

# Slew Rate Controlled Ultralow Noise 1A Isolated DC/DC Transformer Driver

## FEATURES

- Reduced Conducted and Radiated EMI
- Single Resistor Control of Output Switch Voltage and Current Slew Rates
- Cross Conduction Prevention Circuitry
- Two 1A Current Limited Power Switches
- Low Minimum Supply Voltage: 2.8V
- Low Shutdown Current: <math><20\mu\text{A}</math>
- 50% Duty Cycle
- 20kHz to 250kHz Oscillator Frequency
- Synchronizable to 300kHz
- Overcurrent and Overtemperature Protected

## APPLICATIONS


- Low Noise Isolated Supplies
- Radio and Telecom Supplies
- Distributed Supplies
- Medical Instruments
- Precision Instruments
- Low Noise Filament Supplies

## DESCRIPTION

The LT<sup>®</sup>3439 is a push-pull DC/DC transformer driver that reduces conducted and radiated electromagnetic interference (EMI). Ultralow noise and EMI are achieved by controlling the output switch voltage and current slew rates. Slew rates are user adjustable to optimize output noise versus efficiency. The LT3439 can reduce high frequency harmonic content by as much as 40dB with only a minor decrease in efficiency.

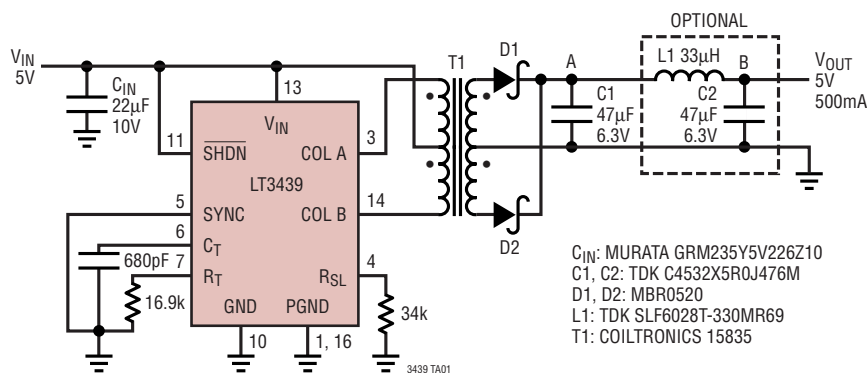
The LT3439 includes two 1A current limited power switches to ensure start-up under heavy loads. It also includes an oscillator that can be synchronized to an external clock for more accurate placement of switcher harmonics. Protection features include current limiting, undervoltage lock-out, thermal shutdown and cross conduction prevention circuitry.

The LT3439 is available in a thermally enhanced 16-pin TSSOP with an exposed backside.

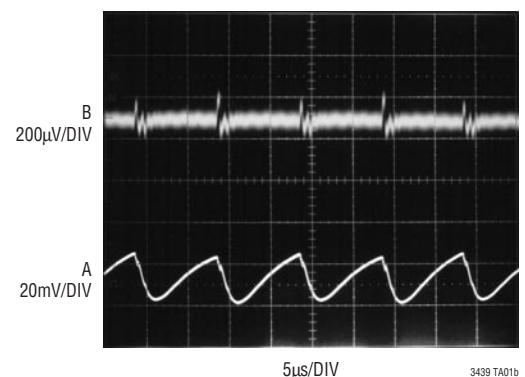
 , LTC and LT are registered trademarks of Linear Technology Corporation.

## TYPICAL APPLICATION

Low Noise 5V to 5V Push-Pull DC/DC Transformer



5V Output Noise

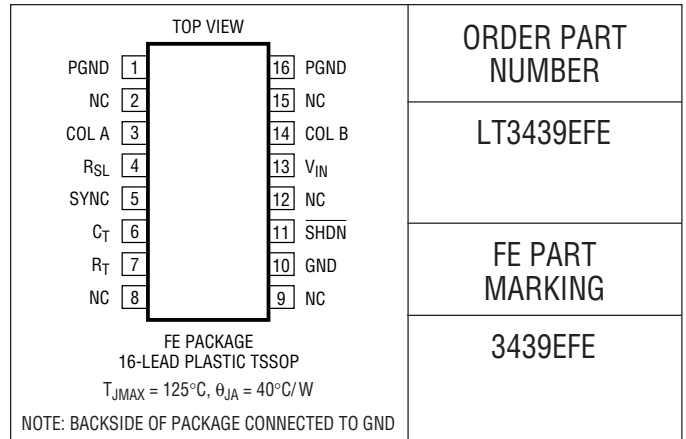


## ABSOLUTE MAXIMUM RATINGS

(Note 1)

$V_{IN}$ Voltage .....	20V
COL A, COL B Voltage .....	35V
SHDN, SYNC Voltage .....	20V
Maximum Junction Temperature .....	150°C
Operating Junction Temperature Range	
(Note 2) .....	-40°C to 125°C
Storage Temperature Range .....	-65°C to 150°C
Lead Temperature (Soldering, 10 sec) .....	300°C

## PACKAGE/ORDER INFORMATION



ORDER PART NUMBER

LT3439EFE

FE PART MARKING

3439EFE

Consult LTC Marketing for parts specified with wider operating temperature ranges.

## ELECTRICAL CHARACTERISTICS

The ● denotes specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .

$V_{IN} = 5\text{V}$ ;  $R_T = 16.9\text{k}$ ;  $C_T = 680\text{pF}$ ;  $R_{SL} = 16.9\text{k}$ ; COL A, COL B, SHDN pins open, unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS	
<b>Supply and Shutdown</b>							
$V_{IN}$	Operating Range		●	2.8	17.5	V	
$V_{IN(MIN)}$	Minimum Input Voltage			2.55	2.7	V	
$I_{VIN}$	Supply Current	$2.8\text{V} \leq V_{IN} \leq 17.5\text{V}$	●	12		mA	
$I_{VIN(SHDN)}$	Supply Current in Shutdown Mode	$2.8\text{V} \leq V_{IN} \leq 17.5\text{V}$ , $V_{SHDN} = 0\text{V}$		5	20	$\mu\text{A}$	
$V_{SHDN(ON)}$	Shutdown Turn-On Threshold	$2.8\text{V} \leq V_{IN} \leq 17.5\text{V}$	●	1.3	1.4	V	
$V_{SHDN(OFF)}$	Shutdown Turn-Off Threshold	$2.8\text{V} \leq V_{IN} \leq 17.5\text{V}$	●	1.20	1.26	V	
$I_{SHDN}$	Shutdown Pin Current Hysteresis	$2.8\text{V} \leq V_{IN} \leq 17.5\text{V}$ , $V_{SHDN} = 1.4\text{V}$	●	10	20	$\mu\text{A}$	
<b>Oscillator and Sync</b>							
$f_{MAX}$	Oscillator Frequency		●		250	kHz	
$f_{SYNC}$	Synchronization Frequency Range		●		300	kHz	
$V_{SYNC}$	SYNC Pin Threshold		●	1.4	2.25	V	
$R_{SYNC}$	SYNC Pin Input Resistance			40		k $\Omega$	
<b>Output Switches (COL A, COL B)</b>							
DC	Switch Duty Cycle		●	50		%	
BV	Output Switch Breakdown Voltage	$2.8\text{V} \leq V_{IN} \leq 17.5\text{V}$	●	35	50	V	
$R_{ON}$	Output Switch On Resistance	$I_{COLA}$ or $I_{COLB} = 0.75\text{A}$	●	0.5	0.95	$\Omega$	
$I_{LIM(MAX)}$	Switch Current Limit			1.2	1.4	1.65	A
<b>Slew Control</b>							
$V_{SLEWR}$	Output Voltage Slew Rising Edge	Collector A or B		17		V/ $\mu\text{s}$	
$V_{SLEWF}$	Output Voltage Slew Falling Edge	Collector A or B		17		V/ $\mu\text{s}$	
$I_{SLEWR}$	Output Current Slew Rising Edge	Collector A or B		5		A/ $\mu\text{s}$	
$I_{SLEWF}$	Output Current Slew Falling Edge	Collector A or B		5		A/ $\mu\text{s}$	

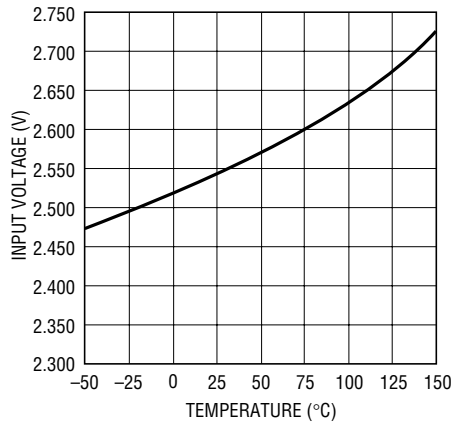
**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

**Note 2:** The LT3439E is guaranteed to meet performance specifications from 0°C to 70°C. Specifications over the -40°C to 125°C operating junction temperature range are assured by design, characterization and correlation with statistical process controls.

sn3439 3439fs

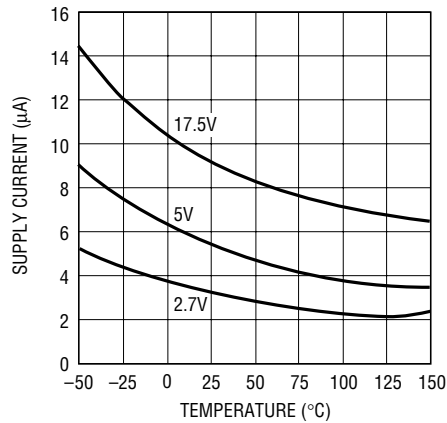
# TYPICAL PERFORMANCE CHARACTERISTICS

**Minimum Input Voltage vs Temperature**



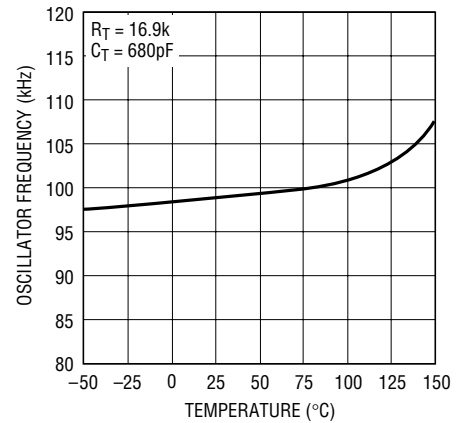
3439 G01

**Supply Current in Shutdown Mode vs Temperature**



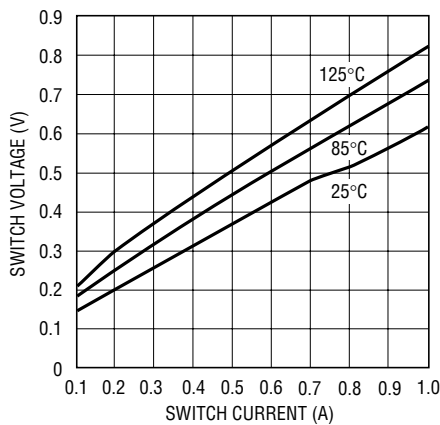
3439 G02

**Oscillator Frequency vs Temperature**



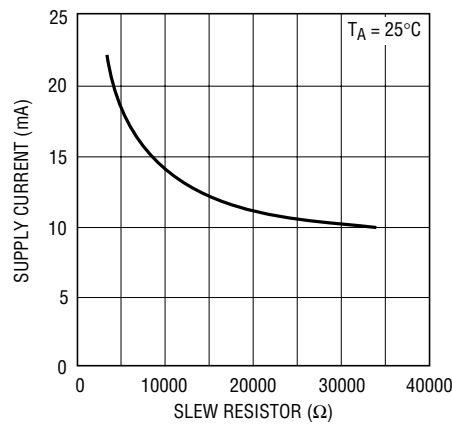
3439 G03

**Switch Voltage Drop vs Switch Current**



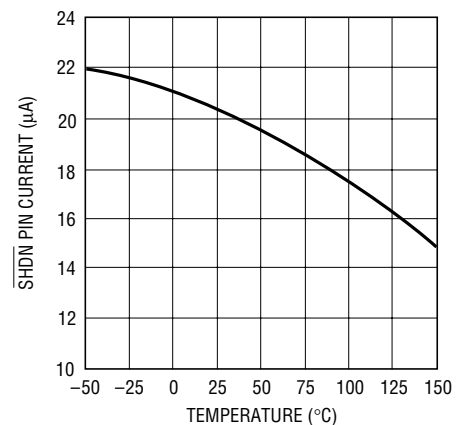
3439 G04

**Supply Current vs Slew Resistor**



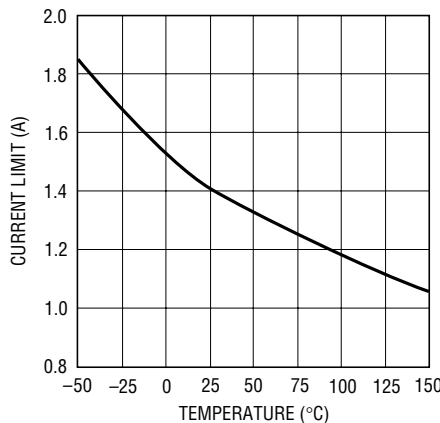
3439 G05

**SHDN Pin Hysteresis Current vs Temperature**



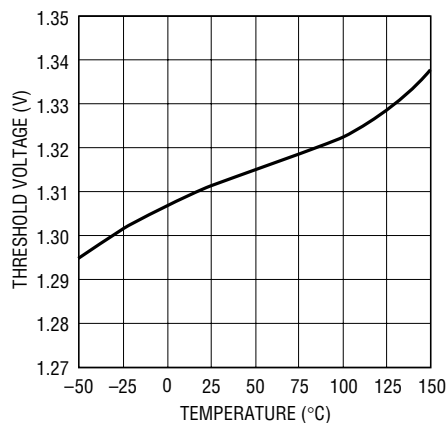
3439 G06

**Current Limit vs Temperature**



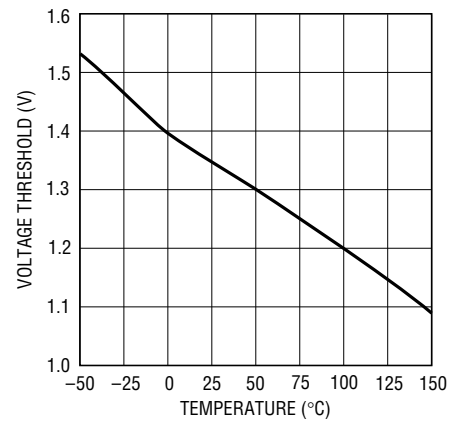
3439 G07

**SHDN Pin Voltage Threshold vs Temperature**



3439 G08

**SYNC Pin Voltage Threshold vs Temperature**



3439 G09

## PIN FUNCTIONS

**PGND (Pins 1, 16):** Power ground is connected to the emitter of the power switches via an internal sense resistor. It has large currents flowing through it and should be connected to a good quality ground plane.

**COL A, COL B (Pins 3, 14):** These are the open collectors of the output power switches. They are connected to the outer terminals of the center tap transformer. Large currents flow into these pins so external traces should be kept as short as possible.

**R<sub>SL</sub> (Pin 4):** The slew control resistor sets the maximum current and voltage slew rate for the collectors A and B. The minimum resistor value is 3.4k for fast slewing and the maximum resistor is 34k for slow slewing. For more details, see “Slew Rate Setting” in the Applications Information section of this data sheet.

**SYNC (Pin 5):** The SYNC pin can be used to synchronize the oscillator to an external clock. R<sub>T</sub> and C<sub>T</sub> should be set such that the oscillator clock frequency is approximately 10% below the external clock frequency. If unused, this pin should be tied to GND. For more details, see “Oscillator Sync” in the Applications Information section of this data sheet.

**C<sub>T</sub> (Pin 6):** The oscillator capacitor pin is used in conjunction with the R<sub>T</sub> pin to set the oscillator frequency. For R<sub>T</sub> = 16.9k, C<sub>T</sub> can be calculated as follows:

$$C_T(\text{nF}) = 70/f_{\text{OSC}}(\text{kHz})$$

The transformer operating frequency and the frequency of each output is one half of the frequency of the oscillator.

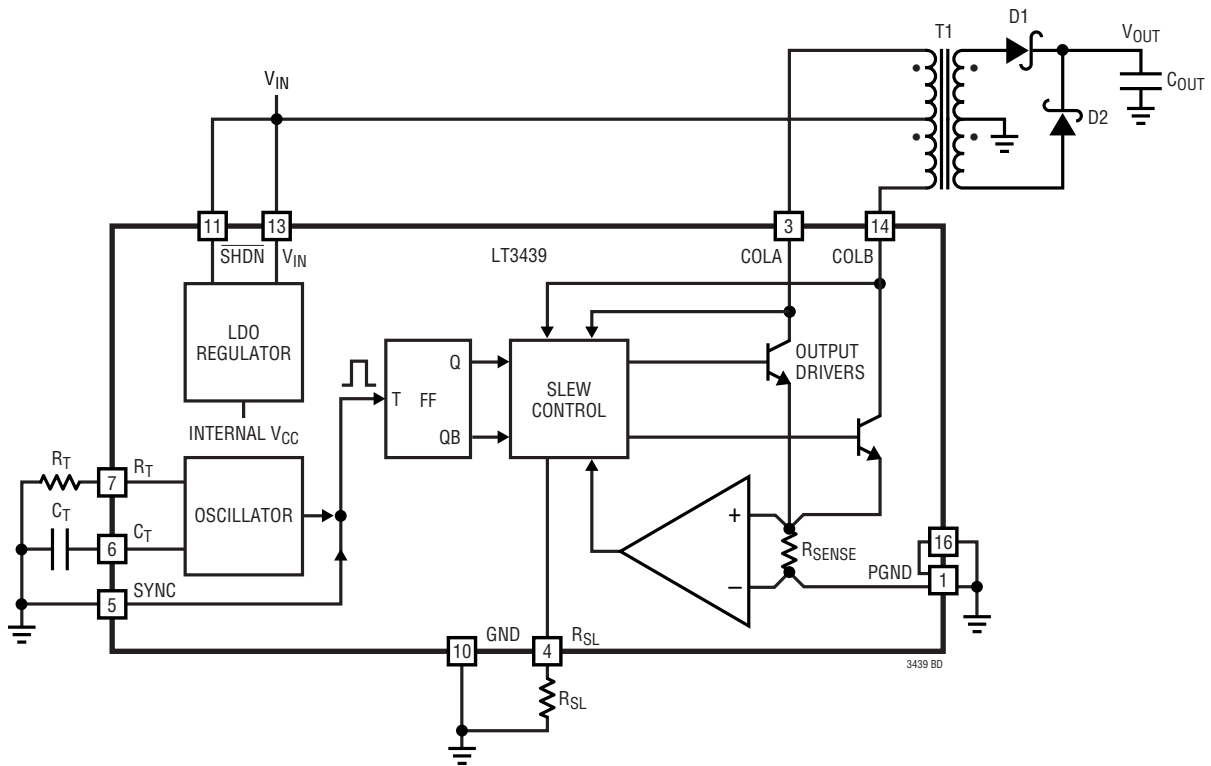
**R<sub>T</sub> (Pin 7):** The oscillator resistor pin is used to set the charge and discharge currents of the oscillator capacitor. The nominal value is 16.9k. The resistance can be adjusted between  $\pm 25\%$  of nominal for better frequency accuracy.

**SHDN (Pin 11):** The SHDN pin is used to shut down the part. Grounding this pin will disable all internal circuitry. Increasing the SHDN voltage above the turn-on threshold will enable the part. At the turn-on threshold, approximately 20 $\mu$ A of current is sourced out of the pin. This current, in conjunction with the Thevenin resistance on the pin, sets up the hysteresis. This allows the user to set the undervoltage lockout (UVLO) of the supply and the amount of start-up hysteresis with a resistor divider off of the input voltage. Above 2.1V on the SHDN pin, the hysteresis current is reduced to zero. If unused the pin can be left floating or tied directly to the input voltage.

**GND (Pin 10):** Signal Ground. The oscillator, slew control circuitry and the internal regulator are referred to signal ground. Internally, signal ground is tied to substrate and the exposed backside of the device. Connect the GND pin to the ground plane and keep the connection free of large currents.

**V<sub>IN</sub> (Pin 13):** This is the supply pin for the part and should be bypassed with a 4.7 $\mu$ F or greater, low ESR capacitor. When V<sub>IN</sub>  $\leq$  2.5V, an internal undervoltage lockout circuit will trip and turn both outputs off.

## BLOCK DIAGRAM



## OPERATION

### Push-Pull Topology

The push-pull DC transformer topology is a very straightforward switching power supply. The two switches are turned on out of phase at 50% duty cycles. During the switch on time,  $V_{IN}$  is applied across the primary side of the transformer. The voltage on the secondary side of the transformer is simply  $V_{IN}$  times the turns ratio. The diodes rectify the secondary voltage and generate the output voltage. The output capacitor is for hold-up and filtering.

Some of the topology's advantages are: 1) Stepping up or down the input voltage can easily be done by setting the turns ratio. 2) The transformer provides isolation between the input and output. 3) Each switch cycle applies  $V_{IN}$  across the transformer in opposite polarities. Therefore, the transformer core never saturates and a separate reset circuit is not necessary.

The push-pull topology is not without its concerns. An imbalance in the two sides of the transformer can

eventually cause the transformer to saturate. Also, during the turn-off of the switches, the leakage inductance causes a large undesirable voltage spike. The LT3439 slew control feature addresses both of these concerns and is discussed in the Applications Information section.

### Slew Control

Control of voltage and current slew rate is maintained via two feedback loops. One loop controls the output switch collector voltage  $dV/dt$  and the other loop controls the emitter current  $dI/dt$ . Output slew control is achieved by comparing the two currents generated by these slewing events to a current set by the external resistor  $R_{SL}$ . The two control loops work together to provide a smooth transition from voltage slew control to current slew control.

### Internal Regulator

Most of the control circuitry operates from an internal 2.4V low dropout regulator that is powered from  $V_{IN}$ .  $V_{IN}$  can

## OPERATION

vary from 2.8V to 17.5V with very little change in device performance. When the part is in shutdown mode, the internal regulator is turned off, drawing less than 20 $\mu$ A of current from  $V_{IN}$ .

### Overcurrent Protection

A linearly controlled current limit circuit is provided to protect the circuit from excessive currents and to facilitate start-up into a highly capacitive load. Upon reaching current limit, the switching cycle is not terminated, instead the base drive to the output transistor is regulated to maintain the maximum current over the entire switch cycle. Very high power dissipation in the switches occurs during this mode of operation. If the current limit is enabled for a long enough period of time, over temperature protection shutdown will be enabled to protect the device.

### Overttemperature Protection

When the IC has exceeded the maximum temperature the part will trigger the overtemperature protection circuit where both output drivers are turned off.

### Undervoltage Lockout Protection

When  $V_{IN}$  is below 2.55V the part will go into undervoltage lockout mode where both output drivers are turned off.

### No Load Operation

The operation of the supply is stable all the way down to zero load and a preload is not required.

## APPLICATIONS INFORMATION

Reducing EMI from switching power supplies has traditionally invoked fear in designers. Many switchers are designed solely on efficiency and, as such, produce waveforms filled with high frequency harmonics that propagate through the rest of the supply.

The LT3439 provides control of two of the primary variables for controlling EMI while switching inductive loads: switch voltage slew rate and switch current slew rate. The use of this part will reduce noise and EMI over conventional switch mode controllers. Because these variables are under control, a supply built with this part will exhibit far less tendency to create EMI and less chance of running into problems during production.

It is beyond the scope of this data sheet to get into EMI fundamentals. AN70, "A Monolithic Switching Regulator with 100 $\mu$ V Output Noise" contains much information concerning noise in switching regulators and should be consulted.

### Oscillator Frequency

The internal oscillator generates the switching frequency that determines the fundamental positioning of the

harmonics. Using quality external components is important to ensure oscillator frequency stability. A current defined by external resistor  $R_T$  charges and discharges the capacitor  $C_T$  creating a saw tooth waveform where the outputs' states change at the peak. The frequency of each output is one half of the frequency of the oscillator.

By having both components external, the user has greater flexibility in setting the frequency and the frequency is less susceptible to any temperature variations in the device.

The external capacitance  $C_T$  is chosen by:

$$C_T(\text{nF}) = 1183/[f_{\text{OSC}}(\text{kHz}) \cdot R_T(\text{k}\Omega)]$$

where  $f_{\text{OSC}}$  is the desired oscillator frequency.

For  $R_T$  equal to 16.9k, this simplifies to:

$$C_T(\text{nF}) = 70/f_{\text{OSC}}(\text{kHz})$$

$$\text{e.g., } C_T = 1\text{nF for } f_{\text{OSC}} = 70\text{kHz}$$

Nominally,  $R_T$  should be set to 16.9k.

Low tolerance and low temperature coefficient components are recommended.

## APPLICATIONS INFORMATION

### Oscillator SYNC

The oscillator can be synchronized to an external clock. Set the RC timing components for an oscillator frequency 10% below the desired sync frequency.

It is recommended that the SYNC pin be driven with a square wave that has an amplitude greater than 2V, a pulse width greater than 1 $\mu$ s and a rise time less than 500ns. The rising edge of the sync waveform triggers the change in the state of the outputs.

### Slew Rate Setting

Setting the LT3439 maximum slew rate is easy. The external resistor to ground on the  $R_{SL}$  pin sets the maximum slew rate. To determine the maximum slew rate connect a 50k resistor pot with a 3.4k series resistance to the  $R_{SL}$  pin. Start at the lowest resistance setting and increase the pot until the noise level meets your requirements. Note that slower slewing waveforms will lower the power supply efficiency. Consult Linear Technology Application Note 70, "A Monolithic Switching Regulator with 100 $\mu$ V Output Noise" for recommended noise measurement techniques.

### Shutdown

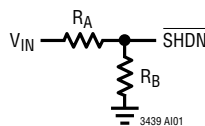
The  $\overline{SHDN}$  pin is used to shut down the part. Grounding this pin will disable all internal circuitry.

Increasing the  $\overline{SHDN}$  voltage above the turn-on threshold, approximately 1.3V, will enable the part. At the turn-on threshold approximately 20 $\mu$ A of current is sourced out of the pin. This current, in conjunction with the Thevenin resistance on the pin, sets up the amount of hysteresis. This allows the user to set the turn-on voltage of the supply and the start-up hysteresis with a resistor divider. The hysteresis can be used to prevent the part from shutting down due to input voltage sag from an initial high current draw. When the  $\overline{SHDN}$  pin is greater than 2.1V, the hysteresis current is reduced to zero.

In addition to the current hysteresis, there is also approximately 35mV of voltage hysteresis on the  $\overline{SHDN}$  pin.

If a resistor divider is used to set the turn on threshold the resistors are determined by the following equations:

$$V_{ON} = \left( \frac{R_A + R_B}{R_B} \right) \cdot V_{\overline{SHDN}}$$



$V_{ON}$  is the input voltage at which the supply will turn on and  $V_{\overline{SHDN}}$  is the  $\overline{SHDN}$  pin turn-on threshold, typically 1.3V.

$$V_{HYST} = R_A \cdot \left( \frac{\Delta V_{\overline{SHDN}}}{R_A \parallel R_B} + I_{\overline{SHDN}} \right)$$

$V_{HYST}$  is the actual hysteresis voltage seen at the input voltage.  $I_{\overline{SHDN}}$  is the current hysteresis sourced by the IC at the turn-on threshold, typically 20 $\mu$ A.  $\Delta V_{\overline{SHDN}}$  is the voltage hysteresis seen at the  $\overline{SHDN}$  pin at the turn-on threshold, typically 35mV.

The resistors can be calculated as follows:

$$R_A = \frac{(V_{HYST} \cdot V_{\overline{SHDN}} - V_{ON} \cdot \Delta V_{\overline{SHDN}})}{I_{\overline{SHDN}} \cdot V_{\overline{SHDN}}}$$

$$R_B = \frac{(V_{HYST} \cdot V_{\overline{SHDN}} - V_{ON} \cdot \Delta V_{\overline{SHDN}})}{I_{\overline{SHDN}} \cdot (V_{ON} - V_{\overline{SHDN}})}$$

For example if the turn-on voltage was to be set at 5V with 0.5V of hysteresis:

$$R_A = \frac{(0.5V \cdot 1.3V - 5V \cdot 35mV)}{20\mu A \cdot 1.3V} = 18.27k$$

$$R_B = \frac{(0.5V \cdot 1.3V - 5V \cdot 35mV)}{20\mu A \cdot (5V - 1.3V)} = 6.42k$$

The nearest 1% values would be 18.2k and 6.49k.

A resistor in series with the  $\overline{SHDN}$  pin could further change hysteresis without changing the turn-on voltage.

### Thermal Considerations

Decreasing the noise by lowering the slew rate of the output switches does not come for free. Lower slew rates

## APPLICATIONS INFORMATION

mean greater switching losses in the internal output switches. However, efficiency is only modestly reduced for a large improvement in EMI.

Care should be taken to ensure that the worst-case input voltage and load current conditions do not cause an excessive die temperature. The total power dissipation of the IC is dominated by three loss terms, regulator losses, saturation losses and switching losses. The following formulas may be used to approximate these losses:

1. Regulator Dissipation:

$$P_{VIN} = V_{IN} \left( 12\text{mA} + \frac{I}{60} \right)$$

where I is the average switch current.

2. Switch Saturation Dissipation:

$$P_{VSAT} = (V_{SAT})(I)$$

3. Switch Switching Dissipation:

$$P_{SW} = 10^{-6} \cdot V_{IN} \cdot I \cdot f_{OSC} \left( \frac{I}{(-2.3 \cdot 10^{-4} \cdot R_{SL} + 10.8)} + \frac{V}{(-1.7 \cdot 10^{-3} \cdot R_{SL} + 65.8)} \right)$$

Total IC power dissipation ( $P_D$ ) is the sum of these three terms. Die junction temperature can be computed as follows:

$$T_J = T_{AMB} + (P_D)(\theta_{JA})$$

where  $T_{AMB}$  is the ambient temperature,  $T_J$  is the junction temperature and  $\theta_{JA}$  is the thermal resistance from junction to ambient.

The LT3439 comes in the 16-pin TSSOP with exposed backside package that has a very low junction-to-ambient thermal resistance ( $\theta_{JA}$ ) of approximately 40°C/W.

### Transformer Design

Table 1 lists recommended center tapped transformers for a variety of input voltage, output voltage and power combinations.

Table 1

NOMINAL INPUT VOLTAGE	NOMINAL OUTPUT VOLTAGE	OUTPUT POWER	COILTRONICS PART NUMBER
5V	12V	1.5W	CTX02-13716-X1
5V	12V	3.0W	CTX02-13665-X1
5V	±15V	1.5W	CTX02-13713-X1
5V	±15V	3.0W	CTX02-13664-X1
5V	12V	1.5W	CTX02-13834-X3
5V	12V	10W	CTX02-13949-X1
12V	-12V	6W	CTX02-16076

These transformers will yield slightly high output voltages so that they can accommodate an LDO regulator on the output.

If your application is not listed, the LTC Applications group is available to assist in the choice and/or the design of the transformer.

In the design/selection of the transformer the following characteristics are critical and should be considered.

### Turns Ratio

The turns ratio of the transformer determines the output voltage. The following equation can be used as a first pass to calculate the turns ratio:

$$\frac{N_S}{N_P} = \frac{V_{OUT} + V_F}{V_{IN} - V_{SW}}$$

where  $V_F$  is the forward voltage of the output diode and  $V_{SW}$  is the voltage drop across the internal switches (see Typical Performance curves).

Sufficient margin should be added to the turns ratio to account for voltage drops due to transformer winding resistances. Also, if using an LDO for regulating the output voltage, don't forget to take into account the voltage drop that should be added to  $V_{OUT}$ .

### Magnetizing Current

The primary inductance of the transformer causes a ripple current that is independent of load current. The ripple current manifests itself in the output voltage through the parasitic resistances of the supply. Increasing the transformer magnetizing inductance can reduce the ripple



## APPLICATIONS INFORMATION

current. This can be accomplished by adding more turns onto a given core or selecting a new core with a higher inductance per turn squared characteristic ( $A_L$ ).

The following equation can be used to set the transformer primary inductance:

$$L_{PRI} = V_{IN} \frac{t_{ON}}{\Delta I}$$

$t_{ON}$  can be calculated by  $1/f_{OSC}$ .

$\Delta I$  is somewhat arbitrary but a general rule of thumb is to set it between 10% to 30% of  $I_{PRI}$  where  $I_{PRI}$  is calculated as follows:

$$I_{PRI} = \frac{V_{OUT} \cdot I_{OUT}}{V_{IN} \text{ Eff}}$$

Eff can be estimated at 70%.

### Winding Resistance

Resistance in either the primary or secondary winding will reduce overall efficiency and degrade load regulation. If efficiency or load regulation is unsatisfactory, verify that the voltage drops in the transformer windings are not excessive.

### Leakage Inductance

When the output switches turn off, the transformer leakage inductance causes a voltage spike on the output switch collector. The size of the voltage spike is proportional to the magnitude of the leakage inductance and to the square of the load current (energy stored in the leakage inductance). The voltage spike should be limited so that it does not exceed the voltage breakdown of the output switches. This can be accomplished by reducing the transformer's leakage inductance or by reducing the maximum slew rate. The voltage slew control will limit the voltage spike by dissipating the leakage energy in the power switches.

### Transformer Imbalance

A common concern for the push-pull topology is transformer imbalance. If the volt/second products of each half

of the switching cycle do not match, the transformer's flux level walks up the BH curve and the transformer goes into saturation. This is undesirable because the effective magnetizing inductance drops off and the magnetizing current increases rapidly. Fortunately, there are parasitics in the circuit that counteract the transformer saturation. When the transformer begins to saturate the magnetizing current increases in one half of the switching cycle and therefore, the IR drops increase thereby reducing the volt/second product of that half cycle. The transformer balance is maintained. Also, the losses in the transformer and the main switches have positive temperature coefficients eliminating the potential for thermal runaway. The LT3439 can compensate for small circuit imbalances, however care should be taken to balance both sides of the circuit including transformer design and PCB layout.

### Transformer Design Example

The following is an example of the design of a DC transformer for a 5V to 5V at 500mA supply.

Supply specs:  $V_{IN} = 5V$ ,  $V_{OUT} = 5V$ ,  $I_{OUT} = 500mA$ ,  
 $f_{OSC} = 100kHz$

Assume:  $V_F = 0.5V$  (forward voltage of output diode)  
Efficiency  $\approx 70\%$

Calculate the primary switch current ( $I_{PRI}$ ):

$$I_{PRI} = \frac{V_{OUT} \cdot I_{OUT}}{V_{IN} \text{ Eff}} = \frac{5V \cdot 500mA}{5V \cdot 70\%} = 0.714A$$

The "Switch Voltage Drop vs Switch Current" Typical Performance curve gives a typical value of the switch voltage drop ( $V_{SW}$ ) for a given switch current ( $I_{PRI}$ ). In this example,  $I_{PRI} \approx 0.7A$ , therefore  $V_{SW} \approx 0.5V$ .

Next, calculate the turns ratio:

$$\frac{N_S}{N_P} = \frac{V_{OUT} + V_F}{V_{IN} - V_{SW}} = \frac{5V + 0.5V}{5V - 0.5V} = 1.22$$

Add 15% margin to account for winding resistance of the transformer:

$$\frac{N_S}{N_P} = 1.22 + 15\% = 1.41$$

## APPLICATIONS INFORMATION

The primary inductance is then calculated:

$$L_{PRI} = V_{IN} \frac{1}{\Delta I_{PRI} f_{OSC}} = 5 \frac{1}{0.107A \cdot 100kHz} = 467\mu H$$

$$\Delta I = 15\% \text{ of } I_{PRI} = 0.15 \cdot 0.714A = 0.107A$$

Next, build a transformer with the calculated values of turns ratio and primary inductance. Minimize resistance in the windings. The turns ratio can be tweaked to get the specified output voltage.

### Capacitors

The DC transformer topology runs effectively at 100% duty cycle (50% each side). This means that the input supply current is approximately constant. Therefore, large “hold-up type” capacitors are not necessary. A low value (>4.7μF), low ESR ceramic will be adequate to filter high frequency noise at the input.

The output capacitors supply energy to the output load only during switch transitions. Therefore, large capacitance values are not necessary. Low ESR, surface mount capacitors such as ceramic, OS-CON or POSCAPs are recommended. An additional LC filter can be added in addition to the output capacitor to further reduce output noise.

Transformer winding capacitance between the isolated primary and secondary have parasitic currents that can cause noise on the grounds. Providing a high frequency, low impedance path between the primary and secondary gives the parasitic currents a local return path. A 2.2nF, 1kV ceramic capacitor is recommended.

### Switching Diode Selection

A fast recovery, surface mount diode such as a Schottky is recommended. The proximity of the diodes to the transformer outputs is important and should be as close as possible with short, wide traces connecting them.

### Optional LC Filter

An optional LC filter, as shown on the Typical Application on the first page of this data sheet, should be included if ultralow noise and ripple are required. It is recommended that the corner frequency of the filter should be set a decade below the switching frequency so that the switch noise is attenuated by a factor of 100. For example, if the  $f_{OSC} = 100kHz$ , then  $f_{CORNER} = 10kHz$  where:

$$f_{CORNER} = \frac{1}{2 \cdot \pi \sqrt{LC}}$$

### Output Voltage Regulation

The output voltage of the DC transformer topology is unregulated. Variations in the input voltage will cause the output voltage to vary because the output voltage is a function of the input voltage and the transformer turn ratio. Also, variations in the output load will cause the output voltage to change because of circuit parasitics, such as the transformer DC resistance and power switch on resistance. If regulation is necessary, a post regulator such as a linear regulator can be added to the output of the supply. See the Typical Applications for examples of adding a linear regulator.

### More Help

AN70: “A Monolithic Switching Regulator with 100μV Output Noise” contains much information concerning applications and noise measurement techniques.

AN19: “LT1070 Design Manual”

AN29: “Some Thoughts on DC-DC Converters” also have general knowledge on switching regulators.

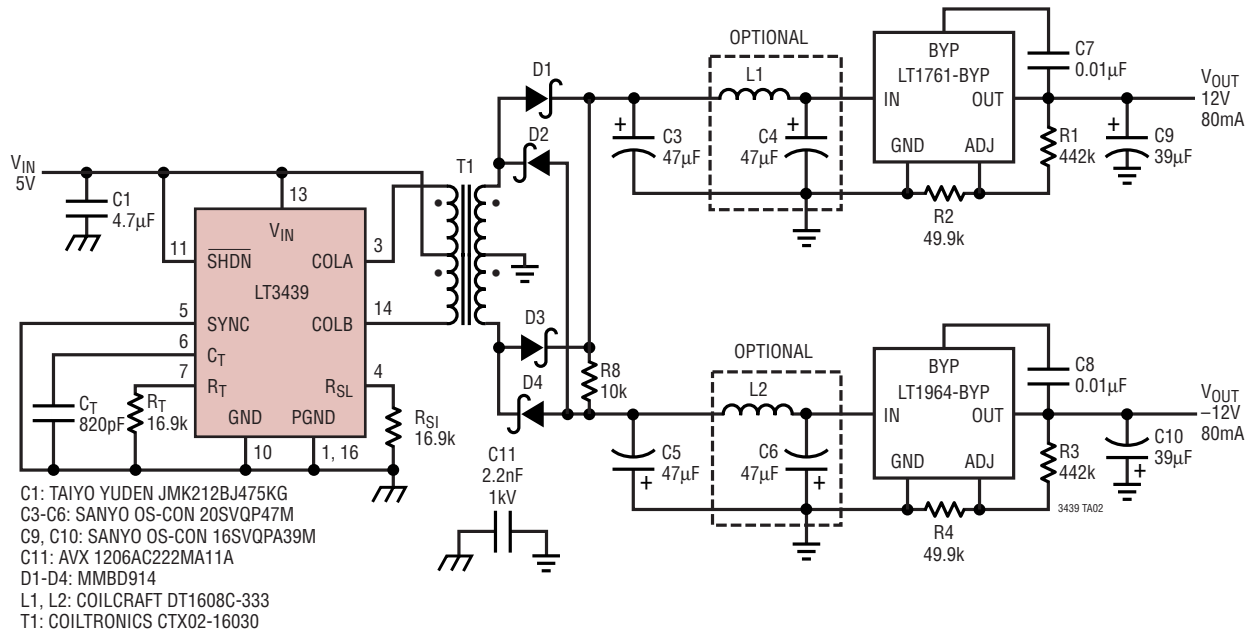
An LTC SwitcherCAD™ model is available to verify design performance.

The LTC Applications department is always ready to lend a helping hand.

SwitcherCAD is a trademark of Linear Technology Corporation.

# TYPICAL APPLICATION

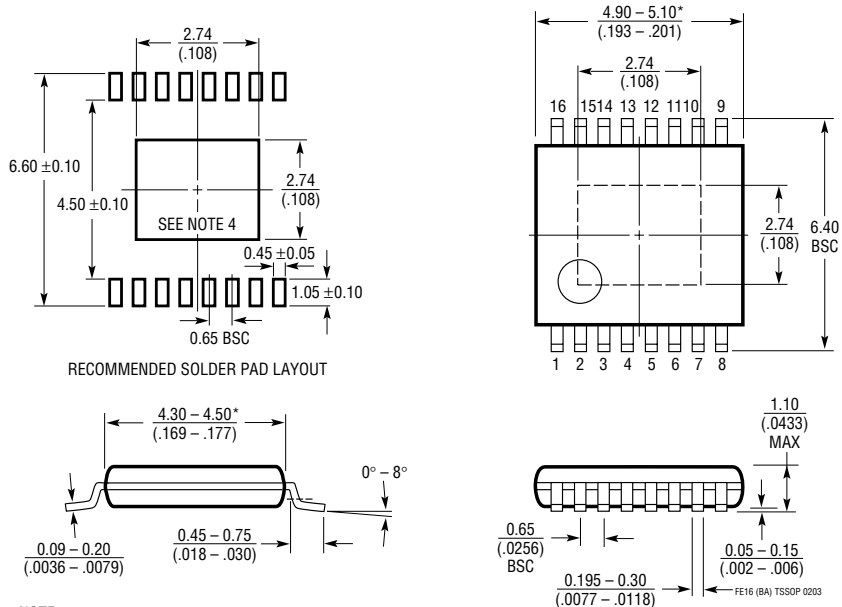
## Low Noise 5V to ±12V Push-Pull DC Transformer



# PACKAGE DESCRIPTION

**FE Package**  
**16-Lead Plastic TSSOP (4.4mm)**  
 (Reference LTC DWG # 05-08-1663)

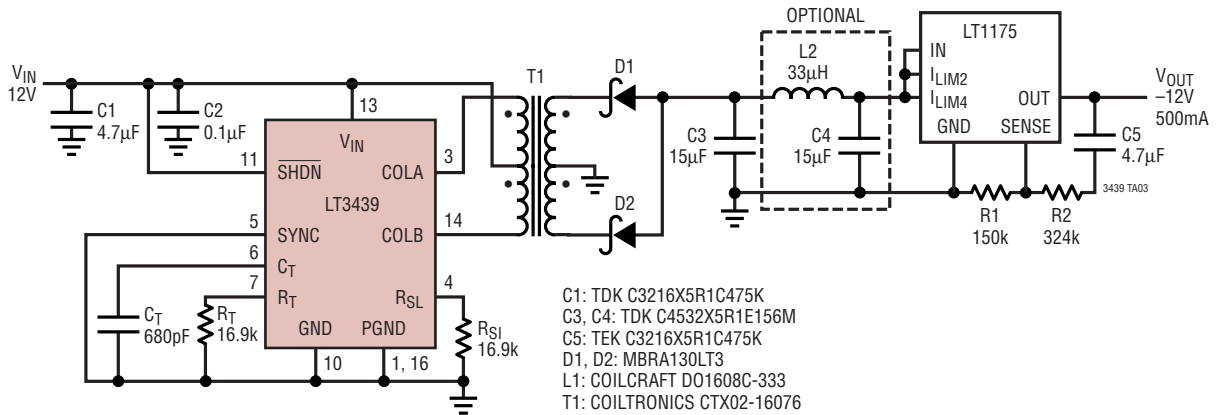
**Exposed Pad Variation BA**



- NOTE:
1. CONTROLLING DIMENSION: MILLIMETERS
  2. DIMENSIONS ARE IN  $\frac{\text{MILLIMETERS}}{\text{INCHES}}$
  3. DRAWING NOT TO SCALE
  4. RECOMMENDED MINIMUM PCB METAL SIZE FOR EXPOSED PAD ATTACHMENT
- \*DIMENSIONS DO NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.150mm (.006") PER SIDE

**TYPICAL APPLICATION**

**Low Noise 12V to -12V, 6W Push-Pull DC Transformer**



**RELATED PARTS**

PART NUMBER	DESCRIPTION	COMMENTS
LT1533	Slew Rate Controlled Ultralow Noise 1A Switching Regulator	$V_{IN}$ : 2.7V to 23V, $I_Q$ (Supply): 12mA, $I_{SD}$ : <12µA, SO-16, Low Noise: <100µV <sub>p-p</sub> , Independent Control of Switch Voltage and Current Slew Rates
LT1534/LT1534-1	Slew Rate Controlled Ultralow Noise 2A Switching Regulators	$V_{IN}$ : 2.7V to 23V, $I_Q$ (Supply): 12mA, $I_{SD}$ : <12µA, SO-16, Low Noise: <2mV <sub>p-p</sub> , Independent Control of Switch Voltage and Current Slew Rates
LT1683	Slew Rate Controlled Ultralow Noise Push-Pull Controller	$V_{IN}$ : 2.7V to 20V, $I_Q$ (Supply): 25mA, $I_{SD}$ : <24µA, SSOP-20, Low Noise: <200µV <sub>p-p</sub> , Independent Control of Switch Voltage and Current Slew Rates
LT1738	Slew Rate Controlled Ultralow Noise DC/DC Controller	$V_{IN}$ : 2.7V to 20V, $I_Q$ (Supply): 12mA, $I_{SD}$ : <24µA, SSOP-20, Greatly Reduced Conducted and Radiated EMI, Independent Control of Switch Voltage and Current Slew Rates
LT1763	500mA, Low Noise Micropower, LDO	$V_{IN}$ : 1.8V to 20V, $V_{OUT(MIN)}$ : 1.22V, Dropout Voltage (V at $I_{OUT}$ ): 0.30V, $I_Q$ (Supply): 30µA, $V_{OUT}$ : 1.5V, 1.8V, 2.5V, 3V, 3.3V, 5V, $I_{SD}$ : <1µA, SO-8, Low Noise: <20µV <sub>RMSP-P</sub>
LT1764/LT1764A	3A, Low Noise, Fast Transient Response, LDOs	$V_{IN}$ : 2.7V to 20V, $V_{OUT(MIN)}$ : 1.21V, Dropout Voltage (V at $I_{OUT}$ ): 0.34V, $I_Q$ (Supply): 1mA, $V_{OUT}$ : 1.8V, 2.5V, 3.3V, $I_{SD}$ : <1µA, DD, TO220-5, Low Noise: <40µV <sub>RMSP-P</sub> , "A" Version Stable with Ceramic Capacitors
LT1962	300mA, Low Noise Micropower, LDO	$V_{IN}$ : 1.8V to 20V, $V_{OUT(MIN)}$ : 1.22V, Dropout Voltage (V at $I_{OUT}$ ): 0.27V, $I_Q$ (Supply): 30µA, $V_{OUT}$ : 1.5V, 1.8V, 2.5V, 3V, 3.3V, 5V, $I_{SD}$ : <1µA, MS8, Low Noise: <20µV <sub>RMSP-P</sub>
LT1963/LT1963A	1.5A, Low Noise, Fast Transient Response, LDOs	$V_{IN}$ : 2.1V to 20V, $V_{OUT(MIN)}$ : 1.21V, Dropout Voltage (V at $I_{OUT}$ ): 0.34V, $I_Q$ (Supply): 1mA, $V_{OUT}$ : 1.5V, 1.8V, 2.5V, 3.3V, $I_{SD}$ : <1µA, DD, TO220-5, SOT-223, SO-8, Low Noise: <40µV <sub>RMSP-P</sub> , "A" Version Stable with Ceramic Capacitors
LT1964	200mA, Low Noise Micropower, Negative LDO	$V_{IN}$ : -0.9V to -20V, $V_{OUT(MIN)}$ : -1.21V, Dropout Voltage (V at $I_{OUT}$ ): 0.34V, $I_Q$ (Supply): 30µA, $V_{OUT}$ : Adj, -5V, $I_{SD}$ : <3µA, ThinSOT™, Low Noise: <30µV <sub>RMSP-P</sub> , Stable with Ceramic Capacitors

ThinSOT is a trademark of Linear Technology Corporation.