Master-Slave Flip-Flop

Master slave construction renders the MC1670 relatively insensitive to the shape of the clock waveform, since only the voltage levels at the clock inputs control the transfer of information from data input (D) to output.

When both clock inputs (C1 and C2) are in the low state, the data input affects only the "Master" portion of the flip-flop. The data present in the "Master" is transferred to the "Slave" when clock inputs (C1 "OR" C2) are taken from a low to a high level. In other words, the output state of the flip-flop changes on the positive transition of the clock pulse.

While either C1 "OR" C2 is in the high state, the "Master" (and data input) is disabled.

Asynchronous Set (S) and Reset (R) override Clock (C) and Data (D) inputs.

Power Dissipation = 220 mW typ (No Load)

 $f_{Tog} = 350 \text{ MHz typ}$

TRUTH TABLE

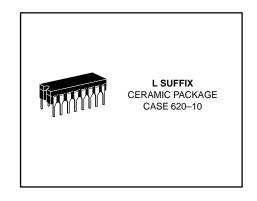
R	S	D	С	Q _{n+1}
	H	X X L L H H	xxxuhzuhz	н

ND = Not DefinedC = C1 + C2

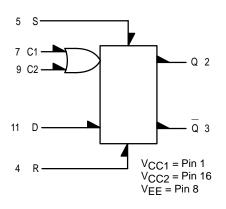
ELECTRICAL CHARACTERISTICS

		–30°C		+25°C		+85°C		
Characteristic	Symbol	Min	Max	Min	Max	Min	Max	Unit
Power Supply Drain Current	ΙE				48		_	mAdc
Input Current Set, Reset Clock Data	linH			_ _ _	550 250 270			μAdc
Switching Times Propagation Delay	t _{pd}	1.0	2.7	1.1	2.5	1.1	2.9	ns
Rise Time (10% to 90%)	t +	0.9	2.7	1.0	2.5	1.0	2.9	ns
Fall Time (10% to 90%)	t -	0.5	2.1	0.6	1.9	0.6	2.3	ns
Setup Time	ts"1" ts"0"	_	_	0.4 0.5		_		ns
Hold Time	^t H"1" ^t H"0"	_	_	0.3 0.5				ns
Toggle Frequency	f _{Tog}	270	_	300		270	_	MHz

MC1670



LOGIC DIAGRAM



PIN ASSIGNMENT

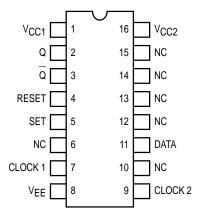
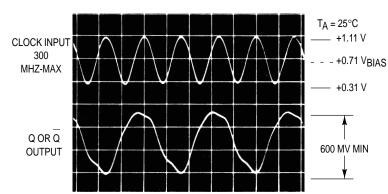


FIGURE 1 — TOGGLE FREQUENCY WAVEFORMS



- The output peak-to-peak voltage swing falls below 600 millivolts,
 OR
- 2. The device ceases to toggle (divide by two).

FIGURE 2 — MAXIMUM TOGGLE FREQUENCY (TYPICAL)

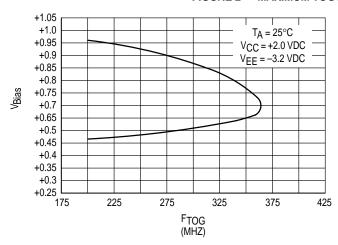
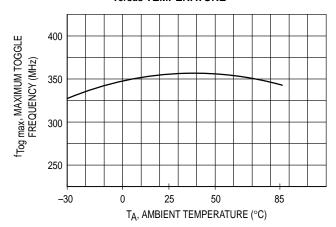


Figure 2 illustrates the variation in toggle frequency with the dc offset voltage (V_{Bias}) of the input clock signal. Figures 4 and 5 illustrate minimum clock pulse width recommended for reliable operation of the MC1670.

FIGURE 3 — TYPICAL MAXIMUM TOGGLE FREQUENCY versus TEMPERATURE



Temperature	−30°C	+25°C	+85°C
V _{Bias}	+0.66 Vdc	+0.71 Vdc	+0.765 Vdc

Note: All power supply and logic levels are shown shifted 2.0 volts positive.

FIGURE 4 — MINIMUM "DOWN TIME" TO CLOCK OUTPUT LOAD = 50 Ω

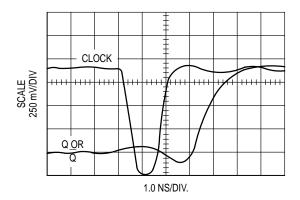
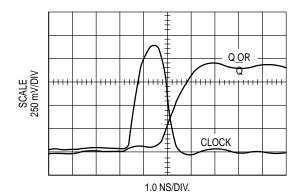
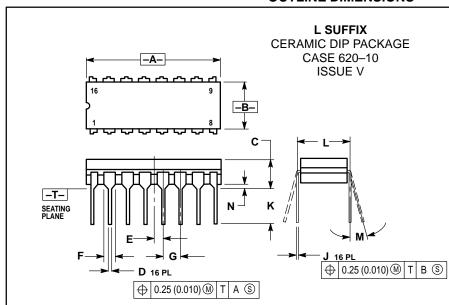


FIGURE 5 — MINIMUM "UP TIME" TO CLOCK OUTPUT LOAD = 50 Ω



MOTOROLA 4–358

OUTLINE DIMENSIONS



NOTES:

- 1. DIMENSIONING AND TOLERANCING PER
- ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
- DIMENSION F MAY NARROW TO 0.76 (0.030)
 WHERE THE LEAD ENTERS THE CERAMIC
 BODY

	INCHES		MILLIMETERS		
DIM	MIN	MAX	MIN	MAX	
Α	0.750	0.785	19.05	19.93	
В	0.240	0.295	6.10	7.49	
С		0.200		5.08	
D	0.015	0.020	0.39	0.50	
Е	0.050 BSC		1.27 BSC		
F	0.055	0.065	1.40	1.65	
G	0.100 BSC		2.54 BSC		
Н	0.008	0.015	0.21	0.38	
K	0.125	0.170	3.18	4.31	
L	0.300 BSC		7.62 BSC		
M	0°	15°	0 °	15°	
N	0.020	0.040	0.51	1.01	

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How to reach us:

USA/EUROPE/Locations Not Listed: Motorola Literature Distribution; P.O. Box 5405, Denver, Colorado 80217. 1–800–441–2447

Mfax™: RMFAX0@email.sps.mot.com – TOUCHTONE 602–244–6609 INTERNET: http://Design=NET.com

JAPAN: Nippon Motorola Ltd.; Tatsumi–SPD–JLDC, 6F Seibu–Butsuryu–Center, 3–14–2 Tatsumi Koto–Ku, Tokyo 135, Japan. 03–81–3521–8315

ASIA/PACIFIC: Motorola Semiconductors H.K. Ltd.; 8B Tai Ping Industrial Park, 51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852–26629298



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