## 10- and 12-Channel TFT-LCD Reference Voltage Generators

The EL5226 and EL5326 are designed to produce the reference voltages required in TFT-LCD applications. Each output is programmed to the required voltage with 10 bits of resolution. Reference pins determine the high and low voltages of the output range, which are capable of swinging to either supply rail. Programming of each output is performed using the $\mathrm{I}^{2} \mathrm{C}$ serial interface.

A number of the EL5226 and EL5326 can be stacked for applications requiring more than 12 outputs. The reference inputs can be tied to the rails, enabling each part to output the full voltage range, or alternatively, they can be connected to external resistors to split the output range and enable finer resolutions of the outputs.

The EL5226 has 10 outputs and the EL5326 has 12 outputs and both are available in a 28 -pin TSSOP package. They are specified for operation over the full $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range.

## Features

- 10- to 12 -channel reference outputs
- Accuracy of $\pm 1 \%$
- Supply voltage of 5 V to 16.5 V
- Digital supply 3.3 V to 5 V
- Low supply current of 10 mA
- Rail-to-rail capability
- Pb-Free available (RoHS compliant)


## Applications

- TFT-LCD drive circuits
- Reference voltage generators


## Ordering Information

| PART NUMBER | PACKAGE | TAPE \& REEL | PKG. DWG. \# |
| :---: | :---: | :---: | :---: |
| EL5226IR | 28-Pin TSSOP | - | MDP0044 |
| EL5226IR-T7 | 28-Pin TSSOP | 7" | MDP0044 |
| EL5226IR-T13 | 28-Pin TSSOP | $13 "$ | MDP0044 |
| EL5226IRZ <br> (See Note) | 28-Pin TSSOP (Pb-free) | - | MDP0044 |
| $\begin{aligned} & \text { EL5226IRZ-T7 } \\ & \text { (See Note) } \end{aligned}$ | 28-Pin TSSOP (Pb-free) | $7 "$ | MDP0044 |
| EL5226IRZ-T13 (See Note) | 28-Pin TSSOP (Pb-free) | $13 "$ | MDP0044 |
| EL5326IR | 28-Pin TSSOP | - | MDP0044 |
| EL5326IR-T7 | 28-Pin TSSOP | $7 "$ | MDP0044 |
| EL5326IR-T13 | 28-Pin TSSOP | $13 "$ | MDP0044 |
| $\begin{aligned} & \text { EL5326IRZ } \\ & \text { (See Note) } \end{aligned}$ | 28-Pin TSSOP (Pb-free) | - | MDP0044 |
| $\begin{aligned} & \text { EL5326IRZ-T7 } \\ & \text { (See Note) } \end{aligned}$ | 28-Pin TSSOP (Pb-free) | 7" | MDP0044 |
| EL5326IRZ-T13 (See Note) | 28-Pin TSSOP (Pb-free) | $13 "$ | MDP0044 |

NOTE: Intersil Pb-free products employ special Pb-free material sets; molding compounds/die attach materials and 100\% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb -free soldering operations. Intersil Pb -free products are MSL classified at Pb -free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

## Pinouts

EL5226
(28-PIN TSSOP)
TOP VIEW
$\left.\begin{array}{ll}\text { EL5326 } \\ \text { (28-PIN TSSOP) } \\ \text { TOP VIEW }\end{array}\right)$

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Absolute Maximum Ratings \(\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)\)
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Supply Voltage between $\mathrm{V}_{\mathrm{S}}$ and GND . . . . . . . . . . . . . . . . . . . +18 V Supply Voltage between $\mathrm{V}_{\mathrm{SD}}$ and GND . . . . . . . $\mathrm{V}_{\mathrm{S}}$ and +7V (max) Maximum Continuous Output Current . . . . . . . . . . . . . . . . . . . 30mA Power Dissipation . . . . . . . . . . . . . . . . . . . . . . . . . . . . . See Curves

Maximum Die Temperature . . . . . . . . . . . . . . . . . . . . . . . . . . $+125^{\circ} \mathrm{C}$
Storage Temperature . . . . . . . . . . . . . . . . . . . . . . . . $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Ambient Operating Temperature . . . . . . . . . . . . . . . . $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

IMPORTANT NOTE: All parameters having Min/Max specifications are guaranteed. Typ values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore: $T_{J}=T_{C}=T_{A}$

Electrical Specifications $V_{S}=15 \mathrm{~V}, \mathrm{~V}_{\mathrm{SD}}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{REFH}}=13 \mathrm{~V}, \mathrm{~V}_{\mathrm{REFL}}=2 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=1.5 \mathrm{k} \Omega$ and $\mathrm{C}_{\mathrm{L}}=200 \mathrm{pF}$ to $0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise specified.

| PARAMETER | DESCRIPTION | CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SUPPLY |  |  |  |  |  |  |
| Is | Supply Current | EL5226 |  | 9 | 11 | mA |
|  |  | EL5326 |  | 10 | 12 | mA |
| ISD | Digital Supply Current |  |  | 0.9 | 3.2 | mA |
| ANALOG |  |  |  |  |  |  |
| $\mathrm{V}_{\text {OL }}$ | Output Swing Low | Sinking $5 \mathrm{~mA}\left(\mathrm{~V}_{\text {REFH }}=15 \mathrm{~V}, \mathrm{~V}_{\text {REFL }}=0\right)$ |  | 50 | 150 | mV |
| $\mathrm{V}_{\mathrm{OH}}$ | Output Swing High | Sourcing 5mA ( $\left.\mathrm{V}_{\text {REFH }}=15 \mathrm{~V}, \mathrm{~V}_{\text {REFL }}=0\right)$ | 14.85 | 14.95 |  | V |
| ISC | Short Circuit Current | $R_{L}=10 \Omega$ | 150 | 240 |  | mA |
| PSRR | Power Supply Rejection Ratio | $\mathrm{V}_{\mathrm{S}^{+}}$is moved from 14 V to 16 V | 45 | 65 |  | dB |
| $t_{D}$ | Program to Out Delay |  |  | 4 |  | ms |
| $V_{\text {AC }}$ | Accuracy |  |  | 20 |  | mV |
| $\mathrm{V}_{\text {DROOP }}$ | Droop Voltage |  |  | 1 | 2 | $\mathrm{mV} / \mathrm{ms}$ |
| R ${ }_{\text {INH }}$ | Input Resistance @ $\mathrm{V}_{\text {REFH }}$, $\mathrm{V}_{\text {REFL }}$ |  |  | 34 |  | k $\Omega$ |
| REG | Load Regulation | I OUT $=5 \mathrm{~mA}$ step |  | 0.5 | 1.5 | $\mathrm{mV} / \mathrm{mA}$ |
| DIGITAL |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{IH}}$ | Logic 1 Input Voltage |  | $\begin{aligned} & \mathrm{V}_{\mathrm{SD}}- \\ & 20 \% \end{aligned}$ |  |  | V |
| $\mathrm{V}_{\text {IL }}$ | Logic 0 Input Voltage |  |  |  | $\begin{gathered} 20 \% * \\ \mathrm{~V}_{\mathrm{SD}} \end{gathered}$ | V |
| FCLK | Clock Frequency |  |  |  | 400 | kHz |

Pin Descriptions

| EL5226 | EL5326 | PIN NAME | PIN TYPE | PIN FUNTION |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 1 | STD_REG | Logic Input | Selects mode, high = standard, low = register mode |
| 2 | 2 | SCL | Logic Input | $\mathrm{I}^{2} \mathrm{C}$ clock |
| 3 | 3 | SDA | Logic Input | $\mathrm{I}^{2} \mathrm{C}$ data |
| 4 | 4 | OSC | Input/Output | Oscillator pin for synchronizing multiple chips |
| 5 | 5 | OSC_SELECT | Logic Input | Selects internal / external OSC source, high = external, low = internal |
| 6, 11 | 6, 11 | VS | Analog Power | Power supply for analog circuit |
| 7, 15, 28 | 7 | NC |  | not connected |
| 8 | 8 | VSD | Digital Power | Power supply for digital circuit |
| 9 | 9 | REFH | Analog Reference Input | High reference voltage |
| 10 | 10 | REFL | Analog Reference Input | Low reference voltage |
| 12, 19, 24 | 12, 18, 25 | GND | Ground | Ground |
| 13 | 13 | CAP | Analog Bypass Pin | Decoupling capacitor for internal reference generator |
| 14 | 14 | DEV_ADDR0 | Logic Input | $\mathrm{I}^{2} \mathrm{C}$ device address input, bit 0 |
| 16 | 17 | OUTJ | Analog Output | Channel J programmable output |
| 17 | 19 | OUTI | Analog Output | Channel I programmable output |
| 18 | 20 | OUTH | Analog Output | Channel H programmable output |
| 20 | 21 | OUTG | Analog Output | Channel G programmable output |
| 21 | 22 | OUTF | Analog Output | Channel F programmable output |
| 22 | 23 | OUTE | Analog Output | Channel E programmable output |
| 23 | 24 | OUTD | Analog Output | Channel D programmable output |
| 25 | 26 | OUTC | Analog Output | Channel C programmable output |
| 26 | 27 | OUTB | Analog Output | Channel B programmable output |
| 27 | 28 | OUTA | Analog Output | Channel A programmable output |
|  | 15 | OUTL | Analog Output | Channel L programmable output |
|  | 16 | OUTK | Analog Output | Channel K programmable output |

## Typical Performance Curves



FIGURE 1. DIFFERENTIAL NONLINEARITY vs CODE


FIGURE 3. TRANSIENT LOAD REGULATION (SOURCING)


FIGURE 5. LARGE SIGNAL RESPONSE (RISING FROM OV TO 8V)


FIGURE 2. DIGITAL SUPPLY VOLTAGE vs DIGITAL SUPPLY CURRENT


FIGURE 4. TRANSIENT LOAD REGULATION (SINKING)

M $=400 \mu \mathrm{~s} / \mathrm{DIV}$


FIGURE 6. LARGE SIGNAL RESPONSE (FALLING FROM 8V TO 0V)

## Typical Performance Curves (Continued)



FIGURE 7. SMALL SIGNAL RESPONSE (RISING FROM OV TO 200 mV )

JEDEC JESD51-3 LOW EFFECTIVE THERMAL CONDUCTIVITY TEST BOARD


FIGURE 9. POWER DISSIPATION vs AMBIENT TEMPERATURE

M $=400 \mu \mathrm{~s} / \mathrm{DIV}$


FIGURE 8. SMALL SIGNAL RESPONSE (FALLING FROM 200 mV TO OV)


FIGURE 10. POWER DISSIPATION vs AMBIENT TEMPERATURE

## General Description

The EL5226 and EL5326 provide a versatile method of providing the reference voltages that are used in setting the transfer characteristics of LCD display panels. The V/T (Voltage/Transmission) curve of the LCD panel requires that a correction is applied to make it linear; however, if the panel is to be used in more than one application, the final curve may differ for different applications. By using the EL5226 and EL5326, the V/T curve can be changed to optimize its characteristics according to the required application of the display product. Each of the eight reference voltage outputs can be set with a 10-bit resolution. These outputs can be driven to within 50 mV of the power rails of the EL5226 and EL5326. As all of the output buffers are identical, it is also possible to use the EL5226 and EL5326 for applications other than LCDs where multiple voltage references are required that can be set to 10 bit accuracy.

## Digital Interface

The EL5226 and EL5326 use a simple two-wire $I^{2} \mathrm{C}$ digital interface to program the outputs. The bus line SCLK is the clock signal line and bus SDA is the data information signal line. The EL5226 and EL5326 can support the clock rate up to 400 kHz . External pull up resistor is required for each bus line. The typical value for these two pull up resistor is about $1 \mathrm{k} \Omega$.

## START AND STOP CONDITION

The Start condition is a high to low transition on the SDA line while SCLK is high. The Stop condition is a low to high transition on the SDA line while SCLK is high. The start and stop conditions are always generated by the master. The bus is considered to be busy after the start condition and to be free again a certain time after the stop condition. The two bus lines must be high when the buses are not in use. The $I^{2} \mathrm{C}$ Timing Diagram 2 shows the format.

## DATA VALIDITY

The data on the SDA line must be stable during the high period of the clock. The high or low state of the data line can only change when the clock signal on the SCLK line is low.

## BYTE FORMAT AND ACKNOWLEDGE

Every byte put on the SDA line must be eight bits long. The number of bytes that can be transmitted per transfer is unrestricted. Each byte has to be followed by an acknowledge bit. Data is transferred with the most significant bit first (MSB).
The master puts a resistive high level on the SDA line during the acknowledge clock pulse. The peripheral that acknowledges has to pull down the SDA line during the acknowledge clock pulse.

## DEVICES ADDRESS AND W/R BIT

Data transfers follow the format shown in Timing Diagram 1. After the Start condition, a first byte is sent which contains
the Device Address and write/read bit. This address is a 7bit long device address and only two device addresses (74H and 75 H ) are allowed for the EL5226 and EL5326. The first 6 bits (A6 to A1, MSBs) of the device address have been factory programmed and are always 111010. Only the least significant bit A0 is allowed to change the logic state, which can be tied to $\mathrm{V}_{\mathrm{SD}}$ or DGND. A maximum of two EL5226 and EL5326 may be used on the same bus at one time. The EL5226 and EL5326 monitor the bus continuously and waiting for the start condition followed by the device address. When a device recognizes its device address, it will start to accept data. An eighth bit is followed by the device address, which is a data direction bit (W/R). A "0" indicates a Write transmission and a "1" indicates a Read transmission.

The EL5226 and EL5326 can be operated as Standard mode and Register mode. See the $I^{2} C$ Timing Diagram 1 for detail formats.

## STANDARD MODE

The part operates at Standard Mode if pin 1 (STD/REG) is held high. The Standard Mode allows the user to program all outputs at one time. Two data bytes are required for 10-bit data for each channel output and there are a total of 20/24 data bytes for 10/12 channels. Data in data byte 1 and 2 is for channel A. Data in data byte 15 and 16 is for channel H . D9 to D0 are the 10-bit data for each channel. The unused bits in the data byte are "don't care" and can be set to either one or zero. See Table 1 for program sample for one channel setting:

TABLE 1.

|  |  |  |  |  |  |  |  | DATA |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 |  | D0 | CONDITION |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Data value $=0$ |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Data value $=512$ |
| 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | Data value $=31$ |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Data value $=1023$ |

When the W/R bit is high, the master can read the data from the EL5226 and EL5326. See Timing Diagram 1 for detail formats.

## REGISTER MODE

The part operates at Register Mode if pin 1 (STD/REG) is held low. The Register Mode allows the user to program each output individually. Followed by the first byte, the second byte sets the register address for the programmed output channel. Bits R0 to R3 set the output channel address. For the unused bits in the R4 to R7 are "don't care". See Table 2 for program sample.
The EL5226 and EL5326 also allows the user to read the data at Register Mode. See Timing Diagram 1 for detail formats.


| REGISTER ADDRESS |  |  |  | DATA |  |  |  |  |  |  |  |  |  | CONDITION |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R3 | R2 | R1 | R0 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |  |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Channel A, Value $=0$ |
| 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Channel B, Value $=512$ |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | Channel C, Value $=31$ |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | Channel H, Value = 1023 |

## $I^{2} C$ Timing Diagram 2



FIGURE 11. START, STOP \& TIMING DETAILS OF I²$C$
INTERFACE

## Analog Section

## TRANSFER FUNCTION

The transfer function is:
$\mathrm{V}_{\text {OUT(IDEAL) }}=\mathrm{V}_{\text {REFL }}+\frac{\text { data }}{1024} \times\left(\mathrm{V}_{\text {REFH }}-\mathrm{V}_{\text {REFL }}\right)$
where data is the decimal value of the 10 -bit data binary input code.
The output voltages from the EL5226 and EL5326 will be derived from the reference voltages present at the $\mathrm{V}_{\text {REFL }}$ and $\mathrm{V}_{\text {REFH }}$ pins. The impedance between those two pins is about $32 \mathrm{k} \Omega$.

Care should be taken that the system design holds these two reference voltages within the limits of the power rails of the
EL5226 and EL5326. GND $<\mathrm{V}_{\text {REFH }} \leq \mathrm{V}_{\mathrm{S}}$ and $\mathrm{GND} \leq \mathrm{V}_{\text {REFL }} \leq$ $V_{\text {REFH }}$.
In some LCD applications that require more than 12 channels, the system can be designed such that one EL5226 or EL5326 will provide the Gamma correction voltages that are more positive than the $\mathrm{V}_{\text {COM }}$ potential. The second EL5226 or EL5326 can provide the Gamma correction voltage more negative than the $\mathrm{V}_{\text {COM }}$ potential. The Application Drawing shows a system connected in this way.

## CLOCK OSCILLATOR

The EL5226 and EL5326 require an internal clock or external clock to refresh its outputs. The outputs are refreshed at the
falling OSC clock edges. The output refreshed switches open at the rising edges of the OSC clock. The driving load shouldn't be changed at the rising edges of the OSC clock. Otherwise, it will generate a voltage error at the outputs. This clock may be input or output via the clock pin labeled OSC. The internal clock is provided by an internal oscillator running at approximately 21 kHz and can be output to the OSC pin. In a 2 chip system, if the driving loads are stable, one chip may be programmed to use the internal oscillator; then the OSC pin will output the clock from the internal oscillator. The second chip may have the OSC pin connected to this clock source.
For transient load application, the external clock Mode should be used to ensure all functions are synchronized together. The positive edge of the external clock to the OSC pin should be timed to avoid the transient load effect. The Application Drawing shows the LCD H rate signal used, here the positive clock edge is timed to avoid the transient load of the column driver circuits.

After power on, the chip will start with the internal oscillator mode. At this time, the OSC pin will be in a high impedance condition to prevent contention. By setting pin 32 to high, the chip is on external clock mode. Setting pin 32 to low, the chip is on internal clock mode.

## Block Diagram



## CHANNEL OUTPUTS

Each of the channel outputs has a rail-to-rail buffer. This enables all channels to have the capability to drive to within 50 mV of the power rails, (see Electrical Characteristics for details).

When driving large capacitive loads, a series resistor should be placed in series with the output. (Usually between $5 \Omega$ and $50 \Omega$ ).

Each of the channels is updated on a continuous cycle, the time for the new data to appear at a specific output will depend on the exact timing relationship of the incoming data to this cycle.

The best-case scenario is when the data has just been captured and then passed on to the output stage immediately; this can be as short as $48 \mu \mathrm{~s}$. In the worst-case scenario this will be $480 \mu$ s for EL5226 and $576 \mu$ s for EL5236, when the data has just missed the cycle.

When a large change in output voltage is required, the change will occur in 2 V steps, thus the requisite number of timing cycles will be added to the overall update time. This means that a large change of 16 V can take between 4.8 ms
and 5.3 ms for EL5226 and between 6.9 ms to 7.48 ms for EL5236 depending on the absolute timing relative to the update cycle.

## POWER DISSIPATION

With the 30 mA maximum continues output drive capability for each channel, it is possible to exceed the $125^{\circ} \mathrm{C}$ absolute maximum junction temperature. Therefore, it is important to calculate the maximum junction temperature for the application to determine if load conditions need to be modified for the part to remain in the safe operation.

The maximum power dissipation allowed in a package is determined according to:

$$
P_{\text {DMAX }}=\frac{T_{J M A X}-T_{\text {AMAX }}}{\Theta_{J A}}
$$

where:

- TJMAX $=$ Maximum junction temperature
- $\mathrm{T}_{\text {AMAX }}=$ Maximum ambient temperature
- $\theta_{\mathrm{JA}}=$ Thermal resistance of the package
- $P_{\text {DMAX }}=$ Maximum power dissipation in the package

The maximum power dissipation actually produced by the IC is the total quiescent supply current times the total power supply voltage and plus the power in the IC due to the loads.

$$
\mathrm{P}_{\text {DMAX }}=\mathrm{V}_{\mathrm{S}} \times \mathrm{I}_{\mathrm{S}}+\Sigma\left[\left(\mathrm{V}_{\mathrm{S}}-\mathrm{V}_{\text {OUT }} \mathrm{i}\right) \times \mathrm{I}_{\text {LOAD }} \mathrm{i}\right]
$$

when sourcing, and:

$$
P_{\text {DMAX }}=\mathrm{V}_{\mathrm{S}} \times \mathrm{I}_{\mathrm{S}}+\Sigma\left(\mathrm{V}_{\text {OUT }} \mathrm{i} \times \mathrm{I}_{\text {LOAD }} \mathrm{i}\right)
$$

when sinking.
Where:

- $\mathrm{i}=1$ to total 12
- $\mathrm{V}_{\mathrm{S}}=$ Supply voltage
- $I_{S}=$ Quiescent current
- $\mathrm{V}_{\text {OUT }}{ }^{i}=$ Output voltage of the i channel
- LoADi $=$ Load current of the i channel

By setting the two PDMAX equations equal to each other, we can solve for the R LOAD's to avoid the device overheat. The package power dissipation curves provide a convenient way to see if the device will overheat.

## POWER SUPPLY BYPASSING AND PRINTED CIRCUIT BOARD LAYOUT

Good printed circuit board layout is necessary for optimum performance. A low impedance and clean analog ground plane should be used for the EL5226 and EL5326. The traces from the two ground pins to the ground plane must be very short. The thermal pad of the EL5226 and EL5326 should be connected to the analog ground plane. Lead length should be as short as possible and all power supply pins must be well bypassed. A $0.1 \mu \mathrm{~F}$ ceramic capacitor must be place very close to the $\mathrm{V}_{\mathrm{S}}, \mathrm{V}_{\text {REFH }}, \mathrm{V}_{\text {REFL }}$, and CAP pins. A $4.7 \mu \mathrm{~F}$ local bypass tantalum capacitor should be placed to the $\mathrm{V}_{\mathrm{S}}, \mathrm{V}_{\text {REFH }}$, and $\mathrm{V}_{\text {REFL }}$ pins.

## APPLICATION USING THE EL5226 AND EL5326

In the first application drawing, the schematic shows the interconnect of a pair of EL5226 and EL5326 chips connected to give 8 gamma corrected voltages above the $\mathrm{V}_{\text {COM }}$ voltage, and 8 gamma corrected voltages below the $V_{\text {COM }}$ voltage.

## Application Drawing



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