



1. General description

The SAA8115HL is the second generation of integrated circuit applicable in PC video cameras to convert D1 video signals and analog audio signals to properly formatted USB packets.

This powerful successor of the SAA8117HL can handle up to 15 fps in VGA format or 30 fps in CIF format. High snapshot quality is achievable using the SDRAM interface to an external memory.

It is designed as a back-end of the SAA8112HL (general camera digital processing IC) and is optimized for use with the TDA8784 to TDA8787 (camera pre-processing ICs).

2. Features

- VGA (progressive mode), CIF and medium resolution (PAL non-interlaced mode) CCD sensors compliant
- D1 digital video input (8 bits YUV 4 : 2 : 2 time multiplexed)
- Internal Pulse Pattern Generator (PPG) dedicated for VGA Panasonic, CIF and medium resolution Sharp sensors or compatibles, and frame rate selection
- Frame rate converter
- SDRAM interface for high quality VGA snapshot (uncompressed 4 : 2 : 2 or 4 : 2 : 0)
- Downsampler and scaler (programmable formatter for CIF, QCIF, sub-QCIF, SIF and QSIF) controlled via SNERT (UART) interface
- Flexible compression engine controlled via SNERT (UART) interface
- Selectable output frame rate (up to 15 fps in VGA, up to 30 fps in CIF and QCIF)
- Video packetizer FIFO
- I²C-bus interface for communication between the USB protocol hardware and the external microcontroller
- Microphone/audio input to USB (microphone supply, controllable gain and ADC)
- Integrated analog bus driver (ATX)
- Integrated main oscillator
- Integrated 5 V power supply and reset circuit including functionalities for bus-powered USB device
- Programmable (frequency and duty cycle) switch mode power signal for CCD supply

- Miscellaneous functions (e.g. power management, PLL for audio frequencies).

3. Applications

- Low-cost desktop video applications with USB interface.

4. Quick reference data

Table 1: Quick reference data

Measured over full voltage and temperature range

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{DDD}	digital supply voltage		3.0	3.3	3.6	V
V _{DDA}	analog supply voltage		3.0	3.3	3.6	V
V _{DDA(USB)}	analog supply voltage from USB		[1] 4.3	5.0	5.5	V
I _{DD}	supply current		[2] –	100	125	mA
I _{DD(DC-DC)}	DC-DC supply current		[3] –	240	320	mA
V _I	input signal levels	3.0 V < V _{DDD} < 3.6 V	low voltage TTL compatible			V
V _O	output signal levels	3.0 V < V _{DDD} < 3.6 V	low voltage TTL compatible			V
f _{clk}	clock frequency		–	48	–	MHz
T _{stg}	storage temperature		–55	–	–	°C
T _{amb}	ambient temperature		0	25	70	°C
T _j	junction temperature	T _{amb} = 70 °C	–40	–	+125	°C

[1] This concerns pins VBUS1 and VBUS2.

[2] Conditions:

- typical: VGA at 15 fps; V_{DDD} = V_{DDA} = 3.3 V; T_{amb} = 25 °C
- maximum: VGA at 30 fps; V_{DDD} = V_{DDA} = 3.6 V; T_{amb} = 70 °C.

[3] Conditions (I_{OUT} = 125 mA):

- typical: V_{DD(USB)} = 5.0 V; T_{amb} = 25 °C
- maximum: V_{DD(USB)} = 4.3 V; T_{amb} = 70 °C.

5. Ordering information

Table 2: Ordering information

Type number	Package		Version
	Name	Description	
SAA8115HL	LQFP144	plastic low profile quad flat package; 144 leads; body 20 × 20 × 1.4 mm	SOT486-1

6. Block diagram

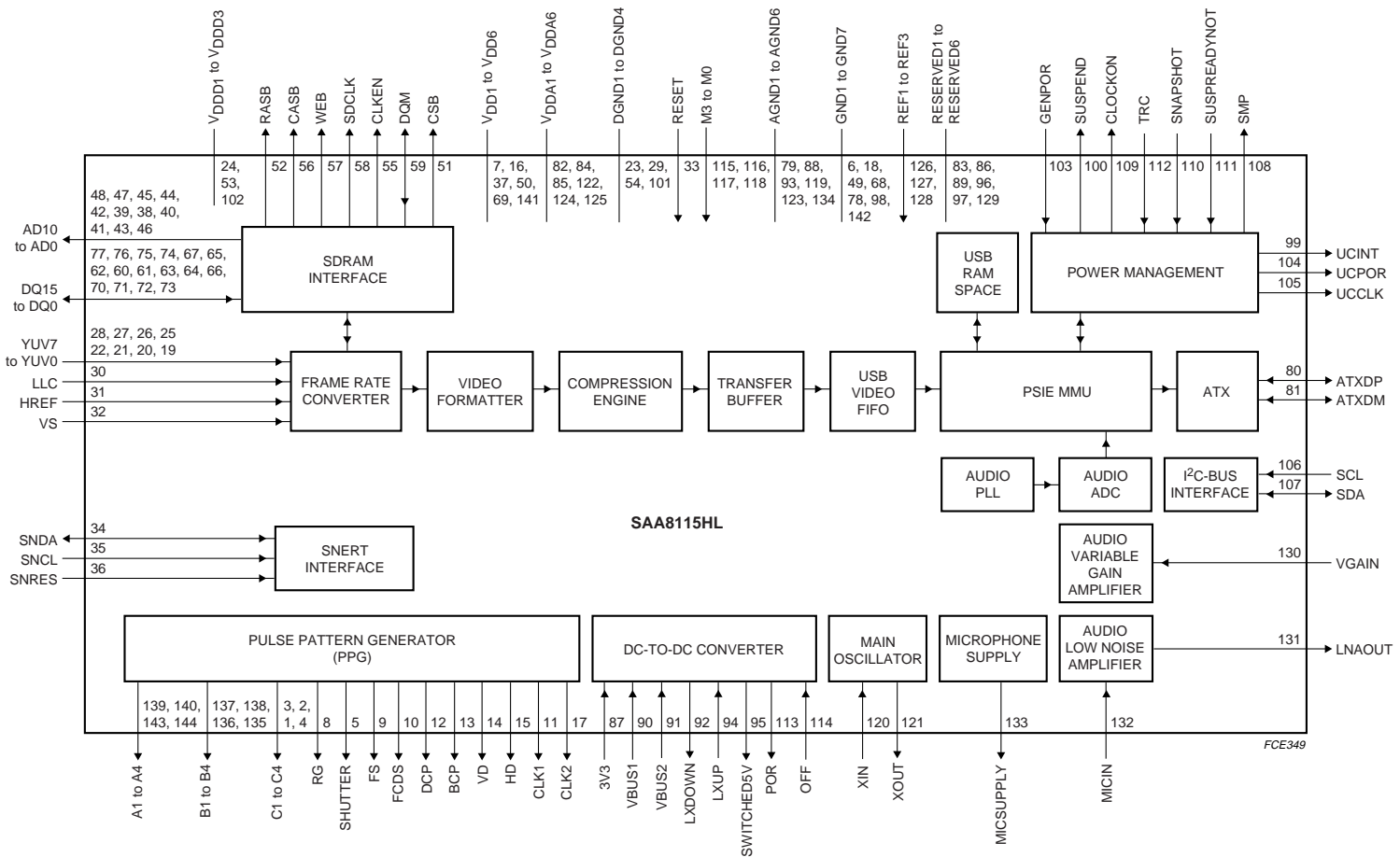


Fig 1. Block diagram.

7. Pinning information

7.1 Pinning

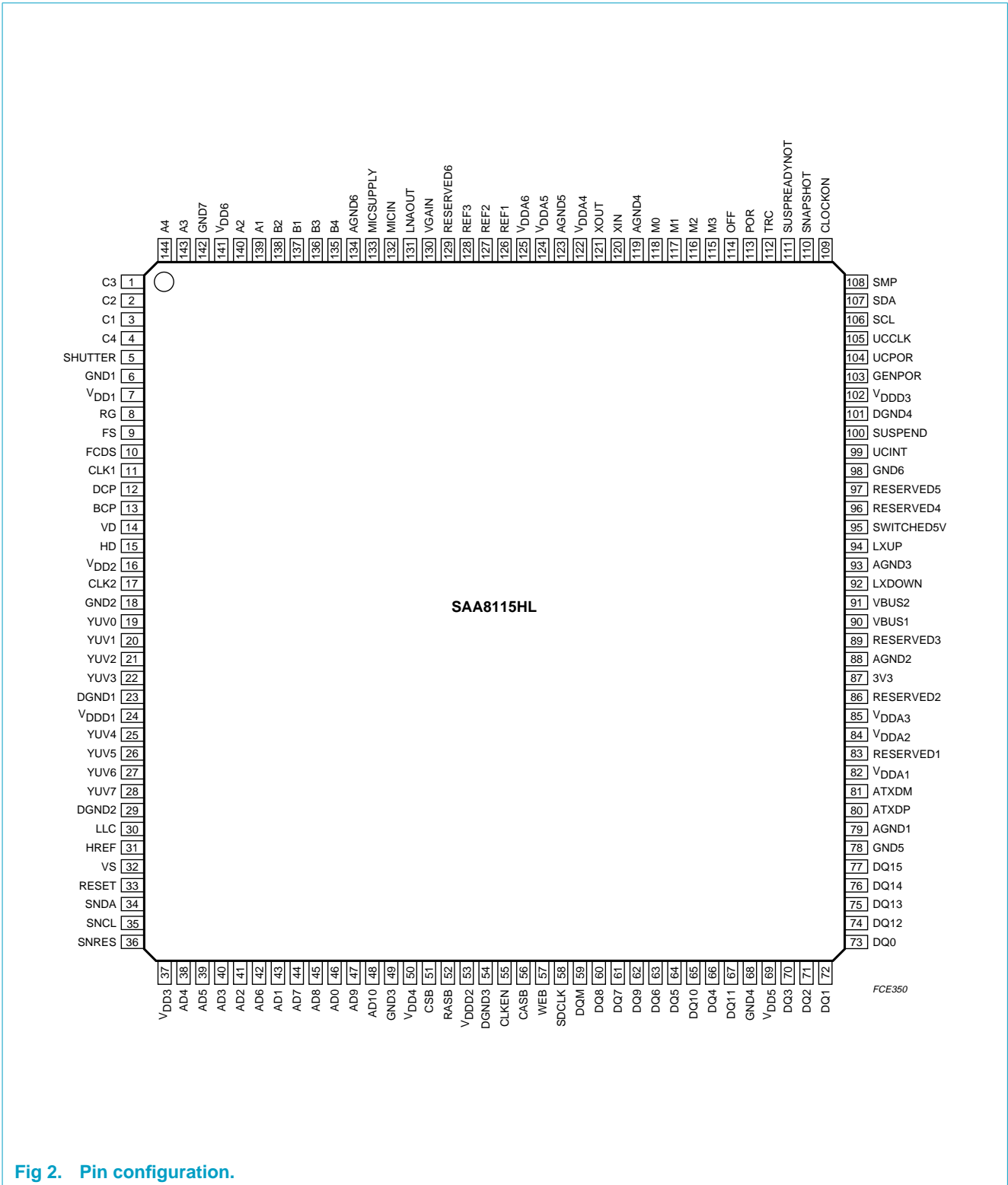


Fig 2. Pin configuration.

7.2 Pin description

Table 3: Pin description

Symbol	Pin	Type ^[1]	Description
C3	1	O	horizontal CCD transfer pulse output
C2	2	O	horizontal CCD transfer pulse output (FH1)
C1	3	O	horizontal CCD transfer pulse output (FH2)
C4	4	O	horizontal CCD transfer pulse output
SHUTTER	5	O	shutter control output for CCD charge reset
GND1	6	P	ground 1 for output buffers
V _{DD1}	7	P	supply voltage 1 for output buffers
RG	8	O	reset output for CCD output amplifier gate
FS	9	O	data sample-and-hold pulse output to TDA8784/87 (SHD)
FCDS	10	O	preset sample-and-hold pulse output to TDA8784/87 (SHP)
CLK1	11	O	pixel clock to TDA8784/87 and SAA8112HL
DCP	12	O	dummy clamp pulse output to TDA8784/87
BCP	13	O	optical black clamp pulse output to TDA8784/87
VD	14	O	vertical definition pulse to SAA8112HL
HD	15	O	horizontal definition pulse to SAA8112HL
V _{DD2}	16	P	supply voltage 2 for output buffers
CLK2	17	O	double pixel clock to SAA8112HL
GND2	18	P	ground 2 for output buffers
YUV0	19	I	multiplexed YUV bit 0
YUV1	20	I	multiplexed YUV bit 1
YUV2	21	I	multiplexed YUV bit 2
YUV3	22	I	multiplexed YUV bit 3
DGND1	23	P	digital ground 1 for input buffers, predrivers and for the digital core
V _{DD1}	24	P	digital supply voltage 1 for input buffers, predrivers and one part of the digital core
YUV4	25	I	multiplexed YUV bit 4
YUV5	26	I	multiplexed YUV bit 5
YUV6	27	I	multiplexed YUV bit 6
YUV7	28	I	multiplexed YUV bit 7
DGND2	29	P	digital ground 2 for input buffers, predrivers and for the digital core
LLC	30	I	line-locked clock input (delayed CLK2) for YUV-port from SAA8112HL
HREF	31	I	horizontal reference input for YUV-port from SAA8112HL
VS	32	I	vertical synchronization input for YUV-port from SAA8112HL
RESET	33	I	Power-on reset input (for video processing and PPG)
SNDA	34	I/O	data input/output for SNERT-interface (communication between SAA8115HL and SAA8112HL)

Table 3: Pin description...continued

Symbol	Pin	Type ^[1]	Description
SNCL	35	I	clock input for SNERT-interface (communication between SAA8115HL and SAA8112HL)
SNRES	36	I	reset input for SNERT-interface (communication between SAA8115HL and SAA8112HL)
V _{DD3}	37	P	supply voltage 3 for output buffers
AD4	38	O	SDRAM output address bit 4
AD5	39	O	SDRAM output address bit 5
AD3	40	O	SDRAM output address bit 3
AD2	41	O	SDRAM output address bit 2
AD6	42	O	SDRAM output address bit 6
AD1	43	O	SDRAM output address bit 1
AD7	44	O	SDRAM output address bit 7
AD8	45	O	SDRAM output address bit 8
AD0	46	O	SDRAM output address bit 0
AD9	47	O	SDRAM output address bit 9
AD10	48	O	SDRAM output address bit 10
GND3	49	P	ground 3 for output buffers
V _{DD4}	50	P	supply voltage 4 for output buffers
CSB	51	O	SDRAM chip select output
RASB	52	O	SDRAM row address strobe output
V _{DD2}	53	P	digital supply voltage 2 for the switchable digital core
DGND3	54	P	digital ground 3 for input buffers, predrivers and for the digital core
CLKEN	55	O	SDRAM clock enable output
CASB	56	O	SDRAM column address strobe output
WEB	57	O	SDRAM write enable output
SDCLK	58	O	SDRAM clock output
DQM	59	I/O	SDRAM data mask enable
DQ8	60	I/O	SDRAM data I/O bit 8
DQ7	61	I/O	SDRAM data I/O bit 7
DQ9	62	I/O	SDRAM data I/O bit 9
DQ6	63	I/O	SDRAM data I/O bit 6
DQ5	64	I/O	SDRAM data I/O bit 5
DQ10	65	I/O	SDRAM data I/O bit 10
DQ4	66	I/O	SDRAM data I/O bit 4
DQ11	67	I/O	SDRAM data I/O bit 11
GND4	68	P	ground 4 for output buffers
V _{DD5}	69	P	supply voltage 5 for output buffers
DQ3	70	I/O	SDRAM data I/O bit 3
DQ2	71	I/O	SDRAM data I/O bit 2
DQ1	72	I/O	SDRAM data I/O bit 1

Table 3: Pin description...continued

Symbol	Pin	Type ^[1]	Description
DQ0	73	I/O	SDRAM data I/O bit 0
DQ12	74	I/O	SDRAM data I/O bit 12
DQ13	75	I/O	SDRAM data I/O bit 13
DQ14	76	I/O	SDRAM data I/O bit 14
DQ15	77	I/O	SDRAM data I/O bit 15
GND5	78	P	ground 5 for output buffers
AGND1	79	P	analog ground 1 for ATX (transceiver)
ATXDP	80	I/O	positive driver of the differential data pair input/output (ATX)
ATXDM	81	I/O	negative driver of the differential data pair input/output (ATX)
V _{DDA1}	82	P	analog supply voltage 1 for ATX
RESERVED1	83	–	test pin 1 (should not be used)
V _{DDA2}	84	P	analog supply voltage 2 for bandgap (reference)
V _{DDA3}	85	P	analog supply voltage 3 for bandgap, comparator and ring oscillator
RESERVED2	86	–	test pin 2 (should not be used)
3V3	87	I	3V3 detector input signal
AGND2	88	P	analog ground 2 for N-switch
RESERVED3	89	–	test pin 3 (should not be used)
VBUS1	90	I	supply voltage input 1 from the USB
VBUS2	91	I	supply voltage input 2 from the USB
LXDOWN	92	O	LX coil node output (5 V downconverter)
AGND3	93	P	analog ground 3 for N-switch
LXUP	94	I	LX coil node input (5 V upconverter)
SWITCHED5V	95	O	5 V switched power supply
RESERVED4	96	–	test pin 4 (should not be used)
RESERVED5	97	–	test pin 5 (should not be used)
GND6	98	P	ground 6 for output buffers
UCINT	99	O	interrupt output from USB to microcontroller
SUSPEND	100	O	control output from USB protocol hardware to microcontroller
DGND4	101	P	digital ground 4 for input buffers, predrivers and for the digital core
V _{DD3}	102	P	digital supply voltage 3 for input buffers, predrivers and one part of the digital core
GENPOR	103	I	Power-on reset input (for USB protocol hardware)
UCPOR	104	O	control output from USB protocol hardware to microcontroller
UCCLK	105	O	clock output from USB protocol hardware to microcontroller
SCL	106	I	slave I ² C-bus clock input
SDA	107	I/O	slave I ² C-bus data input/output

Table 3: Pin description...continued

Symbol	Pin	Type ^[1]	Description
SMP	108	O	switch mode power pulse output for CCD supplies
CLOCKON	109	O	control output for main oscillator switched on
SNAPSHOT	110	I	input for remote wake-up (snapshot)
SUSPREADYNOT	111	I	input from microcontroller for SUSPEND mode
TRC	112	I	threshold control input for enabling clock
POR	113	O	3.3 V supply domain ready indicator output
OFF	114	I	disable 5 V switchable supply domain input
M3	115	I	test mode control input signal bit 3
M2	116	I	test mode control input signal bit 2
M1	117	I	test mode control input signal bit 1
M0	118	I	test mode control input signal bit 0
AGND4	119	P	analog ground 4 for crystal oscillator (48 MHz, 3rd overtone)
XIN	120	I	oscillator input
XOUT	121	O	oscillator output
V _{DDA4}	122	P	analog supply voltage 4 for crystal oscillator (48 MHz, 3rd overtone)
AGND5	123	P	analog ground 5 for PLL
V _{DDA5}	124	P	analog supply voltage 5 for PLL
V _{DDA6}	125	P	analog supply voltage 6 for amplifier and ADC
REF1	126	I	reference voltage 1 (used in the ADC)
REF2	127	I	reference voltage 2 (used in the ADC)
REF3	128	I	reference voltage 3 (used in the amplifier and the ADC)
RESERVED6	129	O	test pin 6 (should not be used)
VGAIN	130	I	variable gain amplifier input
LNAOUT	131	O	low noise amplifier output
MICIN	132	I	microphone input
MICSUPPLY	133	O	microphone supply output
AGND6	134	P	analog ground 6 for amplifier and ADC
B4	135	O	vertical CCD load pulse output (VH1X)
B3	136	O	vertical CCD load pulse output (VH3X)
B1	137	O	vertical CCD load pulse output
B2	138	O	vertical CCD load pulse output
A1	139	O	vertical CCD transfer pulse output (V1X)
A2	140	O	vertical CCD transfer pulse output (V2X)
V _{DD6}	141	P	supply voltage 6 for output buffers
GND7	142	P	ground 7 for output buffers
A3	143	O	vertical CCD transfer pulse output (V3X)
A4	144	O	vertical CCD transfer pulse output (V4X)

[1] I = input, O = output and P = power supply.

8. Functional description

8.1 Video synchronization

The video synchronization module is capable of locking to the video signal implementing a horizontal gate signal HREF (HREF = HIGH when data is valid) and a VS signal indicating the start of a new video frame.

8.2 Frame rate converter and SDRAM interface

An optional SDRAM (external) can be accessed using the SDRAM interface which is integrated in the SAA8115HL. Pinning and functionality is based on the NEC μ PD4516161 (16 Mbits) and the NEC μ PD4564163 (64 Mbits).

When used, the memory is placed at the video input of the SAA8115HL before prefilter, scaler and compression engine. At this point only YUV 4 : 2 : 2 formatted data is available.

The use of the SDRAM is twofold:

- Lowering the frame rate. The memory enables to store one frame of video accumulated at a specific rate and to read it out at a lower frame rate. For interline VGA sensors, the input frame rate is either 30 fps or 15 fps. It can be lowered with a factor of 2, 3, 6, 16 or 32. For CIF or medium resolution PAL, the input frame rate is only 30 fps
- Enhanced snapshot mode. Storage of full size VGA pictures in 4 : 2 : 2 format which can be retrieved upon dedicated software command.

8.3 Video formatter: downsampler and cutter

This block is used to achieve the required output format from the specified sensor formats (see [Figure 3](#)). It works for YUV 4 : 2 : 2 only. In RAW mode this block is by-passed to create a full resolution snapshot.

Horizontally a downsampling from 512 or 640 to either 384, 320, 192 or 160 or from 352 to 176 is necessary. The horizontal downsampling is performed with the use of a Variable Phase Delay filter (VPD-4). This filter can realize the needed downsample factors. To avoid aliasing, this module also contains a prefilter which has four modes:

- No filter for medium resolution PAL (512 × 288) to CIF (352 × 288) or SIF (320 × 240)
- Prefilter A (3 taps) for VGA (640 × 480) to CIF or SIF, CIF to QCIF (176 × 144) or QSIF (160 × 120)
- Prefilter B (7 taps) for medium resolution PAL to QCIF or QSIF
- Prefilter A combined with prefilter B-comb (13 taps) for VGA to QCIF or QSIF.

Prefilter B-comb is similar to prefilter B but inserts extra taps with amplification 0.

The vertical downsampling in PAL mode is from CIF to QCIF only. This is done via a vertical filter A (3 taps). In VGA mode a 4 taps polyphase filter is applied to scale from 640 × 480 to CIF and QCIF.

From a full size QCIF picture a sub-QCIF (128 × 96) cut can be made. For the zoomed sub-QCIF format, the origin (upper left corner) is programmable via SNERT in 13 steps (both horizontally and vertically), so that an electronic pan and tilt is possible.

The incoming 4 : 2 : 2 data is vertically filtered to 4 : 2 : 0, in order to be sent over USB, by throwing away colour samples. In the even lines the V-samples are discarded, in the odd lines the U-samples.

8.4 Compression engine

The compression engine module (see Figure 3) can process VGA, CIF, SIF, QCIF and QSIF but has optimal performance with CIF resolution (30 fps) and VGA resolution (5 fps). The algorithm is Philips proprietary. The compression ratio is continuously programmable by setting the maximum number of bits which can be used for 4 compressed lines, a so-called band (see Table 4). It is possible to reduce the YUV input data by scaling down (divide by 2 or divide by 4 operations) to 7 or 6 bits per sample. For compression with an output rate below 2 bpp (bits per pixel) it leads to performance improvement.

For a number of compression ratios, performance is also improved thanks to different quantization tables which are defined and stored in a ROM. The required table must be selected via software.

Real time decoding can be done in software on any Pentium™1 platform.

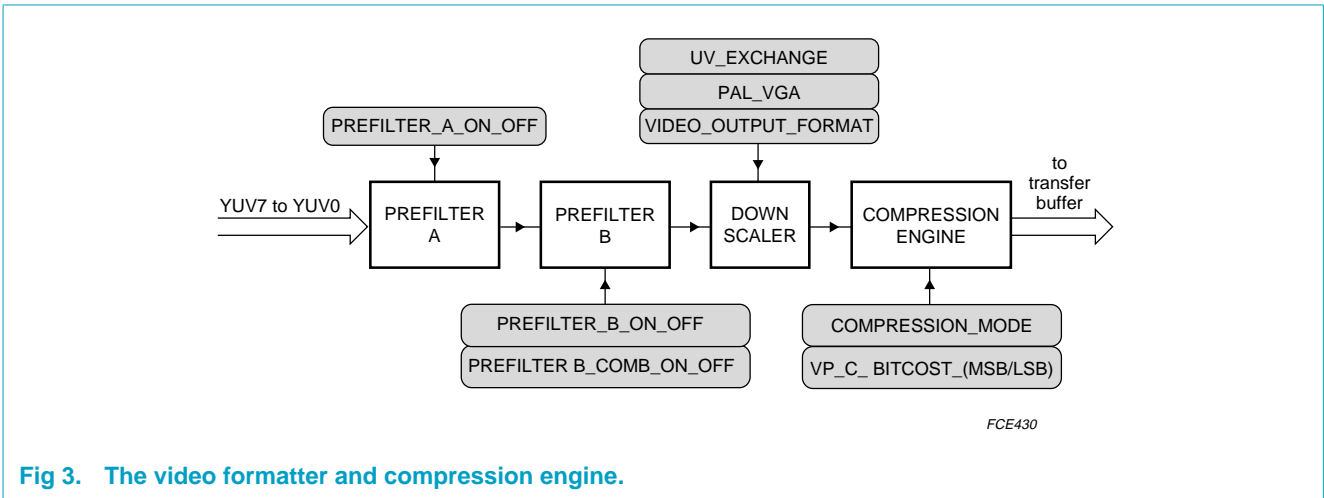


Fig 3. The video formatter and compression engine.

Table 4: Data rate performed by compression engine

Format	Advised data rate	Maximum data rate
CIF/SIF	2 bpp	12 bpp (uncompressed)
QCIF/QSIF	6 bpp	uncompressed
VGA high quality	3 bpp	4 bpp
VGA	1.5 bpp	3 bpp
RAW VGA high quality	4 bpp	4 bpp

1. Pentium — is a trademark of Intel Corp.

8.5 Transfer buffer

The transfer buffer module (see [Figure 4](#)) takes care of a smooth transfer of the data to the FIFO of the USB. Moreover the transfer buffer can insert inband synchronization words in the video data stream. This function can be switched on and off with INBAND_CONTROL in register VP_TR_CONTROL (0x36).

The synchronization words can only be used with non-compressed data stream and are formatted like 0x00 0xFF 0x<framecounter>₇<linecounter>₉. (Subscript denotes the number of bits and the frame counter is circular incrementing).

The non-compressed data is formatted like:

4 : 2 : 0: <optional sync word><Y0><Y1><Y2><Y3>
<C0><C2><Y4><Y5><Y6><Y7><C4><C6>.....,

4 : 2 : 2: <optional sync word><Y0><Y1><Y2><Y3> <U0><V0><U2><V2><Y4>.....,

where C denotes U-data in the even lines (0, 2, 4 etc.) and V-data in the odd lines (1, 3, 5 etc.).

8.6 USB video FIFO

The USB video FIFO is programmed via the I²C-bus (see [Figure 5](#)). The FIFO is designed to achieve three different packets containing video on the isochronous USB channel. Video data is contained in a chain of equally sized USB packets, except for the last packet of a video frame which is always smaller. The video frames can be separated from each other by one or more 0-length packets. For low frame rates (below 10 frames per second) there are always 0-length packets in the stream.

The host can synchronize on the smaller packets for the high frame rates and on the 0-length packets for the low frame rates.

For every mode the FIFO must be adjusted. There are three parameters to program the video FIFO:

- PACKET_SIZE (0x06): this value indicates the length of all packets with video data except for the last packet of a video frame
- FIFO_OFFSET (0x04): this value indicates the number of data in the FIFO before a new packet will be transmitted over USB
- READ_SPACING (0x07): this value indicates the number of 12 MHz clock cycles between read actions from the FIFO.

Moreover the FIFO is enabled and disabled with FIFO_ACTIVE (0x05).

The write process to the FIFO is controlled by the transfer buffer and not programmable.

The read process is executed in the PSIE-MMU and is driven by the USB frame interval (1 ms). Every frame interval the PSIE-MMU tries to read PACKET_SIZE bytes from the FIFO. This read process will not be started when a new video frame is stored in the FIFO and there are less than FIFO_OFFSET bytes written. The read process stops if the next bytes are of another video frame, or if the read-pointer would overtake the write-pointer.

READ_SPACING determines the read rate. Its value can easily be determined with the formula:

$$READ_SPACING < \frac{12000}{PACKET_SIZE}$$

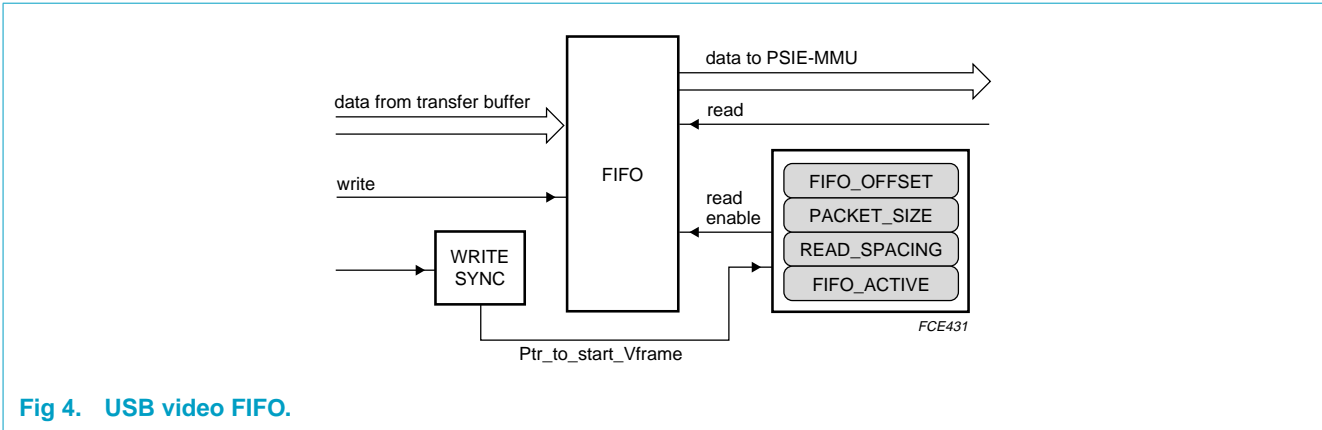


Fig 4. USB video FIFO.

8.7 PSIE-MMU, I²C-bus interface and USB RAM space

The Programmable Serial Interface Engine (PSIE) and Memory Management Unit (MMU) is the heart of the USB protocol hardware (see Figure 5). It formats the actual packets that are transferred to the USB and passes the incoming packets to the right end-point buffers. These buffers are allocated as part of the USB RAM space.

The microcontroller communicates via the I²C-bus with the PSIE-MMU. The I²C-bus protocol distinguishes three register spaces. These spaces are addressed via different commands. The command is sent to the command address.

Depending on the command it is sent to the PSIE-MMU and/or to the command interpreter which configures the (de-)mux to open the path to the right register space. Subsequent write/reads to/from the data address store or retrieve data from the register space selected by the command.

8.8 ATX interface

The SAA8115HL contains an analog bus driver, called the ATX. It incorporates a differential and two single-ended receivers and a differential transmitter.

The interface to the bus consists of a differential data pair (ATXDM and ATXDP).

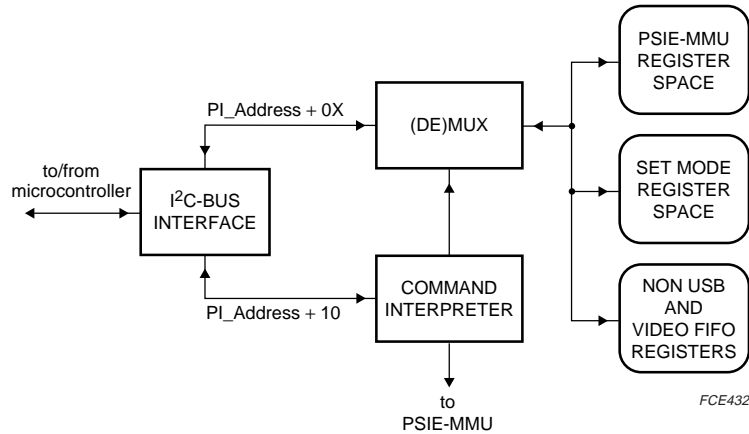


Fig 5. I²C-bus interface and register map.

8.9 Audio

The SAA8115HL contains a microphone supply and an amplifier circuit composed of two stages: a Low Noise Amplifier (LNA) and a variable gain amplifier. The LNA has a fixed gain of 26 dB while the variable gain amplifier can be programmed between 0 and 30 dB by steps of 2 dB. The gain control can be done via either the SNERT interface or the I²C-bus interface (see Table 60). The serial interface must be first selected using bit SIS (see Table 60). The frequency transfer characteristic of the audio path must be controlled via external high-pass or low-pass filters.

The PLL converts the 48 MHz to $256f_s$ (f_s = audio sample frequency). There are three modes for the PLL to achieve the sample frequencies of 48, 44.1 or 32 kHz (see Table 5).

The bitstream ADC samples the audio signal. It runs at an oversample rate of 256 times the base sample rate. In the application, the bitstream can be converted to parallel 16-bit samples. This conversion is programmable with respect to the effective sample frequency (dropping sample results in a lower effective sample frequency) and sample resolution. As a result the effective sample rate can be determined.

Table 5: ADC clock frequencies and sample frequencies

Clock (MHz)	Dividing number	Sample frequency (kHz)	ADC clock (MHz)
8.1920	1	32	4.096
	2	16	2.048
	4	8	1.042
	8	[1]	[1]
11.2996	1	44.1	5.6448
	2	22.05	2.8224
	4	11.025	1.4112
	8	5.5125	0.7056
12.2880	1	48	6.144
	2	24	3.072
	4	12	1.536
	8	6	0.768

[1] Not supported.

8.10 Sensor pulse pattern generator

The SAA8115HL incorporates a Pulse Pattern Generator (PPG) function. The PPG can be used for medium resolution PAL, CIF and VGA CCD-sensors (see Table 6).

Depending on the sensor type, an external inverter driver should be required to convert the 3.3 V pulses into a voltage suitable for the used CCD-sensor.

The active video size is 512×288 for medium resolution PAL, 352×288 for CIF and 640×480 for VGA. The total $H \times V$ size are 685×292 for medium resolution PAL/CIF and 823×486 for VGA. It should be noted that additional HD pulses are added during the vertical blanking interval to reach a total of 312 lines in PAL and CIF modes and 525 lines in VGA mode as required by the SAA8112HL.

A high level of flexibility is available for the PPG thanks to 19 internal registers (see Section 9.1.3).

Table 6: Typical SAA8115HL compatible sensors

Sensor type	Brand	Part number
VGA	Sony	ICX098AK
	Panasonic	MN3777PP and MN37771PT
	Sharp	LZ24BP
Medium resolution PAL	Sony	ICX054, ICX086 and ICX206
	Panasonic	MN37210FP
	Sharp	LZ2423B and LZ2423H
	Toshiba	TCD5391AP
CIF	Sharp	LZ244D and LZ2547
Other sensors	all the sensors fully compatible with the above mentioned sensors	

8.11 Power management

USB requires the device to switch power states. The SAA8115HL contains a power management module since the complete camera may not consume more than 500 μ A during the power state called SUSPEND. This requires that even the crystal oscillator must be switched off. The SAA8115HL is not functional except for some logic that enables the IC to wake-up the camera. After wake-up of the SAA8115HL first the clock to the microcontroller is generated and thereafter an interrupt is generated to wake-up the microcontroller. Therefore the clock of the microcontroller is generated by the SAA8115HL.

The power management module also sets a flag in register SET_MODE_AND_READ (PSIE_MMU_STATUS). After a reset the microcontroller should check this register via the I²C-bus and find the cause of the wake-up. Different causes may require different start-up routines.

The internal video processing core uses another supply domain which can be switched off during SUSPEND mode.

The PPG is switched off by setting PPG_RESUME_MODE (0x08) and resetting PAL_VGA (0x09).

In non CIF modes the power consumption is reduced by resetting COMPRESSION_MODE (0x2F) and COMPRESSION_CLOCK (0x09).

The SAA8115HL has the feature to autonomously wake-up from SUSPEND mode, but requires microcontroller interference before going in SUSPEND mode (via the signal on pin SUSPREADYNOT).

Since the main oscillator of the SAA8115HL is switched off during SUSPEND mode, precautions are needed to avoid undefined states when the clock is switched on. This is ensured via the pins CLOCKON and TRC. Pin CLOCKON goes HIGH as soon as the main oscillator is switched on. The oscillator will need some time to make a stable 48 MHz signal. However, the clock is only passed through to other parts of the SAA8115HL when the level on pin TRC reaches a certain threshold. The time needed to reach the threshold can be trimmed with an external RC circuit.

8.12 Power supply

A power supply regulator is integrated in the device. This DC-to-DC converter transforms the USB supply voltage (range from 4.0 to 5.5 V) into a stable 5 V supply voltage. This power domain is switchable. The power circuit also generates a reset signal when the external 3.3 V supply voltage is stable and in range.

9. Control register description

This specification gives an overview of all registers.

9.1 SNERT (UART)

The SAA8115HL is partly controlled via SNERT. The frame rate converter, the SDRAM interface, the video formatter, the compression engine, the PPG, the SMP and the audio functions are controlled via SNERT. This SNERT interface works independently from the frame rate and can always be operated in the full frequency range.

Via SNERT the following registers are accessible (see [Table 7](#)).

Table 7: SNERT write registers SAA8115HL

Address	Function
00	write register soft reset (see Table 8)
01 to 05	write registers Frame Rate Converter (FRC) including the SDRAM interface
06 and 07	reserved
08 to 1A	write registers Pulse Pattern Generator (PPG)
1B to 1F	reserved
20 to 38	write registers video formatter and compression engine
39 to 3C	reserved
3D and 3E	write registers Switch Mode Power (SMP)
3F	write register audio variable gain amplifier

9.1.1 General register

Table 8: Detailed description of SNERT general register 0x00

SNERT register 00: SOFT_RESET									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X	X				reserved
									RESET_VP_C
							1		compression engine in reset state
							0		compression engine operating
									RESET_VP_VF
							1		formatter engine in reset state
							0		formatter engine operating
									RESET_FRC
								1	frame rate converter engine in reset state (by default)
								0	frame rate converter engine operating

9.1.2 Frame rate converter and SDRAM interface registers

Table 9: Detailed description of SNERT FRC and SDRAM register 0x01

SNERT register 01: FRC_CONTROL_0									
Bit	7	6	5	4	3	2	1	0	Parameter
X									reserved
	X	X	X						number of active lines after rising edge of VS signal; range: 0 to 6 (by default 0)
									FRAMERATE_DIVIDER_SELECT_BIT
					1	1	1		undefined
					1	1	0		32 (30 fps in; 0.9375 fps out)
					1	0	1		16 (15 fps in; 0.9375 fps out)
					1	0	0		6 (30 fps in; 5 fps out)
					0	1	1		3 (30 fps in; 10 fps out) or (15 fps in; 5 fps out)
					0	1	0		2 (30 fps in; 15 fps out) or (15 fps in; 7.5 fps out)
					0	0	1		1 (1 fps in; 1 fps out) (by default)
					0	0	0		undefined
									LLC_CLKFREQ
								1	24 MHz (by default)
								0	12 MHz

Table 10: Detailed description of SNERT FRC and SDRAM register 0x02

SNERT register 02: FRC_CONTROL_1									
Bit	7	6	5	4	3	2	1	0	Parameter
X	X	X							reserved
									REFRESH_MODE
				1					automatic SRAM refresh
				0					precharge command as implicit refresh (by default)
									REFRESH_CLOCK (MSBs)
					X	X			see Table 12
									INPUT_FORMAT
							1	1	undefined
							1	0	medium resolution
							0	1	CIF
							0	0	VGA (by default)

Table 11: Detailed description of SNERT FRC and SDRAM register 0x03

SNERT register 03: FRC_ROWWIDTH									
Bit	7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	X	specifies the width of the row of the SDRAM
									95 for PAL sensors
									159 for VGA sensors (by default)
									63 for CIF sensors

Table 12: Detailed description of SNERT FRC and SDRAM register 0x04

Bit								SNERT register 04: FRC_REFRESH_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	specifies the number of clock cycles between two refresh cycles 246 for PAL sensors 395 for VGA sensors (by default) 239 for CIF sensors

Table 13: Detailed description of SNERT FRC and SDRAM register 0x05

Bit								SNERT register 05: FRC_STOPWRITE
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	number of lines in a frame 243 for VGA sensors (by default) 146 for PAL or CIF sensors

9.1.3 Pulse pattern generator registers

Table 14: Detailed description of SNERT PPG register 0x08

Bit								SNERT register 08: PPG_CONTROL_0	
7	6	5	4	3	2	1	0	Parameter	
X	X	X						reserved	
								SHUTTER_UPDATE_BUFFER	
				1				during the vertical blanking (shutter speed is buffered)	
				0				immediately (by default)	
								PPG_RESUME_MODE	
						1		switched off (except vertical transfer pulses in case of VGA sensors)	
						0		operating (by default)	
								PPG_FRAMERATE	
						1	1	X	undefined
						1	0	1	5 fps
						1	0	0	10 fps
						0	1	1	15 fps
						0	1	0	20 fps
						0	0	1	24 fps
						0	0	1	30 fps (by default)

Table 15: Detailed description of SNERT PPG register 0x09

SNERT register 09: PPG_CONTROL_1								
Bit	7	6	5	4	3	2	1 0	Parameter
	X							reserved
								COMPRESSION_CLOCK
		1	1	X	X			reserved
		1	0	1	1			24 MHz
		1	0	1	0			19.2 MHz
		1	0	0	1			16 MHz
		1	0	0	0			12 MHz (by default)
		0	1	1	1			9.6 MHz
		0	1	1	0			8.0 MHz
		0	1	0	1			6.0 MHz
		0	1	0	0			4.8 MHz
		0	0	1	1			4.0 MHz
		0	0	1	0			2.4 MHz
		0	0	0	1			2.0 MHz
		0	0	0	0			off
								VGA_SENSOR_TYPE (valid if MSB set to logic 0)
						1	1	VGA (Sony and Panasonic)
						1	0	VGA (Sharp)
						0	X	reserved
								PAL_VGA
							1	PAL or CIF timing
							0	VGA timing (by default)

Table 16: Detailed description of SNERT PPG register 0x0A

SNERT register 0A: PPG_H_CTRL								
Bit	7	6	5	4	3	2	1 0	Parameter
	X							reserved
								RG_SHORT
		1						RG pulse width is set to half of nominal value
		0						RG pulse width is set to nominal value
								FH2_CTRL (non FT mode) ^[1]
			1	X	1			no horizontal blanking
			1	X	0			no horizontal blanking, pulse inverted
			0	1	1			blanked to HIGH, starts HIGH
			0	1	0			blanked to LOW, starts LOW
			0	0	1			blanked to LOW, starts HIGH
			0	0	0			blanked to HIGH, starts LOW
								FH1_CTRL (non FT mode) ^[1]
					1	X	1	no horizontal blanking, pulse inverted
					1	X	0	no horizontal blanking
					0	1	1	blanked to HIGH, starts LOW
					0	1	0	blanked to HIGH, starts HIGH
					0	0	1	blanked to HIGH, starts LOW
					0	0	0	blanked to LOW, starts HIGH

[1] If bits [5 to 3] equal bits [2 to 0] then FH2 is the inverse of FH1.

Table 17: Detailed description of SNERT PPG register 0x0B

SNERT register 0B: PPG_V_INV									
Bit	7	6	5	4	3	2	1	0	Parameter
									A4_INV
	1								positive pulses
	0								negative pulses
									A3_INV
		1							positive pulses
		0							negative pulses
									A2_INV
			1						negative pulses
			0						positive pulses
									A1_INV
				1					negative pulses
				0					positive pulses
									B4_INV
					1				positive pulses
					0				negative pulses
									B3_INV
						1			positive pulses
						0			negative pulses
									B2_INV
							1		negative pulses
							0		positive pulses
									B1_INV
								1	negative pulses
								0	positive pulses

Table 18: Detailed description of SNERT PPG register 0x0C

SNERT register 0C: PPG_H_INV									
Bit	7	6	5	4	3	2	1	0	Parameter
									CLK2_INV
	1								inverted pulses
	0								nominal pulses
									CLK1_INV
		1							inverted pulses
		0							nominal pulses
									FS_INV
			1						positive pulses
			0						negative pulses
									FCDS_INV
				1					positive pulses
				0					negative pulses
									FR_INV
					1				positive pulses
					0				negative pulses
									C3_INV
						1			negative pulses
						0			positive pulses
									C2_INV
							1		negative pulses
							0		positive pulses
									C1_INV
								1	negative pulses
								0	positive pulses

Table 19: Detailed description of SNERT PPG register 0x0D

SNERT register 0D: PPG_MISC_INV									
Bit	7	6	5	4	3	2	1	0	Parameter
									SELECT_A2
1									A2 is HIGH during read-out gate in line 2
0									A2 is LOW during read-out gate in line 2
									SELECT_A3
		1							A3 equals A4 (in case of VGA type 1 sensors)
		0							A3 equals A2
									C4_INV
			1						negative pulses
			0						positive pulses
									CR_INV
				1					positive pulses
				0					negative pulses
									BCP_INV
					1				negative pulses
					0				positive pulses
									DCP_INV
						1			negative pulses
						0			positive pulses
									HD_INV
							1		negative pulses
							0		positive pulses
									VD_INV
								1	negative pulses
								0	positive pulses

Table 20: Detailed description of SNERT PPG register 0x0E

SNERT register 0E: PPG_SHUTTERSPEED_V_LSB									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X	X	X	X	X	8 LSBs of line number (9 bits)

Table 21: Detailed description of SNERT PPG register 0x0F

SNERT register 0F: PPG_SHUTTERSPEED_H_LSB									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits)

Table 22: Detailed description of SNERT PPG register 0x10

Bit								SNERT register 10: PPG_SHUTTERSPEED_MSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X					reserved
								SENSOR_TYPE
				1				Sony
				0				Sharp
					X	X		MSBs of pixel number (10 bits)
							X	MSBs of line number (9 bits)

Table 23: Detailed description of SNERT PPG register 0x11

Bit								SNERT register 11: PPG_BCP_START_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where BCP starts

Table 24: Detailed description of SNERT PPG register 0x12

Bit								SNERT register 12: PPG_BCP_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where BCP stops

Table 25: Detailed description of SNERT PPG register 0x13

Bit								SNERT register 13: PPG_DCP_START_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where DCP starts

Table 26: Detailed description of SNERT PPG register 0x14

Bit								SNERT register 14: PPG_DCP_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where DCP stops

Table 27: Detailed description of SNERT PPG register 0x15

Bit								SNERT register 15: PPG_BCP_DCP_MSB
7	6	5	4	3	2	1	0	Parameter
X	X							MSBs of PPG_DCP_STOP
		X	X					MSBs of PPG_DCP_START
				X	X			MSBs of PPG_BCP_STOP
						X	X	MSBs of PPG_BCP_START

Table 28: Detailed description of SNERT PPG register 0x16

Bit								SNERT register 16: PPG_B3_START_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where B3 starts

Table 29: Detailed description of SNERT PPG register 0x17

Bit								SNERT register 14: PPG_B3_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where B3 stops

Table 30: Detailed description of SNERT PPG register 0x18

Bit								SNERT register 18: PPG_B4_START_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where B4 starts

Table 31: Detailed description of SNERT PPG register 0x19

Bit								SNERT register 19: PPG_B4_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	8 LSBs of pixel number (10 bits) where B4 stops

Table 32: Detailed description of SNERT PPG register 0x1A

Bit								SNERT register 1A: PPG_B3_B4_MSB
7	6	5	4	3	2	1	0	Parameter
X	X							MSBs of PPG_B4_STOP
		X	X					MSBs of PPG_B4_START
				X	X			MSBs of PPG_B3_STOP
						X	X	MSBs of PPG_B3_START

9.1.4 Video formatter and compression engine registers

Table 33: Detailed description of SNERT video formatter register 0x20

Bit								SNERT register 20: VP_VF_CONTRL_0
7	6	5	4	3	2	1	0	Parameter
X	X							reserved
								UV_EXCHANGE
		X						exchange chrominance irregularities if needed
								SCALE_DATA: limits the number of bits of the video signal
				1	1			undefined
				1	0			6 bits
				0	1			7 bits
				0	0			8 bits
								PREFILTER_B_COMB_ON_OFF (if filter B is on)
						1		prefilter B_COMB with 13 taps
						0		prefilter B_COMB with 7 taps
								PREFILTER_B_ON_OFF
						1		on with 7 taps
						0		bypassed
								PREFILTER_A_ON_OFF
						1		on with 3 taps
						0		bypassed

Table 34: Detailed description of SNERT video formatter register 0x21

SNERT register 21: VP_VF_CONTRL_1								
Bit	7	6	5	4	3	2	1 0	Parameter
								420_FIL_BYPASS: 4 : 2 : 0 formatter mode
1								throw away samples
0								average UV samples
								VGA_RAW: data mode
	1							raw data, no scaling or 4 : 2 : 0 formatting
	0							YUV data
								VIDEO_OUTPUT_FORMAT
			1	1	1			undefined
			1	1	0			SIF
			1	0	1			QSIF
			1	0	0			undefined
			0	1	1			VGA
			0	1	0			CIF
			0	0	1			QCIF
			0	0	0			sub-QCIF
								VIDEO_INPUT_FORMAT
						1	1 1	undefined
						1	1 0	square SIF (sensors with square pixels)
						1	0 1	CIF (sensors with 12/11 pixel ratio format)
						1	0 0	medium resolution PAL
						0	1 1	undefined
						0	1 0	undefined
						0	0 1	undefined
						0	0 0	VGA

Table 35: Detailed description of SNERT video formatter register 0x22

SNERT register 22: VP_VF_VCOEF_C0_0								
Bit	7	6	5	4	3	2	1 0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 0 phase 0

Table 36: Detailed description of SNERT video formatter register 0x23

SNERT register 23: VP_VF_VCOEF_C0_1								
Bit	7	6	5	4	3	2	1 0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 0 phase 1

Table 37: Detailed description of SNERT video formatter register 0x24

Bit								SNERT register 24: VP_VF_VCOEF_C0_2
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 0 phase 2

Table 38: Detailed description of SNERT video formatter register 0x25

Bit								SNERT register 25: VP_VF_VCOEF_C1_0
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 1 phase 0

Table 39: Detailed description of SNERT video formatter register 0x26

Bit								SNERT register 26: VP_VF_VCOEF_C1_1
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 1 phase 1

Table 40: Detailed description of SNERT video formatter register 0x27

Bit								SNERT register 27: VP_VF_VCOEF_C1_2
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 1 phase 2

Table 41: Detailed description of SNERT video formatter register 0x28

Bit								SNERT register 28: VP_VF_VCOEF_C2_0
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 2 phase 0

Table 42: Detailed description of SNERT video formatter register 0x29

Bit								SNERT register 29: VP_VF_VCOEF_C2_1
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 2 phase 1

Table 43: Detailed description of SNERT video formatter register 0x2A

Bit								SNERT register 2A: VP_VF_VCOEF_C2_2
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 2 phase 2

Table 44: Detailed description of SNERT video formatter register 0x2B

Bit								SNERT register 2B: VP_VF_VCOEF_C3_0
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 3 phase 0

Table 45: Detailed description of SNERT video formatter register 0x2C

Bit								SNERT register 2C: VP_VF_VCOEF_C3_1
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 3 phase 1

Table 46: Detailed description of SNERT video formatter register 0x2D

Bit								SNERT register 2D: VP_VF_VCOEF_C3_2
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X	X	X	X	vertical filter coefficient tap 3 phase 2

Table 47: Detailed description of SNERT video formatter register 0x2E

Bit								SNERT register 2E: VP_VF_LIMITER
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	output of the video formatter is clipped to this maximum value

Table 48: Detailed description of SNERT compression engine register 0x2F

Bit								SNERT register 2F: VP_VF_CONTROL
7	6	5	4	3	2	1	0	Parameter
X								reserved
	X	X	X	X				QTABLE_SELECT: quantization table select range [0 : 15]
								DC_COEFF_LENGTH
						1	1	undefined
						1	0	8 bits
						0	1	7 bits
						0	0	6 bits
								COMPRESSION_MODE
							1	on
							0	off (by default)

Table 49: Detailed description of SNERT compression engine register 0x30

Bit								SNERT register 30: VP_C_YMASK
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	operates an AND between this value and the compression engine input; can be used to set bit positions in the Y signal to 0 (by default 0x00)

Table 50: Detailed description of SNERT compression engine register 0x31

Bit								SNERT register 31: VP_C_UVMASK
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	operates an AND between this value and the compression engine input; can be used to set bit positions in the UV signal to 0 (by default 0x00)

Table 51: Detailed description of SNERT compression engine register 0x32

Bit								SNERT register 32: VP_C_BITCOST_MSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	set the compression ratio; the bitcost determines the maximum number of bits generated by the compression algorithm for 4 subsequent lines

Table 52: Detailed description of SNERT compression engine register 0x33

Bit								SNERT register 33: VP_C_BITCOST_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	set the compression ratio; the bitcost determines the maximum number of bits generated by the compression algorithm for 4 subsequent lines

Table 53: Detailed description of SNERT compression engine register 0x34

Bit								SNERT register 34: VP_C_THRESHOLD_MSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	output of the video formatter is clipped to this maximum value

Table 54: Detailed description of SNERT compression engine register 0x35

Bit								SNERT register 35: VP_C_THRESHOLD_LSB
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	threshold must be set to: (number of UV blocks per band) × (DC_COEFF_LENGTH + 2)

Table 55: Detailed description of SNERT compression engine register 0x36

Bit								SNERT register 36: VP_TR_CONTROL
7	6	5	4	3	2	1	0	Parameter
X								reserved
	1							VGA_FORMAT 4 : 2 : 2 (uncompressed only)
	0							4 : 2 : 0
		1						INBAND_CONTROL on
		0						off
			X	X	X	X	X	LLC_OUT_DIV: select the rate at which the video data is transmitted to the USB core range [1 to 31]

Table 56: Detailed description of SNERT compression engine register 0x37

SNERT register 37: VP_TR_SQCIF_OFFSET									
Bit	7	6	5	4	3	2	1	0	Parameter
									VERTICAL_OFFSET
	X	X	X	X					range $3 \times [0 \text{ to } 15]$
									HORIZONTAL_OFFSET
					X	X	X	X	range $4 \times [0 \text{ to } 12]$

Table 57: Detailed description of SNERT compression engine register 0x38

SNERT register 38: VP_VS_V_SHIFT									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X	X	X	X	X	shift internal line counter with respect to VS pulse

9.1.5 Switch mode power registers

Table 58: Detailed description of SNERT SMP register 0x3D

SNERT register 3D: SMP_PERIOD									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X	X	X	X	X	period of SMP signal in units of $4 \times XOSC_PERIOD$ (0 by default)

Table 59: Detailed description of SNERT SMP register 0x3E

SNERT register 3E: SMP_LOWTIME									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X	X	X	X	X	low edge of SMP signal in units of $4 \times XOSC_PERIOD$ (0 by default)

9.1.6 Audio variable gain amplifier

Table 60: Detailed description of SNERT audio gain amplifier register 0x3F

SNERT register 3F: AUDIO_VGAIN									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X							reserved
									SIS: serial interface select
			1						SNERT
			0						I ² C-bus
				X					reserved
					X	X	X	X	variable gain settings (0 to 30 dB)

9.2 I²C-bus interface

The USB function has its own I²C-bus interface for communication with the microcontroller. The I²C-bus uses two addresses:

- Command address for writing commands to the Memory Manager (MM)
- Data address for writing/reading data to/from the Memory Manager (MM).

An address is a byte. The 7 MSBs are the actual address, the LSB is the R \overline{W} bit. When it is logic 0, data is transferred from the master to the slave, when it is logic 1, data is written from the slave to the master.

The 6 MSBs of the two addresses are equal and are defined by the PI_Address = 010111 (see Table 61). The LSB of the address differentiates between the command address and the data address. When bit 1 is logic 1 the address is the command address (0x5E) and when bit 1 is logic 0 the address is one of the data addresses (0x5C or 0x5D).

Table 61: I²C-bus addresses

Bit								Address
7	6	5	4	3	2	1	0	
0	1	0	1	1	1	0	0	0x5C: for writing data to the memory manager
0	1	0	1	1	1	0	1	0x5D: for reading data from the memory manager
0	1	0	1	1	1	1	0	0x5E: for writing commands
0	1	0	1	1	1	1	1	0x5F: not in use

9.2.1 Commands

The commands listed in Table 62 must be sent to the I²C-bus address 0x5E.

Table 62: I²C-bus USB command codes

Bit								Function
7	6	5	4	3	2	1	0	
0	0							end-point number select end-point
0	1							end-point number read/write status
1	0							end-point number initialize/read status information
1	1	0	1					address read/write register bank
1	1	1	0	0	X	X	X	not used
1	1	1	0	1	0	0	0	set non-USB register
1	1	1	1	0	0	0	0	read/write data
1	1	1	1	0	0	0	1	acknowledge setup
1	1	1	1	0	0	1	0	set buffer empty
1	1	1	1	1	0	1	0	set buffer full
1	1	1	1	0	1	0	0	read interrupt register
1	1	1	1	0	1	0	1	read current frame number
1	1	1	1	0	1	1	0	send resume
1	1	1	1	0	1	1	1	set status change bits
1	1	1	1	0	0	1	1	set mode

Table 63: Detailed description of set mode and write register overview

Byte	Set_mode_and_write
3	N1 timer: programmable timer for power management; counts 12 MHz cycles; must be bigger than number of cycles needed for the microcontroller to go in power-down state after pin SUSPREADYNOT is made LOW
2	N2 timer: programmable timer for power management; counts 12 MHz cycles; determines the time between the microcontroller clock is switched off and the main clock is switched off
1	PSIE-MMU control byte (see Table 64)

Table 64: Detailed description of set mode and write byte 3

Bit		PSIE-MMU control byte						
7	6	5	4	3	2	1	0	Parameter
X	X	X						reserved
			1					interrupt after isochronous audio transfer for each isochronous audio transfer an interrupt to the microcontroller will be generated; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
			0					no interrupts are given to the microcontroller
				1				interrupt after isochronous video transfer for each isochronous video transfer an interrupt to the microcontroller will be generated; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
				0				no interrupts are given to the microcontroller
					1			audio end-point audio end-point enabled; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
					0			audio end-point disabled; the PSIE-MMU will not react on in-tokens on the audio end-point
						1		video end-point video end-point enabled; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
						0		video end-point disabled; the PSIE-MMU will not react on in-tokens on the video end-point
							1	error debug mode interrupts are generated only in the event the transfer is not successfully completed; the microcontroller can read data from the interrupt and status registers to see the cause of this error
							0	all successful USB transactions are reported to the microcontroller via an interrupt; default set to logic 0 upon general power-on reset by the SAA8115HL

Table 65: Detailed description of set mode and read status byte

PSIE-MMU status byte									
Bit	7	6	5	4	3	2	1	0	Parameter
	X	X	X	X					reserved
									remote wake-up status flag
								1	remote wake-up when device is in SUSPEND mode
								0	no remote wake-up
									resume status flag
								1	bus resume by the host when device is in SUSPEND mode
								0	no bus resume
									bus reset status flag
								1	bus reset
								0	no bus reset
									power-up status flag
								1	general power-up reset
								0	no power-up reset

9.2.2 End-points

The SAA8115HL has 6 logical end-points which are listed in Table 66.

Table 66: Mapping of logical to physical end-point numbers for used end-points

End-point name	Logical end-point	Buffer size	Physical end-point	
			Out	In
Control end-point	0	8	0	1
Control end-point	1	8	2	3
Interrupt end-point	2	8	–	4
Interrupt end-point	3	8	–	5
Iso video end-point	4	96.0	–	6
Iso video end-point	5	35.1	–	7

9.2.3 Control top registers

The following registers can be written on I²C-bus address 1 after the command 0xE8 on I²C-bus address 0.

Table 67: I²C-bus control top registers

Address	Control top registers (base address: 0x08)
0x08	clock control
0x09	reset control
0x0A	mux block control
0x0B	power-on analog modules control

Table 68: Detailed description of I²C-bus control top registers 0x08

Top register 0x08: clkshop_control									
Bit	7	6	5	4	3	2	1	0	Parameter
									select ADC clock source
1									sel_ad: clock generated from ADC
0									sel_pll: clock generated from PLL
									set clock dividers for ADC
		0	0						set_divide00: divided by 1
		0	1						set_divide01: divided by 2
		1	0						set_divide10: divided by 4
		1	1						set_divide11: divided by 8
				X					reserved
									disable 48 MHz clock
							1		dis_clk_48: disable 48 MHz clock
							0		enable clock
									disable receiver clock
							1		dis_clk_rec: disable receiver clock
							0		enable clock
									disable ADC clock
							1		dis_clk_ad: disable ADC clock
							0		enable clock
								X	reserved

Table 69: Detailed description of I²C-bus control top registers 0x09

Bit								Top register 0x09: rst_gen and PLL_control
7	6	5	4	3	2	1	0	Parameter
								set PLL frequency
0	0							fcode00: 256 × 44.1 kHz
0	1							fcode01: 256 × 32 kHz
1	0							fcode10: 256 × 48 kHz
1	1							fcode11: 256 × 44.1 kHz
		X	X					reserved
								reset PSIE-MMU top module
							1	upc_rst_mmu: resetting the USB protocol block (called PSIE-MMU) during tests or in case of errors
							0	no reset
					X			reserved
								reset ADIF top module
							1	upc_rst_adif: resetting the digital audio part during tests or in case of errors
							0	no reset
								reset AGC module
							1	upc_rst_AGC: resetting the AGC control during tests or in case of errors
							0	no reset

Table 70: Detailed description of I²C-bus control top registers 0x0A

Bit								Top register 0x0A: io_mux_control
7	6	5	4	3	2	1	0	Parameter
X	X	X	X	X	X	X	X	reserved

Table 71: Detailed description of I²C-bus control top registers 0x0B

Top register 0x0B: power_control_of_analog_modules									
Bit	7	6	5	4	3	2	1	0	Parameter
									power control oscillator module
1									upc_osc_off: power management 48 MHz enabled
0									power management 48 MHz disabled
									power control audio module
		1							upc_osc_ad_off: power management audio enabled
		0							power management audio disabled
									power control PLL module
			1						upc_pll_off: PLL power-off
			0						power-on
				X					reserved
									power control ADC module left channel
					1				upc_adl_off: power-off
					0				power-on
									power control ADC module right channel
						1			upc_adr_off: power-off
						0			power-on
							1		power control AGC module left channel
							0		upc_AGCl_off: power-off
									power-on
								1	power control AGC module right channel
								0	upc_AGCr_off: power-off
									power-on

9.2.4 Video FIFO registers

Table 72: I²C-bus video FIFO registers overview

Address	Video FIFO registers (base address: 0x04)
0x04	FIFO offset (8 LSBs)
0x05	FIFO active and FIFO offset (3 MSBs)
0x06	packet size (8 LSBs)
0x07	read spacing and packet size (2 MSBs)

Table 73: Detailed description of I²C-bus video FIFO registers 0x04

FIFO register 0x04: FIFO_offset									
Bit	7	6	5	4	3	2	1	0	Parameter
									FIFO_OFFSET
X	X	X	X	X	X	X	X	X	mode_fifo_offset: sets the minimum contents of the FIFO that has to be reached, before a new video frame will be put on the USB. This value can be set between 0 and 2047. Total 11 bits with 8 LSBs in this register and 3 MSBs in register 0x05.

Table 74: Detailed description of I²C-bus video FIFO registers 0x05

FIFO register 0x05: FIFO_active and FIFO_offset									
Bit	7	6	5	4	3	2	1	0	Parameter
									FIFO_ACTIVE
1									mode_active: FIFO is active and the contents of the other mode registers should not be updated by the microcontroller (maledictive)
0									FIFO not active
	X	X	X	X					reserved
							X	X	FIFO_OFFSET (MSBs)
								X	3 MSBs of the offset value; see also register 0x04

Table 75: Detailed description of I²C-bus video FIFO registers 0x06

FIFO register 0x06: packet_size									
Bit	7	6	5	4	3	2	1	0	Parameter
									PACKET_SIZE
	X	X	X	X	X	X	X	X	mode_packet_size: sets the packet size of the USB video channel. Packets can vary in size between 0 and 1023. Total 10 bits with 8 LSBs in this register and 2 MSBs in register 0x07.

Table 76: Detailed description of I²C-bus video FIFO registers 0x07

FIFO register 0x07: read_spacing and packet_size									
Bit	7	6	5	4	3	2	1	0	Parameter
									READ_SPACING
	X	X	X	X	X	X			mode_read_spacing: sets the periodicity of the read pulses; the periodicity can be set from 1 to 63 (from '000001' to '111111')
							X	X	PACKET_SIZE
									mode_packet_size: 2 MSBs of the value (8 LSBs in register 0x06)

9.2.5 ADIF top registers

Table 77: I²C-bus ADIF top registers overview

Address	ADIF top registers (base address: 0x0C)
0x0C	reserved
0x0D	reserved
0x0E	VGA control gain
0x0F	ADIF control (ADIF2MMU)

Table 78: Detailed description of I²C-bus ADIF top registers 0x0E

ADIF register 0x0E: GAIN_control									
Bit	7	6	5	4	3	2	1	0	Parameter
	X								reserved
		0							GAIN_SOURCE_SELECT
		1							gain is controlled directly by bits 3 to 0
			X	X					reserved
									GAIN_CONTROL; 0 to 30 dB in steps of 2 dB
					0	0	0	0	0 dB
					0	0	0	1	2 dB
					:	:	:	:	:
					0	1	1	1	28 dB
					1	1	1	1	30 dB

Table 79: Detailed description of I²C-bus ADIF top registers 0x0F

ADIF register 0x0F: ADIF_control									
Bit	7	6	5	4	3	2	1	0	Parameter
	X								reserved
									number of bytes per sample
		0	0						0 (reserved)
		0	1						1 (8 bits audio samples)
		1	0						2 (16 bits audio samples)
		1	1						3 (24 bits audio samples)
									selection mono/stereo operation
				0					mono
				1					stereo
									selection input for ADC path (ADIF mux)
					0				digital input (from I ² S-bus)
					1				analog input (from Vin_left and Vin_right)
									selection high-pass filter (DC filter) for ADC down sample filter
						0			high-pass filter off
						1			high-pass filter on
									selection audio serial input format
							0	0	I ² S-bus
							0	1	LSB-justified, 16 bits
							1	0	LSB-justified, 18 bits
							1	1	LSB-justified, 20 bits

10. Limiting values

Table 80: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{DDA}	analog supply voltage		-0.5	+4.0	V
V _{DDA(USB)}	analog supply voltage from USB		[1] -0.5	+5.5	V
V _{DDD}	digital supply voltage		-0.5	+4.0	V
V _n	voltage on				
	pins AGND and DGND		-0.5	+4.0	V
	all other pins		-0.5	V _{DD} + 0.5	V
T _{stg}	storage temperature		-55	+150	°C
T _{amb}	ambient temperature		0	70	°C
T _j	junction temperature		-40	+125	°C

[1] This concerns pins VBUS1 and VBUS2.

11. Thermal characteristics

Table 81: Thermal characteristics

Symbol	Parameter	Conditions	Value	Unit
R _{th(j-a)}	thermal resistance from junction to ambient	in free air	45	K/W

12. Characteristics

Table 82: Characteristics

V_{DDD} = V_{DDA} = 3.3 V ± 10%; T_{amb} = 0 to 70 °C.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Supplies						
V _{DDDn}	digital supply voltage		3.0	3.3	3.6	V
V _{DDAn}	analog supply voltage		3.0	3.3	3.6	V
V _{DDA(USB)}	analog supply voltage from USB		[1] 4.3	5.0	5.5	V
V _{DGND}	digital ground supply		-0.3	0.0	+0.3	V
V _{AGND}	analog ground supply		-0.3	0.0	+0.3	V
I _{DD}	supply current		[2] -	100	125	mA
I _{DD(DC-DC)}	DC-DC supply current		[3] -	240	320	mA
Data and control inputs						
V _{IL}	LOW-level input voltage		-	-	0.8	V
V _{IH}	HIGH-level input voltage		2.0	-	-	V
Data and control outputs						
V _{OL}	LOW-level output voltage		0	-	0.1V _{DDD}	V
V _{OH}	HIGH-level output voltage		0.9V _{DDD}	-	V _{DDD}	V
Microphone supply						
I _{DD0}	supply current		-	0.85	1.2	mA

Table 82: Characteristics...continued

 $V_{DDD} = V_{DDA} = 3.3 \text{ V} \pm 10\%$; $T_{amb} = 0 \text{ to } 70 \text{ }^\circ\text{C}$.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{ref}	input reference voltage	at $\frac{1}{2} V_{DDA}$	–	1.65	–	V
V_O	output voltage	$V_{DDA} = 3.3 \text{ V}$	–	3.0	–	V
I_O	output current		–	–	2.0	mA
Low noise amplifier						
Transfer function						
R_i	input impedance		3.5	5.0	–	k Ω
I_{DD1}	supply current		–	0.85	1.2	mA
A	amplification		27	28	29	dB
$V_{O(rms)}$	output voltage (RMS value)		–	–	800	mV
THD	total harmonic distortion		[4] –	–69	–63	dB
V_{OO1}	output offset voltage		–	0.0	1.0	mV
Biasing						
I_{ref1}	reference current		–	10	–	μA
Variable gain amplifier						
Transfer function						
R_i	input impedance		7.0	10.5	13	k Ω
I_{DD2}	supply current		–	0.45	0.6	mA
A	amplification		0.0	–	32	dB
THD	total harmonic distortion		[5] –	–88	–82	dB
			[6] –	–65	–57	dB
V_{OO2}	output offset voltage	A = 0 dB	–	1.0	2.0	mV
		A = 30 dB	–	14	30	mV
Biasing						
I_{ref2}	reference current		–	10	–	μA
Audio PLL						
$f_{i(\text{clk})}$	clock input frequency		–	48	–	MHz
$f_{o(\text{clk})}$	clock output frequency		[7] –	11.2996	–	MHz
B	bandwidth		–	2.3	–	kHz
ζ	damping		–	0.98	–	
Audio ADC ($\Sigma\Delta$ converter)						
Inputs						
f_i	input signal frequency		1	–	20	kHz
$V_{i(rms)}$	input voltage (RMS value)		–	800	–	mV
Transfer Function						
N	order of the $\Sigma\Delta$		–	3	–	
N_{bit}	number of output bits		–	1	–	
$N_{bit(eq)}$	equivalent output resolution (bit)		–	16	–	
DR_i	dynamic range at input		[8] –	96.6	–	dB
f_{clk}	clock frequency		–	–	5.6448	MHz
δ	clock frequency duty factor		–	50	–	%

Table 82: Characteristics...continued

$V_{DDD} = V_{DDA} = 3.3\text{ V} \pm 10\%$; $T_{amb} = 0\text{ to }70\text{ }^\circ\text{C}$.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
THD	total harmonic distortion		–	–70	–55	dB

ATX transceiver

Driver characteristics in full speed mode: pins ATXDP and ATXDM

$f_{o(\text{sample})}$	sample output frequency		4	–	48	kHz
t_r	rise transition time	$C_L = 50\text{ pF}$	4	–	20	ns
t_f	fall transition time	$C_L = 50\text{ pF}$	4	–	20	ns
t_{match}	transition time matching		[9] 90	–	110	%
V_{cr}	output signal crossover voltage		1.3	–	2.0	V
Z_o	driver output impedance	steady state drive	30	–	42	Ω

Receiver characteristics in full speed mode: pins ATXDP and ATXDM

$f_{i(\text{sample})}$	sample input frequency		5	–	55	kHz
$f_{i(D)}$	data input frequency rate		–	12.00	–	Mbits/s
t_{frame}	frame interval		–	1.000	–	ms

DC-to-DC converter

5 V up and down converter (switchable supply domain)

V_O	output voltage		4.9	5.0	5.1	V
V_{ripple}	ripple on output voltage		–	20	–	mV
I_L	load current		–	–	150	mA
$R_{\text{DSON_P1}}$	PMOS switch-on resistance; down converter		[10] –	1.0	–	Ω
$R_{\text{DSON_N1}}$	NMOS switch-on resistance; down converter		[10] –	4.5	–	Ω
$R_{\text{DSON_P2}}$	PMOS switch-on resistance; up converter		[10] –	1.1	–	Ω
$R_{\text{DSON_N2}}$	NMOS switch-on resistance; up converter		[10] –	4.6	–	Ω

- [1] This concerns pins VBUS1 and VBUS2.
- [2] Conditions:
 - a) typical: VGA at 15 fps; $V_{DDD} = V_{DDA} = 3.3\text{ V}$; $T_{amb} = 25\text{ }^\circ\text{C}$
 - b) maximum: VGA at 30 fps; $V_{DDD} = V_{DDA} = 3.6\text{ V}$; $T_{amb} = 70\text{ }^\circ\text{C}$.
- [3] Conditions ($I_{\text{OUT}} = 125\text{ mA}$):
 - a) typical: $V_{\text{DD(USB)}} = 5.0\text{ V}$; $T_{amb} = 25\text{ }^\circ\text{C}$
 - b) maximum: $V_{\text{DD(USB)}} = 4.3\text{ V}$; $T_{amb} = 70\text{ }^\circ\text{C}$.
- [4] The distortion is measured at 1 kHz, $V_{o(\text{rms})} = 600\text{ mV}$.
- [5] The distortion is measured at 1 kHz, $V_{o(\text{rms})} = 600\text{ mV}$ and $A = 0\text{ dB}$.
- [6] The distortion is measured at 1 kHz, $V_{o(\text{rms})} = 600\text{ mV}$ and $A = 30\text{ dB}$.
- [7] Frequencies depend on PLL settings (see Table 5).

[8] Defined here as: $20 \times \log \frac{\text{input voltage}}{\text{equivalent input noise voltage}}$

[9] Transition time matching: $t_{\text{match}} = \frac{t_r}{t_f} \times 100\%$

[10] Including metal and contact resistance on chip and bonding wire resistance.

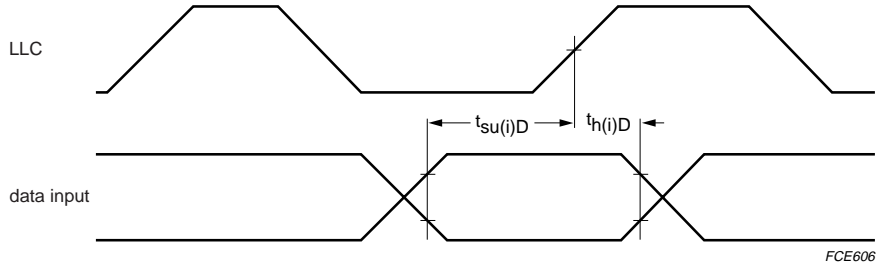
13. Timing

Table 83: Timing

$V_{DDD} = V_{DDA} = 3.3 V \pm 10\%$; $T_{amb} = 0$ to 70 °C.

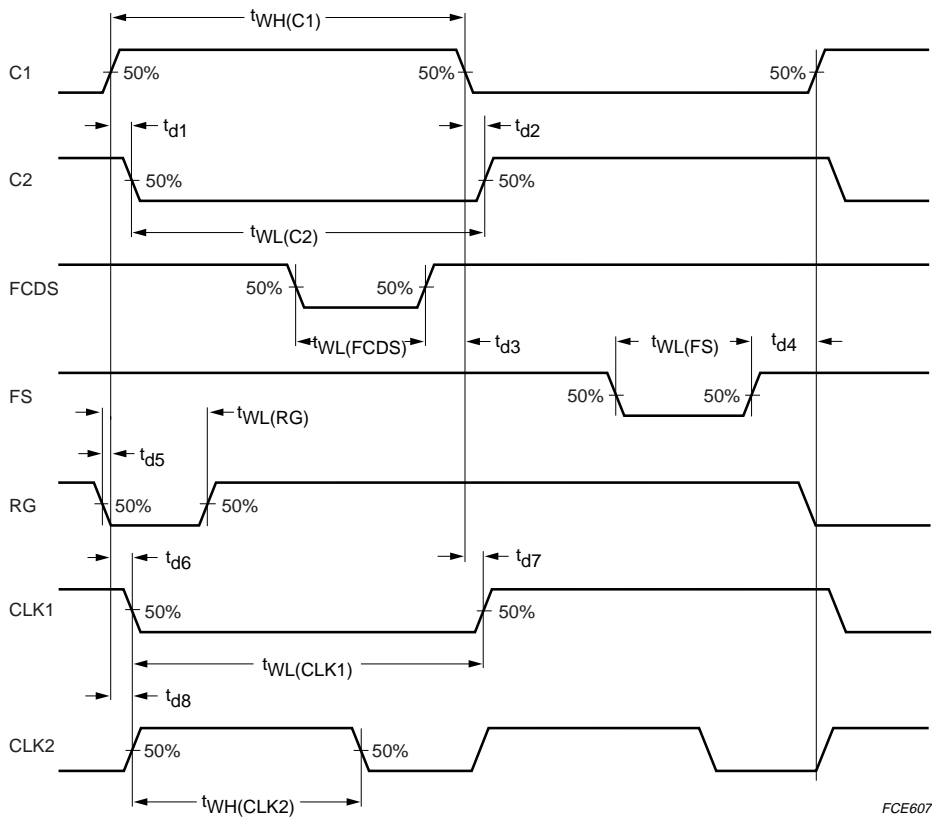
Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
Data input related to LLC (see Figure 6)						
Pins YUV0 to YUV7, HREF, VS						
$t_{su(i)(D)}$	data input set-up time		5	–	–	ns
$t_{h(i)(D)}$	data input hold time		3	–	–	ns
PPG high-speed pulses for Sony ICX098AK VGA CCD-sensor at 15 fps (see Figure 7)						
t_{d1}	delay between falling edge C2 and rising edge C1		–3.5	–2.5	–1.5	ns
t_{d2}	delay between rising edge C2 and falling edge C1		0	1.5	3	ns
t_{d3}	delay between falling edge C1 and rising edge FCDS		19	21	23	ns
t_{d4}	delay between rising edge C1 and rising edge FS		20	22	24	ns
t_{d5}	delay between rising edge C1 and falling edge RG		0	2	4	ns
t_{d6}	delay between falling edge CLK1 and rising edge C1		0	0.5	3	ns
t_{d7}	delay between rising edge CLK1 and falling edge C1		1	3.0	4	ns
t_{d8}	delay between rising edge CLK2 and rising edge C1		0	1.5	2.5	ns
$t_{WH(C1)}$	C1 pulse width HIGH		80	81	–	ns
$t_{WL(C2)}$	C2 pulse width LOW		83	85	–	ns
$t_{WL(FCDS)}$	FCDS pulse width LOW		16	18.5	–	ns
$t_{WL(FS)}$	FS pulse width LOW		41	42	–	ns
$t_{WL(RG)}$	RG pulse width LOW		42	43	–	ns
$t_{WL(CLK1)}$	CLK1 pulse width LOW		82	84.5	–	ns
$t_{WH(CLK2)}$	CLK2 pulse width HIGH		38	40	–	ns
t_r	rise time	[1]				
	pulse C1		–	4	–	ns
	pulse C2		–	4	–	ns
	pulse RG		–	4	–	ns
	pulse FCDS		–	4	–	ns
	pulse FS		–	4	–	ns
t_f	fall time	[1]				
	pulse C1		–	4	–	ns
	pulse C2		–	4	–	ns
	pulse RG		–	4	–	ns
	pulse FCDS		–	4	–	ns
	pulse FS		–	4	–	ns

[1] $C_L = 11$ pF; $T_{amb} = 25$ °C.



FCE606

Fig 6. Data input timing.



FCE607

Fig 7. PPG high-speed pulses for Sony ICX098AK VGA CCD-sensor.

14. Application information

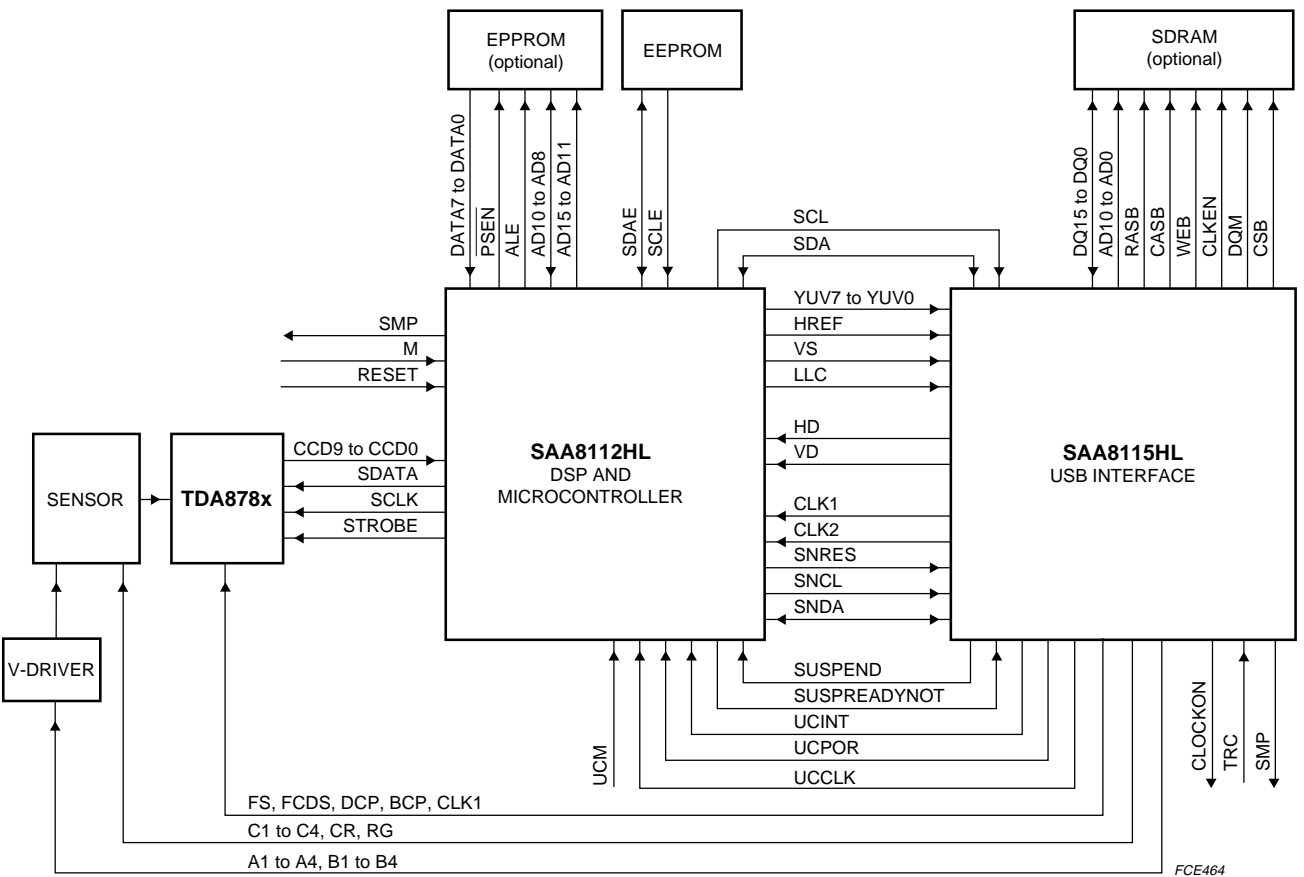
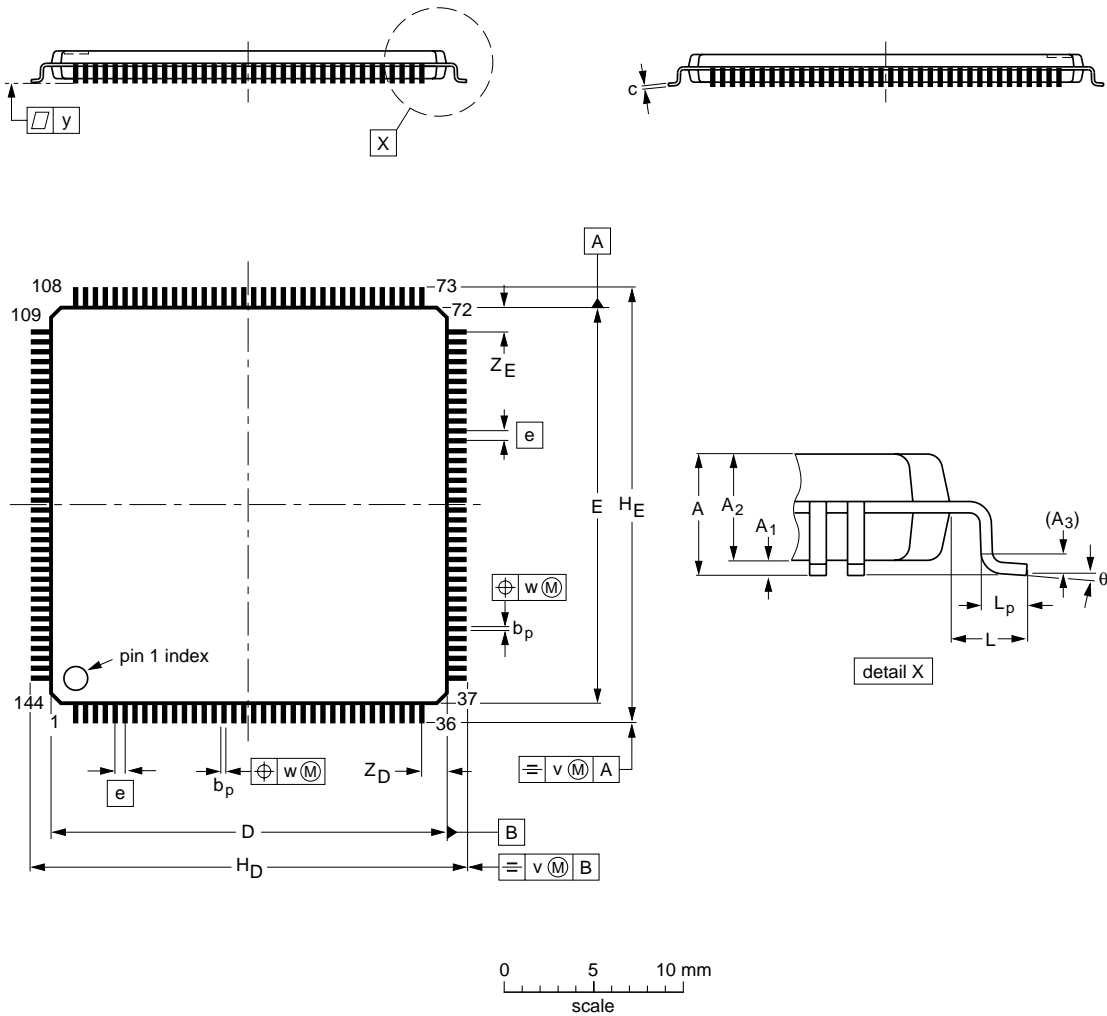


Fig 8. Typical USB camera application.

15. Package outline

LQFP144: plastic low profile quad flat package; 144 leads; body 20 x 20 x 1.4 mm

SOT486-1



DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A ₁	A ₂	A ₃	b _p	c	D ⁽¹⁾	E ⁽¹⁾	e	H _D	H _E	L	L _p	v	w	y	Z _D ⁽¹⁾	Z _E ⁽¹⁾	θ
mm	1.6	0.15 0.05	1.45 1.35	0.25	0.27 0.17	0.20 0.09	20.1 19.9	20.1 19.9	0.50	22.15 21.85	22.15 21.85	1.0	0.75 0.45	0.2	0.08	0.08	1.40 1.10	1.40 1.10	7° 0°

Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES			EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ		
SOT486-1	136E23	MS-026			00-01-19 00-03-14

Fig 9. SOT486-1.

16. Soldering

16.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

16.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferably be kept below 220 °C for thick/large packages, and below 235 °C small/thin packages.

16.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;
 - smaller than 1.27 mm, the footprint longitudinal axis **must** be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

- For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C. A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

16.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 °C.

16.5 Package related soldering information

Table 84: Suitability of surface mount IC packages for wave and reflow soldering methods

Package	Soldering method	
	Wave	Reflow ^[1]
BGA, LFBGA, SQFP, TFBGA	not suitable	suitable
HBCC, HLQFP, HSQFP, HSOP, HTQFP, HTSSOP, SMS	not suitable ^[2]	suitable
PLCC ^[3] , SO, SOJ	suitable	suitable
LQFP, QFP, TQFP	not recommended ^{[3][4]}	suitable
SSOP, TSSOP, VSO	not recommended ^[5]	suitable

- [1] All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the *Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods*.
- [2] These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- [3] If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- [4] Wave soldering is only suitable for LQFP, QFP and TQFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- [5] Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

17. Revision history

Table 85: Revision history

Rev	Date	CPCN	Description
04	20000810	-	Product specification; fourth version
03	20000127	-	Preliminary specification; third version
02	19991126	-	Preliminary specification; second version
01	19990628	-	Preliminary specification; initial version

18. Data sheet status

Datasheet status	Product status	Definition ^[1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

[1] Please consult the most recently issued data sheet before initiating or completing a design.

19. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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