

### **General Description**

The MAX3097E/MAX3098E feature three high-speed RS-485/RS-422 receivers with fault-detection circuitry and fault-status outputs. The receivers' inputs have fault thresholds that detect when the part is not in a valid state.

The MAX3097E/MAX3098E indicate when a receiver input is in an open-circuit condition, short-circuit condition, or outside the common-mode range. They also generate a fault indication when the differential input voltage goes below a preset threshold. See Ordering Information or the Electrical Characteristics for threshold values.

The fault circuitry includes a capacitor-programmable delay to ensure that there are no erroneous fault conditions even at slow edge rates. Each receiver is capable of accepting data at rates up to 32Mbps.

### **Applications**

RS-485/RS-422 Receivers for Motor-Shaft **Encoders** 

High-Speed, Triple RS-485/RS-422 Receiver with Extended Electrostatic Discharge (ESD)

Triple RS-485/RS-422 Receiver with Input Fault Indication

**Telecommunications** 

**Embedded Systems** 

#### Features

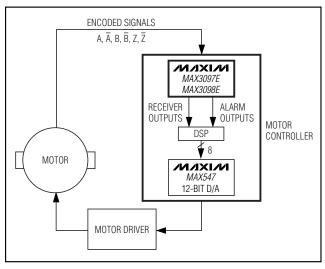
- ♦ Detects the Following RS-485 Faults:
  - **Open-Circuit Condition Short-Circuit Condition** Low Differential Voltage Signal **Common-Mode Range Violation**
- **♦ ESD Protection** 
  - ±15kV—Human Body Model ±15kV—IEC 1000-4-2, Air-Gap Discharge Method
  - ±8kV—IEC 1000-4-2, Contact Discharge Method
- ♦ Single +3V to +5.5V Operation
- ♦ -10V to +13.2V Extended Common-Mode Range
- ♦ Capacitor-Programmable Delay of Fault Indication Allows Error-Free Operation at Slow Data Rates
- ♦ Independent and Universal Fault Outputs
- ♦ 32Mbps Data Rate
- ♦ 16-Pin QSOP is 40% Smaller than Industry-Standard 26LS31/32 Solutions

## **Ordering Information**

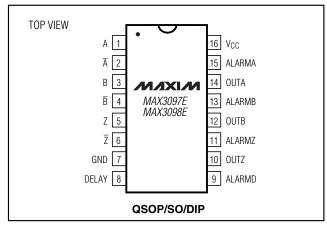
PART	TEMP. RANGE	PIN- PACKAGE
MAX3097ECEE	0°C to +70°C	16 QSOP
MAX3097ECSE	0°C to +70°C	16 SO

Ordering Information continued at end of data sheet.

## **Typical Application Circuit**



## Pin Configuration



MIXIM

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#### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage (V <sub>CC</sub> )	+7V
Receiver Input Voltage (A, A, B, B, Z, Z)	±25V
Output Voltage (OUT_, ALARM_)0.3V to (VC	C + 0.3V
DELAY0.3V to (V <sub>C</sub>	C + 0.3V
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
16-Pin QSOP (derate 8.3mW/°C above +70°C)	667mW
16-Pin SO (derate 8.7mW/°C above +70°C)	696mW
16-Pin Plastic DIP (derate 10.53mW/°C	
above +70°C)	762mW

Operating Temperature Ranges	
MAX3097EC_E	0°C to +70°C
MAX3098E_C_E	0°C to +70°C
MAX3097E_E_E	40°C to +85°C
MAX3098E_E_E	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = +3V \text{ to } +5.5V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	1	MIN	TYP	MAX	UNITS
Supply Voltage Range	Vcc			3		5.5	V
Supply Current	Icc	No load			3.1	4.0	mA
Receiver Differential Threshold Voltage (Note 1)	V <sub>TH</sub>	-10V ≤ V <sub>CM</sub> ≤ 13.2V		-200		+200	mV
Receiver Input Hysteresis	$\Delta V_{TH}$	-10V ≤ V <sub>CM</sub> ≤ 13.2V			40		mV
Output High Voltage	Vou	V <sub>CC</sub> = 4.75V, I <sub>O</sub> = -4mA, V <sub>ID</sub> = 200mV		V <sub>CC</sub> - 1.5			V
Output High Voltage	VoH	$V_{CC} = 3.0V, I_{O} = -1mA, V_{ID} =$	200mV	V <sub>CC</sub> - 1.0			V
Output Low Voltage	Voi	$V_{CC} = 4.75V$ , $I_{O} = +4mA$ , $V_{ID}$	= -200mV			0.4	V
Output Low Voltage	VoL	$V_{CC} = 3.0V, I_{O} = +1mA, V_{ID} =$	= -200mV			0.4	V
Receiver Input Resistance	R <sub>IN</sub>	$-10V \le V_{CM} \le 13.2V$		90		160	kΩ
Input Current	liN	V <sub>CC</sub> = 0 or 5.5V	V <sub>IN</sub> = 13.2V (Note 2)	0.07		0.14	- mA
$(A, \overline{A}, B, \overline{B} (Z, \overline{Z})$			V <sub>IN</sub> = -10V (Note 2)	-0.05		-0.11	
Output Short-Circuit Current	IOSR	0 ≤ V <sub>RO</sub> ≤ V <sub>CC</sub>				±105	mA
FAULT DETECTION							
MAX3097E Fault-Detection Receiver Differential Threshold	FDIFH	V <sub>CM</sub> = 0	High limit	275		475	- mV
Voltage (Note 3)	FDIFL	VOIVI — O	Low limit	-475		-275	1110
MAX3098EA Fault-Detection Receiver Differential Threshold	FDIFH	High limit		0.12		0.20	V
Voltage (Note 3)	FDIFL	$V_{CM} = 0$	Low limit	-0.20		-0.12	V

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC} = +3V \text{ to } +5.5V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	;	MIN	TYP	MAX	UNITS
MAX3098EB Fault-Detection Receiver Differential Threshold	FDIFH	V <sub>CM</sub> = 0	High limit	70		250	- mV
Voltage (Note 3)	F <sub>DIFL</sub>	vCM = 0	Low limit	-250		-70	IIIV
Fault-Detection Common-Mode	FCMH	High limit		13.2			V
Voltage Range (Note 4)	FCML	Low limit				-10	V
DELAY Current Source		$V_{CC} = 5V$ , $V_{DELAY} = 0$	9	10	11	μΑ	
DELAY Threshold		$V_{CC} = 3V$		1.55	1.73	1.90	V
DELAY ITII'eshold		$V_{CC} = 5V$		3.1	3.29	3.5	
ESD PROTECTION							
500 0		Human Body Model			±15		
ESD Protection $(A, \overline{A}, B, \overline{B}, Z, \overline{Z})$		IEC1000-4-2 (Air-Gap Discharge)			±15	•	kV
(,, ,, ,, ,, ,, ,, ,, ,, ,, ,, ,, ,, ,,		IEC1000-4-2 (Contact Discha	rge)		±8		

#### **SWITCHING CHARACTERISTICS**

 $(V_{CC} = +3V \text{ to } +5.5V, V_{ID} = \pm 3.0V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $V_{CC} = +5V$  and  $T_A = +25^{\circ}C$ .)

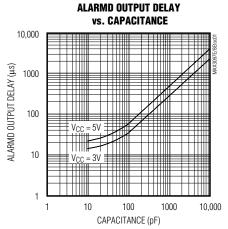
PARAMETER	SYMBOL	CO	NDITIONS	MIN	TYP	MAX	UNITS	
Propagation Delay from Input to Output	t <sub>PLH</sub> , t <sub>PHL</sub>	C <sub>L</sub> = 15pF, Figures 1, 2	V <sub>CC</sub> = 4.5V to 5.5V V <sub>CC</sub> = 3.0V to 3.6V			75 85	ns	
Receiver Skew ItpLH - tpHLI	tskew	$C_L = 15pF$ , Figures	s 1, 2			±10	ns	
Channel-to-Channel Propagation Delay Skew		C <sub>L</sub> = 15pF, Figures	1, 2			±10	ns	
Maximum Data Rate	f <sub>MAX</sub>	C <sub>L</sub> = 15pF, Figure 1		32			Mbps	
FAULT DETECTION								
Differential Fault Propagation	tDFLH	0 45 5 5				15		
Delay to Output (Note 5)	tDFHL	C <sub>LF</sub> = 15pF, Figure	\$ 1, 3			1.2	μs	
Minimum Differential Slew Rate		MAX3097E (Note 6	)	1.0				
to Avoid False Alarm Output		MAX3098E (Note 7	)	0.33			V/μs	
Common-Mode Fault	tCMFLH	0 15 5 5				15		
Propagation Delay to Output (Note 5)	tCMFHL	C <sub>L</sub> = 15pF, Figures	1, 4			1.5	μs	

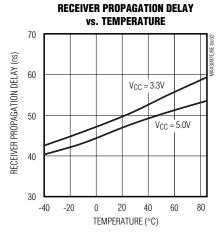
- Note 1:  $V_{CM}$  is the common-mode input voltage.  $V_{ID}$  is the differential input voltage.
- Note 2: V<sub>IN</sub> is the input voltage at pins A, A, B, B, Z, Z.
- Note 3: A differential terminating resistor is required for proper function of open-circuit fault detection (see Applications Information).
- **Note 4:** See *Applications Information* for a discussion of the receiver common-mode voltage range and the operating conditions for fault indication.
- Note 5: Applies to the individual channel immediate-fault outputs (ALARM\_) and the general delayed-fault output (ALARMD) when there is no external capacitor at DELAY.
- Note 6: Equivalent pulse test: 1.3V / (t<sub>DFLH</sub> t<sub>DFHL</sub>) ≥ SR<sub>D</sub>.
- Note 7: Equivalent pulse test: 0.62V / (tDFLH tDFHL) ≥ SRD.

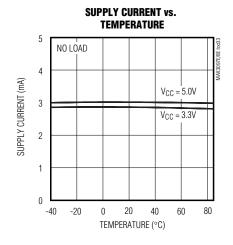


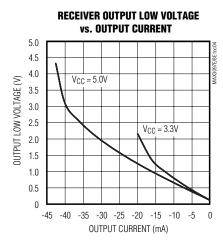
## **Typical Operating Characteristics**

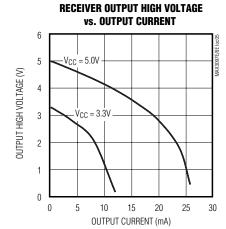
(Typical values are at  $V_{CC} = +5V$  and  $T_A = +25$ °C.)

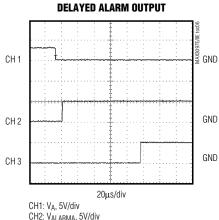






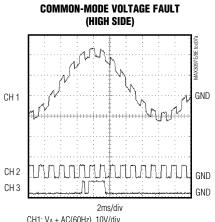






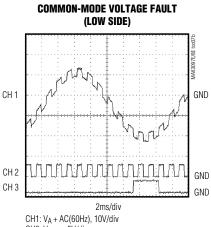
## **Typical Operating Characteristics (continued)**

(Typical values are at  $V_{CC} = +5V$  and  $T_A = +25^{\circ}C$ .)

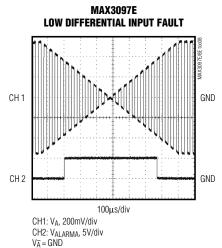


CH1: VA + AC(60Hz), 10V/div CH2: V<sub>OUTA</sub>, 5V/div CH3: V<sub>ALARMA</sub>, 5V/div

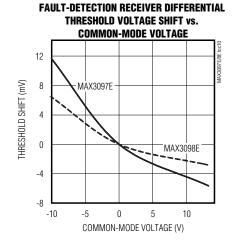
 $V_{CC} = 3V$ 



CH2: V<sub>OUTA</sub>, 5V/div CH3: V<sub>ALARMA</sub>, 5V/div  $V_{CC} = 3V$ 



# **SLEW-RATE FAULT** CH 1 <sup>≨</sup> GND GND CH1: V<sub>A</sub>, 5V/div CH2: VALARMA, 5V/div SLEW RATE = 0.05V/µs $V_{\overline{A}} = GND$



## **Pin Description**

PIN	NAME	FUNCTION
1	А	Noninverting Receiver A Input
2	Ā	Inverting Receiver A Input
3	В	Noninverting Receiver B Input
4	B	Inverting Receiver B Input
5	Z	Noninverting Receiver Z Input
6	Z	Inverting Receiver Z Input
7	GND	Ground
8	DELAY	Programmable Delay Terminal. Connect a capacitor from DELAY to GND to set the ALARMD output delay time. To obtain a minimum delay, leave DELAY unconnected. See Capacitance vs. ALARMD Output Delay in the <i>Typical Operating Characteristics</i> .
9	ALARMD	Delayed Fault Output. This output is the logic OR of ALARMA, ALARMB, and ALARMZ. Place a capacitor from the DELAY pin to GND to set the delay (see <i>Setting Delay Time</i> ). A high logic level indicates a fault condition on at least one receiver input pair. A low level on this pin indicates no fault condition is present.
10	OUTZ	Z Receiver Output. If $V_Z - V_{\overline{Z}} \ge +200 \text{mV}$ , OUTZ will be high. If $V_Z - V_{\overline{Z}} \le -200 \text{mV}$ , OUTZ will be low. If Z or $\overline{Z}$ exceeds the receiver's input common-mode voltage range, the ALARMZ output will be high and OUTZ will be indeterminate.
11	ALARMZ	Z Fault Output. When ALARMZ is high, OUTZ is indeterminate. Tables 1 and 2 show all the possible states for which an alarm is set.
12	OUTB	B Receiver Output. If $V_B - V_{\overline{B}} \ge +200 \text{mV}$ , OUTB will be high. If $V_B - V_{\overline{B}} \le -200 \text{mV}$ , OUTB will be low. If B or $\overline{B}$ exceeds the input receiver's common-mode voltage range, the ALARMB output will be high and OUTB will be indeterminate.
13	ALARMB	B Fault Output. When ALARMB is high, OUTB is indeterminate. Tables 1 and 2 show all the possible states for which an alarm is set.
14	OUTA	A Receiver Output. If $V_A - V_{\overline{A}} \ge +200 \text{mV}$ , OUTA will be high. If $V_A - V_{\overline{A}} \le -200 \text{mV}$ , OUTA will be low. If A or $\overline{A}$ exceeds the receiver's input common-mode voltage range, the ALARMA output will be high and OUTA will be indeterminate.
15	ALARMA	A Fault Output. When ALARMA is high, OUTA is indeterminate. Tables 1 and 2 show all the possible states for which an alarm is set.
16	Vcc	Power Supply

### **Detailed Description**

The MAX3097E/MAX3098E feature high-speed, triple RS-485/RS-422 receivers with fault-detection circuitry and fault-status outputs. The fault outputs are active push-pull, requiring no pull-up resistors. The fault circuitry includes a capacitor-programmable delayed FAULT\_ output to ensure that there are no erroneous fault conditions even at slow edge rates (see *Delayed Fault Output*). The receivers operate at data rates up to 32Mbps.

The MAX3097E/MAX3098E are designed for motorshaft encoders with standard A, B, and Z outputs (see Using the MAX3097E/MAX3098E as Shaft Encoder Receivers). The devices provide an alarm for open-circuit conditions, short-circuit conditions, data nearing the minimum differential threshold conditions, data below the minimum threshold conditions, and receiver inputs outside the input common-mode range. Tables 1 and 2 are functional tables for each receiver.

#### **Test Circuits and Waveforms**

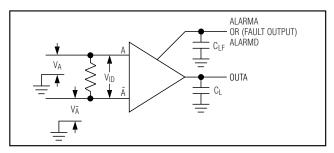


Figure 1. Typical Receiver Test Circuit

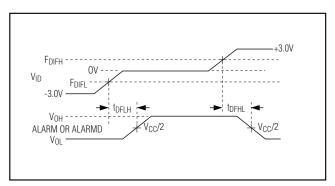


Figure 3. Fault-Detection Timing

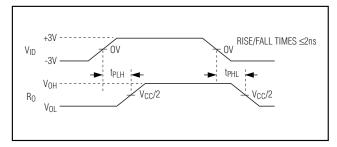


Figure 2. Propagation Delay

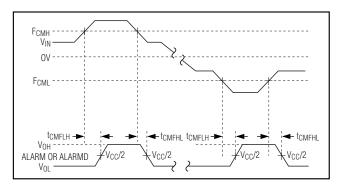


Figure 4. Common-Mode Fault Propagation Delay

Table 1. MAX3097E Alarm Function Table (Each Receiver)

INPU	TS		OUTPUTS		
V <sub>ID</sub> (DIFFERENTIAL INPUT VOLTAGE)	COMMON-MODE VOLTAGE	OUT_	ALARM_	ALARMD t ≥ DELAY (NOTE 1)	FAULT CONDITION
≥0.475V	≤13.2V and ≥-10V	1	0	0	Normal Operation
<0.475V and ≥0.275V		1	Indeterminate	Indeterminate	Indeterminate
<0.275V and ≥0.2V		1	1	1	Low Input Differential Voltage
≤0.2V and ≥-0.2V		Indeterminate (Note 2)	1	1	Low Input Differential Voltage
≤-0.2V and >-0.275V		0	1	1	Low Input Differential Voltage
≤-0.275V and >-0.475V		0	Indeterminate	Indeterminate	Indeterminate
≤-0.475V		0	0	0	
X	<-10V or >+13.2V	Indeterminate (Note 3)	1	1	Outside Common-Mode Voltage Range

X = Don't care

Note 1: ALARMD indicates fault for any receiver.

Note 2: Receiver output may oscillate with this differential input condition.

Note 3: See Applications Information for conditions leading to input range fault condition.

Table 2. MAX3098EA Alarm Function Table (Each Receiver)

INPU	TS		OUTPUTS		
V <sub>ID</sub> (DIFFERENTIAL INPUT VOLTAGE)	COMMON-MODE VOLTAGE	оит_	ALARM_	ALARMD t ≥ DELAY (NOTE 1)	FAULT CONDITION
≥0.2V		1	0	0	Normal Operation
<0.2V and ≥0.12V		Indeterminate	Indeterminate	Indeterminate	Indeterminate
<0.12V and ≥-0.12V	≤13.2V and ≥- 10V	Indeterminate (Note 2)	1	1	Low Input Differential Voltage
≤-0.12V and ≥ -0.2V		Indeterminate	Indeterminate	Indeterminate	Indeterminate
≤-0.2V		0	0	0	Normal Operation
X	<-10V or >+13.2V	Indeterminate (Note 3)	1	1	Outside Common-Mode Voltage Range

X = Don't care; for B-grade functionality, replace  $V_{ID}$  input values in Table 2 with B-grade parameters from Electrical Characteristics.

Note 1: ALARMD indicates fault for any receiver.

Note 2: Receiver output may oscillate with this differential input condition.

Note 3: See Applications Information for conditions leading to input range fault condition.

#### ±15kV ESD Protection

As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against ESD encountered during handling and assembly. The MAX3097E/MAX3098E receiver inputs have extra protection against static electricity found in normal operation. Maxim's engineers developed state-of-the-art structures to protect these pins against ±15kV ESD without damage. After an ESD event, the MAX3097E/MAX3098E continue working without latchup.

ESD protection can be tested in several ways. The receiver inputs are characterized for protection to the following:

- ±15kV using the Human Body Model
- ±8kV using the Contact Discharge method specified in IEC 1000-4-2 (formerly IEC 801-2)
- 15kV using the Air-Gap Discharge method specified in IEC 1000-4-2 (formerly IEC 801-2)

#### **ESD Test Conditions**

ESD performance depends on a number of conditions. Contact Maxim for a reliability report that documents test setup, methodology, and results.

#### **Human Body Model**

Figure 5a shows the Human Body Model, and Figure 5b shows the current waveform it generates when discharged into a low impedance. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the device through a  $1.5 \mathrm{k}\Omega$  resistor.

#### IEC 1000-4-2

Since January 1996, all equipment manufactured and/or sold in the European community has been required to meet the stringent IEC 1000-4-2 specification. The IEC 1000-4-2 standard covers ESD testing and performance of finished equipment; it does not specifically refer to integrated circuits. The MAX3097E/MAX3098E help you design equipment that meets Level 4 (the highest level) of IEC 1000-4-2, without additional ESD-protection components.

The main difference between tests done using the Human Body Model and IEC 1000-4-2 is higher peak current in IEC 1000-4-2. Because series resistance is lower in the IEC 1000-4-2 ESD test model (Figure 6a), the ESD-withstand voltage measured to this standard is generally lower than that measured using the Human Body Model. Figure 6b shows the current waveform for the ±8kV IEC 1000-4-2 Level 4 ESD Contact Discharge test. The Air-Gap test involves approaching the device with a charge probe. The Contact Discharge method connects the probe to the device before the probe is energized.

#### Machine Model

The Machine Model for ESD testing uses a 200pF storage capacitor and zero-discharge resistance. It mimics the stress caused by handling during manufacturing and assembly. All pins (not just RS-485 inputs) require this protection during manufacturing. Therefore, the Machine Model is less relevant to the I/O ports than are the Human Body Model and IEC 1000-4-2.

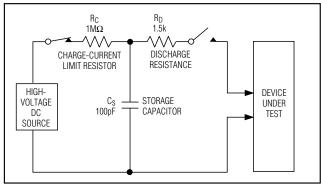


Figure 5a. Human Body ESD Test Model

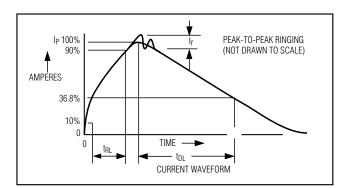


Figure 5b. Human Body Model Current Waveform

## \_Applications Information

#### Using the MAX3097E/MAX3098E as Shaft Encoder Receivers

The MAX3097E/MAX3098E are triple RS-485 receivers designed for shaft encoder receiver applications. A shaft encoder is an electromechanical transducer that converts mechanical rotary motion into three RS-485 differential signals. Two signals, A (A and A) and B (B and B) provide incremental pulses as the shaft turns, while the index signal, Z (Z and Z) occurs only once per revolution to allow synchronization of the shaft to a known position. Digital signal processing (DSP) techniques are used to count the pulses and provide feedback of both shaft position and shaft velocity for a stable positioning system.

Shaft encoders typically transmit RS-485 signals over twisted-pair cables since the signal often has to travel across a noisy electrical environment (Figure 7).

#### **Detecting Faults**

Signal integrity from the shaft encoder to the DSP is essential for reliable system operation. Degraded signals could cause problems ranging from simple miscounts to loss of position. In an industrial environment, many problems can occur within the three twisted pairs. The MAX3097E/MAX3098E can detect various types of common faults, including a low-input-level signal, open-circuit wires, short-circuit wires, and an input signal outside the common-mode input voltage range of the receiver.

#### **Detecting Short Circuits**

In Figure 8, if wires A and  $\overline{A}$  are shorted together, then A and  $\overline{A}$  will be at the same potential, so the difference in the voltage between the two will be approximately 0. This causes fault A to trigger since the difference between A  $\overline{A}$  is less than the differential fault threshold.

#### **Detecting Open-Circuit Conditions**

Detecting an open-circuit condition is similar to detecting a short-circuit condition and relies on the terminating resistor being across A and  $\overline{A}$ . For example, if the wire drops out of the  $\overline{A}$  terminal, A pulls  $\overline{A}$  through the terminating resistor to look like the same signal. In this condition,  $V_{ID}$  is approximately 0 and a fault occurs.

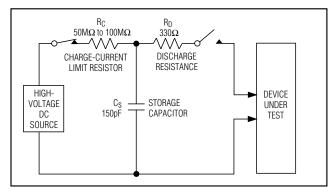


Figure 6a. IEC 1000-4-2 ESD Test Model

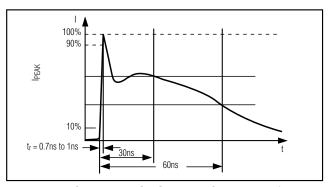


Figure 6b. IEC 1000-4-2 ESD Generator Current Waveform

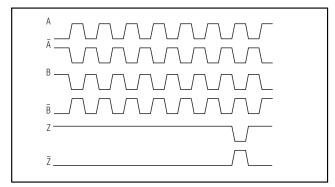


Figure 7. Typical Shaft Encoder Output

#### **Common-Mode Range**

The MAX3097E/MAX3098E contain circuitry that detects if the input stage is going outside its useful common-mode range. If the received data could be unreliable, a fault signal is triggered.

#### **Detecting Low Input Differential**

Due to cable attenuation on long wire runs, it is possible that V<sub>ID</sub> < 200mV, and incorrect data will be received. In this condition, a fault will be indicated.

#### **Delayed Fault Output**

The delayed fault output provides a programmable blanking delay to allow transient faults to occur without triggering an alarm. Such faults may occur with slow signals triggering the receiver alarm through the zero crossover region.

Figure 9 shows the delayed alarm output.

ALARMD performs a logic OR of ALARMA, ALARMB, and ALARMZ (Figure 10). A NOR gate drives an N-channel MOSFET so that in normal operation with no faults, the current source (10µA typ) is shunted to

ground. Upon activation of any alarm from receiver A, B, or Z, the MOSFET is turned off, allowing the current source to charge CDELAY. When VDELAY exceeds the DELAY threshold, the comparator output, ALARMD, goes high. ALARMD is reset when all receiver alarms go low, quickly discharging CDELAY to ground.

#### **Setting Delay Time**

ALARMD's delay time is set with a single capacitor connected from DELAY to GND. The delay comparator threshold varies with supply voltage, and the CDELAY value can be determined for a given time delay period from the Capacitance vs. ALARMD Output Delay graph in the *Typical Operating Characteristics* or using the following equations:

$$t_D = 15 + 0.33 \times C_{DELAY}$$
 (for  $V_{CC} = 5V$ )

and

$$t_D = 10 + 0.187 \times C_{DELAY}$$
 (for  $V_{CC} = 3V$ )

where to is in µs and CDELAY is in pF.

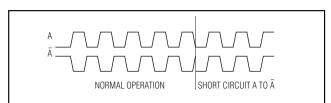


Figure 8. Short-Circuit Detection

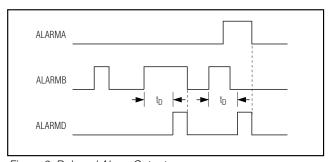


Figure 9. Delayed Alarm Output

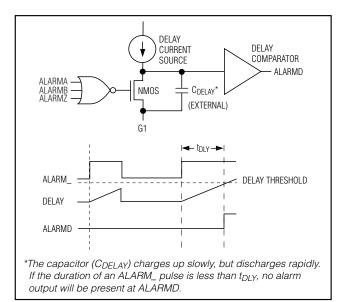
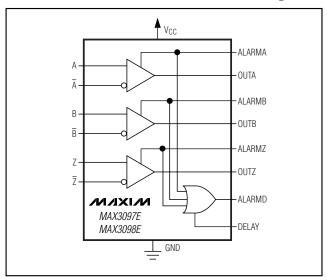


Figure 10. ALARMD Simplified Schematic

## Ordering Information (continued)

PART	TEMP. RANGE	PIN- PACKAGE
MAX3097ECPE	0°C to +70°C	16 Plastic DIP
MAX3097EEEE	-40°C to +85°C	16 QSOP
MAX3097EESE	-40°C to +85°C	16 SO
MAX3097EEPE	-40°C to +85°C	16 Plastic DIP
MAX3098EACEE	0°C to +70°C	16 QSOP
MAX3098EACSE	0°C to +70°C	16 SO
MAX3098EACPE	0°C to +70°C	16 Plastic DIP
MAX3098EAEEE	-40°C to +85°C	16 QSOP
MAX3098EAESE	-40°C to +85°C	16 SO
MAX3098EAEPE	-40°C to +85°C	16 Plastic DIP
MAX3098EBCEE	0°C to +70°C	16 QSOP
MAX3098EBCSE	0°C to +70°C	16 SO
MAX3098EBCPE	0°C to +70°C	16 Plastic DIP
MAX3098EBEEE	-40°C to +85°C	16 QSOP
MAX3098EBESE	-40°C to +85°C	16 SO
MAX3098EBEPE	-40°C to +85°C	16 Plastic DIP

## \_Functional Diagram

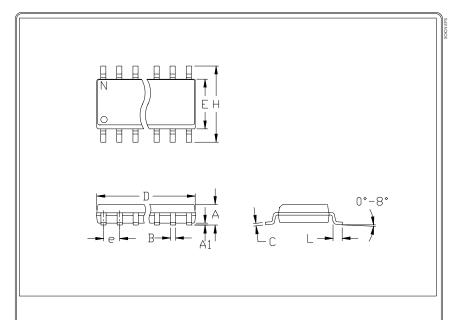


## **Chip Information**

**TRANSISTOR COUNT: 675** 

PROCESS: CMOS

## **Package Information**



	INC	HES	MILLIM	ETERS			
	MIN	MAX	MIN	MAX			
Α	0.053	0.069	1.35	1.75			
Α1	0.004	0.010	0.10	0.25			
В	0.014	0.019	0.35	0.49			
С	0.007	0.010	0.19	0.25			
е	0.0	)50	1.7	27			
Ε	0.150	0.157	3.80	4.00			
Н	0.228	0.244	5.80	6.20			
h	0.010	0.020	0.25	0.50			
L	0.016	0.050	0.40	1.27			

	INCHES		MILLIM	ETERS		
	MIN	MAX	MIN	MAX	Ν	MS012
D	0.189	0.197	4.80	5.00	8	Α
D	0.337	0.344	8.55	8.75	14	В
D	0.386	0.394	9.80	10.00	16	С

#### NOTES:

- NOTES:

  1. D&E DO NOT INCLUDE MOLD FLASH
  2. MOLD FLASH OR PROTRUSIONS NOT
  TO EXCEED .15mm (.006\*)

  3. LEADS TO BE COPLANAR WITHIN
  .102mm (.004\*)

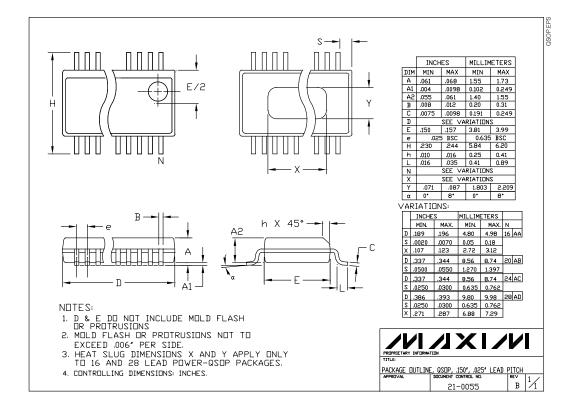
  4. CONTROLLING DIMENSION: MILLIMETER
  5. MEETS JEDEC MS012-XX AS SHOWN
  IN ABOVE TABLE
  6. N = NUMBER OF PINS



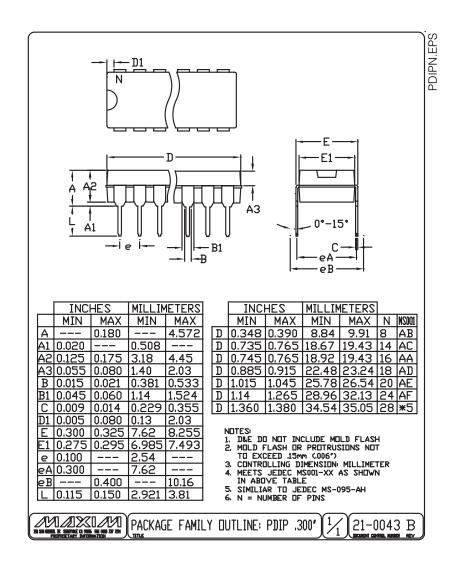
PACKAGE FAMILY DUTLINE: SDIC .150"



## Package Information (continued)



## Package Information (continued)



**NOTES** 

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