July 1998

## National Semiconductor

## DS1487

## Low Power RS-485 <sup>1</sup>/<sub>4</sub> Unit Load Multipoint Transceiver

#### **General Description**

The DS1487 is a low-power transceiver for RS-485 and RS-422 communication. The device contains one driver and one receiver. The drivers slew rate allows for operation up to 2.0 Mbps (see Applications Information section). The transceiver presents 1/4 unit loading to the RS-485 bus allowing up to 128 nodes to be connected together without the use of repeaters.

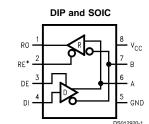
The transceiver draws 200  $\mu A$  of supply current when unloaded or fully loaded with the driver disabled and operates from a single +5V supply.

The driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into TRI-STATE® (High Impedance state) under fault conditions. The driver guarantees a minimum of 1.5V differential output voltage with maximum loading across the common mode range (V<sub>OD3</sub>).

The receiver has a failsafe feature that guarantees a logic-high output if the input is open circuit.

The DS1487 is available in surface mount and DIP packages.

#### **Connection and Logic Diagram**



\*Note: Non Terminated, Open Input only

Order Number	Temp. Range	Package/###
DS1487N	0°C to +70°C	DIP/N08E
DS1487M	0°C to +70°C	SOP/M08A

#### **Features**

- Meets TIA/EIA RS-485 multipoint standard
- Allows up to 128 transceivers on the bus (¼ U.L.)
- Guaranteed full load output voltage (V<sub>OD3</sub>)
- Low quiescent current: 200 µA typ
- –7V to +12V common-mode input voltage range
- TRI-STATE outputs on driver and receiver
- AC performance:
  - Driver transition time: 25 ns typ
  - Driver propagation delay: 40 ns typ
  - Driver skew: 1 ns typ
- Receiver propagation delay: 200 ns typ
- Receiver skew: 20 ns typ
- Half-duplex flow through pinout
- Operates from a single 5V supply
- Current-limiting and thermal shutdown for driver overload protection
- Pin and functional compatible with MAX1487

### Truth Table

DRIVER S	ECTION			
RE	DE	DI	Α	В
(Note 1)				
Х	Н	Н	Н	L
Х	н	L	L	н
х	L	Х	Z	Z
RECEIVER	<b>SECTION</b>			
RE	DE	A	-В	RO
(Note 1)				
Г	L	≥+0	).2V	Н
L	L	≤–0.2V		L
н	Х	Х		Z
L	L	OPEN (Note 1)		н

X = indeterminate Z = TRI-STATE

Note 1: Non Terminated, Open Input only

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DS1487 Low Power RS-485 1/4 Unit Load Multipoint Transceive

#### Absolute Maximum Ratings (Note 2)

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If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (V <sub>CC</sub> )	+12V
Enable Input Voltage (RE (Note 1), DE)	
(RE (NOLE I), DE)	–0.5V to (V <sub>CC</sub> + 0.5V)
Driver Input Voltage (DI)	–0.5V to (V <sub>CC</sub> + 0.5V)
Driver Output Voltage (A, B)	-14V to +14V
Receiver Input Voltage (A, B)	-14V to +14V
Receiver Output Voltage (RO)	-0.5V to (V <sub>CC</sub> + 0.5V)
Maximum Package Power Dissipation	on @ +25°C
M Package	1.19W
N Package	0.74W
Derate M Package 9.5 mW/°C abov	e +25°C
Derate N Package 6.0 mW/°C above	e +25°C
Maximum Package Power Dissipation	on @ +70°C

M Package	0.76W
N Package	0.47W
Storage Temperature Range	-65°C to +150°C
Lead Temperature Range	
(Soldering, 4 sec.)	+260°C
ESD (HBM)	≥2 kV

# Recommended Operating Conditions

	Min	Тур	Max	Units
Supply Voltage (V <sub>CC</sub> )	+4.75	+5.0	+5.25	V
Operating Free Air				
Temperature (T <sub>A</sub> )				
DS1487	0	+25	+70	°C
Bus Common Mode Voltage	-7		+12	V

#### **Electrical Characteristics**

Symbol	Parameter	Conditions	Pin	Min	Тур	Max	Units
V <sub>OD1</sub>	Differential Driver Output Voltage	(No Load)	A, B	1.5		5	V
V <sub>OD2</sub>	Differential Driver Output Voltage	R <sub>L</sub> = 50Ω, (RS422), <i>Figure 1</i>	1	2	2.8		V
	with Load	R <sub>L</sub> = 27Ω, (RS485), <i>Figure 1</i>	1	1.5	2.3	5	V
$\Delta V_{OD}$	Change in Magnitude of Output	$R_L = 27\Omega \text{ or } 50\Omega \text{ (Note 5)}$	1			0.2	V
	Differential Voltage						
V <sub>OD3</sub>	Differential Driver Output Voltage-	R1 = 54Ω, R2 = 375Ω		1.5	2.0	5	V
	Full Load with Max V <sub>CM</sub>	$V_{\text{TEST}}$ = -7V to +12V, Figure 2					
V <sub>oc</sub>	Driver Common-Mode Output Voltage	$R_{L} = 27\Omega \text{ or } 50\Omega, Figure 1$	7	0		3	V
$\Delta V_{OC}$	Change in Magnitude of	$R_L = 27\Omega \text{ or } 50\Omega, Figure 1 (Note 5)$	7			0.2	IVI
	Common-Mode Output Voltage					0.2	
V <sub>IH</sub>	Input High Voltage		DI, DE,	2.0			V
VIL	Input Low Voltage		RE (Note 1)			0.8	V
I <sub>IN1</sub>	Input Current	$V_{IN} = 0V \text{ or } V_{CC}$				±2	μA
I <sub>IN2</sub>	Input Current (Note 6)	V <sub>IN</sub> = +12V	А, В	0	190	250	μA
	DE = 0V, $V_{CC}$ = 0V or 5.25V	$V_{IN} = -7V$		0	-100	-200	μA
V <sub>TH</sub>	Receiver Differential Threshold Voltage	$-7V \le V_{CM} \le +12V$		-0.2		0.2	V
$\Delta V_{TH}$	Receiver Input Hysteresis	V <sub>CM</sub> = 0V	7		70		mV
V <sub>OH</sub>	Receiver Output High Voltage	$I_0 = -4 \text{ mA}, V_{ID} = 0.2 \text{V}$	RO	3.5			V
V <sub>OL</sub>	Receiver Output Low Voltage	$I_0 = 4 \text{ mA}, V_{ID} = -0.2 \text{V}$	7			0.5	V
I <sub>OZR</sub>	TRI-STATE Output Current at Receiver	$0.4V \le V_O \le 2.4V$				±1	μA
R <sub>IN</sub>	Receiver Input Resistance	$-7V \le V_{IN} \le +12V$	A, B	48	68		kΩ
I <sub>cc</sub>	No-Load Supply Current (Note 7)	DE = $V_{CC}$ , RE (Note 1) = 0V or $V_{CC}$	V <sub>cc</sub>		200	500	μA
		DE = 0V, RE (Note 1) = 0V or $V_{CC}$	1		200	500	μA
I <sub>OSD1</sub>	Driver Short Circuit Current, V <sub>O</sub> = HIGH	$-7V \le V_O \le +12V$	A, B			250	mA
I <sub>OSD2</sub>	Driver Short Circuit Current, V <sub>O</sub> = LOW	$-7V \le V_O \le +12V$				-250	mA
IOSR	Receiver Short Circuit Current	$V_{O} = GND$	RO	7		85	mA

Over Supply Voltage and Operating Temperature Ranges, unless otherwise specified (Notes 3, 4)

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Symbol	Parameter	Conditions	Min	Тур	Max	Units
t <sub>PLHD</sub>	Driver Differential Propagation Delay — Low to High	$R_{L} = 54\Omega, C_{L} = 100 \text{ pF}$	10	40	80	ns
t <sub>PHLD</sub>	Driver Differential Propagation Delay — High to Low		10	39	80	ns
t <sub>skew</sub>	Differential Skew  t <sub>PHLD</sub> - t <sub>PLHD</sub>		0	1	10	ns
t <sub>r</sub>	Driver Rise Time		3	25	50	ns
t <sub>f</sub>	Driver Fall Time		3	25	50	ns
t <sub>zH</sub>	Driver Enable to Output High	C <sub>L</sub> = 100 pF		50	200	ns
t <sub>zL</sub>	Driver Enable to Output Low	C <sub>L</sub> = 100 pF		65	200	ns
t <sub>LZ</sub>	Driver Disable from Output Low	C <sub>L</sub> = 15 pF		80	200	ns
t <sub>HZ</sub>	Driver Disable from Output High	C <sub>L</sub> = 15 pF		80	200	ns
t <sub>PLHD</sub>	Receiver Differential Propagation Delay—Low to High	C <sub>L</sub> = 15 pF (RO)	30	190	400	ns
t <sub>PHLD</sub>	Receiver Differential Propagation Delay—High to Low		30	210	400	ns
t <sub>SKEW</sub>	Differential Skew  t <sub>PHLD</sub> - t <sub>PLHD</sub>		0	20	50	ns
t <sub>zH</sub>	Receiver Enable to Output High	C <sub>L</sub> = 15 pF		45	150	ns
t <sub>ZL</sub>	Receiver Enable to Output Low			40	150	ns
t <sub>LZ</sub>	Receiver Disable from Output Low	7		50	150	ns
t <sub>HZ</sub>	Receiver Disable from Output High	1		55	150	ns
f <sub>max</sub>	Maximum Data Rate	(Note 10)	2.0			Mbps

Note 2: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" specifies conditions of device operation.

Note 3: Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except V<sub>OD1/2/3</sub> and V<sub>ID</sub>.

Note 4: All typicals are given for: V<sub>CC</sub> = +5.0V, T<sub>A</sub> = +25°C.

Note 5:  $\Delta |V_{OD}|$  and  $\Delta |V_{OC}|$  are changes in magnitude of  $V_{OD}$  and  $V_{OC}$  respectively, that occur when the input changes state.

Note 6: IIN2 includes the receiver input current and driver TRI-STATE leakage current.

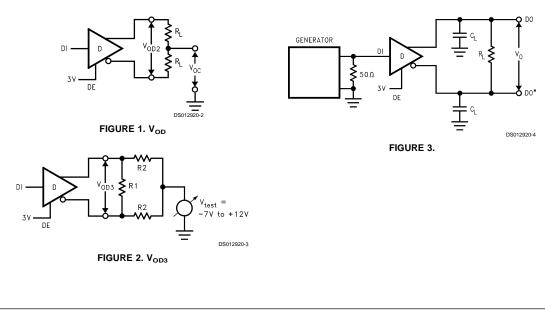
Note 7: Supply current specification is valid for loaded transmitters when DE = 0V or enabled (DE = H) with no load.

Note 8: f = 1 MHz,  $t_r$  and  $t_f \le 6$  ns,  $Z_O = 50\Omega$ .

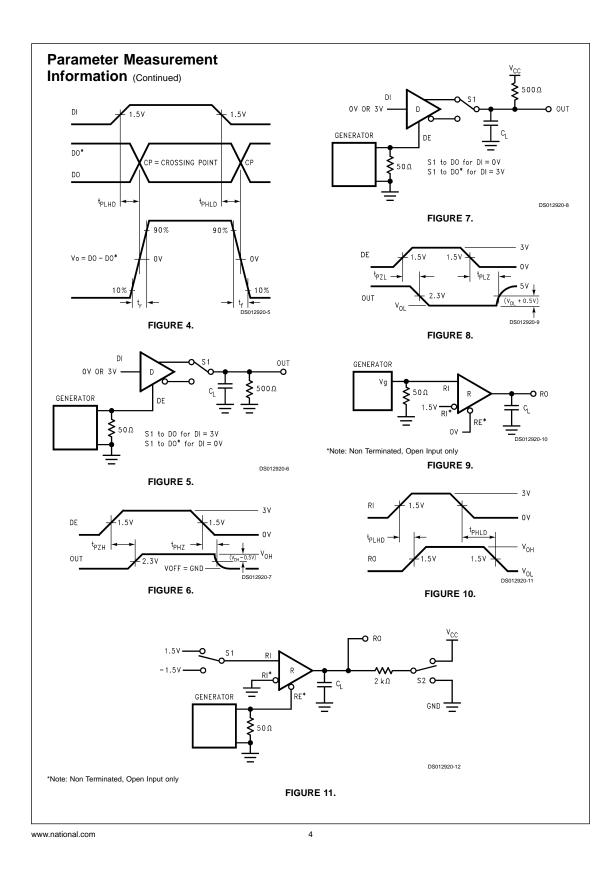
Note 9: CL includes jig and probe capacitance.

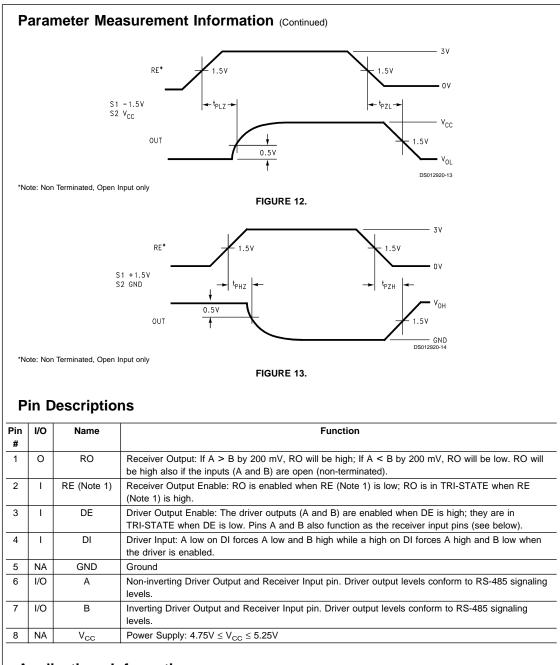
Note 10:  $f_{max}$  is the guaranteed data rate for 50 ft of twisted pair cable.  $f_{max}$  may be conservatively determined from the ratio of driver transition time (t<sub>r</sub>) to the data rate unit interval (1/ $f_{max}$ ). Using a 10% ratio yields  $f_{max} = (0.1)/50$  ns = 2.0 Mb/s. Higher data rates may be supported by allowing larger ratios.

#### **Parameter Measurement Information**



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#### **Applications Information**

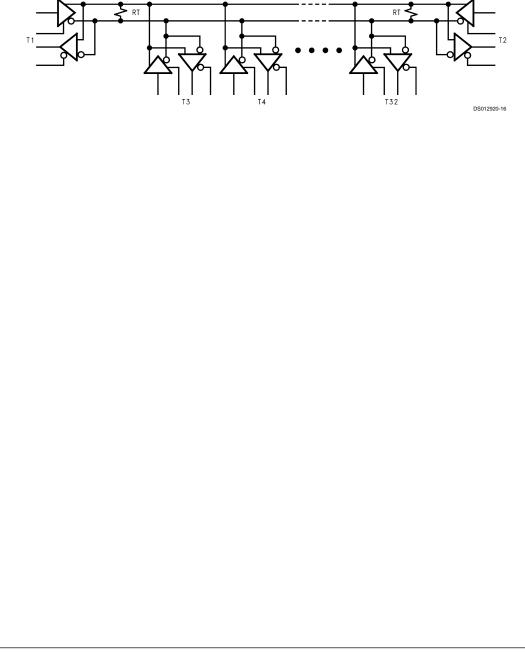
The DS1487 is a low power transceiver designed for use in RS-485 multipoint applications. The DS1487 can transmit data up to 2.0 Mbps based on a ratio of driver transition time to the unit interval (bit time) of 10%. This maximum data rate may be further limited by the interconnecting media. The DS1487 provides a 14 unit load to the RS-485 bus across the common mode range of -7V to +12V. This allows up to 128 transceivers (14 unit load) to be connected to the bus. The

DS1487 also guarantees the driver's output differential voltage into a worst case load that models standard termination loads and 32 unit loads (=128 DS1487's) referenced to the maximum common mode voltage extremes. With a minimum of 1.5V swing into this load, a 1.3V differential noise margin is supported along with the standard common mode rejection range of the receivers.

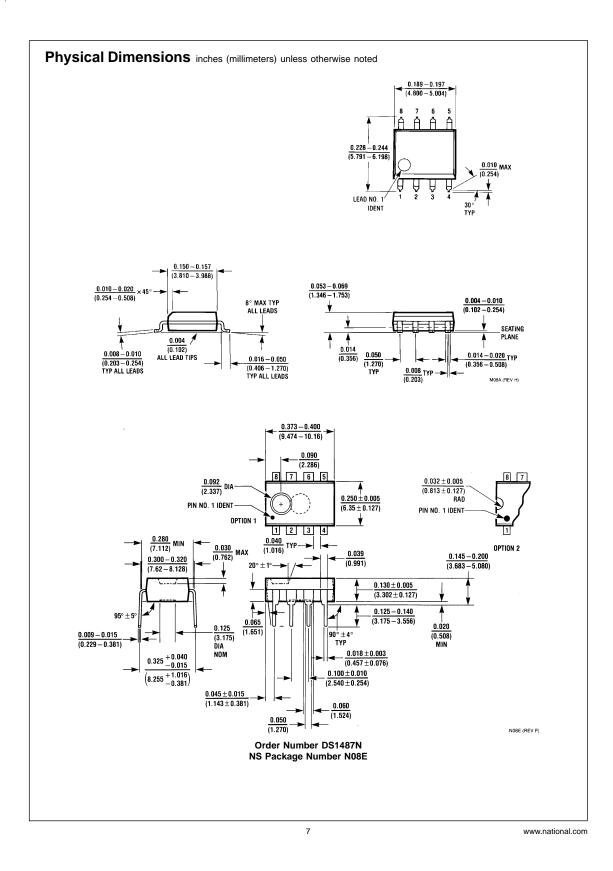
#### Applications Information (Continued)

Due to the multipoint nature of the bus, contention between drivers may occur. This will not cause damage to the drivers since they feature short-circuit protection and also thermal shutdown protection. Thermal shutdown senses die temperature and puts the driver outputs into TRI-STATE if a fault condition occurs that causes excessive power dissipation which can elevate the junction temperature to +150°C.

A typical multipoint application is shown in the following figure. Note that termination is typically required but is only located at the two ends of the cable (not on every node). Commonly pull up and pull down resistors may be required at one end of the bus to provide a failsafe bias. These resistors provide a bias to the line when all drivers are in TRI-STATE. See National Application Note 847 for a complete discussion of failsafe biasing of differention buses.



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