2700 pixel \times 3 line CCD Linear Sensor (Color)

Description

The ILX524KA is a reduction type CCD linear sensor developed for color image scanner. This sensor reads legal-size documents at a density of 300 DPI.

Features

• Number of effective pixels:

8100 pixels (2700 pixels \times 3)

Pixel size: 8μm × 8μm (8μm pitch)

• Distance between line: 64µm (8 Lines)

Single-sided readout

• Ultra low lag / High sensitivity

Single 12V power supply

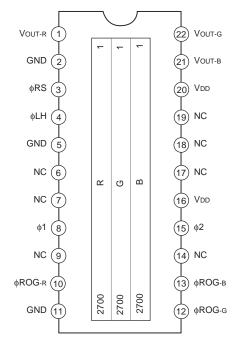
Input clock pulse: CMOS 5V drive
Number of output 3 (R, G, B)

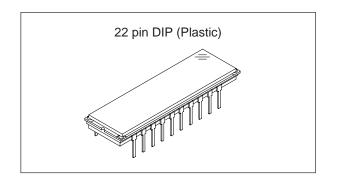
• Package: 22 pin Plastic-DIP (400 mil)

Absolute Maximum Ratings

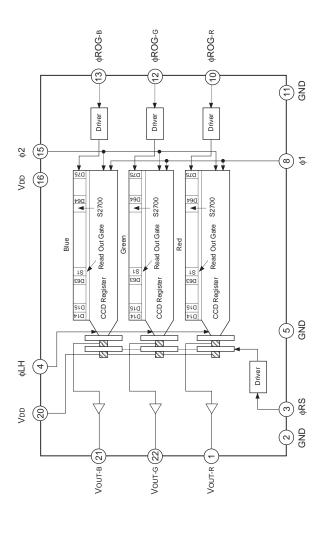
Supply voltage VDD 15 V
 Operating temperature -10 to +55 °C
 Storage temperature -30 to +80 °C

Pin Configuration (Top View)





Block Diagram



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Pin Description

Pin No.	Symbol	Description	Pin No.	Symbol	Description
1	Vout-r	Signal out (red)	12	φ ROG- G	Clock pulse input
2	GND	GND	13	фROG-в	Clock pulse input
3	φRS	Clock pulse input	14	NC	NC
4	φLH	Clock pulse input	15	φ2	Clock pulse input
5	GND	GND	16	VDD	12V power supply
6	NC	NC	17	NC	NC
7	NC	NC	18	NC	NC
8	φ1	Clock pulse input	19	NC	NC
9	NC	NC	20	VDD	12V power supply
10	φ ROG -R	Clock pulse input	21	Vоит-в	Signal out (blue)
11	GND	GND	22	Vout-g	Signal out (green)

Recommended Supply Voltage

Item	Min.	Тур.	Max.	Unit
VDD	11.4	12.0	12.6	V

Clock Characteristics

Item	Symbol	Min.	Тур.	Max.	Unit
Input capacity of \$1, \$2	Сф1, Сф2		400	_	pF
Input capacity of	Сфін		10		pF
Input capacity of φRS	Cors	_	10	_	pF
Input capacity of	Сфкоб		10	_	pF

^{*} It indicates that \$\phi ROG_R\$, \$\phi ROG_G\$, \$\phi ROG_B\$ as \$\phi ROG\$.

Clock Frequency

Item	Symbol	Min.	Тур.	Max.	Unit
φ1, φ2, φLH, φRS	fф1, fф2, fфLH, fфRS	_	1	5	MHz

Input Clock Pulse Voltage Condition

Item	Min.	Тур.	Max.	Unit	
φ1, φ2, φLH, φRS,	High level	4.75	5.0	5.25	V
φROG pulse voltage	Low level	_	0	0.1	V

Electrooptical Characteristics (Note 1)

Ta = 25°C, VDD = 12V, f\u00fcRs = 1MHz, Input clock = 5Vp-p, Light source = 3200K, IR cut filter CM-500S (t = 1.0mm)

Item		Symbol	Min.	Тур.	Max.	Unit	Remarks
	Red	RR	1.3	2.0	2.7		
Sensitivity	Green	Rg	2.1	3.2	4.3	V/(lx · s)	Note 2
	Blue	Rв	1.6	2.5	3.4		
Sensitivity nonuni	formity	PRNU	_	4	20	%	Note 3
Saturation output	voltage	VSAT	2	3.2	_	V	Note 4
	Red	SER	0.74	1.6	_	lx · s	
Saturation exposure	Green	SEG	0.46	1	_		Note 5
одровано	Blue	SEB	0.58	1.28	_		
Dark voltage aver	age	Vdrk	_	0.3	2	mV	Note 6
Dark signal nonur	niformity	DSNU	_	1.5	5	mV	Note 6
Image lag		IL	_	0.02	_	%	Note 7
Supply current		Ivdd	_	26	50	mA	_
Total transfer efficiency		TTE	92	98	_	%	_
Output impedance		Zo	_	250	_	Ω	_
Offset level		Vos	_	6.5	_	V	Note 8
Dynamic range		DR	1000	10670	_	_	Note 9

Note

- 1) In accordance with the given electrooptical characteristics, the black level is defined as the average value of D2, D3 to D12.
- 2) For the sensitivity test light is applied with a uniform intensity of illumination.
- 3) PRNU is defined as indicated below. Ray incidence conditions are the same as for Note 2.

$$Vout-G = 500mV (Typ.)$$

$$PRNU = \frac{(V_{MAX} - V_{MIN})/2}{V_{AVE}} \times 100 [\%]$$

Where the 2700 pixels are divided into blocks of 100. The maximum output of each block is set to VMAX, the minimum output to VMIN and the average output to VAVE.

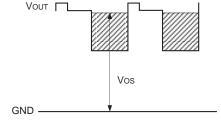
- 4) Use below the minimum value of the saturation output voltage.
- 5) Saturation exposure is defined as follows.

$$SE = \frac{V_{SAT}}{R}$$

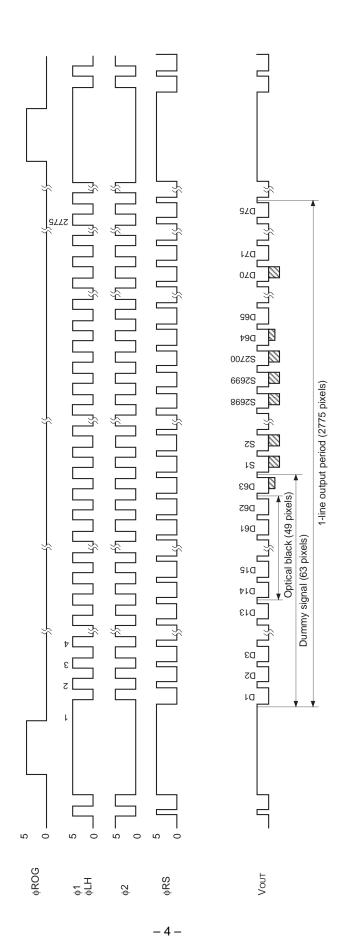
Where R indicates RR, Rg, RB, and SE indicates SER, SEG, SEB.

- 6) Optical signal accumulated time τ int stands at 10ms.
- 7) Vout-g = 500mV (Typ.)
- Vos is defined as indicated bellow.
 Vout indicates Vout-R, Vout-G, and Vout-B.
- 9) Dynamic range is defined as follows.

$$DR = \frac{V_{SAT}}{V_{DRK}}$$



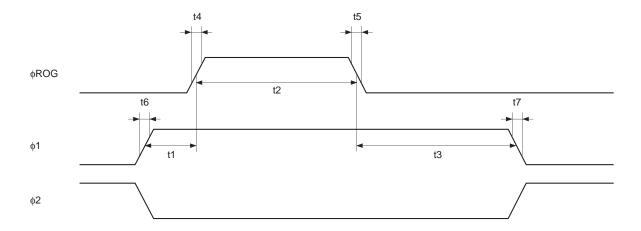
When the optical signal accumulated time is shorter, the dynamic range gets wider because the optical signal accumulated time is in proportion to the dark voltage.



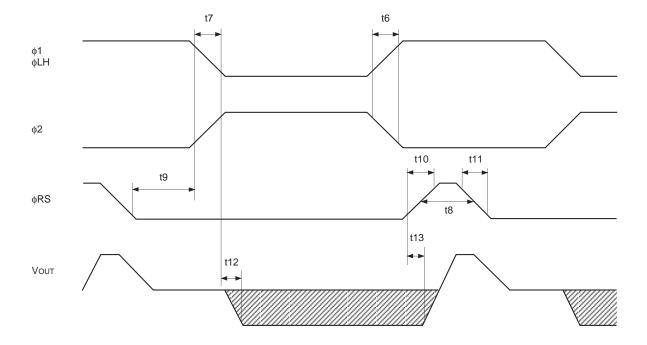
Note) The transfer pulses (\$\psi\$1, \$\psi\$2, \$\psi\$LH) must have more than 2775 cycles. Vour indicates Vour-R, Vour-G, Vour-B.



Clock Timing Chart 2



Clock Timing Chart 3



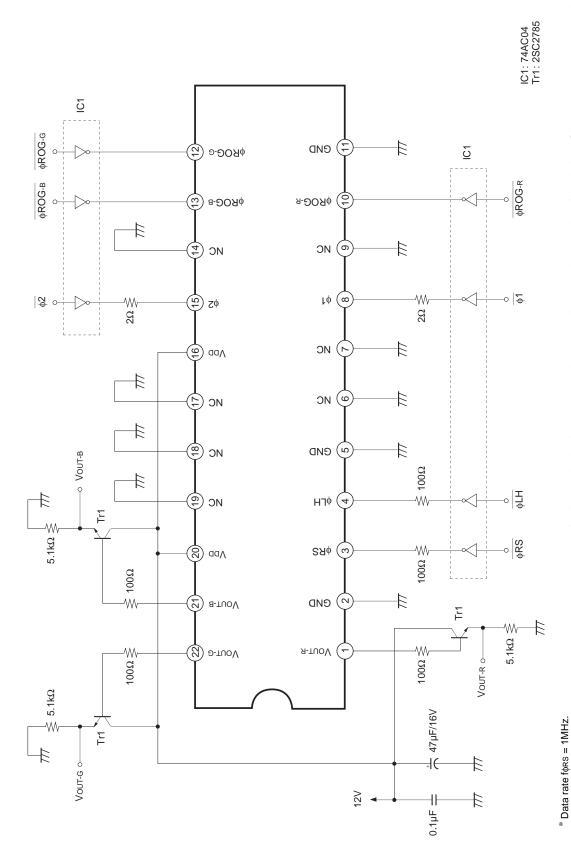


Clock Pulse Recommended Timing

				1	
Item	Symbol	Min.	Тур.	Max.	Unit
φROG, φ1 pulse timing	t1	50	100	_	ns
φROG pulse high level period	t2	800	1000	_	ns
φROG, φ1 pulse timing	t3	800	1000	_	ns
φROG pulse rise time	t4	0	5	10	ns
φROG pulse fall time	t5	0	5	10	ns
φ1 pulse rise time /φ2 pulse fall time	t6	0	20	60	ns
φ1 pulse fall time /φ2 pulse rise time	t7	0	20	60	ns
φRS pulse high level period	t8	45	250*	_	ns
φRS, φLH pulse timing	t9	45	250*	_	ns
φRS pulse rise time	t10	0	10	30	ns
φRS pulse fall time	t11	0	10	30	ns
Signal output dalay time	t12	_	10	_	ns
Signal output delay time	t13	_	10	_	ns

^{*} These timing is the recommended condition under $f\phi_{RS} = 1MHz$.

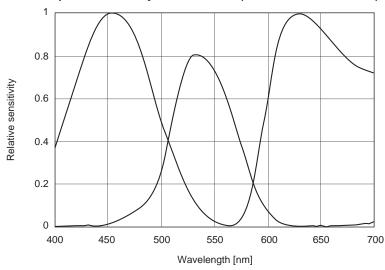
Application Circuit*



Application circuits shown are typical examples illustrating the operation of the devices. Sony cannot assume responsibility for any problems arising out of the use of these circuits or for any infringement of third party patent and other right due to same.

Example of Representative Characteristics (VDD = 12V, Ta = 25°C)

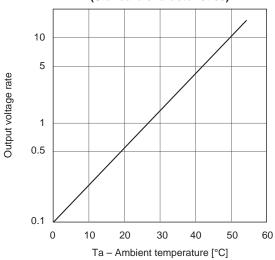


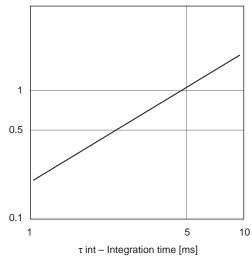


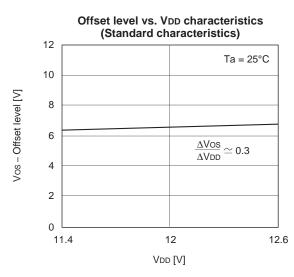
Output voltage rate

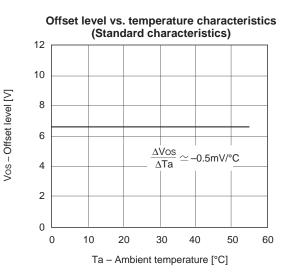
Dark signal output temperature characteristics (Standard characteristics)

Integration time output voltage characteristics (Standard characteristics)









Notes of Handling

1) Static charge prevention

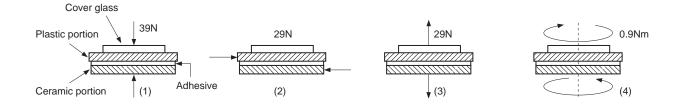
CCD image sensors are easily damaged by static discharge. Before handling be sure to take the following protective measures.

- a) Either handle bare handed or use non chargeable gloves, clothes or material. Also use conductive shoes.
- b) When handling directly use an earth band.
- c) Install a conductive mat on the floor or working table to prevent the generation of static electricity.
- d) Ionized air is recommended for discharge when handling CCD image sensor.
- e) For the shipment of mounted substrates, use boxes treated for prevention of static charges.

2) Notes on Handling CCD Packages

The following points should be observed when handling and installing plastic packages.

- a) Remain within the following limits when applying static load to the package.
 - (1) Compressive strength: 39N/surface (Do not apply load more than 0.7mm inside the outer perimeter of the glass portion.)
 - (2) Shearing strength: 29N/surface(3) Tensile strength: 29N/surface(4) Torsional strength: 0.9Nm



- b) In addition, if a load is applied to the entire surface by a hard component, bending stress may be generated and the package may fracture, etc., depending on the flatness of the ceramic portion. Therefore, for installation, either use an elastic load, such as a spring plate, or an adhesive.
- c) Be aware that any of the following can cause the package to crack or dust to be generated.
 - (1) Applying repetitive bending stress to the external leads.
 - (2) Applying heat to the external leads for an extended period of time with soldering iron.
 - (3) Rapid cooling or heating.
 - (4) Prying the plastic portion and ceramic portion away at a support point of the adhesive layer.
 - (5) Applying the metal a crash or a rub against the plastic portion.

Note that the preceding notes should also be observed when removing a component from a board after it has already been soldered.

d) The notch of the plastic portion is used for directional index, and that can not be used for reference of fixing. In addition, the cover glass and seal resin may overlap with the notch or ceramic may overlap with the notch of the plastic portion.

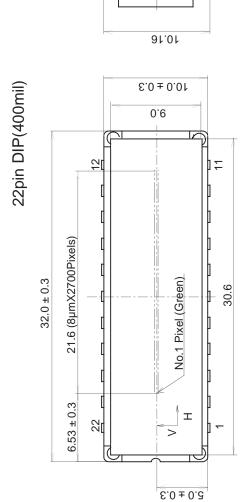
3) Soldering

- a) Make sure the package temperature does not exceed 80°C.
- b) Solder dipping in a mounting furnace causes damage to the glass and other defects. Use a grounded 30W soldering iron and solder each pin in less then 2 seconds. For repairs and remount, cool sufficiently.
- c) To dismount an imaging device, do not use a solder suction equipment. When using an electric desoldering tool, ground the controller. For the control system, use a zero cross type.

- 4) Dust and dirt protection
 - a) Operate in clean environments.
 - b) Do not either touch glass plates by hand or have any object come in contact with glass surfaces. Should dirt stick to a glass surface, blow it off with an air blower. (For dirt stuck through static electricity ionized air is recommended.)
 - c) Clean with a cotton bud and ethyl alcohol if the glass surface is grease stained. Be careful not to scratch the glass.
 - d) Keep in a case to protect from dust and dirt. To prevent dew condensation, preheat or precool when moving to a room with great temperature differences.
- 5) Exposure to high temperatures or humidity will affect the characteristics. Accordingly avoid storage or usage in such conditions.
- 6) CCD image sensors are precise optical equipment that should not be subject to mechanical shocks.

Package Outline

Unit: mm



°6 of °0

1. The height from the bottom to the sensor surface is 1.61 $\pm\,0.3\text{mm}.$

32.0

The thickness of the cover glass is 0.7mm, and the refractive index is 1.5. 2

2.80 ± 08.5

0.51

2.10

♦ 0.3

		
	2.54	JRE
<u> </u> 		PACKAGE STRUCTURE
<u> </u>		TRI
	ı	GES
		X
3.0 ± 0.4		PA

Plastic , Ceramic	GOLD PLATING	42 ALLOY	2.21g	LS-D10(E)
PACKAGE MATERIAL	LEAD TREATMENT	LEAD MATERIAL	PACKAGE MASS	DRAWING NUMBER