

HEF4094B

8-stage shift-and-store register

Rev. 08 — 2 April 2010

Product data sheet

1. General description

The HEF4094B is an 8-stage serial shift register. It has a storage latch associated with each stage for strobing data from the serial input to parallel buffered 3-state outputs QP0 to QP7. The parallel outputs may be connected directly to common bus lines. Data is shifted on positive-going clock transitions. The data in each shift register stage is transferred to the storage register when the strobe (STR) input is HIGH. Data in the storage register appears at the outputs whenever the output enable (OE) signal is HIGH.

Two serial outputs (QS1 and QS2) are available for cascading a number of HEF4094B devices. Serial data is available at QS1 on positive-going clock edges to allow high-speed operation in cascaded systems with a fast clock rise time. The same serial data is available at QS2 on the next negative going clock edge. This is used for cascading HEF4094B devices when the clock has a slow rise time.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input. It is also suitable for use over the industrial ($-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$) and automotive ($-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$) temperature ranges.

2. Features and benefits

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Operates across the automotive temperature range $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$
- Complies with JEDEC standard JESD 13-B

3. Ordering information

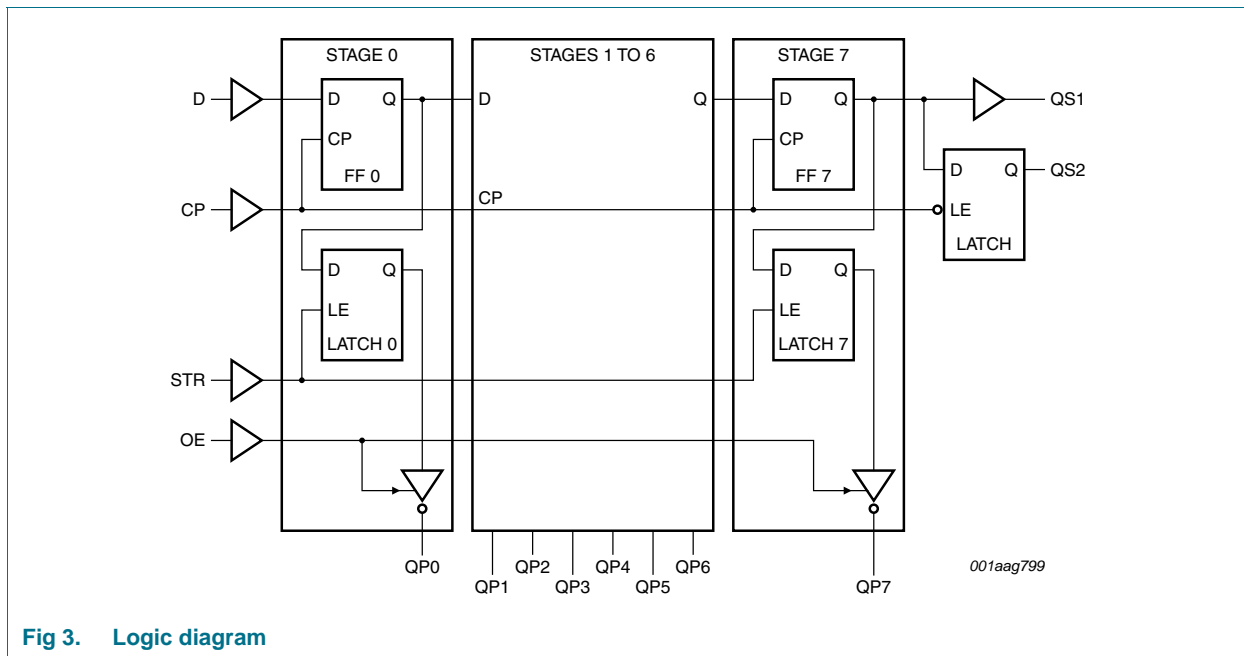
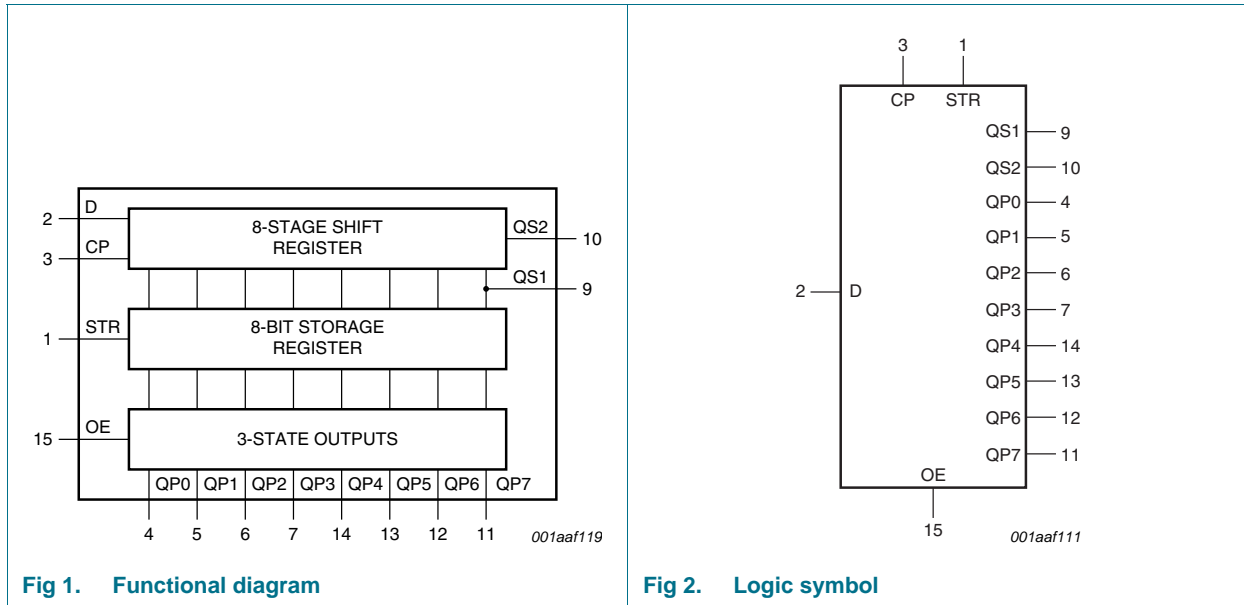
Table 1. Ordering information

All types operate from $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$.

| Type number | Package | | Version |
|-------------|---------|---|----------|
| | Name | Description | |
| HEF4094BP | DIP16 | plastic dual in-line package; 16 leads (300 mil) | SOT38-4 |
| HEF4094BT | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |
| HEF4094BTS | SSOP16 | plastic shrink small outline package; 16 leads; body width 5.3 mm | SOT338-1 |

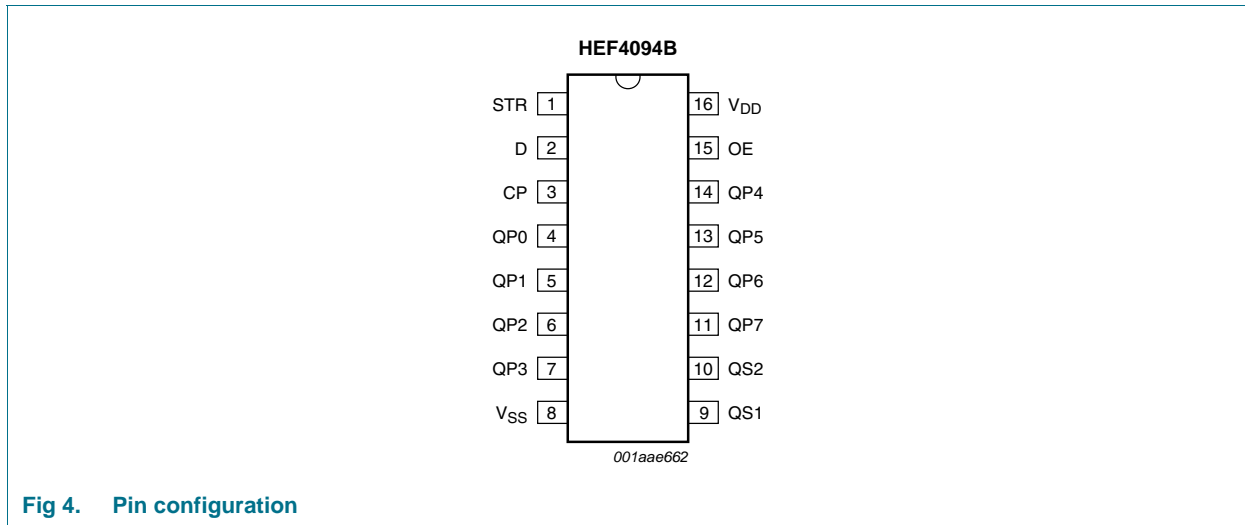


4. Functional diagram



5. Pinning information

5.1 Pinning



5.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|----------------------------|-----------------------|
| STR | 1 | strobe input |
| D | 2 | data input |
| CP | 3 | clock input |
| QP0 to QP7 | 4, 5, 6, 7, 14, 13, 12, 11 | parallel output |
| V _{SS} | 8 | ground supply voltage |
| QS1 | 9 | serial output |
| QS2 | 10 | serial output |
| OE | 15 | output enable input |
| V _{DD} | 16 | supply voltage |

6. Functional description

Table 3. Function table^[1]

| Inputs | | | | Parallel outputs | | Serial outputs | |
|--------|----|-----|---|------------------|--------|----------------|-----|
| CP | OE | STR | D | QP0 | QPn | QS1 | QS2 |
| ↑ | L | X | X | Z | Z | Q6S | NC |
| ↓ | L | X | X | Z | Z | NC | Q7S |
| ↑ | H | L | X | NC | NC | Q6S | NC |
| ↑ | H | H | L | L | QPn -1 | Q6S | NC |
| ↑ | H | H | H | H | QPn -1 | Q6S | NC |
| ↓ | H | H | H | NC | NC | NC | Q7S |

- [1] At the positive clock edge, the information in the 7th register stage is transferred to the 8th register stage and the QSn outputs.
 H = HIGH voltage level; L = LOW voltage level; X = don't care;
 ↑ = positive-going transition; ↓ = negative-going transition;
 Z = HIGH-impedance OFF-state; NC = no change;
 Q6S = the data in register stage 6 before the LOW to HIGH clock transition;
 Q7S = the data in register stage 7 before the HIGH to LOW clock transition.

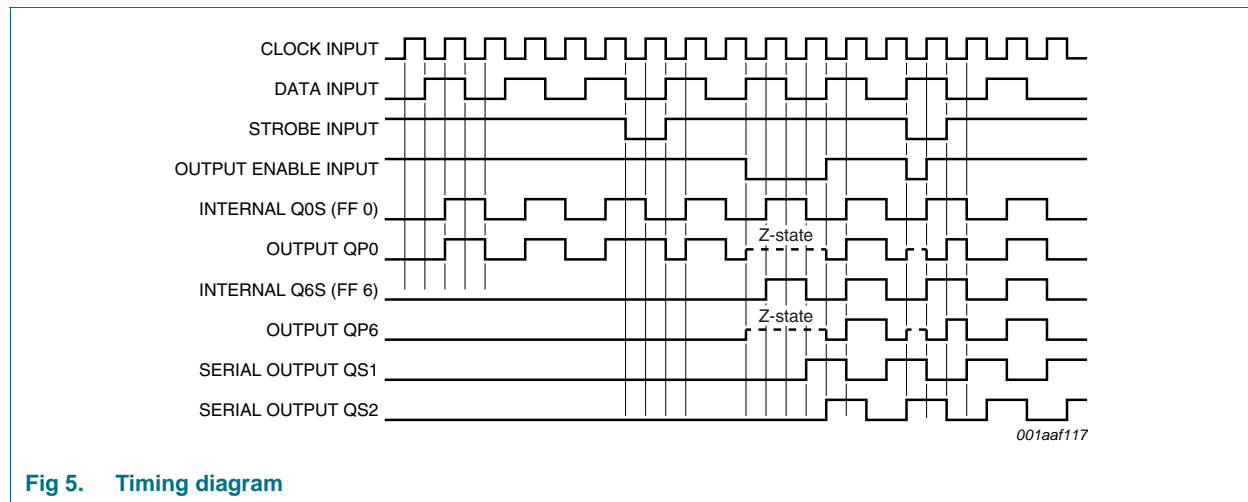


Fig 5. Timing diagram

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to $V_{SS} = 0$ V (ground).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|-------------------------|--|-------|----------------|------|
| V_{DD} | supply voltage | | -0.5 | +18 | V |
| I_{IK} | input clamping current | $V_I < -0.5$ V or $V_I > V_{DD} + 0.5$ V | - | ± 10 | mA |
| V_I | input voltage | | -0.5 | $V_{DD} + 0.5$ | V |
| I_{OK} | output clamping current | $V_O < -0.5$ V or $V_O > V_{DD} + 0.5$ V | - | ± 10 | mA |
| $I_{I/O}$ | input/output current | | - | ± 10 | mA |
| I_{DD} | supply current | | - | 50 | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| T_{amb} | ambient temperature | | -40 | +125 | °C |
| P_{tot} | total power dissipation | DIP16 | [1] - | 750 | mW |
| | | SO16 | [2] - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

[1] For DIP16 packages: above $T_{amb} = 70$ °C, P_{tot} derates linearly with 12 mW/K.

[2] For SO16 packages: above $T_{amb} = 70$ °C, P_{tot} derates linearly with 8 mW/K.

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|-----------------|-----|-----|----------|-----------------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +125 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5$ V | - | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10$ V | - | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15$ V | - | - | 0.08 | $\mu\text{s/V}$ |

9. Static characteristics

Table 6. Static characteristics
 $V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} ; unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ }^{\circ}\text{C}$ | | $T_{amb} = +25\text{ }^{\circ}\text{C}$ | | $T_{amb} = +85\text{ }^{\circ}\text{C}$ | | $T_{amb} = +125\text{ }^{\circ}\text{C}$ | | Unit |
|----------|---------------------------|---|----------|---|-----------|---|-----------|---|-----------|--|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | -1.7 | - | -1.4 | - | -1.1 | - | -1.1 | - | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | -0.64 | - | -0.5 | - | -0.36 | - | -0.36 | - | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | -1.6 | - | -1.3 | - | -0.9 | - | -0.9 | - | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | -4.2 | - | -3.4 | - | -2.4 | - | -2.4 | - | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.64 | - | 0.5 | - | 0.36 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.6 | - | 1.3 | - | 0.9 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 4.2 | - | 3.4 | - | 2.4 | - | 2.4 | - | mA |
| I_{OZ} | OFF-state output current | QPn output is HIGH; $V_O = 15\text{ V}$ | 15 V | - | 0.4 | - | 0.4 | - | 12 | - | 12 | μA |
| I_I | input leakage current | | 15 V | - | ± 0.1 | - | ± 0.1 | - | ± 1.0 | - | ± 1.0 | μA |
| I_{DD} | supply current | all valid input combinations; $I_O = 0\text{ A}$ | 5 V | - | 5 | - | 5 | - | 150 | - | 150 | μA |
| | | | 10 V | - | 10 | - | 10 | - | 300 | - | 300 | μA |
| | | | 15 V | - | 20 | - | 20 | - | 600 | - | 600 | μA |
| C_I | input capacitance | | | - | - | - | 7.5 | - | - | - | pF | |

10. Dynamic characteristics

Table 7. Dynamic characteristics

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ °C}$; for test circuit see [Figure 10](#); unless otherwise specified.

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula | Min | Typ | Max | Unit |
|------------------|-------------------------------------|---|-----------------|--|-----|-----|-----|------|
| t _{PHL} | HIGH to LOW propagation delay | CP to QS1; see Figure 6 | 5 V | [1] 108 ns + (0.55 ns/pF) C _L | - | 135 | 270 | ns |
| | | | 10 V | 54 ns + (0.23 ns/pF) C _L | - | 65 | 130 | ns |
| | | | 15 V | 42 ns + (0.16 ns/pF) C _L | - | 50 | 100 | ns |
| | | CP to QS2; see Figure 6 | 5 V | 78 ns + (0.55 ns/pF) C _L | - | 105 | 210 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF) C _L | - | 50 | 100 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF) C _L | - | 40 | 80 | ns |
| | | CP to QPn; see Figure 6 | 5 V | 138 ns + (0.55 ns/pF) C _L | - | 165 | 330 | ns |
| | | | 10 V | 64 ns + (0.23 ns/pF) C _L | - | 75 | 150 | ns |
| | | | 15 V | 47 ns + (0.16 ns/pF) C _L | - | 55 | 110 | ns |
| | | STR to QPn; see Figure 7 | 5 V | 83 ns + (0.55 ns/pF) C _L | - | 110 | 220 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF) C _L | - | 50 | 100 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF) C _L | - | 35 | 70 | ns |
| t _{PLH} | LOW to HIGH propagation delay, | CP to QS1; see Figure 6 | 5 V | [1] 78 ns + (0.55 ns/pF) C _L | - | 105 | 210 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF) C _L | - | 50 | 100 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF) C _L | - | 40 | 80 | ns |
| | | CP to QS2; see Figure 6 | 5 V | 78 ns + (0.55 ns/pF) C _L | - | 105 | 210 | ns |
| | | | 10 V | 39 ns + (0.23 ns/pF) C _L | - | 50 | 100 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF) C _L | - | 40 | 80 | ns |
| | | CP to QPn; see Figure 6 | 5 V | 123 ns + (0.55 ns/pF) C _L | - | 150 | 300 | ns |
| | | | 10 V | 59 ns + (0.23 ns/pF) C _L | - | 70 | 140 | ns |
| | | | 15 V | 47 ns + (0.16 ns/pF) C _L | - | 55 | 110 | ns |
| | | STR to QPn; see Figure 7 | 5 V | 73 ns + (0.55 ns/pF) C _L | - | 100 | 200 | ns |
| | | | 10 V | 34 ns + (0.23 ns/pF) C _L | - | 45 | 90 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF) C _L | - | 35 | 70 | ns |
| t _t | transition time | | 5 V | [1] 10 ns + (1.00 ns/pF) C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF) C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF) C _L | - | 20 | 40 | ns |
| t _{PZH} | OFF-state to HIGH propagation delay | OE to QPn; see Figure 8 | 5 V | | - | 40 | 80 | ns |
| | | | 10 V | | - | 25 | 50 | ns |
| | | | 15 V | | - | 20 | 40 | ns |
| t _{PZL} | OFF-state to LOW propagation delay | OE to QPn; see Figure 8 | 5 V | | - | 40 | 80 | ns |
| | | | 10 V | | - | 25 | 50 | ns |
| | | | 15 V | | - | 20 | 40 | ns |
| t _{PHZ} | HIGH to OFF-state propagation delay | OE to QPn; see Figure 8 | 5 V | | - | 75 | 150 | ns |
| | | | 10 V | | - | 40 | 80 | ns |
| | | | 15 V | | - | 30 | 60 | ns |

Table 7. Dynamic characteristics ...continued

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ °C}$; for test circuit see [Figure 10](#); unless otherwise specified.

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula | Min | Typ | Max | Unit |
|------------------|------------------------------------|---|-----------------|-----------------------|-----|-----|-----|------|
| t _{PLZ} | LOW to OFF-state propagation delay | OE to QPn; see Figure 8 | 5 V | | - | 80 | 160 | ns |
| | | | 10 V | | - | 40 | 80 | ns |
| | | | 15 V | | - | 30 | 60 | ns |
| t _{su} | set-up time | D to CP; see Figure 9 | 5 V | | 60 | 30 | - | ns |
| | | | 10 V | | 20 | 10 | - | ns |
| | | | 15 V | | 15 | 5 | - | ns |
| t _h | hold time | D to CP; see Figure 9 | 5 V | | +5 | -15 | - | ns |
| | | | 10 V | | 20 | 5 | - | ns |
| | | | 15 V | | 20 | 5 | - | ns |
| t _w | pulse width | minimum LOW clock pulse; see Figure 6 | 5 V | | 60 | 30 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 24 | 12 | - | ns |
| | | minimum HIGH strobe pulse; see Figure 7 | 5 V | | 40 | 20 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 24 | 12 | - | ns |
| f _{max} | maximum frequency | see Figure 6 | 5 V | | 5 | 10 | - | MHz |
| | | | 10 V | | 11 | 22 | - | MHz |
| | | | 15 V | | 14 | 28 | - | MHz |

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation

$V_{SS} = 0\text{ V}$; $t_r = t_f \leq 20\text{ ns}$; $T_{amb} = 25\text{ °C}$.

| Symbol | Parameter | V _{DD} | Typical formula for P _D (μW) | where: |
|----------------|---------------------------|-----------------|---|--|
| P _D | dynamic power dissipation | 5 V | $P_D = 2100 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f _i = input frequency in MHz, |
| | | 10 V | $P_D = 9700 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f _o = output frequency in MHz, |
| | | 15 V | $P_D = 26000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | C _L = output load capacitance in pF, V _{DD} = supply voltage in V, Σ(f _o × C _L) = sum of the outputs. |

11. Waveforms

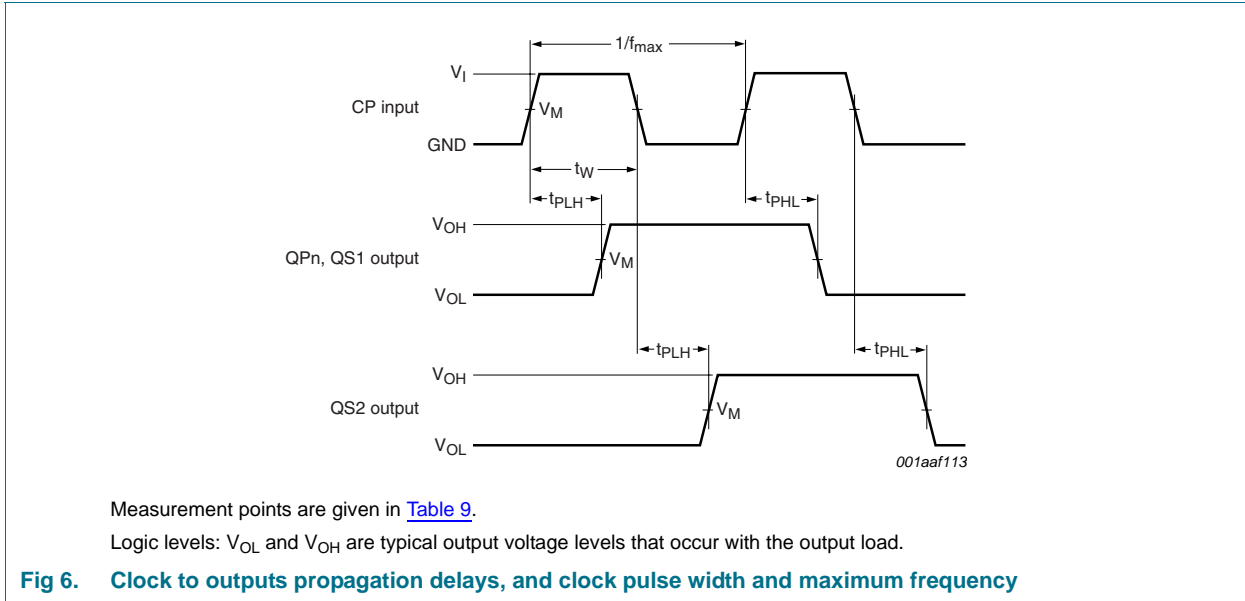
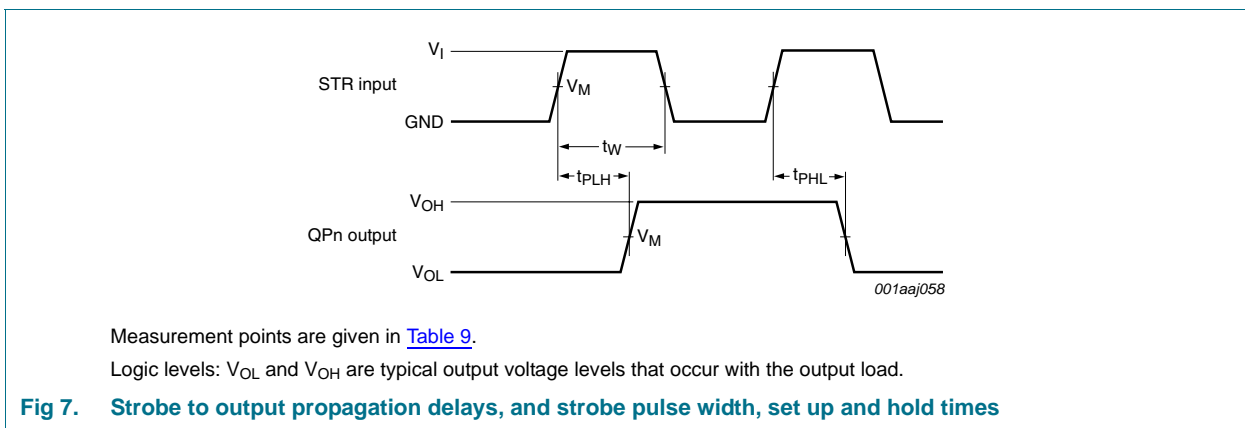
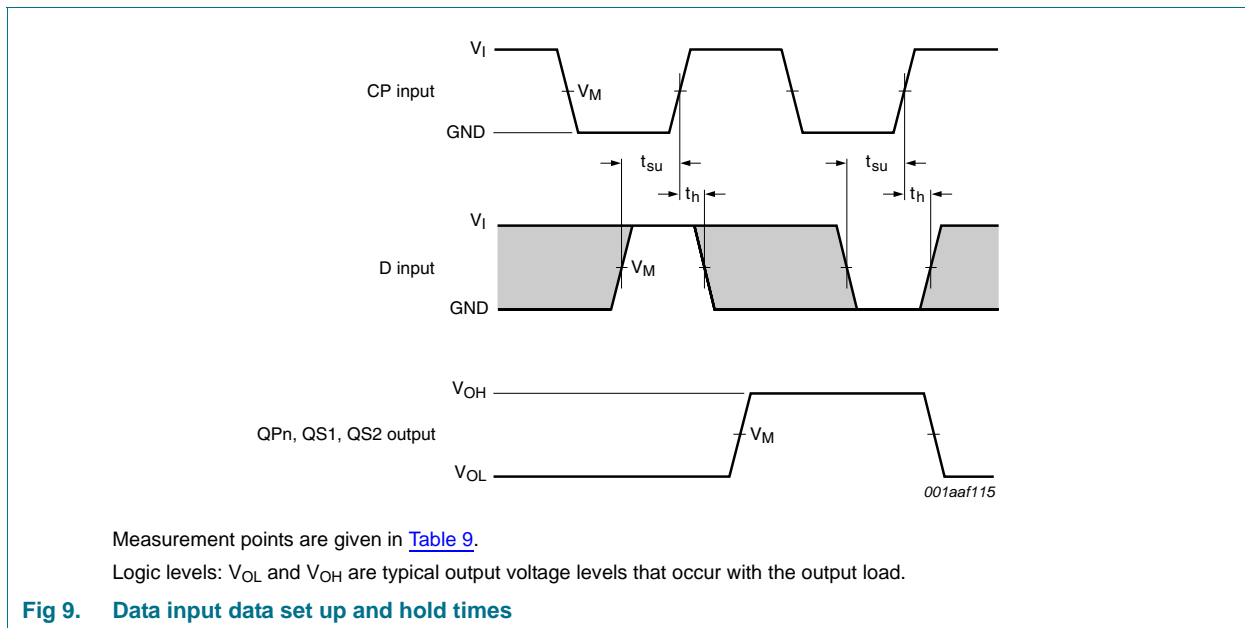
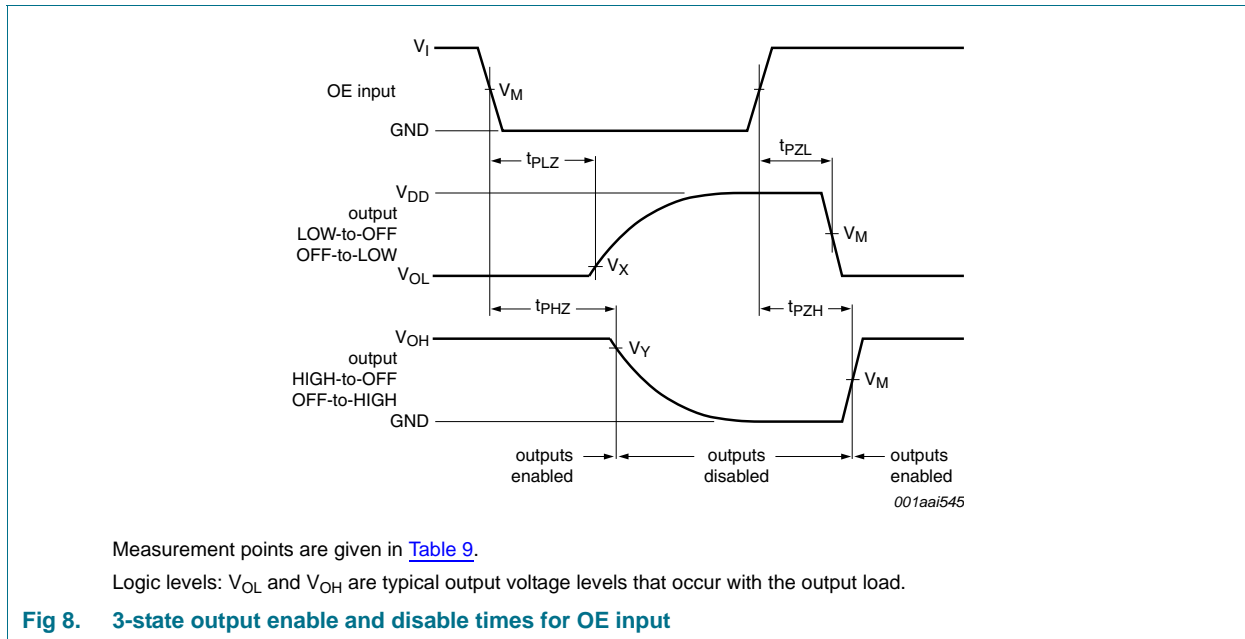


Table 9. Measurement points

| Supply voltage | Input | Output | | |
|----------------|-------------|-------------|-------------|-------------|
| V_{DD} | V_M | V_M | V_X | V_Y |
| 5 V to 15 V | $0.5V_{DD}$ | $0.5V_{DD}$ | $0.1V_{DD}$ | $0.9V_{DD}$ |





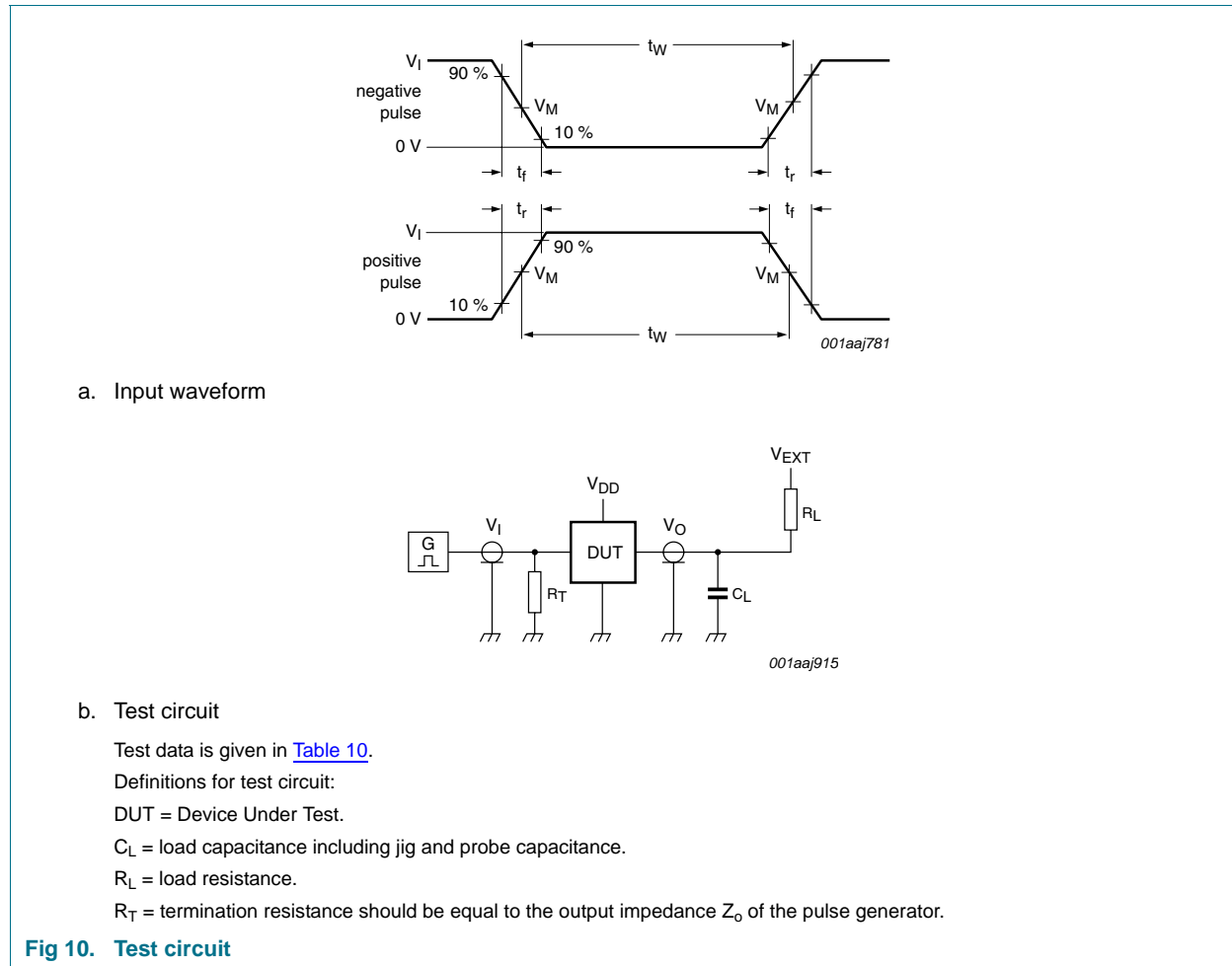


Fig 10. Test circuit

Table 10. Test data

| Supply voltage | Input | | V_{EXT} | | | Load | |
|----------------|----------------------|--------------|--------------------|--------------------|--------------------|-------|--------------|
| V_{DD} | V_I | t_r, t_f | t_{PHL}, t_{PLH} | t_{PHZ}, t_{PZH} | t_{PLZ}, t_{PZL} | C_L | R_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns | open | V_{SS} | V_{DD} | 50 pF | 1 k Ω |

12. Application information

Some examples of applications for the HEF4094B are:

- Serial-to-parallel data conversion
- Remote control holding register

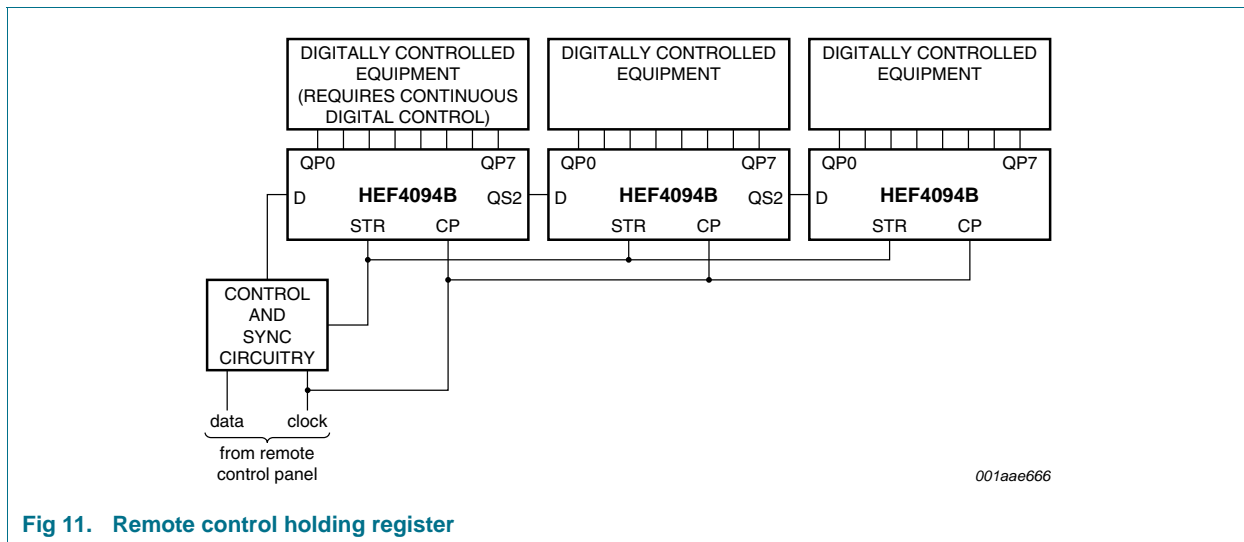


Fig 11. Remote control holding register

13. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4

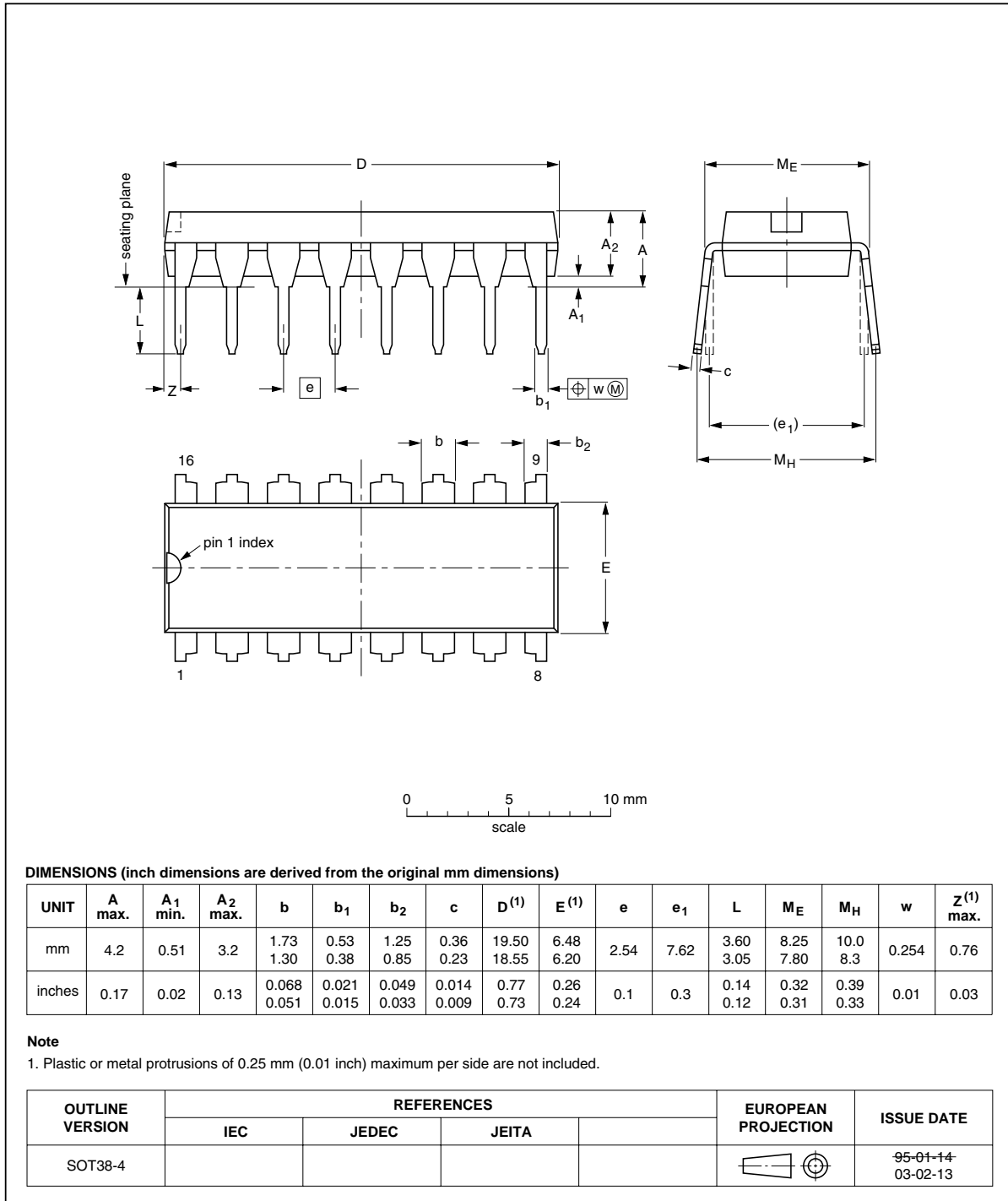


Fig 12. Package outline SOT38-4 (DIP16)

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

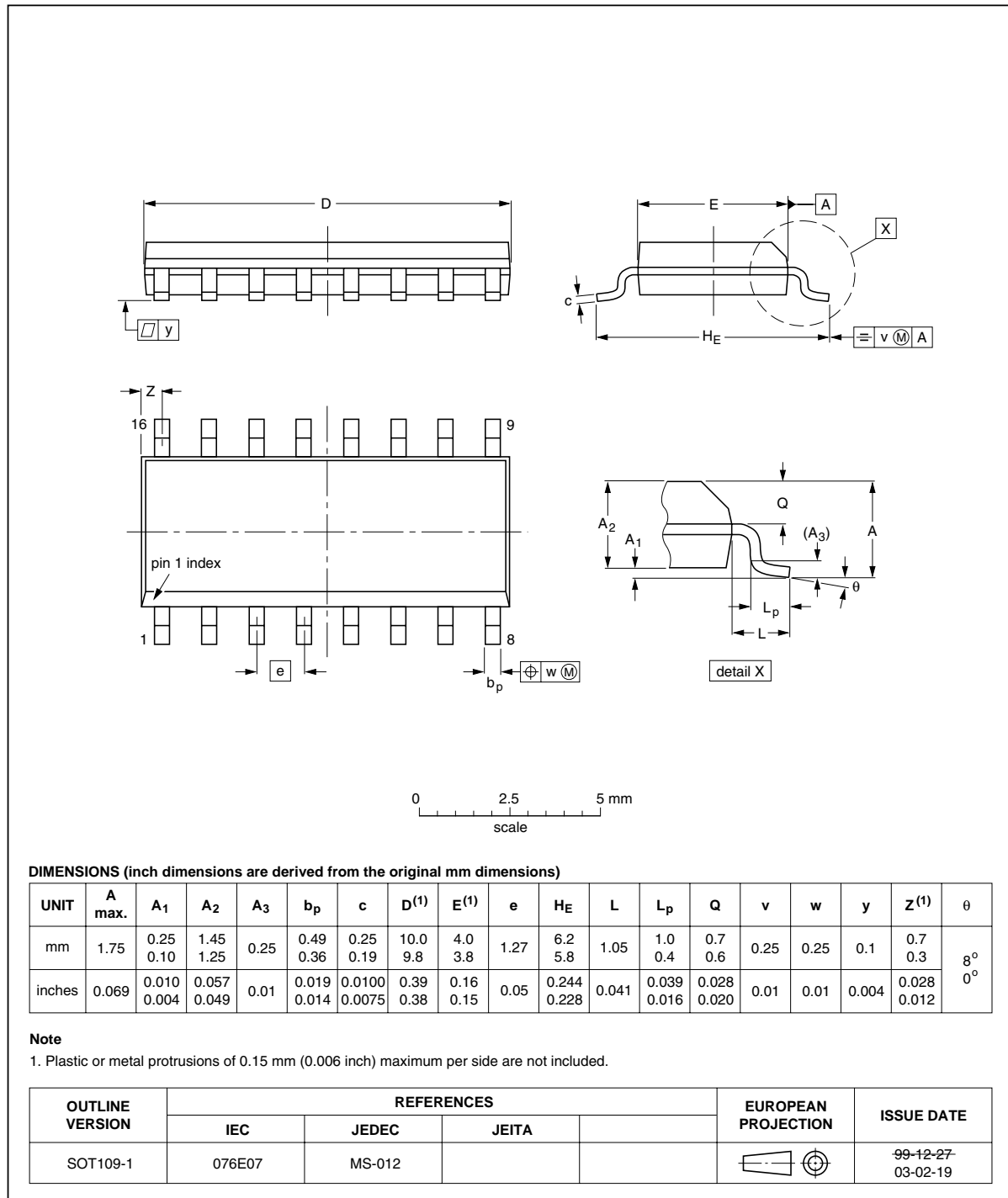


Fig 13. Package outline SOT109-1 (SO16)

SSOP16: plastic shrink small outline package; 16 leads; body width 5.3 mm

SOT338-1

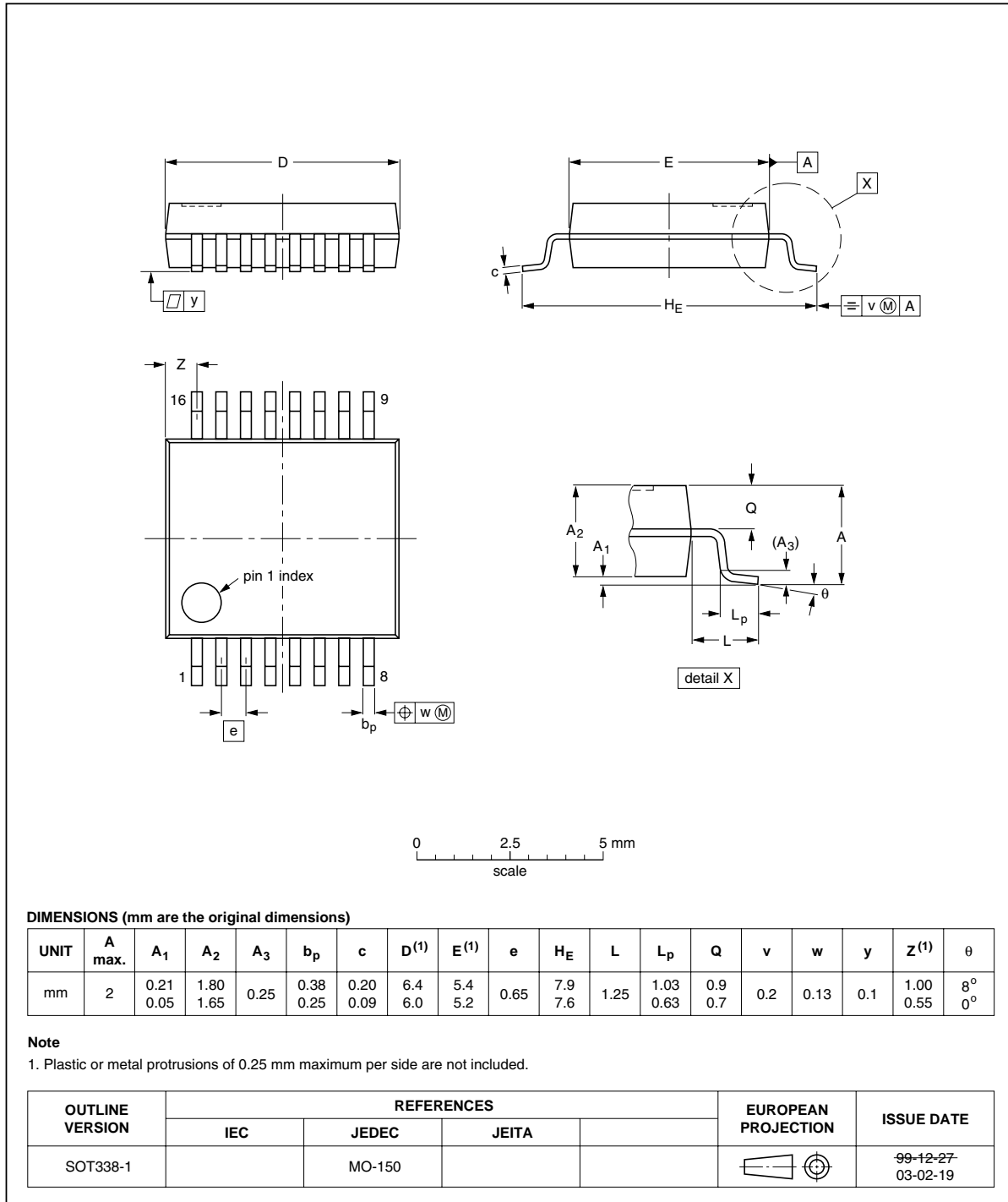


Fig 14. Package outline SOT338-1 (SSOP16)

14. Revision history

Table 11. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|----------------|--|-----------------------|---------------|----------------|
| HEF4094B_8 | 20100402 | Product data sheet | - | HEF4094B_7 |
| Modifications: | <ul style="list-style-type: none"> • Section 4 "Functional diagram" Logic diagram corrected. | | | |
| HEF4094B_7 | 20091216 | Product data sheet | - | HEF4094B_6 |
| Modifications: | <ul style="list-style-type: none"> • Section 11 "Waveforms" Figure 10 "Test circuit": updated. • Section 11 "Waveforms" Table 10 "Test data" t_{PHZ} and t_{PZH} and t_{PLZ} and t_{PZL} values updated. | | | |
| HEF4094B_6 | 20091103 | Product data sheet | - | HEF4094B_5 |
| HEF4094B_5 | 20090728 | Product data sheet | - | HEF4094B_4 |
| HEF4094B_4 | 20081030 | Product data sheet | - | HEF4094B_CNV_3 |
| HEF4094B_CNV_3 | 19950101 | Product specification | - | HEF4094B_CNV_2 |
| HEF4094B_CNV_2 | 19950101 | Product specification | - | - |

15. Legal information

15.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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