

R2J25953

H-Bridge Control High Speed Power Switching with Built-in Driver IC and Power MOS FET

R07DS0044EJ0300 Rev.3.00 Sep 01, 2010

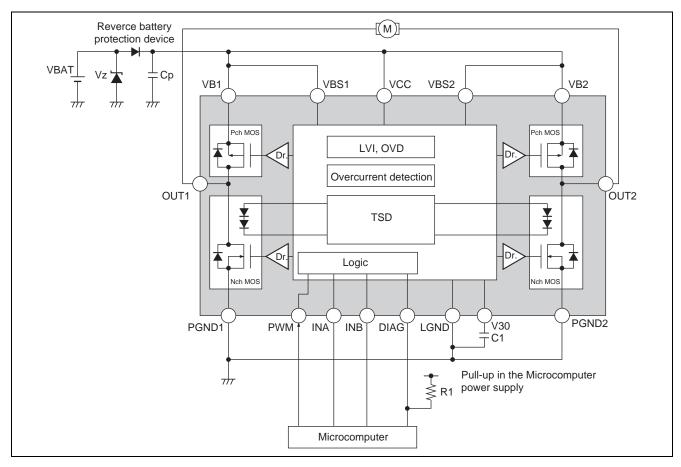
Description

The R2J25953 multi-chip module incorporates high-side Pch MOS FET, low-side Nch MOS FET, and Bi-CMOS driver in a single HSOP-36 package.

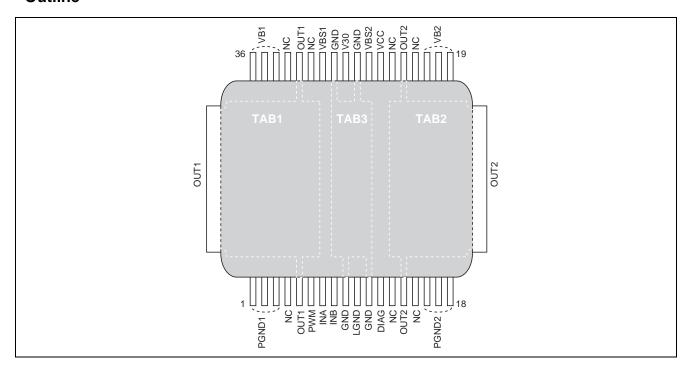
Features

- For Automotive application
- Built-in low on state resistance MOS FET.
 (Pch: 16 mΩ Max., Nch: 11 mΩ Max.)
- Pch MOS FET is adopted on the high-side, and the charge pump noise was lost.
- Built-in protection circuit of Thermal shut-down (TSD), Low Voltage Inhit (LVI), Overvoltage Detection (OVD) and Overcurrent Detection.
- Built-in diagnostic function.
- Built-in cross-conduction protection.
- Small Surface mounting package: HSOP-36

Block Diagram



Outline



Pin Description

Pin No.	Pin name	Description	Pin No.	Pin name	Description
1 to 3	PGND1	Power GND1	22	NC	No connect
4	NC	No connect	23	OUT2	Internally corrected to TAB2
5	OUT1	Internally corrected to TAB1	24	NC	No connect
6	PWM	PWM input	25	VCC	IC power supply
7	INA	A input	26	VBS2	VB2 sense
8	INB	B input	27	GND	Internally corrected to TAB3
9	GND	Internally corrected to TAB3	28	V30	IC bias voltage (3.3 V)
10	LGND	IC GND	29	GND	Internally corrected to TAB3
11	GND	Internally corrected to TAB3	30	VBS1	VB1 sense
12	DIAG	Diagnostic output (open drain)	31	NC	No connect
13	NC	No connect	32	OUT1	Internally corrected to TAB1
14	OUT2	Internally corrected to TAB2	33	NC	No connect
15	NC	No connect	34 to 36	VB1	MOS FET power supply 1
16 to 18	PGND2	Power GND2	TAB1	OUT1	MOS FET output 1
19 to 21	VB2	MOS FET power supply 2	TAB2	OUT2	MOS FET output 2
			TAB3	GND	IC tab GND

Absolute Maximum Ratings

 $(Ta = 25^{\circ}C)$

Item	Symbol	Ratings	Unit	Note
Supply voltage	VB	18	V	1
Input voltage	Vin	−0.3 to VB	V	2
Diag voltage	Vdiag	−0.3 to VB	V	3
Output current	lout	50	A	
Diag current	Idiag	5	mA	3
Junction temperature	Tj	-40 to +150	°C	
Storage temperature	Tstg	-55 to +150	°C	
Power temperature	Pt	40	W	4

Notes: 1. 28 V at 25°C, 1 min. 40 V at 25°C, 1 sec.

- 2. Applies to INA, INB, and PWM. Clamps it with 19 V typ.
- 3. Applies to DIAG
- 4. One element operation: $Tc = 25^{\circ}C$

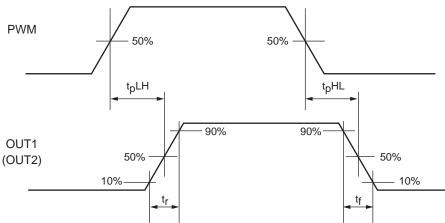
Electrical Characteristics

 $(Ta = 25^{\circ}C, VB = VCC = 12 V)$

Item		Symbol	Min	Тур	Max	Unit	Condition	Application terminal	Note
Supply current		Icc0	_	30	50	μА	Standby	VCC	1
		Icc	_	3.5	10	mA	ACTIVÉ		1
VB	Input current	linvbL	_	_	±1	μΑ	Standby	VB1/VB2	1
MOS	Static High-side	RonH	_	9	16	mΩ	lout = 15 A		
	resistance						Pulse test		
	Static Low-side	RonL	_	7	11	mΩ	lout = 15 A		
	resistance						Pulse test		
	Off state current	loff	_	10	20	μΑ			
IN	Input current	linL	_	_	±10	μΑ	Vin = 0 V	INA/INB	
		linH	_	_	±10	μA	Vin =VB	/PWM	
	High threshold	Vthin	3.0	_	_	V			
	Low threshold	Vtlin	_	_	1.5	V			
Delay time		tpLH	_	1.5	4.0	μS	OUT/IN (PWM)	OUT, PWM	2
		tpHL	_	3.0	6.0	μS	, ,		
Rise time		tr	_	1.0	3.0	μS	OUT	OUT1/2	
Fall time	Fall time		_	1.0	3.0	μS	1		
DIAG	Output voltage	VDiag	_	0.4	0.6	V	I = 2 mA, DIAG = Low	DIAG	
	Leak current	IDiag	_	_	±10	μΑ	Vdiag = 0 V		
TSD	Shut-down	Tsd	150	175	_	°C			3
	temperature								
	Hysteresis	Thys	7	25	_	°C	1		
OVD	Shut-down	VtvH	28.9	34	39.1	V		VCC	
	voltage								
	Return voltage	VtvL	21.3	25	28.7	V			
LVI	Return voltage	VRLVI	5.0	5.35	5.6	V		VCC	
	Hysteresis	VHLVI	0.3	0.5	0.7	V			
Overcurrent	Shut-down	IcL	35	_	_	Α		OUT1/2	
detection	current								
	Detection time	tcL	60	10	20	μS	<u></u>		
MOS FET	Pch forward	VDFp	_	1.0	1.3	V	IF = 50 A,		
Body-diode	voltage						Pulse test		
	Nch forward voltage	VDFn	_	1.0	1.3	V			

Notes: 1. Refer to truth table.

2. Refer to the input condition to the truth table.



3. It is a design guaranteed value, and it doesn't apply to the final test.

Truth table

The operation of OUT1, OUT2, and DIAG is shown in the following.

Input				Status			Output		State	
PWM	INA	INB	LVI	TSD	Overcurrent detection	OVD	OUT1	OUT2	DIAG	
High	High	High			off		High	High	High	ACTIVE
		Low			off		High	Low	High	
	Low	High			off		Low	High	High	
		Low		off				Low	High	
Low	High	High		off				Hi-z	High	
		Low		off			Hi-z	Low	High	
	Low	High		off			Low	Hi-z	High	
		Low	Protection circuit doesn't operate			Low	Low	High	STANDBY	
Exclu	Excluding All = Low on x x		x	Х	Hi-z	Hi-z	High	LVI		
At leas	At least one of PWM,		off	on	x	Х	Hi-z	Hi-z	Low	TSD
INA, ar	INA, and INB is high.		off	х	on	Х	Hi-z	Hi-z	Low	Overcurrent
							(Latch)	(Latch)	(Latch)	detection
			off	Х	х	on	Hi-z	Hi-z	Low	OVD

Notes 1. x: Regardless of High, Low, on and off.

- 2. Protect circuit
 - off = undetection
 - on = detection
- 3. State of pin OUT
 - Low: Nch MOS FET ON, High: Pch MOS FET ON, Hi-z: Nch and Pch MOS FET OFF
- 4. The latch of overcurrent detection is released when LVI = on or INA = INB = Low.

External Parts List

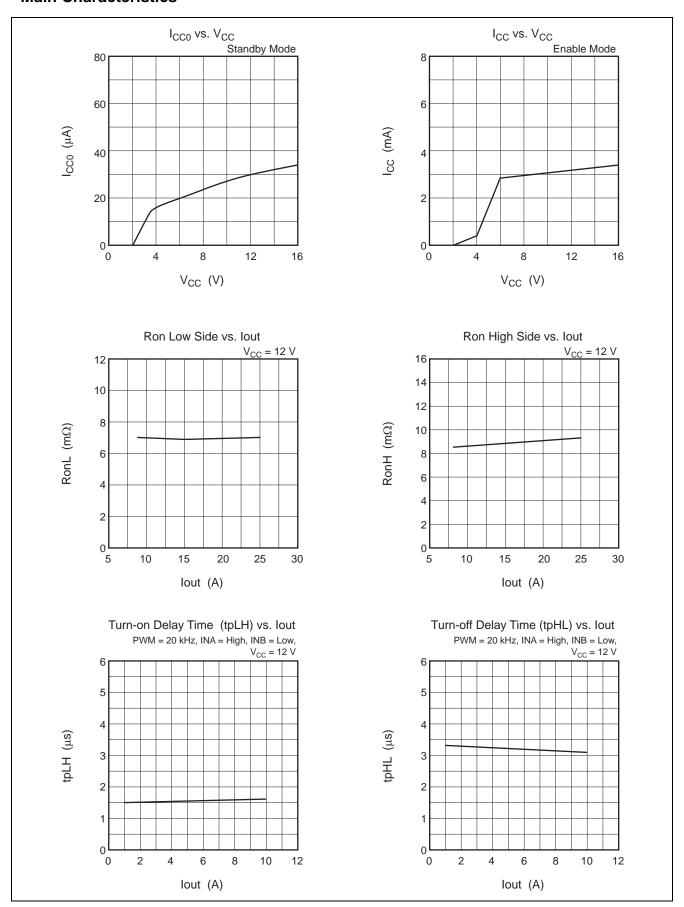
Parts No.	Recommended value	Purpose
Ср	10 μF	Power supply bypass capacitor
R1	> 10 kΩ	Pull up Pin DIAG
C1	0.033 μF	Pin V30 bypass capacitor

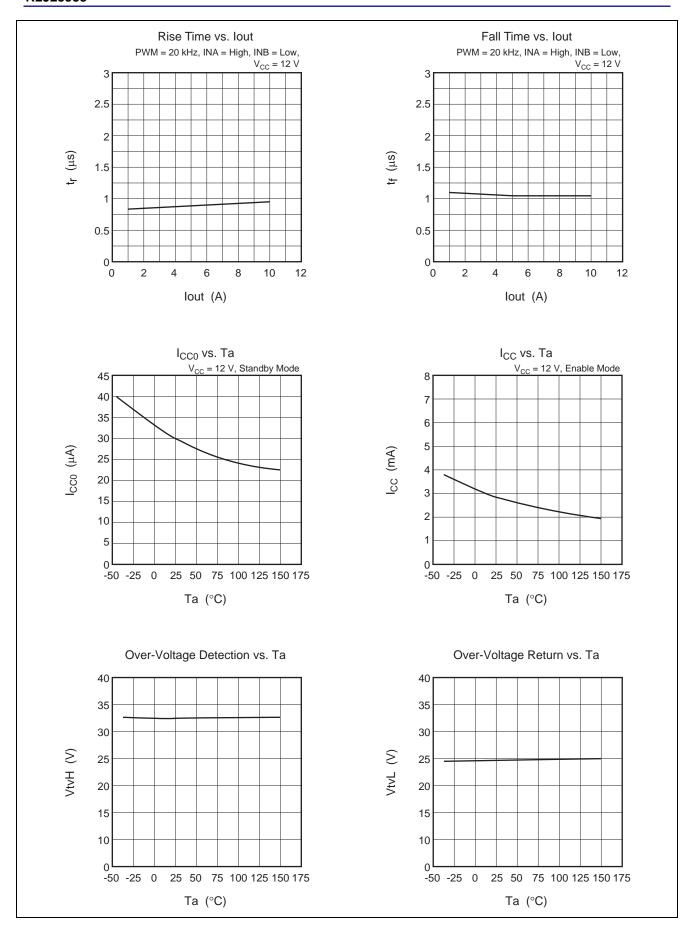
Equivalent Circuit

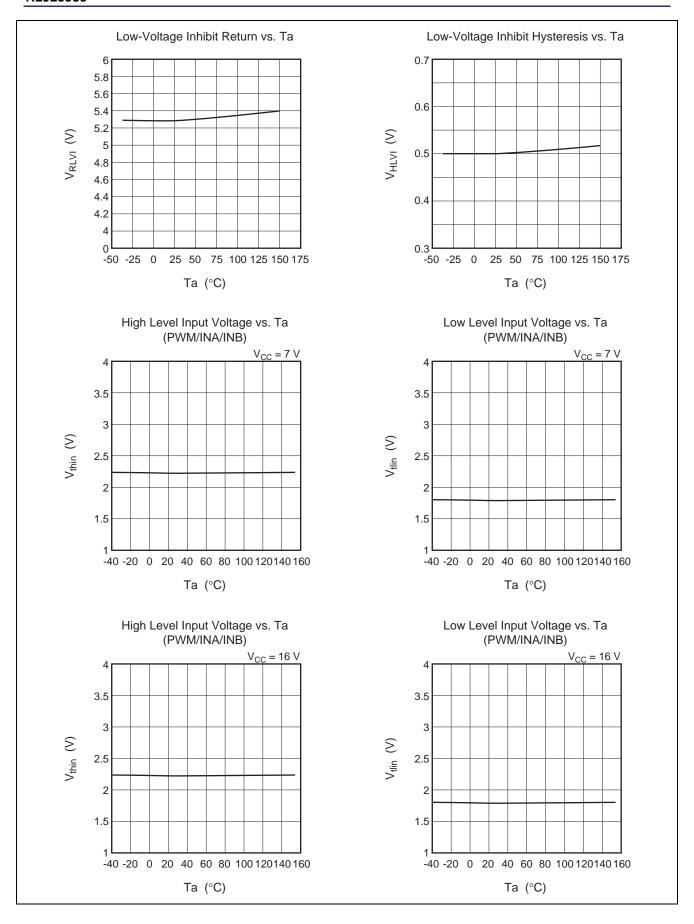
Pin name	Pin No.	Equivalent circuit
PGND1 PGND2	1, 2, 3, 16, 17, 18	LGND O OUT1 OUT2 Nch MOS PGND1 PGND2
OUT1 OUT2	5, 32, TAB1 14, 23, TAB2	Pch MOS OUT1 OUT2 Nch MOS PGND1 PGND2
PWM INA INB	6 7 8	PWM INA INB LGND O Vth Driver
DIAG	12	O LGND
VB1 VB2	34, 35, 36 19, 20, 21	VCC O VB1 VB2

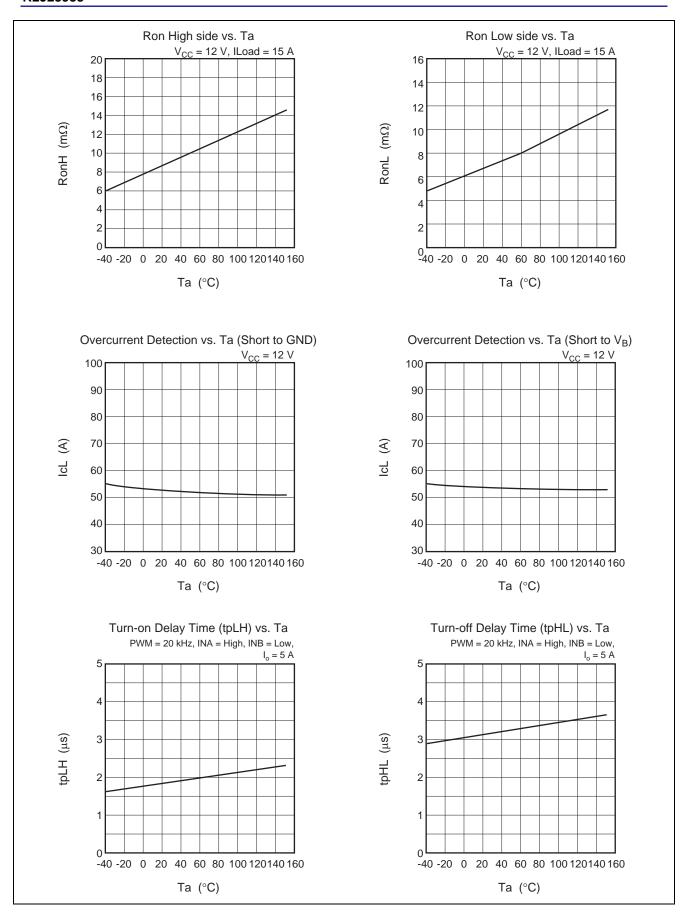
Pin name	Pin No.	Equivalent circuit
VCC	25	
LGND	10	→ O vcc
		<u> </u>
		——— CIGND
VBS1 VBS2	30 26	VB1 O
VD32	20	VBZ \
		VBS1.6
		VBS1 VBS2
V30	28	• O vcc
		¬¬ Т
		→ → → → → → → → → →
		₹ ★
		LGND

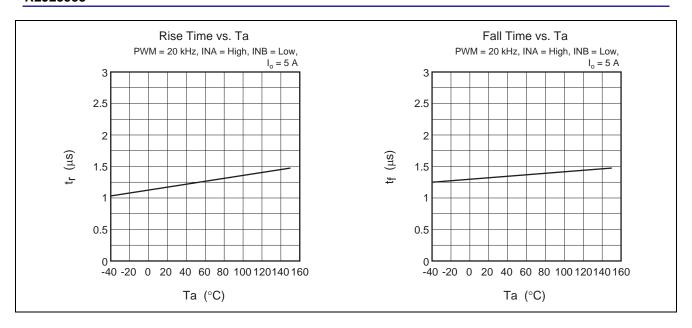
Main Characteristics



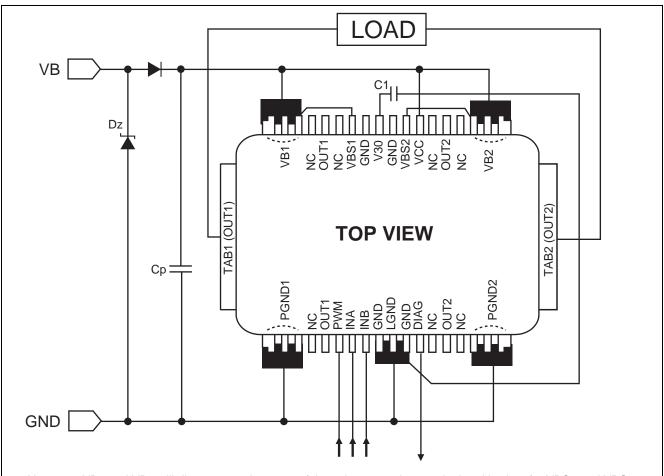








Recommended Wiring Pattern



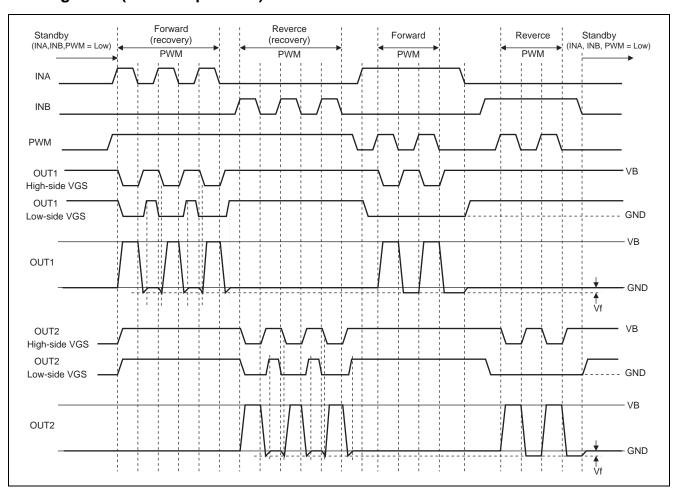
- Notes 1. VB1 and VB2 will diverge soon because of the voltage sensing terminal and it wires for VBS1 and VBS2.
 - 2. GND side wiring of C1 must diverge from the LGND side.
 - 3. Insertion examination of use conditions about the reverse battery protection device and Dz.
 - 4. The reverse battery protection please choose the parts such as MOSFET or Schottky diode by use.

Operational Mode

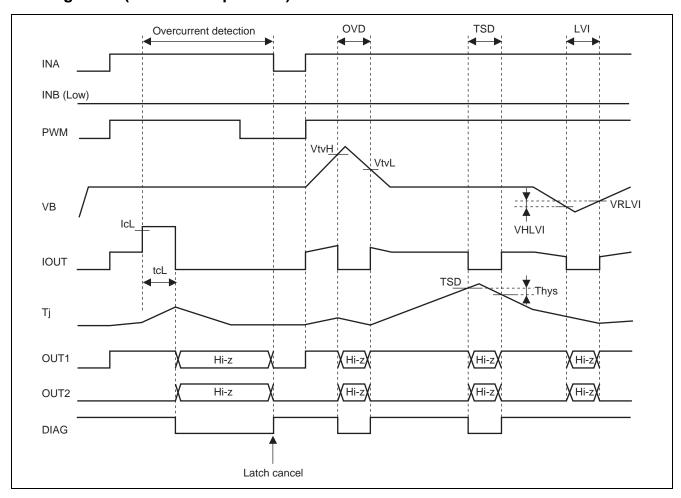
When PWM is controlled, recovery control can be selected because of the low loss. However, please note that reverse-brake hangs at acceleration of the motor.

Operational mode	Circuit operational
Example 1. Forward mode (Recovery control) INA = PWM on/off INB = Low PWM = High	ON ⇔ OFF (Synchronizes with PWM) OFF ⇔ ON (Synchronizes with PWM) OFF ⇔ ON (Synchronizes with PWM)
Example 2. Reverse mode (Recovery control) INA = Low INB = PWM on/off PWM = High	OFF ON (Synchronizes with PWM) ON OFF ⇔ ON (Synchronizes with PWM)
Example 3. Forward mode (No recovery control) INA = High INB = Low PWM = PWM on/off	ON ⇔ OFF (Synchronizes with PWM) OFF OFF ON ON ON
Example 4. Reverse mode (No recovery control) INA = Low INB = High PWM = PWM on/off	OFF ON ⇔ OFF (Synchronizes with PWM) ON OFF

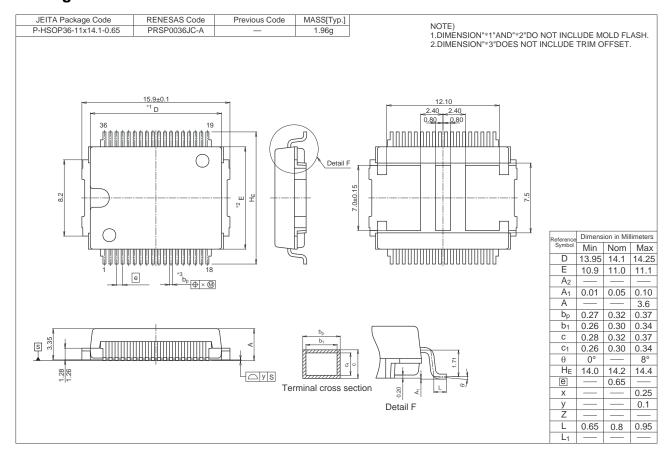
Timing Chart (Normal operation)



Timing Chart (Protection operation)



Package Dimensions



Ordering Information

Part No.	Quantity	Shipping Container
R2J25953-00	700 pcs/ box	Tray

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