



# LC895299W, 895299L

## 48× Speed ATAPI (IDE) CD-ROM Decoder with On-Chip Digital Servo System

### Overview

The LC895299W and LC895299L are CD-ROM drive digital servo system ICs that integrate all signal-processing functions after the RF head amplifier on a single chip.

### Functions

- Built-in digital servo and ATAPI (IDE) CD-ROM, CD-DSP, CAV audio, and 1-Mbit DRAM functions

### Features

#### CD-DSP Block

- Supports full CAV operation at 48× speed
  - Assures stable data readout by performing frame sync signal detection, protection, and interpolation.
  - Demodulates the EFM signal to produce 8-bit symbol data.
  - Applies a CRC check to the subcode Q signal and then outputs that signal via parallel I/O to the system microprocessor.
  - Performs unscrambling and deinterleaving operations to rearrange the demodulated EFM signal in the stipulated order.
  - Detects and corrects error signals and processes flags (C1: 2 errors, C2: 4 errors)
  - References the C1 flags and the C2 error check result to set the C2 flags and interpolates or mutes the signal depending on the C2 flags.
  - Provides two types of muting: zero-cross muting and soft muting.
  - Independent left and right channel digital attenuators (8-bit resolution)
- Provides two types of attenuation: direct attenuation and soft attenuation.

- Bilingual support
- Built-in digital audio interface (supports both CLV and CAV)
- Built-in digital deemphasis
- Built-in 8× oversampling digital filters
- Built-in D/A converters

#### CD-ROM Decoder and ATAPI (IDE) Interface Block

- Built-in ATAPI (IDE) interface
- The user can freely set the CD main channel, C2 flag, and subcode areas in internal DRAM.
- Batch transfer function (Function for transferring the CD main channel, C2 flag, or subcode data in a single operation.)
- Multiple transfer function (Function for transferring multiple blocks automatically in a single operation.)
- CAV audio functions
- Intelligent functions (auto buffering, auto decoding, and CD-R functions)
- Subcode P to W buffering function (No ECC) and CD-TEXT support
- Supports Ultra DMA MODE2, MODE1, and MODE0
- Built in 1-Mbit DRAM

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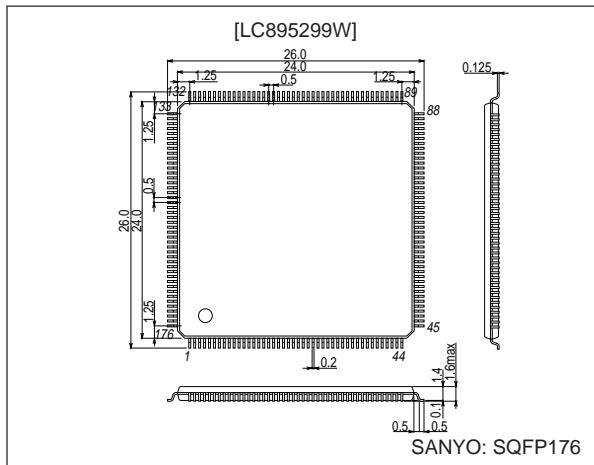
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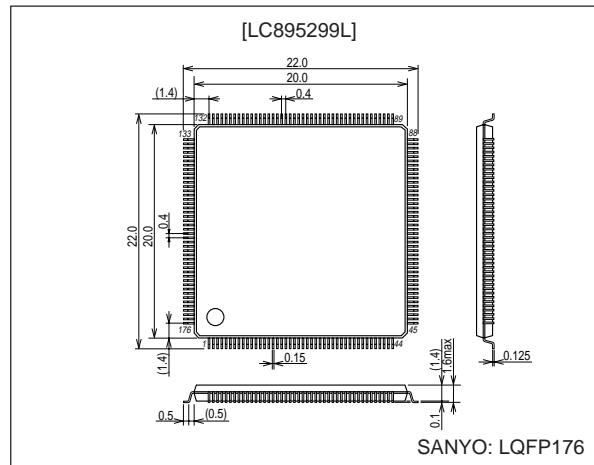
## Package Dimensions

unit: mm

**3230-SQFP176**



**3244-LQFP176**



## Specifications

### Absolute Maximum Ratings at $V_{SS} = 0$ V

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	$V_{DD5}$ max	T <sub>a</sub> = 25°C	-0.3 to +6.0	V
	$V_{DD3}$ max	T <sub>a</sub> = 25°C	-0.3 to +4.6	V
Input and output voltages	$V_{I5}, V_{O5}$	T <sub>a</sub> = 25°C	-0.3 to $V_{DD5} + 0.3$	V
	$V_{I3}, V_{O3}$	T <sub>a</sub> = 25°C	-0.3 to $V_{DD3} + 0.3$	V
Allowable power dissipation	P <sub>d</sub> max	T <sub>a</sub> ≤ 70°C	550	mW
Operating temperature	T <sub>opr</sub>		-30 to +70	°C
Storage temperature	T <sub>stg</sub>		-55 to +125	°C
Soldering conditions (pins only)		10 seconds	235	°C
Input and output power	I <sub>I</sub> , I <sub>O</sub>		±20 *	mA

Note: \* Per single input or output basic cell.

### Allowable Operating Ranges at T<sub>a</sub> = 0 to +70°C, V<sub>SS</sub> = 0 V

#### I/O Cell 5.0-V Power Supply

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Supply voltage	V <sub>DD</sub>		4.5	5.0	5.5	V
Input voltage range	V <sub>IN</sub>		0		V <sub>DD</sub>	V

Note: The input voltage range for speeds of 45x or over is 4.5 to 5.25 V.

#### Internal Cell 3.3-V Power Supply

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Supply voltage	V <sub>DD</sub>		3.0	3.3	3.8	V
Input voltage range	V <sub>IN</sub>		0		V <sub>DD</sub>	V

Note: The input voltage range differs depending on the drive speed used. Contact your Sanyo representative for details.

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### DC Characteristics at $T_a = 0$ to $+70^\circ\text{C}$ , $V_{SS} = 0 \text{ V}$ , $V_{DD} = 4.5$ to $5.5 \text{ V}$

Parameter	Symbol	Conditions	Applicable pins *	Ratings			Unit
				min	typ	max	
Input high-level voltage	$V_{IH}$	TTL level inputs	1	2.2			V
Input low-level voltage	$V_{IL}$					0.8	V
Input high-level voltage	$V_{IH}$	TTL level inputs with pull-up resistors	7	2.2			V
Input low-level voltage	$V_{IL}$					0.8	V
Input high-level voltage	$V_{IH}$	TTL level inputs with pull-down resistors	2	2.2			V
Input low-level voltage	$V_{IL}$					0.8	V
Input high-level voltage	$V_{IH}$	TTL level inputs Schmitt inputs	3, 9	2.4			V
Input low-level voltage	$V_{IL}$					0.8	V
Input high-level voltage	$V_{IH}$	TTL level inputs Schmitt inputs with pull-up resistors	19, 20	2.4			V
Input low-level voltage	$V_{IL}$					0.8	V
Input high-level voltage	$V_{IH}$	CMOS level inputs Schmitt inputs	4	0.8 $V_{DD}$			V
Input low-level voltage	$V_{IL}$					0.2 $V_{DD}$	V
Input high-level voltage	$V_{IH}$	CMOS level inputs with pull-up resistors	5	0.7 $V_{DD}$			V
Input low-level voltage	$V_{IL}$					0.3 $V_{DD}$	V
Analog input voltage	$V_{ANI}$		18	1/4 $V_{DD}$		3/4 $V_{DD}$	V
Output high-level voltage	$V_{OH}$	$I_{OH} = -2 \text{ mA}$	6, 17	$V_{DD} - 2.1$			V
Output low-level voltage	$V_{OL}$	$I_{OL} = 2 \text{ mA}$				0.4	V
Output high-level voltage	$V_{OH}$	$I_{OH} = -8 \text{ mA}$	7, 8, 14	$V_{DD} - 2.1$			V
Output low-level voltage	$V_{OL}$	$I_{OL} = 8 \text{ mA}$				0.4	V
Output high-level voltage	$V_{OH}$	$I_{OH} = -4 \text{ mA}$	9, 12, 10, 20	$V_{DD} - 2.1$			V
Output low-level voltage	$V_{OL}$	$I_{OL} = 24 \text{ mA}$				0.4	V
Output high-level voltage	$V_{OH}$	$I_{OH} = -4 \text{ mA}$	16	$V_{DD} - 2.1$			V
Output low-level voltage	$V_{OL}$	$I_{OL} = 4 \text{ mA}$				0.4	V
Output low-level voltage	$V_{OL}$	$I_{OL} = 24 \text{ mA}$	11, 21			0.4	V
Output low-level voltage	$V_{OL}$	$I_{OL} = 1 \text{ mA}$	13			0.4	V
Output low-level voltage	$V_{OL}$	$I_{OL} = 8 \text{ mA}$	15			0.4	V
Analog output voltage	$V_{ANO}$		22	1/4 $V_{DD}$		3/4 $V_{DD}$	V
Input leakage current	$I_{IL}$	$V_I = V_{SS}, V_{DD}$	1, 3, 4, 9	-10		+10	$\mu\text{A}$
Output leakage current	$I_{OZ}$	During high-impedance output	9, 11, 13, 14, 16, 17	-10		+10	$\mu\text{A}$
Pull-up resistance	$R_{UP}$		5	50	100	200	$\text{k}\Omega$
Pull-up resistance	$R_{UP}$		7, 15	20	40	80	$\text{k}\Omega$
Pull-up resistance	$R_{UP}$		19, 20, 21	7	10	13	$\text{k}\Omega$
Pull-down resistance	$R_{DN}$		2	50	100	200	$\text{k}\Omega$
Pull-down resistance	$R_{DN}$		10	7	10	13	$\text{k}\Omega$

Note: \* The applicable pin column entries refer to the following sets.

#### INPUT

- 1 : ATPINSEL, SUA0 to SUA7
- 2 : TEST0 to TEST2
- 3 : DA0 to DA2, ZCS1FX, ZCS3FX, ZDIOR, ZDIOW, ZHRST, ZCS, ZRD, ZWR
- 4 : ZRESET, ZDSPRST
- 5 : FG
- 18 : AD0, AD1, PH, BH, RREC, FE, TE, VREF, CSS, AD2
- 19 : ZDMACK, CSEL

#### OUTPUT

- 6 : FSEQ
- 8 : HFLO, FSX, EFLG, C2F, WRQ, DIR, PCK, EFMOUT
- 13 : HINTRO
- 11 : ZIOCS16
- 10 : DMARQ
- 13 : PDS1 to PDS3
- 14 : DOUT
- 15 : ZSWAIT, ZINT0, ZINT1
- 21 : IORDY
- 16 : DSLB, EOS, OUTPORT0 to OUTPORT2, MCK
- 17 : RHLD, TSH, BHH, GHS, LDON
- 22 : PHC, BHC, FBAL, TBAL, SGC, TOFST, TDO, FDO, SLDO, SPDO

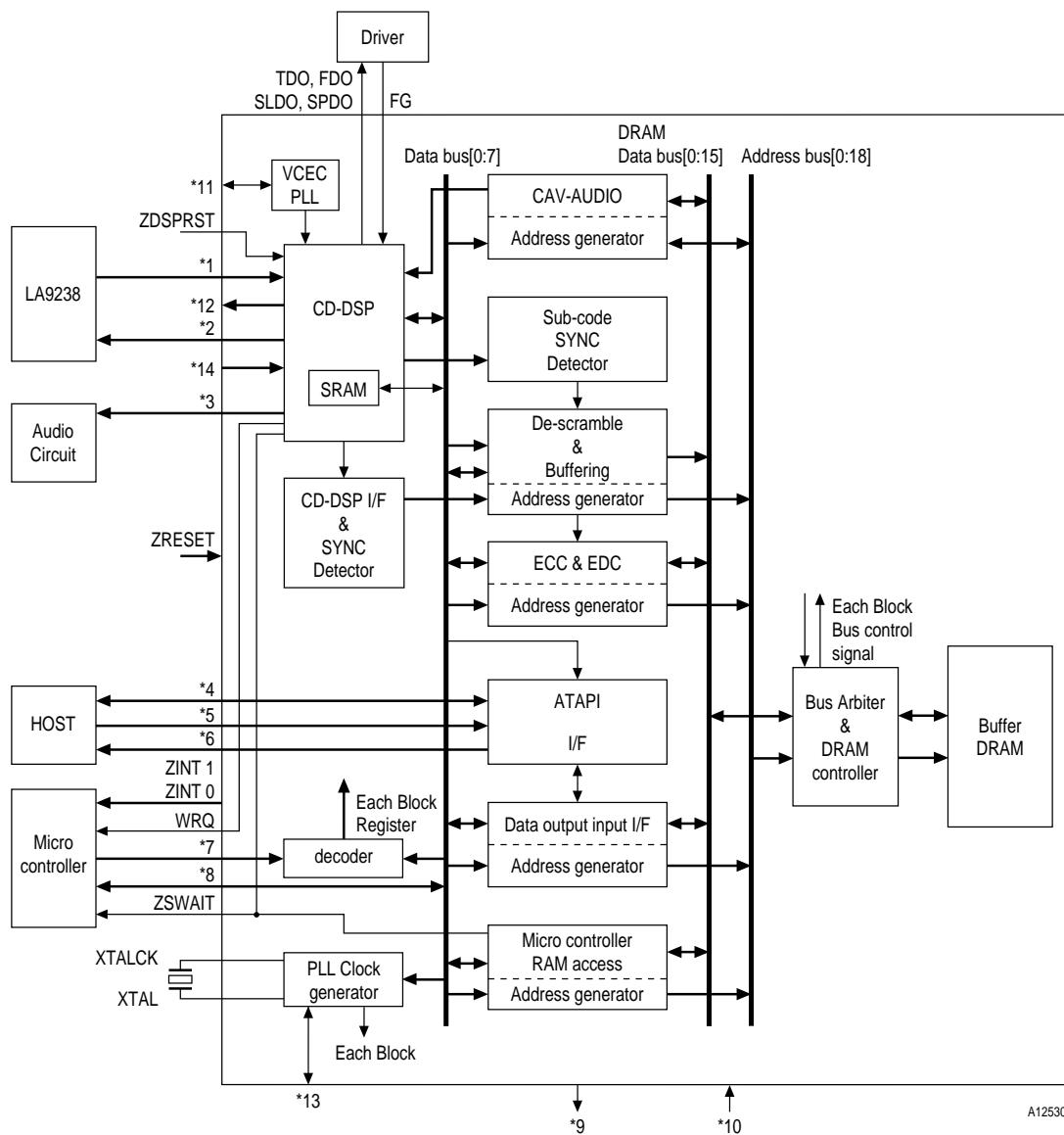
#### INPUT

- 7 : D0 to D7, TRV, TRV2
- 9 : DD0 to DD15
- 20 : ZDASP, ZPDIAG

Note: XTAL, XTALCK

The above pins are not included in the DC Characteristics.

## Block Diagram



A12530

- \*1 EFMIN, EFMIN2, PH, BH, FE, TE, TES, RREC
- \*2 RHLD, TSH, EQS, BHH, GHS, LDON, FBAL, TBAL, TOFST, SGC
- \*3 LOUT, ROUT, DOUT
- \*4 DD0 to DD15, ZDASP, ZPDIAG
- \*5 ZCS1FX, ZCS3FX, DA0 to DA2, ZDIOR, ZDIOW, ZDMACK, ZHRST, CSEL
- \*6 DMARQ, HINTRQ, ZIOCS16, IORDY
- \*7 ZRD, ZWR, ZCS, CSCTRL, SUA0 to SUA7
- \*8 D0 to D7
- \*9 DIR/FLOCK, HFLO/TLOCK, FSEQ, FSX/LRCK, EFLG/CK2, C2F, EFMOUT, PCK, TRV2/DATA, TRV, PORT OUT0 to OUT2
- \*10 ATPINSEL, TEST0 to TEST2
- \*11 RPO, OPP, PCKISTF, PCKISTP, PDO, POS1 to POS3, FR
- \*12 SLCO0 to SLCO3, JITC, DSLB, PHC, BHC
- \*13 PLL1 to PLL3
- \*14 SLCIT1 to SLCIT2, JITIN, AD0 to AD2, VREF, CSS

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### Pin Functions

LC895299 Pin Functions 1  
(When pin 95, ATPINSEL, is low)

Type					
I	INPUT	B	BIDIRECTION	NC	NOT CONNECT
O	OUTPUT	P	POWER		

Pin No.	Pin	Type	Function
1	V <sub>SS</sub>	P	Logic system ground
2	FLOCK/CRCERR	O	
3	DIR/TLOCK	O	Monitor outputs
4	ZSWAIT	O	Wait signal output to the microcontroller
5	WRQ/HFLO	O	Monitor output
6	ZINT0	O	
7	ZINT1	O	Microcontroller interrupt
8	TEST0	I	Test pin (Must be tied to ground during normal operation.)
9	D0	B	
10	D1	B	
11	D2	B	
12	D3	B	
13	D4	B	
14	D5	B	
15	D6	B	
16	D7	B	
17	MCK	O	Clock output to the microcontroller
18	ZCS	I	Microcontroller ZCS signal
19		NC	
20		NC	
21	V <sub>DDD</sub>	P	DRAM V <sub>DD</sub> : 5 V
22	V <sub>DD1</sub>	P	3.3 V
23	V <sub>SS</sub>	P	Logic system ground
24	V <sub>SSD</sub>	P	DRAM ground
25		NC	
26		NC	
27	SUA0	I	
28	SUA1	I	
29	SUA2	I	
30	SUA3	I	
31	SUA4	I	
32	SUA5	I	
33	SUA6	I	
34	SUA7	I	
35	ZWR	I	Microcontroller write signal
36	ZRD	I	Microcontroller read signal
37	FSEQ	O	Frame synchronization detection
38	DOUT/TESO	O	Digital output/tes output
39	V <sub>DD0</sub>	P	I/O system power supply: 5 V
40	V <sub>SS</sub>	P	Logic system ground
41	PLL1	I	
42	PLL2	I	
43	PLL3	O	
44	PLL1 V <sub>DD</sub>	P	Logic PLL V <sub>DD</sub> : 3.3 V
45	PLL1 V <sub>SS</sub>	P	Logic PLL system ground
46	CSEL	I	
47	ZHRST	I	
48	ZDASP	B	
49	ZCS3FX	I	
50	ZCS1FX	I	
51	V <sub>SS1</sub>	I	I/F ground
52	V <sub>DD0</sub>	I	I/O system power supply: 5 V

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Pin No.	Pin	I/O	Function
53	DA2	I	ATAPI I/F
54	DA0	I	
55	ZPDIAG	B	
56	DA1	I	
57	ZIOCS16	O	
58	V <sub>SS1</sub>	P	I/F ground
59	HINTRQ	O	ATAPI I/F
60	ZDMACK	I	
61	IORDY	O	
62	ZDIOR	I	
63	ZDIOW	I	
64	DMARQ	O	
65	V <sub>DD0</sub>	P	I/O system power supply: 5 V
66	V <sub>DD1</sub>	P	3.3 V
67	V <sub>SS1</sub>	P	I/F ground
68	DD15	B	ATAPI I/F
69	DD0	B	
70	DD14	B	
71	DD1	B	
72	DD13	B	
73	V <sub>SS1</sub>	P	I/F ground
74	DD2	B	ATAPI I/F
75	DD12	B	
76	DD3	B	
77	DD11	B	
78	DD4	B	
79	V <sub>SS1</sub>	P	I/F ground
80	DD10	B	ATAPI I/F
81	DD5	B	
82	DD9	B	
83	DD6	B	
84	DD8	B	
85	DD7	B	ATAPI I/F
86	V <sub>DD0</sub>	P	I/O system power supply: 5 V
87	ROUT	O	D/A converter output
88	AUV <sub>DD</sub>	P	D/A converter V <sub>DD</sub> : 5 V
89	AUV <sub>SS</sub>	P	DAC ground
90	LOUT	O	D/A converter output
91	V <sub>SS</sub>	P	Logic system ground
92	XTAL	O	XTALCK output
93	XTALCK	I	XTALCK input (33.8688 MHz)
94	V <sub>DD0</sub>	P	I/O system power supply: 5 V
95	ATPINSEL	I	ATAPI pin assignment selection
96	TEST1	I	Test pin (Must be tied to ground during normal operation.)
97	FSX/LRCK	O	Monitor outputs
98	EFLG/CK2	O	
99	TRV2/DATA	B	General-purpose I/O ports
100	TRV	B	
101	C2F	O	
102	PCK	O	
103	EFMOUT	O	
104	OUTPORT0	O	General-purpose output ports
105	OUTPORT1	O	
106	OUTPORT2	O	
107		NC	

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Continued from preceding page.

Pin No.	Pin	I/O	Function
108		NC	
109	V <sub>SSD</sub>	P	DRAM ground
110	V <sub>DD1</sub>	P	3.3 V
111	V <sub>SS</sub>	P	Logic GND
112	V <sub>DDD</sub>	P	DRAM V <sub>DD</sub> : 5 V
113		NC	
114		NC	
115	DSLB	O	SLC PWM output
116	AV <sub>DD</sub>	P	Slice level V <sub>DD</sub> : 3.3 V
117	SLCIST1	I	EFM slice level setting
118	SLCIST2	I	
119	SLCO0	O	EFM slice level outputs
120	SLCO1	O	
121	SLCO2	O	
122	SLCO3	O	
123	EFMIN	I	EFM input
124	EFMIN2	I	
125	AV <sub>SS</sub>	P	Slice level ground
126	JITIN	I	Jitter detection input
127	JITC	O	Jitter output
128	RPO	O	P/N balance adjustment
129	OPP	I	
130	PCKISTF	I	Frequency comparator charge pump setting
131	PCKISTP	I	Phase comparator charge pump setting
132	PLL2V <sub>DD</sub>	P	VCEC PLL V <sub>DD</sub> : 3.3 V
133	PLL2V <sub>SS</sub>	P	VCEC PLL ground
134	PDO	O	Charge pump filter
135	PDS1	O	Charge pump selection
136	PDS2	O	
137	PDS3	O	
138	FR	I	VCO frequency setting
139	SV <sub>SS</sub>	P	Servo system ground
140	AD0	I	A/D converter input 0
141	AD1	I	A/D converter input 1
142	PH	I	Peak hold circuit
143	BH	I	Bottom hold circuit
144	RREC	I	Optical recognition input
145	FE	I	FE input
146	TE	I	TE input
147	TES	I	TES comparator input
148	VREF	I	VREF input
149	CSS	I	Center servo input
150	AD2	I	A/D converter input 2
151	PHC	O	PH slice capacitor connection
152	BHC	O	BH slice capacitor connection
153	FBAL	O	Focus balance
154	SV <sub>DD</sub>	P	Servo system V <sub>DD</sub> : 5V
155	SV <sub>SS</sub>	P	Servo system ground
156	TBAL	O	Tracking balance
157	SGC	O	Servo gain adjustment
158	TOFST	O	Tracking offset adjustment
159	TDO	O	Tracking output
160	FDO	O	Focus output
161	SLDO	O	Sled output
162	SPDO	O	Spindle output

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Pin No.	Pin	I/O	Function
163	V <sub>DD0</sub>	P	A/D and D/A converter V <sub>DD</sub> : 5 V
164	V <sub>SS</sub>	P	Logic ground
165	V <sub>DD1</sub>	P	3.3 V
166	RHLD	O	RF AGC hold output
167	TSH	O	TS frequency switching
168	EQS	O	RF equalizer selection
169	BHH	O	BH frequency switching
170	GHS	O	RF and TS signal gain switching
171	LDON	O	Laser control
172	TEST2	I	Test pin (Must be tied to ground during normal operation.)
173	FG	I	FG input
174	ZDSPRST	I	DSP RESET
175	ZRESET	I	CHIP RESET
176	V <sub>DD0</sub>	P	I/O system V <sub>DD</sub> : 5 V

All NC pins must be left open.

Pins whose name begin with Z operate with inverted (negative) logic.

Applications must supply 5 V to V<sub>DD0</sub>, 3.3 V to V<sub>DD1</sub>, the 1-bit D/A converter 5 V to AUV<sub>DD</sub>, the logic PLL 3.3 V to PLL1V<sub>DD</sub>, the VCEC PLL 3.3 V to PLL2V<sub>DD</sub>, the slice level 3.3 V to AV<sub>DD</sub>, the servo system 5 V to SV<sub>DD</sub>, and the DRAM 5 V to V<sub>DDD</sub>.

V<sub>SS</sub> is the logic system ground, AUV<sub>SS</sub> is the 1-bit D/A converter ground, V<sub>SS1</sub> is the IDE interface driver ground, PLL1V<sub>SS</sub> is the logic PLL ground, PLL2V<sub>SS</sub> is the VCEC PLL ground, AV<sub>SS</sub> is the slice level ground, SV<sub>SS</sub> is the servo system ground, and V<sub>SSD</sub> is the DRAM ground.

## LC895299W, 895299L

### Pin Functions

LC895299 Pin Functions 2  
(When pin 95, ATPINSEL, is high)

Type					
I	INPUT	B	BIDIRECTION	NC	NOT CONNECT
O	OUTPUT	P	POWER		

Pin No.	Pin	Type	Function
1	V <sub>SS</sub>	P	Logic system ground
2	FLOCK/CRCERR	O	
3	DIR/TLOCK	O	Monitor outputs
4	ZSWAIT	O	Wait signal output to the microcontroller
5	WRQ/HFLO	O	Monitor output
6	ZINT0	O	
7	ZINT1	O	Microcontroller interrupt
8	TEST0	I	Test pin (Must be tied to ground during normal operation.)
9	D0	B	
10	D1	B	
11	D2	B	
12	D3	B	
13	D4	B	
14	D5	B	
15	D6	B	
16	D7	B	
17	MCK	O	Clock output to the microcontroller
18	ZCS	I	Microcontroller ZCS signal
19		NC	
20		NC	
21	V <sub>DDD</sub>	P	DRAM V <sub>DD</sub> : 5 V
22	V <sub>DD1</sub>	P	3.3 V
23	V <sub>SS</sub>	P	Logic system ground
24	V <sub>SSD</sub>	P	DRAM ground
25		NC	
26		NC	
27	SUA0	I	
28	SUA1	I	
29	SUA2	I	
30	SUA3	I	
31	SUA4	I	
32	SUA5	I	
33	SUA6	I	
34	SUA7	I	
35	ZWR	I	Microcontroller write signal
36	ZRD	I	Microcontroller read signal
37	FSEQ	O	Frame synchronization detection
38	DOUT/TESO	O	Digital output/tes output
39	V <sub>DD0</sub>	P	I/O system power supply: 5 V
40	V <sub>SS</sub>	P	Logic system ground
41	PLL1	I	
42	PLL2	I	
43	PLL3	O	
44	PLL1 V <sub>DD</sub>	P	Logic PLL V <sub>DD</sub> : 3.3 V
45	PLL1 V <sub>SS</sub>	P	Logic PLL ground
46	CSEL	I	
47	DD7	B	
48	DD8	B	
49	DD6	B	
50	DD9	B	
51	V <sub>SS1</sub>	P	I/F ground
52	V <sub>DD0</sub>	P	I/O system power supply: 5 V

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Pin No.	Pin	I/O	Function		
53	DD5	B	ATAPI I/F		
54	DD10	B			
55	DD4	B			
56	DD11	B			
57	DD3	B			
58	V <sub>SS1</sub>	P	I/F GND		
59	DD12	B	ATAPI I/F		
60	DD2	B			
61	DD13	B			
62	DD1	B			
63	DD14	B			
64	DD0	B			
65	V <sub>DD0</sub>	P	I/O system power supply: 5 V		
66	V <sub>DD1</sub>	P	3.3 V		
67	V <sub>SS1</sub>	P	I/F GND		
68	DD15	B	ATAPI I/F		
69	DMARQ	O			
70	ZDIOW	I			
71	ZDIOR	I			
72	IORDY	O			
73	V <sub>SS1</sub>	P	I/F GND		
74	ZDMACK	I	ATAPI I/F		
75	HINTRQ	O			
76	ZIOCS16	O			
77	DA1	I			
78	ZPDIAG	B			
79	V <sub>SS1</sub>	P	I/F GND		
80	DA0	I	ATAPI I/F		
81	DA2	I			
82	ZCS1FX	I			
83	ZCS3FX	I			
84	ZDASP	B			
85	ZHRST	I	ATAPI I/F		
86	V <sub>DD0</sub>	P	I/O system power supply: 5 V		
87	ROUT	O	D/A converter output		
88	AUV <sub>DD</sub>	P	D/A converter V <sub>DD</sub> : 5 V		
89	AUV <sub>SS</sub>	P	DAC ground		
90	LOUT	O	D/A converter output	Logic system ground	
91	V <sub>SS</sub>	P	Logic system ground		
92	XTAL	O	XTALCK output		
93	XTALCK	I	XTALCK input (33.8688 MHz)		
94	V <sub>DD0</sub>	P	I/O system power supply: 5 V		
95	ATPINSEL	I	ATAPI pin assignment selection	General-purpose I/O ports	
96	TEST1	I	Test pin (Must be tied to ground during normal operation.)		
97	FSX/LRCK	O	Monitor outputs		
98	EFLG/CK2	O			
99	TRV2/DATA	B	General-purpose I/O ports		
100	TRV	B			
101	C2F	O			
102	PCK	O			
103	EFMOUT	O			
104	OUTPORT0	O	General-purpose output ports		
105	OUTPORT1	O			
106	OUTPORT2	O			
107		NC			

Continued on next page.

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Continued from preceding page.

Pin No.	Pin	I/O	Function
108		NC	
109	V <sub>SSD</sub>	P	DRAM ground
110	V <sub>DD1</sub>	P	3.3 V
111	V <sub>SS</sub>	P	Logic system ground
112	V <sub>DDD</sub>	P	DRAM V <sub>DD</sub> : 5 V
113		NC	
114		NC	
115	DSLB	O	SLC PWM output
116	AV <sub>DD</sub>	P	Slice level V <sub>DD</sub> : 3.3 V
117	SLCIST1	I	EFM slice level setting
118	SLCIST2	I	
119	SLCO0	O	EFM slice level outputs
120	SLCO1	O	
121	SLCO2	O	
122	SLCO3	O	
123	EFMIN	I	EFM input
124	EFMIN2	I	
125	AV <sub>SS</sub>	P	Slice level ground
126	JITIN	I	Jitter detection input
127	JITC	O	Jitter output
128	RPO	O	P/N balance adjustment
129	OPP	I	
130	PCKISTF	I	Frequency comparator charge pump setting
131	PCKISTP	I	Phase comparator charge pump setting
132	PLL2V <sub>DD</sub>	P	VCEC PLL V <sub>DD</sub> : 3.3 V
133	PLL2V <sub>SS</sub>	P	VCEC PLL ground
134	PDO	O	Charge pump filter
135	PDS1	O	Charge pump selection
136	PDS2	O	
137	PDS3	O	
138	FR	I	VCO frequency setting
139	SV <sub>SS</sub>	P	Servo system ground
140	AD0	I	A/D converter input 0
141	AD1	I	A/D converter input 1
142	PH	I	Peak hold circuit
143	BH	I	Bottom hold circuit
144	RREC	I	Optical recognition input
145	FE	I	FE input
146	TE	I	TE input
147	TES	I	TES comparator input
148	VREF	I	VREF input
149	CSS	I	Center servo input
150	AD2	I	A/D converter input 2
151	PHC	O	PH slice capacitor connection
152	BHC	O	BH slice capacitor connection
153	FBAL	O	Focus balance
154	SV <sub>DD</sub>	P	Servo system V <sub>DD</sub> : 5V
155	SV <sub>SS</sub>	P	Servo system ground
156	TBAL	O	Tracking balance
157	SGC	O	Servo gain adjustment
158	TOFST	O	Tracking offset adjustment
159	TDO	O	Tracking output
160	FDO	O	Focus output
161	SLDO	O	Sled output
162	SPDO	O	Spindle output

Continued on next page.

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Continued from preceding page.

Pin No.	Pin	I/O	Function
163	V <sub>DD0</sub>	P	A/D and D/A converter V <sub>DD</sub> : 5 V
164	V <sub>SS</sub>	P	Logic system ground
165	V <sub>DD1</sub>	P	3.3 V
166	RHLD	O	RF AGC hold output
167	TSH	O	TS frequency switching
168	EQS	O	RF equalizer selection
169	BHH	O	BH frequency switching
170	GHS	O	RF and TS signal gain switching
171	LDON	O	Laser control
172	TEST2	I	Test pin (Must be tied to ground during normal operation.)
173	FG	I	FG input
174	ZDSPRST	I	DSP RESET
175	ZRESET	I	CHIP RESET
176	V <sub>DD0</sub>	P	I/O system V <sub>DD</sub> : 5 V

All NC pins must be left open.

Pins whose name begin with Z operate with inverted (negative) logic.

Applications must supply 5 V to V<sub>DD0</sub>, 3.3 V to V<sub>DD1</sub>, the 1-bit D/A converter 5 V to AUV<sub>DD</sub>, the logic PLL 3.3 V to PLL1V<sub>DD</sub>, the VCEC PLL 3.3 V to PLL2V<sub>DD</sub>, the slice level 3.3 V to AV<sub>DD</sub>, the servo system 5 V to SV<sub>DD</sub>, and the DRAM 5 V to V<sub>DDD</sub>.

V<sub>SS</sub> is the logic system ground, AUV<sub>SS</sub> is the 1-bit D/A converter ground, V<sub>SS1</sub> is the IDE interface driver ground, PLL1V<sub>SS</sub> is the logic PLL ground, PLL2V<sub>SS</sub> is the VCEC PLL ground, AV<sub>SS</sub> is the slice level ground, SV<sub>SS</sub> is the servo system ground, and V<sub>SSD</sub> is the DRAM ground.

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