# AN6656, AN6656S

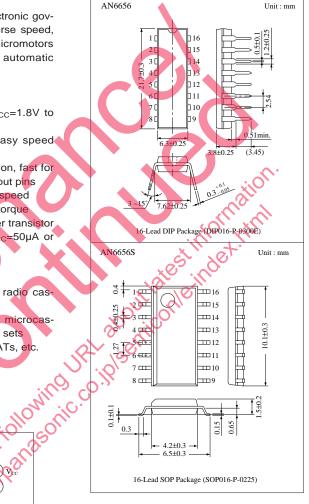
Micromotor Forward/Reverse Electronic Governors

#### Overview

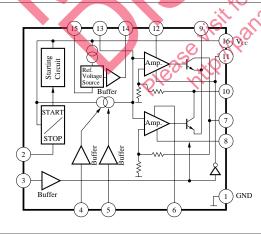
The AN6656 and the AN6656S are the electronic governors capable of controlling the forward/reverse speed, fast forward, rewind, and start stop of the micromotors used for the radio/cassette tape recorders, automatic answering telephone sets, and so on.

#### Features

- Wide operating supply voltage range :  $V_{CC}{=}1.8V$  to 6V
- Stable reference voltage (120mV) and easy speed control
- Capable of controlling forward/reverse rotation, fast for ward/constant speed, and start/stop via 3 input pins
- Capable of controlling a fast forward/rewind speed
- Large starting torque and maximum control torque
- Good secular drift because of external power transistor
- Provided with the motor stop function ;  $I_{CC}{=}50\mu A$  or less at stop time
- Applications
- Speed control of the micromotors for the radio cassettes
- Speed control of the micromotors for the microcassettes of the automatic answering telephone sets
- Control of the tape loading motors for the DATs, etc.



### Block Diagram



#### AN6656, AN6656S

#### ■ Absolute Maximum Ratings (Ta= 25°C)

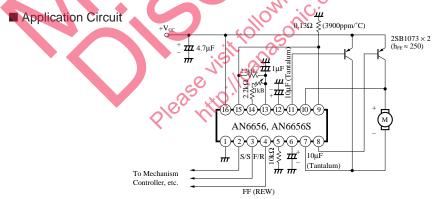
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Parameter		Symbol	Rating	Unit
Supply Voltage		V <sub>CC</sub>	6.5	v
Supply Current		I <sub>CC</sub>	25	mA
Output Current		Io	1000	mA
D. División	AN6656	D	500	
Power Dissipation	AN6656S	P <sub>D</sub>	380	mW
Operating Ambient Temperature		T <sub>opr</sub>	-20 ~ + 70	°C
Storage Temperature	AN6656		-55 ~ +150	*6
	AN6656S	- T <sub>stg</sub>	-55 ~ +125	°C

#### **\blacksquare** Recommended Operating Range (Ta = 25°C)

Parameter	Symbol		Range	
Operating Supply Voltage Range	V <sub>CC</sub>		1.8V ~ 6V	

#### $\blacksquare Electrical Characteristics (Ta = 25^{\circ}C)$

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Parameter	Symbol		Condition	min.	typ.	max.	Unit
Bias Current	I <sub>bias</sub>	$V_{\rm CC} = 5V$			5	15	mA
Prestart Current	$\mathbf{I}_{\mathrm{stop}}$	$V_{CC} = 5V$			Gz	50	μA
Reference Voltage	V <sub>ref</sub>	$V_{cc} = 3V$		85	120	150	mV
Start Voltage	V <sub>CC (S)</sub>	Supply voltage	at which a 50mA current flows to Ra	-S	~- <u>-</u> xe	1.2	v
Start Current	I <sub>st</sub>	$V_{CC} = 1.8V,$	$Ra = 4.9\Omega$	180	, t	_	mA
Rated Load r.p.m.	NL	$V_{\rm CC} = 3V, I_{\rm I}$	= 100mA, N = 2400rpm	-10	0	10	%
Forward/Reverse r.p.m. Difference	$\Delta N_{Logi}$	$V_{\rm CC} = 3V, I_{\rm I}$	= 100mA, N = 2400rpm	-8	0	8	%
r.p.m. Characteristics on Voltage Change	$\Delta N_V$	$V_{CC} = 3V \sim$	$6V, I_L = 100mA$			60	rpm/V
r.p.m. Characteristics on Load Change	$\Delta N_L$	$V_{\rm CC} = 1.8 V,$	$I_L = 50 \text{mA} \sim 100 \text{mA}$			150	rpm
Switching Mode Input H	V <sub>H</sub>		R 100	0.9		V <sub>CC</sub> +0.5	v
Switching Mode Input L	VL			0		0.3	v
Ref. Voltage Temperature Characteristics	∆V <sub>r</sub> /Ta	$V_{cc} = 3V, T$	$a = 0^{\circ}C \sim 60^{\circ}C$		0.01		%/°C



Note) The motor stops when the Pin2 is at "L" (0 to 0.3V), and starts at "H" (0.9 to  $V_{CC} + 0.5V$ ).

The motor runs in the reverse direction (a current flows from the motor  $\bigcirc$  pin to  $\oplus$  pin) when the Pin3 is at "L" (0 to 0.3V). The motor runs in the forward direction (a current flows from the motor  $\oplus$  pin to  $\bigcirc$  pin) when the Pin3 is at "H" (0.9 to V<sub>cc</sub> + 0.5V).

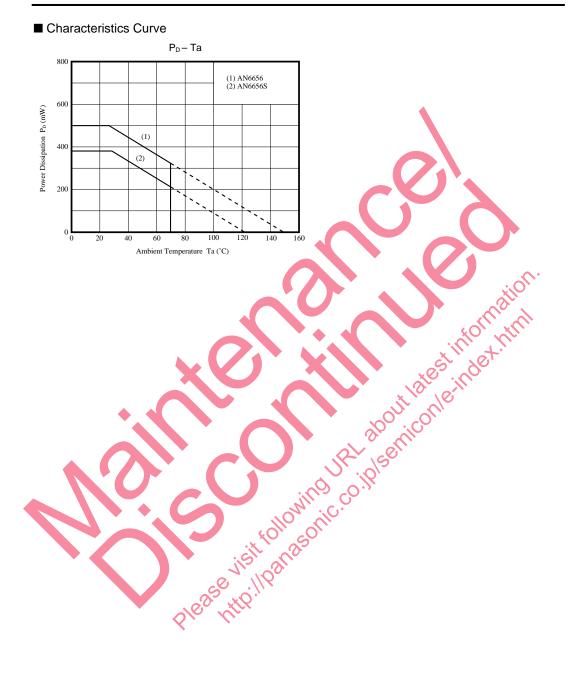
The motor runs at a normal speed when the Pin4 is at "L" (0 to 0.3V), and runs at a high speed (fast forward, rewind) when at "H" (0.9 to  $V_{CC} + 0.5V$ ).

At high speed rotation, the motor speed can be controlled with resistor between the Pin5 and GND.

Pin Description	s
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Pin No.	Pin Name	Description	I/O	Voltage	Equivalent Circuit
1	GND	GND pin	Ι	—	
2	Start/Stop	Start/stop control pin	I		ø 🕇
3	Forward/Reverse	Forward/reverse control pin	I	—	2 3 3 10kΩ 50kΩ
4	FF (REW) Switching	FF (REW) speed control pin	Ι		<i>(1</i> ) <i>m m m</i>
5	FF (REW) Speed Control	FF (REW) speed setting pin	0	0.05V	
6	Phase Compensation	Oscillation preventive phase compensation pin	I	0.7V	
7	Drive 1	Motor drive pin 1	0		
8	Output Control 1	External transistor control pin 1	0	ن م	
9	Load Characteristics Setting	Load characteristics setting pin	0	121-30 er	
10	Drive 2	Motor drive pin 2	inc		
11	Output Control 2	External transistor control pin 2			80012 <b>*</b>
12	Phase Compensation	Oscillation preventive phase compensation pin	I	0.7V	
13	Speed Setting	Speed setting input pin	I		
14	Reference Voltage	Reference voltage (+) output pin	0	0.15V	
15	Reference Voltage	Reference voltage — output pin	0	0	
16	V <sub>cc</sub>	V <sub>CC</sub> pin	I		

#### AN6656, AN6656S



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