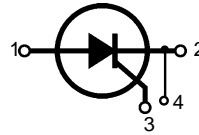


Phase Control Thyristors

$V_{RRM} = 1200-1600 \text{ V}$
 $I_{T(RMS)} = 260 \text{ A}$
 $I_{T(AV)M} = 164 \text{ A}$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
1300	1200	CS 142-12io8
1700	1600	CS 142-16io8

Not for new application



TO-209AC
(TO-94)



1 = Anode, 2 = Cathode,
3 = Gate, 4 = Auxiliary Cathode

Symbol	Test Conditions	Maximum Ratings	
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	260 A	
$I_{T(AV)M}$	$T_{case} = 85^{\circ}\text{C}; 180^{\circ} \text{ sine}$	140 A	
	$T_{case} = 75^{\circ}\text{C}; 180^{\circ} \text{ sine}$	164 A	
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C};$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$	3100 A
		$t = 8.3 \text{ ms (60 Hz), sine}$	3270 A
	$T_{VJ} = T_{VJM}$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$	2600 A
		$t = 8.3 \text{ ms (60 Hz), sine}$	2800 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$	48 000 A ² s
		$t = 8.3 \text{ ms (60 Hz), sine}$	45 000 A ² s
	$T_{VJ} = T_{VJM}$ $V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$	33 800 A ² s
		$t = 8.3 \text{ ms (60 Hz), sine}$	32 000 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 1/2 V_{DRM}$ $I_G = 0.5 \text{ A}$ $di_G/dt = 0.5 \text{ A}/\mu\text{s}$	repetitive, $I_T = 500 \text{ A}$	150 A/ μs
		non repetitive, $I_T = I_{T(AV)M}$	500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$	1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$	120 W
		$t_p = 500 \mu\text{s}$	60 W
		$t_p = 10 \text{ ms}$	16 W
V_{RGM}			10 V
T_{VJ}			-40...+125 °C
T_{VJM}			125 °C
T_{stg}			-40...+125 °C
M_d	Mounting torque		16-20 Nm
			142-177 lb.in.
Weight			110 g

Features

- Thyristor for line frequencies
- International standard package JEDEC TO-209AC
- Planar glassivated chip
- Long-term stability of blocking currents and voltages
- Gate and auxiliary cathode pin connection

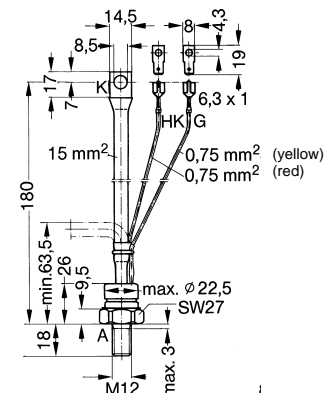
Applications

- Motor control
- Power converter
- AC power controller

Advantages

- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 15 mA
V_T	$I_T = 300$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.35 V
V_{TO}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	1.0 V
r_T		1.7 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 2.5 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 3.5 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 150 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 200 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 10 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.5$ A; $di_G/dt = 0.5$ A/ μs	≤ 300 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 200 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.5$ A; $di_G/dt = 0.5$ A/ μs	≤ 2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 50$ A, $t_p = 200$ μs ; $di/dt = -10$ A/ μs $V_R = 100$ V; $dv/dt = 20$ V/ μs ; $V_D = 2/3 V_{DRM}$	typ. 150 μs
R_{thJC}	DC current	0.18 K/W
R_{thJH}	DC current	0.22 K/W
d_s	Creepage distance on surface	10.5 mm
d_A	Strike distance through air	10.5 mm
a	Max. acceleration, 50 Hz	50 m/s ²

Accessories:

Nut M12 DIN 439/SW27

Lock washer A12 DIN 128