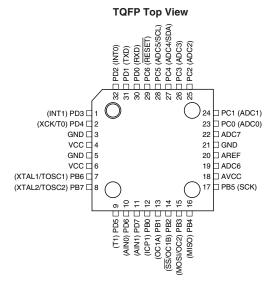
8159CS-AVR-07/09

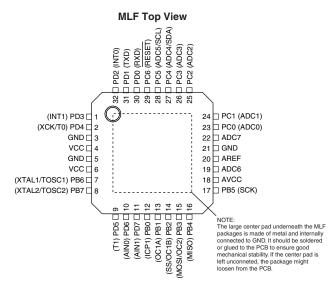


1. Pin Configurations

Figure 1-1. Pinout ATmega8A







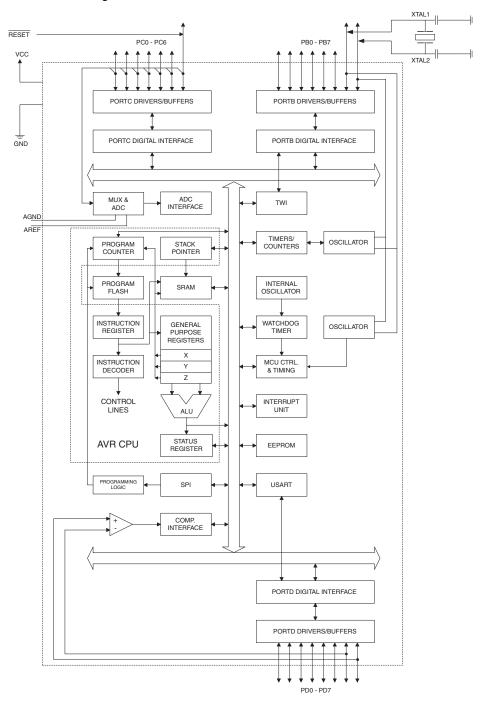


2. Overview

The ATmega8A is a low-power CMOS 8-bit microcontroller based on the AVR RISC architecture. By executing powerful instructions in a single clock cycle, the ATmega8A achieves throughputs approaching 1 MIPS per MHz, allowing the system designer to optimize power consumption versus processing speed.

2.1 Block Diagram

Figure 2-1. Block Diagram





The AVR core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega8A provides the following features: 8K bytes of In-System Programmable Flash with Read-While-Write capabilities, 512 bytes of EEPROM, 1K byte of SRAM, 23 general purpose I/O lines, 32 general purpose working registers, three flexible Timer/Counters with compare modes, internal and external interrupts, a serial programmable USART, a byte oriented Two-wire Serial Interface, a 6-channel ADC (eight channels in TQFP and QFN/MLF packages) with 10-bit accuracy, a programmable Watchdog Timer with Internal Oscillator, an SPI serial port, and five software selectable power saving modes. The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI port, and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next Interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except asynchronous timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the crystal/resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low-power consumption.

The device is manufactured using Atmel's high density non-volatile memory technology. The Flash Program memory can be reprogrammed In-System through an SPI serial interface, by a conventional non-volatile memory programmer, or by an On-chip boot program running on the AVR core. The boot program can use any interface to download the application program in the Application Flash memory. Software in the Boot Flash Section will continue to run while the Application Flash Section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega8A is a powerful microcontroller that provides a highly-flexible and cost-effective solution to many embedded control applications.

The ATmega8A AVR is supported with a full suite of program and system development tools, including C compilers, macro assemblers, program debugger/simulators, In-Circuit Emulators, and evaluation kits.

2.2 Pin Descriptions

2.2.1 VCC

Digital supply voltage.

2.2.2 GND

Ground.

2.2.3 Port B (PB7:PB0) – XTAL1/XTAL2/TOSC1/TOSC2

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.



Depending on the clock selection fuse settings, PB6 can be used as input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

Depending on the clock selection fuse settings, PB7 can be used as output from the inverting Oscillator amplifier.

If the Internal Calibrated RC Oscillator is used as chip clock source, PB7:6 is used as TOSC2:1 input for the Asynchronous Timer/Counter2 if the AS2 bit in ASSR is set.

The various special features of Port B are elaborated in "Alternate Functions of Port B" on page 58 and "System Clock and Clock Options" on page 24.

2.2.4 Port C (PC5:PC0)

Port C is an 7-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.

2.2.5 **PC6/RESET**

If the RSTDISBL Fuse is programmed, PC6 is used as an I/O pin. Note that the electrical characteristics of PC6 differ from those of the other pins of Port C.

If the RSTDISBL Fuse is unprogrammed, PC6 is used as a Reset input. A low level on this pin for longer than the minimum pulse length will generate a Reset, even if the clock is not running. The minimum pulse length is given in Table 25-3 on page 247. Shorter pulses are not guaranteed to generate a Reset.

The various special features of Port C are elaborated on page 61.

2.2.6 Port D (PD7:PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega8A as listed on page 63.

2.2.7 RESET

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running. The minimum pulse length is given in Table 25-3 on page 247. Shorter pulses are not guaranteed to generate a reset.

2.2.8 AV_{CC}

 AV_{CC} is the supply voltage pin for the A/D Converter, Port C (3:0), and ADC (7:6). It should be externally connected to V_{CC} , even if the ADC is not used. If the ADC is used, it should be connected to V_{CC} through a low-pass filter. Note that Port C (5:4) use digital supply voltage, V_{CC} .

2.2.9 AREF

AREF is the analog reference pin for the A/D Converter.



2.2.10 ADC7:6 (TQFP and QFN/MLF Package Only)

In the TQFP and QFN/MLF package, ADC7:6 serve as analog inputs to the A/D converter. These pins are powered from the analog supply and serve as 10-bit ADC channels.

3. Resources

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

4. Data Retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.



5. Register Summary

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x3F (0x5F)	SREG	l I	Т	Н	S	V	N	Z	С	8
0x3E (0x5E)	SPH	-			-		SP10	SP9	SP8	11
0x3D (0x5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	11
0x3C (0x5C)	Reserved	OI 7	0.0	0.0	01 4	0.0	0.2	0. 1	0.0	
0x3B (0x5B)	GICR	INT1	INT0	_	_	_	_	IVSEL	IVCE	48, 68
0x3A (0x5A)	GIFR	INTF1	INTF0	_	_	_	_	_	-	69
0x39 (0x59)	TIMSK	OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	_	TOIE0	73, 104, 124
0x38 (0x58)	TIFR	OCF2	TOV2	ICF1	OCF1A	OCF1B	TOV1	_	TOV0	74, 104, 104
0x37 (0x57)	SPMCR	SPMIE	RWWSB	-	RWWSRE	BLBSET	PGWRT	PGERS	SPMEN	224
0x36 (0x56)	TWCR	TWINT	TWEA	TWSTA	TWSTO	TWWC	TWEN	-	TWIE	191
0x35 (0x55)	MCUCR	SE	SM2	SM1	SM0	ISC11	ISC10	ISC01	ISC00	36, 67
0x34 (0x54)	MCUCSR	-	-	-	-	WDRF	BORF	EXTRF	PORF	43
0x33 (0x53)	TCCR0	-	-	-	-	-	CS02	CS01	CS00	73
0x32 (0x52)	TCNT0				Timer/Cou	inter0 (8 Bits)				73
0x31 (0x51)	OSCCAL		1	1	Oscillator Cal	ibration Register	1	1		31
0x30 (0x50)	SFIOR	-	-	-	-	ACME	PUD	PSR2	PSR10	57, 77, 125, 196
0x2F (0x4F)	TCCR1A	COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	WGM11	WGM10	99
0x2E (0x4E)	TCCR1B	ICNC1	ICES1	_	WGM13	WGM12	CS12	CS11	CS10	101
0x2D (0x4D)	TCNT1H				er/Counter1 – Co					102
0x2C (0x4C)	TCNT1L				er/Counter1 – Co					102
0x2B (0x4B)	OCR1AH				unter1 – Output C unter1 – Output C					103
0x2A (0x4A)	OCR1AL				unter1 – Output C					103
0x29 (0x49) 0x28 (0x48)	OCR1BH OCR1BL				unter1 – Output C					103 103
0x28 (0x48) 0x27 (0x47)	ICR1H				Counter1 - Input					103
0x27 (0x47) 0x26 (0x46)	ICR1L				Counter1 – Input					103
0x25 (0x45)	TCCR2	FOC2	WGM20	COM21	COM20	WGM21	CS22	CS21	CS20	121
0x24 (0x44)	TCNT2	1002	VVGIVIZO	CONIZI		inter2 (8 Bits)	0022	0021	0020	123
0x23 (0x43)	OCR2			Tir	mer/Counter2 Out		gister			123
0x22 (0x42)	ASSR	_	_	_	_	AS2	TCN2UB	OCR2UB	TCR2UB	123
0x21 (0x41)	WDTCR	-	_	_	WDCE	WDE	WDP2	WDP1	WDP0	43
0.00(1) (0.40)(1)	UBRRH	URSEL	-	-	-		UBR	R[11:8]		160
0x20 ⁽¹⁾ (0x40) ⁽¹⁾	UCSRC	URSEL	UMSEL	UPM1	UPM0	USBS	UCSZ1	UCSZ0	UCPOL	159
0x1F (0x3F)	EEARH	_	_	_	-	-	_	-	EEAR8	19
0x1E (0x3E)	EEARL	EEAR7	EEAR6	EEAR5	EEAR4	EEAR3	EEAR2	EEAR1	EEAR0	19
0x1D (0x3D)	EEDR				EEPROM	Data Register				19
0x1C (0x3C)	EECR	-	_	_	-	EERIE	EEMWE	EEWE	EERE	19
0x1B (0x3B)	Reserved									
0x1A (0x3A)	Reserved									
0x19 (0x39)	Reserved		I	I	T	T	I	T		
0x18 (0x38)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	65
0x17 (0x37)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	65
0x16 (0x36)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	65
0x15 (0x35) 0x14 (0x34)	PORTC DDRC		PORTC6 DDC6	PORTC5 DDC5	PORTC4 DDC4	PORTC3 DDC3	PORTC2 DDC2	PORTC1 DDC1	PORTC0 DDC0	65 65
0x14 (0x34) 0x13 (0x33)	PINC	_	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	65
0x13 (0x33)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	65
0x11 (0x31)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	65
0x10 (0x30)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	66
0x0F (0x2F)	SPDR					ta Register				135
0x0E (0x2E)	SPSR	SPIF	WCOL	-	-	-	-	-	SPI2X	134
0x0D (0x2D)	SPCR	SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	133
0x0C (0x2C)	UDR					Data Register		·		156
0x0B (0x2B)	UCSRA	RXC	TXC	UDRE	FE	DOR	PE	U2X	MPCM	157
0x0A (0x2A)	UCSRB	RXCIE	TXCIE	UDRIE	RXEN	TXEN	UCSZ2	RXB8	TXB8	158
0x09 (0x29)	UBRRL				USART Baud Ra	te Register Low b	yte			160
0x08 (0x28)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	196
0x07 (0x27)	ADMUX	REFS1	REFS0	ADLAR	-	MUX3	MUX2	MUX1	MUX0	208
0x06 (0x26)	ADCSRA	ADEN	ADSC	ADFR	ADIF	ADIE	ADPS2	ADPS1	ADPS0	209
0x05 (0x25)	ADCH					egister High byte				210
0x04 (0x24)	ADCL					egister Low byte				210
0x03 (0x23)	TWDR		T		wo-wire Serial In	1		T	T	193
0x02 (0x22)	TWAR	TWA6	TWA5	TWA4	TWA3	TWA2	TWA1	TWA0	TWGCE	194



5. Register Summary (Continued)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x01 (0x21)	TWSR	TWS7	TWS6	TWS5	TWS4	TWS3	-	TWPS1	TWPS0	193
0x00 (0x20)	TWBR		Two-wire Serial Interface Bit Rate Register					191		

Note:

- 1. Refer to the USART description for details on how to access UBRRH and UCSRC.
- 2. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
- 3. Some of the Status Flags are cleared by writing a logical one to them. Note that the CBI and SBI instructions will operate on all bits in the I/O Register, writing a one back into any flag read as set, thus clearing the flag. The CBI and SBI instructions work with registers 0x00 to 0x1F only.



6. Instruction Set Summary

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND L	OGIC INSTRUCTIONS				
ADD	Rd, Rr	Add two Registers	Rd ← Rd + Rr	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	$Rd \leftarrow Rd + Rr + C$	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	Rdh:Rdl ← Rdh:Rdl + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	$Rd \leftarrow Rd - Rr$	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	$Rd \leftarrow Rd - K$	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	$Rd \leftarrow Rd - Rr - C$	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	Rd ← Rd - K - C	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	$Rd \leftarrow Rd \bullet Rr$	Z,N,V	11
ANDI	Rd, K	Logical AND Register and Constant	$Rd \leftarrow Rd \bullet K$	Z,N,V	11
OR	Rd, Rr	Logical OR Registers	Rd ← Rd v Rr	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	Rd ← Rd v K	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	Rd ← Rd ⊕ Rr	Z,N,V	1
COM	Rd	One's Complement	$Rd \leftarrow 0xFF - Rd$	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← 0x00 – Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	Rd ← Rd v K	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	Rd ← Rd • (0xFF - K)	Z,N,V	1
INC	Rd	Increment	Rd ← Rd + 1	Z,N,V	1
DEC	Rd	Decrement	Rd ← Rd − 1	Z,N,V	1
TST	Rd	Test for Zero or Minus	Rd ← Rd • Rd	Z,N,V	1
CLR	Rd	Clear Register	$Rd \leftarrow Rd \oplus Rd$ $Rd \leftarrow 0xFF$	Z,N,V	<u>1</u> 1
SER MUL	Rd Dr	Set Register		None Z,C	2
MULS	Rd, Rr	Multiply Signed	R1:R0 ← Rd x Rr	Z,C	2
MULSU	Rd, Rr Rd, Rr	Multiply Signed Multiply Signed with Unsigned	$R1:R0 \leftarrow Rd \times Rr$ $R1:R0 \leftarrow Rd \times Rr$	Z,C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
FMULS	Rd, Rr	Fractional Multiply Signed	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	R1:R0 ← (Rd x Rr) << 1	Z,C	2
BRANCH INSTRUCT		Tractional Multiply Oighed With Onsigned	TINO (NO XIV)	2,0	
RJMP	k	Relative Jump	PC ← PC + k + 1	None	2
IJMP		Indirect Jump to (Z)	PC ← Z	None	2
RCALL	k	Relative Subroutine Call	PC ← PC + k + 1	None	3
ICALL		Indirect Call to (Z)	PC ← Z	None	3
RET		Subroutine Return	PC ← STACK	None	4
RETI		Interrupt Return	PC ← STACK	1	4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3	None	1/2/3
CP	Rd,Rr	Compare	Rd – Rr	Z, N,V,C,H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N,V,C,H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N,V,C,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBRS	Rr, b	Skip if Bit in Register is Set	if (Rr(b)=1) PC ← PC + 2 or 3	None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if (P(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if (P(b)=1) PC ← PC + 2 or 3	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then PC←PC+k + 1	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then PC←PC+k + 1	None	1/2
BREQ	k	Branch if Equal	if (Z = 1) then PC ← PC + k + 1	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC ← PC + k + 1	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC ← PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC ← PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC ← PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC ← PC + k + 1	None	1/2
BRMI	k	Branch if Blue	if (N = 1) then PC ← PC + k + 1	None	1/2
BRPL	k	Branch if Creater or Freigh Cigned	if (N = 0) then PC ← PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if (N ⊕ V= 0) then PC ← PC + k + 1	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if (N ⊕ V= 1) then PC ← PC + k + 1	None	1/2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC ← PC + k + 1	None	1/2
BRHC BRTS	k k	Branch if Half Carry Flag Cleared Branch if T Flag Set	if (H = 0) then PC ← PC + k + 1 if (T = 1) then PC ← PC + k + 1	None	1/2
BRTC	k	Branch if T Flag Set Branch if T Flag Cleared		None None	1/2
BRVS	k	Branch if 1 Flag Cleared Branch if Overflow Flag is Set	if (T = 0) then PC ← PC + k + 1 if (V = 1) then PC ← PC + k + 1	None	1/2
BRVC	k	Branch if Overflow Flag is Set Branch if Overflow Flag is Cleared	if $(V = 1)$ then PC \leftarrow PC + k + 1 if $(V = 0)$ then PC \leftarrow PC + k + 1	None	1/2
	Operands	Description	Operation	Flags	#Clocks
Mnemonics					



6. Instruction Set Summary (Continued)

BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC ← PC + k + 1	None	1/2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC ← PC + k + 1	None	1/2
DATA TRANSF	ER INSTRUCTIONS				
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$, Rd $\leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1$, Rd $\leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, $Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	$Rd \leftarrow (k)$	None	2
ST	X, Rr	Store Indirect	$(X) \leftarrow Rr$	None	2
			· ` '		
ST	X+, Rr	Store Indirect and Pro Doc	$(X) \leftarrow Rr, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1, (X) \leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect and Poet Inc	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1, (Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
ST	Z, Rr	Store Indirect	(Z) ← Rr	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	(Z) ← Rr, Z ← Z + 1	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, $(Z) \leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	(Z + q) ← Rr	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	R0 ← (Z)	None	3
LPM	Rd, Z	Load Program Memory	$Rd \leftarrow (Z)$	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM		Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	$Rd \leftarrow P$	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2
BIT AND BIT-TE	ST INSTRUCTIONS				
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0)\leftarrow C,Rd(n+1)\leftarrow Rd(n),C\leftarrow Rd(7)$	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	$Rd(7)\leftarrow C,Rd(n)\leftarrow Rd(n+1),C\leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=0:6$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(3:0)←Rd(7:4),Rd(7:4)←Rd(3:0)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	s	Flag Clear	$SREG(s) \leftarrow 0$	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	T	1
BLD	Rd, b	Bit load from T to Register	Rd(b) ← T	None	1
SEC	·	Set Carry	C ← 1	С	1
CLC		Clear Carry	C ← 0	С	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	-	1
CLI		Global Interrupt Disable	1←1	 	1
SES		Set Signed Test Flag	S ← 1	S	1
		· ·			
CLS		Clear Signed Test Flag	S ← 0	S V	1
SEV		Set Twos Complement Overflow.	V ← 1		1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	Т	1
Mnemonics	Operands	Description	Operation	Flags	#Clocks



6. Instruction Set Summary (Continued)

CLT		Clear T in SREG	T ← 0	T	1			
SEH		Set Half Carry Flag in SREG	H ← 1	Н	1			
CLH		Clear Half Carry Flag in SREG	H ← 0	Н	1			
MCU CONTROL I	MCU CONTROL INSTRUCTIONS							
NOP		No Operation		None	1			
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1			
WDR		Watchdog Reset	(see specific descr. for WDR/timer)	None	1			



7. Ordering Information

Speed (MHz)	Power Supply (V)	Ordering Code	Package ⁽¹⁾	Operation Range
16	2.7 - 5.5	ATmega8A-AU ⁽²⁾ ATmega8A-PU ⁽²⁾ ATmega8A-MU ⁽²⁾	32A 28P3 32M1-A	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

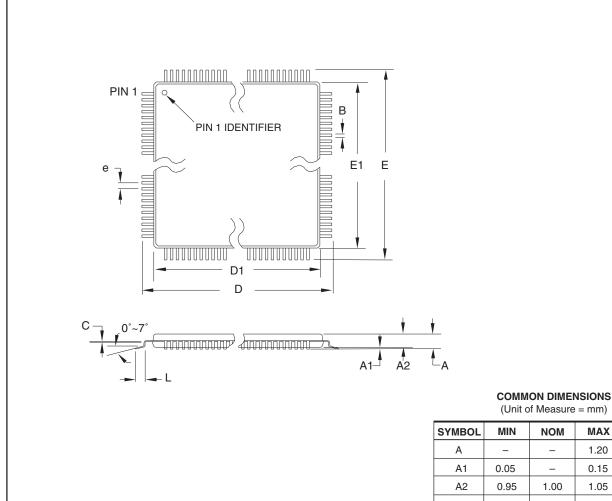
2.	Pb-free packaging alternative,	complies to the Europe	an Directive for	Restriction of Hazardou	s Substances (RoHS direc-
	tive). Also Halide free and fully	Green.			

Package Type					
32A	32-lead, Thin (1.0 mm) Plastic Quad Flat Package (TQFP)				
28P3	28-lead, 0.300" Wide, Plastic Dual Inline Package (PDIP)				
32M1-A	32-pad, 5 x 5 x 1.0 body, Lead Pitch 0.50 mm Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)				



8. Packaging Information

8.1 32A



Notes:

- 1. This package conforms to JEDEC reference MS-026, Variation ABA.
- Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25 mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.
- 3. Lead coplanarity is 0.10 mm maximum.

SYMBOL	MIN	NOM	MAX	NOTE
А	_	_	1.20	
A1	0.05	ı	0.15	
A2	0.95	1.00	1.05	
D	8.75	9.00	9.25	
D1	6.90	7.00	7.10	Note 2
E	8.75	9.00	9.25	
E1	6.90	7.00	7.10	Note 2
В	0.30	_	0.45	
С	0.09	_	0.20	
L	0.45	_	0.75	

0.80 TYP

10/5/2001

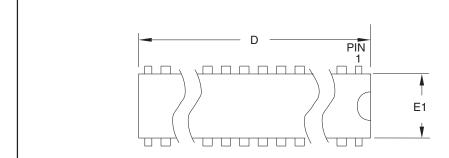
2325 Orchard Parkway San Jose, CA 95131 TITLE

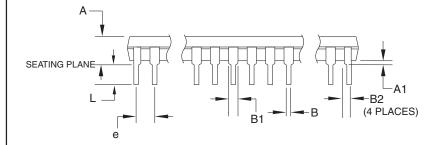
32A, 32-lead, 7 x 7 mm Body Size, 1.0 mm Body Thickness,
0.8 mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)

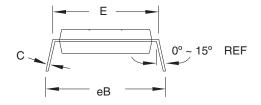
DRAWING NO. REV. 32A B



8.2 28P3







Note: 1. Dimensions D and E1 do not include mold Flash or Protrusion.

Mold Flash or Protrusion shall not exceed 0.25 mm (0.010").

COMMON DIMENSIONS

(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE		
Α	_	_	4.5724			
A1	0.508	_	_			
D	34.544	_	34.798	Note 1		
Е	7.620	_	8.255			
E1	7.112	_	7.493	Note 1		
В	0.381	_	0.533			
B1	1.143	_	1.397			
B2	0.762	_	1.143			
L	3.175	_	3.429			
С	0.203	_	0.356			
eВ	-	_	10.160			
е		2.540 TYP				

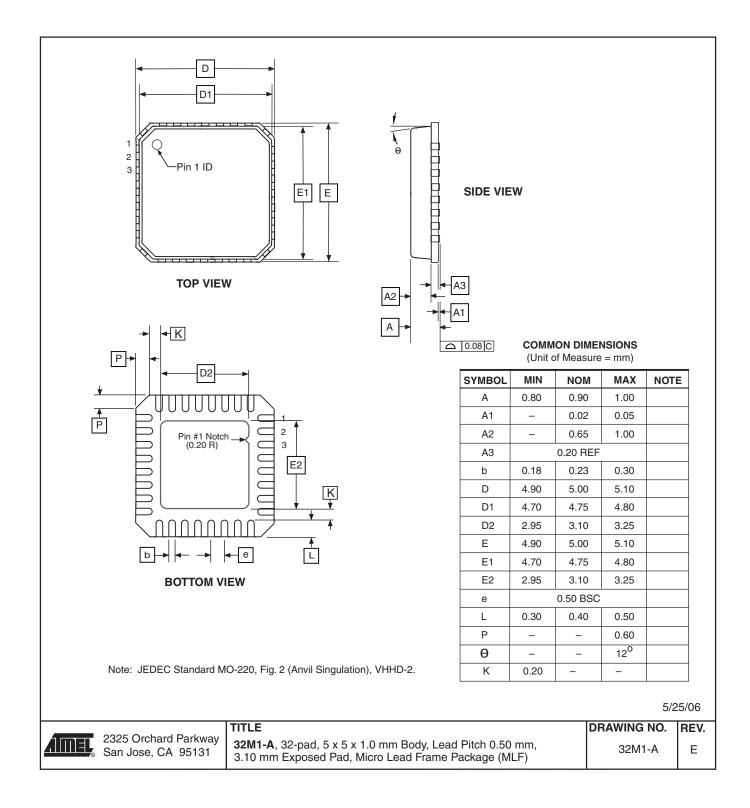
09/28/01

2325 Orchard Parkway San Jose, CA 95131 **TITLE 28P3**, 28-lead (0.300"/7.62 mm Wide) Plastic Dual Inline Package (PDIP)

DRAWING NO. REV. 28P3 B



32M1-A





9. Errata

The revision letter in this section refers to the revision of the ATmega8A device.

9.1 ATmega8A, rev. L

- First Analog Comparator conversion may be delayed
- · Interrupts may be lost when writing the timer registers in the asynchronous timer
- Signature may be Erased in Serial Programming Mode
- CKOPT Does not Enable Internal Capacitors on XTALn/TOSCn Pins when 32 KHz Oscillator is Used to Clock the Asynchronous Timer/Counter2
- Reading EEPROM by using ST or STS to set EERE bit triggers unexpected interrupt request

1. First Analog Comparator conversion may be delayed

If the device is powered by a slow rising V_{CC} , the first Analog Comparator conversion will take longer than expected on some devices.

Problem Fix / Workaround

When the device has been powered or reset, disable then enable the Analog Comparator before the first conversion.

2. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix / Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

3. Signature may be Erased in Serial Programming Mode

If the signature bytes are read before a chiperase command is completed, the signature may be erased causing the device ID and calibration bytes to disappear. This is critical, especially, if the part is running on internal RC oscillator.

Problem Fix / Workaround:

Ensure that the chiperase command has exceeded before applying the next command.

4. CKOPT Does not Enable Internal Capacitors on XTALn/TOSCn Pins when 32 KHz Oscillator is Used to Clock the Asynchronous Timer/Counter2

When the internal RC Oscillator is used as the main clock source, it is possible to run the Timer/Counter2 asynchronously by connecting a 32 KHz Oscillator between XTAL1/TOSC1 and XTAL2/TOSC2. But when the internal RC Oscillator is selected as the main clock source, the CKOPT Fuse does not control the internal capacitors on XTAL1/TOSC1 and XTAL2/TOSC2. As long as there are no capacitors connected to XTAL1/TOSC1 and XTAL2/TOSC2, safe operation of the Oscillator is not guaranteed.

Problem Fix / Workaround

Use external capacitors in the range of 20 - 36 pF on XTAL1/TOSC1 and XTAL2/TOSC2. This will be fixed in ATmega8A Rev. G where the CKOPT Fuse will control internal capacitors also when internal RC Oscillator is selected as main clock source. For ATmega8A Rev. G, CKOPT = 0 (programmed) will enable the internal capacitors on XTAL1 and XTAL2. Customers who want compatibility between Rev. G and older revisions, must ensure that CKOPT is unprogrammed (CKOPT = 1).



5. Reading EEPROM by using ST or STS to set EERE bit triggers unexpected interrupt request.

Reading EEPROM by using the ST or STS command to set the EERE bit in the EECR register triggers an unexpected EEPROM interrupt request.

Problem Fix / Workaround

Always use OUT or SBI to set EERE in EECR.



10. Datasheet Revision History

Please note that the referring page numbers in this section are referred to this document. The referring revision in this section refers to the document revision.

10.1 Rev.8159C - 07/09

- 1. Updated "Errata" on page 298.
- 2. Updated the last page with Atmel's new addresses.

10.2 Rev.8159BS - 05/09

- 1. Updated "System and Reset Characteristics" on page 247 with new BODLEVEL values
- 2. Updated "ADC Characteristics" on page 251 with new V_{INT} values.
- 3. Updated "Typical Characteristics" view.
- 4. Updated "Errata" on page 298. ATmega8A, rev L.
- 5. Created a new Table Of Contents.

10.3 Rev.8159AS - 08/08

- 1. Initial revision (Based on the ATmega8/L datasheet 2486T-AVR-05/08)
- 2. Changes done compared to ATmega8/L datasheet 2486T-AVR-05/08:
 - All Electrical Characteristics are moved to "Electrical Characteristics" on page 244.
 - Updated "DC Characteristics" on page 244 with new $\rm V_{OL}$ Max (0.9V and 0.6V) and typical value for $\rm I_{CC}$.
 - Added "Speed Grades" on page 246.
 - Added a new sub section "System and Reset Characteristics" on page 247.
 - Updated "System and Reset Characteristics" on page 247 with new V_{BOT} BODLEVEL = 0 (3.6V, 4.0V and 4.2V).
 - Register descriptions are moved to sub section at the end of each chapter.
 - New graphics in "Typical Characteristics" on page 252.
 - New "Ordering Information" on page 294.





Headquarters

Atmel Corporation

2325 Orchard Parkway San Jose, CA 95131 USA

Tel: 1(408) 441-0311 Fax: 1(408) 487-2600

International

Atmel Asia

Unit 1-5 & 16, 19/F BEA Tower, Millennium City 5 418 Kwun Tong Road Kwun Tong, Kowloon Hong Kong

Tel: (852) 2245-6100 Fax: (852) 2722-1369 Atmel Europe

Le Krebs 8, Rue Jean-Pierre Timbaud BP 309 78054 Saint-Quentin-en-

Yvelines Cedex France

Tel: (33) 1-30-60-70-00 Fax: (33) 1-30-60-71-11

Atmel Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033

Japan

Tel: (81) 3-3523-3551 Fax: (81) 3-3523-7581

Product Contact

Web Site

www.atmel.com

Technical Support

avr@atmel.com

Sales Contact

www.atmel.com/contacts

Literature Requests

www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDITIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© 2009 Atmel Corporation. All rights reserved. Atmel logo and combinations thereof, AVR® and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.