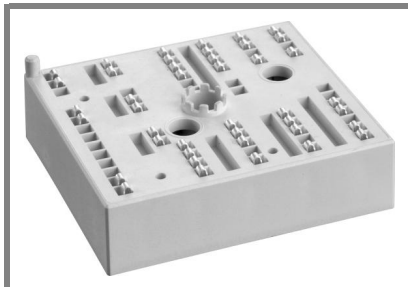


# SKiIP 24NAB126V10



MiniSKiIP<sup>®</sup> 2

3-phase bridge rectifier +  
brake chopper + 3-phase  
bridge inverter  
**SKiIP 24NAB126V10**

## Features

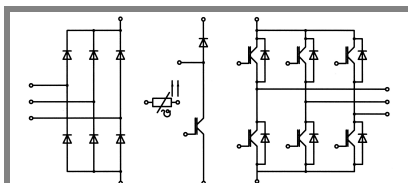
- Fast Trench IGBTs
- Robust and soft freewheeling diodes in CAL technology
- Highly reliable spring contacts for electrical connections
- UL recognised file no. E63532

## Typical Applications

- Inverter up to 19 kVA
- Typical motor power 11 kW

## Remarks

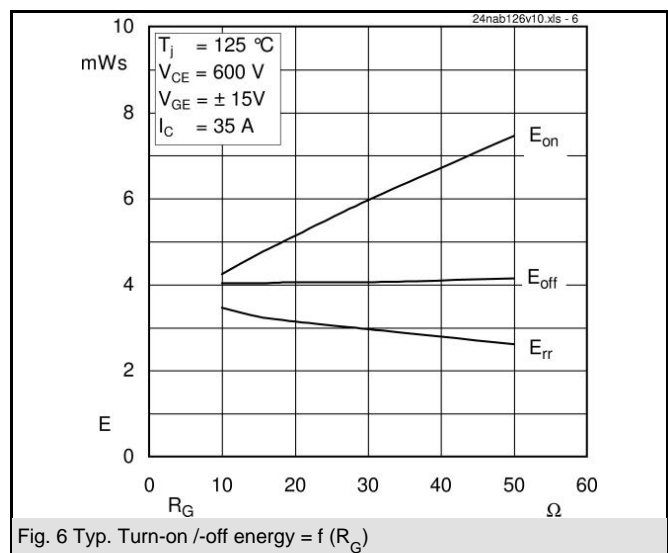
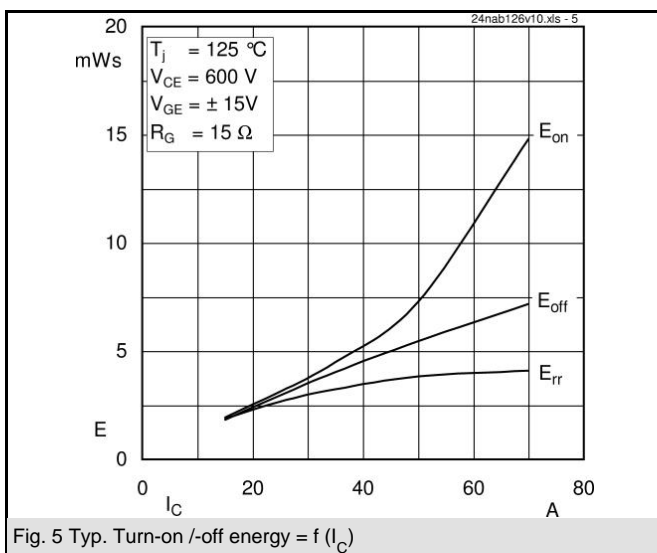
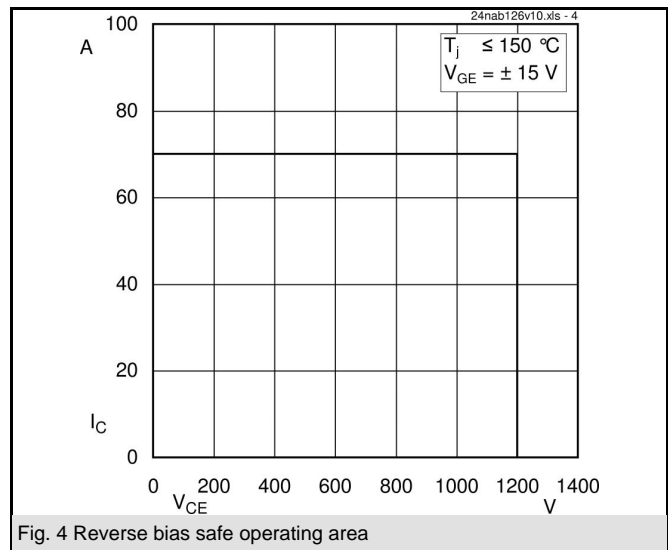
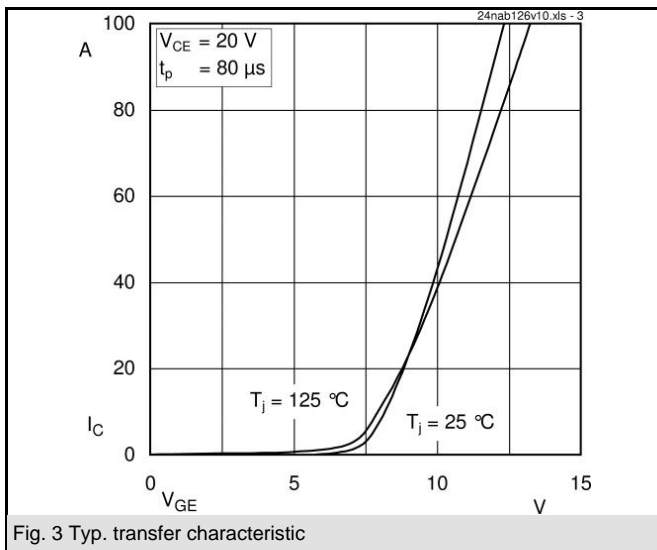
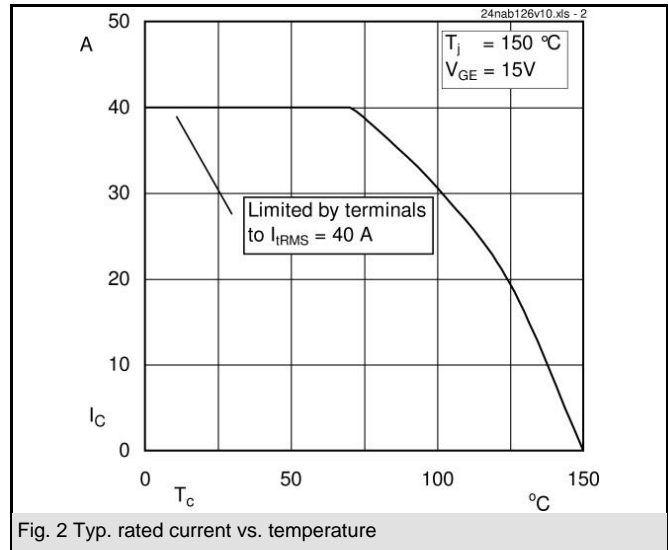
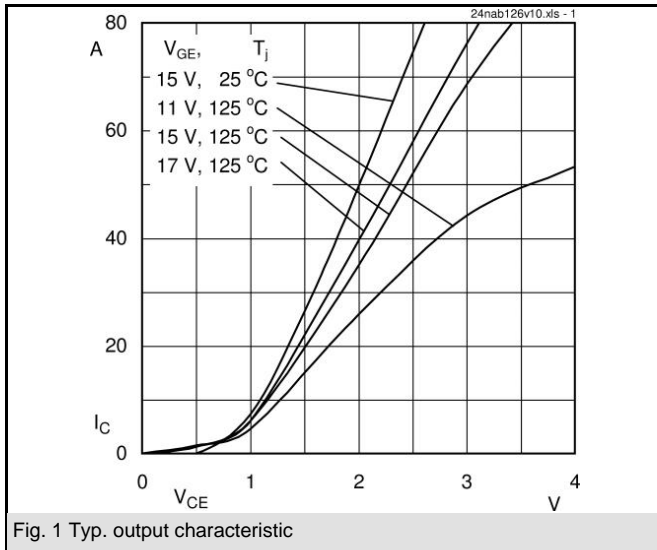
- $V_{CEsat}$ ,  $V_F$  = chip level value



NAB

Absolute Maximum Ratings		$T_s = 25^\circ\text{C}$ , unless otherwise specified		
Symbol	Conditions	Values	Units	
<b>IGBT - Inverter, Chopper</b>				
$V_{CES}$	$T_s = 25 (70)^\circ\text{C}$	1200	V	
$I_C$		52 (40)	A	
$I_{CRM}$		70	A	
$V_{GES}$		$\pm 20$	V	
$T_j$		- 40 ... + 150	$^\circ\text{C}$	
<b>Diode - Inverter, Chopper</b>				
$I_F$	$T_s = 25 (70)^\circ\text{C}$	38 (29)	A	
$I_{FRM}$		70	A	
$T_j$		- 40 ... + 150	$^\circ\text{C}$	
<b>Diode - Rectifier</b>				
$V_{RRM}$	$T_s = 70^\circ\text{C}$	1600	V	
$I_F$		61	A	
$I_{FSM}$		$t_p = 10 \text{ ms, sin } 180^\circ, T_j = 25^\circ\text{C}$	700	A
$i^2t$		$t_p = 10 \text{ ms, sin } 180^\circ, T_j = 25^\circ\text{C}$	2400	$\text{A}^2\text{s}$
$T_j$		- 40 ... + 150	$^\circ\text{C}$	
<b>Module</b>				
$I_{RMS}$	per power terminal (20 A / spring)	40	A	
$T_{stg}$		- 40 ... + 125	$^\circ\text{C}$	
$V_{isol}$	AC, 1 min.	2500	V	

Characteristics		$T_s = 25^\circ\text{C}$ , unless otherwise specified			
Symbol	Conditions	min.	typ.	max.	Units
<b>IGBT - Inverter, Chopper</b>					
$V_{CEsat}$	$I_{Cnom} = 35 \text{ A}, T_j = 25 (125)^\circ\text{C}$		1,7 (2)	2,1 (2,4)	V
$V_{GE(th)}$	$V_{GE} = V_{CE}, I_C = 1,5 \text{ mA}$	5	5,8	6,5	V
$V_{CE(TO)}$	$T_j = 25 (125)^\circ\text{C}$		1 (0,9)	1,2 (1,1)	V
$r_T$	$T_j = 25 (125)^\circ\text{C}$		20 (31)	26 (37)	$\text{m}\Omega$
$C_{ies}$	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$		2,4		nF
$C_{oes}$	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$		0,5		nF
$C_{res}$	$V_{CE} = 25 \text{ V}, V_{GE} = 0 \text{ V}, f = 1 \text{ MHz}$		0,3		nF
$R_{th(j-s)}$	per IGBT		0,75		K/W
$t_{d(on)}$	under following conditions		80		ns
$t_r$	$V_{CC} = 600 \text{ V}, V_{GE} = \pm 15 \text{ V}$		30		ns
$t_{d(off)}$	$I_{Cnom} = 35 \text{ A}, T_j = 125^\circ\text{C}$		410		ns
$t_f$	$R_{Gon} = R_{Goff} = 15 \Omega$		120		ns
$E_{on}$	inductive load		4,6		mJ
$E_{off}$			4		mJ
<b>Diode - Inverter, Chopper</b>					
$V_F = V_{EC}$	$I_{Fnom} = 35 \text{ A}, T_j = 25 (125)^\circ\text{C}$		1,8 (1,8)	2,1 (2,2)	V
$V_{(TO)}$	$T_j = 25 (125)^\circ\text{C}$		1 (0,8)	1,1 (0,9)	V
$r_T$	$T_j = 25 (125)^\circ\text{C}$		23 (31)	29 (37)	$\text{m}\Omega$
$R_{th(j-s)}$	per diode		1,5		K/W
$I_{RRM}$	under following conditions		43		A
$Q_{rr}$	$I_{Fnom} = 35 \text{ A}, V_R = 600 \text{ V}$		7		$\mu\text{C}$
$E_{rr}$	$V_{GE} = 0 \text{ V}, T_j = 125^\circ\text{C}$ $di_F/dt = 1450 \text{ A}/\mu\text{s}$		3,3		mJ
<b>Diode -Rectifier</b>					
$V_F$	$I_{Fnom} = 35 \text{ A}, T_j = 25^\circ\text{C}$		1,1		V
$V_{(TO)}$	$T_j = 150^\circ\text{C}$		0,8		V
$r_T$	$T_j = 150^\circ\text{C}$		11		$\text{m}\Omega$
$R_{th(j-s)}$	per diode		0,9		K/W
<b>Temperature Sensor</b>					
$R_{ts}$	3 %, $T_r = 25 (100)^\circ\text{C}$		1000(1670)		$\Omega$
<b>Mechanical Data</b>					
w			65		g
$M_s$	Mounting torque	2		2,5	Nm



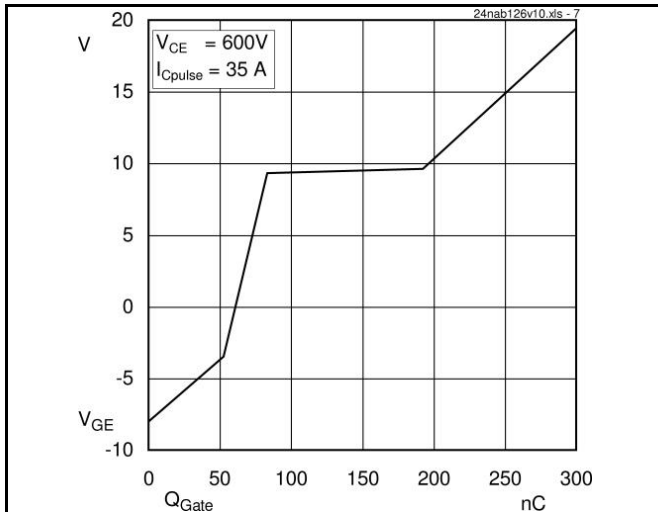


Fig. 7 Typ. gate charge characteristic

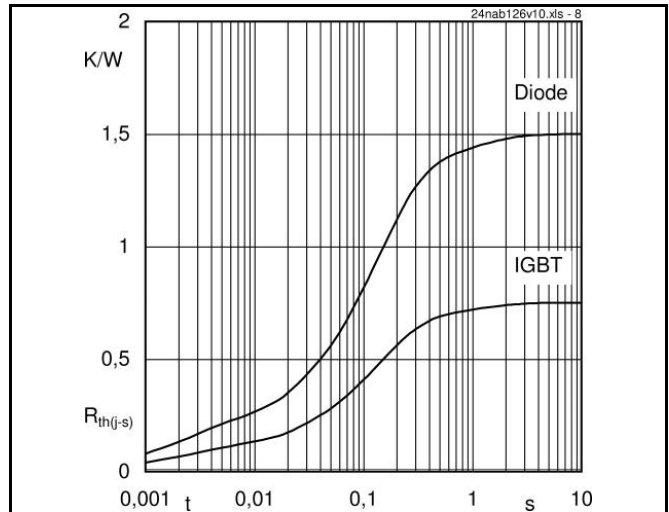


Fig. 8 Typ. thermal impedance

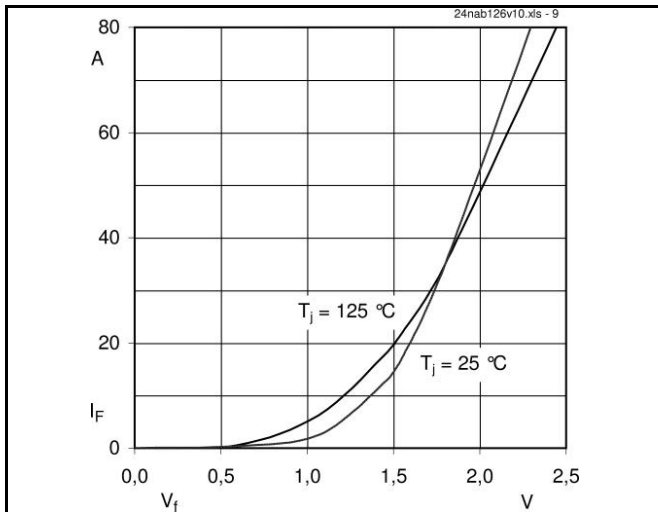


Fig. 9 Typ. freewheeling diode forward characteristic

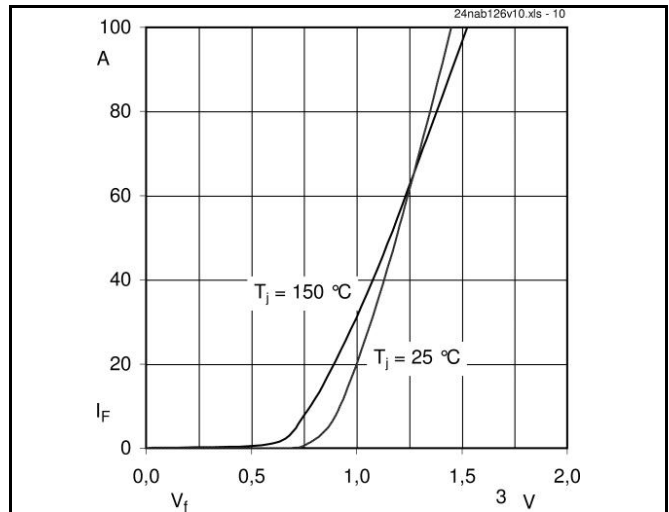
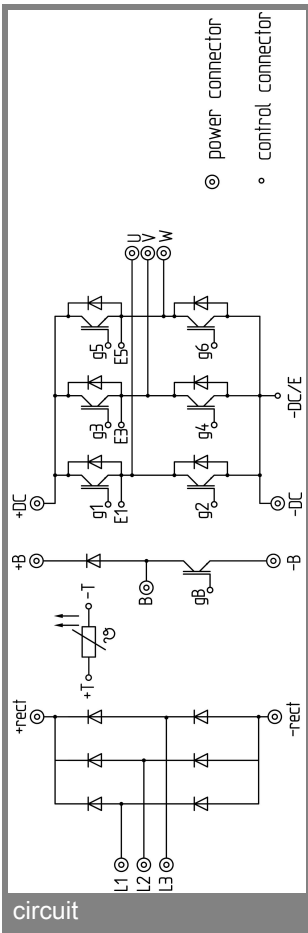
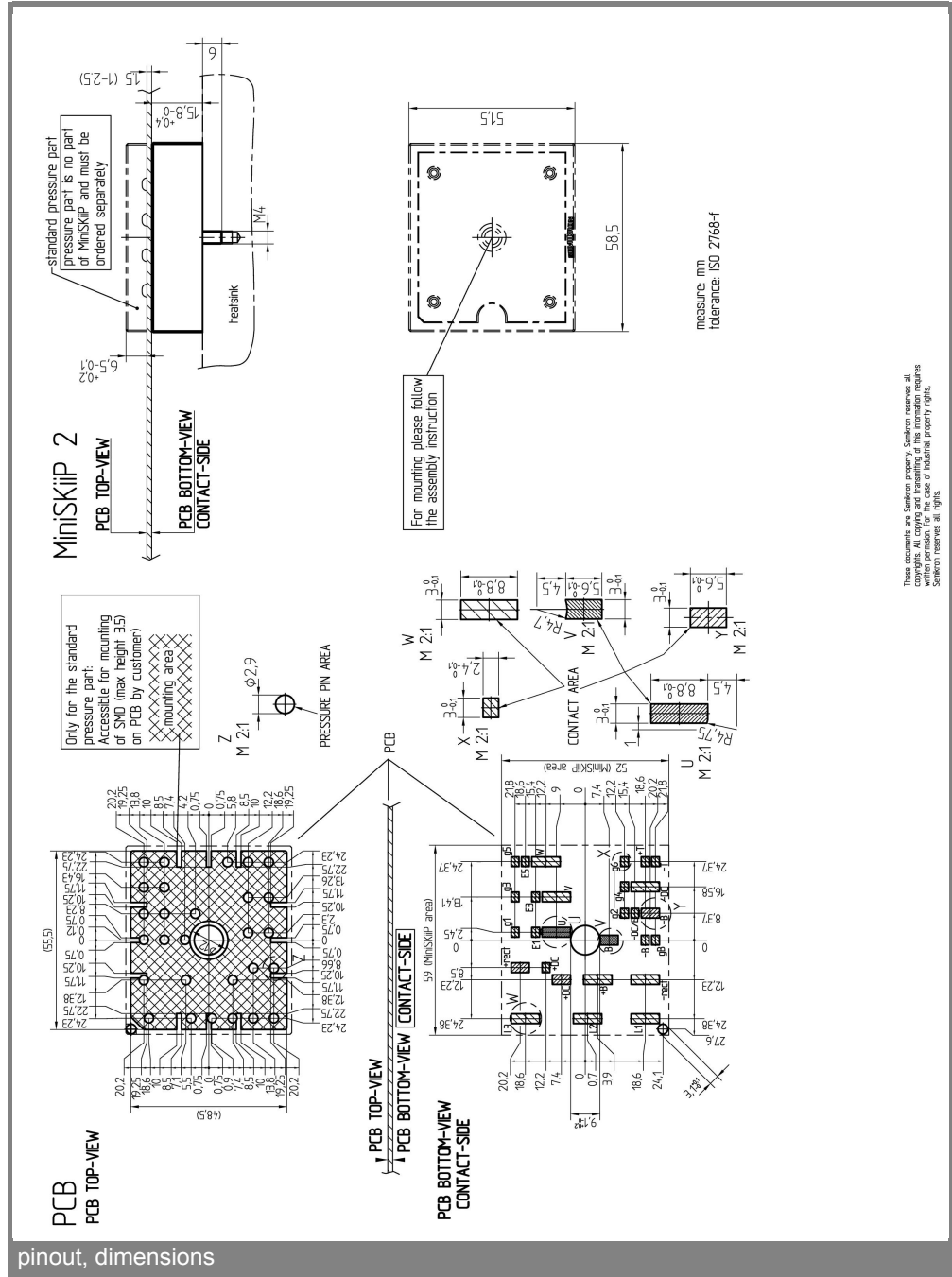


Fig. 10 Typ. input bridge forward characteristic

# SKiIP 24NAB126V10



circuit



pinout, dimensions

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