## $\square$ MN101C62 Series



## Interrupts

Watchdog. External 0 to 4 . Timer 0 to 4 . Timer 6. Timer 7 ( 2 systems). Timer 8 ( 2 systems). Time base. Automatic transfer finish. Serial 0 (2 systems). Serial 1 (2 systems). Serial 2. A/D conversion finish. Key interrupt

## Timer Counter

8 -bit timer $\times 6$
Timer 0 .................Square-wave/8-bit PWM output. Event count. Remote control carrier output. Simple pulse width measurement
Timer 1 ..................Square-wave output. Event count. Synchronous output event. Serial baud rate timer
Timer 2 .................Square-wave output. Event count. Synchronous output event. Simple pulse width measurement. Real time output control. Serial baud rate timer
Timer 3 $\qquad$ Square-wave output. Event count. Remote control carrier output. Serial baud rate timer
Timer 4 $\qquad$ Square-wave/8-bit PWM output. Event count. Remote control carrier output. Simple pulse width measurement
Timer 6 $\qquad$ .8-bit freerun timer
Timer 0,1 can be cascade-connected
Timer 2, 3 can be cascade-connected
16 -bit timer $\times 2$
Timer 7 $\qquad$ .Square-wave output. 16-bit PWM output (cycle/duty continuous variable). Event count. Synchronous output event. Pulse width measurement. Input capture. Real time output control
Timer 8 ...................Square-wave output. 16-bit PWM output (cycle/duty continuous variable). Event count. Synchronous output event. Pulse width measurement. Input capture. Real time output control
Watchdog timer $\times 1$

## Serial interface

Synchronous type/UART (full-duplex) $\times 2$ : Serial 0,1
Synchronous type/Single-master I ${ }^{2} \mathrm{C} \times 1$ : Serial 2

## I/O Pins

I/O 68: Common use. Specified pull-up resistor available. Input/output selectable (bit unit)

## A/D converter

10-bit $\times 8$ channels (with $\mathrm{S} / \mathrm{H}$ )

## Special Ports

Buzzer output. Remote control carrier output. High-current drive port

## ROM Correction

Correcting address designation: Up to 3 addresses possible

Electrical Charactreistics (Supply current)

| Parameter | Symbol | Condition | Limit |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | min | typ | max |  |
| Operating supply current | IDD1 | fosc $=20 \mathrm{MHz} . \mathrm{VDD}=5 \mathrm{~V}$ |  | 15(20) | $30(40)$ | mA |
|  | IDD2 | $\mathrm{fx}=32 \mathrm{kHz} . \mathrm{VDD}=3 \mathrm{~V}$ |  | $30(50)$ | 60(100) | $\mu \mathrm{A}$ |
| Supply current at HALT | IDD3 | $\mathrm{fx}=32 \mathrm{kHz} . \mathrm{VDD}=3 \mathrm{~V} . \mathrm{Ta}=25^{\circ} \mathrm{C}$ |  | 6 | 8 | $\mu \mathrm{A}$ |
| Supply current at HALT | IDD4 | $\mathrm{fx}=32 \mathrm{kHz} . \mathrm{VDD}=3 \mathrm{~V} . \mathrm{Ta}=85^{\circ} \mathrm{C}$ |  |  | 30 | $\mu \mathrm{A}$ |
| Supply current at STOP | IDD5 | $\mathrm{VDD}=5 \mathrm{~V} . \mathrm{Ta}=25^{\circ} \mathrm{C}$ |  |  | 2 | $\mu \mathrm{A}$ |
|  | IDD6 | $\mathrm{VDD}=5 \mathrm{~V} . \mathrm{Ta}=85^{\circ} \mathrm{C}$ |  |  | 50 | $\mu \mathrm{A}$ |

Note) ( ): Flash memory built-in type
Development tools
In-circuit Emulator
PX-ICE101C/D + PX-PRB101C62-LQFP080-P-1414A-M
Pin Assignment
LQFP080-P-1414A


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