

# PRELIMINARY TECHNICAL DATA



## Quad +15V 256-Step DigiPOTs with Pin Selectable SPI / I<sup>2</sup>C Digital Interface

### Preliminary Technical Data

# AD5263

#### FEATURES

- 256 Position
- 4-Channel (Independently Programmable)
- 20k, 50k, 200k Ohms
- Low Temperature Coefficient 50ppm/°C
- Selectable Digital Interface (3-Wire SPI Compatible or 2-Wire I<sup>2</sup>C Compatible Serial Data Input)
- Operating temperature range -40 to 125°C
- +5 to +15V Single-Supply; ±5V Dual-Supply Operation

#### APPLICATIONS

- Mechanical Potentiometer Replacement
- Optical Network Laser LED Adjust
- Instrumentation: Gain, Offset Adjustment
- Stereo Channel Audio Level Control
- Automotive Electronics Adjustment
- Programmable Voltage to Current Conversion
- Programmable Filters, Delays, Time Constants
- Line Impedance Matching
- Low Resolution DAC Replacement

#### GENERAL DESCRIPTION

The AD5263 is the industry first quad channel, 256 position, digital potentiometer<sup>1</sup> selectable digital interface. These devices perform the same electronic adjustment function as mechanical potentiometers or variable resistor with enhanced resolution, solid-state reliability, and superior low temperature coefficient performance. Each Channel of the AD5263 contains a fixed resistor with a wiper contact that taps the fixed resistor value at a point determined by a digital code loaded into the 3 wire SPI or 2-wire I<sup>2</sup>C compatible serial-input register. The resistance between the wiper and either end point of the fixed resistor varies linearly with respect to the digital code transferred into the RDAC latch<sup>1</sup>. The variable resistor offers a completely programmable value of resistance, between the A terminal and the wiper or the B terminal and the wiper. The fixed A to B terminal resistance of 20k, 50k or 200kΩ has a nominal temperature coefficient of 50 ppm/°C. Unlike majority of the digital potentiometers in the market, these devices can operate up to 15V or ±5V provided proper supply voltages are furnished.

The AD5263 are available in thin narrow body TSSOP-24. All parts are guaranteed to operate over the extended automotive temperature range of -40°C to +125°C.

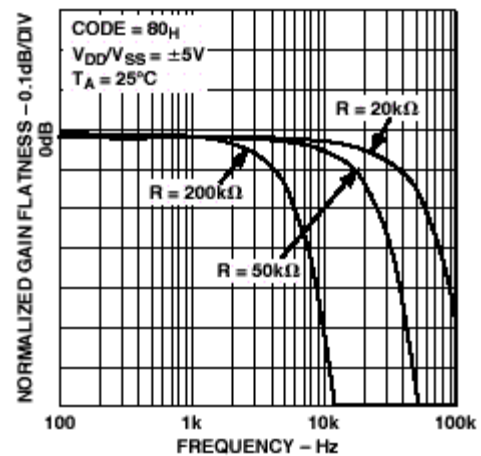
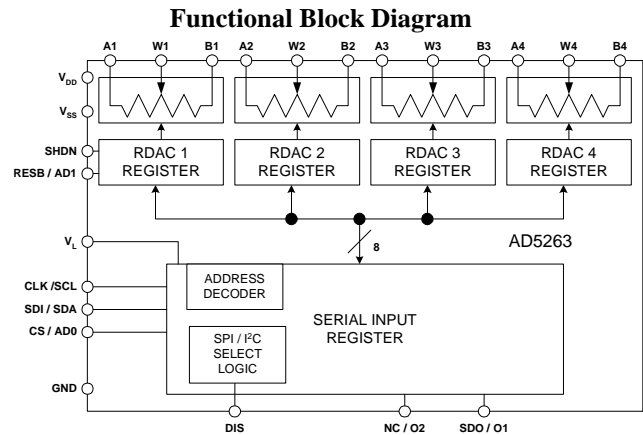


Figure 1 Normalized Gain Flatness Versus Frequency.

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### ELECTRICAL CHARACTERISTICS 20K, 50K, 200K OHM VERSION ( $V_{DD} = +5V$ , $V_{SS} = -5V$ , $V_L = +5V$ ,

$V_A = +V_{DD}$ ,  $V_B = 0V$ ,  $-40^\circ C < T_A < +125^\circ C$  unless otherwise noted.)

Parameter	Symbol	Conditions	Min	Typ <sup>1</sup>	Max	Units
DC CHARACTERISTICS RHEOSTAT MODE Specifications apply to all VRs						
Resistor Differential NL <sup>2</sup>	R-DNL	$R_{WB}$ , $V_A=NC$	-1	$\pm 1/4$	+1	LSB
Resistor Nonlinearity <sup>2</sup>	R-INL	$R_{WB}$ , $V_A=NC$	-2	$\pm 1/2$	+2	LSB
Nominal resistor tolerance <sup>3</sup>	$\Delta R_{AB}$	$T_A = 25^\circ C$	-30		30	%
Resistance Temperature Coefficient	$\Delta R_{AB}/\Delta T$	Wiper = No Connect		30		ppm/ $^\circ C$
Wiper Resistance	$R_W$	$I_W = 1 V/R_{AB}$ , $V_{DD} = +5V$		50	100	$\Omega$
DC CHARACTERISTICS POTENTIOMETER DIVIDER MODE Specifications apply to all VRs						
Resolution	N		8			Bits
Differential Nonlinearity <sup>4</sup>	DNL		-1	$\pm 1/4$	+1	LSB
Integral Nonlinearity <sup>4</sup>	INL		-2	$\pm 1/2$	+2	LSB
Voltage Divider Temperature Coefficient	$\Delta V_W/\Delta T$	Code = 40H		5		ppm/ $^\circ C$
Full-Scale Error	$V_{WFSE}$	Code = FFH	-2	-1	+0	LSB
Zero-Scale Error	$V_{WZSE}$	Code = 00H	0	+1	+2	LSB
RESISTOR TERMINALS						
Voltage Range <sup>5</sup>	$V_{A,B,W}$		$V_{SS}$		$V_{DD}$	V
Capacitance <sup>6</sup> Ax, Bx	$C_{A,B}$	$f = 1 \text{ MHz}$ , measured to GND, Code = 40H		TBD		pF
Capacitance <sup>6</sup> Wx	$C_W$	$f = 1 \text{ MHz}$ , measured to GND, Code = 40H		TBD		pF
Common-Mode Leakage	$I_{CM}$	$V_A = V_B = V_{DD}/2$		1		nA
DIGITAL INPUTS						
Input Logic High	$V_{IH}$		2.4			V
Input Logic Low	$V_{IL}$				0.8	V
Input Logic High	$V_{IH}$	$V_L = +3V$ , $V_{SS} = 0V$	2.1			V
Input Logic Low	$V_{IL}$	$V_L = +3V$ , $V_{SS} = 0V$			0.6	V
Input Current	$I_{IL}$	$V_{IN} = 0V$ or $+5V$			$\pm 1$	$\mu A$
Input Capacitance <sup>6</sup>	$C_{IL}$			5		pF
DIGITAL Output						
O1, O2	$V_{OH}$	$I_{OH} = 0.4mA$	2.4		5.5	V
O1, O2	$V_{OL}$	$I_{OL} = -1.6mA$	0		0.4	V
SDA	$V_{OL}$	$I_{OL} = -6mA$			0.6	V
SDA	$V_{OL}$	$I_{OL} = -3mA$			0.4	V
Three-State Leakage Current	$I_{OZ}$	$V_{IN} = 0V$ or $+5V$			$\pm 1$	$\mu A$
Output Capacitance <sup>6</sup>	$C_{OZ}$			3	8	pF
POWER SUPPLIES						
Logic Supply	$V_L$		2.7		5.5	V
Power Single-Supply Range	$V_{DD \text{ RANGE}}$	$V_{SS} = 0V$	5		16.5	V
Power Dual-Supply Range	$V_{DD/SS \text{ RANGE}}$		$\pm 4.5$		$\pm 5.5$	V
Logic Supply Current	$I_L$	$V_L = +5V$			60	$\mu A$
Positive Supply Current	$I_{DD}$	$V_{IH} = +5V$ or $V_{IL} = 0V$			1	$\mu A$
Negative Supply Current	$I_{SS}$	$V_{SS} = -5V$			1	$\mu A$
Power Dissipation <sup>9</sup>	$P_{DISS}$	$V_{IH} = +5V$ or $V_{IL} = 0V$ , $V_{DD} = +5V$ , $V_{SS} = -5V$			0.6	mW
Power Supply Sensitivity	PSS	$\Delta V_{DD} = +5V \pm 10\%$		0.0002	0.005	%/%
DYNAMIC CHARACTERISTICS <sup>6, 10</sup>						
Bandwidth -3dB	BW_20K	$R_{AB} = 20K\Omega$		400		KHz
Total Harmonic Distortion	THD <sub>W</sub>	$V_A = 1V_{rms}$ , $V_B = 0V$ , $f = 1KHz$ , $R_{AB} = 20K\Omega$		0.008		%
$V_W$ Settling Time	$t_S$	$V_A = 10V$ , $V_B = 0V$ , $\pm 1$ LSB error band		2		$\mu s$
Resistor Noise Voltage	$e_{N\_WB}$	$R_{WB} = 10K\Omega$ , $f = 1KHz$ , $RS = 0$		9		nV $\sqrt{Hz}$

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Parameter	Symbol	Conditions	Min	Typ <sup>1</sup>	Max	Units
SPI (DIS='0') INTERFACE TIMING CHARACTERISTICS applies to all parts (Notes 6,12)						
Input Clock Pulse Width	$t_{CH}, t_{CL}$	Clock level high or low	50			ns
Data Setup Time	$t_{DS}$		20			ns
Data Hold Time	$t_{DH}$		20			ns
CLK to SDO Propagation Delay <sup>13</sup>	$t_{PD}$	$R_L = 1K\Omega, C_L < 20pF$	1		150	ns
CS Setup Time	$t_{CSS}$		20			ns
CS High Pulse Width	$t_{CSW}$		40			ns
Reset Pulse Width	$t_{RS}$		90			ns
CLK Fall to CS Rise Hold Time	$t_{CSH}$		0			ns
CS Rise to Clock Rise Setup	$t_{CS1}$		10			ns
I <sup>2</sup> C (DIS='1') INTERFACE TIMING CHARACTERISTICS applies to all parts(Notes 6,12)						
SCL Clock Frequency	$f_{SCL}$		0		400	KHz
$t_{BUF}$ Bus free time between STOP & START	$t_1$		1.3			$\mu s$
$t_{HD:STA}$ Hold Time (repeated START)	$t_2$	After this period the first clock pulse is generated	0.6			$\mu s$
$t_{LOW}$ Low Period of SCL Clock	$t_3$		1.3			$\mu s$
$t_{HIGH}$ High Period of SCL Clock	$t_4$		0.6			$\mu s$
$t_{SU:STA}$ Setup Time For START Condition	$t_5$		0.6			$\mu s$
$t_{HD:DAT}$ Data Hold Time	$t_6$		0		0.9	$\mu s$
$t_{SU:DAT}$ Data Setup Time	$t_7$		100			ns
$t_F$ Fall Time of both SDA & SCL signals	$t_8$				300	ns
$t_R$ Rise Time of both SDA & SCL signals	$t_9$				300	ns
$t_{SU:STO}$ Setup time for STOP Condition	$t_{10}$		0.6			$\mu s$

#### NOTES:

- Typicals represent average readings at +25°C and  $V_{DD} = +5V, V_{SS} = -5V$ .
- Resistor position nonlinearity error R-INL is the deviation from an ideal value measured between the maximum resistance and the minimum resistance wiper positions. R-DNL measures the relative step change from ideal between successive tap positions. Parts are guaranteed monotonic.  $I_w = V_{DD}/R$  for both  $V_{DD}=+5V, V_{SS}=-5V$ .
- $V_{AB} = V_{DD}$ , Wiper ( $V_W$ ) = No connect
- INL and DNL are measured at  $V_W$  with the RDAC configured as a potentiometer divider similar to a voltage output D/A converter.  $V_A = V_{DD}$  and  $V_B = 0V$ . DNL specification limits of  $\pm 1LSB$  maximum are Guaranteed Monotonic operating conditions.
- Resistor terminals A, B, W have no limitations on polarity with respect to each other.
- Guaranteed by design and not subject to production test.
- Measured at the Ax terminals. All Ax terminals are open circuited in shutdown mode.
- Worst case supply current consumed when input all logic-input levels set at 2.4V, standard characteristic of CMOS logic.
- $P_{DISS}$  is calculated from  $(I_{DD} \times V_{DD})$ . CMOS logic level inputs result in minimum power dissipation.
- All dynamic characteristics use  $V_{DD} = +5V, V_{SS} = -5V, V_L = +5V$ .
- Measured at a  $V_W$  pin where an adjacent  $V_W$  pin is making a full-scale voltage change.
- See timing diagram for location of measured values. All input control voltages are specified with  $t_R=t_F=2ns(10\% \text{ to } 90\% \text{ of } +3V)$  and timed from a voltage level of 1.5V. Switching characteristics are measured using  $V_L = +5V$ .
- Propagation delay depends on value of  $V_{DD}$ ,  $R_L$ , and  $C_L$  see applications text.
- The AD5260/AD5262 contains 1,968 transistors. Die Size: 89mil x 105mil, 9,345sq. mil.

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**ABSOLUTE MAXIMUM RATINGS** ( $T_A = +25^\circ\text{C}$ , unless otherwise noted)

$V_{DD}$ to GND .....	-0.3, +15V
$V_{SS}$ to GND .....	0V, -7V
$V_{DD}$ to $V_{SS}$ .....	+15V
$V_A, V_B, V_W$ to GND .....	$V_{SS}, V_{DD}$
$A_X - B_X, A_X - W_X, B_X - W_X$	
Intermittent <sup>2</sup> .....	$\pm 20\text{mA}$
Continuous .....	$\pm 2\text{mA}$
Digital Inputs & Output Voltage to GND .....	0V, +7V
Operating Temperature Range .....	$-40^\circ\text{C}$ to $+85^\circ\text{C}$
Maximum Junction Temperature ( $T_{J\text{MAX}}$ ) .....	$+150^\circ\text{C}$
Storage Temperature .....	$-65^\circ\text{C}$ to $+150^\circ\text{C}$
Lead Temperature (Soldering, 10 sec) .....	$+300^\circ\text{C}$
Vapor Phase (60 sec) .....	$+215^\circ\text{C}$

Infrared (15 sec) .....	$+220^\circ\text{C}$
Thermal Resistance * $\theta_{JA}$	
TSSOP-24 .....	$143^\circ\text{C/W}$
*Package Power Dissipation = $(T_{J\text{MAX}} - T_A) / \theta_{JA}$	

### NOTES

- Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating; functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.
- Maximum terminal current is bounded by the maximum current handling of the switches, maximum power dissipation of the package, and maximum applied voltage across any two of the A, B, and W terminals at a given resistance.

### ORDERING GUIDE

Model	$R_{AB}$ (k $\Omega$ )	Temp	Package Description	Package Option	# Parts per Container	Top Mark*
AD5263BRU20	20	$-40/+125^\circ\text{C}$	TSSOP-24	RU-24	62	AD5263B20
AD5263BRU20-REEL7	20	$-40/+125^\circ\text{C}$	TSSOP-24	RU-24	1,000	AD5263B20
AD5263BRU50	50	$-40/+125^\circ\text{C}$	TSSOP-24	RU-24	62	AD5263B50
AD5263BRU50-REEL7	50	$-40/+125^\circ\text{C}$	TSSOP-24	RU-24	1,000	AD5263B50
AD5263BRU200	200	$-40/+125^\circ\text{C}$	TSSOP-24	RU-24	62	AD5263B200
AD5263BRU200-REEL7	200	$-40/+125^\circ\text{C}$	TSSOP-24	RU-24	1,000	AD5263B200

\*Line 1 contains part number, line 2 branding containing differentiating detail by part type and ADI logo symbol, line 3 contains date code YWW.

### CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD5263 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



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SPI Compatible Digital Interface (DIS='0')

TABLE IA: SPI 10-Bit Serial-Data Word Format

ADDR		DATA								
B9	B8	B7	B6	B5	B4	B3	B2	B1	B0	
A1	A0	D7	D6	D5	D4	D3	D2	D1	D0	
2 <sup>9</sup>		MSB								LSB
		2 <sup>7</sup>								2 <sup>0</sup>

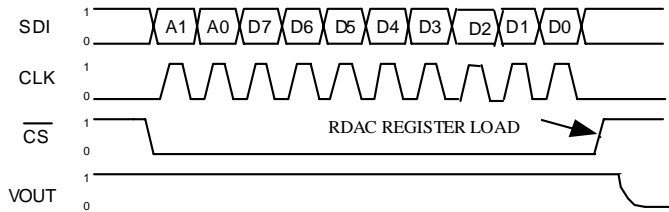


Figure 1A. SPI Timing Diagram

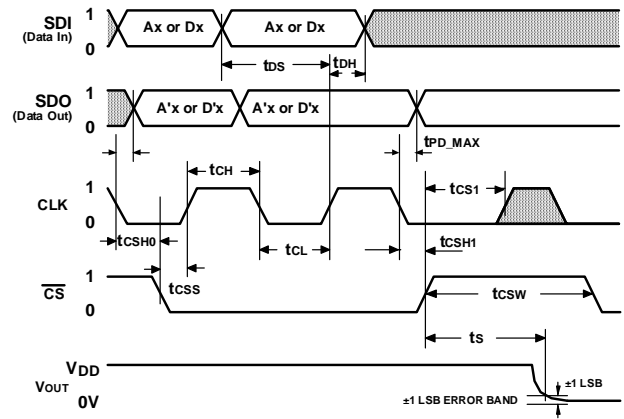


Figure 1B. Detail SPI Timing Diagram

I<sup>2</sup>C Compatible Digital Interface (DIS='1')

TABLE IIA: I<sup>2</sup>C Write Mode Data Word Format

S	0	1	0	1	1	A	A	$\bar{W}$	A	X	A	A	R	S	0	0	X	A	D	D	D	D	D	D	D	D	A	P
Slave Address Byte									Instruction Byte							Data Byte												

TABLE IIB: I<sup>2</sup>C Read Mode Data Word Format:

S	0	1	0	1	1	0	A	R	A	D	D	D	D	D	D	D	D	A	P
Slave Address Byte							Data Byte												

- S = Start Condition
- P = Stop Condition
- A = Acknowledge
- AD1, AD0 = Package pin programmable address bits, Must match with the logic states at pins AD1, AD0
- A1, A0 = RDAC sub address select
- RS = Software Reset wiper (A1, A0) to mid scale position

- SD = Shutdown active high, ties wiper (A1, A0) to terminal A, opens terminal B, RDAC register contents are not disturbed. To exit shutdown a command SD = '0' must be executed for each RDAC (A1, A0).
- $\bar{W}$  = Write = '0'
- R = Read = '1'
- D7,D6,D5,D4,D3,D2,D1,D0 = Data Bits
- X = Don't Care

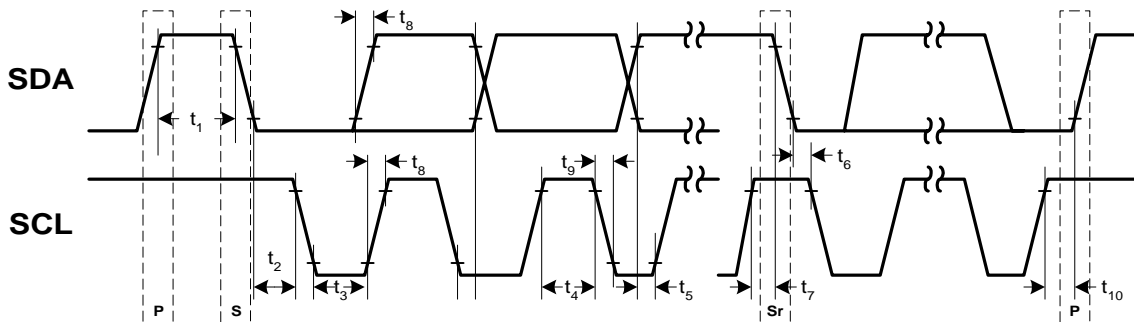


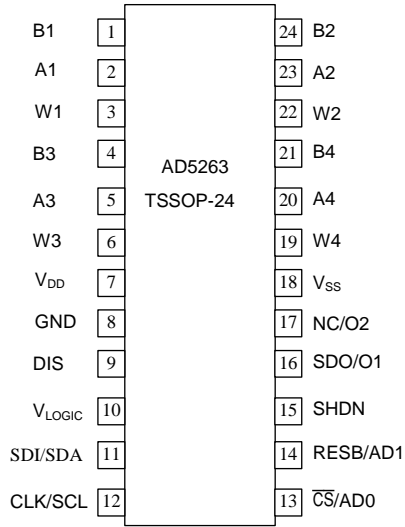
Figure 2. I<sup>2</sup>C Compatible Detail Timing Diagram

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### AD5263 PIN CONFIGURATION



9	DIS	Digital Interface Select (SPI/I <sup>2</sup> C Select); SPI when DIS='0', I <sup>2</sup> C when DIS='1'
10	V <sub>LOGIC</sub>	Logic Supply Voltage, needs to be same voltage as the digital logic controlling the AD5263.
11	SDI/SDA	SDI = 3-wire Serial Data Input/ SDA = 2-wire Serial Data Input/Output
12	CLK/SCL	Serial Clock Input
13	$\overline{CS}/AD0$	Chip Select / I <sup>2</sup> C Compatible Device Address Bit 0
14	RESB/AD1	RESETB/I <sup>2</sup> C Compatible Device Address Bit 1
15	SHDN	Shutdown -- Ties wiper to terminal A, opens terminal B
16	SDO/O1	Serial Data Output, Open Drain transistor requires pull-up resistor/Digital Output O1, can be used to drive external logic
17	NC/O2	No Connection/Digital Output O2, can be used to drive external logic
18	V <sub>SS</sub>	Negative power supply, specified for operation from 0 to -5V.
19	W4	Wiper terminal W4 (ADDR=11)
20	A4	Resistor terminal A4
21	B4	Resistor terminal B4
22	W2	Wiper terminal W2 (ADDR=01)
23	A2	Resistor terminal A2
24	B2	Resistor terminal B2

**TABLE III: AD5263 PIN Descriptions**

Pin	Name	Description
1	B1	Resistor terminal B1
2	A1	Resistor terminal A1 (ADDR=00)
3	W1	Wiper terminal W1
4	B3	Resistor terminal B3
5	A3	Resistor terminal A3
6	W3	Wiper terminal W3 (ADDR=10)
7	V <sub>DD</sub>	Positive power supply, specified for +5V to +15V operation
8	GND	Ground

### OUTLINE DIMENSIONS

Dimensions shown in inches and (mm)

#### 24-Lead Thin Surface Mount TSSOP Package (RU-24)

