



# 500 MHz Dual Integrated DCL with Differential Drive/Receive, Level Setting DACs, and Per Pin PMU

## ADATE302-02

### FEATURES

#### Driver

- 3-level driver with high-Z mode and built-in clamps
- Precision trimmed output resistance
- Low leakage mode (typically <math><10\text{ nA}</math>)
- Voltage range:  $-2.0\text{ V}$  to  $+6.0\text{ V}$
- 1.0 ns minimum pulse width, 1 V terminated

#### Comparator

- Window and differential comparator
- >1 GHz input equivalent bandwidth

#### Load

- $\pm 12\text{ mA}$  maximum current capability

#### Per pin PMU

- Force voltage range:  $-2.0\text{ V}$  to  $+6.0\text{ V}$
- 5 current ranges: 25 mA, 2 mA, 200  $\mu\text{A}$ , 20  $\mu\text{A}$ , and 2  $\mu\text{A}$

#### Levels

- 14-bit DAC for DCL levels
- Typically  $<\pm 5\text{ mV INL}$  (calibrated)
- 16-bit DAC for PMU levels
- Typically  $<\pm 1.5\text{ mV INL}$  (calibrated) linearity in FV mode

#### HVOUT output buffer

- 0 V to 13.5 V output range
- 84-ball, 9 mm  $\times$  9 mm, flip-chip BGA package
- 1.7 W per channel with no load

### APPLICATIONS

- Automatic test equipment
- Semiconductor test systems
- Board test systems
- Instrumentation and characterization equipment

### GENERAL DESCRIPTION

The ADATE302-02 is a complete, single-chip solution that performs the pin electronic functions of the driver, the comparator, and the active load (DCL), per pin PMU, and dc levels for ATE applications. The device also contains an HVOUT driver with a VHH buffer capable of generating up to 13.5 V.

The driver features three active states: data high mode, data low mode, and term mode, as well as an inhibit state. The inhibit state, in conjunction with the integrated dynamic clamp, facilitates the implementation of a high speed active termination. The output voltage range is  $-2.0\text{ V}$  to  $+6.0\text{ V}$  to accommodate a wide variety of test devices.

The ADATE302-02 can be used as either a dual single-ended drive/receive channel or a single differential drive/receive channel. Each channel of the ADATE302-02 features a high speed window comparator per pin for functional testing as well as a per pin PMU with FV or FI and MV or MI functions. All necessary dc levels for DCL functions are generated by on-chip 14-bit DACs. The per pin PMU features an on-chip 16-bit DAC for high accuracy and contains integrated range resistors to minimize external component counts.

The ADATE302-02 uses a serial bus to program all functional blocks and has an on-board temperature sensor for monitoring the device temperature.

#### Rev. 0

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## REVISION HISTORY

6/08—Revision 0: Initial Version

# FUNCTIONAL BLOCK DIAGRAM

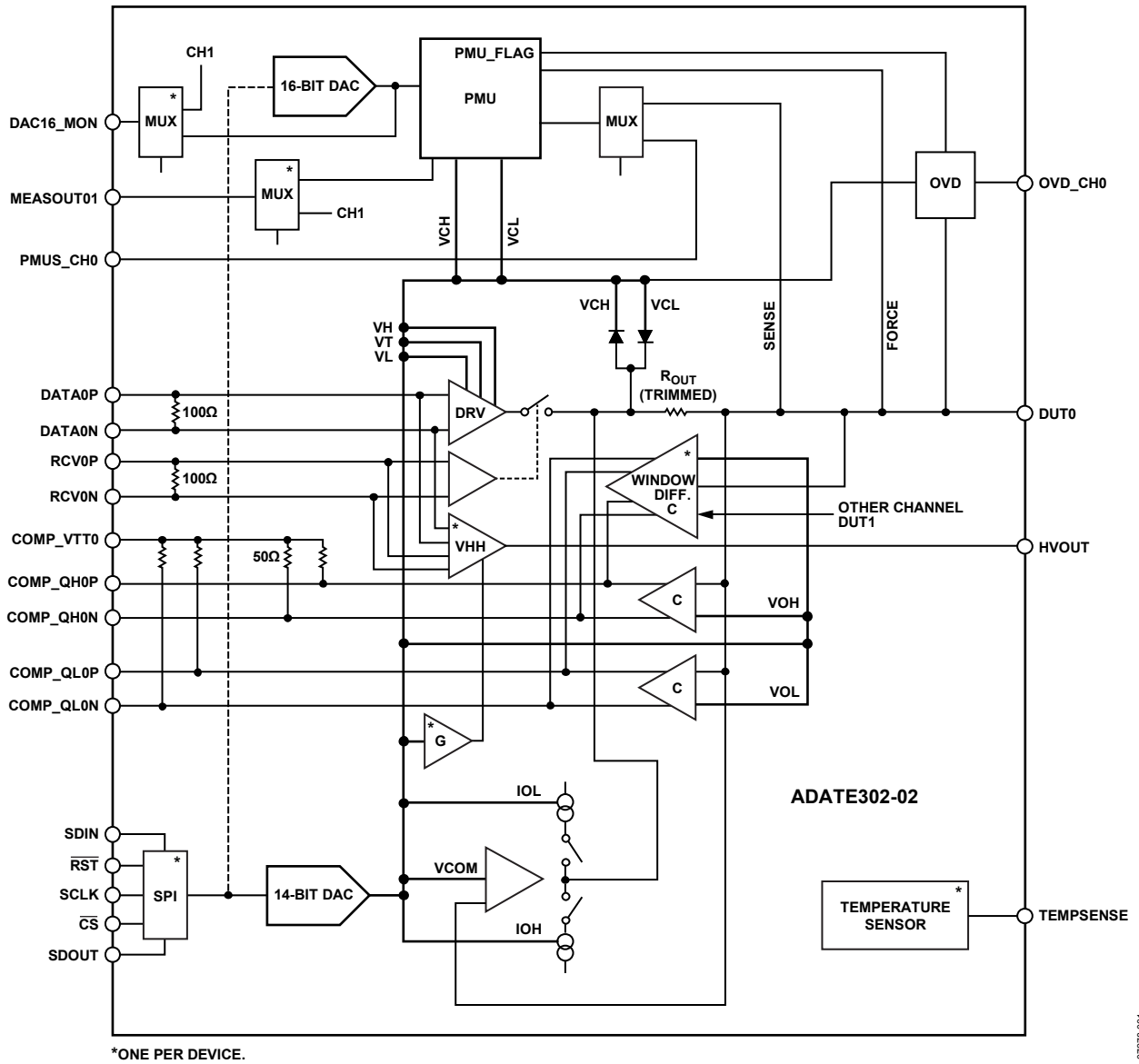


Figure 1. Functional Block Diagram with One of Two Channels Shown

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## SPECIFICATIONS

$V_{DD} = 10.0\text{ V}$ ,  $V_{CC} = 3.3\text{ V}$ ,  $V_{SS} = -5.75\text{ V}$ ,  $V_{PLUS} = 16.75\text{ V}$ ,  $V_{COMP\_VTTX} = 1.5\text{ V}$ ,  $V_{REF} = 5.0\text{ V}$ ,  $V_{REF\_GND} = 0.0\text{ V}$ . All default test conditions are as defined in Table 37. All specified values are at  $T_j = 80^\circ\text{C}$ , where  $T_j$  corresponds to the internal temperature sensor, unless otherwise noted. Temperature coefficients are measured at  $T_j = 80^\circ\text{C} \pm 20^\circ\text{C}$ , unless otherwise noted. Typical values are based on design, simulation analyses, and/or limited bench evaluations. Typical values are not tested or guaranteed. Test levels are specified in the Explanation of Test Levels section.

### TOTAL FUNCTION

Table 1.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
<b>TOTAL FUNCTION</b>						
Output Leakage Current PE Disable, Range E	-20.0	+6.0	+20.0	nA	P	$-2.0\text{ V} < V_{DUTx} < +6.0\text{ V}$ ; PMU and PE disabled via SPI; $V_{CH} = 7.0\text{ V}$ , $V_{CL} = -2.5\text{ V}$
PE Disable, Range A, B, C, D		7.5		nA	$C_T$	$-2.0\text{ V} < V_{DUTx} < +6.0\text{ V}$ ; PMU and PE disabled via SPI; $V_{CH} = 7.0\text{ V}$ , $V_{CL} = -2.5\text{ V}$
High-Z Mode	-400	+15	+400	nA	P	$-2.0\text{ V} < V_{DUTx} < +6.0\text{ V}$ ; PMU disabled and PE enabled via SPI; RCVx pins active, $V_{CH} = 7.0\text{ V}$ , $V_{CL} = -2.5\text{ V}$
Output Capacitance		4		pF	S	VTERM mode operation
DUT Pin Range	-2.0		+6.0	V	D	
<b>POWER SUPPLIES</b>						
Total Supply Range, $V_{PLUS}$ to $V_{SS}$		22.5	23.25	V	D	Defines PSRR conditions
$V_{PLUS}$ Supply, $V_{PLUS}$	16.25	16.75	17.25	V	D	Defines PSRR conditions
Positive Supply, $V_{DD}$	9.5	10.0	10.5	V	D	Defines PSRR conditions
Negative Supply, $V_{SS}$	-6.0	-5.75	-5.5	V	D	Defines PSRR conditions
Logic Supply, $V_{CC}$	3.1	3.3	3.5	V	D	Defines PSRR conditions
Comparator Termination, $V_{COMP\_VTTX}$	1	1.5	3.3	V	D	
$V_{PLUS}$ Supply Current, $I_{PLUS}$	-1.0	+1.3	+4.0	mA	P	HVOUT disabled
$V_{PLUS}$ Supply Current, $I_{PLUS}$	4.0	12.7	17.0	mA	P	HVOUT enabled, RCVx pins active, no load, $V_{HH} = 12\text{ V}$
Logic Supply Current, $I_{CC}$	1.0	2.7	10.0	mA	P	Quiescent (SPI is static)
Comparator Termination Current, $I_{COMP\_VTTX}$	40.0	46	70.0	mA	P	
Positive Supply Current, $I_{DD}$	140.0	190	256.0	mA	P	Load power down ( $I_{OH} = I_{OL} = 0\text{ mA}$ )
	170.0	231	311.0	mA	P	Load active off ( $I_{OH} = I_{OL} = 12\text{ mA}$ )
Negative Supply Current, $I_{SS}$	200.0	272	406.0	mA	P	Load power down ( $I_{OH} = I_{OL} = 0\text{ mA}$ )
	230.0	311	461.0	mA	P	Load active off ( $I_{OH} = I_{OL} = 12\text{ mA}$ )
Total Power Dissipation	2.5	3.55	4.0	W	P	Load power down ( $I_{OH} = I_{OL} = 0\text{ mA}$ )
	3.0	4.2	5.5	W	P	Load active off ( $I_{OH} = I_{OL} = 12\text{ mA}$ )
<b>TEMPERATURE MONITORS</b>						
Temperature Sensor Gain		10		mV/K	$C_T$	
Temperature Sensor Accuracy Without Calibration over $25^\circ\text{C}$ to $100^\circ\text{C}$		6		$^\circ\text{C}$	$C_T$	Temperature voltage available on Pin A1 at all times and on Pin K1 when selected (see Table 24 and Table 36)
<b>VREF INPUT</b>						
Reference Input Voltage Range for DACs (VREF Pin)	4.95	5	5.05	V	D	Referenced to $V_{REF\_GND}$ ; not referenced to $V_{DUTGND}$
Input Bias Current		0.08	100	$\mu\text{A}$	P	Tested with 5 V applied

**DRIVER**

VH – VL ≥ 200 mV (to meet dc/ac specifications).

**Table 2.**

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
<b>DC SPECIFICATIONS</b>						
High-Speed Differential Logic Input Characteristics (DATAx, RCvX)						
Input Termination Resistance	92	100	108	Ω	P	Push 6 mA into xP pins, force 1.3 V on xN pins; measure voltage from xP to xN, calculate resistance (V/I)
Input Voltage Differential	0.2		1.0	V	P <sub>F</sub>	
Common-Mode Voltage	0.85		2.35	V	P <sub>F</sub>	
Input Bias Current	-20.0	+4.0	+20.0	μA	P	Each pin tested at 2.85 V and 0.35 V, while other high speed pin left open
Pin Output Characteristics						
Output High Range, VH	-1.9		+6.0	V	D	
Output Low Range, VL	-2.0		+5.9	V	D	
Output Term Range, VT	-2.0		+6.0	V	D	
Functional Amplitude (VH – VL)	0.0	8.0		V	D	Amplitude can be programmed to VH = VL, accuracy specifications apply when VH – VL ≥ 200 mV
DC Output Current Limit Source	75	100	120	mA	P	Driver high, VH = 6.0 V, short DUTx pin to -2.0 V, measure current
DC Output Current Limit Sink	-120	-100	-75	mA	P	Driver low, VL = -2.0 V, short DUTx pin to 6.0 V, measure current
Output Resistance, ±50 mA	45.0	48.5	51.0	Ω	P	Source: driver high, VH = 3.0 V, I <sub>DUTx</sub> = 1 mA and 50 mA; sink: driver low, VL = 0.0 V, I <sub>DUTx</sub> = -1 mA and -50 mA; ΔV <sub>DUTx</sub> /ΔI <sub>DUTx</sub>
<b>ABSOLUTE ACCURACY</b>						
VH tests done with VL = -2.5 V and VT = -2.5 V; VL tests done with VH = 7.5 V and VT = 7.5 V; VT tests done with VL = -2.5 V and VH = 7.5 V; unless otherwise specified						
VH, VL, VT Uncalibrated Accuracy	-300	±75	+300	mV	P	Error measured at calibration points of 0 V and 5 V
VH, VL, VT Offset Tempco		±450		μV/°C	C <sub>T</sub>	Measured at calibration points
VH, VL, VT DNL		±1		mV	C <sub>T</sub>	After two-point gain/offset calibration
VH, VL, VT INL	-10	±2.5	+10	mV	P	After two-point gain/offset calibration; measured over driver output ranges
VH, VL, VT Resolution		0.6	1	mV	P <sub>F</sub>	After two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 0 V and 5 V
DUTGND Voltage Accuracy	-7	±1.3	+7	mV	P	Over ±0.1 V range; measured at end points of VH, VL, and VT functional range
VH, VL, VT Crosstalk		±2		mV	C <sub>T</sub>	VL = -2.0 V: VH = -1.9 V → 6.0 V, VT = -2.0 V → 6.0 V; VH = 6.0 V: VL = -2.0 V → 5.9 V, VT = -2.0 V → 6.0 V; VT = 1.5 V: VL = -2.0 V → 5.9 V, VH = -1.9 V → 6.0 V; dc crosstalk on VL, VH, VT output level when other driver DACs are varied
Overall Voltage Accuracy		±10		mV	C <sub>T</sub>	Sum of INL, crosstalk, DUTGND, and tempco over ±5°C, after gain/offset calibration
VH, VL, VT DC PSRR		±15		mV/V	C <sub>T</sub>	Measured at calibration points
<b>AC SPECIFICATIONS</b>						
Toggle DATAx pins						
Rise/Fall Times						
0.2 V Programmed Swing		683		ps	C <sub>B</sub>	VH = 0.2 V, VL = 0.0 V, terminated; 20% to 80%
1.0 V Programmed Swing		521		ps	C <sub>B</sub>	VH = 1.0 V, VL = 0.0 V, terminated; 20% to 80%
1.8 V Programmed Swing	430	524	630	ps	P/C <sub>B</sub>	VH = 1.8 V, VL = 0.0 V, terminated; 20% to 80%
2.0 V Programmed Swing		531		ps	C <sub>B</sub>	VH = 2.0 V, VL = 0.0 V, terminated; 20% to 80%
3.0 V Programmed Swing		589		ps	C <sub>B</sub>	VH = 3.0 V, VL = 0.0 V, terminated; 20% to 80%
3.0 V Programmed Swing		811		ps	C <sub>B</sub>	VH = 3.0 V, VL = 0.0 V, unterminated; 10% to 90%
5.0 V Programmed Swing		1105		ps	C <sub>B</sub>	VH = 5.0 V, VL = 0.0 V, unterminated; 10% to 90%
Rise to Fall Matching		6		ps	C <sub>B</sub>	VH = 1.0 V, VL = 0.0 V, terminated; rise to fall within one channel

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Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
Minimum Pulse Width						Toggle DATAx pins
2.0 V Programmed Swing		1.2		ns	C <sub>B</sub>	VH = 2.0 V, VL = 0.0 V, terminated; timing error ±27 ps
		1.2		ns	C <sub>B</sub>	VH = 2.0 V, VL = 0.0 V, terminated; less than 10% amplitude degradation
		1.0		ns	C <sub>B</sub>	VH = 2.0 V, VL = 0.0 V, terminated; less than 20% amplitude degradation
Maximum Toggle Rate		500		MHz	C <sub>B</sub>	VH = 2.0 V, VL = 0.0 V, terminated, 18% amplitude degradation
Dynamic Performance, Drive (VH to VL and VL to VH)						Toggle DATAx pins
Propagation Delay Time		2.1		ns	C <sub>B</sub>	VH = 2.0 V, VL = 0.0 V, terminated
Propagation Delay Tempco		4.5		ps/°C	C <sub>T</sub>	VH = 2.0 V, VL = 0.0 V, terminated
Delay Matching						VH = 2.0 V, VL = 0.0 V, terminated
Edge to Edge		41		ps	C <sub>B</sub>	Rising vs. falling
Channel to Channel		±15		ps	C <sub>B</sub>	Rising vs. rising, falling vs. falling
Delay Change vs. Duty Cycle		±30		ps	C <sub>B</sub>	VH = 3.0 V, VL = 0.0 V, terminated; 5% to 95% duty cycle; 1 MHz
Overshoot and Undershoot		48		mV	C <sub>B</sub>	VH = 3.0 V, VL = 0.0 V, terminated
Settling Time (VH to VL)						Toggle DATAx pins
To Within 3% of Final Value		1.2		ns	C <sub>B</sub>	VH = 3.0 V, VL = 0.0 V, terminated
To Within 1% of Final Value		14		ns	C <sub>B</sub>	VH = 3.0 V, VL = 0.0 V, terminated
Dynamic Performance, VTERM (VH or VL to VT and VT to VH or VL)						Toggle RCVx pins
Propagation Delay Time		2.7		ns	C <sub>B</sub>	VH = 3.0 V, VT = 1.5 V, VL = 0.0 V, terminated
Delay Matching, Edge to Edge		59		ps	C <sub>B</sub>	VH = 3.0 V, VT = 1.5 V, VL = 0.0 V, terminated; rising vs. falling
Propagation Delay Tempco		5.5		ps/°C	C <sub>T</sub>	VH = 3.0 V, VT = 1.5 V, VL = 0.0 V, terminated
Transition Time, Active to VT, VT to Active		0.614		ns	C <sub>B</sub>	VH = 3.0 V, VT = 1.5 V, VL = 0.0 V, terminated; 20% to 80%
Dynamic Performance, Inhibit (VH or VL to/from Inhibit)						Toggle RCVx pins
Propagation Delay Time						VH = +1.0 V, VL = -1.0 V, terminated
Active to Inhibit		2.7		ns	C <sub>B</sub>	
Inhibit to Active		3.7		ns	C <sub>B</sub>	
Transition Time						VH = +1.0 V, VL = -1.0 V, terminated; 20% to 80%
Active to Inhibit		1.3		ns	C <sub>B</sub>	
Inhibit to Active		0.4		ns	C <sub>B</sub>	
I/O Spike		157		mV	C <sub>B</sub>	VH = 0.0 V, VL = 0.0 V, terminated

## REFLECTION CLAMP

Clamp accuracy specifications apply when VCH > VCL.

Table 3.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
VCH						
Range	-1.0		+6.0	V	D	
Uncalibrated Accuracy	-200	±45	+200	mV	P	Driver high-Z, sinking 1 mA; VCH error measured at calibration points of 0 V and 5 V
Resolution		0.6	0.75	mV	P <sub>F</sub>	Driver high-Z, sinking 1 mA; after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 0 V and 5 V
DNL		±1		mV	C <sub>T</sub>	Driver high-Z, sinking 1 mA; after two-point gain/offset calibration
INL	-40	±2	+40	mV	P	Driver high-Z, sinking 1 mA; after two-point gain/offset calibration; measured over VCH range of -1 V to +6 V
Tempco		-0.5		mV/°C	C <sub>T</sub>	Measured at calibration points

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
VCL						
Range	-2		+5.0	V	D	
Uncalibrated Accuracy	-200	±70	+200	mV	P	Driver high-Z, sourcing 1 mA; VCL error measured at calibration points of 0 V and 5 V
Resolution		0.6	0.75	mV	P <sub>F</sub>	Driver high-Z, sourcing 1 mA; after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 0 V and 5 V
DNL		±1		mV	C <sub>T</sub>	Driver high-Z, sourcing 1 mA; after two-point gain/offset calibration
INL	-40	±2	+40	mV	P	Driver high-Z, sourcing 1 mA; after two-point gain/offset calibration; measured over VCL range of -2 V to +5 V
Tempco		0.6		mV/°C	C <sub>T</sub>	Measured at calibration points
DC CLAMP CURRENT LIMIT						
VCH	-120	-83	-60	mA	P	Driver high-Z, VCH = 0 V, VCL = -2.0 V, V <sub>DUTx</sub> = 5 V
VCL	60	86	120	mA	P	Driver high-Z, VCH = 6.0 V, VCL = 5.0 V, V <sub>DUTx</sub> = 0.0 V
DUTGND VOLTAGE ACCURACY	-7	±1	+7	mV	P	Over ±0.1 V range; measured at the end points of VCH and VCL functional range

**NORMAL WINDOW COMPARATOR**

VOH tests done with VOL = -2.0 V, VOL tests done with VOH = 6.0 V, unless otherwise specified.

**Table 4.**

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
DC SPECIFICATIONS						
Input Voltage Range	-2.0		+6.0	V	D	
Differential Voltage Range	±0.1		±8.0	V	D	
Comparator Input Offset Voltage Accuracy, Uncalibrated	-150	±30	+150	mV	P	Offset measured at calibration points of 0 V and 5 V
Comparator Threshold Resolution		0.61	1	mV	P <sub>F</sub>	After two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 0 V and 5 V
Comparator Threshold DNL		±1		mV	C <sub>T</sub>	After two-point gain/offset calibration
Comparator Threshold INL	-7	±1.2	+7	mV	P	After two-point gain/offset calibration; measured over VOH, VOL range of -2.0 V to +6.0 V
Comparator Input Offset Voltage Tempco		±200		µV/°C	C <sub>T</sub>	Measured at calibration points
DUTGND Voltage Accuracy	-7	±0.5	+7	mV	P	Over ±0.1 V range; measured at end points of VOH and VOL functional range
Comparator Uncertainty Range		5.3		mV	C <sub>B</sub>	V <sub>DUTx</sub> = 0 V, sweep comparator threshold to determine uncertainty region
DC Hysteresis		0.5		mV	C <sub>B</sub>	V <sub>DUTx</sub> = 0 V
DC PSRR		±5		mV/V	C <sub>T</sub>	Measured at calibration points
Digital Output Characteristics						
Internal Pull-Up Resistance to Comparator, COMP_VTTx Pin	46	50	54	Ω	P	Pull 1 mA and 10 mA from Logic 1 leg and measure ΔV to calculate resistance; measured ΔV/9 mA; done for both comparator logic states
V <sub>COMP_VTTx</sub> Range	1	1.5	3.3	V	D	
Common-Mode Voltage		V <sub>COMP_VTTx</sub> - 0.3		V	C <sub>T</sub>	Measured with 100 Ω differential termination
		V <sub>COMP_VTTx</sub> - 0.5	V <sub>COMP_VTTx</sub>	V	P	Measured with no external termination
Differential Voltage		250		mV	C <sub>T</sub>	Measured with 100 Ω differential termination
	450	500	550	mV	P	Measured with no external termination
Rise/Fall Time, 20% to 80%		222		ps	C <sub>B</sub>	Measured with each comparator leg terminated 50 Ω to GND

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Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
AC SPECIFICATIONS						
Propagation Delay, Input to Output		1.4		ns	C <sub>B</sub>	Input transition time = 600 ps, 10% to 90%; measured with each comparator leg terminated 50 Ω to GND; unless otherwise specified V <sub>DUTX</sub> = 0 V to 1.0 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.5 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.5 V
Propagation Delay Tempco		4		ps/°C	C <sub>T</sub>	V <sub>DUTX</sub> = 0 V to 1.0 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.5 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.5 V
Propagation Delay Matching						V <sub>DUTX</sub> = 0 V to 1.0 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.5 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.5 V
High Transition to Low Transition		39		ps	C <sub>B</sub>	
High to Low Comparator		±30		ps	C <sub>B</sub>	
Propagation Delay Change with Respect to						
Slew Rate, 600 ps and 1 ns (10% to 90%)		19		ps	C <sub>B</sub>	V <sub>DUTX</sub> = 0 V to 0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.25 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.25 V
Overdrive, 250 mV and 1.0 V		65		ps	C <sub>B</sub>	For 250 mV: V <sub>DUTX</sub> = 0 V to 0.5 V swing; for 1.0 V: V <sub>DUTX</sub> = 0 V to 1.25 V swing; driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.25 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.25 V; input transition time = 400 ps (10%/90%)
Pulse Width, 1 ns, 5 ns, 10 ns, and 15 ns		27		ps	C <sub>B</sub>	V <sub>DUTX</sub> = 0 V to 1.0 V swing @ 32.0 MHz, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.5 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.5 V; input transition time = 400 ps (10%/90%)
Duty Cycle, 5% to 95%		11.8		ps	C <sub>B</sub>	V <sub>DUTX</sub> = 0 V to 1.0 V swing @ 1.0 MHz, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.5 V, VOL = -2.0 V; low-side measurement: VOH = 6.0 V, VOL = 0.5 V; input transition time = 400 ps (10%/90%)
Minimum Pulse Width		1		ns	C <sub>B</sub>	V <sub>DUTX</sub> = 0 V to 1.0 V swing, driver VTERM mode, VT = 0.0 V; less than 10% amplitude degradation measured by shmoo; input transition time = 400 ps (10%/90%)
Input Equivalent Bandwidth, Terminated		1000		MHz	C <sub>B</sub>	V <sub>DUTX</sub> = 0 V to 1.0 V swing, driver VTERM mode, VT = 0.0 V; as measured by shmoo; input transition time = 400 ps (10%/90%)
ERT High-Z Mode, 3 V, 20% to 80%		0.9		ns	C <sub>B</sub>	V <sub>DUTX</sub> = 0 V to 3.0 V swing, driver high-Z; as measured by shmoo

## DIFFERENTIAL COMPARATOR

VOH tests done with VOL = -1.1 V, VOL tests done with VOH = 1.1 V, unless otherwise specified.

Table 5.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
DC SPECIFICATIONS						
Input Voltage Range	-1.5		+4.5	V	D	
Operational Differential Voltage Range	±0.05		±1.1	V	D	
Maximum Differential Voltage Range			±8	V	D	
Comparator Input Offset Voltage Accuracy, Uncalibrated	-150	±25	+150	mV	P	Offset measured at differential calibration points of +1 V and -1 V, with common mode = 0 V



Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
VOH, VOL Resolution		0.61	1	mV	P <sub>F</sub>	After two-point gain/offset calibration; range/number of DAC bits as measured at differential calibration points of +1 V and -1 V, with common mode = 0 V
VOH, VOL DNL		±1		mV	C <sub>T</sub>	After two-point gain/offset calibration; common mode = 0 V
VOH, VOL INL	-7	±1.0	+7	mV	P	After two-point gain/offset calibration; measured over VOH, VOL range of -1.1 V to +1.1 V, common mode = 0 V
VOH, VOL Offset Voltage Tempco		±200		µV/°C	C <sub>T</sub>	Measured at calibration points
Comparator Uncertainty Range		18		mV	C <sub>B</sub>	V <sub>DUTx</sub> = 0 V, sweep comparator threshold to determine uncertainty region
DC Hysteresis		0.5		mV	C <sub>B</sub>	V <sub>DUTx</sub> = 0 V
CMRR			1	mV/V	P	Offset measured at common-mode voltage points of -1.5 V and +4.5 V, with differential voltage = 0 V
DC PSRR		±15		mV/V	C <sub>T</sub>	Measured at calibration points
<b>AC SPECIFICATIONS</b>						
Propagation Delay, Input to Output		1.4		ns	C <sub>B</sub>	Input transition time = 600 ps, 10% to 90%, measured with each comparator leg terminated 50 Ω to GND V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
Propagation Delay Tempco		4		ps/°C	C <sub>T</sub>	V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
Propagation Delay Matching						V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
High Transition to Low Transition		27		ps	C <sub>B</sub>	
High to Low Comparator		±32		ps	C <sub>B</sub>	
Propagation Delay Change with Respect to						V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
Slew Rate, 400 ps and 1 ns (10% to 90%)		25		ps	C <sub>B</sub>	V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
Overdrive, 250 mV and 750 mV		79		ps	C <sub>B</sub>	V <sub>DUT0</sub> = 0 V, for 250 mV: V <sub>DUT1</sub> = 0 V to 0.5 V swing; for 750 mV: V <sub>DUT1</sub> = 0 V to 1.0 V swing, driver VTERM mode, VT = 0.0 V; VOH = -0.25 V; repeat for other DUT channel with comparator threshold = 0.25 V
Pulse Width, 1 ns, 5 ns, 10 ns, and 15 ns		56		ps	C <sub>B</sub>	V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing @ 32 MHz, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
Duty Cycle, 5% to 95%		16		ps	C <sub>B</sub>	V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing @ 32 MHz, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; repeat for other DUT channel
Minimum Pulse Width		1		ns	C <sub>B</sub>	V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; less than 10% amplitude degradation measured by shmoo; repeat for other DUT channel
Input Equivalent Bandwidth, Terminated		500		MHZ	C <sub>B</sub>	V <sub>DUT0</sub> = 0 V, V <sub>DUT1</sub> = -0.5 V to +0.5 V swing, driver VTERM mode, VT = 0.0 V; high-side measurement: VOH = 0.0 V, VOL = -1.1 V; low-side measurement: VOH = 1.1 V, VOL = 0.0 V; less than 22% amplitude degradation measured by shmoo; repeat for other DUT channel

## ACTIVE LOAD

See Table 29 for load control information.

**Table 6.**

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
DC SPECIFICATIONS						
Load active on, RCVx pins active, unless otherwise noted						
Input Characteristics						
VCOM Voltage Range	-1.75		+5.75	V	D	
V <sub>DUTx</sub> Range	-2.0		+6.0	V	D	
VCOM Accuracy, Uncalibrated	-200	±25	+200	mV	P	IOH = IOL = 6 mA, VCOM error measured at calibration points of 0 V and 5 V
VCOM Resolution		0.61	1	mV	P <sub>F</sub>	IOH = IOL = 6 mA, after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 0 V and 5 V
VCOM DNL		±1		mV	C <sub>T</sub>	IOH = IOL = 6 mA, after two-point gain/offset calibration
VCOM INL	-7	±2	+7	mV	P	IOH = IOL = 6 mA, after two-point gain/offset calibration; measured over VCOM range of -1.75 V to +5.75 V
DUTGND Voltage Accuracy	-7	±1	+7	mV	P	Over ±0.1 V range; measured at end points of VCOM functional range
Output Characteristics						
IOL						
Maximum Source Current	12			mA	D	
Uncalibrated Offset	-600.0	±100	+600.0	µA	P	IOH = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 0.0 V, IOL offset calculated from calibration points of 1 mA and 11 mA
Uncalibrated Gain	-12	±1	+12	%	P	IOH = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 0.0 V, IOL gain calculated from calibration points of 1 mA and 11 mA
Resolution		1.5	2	µA	P <sub>F</sub>	IOH = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 0.0 V, after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 1 mA and 11 mA
DNL		±3.0		µA	C <sub>T</sub>	IOH = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 0.0 V, after two-point gain/offset calibration
INL	-70	±20	+70	µA	P	IOH = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 0.0 V, after two-point gain/offset calibration; measured over IOL range of 0 mA to 12 mA
90% Commutation Voltage			0.25	V	P	IOH = IOL = 12 mA, VCOM = 2.0 V, measure IOL reference at V <sub>DUTx</sub> = -1.0 V, measure IOL current at V <sub>DUTx</sub> = 1.75 V, ensure >90% of reference current
IOH						
Maximum Sink Current	12			mA	D	
Uncalibrated Offset	-600.0	±100	+600.0	µA	P	IOL = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 3.0 V, IOH offset calculated from calibration points of 1 mA and 11 mA
Uncalibrated Gain	-12	±1	+12	%	P	IOL = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 3.0 V, IOH gain calculated from calibration points of 1 mA and 11 mA
Resolution		1.5	2	µA	P <sub>F</sub>	IOL = 0 mA, VCOM = 1.5 V, V <sub>DUTx</sub> = 3.0 V, after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 1 mA and 11 mA
DNL		±3.0		µA	C <sub>T</sub>	IOL = 0 mA, VCOM = 1.5V, V <sub>DUTx</sub> = 3.0 V, after two-point gain/offset calibration
INL	-70	±20	+70	µA	P	IOL = 0 mA, VCOM = 1.5V, V <sub>DUTx</sub> = 3.0 V, after two-point gain/offset calibration; measured over IOH range of 0 mA to 12 mA
90% Commutation Voltage			0.25	V	P	IOH = IOL = 12 mA, VCOM = 2.0 V, measure IOH reference at V <sub>DUTx</sub> = 5.0 V, measure IOH current at V <sub>DUTx</sub> = 2.25 V, ensure >90% of reference current
Output Current Tempco		±1.5		µA/°C	C <sub>T</sub>	Measured at calibration points

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
AC SPECIFICATIONS						
Load active on, unless otherwise noted						
Dynamic Performance						
Propagation Delay, Load Active On to Load Active Off; 50%, 90%		4.1		ns	C <sub>B</sub>	Toggle RCVx pins, DUTx terminated 50 Ω to GND, IOH = IOL = 12 mA, VH = VL = 0 V, VCOM = +1.25 V for IOL and VCOM = -1.25 V for IOH; measured from 50% point of RCVxP – RCVxN to 90% point of final output, repeat for drive low and high
Propagation Delay, Load Active Off to Load Active On; 50%, 90%		11		ns	C <sub>B</sub>	Toggle RCVx pins, DUTx terminated 50 Ω to GND, IOH = IOL = 12 mA, VH = VL = 0 V, VCOM = +1.25 V for IOL and VCOM = -1.25 V for IOH; measured from 50% point of RCVxP – RCVxN to 90% point of final output, repeat for drive low and high
Propagation Delay Matching		6.9		ns	C <sub>B</sub>	Toggle RCVx pins, DUTx terminated 50 Ω to GND, IOH = IOL = 12 mA, VH = VL = 0 V, VCOM = +1.25 V for IOL and VCOM = -1.25 V for IOH; active on vs. active off, repeat for drive low and high
Load Spike		156		mV	C <sub>B</sub>	Toggle RCVx pins, DUTx terminated 50 Ω to GND, IOH = IOL = 0 mA, VH = VL = 0 V, VCOM = +1.25 V for IOL and VCOM = -1.25 V for IOH; repeat for drive low and high
Settling Time to 90%		1.6		ns	C <sub>B</sub>	Toggle RCVx pins, DUTx terminated 50 Ω to GND, IOH = IOL = 12 mA, VH = VL = 0 V, VCOM = +1.25 V for IOL and VCOM = -1.25 V for IOH; measured at 90% of final value

**PMU**

FV = force voltage, MV = measure voltage, FI = force current, MI = measure current, FN = force nothing.

Table 7.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
FORCE VOLTAGE (FV)						
Current Range A	±25			mA	D	
Current Range B	±2			mA	D	
Current Range C	±200			μA	D	
Current Range D	±20			μA	D	
Current Range E	±2			μA	D	
Force Input Voltage Range at Output For All Ranges	-2.0		+6.0	V	D	
Force Voltage Uncalibrated Accuracy for Range C	-100	±25	+100	mV	P	PMU enabled, FV, PE disabled, error measured at calibration points of 0 V and 5 V
Force Voltage Uncalibrated Accuracy for All Ranges		±25		mV	C <sub>T</sub>	PMU enabled, FV, PE disabled, error measured at calibration points of 0 V and 5 V; repeat for each PMU current range
Force Voltage Offset Tempco for All Ranges		±25		μV/°C	C <sub>T</sub>	Measured at calibration points for each PMU current range
Force Voltage Gain Tempco for All Ranges		±75		ppm/°C	C <sub>T</sub>	Measured at calibration points for each PMU current range
Forced Voltage INL	-7	±2	+7	mV	P	PMU enabled, FV, Range C, PE disabled, after two-point gain/offset calibration; measured over output range of -2.0 V to +6.0 V
Force Voltage Compliance vs. Current Load						PMU enabled, FV, PE disabled, force -2.0 V, measure voltage while PMU sinking zero- and full-scale current; measure ΔV; force 6.0 V, measure voltage while PMU sourcing zero- and full-scale current; measure ΔV; repeat for each PMU current range
Range A		±4		mV	C <sub>T</sub>	
Range B to Range E		±1		mV	C <sub>T</sub>	

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Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
Current Limit, Source and Sink Range A	108	135	180	% FS	P	PMU enabled, FV, PE disabled; sink: force 2.5 V, short DUTx to 6.0 V; source: force 2.5 V, short DUTx to -1.0 V; Range A FS = 25 mA, 108% FS = 27 mA, 180% FS = 45 mA
Range B to Range E	120	140	180	% FS	P	PMU enabled, FV, PE disabled; sink: force 2.5 V, short DUTx to 6.0 V; source: force 2.5 V, short DUTx to -1.0 V; repeat for each PMU current range; example: Range B FS = 2 mA, 120% FS = 2.4 mA, 180% FS = 3.6 mA
DUTGND Voltage Accuracy	-7	±1	+7	mV	P	Over ±0.1 V range; measured at end points of FV functional range
<b>MEASURE CURRENT (MI)</b>						
Measure Current, Pin DUTx Voltage Range for All Ranges	-2.0		+6.0	V	D	$V_{DUTx}$ externally forced to 0.0 V, unless otherwise specified; ideal MEASOUT transfer functions: $V_{MEASOUT01} [V] = (I_{MEASOUT01} \times 5/FSR) + 2.5 + V_{DUTGND}$ $I_{MEASOUT01} [A] = (V_{MEASOUT01} - V_{DUTGND} - 2.5) \times FSR/5$
Measure Current Uncalibrated Accuracy Range A		±650		µA	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, error at calibration points of -20 mA and 20 mA, error = $(I_{MEASOUT01} - I_{DUTx})$
Range B	-400	±20	+400	µA	P	PMU enabled, FIMI, PE disabled, error at calibration points of -1.6 mA and 1.6 mA, error = $(I_{MEASOUT01} - I_{DUTx})$
Range C		± 2.00		µA	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, error at calibration points of ±80% FS, error = $(I_{MEASOUT01} - I_{DUTx})$
Range D		±0.20		µA	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, error at calibration points of ±80% FS, error = $(I_{MEASOUT01} - I_{DUTx})$
Range E		±0.02		µA	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, error at calibration points of ±80% FS, error = $(I_{MEASOUT01} - I_{DUTx})$
Measure Current Offset Tempco Range A		±2.5		µA/°C	C <sub>T</sub>	Measured at calibration points
Range B		±125		nA/°C	C <sub>T</sub>	Measured at calibration points
Range C		±20		nA/°C	C <sub>T</sub>	Measured at calibration points
Range D and Range E		±4		nA/°C	C <sub>T</sub>	Measured at calibration points
Measure Current Gain Error, Nominal Gain = 1 Range A		-3.5		%	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, gain error from calibration points of ±80% FS
Range B	-20	±2	+20	%	P	PMU enabled, FIMI, PE disabled, gain error from calibration points of ±1.6 mA
Range C to Range E		±2		%	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, gain error from calibration points of ±80% FS
Measure Current Gain Tempco Range A		±300		ppm/°C	C <sub>T</sub>	Measured at calibration points
Range B to Range E		±50		ppm/°C	C <sub>T</sub>	Measured at calibration points
Measure Current INL Range A		±0.05		% FSR	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, after two-point gain/offset calibration, measured over FSR output of -25 mA to +25 mA
Range B	-0.02	±0.005	0.02	% FSR	P	PMU enabled, FIMI, PE disabled, after two-point gain/offset calibration measured over FSR output of -2 mA to +2 mA
Range B to Range E		±0.005		% FSR	C <sub>T</sub>	PMU enabled, FIMI, PE disabled, after two-point gain/offset calibration; measured over FSR output
FVMI DUT Pin Voltage Rejection	-0.01		0.01	% FSR/V	P	PMU enabled, FVMI, PE disabled, force -1 V and +5 V into load of 1 mA; measure ΔI reported at MEASOUT01
DUTGND Voltage Accuracy		±2.5		mV	C <sub>T</sub>	Over ±0.1 V range; measured at end points of MI functional range

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
<b>FORCE CURRENT (FI)</b>						
Force Current, DUTx Pin Voltage Range for All Ranges	-2.0		+6.0	V	D	$V_{DUTx}$ externally forced to 0.0 V, unless otherwise specified Ideal force current transfer function: $I_{FORCE} = (PMUDAC - 2.5) \times (FSR/5)$
Force Current Uncalibrated Accuracy						
Range A	-5.0	±0.5	+5.0	mA	P	PMU enabled, FIMI, PE disabled, error at calibration points of -20 mA and +20 mA
Range B	-400	±40	+400	µA	P	PMU enabled, FIMI, PE disabled, error at calibration points of -1.6 mA and +1.6 mA
Range C	-40	±4	+40	µA	P	PMU enabled, FIMI, PE disabled, error at calibration points of ±80% FS
Range D	-4	±0.4	+4	µA	P	PMU enabled, FIMI, PE disabled, error at calibration points of ±80% FS
Range E	-400	±75	+400	nA	P	PMU enabled, FIMI, PE disabled, error at calibration points of ±80% FS
Force Current Offset Tempco						
Range A		±1		µA/°C	C <sub>T</sub>	Measured at calibration points
Range B		±80		nA/°C	C <sub>T</sub>	Measured at calibration points
Range C to Range E		±4		nA/°C	C <sub>T</sub>	Measured at calibration points
Forced Current Gain Error, Nominal Gain = 1	-20	±4	+20	%	P	PMU enabled, FIMI, PE disabled, gain error from calibration points of ±80% FS
Forced Current Gain Tempco						Measured at calibration points
Range A		-500		ppm/°C	C <sub>T</sub>	
Range B to Range E		±75		ppm/°C	C <sub>T</sub>	
Force Current INL						
Range A	-0.3	±0.05	+0.3	% FSR	P	PMU enabled, FIMI, PE disabled, after two-point gain/offset calibration; measured over FSR output of -25 mA to +25 mA
Range B to Range E	-0.2	±0.015	0.2	% FSR	P	PMU enabled, FIMI, PE disabled, after two-point gain/offset calibration; measured over FSR output
Force Current Compliance vs. Voltage Load						PMU enabled, FIMV, PE disabled; force positive full-scale current driving -2.0 V and +6.0 V, measure ΔI @ DUTx pin; force negative full-scale current driving -2.0 V and +6.0 V, measure ΔI @ DUTx pin
Range A to Range D	-0.6	±0.06	+0.6	% FSR	P	
Range E	-1.0	±±0.1	+1.0	% FSR	P	
<b>MEASURE VOLTAGE</b>						
Measure Voltage Range	-2.0		+6.0	V	D	
Measure Voltage Uncalibrated Accuracy	-25	±2.0	+25	mV	P	PMU enabled, FVMV, Range B, PE disabled, error at calibration points of 0 V and 5 V, error = $(V_{MEASOUT01} - V_{DUTx})$
Measure Voltage Offset Tempco		±10		µV/°C	C <sub>T</sub>	Measured at calibration points
Measure Voltage Gain Error	-2	±0.01	+2	%	P	PMU enabled, FVMV, Range B, PE disabled, gain error from calibration points of 0 V and 5 V
Measure Voltage Gain Tempco		25		ppm/°C	C <sub>T</sub>	Measured at calibration points
Measure Voltage INL	-7	±1	+7	mV	P	PMU enabled, FVMV, Range B, PE disabled, after two-point gain/offset calibration; measured over output range of -2.0 V to +6.0 V
Rejection of Measure V vs. I <sub>DUTx</sub>	-1.5	±0.1	+1.5	mV	P	PMU enabled, FVMV, Range D, PE disabled, force 0 V into load of -10 µA and +10 µA; measure ΔV reported at MEASOUT01

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Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments	
<b>MEASOUT01 DC CHARACTERISTICS</b>							
MEASOUT01 Voltage Range	-2.0		+6.0	V	D	PMU enabled, FVMV, PE disabled; source resistance: PMU force 6.0 V and load with 0 mA and 4 mA; sink resistance: PMU force -2.0 V and load with 0 mA and -4 mA; resistance = $\Delta V/\Delta I$ at MEASOUT01 pin	
DC Output Current			4	mA	D		
MEASOUT01 Pin Output Impedance		25	200	$\Omega$	P		
Output Leakage Current When Tristated	-1		+1	$\mu$ A	P		Tested at -2.0 V and +6.0 V
Output Short-Circuit Current	-25		+25	mA	P		PMU enabled, FVMV, PE disabled; source: PMU force 6.0 V, short MEASOUT01 to -2.0 V; sink: PMU force -2.0 V, short MEASOUT01 to 6.0 V
<b>VOLTAGE CLAMPS</b>							
Low Clamp Range (VCL)	-2.0		+4.0	V	D	PMU enabled, FIMI, Range A, PE disabled, PMU clamps enabled, VCH = 5 V, VCL = -1 V, PMU force 1 mA and 25 mA into open; $\Delta V$ seen at DUTx pin	
High Clamp Range (VCH)	0.0		6.0	V	D		
Positive Clamp Voltage Droop	-300	+50	+300	mV	P		
Negative Clamp Voltage Droop	-300	-50	+300	mV	P		PMU enabled, FIMI, Range A, PE disabled, PMU clamps enabled, VCH = 5 V, VCL = -1 V, PMU force -1 mA and -25 mA into open; $\Delta V$ seen at DUTx pin
Uncalibrated Accuracy	-250	$\pm 100$	+250	mV	P		PMU enabled, FIMI, Range B, PE disabled, PMU damps enabled, PMU force $\pm 1$ mA into open; VCH errors at calibration points of 0 V and 5 V; VCL errors at the calibration points of 0 V and 4 V
INL	-70	$\pm 5$	+70	mV	P		PMU enabled, FIMI, Range B, PE disabled, PMU damps enabled, PMU force $\pm 1$ mA into open; after two-point gain/offset calibration; measured over PMU clamp range
DUTGND Voltage Accuracy		$\pm 1$		mV	C <sub>T</sub>		Over $\pm 0.1$ V range; measured at end points of PMU clamp functional range
<b>SETTLING/SWITCHING TIMES</b>							
Voltage Force Settling Time to 0.1% of Final Value						SCAP = 330 pF, FFCAP = 220 pF PMU enabled, FV, PE disabled, program PMUDAC steps of 500 mV and 5.0 V; simulation of worst case, 2000 pF load, PMUDAC step of 5.0 V	
Range A, 200 pF and 2000 pF Load		15		$\mu$ s	S	PMU enabled, FV, PE disabled, start with PMUDAC programmed to 0.0 V, program PMUDAC to 500 mV	
Range B, 200 pF and 2000 pF Load		20		$\mu$ s	S		
Range C, 200 pF and 2000 pF Load		124		$\mu$ s	S		
Range D, 200 pF and 2000 pF Load		1015		$\mu$ s	S		
Range E, 200 pF and 2000 pF Load		3455		$\mu$ s	S		
Voltage Force Settling Time to 1.0% of Final Value							
Range A, 200 pF and 2000 pF Load		8.0		$\mu$ s	C <sub>B</sub>		
Range B, 200 pF and 2000 pF Load		8.0		$\mu$ s	C <sub>B</sub>		
Range C, 200 pF and 2000 pF Load		8.0		$\mu$ s	C <sub>B</sub>		
Range D, 200 pF Load		8.1		$\mu$ s	C <sub>B</sub>		
Range D, 2000 pF Load		585		$\mu$ s	C <sub>B</sub>		
Range E, 200 pF Load		8.1		$\mu$ s	C <sub>B</sub>		
Range E, 2000 pF Load		590		$\mu$ s	C <sub>B</sub>		

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
Voltage Force Settling Time to 1.0% of Final Value						PMU enabled, FV, PE disabled, start with PMUDAC programmed to 0.0 V, program PMUDAC to 5.0 V
Range A, 200 pF and 2000 pF Load		4.2		μs	C <sub>B</sub>	
Range B, 200 pF Load		4.4		μs	C <sub>B</sub>	
Range B, 2000 pF Load		7.6		μs	C <sub>B</sub>	
Range C, 200 pF Load		6.3		μs	C <sub>B</sub>	
Range C, 2000 pF Load		8.1		μs	C <sub>B</sub>	
Range D, 200 pF Load		130		μs	C <sub>B</sub>	
Range D, 2000 pF Load		280		μs	C <sub>B</sub>	
Range E, 200 pF Load		390		μs	C <sub>B</sub>	
Range E, 2000 pF Load		605		μs	C <sub>B</sub>	
Current Force Settling Time to 0.1% of Final Value						PMU enabled, FI, PE disabled, start with PMUDAC programmed to 0 current, program PMUDAC to FS current
Range A, 200 pF in Parallel with 120 Ω		8.2		μs	S	
Range B, 200 pF in Parallel with 1.5 kΩ		9.4		μs	S	
Range C, 200 pF in Parallel with 15.0 kΩ		30		μs	S	
Range D, 200 pF in Parallel with 150 kΩ		281		μs	S	
Range E, 200 pF in Parallel with 1.5 MΩ		2668		μs	S	
Current Force Settling Time to 1.0% of Final Value						PMU enabled, FI, PE disabled, start with PMUDAC programmed to 0 current, program PMUDAC to FS current
Range A, 200 pF in Parallel with 120 Ω		3.3		μs	C <sub>B</sub>	
Range B, 200 pF in Parallel with 1.5 kΩ		4.4		μs	C <sub>B</sub>	
Range C, 200 pF in Parallel with 15.0 kΩ		8		μs	C <sub>B</sub>	
Range D, 200 pF in Parallel with 150 kΩ		205		μs	C <sub>B</sub>	
Range E, 200 pF in Parallel with 1.5 MΩ		505		μs	C <sub>B</sub>	
INTERACTION AND CROSSTALK						
Measure Voltage Channel-to-Channel Crosstalk		±0.125		% FSR	C <sub>T</sub>	PMU enabled, FIMV, PE disabled, Range B, forcing 0 mA into 0 V load; other channel: Range A, forcing a step of 0 mA to 25 mA into 0 V load; report ΔV of MEASOUT01 pin under test; 0.125% × 8.0 V = 10 mV
Measure Current Channel-to-Channel Crosstalk		±0.01		% FSR	C <sub>T</sub>	PMU enabled, FVMI, PE disabled, Range E, forcing 0 V into 0 mA current load; other channel: Range E, forcing a step of 0 V to 5 V into 0 mA current load; report ΔV of MEASOUT01 pin under test; 0.01% × 5.0 V = 0.5 mV

**EXTERNAL SENSE (PMUS\_CHx)**

Table 8.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
Voltage Range	-2.0		+6.0	V	D	
Input Leakage Current	-20		+20	nA	P	Tested at -2.0 V and +6.0 V

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## DUTGND INPUT

Table 9.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
Input Voltage Range, Referenced to GND	-0.1		+0.1	V	D	
Input Bias Current		1	100	μA	P	Tested at -100 mV and +100 mV

## SERIAL PERIPHERAL INTERFACE

Table 10.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
Serial Input Logic High	1.8		V <sub>CC</sub>	V	P <sub>F</sub>	
Serial Input Logic Low	0		0.7	V	P <sub>F</sub>	
Input Bias Current	-10	+1	+10	μA	P	Tested at 0.0 V and 3.3 V
SCLK Clock Rate		50		MHz	P <sub>F</sub>	
SCLK Pulse Width		9		ns	C <sub>T</sub>	
SCLK Crosstalk on DUTx Pin		8		mV	C <sub>B</sub>	PE disabled, PMU FV enabled and forcing 0 V
Serial Output Logic High	V <sub>CC</sub> - 0.4		V <sub>CC</sub>	V	P <sub>F</sub>	Sourcing 2 mA
Serial Output Logic Low	0		0.8	V	P <sub>F</sub>	Sinking 2 mA
Update Time		10		μs	D	Maximum delay time required for the part to enter a stable state after a serial bus command is loaded

## HVOUT DRIVER

Table 11.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
VHH BUFFER						VHH = (VT + 1 V) × 2 + DUTGND
Voltage Range	5.9		V <sub>PLUS</sub> - 3.25	V	D	V <sub>PLUS</sub> = 16.75 V nominal; in this condition, V <sub>HVOUT</sub> maximum = 13.5 V
Output High	13.5			V	P	VHH mode enabled, RCVx pins active, VHH level = full scale, sourcing 15 mA
Output Low			5.9	V	P	VHH mode enabled, RCVx pins active, VHH level = zero scale, sinking 15 mA
Accuracy Uncalibrated	-500	±100	+500	mV	P	VHH mode enabled, RCVx pins active, V <sub>HVOUT</sub> error measured at calibration points of 7 V and 12 V
Offset Tempco		1		mV/°C	C <sub>T</sub>	Measured at calibration points
Resolution		1.21	1.5	mV	P <sub>F</sub>	VHH mode enabled, RCVx pins active, after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 7 V and 12 V
INL	-30	±15	+30	mV	P	VHH mode enabled, RCVx pins active, after two-point gain/offset calibration; measured over VHH range of 5.9 V to 13.5 V
DUTGND Voltage Accuracy		±1		mV	C <sub>T</sub>	Over ±0.1 V range; measured at end points of VHH functional range
Output Resistance		1	10	Ω	P	VHH mode enabled, RCVx pins active, source: VHH = 10.0 V, I <sub>HVOUT</sub> = 0 mA and 15 mA; sink: VHH = 6.5 V, I <sub>HVOUT</sub> = 0 mA and -15 mA; ΔV/ΔI
DC Output Current Limit Source	60		100	mA	P	VHH mode enabled, RCVx pins active, VHH = 10.0 V, short HVOUT pin to 5.9 V, measure current
DC Output Current Limit Sink	-100		-60	mA	P	VHH mode enabled, RCVx pins active, VHH = 6.5 V, short HVOUT pin to 14.1 V, measure current
Rise Time (From VL or VH to VHH)		175		ns	C <sub>B</sub>	VHH mode enabled, toggle RCVx pins, VHH = 13.5 V, VL = VH = 3.0 V; 20% to 80%, for DATAx high and DATAx low
Fall Time (From VHH to VL or VH)		23		ns	C <sub>B</sub>	VHH mode enabled, toggle RCVx pins, VHH = 13.5 V, VL = VH = 3.0 V; 20% to 80%, for DATAx high and DATAx low
Preshoot, Overshoot, and Undershoot		±100		mV	C <sub>B</sub>	VHH mode enabled, toggle RCVx pins, VHH = 13.5 V, VL = VH = 3.0 V; for DATAx high and DATAx low



Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
VL/VH BUFFER						
Voltage Range	-0.1		+6.0	V	D	
Accuracy Uncalibrated	-500	±100	+500	mV	P	VHH mode enabled, RCVx pins inactive, error measured at calibration points of 0 V and 5 V
Offset Tempco		1		mV/°C	C <sub>T</sub>	Measured at calibration points
Resolution		0.61	0.75	mV	P <sub>F</sub>	VHH mode enabled, RCVx pins inactive, after two-point gain/offset calibration; range/number of DAC bits as measured at calibration points of 0 V and 5 V
INL	-20	±4	+20	mV	P	VHH mode enabled, RCVx pins inactive, after two-point gain/offset calibration; measured over range of -0.1 V to +6.0 V
DUTGND Voltage Accuracy		±2		mV	C <sub>T</sub>	Over ±0.1 V range; measured at end points of VH and VL, functional range
Output Resistance	46	48	50	Ω	P	VHH mode enabled, RCVx pins inactive, source: VH = 3.0 V, I <sub>HVOUT</sub> = 1 mA and 50 mA; sink: VL = 2.0 V, I <sub>HVOUT</sub> = -1 mA and -50 mA; ΔV/ΔI
DC Output Current Limit Source	60		100	mA	P	VHH mode enabled, RCVx pins inactive, VH = 6.0 V, short HVOUT pin to -0.1 V, DATAx high, measure current
DC Output Current Limit Sink	-100		-60	mA	P	VHH mode enabled, RCVx pins inactive, VL = -0.1 V, short HVOUT pin to 6.0 V, DATAx low, measure current
Rise Time (VL to VH)		10.0		ns	C <sub>B</sub>	VHH mode enabled, RCVx pins inactive, VL = 0.0 V, VH = 3.0 V, toggle DATAx pins; 20% to 80%
Fall Time (VH to VL)		11.3		ns	C <sub>B</sub>	VHH mode enabled, RCVx pins inactive, VL = 0.0 V, VH = 3.0 V, toggle DATAx pins; 20% to 80%
Preshoot, Overshoot, and Undershoot		±54		mV	C <sub>B</sub>	VHH mode enabled, RCVx pins inactive, VL = 0.0 V, VH = 3.0 V, toggle DATAx pins

**OVERVOLTAGE DETECTOR (OVD)**

Table 12.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
DC CHARACTERISTICS						
Programmable Voltage Range	-3.0		+7.0	V	D	
Accuracy Uncalibrated	-200		+200	mV	P	OVD offset errors measured at programmed levels of 7.0 V and -3.0 V
Hysteresis		112		mV	C <sub>B</sub>	
LOGIC OUTPUT CHARACTERISTICS						
Off State Leakage		10	1000	nA	P	Disable OVD alarm, apply 3.3 V to OVD_CHx pin, measure leakage current
Maximum On Voltage @100 μA		0.2	0.7	V	P	Activate alarm, force 100 μA into OVD_CHx, measure active alarm voltage
Propagation Delay		1.8		μs	C <sub>B</sub>	For OVD high: DUTx = 0 V to 6 V swing, OVD_CHx high = 3.0 V, OVD_CHx low = -3.0 V; for OVD_CHx low: DUTx = 0 V to 6 V swing, OVD_CHx high = 7.0 V, OVD_CHx low = 3.0 V

**16-BIT DAC MONITOR MUX**

Table 13.

Parameter	Min	Typ	Max	Unit	Test Level	Conditions/Comments
DC CHARACTERISTICS						
Programmable Voltage Range	-2.5		+7.5	V	D	
Output Resistance		16		kΩ	C <sub>T</sub>	PMUDAC = 0.0 V, FV, I = 0 μA, 200 μA; ΔV/ΔI

## ABSOLUTE MAXIMUM RATINGS

Table 14.

Parameter	Rating
Supply Voltages	
Positive Supply Voltage ( $V_{DD}$ to GND)	-0.5 V to +11.0 V
Positive $V_{CC}$ Supply Voltage ( $V_{CC}$ to GND)	-0.5 V to +4.0 V
Negative Supply Voltage ( $V_{SS}$ to GND)	-6.25 V to +0.5 V
Supply Voltage Difference ( $V_{DD}$ to $V_{SS}$ )	-1.0 V to +16.5 V
Reference Ground (DUTGND to GND)	-0.5 V to +0.5 V
AGND to DGND	-0.5 V to +0.5 V
VPLUS Supply Voltage ( $V_{PLUS}$ to GND)	-0.5 V to +17.5 V
Input Voltages	
Input Common-Mode Voltage	$V_{SS}$ to $V_{DD}$
Short-Circuit Voltage <sup>1</sup>	-3.0 V to +8.0 V
High Speed Input Voltage <sup>2</sup>	0 to $V_{CC}$
High Speed Differential Input Voltage <sup>3</sup>	0 to $V_{CC}$
VREF	-0.5 V to +5.5 V
DUTx I/O Pin Current	
DCL Maximum Short-Circuit Current <sup>4</sup>	±140 mA
Temperature	
Operating Temperature, Junction	125°C
Storage Temperature Range	-65°C to +150°C

<sup>1</sup>  $R_L = 0 \Omega$ ,  $V_{DUTx}$  continuous short-circuit condition (VH, VL, VT, high-Z, VCOM, clamp modes).

<sup>2</sup> DATAxP, DATAxN, RCVxP, RCVxN, under source  $R = 0 \Omega$ .

<sup>3</sup> DATAxP to DATAxN, RCVxP, RCVxN.

<sup>4</sup>  $R_L = 0 \Omega$ ,  $V_{DUTx} = -3 V$  to +8 V; DCL current limit. Continuous short-circuit condition. ADATE302-02 must current limit and survive continuous short circuit.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL RESISTANCE

Table 15. Thermal Resistance

Package Type	$\theta_{JA}$	$\theta_{JC}$	Unit
84-Ball CSP_BGA	31.1	0.51	°C/W

## EXPLANATION OF TEST LEVELS

D	Definition
S	Design verification simulation
P	100% production tested
P <sub>F</sub>	Functionally checked during production test
C <sub>T</sub>	Characterized on tester
C <sub>B</sub>	Characterized on bench

## ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

	10	9	8	7	6	5	4	3	2	1
A	HVOUT	PMUS_CH0	VSSO_0 (DRIVE)	DUT0	VDDO_0 (DRIVE)	VDDO_1 (DRIVE)	DUT1	VSSO_1 (DRIVE)	PMUS_CH1	TEMPSENSE
B	VPLUS	SCAP0	VSS	AGND	VDD	VDD	AGND	VSS	SCAP1	VDD/VDD_TMPSENS
C	FFCAP_0B	AGND	DATA0N	VSS	VDD	VDD	VSS	DATA1N	AGND	FFCAP_1B
D	OVD_CH0	VDD	DATA0P					DATA1P	VDD	OVD_CH1
E	FFCAP_0A	VSS	RCV0N					RCV1N	VSS	FFCAP_1A
F	AGND	AGND	RCV0P					RCV1P	AGND	AGND
G	COMP_QL0P	COMP_QL0N	COMP_VTT0					COMP_VTT1	COMP_QL1N	COMP_QL1P
H	COMP_QH0P	COMP_QH0N	AGND	VSS	VDD	VDD	VSS	AGND	COMP_QH1N	COMP_QH1P
J	AGND	AGND	AGND	RST	SDIN	DGND	DAC16_MON	AGND	AGND	AGND
K	VREF_GND	VREF	AGND	VCC	SCLK	SDOUT	CS	AGND	DUTGND	MEASOUT01/TEMPSENSE

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Figure 2. Pin Configuration, Bottom Side (BGA Balls Are Visible)

Table 16. Pin Function Descriptions

BGA Designator	Mnemonic	Description
A1	TEMPSENSE	Temperature Sense Output
A2	PMUS_CH1	PMU External Sense Path Channel 1
A3	VSSO_1 (Drive)	Driver Output Supply -5.75 V Channel 1
A4	DUT1	Device Under Test Channel 1
A5	VDDO_1 (Drive)	Driver Output Supply +10.0 V Channel 1
A6	VDDO_0 (Drive)	Driver Output Supply +10.0 V Channel 0
A7	DUT0	Device Under Test Channel 0
A8	VSSO_0 (Drive)	Driver Output Supply -5.75 V Channel 0
A9	PMUS_CH0	PMU External Sense Path Channel 0
A10	HVOUT	High Voltage Driver Output
B1	VDD/VDD_TMPSENS	Temperature Sense Supply +10.0 V
B2	SCAP1	PMU Stability Capacitor Connection Channel 1 (330 pF)

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BGA Designator	Mnemonic	Description
B3	VSS	Supply -5.75 V
B4	AGND	Analog Ground
B5	VDD	Supply +10.0 V
B6	VDD	Supply +10.0 V
B7	AGND	Analog Ground
B8	VSS	Supply -5.75 V
B9	SCAPO	PMU Stability Capacitor Connection Channel 0 (330 pF)
B10	VPLUS	Supply +16.75 V
C1	FFCAP_1B	PMU Feedforward Capacitor Connection B Channel 1 (220 pF)
C2	AGND	Analog Ground
C3	DATA1N	Driver Data Input (Negative) Channel 1
C4	VSS	Supply -5.75 V
C5	VDD	Supply +10.0 V
C6	VDD	Supply +10.0 V
C7	VSS	Supply -5.75 V
C8	DATA0N	Driver Data Input (Negative) Channel 0
C9	AGND	Analog Ground
C10	FFCAP_0B	PMU Feedforward Capacitor Connection B Channel 0 (220 pF)
D1	OVD_CH1	Overvoltage Detection Flag Output Channel 1
D2	VDD	Supply +10.0 V
D3	DATA1P	Driver Data Input (Positive) Channel 1
D8	DATA0P	Driver Data Input (Positive) Channel 0
D9	VDD	Supply +10.0 V
D10	OVD_CH0	Overvoltage Detection Flag Output Channel 0
E1	FFCAP_1A	PMU Feedforward Capacitor Connection A Channel 1 (220 pF)
E2	VSS	Supply -5.75 V
E3	RCV1N	Receive Data Input (Negative) Channel 1
E8	RCV0N	Receive Data Input (Negative) Channel 0
E9	VSS	Supply -5.75 V
E10	FFCAP_0A	PMU Feedforward Capacitor Connection A Channel 0 (220 pF)
F1	AGND	Analog Ground
F2	AGND	Analog Ground
F3	RCV1P	Receive Data Input (Positive) Channel 1
F8	RCV0P	Receive Data Input (Positive) Channel 0
F9	AGND	Analog Ground
F10	AGND	Analog Ground
G1	COMP_QL1P	Low-Side Comparator Output (Positive) Channel 1
G2	COMP_QL1N	Low-Side Comparator Output (Negative) Channel 1
G3	COMP_VTT1	Comparator Supply Termination Channel 1
G8	COMP_VTT0	Comparator Supply Termination Channel 0
G9	COMP_QL0N	Low-Side Comparator Output (Negative) Channel 0
G10	COMP_QL0P	Low-Side Comparator Output (Positive) Channel 0
H1	COMP_QH1P	High-Side Comparator Output (Positive) Channel 1
H2	COMP_QH1N	High-Side Comparator Output (Negative) Channel 1
H3	AGND	Analog Ground
H4	VSS	Supply -5.75 V
H5	VDD	Supply +10.0 V
H6	VDD	Supply +10.0 V
H7	VSS	Supply -5.75 V
H8	AGND	Analog Ground
H9	COMP_QH0N	High-Side Comparator Output (Negative) Channel 0
H10	COMP_QH0P	High-Side Comparator Output (Positive) Channel 0
J1	AGND	Analog Ground

<b>BGA Designator</b>	<b>Mnemonic</b>	<b>Description</b>
J2	AGND	Analog Ground
J3	AGND	Analog Ground
J4	DAC16_MON	16-Bit DAC Monitor Mux Output
J5	DGND	Digital Ground
J6	SDIN	Serial Peripheral Interface (SPI) Data In
J7	$\overline{\text{RST}}$	Serial Peripheral Interface (SPI) Reset
J8	AGND	Analog Ground
J9	AGND	Analog Ground
J10	AGND	Analog Ground
K1	MEASOUT01/TEMPSENSE	Muxed Output Shared by PMU MEASOUT Channel 0, PMU MEASOUT Channel 1, Temperature Sense and Temperature Sense GND Reference
K2	DUTGND	DUT Ground Reference
K3	AGND	Analog Ground
K4	$\overline{\text{CS}}$	Serial Peripheral Interface (SPI) Chip Select
K5	SDOUT	Serial Peripheral Interface (SPI) Data Out
K6	SCLK	Serial Peripheral Interface (SPI) Clock
K7	VCC	Supply +3.3 V
K8	AGND	Analog Ground
K9	VREF	+5 V DAC Reference Voltage
K10	VREF_GND	DAC Ground Reference

TYPICAL PERFORMANCE CHARACTERISTICS

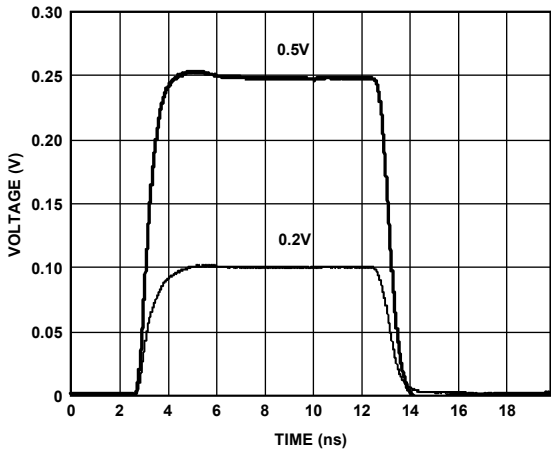


Figure 3. Driver Small Signal Response;  $V_H = 0.2\text{ V}, 0.5\text{ V}; V_L = 0.0\text{ V}; 50\ \Omega$  Termination

07Z78-080

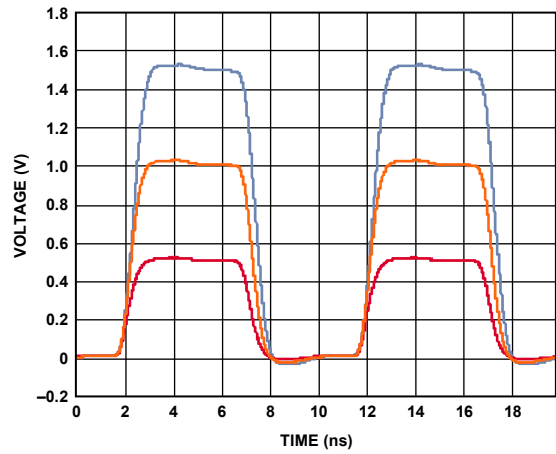


Figure 6. 100 MHz Driver Response;  $V_H = 1.0\text{ V}, 2.0\text{ V}, 3.0\text{ V}; V_L = 0.0\text{ V}; 50\ \Omega$  Termination

07Z78-085

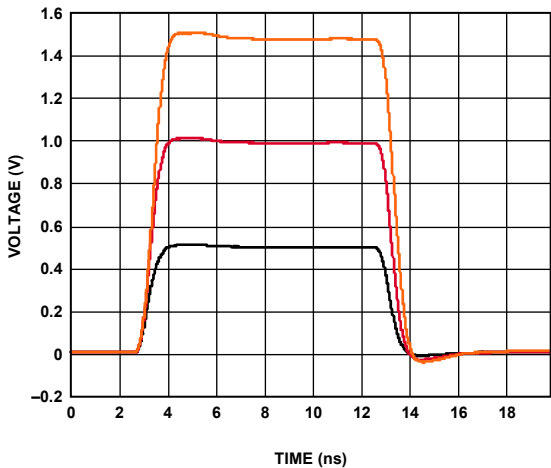


Figure 4. Driver Large Signal Response;  $V_H = 1.0\text{ V}, 2.0\text{ V}, 3.0\text{ V}; V_L = 0.0\text{ V}; 50\ \Omega$  Termination

07Z78-079

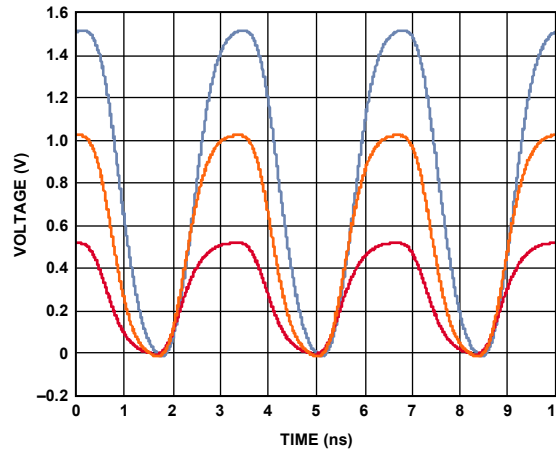


Figure 7. 300 MHz Driver Response;  $V_H = 1.0\text{ V}, 2.0\text{ V}, 3.0\text{ V}; V_L = 0.0\text{ V}; 50\ \Omega$  Termination

07Z78-084

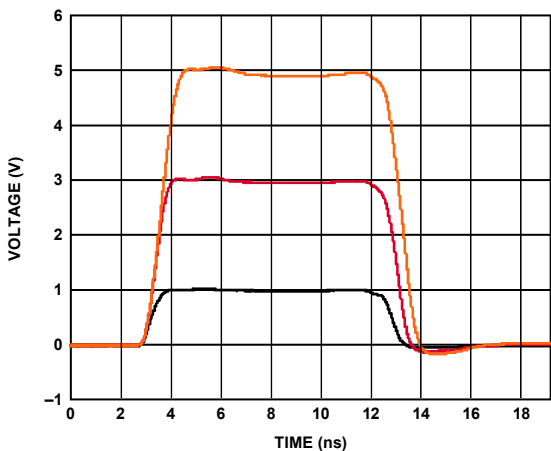


Figure 5. Driver Large Signal Response;  $V_H = 1.0\text{ V}, 3.0\text{ V}, 5.0\text{ V}; V_L = 0.0\text{ V}; 500\ \Omega$  Termination

07Z78-078

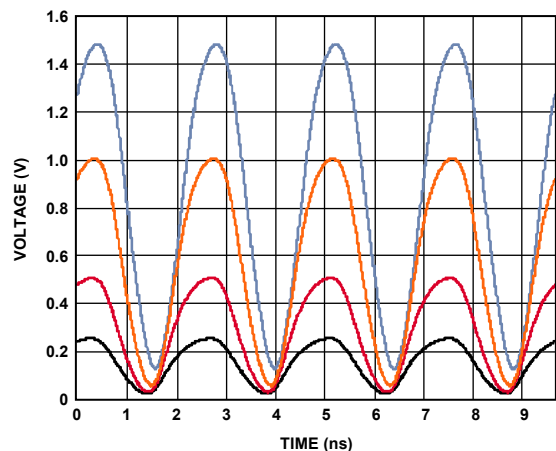


Figure 8. 400 MHz Driver Response;  $V_H = 0.5\text{ V}, 1.0\text{ V}, 2.0\text{ V}, 3.0\text{ V}; V_L = 0.0\text{ V}; 50\ \Omega$  Termination

07Z78-083

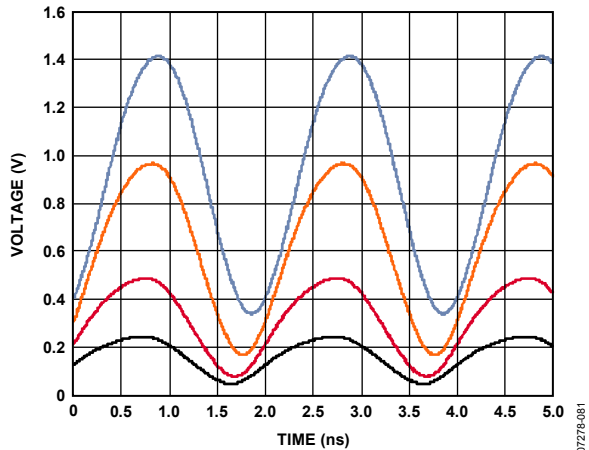


Figure 9. 500 MHz Driver Response;  $V_H = 0.5\text{ V}, 1.0\text{ V}, 2.0\text{ V}, 3.0\text{ V}$ ;  $V_L = 0.0\text{ V}$ ;  $50\ \Omega$  Termination

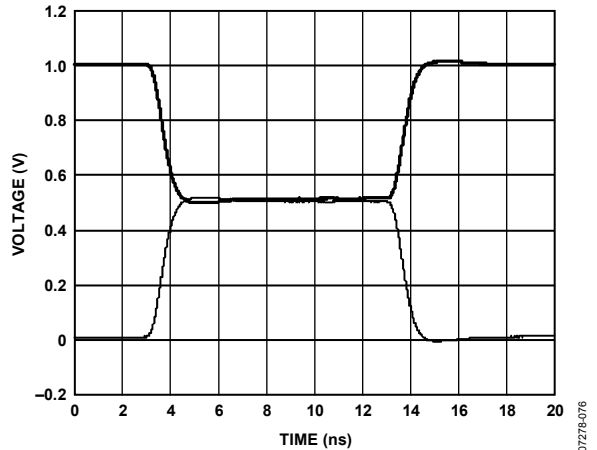


Figure 12. Driver Active ( $V_H/V_L$ ) to/from  $V_{TERM}$  Transition;  $V_H = 2.0\text{ V}$ ;  $V_T = 1.0\text{ V}$ ;  $V_L = 0.0\text{ V}$

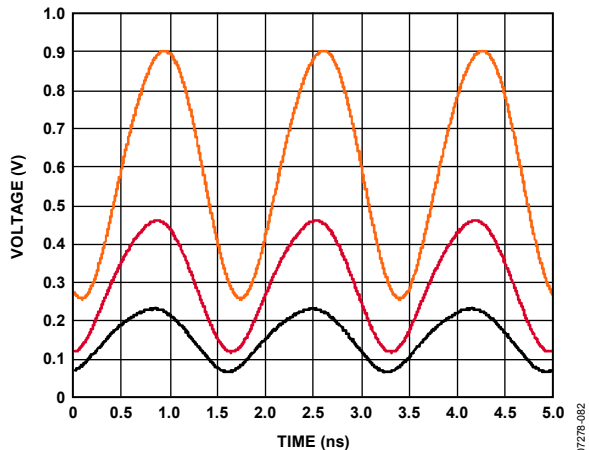


Figure 10. 600 MHz Driver Response;  $V_H = 0.5\text{ V}, 1.0\text{ V}, 2.0\text{ V}$ ;  $V_L = 0.0\text{ V}$ ;  $50\ \Omega$  Termination

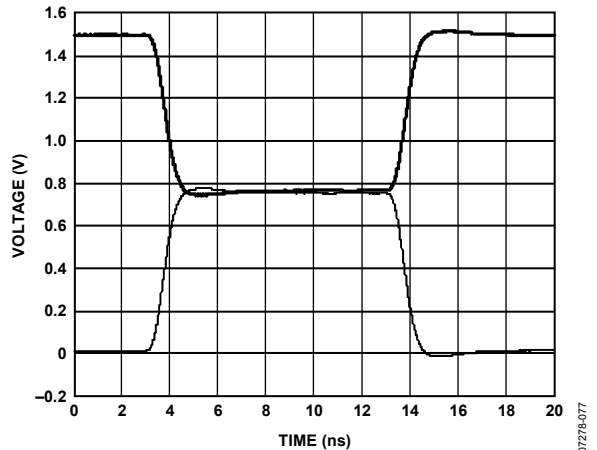


Figure 13. Driver Active ( $V_H/V_L$ ) to/from  $V_{TERM}$  Transition;  $V_H = 3.0\text{ V}$ ;  $V_T = 1.5\text{ V}$ ;  $V_L = 0.0\text{ V}$

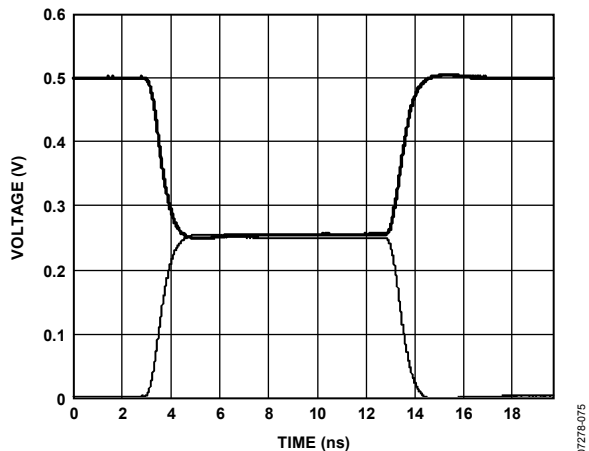


Figure 11. Driver Active ( $V_H/V_L$ ) to/from  $V_{TERM}$  Transition;  $V_H = 1.0\text{ V}$ ;  $V_T = 0.5\text{ V}$ ;  $V_L = 0.0\text{ V}$

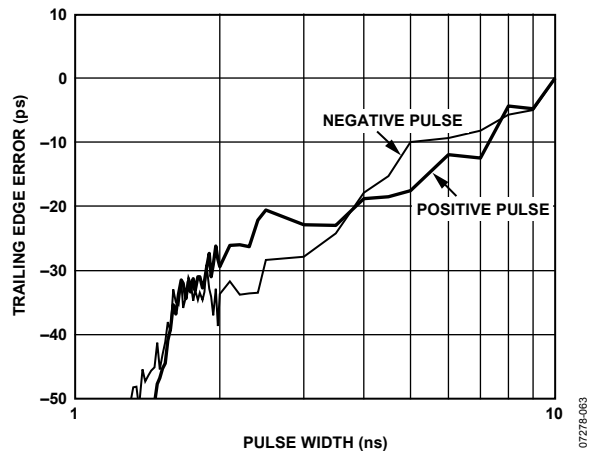


Figure 14. Driver Minimum Pulse Width;  $V_H = 0.2\text{ V}$ ;  $V_L = 0.0\text{ V}$

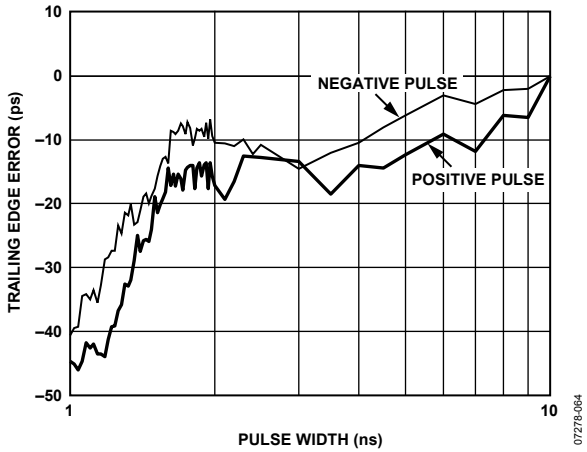


Figure 15. Driver Minimum Pulse Width;  
 $V_H = 0.5\text{ V}$ ;  $V_L = 0.0\text{ V}$

07278-064

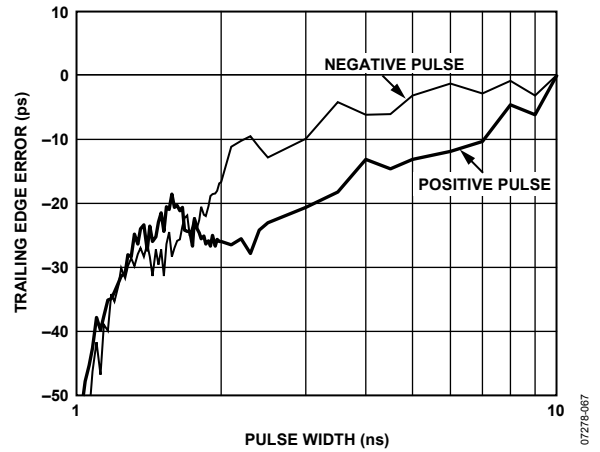


Figure 18. Driver Minimum Pulse Width;  
 $V_H = 3.0\text{ V}$ ;  $V_L = 0.0\text{ V}$

07278-067

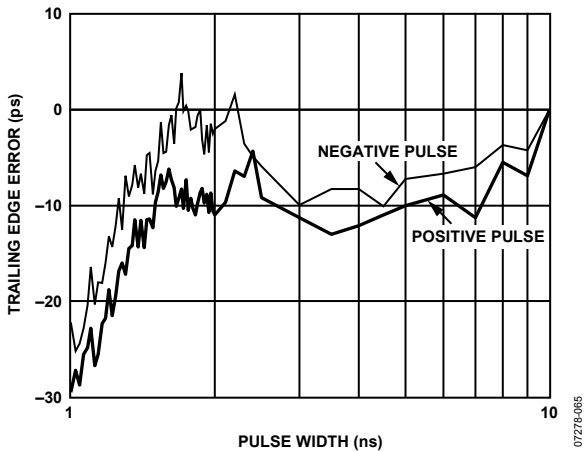


Figure 16. Driver Minimum Pulse Width;  
 $V_H = 1.0\text{ V}$ ;  $V_L = 0.0\text{ V}$

07278-065

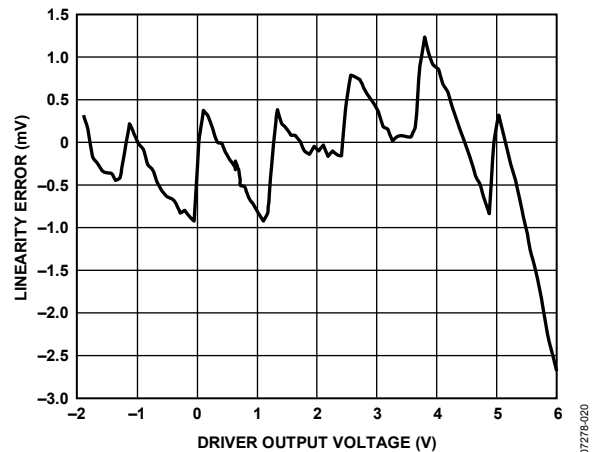


Figure 19. Driver  $V_H$  Linearity Error

07278-020

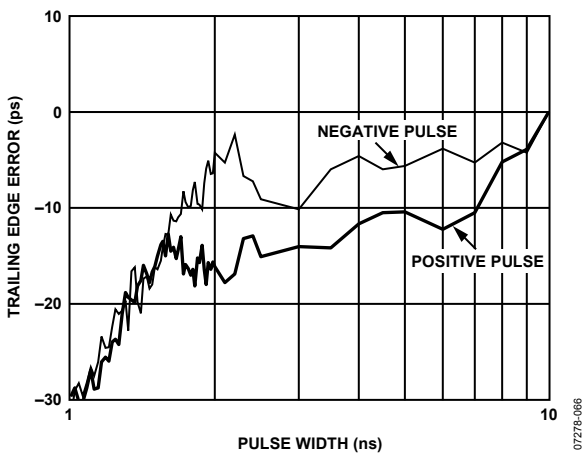


Figure 17. Driver Minimum Pulse Width;  
 $V_H = 2.0\text{ V}$ ;  $V_L = 0.0\text{ V}$

07278-066

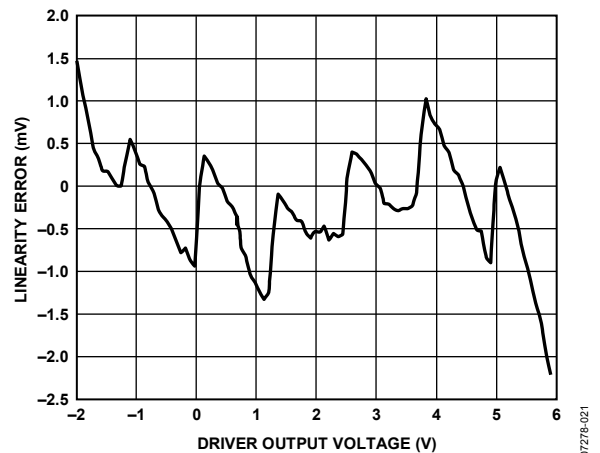


Figure 20. Driver  $V_L$  Linearity Error

07278-021



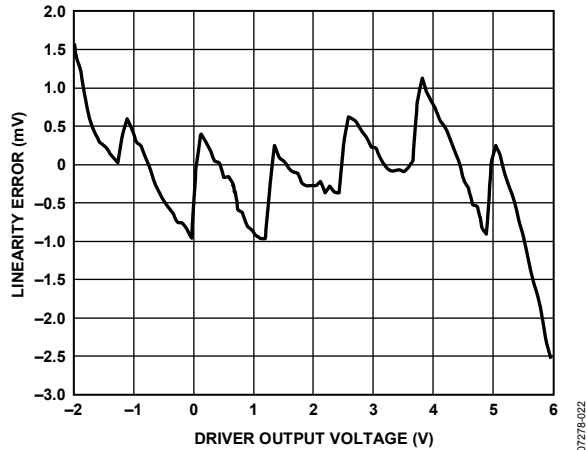


Figure 21. Driver VT Linearity Error

07278-022

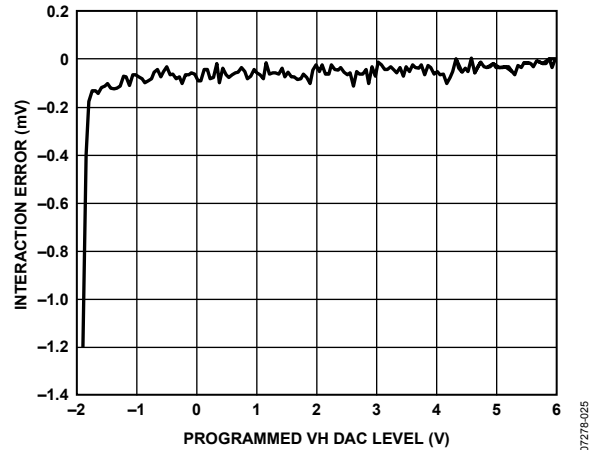


Figure 24. Driver Interaction Error;  
VL = -2.0 V; VH Swept from -1.9 V to +6.0 V

07278-025

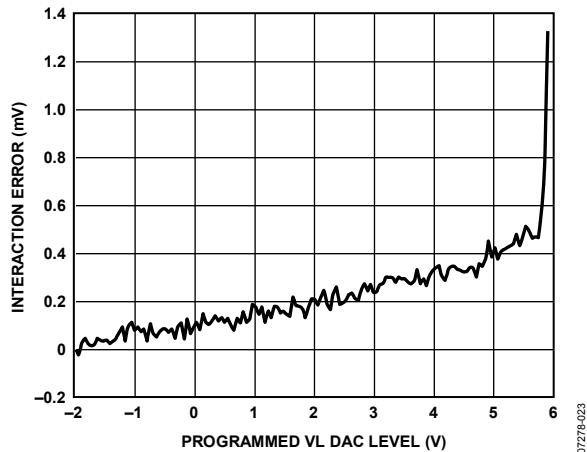


Figure 22. Driver Interaction Error;  
VH = 6.0 V; VL Swept from -2.0 V to +5.9 V

07278-023

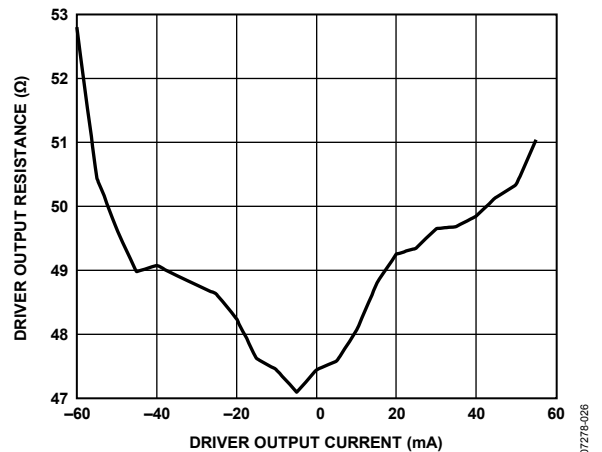


Figure 25. Driver Output Resistance vs. Output Current

07278-026

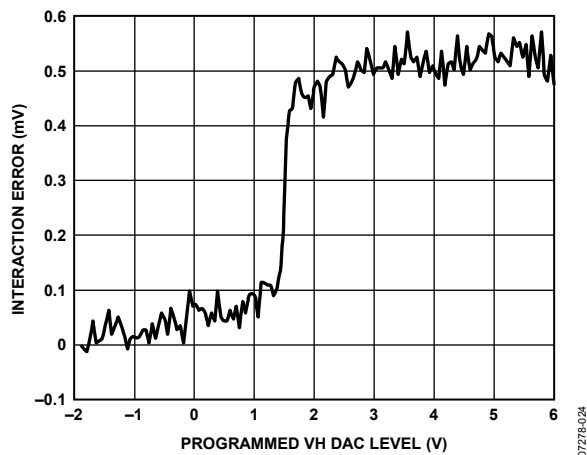


Figure 23. Driver Interaction Error;  
VT = 1.5 V; VH Swept from -1.9 V to +6.0 V

07278-024

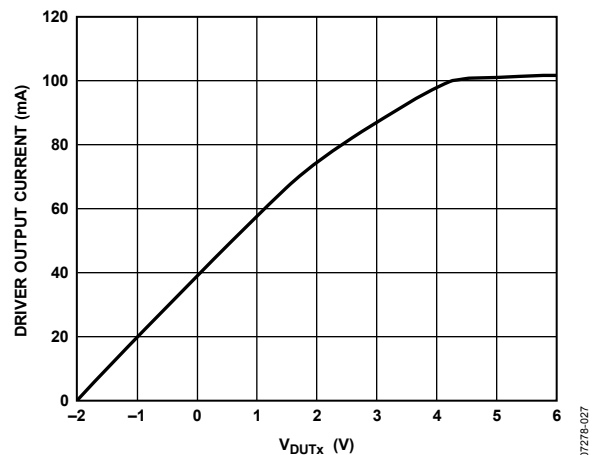


Figure 26. Driver Output Current Limit;  
Driver Programmed to -2.0 V; V<sub>DUTx</sub> Swept from -2.0 V to +6.0 V

07278-027

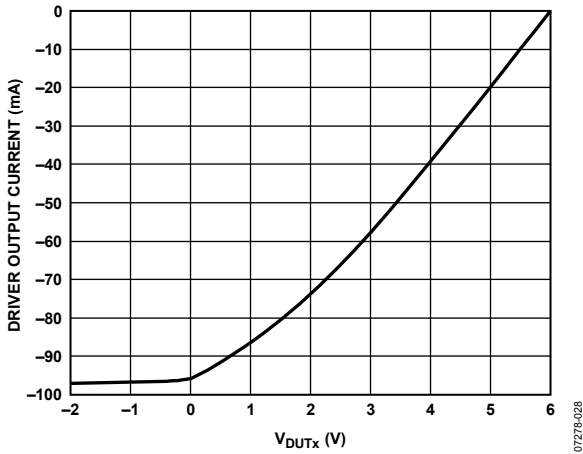


Figure 27. Driver Output Current Limit; Driver Programmed to 6.0 V;  $V_{DUTx}$  Swept from  $-2.0$  V to  $+6.0$  V

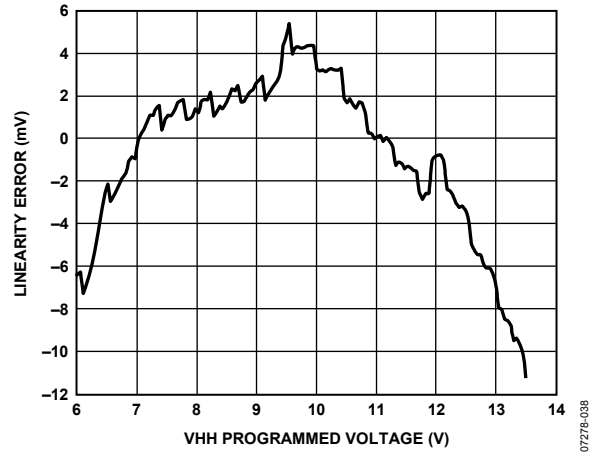


Figure 30. HVOUT VHH Linearity Error

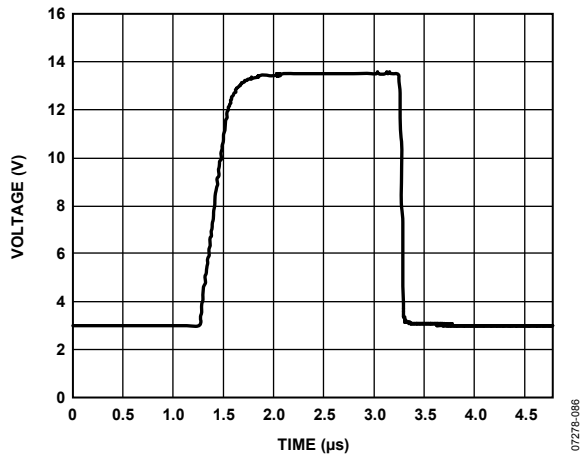


Figure 28. HVOUT VHH Response;  $V_{HH} = 13.5$  V

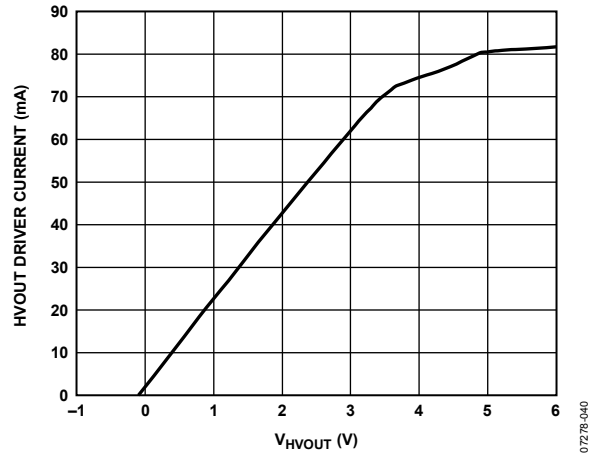


Figure 31. HVOUT VH Current Limit;  $V_H = -0.1$  V;  $V_{HVOUT}$  Swept from  $-0.1$  V to  $+6.0$  V

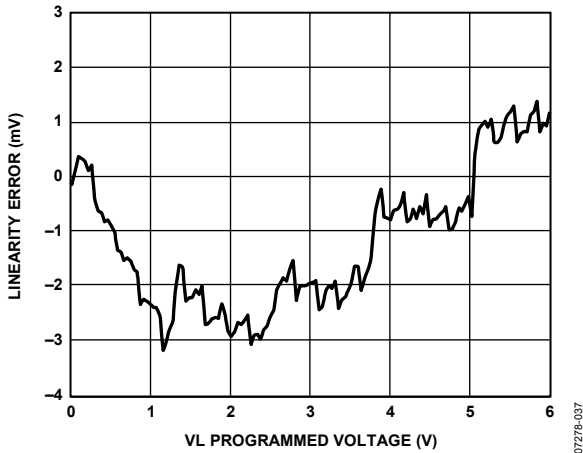


Figure 29. HVOUT VL Linearity Error

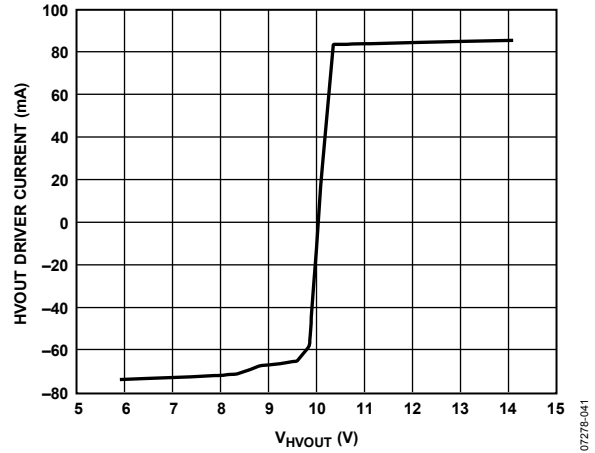


Figure 32. HVOUT VHH Current Limit;  $V_{HH} = 10.0$  V;  $V_{HVOUT}$  Swept from  $5.9$  V to  $14.1$  V

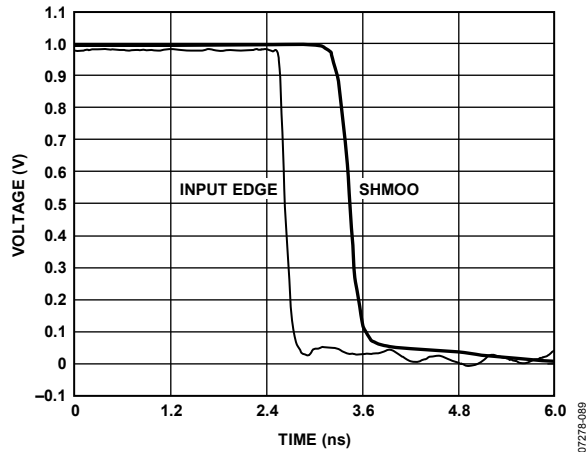


Figure 33. Comparator Shmoo; 1.0 V Swing; 200 ps (10%/90%)

07276-089

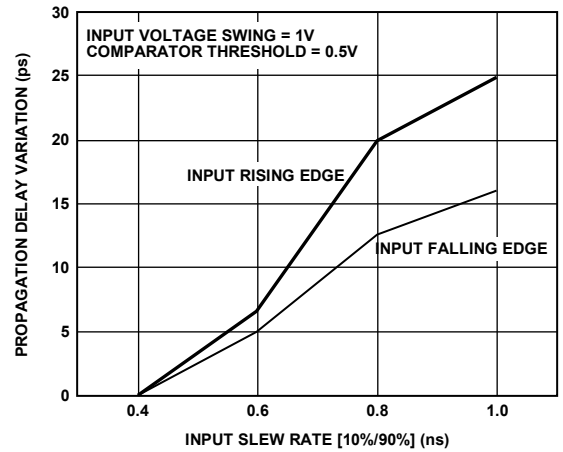


Figure 36. Comparator Slew Rate Dispersion

07276-087

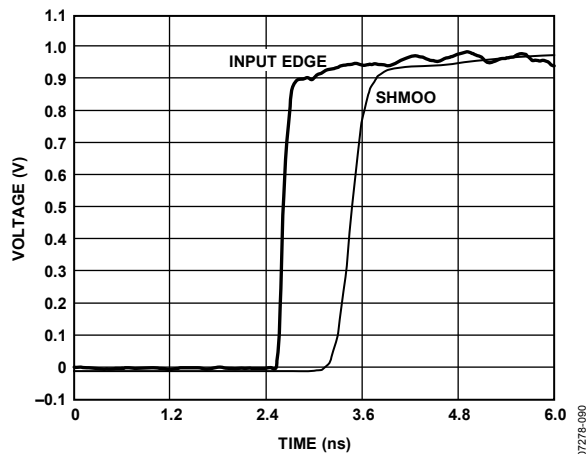


Figure 34. Comparator Shmoo; 1.0 V Swing; 200 ps (10%/90%)

07276-090

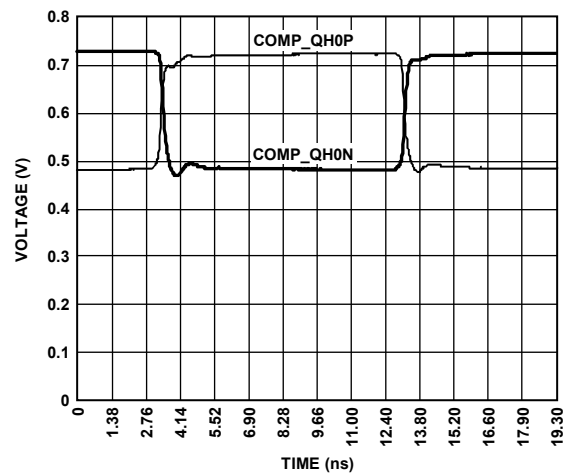


Figure 37. Comparator Output Waveform; COMP\_QH0P, COMP\_QH0N

07276-088

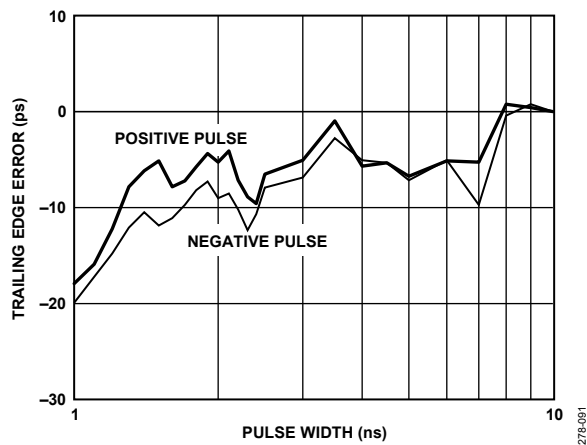


Figure 35. Comparator Minimum Pulse Width Input; 1.0 V Swing; 200 ps (10%/90%)

07276-091

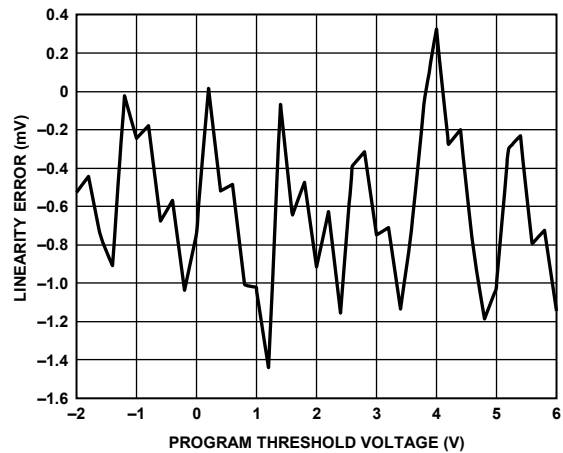


Figure 38. Comparator Threshold Linearity

07276-029

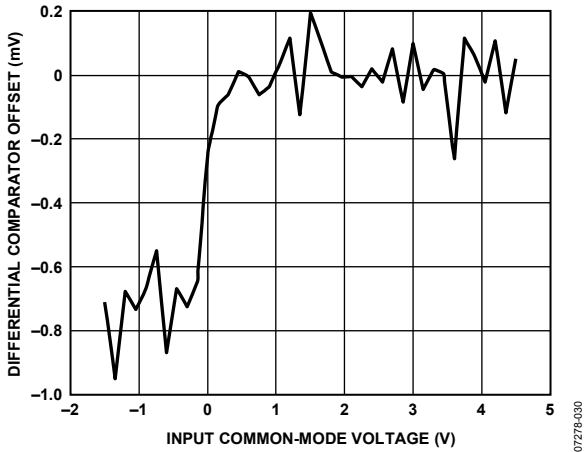


Figure 39. Differential Comparator CMRR

07278-030

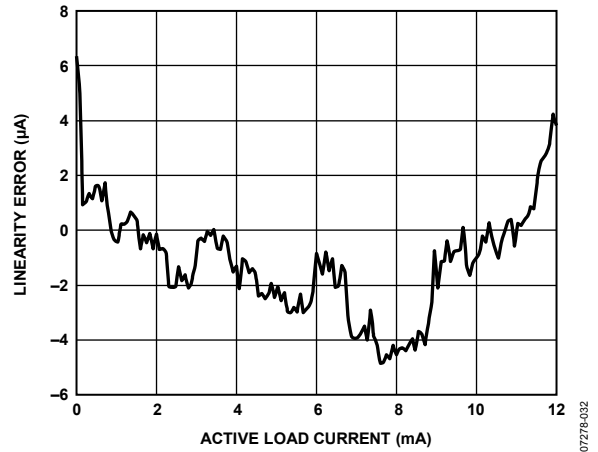


Figure 42. Active Load Current Linearity

07278-032

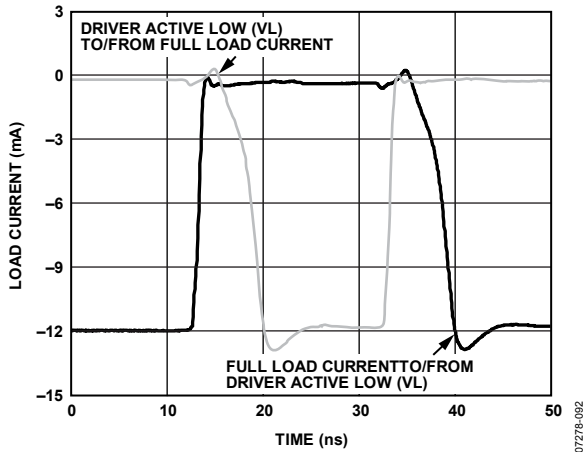


Figure 40. Active Load Response

07278-002

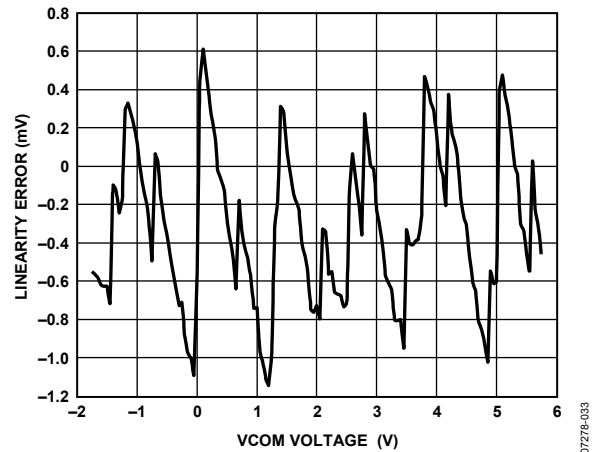


Figure 43. Active Load VCOM Linearity

07278-033

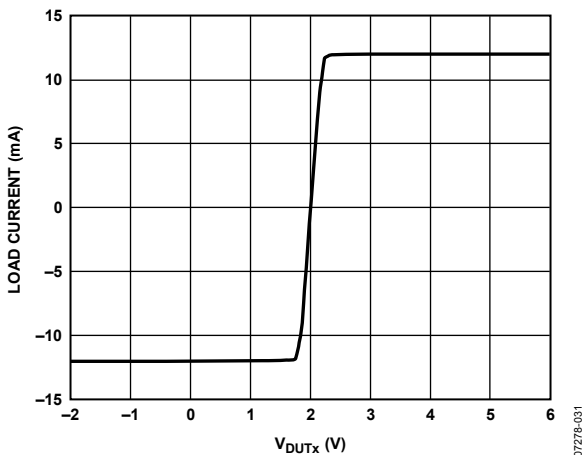


Figure 41. Active Load Commutation Response;  
VCOM = 2.0 V; IOH = IOL = 12 mA

07278-031

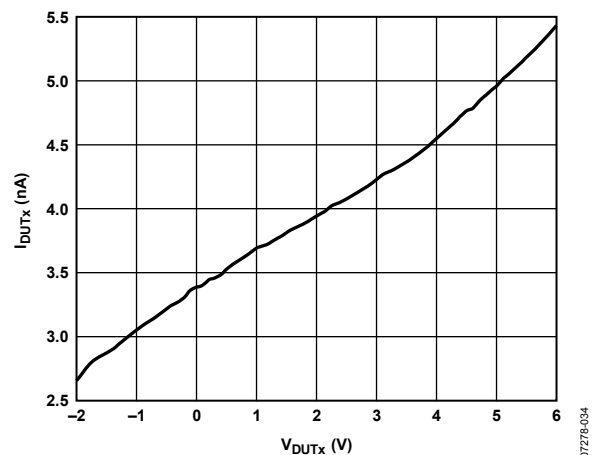


Figure 44. DUTx Pin Leakage Current in Low Leakage Mode

07278-034

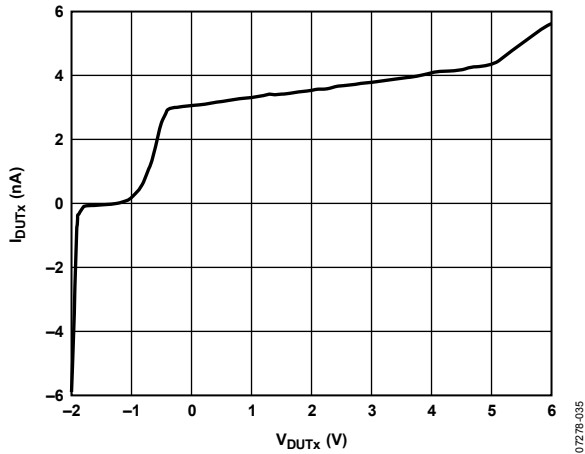


Figure 45. DUTx Pin Leakage Current in High-Z Mode

07278-035

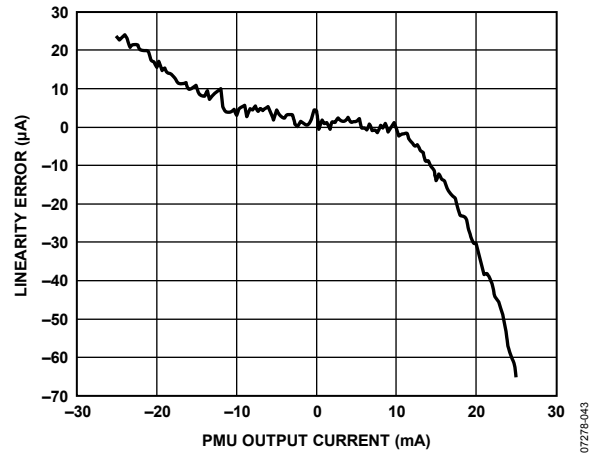


Figure 48. PMU Force Current Range A Linearity

07278-043

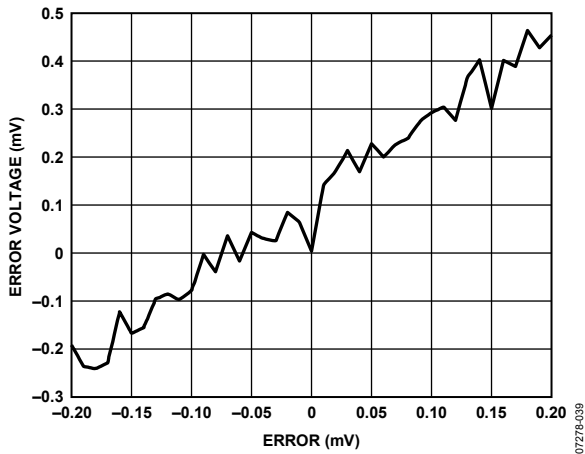


Figure 46. DUTGND Voltage Effects

07278-039

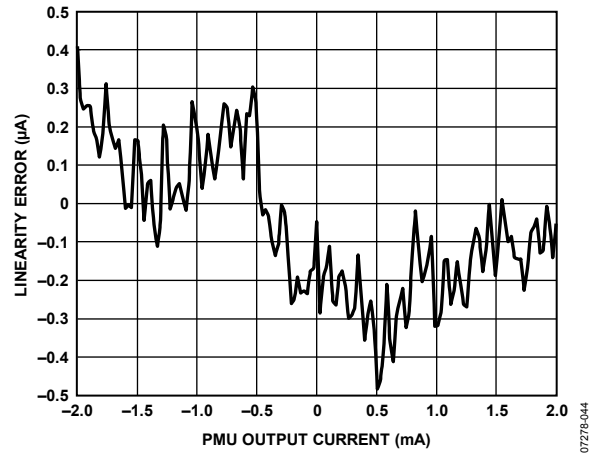


Figure 49. PMU Force Current Range B Linearity

07278-044

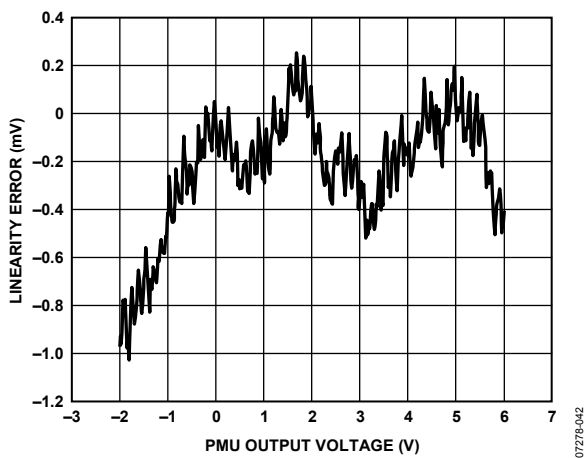


Figure 47. PMU Force Voltage Linearity

07278-042

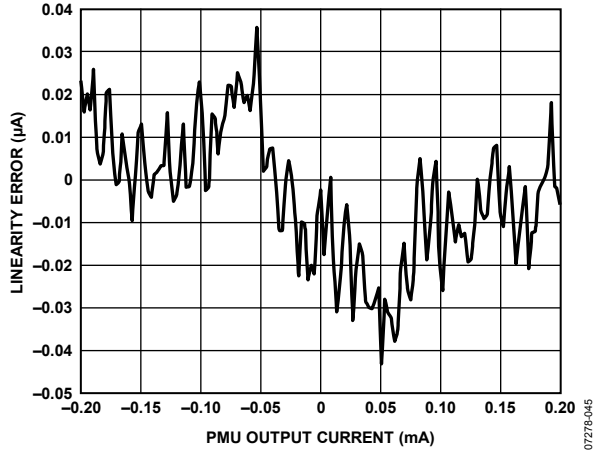


Figure 50. PMU Force Current Range C Linearity

07278-045

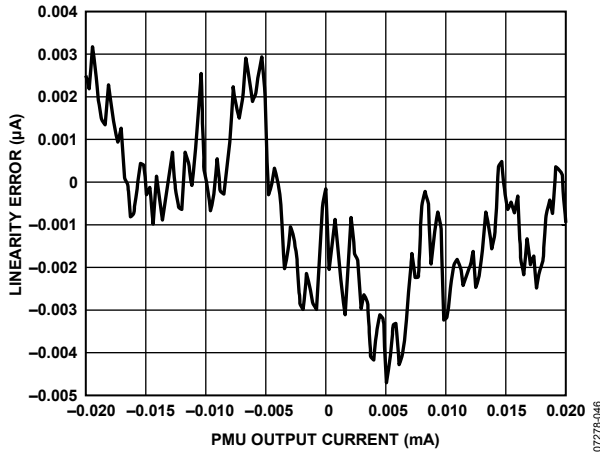


Figure 51. PMU Force Current Range D Linearity

07278-046

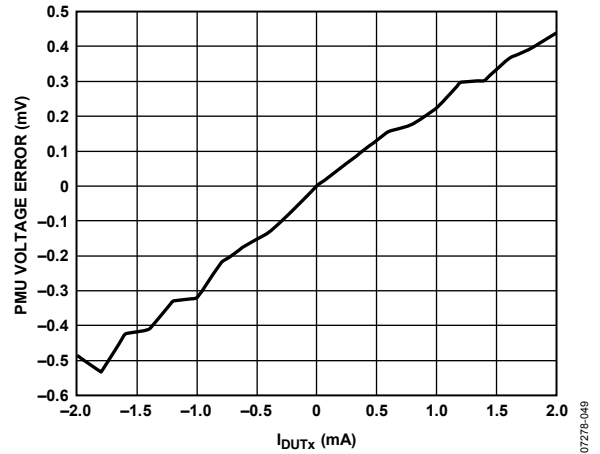


Figure 54. PMU Force Voltage Range B Output Voltage Error at  $-2.0\text{ V}$  vs. Output Current

07278-049

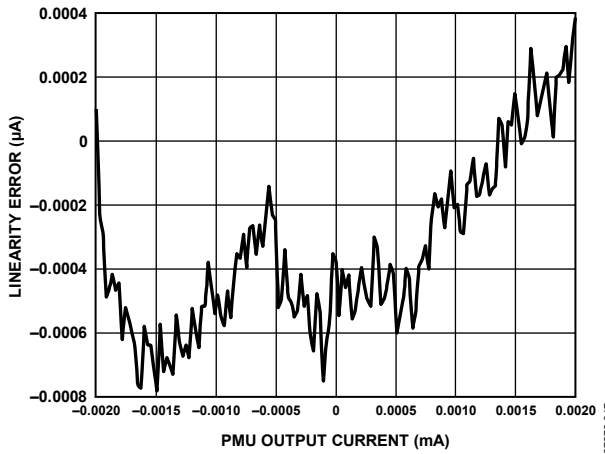


Figure 52. PMU Force Current Range E Linearity

07278-047

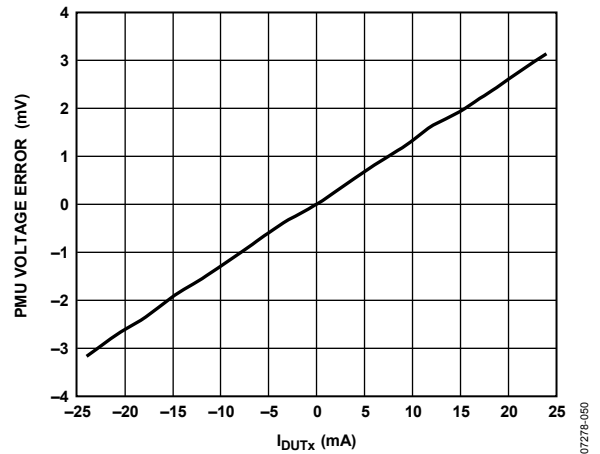


Figure 55. PMU Force Voltage Range A Output Voltage Error at  $6.0\text{ V}$  vs. Output Current

07278-050

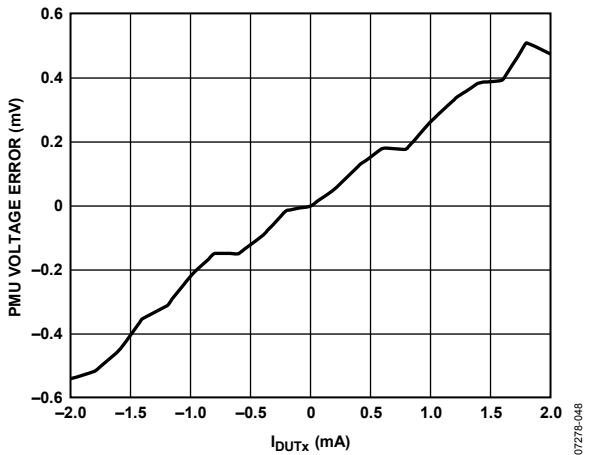


Figure 53. PMU Force Voltage Range B Output Voltage Error at  $6.0\text{ V}$  vs. Output Current

07278-048

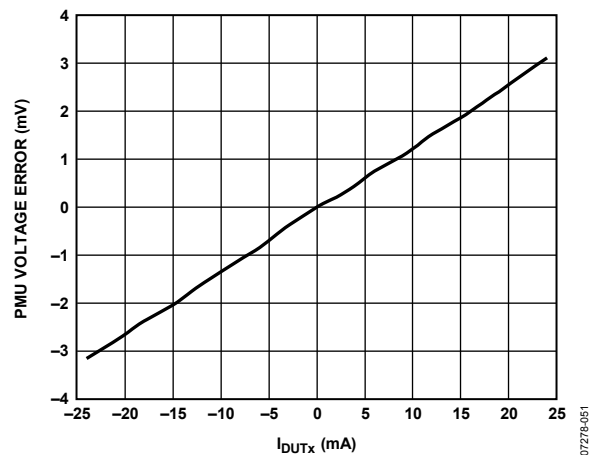


Figure 56. PMU Force Voltage Range A Output Voltage Error at  $-2.0\text{ V}$  vs. Output Current

07278-051

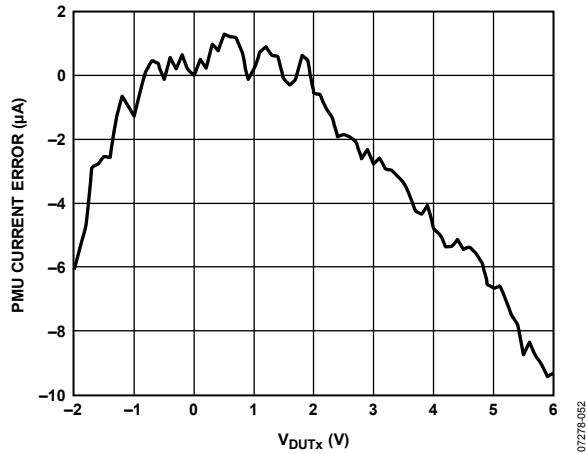


Figure 57. PMU Force Current Range A Output Current Error at -25 mA vs. Output Voltage

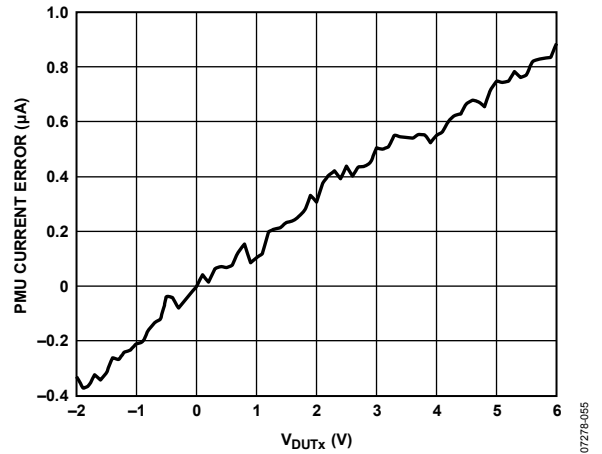


Figure 60. PMU Force Current Range B Output Current Error at 2 mA vs. Output Voltage; Output Voltage Is Pulled Externally

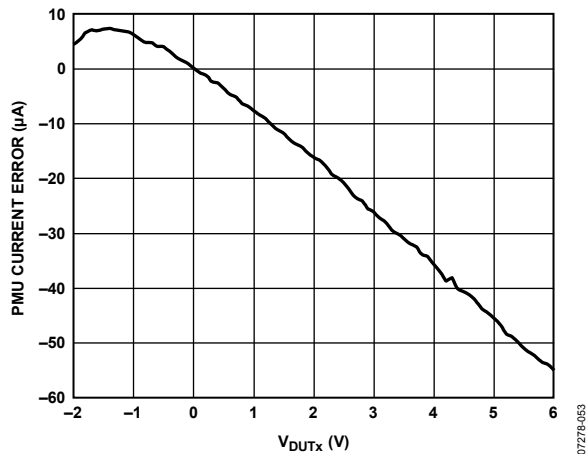


Figure 58. PMU Force Current Range A Output Current Error at 25 mA vs. Output Voltage; Output Voltage Is Pulled Externally

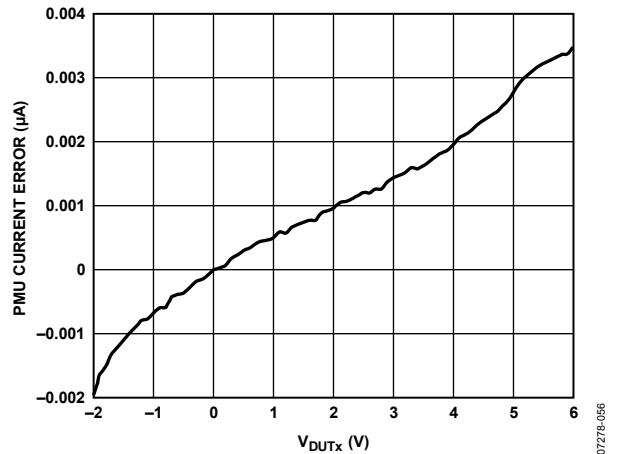


Figure 61. PMU Force Current Range E Output Current Error at -2 µA vs. Output Voltage; Output Voltage Is Pulled Externally

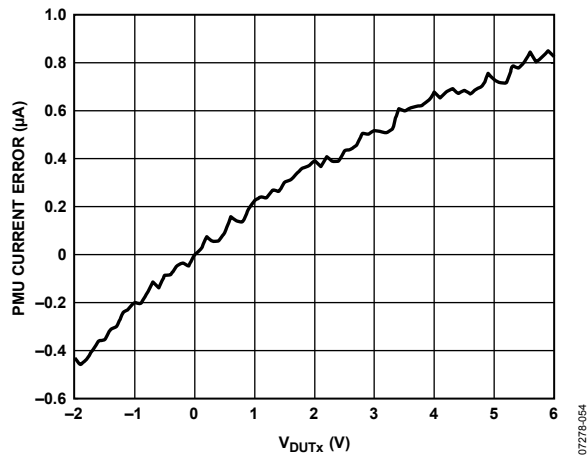


Figure 59. PMU Force Current Range B Output Current Error at -2 mA vs. Output Voltage; Output Voltage Is Pulled Externally

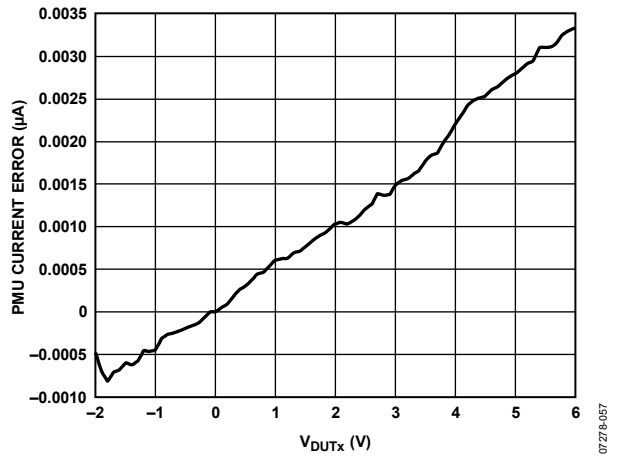


Figure 62. PMU Force Current Range E Output Current Error at 2 µA vs. Output Voltage; Output Voltage Is Pulled Externally

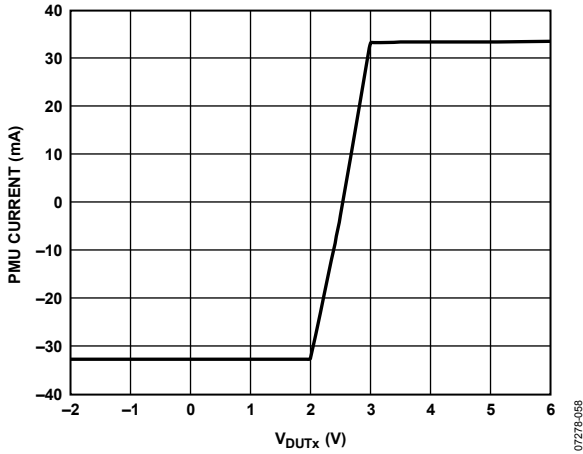


Figure 63. PMU Range A Internal Current Limit, Programmed to Force 2.5 V;  $V_{DUTx}$  Swept from -2.0 V to +6.0 V

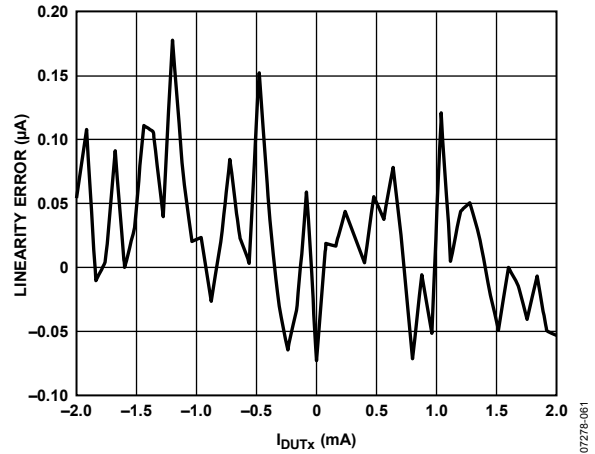


Figure 66. PMU Range B Measure Current Linearity

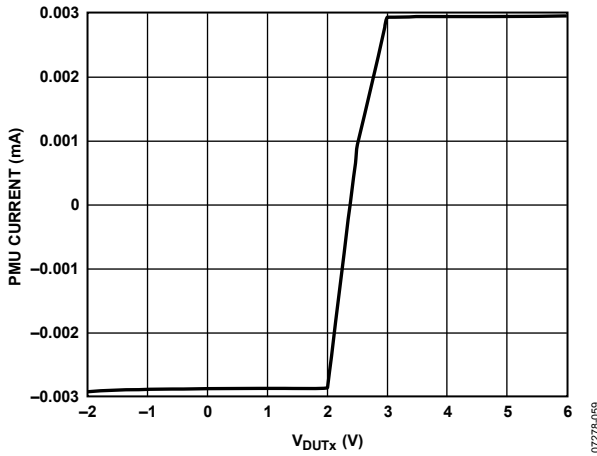


Figure 64. PMU Range E Internal Current Limit, Programmed to Force 2.5 V;  $V_{DUTx}$  Swept from -2.0 V to +6.0 V

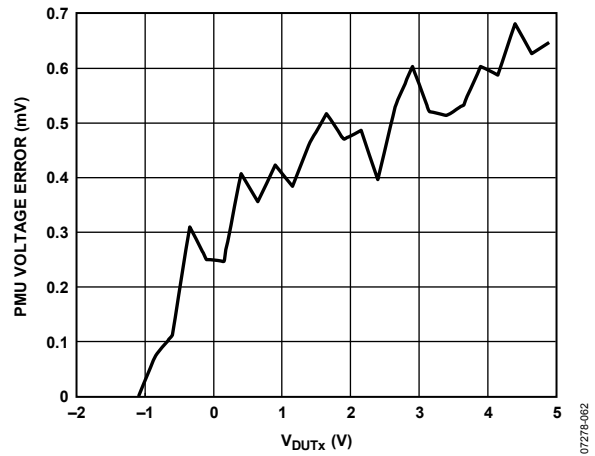


Figure 67. PMU Measure Current CMRR, Externally Pulling 1 mA, FVMI; Error of MI vs. External 1 mA

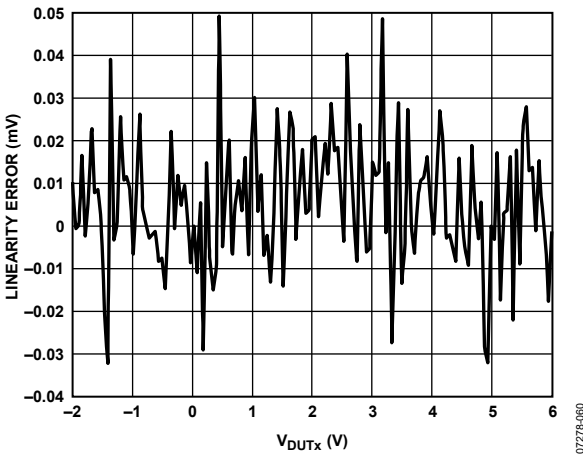


Figure 65. PMU Range B Measure Voltage Linearity

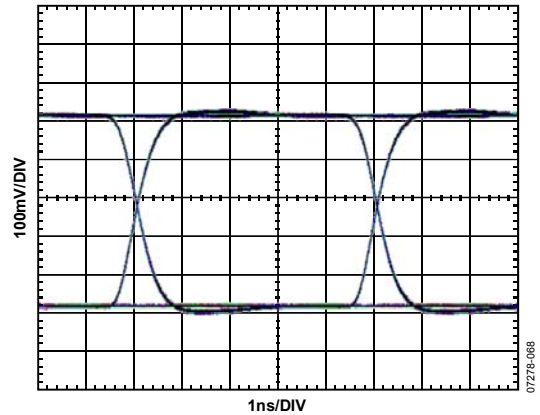


Figure 68. Eye Diagram, 200 Mbps, PRBS31;  $V_H = 1.0 V$ ;  $V_L = 0.0 V$



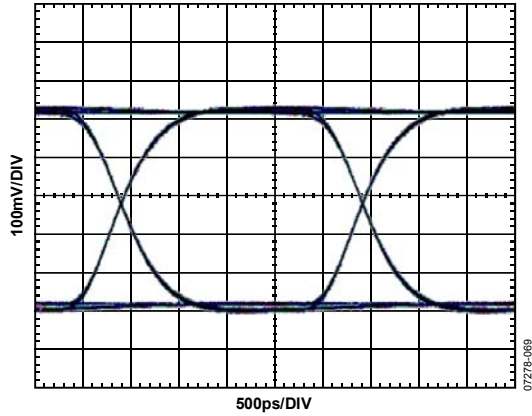


Figure 69. Eye Diagram, 400 Mbps, PRBS31;  
 $V_H = 1.0\text{ V}; V_L = 0.0\text{ V}$

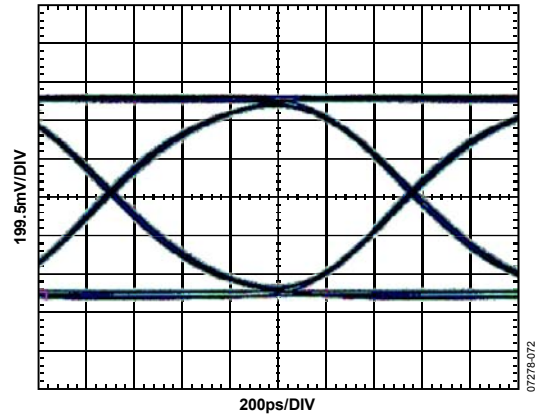


Figure 72. Eye Diagram, 800 Mbps, PRBS31;  
 $V_H = 2.0\text{ V}; V_L = 0.0\text{ V}$

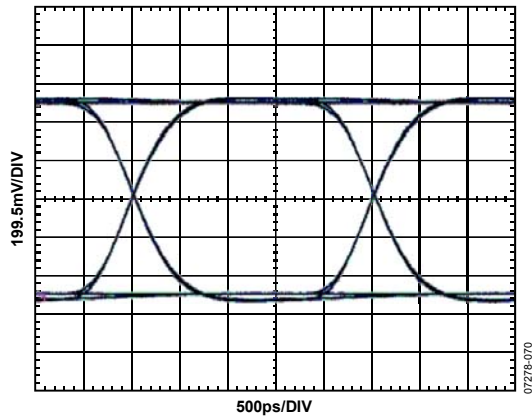


Figure 70. Eye Diagram, 400 Mbps, PRBS31;  
 $V_H = 2.0\text{ V}; V_L = 0.0\text{ V}$

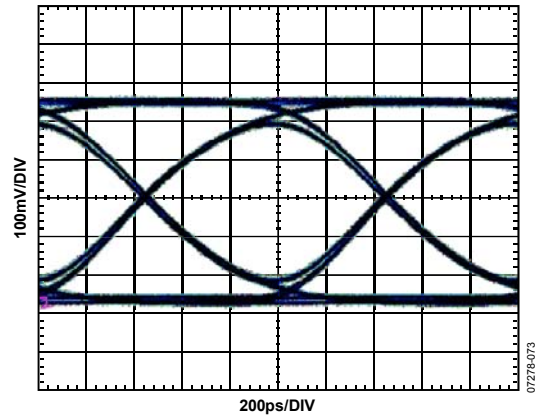


Figure 73. Eye Diagram, 1000 Mbps, PRBS31;  
 $V_H = 1.0\text{ V}; V_L = 0.0\text{ V}$

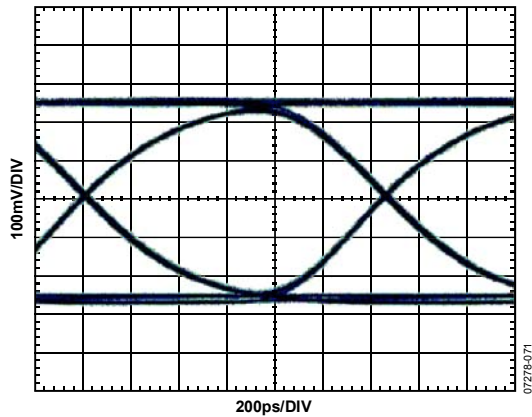


Figure 71. Eye Diagram, 800 Mbps, PRBS31;  
 $V_H = 1.0\text{ V}; V_L = 0.0\text{ V}$

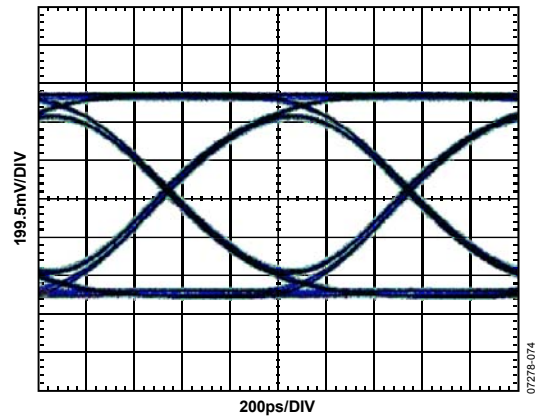


Figure 74. Eye Diagram, 1000 Mbps, PRBS31;  
 $V_H = 2.0\text{ V}; V_L = 0.0\text{ V}$

SERIAL PERIPHERAL INTERFACE DETAILS

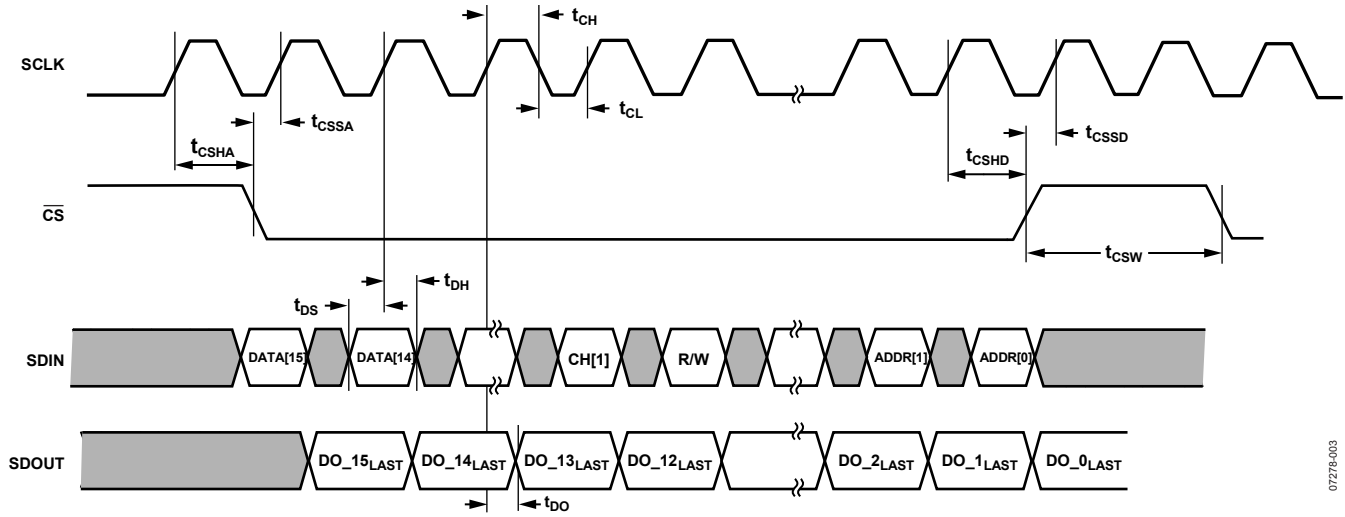


Figure 75. SPI Timing Diagram

07278-003

Table 17. Serial Peripheral Interface Timing Requirements

Symbol	Parameter	Min	Max	Unit
$t_{CH}$	SCLK minimum high	9.0		ns
$t_{CL}$	SCLK minimum low	9.0		ns
$t_{CSHA}$	$\overline{CS}$ assert hold	3.0		ns
$t_{CSSA}$	$\overline{CS}$ assert setup	3.0		ns
$t_{CSHD}$	$\overline{CS}$ deassert hold	3.0		ns
$t_{CSSD}$	$\overline{CS}$ deassert setup	3.0		ns
$t_{DH}$	SDIN hold	3.0		ns
$t_{DS}$	SDIN setup	3.0		ns
$t_{DO}$	SDOUT Data Out		15.0	ns
$t_{CSW}$	$\overline{CS}$ minimum between assertions <sup>1</sup>	2		SCLK cycles
	$\overline{CS}$ minimum directly after a read request	3		SCLK cycles
$t_{CSTP}$	Minimum delay after $\overline{CS}$ is deasserted before SCLK can be stopped (not shown in Figure 75); this allows any internal operations to complete	16		SCLK cycles

<sup>1</sup> Extra cycle is needed after read request to prime read data into SPI shift register.

**DEFINITION OF SPI WORD**

The SPI can take variable length words, depending on the operation. At most, the word is 24 bits long: 16 bits of data, two channel selects, one R/W selector, and a 5-bit address.

Depending on the operation, the data can be smaller (or nonexistent in the case of a read operation).

**Example 1**

Write 16 bits of data to a register or DAC; unused MSBs are ignored. For example, Bit 15 and Bit 14 are ignored, while Bit 13 through Bit 0 are applied to the 14-bit DAC.

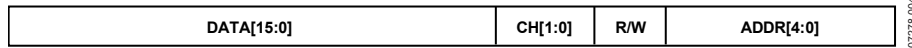


Figure 76.

**Example 2**

Write 14 bits of data to the DAC.

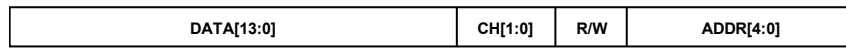


Figure 77.

**Example 3a**

Write two bits of data to the 2-bit register.

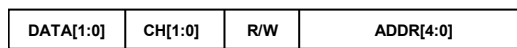


Figure 78.

**Example 3b**

Write two bits of data to the 2-bit register. Bit 15 through Bit 2 are ignored, while Bit 1 through Bit 0 are applied to the register.



Figure 79.

**Example 4**

Read request and follow with a 2<sup>nd</sup> instruction (could be NOP) to clock out the data.

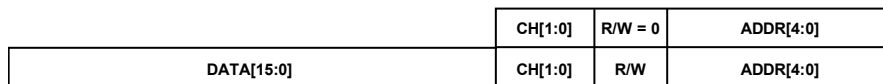


Figure 80.

**Table 18. Channel Selection**

Channel 1	Channel 0	Channel Selected
0	0	NOP (no channel selected, no register changes)
0	1	Channel 0 selected
1	0	Channel 1 selected
1	1	Channel 0 and Channel 1 selected

**Table 19. R/W Definition**

R/W	Description
0	Current register specified by address is shifted out of SDO <sub>OUT</sub> on next shift operation
1	Current data is written to register specified by address and channel select

## WRITE OPERATION

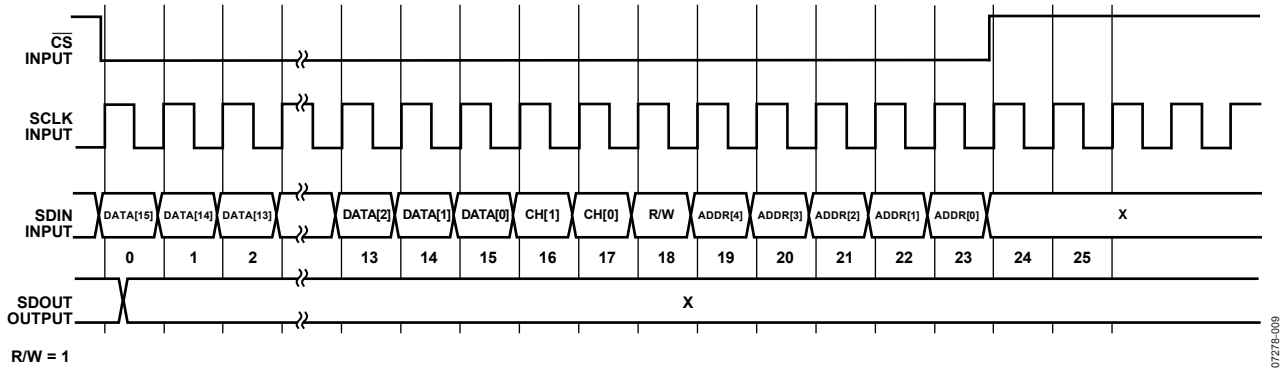


Figure 81. 16-Bit SPI Write

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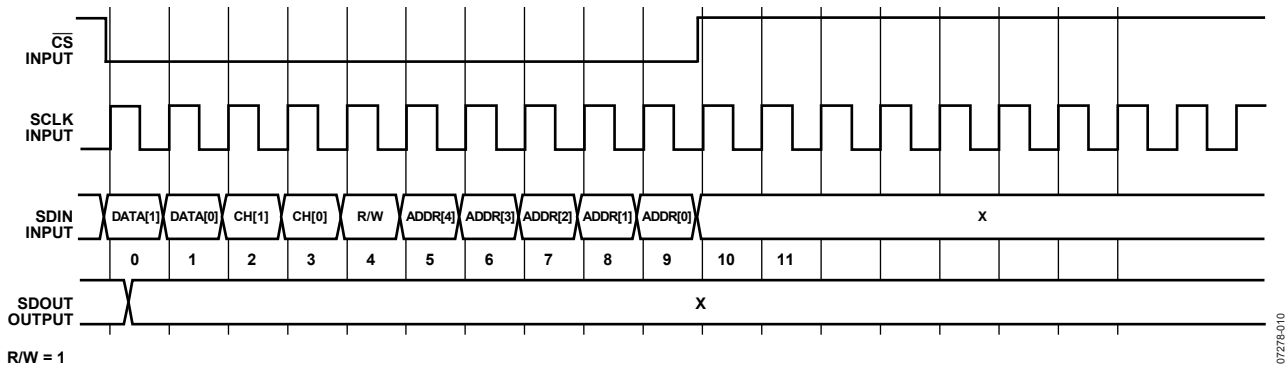


Figure 82. 2-Bit SPI Write

07278-010

**READ OPERATION**

The read operation is a two-stage operation. First, a word is shifted in, specifying which register to read. CS is deasserted for three clock cycles, and then a second word is shifted in to get the readback data. This second word can be either another operation or an NOP address. If another operation is shifted in, it needs to shift in at least eight bits of data to read back the

previous specified data. The NOP address can be used for this read if there is no need to write/read another register. It is strongly recommended that the NOP address be used for all reads for clarity of operations.

Any register read that is less than 16 bits has zeros filled in the top bits to make it a 16-bit word.

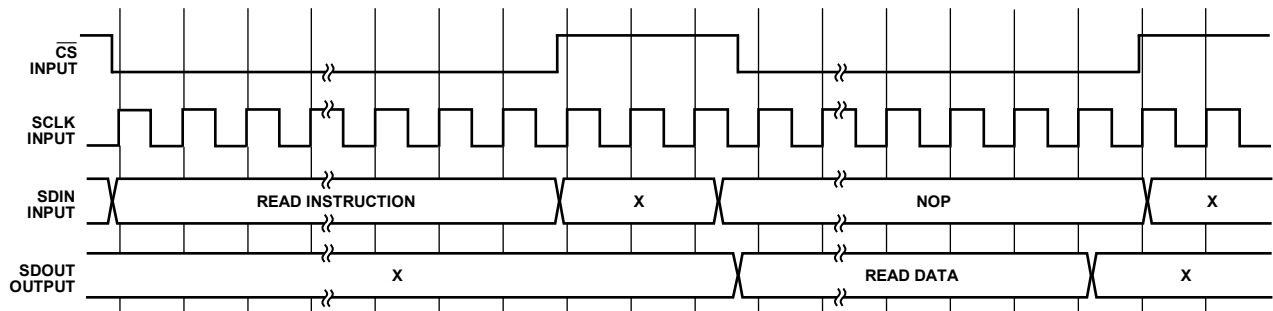


Figure 83. SPI Read Overview

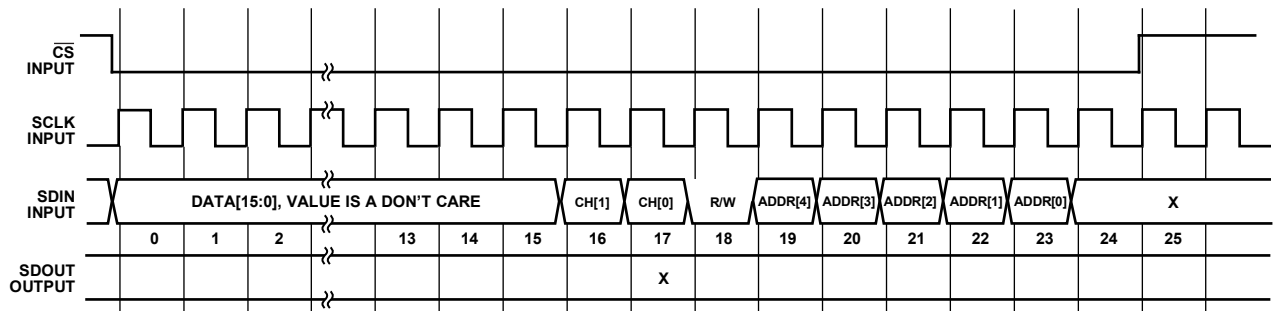
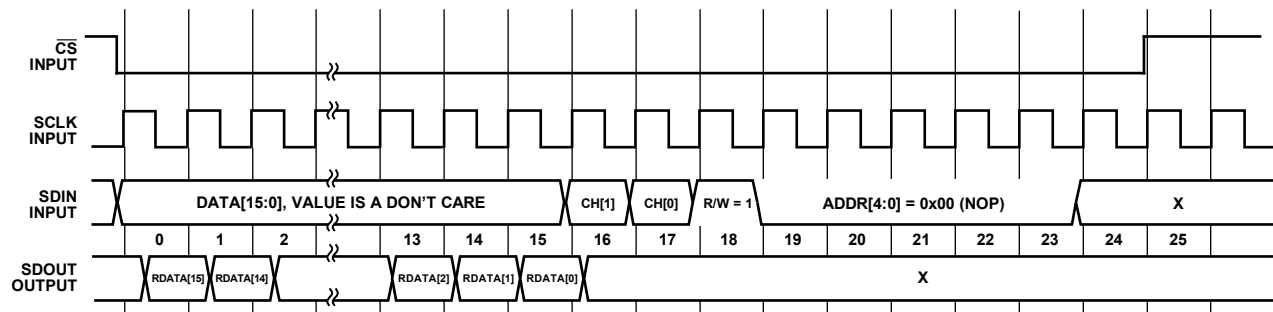


Figure 84. SPI Read—Details of Read Request



RDATA IS THE REGISTER VALUE BEING READ.

Figure 85. SPI Read—Details of Read Out

# ADATE302-02

## RESET OPERATION

The ADATE302-02 contains an asynchronous reset feature. The ADATE302-02 can be reset to the default values shown in Table 20 by utilizing the  $\overline{\text{RST}}$  pin. To initiate the reset operation, deassert the  $\overline{\text{RST}}$  pin for a minimum of 100 ns and deassert the  $\overline{\text{CS}}$  pin for a minimum of two SCLK cycles.

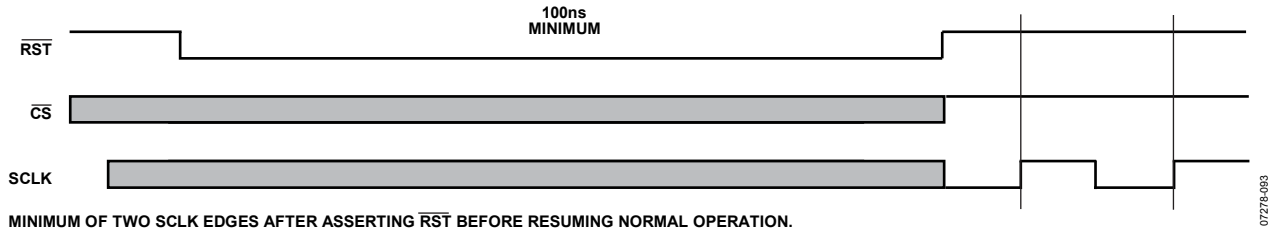


Figure 86. Reset Operation

## REGISTER MAP

The ADDR[4:0] bits determine the destination register of the data being written to the ADATE302-02.

**Table 20. Register Selection**

DATA[15:0]	CH[1:0]	R/W	ADDR[4:0]	Register Selected	Reset State
N/A	N/A	N/A	0x00	NOP	N/A
DATA[13:0]	CH[1:0]	R/W	0x01	VH DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x02	VL DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x03	VT/VCOM DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x04	VOL DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x05	VOH DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x06	VCH DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x07	VCL DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x08	V(IOH ) DAC level	4096d
DATA[13:0]	CH[1:0]	R/W	0x09	V(IOL ) DAC level	4096d
DATA[13:0]	CH[1]	R/W	0x0A	OVD high level	4096d
DATA[13:0]	CH[0]	R/W	0x0A	OVD low level	4096d
DATA[15:0]	CH[1:0]	R/W	0x0B	PMUDAC level	16384d
DATA[2:0]	CH[1:0]	R/W	0x0C	PE/PMU enable	000b
DATA[2:0]	CH[1:0]	R/W	0x0D	Channel state	000b
DATA[9:0]	CH[1:0]	R/W	0x0E	PMU state	0d
DATA[2:0]	CH[1:0]	R/W	0x0F	PMU measure enable	000b
DATA[0]	CH[1:0]	R/W	0x10	Differential comparator enable	0b
DATA[1:0]	CH[1:0]	R/W	0x11	16-bit DAC monitor	00b
DATA[1:0]	CH[1:0]	R/W	0x12	OVD_CHx alarm mask	01b
DATA[2:0]	CH[1:0]	R	0x13	OVD_CHx alarm state	N/A
N/A	N/A	N/A	0x14 to 0x1F	Reserved	N/A

## DETAILS OF REGISTERS

**Table 21. PE/PMU Enable (ADDR[4:0] = 0x0C)**

Bit	Name	Description
DATA[2]	PMU enable	0 = disable PMU force output and clamps, place PMU in MV mode 1 = enable PMU force output
DATA[1]	Force VT	When set to 0, the PMU State bits are ignored, except for PMU Sense Path (DATA[7]). 0 = normal driver operation 1 = force driver to $V_T$
DATA[0]	PE disable	See Table 29 for complete functionality of this bit. 0 = enable driver functions 1 = disable driver (low leakage) See Table 29 for complete functionality of this bit.

**Table 22. Channel State (ADDR[4:0] = 0x0D)**

Bit	Name	Description
DATA[2]	HVOUT mode select	0 = HVOUT driver in low impedance 1 = enable HVOUT driver This bit affects Channel 0 only. Ensure that Channel 0 bit in SPI write is active. Channel 1 bit in SPI write is don't care.
DATA[1]	Load enable	0 = disable load 1 = enable load See Table 29 for complete functionality of this bit.
DATA[0]	Driver high-Z/VT	0 = enable driver high-Z function 1 = enable driver VTERM function See Table 29 for complete functionality of this bit.

**Table 23. PMU State (ADDR[4:0] = 0x0E)<sup>1, 2</sup>**

Bit	Name	Description
DATA[9:8]	PMU input selection	00 = $V_{DUTGND}$ (calibrated for 0.0 V voltage reference) 01 = $2.5 V + V_{DUTGND}$ (calibrated for 0.0 A current reference) 1X = PMUDAC
DATA[7]	PMU sense path	0 = internal sense 1 = external sense
DATA[6]	Reserved	
DATA[5]	PMU clamp enable	0 = disable clamps 1 = enable clamps
DATA[4]	PMU measure V/I	0 = measure voltage mode 1 = measure current mode
DATA[3]	PMU force V/I	0 = force voltage mode 1 = force current mode
DATA[2:0]	PMU range	0XX = Range E (2 $\mu$ A) 100 = Range D (20 $\mu$ A) 101 = Range C (200 $\mu$ A) 110 = Range B (2 mA) 111 = Range A (25 mA)

<sup>1</sup> Note that when the ADDR[4:0] = 0x0C PMU enable bit (DATA[2]) = 0, the PMU force outputs and clamps are disabled, and the PMU is placed into measure voltage mode. DATA[9:8] and DATA[6:0] of the PMU state register are ignored, and only DATA[7], the PMU sense path bit, is valid.

<sup>2</sup> X = don't care.



**Table 24. PMU Measure Enable (ADDR[4:0] = 0x0F)<sup>1</sup>**

Bit	Name	Description
DATA[2:1]	MEASOUT01 select	00 = PMU MEASOUT Channel 0 01 = PMU MEASOUT Channel 1 10 = Temp sensor ground reference 11 = Temp sensor
DATA[0]	MEASOUT01 output enable	0 = MEASOUT01 is tristated 1 = MEASOUT01 is enabled

<sup>1</sup> This register is written to or read from if either of the CH[1:0] bits is 1.

**Table 25. Differential Comparator Enable (ADDR[4:0] = 0x10)<sup>1</sup>**

Bit	Name	Description
DATA[0]	Differential comparator enable	0 = differential comparator is disabled, Channel 0 normal window comparator (NWC) outputs are on Channel 0 1 = differential comparator is enabled, the differential comparator outputs are on Channel 0

<sup>1</sup> This register is written to or read from if either of the CH[1:0] bits is 1.

**Table 26. DAC16\_MON (16-Bit DAC Monitor) (ADDR[4:0] = 0x11)<sup>1</sup>**

Bit	Name	Description
DATA[1]	16-bit DAC mux enable	0 = 16-bit DAC mux is tristated 1 = 16-bit DAC mux is enabled
DATA[0]	16-bit DAC mux select	0 = 16-bit DAC Channel 0 1 = 16-bit DAC Channel 1

<sup>1</sup> This register is written to or read from if either of the CH[1:0] bits is 1.

**Table 27. OVD\_CHx Alarm Mask (ADDR[4:0] = 0x12)**

Bit	Name	Description
DATA[1]	PMU mask	0 = disable PMU alarm flag 1 = enable PMU alarm flag
DATA[0]	OVD mask	0 = disable OVD alarm flag 1 = enable OVD alarm flag

**Table 28. OVD\_CHx Alarm State (ADDR[4:0] = 0x13)<sup>1</sup>**

Bit	Name	Description
DATA[2]	PMU clamp flag	0 = PMU not clamped 1 = PMU clamped
DATA[1]	OVD high flag	0 = DUT voltage < OVD high voltage 1 = DUT voltage > OVD high voltage
DATA[0]	OVD low flag	0 = DUT voltage > OVD low voltage 1 = DUT voltage < OVD low voltage

<sup>1</sup> This register is a read-only register.

## USER INFORMATION

Table 29. Driver and Load Truth Table<sup>1</sup>

Registers				Signals		Driver State	Load State
PE Disable DATA[0] ADDR[4:0] = 0x0C	Force VT DATA[1] ADDR[4:0] = 0x0C	Load Enable DATA[1] ADDR[4:0] = 0x0D	Driver High-Z/VT DATA[0] ADDR[4:0] = 0x0D	DATAx	RCVx		
1	X	X	X	X	X	High-Z without clamps	Power-down
0	1	X	X	X	X	VT	Power-down
0	0	0	0	0	0	VL	Power-down
0	0	0	0	0	1	High-Z with clamps	Power-down
0	0	0	0	1	0	VH	Power-down
0	0	0	0	1	1	High-Z with clamps	Power-down
0	0	0	1	0	0	VL	Power-down
0	0	0	1	0	1	VT	Power-down
0	0	0	1	1	0	VH	Power-down
0	0	0	1	1	1	VT	Power-down
0	0	1	0	0	0	VL	Active off
0	0	1	0	0	1	High-Z with clamps	Active on
0	0	1	0	1	0	VH	Active off
0	0	1	0	1	1	High-Z with clamps	Active on
0	0	1	1	0	0	VL	Active on
0	0	1	1	0	1	High-Z with clamps	Active on
0	0	1	1	1	0	VH	Active on
0	0	1	1	1	1	High-Z with clamps	Active on

<sup>1</sup> X = don't care.

Table 30. HVOOUT Truth Table<sup>1</sup>

HVOOUT Mode Select DATA[2] ADDR[4:0] = 0x0D	Channel 0 RCV	Channel 0 DATA	HVOOUT Driver Output
1	1	X	VHH mode; $V_{HH} = (VT + 1V) \times 2 + DUTGND$ (Channel 0 VT DAC)
1	0	0	VL (Channel 0 VL DAC)
1	0	1	VH (Channel 0 VH DAC)
0	X	X	Disabled (HVOOUT pin set to 0 V low impedance)

<sup>1</sup> X = don't care.

Table 31. Comparator Truth Table

Differential Comparator Enable DATA[0] ADDR[4:0] = 0x10	COMP_QH0	COMP_QL0	COMP_QH1	COMP_QL1
0	Normal window mode Logic high: $VOH0 < V_{DUT0}$ Logic low: $VOH0 > V_{DUT0}$	Normal window mode Logic high: $VOL0 < V_{DUT0}$ Logic low: $VOL0 > V_{DUT0}$	Normal window mode Logic high: $VOH1 < V_{DUT1}$ Logic low: $VOH1 > V_{DUT1}$	Normal window mode Logic high: $VOL1 < V_{DUT1}$ Logic low: $VOL1 > V_{DUT1}$
1	Differential comparator mode Logic high: $VOH0 < V_{DUT0} - V_{DUT1}$ Logic low: $VOH0 > V_{DUT0} - V_{DUT1}$	Differential comparator mode Logic high: $VOL0 < V_{DUT0} - V_{DUT1}$ Logic low: $VOL0 > V_{DUT0} - V_{DUT1}$	Normal window mode Logic high: $VOH1 < V_{DUT1}$ Logic low: $VOH1 > V_{DUT1}$	Normal window mode Logic high: $VOL1 < V_{DUT1}$ Logic low: $VOL1 > V_{DUT1}$

**DETAILS OF DACs vs. LEVELS**

There are ten 14-bit DACs per channel. These DACs provide levels for the driver, comparator, load currents, VHH buffer, OVD, and clamp levels. There are three versions of output levels:

- -2.5 V to +7.5 V; tracks DUTGND. Controls VH, VL, VT/VCOM/VHH, VOH, VOL, VCH, and VCL levels.
- -3.0 V to +7.0 V; tracks DUTGND. Controls OVD levels.
- -2.5 V to +7.5 V; does not track DUTGND. Controls IOH and IOL levels.

There is one 16-bit DAC per channel. This DAC provides the levels for the PMU. The output level is:

- -2.5 V to +7.5 V; tracks DUTGND. Controls PMU levels.

**Table 32. Level Transfer Functions**

DAC Transfer Function	Programmable Range <sup>1</sup> (All 0s to All 1s)	Levels
$V_{OUT} = 2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{14})) - 0.5 \times (V_{REF} - V_{REF\_GND}) + V_{DUTGND}$ Code = $[V_{OUT} - V_{DUTGND} + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{14})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-2.5 V to +7.5 V	VH, VL, VT/VCOM, VOL, VOH, VCH, VCL
$V_{OUT} = 4.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{14})) - 1.0 \times (V_{REF} - V_{REF\_GND}) + 2.0 + V_{DUTGND}$ Code = $[V_{OUT} - V_{DUTGND} - 2.0 + 1.0 \times (V_{REF} - V_{REF\_GND})] \times [(2^{14})/(4.0 \times (V_{REF} - V_{REF\_GND}))]$	-3.0 V to +17.0 V	VHH
$V_{OUT} = 2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{14})) - 0.6 \times (V_{REF} - V_{REF\_GND}) + V_{DUTGND}$ Code = $[V_{OUT} - V_{DUTGND} + 0.6 \times (V_{REF} - V_{REF\_GND})] \times [(2^{14})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-3.0 V to +7.0 V	OVD
$I_{OUT} = [2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{14})) - 0.5 \times (V_{REF} - V_{REF\_GND})] \times (0.012/5.0)$ Code = $[(I_{OUT} \times (5.0/0.012)) + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{14})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-6 mA to +18 mA	IOH, IOL
$V_{OUT} = 2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{16})) - 0.5 \times (V_{REF} - V_{REF\_GND}) + V_{DUTGND}$ Code = $[V_{OUT} - V_{DUTGND} + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{16})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-2.5 V to +7.5 V	PMUDAC
$I_{OUT} = [2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{16})) - 0.5 \times (V_{REF} - V_{REF\_GND}) - 2.5] \times (0.050/5.0)$ Code = $[(I_{OUT} \times (5.0/0.050)) + 2.5 + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{16})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-50 mA to +50 mA	PMUDAC (PMU FI Range A)
$I_{OUT} = [2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{16})) - 0.5 \times (V_{REF} - V_{REF\_GND}) - 2.5] \times (0.004/5.0)$ Code = $[(I_{OUT} \times (5.0/0.004)) + 2.5 + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{16})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-4 mA to +4 mA	PMUDAC (PMU FI Range B)
$I_{OUT} = [2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{16})) - 0.5 \times (V_{REF} - V_{REF\_GND}) - 2.5] \times (0.0004/5.0)$ Code = $[(I_{OUT} \times (5.0/0.0004)) + 2.5 + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{16})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-400 µA to +400 µA	PMUDAC (PMU FI Range C)
$I_{OUT} = [2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{16})) - 0.5 \times (V_{REF} - V_{REF\_GND}) - 2.5] \times (0.00004/5.0)$ Code = $[(I_{OUT} \times (5.0/0.00004)) + 2.5 + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{16})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-40 µA to +40 µA	PMUDAC (PMU FI Range D)
$I_{OUT} = [2.0 \times (V_{REF} - V_{REF\_GND}) \times (Code/(2^{16})) - 0.5 \times (V_{REF} - V_{REF\_GND}) - 2.5] \times (0.000004/5.0)$ Code = $[(I_{OUT} \times (5.0/0.000004)) + 2.5 + 0.5 \times (V_{REF} - V_{REF\_GND})] \times [(2^{16})/(2.0 \times (V_{REF} - V_{REF\_GND}))]$	-4 µA to +4 µA	PMUDAC (PMU FI Range E)

<sup>1</sup> Programmable range includes margin outside of specified part performance, allowing for offset/gain calibration.

**Table 33. Load Transfer Functions**

Load Level	Transfer Function <sup>1</sup>
IOL	$V(IOL)/5 V \times 12 mA$
IOH	$V(IOH)/5 V \times 12 mA$

<sup>1</sup> V(IOH), V(IOL) DAC levels are not referenced to DUTGND.

**Table 34. PMU Transfer Functions**

PMU Mode	Transfer Function
Force Voltage	$V_{OUT} = PMUDAC$
Measure Voltage	$V_{MEASOUT01} = V_{DUTx}$ (internal sense) or $V_{MEASOUT01} = V_{PMUS\_CHx}$ (external sense)
Force Current	$I_{OUT} = [PMUDAC - (V_{REF}/2)]/(R^1 \times 5)$
Measure Current	$V_{MEASOUT01} = (V_{REF}/2) + V_{DUTGND} + (I_{DUTx} \times 5 \times R^1)$

<sup>1</sup> R = 20 Ω for Range A; 250 Ω for Range B; 2.5 kΩ for Range C; 25 kΩ for Range D; 250 kΩ for Range E.

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**Table 35. PMU User Required Capacitors**

Capacitor	Location
220 pF	Across Pin C10 (FFCAP_0B) and Pin E10 (FFCAP_0A)
220 pF	Across Pin C1 (FFCAP_1B) and Pin E1 (FFCAP_1A)
330 pF	Between GND and Pin B9 (SCAP0)
330 pF	Between GND and Pin B2 (SCAP1)

**Table 36. Temperature Sensor**

Temperature	Output
0 K	0 V
300 K	3 V
x K	(x K) × 10 mV/K

**Table 37. Default Test Conditions**

Name	Default Test Condition
VH DAC Level	2.0 V
VL DAC Level	0.0 V
VT/VCOM DAC Level	1.0 V
VOL DAC Level	-2.0 V
VOH DAC Level	6.0 V
VCH DAC Level	7.5 V
VCL DAC Level	-2.5 V
IOH DAC Level	0.0 A
IOL DAC Level	0.0 A
OVD Low DAC Level	-2.5 V
OVD High DAC Level	6.5 V
PMUDAC DAC Level	0.0 V
PE/PMU Enable	0x0000: PMU disabled, not force VT, PE enabled
Channel State	0x0000: HVOUT mode disabled, load disabled, VTERM inactive
PMU State	0x0000: input of DUTGND, internal sense, clamps disabled, FVMV, Range E
PMU Measure Enable	0x0000: MEASOUT01 pin tristated
Differential Comparator Enable	0x0000: normal window comparator mode
16-Bit DAC Monitor	0x0000: DAC16_MON tristated
OVD_CHx Alarm Mask	0x0000: disable alarm functions
Data Input	Logic low
Receive Input	Logic low
DUTx Pin	Unterminated
Comparator Output	Unterminated

**RECOMMENDED PMU MODE SWITCHING SEQUENCES**

To minimize any possible aberrations and voltage spikes on the DUT output, specific mode switching sequences are recommended for the following transitions:

- PMU disable to PMU enable
- PMU force voltage mode to PMU force current mode
- PMU force current mode to PMU force voltage mode.

**PMU Disable to PMU Enable**

Step 1: See Table 38 for state of registers in PMU disabled mode.

**Table 38.**

Register	Bit	Setting
PE/PMU Enable Register, ADDR[4:0] = 0x0C	DATA[2]	0
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	XX
	DATA[7]	X
	DATA[6]	X
	DATA[5]	X
	DATA[4]	X
	DATA[3]	X
	DATA[2:0]	XXX

Step 2: Write to Register ADDR[4:0] = 0x0E (see Table 39).

**Table 39.**

Register	Bit	Setting	Comments	
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	1X or 00	Set desired input selection	
	DATA[7]	X		
	DATA[6]	X		
	DATA[5]	X		
	DATA[4]	X		
	DATA[3]	0		This bit must be set to force voltage mode to reduce aberrations
	DATA[2:0]	XXX		

Step 3: Write to Register ADDR[4:0] = 0x0C (see Table 40).

**Table 40.**

Register	Bit	Setting	Comments
PE/PMU Enable Register, ADDR[4:0] = 0x0C	DATA[2]	1	PMU is now enabled in force voltage mode

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## PMU Force Voltage Mode to PMU Force Current Mode

Step 1: See Table 41 for state of registers in force voltage mode.

Table 41.

Register	Bit	Setting
PE/PMU Enable Register, ADDR[4:0] = 0x0C	DATA[2]	1
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	XX
	DATA[7]	X
	DATA[6]	X
	DATA[5]	X
	DATA[4]	X
	DATA[3]	0
	DATA[2:0]	XXX

Step 2: Write to Register ADDR[4:0] = 0x0E (see Table 42).

Table 42.

Register	Bit	Setting	Comments
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	01	Set 2.5 V + V <sub>DUTGND</sub> input selection
	DATA[7]	X	
	DATA[6]	X	
	DATA[5]	X	
	DATA[4]	X	
	DATA[3]	1	Set to force current mode
	DATA[2:0]	0XX	2 $\mu$ A range has the minimum offset current

Step 3: Write to Register ADDR[4:0] = 0x0B (see Table 43).

Table 43.

Register	Bit	Setting	Comments
PMUDAC Level, ADDR[4:0] = 0x0B	DATA[15:0]	X	Update the PMUDAC level register to the desired value

Step 4: Write to Register ADDR[4:0] = 0x0E (see Table 44).

Table 44.

Register	Bit	Setting	Comments
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	1X	PMUDAC input selection
	DATA[7]	X	
	DATA[6]	X	
	DATA[5]	X	
	DATA[4]	X	
	DATA[3]	1	Set to force current mode
	DATA[2:0]	XXX	Set to the desired current range

**Transition from PMU Force Current Mode to PMU Force Voltage Mode**

Step 1: See Table 45 for state of registers in force current mode.

**Table 45.**

Register	Bits	Setting
PE/PMU Enable Register, ADDR[4:0] = 0x0C	DATA[2]	1
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	XX
	DATA[7]	X
	DATA[6]	X
	DATA[5]	X
	DATA[4]	X
	DATA[3]	1
	DATA[2:0]	XXX

Step 2: Write to Register ADDR[4:0] = 0x0E (see Table 46).

**Table 46.**

Register	Bits	Setting	Comments
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	00	Set DUTGND input selection
	DATA[7]	X	
	DATA[6]	X	
	DATA[5]	X	
	DATA[4]	X	
	DATA[3]	0	Set to force voltage mode
	DATA[2:0]	XXX	Set to the desired current range

Step 3: Write to Register ADDR[4:0] = 0x0B (see Table 47).

**Table 47.**

Register	Bits	Setting	Comments
PMUDAC Level, ADDR[4:0] = 0x0B	DATA[15:0]	X	Update the PMUDAC level register to the desired value

Step 4: Write to Register ADDR[4:0] = 0x0E (see Table 48).

**Table 48.**

Register	Bits	Setting	Comments
PMU State Register, ADDR[4:0] = 0x0E	DATA[9:8]	1X	PMUDAC input selection
	DATA[7]	X	
	DATA[6]	X	
	DATA[5]	X	
	DATA[4]	X	
	DATA[3]	0	Force voltage mode
	DATA[2:0]	XXX	

BLOCK DIAGRAMS

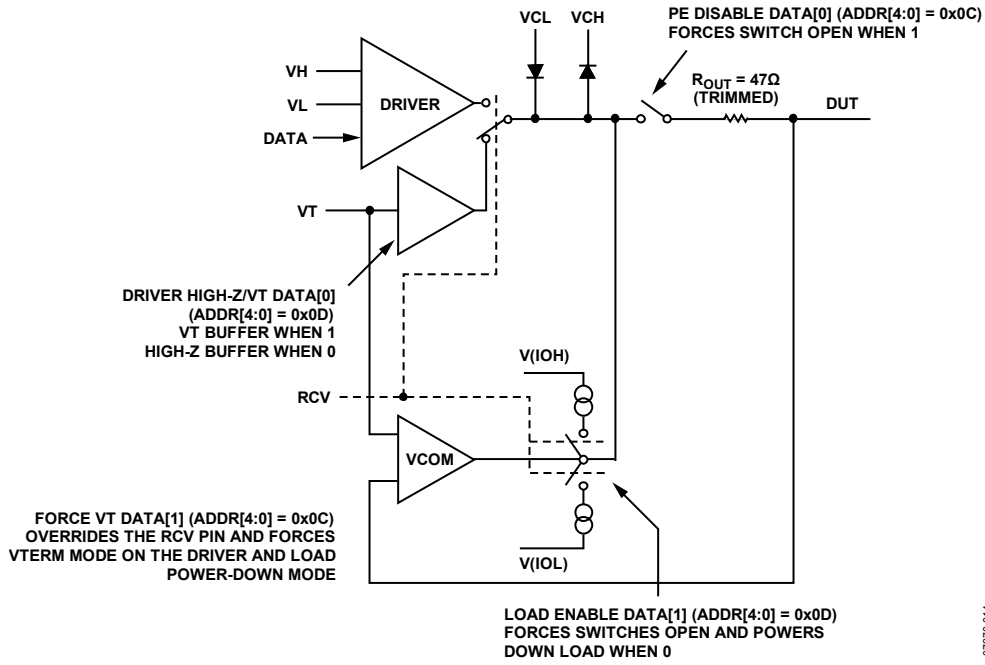


Figure 87. Driver and Load Block Diagram

07278-014

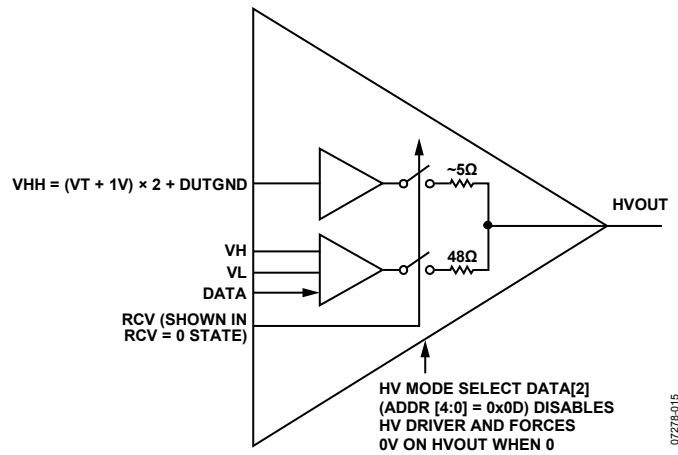
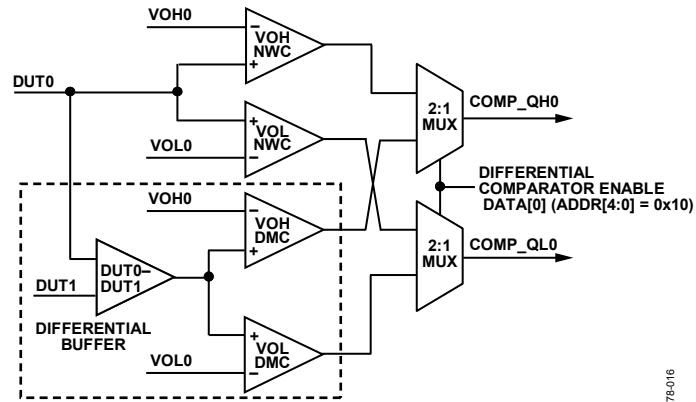


Figure 88. HVOUT Driver Output Stage

07278-015





NOTES  
1. DIFFERENTIAL COMPARATOR ONLY ON CHANNEL 0.

Figure 89. Comparator Block Diagram

07278-016

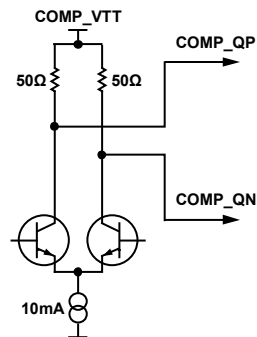
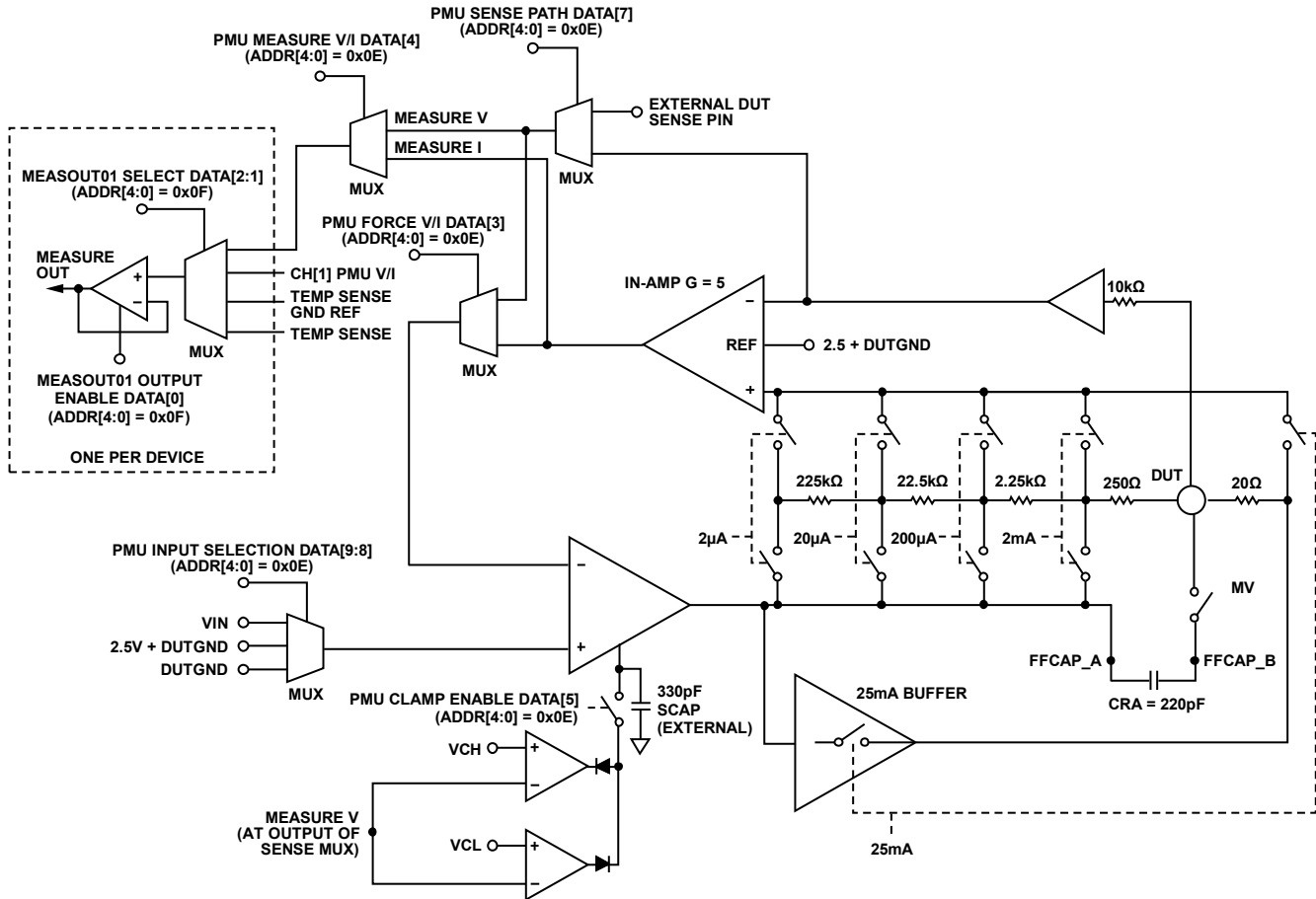


Figure 90. Comparator Output Scheme

07278-017

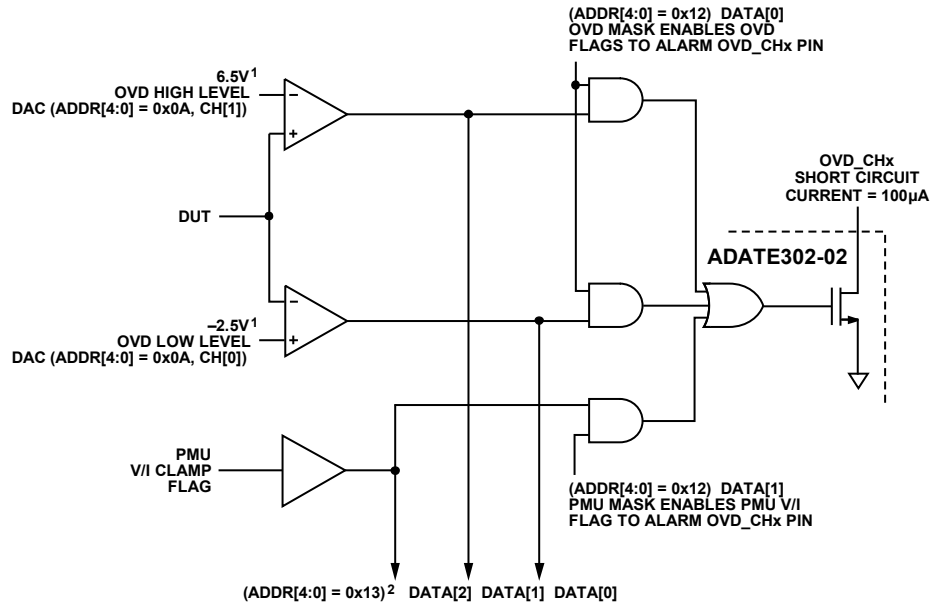


## NOTES

1. SWITCHES CONNECTED WITH DOTTED LINES REPRESENT PMU RANGE DATA[2:0] (ADDR[4:0] = 0x0E); WHEN PMU ENABLE DATA[2] = 0 (ADDR[4:0] = 0x0C), ALL SWITCHES OPEN AND PMU POWERS DOWN.
2. THE EXTERNAL SENSE PATH MUST CLOSE THE LOOP TO ENABLE THE CLAMPS TO OPERATE CORRECTLY.
3. 25mA RANGE HAS ITS OWN OUTPUT BUFFER.
4. 25mA BUFFER WILL BE TRISTATED WHEN NOT IN USE.

Figure 91. PMU Block Diagram

07275-018

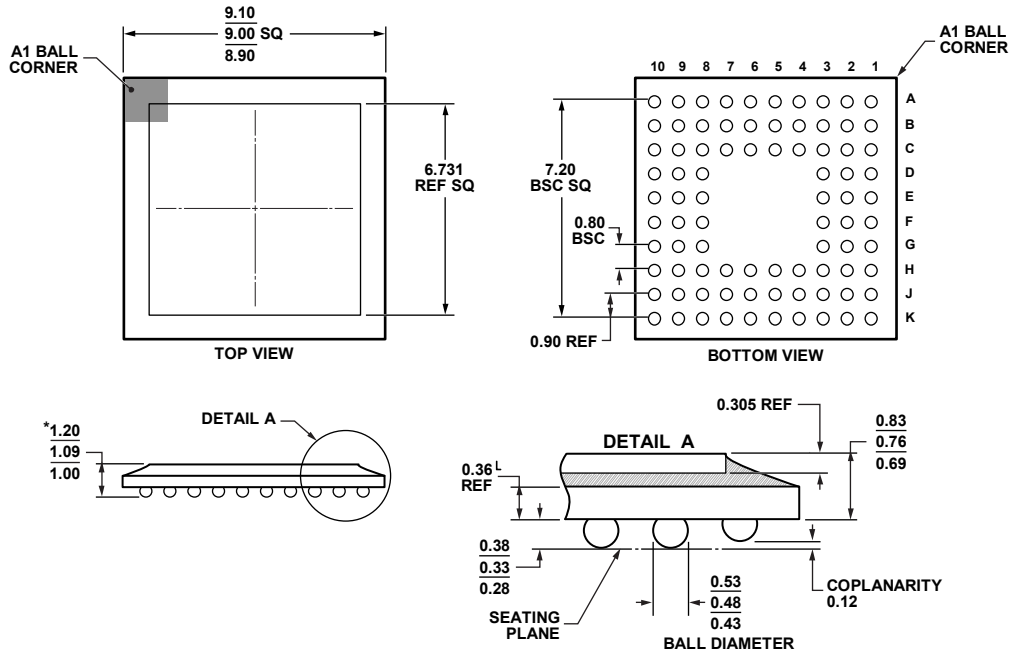


<sup>1</sup>THE OVD HIGH/LOW LEVEL DAC IS SHARED BY EACH CHANNEL; THEREFORE, ONLY ONE OVD HIGH/LOW VOLTAGE LEVEL CAN BE SET PER CHIP. THE OVD DACs PROVIDE A VOLTAGE RANGE OF -3V TO +7V. THE RECOMMENDED HIGH/LOW SETTINGS ARE +6.5V/-2.5V. (THESE VALUES NEED TO BE PROGRAMMED BY THE USER UPON STARTUP/RESET.)  
<sup>2</sup>THIS IS A READ ONLY REGISTER THAT ALLOWS THE USER TO DETERMINE THE CAUSE OF THE ACTIVE OVD FLAG.

07278-019

Figure 92. OVD Block Diagram

OUTLINE DIMENSIONS



\*COMPLIANT TO JEDEC STANDARDS MO-219 WITH EXCEPTION TO PACKAGE HEIGHT.

Figure 93. 84-Ball Chip Scale Package Ball Grid Array [CSP\_BGA] (BC-84-2)  
Dimensions shown in millimeters

022708-A

ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
ADATE302-02BBCZ <sup>1</sup>	-40°C to +85°C	84-Ball Chip Scale Package Ball Grid Array [CSP_BGA]	BC-84-2

<sup>1</sup> Z = RoHS Compliant Part.