## FXLA102

# Low Voltage Dual Supply 2-Bit Voltage Translator with Configurable Voltage Supplies and Signal Levels, 3-State Outputs, and Auto Direction Sensing 

## Features

■ Bi-directional interface between two levels from 1.1V to 3.6 V .
■ Fully configurable: Inputs and outputs track $\mathrm{V}_{\mathrm{CC}}$ level.
■ Non-preferential power-up; either $\mathrm{V}_{\mathrm{CC}}$ may be powered-up first.
■ Outputs remain in 3-state until active $\mathrm{V}_{\mathrm{CC}}$ level is reached.
■ Outputs switch to 3 -state if either $\mathrm{V}_{\mathrm{CC}}$ is at GND.

- Power off protection

■ Bushold on data inputs eliminates the need for pull-up or pull-down resistors

- Control input ( $\overline{\mathrm{OE}}$ ) is referenced to $\mathrm{V}_{\mathrm{CCA}}$ voltage.

■ Packaged in 8-terminal leadless MicroPak (1.6mm x 1.6 mm )

- Direction control not needed.
- 100 Mbps throughput when translating between 1.8 V and 2.5 V .
■ ESD protection exceeds:
- 15kV HBM (B port I/O to GND)
(per JESD22-A114 \& Mil Std 883e 3015.7)
- 8kV HBM (A port I/O to GND)
(per JESD22-A114 \& Mil Std 883e 3015.7)
- 2kV CDM (per ESD STM 5.3)


## General Description

The FXLA102 is a configurable dual-voltage-supply translator designed for both uni-directional and bidirectional voltage translation between two logic levels. The device allows translation between voltages as high as 3.6 V to as low as 1.1 V . The A port tracks the $\mathrm{V}_{\mathrm{CCA}}$ level, and the $B$ port tracks the $\mathrm{V}_{\mathrm{CCB}}$ level. This allows for bi-directional voltage translation over a variety of voltage levels: $1.2 \mathrm{~V}, 1.5 \mathrm{~V}, 1.8 \mathrm{~V}, 2.5 \mathrm{~V}$ and 3.3 V .

The device remains in 3-state until both VCCs reach active levels, allowing either $\mathrm{V}_{\mathrm{CC}}$ to be powered-up first. Internal power down control circuits place the device in 3-state if either $\mathrm{V}_{\mathrm{CC}}$ is removed.
The $\overline{O E}$ input, when high, disables both the $A$ and $B$ ports by placing them in a 3-state condition. The $\overline{\mathrm{OE}}$ input is supplied by $\mathrm{V}_{\text {CCA }}$.
The FXLA102 supports bi-directional translation without the need for a direction control pin. The two ports of the device have auto-direction sense capability. Either port may sense an input signal and transfer it as an output signal to the other port.

## Ordering Information

| Order <br> Number | Package <br> Number | Product Code <br> Top Mark | Package Description | Supplied As |
| :---: | :---: | :---: | :---: | :---: |
| FXLA102L8X | MAC08A | XF | 8-Lead MicroPak, 1.6mm Wide | 3k Units on Tape and Reel |

All packages are lead free per JEDEC: J-STD-020B standard.

## Connection Diagram


(Top Thru View)

## Pin Description

| Number | Name | Description |
| :---: | :---: | :--- |
| 1 | $\mathrm{~V}_{\mathrm{CCA}}$ | A Side Power Supply |
| 2,3 | $\mathrm{~A}_{0}, \mathrm{~A}_{1}$ | A Side Inputs or 3-State <br> Outputs |
| 4 | GND |  |
| 5 | $\overline{\mathrm{OE}}$ | Output Enable Input |
| 6,7 | $\mathrm{~B}_{1}, \mathrm{~B}_{0}$ | A Side Inputs or 3-State <br> Outputs |
| 8 | $\mathrm{~V}_{\mathrm{CCB}}$ | B Side Power Supply |

Functional Diagram


Function Table

| Control | Outputs |
| :---: | :--- |
| $\overline{\mathbf{O E}}$ | Normal Operation |
| L | 3-State |
| H |  |

H = HIGH Logic Level
L = LOW Logic Level

## Power-Up/Power-Down Sequencing

FXL translators offer an advantage in that either $\mathrm{V}_{\mathrm{CC}}$ may be powered up first. This benefit derives from the chip design. When either $\mathrm{V}_{\mathrm{CC}}$ is at 0 volts, outputs are in a high-impedance state. The control input ( $\overline{\mathrm{OE}})$ is designed to track the $\mathrm{V}_{\text {CCA }}$ supply. A pull-up resistor tying $\overline{\mathrm{OE}}$ to $\mathrm{V}_{\mathrm{CCA}}$ should be used to ensure that bus contention, excessive currents, or oscillations do not occur during power-up/power-down. The size of the pull-up resistor is based upon the current-sinking capability of the device driving the $\overline{\mathrm{OE}}$ pin.

The recommended power-up sequence is the following:

1. Apply power to the first $\mathrm{V}_{\mathrm{CC}}$.
2. Apply power to the second $\mathrm{V}_{\mathrm{CC}}$.
3. Drive the $\overline{\mathrm{OE}}$ input LOW to enable the device.

The recommended power-down sequence is the following:

1. Drive $\overline{\mathrm{OE}}$ input HIGH to disable the device.
2. Remove power from either $\mathrm{V}_{\mathrm{CC}}$.
3. Remove power from other $\mathrm{V}_{\mathrm{CC}}$.

## Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol | Parameter | Rating |
| :---: | :---: | :---: |
| $\mathrm{V}_{\text {CCA }}, \mathrm{V}_{\text {CCB }}$ | Supply Voltage | -0.5 V to +4.6 V |
| $V_{1}$ | DC Input Voltage <br> I/O Port A <br> I/O Port B <br> Control Input ( $\overline{\mathrm{OE}}$ ) | $\begin{aligned} & -0.5 \mathrm{~V} \text { to }+4.6 \mathrm{~V} \\ & -0.5 \mathrm{~V} \text { to }+4.6 \mathrm{~V} \\ & -0.5 \mathrm{~V} \text { to }+4.6 \mathrm{~V} \end{aligned}$ |
| $\mathrm{V}_{\mathrm{O}}$ | Output Voltage ${ }^{(2)}$ <br> Outputs 3-STATE <br> Outputs Active $\left(A_{n}\right)$ <br> Outputs Active ( $\mathrm{B}_{\mathrm{n}}$ ) | $\begin{array}{r} -0.5 \mathrm{~V} \text { to }+4.6 \mathrm{~V} \\ -0.5 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{CCA}}+0.5 \mathrm{~V} \\ -0.5 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{CCB}}+0.5 \mathrm{~V} \end{array}$ |
| $\mathrm{I}_{\mathrm{IK}}$ | DC Input Diode Current @ $\mathrm{V}_{1}<0 \mathrm{~V}$ | $-50 \mathrm{~mA}$ |
| $\mathrm{I}_{\mathrm{OK}}$ | DC Output Diode Current @ $\begin{aligned} & \mathrm{V}_{\mathrm{O}}<0 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{O}}>\mathrm{V}_{\mathrm{CC}} \end{aligned}$ | $\begin{aligned} & -50 \mathrm{~mA} \\ & +50 \mathrm{~mA} \end{aligned}$ |
| $\mathrm{IOH} / \mathrm{OL}$ | DC Output Source/Sink Current | $-50 \mathrm{~mA} /+50 \mathrm{~mA}$ |
| $\mathrm{I}_{\mathrm{CC}}$ | DC $\mathrm{V}_{\text {CC }}$ or Ground Current per Supply Pin | $\pm 100 \mathrm{~mA}$ |
| $\mathrm{T}_{\text {STG }}$ | Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |

## Note:

1. $\mathrm{I}_{\mathrm{O}}$ Absolute Maximum Rating must be observed.

## Recommended Operating Conditions ${ }^{(2)}$

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to absolute maximum ratings.

| Symbol | Parameter | Rating |
| :---: | :--- | ---: |
| $\mathrm{V}_{\mathrm{CCA}}$ or $\mathrm{V}_{\mathrm{CCB}}$ | Power Supply Operating | 1.1 V to 3.6 V |
| $\mathrm{~V}_{\mathrm{I}}$ | Input Voltage |  |
|  | I/O Port A | 0.0 V to 3.6 V |
|  | I/O Port B | 0.0 V to 3.6 V |
|  | Control Inputs $(\overline{\mathrm{OE}})$ | 0.0 V to $\mathrm{V}_{\mathrm{CCA}}$ |
|  | Dynamic Output Current $\mathrm{I}_{\mathrm{OH}} / \mathrm{I}_{\mathrm{OL}}$ with $\mathrm{V}_{\mathrm{CC}} @$ |  |
|  | 3.0 V to 3.6 V | $\pm 12.0 \mathrm{~mA}$ |
|  | 2.3 V to 2.7 V | $\pm 8.0 \mathrm{~mA}$ |
|  | 1.65 V to 1.95 V | $\pm 5.0 \mathrm{~mA}$ |
|  | 1.4 V to 1.65 V | $\pm 3.0 \mathrm{~mA}$ |
|  | 1.1 V to 1.4 V | $\pm 2.0 \mathrm{~mA}$ |
|  | Static Output Current $\mathrm{I}_{\mathrm{OH}} / \mathrm{I}_{\mathrm{OL}}$ with $\mathrm{V}_{\mathrm{CC}} @ 1.1 \mathrm{~V}$ to 3.6 V | $\pm 4.0 \mu \mathrm{~A}$ |
|  | Free Air Operating Temperature | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{A}}$ | Maximum Input Edge Rate $\mathrm{V}_{\mathrm{CCA} / \mathrm{B}}=1.1 \mathrm{~V}$ to 3.6 V | $10 \mathrm{~ns} / \mathrm{V}$ |
| $\Delta \mathrm{t} / \Delta \mathrm{V}$ |  |  |

## Note:

2. All unused inputs and $\mathrm{I} / \mathrm{O}$ pins must be held at $\mathrm{V}_{\mathrm{CCI}}$ or GND .

DC Electrical Characteristics ( $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

| Symbol | Parameter | $\mathrm{V}_{\text {CCA }}(\mathrm{V})$ | $\mathrm{V}_{\text {ccB }}(\mathrm{V})$ | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IHA }}$ | High Level Input Voltage | 2.7-3.6 | 1.1-3.6 | Data inputs An, Control Input OE | 2.0 |  |  | V |
|  |  | 2.3-2.7 |  |  | 1.6 |  |  |  |
|  |  | 1.65-2.3 |  |  | $0.65 \times \mathrm{V}_{\text {CCA }}$ |  |  |  |
|  |  | 1.4-1.65 |  |  | $0.65 \times \mathrm{V}_{\text {CCA }}$ |  |  |  |
|  |  | 1.1-1.4 |  |  | $0.9 \times \mathrm{V}_{\text {CCA }}$ |  |  |  |
| $\mathrm{V}_{\mathrm{IHB}}$ |  | 1.1-3.6 | 2.7-3.6 | Data Inputs Bn | 2.0 |  |  | V |
|  |  |  | 2.3-2.7 |  | 1.6 |  |  |  |
|  |  |  | 1.65-2.3 |  | $0.65 \times \mathrm{V}_{\text {CCB }}$ |  |  |  |
|  |  |  | 1.4-1.65 |  | $0.65 \times \mathrm{V}_{\text {CCB }}$ |  |  |  |
|  |  |  | 1.1-1.4 |  | $0.9 \times \mathrm{V}_{\text {CCB }}$ |  |  |  |
| $\mathrm{V}_{\text {ILA }}$ | Low Level Input Voltage | 2.7-3.6 | 1.1-3.6 | Data Inputs An, Control Input $\overline{\mathrm{OE}}$ |  |  | 0.8 | V |
|  |  | 2.3-2.7 |  |  |  |  | 0.7 |  |
|  |  | 1.65-2.3 |  |  |  |  | $0.35 \times \mathrm{V}_{\text {CCA }}$ |  |
|  |  | 1.4-1.65 |  |  |  |  | $0.35 \times V_{\text {CCA }}$ |  |
|  |  | 1.1-1.4 |  |  |  |  | $0.1 \times \mathrm{V}_{\text {CCA }}$ |  |
| $\mathrm{V}_{\text {ILB }}$ |  | 1.1-3.6 | 2.7-3.6 | Data Inputs Bn |  |  | 0.8 | V |
|  |  |  | 2.3-2.7 |  |  |  | 0.7 |  |
|  |  |  | 1.65-2.3 |  |  |  | $0.35 \times \mathrm{V}_{\text {CCB }}$ |  |
|  |  |  | 1.4-1.65 |  |  |  | $0.35 \times V_{\text {CCB }}$ |  |
|  |  |  | 1.1-1.4 |  |  |  | $0.1 \times \mathrm{V}_{\text {CCB }}$ |  |
| $\mathrm{V}_{\text {OHA }}{ }^{(3)}$ | High Level Output Voltage | 1.1-3.6 | 1.1-3.6 | $\mathrm{I}_{\mathrm{OH}}=-4 \mu \mathrm{~A}$ | $\mathrm{V}_{\text {CCA }}-0.4$ |  |  | V |
| $\mathrm{V}_{\mathrm{OHB}}{ }^{(3)}$ |  | 1.1-3.6 | 1.1-3.6 | $\mathrm{I}_{\mathrm{OH}}=-4 \mu \mathrm{~A}$ | $\mathrm{V}_{\text {CCB }}-0.4$ |  |  | V |
| $\mathrm{V}_{\text {OLA }}{ }^{(3)}$ | Low Level Output Voltage | 1.1-3.6 | 1.1-3.6 | $\mathrm{I}_{\mathrm{OL}}=4 \mu \mathrm{~A}$ |  |  | 0.4 | V |
| $\mathrm{V}_{\text {OLB }}{ }^{(3)}$ |  | 1.1-3.6 | 1.1-3.6 | $\mathrm{I}_{\mathrm{OL}}=4 \mu \mathrm{~A}$ |  |  | 0.4 | V |
| $I_{\text {(HOLD })}$ | Bushold Input Minimum Drive Current | 3.0 | 3.0 | $\mathrm{V}_{\text {IN }}=0.8 \mathrm{~V}$ | 75.0 |  |  | $\mu \mathrm{A}$ |
|  |  | 3.0 | 3.0 | $\mathrm{V}_{\text {IN }}=2.0 \mathrm{~V}$ | -75.0 |  |  |  |
|  |  | 2.3 | 2.3 | $\mathrm{V}_{\text {IN }}=0.7 \mathrm{~V}$ | 45.0 |  |  |  |
|  |  | 2.3 | 2.3 | $\mathrm{V}_{\text {IN }}=1.6 \mathrm{~V}$ | -45.0 |  |  |  |
|  |  | 1.65 | 1.65 | $\mathrm{V}_{\mathrm{IN}}=0.57 \mathrm{~V}$ | 25.0 |  |  |  |
|  |  | 1.65 | 1.65 | $\mathrm{V}_{\text {IN }}=1.07 \mathrm{~V}$ | -25.0 |  |  |  |
|  |  | 1.4 | 1.4 | $\mathrm{V}_{\text {IN }}=0.49 \mathrm{~V}$ | 11.0 |  |  |  |
|  |  | 1.4 | 1.4 | $\mathrm{V}_{\text {IN }}=0.91 \mathrm{~V}$ | -11.0 |  |  |  |
|  |  | 1.1 | 1.1 | $\mathrm{V}_{\text {IN }}=0.11 \mathrm{~V}$ |  | 4 |  |  |
|  |  | 1.1 | 1.1 | $\mathrm{V}_{\text {IN }}=0.99 \mathrm{~V}$ |  | -4 |  |  |
| $\mathrm{I}_{\text {(ODH) }}{ }^{(4)}$ | Bushold Input Overdrive High Current | 3.6 | 3.6 | Data Inputs $A_{n}, B_{n}$ | 450 |  |  | $\mu \mathrm{A}$ |
|  |  | 2.7 | 2.7 |  | 300 |  |  |  |
|  |  | 1.95 | 1.95 |  | 200 |  |  |  |
|  |  | 1.6 | 1.6 |  | 120 |  |  |  |
|  |  | 1.4 | 1.4 |  | 80 |  |  |  |
| $\mathrm{I}_{(\text {ODL })^{(5)}}$ | Bushold Input Overdrive Low Current | 3.6 | 3.6 | Data Inputs $A_{n}, B_{n}$ | -450 |  |  | $\mu \mathrm{A}$ |
|  |  | 2.7 | 2.7 |  | -300 |  |  |  |
|  |  | 1.95 | 1.95 |  | -200 |  |  |  |
|  |  | 1.6 | 1.6 |  | -120 |  |  |  |
|  |  | 1.4 | 1.4 |  | -80 |  |  |  |

DC Electrical Characteristics $\left(\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}\right.$ to $+85^{\circ} \mathrm{C}$ ) (Continued)

| Symbol | Parameter | $\mathrm{V}_{\text {CCA }}(\mathrm{V})$ | $\mathrm{V}_{\text {CCB }}(\mathrm{V})$ | Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Input Leakage Current | 1.1-3.6 | 3.6 | Control input $\overline{\mathrm{OE}}$, $\mathrm{V}_{1}=\mathrm{V}_{\mathrm{CCA}}$ or GND |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {OFF }}$ | Power Off Leakage Current | 0 | 3.6 | $\mathrm{A}_{\mathrm{n}}$ Port, $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ to 3.6 V |  |  | $\pm 2.0$ | $\mu \mathrm{A}$ |
|  |  | 3.6 | 0 | $\mathrm{B}_{\mathrm{n}}$ Port, $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ to 3.6 V |  |  | $\pm 2.0$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{OZ}}$ | 3-State Output Leakage | 3.6 | 3.6 | $\begin{aligned} & \text { Data Outputs } A_{n}, B_{n} \\ & V_{\mathrm{O}}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V} \text {, } \\ & \mathrm{OE}=\mathrm{V}_{\mathrm{IH}} \end{aligned}$ |  |  | $\pm 5.0$ | $\mu \mathrm{A}$ |
|  |  | 3.6 | 0 | $\begin{aligned} & \text { Data outputs } \mathrm{A}_{n}, \\ & \mathrm{~V}_{\mathrm{O}}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V}, \\ & \mathrm{OE}=\mathrm{GND} \end{aligned}$ |  |  | $\pm 5.0$ | $\mu \mathrm{A}$ |
|  |  | 0 | 3.6 | $\begin{aligned} & \text { Data outputs } \mathrm{B}_{\mathrm{n}} \\ & \mathrm{~V}_{\mathrm{O}}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V} \text {, } \\ & \mathrm{OE}=\mathrm{GND} \end{aligned}$ |  |  | $\pm 5.0$ | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {CCAB }}{ }^{(6)(7)}$ | Quiescent Supply Current | 1.1-3.6 | 1.1-3.6 | $\begin{aligned} & \mathrm{V}_{1}=\mathrm{V}_{\mathrm{CCI}} \text { or } \mathrm{GND}, \\ & \mathrm{I}_{\mathrm{O}}=0, \overline{O E}=\mathrm{GND} \end{aligned}$ |  |  | 10.0 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{Ccz}}{ }^{(6)(7)}$ | Quiescent Supply Current | 1.1-3.6 | 1.1-3.6 | $\begin{aligned} & \mathrm{V}_{\mathrm{I}}=\mathrm{VC}_{\mathrm{CI}} \text { or } \mathrm{GND}, \\ & \mathrm{I}_{\mathrm{O}}=0, \overline{\mathrm{OE}}=\mathrm{V}_{\mathrm{IH}}, \end{aligned}$ |  |  | 10.0 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {CCA }}$ | Quiescent Supply Current | 0 | 1.1-3.6 | $\begin{aligned} & \mathrm{V}_{1}=\mathrm{V}_{\mathrm{CCB}} \text { or } \mathrm{GND}, \\ & \mathrm{IO}_{\mathrm{O}}=0, \mathrm{~B} \text {-to-A Direction, } \\ & \mathrm{OE}=\mathrm{GND} \end{aligned}$ |  |  | -10.0 | $\mu \mathrm{A}$ |
|  |  | 1.1-3.6 | 0 |  |  |  | 10.0 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {CCB }}$ | Quiescent Supply Current | 1.1-3.6 | 0 | $\begin{aligned} & \mathrm{V}_{1}=\mathrm{V}_{\mathrm{CCA}} \text { or } \mathrm{GND}, \\ & \mathrm{IO}_{0}=0, \mathrm{~A} \text {-to-B Direction, } \\ & \hline \mathrm{OE}=\mathrm{GND} \end{aligned}$ |  |  | -10.0 | $\mu \mathrm{A}$ |
|  |  | 0 | 1.1-3.6 |  |  |  | 10.0 | $\mu \mathrm{A}$ |

## Notes:

3. This is the output voltage for static conditions. Dynamic drive specifications are given in "Dynamic Output Electrical Characteristics."
4. An external driver must source at least the specified current to switch LOW-to-HIGH.
5. An external driver must source at least the specified current to switch HIGH-to-LOW.
6. $\mathrm{V}_{\mathrm{CCI}}$ is the $\mathrm{V}_{\mathrm{CC}}$ associated with the input side.
7. Reflects current per supply, $\mathrm{V}_{\mathrm{CCA}}$ or $\mathrm{V}_{\mathrm{CCB}}$.

Dynamic Output Electrical Characteristics ${ }^{(8)}$
A Port (An)
Output Load: $C_{L}=15 p F, R_{L} \geq 1 \mathrm{M} \Omega\left(C_{/ / O}=4 p F\right)$

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\text {CCA }}=$ |  |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0 V to 3.6V |  | 2.3V to 2.7V |  | 1.65 V to 1.95 V |  | 1.4V to 1.6V |  | 1.1V to 1.3V |  |
|  |  | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. |  |
| $\mathrm{t}_{\text {rise }}{ }^{(9)}$ | Output Rise Time A port |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| $\mathrm{t}_{\text {fall }}{ }^{(10)}$ | Output Fall Time A port |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| $\mathrm{IOHD}^{(9)}$ | Dynamic Output Current High | -11.4 |  | -7.5 |  | -4.7 |  | -3.2 |  | -1.7 | mA |
| $\mathrm{I}_{\text {OLD }}{ }^{(10)}$ | Dynamic Output Current Low | +11.4 |  | +7.5 |  | +4.7 |  | +3.2 |  | +1.7 | mA |

B Port (Bn)
Output Load: $C_{L}=15 p F, R_{L} \geq 1 \mathrm{M} \Omega\left(C_{/ / O}=5 p F\right)$

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\text {CCB }}=$ |  |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0 V to 3.6V |  | 2.3V to 2.7V |  | 1.65 V to 1.95 V |  | 1.4 V to 1.6V |  | 1.1V to 1.3 V |  |
|  |  | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. | Max. | Typ. |  |
| $\mathrm{t}_{\text {rise }}{ }^{(9)}$ | Output Rise Time B port |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| $\mathrm{t}_{\text {fall }}{ }^{(10)}$ | Output Fall Time B port |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| $\mathrm{lOHD}^{(9)}$ | Dynamic Output Current High | -12.0 |  | -7.9 |  | -5.0 |  | -3.4 |  | -1.8 | mA |
| $\mathrm{I}_{\text {OLD }}{ }^{(10)}$ | Dynamic Output Current Low | +12.0 |  | +7.9 |  | +5.0 |  | +3.4 |  | +1.8 | mA |

## Notes:

8. Dynamic Output Characteristics are guaranteed but not tested.
9. See Figure 5.
10. See Figure 6.

AC Characteristics
$\mathrm{V}_{\mathrm{CCA}}=3.0 \mathrm{~V}$ to 3.6 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0V-3.6V |  | 2.3V-2.7V |  | 1.65V-1.95V |  | 1.4V-1.6V |  | $\frac{1.1 \mathrm{~V}-1.3 \mathrm{~V}}{\text { Typ. }}$ |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |  |
| $\mathrm{t}_{\text {PLH }}, \mathrm{t}_{\text {PHL }}$ | A to B | 0.2 | 3.5 | 0.3 | 3.9 | 0.5 | 5.4 | 0.6 | 6.8 | 10.0 | ns |
|  | B to A | 0.2 | 3.5 | 0.2 | 3.8 | 0.3 | 5.0 | 0.5 | 6.0 | 7.0 | ns |
| $\mathrm{t}_{\text {PZL }}, \mathrm{t}_{\text {PZ }}$ | $\overline{O E}$ to $A, \overline{O E}$ to $B$ |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {skew }}{ }^{(11)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 1.0 | 1.0 | ns |

$\mathrm{V}_{\mathrm{CCA}}=2.3 \mathrm{~V}$ to 2.7 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0V-3.6V |  | 2.3V-2.7V |  | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ |  | 1.4V-1.6V |  | $\frac{1.1 \mathrm{~V}-1.3 \mathrm{~V}}{\text { Typ. }}$ |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |  |
| $\mathrm{t}_{\text {PLH }}, \mathrm{t}_{\text {PHL }}$ | A to B | 0.2 | 3.8 | 0.4 | 4.2 | 0.5 | 5.6 | 0.8 | 6.9 | 10.5 | ns |
|  | $B$ to $A$ | 0.3 | 3.9 | 0.4 | 4.2 | 0.5 | 5.5 | 0.5 | 6.5 | 7.0 | ns |
| $\mathrm{t}_{\text {PZL }}, \mathrm{t}_{\text {PZ }}$ | $\overline{O E}$ to $A, \overline{O E}$ to $B$ |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {skew }}{ }^{(11)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 1.0 | 1.0 | ns |


| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0V-3.6V |  | 2.3V-2.7V |  | 1.65V-1.95V |  | 1.4V-1.6V |  | $\begin{gathered} \hline \text { 1.1V-1.3V } \\ \hline \text { Typ. } \end{gathered}$ |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. |  |  |
| $\mathrm{t}_{\text {PLH, }}$ t PHL | A to B | 0.3 | 5.0 | 0.5 | 5.5 | 0.8 | 6.7 | 0.9 | 7.5 | 11.0 | ns |
|  | B to A | 0.5 | 5.4 | 0.5 | 5.6 | 0.8 | 6.7 | 1.0 | 7.0 | 7.0 | ns |
| tpzL, t ${ }_{\text {PzH }}$ | $\overline{\mathrm{OE}}$ to $\mathrm{A}, \overline{\mathrm{OE}}$ to B |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | us |
| $\mathrm{t}_{\text {skew }}{ }^{(11)}$ | A Port, B Port |  | 0.5 |  | 0.5 |  | 0.5 |  | 1.0 | 1.0 | ns |

$\mathrm{V}_{\mathrm{CCA}}=1.4 \mathrm{~V}$ to 1.6 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0V-3.6V |  | 2.3V-2.7V |  | $1.65 \mathrm{~V}-1.95 \mathrm{~V}$ |  | 1.4V-1.6V |  | 1.1V-1.3V |  |
|  |  | Min. | Max. | Min. | Max. | Min. | Max. | Min. | Max. | Typ. |  |
| $\mathrm{t}_{\text {PLH }}, \mathrm{t}_{\text {PHL }}$ | A to B | 0.5 | 6.0 | 0.5 | 6.5 | 1.0 | 7.0 | 1.0 | 8.5 | 11.5 | ns |
|  | B to A | 0.6 | 6.8 | 0.8 | 6.9 | 0.9 | 7.5 | 1.0 | 8.5 | 9.0 | ns |
| $\mathrm{t}_{\text {PZL }}, \mathrm{t}_{\text {PZH }}$ | $\overline{\mathrm{OE}}$ to $\mathrm{A}, \overline{\mathrm{OE}}$ to B |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {skew }}{ }^{(11)}$ | A Port, B Port |  | 1.0 |  | 1.0 |  | 1.0 |  | 1.0 | 1.0 | ns |

## Note:

11. Skew is the variation of propagation delay between output signals and applies only to output signals on the same port (An, or Bn) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW). Skew is guaranteed but not tested. See Figure 8.

AC Characteristics (Continued)
$\mathrm{V}_{\mathrm{CCA}}=1.1 \mathrm{~V}$ to 1.3 V

| Symbol | Parameter | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 3.0V-3.6V | 2.3V-2.7V | 1.65V-1.95V | 1.4V-1.6V | 1.1V-1.3V |  |
|  |  | Typ. | Typ. | Typ. | Typ. | Typ. |  |
| $\mathrm{t}_{\text {PLH }}, \mathrm{t}_{\text {PHL }}$ | A to B | 7.1 | 6.5 | 7.0 | 7.1 | 13.5 | ns |
|  | B to A | 10.3 | 10.5 | 10.8 | 11.3 | 13.5 | ns |
| $\mathrm{t}_{\text {PZL }}, \mathrm{t}_{\text {PZH }}$ | $\overline{\mathrm{OE}}$ to $\mathrm{A}, \overline{\mathrm{OE}}$ to B | 1.7 | 1.7 | 1.7 | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {skew }}{ }^{(11)}$ | A Port, B Port | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | ns |

## Note:

11. Skew is the variation of propagation delay between output signals and applies only to output signals on the same port (An, or Bn) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW). Skew is guaranteed but not tested. See Figure 8.

## Max Data Rate ${ }^{(12)(13)}$

| $\mathrm{V}_{\text {CCA }}=$ | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CCB}}=$ |  |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{gathered} \hline 3.0 \mathrm{~V} \text { to } 3.6 \mathrm{~V} \\ \hline \text { Min. } \end{gathered}$ | $\begin{array}{\|c\|} \hline 2.3 \mathrm{~V} \text { to } 2.7 \mathrm{~V} \\ \hline \text { Min. } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 1.65 \mathrm{~V} \text { to } 1.95 \mathrm{~V} \\ \hline \text { Min. } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline 1.4 \mathrm{~V} \text { to } 1.6 \mathrm{~V} \\ \hline \text { Min. } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \text { 1.1V to } 1.3 \mathrm{~V} \\ \hline \text { Typ. } \\ \hline \end{array}$ |  |
|  |  |  |  |  |  |  |
| 3.0 V to 3.6 V | 140 | 120 | 100 | 80 | 40 | Mbps |
| 2.3 V to 2.7 V | 120 | 120 | 100 | 80 | 40 | Mbps |
| 1.65 V to 1.95 V | 100 | 100 | 80 | 60 | 40 | Mbps |
| 1.4 V to 1.6 V | 80 | 80 | 60 | 60 | 40 | Mbps |
|  | Typ. | Typ. | Typ. | Typ. | Typ. |  |
| 1.1 V to 1.3 V | 40 | 40 | 40 | 40 | 40 | Mbps |

## Note:

12. Max Data Rate is guaranteed but not tested.
13. Max Data Rate is specified in megabits per second. See Figure 7. It is equivalent to two times the F-toggle frequency, specified in megahertz. For example, 100 Mbps is equivalent to 50 MHz .

## Capacitance

| Symbol | Parameter |  | Conditions | $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Typical |  |
| Cin | Input Capacitance, Control pin ( $\overline{\mathrm{OE}})$ |  |  | $\mathrm{V}_{\mathrm{CCA}}=\mathrm{V}_{\mathrm{CCB}}=\mathrm{GND}$ | 3 | pF |
| Ci/o | Input/Output Capacitance | An | $\begin{aligned} & \mathrm{V}_{\mathrm{CCA}}=\mathrm{V}_{\mathrm{CCB}}=3.3 \mathrm{~V}, \\ & \mathrm{OE}=\mathrm{V}_{\mathrm{CCA}} \end{aligned}$ | 4 | pF |
|  |  | Bn |  | 5 |  |
| Cpd | Power Dissipation Capacitance |  | $\begin{aligned} & V_{C C A}=V_{C C B}=3.3 \mathrm{~V}, \\ & V_{i}=0 V \text { or } V_{C C}, \\ & f=10 \mathrm{MHz} \end{aligned}$ | 25 | pF |




Input $t_{R}=t_{F}=2.0 n s, 10 \%$ to $90 \%$
Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, @ $\mathrm{Vi}=3.0 \mathrm{~V}$ to 3.6 V only
Figure 2. Waveform for Inverting and Non-inverting Functions


Input $t_{R}=t_{F}=2.0$ ns, $10 \%$ to $90 \%$
Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%, @ \mathrm{Vi}=3.0 \mathrm{~V}$ to 3.6 V only
Figure 4. 3-STATE Output High Enable Time for LOW Voltage Logic


Input $t_{R}=t_{F}=2.0 \mathrm{~ns}, 10 \%$ to $90 \%$
Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%, @ \mathrm{Vi}=3.0 \mathrm{~V}$ to 3.6 V only
Figure 3. 3-STATE Output Low Enable Time for LOW Voltage Logic

| Symbol | $\mathbf{V}_{\mathbf{C C}}$ |
| :---: | :---: |
| $\mathrm{Vmi}^{(14)}$ | $\mathrm{V}_{\mathrm{ClI}} / 2$ |
| $\mathrm{Vmo}_{\mathrm{mo}}$ | $\mathrm{V}_{\mathrm{CCO}} / 2$ |
| $\mathrm{~V}_{\mathrm{X}}$ | $0.9 \times \mathrm{V}_{\mathrm{CCO}}$ |
| $\mathrm{V}_{\mathrm{Y}}$ | $0.1 \times \mathrm{V}_{\mathrm{CCO}}$ |

Note:
14. $\mathrm{V}_{\mathrm{CCI}}=\mathrm{V}_{\mathrm{CCA}}$ for control pin $\overline{\mathrm{OE}}$ or $\mathrm{Vmi}=\left(\mathrm{V}_{\mathrm{CCA}} / 2\right)$.


Figure 5. Active Output Rise Time and Dynamic Output Current HIGH


Figure 7. Maximum Data Rate


IOLD $\approx\left(C_{L}+C_{/ / O}\right) \times \frac{\Delta V_{\text {OUT }}}{\Delta t}=\left(C_{L}+C_{/ / O}\right) \times \frac{(80 \%-20 \%) \times V_{C C O}}{t_{\text {FALL }}}$

Figure 6. Active Output Fall Time and Dynamic Output Current LOW

$t_{\text {skew }}=\left(t_{p H L m a x}-t_{\text {pHLmin }}\right)$ or $\left(t_{p L H m a x}-t_{\text {pLHmin }}\right)$
Figure 8. Output Skew Time

Tape and Reel Dimensions

| Package Designator | Tape Section | Number of Cavities | Cavity Status | Cover Tape Status |
| :---: | :---: | :---: | :---: | :---: |
| L8X | Leader (Start End) | 125 (typ.) | Empty | Sealed |
|  | Carrier | 3000 | Filled | Sealed |
|  | Trailer (Hub End) | 75 (typ.) | Empty | Sealed |

Tape Dimensions inches (millimeters)


Reel Dimensions inches (millimeters)


| Tape <br> Size | $\mathbf{A}$ | $\mathbf{B}$ | $\mathbf{C}$ | $\mathbf{D}$ | $\mathbf{N}$ | $\mathbf{W}$ | W1 | W2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

## Physical Dimensions




Recommended Landpattern
(0.15)


DETAIL A
PIN \#1 TERMINAL SCALE: 2X

## BOTTOM VIEW

Notes:

1. PACKAGE CONFORMS TO JEDEC MO-255 VARIATION UAAD
2. DIMENSIONS ARE IN MILLIMETERS
3. DRAWING CONFORMS TO ASME Y.14M-1994
4.PIN 1 FLAG, END OF PACKAGE OFFSET
4. DRAWING FILE NAME: MKT-MAC08AREV4

## MAC08AREV4

Figure 9. 8-Lead MicroPak, 1.6mm Wide
Package drawings are provided as a service to customers considering Fairchild components. Drawings may change in any manner without notice. Please note the revision andlor date on the drawing and contact a Fairchild Semiconductor representative to verify or obtain the most recent revision. Package specifications do not expand the terms of Fairchild's worldwide terms and conditions, specifically the warranty therein, which covers Fairchild products.

Always visit Fairchild Semiconductor's online packaging area for the most recent package drawings: http://www.fairchildsemi.com/packaging/

## FAIRCHILD

SEMICロNロபCTロR＊

## TRADEMARKS

The following includes registered and unregistered trademarks and service marks，owned by Fairchild Semiconductor and／or its global subsidiaries，and is not intended to be an exhaustive list of all such trademarks．

| Build it Now ${ }^{\text {TM }}$ | FPS ${ }^{\text {TM }}$ | PDP SPM ${ }^{\text {TM }}$ | The Power Franchise ${ }^{\text {® }}$ |
| :---: | :---: | :---: | :---: |
| CorePLUS ${ }^{\text {™ }}$ | F－PFS ${ }^{\text {TM }}$ | Power－SPM ${ }^{\text {TM }}$ | the wer |
| CorePOWER ${ }^{\text {™ }}$ | FRFET ${ }^{\text {® }}$ | PowerTrench ${ }^{\text {® }}$ | P wer |
| CROSSVOLT ${ }^{\text {TM }}$ | Global Power Resource ${ }^{\text {SM }}$ | Programmable Active Droop ${ }^{\text {TM }}$ | TinyBoost ${ }^{\text {TM }}$ |
| CTL ${ }^{\text {TM }}$ | Green FPS ${ }^{\text {™ }}$ | QFET ${ }^{\text {® }}$ | TinyBuck ${ }^{\text {TM }}$ |
| Current Transfer Logic ${ }^{\text {TM }}$ | Green FPS ${ }^{\text {™ }}$ e－Series ${ }^{\text {™ }}$ | QS ${ }^{\text {TM }}$ | TinyLogic ${ }^{\circledR}$ |
| EcoSPARK ${ }^{\text {® }}$ | GTO $^{\text {TM }}$ | Quiet Series ${ }^{\text {TM }}$ | $\begin{aligned} & \text { TinyLogic } \\ & \text { TINYOPTOTм } \end{aligned}$ |
| EfficentMax ${ }^{\text {TM }}$ | IntelliMAX ${ }^{\text {TM }}$ | RapidConfigure ${ }^{\text {TM }}$ | TinyPower ${ }^{\text {TM }}$ |
| EZSWITCH ${ }^{\text {TM }}$＊ | ISOPLANAR ${ }^{\text {TM }}$ | Saving our world， 1 mW at a time ${ }^{\text {TM }}$ | $\text { TinyPWM }{ }^{\text {™ }}$ |
| E－7 | MegaBuck ${ }^{\text {TM }}$ | SmartMax ${ }^{\text {TM }}$ SMART START ${ }^{\text {TM }}$ | TinyWire ${ }^{\text {TM }}$ |
| $5^{\circledR}$ | MICROCOUPLER MicroFET | $\mathrm{SMART}^{\text {SPM }}{ }^{\text {® }}$ START ${ }^{\text {TM }}$ | $\mu$ SerDes $^{\text {™ }}$ |
|  | MicroPak ${ }^{\text {TM }}$ | STEALTH ${ }^{\text {TM }}$ | M |
| Fairchild ${ }^{\text {® }}$ | MillerDrive ${ }^{\text {TM }}$ | SuperFET ${ }^{\text {TM }}$ | SerDes ${ }^{\text {－}}$ |
| Fairchild Semiconductor ${ }^{\text {® }}$ | MotionMax ${ }^{\text {Mm }}$ | SuperSOT ${ }^{\text {tm }} 3$ | UHC ${ }^{\text {® }}$ |
| FACT Quiet Series ${ }^{\text {TM }}$ | Motion－SPM ${ }^{\text {M }}$ | SuperSOT ${ }^{\text {TM }}$－6 | Ultra FRFET ${ }^{\text {TM }}$ |
| $\mathrm{FACT}^{\text {® }}$ | OPTOLOGIC ${ }^{\text {® }}$ | SuperSOT ${ }^{\text {TM }}$－ 8 | UniFET ${ }^{\text {m／M }}$ |
| $\mathrm{FAST}^{\text {® }}$ | OPTOPLANAR ${ }^{\circledR}$ | SupreMOS ${ }^{\text {TM }}$ | VCX ${ }^{\text {™ }}$ |
| FastvCore ${ }^{\text {TM }}$＊ | $\underbrace{}_{\text {® }}$ | SyncFET ${ }^{\text {TM }}$ | VisualMax ${ }^{\text {TM }}$ |
| FlashWriter ${ }^{\text {® }}$ | － | 5 SYSTEM ${ }_{\text {GENERAL }}$ |  |

＊EZSWITCH ${ }^{\text {TM }}$ and FlashWriter ${ }^{\circledR}$ are trademarks of System General Corporation，used under license by Fairchild Semiconductor
DISCLAIMER
FAIRCHILD SEMICONDUCTOR RESERVES THE RIGHT TO MAKE CHANGES WITHOUT FURTHER NOTICE TO ANY PRODUCTS HEREIN TO IMPROVE RELIABILITY，FUNCTION，OR DESIGN．FAIRCHILD DOES NOT ASSUME ANY LIABILITY ARISING OUT OF THE APPLICATION OR USE OF ANY PRODUCT OR CIRCUIT DESCRIBED HEREIN；NEITHER DOES IT CONVEY ANY LICENSE UNDER ITS PATENT RIGHTS，NOR THE RIGHTS OF OTHERS．THESE SPECIFICATIONS DO NOT EXPAND THE TERMS OF FAIRCHILD＇S WORLDWIDE TERMS AND CONDITIONS，SPECIFICALLY THE WARRANTY THEREIN， WHICH COVERS THESE PRODUCTS．

LIFE SUPPORT POLICY
FAIRCHILD＇S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF FAIRCHILD SEMICONDUCTOR CORPORATION

As used herein：

1．Life support devices or systems are devices or systems which，（a）are intended for surgical implant into the body or（b）support or sustain life， and（c）whose failure to perform when properly used in accordance with instructions for use provided in the labeling，can be reasonably expected to result in a significant injury of the user．

2．A critical component in any component of a life support，device，or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system，or to affect its safety or effectiveness．

## ANTI－COUNTERFEITING POLICY

Fairchild Semiconductor Corporation＇s Anti－Counterfeiting Policy．Fairchild＇s Anti－Counterfeiting Policy is also stated on our external website，www．fairchildsemi．com， under Sales Support．
Counterfeiting of semiconductor parts is a growing problem in the industry．All manufacturers of semiconductor products are experiencing counterfeiting of their parts， Customers who inadvertently purchase counterfeit parts experience many problems such as loss of brand reputation，substandard performance，failed applications， and increased cost of production and manufacturing delays．Fairchild is taking strong measures to protect ourselves and our customers from the proliferation of counterfeit parts．Fairchild strongly encourages customers to purchase Fairchild parts either directly from Fairchild or from Authorized Fairchild Distributors who are listed by country on our web page cited above．Products customers buy either from Fairchild directly or from Authorized Fairchild Distributors are genuine parts，have full traceability，meet Fairchild＇s quality standards for handling and storage and provide access to Fairchild＇s full range of up－to－date technical and product information． Fairchild and our Authorized Distributors will stand behind all warranties and will appropriately address any warranty issues that may arise．Fairchild will not provide any warranty coverage or other assistance for parts bought from Unauthorized Sources．Fairchild is committed to combat this global problem and encourage our customers to do their part in stopping this practice by buying direct or from authorized distributors．

PRODUCT STATUS DEFINITIONS
Definition of Terms

| Datasheet Identification | Product Status | Definition |
| :--- | :--- | :--- |
| Advance Information | Formative／In Design | Datasheet contains the design specifications for product development．Specifications may change in <br> any manner without notice． |
| Preliminary | First Production | Datasheet contains preliminary data；supplementary data will be published at a later date．Fairchild <br> Semiconductor reserves the right to make changes at any time without notice to improve design． |
| No Identification Needed | Full Production | Datasheet contains final specifications．Fairchild Semiconductor reserves the right to make changes <br> at any time without notice to improve the design． |
| Obsolete | Not In Production | Datasheet contains specifications on a product that is discontinued by Fairchild Semiconductor．The <br> datasheet is for reference information only． |

