



CYPRESS

# CY7C1359A/GVT71256T18

## 256K x 18 Synchronous-Pipelined Cache Tag RAM

### Features

- Fast match times: 3.5, 3.8, 4.0 and 4.5 ns
- Fast clock speed: 166, 150, 133, and 100 MHz
- Fast OE access times: 3.5, 3.8, 4.0 and 5.0 ns
- Pipelined data comparator
- Data input register load control by  $\overline{DEN}$
- Optimal for depth expansion (one cycle chip deselect to eliminate bus contention)
- 3.3V -5% and +10% core power supply
- 2.5V or 3.3V I/O supply
- 5V tolerant inputs except I/Os
- Clamp diodes to  $V_{SS}$  at all inputs and outputs
- Common data inputs and data outputs
- JTAG boundary scan
- Byte Write Enable and Global Write control
- Three chip enables for depth expansion and address pipeline
- Address, data, and control registers
- Internally self-timed Write Cycle
- Burst control pins (interleaved or linear burst sequence)
- Automatic power-down for portable applications
- Low-profile JEDEC standard 100-pin TQFP package

### Functional Description

The Cypress Synchronous Burst SRAM family employs high-speed, low power CMOS designs using advanced triple-layer polysilicon, double-layer metal technology. Each memory cell consists of four transistors and two high valued resistors.

All synchronous inputs are gated by registers controlled by a positive-edge-triggered Clock Input (CLK). The synchronous inputs include all addresses, all data inputs, address-pipelining Chip Enable (CE), depth-expansion Chip Enables ( $\overline{CE}_2$  and  $\overline{CE}_1$ ), Burst Control Inputs (ADSC, ADSP, and ADV), Write Enables (WEL, WEH, and BWE), Global Write ( $\overline{GW}$ ), and Data Input Enable (DEN).

Asynchronous inputs include the Burst Mode Control (MODE), the Output Enable ( $\overline{OE}$ ) and the Match Output Enable ( $\overline{MOE}$ ). The data outputs (Q) and Match Output (MATCH), enabled by  $\overline{OE}$  and  $\overline{MOE}$  respectively, are also asynchronous.

Addresses and chip enables are registered with either Address Status Processor (ADSP) or Address status Controller (ADSC) input pins. Subsequent burst addresses can be internally generated as controlled by the Burst Advance pin (ADV).

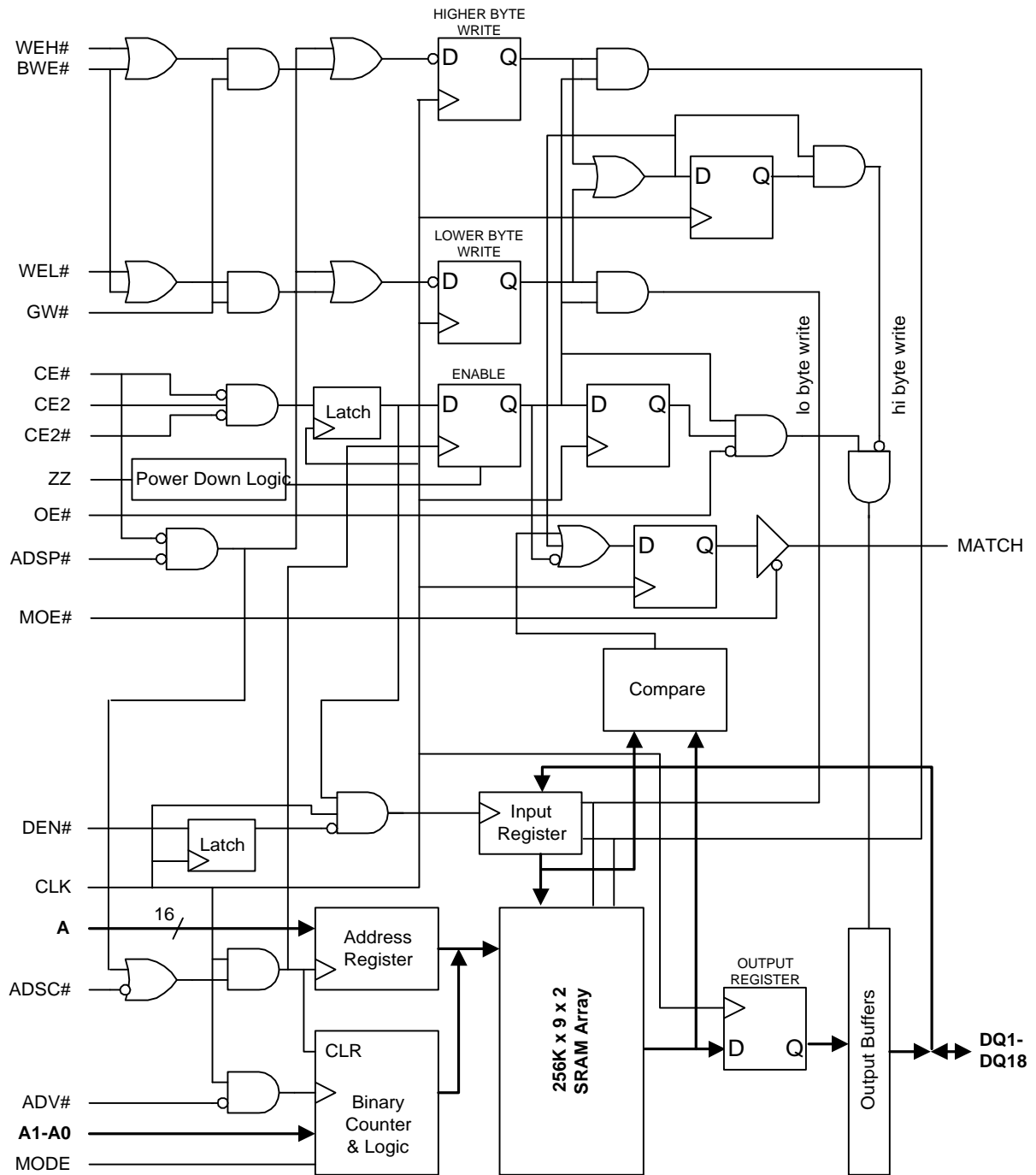
Data inputs are registered with Data Input Enable ( $\overline{DEN}$ ) and chip enable pins (CE,  $\overline{CE}_2$ , and  $\overline{CE}_1$ ). The outputs of the data input registers are compared with data in the memory array and a match signal is generated. The match output is gated into a pipeline register and released to the match output pin at the next rising edge of Clock (CLK).

Address, data inputs, and write controls are registered on-chip to initiate self-timed WRITE cycle. WRITE cycles can be one to two bytes wide as controlled by the write control inputs. Individual byte write allows individual byte to be written. WEL controls DQ1-DQ9. WEH controls DQ10-DQ18. WEL and WEH can be active only with BWE being LOW.  $\overline{GW}$  being LOW causes all bytes to be written.

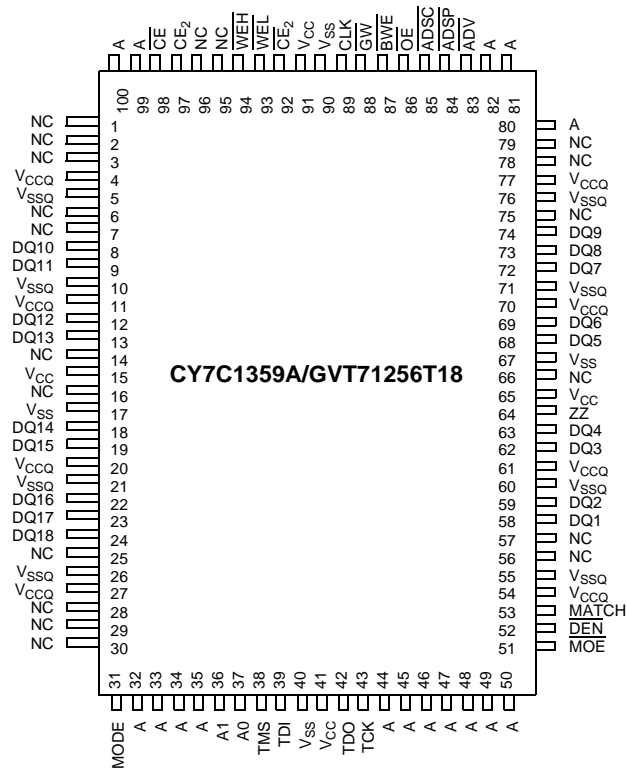
The CY7C1359C/GVT71256T18 operates from a +3.3V power supply with output power supply being +2.5V or +3.3V. All inputs and outputs are LVTTTL compatible. The device is ideally suited for address tag RAM for up to 8 MB secondary cache.

### Selection Guide

	7C1359A-166 71256T36-6	7C1359A-150 71256T36-6.7	7C1359A-133 71256T36-7.5	7C1359A-100 71256T36-10
Maximum Access Time (ns)	3.5	3.8	4.0	4.5
Maximum Operating Current (mA)	310	275	250	190
Maximum CMOS Standby Current (mA)	20	20	20	20

**Functional Block Diagram—256Kx18<sup>[1]</sup>**

**Note:**

1. The Functional Block Diagram illustrates simplified device operation. See Truth Table, pin descriptions and timing diagrams for detailed information.

**Pin Configurations**
**100-Pin TQFP  
Top View**

**119-Lead BGA  
Top View**

	1	2	3	4	5	6	7
<b>A</b>	V <sub>CCQ</sub>	A	A	ADSP	A	A	V <sub>CCQ</sub>
<b>B</b>	NC	CE <sub>2</sub>	A	ADSC	A	CE <sub>2</sub>	NC
<b>C</b>	NC	A	A	V <sub>CC</sub>	A	A	NC
<b>D</b>	DQ10	NC	V <sub>SS</sub>	NC	V <sub>SS</sub>	DQ9	NC
<b>E</b>	NC	DQ11	V <sub>SS</sub>	CE	V <sub>SS</sub>	NC	DQ8
<b>F</b>	V <sub>CCQ</sub>	NC	V <sub>SS</sub>	OE	V <sub>SS</sub>	DQ7	V <sub>CCQ</sub>
<b>G</b>	NC	DQ12	WEH	ADV	V <sub>SS</sub>	NC	DQ6
<b>H</b>	DQ13	NC	V <sub>SS</sub>	GW	V <sub>SS</sub>	DQ5	NC
<b>J</b>	V <sub>CCQ</sub>	V <sub>CC</sub>	NC	V <sub>CC</sub>	NC	V <sub>CC</sub>	V <sub>CCQ</sub>
<b>K</b>	NC	DQ14	V <sub>SS</sub>	CLK	V <sub>SS</sub>	NC	DQ4
<b>L</b>	DQ15	NC	V <sub>SS</sub>	NC	WEL	DQ3	NC
<b>M</b>	V <sub>CCQ</sub>	DQ16	V <sub>SS</sub>	BWE	V <sub>SS</sub>	MATCH	V <sub>CCQ</sub>
<b>N</b>	DQ17	NC	V <sub>SS</sub>	A1	V <sub>SS</sub>	DQ2	DEN
<b>P</b>	NC	DQ18	V <sub>SS</sub>	A0	V <sub>SS</sub>	MOE	DQ1
<b>R</b>	NC	A	MODE	V <sub>CC</sub>	NC	A	NC
<b>T</b>	NC	A	A	NC	A	A	ZZ
<b>U</b>	V <sub>CCQ</sub>	TMS	TDI	TCK	TDO	NC	V <sub>CCQ</sub>

**Pin Descriptions**

BGA Pins	TQFP Pins	Name	Type	Description
4P 4N 2A, 3A, 5A, 6A, 3B, 5B, 2C, 3C, 5C, 6C, 2R, 6R, 2T, 3T, 5T, 6T	37 36 35, 34, 33, 32, 100, 99, 82, 81, 80, 48, 47, 46, 45, 44, 49, 50	A0 A1 A	Input- Synchronous	Addresses: These inputs are registered and must meet the set-up and hold times around the rising edge of CLK. The burst counter generates internal addresses associated with A0 and A1, during burst cycle and wait cycle.
5L 3G	93 94	$\overline{WEL}$ $\overline{WEH}$	Input- Synchronous	Byte Write Enables: A byte write enable is LOW for a WRITE cycle and HIGH for a READ cycle. $\overline{WEL}$ controls DQ1–DQ9. $\overline{WEH}$ controls DQ10–DQ18. Data I/O are high impedance if either of these inputs are LOW, conditioned by BWE being LOW.
4M	87	$\overline{BWE}$	Input- Synchronous	Write Enable: This active LOW input gates byte write operations and must meet the set-up and hold times around the rising edge of CLK.
4H	88	$\overline{GW}$	Input- Synchronous	Global Write: This active LOW input allows a full 18-bit WRITE to occur independent of the $\overline{BWE}$ and $\overline{WEn}$ lines and must meet the set-up and hold times around the rising edge of CLK.
4K	89	CLK	Input- Synchronous	Clock: This signal registers the addresses, data, chip enables, write control, and data input enable control input on its rising edge. All synchronous inputs must meet set-up and hold times around the clock's rising edge.
4E	98	$\overline{CE}$	Input- Synchronous	Chip Enable: This active LOW input is used to enable the device and to gate ADSP.
6B	92	$\overline{CE}_2$	Input- Synchronous	Chip Enable: This active LOW input is used to enable the device.
2B	97	$CE_2$	input- Synchronous	Chip Enable: This active HIGH input is used to enable the device.
4F	86	$\overline{OE}$	Input	Output Enable: This active LOW asynchronous input enables the data output drivers.
4G	83	$\overline{ADV}$	Input- Synchronous	Address Advance: This active LOW input is used to control the internal burst counter. A HIGH on this pin generates wait cycle (no address advance).
4A	84	$\overline{ADSP}$	Input- Synchronous	Address Status Processor: This active LOW input, along with CE being LOW, causes a new external address to be registered and a READ cycle is initiated using the new address.
4B	85	$\overline{ADSC}$	Input- Synchronous	Address Status Controller: This active LOW input causes device to be deselected or selected along with new external address to be registered. A READ or WRITE cycle is initiated depending upon write control inputs.
3R	31	MODE	Input- Static	Mode: This input selects the burst sequence. A LOW on this pin selects Linear Burst. A NC or HIGH on this pin selects Interleaved Burst.
7T	64	ZZ	Input- Asynchronous	Snooze: This active HIGH input puts the device in low power consumption standby mode. For normal operation, this input has to be either LOW or NC (No Connect).
7N	52	$\overline{DEN}$	Input- Synchronous	Data Input Enable: This active LOW input is used to control the update of data input registers.
6M	53	MATCH	Output	Match Output: MATCH will be HIGH if data in the data input registers match the data stored in the memory array, assuming MOE being LOW. MATCH will be LOW if data do not match.

**Pin Descriptions** (continued)

BGA Pins	TQFP Pins	Name	Type	Description
6P	51	$\overline{\text{MOE}}$	Input	Match Output Enable: This active LOW asynchronous input enables the MATCH output drivers.
7P, 6N, 6L, 7K, 6H, 7G, 6F, 7E, 6D, 1D, 2E, 2G, 1H, 2K, 1L, 2M, 1N, 2P	58, 59, 62, 63, 68, 69, 72, 73, 74, 8, 9, 12, 13, 18, 19, 22, 23, 24	DQ1–DQ18	Input/Output	Data Inputs/Outputs: Input data must meet setup and hold times around the rising edge of CLK.
5U	42	TDO	Output	IEEE 1149.1 test output. LVTTTL-level output.
2U 3U 4U	38 39 43	TMS TDI TCK	Input	IEEE 1149.1 test inputs. LVTTTL-level inputs.
4C, 2J, 4J, 6J, 4R	15, 41, 65, 91	$V_{CC}$	Supply	Power Supply: +3.3V –5% and +10%
3D, 5D, 3E, 5E, 3F, 5F, 5G, 3H, 5H, 3K, 5K, 3L, 3M, 5M, 3N, 5N, 3P, 5P	5, 10, 17, 21, 26, 40, 55, 60, 67, 71, 76, 90	$V_{SS}$	Ground	Ground: GND
1A, 7A, 1F, 7F, 1J, 7J, 1M, 7M, 1U, 7U	4, 11, 20, 27, 54, 61, 70, 77	$V_{CCQ}$	I/O Supply	Output Buffer Supply: +2.5V (from 2.375V to $V_{CC}$ )
1B, 7B, 1C, 7C, 2D, 4D, 7D, 1E, 6E, 2F, 1G, 6G, 2H, 7H, 3J, 5J, 1K, 6K, 2L, 4L, 7L, 2N, 1P, 1R, 5R, 7R, 1T, 4T, 6U	1-3, 6, 7, 14, 16, 25, 28-30, 56, 57, 66, 75, 78, 79, 95, 96	NC	-	No Connect: These signals are not internally connected.

**Burst Address Table (MODE = NC/ $V_{CC}$ )**

First Address (external)	Second Address (internal)	Third Address (internal)	Fourth Address (internal)
A...A00	A...A01	A...A10	A...A11
A...A01	A...A00	A...A11	A...A10
A...A10	A...A11	A...A00	A...A01
A...A11	A...A10	A...A01	A...A00

**Burst Address Table (MODE = GND)**

First Address (external)	Second Address (internal)	Third Address (internal)	Fourth Address (internal)
A...A00	A...A01	A...A10	A...A11
A...A01	A...A10	A...A11	A...A00
A...A10	A...A11	A...A00	A...A01
A...A11	A...A00	A...A01	A...A10

**Partial Truth Table for MATCH<sup>[2, 3, 4, 5, 6]</sup>**

Operation	$\overline{\text{E}}$	$\overline{\text{WE}}$	$\overline{\text{DEN}}$	$\overline{\text{MOE}}$	$\overline{\text{OE}}$	MATCH	DQ
READ Cycle	L	H	X	X	L	-	Q
WRITE Cycle	L	L	L	X	H	-	D
Fill WRITE Cycle	L	L	H	X	H	-	High-Z
COMPARE Cycle	L	H	L	L	H	Output	D
Deselected Cycle (MATCH Out)	H	X	X	L	X	H	High-Z
Deselected Cycle	H	X	X	H	X	High-Z	High-Z

**Notes:**

- X means "don't care." H means logic HIGH. L means logic LOW. It is assumed in this table that  $\overline{\text{ADSP}}$  is HIGH and  $\overline{\text{ADSC}}$  is LOW.
- $\overline{\text{E}}=L$  is defined as  $\text{CE}_1=\text{LOW}$  and  $\text{CE}_2=\text{LOW}$  and  $\text{CE}_2=\text{HIGH}$ .  $\overline{\text{E}}=H$  is defined as  $\text{CE}_1=\text{HIGH}$  or  $\text{CE}_2=\text{HIGH}$  or  $\text{CE}_2=\text{LOW}$ .  $\overline{\text{WE}}$  is defined as  $[\overline{\text{BWE}} + \overline{\text{WEL}} * \overline{\text{WEH}}] * \overline{\text{GW}}$ .
- All inputs except OE and MOE must meet setup and hold times around the rising edge (LOW to HIGH) of CLK.
- For a write operation following a read operation, OE must be HIGH before the input data required setup time plus High-Z time for OE and staying HIGH throughout the input data hold time.
- This device contains circuitry that will ensure the outputs will be in High-Z during power-up.

**Truth Table**<sup>[5, 6, 7, 8, 9, 10, 11]</sup>

Operation	Address Used	$\overline{CE}$	$\overline{CE2}$	CE2	$\overline{ADSP}$	$\overline{ADSC}$	$\overline{ADV}$	$\overline{WRITE}$	$\overline{OE}$	CLK	DQ
Deselected Cycle, Power Down	None	H	X	X	X	L	X	X	X	L-H	High-Z
Deselected Cycle, Power Down	None	L	X	L	L	X	X	X	X	L-H	High-Z
Deselected Cycle, Power Down	None	L	H	X	L	X	X	X	X	L-H	High-Z
Deselected Cycle, Power Down	None	L	X	L	H	L	X	X	X	L-H	High-Z
Deselected Cycle, Power Down	None	L	H	X	H	L	X	X	X	L-H	High-Z
READ Cycle, Begin Burst	External	L	L	H	L	X	X	X	L	L-H	Q
READ Cycle, Begin Burst	External	L	L	H	L	X	X	X	H	L-H	High-Z
WRITE Cycle, Begin Burst	External	L	L	H	H	L	X	L	X	L-H	D
READ Cycle, Begin Burst	External	L	L	H	H	L	X	H	L	L-H	Q
READ Cycle, Begin Burst	External	L	L	H	H	L	X	H	H	L-H	High-Z
READ Cycle, Continue Burst	Next	X	X	X	H	H	L	H	L	L-H	Q
READ Cycle, Continue Burst	Next	X	X	X	H	H	L	H	H	L-H	High-Z
READ Cycle, Continue Burst	Next	H	X	X	X	H	L	H	L	L-H	Q
READ Cycle, Continue Burst	Next	H	X	X	X	H	L	H	H	L-H	High-Z
WRITE Cycle, Continue Burst	Next	X	X	X	H	H	L	L	X	L-H	D
WRITE Cycle, Continue Burst	Next	H	X	X	X	H	L	L	X	L-H	D
READ Cycle, Suspend Burst	Current	X	X	X	H	H	H	H	L	L-H	Q
READ Cycle, Suspend Burst	Current	X	X	X	H	H	H	H	H	L-H	High-Z
READ Cycle, Suspend Burst	Current	H	X	X	X	H	H	H	L	L-H	Q
READ Cycle, Suspend Burst	Current	H	X	X	X	H	H	H	H	L-H	High-Z
WRITE Cycle, Suspend Burst	Current	X	X	X	H	H	H	L	X	L-H	D
WRITE Cycle, Suspend Burst	Current	H	X	X	X	H	H	L	X	L-H	D

**Partial Truth Table for READ/WRITE**<sup>[12]</sup>

Function	$\overline{GW}$	$\overline{BWE}$	$\overline{WEH}$	$\overline{WEL}$
READ	H	H	X	X
READ	H	L	H	H
WRITE one byte	H	L	L	H
WRITE all bytes	H	L	L	L
WRITE all bytes	L	X	X	X

**Notes:**

- X means "Don't Care." H means logic HIGH. L means logic LOW.  $\overline{WRITE} = L$  means  $[\overline{BWE} + \overline{WEL} * \overline{WEH}] * \overline{GW}$  equals LOW.  $\overline{WRITE} = H$  means  $[\overline{BWE} + \overline{WEL} * \overline{WEH}] * \overline{GW}$  equals HIGH. It is assumed in this truth table that  $\overline{DEN}$  is LOW.
- $\overline{WEL}$  enables write to DQ1–DQ9.  $\overline{WEH}$  enables write to DQ10–DQ18.
- All inputs except  $\overline{OE}$  must meet set-up and hold times around the rising edge (LOW to HIGH) of CLK.
- Suspending burst generates wait cycle.
- $\overline{ADSP}$  LOW along with chip being selected always initiates a READ cycle at the L-H edge of CLK. A WRITE cycle can be performed by setting  $\overline{WRITE}$  LOW for the CLK L-H edge of the subsequent wait cycle. Refer to WRITE timing diagram for clarification.
- X means "don't care." H means logic HIGH. L means logic LOW. It is assumed in this truth table that chip is selected and  $\overline{ADSP}$  is HIGH along with  $\overline{DEN}$  being LOW.

## IEEE 1149.1 Serial Boundary Scan (JTAG)

### Overview

This device incorporates a serial boundary scan access port (TAP). This port is designed to operate in a manner consistent with IEEE Standard 1149.1-1990 (commonly referred to as JTAG), but does not implement all of the functions required for IEEE 1149.1 compliance. Certain functions have been modified or eliminated because their implementation places extra delays in the critical speed path of the device. Nevertheless, the device supports the standard TAP controller architecture (the TAP controller is the state machine that controls the TAP's operation) and can be expected to function in a manner that does not conflict with the operation of devices with IEEE Standard 1149.1 compliant TAPs. The TAP operates using LVTTTL/LVCMOS logic level signaling.

### Disabling the JTAG Feature

It is possible to use this device without using the JTAG feature. To disable the TAP controller without interfering with normal operation of the device, TCK should be tied LOW ( $V_{SS}$ ) to prevent clocking the device. TDI and TMS are internally pulled up and may be unconnected. They may alternately be pulled up to  $V_{CC}$  through a resistor. TDO should be left unconnected. Upon power-up the device will come up in a reset state which will not interfere with the operation of the device.

## Test Access Port (TAP)

### TCK - Test Clock (INPUT)

Clocks all TAP events. All inputs are captured on the rising edge of TCK and all outputs propagate from the falling edge of TCK.

### TMS - Test Mode Select (INPUT)

The TMS input is sampled on the rising edge of TCK. This is the command input for the TAP controller state machine. It is allowable to leave this pin unconnected if the TAP is not used. The pin is pulled up internally, resulting in a logic HIGH level.

### TDI - Test Data In (INPUT)

The TDI input is sampled on the rising edge of TCK. This is the input side of the serial registers placed between TDI and TDO. The register placed between TDI and TDO is determined by the state of the TAP controller state machine and the instruction that is currently loaded in the TAP instruction register (refer to *Figure 1*, TAP Controller State Diagram). It is allowable to leave this pin unconnected if it is not used in an application. The pin is pulled up internally, resulting in a logic HIGH level. TDI is connected to the most significant bit (MSB) of any register. (See *Figure 2*.)

### TDO - Test Data Out (OUTPUT)

The TDO output pin is used to serially clock data-out from the registers. The output that is active depending on the state of the TAP state machine (refer to *Figure 1*, TAP Controller State Diagram). Output changes in response to the falling edge of TCK. This is the output side of the serial registers placed between TDI and TDO. TDO is connected to the least significant bit (LSB) of any register. (See *Figure 2*.)

## Performing a TAP Reset

The TAP circuitry does not have a Reset pin ( $\overline{TRST}$ , which is optional in the IEEE 1149.1 specification). A RESET can be performed for the TAP controller by forcing TMS HIGH ( $V_{CC}$ ) for five rising edges of TCK and pre-loads the instruction register with the IDCODE command. This type of reset does not affect the operation of the system logic. The reset affects test logic only.

At power-up, the TAP is reset internally to ensure that TDO is in a High-Z state.

## Test Access Port (TAP) Registers

### Overview

The various TAP registers are selected (one at a time) via the sequences of ones and zeros input to the TMS pin as the TCK is strobed. Each of the TAP's registers are serial shift registers that capture serial input data on the rising edge of TCK and push serial data out on subsequent falling edge of TCK. When a register is selected, it is connected between the TDI and TDO pins.

### Instruction Register

The instruction register holds the instructions that are executed by the TAP controller when it is moved into the run test/idle or the various data register states. The instructions are three bits long. The register can be loaded when it is placed between the TDI and TDO pins. The parallel outputs of the instruction register are automatically preloaded with the IDCODE instruction upon power-up or whenever the controller is placed in the test-logic reset state. When the TAP controller is in the Capture-IR state, the two least significant bits of the serial instruction register are loaded with a binary "01" pattern to allow for fault isolation of the board-level serial test data path.

### Bypass Register

The bypass register is a single-bit register that can be placed between TDI and TDO. It allows serial test data to be passed through the device TAP to another device in the scan chain with minimum delay. The bypass register is set LOW ( $V_{SS}$ ) when the BYPASS instruction is executed.

### Boundary Scan Register

The Boundary scan register is connected to all the input and bidirectional I/O pins (not counting the TAP pins) on the device. This also includes a number of NC pins that are reserved for future needs. There are a total of 70 bits for a x36 device and 51 bits for a x18 device. The boundary scan register, under the control of the TAP controller, is loaded with the contents of the device I/O ring when the controller is in Capture-DR state and then is placed between the TDI and TDO pins when the controller is moved to Shift-DR state. The EXTTEST, SAMPLE/PRELOAD and SAMPLE-Z instructions can be used to capture the contents of the I/O ring.

The Boundary Scan Order table describes the order in which the bits are connected. The first column defines the bit's position in the boundary scan register. The MSB of the register is connected to TDI, and LSB is connected to TDO. The second column is the signal name and the third column is the bump number. The third column is the TQFP pin number and the fourth column is the BGA bump number.

## Identification (ID) Register

The ID Register is a 32-bit register that is loaded with a device and vendor specific 32-bit code when the controller is put in Capture-DR state with the IDCODE command loaded in the instruction register. The register is then placed between the TDI and TDO pins when the controller is moved into Shift-DR state. Bit 0 in the register is the LSB and the first to reach TDO when shifting begins. The code is loaded from a 32-bit on-chip ROM. It describes various attributes of the device as described in the Identification Register Definitions table.

## TAP Controller Instruction Set

### Overview

There are two classes of instructions defined in the IEEE Standard 1149.1-1990; the standard (public) instructions and device specific (private) instructions. Some public instructions are mandatory for IEEE 1149.1 compliance. Optional public instructions must be implemented in prescribed ways.

Although the TAP controller in this device follows the IEEE 1149.1 conventions, it is not IEEE 1149.1 compliant because some of the mandatory instructions are not fully implemented. The TAP on this device may be used to monitor all input and I/O pads, but can not be used to load address, data, or control signals into the device or to preload the I/O buffers. In other words, the device will not perform IEEE 1149.1 EXTEST, INTEST, or the preload portion of the SAMPLE/PRELOAD command.

When the TAP controller is placed in Capture-IR state, the two least significant bits of the instruction register are loaded with 01. When the controller is moved to the Shift-IR state the instruction is serially loaded through the TDI input (while the previous contents are shifted out at TDO). For all instructions, the TAP executes newly loaded instructions only when the controller is moved to Update-IR state. The TAP instruction sets for this device are listed in the following tables.

### EXTEST

EXTEST is an IEEE 1149.1 mandatory public instruction. It is to be executed whenever the instruction register is loaded with all 0s. EXTEST is not implemented in this device.

The TAP controller does not recognize an all-0 instruction. When an EXTEST instruction is loaded into the instruction register, the device responds as if a SAMPLE/PRELOAD instruction has been loaded. There is one difference between two instructions. Unlike SAMPLE/PRELOAD instruction, EXTEST places the device outputs in a High-Z state.

### IDCODE

The IDCODE instruction causes a vendor-specific, 32-bit code to be loaded into the ID register when the controller is in

Capture-DR mode and places the ID register between the TDI and TDO pins in Shift-DR mode. The IDCODE instruction is the default instruction loaded in the instruction register upon power-up and at any time the TAP controller is placed in the test-logic reset state.

### SAMPLE-Z

If the High-Z instruction is loaded in the instruction register, all output pins are forced to a High-Z state and the boundary scan register is connected between TDI and TDO pins when the TAP controller is in a Shift-DR state.

### SAMPLE/PRELOAD

SAMPLE/PRELOAD is an IEEE 1149.1 mandatory instruction. The PRELOAD portion of the command is not implemented in this device, so the device TAP controller is not fully IEEE 1149.1-compliant.

When the SAMPLE/PRELOAD instruction is loaded in the instruction register and the TAP controller is in the Capture-DR state, a snap shot of the data in the device's input and I/O buffers is loaded into the boundary scan register. Because the device system clock(s) are independent from the TAP clock (TCK), it is possible for the TAP to attempt to capture the input and I/O ring contents while the buffers are in transition (i.e., in a metastable state). Although allowing the TAP to sample metastable inputs will not harm the device, repeatable results can not be expected. To guarantee that the boundary scan register will capture the correct value of a signal, the device input signals must be stabilized long enough to meet the TAP controller's capture setup plus hold time ( $t_{CS}$  plus  $t_{CH}$ ). The device clock input(s) need not be paused for any other TAP operation except capturing the input and I/O ring contents into the boundary scan register.

Moving the controller to Shift-DR state then places the boundary scan register between the TDI and TDO pins. Because the PRELOAD portion of the command is not implemented in this device, moving the controller to the Update-DR state with the SAMPLE/PRELOAD instruction loaded in the instruction register has the same effect as the Pause-DR command.

### BYPASS

When the BYPASS instruction is loaded in the instruction register and the TAP controller is in the Shift-DR state, the bypass register is placed between TDI and TDO. This allows the board level scan path to be shortened to facilitate testing of other devices in the scan path.

### Reserved

Do not use these instructions. They are reserved for future use.



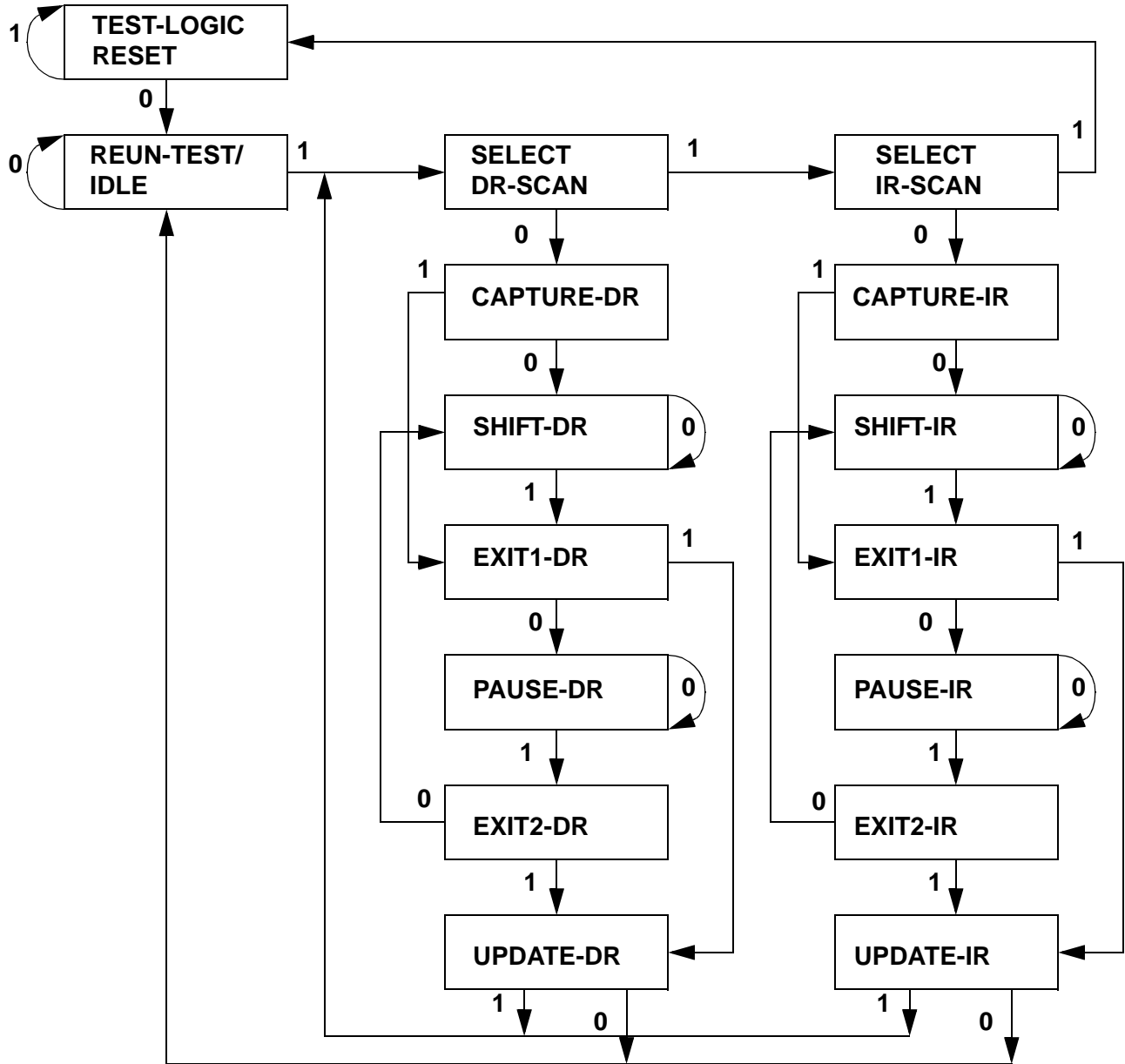
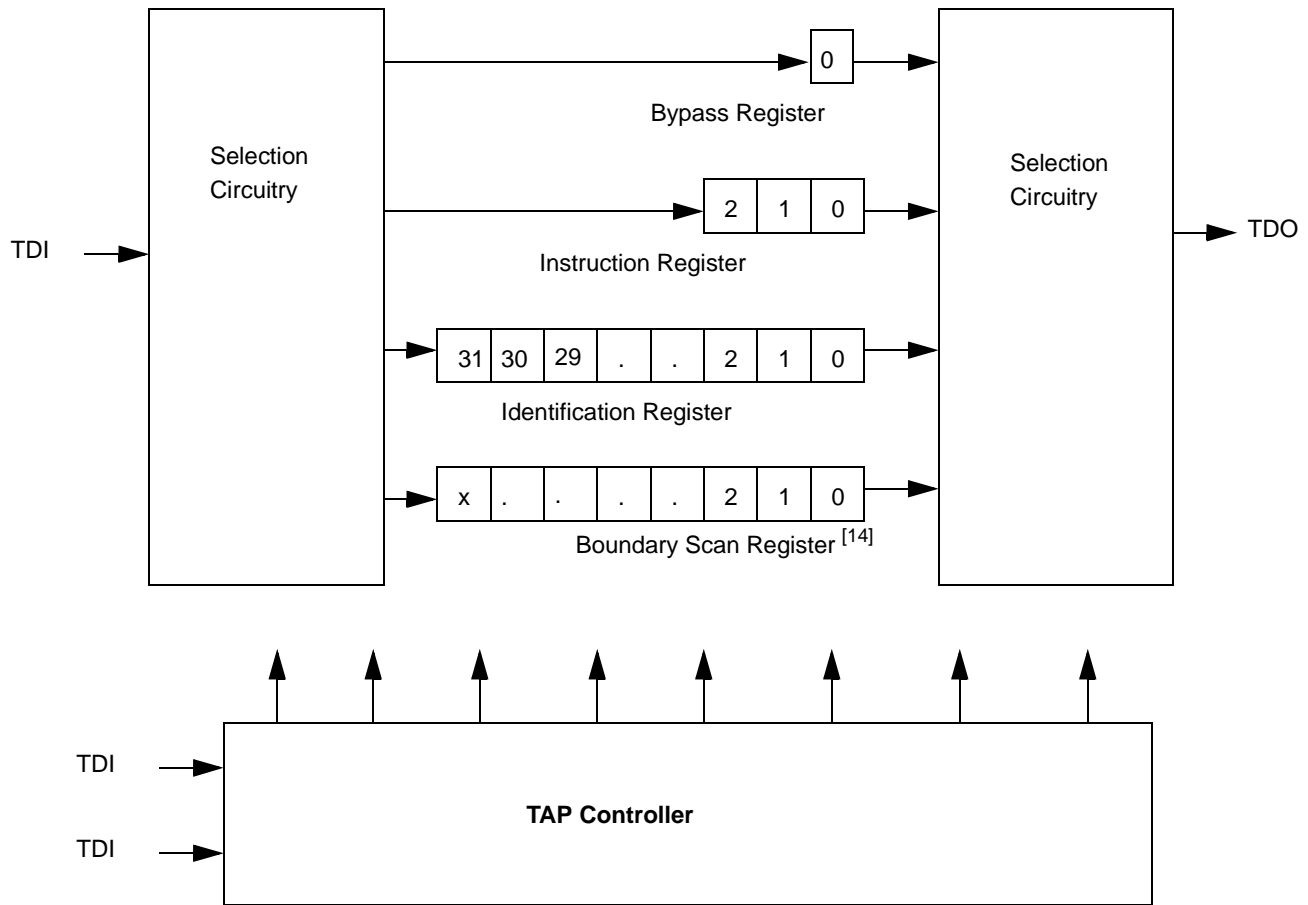


Figure 1. TAP Controller State Diagram<sup>[13]</sup>

**Note:**

13. The 0/1 next to each state represents the value at TMS at the rising edge of TCK.


**Figure 2. TAP Controller Block Diagram**
**TAP DC Electrical Characteristics** ( $20^{\circ}\text{C} \leq T_j \leq 110^{\circ}\text{C}$ ;  $V_{CC} = 3.3\text{V} - 0.2\text{V}$  and  $+0.3\text{V}$  unless otherwise noted)

Parameter	Description	Test Conditions	Min.	Max.	Unit
$V_{IH}$	Input High (Logic 1) Voltage <sup>[15, 16]</sup>		2.0	$V_{CC} + 0.3$	V
$V_{IL}$	Input Low (Logic 0) Voltage <sup>[15, 16]</sup>		-0.3	0.8	V
$I_{LI}$	Input Leakage Current	$0\text{V} \leq V_{IN} \leq V_{CC}$	-5.0	5.0	$\mu\text{A}$
$I_{LO}$	Output Leakage Current	Output disabled, $0\text{V} \leq V_{IN} \leq V_{CCQ}$	-5.0	5.0	$\mu\text{A}$
$V_{OLC}$	LVC MOS Output Low Voltage <sup>[15, 17]</sup>	$I_{OLC} = 100 \mu\text{A}$		0.2	V
$V_{OHC}$	LVC MOS Output High Voltage <sup>[15, 17]</sup>	$I_{OHC} = 100 \mu\text{A}$	$V_{CC} - 0.2$		V
$V_{OLT}$	LVTTL Output Low Voltage <sup>[15]</sup>	$I_{OLT} = 8.0 \text{ mA}$		0.4	V
$V_{OHT}$	LVTTL Output High Voltage <sup>[15]</sup>	$I_{OHT} = 8.0 \text{ mA}$	2.4		V

**Notes:**

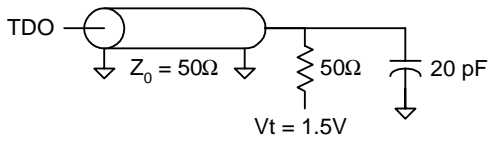
14. X = 53 for this device.
15. All Voltage referenced to  $V_{SS}$  (GND).
16. Overshoot:  $V_{IH}(AC) \leq V_{CC} + 1.5\text{V}$  for  $t \leq t_{KHKH}/2$ , Undershoot:  $V_{IL}(AC) \leq -0.5\text{V}$  for  $t \leq t_{KHKL}/2$ . Power-up:  $V_{IH} \leq 3.6\text{V}$  and  $V_{CC} \leq 3.135\text{V}$  and  $V_{CCQ} \leq 1.4\text{V}$  for  $t \leq 200 \text{ ms}$ . During normal operation,  $V_{CCQ}$  must not exceed  $V_{CC}$ . Control input signals (such as GW, ADSC, etc.) may not have pulse widths less than  $t_{KHKL}$  (min.).
17. This parameter is sampled.

**TAP AC Switching Characteristics** Over the Operating Range<sup>[18, 19]</sup>

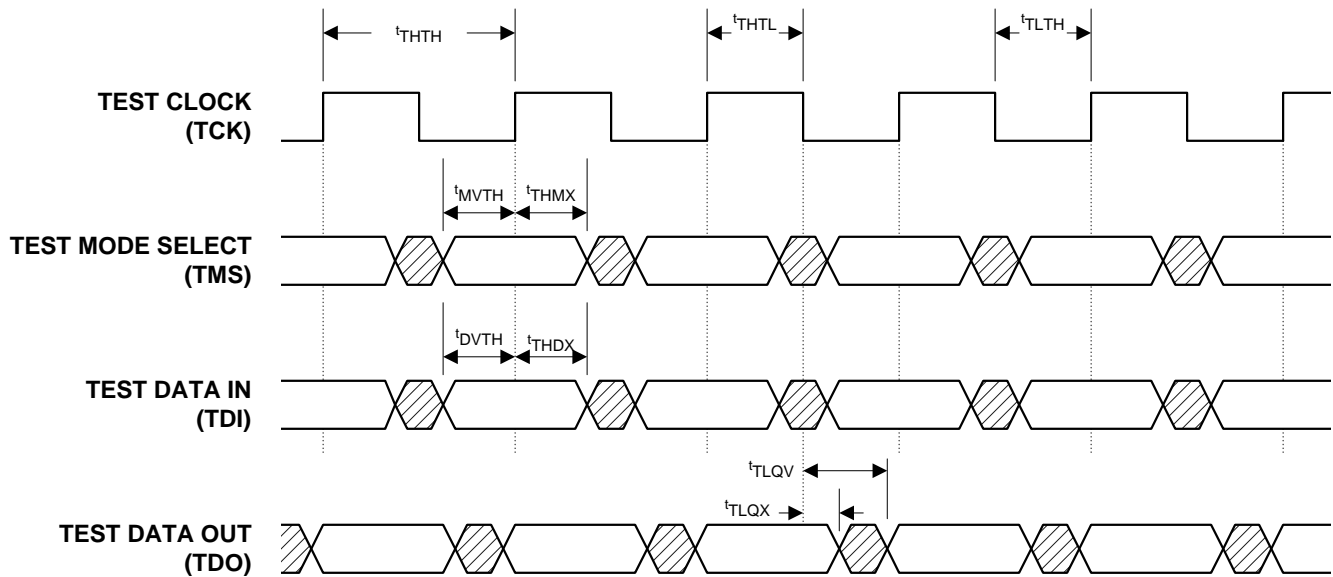
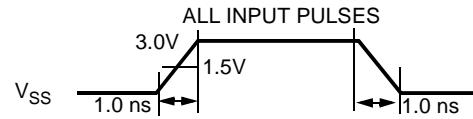
Parameter	Description	Min.	Max	Unit
<b>Clock</b>				
$t_{THTH}$	Clock Cycle Time	20		ns
$f_{TF}$	Clock Frequency		50	MHz
$t_{HTL}$	Clock HIGH Time	8		ns
$t_{LTH}$	Clock LOW Time	8		ns
<b>Output Times</b>				
$t_{TLQX}$	TCK LOW to TDO Unknown	0		ns
$t_{TLQV}$	TCK LOW to TDO Valid		10	ns
$t_{DVTH}$	TDI Valid to TCK HIGH	5		ns
$t_{THDX}$	TCK HIGH to TDI Invalid	5		ns
<b>Set-up Times</b>				
$t_{MVTH}$	TMS Set-up	5		ns
$t_{CS}$	Capture Set-up	5		ns
<b>Hold Times</b>				
$t_{THMX}$	TMS Hold	5		ns
$t_{CH}$	Capture Hold	5		ns

**Notes:**

18.  $t_{CS}$  and  $t_{CH}$  refer to the set-up and hold time requirements of latching data from the boundary scan register.  
 19. Test conditions are specified using the load in TAP AC Test Conditions.

**TAP Timing and Test Conditions**


(a)



**Identification Register Definitions**

Instruction Field	512K x 18	Description
REVISION NUMBER (31:28)	XXXX	Reserved for revision number.
DEVICE DEPTH (27:23)	00111	Defines depth of 256K words.
DEVICE WIDTH (22:18)	00011	Defines width of x18 bits.
RESERVED (17:12)	XXXXXX	Reserved for future use.
CYPRESS JEDEC ID CODE (11:1)	00011100100	Allows unique identification of DEVICE vendor.
ID Register Presence Indicator (0)	1	Indicates the presence of an ID register.

**Scan Register Sizes**

Register Name	Bit Size
Instruction	3
Bypass	1
ID	32
Boundary Scan	54

**Instruction Codes**

Instruction	Code	Description
EXTEST	000	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. Forces all device outputs to High-Z state. This instruction is not IEEE 1149.1-compliant.
IDCODE	001	Preloads ID register with vendor ID code and places it between TDI and TDO. This instruction does not affect device operations.
SAMPLE-Z	010	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. Forces all device outputs to High-Z state.
RESERVED	011	Do not use these instructions; they are reserved for future use.
SAMPLE/PRELOAD	100	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. This instruction does not affect device operations. This instruction does not implement IEEE 1149.1 PRELOAD function and is therefore not 1149.1-compliant.
RESERVED	101	Do not use these instructions; they are reserved for future use.
RESERVED	110	Do not use these instructions; they are reserved for future use.
BYPASS	111	Places the bypass register between TDI and TDO. This instruction does not affect device operations.

**Boundary Scan Order**

Bit#	Signal Name	TQFP	Bump ID
1	A	44	2R
2	A	45	2T
3	A	46	3T
4	A	47	5T
5	A	48	6R
6	A	49	3B
7	A	50	5B
8	$\overline{\text{MOE}}$	51	6P
9	$\overline{\text{DEN}}$	52	7N
10	MATCH	53	6M
11	DQ1	58	7P
12	DQ2	59	6N
13	DQ3	62	6L
14	DQ4	63	7K
15	ZZ	64	7T
16	DQ5	68	6H
17	DQ6	69	7G
18	DQ7	72	6F
19	DQ8	73	7E
20	DQ9	74	6D
21	A	80	6T
22	A	81	6A
23	A	82	5A
24	$\overline{\text{ADV}}$	83	4G
25	$\overline{\text{ADSP}}$	84	4A
26	$\overline{\text{ADSC}}$	85	4B
27	$\overline{\text{OE}}$	86	4F
28	$\overline{\text{BWE}}$	87	4M
29	$\overline{\text{GW}}$	88	4H
30	CLK	89	4K
31	$\overline{\text{CE}}_2$	92	6B
32	$\overline{\text{WEL}}$	93	5L
33	$\overline{\text{WEH}}$	94	3G
34	$\text{CE}_2$	97	2B

**Note:**

20.  $T_A$  is the case temperature.

**Boundary Scan Order (continued)**

Bit#	Signal Name	TQFP	Bump ID
35	$\overline{\text{CE}}$	98	4E
36	A	99	3A
37	A	100	2A
38	DQ10	8	ID
39	DQ11	9	2E
40	DQ12	12	2G
41	DQ13	13	1H
42	NC	14	5R
43	DQ14	18	2K
44	DQ15	19	1L
45	DQ16	22	2M
46	DQ17	23	1N
47	DQ18	24	2P
48	MODE	31	3R
49	A	32	2C
50	A	33	3C
51	A	34	5C
52	A	35	6C
53	A1	36	4N
54	A0	37	4P

**Maximum Ratings**

(Above which the useful life may be impaired. For user guidelines, not tested.)

Voltage on  $V_{CC}$  Supply Relative to  $V_{SS}$ ..... -0.5V to +4.6V

$V_{IN}$  ..... -0.5V to  $V_{CC}+0.5V$

Storage Temperature (plastic) ..... -55°C to +150°C

Junction Temperature ..... +150°C

Power Dissipation..... 1.0W

Short Circuit Output Current..... 50 mA

**Operating Range**

Range	Ambient Temperature <sup>[20]</sup>	$V_{CC}$
Com'l	0°C to +70°C	3.3V -5%/+10%

**Electrical Characteristics** Over the Operating Range

Parameter	Description	Test Conditions	Min.	Max.	Unit
V <sub>IHD</sub>	Input High (Logic 1) Voltage <sup>[15, 21]</sup>	Data Inputs (DQxx)	1.7	V <sub>CC</sub> +0.3	V
V <sub>IH</sub>		All Other Inputs	1.7	4.6	V
V <sub>IL</sub>	Input Low (Logic 0) Voltage <sup>[15, 21]</sup>		-0.3	0.8	V
I <sub>LI</sub>	Input Leakage Current <sup>[22]</sup>	0V ≤ V <sub>IN</sub> ≤ V <sub>CC</sub>	-2	2	μA
I <sub>LO</sub>	Output Leakage Current	Output(s) disabled, 0V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub>	-2	2	μA
V <sub>OH</sub>	Output High Voltage <sup>[15, 23]</sup>	I <sub>OH</sub> = -4.0 mA at V <sub>CCQ</sub> = 3.135V	2.4		V
V <sub>OH</sub>		I <sub>OH</sub> = -4.0 mA at V <sub>CCQ</sub> = 2.375V	1.7		
V <sub>OL</sub>	Output Low Voltage <sup>[15, 23]</sup>	I <sub>OL</sub> = 8.0 mA		0.4	V
V <sub>CC</sub>	Supply Voltage <sup>[15]</sup>		3.135	3.6	V
V <sub>CCQ</sub>	I/O Supply Voltage <sup>[15]</sup>		2.375	V <sub>CC</sub>	V

Parameter	Description	Conditions	Typ.	166 MHz/-6	150 MHz/-6.7	133 MHz/-7.5	100 MHz/-10	Unit
I <sub>CC</sub>	Power Supply Current: Operating <sup>[24, 25, 26]</sup>	Device selected; all inputs ≤ V <sub>IL</sub> or ≥ V <sub>IH</sub> ; cycle time ≥ t <sub>KC</sub> min.; V <sub>CC</sub> = Max.; outputs open	100	310	275	250	190	mA
I <sub>SB2</sub>	CMOS Standby <sup>[25, 26]</sup>	Device deselected; V <sub>CC</sub> = Max.; all inputs ≤ V <sub>SS</sub> + 0.2 or ≥ V <sub>CC</sub> - 0.2; all inputs static; CLK frequency = 0	5	10	10	10	10	mA
I <sub>SB3</sub>	TTL Standby <sup>[25, 26]</sup>	Device deselected; all inputs ≤ V <sub>IL</sub> or ≥ V <sub>IH</sub> ; all inputs static; V <sub>CC</sub> = Max.; CLK frequency = 0	10	20	20	20	20	mA
I <sub>SB4</sub>	Clock Running <sup>[25, 26]</sup>	Device deselected; all inputs ≤ V <sub>IL</sub> or ≥ V <sub>IH</sub> ; V <sub>CC</sub> = Max.; CLK cycle time ≥ t <sub>KC</sub> min.	40	80	70	60	50	mA

**Capacitance<sup>[17]</sup>**

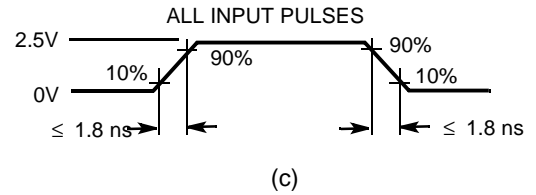
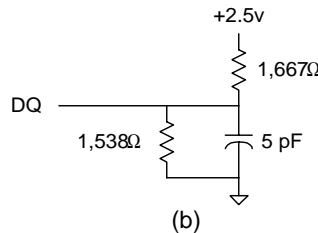
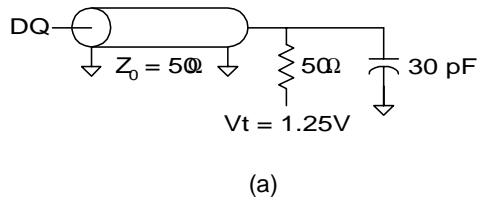
Parameter	Description	Test Conditions	Typ.	Max.	Unit
C <sub>I</sub>	Input Capacitance	T <sub>A</sub> = 25°C, f = 1 MHz, V <sub>CC</sub> = 3.3V	4	5	pF
C <sub>O</sub>	Input/Output Capacitance (DQ)		7	8	pF

**Thermal Resistance**

Description	Test Conditions	Symbol	BGA Typ.	TQFP Typ.	Unit
Thermal Resistance (Junction to Ambient)	Still Air, soldered on a 4.25 x 1.125 inch, 4-layer PCB	Θ <sub>JA</sub>	19	25	°C/W
Thermal Resistance (Junction to Case)		Θ <sub>JC</sub>	9	9	°C/W

**Note:**

21. Overshoot: V<sub>IH</sub> ≤ +6.0V for t ≤ t<sub>KC</sub> /2.  
Undershoot: V<sub>IL</sub> ≤ -2.0V for t ≤ t<sub>KC</sub> /2.
22. MODE pin has an internal pull-up and ZZ pin has an internal pull-down. These two pins exhibit an input leakage current of ±30 μA.
23. AC I/O curves are available upon request.
24. I<sub>CC</sub> is given with no output current. I<sub>CC</sub> increases with greater output loading and faster cycle times.
25. "Device Deselected" means the device is in Power-Down mode as defined in the truth table. "Device Selected" means the device is active.
26. Typical values are measured at 3.3V, 25°C, and 8.5-ns cycle time.

**AC Test Loads and Waveforms**

**Switching Characteristics Over the Operating Range<sup>[27]</sup>**

Parameter	Description	-6 166 MHz		-6.7 150 MHz		-7.5 133 MHz		-10 100 MHz		Unit
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
<b>Clock</b>										
t <sub>KC</sub>	Clock Cycle Time	6.0		6.7		7.5		8.5		ns
t <sub>KF</sub>	Clock Frequency									
t <sub>KH</sub>	Clock HIGH Time	2.4		2.6		2.8		3.4		ns
t <sub>KL</sub>	Clock LOW Time	2.4		2.6		2.8		3.4		ns
<b>Output Times</b>										
t <sub>KQ</sub>	Clock to Output Valid		3.5		3.8		4.0		4.0	ns
t <sub>KM</sub>	Clock to MATCH Valid									
t <sub>KQX</sub>	Clock to Output Invalid	1.5		1.5		1.5		1.5		ns
t <sub>KMX</sub>	Clock to MATCH Invalid									
t <sub>KQLZ</sub>	Clock to Output in Low-Z <sup>[17, 28, 29]</sup>	0		0		0		0		ns
t <sub>KQHZ</sub>	Clock to Output in High-Z <sup>[17, 28, 29]</sup>	1.5	6.0	1.5	6.7	1.5	7.5	1.5	8.5	ns
t <sub>OEQ</sub>	OE to Output Valid <sup>[30]</sup>		3.5		3.5		3.8		3.8	ns
t <sub>MOEM</sub>	MOE to MATCH Valid <sup>[30]</sup>									
t <sub>OELZ</sub>	OE to Output in Low-Z <sup>[17, 28, 29]</sup>	0		0		0		0		ns
t <sub>MOELZ</sub>	MOE to MATCH in Low-Z <sup>[17, 28, 29]</sup>									
t <sub>OEHZ</sub>	OE to Output in High-Z <sup>[17, 28, 29]</sup>		3.5		3.5		3.8		3.8	ns
t <sub>MOEHZ</sub>	MOE to MATCH in High-Z <sup>[17, 28, 29]</sup>									
<b>Set-up Times</b>										
t <sub>S</sub>	Address, Controls, and Data In <sup>[31]</sup>	1.5		1.5		1.5		2.0		ns
<b>Hold Times</b>										
t <sub>H</sub>	Address, Controls, and Data In <sup>[31]</sup>	0.5		0.5		0.5		0.5		ns

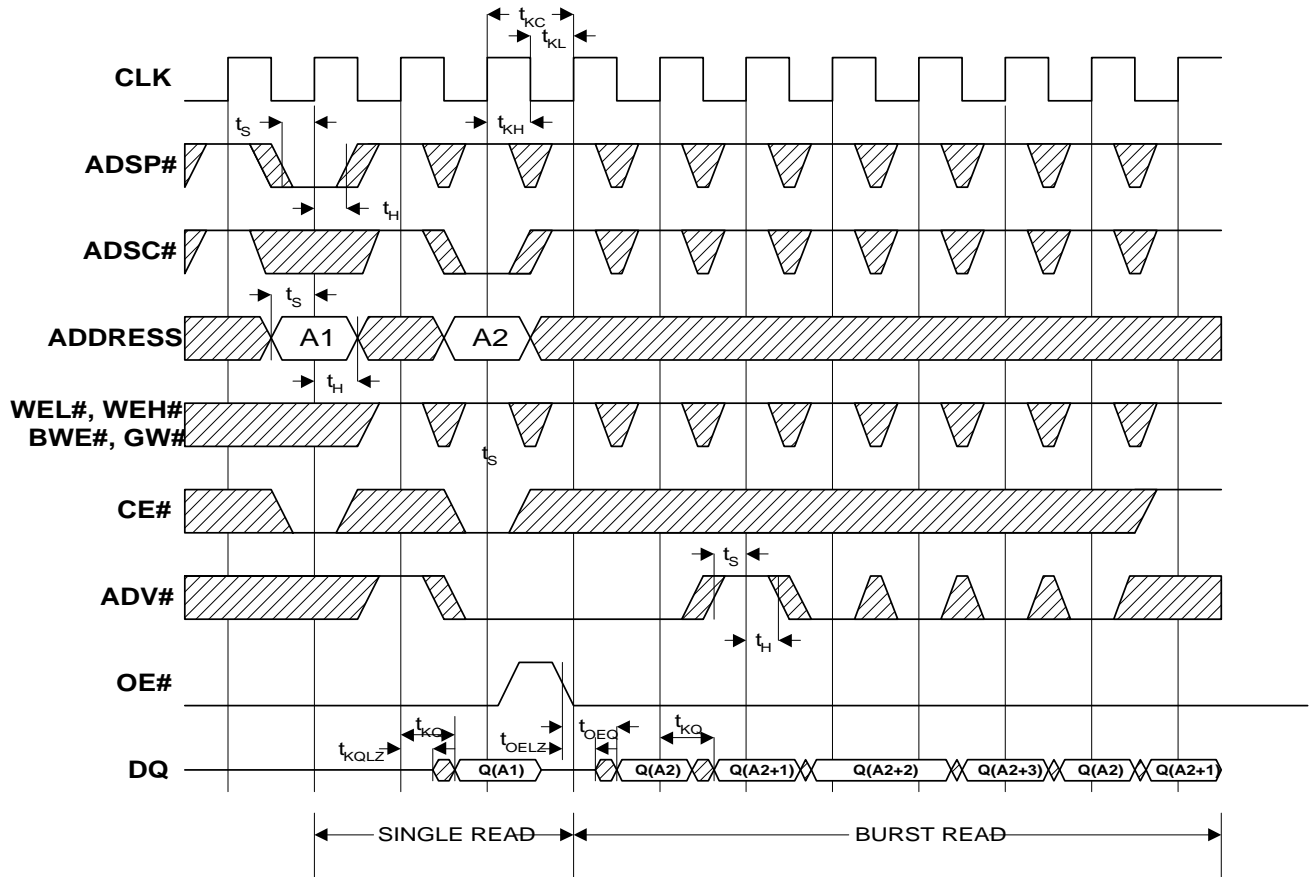
**Notes:**

27. Test conditions as specified with the output loading as shown in part (a) of AC Test Loads unless otherwise noted.
28. Output loading is specified with C<sub>L</sub> = 5 pF as in AC Test Loads.
29. At any given temperature and voltage condition, t<sub>KQHZ</sub> is less than t<sub>KQLZ</sub>, t<sub>OEHZ</sub> is less than t<sub>OELZ</sub> and t<sub>MOEHZ</sub> is less than t<sub>MOELZ</sub>.
30.  $\overline{OE}$  is a "Don't Care" after a write cycle begins. To prevent bus contention,  $\overline{OE}$  should be negated prior before the start of write cycle.
31. This is a synchronous device. All synchronous inputs must meet specified set-up and hold time, except for "don't care" as defined in the truth table.

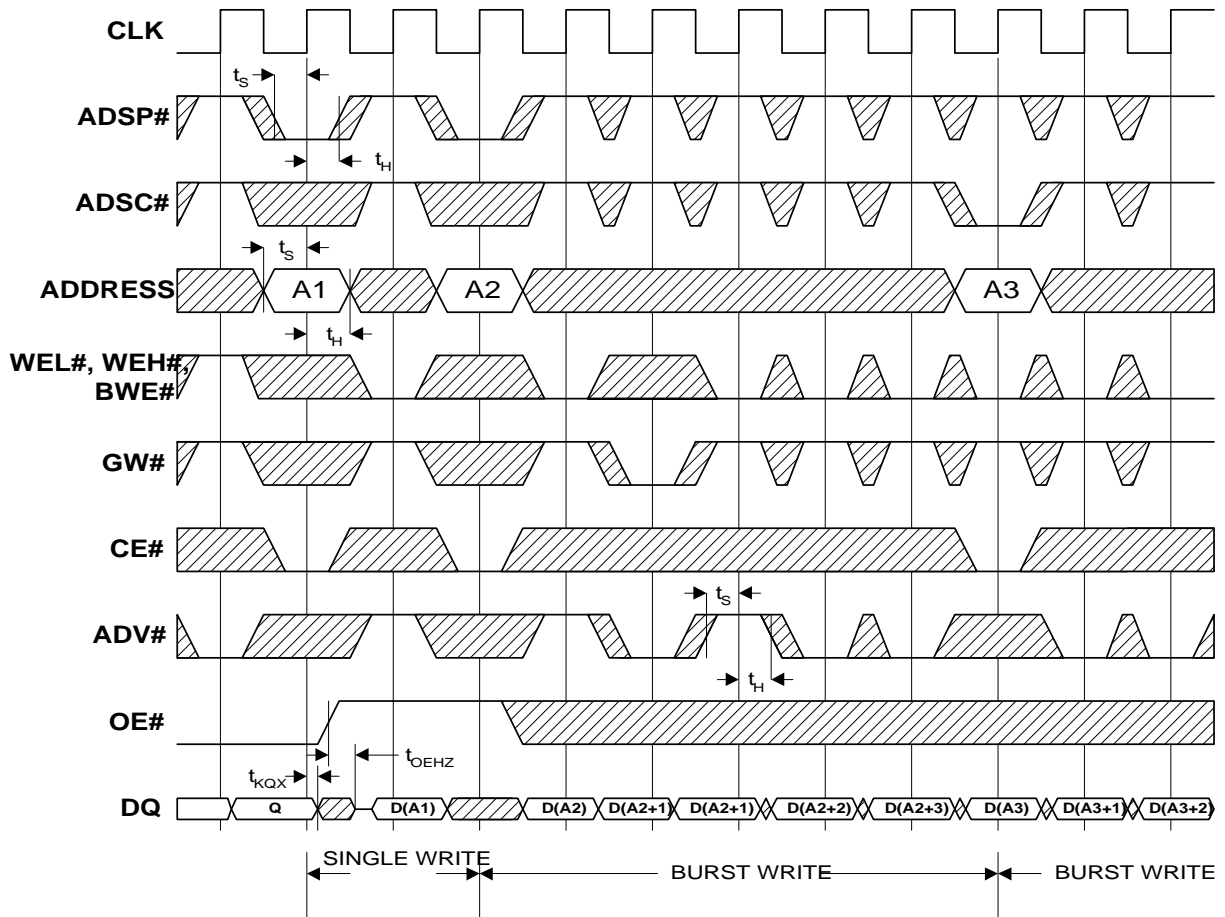


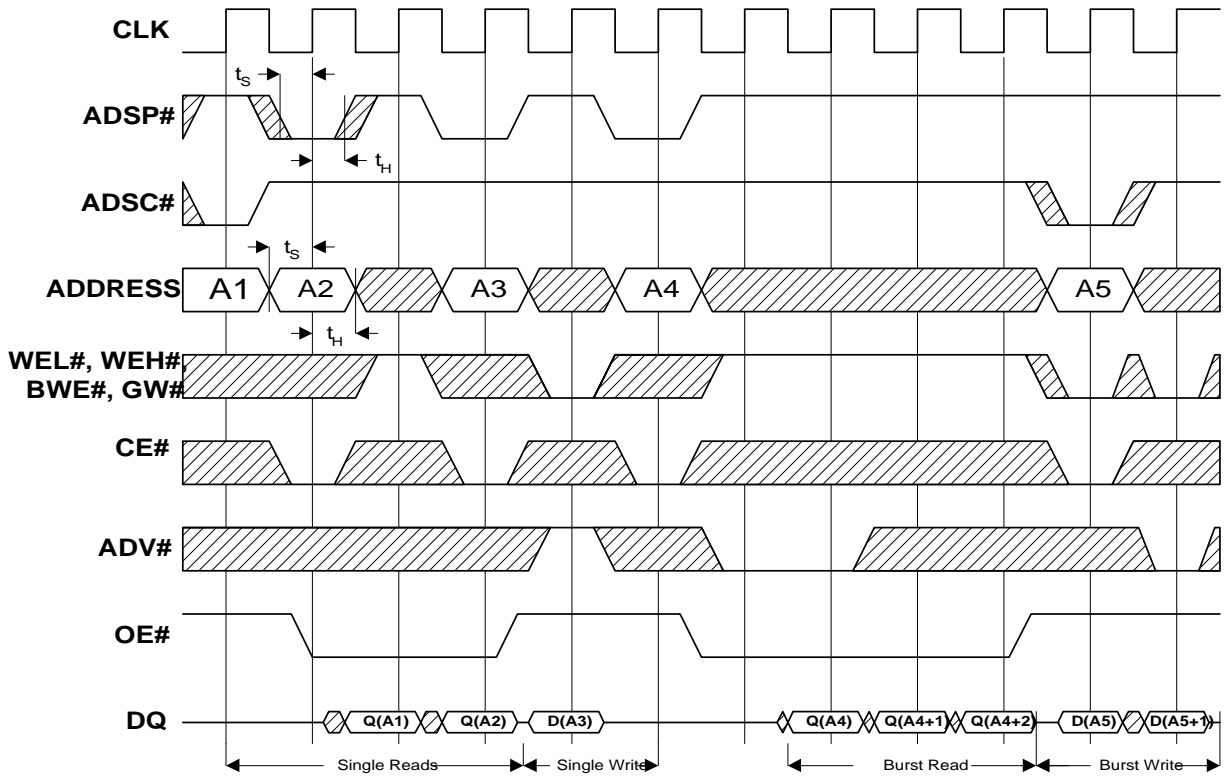
**Typical Output Buffer Characteristics**

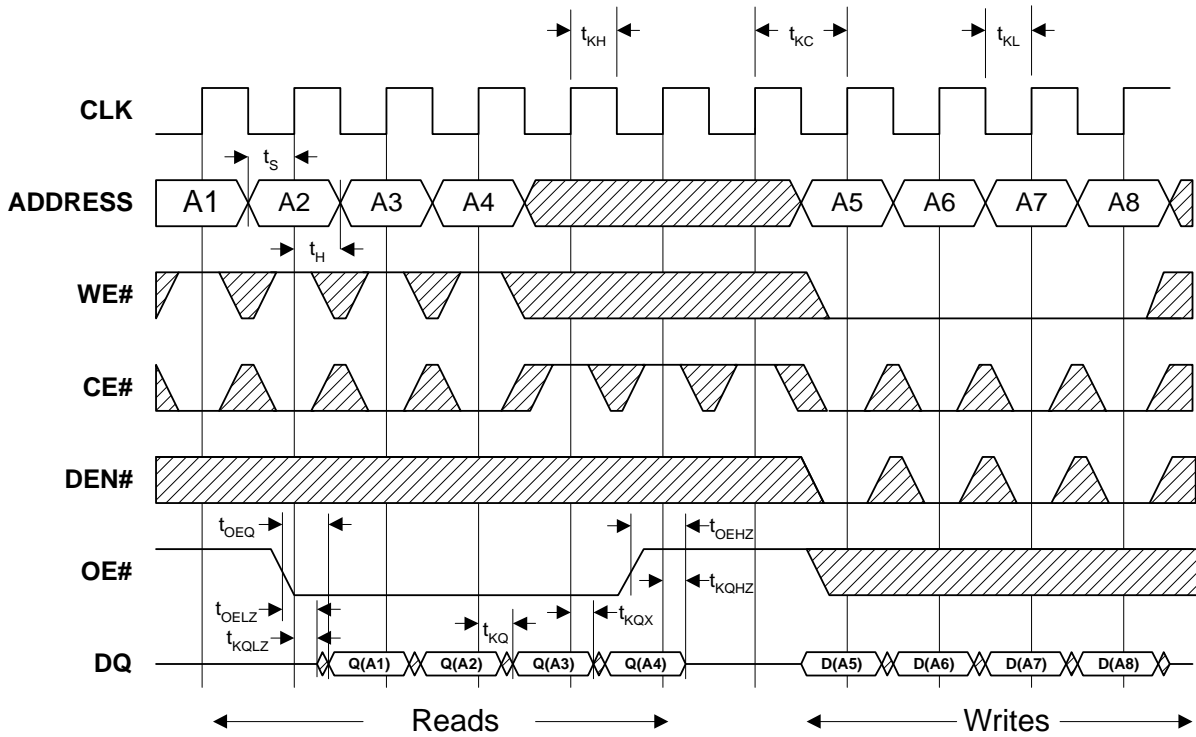
Output High Voltage	Pull-Up Current		Output Low Voltage	Pull-Down Current	
$V_{OH}$ (V)	$I_{OH}$ (mA) Min.	$I_{OH}$ (mA) Max.	$V_{OL}$ (V)	$I_{OL}$ (mA) Min.	$I_{OL}$ (mA) Max.
-0.5	-38	-105	-0.5	0	0
0	-38	-105	0	0	0
0.8	-38	-105	0.4	10	20
1.25	-26	-83	0.8	20	40
1.5	-20	-70	1.25	31	63
2.3	0	-30	1.6	40	80
2.7	0	-10	2.8	40	80
2.9	0	0	3.2	40	80
3.4	0	0	3.4	40	80

**Switching Waveforms**
**Read Timing with Burst Feature<sup>[32, 33]</sup>**

**Notes:**

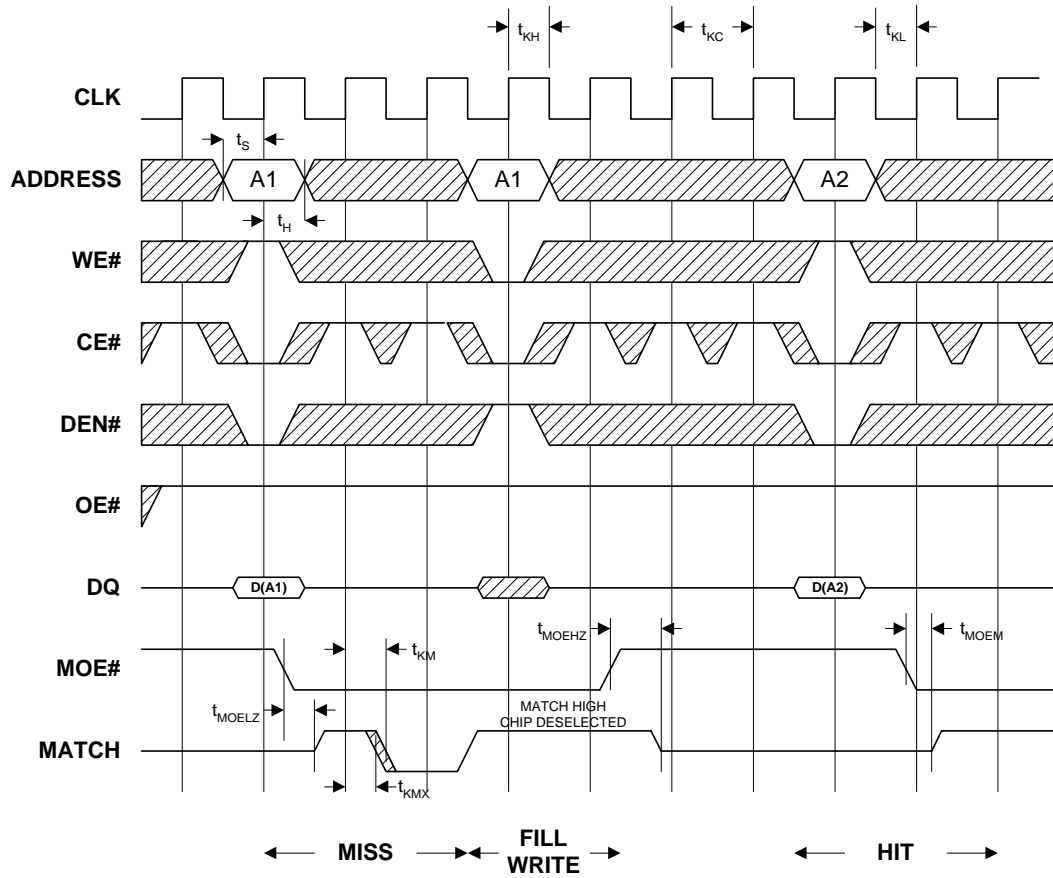
32.  $\overline{CE}$  active in this timing diagram means that all Chip Enables  $\overline{CE}$ ,  $CE_2$ , and  $\overline{CE}_2$  are active.
33. In this timing diagram, it is assumed that  $\overline{DEN}$  is tied to LOW ( $V_{SS}$ ).

**Switching Waveforms (continued)**
**Write Timing with Burst Feature<sup>[32, 33]</sup>**


**Switching Waveforms (continued)**
**Read/Write Timing with Burst Feature<sup>[32, 33]</sup>**


**Switching Waveforms (continued)**
**Read/Write Timing without Burst Feature<sup>[32, 34, 35]</sup>**

**Notes:**

34. In this timing diagram, it is assumed that burst feature is not used and therefore  $\overline{ADSP}$  is tied to HIGH ( $V_{CC}$ ) and  $\overline{ADSC}$  is tied to LOW ( $V_{SS}$ ). The logic state of  $\overline{ADV}$  is a "Don't Care".
35. In this timing diagram, it is assumed that  $\overline{WE} = [\overline{BWE} + \overline{WEL} \cdot \overline{WEH}] \cdot \overline{GW}$ .

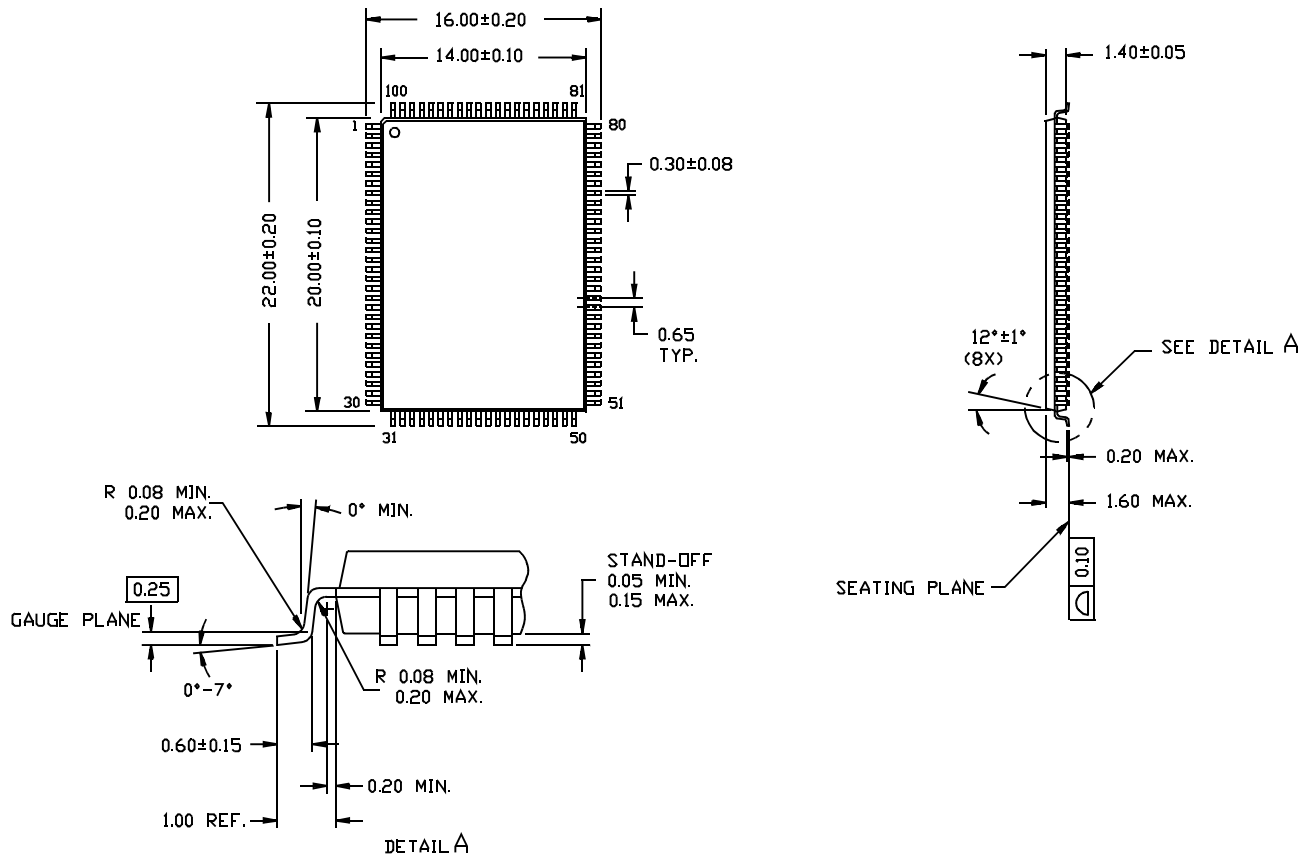
**Switching Waveforms (continued)**
**Compare/Fill Write Timing** [32, 34, 35]


**Ordering Information**

Speed (MHz)	Ordering Code	Package Name	Package Type	Operating Range
166	CY7C1359A-166AC/ GVT71256T18T-6	A101	100-Lead 14 x 20 x 1.4 mm Thin Quad Flat Pack	Commercial
150	CY7C1359A-150AC/ GVT71256T18T-6.7	A101	100-Lead 14 x 20 x 1.4 mm Thin Quad Flat Pack	
133	CY7C1359A-133AC/ GVT71256T18T-7.5	A101	100-Lead 14 x 20 x 1.4 mm Thin Quad Flat Pack	
100	CY7C1359A-100AC/ GVT71256T18T-10	A101	100-Lead 14 x 20 x 1.4 mm Thin Quad Flat Pack	

**Package Diagrams**
**100-Pin Thin Plastic Quad Flatpack (14 x 20 x 1.4 mm) A101**

DIMENSIONS ARE IN MILLIMETERS.



51-85050-A

<b>Document Title: CY7C1359A/GVT71256T18 256K x 18 Synchronous-Pipelined Cache Tag RAM</b> <b>Document Number: 38-05120</b>				
<b>REV.</b>	<b>ECN NO.</b>	<b>Issue Date</b>	<b>Orig. of Change</b>	<b>Description of Change</b>
**	108311	09/25/01	BRI	New Cypress spec—converted from Galvantech format