

H6060

Self Recovering Watchdog

Description

The H6060 is a monolithic low-power CMOS device combining a programmable timer and a series of voltage comparators on the same chip. The device is specially suited for watchdog functions such as microprocessor and supply voltage monitoring. If the μP system malfunctions, the watchdog will recover it by issuing repeated active reset signals. The voltage monitoring part provides double security by combining both the unregulated voltage (V_{IN}) regulated voltage (V_{DD}) simultaneously. The H6060 initializes the power-on reset after V_{IN} reaches V_{SH} (see table 4) and V_{DD} rises above 3.V. If V_{IN} drops below V_{SL} (see table 4), the H6060 gives an advanced warning signal for register saving and if the voltage drops further below V_{RL} (see table 4), RES and RES go active. The H6060 functions at any supply voltage down to 1.6 V and is therefore particularly suited for start-up and shut-down control of microprocessor systems.

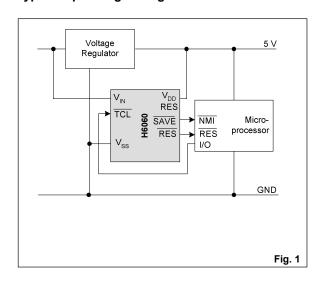
Features

- ☐ Self recovering watchdog function: reset goes active after the 1st timeout period, reset goes inactive again after the 2nd timeout period, repeated active reset signal until the system recovers
- Standard timeout period and power-on reset time (100 ms), externally programmable if required
- □ Unregulated DC monitoring (V_{IN}) with 3 standard or programmable trigger voltages for: power-on reset initialization, advanced power-fail warning (SAVE), reset at power-down (RES)
- $\hfill \square$ Regulated DC monitoring (V_DD): power-on reset initialization enabled only if V_DD $\geq 3.5\ V$
- ☐ Internal voltage reference
- ☐ Works down to 1.6 V supply voltage
- ☐ Push-pull or Open drain outputs
- Low current consumption
- ☐ SO8 package

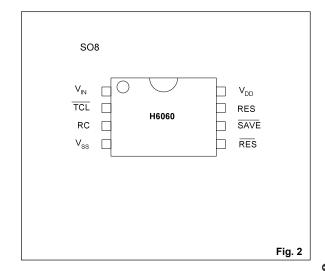
Applications

- Microprocessor and microcontroller systems
- Point of sales equipment
- □ Telecom products
- □ Automotive subsystems

Typical Operating Configuration



Pin Assignment







Absolute Maximum Ratings

Parameter	Symbol	Conditions		
Voltage V _{DD} to V _{SS}	V_{DD}	– 0.3 to + 8 V		
Voltage at any pin to V _{SS}	V_{MIN}	- 0.3		
Voltage at any pin to V _{DD}	V	+ 0.3		
(except V _{IN})	V _{INMAX}	+ 0.3		
Voltage at V _{IN} to V _{SS}	V_{MIN}	+ 15 V		
Current at any output	I _{MAX}	± 10 mA		
Storage temperature	T _{STO}	-65°C to +150°C		

Table 1

Stresses above these listed maximum ratings may cause permanent damages to the device. Exposure beyond specified operating conditions may affect device reliability or cause malfunction.

Handling Procedures

This device has built-in protection against high static voltages or electric fields; however, anti-static precautions must be taken as for any other CMOS component. Unless otherwise specified, proper operation can only occur when

all terminal voltages are kept within the voltage range. Unused inputs must always be tied to a defined logic voltage level.

Operating Conditions

Parameter	Symbol	Min.	Max.	Units
Operating temperature Industrial	T _{AI}	-40	+85	°C
Supply voltage	V_{DD}	1.6	5.5	V
Comparator input voltage				
Version 13, 14, 15, 16	V_{IN}	0	V_{DD}	V
Version 11,12	V_{IN}	0	12	V
RC-oscillator programming (see Fig. 15)				
External capacitance*	C1		1	μF
External resistance	R1	10		kΩ

Table 2

Electrical Characteristics

 V_{DD} = 5.0 V, T_A = -40 to +85 °C, unless otherwise specified

Parameter	Symbol	Test Conditions	Min.	Тур.	Max.	Units
V _{DD} activation threshold	V _{ON}	T _A = 25 °C	3		3.5	V
V _{DD} deactivation threshold	V_{OFF}	T _A = 25 °C		$V_{ON} - 0.3$		V
Supply current	I_{DD}	RC open, TCL at V _{DD} or V _{SS}		80	140	μΑ
Input V _{IN} , TCL						
Leakage current	I_{IP}	$V_{SS} \le V_{IP} \le V_{DD}$;				
		T _A = 85 °C		0.005	1	μΑ
Input current on pin V _{IN}	I _{IN}	Version 12; V _{IN} = 10 V		100	180	μA
TCL input low level	V_{IL}				8.0	V
TCL input high level	V_{IH}		2.4			V
SAVE, RES, RES outputs						
Leakage currents	I _{OLK}	Version 15;				
		$V_{OUT} = V_{DD}$		0.05	1	μΑ
Drive currents (all versions)	I _{OL}	V _{OL} = 0.4 V	3.2	8		mA
,	I _{OL}	$V_{DD} = 3.5 \text{ V}; V_{OL} = 0.4 \text{ V}$	2			mA
	I _{OL}	$V_{DD} = 1.6 \text{ V}; V_{OL} = 0.4 \text{ V}$	80			μΑ
Drive currents	I _{OH}	V _{OH} = 4.0 V	3.2	8		mA
(versions 14,16) ¹⁾	I _{OH}	$V_{DD} = 3.5 \text{ V}; V_{OH} = 2.8 \text{ V}$	2			mA
	I _{ОН}	V _{DD} = 1.6 V; V _{OH} = 1.2 V	80			μΑ

¹⁾ Versions: 15 = open drain outputs; 14, 16 = push-pull outputs

V_{IN} Surveillance

Voltage thresholds at T_A = 25 °C

Version 1) Comparator Input Resistance Threshold Thresholds Ratio Tolerance 3) Reference on V_{IN} (R_{VIN}) V_{SH} \mathbf{V}_{SL} V_{RL} Tolerance 1.75²⁾ 14 ~100MΩ 2.25 2.00 ±2% V_{DD} ±5% 15, 16 Band-gap reference ${\sim}100M\Omega$ 2.00 1.95 1.90 ±10% ±2%

Table 4

Table 3

^{*} Leakage < 1µA

¹⁾ Version: 15 = open drain outputs; 14, 16 = push-pull outputs

 $^{^{2)}}$ at V_{DD} = 5 V

 $^{^{3)}}$ Threshold ratio tolerance is defined as the tolerance of V_{SH} / V_{SL} and V_{SL} / $V_{RL}.$



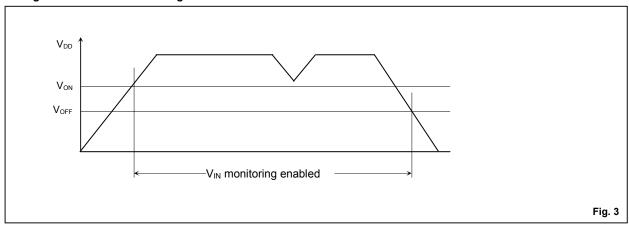
Timing Characteristics

 V_{DD} = 5.0 V, T_A = -40 °C to +85 °C, unless otherwise specified

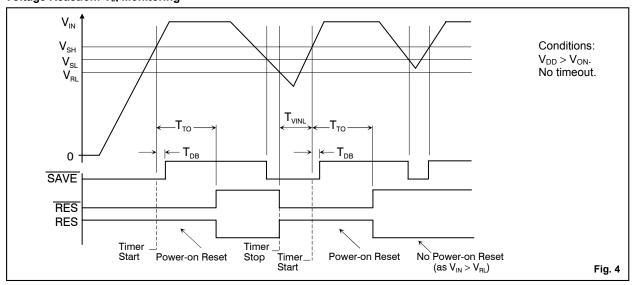
Parameter	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Propagation delays TCL to output pins V _{IN} to output pins	T _{DIDO}	Excluding debounce time T _{DB}		250 4	500 10	ns μs
Logic transition times on all output pins	T _{TR}	Load 10 kΩ, 100 pF		30	100	ns
Timeout period	T _{TO}	RC open, unshielded, T _A = 25 °C RC open, unshielded (not tested)	60 45	100	160 200	ms ms
T _{TCL} input pulse width	T _{TCL}	,	150			ns
Power-on reset debounce	T_DB			T _{TO} /64		ms
V _{IN} low pulse	T _{VINL}	Where debounce time T _{DB} Is guaranteed	10			μs

Table 5

Timing Waveforms Voltage Reaction: V_{DD} Monitoring

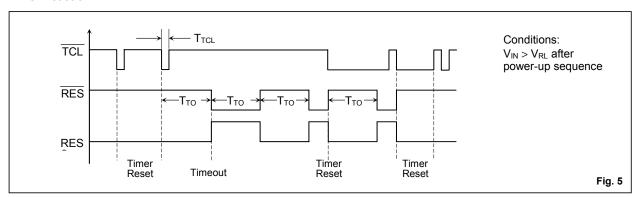


Voltage Reaction: V_{IN} Monitoring

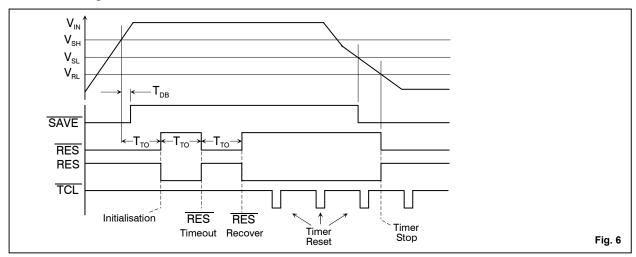




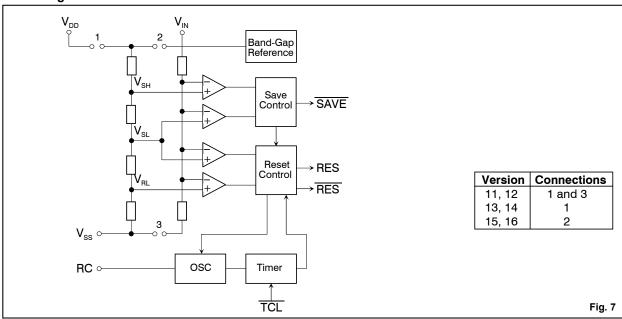
Timer Reaction



Combined Voltage and Timer Reaction



Block Diagram





Pin Description

2000p						
Name	Function					
V _{IN}	Voltage sense input					
TCL	Timer clear input signal					
RC	RC oscillator tuning input					
V_{SS}	GND terminal					
RES	Active low reset output					
SAVE	Save output					
RES	Active high reset output					
V_{DD}	Positive supply voltage terminal					
	VIN TCL RC VSS RES SAVE RES					

Table 6

Functional Description

Supply Lines

The circuit is powered through the V_{DD} and V_{SS} pins. It monitors both its own V_{DD} supply and a voltage applied to the V_{IN} input.

V_{DD} Monitoring

During power-up the V_{IN} monitoring is disabled and \overline{RES} , RES and \overline{SAVE} stay active low as long as V_{DD} is below V_{ON} (3.5 V). As soon as V_{DD} reaches the V_{ON} level, the state of the outputs depend on the watchdog timer and the voltage at V_{IN} relative to the thresholds (see Fig. 4). If the supply voltage V_{DD} falls back below V_{OFF} ($V_{ON}-0.3$ V) the watchdog timer and the V_{IN} monitoring are disabled and the outputs \overline{RES} , RES and \overline{SAVE} become active. The V_{DD} line should be free of voltage spikes.

VIN Monitoring

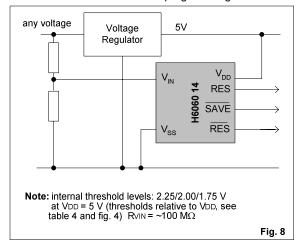
The analog voltage comparators compare the voltage applied to V_{IN} (typically connected to the input of the voltage regulator) with the stabilized supply voltage V_{DD} (version 14) or with the bandgap voltage (versions 15, 16) (see Fig. 7). At power-up, when V_{DD} reached V_{ON} and V_{IN} reaches the V_{SH} level, the SAVE output goes inactive, and the timer starts running, setting RES and RES in active after the time T_{TO} (see. Fig. 4). If V_{IN} falls below V_{SL} , the $\overline{\text{SAVE}}$ output goes active and stays active until V_{IN} rises again above V_{SH} . If V_{IN} falls below the voltage V_{RL} , RES and RES will become active and the on-chip timer will stop. When V_{IN} rises again above V_{SH} , the timer will initiate a power-up sequence. The RES and RES outputs may however be influenced independently of the voltage V_{IN} by the timer action, see section "Combined Voltage and Timer Action". Monitoring the rough DC side of the regulator, as shown in Fig. 11, is the only way to have advanced warning of power-down. Spikes on V_{IN} should be filtered if they are likely to exceed the value (V_{SL} -

The combination of V_{IN} and V_{DD} monitoring provide high system security: if V_{IN} rises much faster than V_{DD} , then the device starts the power-on sequence only when V_{DD} reached V_{ON} (Fig. 10). Short circuits on the regulated supply voltage can be detected.

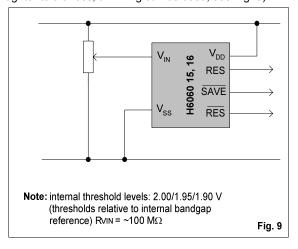
Voltage Thresholds on V_{IN}

The H6060 is available with 3 different sets of thresholds:

Version 14: monitor the unregulated voltage and are ideal for programming of the V_{IN} voltage thresholds. Fixed resistor values can be used for programming.



Version 15, 16: monitor the regulated voltage. They are suited to applications where the unregulated voltage is not available. (The tolerance is \pm 10%, see table 4. For tighter tolerances, trimming can be used, see Fig. 9).



Monitoring of the unregulated voltage requires version 14. These versions are based on the principle that V_{DD} rises with V_{IN} on power-up an V_{DD} holds up for a certain time after V_{IN} starts dropping on power-down. The versions 11 and 12 have a 100 k Ω nominal resistance from V_{IN} to V_{SS} (internal voltage divider). The versions 14, 15 and 16 have high impedance V_{IN} inputs (see Fig. 7 and Table 4) for external threshold voltage programming by a voltage divider on pin V_{IN} . The levels obtained are proportional to the internal levels $V_{\text{SH}},\,V_{\text{SL}}$ and V_{RL} on the chip itself (see Electrical Specifications).



Timer Programming

With pin RC unconnected, the on-chip RC oscillator together with its divider chain give a timeout T_{TO} of typically 100 ms. To program different T_{TO} , an approximation for calculating component values is given by the formula:

$$T_{TO} = \begin{bmatrix} 0.75 + \frac{(32 + C_1) \cdot 2}{5.5 + \frac{V_{DD} - 1}{R_1}} \end{bmatrix} 8.192$$

 $R_{1~\text{min.}}$ = 10 k $\Omega,~C_{1~\text{max.}}$ = 1 μF If R_{1} is in $M\Omega$ and C_{1} in pF, T_{TO} will be in ms.

A resistor decreases and a capacitor increases the interval to timeout. Excellent temperature stability of T_{TO} can be achieved by using external components. A precise square wave of period $2\times T_{TO}$ is generated at the outputs \overline{RES} and RES when \overline{TCL} is tied to either V_{DD} or $V_{SS}.$ The oscillator and watchdog timer start running when both V_{IN} is greater than V_{SH} (see Fig. 6) and V_{DD} is greater than V_{ON} (see Fig. 3).

They will remain running while both V_{IN} is greater than V_{RL} and V_{DD} is greater than V_{OFF} (see Fig. 3).

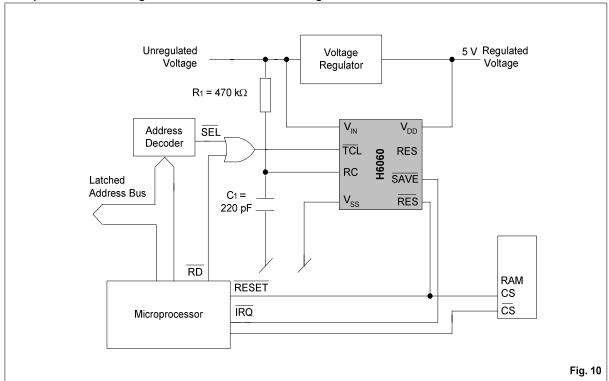
Timer Clearing and RES /RES Action

A negative edge or a negative pulse at the \overline{TCL} input for longer than 150 ns will reset the timer and set RES and RES inactive. If a further \overline{TCL} signal edge or pulse is applied before T_{TO} timeout, \overline{RES} and RES will remain inactive and the timer will again be reset to zero (see Fig. 5). If no \overline{TCL} signal is applied before the T_{TO} timeout, \overline{RES} and RES will start to generate square waves of period 2 \times T_{TO} starting with the inactive state. The watchdog will remain in this state until the next \overline{TCL} signal appears, or until a fresh power-up sequence.

Combined Voltage and Timer Action

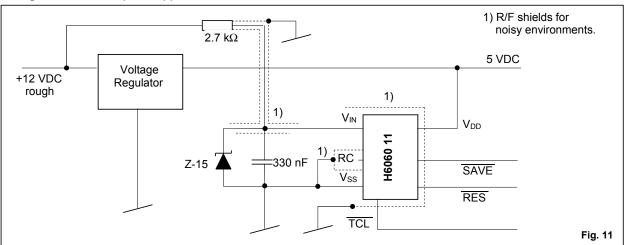
The combination of voltage and timer actions is illustrated by the sequence of events shown in Fig. 6. One timeout period after V_{IN} reaches V_{SH} , during power-up, $\overline{\text{RES}}$ and RES go inactive. A $\overline{\text{TCL}}$ pulse will have no effect until this power-on reset delay is completed. After completing the power-up sequence the watchdog timer starts acting. If no $\overline{\text{TCL}}$ pulse occurs, $\overline{\text{RES}}$ and RES go active after one timeout period T_{TO} . After each subsequent timeout period, without a timer clear pulse at $\overline{\text{TCL}}$, $\overline{\text{RES}}$ and RES change polarity providing square wave signals. A $\overline{\text{TCL}}$ pulse clears the watchdog timer and causes $\overline{\text{RES}}$ and RES to go inactive. A voltage drop below the V_{RL} level overrides the timer and immediately forces $\overline{\text{RES}}$, RES and $\overline{\text{SAVE}}$ active. Any further $\overline{\text{TCL}}$ pulse has no effect until the next power-up sequence is completed.

Typical Applications Microprocessor Watchdog with Power-On Reset and Voltage Monitor

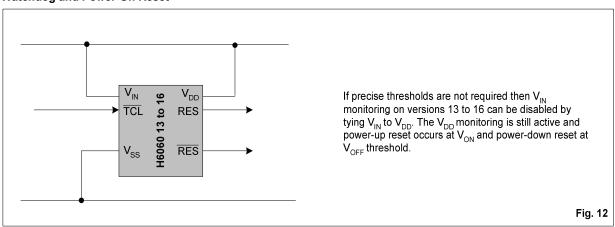




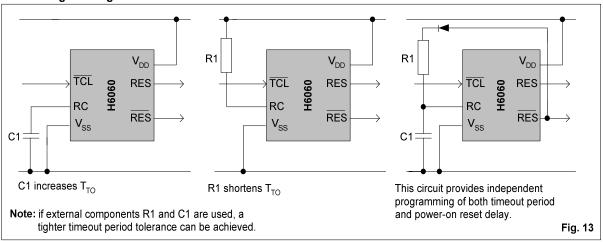
Voltage Monitor with Spike Suppression



Watchdog and Power-On Reset

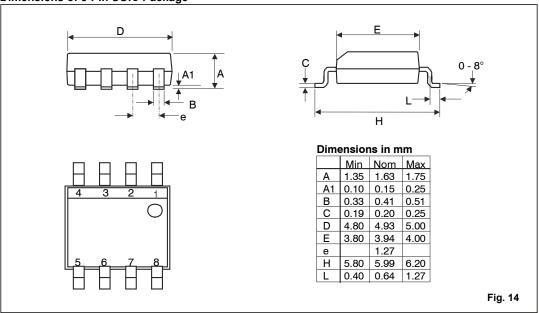


External Programming of RC Oscillator





Package Information
Dimensions of 8-Pin SOIC Package



Ordering Information

When ordering please specify complete part number.

Part Number	Version	Threshold (see Table 4)	Output	Package	Delivery Form	Package Marking (first line)	Temperature						
H6060V15SO8A	V15	1.95	Open drain	8-pin SOIC	Stick	606015							
H6060V15SO8B	V 15	1.95		8-pin SOIC	Tape&Reel	606015							
H6060V14SO8A	V/1.4	2.00	2.00	2.00	2.00	V14 2.00	2.00	2.00		8-pin SOIC	Stick	606014	-40°C to °85°C
H6060V14SO8B	V 14						Duch pull	8-pin SOIC	Tape&Reel	606014	-40 C to 85 C		
H6060V16SO8A	V16	1.95	Push-pull	8-pin SOIC	Stick	606016							
H6060V16SO8B	V 16	1.95	1.95	1.95	1.95	1.95	1.95	1.95	1.90	8-pin SOIC	Tape&Reel	606016	

Note: Other versions are no longer available

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