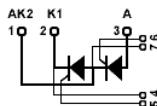


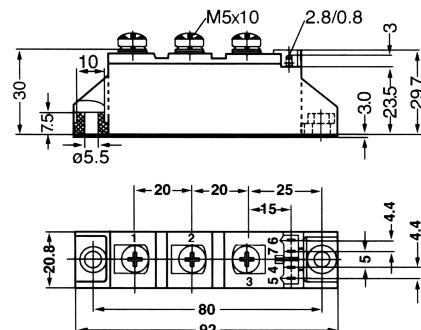
STT116

Thyristor-Thyristor Modules



Type	V_{RSM}	V_{RRM}
	V_{DSM}	V_{DRM}
	V	V
STT116GK08	900	800
STT116GK12	1300	1200
STT116GK14	1500	1400
STT116GK16	1700	1600
STT116GK18	1900	1800

Dimensions in mm (1mm=0.0394")



Symbol	Test Conditions	Maximum Ratings	Unit
I_{TRMS}, I_{FRMS}	$T_{VJ}=T_{VJM}$ $T_C=85^\circ C$; 180° sine	180 116	A
I_{TSM}, I_{FSM}	$T_{VJ}=45^\circ C$ $V_R=0$ $T_{VJ}=T_{VJM}$ $V_R=0$	2250 2400 2000 2150	A
$\int i^2 dt$	$T_{VJ}=45^\circ C$ $V_R=0$ $t=10ms (50Hz), sine$ $t=8.3ms (60Hz), sine$ $T_{VJ}=T_{VJM}$ $V_R=0$ $t=10ms(50Hz), sine$ $t=8.3ms(60Hz), sine$	25300 23900 20000 19100	$A^2 s$
$(di/dt)_{cr}$	$T_{VJ}=T_{VJM}$ $f=50Hz, t_p=200\mu s$ $V_D=2/3V_{DRM}$ $I_G=0.45A$ $di/dt=0.45A/\mu s$	150 500	$A/\mu s$
$(dv/dt)_{cr}$	$T_{VJ}=T_{VJM};$ $V_{DR}=2/3V_{DRM}$ $R_{ck}=\infty$; method 1 (linear voltage rise)	1000	$V/\mu s$
P_{GM}	$T_{VJ}=T_{VJM}$ $t_p=30\mu s$ $I_T=I_{AVM}$ $t_p=300\mu s$	10 5	W
P_{GAV}		0.5	W
V_{RGM}		10	V
T_{VJ} T_{VJM} T_{stg}		-40...+125 125 -40...+125	$^\circ C$
V_{ISOL}	50/60Hz, RMS $I_{ISOL}\leq 1mA$	3000 3600	V_\sim
M_d	Mounting torque (M5) Terminal connection torque (M5)	2.5-4.0/22-35 2.5-4.0/22-35	Nm/lb.in.
Weight	Typical including screws	90	g



STT116

Thyristor-Thyristor Modules

Symbol	Test Conditions	Characteristic Values	Unit
I_{RRM}, I_{DRM}	$T_{VJ}=T_{VJM}$; $V_R=V_{RRM}$; $V_D=V_{DRM}$	5	mA
V_T, V_F	$I_T, I_F=300A$; $T_{VJ}=25^\circ C$	1.5	V
V_{TO}	For power-loss calculations only ($T_{VJ}=125^\circ C$)	0.8	V
r_T		2.4	$m\Omega$
V_{GT}	$V_D=6V$; $T_{VJ}=25^\circ C$ $T_{VJ}=-40^\circ C$	2.5 2.6	V
I_{GT}	$V_D=6V$; $T_{VJ}=25^\circ C$ $T_{VJ}=-40^\circ C$	150 200	mA
V_{GD}	$T_{VJ}=T_{VJM}$; $V_D=2/3V_{DRM}$	0.2	V
I_{GD}		10	mA
I_L	$T_{VJ}=25^\circ C$; $t_p=10\mu s$; $V_D=6V$ $I_G=0.45A$; $dI/dt=0.45A/\mu s$	450	mA
I_H	$T_{VJ}=25^\circ C$; $V_D=6V$; $R_{GK}=\infty$	200	mA
t_{gd}	$T_{VJ}=25^\circ C$; $V_D=1/2V_{DRM}$ $I_G=0.45A$; $dI/dt=0.45A/\mu s$	2	μs
t_q	$T_{VJ}=T_{VJM}$; $I_T=150A$; $t_p=200\mu s$; $-di/dt=10A/\mu s$ $V_R=100V$; $dv/dt=20V/\mu s$; $V_D=2/3V_{DRM}$	typ. 185	μs
Q_s	$T_{VJ}=T_{VJM}$; $I_T, I_F=50A$; $-di/dt=6A/\mu s$	170	μC
I_{RM}		45	A
R_{thJC}	per thyristor/diode; DC current per module	0.22 0.11	K/W
R_{thJK}	per thyristor/diode; DC current per module	0.42 0.21	K/W
ds	Creeping distance on surface	12.7	mm
da	Strike distance through air	9.6	mm
a	Maximum allowable acceleration	50	m/s^2

FEATURES

- * International standard package
- * Copper base plate
- * Planar passivated chips
- * Isolation voltage 3600 V~

APPLICATIONS

- * DC motor control
- * Softstart AC motor controller
- * Light, heat and temperature control

ADVANTAGES

- * Space and weight savings
- * Simple mounting with two screws
- * Improved temperature and power cycling
- * Reduced protection circuits



STT116

Thyristor-Thyristor Modules

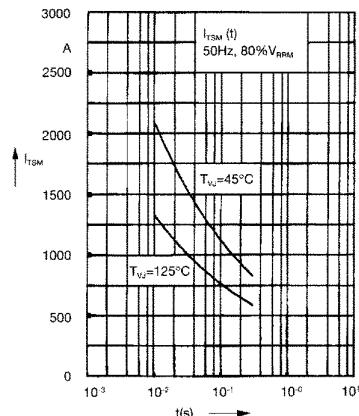


Fig. 1 Surge overload current
 I_{TSM} , I_{FSM} ; Crest value, t : duration

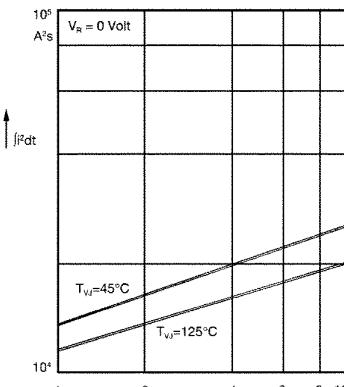


Fig. 2 $\int i^2 dt$ versus time (1-10 ms)

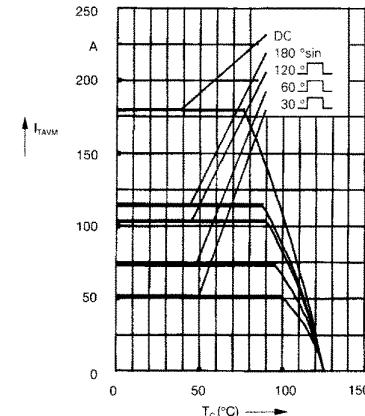


Fig. 2a Maximum forward current
at case temperature

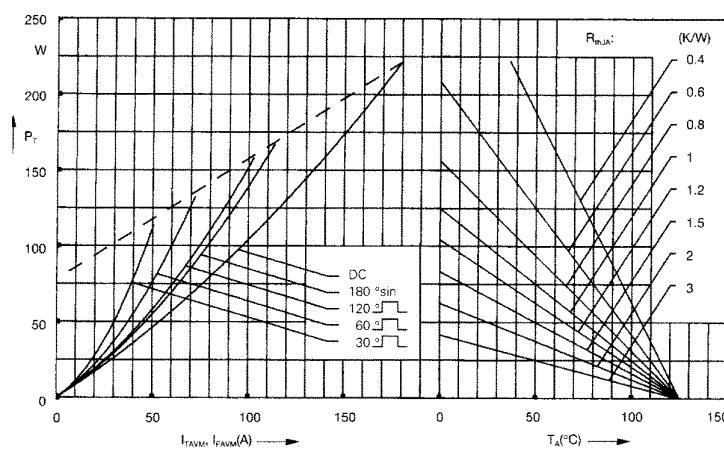


Fig. 3 Power dissipation versus on-state current and ambient temperature
(per thyristor or diode)

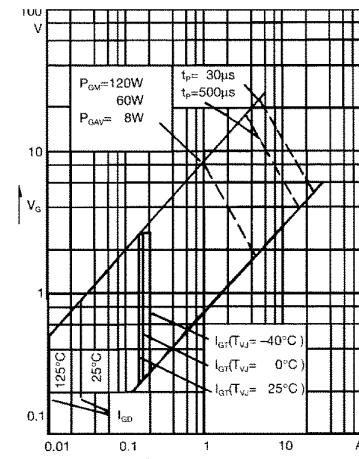


Fig. 4 Gate trigger characteristics

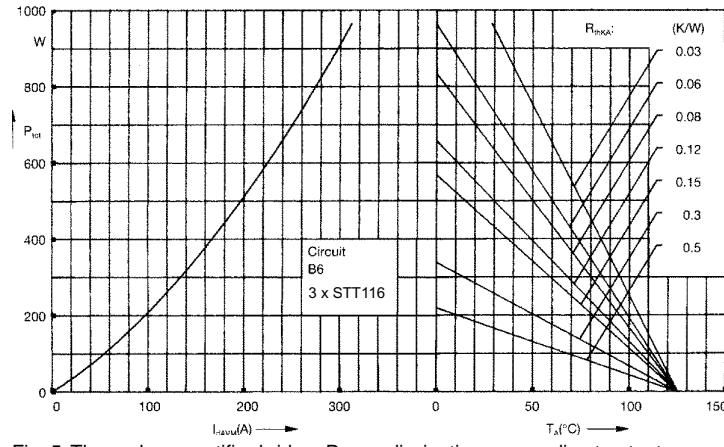


Fig. 5 Three phase rectifier bridge: Power dissipation versus direct output current
and ambient temperature

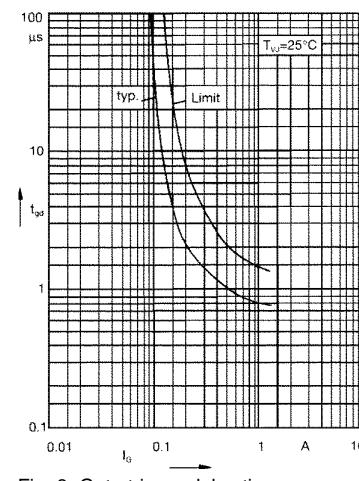


Fig. 6 Gate trigger delay time

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Thyristor-Thyristor Modules

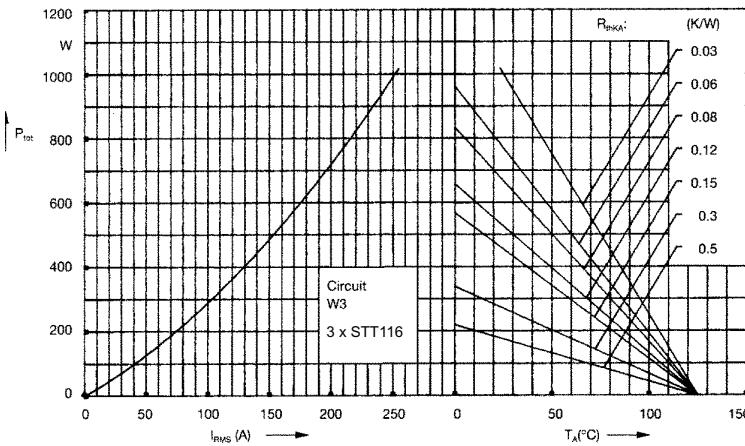


Fig. 7 Three phase AC-controller:
Power dissipation versus RMS
output current and ambient
temperature

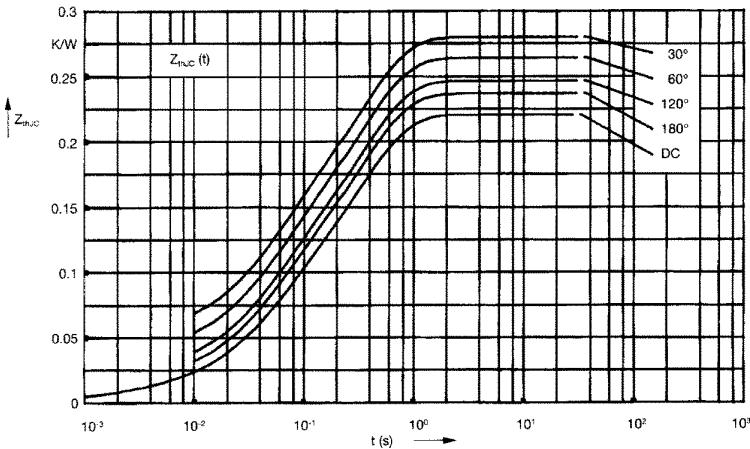


Fig. 8 Transient thermal impedance
junction to case (per thyristor or
diode)

R_{thJC} for various conduction angles d:

d	R_{thJC} (K/W)
DC	0.22
180°	0.23
120°	0.25
60°	0.27
30°	0.28

Constants for Z_{thJC} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.0066	0.0019
2	0.0678	0.0477
3	0.1456	0.344

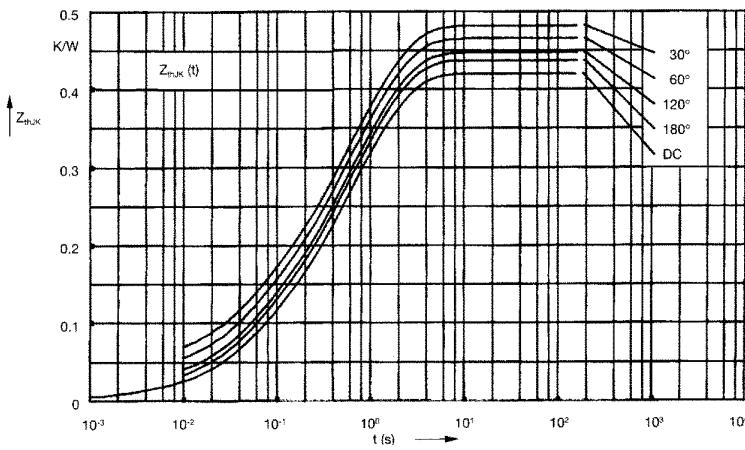


Fig. 9 Transient thermal impedance
junction to heatsink (per thyristor or
diode)

R_{thJK} for various conduction angles d:

d	R_{thJK} (K/W)
DC	0.42
180°	0.43
120°	0.45
60°	0.47
30°	0.48

Constants for Z_{thJK} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.0066	0.0019
2	0.0678	0.0477
3	0.1456	0.344
4	0.2	1.32

