

### FEATURES

- isoPower* integrated, isolated dc-to-dc converter
- Regulated 3.3 V or 5 V output
- 500 mW output power
- Quad dc-to-25 Mbps (NRZ) signal isolation channels
- Schmitt trigger inputs
- 16-lead SOIC package with >8 mm creepage
- High temperature operation: 105°C
- High common-mode transient immunity: >25 kV/μs
- Safety and regulatory approvals (pending)
  - UL recognition
    - 2500 V rms for 1 minute per UL1577
  - CSA Component Acceptance Notice #5A
  - VDE certificate of conformity
    - DIN V VDE V 0884-10 (VDE V 0884-10):2006-12
    - $V_{IORM} = 560$  V peak

### APPLICATIONS

- RS-232/RS-422/RS-485 transceiver
- Industrial field bus isolation
- Power supply startup bias and gate drive
- Isolated sensor interface
- Industrial PLC

### GENERAL DESCRIPTION

The ADuM5400<sup>1</sup> device is a quad-channel digital isolators with *isoPower*<sup>™</sup>, an integrated, isolated dc-to-dc converter. Based on the Analog Devices, Inc., *iCoupler*<sup>®</sup> technology, the dc-to-dc converter provides up to 500 mW of regulated, isolated power at either 5.0 V from a 5.0 V input supply or 3.3 V from a 3.3 V supply. This eliminates the need for a separate, isolated dc-to-dc converter in low power, isolated designs. The *iCoupler* chip scale transformer technology is used to isolate the logic signals and the magnetic components of the dc-to-dc converter. The result is a small form factor, total isolation solution.

The ADuM5400 isolator provides four independent isolation channels in a variety of channel configurations and data rates (see the Ordering Guide for more information).

<sup>1</sup> Protected by U.S. Patents 5,952,849; 6,873,065; and 7075 329 B2. Other patents pending.

### FUNCTIONAL BLOCK DIAGRAMS

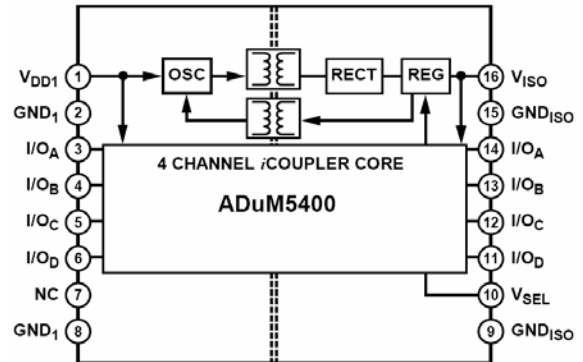


Figure 1.

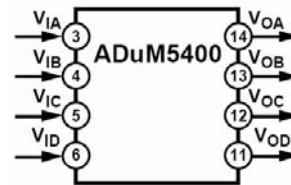


Figure 2. ADuM5400

### Rev. PrA

Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.

**TABLE OF CONTENTS**

Features .....	1	Pin Configurations and Function Descriptions .....	10
Applications .....	1	Typical Performance Characteristics .....	11
General Description .....	1	Terminology .....	13
Functional Block Diagrams .....	1	Applications Information .....	14
Revision History .....	2	Theory of Operation .....	14
Specifications .....	3	PC Board Layout .....	14
Electrical Characteristics—5 V Primary Input Supply/ 5 V Secondary Isolated Supply .....	3	Thermal Analysis .....	14
Electrical Characteristics—3.3 V Primary Input Supply/ 3.3 V Secondary Isolated Supply .....	5	Propagation Delay-Related Parameters .....	15
Package Characteristics .....	7	EMI Considerations .....	15
Regulatory Approvals .....	7	DC Correctness and Magnetic Field Immunity .....	15
Insulation and Safety-Related Specifications .....	7	Power Consumption .....	16
DIN V VDE V 0884-10 (VDE V 0884-10) Insulation Characteristics .....	8	Power Considerations .....	17
Recommended Operating Conditions .....	8	Insulation Lifetime .....	17
Absolute Maximum Ratings .....	9	Outline Dimensions .....	18
ESD Caution .....	9	Ordering Guide .....	18

**REVISION HISTORY**

# SPECIFICATIONS

## ELECTRICAL CHARACTERISTICS—5 V PRIMARY INPUT SUPPLY/5 V SECONDARY ISOLATED SUPPLY

4.5 V ≤ V<sub>DD1</sub> ≤ 5.5 V, V<sub>SEL</sub> = V<sub>ISO</sub>; all voltages are relative to their respective ground. All minimum/maximum specifications apply over the entire recommended operating range, unless otherwise noted. All typical specifications are at T<sub>A</sub> = 25°C, V<sub>DD1</sub> = 5.0 V, V<sub>SEL</sub> = V<sub>ISO</sub> = 5.0 V.

Table 1.

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions/Comments
<b>DC-TO-DC CONVERTER POWER SUPPLY</b>						
Setpoint	V <sub>ISO</sub>	4.7	5.0	5.4	V	I <sub>ISO</sub> = 0 mA
Line Regulation	V <sub>ISO(LINE)</sub>		1		mV/V	I <sub>ISO</sub> = 50 mA, V <sub>DD1</sub> = 4.5 V to 5.5 V
Load Regulation	V <sub>ISO(LOAD)</sub>		1	5	%	I <sub>ISO</sub> = 10 mA to 90 mA
Output Ripple	V <sub>ISO(RIP)</sub>		75		mV p-p	20 MHz bandwidth, C <sub>Bo</sub> = 0.1 μF    10 μF, I <sub>ISO</sub> = 90 mA
Output Noise	V <sub>ISO(N)</sub>		200		mV p-p	20 MHz bandwidth, C <sub>Bo</sub> = 0.1 μF    10 μF, I <sub>ISO</sub> = 90 mA
Switching Frequency	f <sub>OSC</sub>		180		MHz	
Pulse-Width Modulation Frequency	f <sub>PWM</sub>		625		kHz	
<b>iCoupler DATA CHANNELS</b>						
DC to 2 Mbps Data Rate <sup>1</sup>						
Maximum Output Supply Current <sup>2</sup>	I <sub>ISO(MAX)</sub>	100			mA	f ≤ 1 MHz, V <sub>ISO</sub> > 4.5 V
Efficiency at Maximum Output Supply Current <sup>3</sup>			34		%	I <sub>ISO</sub> = I <sub>ISO(2,MAX)</sub> , f ≤ 1 MHz
I <sub>DD1</sub> Supply Current, No V <sub>ISO</sub> Load	I <sub>DD1(Q)</sub>		19	30	mA	I <sub>ISO</sub> = 0 mA, f ≤ 1 MHz
25 Mbps Data Rate (CRWZ Grade Only)						
I <sub>DD1</sub> Supply Current, No V <sub>ISO</sub> Load ADuM5400	I <sub>DD1(D)</sub>		64		mA	I <sub>ISO</sub> = 0 mA, C <sub>L</sub> = 15 pF, f = 12.5 MHz
Available V <sub>ISO</sub> Supply Current <sup>4</sup> ADuM5400	I <sub>ISO(LOAD)</sub>		89		mA	C <sub>L</sub> = 15 pF, f = 12.5 MHz
I <sub>DD1</sub> Supply Current, Full V <sub>ISO</sub> Load	I <sub>DD1(MAX)</sub>		290		mA	C <sub>L</sub> = 0 pF, f = 0 MHz, V <sub>DD</sub> = 5 V, I <sub>ISO</sub> = 100 mA
I/O Input Currents	I <sub>IA</sub> , I <sub>IB</sub> , I <sub>IC</sub> , I <sub>ID</sub>	-20	+0.01	+20	μA	
Logic High Input Threshold	V <sub>IH</sub>	0.7 × V <sub>ISO</sub> , 0.7 × V <sub>DD1</sub>			V	
Logic Low Input Threshold	V <sub>IL</sub>			0.3 × V <sub>ISO</sub> , 0.3 × V <sub>DD1</sub>	V	
Logic High Output Voltages	V <sub>OAH</sub> , V <sub>OBH</sub> , V <sub>OCH</sub> , V <sub>ODH</sub>	V <sub>DD1</sub> - 0.3, V <sub>ISO</sub> - 0.3	5.0		V	I <sub>Ox</sub> = -20 μA, V <sub>Ix</sub> = V <sub>IxH</sub>
		V <sub>DD1</sub> - 0.5, V <sub>ISO</sub> - 0.3	4.8		V	I <sub>Ox</sub> = -4 mA, V <sub>Ix</sub> = V <sub>IxH</sub>
Logic Low Output Voltages	V <sub>OAL</sub> , V <sub>OBL</sub> , V <sub>OCL</sub> , V <sub>ODL</sub>		0.0	0.1	V	I <sub>Ox</sub> = 20 μA, V <sub>Ix</sub> = V <sub>IxL</sub>
			0.0	0.4	V	I <sub>Ox</sub> = 4 mA, V <sub>Ix</sub> = V <sub>IxL</sub>
<b>AC SPECIFICATIONS</b>						
ADuM5400ARWZ						
Minimum Pulse Width	PW			1000	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Maximum Data Rate		1			Mbps	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay	t <sub>PHL</sub> , t <sub>PLH</sub>		55	100	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Pulse Width Distortion,  t <sub>PLH</sub> - t <sub>PHL</sub>	PWD			40	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay Skew	t <sub>PSK</sub>			50	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Channel-to-Channel Matching	t <sub>PSKCD</sub> /t <sub>PSKOD</sub>			50	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
ADuM5400CRWZ						
Minimum Pulse Width	PW			40	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Maximum Data Rate		25			Mbps	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay	t <sub>PHL</sub> , t <sub>PLH</sub>		45	60	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Pulse Width Distortion,  t <sub>PLH</sub> - t <sub>PHL</sub>	PWD			6	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Change vs. Temperature			5		ps/°C	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay Skew	t <sub>PSK</sub>			15	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Channel-to-Channel Matching	t <sub>PSKCD</sub>			6	ns	C <sub>L</sub> = 15 pF, CMOS signal levels

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions/Comments
Codirectional Channels						
Channel-to-Channel Matching, Opposing Directional Channels	$t_{PSKOD}$			15	ns	$C_L = 15$ pF, CMOS signal levels
Output Rise/Fall Time (10% to 90%)	$t_R/t_F$		2.5		ns	$C_L = 15$ pF, CMOS signal levels
Common-Mode Transient Immunity at Logic High Output	$ CM_H $	25	35		kV/ $\mu$ s	$V_{IK} = V_{DD}$ or $V_{ISO}$ , $V_{CM} = 1000$ V, transient magnitude = 800 V
Common-Mode Transient Immunity at Logic Low Output	$ CM_L $	25	35		kV/ $\mu$ s	$V_{IK} = 0$ V, $V = 1000$ V, transient magnitude = 800 V
Refresh Rate	$f_r$		1.0		Mbps	

<sup>1</sup> The contributions of supply current values for all four channels are combined at identical data rates.

<sup>2</sup> The  $V_{ISO}$  supply current is available for external use when all data rates are below 2 Mbps. At data rates above 2 Mbps, the data I/O channels draw additional current proportional to the data rate. Additional supply current associated with an individual channel operating at a given data rate can be calculated as described in the Power Consumption section. The dynamic I/O channel load must be treated as an external load and included in the  $V_{ISO}$  power budget.

<sup>3</sup> The power demands of the quiescent operation of the data channels cannot be separated from the power supply section. Efficiency includes the quiescent power consumed by the I/O channels as part of the internal power consumption.

<sup>4</sup> This current is available for driving external loads at the  $V_{ISO}$  pin. All channels are simultaneously driven at a maximum data rate of 25 Mbps with full capacitive load representing the maximum dynamic load conditions. Refer to the Power Consumption section for calculation of available current at less than the maximum data rate.

**ELECTRICAL CHARACTERISTICS—3.3 V PRIMARY INPUT SUPPLY/3.3 V SECONDARY ISOLATED SUPPLY**

3.0 V ≤ V<sub>DD1</sub> ≤ 3.6 V, V<sub>SEL</sub> = GND<sub>ISO</sub>; all voltages are relative to their respective ground. All minimum/maximum specifications apply over the entire recommended operating range, unless otherwise noted. All typical specifications are at T<sub>A</sub> = 25°C, V<sub>DD1</sub> = 3.3 V, V<sub>ISO</sub> = 3.3 V, V<sub>SEL</sub> = GND<sub>ISO</sub>.

**Table 2.**

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions/Comments
<b>DC-TO-DC CONVERTER POWER SUPPLY</b>						
Setpoint	V <sub>ISO</sub>	3.0	3.3	3.6	V	I <sub>ISO</sub> = 0 mA
Line Regulation	V <sub>ISO(LINE)</sub>		1		mV/V	I <sub>ISO</sub> = 37.5 mA, V <sub>DD1</sub> = 3.0 V to 3.6 V
Load Regulation	V <sub>ISO(LOAD)</sub>		1	5	%	I <sub>ISO</sub> = 6 mA to 54 mA
Output Ripple	V <sub>ISO(RIP)</sub>		50		mV p-p	20 MHz bandwidth, C <sub>BO</sub> = 0.1 μF    10 μF, I <sub>ISO</sub> = 54 mA
Output Noise	V <sub>ISO(N)</sub>		130		mV p-p	20 MHz bandwidth, C <sub>BO</sub> = 0.1 μF    10 μF, I <sub>ISO</sub> = 54 mA
Switching Frequency	f <sub>OSC</sub>		180		MHz	
Pulse-Width Modulation Frequency	f <sub>PWM</sub>		625		kHz	
<b>iCoupler DATA CHANNELS</b>						
<b>DC to 2 Mbps Data Rate<sup>1</sup></b>						
Maximum Output Supply Current <sup>2</sup>	I <sub>ISO(MAX)</sub>	60			mA	f ≤ 1 MHz, V <sub>ISO</sub> > 3.0 V
Efficiency at Maximum Output Supply Current <sup>3</sup>			36		%	I <sub>ISO</sub> = I <sub>ISO(2,max)</sub> , f ≤ 1 MHz
I <sub>DD1</sub> Supply Current, No V <sub>ISO</sub> Load	I <sub>DD1(Q)</sub>		14	20	mA	I <sub>ISO</sub> = 0 mA, f ≤ 1 MHz
<b>25 Mbps Data Rate (CRWZ Grade Only)</b>						
I <sub>DD1</sub> Supply Current, No V <sub>ISO</sub> Load ADuM5400	I <sub>DD1(D)</sub>		41		mA	I <sub>ISO</sub> = 0 mA, C <sub>L</sub> = 15 pF, f = 12.5 MHz
Available V <sub>ISO</sub> Supply Current <sup>4</sup> ADuM5400	I <sub>ISO(LOAD)</sub>		43		mA	C <sub>L</sub> = 15 pF, f = 12.5 MHz
I <sub>DD1</sub> Supply Current, Full V <sub>ISO</sub> Load	I <sub>DD1(MAX)</sub>		175		mA	C <sub>L</sub> = 0 pF, f = 0 MHz, V <sub>DD</sub> = 3.3 V, I <sub>ISO</sub> = 60 mA
I/O Input Currents	I <sub>IA</sub> , I <sub>IB</sub> , I <sub>IC</sub> , I <sub>ID</sub>	-10	+0.01	+10	μA	
Logic High Input Threshold	V <sub>IH</sub>	0.7 × V <sub>ISO</sub> , 0.7 × V <sub>DD1</sub>			V	
Logic Low Input Threshold	V <sub>IL</sub>			0.3 × V <sub>ISO</sub> , 0.3 × V <sub>DD1</sub>	V	
Logic High Output Voltages	V <sub>OAH</sub> , V <sub>OBH</sub> , V <sub>OCH</sub> , V <sub>ODH</sub>	V <sub>DD1</sub> - 0.2, V <sub>ISO</sub> - 0.2	5.0		V	I <sub>OX</sub> = -20 μA, V <sub>IX</sub> = V <sub>IxH</sub>
		V <sub>DD1</sub> - 0.5, V <sub>ISO</sub> - 0.5	4.8		V	I <sub>OX</sub> = -4 mA, V <sub>IX</sub> = V <sub>IxH</sub>
Logic Low Output Voltages	V <sub>OAL</sub> , V <sub>OBL</sub> , V <sub>OCL</sub> , V <sub>ODL</sub>		0.0	0.1	V	I <sub>OX</sub> = 20 μA, V <sub>IX</sub> = V <sub>IxL</sub>
			0.0	0.4	V	I <sub>OX</sub> = 4 mA, V <sub>IX</sub> = V <sub>IxL</sub>
<b>AC SPECIFICATIONS</b>						
<b>ADuM5400ARWZ</b>						
Minimum Pulse Width	PW			1000	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Maximum Data Rate		1			Mbps	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay	t <sub>PHL</sub> , t <sub>PLH</sub>		60	100	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Pulse Width Distortion,  t <sub>PLH</sub> - t <sub>PHL</sub>	PWD			40	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay Skew	t <sub>PSK</sub>			50	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Channel-to-Channel Matching	t <sub>PSKCD</sub> /t <sub>PSKOD</sub>			50	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
<b>ADuM5400CRWZ</b>						
Minimum Pulse Width	PW			40	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Maximum Data Rate		25			Mbps	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay	t <sub>PHL</sub> , t <sub>PLH</sub>		45	60	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Pulse Width Distortion,  t <sub>PLH</sub> - t <sub>PHL</sub>   Change vs. Temperature	PWD		5	6	ps/°C	C <sub>L</sub> = 15 pF, CMOS signal levels
Propagation Delay Skew	t <sub>PSK</sub>			45	ns	C <sub>L</sub> = 15 pF, CMOS signal levels
Channel-to-Channel Matching, Codirectional Channels	t <sub>PSKCD</sub>			6	ns	C <sub>L</sub> = 15 pF, CMOS signal levels

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions/Comments
Channel-to-Channel Matching, Opposing Directional Channels	$t_{PSKOD}$			15	ns	$C_L = 15$ pF, CMOS signal levels
Output Rise/Fall Time (10% to 90%)	$t_R/t_F$		2.5		ns	$C_L = 15$ pF, CMOS signal levels
Common-Mode Transient Immunity at Logic High Output	$ CM_H $	25	35		kV/ $\mu$ s	$V_{IX} = V_{DD}$ or $V_{ISO}$ , $V_{CM} = 1000$ V, transient magnitude = 800 V
Common-Mode Transient Immunity at Logic Low Output	$ CM_L $	25	35		kV/ $\mu$ s	$V_{IX} = 0$ V, $V = 1000$ V, transient magnitude = 800 V
Refresh Rate	$f_r$		1.0		Mbps	

<sup>1</sup> The contributions of supply current values for all four channels are combined at identical data rates.

<sup>2</sup> The  $V_{ISO}$  supply current is available for external use when all data rates are below 2 Mbps. At data rates above 2 Mbps, the data I/O channels draw additional current proportional to the data rate. Additional supply current associated with an individual channel operating at a given data rate can be calculated as described in the Power Consumption section. The dynamic I/O channel load must be treated as an external load and included in the  $V_{ISO}$  power budget.

<sup>3</sup> The power demands of the quiescent operation of the data channels cannot be separated from the power supply section. Efficiency includes the quiescent power consumed by the I/O channels as part of the internal power consumption.

<sup>4</sup> This current is available for driving external loads at the  $V_{ISO}$  pin. All channels are simultaneously driven at a maximum data rate of 25 Mbps with full capacitive load representing the maximum dynamic load conditions. Refer to the Power Consumption section for calculation of available current at less than the maximum data rate.

**PACKAGE CHARACTERISTICS**

Table 3.

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Resistance (Input to Output) <sup>1</sup>	R <sub>I-O</sub>		10 <sup>12</sup>		Ω	f = 1 MHz
Capacitance (Input to Output) <sup>1</sup>	C <sub>I-O</sub>		2.2		pF	
Input Capacitance <sup>2</sup>	C <sub>i</sub>		4.0		pF	Thermocouple located at center of package underside, test conducted on four-layer board with thin traces. <sup>3</sup>
IC Junction to Ambient Thermal Resistance	θ <sub>JA</sub>		45		°C/W	

<sup>1</sup> The device is considered a 2-terminal device: Pin 1 to Pin 8 are shorted together; and Pin 9 to Pin 16 are shorted together.

<sup>2</sup> Input capacitance is from any input data pin to ground.

<sup>3</sup> See the Thermal Analysis section for thermal model definitions.

**REGULATORY APPROVALS**

Table 4.

UL (Pending)	CSA (Pending)	VDE (Pending)
Recognized under the UL1577 component recognition program <sup>1</sup>	Approved under CSA Component Acceptance Notice #5A	Certified according to DIN V VDE V 0884-10 (VDE V 0884-10):2006-12 <sup>2</sup>
Reinforced insulation, 2500 V rms isolation voltage	Reinforced insulation per CSA 60950-1-03 and IEC 60950-1, 300 V rms (424 V peak) maximum working voltage	Reinforced insulation, 560 V peak
File E214100	File 205078	File 2471900-4880-0001

<sup>1</sup> In accordance with UL1577, each ADuM5400 is proof tested by applying an insulation test voltage of ≥3000 V rms for 1 sec (current leakage detection limit = 10 μA).

<sup>2</sup> In accordance with DIN V VDE V 0884-10, each of the ADuM5400 is proof tested by applying an insulation test voltage of ≥1050 V peak for 1 sec (partial discharge detection limit = 5 pC). The asterisk (\*) marking branded on the component designates DIN V VDE V 0884-10 approval.

**INSULATION AND SAFETY-RELATED SPECIFICATIONS**

Table 5.

Parameter	Symbol	Value	Unit	Test Conditions/Comments
Rated Dielectric Insulation Voltage		2500	V rms	1 minute duration
Minimum External Air Gap (Clearance)	L(I01)	>8.0	mm	Measured from input terminals to output terminals, shortest distance through air
Minimum External Tracking (Creepage)	L(I02)	>8.0	mm	Measured from input terminals to output terminals, shortest distance path along body
Minimum Internal Gap (Internal Clearance)		0.017 min	mm	Distance through insulation
Tracking Resistance (Comparative Tracking Index)	CTI	>175	V	DIN IEC 112/VDE 0303 Part 1
Isolation Group		IIIa		Material Group (DIN VDE 0110, 1/89, Table 1)

## DIN V VDE V 0884-10 (VDE V 0884-10) INSULATION CHARACTERISTICS

These isolators are suitable for reinforced electrical isolation only within the safety limit data. Maintenance of the safety data is ensured by protective circuits. The asterisk (\*) marking on packages denotes DIN V VDE V 0884-10 approval.

Table 6.

Description	Conditions	Symbol	Characteristic	Unit
Installation Classification per DIN VDE 0110 For Rated Mains Voltage ≤ 150 V rms For Rated Mains Voltage ≤ 300 V rms For Rated Mains Voltage ≤ 400 V rms			I to IV I to III I to II	
Climatic Classification			40/105/21	
Pollution Degree per DIN VDE 0110, Table 1			2	
Maximum Working Insulation Voltage		$V_{IORM}$	560	V peak
Input-to-Output Test Voltage, Method B1	$V_{IORM} \times 1.875 = V_{PR}$ , 100% production test, $t_m = 1$ sec, partial discharge < 5 pC	$V_{PR}$	1050	V peak
Input-to-Output Test Voltage, Method A		$V_{PR}$		
After Environmental Tests Subgroup 1	$V_{IORM} \times 1.6 = V_{PR}$ , $t_m = 60$ sec, partial discharge < 5 pC		896	V peak
After Input and/or Safety Test Subgroup 2 and Subgroup 3	$V_{IORM} \times 1.2 = V_{PR}$ , $t_m = 60$ sec, partial discharge < 5 pC		672	V peak
Highest Allowable Overvoltage	Transient overvoltage, $t_{TR} = 10$ sec	$V_{TR}$	4000	V peak
Safety Limiting Values	Maximum value allowed in the event of a failure (see Figure 3)			
Case Temperature		$T_S$	150	°C
Side 1 Current		$I_{S1}$	265	mA
Side 2 Current		$I_{S2}$	335	mA
Insulation Resistance at $T_S$	$V_{IO} = 500$ V	$R_S$	>10 <sup>9</sup>	Ω

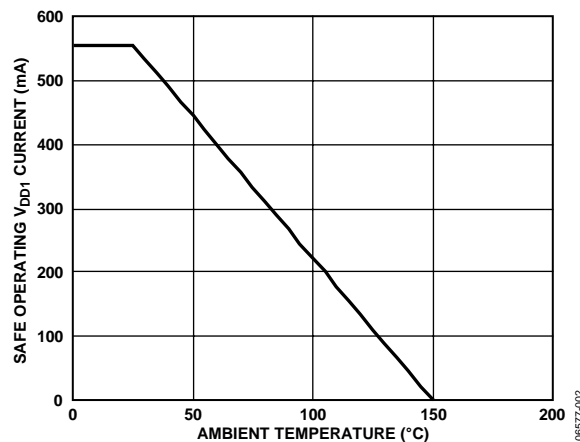


Figure 3. Thermal Derating Curve, Dependence of Safety Limiting Values on Case Temperature, per DIN EN 60747-5-2

## RECOMMENDED OPERATING CONDITIONS

Table 7.

Parameter	Symbol	Min	Max	Unit
Operating Temperature	$T_A$	-40	+105	°C
Supply Voltages <sup>1</sup>				
$V_{DD1}$ @ $V_{SEL} = 0$ V	$V_{DD}$	3.0	3.6	V
$V_{DD1}$ @ $V_{SEL} = 5$ V	$V_{DD}$	4.5	5.5	V
Minimum Load	$I_{ISO(MIN)}$	10		mA

<sup>1</sup> All voltages are relative to their respective ground.



## ABSOLUTE MAXIMUM RATINGS

Ambient temperature = 25°C, unless otherwise noted.

Table 8.

Parameter	Rating
Storage Temperature ( $T_{ST}$ )	-55°C to +150°C
Ambient Operating Temperature ( $T_A$ )	-40°C to +105°C
Supply Voltages ( $V_{DD}$ , $V_{ISO}$ ) <sup>1</sup>	-0.5 V to +7.0 V
Input Voltage ( $V_{IA}$ , $V_{IB}$ , $V_{IC}$ , $V_{ID}$ , $V_{SEL}$ ) <sup>1,2</sup>	-0.5 V to $V_{DD1}$ + 0.5 V
Output Voltage ( $V_{OA}$ , $V_{OB}$ , $V_{OC}$ , $V_{OD}$ ) <sup>1,2</sup>	-0.5 V to $V_{DD0}$ + 0.5 V
Average Output Current per Pin <sup>3</sup>	
Side 1 ( $I_{O1}$ )	-18 mA to +18 mA
Side 2 ( $I_{O2}$ )	-22 mA to +22 mA
Common-Mode Transients <sup>4</sup>	-100 kV/μs to +100 kV/μs

<sup>1</sup> All voltages are relative to their respective ground.

<sup>2</sup>  $V_{DD1}$  and  $V_{DD0}$  refer to the supply voltages on the input and output sides of a given channel, respectively. See the PC Board Layout section.

<sup>3</sup> See Figure 3 for maximum rated current values for various temperatures.

<sup>4</sup> Refers to common-mode transients across the insulation barrier. Common-mode transients exceeding the absolute maximum ratings may cause latch-up or permanent damage.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

Table 9. Maximum Continuous Working Voltage Supporting 50-Year Minimum Lifetime<sup>1</sup>

Parameter	Max	Unit	Applicable Certification
AC Voltage, Bipolar Waveform	424	V peak	All certifications
AC Voltage, Unipolar Waveform			
Basic Insulation	600	V peak	Working voltage per IEC 60950-1
Reinforced Insulation	560	V peak	Working voltage per VDE V 0884-10
DC Voltage			
Basic Insulation	600	V peak	Working voltage per IEC 60950-1
Reinforced Insulation	560	V peak	Working voltage per VDE V 0884-10

<sup>1</sup> Refers to the continuous voltage magnitude imposed across the isolation barrier. See the Insulation Lifetime section for more information.

Table 10. Truth Table (Positive Logic)

$V_{ix}$ Input <sup>1</sup>	$V_{SEL}$ Input	$V_{DD1}$ State	$V_{DD1}$ Input (V)	$V_{iso}$ State	$V_{iso}$ Output (V)	$V_{ox}$ Output <sup>1</sup>	Notes
High	High	Powered	5.0	Powered	5.0	High	Normal operation, data is high
Low	High	Powered	5.0	Powered	5.0	Low	Normal operation, data is low
High	Low	Powered	3.3	Powered	3.3	High	Normal operation, data is high
Low	Low	Powered	3.3	Powered	3.3	Low	Normal operation, data is low
High	Low	Powered	5.0	Powered	3.3	High	Configuration not recommended
Low	Low	Powered	5.0	Powered	3.3	Low	Configuration not recommended
High	High	Powered	3.3	Powered	5.0	High	Configuration not recommended
Low	High	Powered	3.3	Powered	5.0	Low	Configuration not recommended

<sup>1</sup>  $V_{ix}$  and  $V_{ox}$  refer to the input and output signals of a given channel (A, B, C, or D).

## PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

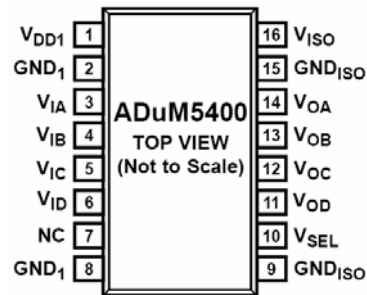


Figure 4. ADuM5400 Pin Configuration

Table 11. ADuM5400 Pin Function Descriptions

Pin No.	Mnemonic	Description
1	V <sub>DD1</sub>	Primary Supply Voltage, 3.0 V to 5.5 V.
2, 8	GND <sub>1</sub>	Ground 1. Ground reference for isolator primary. Pin 2 and Pin 8 are internally connected, and it is recommended that both pins be connected to a common ground.
3	V <sub>IA</sub>	Logic Input A.
4	V <sub>IB</sub>	Logic Input B.
5	V <sub>IC</sub>	Logic Input C.
6	V <sub>ID</sub>	Logic Input D.
7	NC	Make no connection to this pin.
9, 15	GND <sub>ISO</sub>	Ground Reference for Isolator Side 2. Pin 9 and Pin 15 are internally connected, and it is recommended that both pins be connected to a common ground.
10	V <sub>SEL</sub>	Output Voltage Selection. When V <sub>SEL</sub> = V <sub>ISO</sub> , the V <sub>ISO</sub> setpoint is 5.0 V. When V <sub>SEL</sub> = GND <sub>ISO</sub> , the V <sub>ISO</sub> setpoint is 3.3 V. V <sub>DD1</sub> and V <sub>ISO</sub> voltages must be in the same operating range to guarantee proper operation of the data channels.
11	V <sub>OD</sub>	Logic Output D.
12	V <sub>OC</sub>	Logic Output C.
13	V <sub>OB</sub>	Logic Output B.
14	V <sub>OA</sub>	Logic Output A.
16	V <sub>ISO</sub>	Secondary Supply Voltage Output for External Loads, 3.3 V (V <sub>SEL</sub> Low) or 5.0 V (V <sub>SEL</sub> High). V <sub>DD1</sub> and V <sub>ISO</sub> voltages must be in the same operating range to guarantee proper operation of the data channels.

### TYPICAL PERFORMANCE CHARACTERISTICS

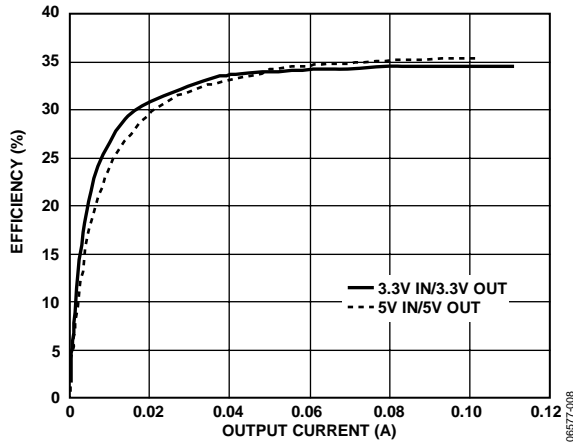


Figure 5. Typical Power Supply Efficiency at 5 V/5 V and 3.3 V/3.3 V

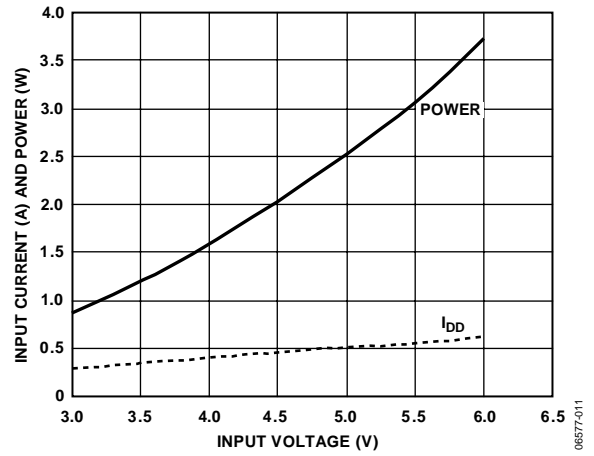


Figure 8. Typical Short-Circuit Input Current and Power vs.  $V_{DD}$  Supply Voltage

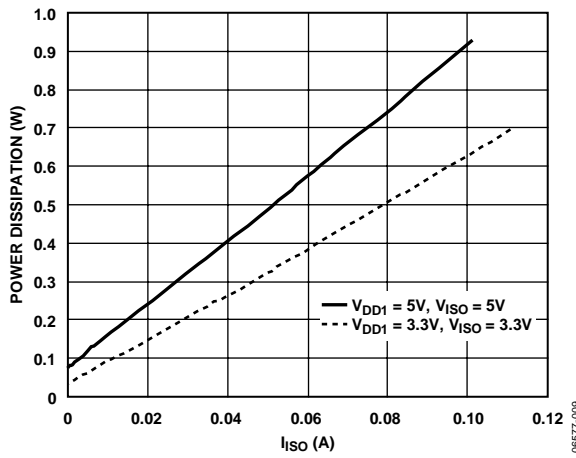


Figure 6. Typical Total Power Dissipation vs.  $I_{ISO}$  with Data Channels Idle

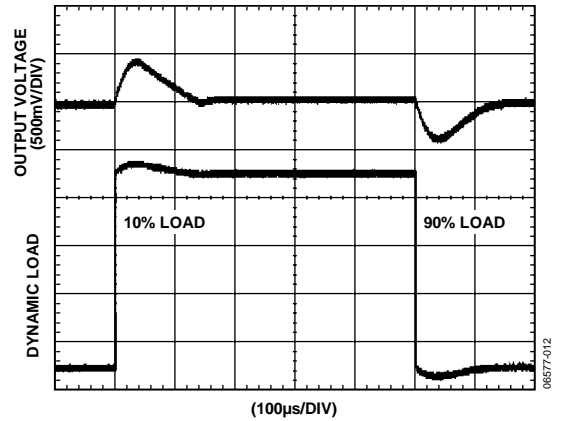


Figure 9. Typical  $V_{ISO}$  Transient Load Response, 5 V Output, 10% to 90% Load Step

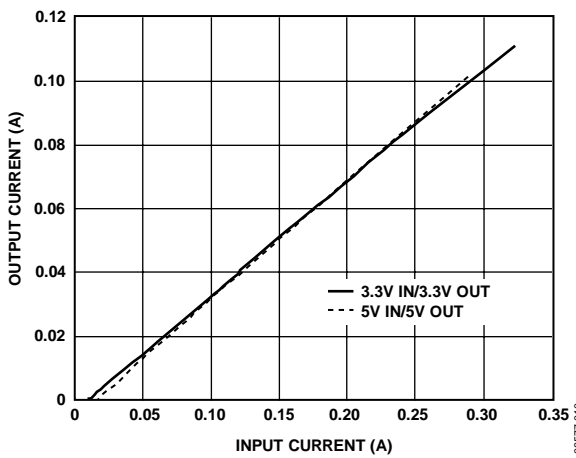


Figure 7. Typical Isolated Output Supply Current,  $I_{ISO}$ , as a Function of External Load, No Dynamic Current Draw at 5 V/5 V and 3.3 V/3.3 V

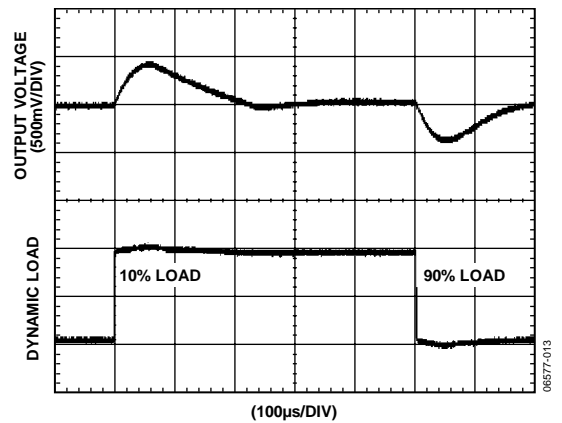


Figure 10. Typical Transient Load Response, 3 V Output, 10% to 90% Load Step

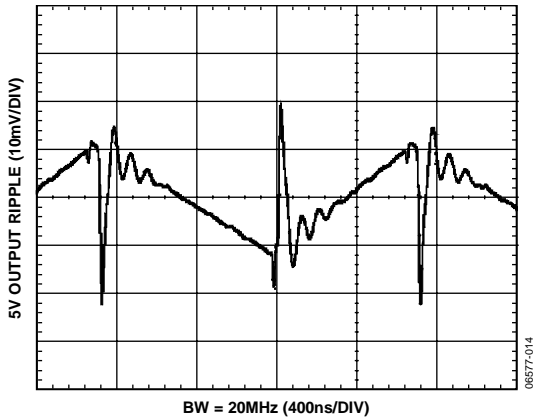


Figure 11. Typical  $V_{ISO} = 5\text{ V}$  Output Voltage Ripple at 90% Load

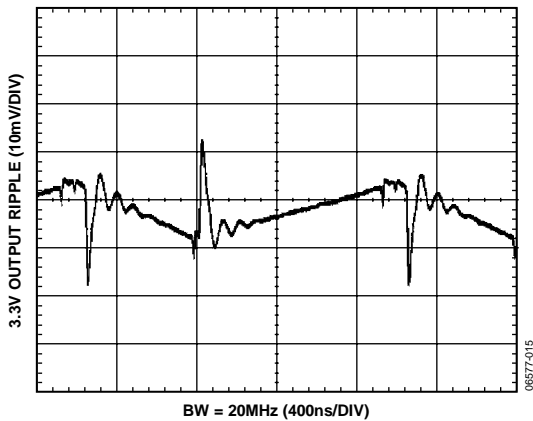


Figure 12. Typical  $V_{ISO} = 3.3\text{ V}$  Output Voltage Ripple at 90% Load

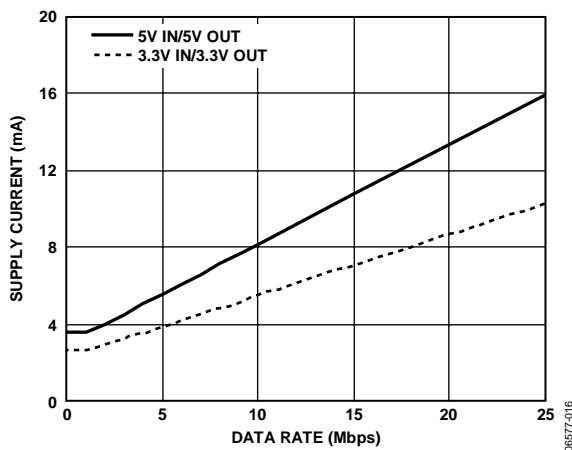


Figure 13. Typical  $I_{CH}$  Supply Current per Forward Data Channel (15 pF Output Load)

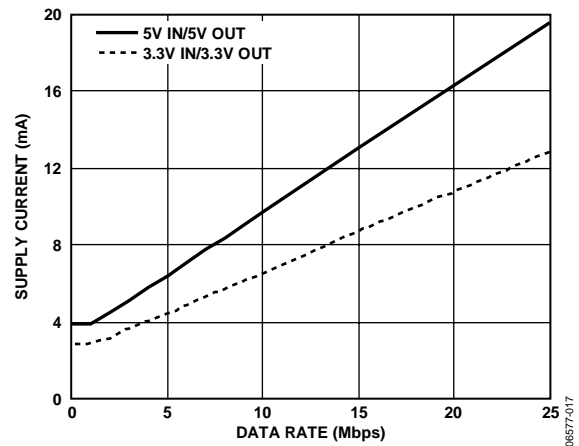


Figure 14. Typical  $I_{CH}$  Supply Current per Reverse Data Channel (15 pF Output Load)

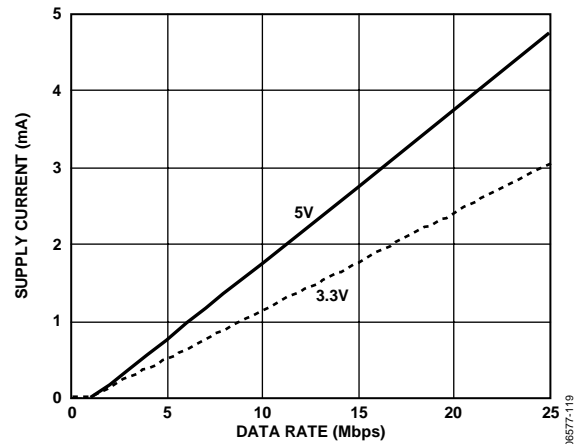


Figure 15. Typical  $I_{ISO(D)}$  Dynamic Supply Current per Input

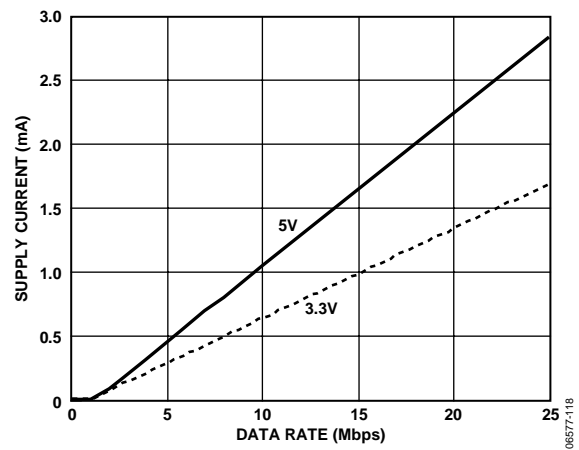


Figure 16. Typical  $I_{ISO(D)}$  Dynamic Supply Current per Output (15 pF Output Load)

## TERMINOLOGY

### $I_{DD1(Q)}$

$I_{DD1(Q)}$  is the minimum operating current drawn at the  $V_{DD1}$  pin when there is no external load at  $V_{ISO}$  and the I/O pins are operating below 2 Mbps, requiring no additional dynamic supply current.  $I_{DDIO(Q)}$  reflects the minimum current operating condition.

### $I_{DD1(D)}$

$I_{DD1(D)}$  is the typical input supply current with all channels simultaneously driven at maximum data rate of 25 Mbps with full capacitive load representing the maximum dynamic load conditions. Resistive loads on the outputs should be treated separately from the dynamic load.

### $I_{DD1(MAX)}$

$I_{DD1(MAX)}$  is the input current under full dynamic and  $V_{ISO}$  load conditions.

### $t_{PHL}$ Propagation Delay

$t_{PHL}$  propagation delay is measured from the 50% level of the falling edge of the  $V_{IX}$  signal to the 50% level of the falling edge of the  $V_{OX}$  signal.

### $t_{PLH}$ Propagation Delay

$t_{PLH}$  propagation delay is measured from the 50% level of the rising edge of the  $V_{IX}$  signal to the 50% level of the rising edge of the  $V_{OX}$  signal.

### Propagation Delay Skew ( $t_{PSK}$ )

$t_{PSK}$  is the magnitude of the worst-case difference in  $t_{PHL}$  and/or  $t_{PLH}$  that is measured between units at the same operating temperature, supply voltages, and output load within the recommended operating conditions.

### Channel-to-Channel Matching

Channel-to-channel matching is the absolute value of the difference in propagation delays between the two channels when operated with identical loads.

### Minimum Pulse Width

The minimum pulse width is the shortest pulse width at which the specified pulse width distortion is guaranteed.

### Maximum Data Rate

The maximum data rate is the fastest data rate at which the specified pulse width distortion is guaranteed.

## APPLICATIONS INFORMATION

### THEORY OF OPERATION

The dc-to-dc converter section of the ADuM5400 works on principles that are common to most modern power supplies. It is a secondary side controller architecture with isolated pulse-width modulation (PWM) feedback.  $V_{DD1}$  power is supplied to an oscillating circuit that switches current into a chip-scale air core transformer. Power transferred to the secondary side is rectified and regulated to either 3.3 V or

5 V. The secondary ( $V_{ISO}$ ) side controller regulates the output by creating a PWM control signal that is sent to the primary ( $V_{DD1}$ ) side by a dedicated iCoupler data channel. The PWM modulates the oscillator circuit to control the power being sent to the secondary side. Feedback allows for significantly higher power and efficiency.

The ADuM5400 implements under voltage lockout (UVLO) with hysteresis on the  $V_{DD1}$  power input. This feature ensures that the converter does not go into oscillation due to noisy input power or slow power on ramp rates.

A minimum load current of 10 mA is recommended to ensure optimum load regulation. Smaller loads can generate excess noise on chip due to short or erratic PWM pulses. Excess noise generated this way can cause data corruption, in some circumstances.

### PC BOARD LAYOUT

The ADuM5400 digital isolator with 0.5 W *isoPower* integrated dc-to-dc converters requires no external interface circuitry for the logic interfaces. Power supply bypassing is required at the input and output supply pins (Figure 17). Note that a low ESR bypass capacitor is required between Pin 1 and Pin 2, as close to the chip pads as possible.

The power supply section of the ADuM5400 uses a very high oscillator frequency to efficiently pass power through its chip scale transformers. In addition, normal operation of the data section of the iCoupler introduces switching transients on the power supply pins. Bypass capacitors are required for several operating frequencies. Noise suppression requires a low inductance, high frequency capacitor; ripple suppression and proper regulation require a large value capacitor. These are most conveniently connected between Pin 1 and Pin 2 for  $V_{DD1}$  and between Pin 15 and Pin 16 for  $V_{ISO}$ . To suppress noise and reduce ripple, a parallel combination of at least two capacitors is required. The recommended capacitor values are 0.1  $\mu\text{F}$  and 33  $\mu\text{F}$  for  $V_{DD1}$ . The smaller capacitor must have a low ESR; for example, use of a ceramic capacitor is advised.

Note that the total lead length between the ends of the low ESR capacitor and the input power supply pin must not exceed 2 mm. Installing the bypass capacitor with traces more than 2 mm in length may result in data corruption. A bypass between Pin 1 and Pin 8 and between Pin 9 and Pin 16 should also be considered unless both common ground pins are connected together close to the package.

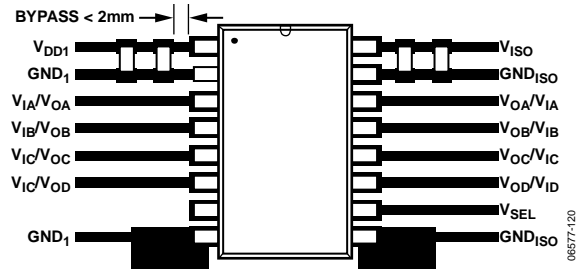


Figure 17. Recommended Printed Circuit Board Layout

In applications involving high common-mode transients, care should be taken to ensure that board coupling across the isolation barrier is minimized. Furthermore, the board layout should be designed such that any coupling that does occur equally affects all pins on a given component side. Failure to ensure this could cause voltage differentials between pins, exceeding the Absolute Maximum Ratings specified in Table 8, thereby leading to latch-up and/or permanent damage.

The ADuM5400 is a power device that dissipates about 1 W of power when fully loaded and running at maximum speed. Because it is not possible to apply a heat sink to an isolation device, the devices primarily depend on heat dissipation into the PCB through the GND pins. If the devices are used at high ambient temperatures, care should be taken to provide a thermal path from the GND pins to the PCB ground plane. The board layout in Figure 17 shows enlarged pads for Pin 8 and Pin 9. Large diameter vias should be implemented from the pad to the ground, and power planes should be used to reduce inductance. Multiple vias in the thermal pads can significantly reduce temperatures inside the chip. The dimensions of the expanded pads are left to the discretion of the designer and the available board space.

### THERMAL ANALYSIS

The ADuM5400 part consists of four internal die attached to a split lead frame with two die attach paddles. For the purposes of thermal analysis, the die are treated as a thermal unit, with the highest junction temperature reflected in the  $\theta_{JA}$  from Table 3. The value of  $\theta_{JA}$  is based on measurements taken with the parts mounted on a JEDEC standard, four-layer board with fine width traces and still air. Under normal operating conditions, the ADuM5400 device operates at full load across the full temperature range without derating the output current. However, following the recommendations in the PC Board Layout section decreases thermal resistance to the PCB, allowing increased thermal margins in high ambient temperatures.

**PROPAGATION DELAY-RELATED PARAMETERS**

Propagation delay is a parameter that describes the time it takes a logic signal to propagate through a component (see Figure 18). The propagation delay to a logic low output may differ from the propagation delay to a logic high.

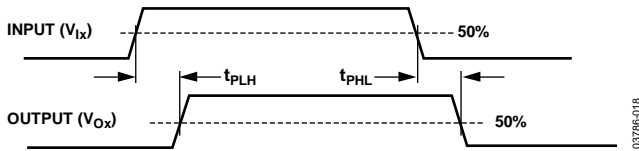


Figure 18. Propagation Delay Parameters

Pulse width distortion is the maximum difference between these two propagation delay values and is an indication of how accurately the input signal timing is preserved.

Channel-to-channel matching refers to the maximum amount the propagation delay differs between channels within a single ADuM5400 component.

Propagation delay skew refers to the maximum amount the propagation delay differs between multiple ADuM540x components operating under the same conditions.

**EMI CONSIDERATIONS**

The dc-to-dc converter section of the ADuM5400 component must, of necessity, operate at very high frequency to allow efficient power transfer through the small transformers. This creates high frequency currents that can propagate in circuit board ground and power planes, causing edge and dipole radiation. Grounded enclosures are recommended for applications that use these devices. If grounded enclosures are not possible, good RF design practices should be followed in layout of the PCB. See [www.analog.com](http://www.analog.com) for the most current PCB layout recommendations specifically for the ADuM5400.

**DC CORRECTNESS AND MAGNETIC FIELD IMMUNITY**

Positive and negative logic transitions at the isolator input cause narrow (~1 ns) pulses to be sent to the decoder via the transformer. The decoder is bistable and is, therefore, either set or reset by the pulses, indicating input logic transitions. In the absence of logic transitions at the input for more than 1 μs, periodic sets of refresh pulses indicative of the correct input state are sent to ensure dc correctness at the output. If the decoder receives no internal pulses of more than approximately 5 μs, the input side is assumed to be unpowered or nonfunctional, in which case the isolator output is forced to a default state (see Table 10) by the watchdog timer circuit. This situation should occur in the ADuM5400 device only during power-up and power-down operations.

The limitation on the ADuM5400 magnetic field immunity is set by the condition in which induced voltage in the transformer receiving coil is sufficiently large to either falsely set or reset the decoder. The following analysis defines the conditions under which this can occur.

The 3.3 V operating condition of the ADuM5400 is examined because it represents the most susceptible mode of operation.

The pulses at the transformer output have an amplitude of >1.0 V. The decoder has a sensing threshold of about 0.5 V, thus establishing a 0.5 V margin in which induced voltages can be tolerated. The voltage induced across the receiving coil is given by

$$V = (-d\beta/dt)\sum\pi r_n^2; n = 1, 2, \dots, N$$

where:

$\beta$  is magnetic flux density (gauss).

$N$  is the number of turns in the receiving coil.

$r_n$  is the radius of the  $n^{\text{th}}$  turn in the receiving coil (cm).

Given the geometry of the receiving coil in the ADuM5400, and an imposed requirement that the induced voltage be, at most, 50% of the 0.5 V margin at the decoder, a maximum allowable magnetic field is calculated as shown in Figure 19.

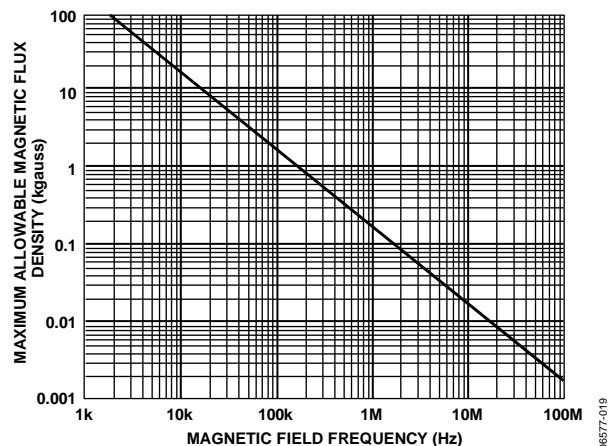


Figure 19. Maximum Allowable External Magnetic Flux Density

For example, at a magnetic field frequency of 1 MHz, the maximum allowable magnetic field of 0.2 kgauss induces a voltage of 0.25 V at the receiving coil. This is about 50% of the sensing threshold and does not cause a faulty output transition. Similarly, if such an event occurs during a transmitted pulse (and is of the worst-case polarity), it reduces the received pulse from >1.0 V to 0.75 V, which is still well above the 0.5 V sensing threshold of the decoder.

The preceding magnetic flux density values correspond to specific current magnitudes at given distances from the ADuM5400 transformers. Figure 20 expresses these allowable current magnitudes as a function of frequency for selected distances. As shown in Figure 20, the ADuM5400 is extremely immune and can be affected only by extremely large currents operated at high frequency very close to the component. For the 1 MHz example, a 0.5 kA current would need to be placed 5 mm away from the ADuM5400 to affect component operation.

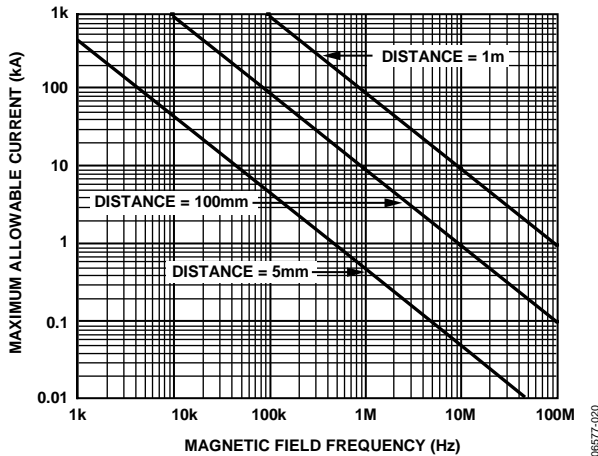


Figure 20. Maximum Allowable Current for Various Current-to-ADuM5400 Spacings

Note that in combinations of strong magnetic field and high frequency, any loops formed by printed circuit board traces could induce error voltages sufficiently large to trigger the thresholds of succeeding circuitry. Care should be taken in the layout of such traces to avoid this possibility.

## POWER CONSUMPTION

The  $V_{DD1}$  power supply input provides power to the *iCoupler* data channels, as well as to the power converter. For this reason, the quiescent currents drawn by the data converter and the primary and secondary I/O channels cannot be determined separately. All of these quiescent power demands have been combined into the  $I_{DD1(Q)}$  current, as shown in Figure 21. The total  $I_{DD1}$  supply current is equal to the sum of the quiescent operating current; the dynamic current,  $I_{DD1(D)}$ , demanded by the I/O channels; and any external  $I_{ISO}$  load.

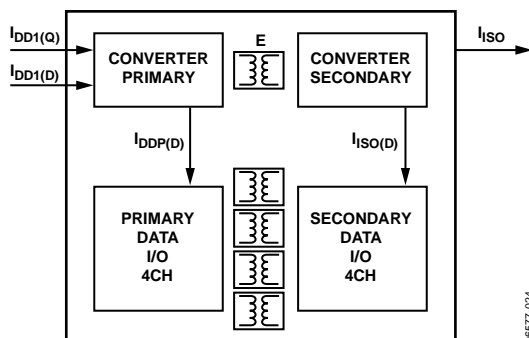


Figure 21. Power Consumption Within the ADuM5400

Dynamic I/O current is consumed only when operating a channel at speeds higher than the refresh rate of  $f_r$ . The dynamic current of each channel is determined by its data rate. Figure 13 shows the current for a channel in the forward direction, meaning that the input is on the  $V_{DD1}$  side of the part. Figure 14 shows the current for a channel in the reverse direction, meaning that the input is on the  $V_{ISO}$  side of the part. Both figures assume a typical 15 pF load.

The following relationship allows the total  $I_{DD1}$  current to be calculated:

$$I_{DD1} = (I_{ISO} \times V_{ISO}) / (E \times V_{DD1}) + \sum I_{CHn}; n = 1 \text{ to } 4 \quad (1)$$

where:

$I_{DD1}$  is the total supply input current.

$I_{CHn}$  is the current drawn by a single channel determined from Figure 13 or Figure 14, depending on channel direction.

$I_{ISO}$  is the current drawn by the secondary side external load.

$E$  is the power supply efficiency at 100 mA load from Figure 5 at the  $V_{ISO}$  and  $V_{DD1}$  condition of interest.

The maximum external load can be calculated by subtracting the dynamic output load from the maximum allowable load.

$$I_{ISO(LOAD)} = I_{ISO(MAX)} - \sum I_{ISO(D)n}; n = 1 \text{ to } 4 \quad (2)$$

where:

$I_{ISO(LOAD)}$  is the current available to supply an external secondary side load.

$I_{ISO(MAX)}$  is the maximum external secondary side load current available at  $V_{ISO}$ .

$I_{ISO(D)n}$  is the dynamic load current drawn from  $V_{ISO}$  by an input or output channel, as shown in Figure 15 and Figure 16.

The preceding analysis assumes a 15 pF capacitive load on each data output. If the capacitive load is larger than 15 pF, the additional current must be included in the analysis of  $I_{DD1}$  and  $I_{ISO(LOAD)}$ .



**POWER CONSIDERATIONS**

The ADuM5400 power input, the data input channels on the primary side, and the data input channels on the secondary side are all protected from premature operation by UVLO circuitry. Below the minimum operating voltage, the power converter holds its oscillator inactive, and all input channel drivers and refresh circuits are idle. Outputs are held in a low state. This is to prevent transmission of undefined states during power-up and power-down operations.

During application of power to  $V_{DD1}$ , the primary side circuitry is held idle until the UVLO preset voltage is reached. At that time, the data channels are initialized to their default low output state until they receive data pulses from the secondary side.

The primary side input channels sample the input and send a pulse to the inactive secondary output. The secondary side converter begins to accept power from the primary, and the  $V_{ISO}$  voltage starts to rise. When the secondary side UVLO is reached, the secondary side outputs are initialized to their default low state until data, either a transition or a dc refresh pulse, is received from the corresponding primary side input. It can take up to 1  $\mu$ s after the secondary side is initialized for the state of the output to correlate with the primary side input.

Secondary side inputs sample their state and transmit it to the primary side. Outputs are valid one propagation delay after the secondary side becomes active.

Because the rate of charge of the secondary side is dependent on loading conditions, input voltage, and output voltage level selected, care should be taken in the design to allow the converter to stabilize before valid data is required.

When power is removed from  $V_{DD1}$ , the primary side converter and coupler shut down when the UVLO level is reached. The secondary side stops receiving power and starts to discharge. The outputs on the secondary side hold the last state that they received from the primary until either the UVLO level is reached and the outputs are placed in their default low state, or the outputs detect a lack of activity from the inputs and the outputs are set to their default value before the secondary power reaches UVLO.

**INSULATION LIFETIME**

All insulation structures eventually break down when subjected to voltage stress over a sufficiently long period. The rate of insulation degradation is dependent on the characteristics of the voltage waveform applied across the insulation. Analog Devices conducts an extensive set of evaluations to determine the lifetime of the insulation structure within the ADuM5400.

Accelerated life testing is performed using voltage levels higher than the rated continuous working voltage. Acceleration factors

for several operating conditions are determined, allowing calculation of the time to failure at the working voltage of interest. The values shown in Table 9 summarize the peak voltages for 50 years of service life in several operating conditions. In many cases, the working voltage approved by agency testing is higher than the 50-year service life voltage. Operation at working voltages higher than the service life voltage listed leads to premature insulation failure.

The insulation lifetime of the ADuM5400 depends on the voltage waveform type imposed across the isolation barrier. The *i*Coupler insulation structure degrades at different rates, depending on whether the waveform is bipolar ac, unipolar ac, or dc. Figure 22, Figure 23, and Figure 24 illustrate these different isolation voltage waveforms.

Bipolar ac voltage is the most stringent environment. A 50-year operating lifetime under the bipolar ac condition determines the Analog Devices recommended maximum working voltage.

In the case of unipolar ac or dc voltage, the stress on the insulation is significantly lower. This allows operation at higher working voltages while still achieving a 50-year service life. The working voltages listed in Table 9 can be applied while maintaining the 50-year minimum lifetime, provided the voltage conforms to either the unipolar ac or dc voltage cases. Any cross-insulation voltage waveform that does not conform to Figure 23 or Figure 24 should be treated as a bipolar ac waveform, and its peak voltage should be limited to the 50-year lifetime voltage value listed in Table 9.

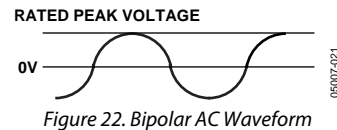


Figure 22. Bipolar AC Waveform

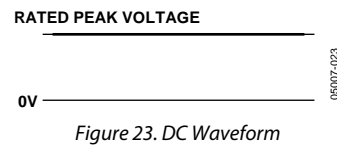
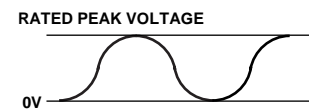


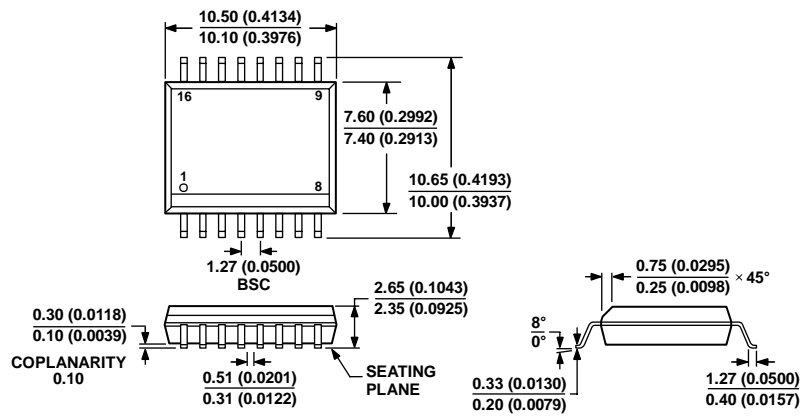
Figure 23. DC Waveform



NOTES:  
 1. THE VOLTAGE IS SHOWN AS SINUSOIDAL FOR ILLUSTRATION PURPOSES ONLY. IT IS MEANT TO REPRESENT ANY VOLTAGE WAVEFORM VARYING BETWEEN 0 AND SOME LIMITING VALUE. THE LIMITING VALUE CAN BE POSITIVE OR NEGATIVE, BUT THE VOLTAGE CANNOT CROSS 0V.

Figure 24. Unipolar AC Waveform

## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-013-AA  
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS  
(IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR  
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 25. 16-Lead Standard Small Outline Package [SOIC\_W]  
Wide Body (RW-16)

Dimensions shown in millimeters and (inches)

032707-B

## ORDERING GUIDE

Model	Number of Inputs, $V_{DD1}$ Side	Number of Inputs, $V_{ISO}$ Side	Maximum Data Rate (Mbps)	Maximum Propagation Delay, 5 V (ns)	Maximum Pulse Width Distortion (ns)	Temperature Range (°C)	Package Description	Package Option
ADuM5400ARWZ <sup>1,2</sup>	4	0	1	100	40	-40 to +105	16-Lead SOIC_W	RW-16
ADuM5400CRWZ <sup>1,2</sup>	4	0	25	60	6	-40 to +105	16-Lead SOIC_W	RW-16

<sup>1</sup> Tape and reel are available. The addition of an RL suffix designates a 13" (1,000 units) tape and reel option.

<sup>2</sup> Z = RoHS Compliant Part.

**NOTES**

**NOTES**

**NOTES**