# 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface 

## General Description

The MAX6633/MAX6634/MAX6635 combine a temperature sensor, a programmable overtemperature alarm, and an SMBus ${ }^{\mathrm{TM}} / \mathrm{I}^{2} \mathrm{C}^{\mathrm{TM}}$-compatible serial interface into a single package. They convert their die temperatures into digital values using internal analog-to-digital converters (ADCs). The result of the conversion is then held in a temperature register as a 12-bit + sign value, allowing $0.0625^{\circ} \mathrm{C}$ resolution, readable at any time through the serial interface. The devices are capable of reading temperatures up to $+150^{\circ} \mathrm{C}$.
The MAX6633/MAX6634/MAX6635 feature a shutdown mode that saves power by turning off everything except the power-on reset (POR) and the serial interface. The devices can be configured to separate addresses, allowing multiple devices to be used on the same bus.
The MAX6633 has four address pins, allowing up to 16 devices to be connected to a single bus. The MAX6634 has three address pins, allowing up to eight devices to be connected to a single bus. The MAX6635 has two address pins, allowing up to four devices to be connected to a single bus.
The MAX6633/MAX6634/MAX6635 make temperature data available for transfer over the serial interface. The MAX6634 incorporates a dual-mode ALERT output (open drain) and can serve as an upgraded alternative to the LM75. The MAX6635 includes an ALERT output and an OVERT output (both open drain) and can function as an upgraded replacement for the LM76 in most applications. The MAX6634/MAX6635 feature user-programmable temperature thresholds. All three devices come in an 8-pin SO package.
Battery Temperature Alarms
PC Temperature Control
Automotive Equipment

Pin Configurations appear at end of data sheet.

SMBus is a trademark of Intel Corp.
${ }^{2} C$ is a trademark of Philips Corp.

## Applications

Battery Temperature Alarms

Automotive Equipment

Features

- +3V to +5.5V Supply Range
- Accuracy
$\pm 1^{\circ} \mathrm{C}$ max $\left(0^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right)$ $\pm 1.5^{\circ} \mathrm{C}$ max $\left(-20^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$ $\pm 2.5^{\circ} \mathrm{C}$ max $\left(-40^{\circ} \mathrm{C}\right.$ to $\left.+125^{\circ} \mathrm{C}\right)$ $\pm 2.5^{\circ} \mathrm{C}$ typ $\left(+150^{\circ} \mathrm{C}\right)$
- User-Programmable Temperature Thresholds (MAX6634/MAX6635)
- User-Configurable Alarm Output(s) (MAX6634/MAX6635)
- Ability to Respond to SMBus/I²C-Compatible Alert Response Address (MAX6634/MAX6635)
- OVERT Output for System Shutdown (MAX6635)
- Multiple Devices per Bus

16 devices (MAX6633)
8 devices (MAX6634)
4 devices (MAX6635)
Ordering Information

| PART | TEMP. RANGE | PIN-PACKAGE |
| :---: | :--- | :--- |
| MAX6633MSA | $-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ | 8 SO |
| MAX6634MSA | $-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ | 8 SO |
| MAX6635MSA | $-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ | 8 SO |

Typical Operating Circuit


# 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface 

\author{

ABSOLUTE MAXIMUM RATINGS <br> | VCc, SDA, SCL | to +6.0 V |
| :---: | :---: |
| All Other Pins | -0.3V to Vcc +0.3V |
| SDA, ALERT, | ..-1mA to +50mA |
| ESD Protection | 2000V |
| Continuous Pow |  |
| 8 -Pin SO (der | ..... 471 m |

Junction Temperature
$+150^{\circ} \mathrm{C}$
Operating Temperature Range .............................. $55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Storage Temperature Range
$-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
Lead Temperature (soldering, 10s) ................................... $300^{\circ} \mathrm{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

$\left(\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}\right.$ to $+5.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are $\mathrm{V}_{\mathrm{C}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TEMPERATURE-TO-DIGITAL CONVERTER CHARACTERISTICS |  |  |  |  |  |  |
| Supply Range | VCC |  | 3.0 |  | 5.5 | V |
| Accuracy (Note 1) |  | $0^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}}=\leq+50^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}$ | -1.0 | $\pm 0.4$ | +1.0 | ${ }^{\circ} \mathrm{C}$ |
|  |  | $-20^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}}=\leq+85^{\circ} \mathrm{C}, \mathrm{V}_{C C}=+3.3 \mathrm{~V}$ | -1.5 | $\pm 0.6$ | +1.5 |  |
|  |  | $-40^{\circ} \mathrm{C} \leq \mathrm{T}_{\mathrm{A}}=\leq 125^{\circ} \mathrm{C}, V_{C C}=+3.3 \mathrm{~V}$ | -2.5 | $\pm 1.0$ | +2.5 |  |
|  |  | $\mathrm{T}_{\mathrm{A}}=-55^{\circ} \mathrm{C}, \mathrm{V}_{C C}=+3.3 \mathrm{~V}$ | -2.8 | $\pm 1.5$ | +2.8 |  |
|  |  | $\mathrm{T}_{\mathrm{A}}=+150^{\circ} \mathrm{C}, \mathrm{V}_{C C}=+3.3 \mathrm{~V}$ |  | $\pm 2.5$ |  |  |
| Power-Supply Rejection Ratio | PSRR |  |  | 0.2 | 0.5 | ${ }^{\circ} \mathrm{C} / \mathrm{V}$ |
| POR Threshold Hysteresis |  |  |  | 90 |  | mV |
| Supply Current in Shutdown |  | $\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}$, SMBus inactive |  | 12 | 20 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}}=+5.5 \mathrm{~V}$, SMBus inactive |  | 20 | 30 |  |
| Average Operating Current |  | $\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}$, SMBus inactive |  | 150 |  | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}}=+5.5 \mathrm{~V}$, SMBus inactive |  | 200 |  |  |
| Peak Operating Current (Note 2) |  | $\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}$, SMBus inactive |  | 270 | 350 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{CC}}=+5.5 \mathrm{~V}$, SMBus inactive |  | 350 | 700 |  |
| Conversion Rate |  |  | 1.4 | 2 | 2.4 | Hz |
| DIGITAL INTERFACE |  |  |  |  |  |  |
| Logic Input Low Voltage | VIL | $\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}$ to +5.5 V |  |  | 0.65 | V |
| Logic Input High Voltage | $\mathrm{V}_{\mathrm{IH}}$ | $V_{C C}=+3 \mathrm{~V}$ | 2.2 |  |  | V |
|  |  | $\mathrm{V}_{C C}=+5.5 \mathrm{~V}$ | 2.4 |  |  |  |
| Input Leakage Current | II_LEAK | $\mathrm{V}_{\mathrm{IN}}=$ GND or $\mathrm{V}_{\text {CC }}$ |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| Output Low Sink Current | IOL | $\begin{aligned} & \mathrm{VOL}=0.6 \mathrm{~V}(\mathrm{SMBDATA}, \\ & \left.\frac{\mathrm{V}}{\mathrm{ALERT}}, \overline{\text { OVERT }}\right) \end{aligned}$ | 6 |  |  | mA |
| Output Leakage Current | IO_LEAK | ALERT, OVERT at VCC |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| Input Capacitance | CIN |  |  | 5 |  | pF |

## 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface

## ELECTRICAL CHARACTERISTICS (continued)

$\left(\mathrm{V}_{\mathrm{CC}}=+3.0 \mathrm{~V}\right.$ to $+5.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-55^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX |
| :--- | :---: | :--- | :--- | :--- | :---: | UNITS

Note 1: Guaranteed by design and characterization.
Note 2: Peak operating current measured during conversion. See Figure 4.
Note 3: Guaranteed by design, not production tested.
Note 4: A master device must provide a hold time of at least 300ns for the SDA signal in order to bridge the undefined region of SCL's falling edge.

## 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface

## Typical Operating Characteristics

$\left(\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted.)


# 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface 

| PIN |  |  | NAME | FUNCTION |
| :---: | :---: | :---: | :---: | :---: |
| MAX6633 | MAX6634 | MAX6635 |  |  |
| 1 | 1 | 1 | SDA | Serial Data Input/Output. Open drain. |
| 2 | 2 | 2 | SCL | Serial Clock Input |
| 3 | - | - | A3 | Address Pin |
| 4 | 4 | 4 | GND | Ground |
| 5 | 5 | - | A2 | Address Pin |
| 6 | 6 | 6 | A1 | Address Pin |
| 7 | 7 | 7 | A0 | Address Pin |
| 8 | 8 | 8 | VCC | Supply Voltage Input. +3.0 V to +5.5 V . Bypass $\mathrm{V}_{\mathrm{CC}}$ to GND with a $0.1 \mu \mathrm{~F}$ capacitor. |
| - | 3 | 5 | $\overline{\text { ALERT }}$ | $\overline{\text { ALERT Output. Open drain. }}$ |
| - | - | 3 | OVERT | OVERT Output. Open drain. |

## Detailed Description

The MAX6633/MAX6634/MAX6635 continuously convert their die temperatures into digital values using their integrated ADCs. The resulting data is readable at any time through the SMBus $/{ }^{2} \mathrm{C}$-compatible serial interface. The device functions as a slave on the SMBus interface, supporting Write Byte, Write Word, Read Byte, and Read Word commands. Separate addresses can be configured using the individual address pins. Figures 5, 6, and 7 show the functional diagrams of the MAX6633/MAX6634/MAX6635, respectively.

## SMBus/I $\mathbf{2}^{C}$ C-Compatible Operation

The MAX6633/MAX6634/MAX6635 are readable and programmable through their SMBus $/ I^{2} \mathrm{C}$-compatible serial interface. Figures 1, 2, and 3 show the timing details of the clock (SCL) and data (SDA) signals. The devices function as slaves on the SMBus and support Write Byte, Write Word, Read Byte, and Read Word commands. Figure 8 is the MAX6633/MAX6634/ MAX6635 programmer's model.


#### Abstract

Addressing Separate addresses can be configured using the individual address pins. The address of each device is selected by connecting the address (A_) pins to one of two potentials: GND or Vcc. The MAX6635 makes two address pins available (A0, A1), allowing up to four devices to be connected to a single bus line. The MAX6634 makes three address pins available (A0, A1, A2), allowing up to eight devices to be connected to a single bus line. The MAX6633 makes four address pins available (A0, A1, A2, A3), allowing as many as 16


devices to be connected to a single bus line. Table 1 shows the full SMBus $/{ }^{2} \mathrm{C}$ address for each device type.

Control Registers (MAX6633)
Three registers control the operation of the MAX6633 (Figure 5 and Tables 2 through 6). The Pointer register is the first addressed and determines which of the other two registers is acted upon. The other two are the Temperature and Configuration registers. The temperature value is stored as 12 bits plus a sign bit, read only, and contains the latest temperature data. The true register length is 16 bits, with the lower 3 unused in this part. The digital temperature data contained in the temperature register is in ${ }^{\circ} \mathrm{C}$, using a two's-complement format with 1 LSB corresponding to $0.0625^{\circ} \mathrm{C}$.
The Configuration register is 8 bits, read/write, and contains the SMBus timeout disable bit, fault queue enable bit, and the shutdown bit.

Control Registers (MAX6634)
Six registers control the operation of the MAX6634 (Figure 6 and Tables 2 through 7). The pointer register is the first addressed and determines which of the other five registers is acted upon. The other five are the Temperature, Configuration, High-Temperature (Thigh), Low-Temperature (TLow), and Hysteresis (THYST) registers. The temperature value is stored as 12 bits plus a sign bit, read only, and contains the latest temperature data. The true register length is 16 bits, with the lowest 2 used as status bits, and the third bit (D2) is unused. The digital temperature data contained in the temperature register is in ${ }^{\circ} \mathrm{C}$, using a two's-complement format with 1 LSB corresponding to $0.0625^{\circ} \mathrm{C}$.

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Write Byte Format

| S | ADDRESS | WR | ACK | COMMAND | ACK | DATA | ACK | P |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 7 bits |  |  | 8 bits |  | 8 bits |  |  |
|  | Slave Address: <br> equivalent <br> to chip-select line of a 3- <br> wire interface |  | Command Byte: selects <br> register you are writing to | Data Byte: data goes into the register set by the <br> command byte |  |  |  |  |

Write Word Format

| $\mathbf{S}$ | ADDRESS | WR | ACK | COMMAND | ACK | DATA | ACK | DATA | ACK | P |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 7 bits |  | 8 bits |  | 8 bits <br> $(M S B)$ | 8 bits <br> $(L S B)$ |  |  |  |  |
|  | Slave Address: <br> equivalent to chip-select <br> line of a <br> 3-wire interface |  | Command Byte: <br> selects register you <br> are writing to | Data Bytes: data goes into the <br> register set by the command <br> byte |  |  |  |  |  |  |

## Read Byte Format

| S | ADDRESS | WR | ACK | COMMAND | ACK | S | ADDRESS | RD | ACK | DATA | III |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 7 bits |  |  | 8 bits |  |  | 7 bits |  |  | 8 bits |  |
|  | Slave Address: equivalent <br> to chip-select line | Command Byte: <br> selects register you <br> are reading from |  | Slave Address: repeated due to <br> change in data-flow direction | Data Byte: reads from the <br> register set by the command <br> byte |  |  |  |  |  |  |

Read Word Format

| S | ADDRESS | WR | ACK | COMMAND | ACK | S | ADDRESS | RD | ACK | DATA | ACK | DATA | III | P |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 7 bits | 8 bits |  | 7 bits |  | 8 bits <br> (MSB) | 8 bits <br> (LSB) |  |  |  |  |  |  |  |
|  | Slave Address: <br> equivalent to chip- <br> select line |  | Command Byte: <br> selects register you <br> are reading from |  | Slave Address: repeated <br> due to change in data-flow <br> direction | Data Bytes: reads from the <br> register set by the command <br> byte |  |  |  |  |  |  |  |  |

$$
\begin{array}{ll}
S=\text { Start condition } & \text { Shaded }=\text { Slave transmission } \\
P=\text { Stop condition } & / / /=\text { Not acknowledged }
\end{array}
$$

Figure 1. SMBus Protocols


Figure 2. SMBus Write Timing Diagram

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Figure 3. SMBus Read Timing Diagram


Figure 4. ADC Conversion Timing Diagram

The Configuration register is 8 bits, read/write, and contains the SMBus timeout disable bit, fault queue enable bit, the temperature alarm output polarity select bits, the interrupt mode select bit, and the shutdown bit. Registers THIGH and TLOW are 16 bits, read/write, and contain the values that trigger ALERT. Register THYST is 16 bits, read/write, and contains the values by which the temperature must rise or fall beyond THIGH or TLOW, before ALERT deasserts.

## Control Registers (MAX6635)

Seven registers control the operation of the MAX6635 (Figure 7 and Tables 2 through 7). The Pointer register is the first addressed and determines which of the other six registers is acted upon. The other six are the Temperature, Configuration, High-Temperature (THIGH), Low-Temperature (TLOW), Maximum Temperature (TMAX), and Hysteresis (THYST) registers. The temperature value is stored as 12 bits plus a sign bit, read only, and contains the latest temperature data. The true register length is 16 bits, with the lower three used as status bits. The digital temperature data contained in the temperature register is in ${ }^{\circ} \mathrm{C}$, using a two's-complement format with 1LSB corresponding to $0.0625^{\circ} \mathrm{C}$.
The Configuration register is 8 bits, read/write, and contains the SMBus timeout disable bit, fault queue enable bit, the temperature alarm output polarity select bits, the interrupt mode select bit, and the shutdown


Figure 5. MAX6633 Functional Diagram

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MAX6633/MAX6634/MAX6635


Figure 6. MAX6634 Functional Diagram


Figure 7. MAX6635 Functional Diagram

## 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface



Figure 8. MAX6633/MAX6634/MAX6635 Programmer's Model

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Figure 9. Alarm Output and Reset Diagram
bit. Registers THIGH and TLOW are 16 bits, read/write, and contain values that trigger ALERT and OVERT. Register THYST is 16 bits, read/write, and contains the values by which the temperature must rise or fall beyond THIGH, TLOW, or TMAX, before $\overline{\text { ALERT or }}$ OVERT deassert.

Temperature Conversion
An on-chip bandgap reference produces a signal proportional to absolute temperature (PTAT), as well as the temperature-stable reference voltage necessary for the analog-to-digital conversion. The PTAT signal is digitized by the on-board ADC to a resolution of $0.0625^{\circ} \mathrm{C}$. The resulting digital value is placed in the Temperature register. The temperature conversion runs continuously and asynchronously from the serial interface at a rate of 500ms per conversion. When the Temperature register is read, the conversion in progress is aborted. The bus transaction is completed by a stop condition.

Fault Queue (MAX6634/MAX6635)
A programmable fault queue on the MAX6634/ MAX6635 eliminates spurious alarm activity in noisy environments. The queue sets the number of consecutive out-of-tolerance temperature readings that must occur before the ALERT or OVERT alarm outputs are toggled. An out-of-tolerance reading is above THIGH or TMAX or below TLOW. The fault queue depth defaults to 1 at power-up and may be programmed-through the Configuration register-to four consecutive conversions. Any time the conversion result is in tolerance, and the particular alarm output is not asserted, the queue is cleared, even if it contains some out-of-tolerance counts. Additionally, the fault queue automatically clears at power-up and in shutdown. Whenever the fault queue is cleared, the alarm outputs are deasserted. Figure 9 is the alarm output and reset diagram.

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Figure 10. Simple Thermostat

## Temperature Alert <br> (MAX6634/MAX6635)

$\overline{\text { ALERT }}$ has programmable polarity and two modes: comparator and interrupt. Polarity and mode are selected through the Configuration register (Table 4). The $\overline{\text { ALERT }}$ output is open drain.

Interrupt Mode
With ALERT in interrupt mode, the MAX6634/MAX6635 look for a THIGH or a TLOW fault. The ALERT pin asserts an alarm for an undertemperature fault, as well as for an overtemperature fault. Once either fault has occurred, it remains active until deasserted by a read of any register. The device then begins to look for a temperature change crossing the hysteresis level. The activation of ALERT is subject to the depth of the fault queue.
For example: If THIGH is set to $100^{\circ} \mathrm{C}$, THYST is set to $20^{\circ} \mathrm{C}$, and the fault queue depth is set to 4 , $\overline{\text { ALERT }}$ does not assert until four consecutive conversions exceed $100^{\circ} \mathrm{C}$. If the temperature is then read through the $\mathrm{I}^{2} \mathrm{C}$-compatible interface, $\overline{\mathrm{ALERT}}$ deasserts. $\overline{\mathrm{ALERT}}$ asserts again when four consecutive conversions are less than $80^{\circ} \mathrm{C}$.

## Comparator Mode

In comparator mode, $\overline{\text { ALERT }}$ is asserted when the number of consecutive conversions exceeding the value in the THIGH register, or lower than the value in the TLOW register, is equal to the depth of the fault queue. ALERT deasserts when the number of consecutive conversions


Figure 11. Fan Controller
less than Thigh - Thyst or greater than Tlow + THYST is equal to the depth of the fault queue.
For example: If THIGH is set to $100^{\circ} \mathrm{C}$, TLOW is set to $80^{\circ} \mathrm{C}$, and the fault queue depth is set to four, ALERT does not assert until four consecutive conversions exceed $100^{\circ} \mathrm{C}$, or are below $80^{\circ} \mathrm{C}$. ALERT only deasserts if four consecutive conversions are less than THIGH - THYST or greater than TLOW + THYST.
Comparator mode allows autonomous clearing of an ALERT fault without the intervention of a master and is ideal to use for driving a thermostat (Figure 10).

## Overtemperature Alarm (MAX6635)

The MAX6635 also includes an overtemperature output that is always in comparator mode. Whenever the temperature exceeds a value in the programmable TMAX register, OVERT is asserted. OVERT only deasserts after the temperature drops below TMAX - THYST. When the fault queue is activated, OVERT is subject to that queue, which sets the number of faults that must occur before OVERT asserts or deasserts. This helps prevent spurious alarms in noisy environments.
Comparator mode also allows autonomous clearing of an OVERT fault without the intervention of a master and thus is ideal to use for driving a cooling fan (Figure 11). In this application, the polarity of OVERT is active high.

## Shutdown

The MAX6633/MAX6634/MAX6635 feature a shutdown mode, accessible through the serial interface that saves power by turning off everything except the POR

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and the serial interface. Enter shutdown by programming the shutdown bit of the Configuration register high. While in shutdown, the Temperature register retains the last conversion result and can be read at any time. The ADC is turned off, reducing the device current draw to $30 \mu \mathrm{~A}$ (max). The outputs of ALERT and OVERT are latched upon entering shutdown, and the fault queue is held in reset. After coming out of shutdown, the Temperature register continues to read the last converted temperature, until the next conversion result is available.

Thermal Considerations
The MAX6633/MAX6634/MAX6635 supply current is typically $200 \mu \mathrm{~A}$ when the serial interface is inactive. When used to drive high-impedance loads, the devices dissipate negligible power; therefore, the die temperature is essentially the same as the package temperature. The key to accurate temperature monitoring is good thermal contact between the MAX6633/MAX6634/ MAX6635 package and the monitored device or circuit. Heat flows in and out of plastic packages primarily through the leads. Short, wide copper traces leading to the temperature monitor ensure that heat transfers quickly and reliably. The rise in die temperature due to self-heating is given by the following formula:

$$
\Delta T J=\text { PDISSIPATION } \times \theta J A
$$

where PDISSIPATION is the power dissipated by the MAX6633/MAX6634/MAX6635, and $\theta$ JA is the package's thermal resistance.
The typical thermal resistance is $170^{\circ} \mathrm{C} / \mathrm{W}$ for the 8 -pin SO package. To limit the effects of self-heating, minimize the output currents. For example, if the MAX6634/MAX6635 sink 4 mA with the maximum ALERT VL specification of 0.8 V , an additional 3.2 mW of power is dissipated within the IC. This corresponds to a $0.54^{\circ} \mathrm{C}$ rise in the die temperature.

## Applications Information

Figure 10 shows the MAX6634 used as a simple thermostat to control a heating element. Figure 11 shows the MAX6635 used as a temperature-triggered fan controller.

## Chip Information

TRANSISTOR COUNT: 12,085
PROCESS: BiCMOS PROCESS: BiCMOS

Table 1. Address Selection

| MAX6633 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| A3 | A2 | A1 | A0 | ADDRESS |
| GND | GND | GND | GND | 1000000 |
| GND | GND | GND | VCC | 1000001 |
| GND | GND | $V_{\text {CC }}$ | GND | 1000010 |
| GND | GND | VCC | VCC | 1000011 |
| GND | VCC | GND | GND | 1000100 |
| GND | VCC | GND | VCC | 1000101 |
| GND | VCC | VCC | GND | 1000110 |
| GND | $V_{\text {CC }}$ | $V_{\text {CC }}$ | VCC | 1000111 |
| Vcc | GND | GND | GND | 1001000 |
| VCC | GND | GND | VCC | 1001001 |
| Vcc | GND | VCC | GND | 1001010 |
| Vcc | GND | VCC | VCC | 1001011 |
| VCC | VCC | GND | GND | 1001100 |
| VCC | VCC | GND | VCC | 1001101 |
| Vcc | VCC | Vcc | GND | 1001110 |
| Vcc | VCC | $V_{\text {cC }}$ | VCC | 1001111 |
| MAX6634 |  |  |  |  |
|  | A2 | A1 | A0 | ADDRESS |
|  | GND | GND | GND | 1001000 |
|  | GND | GND | VCC | 1001001 |
|  | GND | VCC | GND | 1001010 |
|  | GND | VCC | VCC | 1001011 |
|  | VCC | GND | GND | 1001100 |
|  | VCC | GND | VCC | 1001101 |
|  | VCC | $V_{C C}$ | GND | 1001110 |
|  | Vcc | $V_{\text {cc }}$ | VCC | 1001111 |
| MAX6635 |  |  |  |  |
|  |  | A1 | A0 | ADDRESS |
|  |  | GND | GND | 1001000 |
|  |  | GND | VCC | 1001001 |
|  |  | VCC | GND | 1001010 |
|  |  | VCC | VCC | 1001011 |

# 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface 

Table 2. Pointer Register Bit
Assignments

| ADDRESS | DESCRIPTION | POR STATE |
| :---: | :---: | :---: |
| 00 h | Temperature register <br> (READ only) | 0000 h |
| 01 h | Configuration-Byte <br> register | 00 h |
| 02 h | THYST register | 0100 h |
| 03 h | TMAX register | 2800 h |
| 04 h | TLOW register | 0500 h |
| 05 h | THIGH register | 2000 h |

Table 3. Temperature Register

| D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MSB <br> (Sign) | Bit <br> 12 | Bit <br> 11 | Bit <br> 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | TMAX | THIGH | TLOW |

D15: MSB is the first sign bit.
D2, D1, D0: Flag bits for TmAX, Thigh, TLOw.
$1 \mathrm{LSB}=0.0625^{\circ} \mathrm{C}$.
Temperature is stored in two's complement format.

## Table 4. Configuration Register

| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | SMB Timeout <br> Disable | Fault Queue <br> Enable | $\overline{\text { ALERT }}$ <br> Polarity | $\overline{\text { OVERT }}$ <br> Polarity | Comparator <br> or Interrupt | Shutdown |

Power-on default $=0$ h.
DO: $0=$ normal operation; $1=$ shutdown.
D1: 0 = comparator mode; 1 = interrupt mode.
D2 to D3: $0=$ active low; 1 = active high.
D5: $0=$ normal SMBus operation; $1=$ full $I^{2} \mathrm{C}$ compatibility.
D7 to D6: Reserved locations, always write zeros.

## 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface

Table 5. Fault Queue Depth

| D4 | NO. OF FAULTS |
| :---: | :---: |
| 0 | 1 (DEFAULT) |
| 1 | 4 |

Table 6. Output Code vs. Temperature

| TEMP. ( ${ }^{\circ} \mathrm{C}$ ) | DIGITAL OUTPUT CODE |  |  |
| :---: | :---: | :---: | :---: |
|  | BINARY |  | HEX |
|  | MSB | LSB |  |
| +150.0000 | 010010110000 0XXX |  | 4B00 |
| +125.0000 | 001111101000 OXXX |  | 3E80 |
| +25.0000 | 000011001000 0XXX |  | 0C80 |
| +0.0625 | 000000000000 1XXX |  | 0008 |
| 0.0000 | 000000000000 0XXX |  | 0000 |
| -0.0625 | 111111111111 1XXX |  | FFF8 |
| -25.0000 | 111100110111 0XXX |  | F370 |
| -55.0000 | 111001000111 OXXX |  | E470 |

Table 7. Thigh, Tlow, Tmax, and Thyst Registers

| D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MSB <br> (Sign) | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | LSB | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

D6 to D0: Reads all zeros, cannot be written.
$1 \mathrm{LSB}=1^{\circ} \mathrm{C}$.
Power-On Default: $\mathrm{THIGH}=+64^{\circ} \mathrm{C}(2000 \mathrm{~h})$, TLOW $=+10^{\circ} \mathrm{C}(0500 \mathrm{~h})$, TMAX $=+80^{\circ} \mathrm{C}(2008 \mathrm{~h})$, THYST $=2^{\circ} \mathrm{C}(0100 \mathrm{~h})$.
$\qquad$

## 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface

Pin Configurations


# 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface 



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