



Genesys Logic, Inc.

GL848

High Speed USB 2.0 2-in-1 Scanner Controller With Fast ADF & Bus Power

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Revision History

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CHAPTER 1 GENERAL DESCRIPTION

Genesys Logic's single-chip GL848 (GeneScan™ series) is a high speed, high performance and rich scalability controller for scanner with fast ADF function and bus power. It successfully integrates scanner function ASIC and USB 2.0 interface controller into one single-chip. With its high performance design architecture, GL848 is not only ready for supporting CIS or CCD image sensors (600, 1200, 2400, 3200, 3600, 4800 and 9600dpi resolution) that are used in sheet-fed, flatbed or transparency scanners, but is able to co-work with unipolar or bipolar stepping motors. Advanced features of GL848 include five motor acceleration/ deceleration curve tables for high speed motor moving.



CHAPTER 2 FEATURES

- Highly integrated scanner controller chip (2-in-1; Scanner Controller and USB 2.0 Interface)
- USB 2.0 High Speed (480Mbit) compliant
- Designed for sheetfed, flatbed and transparency scanners
- Designed for self-power and bus-power application
- Embedded RISC CPU for USB protocol handling
- Support single AFE for dual head scanning
- 12MHz low frequency clock input for better EMI
- Adjustable working clock of scanner controller for different usage (12M, 24M, 30M, 40M, 48M, 60MHz)
- Supports linear or stagger CCD, such as NEC, Toshiba or Sony CCD
- Available sensor types: 600, 1200, 2400, 3200, 3600, 4800 and 9600 dpi color CIS or CCD
- Multi-TG control for CCD (separately controls the R/G/B exposure time)
- Shutter-control for CCD (separately controls the R/G/B exposure time)
- Supports two scanning types: pixel-by-pixel (pixel rate), line-by-line (line rate)
- Support 48-bits color, 16-bits gray and 1-bit line-art
- “True gray” with R, G and B weightings
- 16 bits white/dark shading and 16 bits Gamma correction
- Supports RS232 interface for special applications
- Supports EEPROM (93C46) interface for special applications
- Supports ADF (Auto-Document-Feeder) function with document, ADF and cover sensors
- Supports auto-ADF with automatically feeding in, automatically scanning and automatically feeding out
- Lines packing for stagger CCD or R/G/B line differences
- Fine CDS sampling adjustment to avoid the digital noise influence (8.33ns adjustment)
- Digital average and hardware deletion for various resolutions
- Hardware deletion for various resolutions (from 9600~1dpi with 1dpi decrement)
- Supports 1M*16, 4M*16, 8M*16, 16M*16 and 32M*16 SDRAM
- Supports up to 1 G bits size SDRAM (implements two SDRAM)
- Supports 5 acceleration/deceleration motor tables for high speed motor moving and wall hitting protection
- Supports controllable bipolar motor in full, half, quarter and eighth steps moving
- Supports controllable unipolar motor in full and half steps moving
- Supports V-reference automatic control for motor driver Ics
- Build-in PWM control phase for unipolar motors
- Programmable dummy lines to resolve start/stop (discontinuous) problem
- Watchdog protection for lamp, motor and ASIC
- Lamp time-out (sleeping) control
- Supports 21 GPIO pins and 5 GPO pins for I/O control



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- Supports PWM outputs for flatbed/transparency lamp control with programmable duties and frequencies
- Supports LED blinking
- Supports back-scanning
- Supports multi-film scanning

CHAPTER 3 PIN ASSIGNMENT

3.1 Pinouts

Figure 3.1 – 128 Pin QFP Pinout Diagram





3.2 Pin List

Table 3.1 – 128 Pin List

Pin#	Pin Name	Type	Pin#	Pin Name	Type	Pin#	Pin Name	Type	Pin#	Pin Name	Type
1	DBUS15	I/O	33	ABUS2	O	65	OP7	I	97	GPIO8	I/O
2	DBUS14	I/O	34	ABUS1	O	66	OP6	I	98	GPIO9	I/O
3	DBUS13	I/O	35	ABUS0	O	67	OP5	I	99	GPIO10	I/O
4	DBUS12	I/O	36	CS1	O	68	OP4	I	100	GPIO11	I/O
5	DBUS11	I/O	37	CS0	O	69	OP3	I	101	GPIO13	I/O
6	DBUS10	I/O	38	RASJ	O	70	OP2	I	102	GPIO12	I/O
7	DBUS9	I/O	39	WEJ	O	71	OP1	I	103	VccIO6	I/O
8	DBUS8	I/O	40	CASJ	O	72	OP0	I	104	GndIO6	I/O
9	VccIO1	P	41	BANK0	O	73	VccIO5	P	105	GPIO14	P
10	GndIO1	P	42	BANK1	O	74	GndIO5	P	106	GPIO15	P
11	DBUS7	I/O	43	CKE	O	75	MCLK	O	107	GPIO16	I/O
12	DBUS6	I/O	44	DRAMCLK	O	76	BSMP	O	108	GPIO17	I/O
13	DBUS5	I/O	45	VccIO3	P	77	VSMP	O	109	GPIO18	I/O
14	DBUS4	I/O	46	GndIO3	P	78	SCLK	O	110	GPIO19	I/O
15	DBUS3	I/O	47	ADF_SENR	I/O	79	SEN	O	111	GPIO20	I/O
16	DBUS2	I/O	48	HOME	I	80	SDI	O	112	GPIO21	I/O
17	DBUS1	I/O	49	LED_B	O	81	SDO	O	113	VccCore4	I/O
18	DBUS0	I/O	50	XPA_SW	O	82	MT_PH0	O	114	GndCore4	I/O
19	VccCore1	P	51	VccCore2	P	83	MT_PH1	O	115	EXTRST_	P
20	GndCore1	P	52	GndCore2	P	84	MT_PH2	O	116	X1	P
21	ABUS12	O	53	LAMP_SW	O	85	VccCore3	P	117	X2	O
22	ABUS11	O	54	CCD_TGB	O	86	GndCore3	P	118	DVCC1	I
23	ABUS10	O	55	CCD_TGG	O	87	MT_PH3	O	119	DGND2	O
24	ABUS9	O	56	VccIO4	P	88	MT_PH4	O	120	VBUS	P
25	ABUS8	O	57	GndIO4	P	89	MT_PH5	O	121	AGND3	P
26	ABUS7	O	58	CCD_CK4X	O	90	GPIO1	O	122	AVDD3	P
27	ABUS6	O	59	CCD_CK2X	O	91	GPIO2	O	123	DM	P
28	VccIO2	P	60	CCD_RSX	O	92	GPIO3	I/O	124	DP	I/O
29	GndIO2	P	61	CCD_CK3X	O	93	GPIO4	I/O	125	AGND2	I/O
30	ABUS5	O	62	CCD_CPX	O	94	GPIO5	I/O	126	RREF	P
31	ABUS4	O	63	CCD_CK1X	O	95	GPIO6	I/O	127	AVDD1	I/O
32	ABUS3	O	64	CCD_TGX	O	96	GPIO7	I/O	128	AVDD2	P

3.3 Pin Descriptions

Table 3.3 - Pin Descriptions

Pin Name	Type	Description
GPIO1 (Hot Key)	B	General Purpose Input/Output (as a hot key).
GPIO2 (Hot Key)	B	General Purpose Input/Output (as a hot key).
GPIO3 (Hot Key)	B	General Purpose Input/Output (as a hot key);
GPIO4 (Hot Key)	B	General Purpose Input/Output (as a hot key);
GPIO5 (Hot Key)/ROM_D	B	General Purpose Input/Output (as a hot key); EEPROM (93C46) serial data input/output DI/DO;
GPIO6/TXD/MOTORTGO/ROM_SK	B	General Purpose Input/Output; RS232 transmit data output; Output motor trigger for ADF scanning; EEPROM (93C46) serial data clock.
GPIO7/ROM_CS	B	General Purpose Input/Output; EEPROM (93C46) chip select.
GPIO8/ICG1/LEDBLINK/SH_ENB	B	General Purpose Input/Output; CCD shutter control ICG1; LED control with Blinking function; Output SH_ENB for external CPLD.
GPIO9/VREF3/SW1/LEDBLINK/SH_ENBX	B	General Purpose Input/Output; Vref3 control for motor driver IC Imax; SW1 output for special CCD application; LED control with Blinking function; Output SH_ENBX for external CPLD.
GPIO10/SW2/LEDBLINK /CCD_SW2	B	General Purpose Input/Output; SW2 output for special CCD application; LED control with Blinking function; CCD SW2 control for special CCD application.
GPIO11/VREF0	B	General Purpose Input/Output; Vref0 control for motor driver IC Imax;
GPIO12/VREF1	B	General Purpose Input/Output; Vref1 control for motor driver IC Imax.
GPIO13/VREF2	B	General Purpose Input/Output; Vref2 control for motor driver IC Imax.
GPIO14/CCD_CNT0	B	General Purpose Input/Output;



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		Output CCD_CNT0 for external CPLD.
GPIO15/CCD_SW5/CCD_CNT1	B	General Purpose Input/Output; CCD SW5 control for special CCD application; Output CCD_CNT1 for external CPLD.
GPIO16/COVERSNR	B	General Purpose Input/Output; Cover sensor for ADF
GPIO17	B	General Purpose Input/Output.
GPIO18	B	General Purpose Input/Output.
GPIO19	B	General Purpose Input/Output.
GPIO20	B	General Purpose Input/Output.
GPIO21/LEDBLINK	B	General Purpose Input/Output; LED control with Blinking function.
ADF_SENR	B	ADF sensor for ADF operation.
MT_PH0-5	O	<p>Bi-polar (3967):</p> <p style="padding-left: 40px;">MT_PH5=RESETJ</p> <p style="padding-left: 40px;">MT_PH4=ENABLEJ</p> <p style="padding-left: 40px;">MT_PH3=DIR</p> <p style="padding-left: 40px;">MT_PH2=STEP</p> <p style="padding-left: 40px;">MT_PH1=MS2</p> <p style="padding-left: 40px;">MT_PH0=MS1</p> <p>Bi-polar(1939):</p> <p style="padding-left: 40px;">MT_PH3=IN1</p> <p style="padding-left: 40px;">MT_PH2=IN2</p> <p style="padding-left: 40px;">MT_PH1=ENA1</p> <p style="padding-left: 40px;">MT_PH0=ENA2</p> <p style="padding-left: 40px;">MT_PH5=GPO34</p> <p>Bi-polar (2916 or 6219):</p> <p style="padding-left: 40px;">MT_PH5=PHASE1</p> <p style="padding-left: 40px;">MT_PH4=PHASE2</p> <p style="padding-left: 40px;">MT_PH3=I11</p> <p style="padding-left: 40px;">MT_PH2=I01</p> <p style="padding-left: 40px;">MT_PH1=I12</p> <p style="padding-left: 40px;">MT_PH0=I02</p> <p>Uni-polar(2003):</p> <p style="padding-left: 40px;">MT_PH3=PHASE A</p> <p style="padding-left: 40px;">MT_PH2=PHASE B</p> <p style="padding-left: 40px;">MT_PH1=PHASE / A</p> <p style="padding-left: 40px;">MT_PH0=PHASE /B</p>
BSMP/CDSCLK1/GPO31	O	Video sample synchronization pulse for Wolfson AFE or CDS



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		Reference level sampling clock for Analog Device AFE; General Purpose Output.
HOME/DOC_SENR	I	Document sensor for ADF operation; Home sensor for flatbed operation.
CCD_CK1X	O	CCD Shift register clock1 or CIS clock output.
CCD_CPX/GPO32	O	CCD Clamp gate clock or CIS clock output; General Purpose Output.
CCD_TGX/TSTSEL0	B	When power-on initiates the scanner, this pin is used as mode-select pin. Normally, it is for CCD Transfer gate clock for R channel or CIS Line start pulse.
CCD_CK2X/TSTSEL1		When power-on initiates the scanner, this pin is used as mode-select pin. Normally, it is for CCD Shift register clock2 or CIS clock output.
CCD_RSX/TSTSEL2		When power-on initiates the scanner, this pin is used as mode-select pin. Normally, it is for CCD Reset gate clock or CIS clock output.
CCD_CK3X/TSTSEL3		When power-on initiates the scanner, this pin is used as mode-select pin. Normally, it is for CCD Shift register clock3. Normal mode is TSTSEL[3:0] = 4'b0000
CCD_CK4X/GPO33/MTR_SEL0	B	When power-on initiates the scanner, this pin is used as motor-select pin. Normally, it is for CCD Shift register clock4, or General Purpose Output.
CCD_TGG/MTR_SEL1		When power-on initiates the scanner, this pin is used as motor-select pin. Normally, it is for CCD Transfer gate clock of G channel.
CCD_TGB/MTR_SEL2		When power-on initiates the scanner, this pin is used as motor-select pin. Normally, it is for CCD Transfer gate clock of B channel. MTR_SEL[2:0]=111 select Phase Table to output any timing MTR_SEL[2:0]=100 select 3967 MTR_SEL[2:0]=011 select LB1939T/LB1940T MTR_SEL[2:0]=001 select Bi_polar 2916 or 6219 MTR_SEL[2:0]=000 select Uni_polar 2003
LAMP_SW/LED_R	O	Flatbed lamp power control; CIS Red LED array control
XPA_SW/LED_G	O	Transparency lamp power control;



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		CIS Green LED array control
LED_B/ RXD /MOTORDIR/GPO28	O	CIS Blue LED control; RS232 receive data input; Motor direction control for moving TMA or ADF application; General Purpose Input/Output.
OP0~7	I	AFE digital data input.
SEN/SLOAD	O	Serial interface load pulse.
SCLK	O	Serial interface clock output.
SDI	O	Serial data output.
SDO	I	Serial data input.
VSMP/CDSCLK2	O	Wolfson type : Video sample synchronization pulse. Analog Device : CDS Data level sampling clock.
MCLK/ADCCLK	O	Wolfson type : Master clock. Analog Device : A/D Converter sampling clock.
DBUS0~15	B	DRAM data bus
ABUS0~12	O	DRAM address bus
RASJ	O	SDRAM row address strobe
CASJ	O	SDRAM column address strobe
WEJ	O	SDRAM write enable
BANK0-1	O	SDRAM bank select
CKE	O	SDRAM clock enable
RAMCLK	O	SDRAM clock
X1	I	Clock input for crystal (12MHz)
X2	O	Clock output for crystal
EXTRST_	I	Hardware reset input
AVDD1, AVDD2, AVDD3	P	Analog power input for USB2.0 transceiver 3.3V
AGND1, AGND2, AGND3	P	Analog ground input for USB2.0 transceiver
DVCC1	P	Digital power input for USB2.0 controller 1.8V
DGND1, DGND2	P	Digital ground input for USB2.0 controller.
VccCore1, VccCore2, VccCore3, VccCore4	P	Digital power input for scanner controller logic core 1.8V
GndCore1, GndCore2, GndCore3, GndCore4	P	Digital ground input for scanner controller logic core.
VccIO1, VccIO2, VccIO3, VccIO4, VccIO5, VccIO6	P	Digital power input for scanner controller I/O pads 3.3V
GndIO1, GndIO2, GndIO3, GndIO4, GndIO5, GndIO6	P	Digital ground input for scanner controller I/O pads.



GL848 High Speed USB2.0 2-in-1 Scanner Controller With Fast ADF

DP	B	Positive USB differential data
DM	B	Negative USB Differential Data
RREF	B	715 Ohm 1% reference resistor input which should be tied to analog ground
VBUS	F	Floating
FSHD0-7	B	Flash data bus
FSHA0-14	O	Flash address bus
FSH_WEB	O	Flash write enable
FSH_OEB	O	Flash data output enable

Notation:

Type	O	Output
	I	Input
	B	Bi-directional
	I/O	Bi-directional
	P	Power / Ground
	F	Floating

CHAPTER 4 REGISTERS

4.1 Registers Base Address

Table 4.1 - Base Address for Registers

Offset	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
01h	CISSET	DOGENB	DVDSET	STAGGER	X	TRUEGRAY	SHDAREA	SCAN	8'h00
02h	NOTHOME	ACDCDIS	AGOHOME	MTRPWR	FASTFED	MTRREV	HOMENEG	LONGCURV	8'h00
03h	LAMPDOG	AVEENB	XPASEL	LAMPPWR	LAMPTIM[3:0]				8'h8F
04h	LINEART	BITSET	AFEMOD[1:0]		FILTER[1:0]		FESET[1:0]		8'h00
05h	DPIHW[1:0]		MTLLAMP[1:0]		GMMENB	ENB20M	MTLBASE[1:0]		8'h40
06h	SCANMOD[2:0]			PWRBIT	GAIN4	OPTTEST[2:0]			8'h00
07h	LAMPSIM	RESERVE[6:0]							8'h00
08h	DRAM2X	SCNUMENB	MPENB	CIS_LINE	X	X	X	ENB24M	8'h00
09h	MCNTSET[1:0]		EVEN1ST	BLINE1ST	BACKSCAN	X	SHORTTG	X	8'h00
0Ah	X	X	ADFSEL	LPWMEN	X	RS232SEL	BAUDRAT[1:0]		8'h00
0Bh	CLKSET[2:0]			RFHDIS	ENBDRAM	DRAMSEL[2:0]			8'h01
0Ch	X	X	X	X	CCDLMT[3:0]				8'h00
0Dh	X	X	X	FULLSTP	SEND	CLRMCNT	CLRDOCJM	CLRLNCNT	-
0Eh	SCANRESET								-
0Fh	MOVE								-
10h	EXPR[15:8]								8'h00
11h	EXPR[7:0]								8'h00
12h	EXPG[15:0]								8'h00
13h	EXPG[7:0]								8'h00
14h	EXPB[15:8]								8'h00
15h	EXPB[7:0]								8'h00
16h	CTRLHI	TOSHIBA	TGINV	CK1INV	CK2INV	CTRLINV	CKDIS	CTRLDIS	8'h33
17h	TGMODE[1:0]		TGW[5:0]						8'h14
18h	CNSET	DCKSEL[1:0]		CKTOGGLE	CKDELAY[1:0]		CKSEL[1:0]		8'h10
19h	EXPDMY[7:0]								8'h00
1Ah	SW2SET	SW1SET	MANUAL3	MANUAL1	CK4INV	CK3INV	LINECLP	X	8'h10
1Bh	GRAY2C	SEL12C	BGRENB	ICGENB	ICGDLY[3:0]				8'h00
1Ch	CK4MTGL	CK3MTGL	CK1MTGL	CKAREA	MTLWD	TGTIME[2:0]			8'h00
1Dh	CK4LOW	CK3LOW	CK1LOW	TGSGLD[4:0]					8'h04
1Eh	WDTIME[3:0]				LINESEL[3:0]				8'h80
1Fh	SCANFED[7:0]								8'h00
20h	BUFSEL[7:0]								8'h00
21h	STEPNO[7:0]								8'h00
22h	FWDSTEP[7:0]								8'h00
23h	BWDSTEP[7:0]								8'h00
24h	FASTNO[7:0]								8'h00
25h	X	X	X	X	LINCNT[19:16]				8'h08
26h	LINCNT[15:8]								8'h00
27h	LINCNT[7:0]								8'h00
2Ch	X	X	DPISET[13:8]					8'h00	



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2Dh	DPISET[7:0]								8'h00	
2Eh	BWHI[7:0]								8'h00	
2Fh	BWLOW[7:0]								8'h00	
30h	STRPIXEL[15:8]								8'h00	
31h	STRPIXEL[7:0]								8'h00	
32h	ENDPIXEL[15:8]								8'h00	
33h	ENDPIXEL[7:0]								8'h00	
34h	DUMMY[7:0]								8'h00	
35h	MAXWD[25:18]								8'h00	
36h	MAXWD[17:10]								8'h00	
37h	MAXWD[9:2]								8'h00	
38h	LPERIOD[15:8]								8'h2A	
39h	LPERIOD[7:0]								8'h30	
3Ah	X	X	X	X	X	X	X	FEWRDATA[8]	8'h00	
3Bh	FEWRDATA[7:0]								8'h00	
3Dh	X	X	X	X	FEEDL[19:16]				8'h00	
3Eh	FEEDL[15:8]								8'h37	
3Fh	FEEDL[7:0]								8'h00	
40h	DOCSNR	ADFSNR	COVERSNR	CHKVER	DOCJAM	HISPDFLG	MOTMFLG	DATAENB	-	
41h	PWRBIT	BUFEMPTY	FEEDFSH	SCANFSH	HOMESNR	LAMPSTS	FEBUSY	MOTORENB	-	
42h	X	X	X	X	X	X	VALIDWORD[25:24]		8'h00	
43h	VALIDWORD[23:16]								8'h00	
44h	VALIDWORD[15:8]								8'h00	
45h	VALIDWORD[7:0]								8'h00	
46h	X	X	X	X	X	X	X	FERDDATA[8]	-	
47h	FERDDATA[7:0]								-	
48h	X	X	X	FEDCNT[20:16]						8'h00
49h	FEDCNT[15:8]								8'h00	
4Ah	FEDCNT[7:0]								8'h00	
4Bh	X	X	X	X	SCANCNT[19:16]					8'h00
4Ch	SCANCNT[15:8]								8'h00	
4Dh	SCANCNT[7:0]								8'h00	
4Fh	X	X	DOGON	X	X	TX232BSY	RX232BSY	RXREADY	8'h00	
50h	X	X	FERDA[5:0]							8'h00
51h	X	X	FEWRA[5:0]							8'h00
52h	X	X	X	RHI[4:0]						8'h00
53h	X	X	X	RLOW[4:0]						8'h00
54h	X	X	X	GHI[4:0]						8'h00
55h	X	X	X	GLOW[4:0]						8'h00
56h	X	X	X	BHI[4:0]						8'h00
57h	X	X	X	BLOW[4:0]						8'h00
58h	VSMP[4:0]				VSMPW[2:0]				8'h00	
59h	BSMP[4:0]				BSMPW[2:0]				8'h00	
5Ah	ADCLKINV	RLCSEL	CDSREF[1:0]		RLC[3:0]				8'h00	
5Dh	HISPD[7:0]								8'h00	
5Eh	DECSEL[2:0]			STOPTIM[4:0]						8'hA4
5Fh	FMOVDEC[7:0]								8'h00	



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60h	STEPSEL[2:0]			Z1MOD[20:16]					8'h20
61h	Z1MOD[15:8]								8'h00
62h	Z1MOD[7:0]								8'h00
63h	FSTPSEL[2:0]			Z2MOD[20:16]					8'h00
64h	Z2MOD[15:8]								8'h00
65h	Z2MOD[7:0]								8'h00
66h	PHFREQ[7:0]								8'h00
67h	X	X	MTRPWM[5:0]					8'h3F	
68h	X	X	FASTPWM[5:0]					8'h3F	
69h	FSHDEC[7:0]								8'h00
6Ah	FMOVNO[7:0]								8'h00
6Bh	MULTFILM	GPOM13	GPOM12	GPOM11	GPOCK4	GOPCP	GPOLEDB	GPOADF	8'h00
6Ch	GPIO16	GPIO15	GPIO14	GPIO13	GPIO12	GPIO11	GPIO10	GPIO9	8'h00
6Dh	GPIO8	GPIO7	GPOI6	GPIO5	GPIO4	GPIO3	GPIO2	GPIO1	8'h00
6Eh	GPOE16	GPOE15	GPOE14	GPOE13	GPOE12	GPOE11	GPOE10	GPOE9	8'h00
6Fh	GPOE8	GPOE7	GPOE6	GPOE5	GPOE4	GPOE3	GPOE2	GPOE1	8'h00
70h	X	X	X	RSH[4:0]				8'h06	
71h	X	X	X	RSL[4:0]				8'h08	
72h	X	X	X	CPH[4:0]				8'h08	
73h	X	X	X	CPL[4:0]				8'h0A	
74h	X	X	X	X	X	X	CK1MAP[17:16]		8'h00
75h	CK1MAP[15:8]								8'h00
76h	CK1MAP[7:0]								8'h00
77h	X	X	X	X	X	X	CK3MAP[17:16]		8'h00
78h	CK3MAP[15:8]								8'h00
79h	CK3MAP[7:0]								8'h00
7Ah	X	X	X	X	X	X	CK4MAP[17:16]		8'h00
7Bh	CK4MAP[15:8]								8'h00
7Ch	CK4MAP[7:0]								8'h00
7Dh	CK1NEG	CK3NEG	CK4NEG	RSNEG	CPNEG	BSMPNEG	VSMPNEG	DLYSET	8'h00
7Eh	GPOLED25	GPOLED24	GPOLED23	GPOLED22	GPOLED21	GPOLED10	GPOLED9	GPOLED8	8'h00
7Fh	BSMPDLY[1:0]		VSMPDLY[1:0]		LEDCNT[3:0]				8'h00
80h	VRHOME[1:0]		VRMOVE[1:0]		VRBACK[1:0]		VRSCAN[1:0]		8'h00
81h	X	X	X	X	X	X	X	ROFFSET[8]	8'h00
82h	ROFFSET[7:0]								8'h00
83h	X	X	X	X	X	X	X	GOFFSET[8]	8'h00
84h	GOFFSET[7:0]								8'h00
85h	X	X	X	X	X	X	X	BOFFSET[8]	8'h00
86h	BOFFSET[7:0]								8'h00
87h	LED4TG	YENB	YBIT	ACYCNRLC	ENOFFSET	LEDADD	CK4ADC	AUTOCONF	8'h00
88h	X	X	X	RDNUM[4:0]					8'h00
89h	RS232WD[7:0]								8'h00
8Ah	RS232RD[7:0]								-
8Fh	X	X	X	X	PREFED[19:16]				8'h00
90h	PREFED[15:8]								8'h00
91h	PREFED[7:0]								8'h00



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92h	PSTFED[15:8]								8'h00
93h	PSTFED[7:0]								8'h00
94h	MTRPLS [7:0]								8'h1F
95h	X	X	X	X	SCANLEN[19:16]			8'h00	
96h	SCANLEN[15:8]								8'h00
97h	SCANLEN[7:0]								8'h00
98h	ONDUR[15:8]								8'h00
99h	ONDUR[7:0]								8'h00
9Ah	OFFDUR[15:8]								8'h00
9Bh	OFFDUR[7:0]								8'h00
9Dh	RAMDLY[1:0]	MOTLAG	X	STEPTIM[2:0]			X	8'h00	
9Eh	X	X	TGSTIME[2:0]			TGWTIME[2:0]			8'h00
9Fh	X	X	X	FULLPAGE	AUTOADF	MOTMPU	MULDMYLN	DPI9600	8'h00
A0h	X	X	LNOFSET[5:0]					8'h00	
A1h	SNRSYN[2:0]			STGSET[4:0]				8'h80	
A2h	X	X	X	RFHSET[4:0]				8'h00	
A3h	TRUER[7:0]								8'h00
A4h	TRUEG[7:0]								8'h00
A5h	TRUEB[7:0]								8'h00
A6h	X	X	X	GPIO21	GPIO20	GPIO19	GPIO18	GPIO17	8'h00
A7h	X	X	X	GPOE21	GPOE20	GPOE19	GPOE18	GPOE17	8'h00
A8h	X	X	ADFSNRDIS	X	X	X	X	X	8'h00
A9h	X	GPO34	GPO33	GPO32	GPO31	X	X	GPO28	8'h00
AAh	RESERVE[7:0]								8'h00
ABh	GPOM9	MULSTOP[2:0]			NODECEL	TB3TB1	TB5TB2	FIX16CLK	8'h00
ACh	VRHOME3	VRHOME2	VRMOME3	VRMOME2	VRBACK3	VRBACK2	VRSCAN3	VRSCAN2	8'h00
ADh	X	X	X	SWSH[4:0]				8'h00	
A Eh	X	X	STOPPWM[5:0]					8'h3F	
B8h	X	X	X	X	SW2_EN	SW2_SEL	X	X	8'h00
BAh	CCD_OUT	AV_EN							8'h00
BBh	X	X	MT_OFF [13:8]					8'h00	
BCh	MT_OFF [7:0]								8'hFF
BDh	SW5_EN	SW5_SEL	SW5EXCHG	X	X	BGMM_N	GGMM_N	RGMM_N	8'h1F
BEh	SW2INV	X	SW5INV	X	X	BGMM_F	GGMM_F	RGMM_F	8'h00
BFh	X	X	SC_NUM[5:0]					-	
C5h	RGMM_Z[15:8]								8'h00
C6h	RGMM_Z[7:0]								8'h00
C7h	GGMM_Z[15:8]								8'h00
C8h	GGMM_Z[7:0]								8'h00
C9h	BGMM_Z[15:8]								8'h00
CAh	BGMM_Z[7:0]								8'h00
D0h	SH0DWN[7:0]								8'h00
D1h	SH1DWN[7:0]								8'h00
D2h	SH2DWN[7:0]								8'h00
D3h	SH3DWN[7:0]								8'h00
D4h	SH4DWN[7:0]								8'h00
D5h	SH5DWN[7:0]								8'h00



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D6h	SH6DWN[7:0]								8'h00
D7h	SH7DWN[7:0]								8'h00
D8h	SH8DWN[7:0]								8'h00
D9h	SH9DWN[7:0]								8'h00
DAh	PROTLN[15:8]								8'h00
DBh	PROTLN[7:0]								8'h00
DCh	X	X	X	X	X	X	X	X	8'h00
DDh	X	X	X	X	X	X	X	X	8'h00
E0h	R1DWN[15:8]								8'h00
E1h	R1DWN[7:0]								8'h00
E2h	R1UP[15:8]								8'h00
E3h	R1UP[7:0]								8'h00
E4h	R2DWN[15:8]								8'h00
E5h	R2DWN[7:0]								8'h00
E6h	R2UP[15:8]								8'h00
E7h	R2UP[7:0]								8'h00
E8h	G1DWN[15:8]								8'h00
E9h	G1DWN[7:0]								8'h00
EAh	G1UP[15:8]								8'h00
EBh	G1UP[7:0]								8'h00
ECh	G2DWN[15:8]								8'h00
EDh	G2DWN[7:0]								8'h00
EEh	G2UP[15:8]								8'h00
EFh	G2UP[7:0]								8'h00
F0h	B1DWN[15:8]								8'h00
F1h	B1DWN[7:0]								8'h00
F2h	B1UP[15:8]								8'h00
F3h	B1UP[7:0]								8'h00
F4h	B2DWN[15:8]								8'h00
F5h	B2DWN[7:0]								8'h00
F6h	B2UP[15:8]								8'h00
F7h	B2UP[7:0]								8'h00
F8h	MAXSEL[3:0]				MINSEL[3:0]				-
FDh	MAINTSK[3:0]				SUBTSK[3:0]				-
FEh	MOTTGST[3:0]				AUTO_O[3:0]				-
FFh	AUTO_S[7:0]								8'h00

Notation:

R/W	Read / Write
R/O	Read Only
W/O	Write Only
R/WIC	Readable and Write-1-Clear
R/W/C	Read / Write and hardware automatic Clear
X	Don't care and should be wrote by logic "0"



4.2 Register Descriptions

Offset 01h

CISSET	DOGENB	DVDSET	STAGGER	X	TRUEGRAY	SHDAREA	SCAN
R/W	R/W	R/W	R/W	X	R/W	R/W	R/W

- 7 CISSET** 0 CCD scan type.
 1 CIS scan type.
- 6 DOGENB** 0 Disable watchdog function.
 1 Enable watchdog function (set time out duration in Reg1E[7:4]).
- 5 DVDSET** 0 Disable shading function.
 1 Enable shading function (include whole line shading and area shading).
- 4 STAGGER** 1 Enable double shading.
 0 Disable double shading.
- 3 Reserved**
- 2 TRUEGRAY** 0 Disable true gray function.
 1 Enable true gray function. The weightings are stored in Reg A3,A4 and A5.
- 1 SHDAREA** 0 Select whole-line shading.
 1 Select area-shading (depend on scan area and scan dpi).
- 0 SCAN** 0 Disable scanning process.
 1 Enable scanning process.

Offset 02h

NOTHOME	ACDCDIS	AGOHOME	MTRPWR	FASTFED	MTRREV	HOMENEG	LONGCURV
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 NOTHOME** 0 In auto-go-home function, carriage will not stop until touching the home sensor.
 1 In auto-go-home function, moving steps of carriage depends on steps setting from software (Reg 3D, 3E and 3F).
- 6 ACDCDIS** 0 Enable carriage backtracking when image buffer is full.
 1 Disable carriage backtracking when image buffer is full.
- 5 AGOHOME** 0 Disable auto-go-home function.
 1 Enable auto-go-home function. It's for carriage to go home automatically after scanning finished.
- 4 MTRPWR** 0 Turn off MOTOR power and phase to idle state.
 1 Turn on MOTOR power and phase.
- 3 FASTFED** 0 Move to scanning window by only one acceleration/deceleration tables.
 1 Move to scanning window by two acceleration/deceleration tables.
- 2 MTRREV** 0 Set motor to move in forward direction.
 1 Set motor to move in reverse direction.
- 1 HOMENEG** 0 Motor will be decelerated when home sensor input (HOME) changes from low to high (rising edge).
 1 Motor will be decelerated when home sensor input (HOME) changes from high to low (falling edge).
- 0 LONGCURV** 0 The deceleration curve of the fast moving is defined in table 4 or use default curve.
 1 The deceleration curve of the fast moving is defined in table 5 to protect wall-hitting.

Offset 03h Default value = 8'h94



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LAMPDOG	AVEENB	XPASEL	LAMPPWR	LAMPTIM3	LAMPTIM2	LAMPTIM1	LAMPTIM0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 LAMPDOG** 0 To disable sleep mode of lamp.
 1 To start sleep mode of lamp (default on).
- 6 AVEENB** 0 Select dpi deletion function
 1 Select dpi average function.
- 5 XPASEL** 0 Select flatbed lamp on.
 1 Select transparency lamp on.
- 4 LAMPPWR** 0 Turn off LAMP power.
 1 Turn on LAMP power.

3-0 LAMPTIM [3:0] Counter of the sleep mode of lamp (default: 4).
 The unit is minute.

Offset 04h Default value = 8'h00

LINEART	BITSET	AFEMOD1	AFEMOD0	FILTER1	FILTER0	FESET1	FESET0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 LINEART** 0 Color/Gray scanning.
 1 Black/White scanning.
- 6 BITSET** 0 8 bits image data type (= byte).
 1 16 bits image data type (= word).

5-4 AFEMOD [1:0] AFE operation mode.

Wolfson Type					
AFEMOD	SCANMOD	Description	CDS Available	Max Sample Rate	Timing Requirements
2	0,1,7	Slow color Pixel-by-pixel	Yes	5MSPS *3 channel	MCLK:VSMP Rate is 8:1
1	0,1,6,7	Color pixel-by-pixel	Yes	6.67MSPS *3 channel	MCLK:VSMP Rate is 6:1
0	0,1,4,5,6	Fast Mono	Yes	13.3MSPS *1 channel	MCLK:VSMP Rate is 3:1
Analog Device Type					
AFEMOD	SCANMOD	Description	CDS Available	Max Sample Rate	Timing Requirements
2	0,1,6,7	Slow color Pixel-by-pixel	Yes		MCLK:VSMP Rate is 3:1
1	0,1,6,7	Mono	Yes		MCLK:VSMP Rate is 2:1
0	0,1,6,7	Fast Mono	Yes		MCLK:VSMP Rate is 1:1

3-2 FILTER [1:0] Scan color type:
 00 Color
 01 R
 10 G
 11 B

1-0 FESET [1:0] Front end operation type:
 00 Wolfson type 1
 01 Wolfson type2



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- 10 ADI type
- 11 Reserved

Offset 05h Default value = 8'h00

DPIHW1	DPIHW0	MTLLAMP1	MTLLAMP0	GMMENB	ENB20M	MTLBASE1	MTLBASE0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-6 DPIHW [1:0]** To set CCD/CIS resolution.
 - 00 600 dpi
 - 01 1200 dpi
 - 10 2400 dpi
 - 11 4800 dpi
- 5-4 MTLLAMP [1:0]** Multiply coefficient for time-out counter of lamp.
 - 00 1* LAMPTIM
 - 01 2* LAMPTIM
 - 10 4* LAMPTIM
 - 11 Reserved
- 3 GMMENB** 0 Disable gamma correction.
1 Enable gamma correction.
- 2 ENB20M** 0 CCD_CK1X output clocks according to designer's settings .
1 CCD_CK1X generate 20MHz clock to CCD or CIS sensors.
- 1-0 MTLBASE [1:0]** To set output CCD pixel number under each system pixel time.
 - 00 1 CCD pixel/sstem pixel time.
 - 01 2 CCD pixel/sstem pixel time.
 - 10 3 CCD pixel/sstem pixel time.
 - 11 4 CCD pixel/sstem pixel time.

Offset 06h Default value = 8'h00

SCANMOD2	SCANMOD1	SCANMOD0	PWRBIT	GAIN4	OPTTEST2	OPTTEST1	OPTTEST0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-5 SCANMOD [2:0]** To set operation mode.
 - 000 12 clocks/pixel ; normal mode operation for scanning.
 - Color scanning : 24 bits image with gamma correction
 - Gray scanning : 8 bits image with gamma correction
16 bits image without gamma correction
 - Line art scanning : 1 bit image with gamma correction
 - 001 12 clocks/pixel ; bypass mode operation for calibration.
Include color(pixel rate) , gray line-art.
 - 010 8 clocks/pixel ; fast mode operation for scanning
 - Color scanning : 24 or 48 bits image with gamma correction for CIS
 - Gray scanning : 8 or 16 bits image with gamma correction for CIS or
CCD scanning.
 - 011 Reserved
 - 100 Reserved
 - 101 Reserved
 - 110 18 clocks/pixel.
 - Color scanning : 24 bits image with gamma correction
48 bits image without gamma correction
 - Gray scanning : 8 bits image with gamma correction
16 bits image without gamma correction
 - Line art scanning : 1 bit image with gamma correction
 - 111 16 clocks/pixel.



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- Color scanning : 24 bits image with gamma correction
48 bits image without gamma correction
- Gray scanning : 8 bits image with gamma correction
16 bits image without gamma correction
- Line art scanning : 1 bit image with gamma correction

- 4 PWRBIT** The hardware will reset this bit during power-on initial process. It can be set and checked by S/W to know if the power had been turned off or not.
Default is reset.
- 3 GAIN4**
 - 0 Digital shading gain=8 times system.
 - 1 Digital shading gain=4 times system.
 Note: If you want to get more precise image quality, you can set GAIN4 bit.
- 2-0 OPTTEST [2:0]** Select ASIC operation type.
 - 000 Set normal mode to capture AFE image.
 - 001 Set SDRAM bank testing and power-on moving testing for ASIC simulation
 - 010 Pixel count pattern for ASIC image test.
 - 011 Line count pattern for ASIC image test.
 - 100 Counter and adder test for ASIC simulation test.
 - 101 Reserved.
 - 110 Reserved.
 - 111 Reserved.

Offset 07h Default value = 8'h00

LAMPSIM	RESERVE6	RESERVE5	RESERVE4	RESERVE3	RESERVE2	RESERVE1	RESERVE0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 LAMPSIM** for timer simulation
- 6-0 RESERVE [6:0]** These bits are reserved for special application

Note: Please do not write other values than 00H into this register under normal condition.

Offset 08h Default value = 8'h00

DRAM2X	SCNUMENB	MPENB	CIS_LINE	X	X	X	ENB24M
R/W	R/W	R/W	R/W	X	X	X	R/W

- 7 DRAM2X**
 - 0 Select single chip of SDRAM
 - 1 Enable two chips of SDRAM
- 6 SCNUMENB** Enable page count which is stored in memory for ADF operation
- 5 MPENB** Enable motor phase generating function which is stored in memory
- 4 CIS_LINE** Set CIS_LINE to "1" and set CISSET to "1" at the same time to enable CIS scanning, and work on line by line mode.
- 0 ENB24M**
 - 0 Disable 24MHz CCD/CIS Clock output
 - 1 Enable 24MHz CCD/CIS Clock output

Offset 09h Default value = 8'h00

MCNTSET1	MCNTSET0	EVEN1ST	BLINE1ST	BACKSCAN	X	SHORTTG	X
R/W	R/W	R/W	R/W	R/W	X	R/W	X

- 7-6 MCNTSET [1:0]** To select the unit of motor table counter.
 - 00 Pixel count.
 - 01 System clock*2.
 - 10 System clock*3.



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- 11 System clock*4.
- 5 **EVEN1ST** 0 The first pixel of stagger CCD is located at odd sensor line.
1 The first pixel of stagger CCD is located at even sensor line.
- 4 **BLINE1ST** 0 The first sensor of CCD is red line.
1 The first sensor of CCD is blue line.
- 3 **BACKSCAN** 0 Select forward scanning function.
1 Select backward scanning function.
- 1 **SHORTTG** 0 Disable this function.
1 Enable short CCD SH(TG) period for film scanning.

Offset 0Ah Default value = 8'h00

X	X	ADFSEL	LPWMEN	X	RS232SEL	BAUDRAT1	BAUDRAT0
R/W	R/W	R/W	R/W	X	R/W	R/W	R/W

- 5 **ADFSEL** 0 Disable ADF function.
1 Enable ADF function and the specific GPIOs are defined to drive ADF module.
- 4 **LPWMEN** 0 Disable ADF function.
1 Enable PWM function of lamp.
- 2 **RS232SEL** 0 Disable RS232 interface.
1 Enable RS232 interface for special application and the specific GPIOs are defined to implement RS232 protocol.
- 1-0 **BAUDRAT [1:0]** Set baud rate of RS232.
00 2400bps.
01 4800bps.
10 9600bps.
11 19200bps.

Offset 0Bh Default value = 8'h00

CLKSET2	CLKSET1	CLKSET0	RFHDIS	ENBDRAM	DRAMSEL2	DRAMSEL1	DRAMSEL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-5 **CLKSET [2:0]** To select the system clock frequency.
000 24MHz.
001 30MHz.
010 40MHz.
011 48MHz.
100 60MHz.
101 Reserved.
110 Reserved.
111 Reserved.
- 4 **RFHDIS** 0 Enable auto-refresh mode for SDRAM.
1 Enable self-refresh mode for SDRAM.
- 3 **ENBDRAM** A rising edge from low to high: to start power on sequence of SDRAM.
- 2-0 **DRAMSEL [2:0]** Select the SDRAM size.
000 Reserved.
001 16M bits.
010 64M bits.
011 128M bits.
100 256M bits.
101 512M bits.
110 **1G bits.**



111 Reserved.

Offset 0Ch Default value = 8'h00

X	X	X	X	CCDLMT3	CCDLMT2	CCDLMT1	CCDLMT0
X	X	X	X	R/W	R/W	R/W	R/W

7-4 Reserved -

3-0 CCDLMT [3:0] To set the lines count which is synchronized for CCD timing(like NEC8884).

Offset 0Dh

X	X	X	FULLSTP	SEND	CLRMCNT	CLRDOCJM	CLRLNCNT
X	X	X	W	W	W	W	W

Command: Scanner command.

- 4 FULLSTP** To reset steps type to full step.
- 3 SEND** To send the RS232 data.
- 2 CLRMCNT** To clear FEDCNT(Reg48,Reg49,Reg4A) counter information.
- 1 CLRDOCJM** To clear document jam message for ADF module.
- 0 CLRLNCNT** To clear SCANCNT (Reg4B,Reg4C,Reg4D).

Note: 1.For each scanning, designers must clear SCANCNT before starting process.
2.They are write-one commands.

Offset 0Eh

SCANRESET
W

Command: Scanner software reset.

It can initiate AISC system including lamp and motor, control registers, internal circuit; but not including tables in DRAM, like gamma table, shading table and acceleration/deceleration table.

Note: In normal condition, it is unnecessary to reset scanner unless the scanner is out of control.

Offset 0Fh

MOVE
W

Command: Motor moving.

Start motor forward/backward moving.

Offset 10h Default value = 8'h00

EXPR15	EXPR14	EXPR13	EXPR12	EXPR11	EXPR10	EXPR9	EXPR8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 EXPR [15:8] Exposure time setting (in pixel time) for Red-LED of CIS or Red channel of CCD.

Note: It cannot be programmed to logic zero.



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Offset 11h Default value = 8'h00

EXPR7	EXPR6	EXPR5	EXPR4	EXPR3	EXPR2	EXPR1	EXPR0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 EXPR [7:0] Exposure time setting (in pixel time) for Red-LED of CIS or Red channel of CCD.

Note: It cannot be programmed to logic zero.

Offset 12h Default value = 8'h00

EXPG15	EXPG14	EXPG13	EXPG12	EXPG11	EXPG10	EXPG9	EXPG8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 EXPG [15:8] Exposure time setting (in pixel time) for Green-LED of CIS or Red channel of CCD.

Note: It cannot be programmed to logic zero.

Offset 13h Default value = 8'h00

EXPG7	EXPG6	EXPG5	EXPG4	EXPG3	EXPG2	EXPG1	EXPG0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 EXPG [7:0] Exposure time setting (in pixel time) for Green-LED of CIS or Red channel of CCD.

Note: It cannot be programmed to logic zero.

Offset 14h Default value = 8'h00

EXPB15	EXPB14	EXPB13	EXPB12	EXPB11	EXPB10	EXPB9	EXPB8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 EXPB [15:8] Exposure time setting (in pixel time) for Blue-LED of CIS or Red channel of CCD.

Note: It cannot be programmed to logic zero.

Offset 15h Default value = 8'h00

EXPB7	EXPB6	EXPB5	EXPB4	EXPB3	EXPB2	EXPB1	EXPB0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 EXPB [7:0] Exposure time setting (in pixel time) for Blue-LED of CIS or Red channel of CCD.

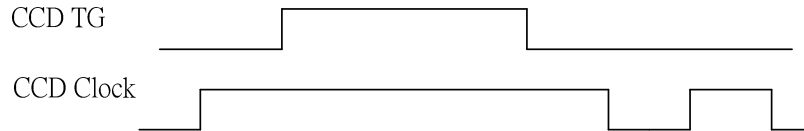
Note: It cannot be programmed to logic zero.

Offset 16h Default value = 8'h32

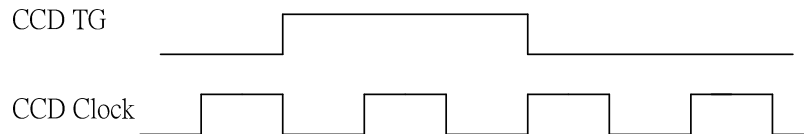
CTRLHI	TOSHIBA	TGINV	CK1INV	CK2INV	CTRLINV	CKDIS	CTRLDIS
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 CTRLHI**
 - 0 CCD CP & RS will be low when TG goes high.
 - 1 CCD CP & RS will be high when TG goes high.
- 6 TOSHIBA**
 - 0 Not TOSHIBA CIS.
 - 1 To indicate the image sensor is TOSHIBA CIS.
- 5 TGINV**
 - 0 Don't reverse.
 - 1 To reverse CCD TG.

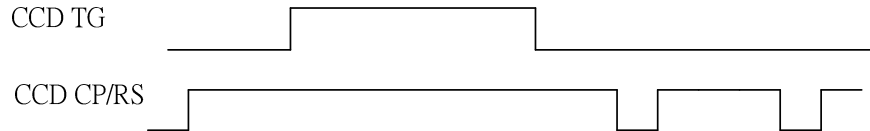
- 4 **CK1INV** 0 Don't reverse.
 1 To reverse CCD Clock 1.
- 3 **CK2INV** 0 Don't reverse.
 1 To reverse CCD Clock 2.
- 2 **CTRLINV** 0 Don't reverse.
 1 To reverse CCD CP & RS.
- 1 **CKDIS** 0 Disable clock1 and 2 under CCD TG position as illustrated.



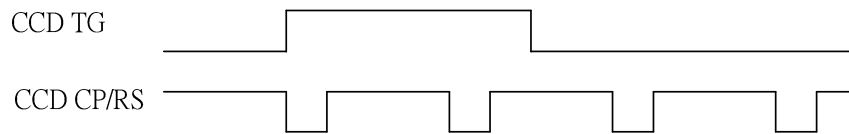
- 0 Enable clock 1 and 2 under CCD TG position as illustrated.



- 0 **CTRLDIS** 1 Disable CCD CP & RS signals under CCD TG position as illustrated.



- 0 Enable CCD CP & RS signals under CCD TG position as illustrated.



Offset 17h Default value = 8'h14

TGMODE1	TGMODE0	TGW5	TGW4	TGW3	TGW2	TGW1	TGW0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-6 TGMODE [1:0]** To set CCD TG mode.
 - 00 normal CCD TG type.
 - 01 CCD TG control with dummy line.
 - 10 CCD TG control with dummy lines for transparency scanning type.
 - 11 reserved for ASIC simulation.

- 5-0 TGW [5:0]** To set CCD TG plus width (in pixel time).

Note: It cannot be programmed to logic zero.

Offset 18h Default value = 8'h00

- 7 **SW2SET** Set CCD SW2 output for special CCD control.
- 6 **SW1SET** Set CCD SW1 output for special CCD control.
- 5 **MANUAL3** 0 CCD Clock 3,Clock4 automatic output.
1 CCD Clock 3,Clock4 manual output.
- 4 **MANUAL1** 0 CCD Clock 1,Clock2 automatic output.
1 CCD Clock 1,Clock2 manual output.
- 3 **CK4INV** 0 Don't reverse.
1 To reverse CCD Clock4.
- 2 **CK3INV** 0 Don't reverse.
1 To reverse CCD Clock 3.
- 1 **LINECLP** 0 To select CCD pixel clamping.
1 To select CCD line clamping.

Offset 1Bh Default value = 8'h00

GRAYSET	CHANSEL	BGRENB	ICGENB	ICGDLY3	ICGDLY2	ICGDLY1	ICGDLY0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 **GRAYSET** 0 Select single channel output.
1 Select two channel output.
- 6 **CHANSEL** 0 Fast true gray latch is 2 and 3 position.
1 Fast true gray latch is 1 and 2 position.
- 5 **BGRENB** 0 The order is R-G-B.
1 The order of latching A/D data is B-G-R.
- 4 **ICGENB** 0 To disable ICG control.
1 To enable CCD shutter control signal ICG.
- 3-0 **ICGDLY [3:0]** CCD ICG delay for rising/falling edge.

Offset 1Ch Default value = 8'h00

CK4MTGL	CK3MTGL	CK1MTGL	CKAREA	MTLWD	TGTIME2	TGTIME1	TGTIME0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 **CK4MTGL** 0 Disable toggle function in CCD clock 4.
1 Enable toggle function in CCD clock 4.
- 6 **CK3MTGL** 0 Disable toggle function in CCD clock 3.
1 Enable toggle function in CCD clock 3.
- 5 **CK1MTGL** 0 Disable toggle function in CCD clock 1 & 2.
1 Enable toggle function in CCD clock 1 & 2.
- 4 **CKAREA** 0 This function is disabled.
1 CCD clock speed depends on CKSEL in scan area and DCKSEL in non-scan area.
- 3 **MTLWD** 0 Set the watchdog time-out as WDTIME[3:0].
1 Set the watchdog time-out as WDTIME[3:0] * 2.
- 2-0 **TGTIME [2:0]** CCD line period selection.
000 1*LPERIOD(Reg38,Reg39)
001 2*LPERIOD



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- 010 4*LPERIOD
- 011 8*LPERIOD
- 100 16*LPERIOD
- 101 32*LPERIOD
- 110 Reserved.
- 111 Reserved.

Offset 1Dh Default value = 8'h04

CK4LOW	CK3LOW	CK1LOW	TGSHLD4	TGSHLD3	TGSHLD2	TGSHLD1	TGSHLD0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 CK4LOW**
 - 0 Clock 4 will be high when TG goes high.
 - 1 Clock 4 will be low when TG goes high.
- 6 CK3LOW**
 - 0 Clock 3 will be high when TG goes high.
 - 1 Clock 3 will be low when TG goes high.
- 5 CK1LOW**
 - 0 Clock 1 & 2 will be high when TG goes high.
 - 1 Clock 1 & 2 will be low when TG goes high.
- 4-0 TGSHLD [4:0]** CCD TG shoulder width (in pixel time). Please refer to Reg34.
 Note: Designers have to program the TGSHLD >= 2 (more than two).

Offset 1Eh Default value = 8'h20

WDTIME3	WDTIME2	WDTIME1	WDTIME0	LINESEL3	LINESEL2	LINESEL1	LINESEL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-4 WDTIME [3:0]** To set watch-dog time.
The unit is 30 seconds.
- 3-0 LINESEL [3:0]** To set vertical resolution for CIS or dummy lines for CCD.
 CIS : LINESEL = 0 full resolution.
 = 1 1/2 resolution.
 = 2 1/3 resolution .

 = 15 1/16 resolution.
 CCD : LINESEL = 0 no dummy line.
 = 1 1 dummy line.
 = 2 2 dummy lines.

 = 15 15 dummy lines.

Note: In contrary to dummy line feature in CCD, for low resolution in CIS, the scanning speed is improved by implementing fast motor moving.

Offset 1Fh Default value = 8'h00

SCANFED7	SCANFED6	SCANFED5	SCANFED4	SCANFED3	SCANFED2	SCANFED1	SCANFED0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-0 SCANFED [7:0]** Steps number setting for moving to scanning position.
Please refer to description of Reg6A
 Note: 1.it cannot be programmed to logic zero.
 2.it can be multiplied by $2^{*STEP\ TIME}$

Offset 20h Default value = 8'h00



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BUFSEL7	BUFSEL6	BUFSEL5	BUFSEL4	BUFSEL3	BUFSEL2	BUFSEL1	BUFSEL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 BUFSEL [7:0] To set buffer condition.
 When buffer is full, scanner will stop and wait for host to read out image data from SDRAM.
 The valid data count (has not been read) is represented by VALIDWORD (in word).
 If VALIDWORD < buffer condition, then the scanner will re-start to scan.

Following are the units of this register under various SDRAM size.
 16M bits SDRAM : 4k words
 64M bits SDRAM : 16k words
 128M bits SDRAM : 32K words
 256M bits SDRAM : 64K words
 512M bits SDRAM : 128K words

Offset 21h Default value = 8'h00

STEPNO7	STEPNO6	STEPNO5	STEPNO4	STEPNO3	STEPNO2	STEPNO1	STEPNO0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 STEPNO [7:0] Steps number of “table one” for the acceleration/deceleration of scanning moving.
 Please refer to section 6.19 and the descriptions of Reg24 & Reg6A.
 Note: 1.It cannot be programmed to logic zero.
 2.it can be multiplied by $2^{*STEP\overline{TIM}}$

Offset 22h Default value = 8'h00

FWDSTEP7	FWDSTEP6	FWDSTEP5	FWDSTEP4	FWDSTEP3	FWDSTEP2	FWDSTEP1	FWDSTEP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 FWDSTEP [7:0] Steps number for forward moving when buffer condition is met.
 Please refer to section 6.19 and the descriptions of Reg20 & Reg24.
 Note: 1.It cannot be programmed to logic zero.
 2.it can be multiplied by $2^{*STEP\overline{TIM}}$

Offset 23h Default value = 8'h00

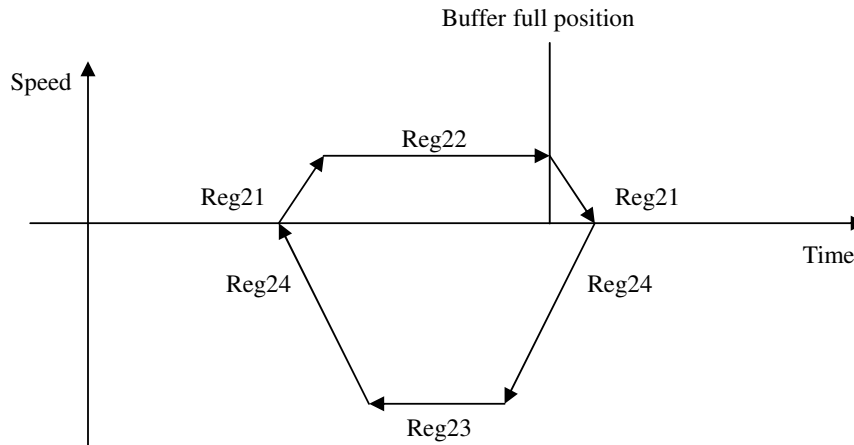
BWDSTEP7	BWDSTEP6	BWDSTEP5	BWDSTEP4	BWDSTEP3	BWDSTEP2	BWDSTEP1	BWDSTEP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 BWDSTEP [7:0] Steps number for backward moving when image buffer is full.
 Please refer to section 6.19 and the descriptions of Reg24.
 Note: 1.It cannot be programmed to logic zero.
 2.it can be multiplied by $2^{*STEP\overline{TIM}}$

Offset 24h Default value = 8'h00

FASTNO7	FASTNO6	FASTNO5	FASTNO4	FASTNO3	FASTNO2	FASTNO1	FASTNO0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 FASTNO [7:0] Steps number of “table two” for the acceleration/deceleration when image buffer is full.
 Please refer to section 6.19 and the descriptions of Reg20.
 Note: It cannot be programmed to logic zero.



Offset 25h Default value = 8'h00

X	X	X	X	LINCNT19	LINCNT18	LINCNT17	LINCNT16
X	X	X	X	R/W	R/W	R/W	R/W

7-4 RESERVED -

3-0 LINCNT [19:16] Scanning lines count specified by designers.
Note: It cannot be programmed to logic zero.

Offset 26h Default value = 8'h00

LINCNT15	LINCNT14	LINCNT13	LINCNT12	LINCNT11	LINCNT10	LINCNT9	LINCNT8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 LINCNT [15:8] Scanning lines count specified by designers.
Note: It cannot be programmed to logic zero.

Offset 27h Default value = 8'h00

LINCNT7	LINCNT6	LINCNT5	LINCNT4	LINCNT3	LINCNT2	LINCNT1	LINCNT0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 LINCNT [7:0] Scanning lines count specified by designers.
Note: It cannot be programmed to logic zero.

Offset 2Ch Default value = 8'h00

X	X	DPISET13	DPISET12	DPISET11	DPISET10	DPISET9	DPISET8
X	X	R/W	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 DPISET [13:8] Set resolution in dpi for average or deletion type.
A. average type : digital average function support 1/2,1/3,1/4,1/5,1/6,1/8,1/10,1/12,1/15.
a. 9600 dpi mode CCD:support 4800,3200,2400,1920,1600,1200,960,800,640 dpi.
b. 4800 dpi mode CCD:support 2400,1600,1200,960,800,480,400,320 dpi.
c. 2400 dpi mode CCD:support 1200,800,600,480,400,300,240,200,160 dpi.

d. 1200 dpi mode CCD:support 600,400,300,240,200,150,120,100,80 dpi.

e. 600 dpi mode CCD:support 300,200,150,120,100,75,60,50,40 dpi.

B. deletion type : 9600,4800,2400,1200 or 600dpi to 1 dpi setting decrement by one dpi.

Note: It cannot be programmed to logic zero.

Offset 2Dh Default value = 8'h00

DPISET7	DPISET6	DPISET5	DPISET4	DPISET3	DPISET2	DPISET1	DPISET0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 DPISET [7:0] Set resolution in dpi for average or deletion type.

A. average type : digital average function support 1/2,1/3,1/4,1/5,1/6,1/8,1/10,1/12,1/15.

a. 9600 dpi mode CCD:support 4800,3200,2400,1920,1600,1200,960,800,640 dpi.

b. 4800 dpi mode CCD:support 2400,1600,1200,960,800,480,400,320 dpi.

c. 2400 dpi mode CCD:support 1200,800,600,480,400,300,240,200,160 dpi.

d. 1200 dpi mode CCD:support 600,400,300,240,200,150,120,100,80 dpi.

e. 600 dpi mode CCD:support 300,200,150,120,100,75,60,50,40 dpi.

B. deletion type : 9600,4800,2400,1200 or 600dpi to 1 dpi setting decrement by one dpi.

Note: It cannot be programmed to logic zero.

Offset 2Eh Default value = 8'h00

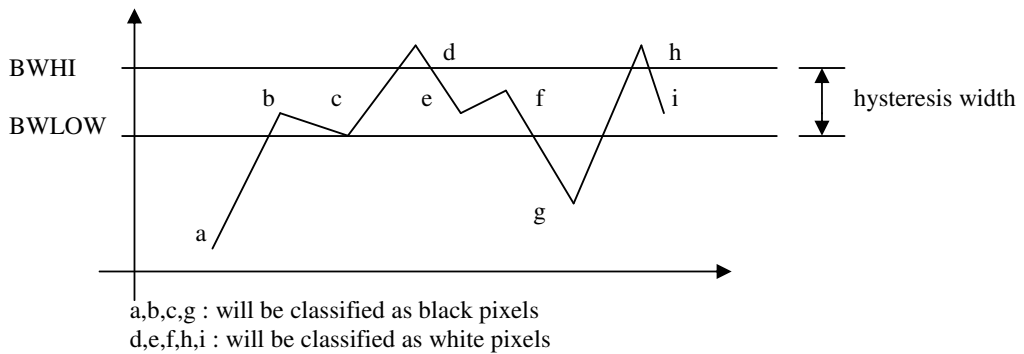
BWHI7	BWHI6	BWHI5	BWHI4	BWHI3	BWHI2	BWHI1	BWHI0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 BWHI [7:0] High level of Black & White threshold.

Offset 2Fh Default value = 8'h00

BWLOW7	BWLOW6	BWLOW5	BWLOW4	BWLOW3	BWLOW2	BWLOW1	BWLOW0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 BWLOW [7:0] Low level of Black & White threshold.



Offset 30h Default value = 8'h00

STRPIXEL15	STRPIXEL14	STRPIXEL13	STRPIXEL12	STRPIXEL11	STRPIXEL10	STRPIXEL9	STRPIXEL8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 STRPIXEL [15:8] The start pixel position of horizontal line (unit : pixel count).

STRPIXEL=(TGW+2*TGSHLD)+start pixels number (count from CCD pixel 0)

Note: 1.It cannot be programmed to logic zero.
2.If the DPI9600 control bit is set to “1”,the STRPIXEL is doubled.

Offset 31h Default value = 8'h00

STRPIXEL7	STRPIXEL6	STRPIXEL5	STRPIXEL4	STRPIXEL3	STRPIXEL2	STRPIXEL1	STRPIXEL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 STRPIXEL [7:0] The start pixel position of horizontal line (unit : pixel count).
 $STRPIXEL=(TGW+2*TGSHLD)+start\ pixels\ number\ (count\ from\ CCD\ pixel\ 0)$
 Note: 1.It cannot be programmed to logic zero.
 2.If the DPI9600 control bit is set to “1”,the STRPIXEL is doubled.

Offset 32h Default value = 8'h00

ENDPIXEL15	ENDPIXEL14	ENDPIXEL13	ENDPIXEL12	ENDPIXEL11	ENDPIXEL10	ENDPIXEL9	ENDPIXEL8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 ENDPIXEL [15:8] The end pixel position of horizontal line (unit : pixel count).
 $ENDPIXEL=(TGW+2*TGSHLD)+end\ pixels\ number\ (count\ from\ CCD\ pixel\ 0)$
 Note: 1.It cannot be programmed to logic zero.
 2.If the DPI9600 control bit is set to “1”,the STRPIXEL is doubled.

Offset 33h Default value = 8'h00

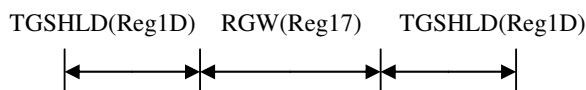
ENDPIXEL7	ENDPIXEL6	ENDPIXEL5	ENDPIXEL4	ENDPIXEL3	ENDPIXEL2	ENDPIXEL1	ENDPIXEL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 ENDPIXEL [7:0] The end pixel position of horizontal line (unit : pixel count).
 $ENDPIXEL=(TGW+2*TGSHLD)+end\ pixels\ number\ (count\ from\ CCD\ pixel\ 0)$
 Note: 1.It cannot be programmed to logic zero.
 2.If the DPI9600 control bit is set to “1”,the STRPIXEL is doubled.

Offset 34h Default value = 8'h00

DUMMY7	DUMMY6	DUMMY5	DUMMY4	DUMMY3	DUMMY2	DUMMY1	DUMMY0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 DUMMY [7:0] The CCD dummy & optical black pixels number (unit : pixel count).
 Note: It cannot be programmed to logic zero.
 Setting rule of Reg30,31,32,33 and 34.





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R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
-----	-----	-----	-----	-----	-----	-----	-----

7-0 LPERIOD [7:0] Line period (or exposure time) for CCD or CIS.

Unit : pixel count

Note: It cannot be programmed to logic zero.

Offset 3Ah

X	X	X	X	X	X	X	FEWRDATA8
X	X	X	X	X	X	X	W

7-1 RESERVED -

0 FEWRDATA [8] This port is for designers to write control register of front-end.

Offset 3Bh

FEWRDATA7	FEWRDATA6	FEWRDATA5	FEWRDATA4	FEWRDATA3	FEWRDATA2	FEWRDATA1	FEWRDATA0
W	W	W	W	W	W	W	W

7-0 FEWRDATA [7:0] This port is for designers to write control register of front-end.

Offset 3Dh Default value = 8'h00

X	X	X	X	FEEDL19	FEEDL18	FEEDL17	FEEDL16
X	X	X	X	R/W	R/W	R/W	R/W

7-4 RESERVED -

3-0 FEEDL [19:16] Steps number of motor moving.

Note: It cannot be programmed to logic zero.

Offset 3Eh Default value = 8'h00

FEEDL15	FEEDL14	FEEDL13	FEEDL12	FEEDL11	FEEDL10	FEEDL9	FEEDL8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 FEEDL [15:8] Steps number of motor moving.

Note: It cannot be programmed to logic zero.

Offset 3Fh Default value = 8'h00

FEEDL7	FEEDL6	FEEDL5	FEEDL4	FEEDL3	FEEDL2	FEEDL1	FEEDL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 FEEDL [7:0] Steps number of motor moving.

Note: It cannot be programmed to logic zero.

Offset 40h

DOCSNR	ADFSNR	COVERSNR	CHKVER	DOCJAM	HISPDFLG	MOTMFLG	DATAENB
R	R	R	R	R	R	R	R



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- 7 **DOCSNR** Respond to document sensor status for ADF function.
- 6 **ADFSNR** Respond to ADF sensor status for ADF function.
- 5 **COVERSNR** Respond to cover sensor status for ADF function.
- 4 **CHKVER** It is fixed to '1' to indicate that the value in Reg00 is valid.
- 3 **DOCJAM** Respond to document feeding status for ADF function.
 - 0 No jam happened.
 - 1 Document jammed.
- 2 **HISPDFLG** 0 Motor is not in high-speed moving.
1 Motor is in high-speed moving.
- 1 **MOTMFLG** 0 Motor is stop.
1 Motor is moving.
- 0 **DATAENB** 0 Scanner is in command mode. Designers can access other data in SDRAM rather than image data.
1 Scanner is in scanning mode. Designers can only read the image data.

Offset 41h

PWRBIT	BUFEMPTY	FEEDFSH	SCANFSH	HOMESNR	LAMPSTS	FEBUSY	MOTORENB
R	R	R	R	R	R	R	R

- 7 **PWRBIT** To indicate power status. If it is reset, the power had been turned off. Power on initial process will set PWRBIT to 0. This bit will have the same value as bit 4 of Reg06 except for it's read only.
- 6 **BUFEMPTY** 0 The image buffer is not empty.
1 The image buffer is empty.
- 5 **FEEDFSH** 0 Motor feeding is not finished.
1 Motor feeding is finished.
- 4 **SCANFSH** 0 Scanning is not finished.
1 Scanning is finished.
- 3 **HOMESNR** 0 Home sensor is on (is not located in home position).
1 Home sensor is off (located in home position).
- 2 **LAMPSTS** 0 Lamp is off.
1 Lamp is on.
- 1 **FEBUSY** 0 Front end is ready for read/write operations.
1 Front end is busy and can not perform read/write operations.
- 0 **MOTORENB** 0 Motor is not operation.
1 Motor is operation.

Offset 42h Default value = 8'h00

X	X	X	X	X	X	VALIDWORD 25	VALIDWORD 24
X	X	X	X	X	X	R	R

- 1-0 **VALIDWORD** The available image data stored in SDRAM for host to read.
[25:24] The unit is in word.

Offset 43h Default value = 8'h00

VALIDWORD 23	VALIDWORD 22	VALIDWORD 21	VALIDWORD 20	VALIDWORD 19	VALIDWORD 18	VALIDWORD 17	VALIDWORD 16
R	R	R	R	R	R	R	R



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7-0 VALIDWORD [23:16] The available image data stored in SDRAM for host to read.
The unit is in word.

Offset 44h **Default value = 8'h00**

VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD
15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R

7-0 VALIDWORD [15:8] The available image data stored in SDRAM for host to read.
The unit is in word.

Offset 45h

VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD	VALIDWORD
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

7-0 VALIDWORD [7:0] The available image data stored in SDRAM for host to read.
The unit is in word.

Offset 46h

X	X	X	X	X	X	X	FERDDATA8
X	X	X	X	X	X	X	R

7-1 RESERVED -

0 FERDDATA [8] This port is for designers to read control register from front-end.

Offset 47h

FERDDATA7	FERDDATA6	FERDDATA5	FERDDATA4	FERDDATA3	FERDDATA2	FERDDATA1	FERDDATA0
R	R	R	R	R	R	R	R

7-0 FERDDATA [7:0] This port is for designers to read control register from front-end.

Offset 48h **Default value = 8'h00**

X	X	X	FEDCNT20	FEDCNT19	FEDCNT18	FEDCNT17	FEDCNT16
X	X	X	R	R	R	R	R

7-5 RESERVED -

4-0 FEDCNT [20:16] Steps number which motor has moved.

For example, after setting the moving steps number (Reg 3D, 3E 3F) and execute the moving command (Reg 0F), designers can get steps number which has been moved via these registers. It can be reset to zero by CLRMCNT command.

The unit is in quarter step.

Offset 49h **Default value = 8'h00**

FEDCNT15	FEDCNT14	FEDCNT13	FEDCNT12	FEDCNT11	FEDCNT10	FEDCNT9	FEDCNT8
R	R	R	R	R	R	R	R



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7-0 FEDCNT [15:8] Steps number which motor has moved.

Offset 4Ah **Default value = 8'h00**

FEDCNT7	FEDCNT6	FEDCNT5	FEDCNT4	FEDCNT3	FEDCNT2	FEDCNT1	FEDCNT0
R	R	R	R	R	R	R	R

7-0 FEDCNT [7:0] Steps number which motor has moved.

Offset 4Bh **Default value = 8'h00**

X	X	X	X	SCANCNT19	SCANCNT18	SCANCNT17	SCANCNT16
X	X	X	X	R	R	R	R

7-4 RESERVED -

3-0 SCANCNT [19:16] Line number which scanner has finished.
 For example, after setting the line number (Reg 25, 26 27) and execute the scanning enable (bit 0 of Reg 01), designers can get line number which has been finished via these registers. It can be reset to zero by CLRLNCNT command.

Offset 4Ch **Default value = 8'h00**

SCANCNT15	SCANCNT14	SCANCNT13	SCANCNT12	SCANCNT11	SCANCNT10	SCANCNT9	SCANCNT8
R	R	R	R	R	R	R	R

7-0 SCANCNT [15:8] Line number which scanner has finished.

Offset 4Dh **Default value = 8'h00**

SCANCNT7	SCANCNT6	SCANCNT5	SCANCNT4	SCANCNT3	SCANCNT2	SCANCNT1	SCANCNT0
R	R	R	R	R	R	R	R

7-0 SCANCNT [7:0] Line number which scanner has finished.

Offset 4Fh

X	X	DOGON	X	X	TX232BSY	RX232BSY	RXREADY
X	X	R	X	X	R	R	R

- 5 DOGON** 0 Lamp dog hasn't occurred
 1 Lamp dog has occurred
- 2 TX232BSY** 0 RS232 transmitter is ready for access.
 1 RS232 transmitter is busy and can not be accessed.
- 1 RX232BSY** 0 RS232 receiver is ready for access.
 1 RS232 receiver is busy and can not be accessed.
- 0 RXREADY** 0 The receiving has not been completed.
 1 Has received data number specified in Reg 88 from RS232.

Offset 50h **Default value = 8'h00**

X	X	FERDA5	FERDA4	FERDA3	FERDA2	FERDA1	FERDA0
X	X	R/W	R/W	R/W	R/W	R/W	R/W



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7-6 RESERVED -

5-0 FERDA [5:0] Address of control register of front-end in read operation.
Before reading control register of front-end (Reg 46, 47), designers have to specify address of the control register by writing address to this port.

Offset 51h Default value = 8'h00

X	X	FEWRA5	FEWRA4	FEWRA3	FEWRA2	FEWRA1	FEWRA0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

7-6 RESERVED -

5-0 FEWRA [5:0] Address of control register of front-end in write operation.
Before writing control register of front-end (Reg 3A, 3B), designers have to specify address of the control register by writing address to this port.

Offset 52h Default value = 8'h00

X	X	X	RHI4	RHI3	RHI2	RHI1	RHI0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 RHI [4:0] The latch point for high-byte of R channel of AFE in every pixel.
For example, if a system is designed to have 12 clocks/pixel, and designer wants to latch the high-byte of R channel at 1'st clock in every pixel, designer has to fill '00001' to RHI [4:0].

Offset 53h Default value = 8'h00

X	X	X	RLOW4	RLOW3	RLOW2	RLOW1	RLOW0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 RLOW [4:0] The latch point for low-byte of R channel of AFE in every pixel.
For example, if a system is designed to have 12 clocks/pixel, and designer wants to latch the high-byte of R channel at 1'st clock in every pixel, designer has to fill '00001' to RHI [4:0].

Offset 54h Default value = 8'h00

X	X	X	GHI4	GHI3	GHI2	GHI1	GHI0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 GHI [4:0] The latch point for high-byte of G channel of AFE in every pixel.

Offset 55h Default value = 8'h00

X	X	X	GLOW4	GLOW3	GLOW2	GLOW1	GLOW0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -



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4-0 GLOW [4:0] The latch point for low-byte of G channel of AFE in every pixel.

Offset 56h **Default value = 8'h00**

X	X	X	BHI4	BHI3	BHI2	BHI1	BHI0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 BHI [4:0] The latch point for high-byte of B channel of AFE in every pixel.

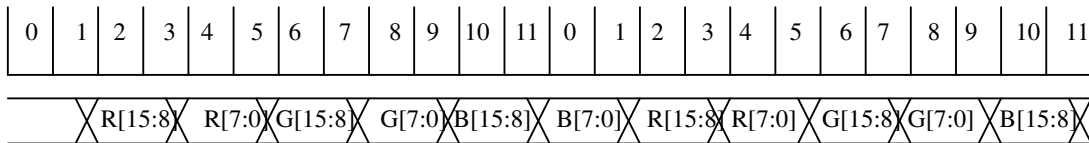
Offset 57h **Default value = 8'h00**

X	X	X	BLOW4	BLOW3	BLOW2	BLOW1	BLOW0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 BLOW [4:0] The latch point for low-byte of B channel of AFE in every pixel.

(1). Color, gray or line-art : 12 clocks (phase)/pixel mode



RHI = 01H RLOW = 03H
 GHI = 05H GLOW = 07H
 BHI = 09H BLOW = 11H

Note: 16 clocks (phase)/pixel and 18 clocks(phase)/pixel modes are similar to 12 clocks(phase)/pixel mode.

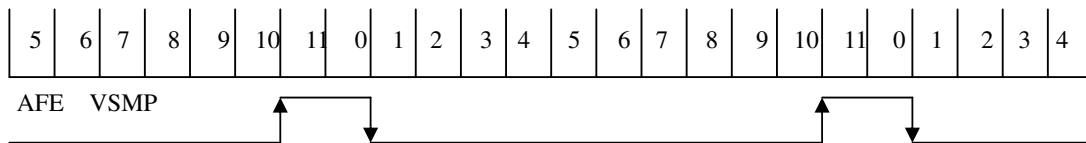
Offset 58h **Default value = 8'h00**

VSMP4	VSMP3	VSMP2	VSMP1	VSMP0	VSMPW2	VSMPW1	VSMPW0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-3 VSMP [4:0] Rising edge position of image sampling for AFE.

2-0 VSMPW [2:0] Pulse width of image sampling.

(1). Color, gray or line-art : 12 clocks (phase)/pixel mode



Reg58=52H : VSMP[4:0]=10H VSMPW[2:0]=2H

Note: 16 clocks (phase)/pixel and 18 clocks(phase)/pixel modes are similar to 12 clocks(phase)/pixel mode.

Offset 59h **Default value = 8'h00**

BSMP4	BSMP3	BSMP2	BSMP1	BSMP0	BSMPW2	BSMPW1	BSMPW0
-------	-------	-------	-------	-------	--------	--------	--------



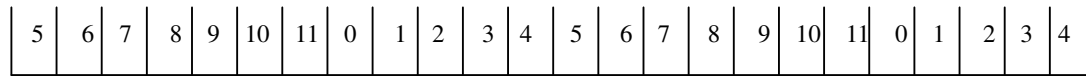
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R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
-----	-----	-----	-----	-----	-----	-----	-----

7-3 BSMP [4:0] Rising edge position of dark voltage sampling for AFE.

2-0 BSMPW [2:0] Pulse width of dark voltage sampling.

(1). Color, gray or line-art : 12 clocks (phase)/pixel mode



AFE BSMP

Reg59=52H : BSMP[4:0]=10H BSMPW[2:0]=2H

Note: 16 clocks (phase)/pixel and 18 clocks(phase)/pixel modes are similar to 12 clocks(phase)/pixel mode.

Offset 5Ah Default value = 8'h00

ADCLKINV	RLCSEL	CDSREF1	CDSREF0	RLC3	RLC2	RLC1	RLC0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7 ADCLKINV 0 ADC clock in not reversed.
1 ADC clock is reversed.

6 RLCSEL 0 Do not select.
1 Select reset level clamp on a pixel-by-pixel basis.

5-4 CDSREF [1:0] Front-end CDS reference for line rate scanning type.

3-0 RLC [3:0] Front-end RLC for line rate scanning type.

Offset 5Dh Default value = 8'h00

HISPD7	HISPD6	HISPD5	HISPD4	HISPD3	HISPD2	HISPD1	HISPD0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 HISPD [7:0] To change of the speed of motor during moving
Note: It cannot be programmed to logic zero.

Offset 5Eh Default value = 8'h00

DECSEL2	DECSEL1	DECSEL0	STOPTIM4	STOPTIM3	STOPTIM2	STOPTIM1	STOPTIM0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-5 DECSEL [2:0] Deceleration steps number after touching home sensor.
000 1 steps deceleration
001 2 steps deceleration
010 4 steps deceleration
011 8 steps deceleration
100 16 steps deceleration
101 32 steps deceleration
110 64 steps deceleration
111 128 steps deceleration

4-0 STOPTIM [4:0] Stop time between forward and backward direction in backtracking.

Note: In ASIC simulation process, STOPTIM has to be set to tptime=6,7.



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It cannot be programmed to logic zero.

Offset 5Fh Default value = 8'h00

FMOVDEC7	FMOVDEC6	FMOVDEC5	FMOVDEC4	FMOVDEC3	FMOVDEC2	FMOVDEC1	FMOVDEC0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 FMOVDEC [7:0] Deceleration steps in table 5 for auto-go-home.

- Note: 1.It cannot be programmed to logic zero.
2.It can be multiplied by 2 *^{STEPTIM}

Offset 60h Default value = 8'h20

STEPSEL2	STEPSEL1	STEPSEL0	Z1MOD20	Z1MOD19	Z1MOD18	Z1MOD17	Z1MOD16
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-5 STEPSEL [2:0] For type selection of table one, table two and table three in scanning mode.

- (1) For bipolar motors:
 000 Full step (for 1939, 1940, 2916, 6219, 3967).
 001 Half step (for 1939, 1940, 2916, 6219, 3967).
 010 Quarter step (for 2916, 6219, 3967).
 011 Eighth step (for 3967).
 (2) For unipolar motors:
 000 Two-phase-on full step.
 001 Half step.
 010 Reserved.
 011 Single-phase-on full step.
 100 Reserved.

4-0 Z1MOD [20:16] “remainder value” of MOD operation in acceleration/deceleration tables.
ASIC calculate the moving time by MOD operation when buffer-full occurs.
Note: It should be less than LPERIOD.

Offset 61h Default value = 8'h00

Z1MOD15	Z1MOD14	Z1MOD13	Z1MOD12	Z1MOD11	Z1MOD10	Z1MOD7	Z1MOD8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 Z1MOD [15:8] “remainder value” of MOD operation in acceleration/deceleration tables.
ASIC calculate the moving time by MOD operation when buffer-full occurs.
Note: It should be less than LPERIOD.

Offset 62h Default value = 8'h00

Z1MOD7	Z1MOD6	Z1MOD5	Z1MOD4	Z1MOD3	Z1MOD2	Z1MOD1	Z1MOD0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 Z1MOD [7:0] “remainder value” of MOD operation in acceleration/deceleration tables.
ASIC calculate the moving time by MOD operation when buffer-full occurs.
Note: It should be less than LPERIOD.

Offset 63h Default value = 8'h00

FSTPSEL2	FSTPSEL1	FSTPSEL0	Z2MOD20	Z2MOD19	Z2MOD18	Z2MOD17	Z2MOD16
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-5 FSTPSEL [2:0] For type selection of table four and table five in command mode.

(1) For bipolar motors:

- 000 Full step (for 1939, 1940, 2916, 6219, 3967).
- 001 Half step (for 1939, 1940, 2916, 6219, 3967).
- 010 Quarter step (for 2916, 6219, 3967).
- 011 Eighth step (for 3967).

(2) For unipolar motors:

- 000 Two-phase-on full step.
- 001 Half step.
- 010 Reserved.
- 011 Single-phase-on full step.
- 100 Reserved.

7-0 Z2MOD [20:16] “remainder value” of MOD operation in acceleration/deceleration tables.
ASIC calculate the moving time by MOD operation when scanner start to move.
Note: It should be less than LPERIOD.

Note:for ACDCDIS=1,designer must subtract any small offset value from Z2MOD to solve the first time start/stop motor position problem.

Offset 64h Default value = 8’h00

Z2MOD15	Z2MOD14	Z2MOD13	Z2MOD12	Z2MOD11	Z2MOD10	Z2MOD9	Z2MOD8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 Z2MOD [15:8] “remainder value” of MOD operation in acceleration/deceleration tables.
ASIC calculate the moving time by MOD operation when scanner start to move.
Note: It should be less than LPERIOD.

Note:for ACDCDIS=1,designer must subtract any small offset value from Z2MOD to solve the first time start/stop motor position problem.

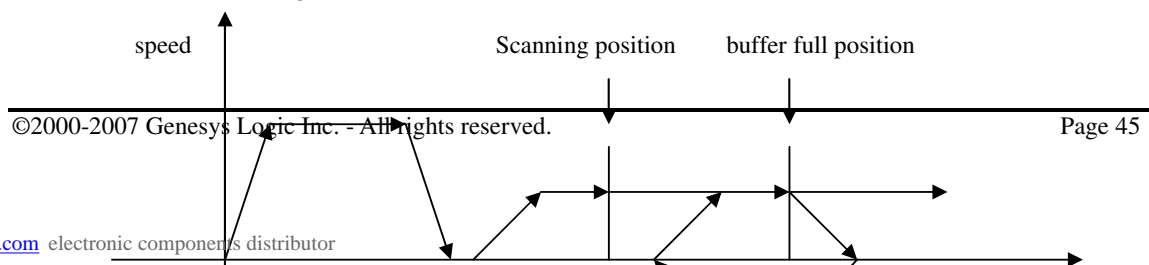
Offset 65h Default value = 8’h00

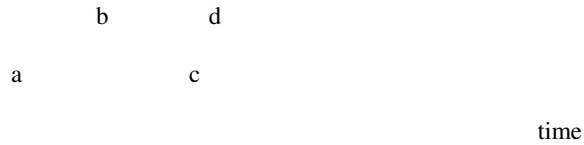
Z2MOD7	Z2MOD6	Z2MOD5	Z2MOD4	Z2MOD3	Z2MOD2	Z2MOD1	Z2MOD0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 Z2MOD [7:0] “remainder value” of MOD operation in acceleration/deceleration tables.
ASIC calculate the moving time by MOD operation when scanner start to move.
Note: It should be less than LPERIOD.

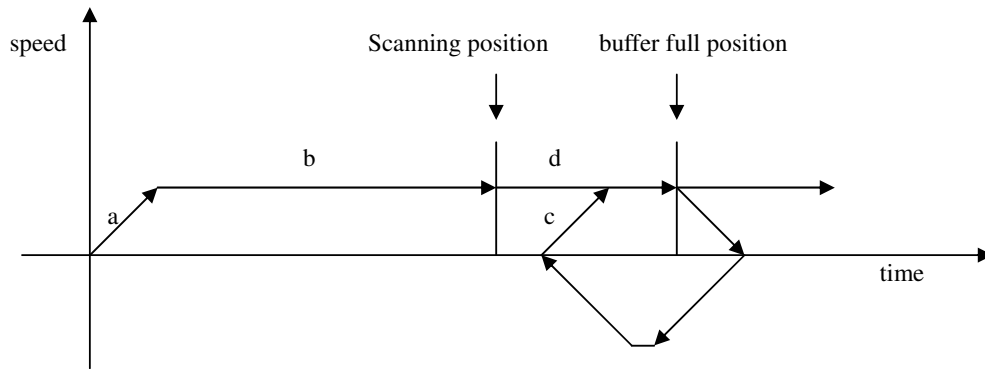
Note:for ACDCDIS=1,designer must subtract any small offset value from Z2MOD to solve the first time start/stop motor position problem.

(1). Two table moving :





(2). One table moving :



$$\{a + (b-1)\} \text{ mode } \{LPERIOD * (CCDLMT+1)\} = Z2MOD$$

$$\{c + (d-1)\} \text{ mode } \{LPERIOD * (CCDLMT+1)\} = Z1MOD$$

For example, c (STEPNO = 4 steps for table 1) = 60H, 48H, 30H, 18H
 d (FWDSTEP = 3 steps for moving) = 18H, 18H, 18H
 LPERIOD = 30H
 CCDLMT = 0
 Then Z1MOD = {(60H + 48H + 30H + 18H) + (18H + 18H)} MOD {30H} = 00H

Note: If MCNTSET [1:0] = 01 or 10 or 11, then (each step curve value + 1)/VCNT.
 VCNT= system clocks per pixel / (MCNTSET+1).

Offset 66h Default value = 8'h00

PHFREQ7	PHFREQ6	PHFREQ5	PHFREQ4	PHFREQ3	PHFREQ2	PHFREQ1	PHFREQ0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 PHFREQ [7:0] PWM frequency for motor phase of unipolar motors
 Frequency: (system clock frequency)/[(PHFREQ+1)*4]

Offset 67h Default value = 8'h7F

X	X	MTRPWM5	MTRPWM4	MTRPWM3	MTRPWM2	MTRPWM1	MTRPWM0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

7-6 RESERVED -

5-0 MTRPWM [5:0] PWM duty cycle selection of table one, table two and table three of motor phase of unipolar motors in scanning mode.
 MTRPWM = 0 1/64 duty
 = 1 2/64 duty
 = 2 3/64 duty

.....
= 63 64/64 duty

Note: If PHFREQ < 0FH, then PWM setting must < (PHFREQ+1)*4

Offset 68h Default value = 8'h7F

X	X	FASTPWM5	FASTPWM4	FASTPWM3	FASTPWM2	FASTPWM1	FASTPWM0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

7-6 RESERVED -

5-0 FASTPWM [5:0] PWM duty cycle selection of table four and table five of motor phase of unipolar motors in scanning mode.

FASTPWM = 0 1/64 duty
= 1 2/64 duty
= 2 3/64 duty
.....
= 63 64/64 duty

Note: If PHFREQ < 0FH, then PWM setting must < (PHFREQ+1)*4

Offset 69h Default value = 8'h00

FSHDEC7	FSHDEC6	FSHDEC5	FSHDEC4	FSHDEC3	FSHDEC2	FSHDEC1	FSHDEC0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 FSHDEC [7:0] Deceleration steps after scanning finished (table three).

Note: It cannot be programmed to logic zero.

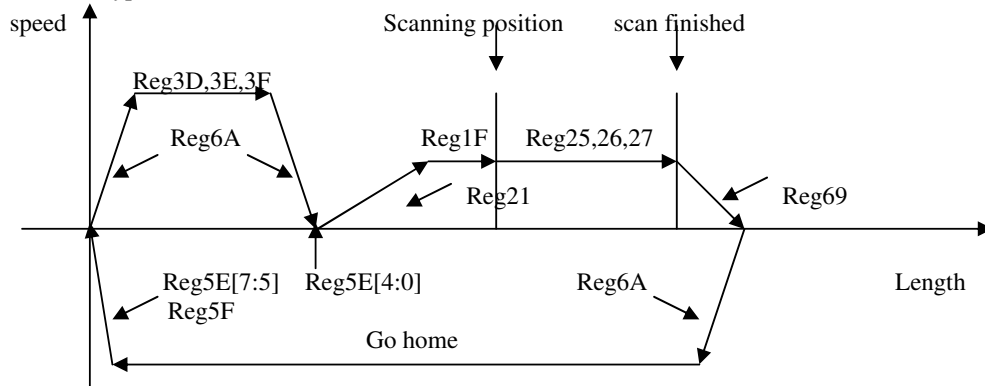
Offset 6Ah Default value = 8'h00

FMOVNO7	FMOVNO6	FMOVNO5	FMOVNO4	FMOVNO3	FMOVNO2	FMOVNO1	FMOVNO0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

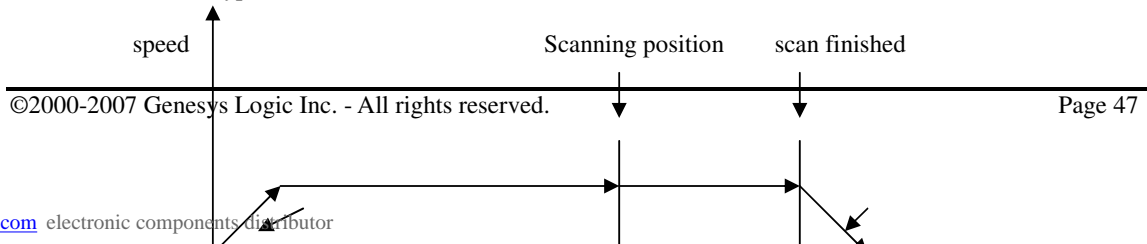
7-0 FMOVNO [7:0] Acceleration/deceleration steps for fast moving (table four).

Note: 1.It cannot be programmed to logic zero.
2.It can be multiplied by 2^{STEP_TIM}

(1). Two table type:



(2). One table type:





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Reg3D,3E,3F Reg25,26,27
 Reg21 Reg69
 Reg5F Length
 Reg5E[7:5] Reg6A
 Go home

Offset 6Bh Default value = 8'h00

MULTFILM	GPOM13	GPOM12	GPOM11	GPOCK4	GPOCP	GPOLEDB	GPOADF
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 **MULTFILM** 0 Disable multi-film scanning mode.
 1 Enable multi-film scanning mode. Motor power will not be turned off in this mode.
- 6 **GPOM 13** 0 Select GPIO13 as general purpose I/O.
 1 Select GPIO13 as V-ref control of bipolar motor driver IC to control I_{max}.
- 5 **GPOM12** 0 Select GPIO12 as general purpose I/O.
 1 Select GPIO12 as V-ref control of bipolar motor driver IC to control I_{max}.
- 4 **GPOM11** 0 Select GPIO11 as general purpose I/O..
 1 Select GPIO11 as V-ref control of bipolar motor driver IC to control I_{max}.
 Note: GPIO12: 1. Add a pull up resistor on GPIO12 will indicate ASIC to turn on lamp power in power-on initial state. This behavior is independent to setting of GPOM12.
 2. Add a pull down resistor on GPIO12 will indicate ASIC to turn off lamp power in power-on initial state. This behavior is independent to setting of GPOM12.
 3. This pin can control bipolar motor driver IC (2916,6219 or 3967) Vref for controlling I_{max} current when GPOM12 is set to '1'.
 GPIO11: This pin can control bipolar motor driver IC (2916,6219 or 3967) Vref for controlling I_{max} current when GPOM11 is set to '1'.
- 3 **GPOCK4** 0 Select pin62 as CCD_CK4X
 1 Select CCD_CK4X as GPO33
- 2 **GPOCP** 0 Select this pin68 as CCD_CPX.
 1 CCD_CPX as GPO32.
- 1 **GPOLEDB** 0 Select this pin as LED_B for CIS.
 1 Select LED_B as GPO28.
- 0 **GPOADF** 0 Select normal function for GPIO6 and GPO28.
 1 Select GPIO6 as motor STEP output of 3967 and GPO28(LED_B) as DIR output of 3967.

Offset 6Ch Default value = 8'h00

GPIO16	GPIO15	GPIO14	GPIO13	GPIO12	GPIO11	GPIO10	GPIO9
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 GPIO [16:9] GPIO16~9 input/output ports

Offset 6Dh Default value = 8'h00



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GPIO8	GPIO7	GPIO6	GPIO5	GPIO4	GPIO3	GPIO2	GPIO1
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 GPIO [8:1] GPIO8~1 input/output ports

Offset 6Eh Default value = 8'h00

GPOE16	GPOE15	GPOE14	GPOE13	GPOE12	GPOE11	GPOE10	GPOE9
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 GPOE [16:9] Select directions of GPIO16~9 ports. They can be set to different values independently.
 0 Set as input port.
 1 Set as output port.

Offset 6Fh Default value = 8'h00

GPOE8	GPOE7	GPOE6	GPOE5	GPOE4	GPOE3	GPOE2	GPOE1
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 GPOE [8:1] Select directions of GPIO8~1 ports. They can be set to different values independently.
 0 Set as input port.
 1 Set as output port.

Offset 70h Default value = 8'h06

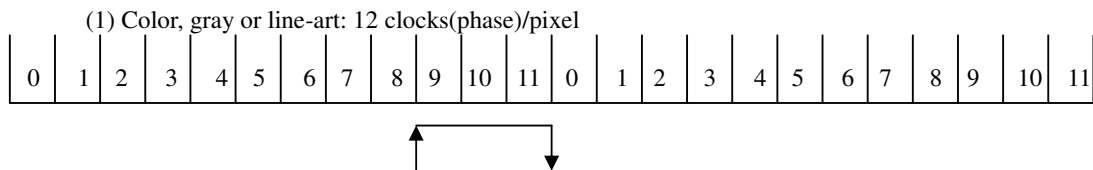
X	X	X	RSH4	RSH3	RSH2	RSH1	RSH0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -
4-0 RSH [4:0] Rising edge position of CCD RS.

Offset 71h Default value = 8'h08

X	X	X	RSL4	RSL3	RSL2	RSL1	RSL0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -
4-0 RSL [4:0] Falling edge position of CCD RS.



CCD RS : RSH=08H RSL=0BH

Note: 16 clocks(phase)/pixel and 18 clocks(phase)/pixel modes are similar to 12 clocks(phase)/pixel mode.

Offset 72h Default value = 8'h08

X	X	X	CPH4	CPH3	CPH2	CPH1	CPH0
---	---	---	------	------	------	------	------



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X	X	X	R/W	R/W	R/W	R/W	R/W
---	---	---	-----	-----	-----	-----	-----

7-5 RESERVED -

4-0 CPH [4:0] Rising edge position of CCD CP.

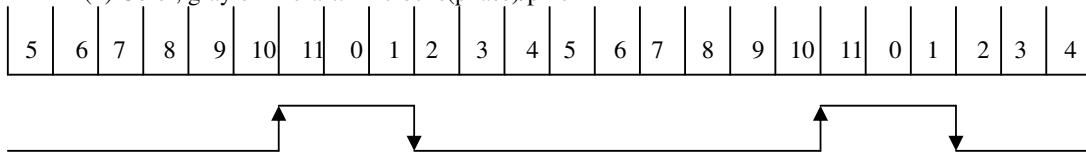
Offset 73h Default value = 8'h0A

X	X	X	CPL4	CPL3	CPL2	CPL1	CPL0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 RESERVED -

4-0 CPL [4:0] Falling edge position of CCD CP.

(1) Color, gray or line-art: 12 clocks(phase)/pixel



CCD CP : CPH=0AH CPL=01H

Note: 16 clocks(phase)/pixel and 18 clocks(phase)/pixel modes are similar to 12 clocks(phase)/pixel mode.

Offset 74h Default value = 8'h00

X	X	X	X	X	X	CK1MAP17	CK1MAP16
X	X	X	X	X	X	R/W	R/W

7-2 RESERVED -

1-0 CK1MAP [17:16] Bits mapping setting for CCD clock 1 or 2.

Offset 75h Default value = 8'h00

CK1MAP15	CK1MAP14	CK1MAP13	CK1MAP12	CK1MAP11	CK1MAP10	CK1MAP9	CK1MAP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 CK1MAP [15:8] Bits mapping setting for CCD clock 1 or 2.

Offset 76h Default value = 8'h00

CK1MAP7	CK1MAP6	CK1MAP5	CK1MAP4	CK1MAP3	CK1MAP2	CK1MAP1	CK1MAP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 CK1MAP [7:0] Bits mapping setting for CCD clock 1 or 2.

Offset 77h Default value = 8'h00

X	X	X	X	X	X	CK3MAP17	CK3MAP16
X	X	X	X	X	X	R/W	R/W

7-2 RESERVED -

1-0 CK3MAP [17:16] Bits mapping setting for CCD clock 3.



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Offset 78h Default value = 8'h00

CK3MAP15	CK3MAP14	CK3MAP13	CK3MAP12	CK3MAP11	CK3MAP10	CK3MAP9	CK3MAP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 CK3MAP [15:8] Bits mapping setting for CCD clock 3.

Offset 79h Default value = 8'h00

CK3MAP7	CK3MAP6	CK3MAP5	CK3MAP4	CK3MAP3	CK3MAP2	CK3MAP1	CK3MAP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 CK3MAP [7:0] Bits mapping setting for CCD clock 3.

Offset 7Ah Default value = 8'h00

X	X	X	X	X	X	CK4MAP17	CK4MAP16
X	X	X	X	X	X	R/W	R/W

7-2 RESERVED -

1-0 CK4MAP [17:16] Bits mapping setting for CCD clock 4.

Offset 7Bh Default value = 8'h00

CK4MAP15	CK4MAP14	CK4MAP13	CK4MAP12	CK4MAP11	CK4MAP10	CK4MAP9	CK4MAP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 CK4MAP [15:8] Bits mapping setting for CCD clock 4.

Offset 7Ch Default value = 8'h00

CK4MAP7	CK4MAP6	CK4MAP5	CK4MAP4	CK4MAP3	CK4MAP2	CK4MAP1	CK4MAP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 CK4MAP[7:0] Bits mapping setting for CCD clock 4.

Offset 7Dh Default value = 8'h00

CK1NEG	CK3NEG	CK4NEG	RSNEG	CPNEG	BSMPNEG	VSMPEG	DLYSET
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 CK1NEG
 - 0 CCD clock1,clock2 output are synchronized with rising edge of system clock.
 - 1 CCD clock1 & clock2 output are synchronized with falling edge of system clock.
- 6 CK3NEG
 - 0 CCD clock3 output is synchronized with rising edge of system clock.
 - 1 CCD clock3 output is synchronized with falling edge of system clock.
- 5 CK4NEG
 - 0 CCD clock4 output is synchronized with rising edge of system clock.
 - 1 CCD clock4 output is synchronized with falling edge of system clock.
- 4 RSNEG
 - 0 CCD RS output is synchronized with rising edge of system clock.
 - 1 RS output is synchronized with falling edge of system clock.
- 3 CPNEG
 - 0 CCD CP output is synchronized with rising edge of system clock.
 - 1 CCD CP output is synchronized with falling edge of system clock.



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- 2 **BSMPNEG** 0 AFE video sample output is synchronized with rising edge of system clock.
1 AFE video sample output is synchronized with falling edge of system clock.
- 1 **VSMPNEG** 0 AFE dark sample output is synchronized with rising edge of system clock.
1 AFE dark sample output is synchronized with falling edge of system clock.
- 0 **DLYSET** 0 The function is disabled.
1 To enable VSMP and BSMP to delay output by 8.33ns unit. Please refer to Reg 7F.

Offset 7Eh Default value = 8'h00

GPOLED25	GPOLED24	GPOLED23	GPOLED22	GPOLED21	GPOLED10	GPOLED9	GPOLED8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 **GPOLED25** 0 Set GPIO25 as general purpose I/O.
1 Set GPIO25 as LED output.
- 6 **GPOLED24** 0 Set GPIO24 as general purpose I/O.
1 Set GPIO24 as LED output.
- 5 **GPOLED23** 0 Set GPIO23 as general purpose I/O.
1 Set GPIO23 as LED output.
- 4 **GPOLED22** 0 Set GPIO22 as general purpose I/O.
1 Set GPIO22 as LED output.
- 3 **GPOLED21** 0 Set GPIO21 as general purpose I/O.
1 Set GPIO21 as LED output.
- 2 **GPOLED10** 0 Set GPIO10 as general purpose I/O.
1 Set GPIO10 as LED output.
- 1 **GPOLED9** 0 Set GPIO9 as general purpose I/O.
1 Set GPIO9 as LED output.
- 0 **GPOLED8** 0 Set GPIO8 as general purpose I/O.
1 Set GPIO8 as LED output.

Offset 7Fh Default value = 8'h00

BSMPDLY1	BSMPDLY0	VSMPDLY1	VSMPDLY0	LEDCNT3	LEDCNT2	LEDCNT1	LEDCNT0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-6 **BSMPDLY[1:0]** BSMP output delay.
00 No delay.
01 Delay 8.33ns
10 Delay 16.67ns
11 Delay 25ns.
- 5-4 **VSMPDLY[1:0]** VSMP output delay.
00 No delay.
01 Delay 8.33ns
10 Delay 16.67ns
11 Delay 25ns.
- 3-0 **LEDCNT[1:0]** LED blinking period = (LEDCNT)*(100ms on + 100ms off).
LED will not blink if LEDCNT=0.

Offset 80h Default value = 8'h00

VRHOME1	VRHOME0	VRMOVE1	VRMOVE0	VRBACK1	VRBACK0	VRSCAN1	VRSCAN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W



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- 7-6 VRHOME[1:0] Vref. of the motor driver IC for go-home moving.
- 5-4 VRMOVE[1:0] Vref. of the motor driver IC for fast forward moving.
- 3-2 VRBACK[1:0] Vref. of the motor driver IC for backward moving when the image buffer is full.
- 1-0 VRSCAN[1:0] Vref. of the motor driver IC forward scanning moving.

Offset 81h Default value = 8'h00

X	X	X	X	X	X	X	ROFFSET8
X	X	X	X	X	X	X	R/W

- 7-1 RESERVED -
- 0 ROFFSET [8] R channel offset of the AFE for CIS color scanning

Offset 82h Default value = 8'h00

ROFFSET7	ROFFSET6	ROFFSET5	ROFFSET4	ROFFSET3	ROFFSET2	ROFFSET1	ROFFSET0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 ROFFSET [7:0] R channel offset of the AFE for CIS color scanning

Offset 83h Default value = 8'h00

X	X	X	X	X	X	X	GOFFSET8
X	X	X	X	X	X	X	R/W

- 7-1 RESERVED -
- 0 GOFFSET [8] G channel offset of the AFE for CIS color scanning

Offset 84h Default value = 8'h00

GOFFSET7	GOFFSET6	GOFFSET5	GOFFSET4	GOFFSET3	GOFFSET2	GOFFSET1	GOFFSET0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 GOFFSET [7:0] G channel offset of the AFE for CIS color scanning

Offset 85h Default value = 8'h00

X	X	X	X	X	X	X	BOFFSET8
X	X	X	X	X	X	X	R/W

- 7-1 RESERVED -
- 0 BOFFSET [8] B channel offset of the AFE for CIS color scanning

Offset 86h Default value = 8'h00

BOFFSET7	BOFFSET6	BOFFSET5	BOFFSET4	BOFFSET3	BOFFSET2	BOFFSET1	BOFFSET0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 BOFFSET [7:0] B channel offset of the AFE for CIS color scanning

Offset 87h Default value = 8'h00

LED4TG	YENB	YBIT	ACYCNRLC	ENOFFSET	LEDADD	CK4ADC	AUTOCONF
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7 LED4TG** 0 Disable one dummy line for CIS motor moving purpose.
 1 Enable one dummy line for CIS motor moving purpose.
- 6 YENB** 0 Disable PH_Y output of the YBIT.
 1 Enable PH_Y output of the YBIT to improve half-step operation of motor control.
- 5 YBIT** Output port of PH_Y control signal to control I_{max} of 1939/1940 motor driver IC.
- 4 ACYCNRLC** 0 Disable this function.
 1 Generate RLC/ACYC pulse through BSMP pin to trigger Wolfson AFE auto-cycling for line-by-line color scanning.
- 3 ENOFFSET** 0 To disable this function.
 1 To select automatic offset configuration for CIS color scanning.
- 2 LEDADD** 0 Normal gray by controlling CIS single color LED array.
 1 Enable true gray weighting in CIS by separately controlling the exposure times of R, G, B LED array. Please refer to Reg 10~15.
- 1 CK4ADC** 0 Select MCLK (ADCCLK) to output default timing for specified AFE.
 1 Select MCLK (ADCCLK) pin to output according to pattern defined by CK4MAP (Reg 7A,7B,7C).
- 0 AUTOCONF** 0 To disable these functions.
 1 Enable automatic channel switching and offset configuration for CIS color scanning.

Note: If YBIT=1, then YENB=1 => PH_Y=1; YENB=0 => PH_Y=0.
 If YBIT=0, then YENB=1 => PH_Y=0; YENB=0 => PH_Y=1.

Offset 88h Default value = 8'h00

X	X	X	RDNUM4	RDNUM3	RDNUM2	RDNUM1	RDNUM0
X	X	X	R/W	R/W	R/W	R/W	R/W

- 7-5 RESERVED** -
- 4-0 RDNUM[4:0]** Set the receiving length in bytes of RS232 interface.

Offset 89h

RS232WD7	RS232WD6	RS232WD5	RS232WD4	RS232WD3	RS232WD2	RS232WD1	RS232WD0
-	-	-	-	-	-	-	-

- 7-0 RS232WD[7:0]** This port is for designers to write data to RS232 interface.

Offset 8Ah

RS232RD7	RS232RD6	RS232RD5	RS232RD4	RS232RD3	RS232RD2	RS232RD1	RS232RD0
-	-	-	-	-	-	-	-

- 7-0 RS232RD[7:0]** This port is for designers to read data to RS232 interface.

Offset 8Fh Default value = 8'h00

X	X	X	X	RREFED19	RREFED18	RREFED17	RREFED16
X	X	X	X	R/W	R/W	R/W	R/W

7-4 RESERVED -

3-0 RREFED [19:16] Pre-feed steps for ADF (or sheetfed scanner).

Offset 90h Default value = 8'h00

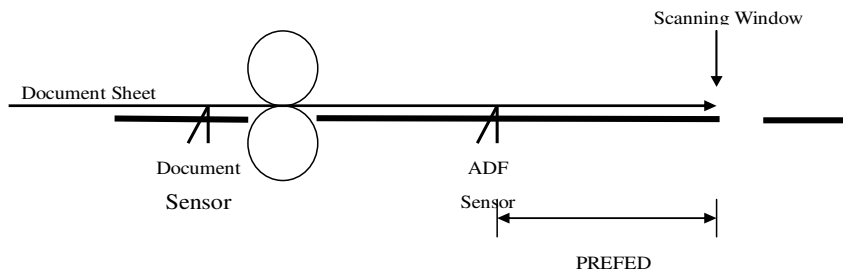
RREFED15	RREFED14	RREFED13	RREFED12	RREFED11	RREFED10	RREFED9	RREFED8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 RREFED [15:8] Pre-feed steps for ADF (or sheetfed scanner).

Offset 91h Default value = 8'h00

RREFED7	RREFED6	RREFED5	RREFED4	RREFED3	RREFED2	RREFED1	RREFED0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 RREFED [7:0] Pre-feed steps for ADF (or sheetfed scanner).



Note: If the DPI9600 control bit is set to "1", the STRPIXEL is doubled.

Offset 92h Default value = 8'h00

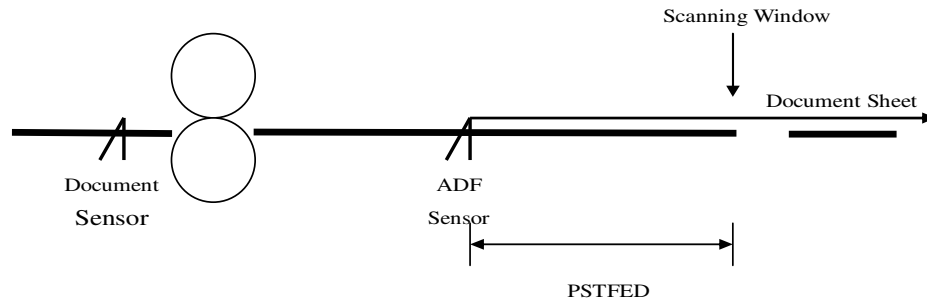
PSTFED15	PSTFED14	PSTFED13	PSTFED12	PSTFED11	PSTFED10	PSTFED9	PSTFED8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 PSTFED [15:8] Past scanning steps for ADF (or sheetfed scanner).

Offset 93h Default value = 8'h00

PSTFED7	PSTFED6	PSTFED5	PSTFED4	PSTFED3	PSTFED2	PSTFED1	PSTFED0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 PSTFED [7:0] Past scanning steps for ADF (or sheetfed scanner).



Offset 94h Default value = 8'h00

MTRPLS7	MTRPLS6	MTRPLS5	MTRPLS4	MTRPLS3	MTRPLS2	MTRPLS1	MTRPLS0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 MTRPLS [7:0] Pulse width of ADF motor trigger signal (GPIO6). It's valid when ADFSEL = 1.

Offset 95h Default value = 8'h00

X	X	X	X	SCANLEN19	SCANLEN18	SCANLEN17	SCANLEN16
X	X	X	X	R/W	R/W	R/W	R/W

7-4 RESERVED -

4-0 SCANLEN [19:16] Scanning length limitation of ADF (or sheetfed scanner). If the scanned lines are larger than this value but document sensor is still active (ADF_SENR is high), the paper-jam bit (bit 3 in Reg 40) will be set.

Offset 96h Default value = 8'h00

SCANLEN15	SCANLEN14	SCANLEN13	SCANLEN12	SCANLEN11	SCANLEN10	SCANLEN9	SCANLEN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SCANLEN [8:15] Scanning length limitation of ADF (or sheetfed scanner).

Offset 97h Default value = 8'h00

SCANLEN7	SCANLEN6	SCANLEN5	SCANLEN4	SCANLEN3	SCANLEN2	SCANLEN1	SCANLEN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SCANLEN [7:0] Scanning length limitation of ADF (or sheetfed scanner).

Offset 98h Default value = 8'h00

ONDUR15	ONDUR14	ONDUR13	ONDUR12	ONDUR11	ONDUR10	ONDUR9	ONDUR8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 ONDUR [15:8] On duration (in system clock) of PWM for LAMP control.

Offset 99h Default value = 8'h00



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ONDUR7	ONDUR6	ONDUR5	ONDUR4	ONDUR3	ONDUR2	ONDUR1	ONDUR0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 ONDUR [7:0] On duration (in system clock) of PWM for LAMP control.

Offset 9Ah Default value = 8'h00

OFFDUR15	OFFDUR14	OFFDUR13	OFFDUR12	OFFDUR11	OFFDUR10	OFFDUR9	OFFDUR8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 OFFDUR [15:8] Off duration (in system clock) of PWM for LAMP control.

Offset 9Bh Default value = 8'h00

OFFDUR7	OFFDUR6	OFFDUR5	OFFDUR4	OFFDUR3	OFFDUR2	OFFDUR1	OFFDUR0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 OFFDUR [7:0] Off duration (in system clock) of PWM for LAMP control.

Offset 9Dh Default value = 8'h00

RAMDLY1	RAMDLY0	MOTLAG	X	STEPTIM2	STEPTIM1	STEPTIM0	X
R/W	R/W	R/W	R/W	R/W	R/W	R/W	X

7-6 RAMDLY [1:0] Select timing delay for SCLK of SDRAM.

- 5 MOTLAG** 0 Do not force the trigger position of motor trigger.
 1 Force motor to locate its trigger at the end of line when dummy lines function is activated.

3-1 STEPTIM [2:0] Select the multiplier of slope table. For Reg 21, 24, 5F, 69, 6A, the real slope steps are register values multiplied by STEPTIM.

- STEPTIM[2:0] =000 : Slope steps = register values
 =001 : Slope steps = register values * 2
 =010 : Slope steps = register values * 4
 =011 : Slope steps = register values * 8
 =100 : Slope steps = register values * 16
 =101 : Slope steps = register values * 32

Offset 9Eh Default value = 8'h00

X	X	TGSTIME2	TGSTIME1	TGSTIME0	TGWTIME2	TGWTIME1	TGWTIME0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

7-6 RESERVED -

5-3 TGSTIME [2:0] To set the times of TGSHLD[4:0] . So , the width is TGSHLD[4:0]* 2^{TGSTIME}

2-0 TGWTIME [2:0] To set the times of TGW[5:0] . So, the width is TGW [5:0]* 2^{TGWTIME}

Offset 9Fh Default value = 8'h00

X	X	X	FULLPAGE	AUTOADF	MOTMPU	MULDMYLN	DPI9600
X	X	X	R/W	R/W	R/W	R/W	R/W

- 4 FULLPAGE** 0 To select general operation of motor when the Start/Stop occurs
 1 To enable full-page operation of motor during ADF scanning



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- 3 **AUTOADF** 0 To select one-page scanning under ADF operation
 1 To enable multi-page scanning under ADF operation
- 2 **MOTMPU** To select motor trigger output to MPU. The MPU can process the trigger signal.
Note: If designer set MOTMPU=1 then he must set ACDCDIS=1.
- 1 **MULDMYLN** 0 Set dummy lines are equal to LINESEL.
 1 Set dummy lines are equal to LINESEL*2
- 0 **DPI9600** To enable 9600d resolution.

Offset A0h Default value = 8'h00

X	X	LNOFSET5	LNOFSET4	LNOFSET3	LNOFSET2	LNOFSET1	LNOFSET0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

7-6 **RESERVED** -

5-0 **LNOFSET [5:0]** Line difference of R, G, B in packing three channels to one color line.

Offset A1h Default value = 8'h80

SNRSYN2	SNRSYN1	SNRSYN0	STGSET4	STGSET3	STGSET2	STGSET1	STGSET0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-5 **SNRSYN [2:0]** Sensor debouncing such as HOME sensor.

4-0 **STGSET [4:0]** Line difference of stagger CCD between even and odd lines in packing them to the same color line.

Offset A2h Default value = 8'h00

X	X	X	RFHSET4	RFHSET3	RFHSET2	RFHSET1	RFHSET0
X	X	X	R/W	R/W	R/W	R/W	R/W

7-5 **RESERVED** -

4-0 **RFHSET[4:0]** Refresh time of SDRAM.
 The unit is 2us.

Offset A3h Default value = 8'h00

TRUER7	TRUER6	TRUER5	TRUER4	TRUER3	TRUER2	TRUER1	TRUER0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 **TRUER [7:0]** Weighting of R channel in true gray scanning.

Offset A4h Default value = 8'h00

TRUEG7	TRUEG6	TRUEG5	TRUEG4	TRUEG3	TRUEG2	TRUEG1	TRUEG0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 **TRUEG [7:0]** Weighting of G channel in true gray scanning.

Offset A5h Default value = 8'h00



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TRUEB7	TRUEB6	TRUEB5	TRUEB4	TRUEB3	TRUEB2	TRUEB1	TRUEB0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 TRUEB [7:0] Weighting of B channel in true gray scanning.

Offset A6h Default value = 8'h00

X	X	X	GPIO21	GPIO20	GPIO19	GPIO18	GPIO17
X	X	X	R/W	R/W	R/W	R/W	R/W

7-0 GPIO [21:17] GPIO21~17 input/output ports.

Offset A7h Default value = 8'h00

X	X	X	GPOE21	GPOE20	GPOE19	GPOE18	GPOE17
X	X	X	R/W	R/W	R/W	R/W	R/W

7-0 GPOE [21:17] Select directions of GPIO21~17 ports. They can be set to different values independently.
 0 Set as input port.
 1 Set as output port.

Offset A8h Default value = 8'h00

X	X	ADFSNRDIS	X	X	X	X	X
X	X	R/W	X	X	X	X	X

5 ADFSNRDIS 0 Enable ADF sensor when working on ADF mode.
 1 Disable ADF sensor.

Offset A9h Default value = 8'h00

X	GPO34	GPO33	GPO32	GPO31	X	X	GPO28
X	R/W	R/W	R/W	R/W	X	X	R/W

6-3 GPO34~31 GPO34~31 output ports.
0 GPO28 output port.

Offset AAh Default value = 8'h00

RESERVE7	RESERVE6	RESERVE5	RESERVE4	RESERVE3	RESERVE2	RESERVE1	RESERVE0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 RESERVE7 [7:0] The 8 bits registers are reserved for special application

Offset ABh Default value = 8'h00

GPOM9	MULSTOP2	MULSTOP1	MULSTOP0	NODECEL	TB3TB1	TB5TB2	FIX16CLK
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-6 GPOM9 0 Select GPIO9 as general purpose I/O.
 1 Select GPIO9 as V-ref control of bipolar motor driver IC to control I_{max}



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- 6-4 MULSTOP [2:0]** Select stop time of motor start/stop. The stop time = $STOPTIM * 2^{MULSTOP}$
- 3 NODECEL** 0 Motor decelate when carriage touch home sensor
1 Motor doesn't decelerate when carriage touch home sensor
 - 2 TB3TB1** 0 Don't replace.
1 Use table 1 of motor table to replace table 3.
 - 1 TB5TB2** 0 Don't replace.
1 Use table 2 of motor table to replace table 5.
 - 0 FIX16CLK** To enable 16 system clocks/pixel recover function

Offset ACh Default value = 8'h00

VRHOME3	VRHOME2	VRMOVE3	VRMOVE2	VRBACK3	VRBACK2	VRSCAN3	VRSCAN2
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-6 VRHOME [3:2]** Vref of the motor driver IC for go-home moving
- 5-4 VRMOVE [3:2]** Vref of the motor driver IC for fast forward moving
- 3-2 VRBACK [3:2]** Vref of the motor driver IC for backward moving when the image buffer is full

Offset ADh Default value = 8'h00

X	X	X	SWSH4	SWSH3	SWSH2	SWSH1	SWSH0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 4-0 SWSH [4:0]** To set the distance from SW to TG for NEC/Toshiba CCD. The width is $SWSH[4:2]*2^{TGSTIME}$

Offset AEh Default value = 8'h00

X	X	STOPPWM5	STOPPWM4	STOPPWM3	STOPPWM2	STOPPWM1	STOPPWM0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

- 7-6 RESERVED** -
- 5-0 STOPPWM [5:0]** Set the PWM control of motor driver IC during motor stopping.

Offset B8h Default value = 8'h00

X	X	X	X	SW2_EN	SW2_SEL	X	X
X	X	X	X	R/W	R/W	X	X

- 3 SW2_EN** Enable special CCD timing of CCD SW2 for special application
- 2 SW2_SEL** 0 CCD SW2 and CCD SW5 timing control is based on internal CCD_CNx counter of ASIC
1 CCD SW2 and CCD SW5 timing control is based on internal SH_CNT counter of ASIC

Offset BAh Default value = 8'h00

CCD_OUT	AV_EN	X	X	X	X	X	X
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R/W	R/W	X	X	X	X	X	X
-----	-----	---	---	---	---	---	---

- 7 **CCD_OUT** Enable internal CCD signal outputs including sh_enb, sh_enbx and ccd_cnt[2:0] for external CPLD implementation to meet special CCD timing
- 6 **AV_EN** Enable switch control for special CCD or CIS

Offset BBh Default value = 8'h00

X	X	MT_OFF13	MT_OFF12	MT_OFF11	MT_OFF10	MT_OFF9	MT_OFF8
X	X	R/W	R/W	R/W	R/W	R/W	R/W

- 5-0 **MT_OFF [13:8]** Output motor-off timing when motor releases the power for motor phase table operation

Offset BCh Default value = 8'hFF

MT_OFF7	MT_OFF6	MT_OFF5	MT_OFF4	MT_OFF3	MT_OFF2	MT_OFF1	MT_OFF0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

- 7-0 **MT_OFF [7:0]** Output motor-off timing when motor releases the power for motor phase table operation

Offset BDh Default value = 8'h1F

SW5_EN	SW5_SEL	SW5EXCHG	X	X	BGMM_N	GGMM_N	RGMM_N
R/W	R/W	R/W	X	X	R/W	R/W	R/W

- 7 **SW5_EN** Enable special CCD timing of CCD SW5 for special application
- 6 **SW5_SEL** Control CCD SW5 output which is based on internal CCD_CNXX0 or CCD_CNXX1 of ASIC
- 5 **SW5EXCHG** Control output position of CCD SW5 which is based on CCD SH
- 2 **BGMM_N** If this bit is set to "1", it indicates that table[256] of B gamma in RAM is ignored and replaced by "-1"
- 1 **GGMM_N** If this bit is set to "1", it indicates that table[256] of G gamma in RAM is ignored and replaced by "-1"
- 0 **RGMM_N** If this bit is set to "1", it indicates that table[256] of R gamma in RAM is ignored and replaced by "-1"

Offset BEh Default value = 8'h00

SW2INV	X	SW5INV	X	X	BGMM_F	GGMM_F	RGMM_F
X	X	R/W	X	X	R/W	R/W	R/W



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- 7 **SW2INV** Invert CCD SW2 output
- 5 **SW5INV** Invert CCD SW5 output
- 2 **BGMM_F** If this bit is set to “1”, it indicates that table[256] of B gamma in RAM is ignored and replaced by “0x10000”
- 1 **GGMM_F** If this bit is set to “1”, it indicates that table[256] of G gamma in RAM is ignored and replaced by “0x10000”
- 0 **RGMM_F** If this bit is set to “1”, it indicates that table[256] of R gamma in RAM is ignored and replaced by “0x10000”

Offset BFh Default value = 8'h00

X	X	SC_NUM5	SC_NUM4	SC_NUM3	SC_NUM2	SC_NUM1	SC_NUM0
X	X	R/W	R/W	R/W	R/W	R/W	R/W

5-0 **SC_NUM [5:0]** Page count scanned when scanner works on ADF mode

Offset C5h Default value = 8'h00

RGMM_Z15	RGMM_Z14	RGMM_Z13	RGMM_Z12	RGMM_Z11	RGMM_Z10	RGMM_Z9	RGMM_Z8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 **RGMM_Z [15:8]** Bit15~8 setting of table[0] for R gamma

Offset C6h Default value = 8'h00

RGMM_Z7	RGMM_Z6	RGMM_Z5	RGMM_Z4	RGMM_Z3	RGMM_Z2	RGMM_Z1	RGMM_Z0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 **RGMM_Z [7:0]** Bit7~0 setting of table[0] for R gamma

Offset C7h Default value = 8'h00

GGMM_Z15	GGMM_Z14	GGMM_Z13	GGMM_Z12	GGMM_Z11	GGMM_Z10	GGMM_Z9	GGMM_Z8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-5 **GGMM_Z [15:8]** Bit15~8 setting of table[0] for G gamma

Offset C8h Default value = 8'h00

GGMM_Z7	GGMM_Z6	GGMM_Z5	GGMM_Z4	GGMM_Z3	GGMM_Z2	GGMM_Z1	GGMM_Z0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 **GGMM_Z [7:0]** Bit7~0 setting of table[0] for G gamma

Offset C9h Default value = 8'h00



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BGMM_Z15	BGMM_Z14	BGMM_Z13	BGMM_Z12	BGMM_Z11	BGMM_Z10	BGMM_Z9	BGMM_Z8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 BGMM_Z [15:8] Bit15~8 setting of table[0] for B gamma

Offset CAh Default value = 8'h00

BGMM_Z7	BGMM_Z6	BGMM_Z5	BGMM_Z4	BGMM_Z3	BGMM_Z2	BGMM_Z1	BGMM_Z0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 BGMM_Z [7:0] Bit7~0 setting of table[0] for B gamma

Offset D0h Default value = 8'h00

SH0DWN7	SH0DWN6	SH0DWN5	SH0DWN4	SH0DWN3	SH0DWN2	SH0DWN1	SH0DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-5 SH0DWN [7:0] Shading bank0 address setting for CCD. Unit is in 4k words.
It is also R-Channel shading bank0 address setting for CIS

Offset D1h Default value = 8'h00

SH1DWN7	SH1DWN6	SH1DWN5	SH1DWN4	SH1DWN3	SH1DWN2	SH1DWN1	SH1DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH1DWN [7:0] Shading bank1 address setting for CCD. Unit is in 4k words.
It is also G-Channel shading bank0 address setting for CIS

Offset D2h Default value = 8'h00

SH2DWN7	SH2DWN6	SH2DWN5	SH2DWN4	SH2DWN3	SH2DWN2	SH2DWN1	SH2DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH2DWN [7:0] Shading bank2 address setting for CCD. Unit is in 4k words.
It is also B-Channel shading bank0 address setting for CIS

Offset D3h Default value = 8'h00

SH3DWN7	SH3DWN6	SH3DWN5	SH3DWN4	SH3DWN3	SH3DWN2	SH3DWN1	SH3DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH3DWN [7:0] Shading bank3 address setting for CCD. Unit is in 4k words.
It is also Channel-4 shading bank0 address setting for CIS

Offset D4h Default value = 8'h00



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SH4DWN7	SH4DWN6	SH4DWN5	SH4DWN4	SH4DWN3	SH4DWN2	SH4DWN1	SH4DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH4DWN [7:0] Shading bank4 address setting for CCD. Unit is in 4k words.
It is also Channel-5 shading bank0 address setting for CIS

Offset D5h Default value = 8'h00

SH5DWN7	SH5DWN6	SH5DWN5	SH5DWN4	SH5DWN3	SH5DWN2	SH5DWN1	SH5DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH5DWN [7:0] Shading bank5 address setting for CCD. Unit is in 4k words.
It is also R-Channel shading bank1 address setting for CIS

Offset D6h Default value = 8'h00

SH6DWN7	SH6DWN6	SH6DWN5	SH6DWN4	SH6DWN3	SH6DWN2	SH6DWN1	SH6DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH6DWN [7:0] Shading bank6 address setting for CCD. Unit is in 4k words.
It is also G-Channel shading bank1 address setting for CIS

Offset D7h Default value = 8'h00

SH7DWN7	SH7DWN6	SH7DWN5	SH7DWN4	SH7DWN3	SH7DWN2	SH7DWN1	SH7DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH7DWN [7:0] Shading bank7 address setting for CCD. Unit is in 4k words.
It is also B-Channel shading bank1 address setting for CIS

Offset D8h Default value = 8'h00

SH8DWN7	SH8DWN6	SH8DWN5	SH8DWN4	SH8DWN3	SH8DWN2	SH8DWN1	SH8DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH8DWN [7:0] Shading bank8 address setting for CCD. Unit is in 4k words.
It is also Channel-4 shading bank1 address setting for CIS

Offset D9h Default value = 8'h00

SH9DWN7	SH9DWN6	SH9DWN5	SH9DWN4	SH9DWN3	SH9DWN2	SH9DWN1	SH9DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 SH9DWN [7:0] Shading bank9 address setting for CCD. Unit is in 4k words.
It is also Channel-5 shading bank1 address setting for CIS

Offset DAh Default value = 8'h00



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PROTLN15	PROTLN14	PROTLN13	PROTLN12	PROTLN11	PROTLN10	PROTLN9	PROTLN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 PROTLN [15:8] Minimum scanning length protection setting for ADF operation

Offset DBh Default value = 8'h00

PROTLN7	PROTLN6	PROTLN5	PROTLN4	PROTLN3	PROTLN2	PROTLN1	PROTLN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 PROTLN [7:0] Minimum scanning length protection setting for ADF operation

Offset E0h Default value = 8'h00

R1DWN15	R1DWN14	R1DWN13	R1DWN12	R1DWN11	R1DWN10	R1DWN9	R1DWN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R1DWN [15:8] Bit15~8 Registers setting for R-Channel ODD image buffer start-address.
When working on CIS mode, it is for ODD image buffer start-address setting.
Unit is in 1k words.

Offset E1h Default value = 8'h00

R1DWN7	R1DWN6	R1DWN5	R1DWN4	R1DWN3	R1DWN2	R1DWN1	R1DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R1DWN [7:0] Bit7~0 Registers setting for R-Channel ODD image buffer start-address.
When working on CIS mode, it is for ODD image buffer start-address setting.
Unit is in 1k words.

Offset E2h Default value = 8'h00

R1UP15	R1UP14	R1UP13	R1UP12	R1UP11	R1UP10	R1UP9	R1UP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R1UP[15:8] Bit15~8 Registers setting for R-Channel ODD image buffer end-address.
When working on CIS mode, it is for ODD image buffer end-address setting.
Unit is in 1k words.

Offset E3h Default value = 8'h00

R1UP7	R1UP6	R1UP5	R1UP4	R1UP3	R1UP2	R1UP1	R1UP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R1UP [7:0] Bit7~0 Registers setting for R-Channel ODD image buffer end-address.



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When working on CIS mode, it is for ODD image buffer end-address setting.

Unit is in 1k words.

Offset E4h Default value = 8'h00

R2DWN15	R2DWN14	R2DWN13	R2DWN12	R2DWN11	R2DWN10	R2DWN9	R2DWN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R2DWN [15:8] Bit15~8 Registers setting for R-Channel EVEN image buffer start-address.

When working on CIS mode, it is for EVEN image buffer start-address setting.

Unit is in 1k words.

Offset E5h Default value = 8'h00

R2DWN7	R2DWN6	R2DWN5	R2DWN4	R2DWN3	R2DWN2	R2DWN1	R2DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R2DWN [7:0] Bit7~0 Registers setting for R-Channel EVEN image buffer start-address.

When working on CIS mode, it is for EVEN image buffer start-address setting.

Unit is in 1k words.

Offset E6h Default value = 8'h00

R2UP15	R2UP14	R2UP13	R2UP12	R2UP11	R2UP10	R2UP9	R2UP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R2UP[15:8] Bit15~8 Registers setting for R-Channel EVEN image buffer end-address.

When working on CIS mode, it is for EVEN image buffer end-address setting.

Unit is in 1k words.

Offset E7h Default value = 8'h00

R2UP7	R2UP6	R2UP5	R2UP4	R2UP3	R2UP2	R2UP1	R2UP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 R2UP [7:0] Bit7~0 Registers setting for R-Channel EVEN image buffer end-address.

When working on CIS mode, it is for EVEN image buffer end-address setting.

Unit is in 1k words.

Offset E8h Default value = 8'h00

G1DWN15	G1DWN14	G1DWN13	G1DWN12	G1DWN11	G1DWN10	G1DWN9	G1DWN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G1DWN [15:8] Bit15~8 Registers setting for G-Channel ODD image buffer start-address. Unit is



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in 1k words

Offset E9h Default value = 8'h00

G1DWN7	G1DWN6	G1DWN5	G1DWN4	G1DWN3	G1DWN2	G1DWN1	G1DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G1DWN [7:0] Bit7~0 Registers setting for G-Channel ODD image buffer start-address. Unit is in 1k words.

Offset EAh Default value = 8'h00

G1UP15	G1UP14	G1UP13	G1UP12	G1UP11	G1UP10	G1UP9	G1UP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G1UP[15:8] Bit15~8 Registers setting for G-Channel ODD image buffer end-address. Unit is in 1k words.

Offset EBh Default value = 8'h00

G1UP7	G1UP6	G1UP5	G1UP4	G1UP3	G1UP2	G1UP1	G1UP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G1UP [7:0] Bit7~0 Registers setting for G-Channel ODD image buffer end-address. Unit is in 1k words.

Offset ECh Default value = 8'h00

G2DWN15	G2DWN14	G2DWN13	G2DWN12	G2DWN11	G2DWN10	G2DWN9	G2DWN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G2DWN [15:8] Bit15~8 Registers setting for G-Channel EVEN image buffer start-address. Unit is in 1k words

Offset EDh Default value = 8'h00

G2DWN7	G2DWN6	G2DWN5	G2DWN4	G2DWN3	G2DWN2	G2DWN1	G2DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G2DWN [7:0] Bit7~0 Registers setting for G-Channel EVEN image buffer start-address. Unit is in 1k words.

Offset EEh Default value = 8'h00

G2UP15	G2UP14	G2UP13	G2UP12	G2UP11	G2UP10	G2UP9	G2UP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W



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7-0 G2UP [15:8] Bit15~8 Registers setting for G -Channel EVEN image buffer end-address. Unit is in 1k words

Offset EFh Default value = 8'h00

G2UP7	G2UP6	G2UP5	G2UP4	G2UP3	G2UP2	G2UP1	G2UP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 G2UP [7:0] Bit7~0 Registers setting for G -Channel EVEN image buffer end-address. Unit is in 1k words

Offset F0h Default value = 8'h00

B1DWN15	B1DWN14	B1DWN13	B1DWN12	B1DWN11	B1DWN10	B1DWN9	B1DWN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B1DWN [15:8] Bit15~8 Registers setting for B-Channel ODD image buffer start-address. Unit is in 1k words.

Offset F1h Default value = 8'h00

B1DWN7	B1DWN6	B1DWN5	B1DWN4	B1DWN3	B1DWN2	B1DWN1	B1DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B1DWN [7:0] Bit7~0 Registers setting for B-Channel ODD image buffer start-address. Unit is in 1k words.

Offset F2h Default value = 8'h00

B1UP15	B1UP14	B1UP13	B1UP12	B1UP11	B1UP10	B1UP9	B1UP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B1UP[15:8] Bit15~8 Registers setting for B-Channel ODD image buffer end-address. Unit is in 1k words.

Offset F3h Default value = 8'h00

B1UP7	B1UP6	B1UP5	B1UP4	B1UP3	B1UP2	B1UP1	B1UP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B1UP [7:0] Bit7~0 Registers setting for B-Channel ODD image buffer end-address. Unit is in 1k words.

Offset F4h Default value = 8'h00



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B2DWN15	B2DWN14	B2DWN13	B2DWN12	B2DWN11	B2DWN10	B2DWN9	B2DWN8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B2DWN [15:8] Bit15~8 Registers setting for B-Channel EVEN image buffer start-address. Unit is in 1k words

Offset F5h Default value = 8'h00

B2DWN7	B2DWN6	B2DWN5	B2DWN4	B2DWN3	B2DWN2	B2DWN1	B2DWN0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B2DWN [7:0] Bit7~0 Registers setting for B-Channel EVEN image buffer start-address. Unit is in 1k words.

Offset F6h Default value = 8'h00

B2UP15	B2UP14	B2UP13	B2UP12	B2UP11	B2UP10	B2UP9	B2UP8
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B2UP [15:8] Bit15~8 Registers setting for B-Channel EVEN image buffer end-address. Unit is in 1k words

Offset F7h Default value = 8'h00

B2UP7	B2UP6	B2UP5	B2UP4	B2UP3	B2UP2	B2UP1	B2UP0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 B2UP [7:0] Bit7~0 Registers setting for B-Channel EVEN image buffer end-address. Unit is in 1k words

Offset F8h Default value = 8'h00

MAXSEL3	MAXSEL2	MAXSEL1	MAXSEL0	MINSEL3	MINSEL2	MINSEL1	MINSEL0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-4 MAXSEL [3:0] Define bank number of image buffer for buffer-full (for MAXWD)

3-0 MINSEL [3:0] Define bank number of image buffer for buffer-empty

MAXSEL/MINSEL :

0 → r_odd 1 → r_even

2 → g_odd 3 → g_even

4 → b_odd 5 → b_even

Offset FDh

MAINTSK3	MAINTSK2	MAINTSK1	MAINTSK0	SUBTSK3	SUBTSK2	SUBTSK1	SUBTSK0
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R	R	R	R	R	R	R	R
---	---	---	---	---	---	---	---

7-4 MAINTSK [3:0] To monitor internal flow control status of main task

3-0 SUBTSK [3:0] To monitor internal flow control status of main task

Offset FEh Default value = 8'h00

MOTTGST3	MOTTGST2	MOTTGST1	MOTTGST0	AUTO_O3	AUTO_O2	AUTO_O1	AUTO_O0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-4 MOTTGST [3:0] For debug usage

3-0 AUTO_O [3:0] Auto pattern offset --> unit : $2^{auto_o[3:0]}$

Offset FFh Default value = 8'h00

AUTO_S7	AUTO_S6	AUTO_S5	AUTO_S4	AUTO_S3	AUTO_S2	AUTO_S1	AUTO_S0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

7-0 AUTO_S [7:0] Auto pattern High byte initial value

Low byte initial value=0

$$auto_pattern[15:0] = AUTO_S[7:0] \ll 8 + 2^{AUTO_O[3:0]}$$

4.3 Motor Table

		Scanner Address[25:0]	AHB Address[31:0]
	Table 1	0000000H-0001FFFFH	0x1000_0000 – 0x100_3FFF

Motor Table (8K word/per table)	Table 2	0002000H~0003FFFH	0x1000_4000 – 0x100_7FFF
	Table 3	0004000H~0005FFFH	0x1000_8000 – 0x100_BFFF
	Table 4	0006000H~0007FFFH	0x1000_C000 – 0x100_FFFF
	Table 5	0008000H~0009FFFH	0x1001_0000 – 0x101_3FFF

4.4 AHB address allocation

Address range	Size (Byte)	Mapping	Module
0x0000_0000 – 0x0FFF_FFFF	256M	On-chip register	APB bridge
0x1000_0000 – 0x17FF_FFFF	128M	SDRAM (16bits)	Scanner controller

4.5 On-chip registers (APB) address allocation

Address range	Size (Byte)	Data width (bit)	Module
0x0000_0000 – 0x0000_01FF	512	8	Scanner register
0x0100_0000 – 0x0100_09FF	2560	16	Scanner gamma table
0x0100_0000 – 0x0100_01FF	512	16	gamma R (256x16)
0x0100_0200 – 0x0100_03FF	512	16	gamma G (256x16)
0x0100_0400 – 0x0100_05FF	512	16	gamma B (256x16)
0x0100_0600 – 0x0100_07FF	512	16	gamma CH4 (256x16)
0x0100_0800 – 0x0100_09FF	512	16	gamma CH5 (256x16)
0x0100_0A00 – 0x0100_0A7F	128	16	motor phase table (64x14)
0x0110_0000 – 0x0110_007F	128	32	scan count ram(32x20)
0x0200_0000 – 0x0200_03FF		8	USB register



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CHAPTER 5 BLOCK DIAGRAM

5.1 USB2.0 System Block Diagram

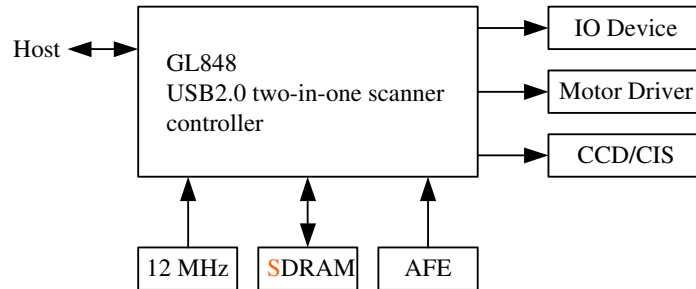


Figure 5.1 - USB2.0 System Block Diagram

5.2 Function Block Diagram

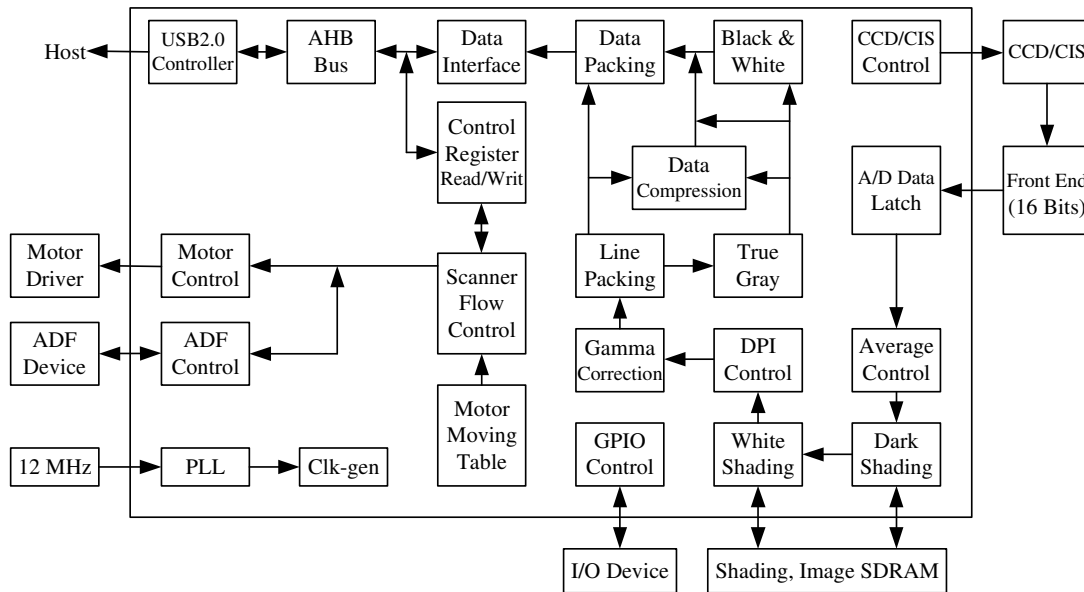


Figure 5.2 - Function Block Diagram



CHAPTER 6 FUNCTIONAL DESCRIPTION

1 System Clock

Internal PLL.

- A. Input: 12MHz crystal.
- B. Output: 12, 24, 30, 40, 48 or 60 MHz to scanner controller system.

2 Pixel Clock

- A. Normal mode
Scan mode 0:
 - a. 12 system clock/pixel.
 - b. Chunky color (three line in), gray or art scanning for CCD.
 - c. Planar color scan (one line in) or Monochrome scanning for CIS.
- B. fast mode
Scan mode 2:
 - a. 8 system clock/pixel.
 - b. fast gray or art scanning for CCD or CIS.
 - c. Planar color scan (one line in) or Monochrome scanning for CIS.
- C. Scan mode 7
 - a. 16 system clock/pixel.
 - b. Chunky color (three line in), gray or line-art scanning for CCD.
 - c. Planar color scan (one line in) or Monochrome scanning for CIS.
- D. Scan mode 6
 - a. 18 system clock/pixel
 - b. Chunky color (three line in), gray or art scanning for CCD.
 - c. Planar color scan (one line in) or Monochrome scan for CIS.

Note: Chunky Color is R1G1B1, R2G2B2, R3G3B3,.....(three-line-in or pixel rate).
Planar Color is R1, R2, R3,.....; G1, G2, G3,.....; B1, B2, B3,.....(one-line-in or line rate).
CCD: Chunky color or planar color.
CIS: Planar color.

3 Scan Speed

- A. System clock = 30MHz:
 - a. Normal Mode: Chunky color, fine gray or fine line art scan.
(scan mode 0) $12 \times 33.333\text{ns/pixel} = 0.4\mu\text{s/pixel}$
 - (1). 600dpi: 2.160ms/line, 15.163s/page.
 - (2). 1200dpi: 4.320ms/line, 60.653s/page.
- B. System clock = 40MHz:
 - a. Normal Mode: Chunky color, fine gray or fine line art scan.
 $12 \times 25\text{ns/pixel} = 0.3\mu\text{s/pixel}$
 - (1). 600dpi: 1.620ms/line, 11.372s/page.
 - (2). 1200dpi: 3.240ms/line, 45.488s/page.

4 Fast Scan for Low Resolutions

Designers are allowed to increase CCD clock rates to up scanning speed in low resolutions, such as 2, 4, 8, ...times..

5 Scanning Type

GL848 supports three-line-in (parallel) for CCD and one-line-in for CIS.

A. CCD Type

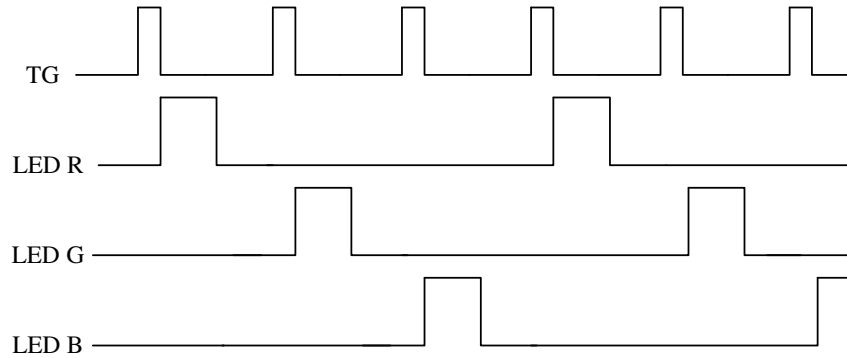
CCD Exposure control:

There are three modes to control CCD TG by TGMODE control bits.

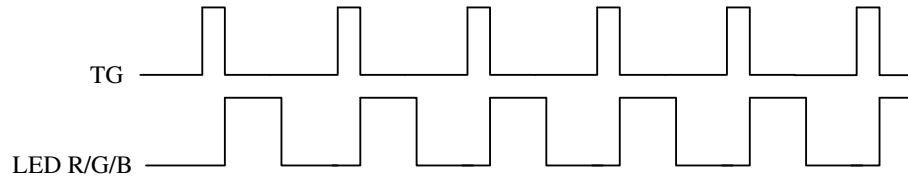
Mode 0: single exposure time for R, G and B channels.
 Mode 1, 2: different exposure times for R, G and B channels .

B. CIS Type

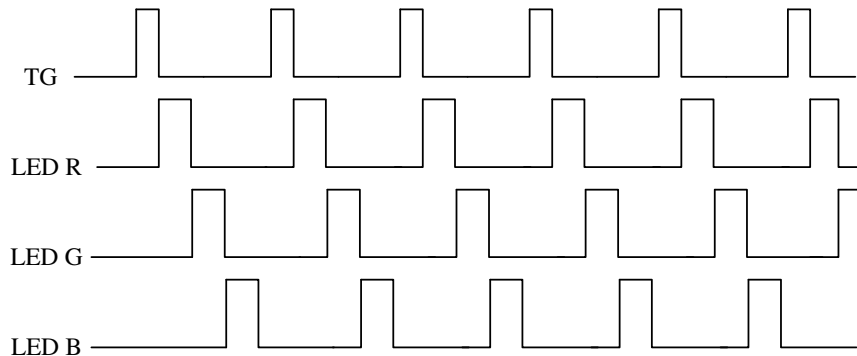
a. Color scan:



b. Gray scan:



c. True gray scan:



6 Image Sensor Timing

Image sensor timings can be programmed by S/W.

- A. For CCD: Support 600, 1200, 2400, 3200, 3600, 4800dpi ~ 9600dpi CCD such as NEC, TOSHIBA, Sonyetc.
- B. For CIS: Support 600, 1200, 2400, 3200, 3600, 4800dpi ~ 9600dp CIS such as TOSHIBA, Canonetc

7 Dummy Line

GL848 supports programmable dummy lines to resolve (overcome) start/stop problem. Designers can insert dummy lines to reduce scanner start/stop events (buffer full).

A. Line base of dummy lines:

The range of dummy lines is 0~30 lines.

B. Adjustable dummy line:

The range is from the minimum shift time of CCD/CIS up to 2096K pixel time,

with 1 pixel time resolution.

8 Support Analog Front End Timing

GL848 supports external 16 bits front-end.
 Wolfson: WM8199, WM8196,..etc.
 Analog device: AD9826, ...etc.

9 Image Type

- A. Supports color, gray and line art scanning.
- B. Supports color filters options (R, G or B channels) in gray or line art scanning.
- C. Supports true gray with programmable R, G and B weightings.

10 Bits Depth

16*3 bits color, 16 bits gray level and 1 bit line art (Black & White).
 Image data type: 16 bits, 8 bits and 1 bit.

11 Shading & Correction

a. White Shading & Dark Shading:

White shading and dark shading are pixel-by-pixel corrections with 16-bit solution and can be enabled or disabled by S/W. The white shading curve is calculated by S/W.

Data arrangement: three line in mode: dark R1, white R1, dark G1, white G1, dark B1, white B1,
 dark R2, white R2, dark G2, white G2, dark B2, white B2,
 dark R3, white R3, dark G3, white G3, dark B3, white B3,
 one line in mode: dark R1, white R1, dark R2, white R2, dark R3, white R3...
 dark G1, white G1, dark G2, white G2, dark G3, white G3...
 dark B1, white B1, dark B2, white B2, dark B3, white B3...

White shading formula: $2000H * Target / (Wn-Dn) = White Gain data -----$ for 8 times system

White shading formula: $4000H * Target / (Wn-Dn) = White Gain data -----$ for 4 times system

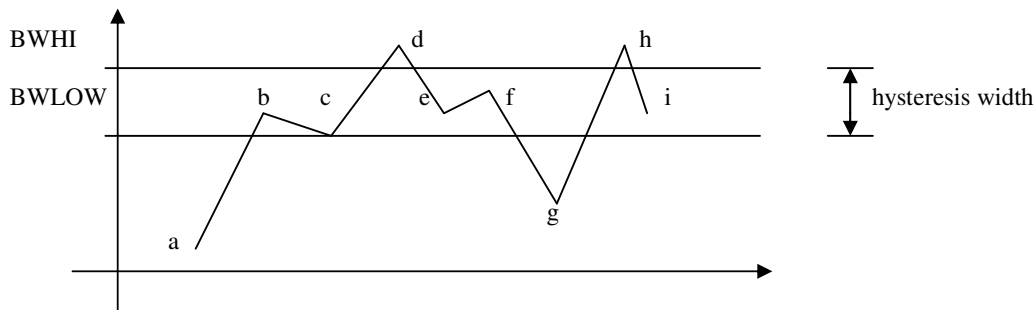
For example: Target = 3FFFH, Wn = 2FFFH, Dn = 0040H and 8 times system operation
 then White Gain = $2000H * 3FFFH / (2FFFH-0040H) = 2AE4H$ (1.34033 times)

b. Gamma Correction:

16-bit GAMMA correction table is programmed by S/W.
 Range: 0 ~ 64k (16 bits) input mapping to 0 ~ 64k (16 bits) or 0 ~ 255 (8 bits) output.
 Style: increment or decrement gamma curve

12 Threshold Setting for Line-Art

Threshold can be programmed by S/W.
 Range: 0 ~ 255 adjustable.
 The threshold with hysteresis characteristic is for reducing image noise.





a,b,c,g : are black pixels
d,e,f,h,i : are white pixels

13 Exposure Time

Maximum: 2096k pixels time

Adjustment step: 1 pixel time.

For transparency scanning, the exposure time can be up to 2096k pixels time.

14 Scan Width control for Horizontal Line

a. Supports start and end pixels assignment in setting scan width.

b. Scanning width= end pixels - start pixels

Maximum length: 128K pixels.

Minimum length: 1 pixel.

15 Support built-in USB 2.0 Controller

2-in-1 USB2.0 controller + scanner controller.

16 SDRAM Timing

Supports 16M Bits (1M*16), 64M Bits (4M*16), 128M Bits (8M*16), 256M Bits (16M*16) and 512 M Bits (32M*16) SDRAM as image buffer and calibration buffer. Designer can implement single chip or two chips of SDRAM.

17 Horizontal Resolution Adjustable for DPI Function

A. Digital deletion type:

Software adjustable resolutions range from 9600 to 1 dpi with 1 dpi decrement.

B. Digital average type:

Supports 1/2, 1/3, 1/4, 1/5, 1/6, 1/8, 1/10, 1/12, 1/15 digital average function.

For example, options for 1200dpi scanner are:

1200dpi, 600dpi, 400dpi, 300dpi, 240dpi, 200dpi, 150dpi, 120dpi, 100dpi, 80dpi by average function.

C. Support stagger CCD:

Supports 1/2, 1/4, 1/8 resolutions, such as NEC Toshiba and Sony stagger CCD.

18 Vertical Resolution Adjustable for DPI Function

The resolution of motor moving is 16 bits wide and is flexibly controlled by motor tables.

The resolution can be up to 4800 dpi for 1200 dpi scanners, 9600 dpi for 2400 dpi scanners and 19200 dpi for 4800 dpi scanners.

Note: The resolution of vertical direction of quarter step can up to four times resolution.

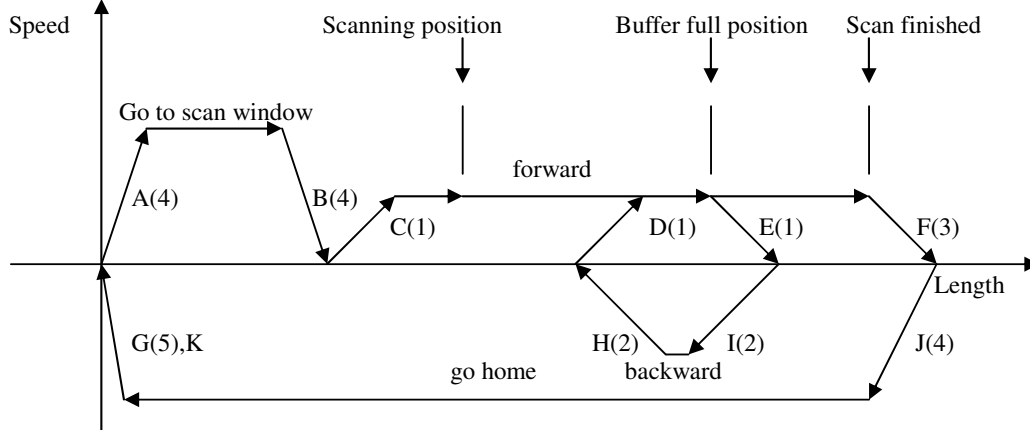
19 Five Acceleration/Deceleration Tables

The acceleration/deceleration tables are stored in internal SRAM and can be downloaded by S/W.

And the resolution is 16 bits in pixel-time. The number of table steps is from 1 to 1020 steps for arbitrary curves. There are five tables for motor moving. Three tables are for scanning and the others are for fast moving. The forward and backward steps can be programmed by S/W separately.

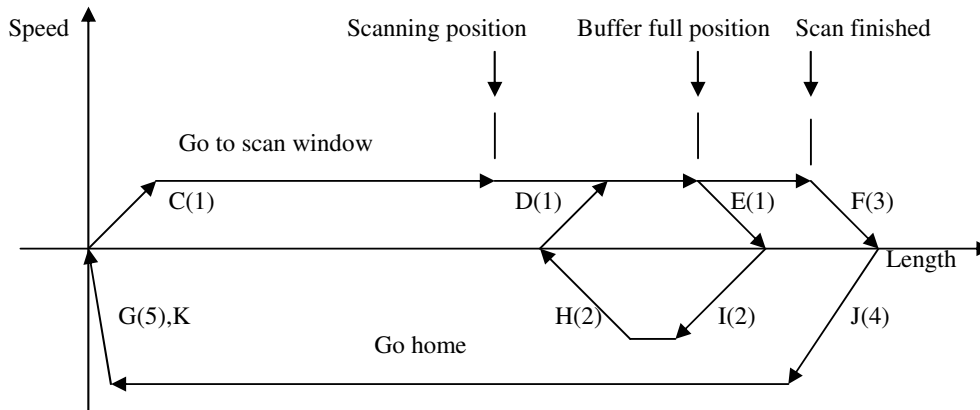
Note: "Fast move" means move back to home position or move forward to scan window in any position.

(1) Two tables type:



- A,J : Acceleration curve in table four (slope four) for fast moving.
- B : Deceleration curve in table four (slope four) for fast moving.
- C,D : Acceleration curve in table one (slope one) for scanning.
- E : Deceleration curve in table one (slope one) for scanning.
- F : Deceleration curve in table three (slope three) for scanning finished to protect wall hitting.
- I : Acceleration curve in table two (slope two) for back-track when image buffer full.
- H : Deceleration curve in table two (slope two) for back-track when image buffer full.
- G : Deceleration curve in table five (slope five) for go-home to protect wall hitting.
- K : Touch home sensor deceleration curve for go-home.

(2) One tables type:



- J : Acceleration curve in table four (slope four) for fast moving.
- C,D : Acceleration curve in table one (slope one) for forward scanning.
- E : Deceleration curve in table one (slope one) for scanning.
- F : Deceleration curve in table three (slope three) for scanning finished to protect wall hitting.
- I : Acceleration curve in table two (slope two) for back-track when image buffer full.
- H : Deceleration curve in table two (slope two) for back-track when image buffer full.
- G : Deceleration curve in table five (slope five) for go-home to protect wall hitting.
- K : Touch home sensor deceleration curve for go-home.

20 Trigger Position Control

Designers can select to move motor first then capture image; or capture image first then move motor.

21 Stepping Motor Phase Control

There are 8 output control pins to control stepping motors:

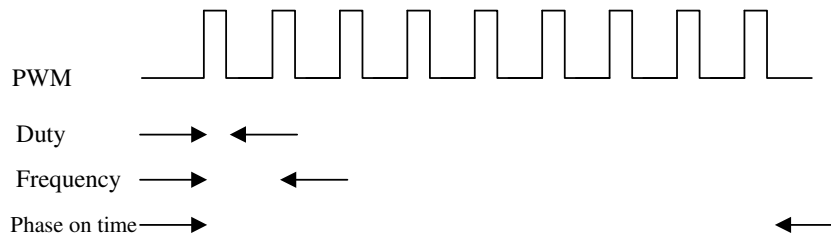
MTR_PH 0~7 for bipolar motors MTR_PH 0~3 for unipolar motors

A. Bipolar motors:

- a. Supports 2916 motor driver timing and 2916 compatible driver IC, such as L6219.
Include full, half and quarter steps control.
- b. Supports 3967 motor driver timing.
Include full, half, quarter and eighth steps control.
- c. Supports LB1939, 1940 motor driver timing.
Include full and half steps control

B. Unipolar motors:

- a. Supports 2003 motor driver timing and 2003 compatible driver IC.
- b. Include full step two phases on, full step single phase on and half step.
- c. PWM control, include frequency and duty controls.



22 Watchdog Protection

This function can automatically reset the system to initial state when the system is hanged (no access signal) beyond the time limit. It can be enabled or disabled by S/W.

This function can protect motor power, lamp power and ASIC system.

Calculation formula: (30sec.) * (times setting) * (setting number.).

The range of setting number is from 1 to 15; the range of times setting is 0 or 1.

23 Lamp Time-out Control

This circuitry can automatically turn off the lamp power when this function is enabled. It can be enabled or disabled by S/W.

Calculation formula: (60sec.) * (times setting) * (setting number).

The range of setting number is from 1 to 7; the range of times setting is 0 to 3.

24 Lamp Power Control

These are two power control ports for lamp. One is for Flatbed and the other is for XPA (Transparency or film).

These control ports have PWM function. According to the system clock, designers can flexibly adjust their frequency and duty by S/W. And the resolution of PWM is 16 bits.

25 Sensors

The system supports home sensor for flatbed; ADF sensor, document sensor and cover sensor for ADF module.

26 GPIO Ports

Designers can separately assign input or output direction for each GPIO pin of GPIO1~21. Some GPIO can be designed for keypads or motor power control...etc.

Note : There are four pins for special function.

GPIO9: This pin can control bipolar motor driver IC (2916,6219 or 3967) Vref3 for control
Imax current.

GPIO13: This pin can control bipolar motor driver IC (2916,6219 or 3967) Vref2 for control

Imax current.

- GPIO12: 1. Pull up by resistor to indicate ASIC to turn on lamp power in power-on initial state.
 2. Pull down by resistor to indicate ASIC to turn off lamp power in power-on initial state..
 3. This pin can control bipolar motor driver IC (2916,6219 or 3967) Vref1 for controlling Imax current.

GPIO11: This pin can control bipolar motor driver IC (2916,6219 or 3967) Vref0 for control Imax current.

27 GPO28, 31~34 Ports

GL848 provides 5 ports for general-purpose output. They are multi-functions.

28 Power on Check

The default status of the PWRBIT control bit is reset. Programmers can set the PWRBIT control bit before controlling the ASIC. GL848 will keep the status until power is turn off. This operation is to check if the power had been turned off or not.

30 LED Blinking

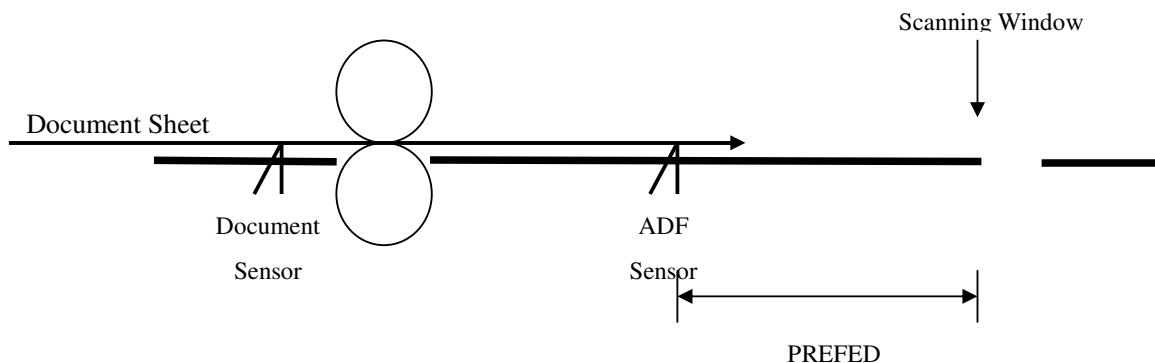
GL848 supports LED -blinking function. It is implemented in GPIO8~10 and GPIO21.

31 Support Back Scanning

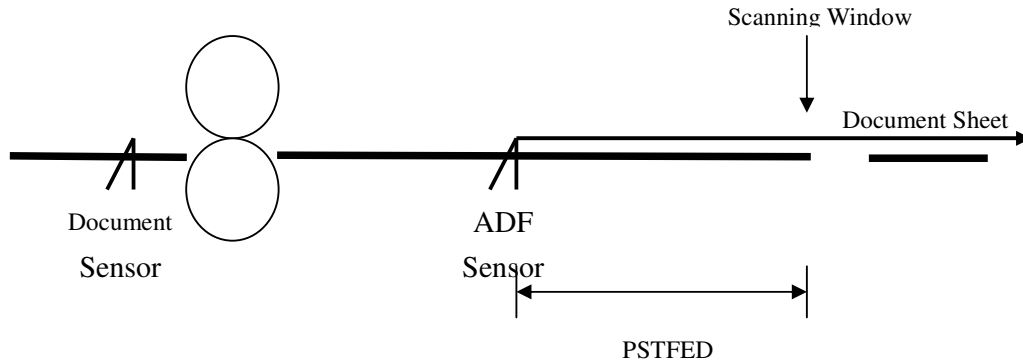
GL848 supports forward or backward scanning.

32 Supports ADF Function

GL848 supports ADF (Auto-document-feeder) function via internal logic circuitry. Programmers need to set the ADFSEL control bit to logic '1'. GPIO6 controls the motor pulse trigger if the motor moving of ADF module is implemented by trigger pulse, otherwise the motor moving is driven by motor phases. GPO28 controls the moving direction of motor if ADF module is necessary. GPIO16 is the cover sensor input, ADF_SENR is the ADF sensor input and HOME is document sensor input under ADF mode.



GL848 can feed document sheets automatically to scanning window. After sensing the present of document by document sensor, software should issue feed command to GL848 for paper feeding. After document sheet reaches ADF sensor, scanning process will be started after PREFED motor steps.



When document sheet keeps moving forward, after sensing the absent of document by ADF sensor, scanning process will be terminated after PSTFED scanning lines.

33 Supports RS232 Interface

GL848 supports RS232 interface via internal logic circuitry. Programmers need to set the RS232SEL control bit to logic '1'. GPIO6 transmits the data of RS232 and GPIO28 receives the data of RS232 under RS232 mode. The baud rate can be programmed to 2400,4800, 9600 and 19200 bps by S/W.

34 Supports EEPROM (93C46) Interface

GL848 supports EEPROM interface via internal firmware. GPIO6 controls SK of external EEPROM, GPIO5 controls DI/DO of EEPROM and GPIO7 controls CS of external EEPROM.

36 “True gray” with R,G and B weightings

Designers can obtain the “true gray” image data by enabling “true gray” function. Image data is generated by R,G and B outputs and multiplied by weightings.

Formula of true gray value = $R*(TRUER [7:0]) + G*(TRUEG [7:0]) + B*(TRUEB [7:0])$

38 Lines Packing for Stagger CCD or R/G/B Line Differences

GL848 packs R, G and B lines together for CCD sensors by hardware. And it also packs the same color lines of stagger CCD together.

39 Fine CDS Sampling Adjustment

Designers can fine-tune the CDS sampling position to avoid the digital noise influence (8.33ns adjustment). The image noise may come from the digital noise of PCB.

40 Wall-Hitting Protection

Designers can use table five of motor moving to protect the wall hitting. The LONGCURV control bit has to be set to logic '1' to enable the long-curve function. The first several steps are used to decelerate the carriage moving; the other slower steps are focused on touching the home sensor.

Due to the special table five, designers can replace the photo-sensor by simple, cheaper mechanical-type sensors.



41 Motor Driver IC Setting

Designers add pull up/pull down resistors on MTR_SEL0~2 will indicate ASIC to generate the timing of specified motor driver IC.

Motor type select : CCD_TGB MTR_SEL2
 CCD_TGG MTR_SEL1
 CCD_CK4X MTR_SEL0

When designers select MTR_SEL0~2 to "111", MT_PH0~7 will output phase table which is stored in internal RAM.

42 Operation Mode Setting

Designers add pull down resistors on TSTSEL0~3 will indicate ASIC to work on normal mode.

ASIC mode select : CCD_CK3X TSTSEL3
 CCD_RSX TSTSEL2
 CCD_CK2X TSTSEL1
 CCD_TGX TSTSEL0

CHAPTER 7 ELECTRICAL CHARACTERISTICS

7.1 Absolute Maximum Ratings (Voltage Referenced to GND)

Table 7.1 - Absolute Maximum Ratings (Voltage Referenced to GND)

Symbol	Description	Min	Max
DVCC1	DC supply voltage	-0.5V	2.5V
AVDD1~3	DC supply voltage	-0.5V	4.6V
VccCore1~4	DC supply voltage	-0.5V	2.5V
VccIO1~6	DC supply voltage	-0.5V	4.6V
V _I	Input Voltage	-0.5V	6V
V _O	Output Voltage	-0.5V	4.6V
V _{AIO}	DC input voltage for USB D+/D- pins	-0.5V	4.6V
T _{OPT}	Operating Temperature	0°C	70°C
T _{OSTG}	Storage Temperature	-60°C	+125°C

7.2 DC Characteristics (Digital Pins): 1.8 V Logic Core and 3.3V Pads

Table 7.2 - DC Characteristics (Digital Pins): 1.8 V Logic Core and 3.3V Pads

SYMBOL	Description	Min	Typ.	Max	Unit
DVCC1	Power Supply Voltage	1.62	1.8	1.98	V
AVDD1~3	Power Supply Voltage	3.0	3.3	3.6	V
VccCore1~4	Power Supply Voltage	1.62	1.8	1.98	V
VccIO1~6	Power Supply Voltage 3.3V	3.0	3.3	3.6	V
I _{dd}	High speed (USB2.0) un-config current	1.8V	10.5	18	mA
		3.3V	41	50	
	Full speed (USB1.1) un-config current	1.8V	9	17	mA
		3.3V	22	32.5	
I _{sus}	Suspend current	1.8V	26	90	uA
		3.3V	990	1750	uA
V _{IH}	Input High Voltage	2.0		5.5	V
V _{IL}	Input Low Voltage	-0.3		0.8	V
V _T	Threshold point	1.45	1.58	1.74	V
V _{T+}	Schmitt trig. Low to High threshold point	1.44	1.50	1.56	V
V _{T-}	Schmitt trig. High to Low threshold point	0.89	0.94	0.99	V
V _J	Junction Temperature	0	25	125	°C
I _L	Input Leakage Current			±10	µA
I _{oz}	Tri-State output leakage current			±10	µA
R _{PU}	Pull-up Resistor	39K	65K	116K	Ω
R _{PD}	Pull-down Resistor	40K	56K	108K	Ω
V _{OL}	Output low voltage			0.4	V
V _{OH}	Output high voltage	2.4			V
I _{OL}	Low level output current @ V _{OL} = 0.4V	18.9	31.8	39.8	mA



GL848 High Speed USB2.0 2-in-1 Scanner Controller With Fast ADF

	excluding D+/D-/VCC/GND				
I_{OH}	Low level output current @ $V_{OH}=2.4V$ excluding D+/D-/VCC/GND	22	47.7	76	mA

7.3 DC Characteristics (D+/D-)

Table 7.3 - DC Characteristics (D+/D-)

SYMBOL	Description	Min	Typ.	Max	Unit
V_{OL}	D+/D- static output LOW(R_L of 1.5K to 3.6V)			0.3	V
V_{OH}	D+/D- static output HIGH (R_L of 15K to GND)	2.7		3.6	V
V_{DI}	Differential input sensitivity	0.2			V
V_{CM}	Differential common mode range	0.8		2.5	V
V_{SE}	Single-ended receiver threshold	0.2			V
C_{IN}	Transceiver capacitance			10	pF
I_{LO}	Hi-Z state data line leakage	-10		+10	μA
Z_{DRV}	Driver output resistance	40.5		49.5	Ω

CHAPTER 8 PACKAGE DIMENSION

QFP-128L (14*20 mm, F/P: 3.2 mm):

SYMBOLS	MIN(mm)	NOM(mm)	MAX(mm)
A1	0.25	0.35	0.45
A2	2.57	2.72	2.87
b	0.10	0.20	0.30
C	0.10	0.15	0.20
D	13.90	14.00	14.10
E	19.90	20.00	20.10
e	-	0.50	-
Hd	17.00	17.20	17.40
He	23.00	23.20	23.40
L	0.65	0.80	0.95
L1	-	1.60	-
Y	-	-	0.08
\ominus	0	-	12

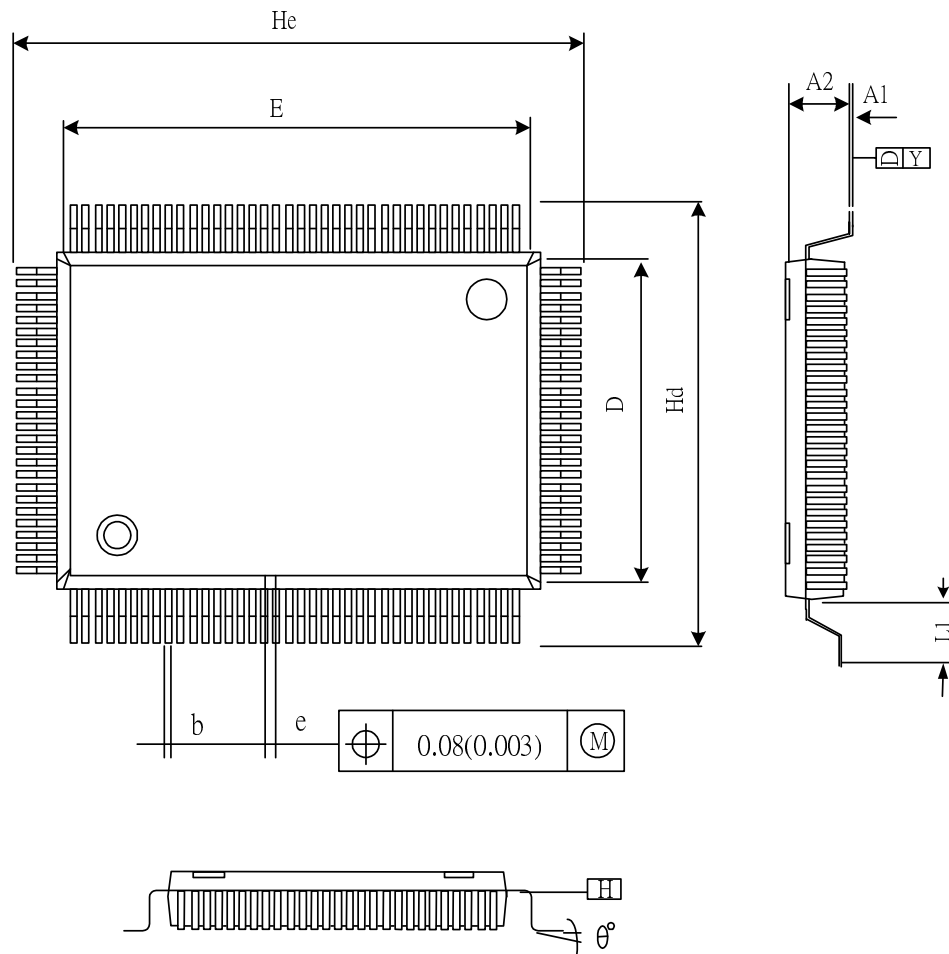


Figure 8.1 - GL848 128 Pin QFP Package