

LMV841/LMV842/LMV844 **CMOS Input, RRIO, Wide Supply Range Operational Amplifiers**

General Description

Typical Applications

SENSOR

The LMV841/LMV842/LMV844 are low-voltage and low-power operational amplifiers that operate with supply voltages ranging from 2.7V to 12V and have rail-to-rail input and output capability. Their low offset voltage, low supply current, and MOS inputs make them ideal for sensor interface and batterypowered applications.

The single LMV841 is offered in the space-saving 5-Pin SC70 package, the dual LMV842 in the 8-Pin MSOP and 8-Pin SOIC packages, and the quad LMV844 in the 14-Pin TSSOP and 14-Pin SOIC packages. These small packages are ideal solutions for area-constrained PC boards and portable electronics.

Features

Unless otherwise noted, typical values at $T_A = 25^{\circ}C$, $V^+ = 5V$.

- Space saving 5-Pin SC70 package
- Supply voltage range 2.7V to 12V
- Guaranteed at 3.3V, 5V and ±5V
- Low supply current
- Unity gain bandwidth
 - Open loop gain
- Input offset voltage Input bias current
 - CMRR
- Input voltage noise Temperature range
- Rail-to-Rail input
- . Rail-to-Rail output

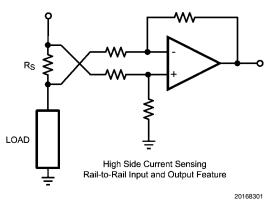
Applications

- High impedance sensor interface
- Battery powered instrumentation
- High gain amplifiers
- DAC buffer
- Instrumentation amplifiers
- Active filters



Rs Rs LOAD High Impedance Sensor Interface CMOS Input Feature

Active Band-Pass Filter



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1 mA per channel

4.5 MHz

500 µV max

20 nV/√Hz

-40°C to 125°C

133 dB

0.3 pA

112 dB

Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

| ESD Tolerance (Note 2) | |
|-------------------------------|-----------------|
| Human Body Model | 2 kV |
| Machine Model | 200V |
| V _{IN} Differential | ±300 mV |
| Supply Voltage (V+ – V-) | 13.2V |
| Voltage at Input/Output Pins | V++0.3V, V0.3V |
| Input Current | 10 mA |
| Storage Temperature Range | –65°C to +150°C |
| Junction Temperature (Note 3) | +150°C |

| Soldering Information | |
|------------------------------------|-------|
| Infrared or Convection (20 sec) | 235°C |
| Wave Soldering Lead Temp. (10 sec) | 260°C |

Operating Ratings (Note 1)

| Temperature Range (Note 3) | –40°C to +125°C |
|--|-----------------|
| Supply Voltage (V+ – V−) | 2.7V to 12V |
| Package Thermal Resistance (θ_{JA} (Note | e 3)) |
| 5-Pin SC70 | 334 °C/W |
| 8-Pin MSOP | 205 °C/W |
| 8-Pin SOIC | 126 °C/W |
| 14-Pin TSSOP | 110 °C/W |
| 14-Pin SOIC | 93 °C/W |

3.3V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^{\circ}C$, V⁺ = 3.3V, V⁻ = 0V, V_{CM} = V⁺/2, and R_L > 10 M Ω to V⁺/2. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units | |
|-------------------|---|--|------------------|-------------------|---------------------|-------|--|
| V _{OS} | Input Offset Voltage | | | ±50 | ±500 ±800 | μV | |
| TCV _{OS} | Input Offset Voltage Drift (Note 7) | | | 0.5 | ±5 | µV/°C | |
| I _B | Input Bias Current (Notes 7, 8) | | | 0.3 | 10 300 | pА | |
| I _{os} | Input Offset Current | | | 40 | | fA | |
| CMRR | Common Mode Rejection Ratio $0V \le V_{CM} \le 3.3V$ 84LMV84180 | | - | 112 | | | |
| | Common Mode Rejection Ratio LMV842 and LMV844 | | 77 75 | 106 | | dB | |
| PSRR | Power Supply Rejection Ratio | $2.7V \le V^+ \le 12V, V_0 = V^+/2$ | 86 82 | 108 | | dB | |
| CMVR | Input Common-Mode Voltage Range | CMRR ≥ 50 dB | -0.1 | | 3.4 | V | |
| A _{VOL} | Large Signal Voltage Gain | $R_{L} = 2 k\Omega$ $V_{O} = 0.3V \text{ to } 3.0V$ | 100 96 | 123 | | dB | |
| | | $R_{L} = 10 \text{ k}\Omega$ $V_{O} = 0.2 \text{V to } 3.1 \text{V}$ | 100 96 | 131 | | | |
| V 1 | Output Swing High, (measured from V ⁺) | $R_L = 2 k\Omega$ to V+/2 | | 52 | 80 120 | mV | |
| | | $R_L = 10 \text{ k}\Omega$ to V+/2 | | 28 | 50 70 | | |
| | Output Swing Low, (measured from V-) | | 65 | 100 120 | | | |
| | | $R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ | | 33 | 65 75 | mV | |
| I _o | Output Short Circuit Current (Notes 3, 9) | Sourcing $V_0 = V^+/2$ $V_{IN} = 100 \text{ mV}$ | 20 15 | 32 | | | |
| | | Sinking $V_0 = V^+/2$ $V_{IN} = -100 \text{ mV}$ | 20 15 | 27 | | - mA | |
| I _s | Supply Current | Per Channel | | 0.93 | 1.5 2 | mA | |
| SR | Slew Rate (Note 10) | $A_V = +1, V_O = 2.3 V_{PP}$ 10% to 90% | | 2.5 | | V/µs | |
| GBW | Gain Bandwidth Product | | | 4.5 | | MHz | |

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| LMV841 |
|---------|
| Single/ |
| LMV842 |
| Dual/ |
| LMV844 |
| Quad |

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|------------------|-----------------------------------|--------------------------------|----------|----------|----------|--------|
| | | | (Note 6) | (Note 5) | (Note 6) | |
| Φ _m | Phase Margin | | | 67 | | Deg |
| e _n | Input-Referred Voltage Noise | f = 1 kHz | | 20 | | nV/√Hz |
| R _{OUT} | Open Loop Output Impedance | f = 3 MHz | | 70 | | Ω |
| THD+N | Total Harmonic Distortion + Noise | f = 1 kHz , A _V = 1 | | 0.005 | | 0/ |
| | | $R_L = 10 \text{ k}\Omega$ | | | | % |
| C _{IN} | Input Capacitance | | | 7 | | pF |

5V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^{\circ}C$, $V^+ = 5V$, $V^- = 0V$, $V_{CM} = V^+/2$, and $R_L > 10 \text{ M}\Omega$ to $V^+/2$. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|------------------|--|--|------------------|----------|---------------------|-------|
| | | | (Note 6) | (Note 5) | (Note 6) | |
| / _{os} | Input Offset Voltage | | | ±50 | ±500 ±800 | μV |
| CV _{os} | Input Offset Voltage Drift (Note 7) | | | 0.35 | ±5 | μV/°C |
| 3 | Input Bias Current (Notes 7, 8) | | | 0.3 | 10 300 | pА |
| OS | Input Offset Current | | | 40 | | fA |
| MRR | Common Mode Rejection Ratio | $0V \le V_{CM} \le 5V$ | 86 80 | 112 | 12 | |
| | Common Mode Rejection Ratio LMV842 and LMV844 | | 81 79 | 106 | | dB |
| PSRR | Power Supply Rejection Ratio | $2.7V \le V^+ \le 12V, V_0 = V^+/2$ | 86 82 | 108 | | dB |
| CMVR | Input Common-Mode Voltage Range | CMRR ≥ 50 dB | -0.2 | | 5.2 | V |
| A _{VOL} | Large Signal Voltage Gain | $R_{L} = 2 k\Omega$ $V_{O} = 0.3V \text{ to } 4.7V$ | 100 96 | 125 | | ٩D |
| | | $R_{L} = 10 \text{ k}\Omega$ $V_{O} = 0.2 \text{V to } 4.8 \text{V}$ | 100 96 | 133 | 33 dB | uв |
| V _o | Output Swing High, (measured from V+) | $R_L = 2 k\Omega$ to V+/2 | | 68 | 100 120 | |
| | | $R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ | | 32 | 50 70 | mV |
| | Output Swing Low, (measured from V ⁻) | $R_L = 2 k\Omega$ to V+/2 | | 78 | 120 140 | m)/ |
| | | $R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ | | 38 | 70 80 | mV |
| I _o | Output Short Circuit Current (Notes 3, 9) | Sourcing $V_0 = V^{+/2}$ $V_{IN} = 100 \text{ mV}$ | 20 15 | 33 | | mA |
| | | Sinking $V_0 = V^+/2$ $V_{IN} = -100 \text{ mV}$ | 20 15 | 28 | | IIIA |
| s | Supply Current | Per Channel | | 0.96 | 1.5 2 | mA |
| SR | Slew Rate (Note 10) | $A_V = +1, V_O = 4 V_{PP}$ 10% to 90% | | 2.5 | | V/µs |
| GBW | Gain Bandwidth Product | | | 4.5 | | MHz |
| Ф _m | Phase Margin | | | 67 | | Deg |
| e _n | Input-Referred Voltage Noise | f = 1 kHz | | 20 | | nV/√F |
| R _{OUT} | Open Loop Output Impedance | f = 3 MHz | | 70 | | Ω |

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|--------------------------|--|---|---------------------------|-----------------|---------------------|-------|
| THD+N | Total Harmonic Distortion + Noise | $f = 1 \text{ kHz}$, $A_V = 1$ $R_L = 10 \text{ k}\Omega$ | | 0.003 | | % |
| C _{IN} | Input Capacitance | | | 6 | | pF |
| Unless of Boldfac | Electrical Characteristic otherwise specified, all limits are guara re limits apply at the temperature extrem Parameter | nteed for $T_A = 25^{\circ}C$, V+ = 5V, V- = | –5V, V _{CM} = 0V | | - | |
| Symbol | | Conditions | (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
| V _{os} | Input Offset Voltage | | | ±50 | ±500 ±800 | μV |
| TCV _{OS} | Input Offset Voltage Drift (Note 7) | | | 0.25 | ±5 | µV/°C |
| I _B | Input Bias Current (Notes 7, 8) | | | 0.3 | 10 300 | pА |
| I _{os} | Input Offset Current | | | 40 | | fA |
| CMRR | Common Mode Rejection Ratio | $-5V \le V_{CM} \le 5V$ | 86 80 | 112 | | |
| | Common Mode Rejection Ratio LMV842 and LMV844 | | 86 80 | 106 | | dB |
| PSRR | Power Supply Rejection Ratio | $2.7V \le V^+ \le 12V, V_0 = 0V$ | 86 82 | 108 | | dB |
| CMVR | Input Common-Mode Voltage Range | CMRR ≥ 50 dB | -5.2 | | 5.2 | V |
| A _{VOL} | Large Signal Voltage Gain | $R_L = 2 k\Omega$ $V_O = -4.7V$ to 4.7V | 100 96 | 126 | | dB |
| | | $R_L = 10 \text{ k}\Omega$ $V_O = -4.8 \text{V}$ to 4.8V | 100 96 | 136 | | dB |
| Vo | Output Swing High, (measured from V+) | $R_L = 2 k\Omega$ to 0V | | 95 | 130 155 | mV |
| | | $R_L = 10 \text{ k}\Omega \text{ to } 0\text{V}$ | | 44 | 75 95 | |
| | Output Swing Low, (measured from V-) | $R_L = 2 k\Omega \text{ to } 0V$ | | 105 | 160 200 | |
| | | $R_L = 10 \text{ k}\Omega \text{ to } 0\text{V}$ | | 52 | 80 100 | mV |

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 I_0

 I_{S}

SR

GBW

 $\Phi_{\rm m}$

 \mathbf{e}_{n}

R_{OUT}

 \mathbf{C}_{IN}

THD+N

Sourcing $V_0 = 0V$ $V_{IN} = 100 \text{ mV}$

Sinking $V_0 = 0V$

 $A_V = +1, V_O = 9 V_{PP}$

 $V_{IN} = -100 \text{ mV}$

Per Channel

10% to 90%

f = 1 kHz

f = 3 MHz

 $R_L = 10 \ k\Omega$

f = 1 kHz , $A_V = 1$

100

1.7

2

mΑ

mΑ

V/µs

MHz

Deg

nV/√Hz

Ω

%

pF

37

29

1.03

2.5

4.5

67

20

70

0.006

3

20

15

20

15

Output Short Circuit Current

(Notes 3, 9)

Supply Current

Phase Margin

Input Capacitance

Slew Rate (Note 10)

Gain Bandwidth Product

Input-Referred Voltage Noise

Open Loop Output Impedance

Total Harmonic Distortion + Noise

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics Tables.

Note 2: Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

Note 3: The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} , and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A)/|\theta_{JA}|$. All numbers apply for packages soldered directly onto a PC board.

Note 4: Electrical table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device.

Note 5: Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

Note 6: Limits are 100% production tested at 25°C. Limits over the operating temperature range are guaranteed through correlations using statistical quality control (SQC) method.

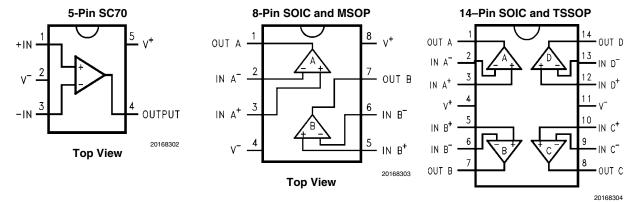
Note 7: This parameter is guaranteed by design and/or characterization and is not tested in production.

Note 8: Positive current corresponds to current flowing into the device.

Note 9: Short circuit test is a momentary test.

Note 10: Number specified is the slower of positive and negative slew rates.

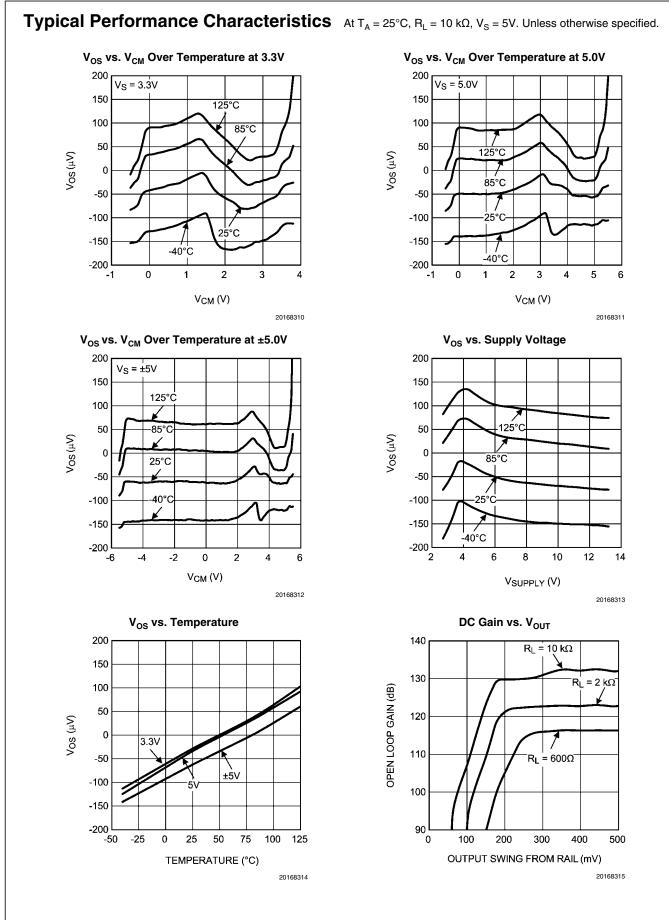
Connection Diagrams



Top View

Ordering Information

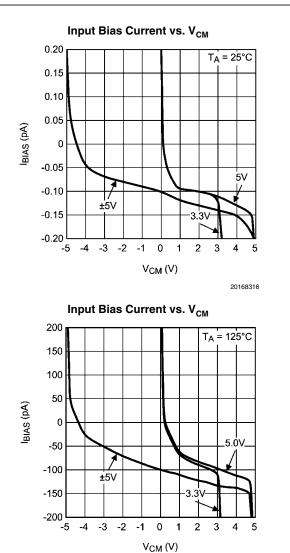
| Package | Part Number | Package Marking | Transport Media | NSC Drawing | |
|------------------------|-------------|-----------------|--------------------------|-------------|--|
| 5-Pin SC70 | LMV841MG | A97 | 1k Units Tape and Reel | MAA05A | |
| 5-PIII 3070 | LMV841MGX | A97 | 3k Units Tape and Reel | IVIAAU5A | |
| 8-Pin MSOP | LMV842MM | AC4A | 1k Units Tape and Reel | MUA08A | |
| 0-FIII MISOF | LMV842MMX | AC4A | 3.5k Units Tape and reel | IVIUAU8A | |
| 8-Pin SOIC | LMV842MA | | 95 Units/Rail | M08A | |
| 0-PIII 3010 | LMV842MAX | LMV842MA | 2.5k Units Tape and Reel | IVIUOA | |
| 14-Pin SOIC | LMV844MA | LMV844MA | 55 Units/Rail | M14A | |
| 14-PIII 5010 | LMV844MAX | | 2.5k Units Tape and Reel | | |
| | LMV844MT | LMV844MT | 94 Units/Rail | MTC14 | |
| 14-Pin TSSOP LMV844MTX | | | 2.5k Units Tape and Reel | 1 1011014 | |



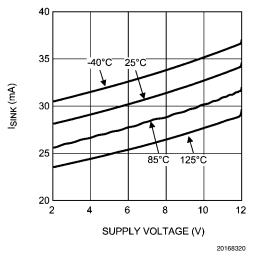
LMV841 Single/ LMV842 Dual/ LMV844 Quad

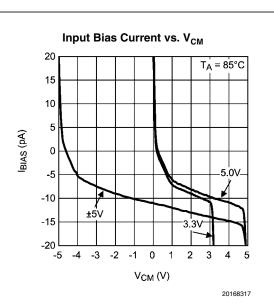
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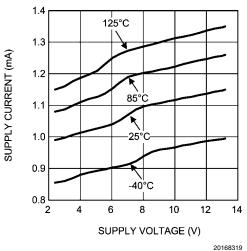


Sinking Current vs. Supply Voltage

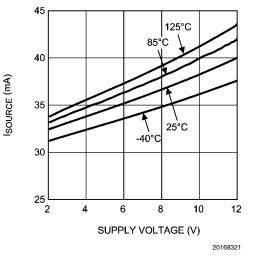


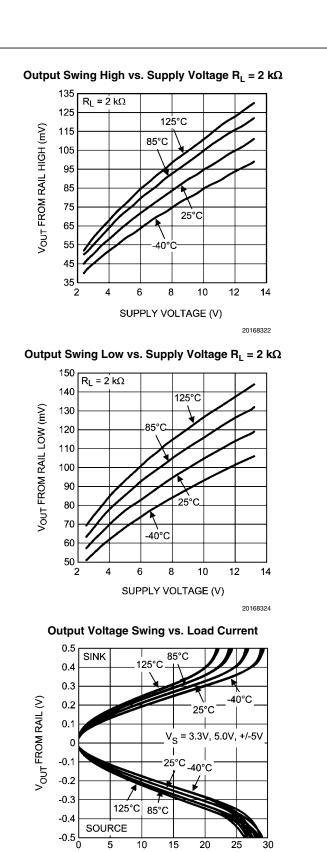


Supply Current per Channel vs. Supply Voltage

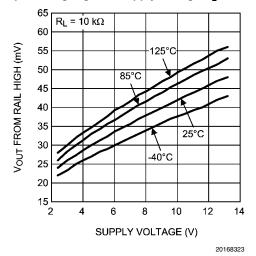


Sourcing Current vs. Supply Voltage

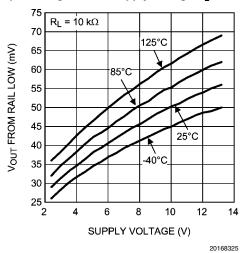




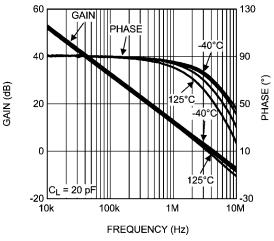
Output Swing High vs. Supply Voltage $R_L = 10 \text{ k}\Omega$



Output Swing Low vs. Supply Voltage $R_L = 10 \text{ k}\Omega$



Open Loop Frequency Response Over Temperature



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5

10

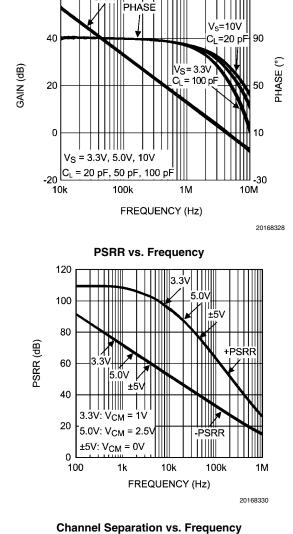
15

I_{LOAD} (mA)

20

25

30

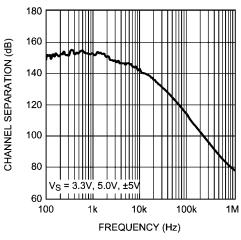


Open Loop Frequency Response Over Load Conditions

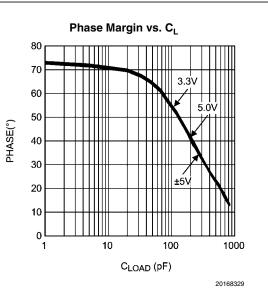
GAIN

60

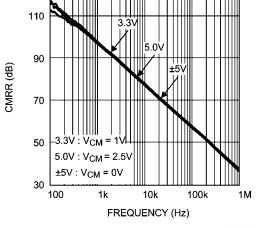
130



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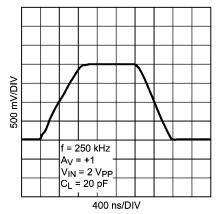


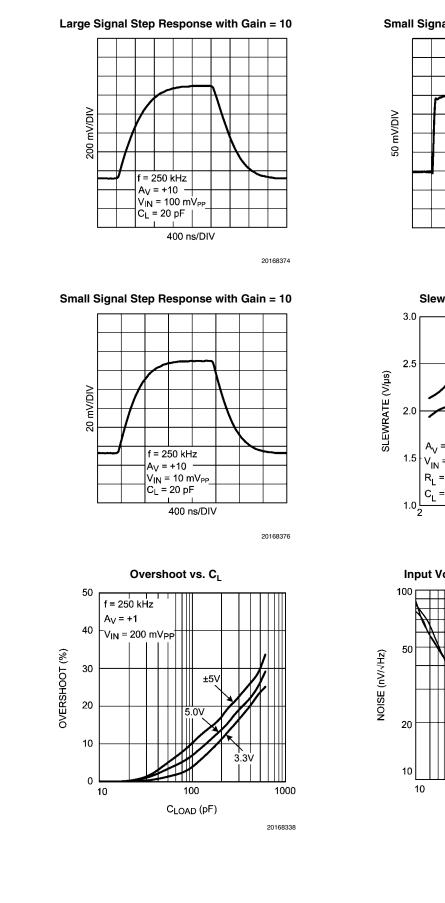




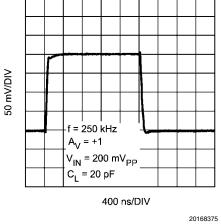
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Large Signal Step Response with Gain = 1

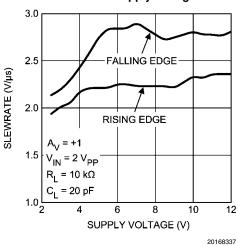




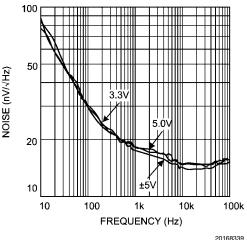
Small Signal Step Response with Gain = 1



Slew Rate vs Supply Voltage



Input Voltage Noise vs. Frequency



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THD+N vs. V_{OUT}

A_V

0.1

 $V_{OUT}(V)$

10

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A_V

10 _F

= 10 kΩ Rı

= 20 pF

0.01

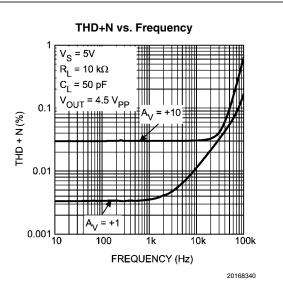
V_S = 5V

C - _ _ 1 kHz

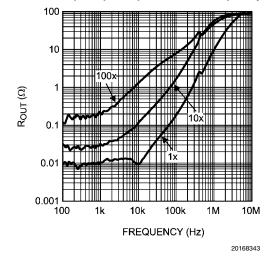
f١ 0.001

THD + N (%) 0.1

0.01







Application Information

INTRODUCTION

The LMV841/LMV842/LMV844 are operational amplifiers with near-precision specifications: low noise, low temperature drift, low offset, and rail-to-rail input and output. Possible application areas include instrumentation, medical, test equipment, audio, and automotive applications.

Its low supply current of 1mA per amplifier, temperature range of -40° C to 125° C, 12V supply with CMOS input, and the small SC70 package for the LMV841 make the LMV841/LMV842/LMV844 a unique op amp family and a perfect choice for portable electronics.

INPUT PROTECTION

The LMV841/LMV842/LMV844 have a set of anti-parallel diodes D_1 and D_2 between the input pins, as shown in *Figure 1*. These diodes are present to protect the input stage of the amplifier. At the same time, they limit the amount of differential input voltage that is allowed on the input pins.

A differential signal larger than one diode voltage drop can damage the diodes. The differential signal between the inputs needs to be limited to ± 300 mV or the input current needs to be limited to ± 10 mA.

Note that when the op amp is slewing, a differential input voltage exists that forward biases the protection diodes. This may result in current being drawn from the signal source. While this current is already limited by the internal resistors R₁ and R₂ (both 130 Ω), a resistor of 1 k Ω can be placed in the feedback path, or a 500 Ω resistor can be placed in series with the input signal for further limitation.

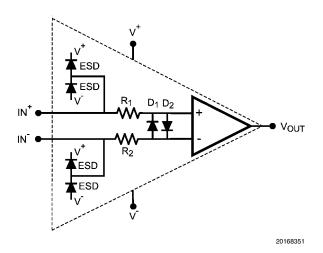


FIGURE 1. Protection Diodes between the Input Pins

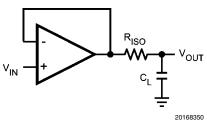
INPUT STAGE

The input stage of this amplifier consists of both a PMOS and an NMOS input pair to achieve a rail-to-rail input range. For input voltages close to the negative rail, only the PMOS pair is active. Close to the positive rail, only the NMOS pair is active. In a transition region that extends from approximately 2V below V+ to 1V below V+, both pairs are active, and one pair gradually takes over from the other. In this transition region, the input-referred offset voltage changes from the offset voltage associated with the PMOS pair to that of the NMOS pair. The input pairs are trimmed independently to guarantee an input offset voltage of less then 0.5 mV at room temperature over the complete rail-to-rail input range. This also significantly improves the CMRR of the amplifier in the transition region. Note that the CMRR and PSRR limits in the tables are large-signal numbers that express the maximum variation of the amplifier's input offset over the full common-mode voltage and supply voltage range, respectively. When the amplifier's common-mode input voltage is within the transition region, the small signal CMRR and PSRR may be slightly lower than the large signal limits.

CAPACITIVE LOAD

The LMV841/LMV842/LMV844 can be connected as non-inverting unity gain amplifiers. This configuration is the most sensitive to capacitive loading. The combination of a capacitive load placed on the output of an amplifier along with the amplifier's output impedance creates a phase lag, which reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response will be underdamped which causes peaking in the transfer and, when there is too much peaking, the op amp might start oscillating.

The LMV841/LMV842/LMV844 can directly drive capacitive loads up to 100 pF without any stability issues. In order to drive heavier capacitive loads, an isolation resistor, $R_{\rm ISO}$, should be used, as shown in *Figure 2*. By using this isolation resistor, the capacitive load is isolated from the amplifier's output, and hence, the pole caused by $C_{\rm L}$ is no longer in the feedback loop. The larger the value of $R_{\rm ISO}$, the more stable the output voltage will be. If values of $R_{\rm ISO}$ are sufficiently large, the feedback loop will be stable, independent of the value of $C_{\rm L}$. However, larger values of $R_{\rm ISO}$ result in reduced output swing and reduced output current drive.



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FIGURE 2. Isolating Capacitive Load

DECOUPLING AND LAYOUT

For decoupling the supply lines it is suggested that 10 nF capacitors be placed as close as possible to the op amp.

For single supply, place a capacitor between V⁺ and V⁻. For dual supplies, place one capacitor between V⁺ and the board ground, and the second capacitor between ground and V⁻.

OP AMP CIRCUIT NOISE

The LMV841/LMV842/LMV844 have good noise specifications, and will frequently be used in low-noise applications. Therefore it is important to determine the noise of the total circuit. Besides the input referred noise of the op amp, the feedback resistors may have an important contribution to the total noise.

For applications with a voltage input configuration it is, in general, beneficial to keep the resistor values low. In these configurations high resistor values mean high noise levels. However, using low resistor values will increase the power consumption of the application. This is not always acceptable for portable applications, so there is a trade-off between noise level and power consumption.

Besides the noise contribution of the signal source, three types of noise need to be taken into account for calculating the noise performance of an op amp circuit:

- Input referred voltage noise of the op amp
- Input referred current noise of the op amp
- Noise sources of the resistors in the feedback network, configuring the op amp

To calculate the noise voltage at the output of the op amp, the first step is to determine a total equivalent noise source. This requires the transformation of all noise sources to the same reference node. A convenient choice for this node is the input of the op amp circuit. The next step is to add all the noise sources. The final step is to multiply the total equivalent input voltage noise with the gain of the op amp configuration.

The input referred voltage noise of the op amp is already located at the input, we can use the input referred voltage noise without further transferring. The input referred current noise needs to be converted to an input referred voltage noise. The current noise is negligibly small, as long as the equivalent resistance is not unrealistically large, so we can leave the current noise out for these examples. That leaves us with the noise sources of the resistors on the total noise can be seen in the following examples, one with high resistor values and one with low resistor values. Both examples describe an op amp configuration with a gain of 101 which will give the circuit a bandwidth of 44.5 kHz. The op amp noise is the same for both cases, i.e. an input referred noise current.

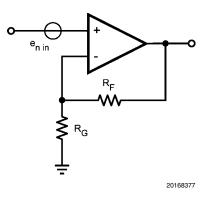


FIGURE 3. Noise Circuit

To calculate the noise of the resistors in the feedback network, the equivalent input referred noise resistance is needed. For the example in *Figure 3*, this equivalent resistance R_{eq} can be calculated using the following equation:

$$\mathsf{R}_{\mathsf{eq}} = \frac{\mathsf{R}_{\mathsf{F}} \times \mathsf{R}_{\mathsf{G}}}{\mathsf{R}_{\mathsf{F}} + \mathsf{R}_{\mathsf{G}}}$$

The voltage noise of the equivalent resistance can be calculated using the following equation:

$$e_{nr} = \sqrt{4kTR_{eq}}$$

where:

 e_{nr} = thermal noise voltage of the equivalent resistor R_{ea} (V/ \sqrt{Hz})

k = Boltzmann constant (1.38 x 10⁻²³ J/K)

T = absolute temperature (K)

$$R_{eq} = resistance (\Omega)$$

The total equivalent input voltage noise is given by the equation:

$$e_{n in} = \sqrt{e_{nv}^2 + e_{nr}^2}$$

where:

en in = total input equivalent voltage noise of the circuit

 e_{nv} = input voltage noise of the op amp

The final step is multiplying the total input voltage noise by the noise gain, which is in this case the gain of the op amp configuration:

The equivalent resistance for the first example with a resistor $\rm R_F$ of 10 $\rm M\Omega$ and a resistor $\rm R_G$ of 100 $\rm k\Omega$ at 25°C (298 K) equals:

$$R_{eq} = \frac{R_F \times R_G}{R_F + R_G} = \frac{10 \text{ M}\Omega \times 100 \text{ k}\Omega}{10 \text{ M}\Omega + 100 \text{ k}\Omega} = 99 \text{ k}\Omega$$

Now the noise of the resistors can be calculated, yielding:

$$e_{nr} = \sqrt{4kTR_{eq}}$$
$$= \sqrt{4 \times 1.38 \times 10^{-23} \text{ J/K} \times 298K \times 99 \text{ k}\Omega}$$
$$= 40 \text{ nV}/\sqrt{\text{Hz}}$$

The total noise at the input of the op amp is:

$$e_{n in} = \sqrt{e_{nv}^2 + e_{nr}^2}$$

= $\sqrt{(20 \text{ nV}/\sqrt{\text{Hz}})^2 + (40 \text{ nV}/\sqrt{\text{Hz}})^2} = 45 \text{ nV}/\sqrt{\text{Hz}}$

For the first example, this input noise will, multiplied with the noise gain, give a total output noise of:

$$e_{n out} = e_{n in} \times A_{noise}$$

= 45 nV/ $\sqrt{Hz} \times 101 = 4.5 \ \mu V/\sqrt{Hz}$

In the second example, with a resistor R_F of 10 $k\Omega$ and a resistor R_G of 100 Ω at 25°C (298 K), the equivalent resistance equals:

$$R_{eq} = \frac{R_{F} \times R_{G}}{R_{F} + R_{G}} = \frac{10 \text{ k}\Omega \times 100\Omega}{10 \text{ k}\Omega + 100\Omega} = 99\Omega$$

The resistor noise for the second example is:

$$e_{nr} = \sqrt{4kTR_{eq}}$$
$$= \sqrt{4 \times 1.38 \times 10^{-23} \text{ J/K} \times 298\text{K} \times 99\Omega}$$
$$= 1 \text{ nV}/\sqrt{\text{Hz}}$$

The total noise at the input of the op amp is:

$$e_{n in} = \sqrt{e_{nv}^{2} + e_{nr}^{2}}$$
$$= \sqrt{(20 \text{ nV}/\sqrt{\text{Hz}})^{2} + (1 \text{ nV}/\sqrt{\text{Hz}})^{2}}$$
$$= 20 \text{ nV}/\sqrt{\text{Hz}}$$

For the second example the input noise will, multiplied with the noise gain, give an output noise of

$$e_{n out} = e_{n in} \times A_{noise}$$

= 20 nV/ $\sqrt{Hz} \times 101 = 2 \mu V/\sqrt{Hz}$

In the first example the noise is dominated by the resistor noise due to the very high resistor values, in the second example the very low resistor values add only a negligible contribution to the noise and now the dominating factor is the op amp itself. When selecting the resistor values, it is important to choose values that don't add extra noise to the application. Choosing values above 100 k Ω may increase the noise too much. Low values will keep the noise within acceptable levels; choosing very low values however, will not make the noise even lower, but will increase the current of the circuit.

ACTIVE FILTER

The rail-to-rail input and output of the LMV841/LMV842/ LMV844 and the wide supply voltage range make these amplifiers ideal to use in numerous applications. One of the typical applications is an active filter as shown in *Figure 4*. This example is a band-pass filter, for which the pass band is widened. This is achieved by cascading two band-pass filters, with slightly different center frequencies.

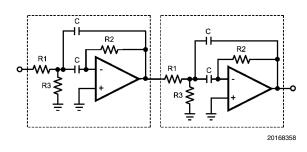


FIGURE 4. Active Filter

The center frequency of the separate band-pass filters can be calculated by:

$$f_{mid} = \frac{1}{2\pi C} \sqrt{\frac{R_1 + R_3}{R_1 R_2 R_3}}$$

In this example a filter was designed with its pass band at 10 kHz. The two separate band-pass filters are designed to have

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a center frequency of approximately 10% from the frequency of the total filter:

$$C = 33 \text{ nF}$$

 $R1 = 2 \text{ k}\Omega$
 $R2 = 6.2 \text{ k}\Omega$
 $R3 = 45 \Omega$

This will give for filter A:

$$f_{mid} = \frac{1}{\pi \text{ x 33 nF}} \sqrt{\frac{2 \text{ k}\Omega + 6.2 \text{ k}\Omega}{2 \text{ k}\Omega \text{ x 6.2 k}\Omega \text{ x 45}\Omega}} = 9.2 \text{ kHz}$$

and for filter B with C = 27 nF:

$$f_{mid} = \frac{1}{\pi \text{ x } 27 \text{ nF}} \sqrt{\frac{2 \text{ } \text{k}\Omega + 6.2 \text{ } \text{k}\Omega}{2 \text{ } \text{k}\Omega \text{ x } 6.2 \text{ } \text{k}\Omega \text{ x } 45\Omega}} = 11.2 \text{ } \text{kHz}$$

Bandwidth can be calculated by:

$$\mathsf{B} = \frac{1}{\pi \mathsf{R}_2 \mathsf{C}}$$

For filter A this will give:

B =
$$\frac{1}{\pi x \, 6.2 \, \text{k}\Omega \, x \, 33 \, \text{nF}}$$
 = 1.6 kHz

and for filter B:

B =
$$\frac{1}{\pi \text{ x } 6.2 \text{ k}\Omega \text{ x } 27 \text{ nF}}$$
 = 1.9 kHz

The response of the two filters and the combined filter is shown in *Figure 5*.

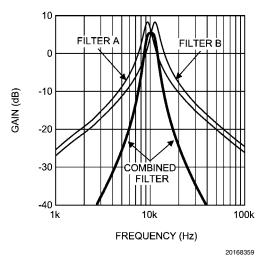


FIGURE 5. Active Filter Curve

The responses of filter A and filter B are shown as the thin lines in *Figure 5*; the response of the combined filter is shown as the thick line. Shifting the center frequencies of the separate filters farther apart, will result in a wider band; however, positioning the center frequencies too far apart will result in a less flat gain within the band. For wider bands more bandpass filters can be cascaded.

Tip: Use the WEBENCH internet tools at www.national.com for your filter application.

HIGH-SIDE CURRENT SENSING

The rail-to-rail input and the low V_{OS} features make the LMV841/LMV842/LMV844 ideal op amps for high-side current sensing applications.

To measure a current, a sense resistor is placed in series with the load, as shown in *Figure 6*. The current flowing through this sense resistor will result in a voltage drop, that is amplified by the op amp.

Suppose it is necessary to measure a current between 0A and 2A using a sense resistor of 100 m Ω , and convert it to an output voltage of 0 to 5V. A current of 2A flowing through the load and the sense resistor will result in a voltage of 200 mV across the sense resistor. The op amp will amplify this 200 mV to fit the current range to the output voltage range. Use the formula:

$$V_{OUT} = R_F/R_G * V_{SENSE}$$

to calculate the gain needed. For a load current of 2A and an output voltage of 5V the gain would be V_{OUT}/V_{SENSE} = 25. If the feedback resistor, R_F, is 100 kΩ, then the value for R_G will be 4 kΩ. The tolerance of the resistors has to be low to obtain a good common-mode rejection.

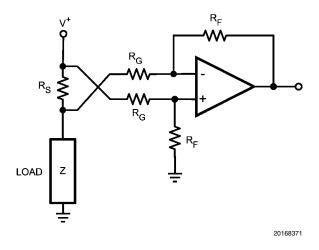


FIGURE 6. High-Side Current Sensing

HIGH IMPEDANCE SENSOR INTERFACE

With CMOS inputs, the LMV841/LMV842/LMV844 are particularly suited to be used as high impedance sensor interfaces.

Many sensors have high source impedances that may range up to 10 M Ω . The input bias current of an amplifier will load the output of the sensor, and thus cause a voltage drop across the source resistance, as shown in *Figure 7*. When an op amp is selected with a relatively high input bias current, this error may be unacceptable.

The low input current of the LMV841/LMV842/LMV844 significantly reduces such errors. The following examples show the difference between a standard op amp input and the CMOS input of the LMV841/LMV842/LMV844.

The voltage at the input of the op amp can be calculated with

$$V_{IN+} = V_S - I_B * R_S$$

For a standard op amp the input bias lb can be 10 nA. When the sensor generates a signal of 1V (V_S) and the sensors

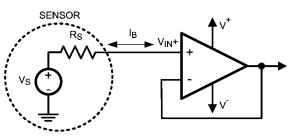
impedance is 10 $\text{M}\Omega$ (R_{\text{S}}), the signal at the op amp input will be

$$V_{IN} = 1V - 10 \text{ nA} * 10 \text{ M}\Omega = 1V - 0.1V = 0.9V$$

For the CMOS input of the LMV841/LMV842/LMV844, which has an input bias current of only 0.3 pA, this would give

$$V_{IN} = 1V - 0.3 \text{ pA} * 10 \text{ M}\Omega = 1V - 3 \mu V = 0.999997 V$$

The conclusion is that a standard op amp, with its high input bias current input, is not a good choice for use in impedance sensor applications. The LMV841/LMV842/LMV844, in contrast, are much more suitable due to the low input bias current. The error is negligibly small; therefore, the LMV841/LMV842/LMV844 are a must for use with high impedance sensors.



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FIGURE 7. High Impedance Sensor Interface

THERMOCOUPLE AMPLIFIER

The following is a typical example for a thermocouple amplifier application using an LMV841, LMV842, or LMV844. A thermocouple senses a temperature and converts it into a voltage. This signal is then amplified by the LMV841, LMV842, or LMV844. An ADC can then convert the amplified signal to a digital signal. For further processing the digital signal can be processed by a microprocessor, and can be used to display or log the temperature, or the temperature data can be used in a fabrication process.

Characteristics of a Thermocouple

A thermocouple is a junction of two different metals. These metals produce a small voltage that increases with temperature.

The thermocouple used in this application is a K-type thermocouple. A K-type thermocouple is a junction between Nickel-Chromium and Nickel-Aluminum. This is one of the most commonly used thermocouples. There are several reasons for using the K-type thermocouple. These include temperature range, the linearity, the sensitivity, and the cost.

A K-type thermocouple has a wide temperature range. The range of this thermocouple is from approximately -200° C to approximately 1200° C, as can be seen in *Figure 8*. This covers the generally used temperature ranges.

Over the main part of the range the behavior is linear. This is important for converting the analog signal to a digital signal.

The K-type thermocouple has good sensitivity when compared to many other types; the sensitivity is 41 uV/°C. Lower sensitivity requires more gain and makes the application more sensitive to noise.

In addition, a K-type thermocouple is not expensive, many other thermocouples consist of more expensive materials or are more difficult to produce.

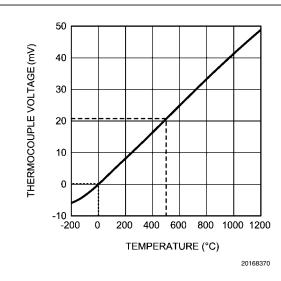


FIGURE 8. K-Type Thermocouple Response

Thermocouple Example

For this example suppose the range of interest is from 0° C to 500° C, and the resolution needed is 0.5° C. The power supply for both the LMV841, LMV842, or LMV844 and the ADC is 3.3V.

The temperature range of 0°C to 500°C results in a voltage range from 0 mV to 20.6 mV produced by the thermocouple. This is shown in *Figure 8*

To obtain the best accuracy the full ADC range of 0 to 3.3V is used and the gain needed for this full range can be calculated as follows: $A_V = 3.3V/0.0206V = 160$.

If R_G is 2 k Ω , then the value for R_F can be calculated with this gain of 160. Since $A_V = R_F/R_G$, R_F can be calculated as follow: $R_F = A_V * R_G = 160 \times 2 \ k\Omega = 320 \ k\Omega$.

To get a resolution of 0.5° C a step smaller then the minimum resolution is needed. This means that at least 1000 steps are necessary (500°C/0.5°C). A 10-bit ADC would be sufficient as this will give 1024 steps. A 10-bit ADC such as the two channel 10-bit ADC102S021 would be a good choice.

Unwanted Thermocouple Effect

At the point where the thermocouple wires are connected to the circuit, usually copper wires or traces, an unwanted thermocouple effect will occur.

At this connection, this could be the connector on a PCB, the thermocouple wiring forms a second thermocouple with the connector. This second thermocouple disturbs the measurements from the intended thermocouple.

Using an isothermal block as a reference will compensate for this additional thermocouple effect . An isothermal block is a good heat conductor. This means that the two thermocouple connections both have the same temperature. The temperature of the isothermal block can be measured, and thereby the temperature of the thermocouple connections. This is usually called the cold junction reference temperature.

In the example, an LM35 is used to measure this temperature. This semiconductor temperature sensor can accurately measure temperatures from -55 °C to 150 °C.

The ADC in this example also coverts the signal from the LM35 to a digital signal. Now the microprocessor can compensate the amplified thermocouple signal, for the unwanted thermocouple effect.

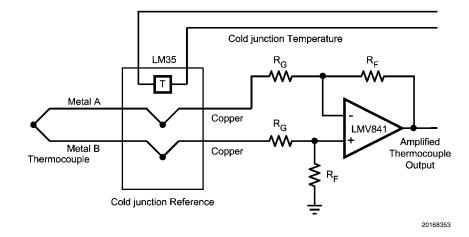
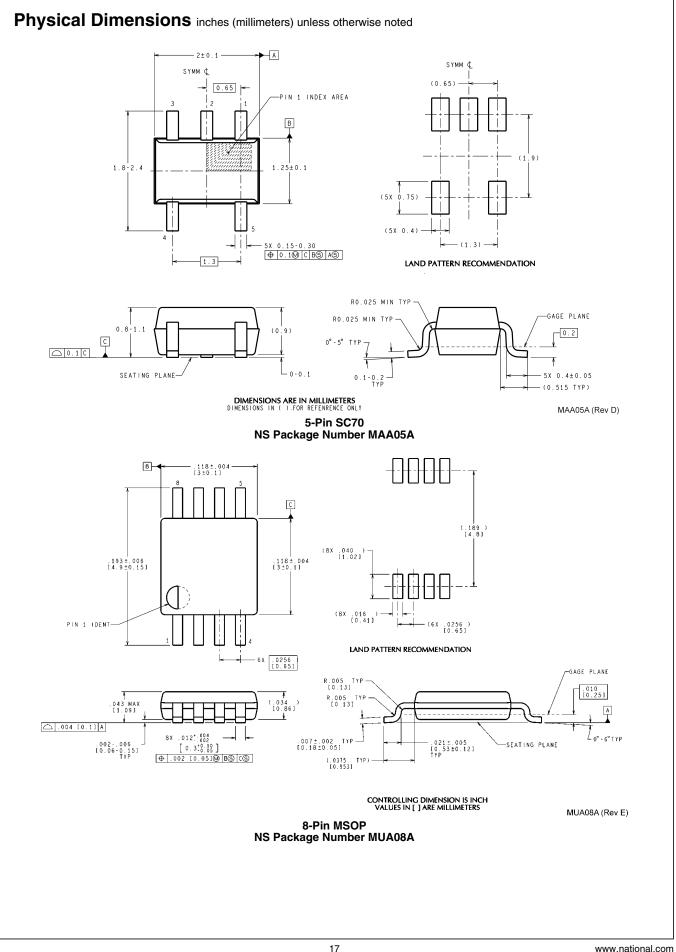
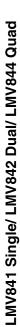
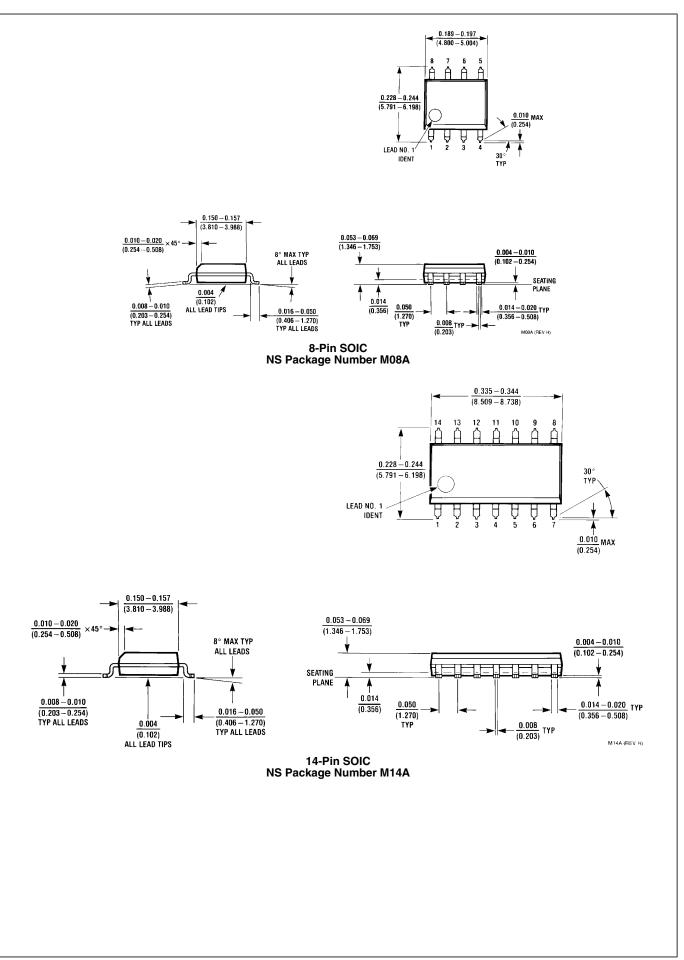


FIGURE 9. Thermocouple Amplifier

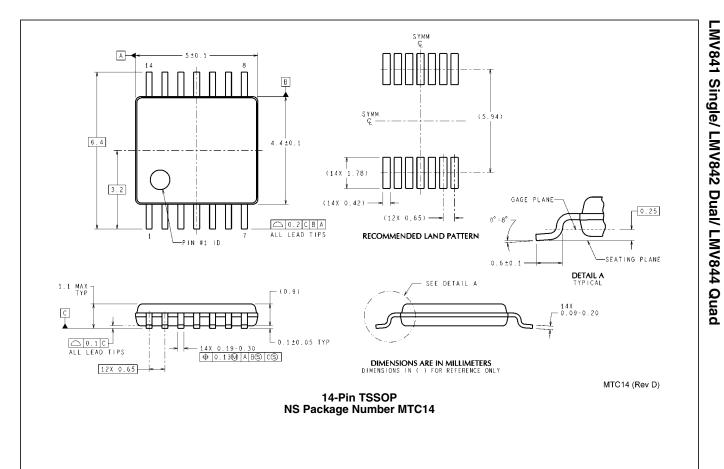
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