

High Speed 8-Bit TTL A/D Converter

AD9012

FEATURES

100 MSPS Encode Rate Very Low Input Capacitance—16 pF Low Power—1 W TTL Compatible Outputs MIL-STD-883 Compliant Versions Available

APPLICATIONS Radar Guidance Digital Oscilloscopes/ATE Equipment Laser/Radar Warning Receivers Digital Radio Electronic Warfare (ECM, ECCM, ESM) Communication/Signal Intelligence

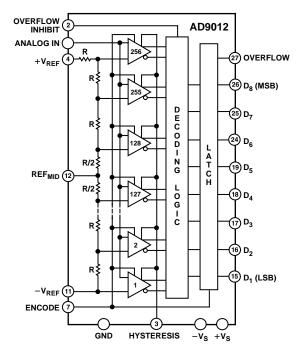
GENERAL DESCRIPTION

The AD9012 is an 8-bit, ultrahigh speed, analog-to-digital converter. The AD9012 is fabricated in an advanced bipolar process that allows operation at sampling rates up to one hundred megasamples/second. Functionally, the AD9012 is comprised of 256 parallel comparator stages whose outputs are decoded to drive the TTL compatible output latches.

The exceptionally wide large-signal analog input bandwidth of 160 MHz is due to an innovative comparator design and very close attention to device layout considerations. The wide input bandwidth of the AD9012 allows very accurate acquisition of high speed pulse inputs without an external track-and-hold. The comparator output decoding scheme minimizes false codes, which is critical to high speed linearity.

The AD9012 is available in two grades: one with 0.5 LSB linearity and one with 0.75 LSB linearity. Both versions are offered in

FUNCTIONAL BLOCK DIAGRAM



an industrial grade, -25° C to $+85^{\circ}$ C, packaged in a 28-lead DIP and a 28-lead JLCC. The military temperature range devices, -55° C to $+125^{\circ}$ C, are available in ceramic DIP and LCC packages and are compliant to MIL-STD-883 Class B.

The AD9012 is available in versions compliant with MIL-STD-883. Refer to the Analog Devices Military Products Databook or current AD9012/883B data sheet for detailed specifications.

REV. D

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$\label{eq:additional} \begin{array}{l} \textbf{AD9012-SPECIFICATIONS} \\ \textbf{ELECTRICAL CHARACTERISTICS} & (+V_s=+5.0 \ \text{V}; -V_s=-5.2 \ \text{V}; \ \text{Differential Reference Voltage} = 2.0 \ \text{V}; \ \text{unless otherwise noted}) \end{array}$

		Teer		001244			001204)/D1	40	001202	NET	40	001277	N/TF	
Parameter	Temp	Test Level		09012AC Typ	J/AJ Max	AL Min	09012BC Typ	2/BJ Max	AD Min	9012SQ Typ	VSE Max	AD Min	9012TC Typ	2/TE Max	Units
RESOLUTION			8			8			8			8			Bits
DC ACCURACY Differential Linearity Integral Linearity No Missing Codes	+25°C Full +25°C Full Full	I VI I VI VI	GUA	0.6 0.6 RANTE	0.75 1.0 1.0 1.2 EED	GU	0.4 0.4 ARANT	0.5 0.75 0.5 1.2 YEED	GU	0.6 0.6 JARANT	0.75 1.0 1.0 1.2 FEED	GU	0.4 0.4 JARAN	0.5 0.75 0.5 1.2 TEED	LSB LSB LSB LSB
INITIAL OFFSET ERROR Top of Reference Ladder Bottom of Reference Ladder Offset Drift Coefficient	+25°C Full +25°C Full Full	I VI I VI V		7 6 25	15 18 10 13		7 6 25	15 18 10 13		7 6 25	15 18 10 13		7 6 25	15 18 10 13	mV mV mV µV/°C
ANALOG INPUT Input Bias Current ¹ Input Resistance Input Capacitance Large Signal Bandwidth ² Analog Input Slew Rate ³	+25°C Full +25°C +25°C +25°C +25°C	I VI I III V V	25	60 200 16 160 440	200 200 18	25	60 200 16 160 440	200 200 18	25	60 200 16 160 440	200 200 18	25	60 200 16 160 440	200 200 18	μΑ μΑ kΩ pF MHz V/μs
REFERENCE INPUT Reference Ladder Resistance Ladder Temperature Coefficient Reference Input Bandwidth	+25°C +25°C	VI V V	40	80 0.25 10	110	40	80 0.25 10	110	40	80 0.25 10	110	40	80 0.25 10	110	Ω Ω/°C MHz
DYNAMIC PERFORMANCE Conversion Rate Aperture Delay Aperture Uncertainty (Jitter) Output Delay $(t_{PD})^{4,5}$ Transient Response ⁶ Overvoltage Recovery Time ⁷ Output Rise Time ⁴ Output Fall Time ⁴ Output Time Skew ^{4,8}	+25°C +25°C +25°C +25°C +25°C +25°C +25°C +25°C +25°C +25°C	I V V I V I I V	75 4	100 3.8 15 4.9 8 6.6 3.3 3.0	11 8.0 4.3	75 4	100 3.8 15 4.9 8 8 6.6 3.3 3.0	11 8.0 4.3	75 4	100 3.8 15 4.9 8 8 6.6 3.3 3.0	11 8.0 4.3	75 4	100 3.8 15 4.9 8 6.6 3.3 3.0	11 8.0 4.3	MSPS ns ps ns ns ns ns ns ns ns ns ns
ENCODE INPUT Logic "1" Voltage ⁴ Logic "0" Voltage ⁴ Logic "1" Current Logic "0" Current Input Capacitance Encode Pulsewidth (Low) ⁹ Encode Pulsewidth (High) ⁹	Full Full Full +25°C +25°C +25°C	VI VI VI VI I I	2.0 2.5 2.5	2.5	0.8 250 400	2.0 2.5 2.5	2.5	0.8 250 400	2.0 2.5 2.5	2.5	0.8 250 400	2.0 2.5 2.5	2.5	0.8 250 400	V V µA pF ns ns
OVERFLOW INHIBIT INPUT 0 V Input Current	Full	VI		200	250		200	250		200	250		200	250	μА
AC LINEARITY ¹⁰ Effective Bits ¹¹ In-Band Harmonics dc to 1.23 MHz dc to 9.3 MHz dc to 19.3 MHz Signal-to-Noise Ratio ¹² Noise Power Ratio ¹³	+25°C +25°C +25°C +25°C +25°C +25°C	V I V I V	48 46	7.5 55 50 44 47.6 37		48 46	7.5 55 50 44 47.6 37		48 46	7.5 55 50 44 47.6 37		48 46	7.5 55 50 44 47.6 37		Bits dBc dBc dBc dBc dBc dBc
DIGITAL OUTPUT Logic "1" Voltage Logic "0" Voltage	Full Full	VI VI	2.4		0.4	2.4		0.4	2.4		0.4	2.4		0.4	V V
POWER SUPPLY ¹⁴ Positive Supply Current (+5.0 V) Supply Current (-5.2 V) Nominal Power Dissipation Reference Ladder Dissipation Power Supply Rejection Ratio ¹⁵	+25°C Full +25°C Full +25°C +25°C +25°C	I VI I VI V V I		33 152 955 44 0.85	45 48 179 191 2.5		33 152 955 44 0.85	45 48 179 191 2.5		33 152 955 44 0.8	45 48 179 191 2.5		33 152 955 44 0.8	45 48 179 191 2.5	mA mA mA mW mW mV/V

NOTES

¹Measured with Analog Input = 0 V. ²Measured by FFT analysis where fundamental is -3 dBc. ³Input slew rate derived from rise time (10% to 90%) of full-scale step input. ⁴Outputs terminated with two equivalent 'LS00 type loads. (See load circuit.) ⁵Measured from ENCODE into data out for LSB only. ⁶For full-scale step input, 8-bit accuracy is attained in specified time. ⁷Recovers to 8-bit accuracy in specified time, after 150% full-scale input overvoltage. ⁸Output time skew includes high-to-low and low-to-high transitions as well as bit-to-bit time skew differences.

ABSOLUTE MAXIMUM RATINGS¹

Positive Supply Voltage $(+V_S)$ +6 V
Analog to Digital Supply Voltage Differential $(-V_S)$ 0.5 V
Negative Supply Voltage $(-V_S)$
Analog Input Voltage $\dots \dots -V_S$ to +0.5 V
ENCODE Input Voltage
OVERFLOW INH Input Voltage
Reference Input Voltage $(+V_{REF}-V_{REF})^2$ 3.5 V to +0.1 V
Differential Reference Voltage2.1 V
Reference Midpoint Current ±4 mA
Digital Output Current 30 mA
Operating Temperature Range
AD9012AQ/BQ/AJ/BJ25°C to +85°C
AD9012SE/SQ/TE/TQ
Storage Temperature Range65°C to +150°C
Junction Temperature ³ +175°C

NOTES

¹Absolute maximum ratings are limiting values, to be applied individually, and beyond which the serviceability of the circuit may be impaired. Functional operability under any of these conditions is not necessarily implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

 $^{2}+V_{REF} \ge -V_{REF}$ under all circumstances.

³Maximum junction temperature (t₁ max) should not exceed +175°C for ceramic packages, and +150°C for plastic packages:

 $t_{I} = PD(\theta_{IA}) + t_{A}$

PD (θ_{JC}) + tc where

PD = power dissipation

 θ_{IA} = thermal impedance from junction to ambient (°C/W)

 θ_{IC} = thermal impedance from junction to case (°C/W)

 t_A = ambient temperature (°C)

 $t_{\rm C}$ = case temperature (°C)

Ceramic DIP $\theta_{IA} = 42^{\circ}C/W$; $\theta_{IC} = 10^{\circ}C/W$ Ceramic LCC $\theta_{IA} = 50^{\circ}C/W$; $\theta_{IC} = 15^{\circ}C/W$ JLCC $\theta_{IA} = 59^{\circ}C/W$; $\theta_{IC} = 15^{\circ}C/W$.

Recommended Operating Conditions

		Input Voltage	ge		
Parameter	Min	Nominal	Max		
$\overline{-V_s}$	-5.46	-5.20	-4.94		
$+V_{s}$	+4.75	5.00	+5.25		
$+V_{REF}$	-V _{REF}	0.0 V	+0.1		
-V _{REF}	-2.1	-2.0	$+V_{REF}$		
Analog Input	-V _{REF}		+V _{REF}		

⁹ENCODE signal rise/fall times should be less than 30 ns for normal operation.

¹⁰Measured at 75 MSPS encode rate. Harmonic data based on worst case harmonics. ¹¹Analog input frequency = 1.23 MHz.

¹²RMS signal to rms noise, including harmonics with 1.23 MHz. analog input signal.

- ¹³NPR measured @ 0.5 MHz. Noise Source is 250 mW (rms) from 0.5 MHz to 8 MHz.
- $^{14}\text{Supplies}$ should remain stable within $\pm 5\%$ for normal operation.

 15 Measured at -5.2 V ± 5% and +5.0 V ± 5%.

Specifications subject to change without notice.

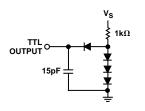


Figure 1. Load Circuit

EXPLANATION OF TEST LEVELS Test Level

- I 100% production tested.
- II -100% production tested at +25°C, and sample tested at specified temperatures. AC testing done on sample basis.
- III Sample tested only.
- IV Parameter is guaranteed by design and characterization testing.
- V Parameter is a typical value only.
- VI All devices are 100% production tested at +25°C. 100% production tested at temperature extremes for extended temperature devices; guaranteed by design and characterization testing for industrial devices.

ORDERING GUIDE

Device	Linearity	Temperature Ranges	Package Options*		
AD9012AQ	0.75 LSB	–25°C to +85°C	Q-28		
AD9012BQ	0.50 LSB	–25°C to +85°C	Q-28		
AD9012AJ	0.75 LSB	–25°C to +85°C	J-28A		
AD9012BJ	0.50 LSB	–25°C to +85°C	J-28A		
AD9012SQ	0.75 LSB	–55°C to +125°C	Q-28		
AD9012SE	0.75 LSB	–55°C to +125°C	E-28A		
AD9012TQ	0.50 LSB	–55°C to +125°C	Q-28		
AD9012TE	0.50 LSB	–55°C to +125°C	E-28A		

*E = Leadless Ceramic Chip Carrier; J = Ceramic Leaded Chip Carrier; Q = Cerdip.

CAUTION_

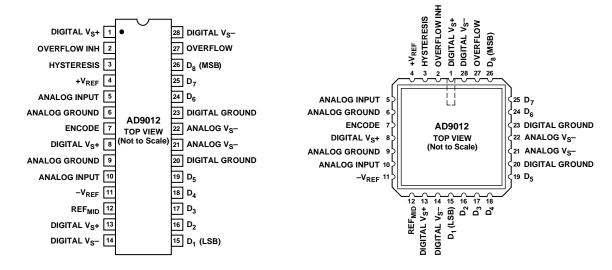
ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD9012 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



PIN FUNCTION DESCRIPTIONS

Pin #	Name	Description						
1 2	DIGITAL +V _S OVERFLOW INH	One of three positive digital supply pins (nominally +5.0 V). OVERFLOW INHIBIT controls the data output coding for overvoltage inputs (AIN \geq + V _{REF}).						
		ANALOG INPUT	OVERFLOW ENABLED (FLOATING) OF $D_1 D_2 D_3 D_4 D_5 D_6 D_7 D_8$	$\begin{array}{c} OVERFLOW \ INHIBITED \ (GND) \\ OF \ D_1 \ D_2 \ D_3 \ D_4 \ D_5 \ D_6 \ D_7 \ D_8 \end{array}$				
		$V_{\rm IN} \ge + V_{\rm REF}$ $V_{\rm IN} < + V_{\rm REF}$	1 0 0 0 0 0 0 0 0 0 0 X X X X X X X X X X	0 1 1 1 1 1 1 1 1 1 0 X X X X X X X X X				
3	HYSTERESIS		is control voltage varies the comparator hyste -5.2 V to -2.2 V at the Hysteresis control pin					
4	+V _{REF}	The most positive reference voltage for the internal resistor ladder.						
5	ANALOG INPUT	One of two analog input pins. Both analog input pins should be connected together.						
6	ANALOG GROUND	One of two analog ground pins. Both analog ground pins should be connected together.						
7	ENCODE	TTL level encode command input. ENCODE is rising edge sensitive.						
8	DIGITAL +V _S	One of three positive digital supply pins (nominally +5.0 V).						
9	ANALOG GROUND		One of two analog ground pins. Both analog ground pins should be connected together.					
10	ANALOG INPUT	One of two analog input pins. Both analog inputs should be connected together.						
11	-V _{REF}	The most negative reference voltage for the internal resistor ladder.						
12	REF _{MID}	The midpoint tap on the internal resistor ladder.						
13	DIGITAL +V _S	One of three positive digital supply pins (nominally +5.0 V).						
14	DIGITAL –V _S	One of two no connected tog	egative digital supply pins (nominally –5.2 V) gether.	. Both digital supply pins should be				
15	D_1 (LSB)	Digital data o	utput. D_1 (LSB) is the least significant bit of	the digital output word.				
16-19	D_2-D_5	Digital data o	utput.					
20	DIGITAL GROUND	One of two di	gital ground pins. Both digital grounds pins	should be connected together.				
21, 22	ANALOG –V _S	One of two no connected tog	egative analog supply pins (nominally -5.2 V gether.). Both analog supply pins should be				
23	DIGITAL GROUND		gital ground pins. Both digital ground pins s	hould be connected together.				
24, 25	D_6, D_7	Digital data o		6				
26	$D_8^{(MSB)}$		utput D_8 (MSB) is the most significant bit of	f the digital output word.				
27	OVERFLOW	Overflow data	a output. Logic HIGH indicates an input ove INHIBIT is enabled (overflow enabled, floa	rvoltage ($V_{IN} > + V_{REF}$), if				
28	DIGITAL –Vs		egative digital supply pins (nominally -5.2 V)					

PIN CONFIGURATIONS



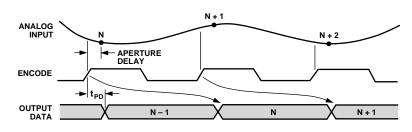
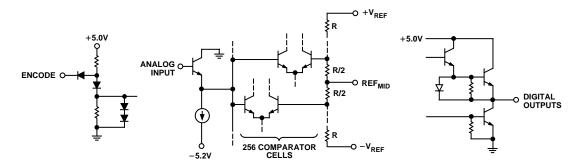
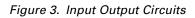
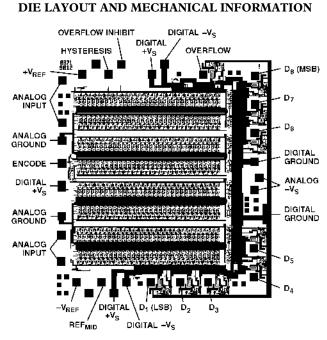


Figure 2. Timing Diagram







Die Dimensions $\dots \dots \dots$
Pad Dimensions
Metalization Gold
Backing None
Substrate PotentialV _S
Passivation Nitride
Die Attach Gold Eutectic (Ceramic)
Epoxy (Plastic)
Bond Wire 1–1.3 mil Gold; Gold Ball Bonding

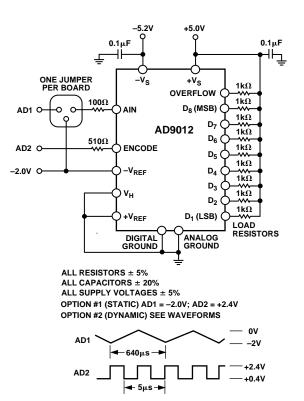


Figure 4. Burn-In Diagram

APPLICATION INFORMATION

The AD9012 is compatible with all standard TTL logic families. However, to operate at the highest encode rates, the supporting logic around the AD9012 will need to be equally fast. Two possible choices are the AS and the ALS families. Whichever of the TTL logic families is used, special care must be exercised to keep digital switching noise away from the analog circuits around the AD9012. The two most critical items are the digital supply lines and the digital ground return.

The input capacitance of the AD9012 is an exceptionally low 16 pF. This allows the use of a wide range of input amplifiers, both hybrid and monolithic. To take full advantage of the 160 MHz input bandwidth of the AD9012, a hybrid amplifier like the AD9610/AD9611 will be required. For those applications that do not require the full input bandwidth of the AD9012, some of the more traditional monolithic amplifiers, like the AD846, should work very well. Overall performance with monolithic amplifiers can be improved by inserting a 40 Ω resistor in series with the amplifier output.

The output data is buffered through the TTL compatible output latches. In addition to the latch propagation delay (t_{PD}) , all data is delayed by one clock cycle, before becoming available at the outputs. Both the analog-to-digital conversion cycle and the data transfer to the output latches are triggered on the rising edge of the TTL-compatible ENCODE signal (see timing diagram).

The AD9012 also incorporates a HYSTERESIS control pin which provides from 0 mV to 10 mV of additional hysteresis in the comparator input stages. Adjustments in the HYSTERESIS control voltage may help to improve noise immunity and overall performance in harsh environments.

The OVERFLOW INHIBIT pin of the AD9012 determines how the converter handles overrange inputs (AIN \geq + V_{REF}). In the "enabled" state (floating at –5.2 V), the OVERFLOW output will be at logic HIGH and all other outputs will be at logic LOW for overrange inputs (return-to-zero operation). In the "inhibited" state (tied to ground), the OVERFLOW output will be at logic LOW for overrange inputs, and all other digital outputs will be at logic HIGH (nonreturn-to-zero operation).

The AD9012 provides outstanding error rate performance. This is due to tight control of comparator offset matching and a fault tolerant decoding stage. Additional improvements in error rate are possible through the addition of hysteresis (see HYSTER-ESIS control pin). This level of performance is extremely important in fault sensitive applications such as digital radio (QAM).

Dramatic improvements in comparator design and construction give the AD9012 excellent dynamic characteristics, namely SNR (signal-to-noise ratio). The 160 MHz input bandwidth and low error rate performance give the AD9012 an SNR of 47 dB with a 1.23 MHz input. High SNR performance is particularly important in broadcast video applications where signals may pass through the converter several times before the processing is complete. Pulse signature analysis, commonly performed in advanced radar receivers, is another area that is especially dependent on high quality dynamic performance.

LAYOUT SUGGESTIONS

Designs using the AD9012, like all high-speed devices, must follow a few basic layout rules to insure optimum performance. Essentially, these guidelines are meant to avoid many of the problems associated with high-speed designs. The first requirement is for a substantial ground plane around and under the AD9012. Separate ground plane areas for the digital and analog components may be useful, but the separate grounds should be connected together at the AD9012 to avoid the effects of "ground loop" currents.

The second area that requires an extra degree of attention involves the three reference inputs, $+V_{REF}$, REF_{MID} , and $-V_{REF}$. The $+V_{REF}$ input and the $-V_{REF}$ input should both be driven from a low impedance source (note that the $+V_{REF}$ input is typically tied to analog ground). A low drift amplifier should provide satisfactory results, even over an extended temperature range. Adjustments at the REF_{MID} input may be useful in improving the integral linearity by correcting any reference ladder skews.

The reference inputs should be adequately decoupled to ground through 0.1 μ F chip capacitors to limit the effects of system noise on conversion accuracy. The power supply pins must also be decoupled to ground to improve noise immunity; 0.1 μ F and 0.01 μ F chip capacitors should be very effective.

The analog input signal is brought into the AD9012 through two separate input pins. It is very important that the two input pins be driven symmetrically with equal length electrical connections. Otherwise, aperture delay errors may degrade converter performance at high frequencies.

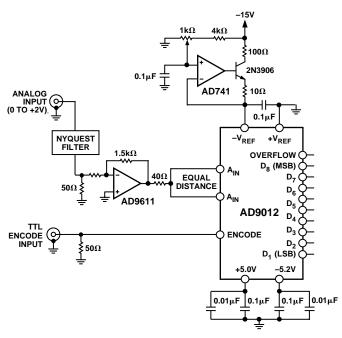


Figure 5. Typical Application

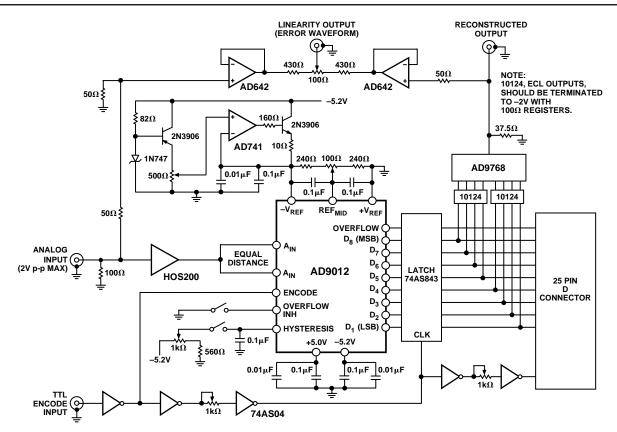


Figure 6. Evaluation Circuit

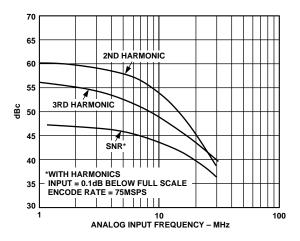


Figure 7. Dynamic Performance

OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

