CLC402 Low-Gain Op Amp with Fast 14-Bit Settling

General Description

The CLC402 is an operational amplifier designed for low-gain applications (± 1 to ± 8), requiring fast, accurate settling and superior DC accuracy. Settling to 0.0025% in 25ns (32ns guaranteed over temperature), the CLC402 is ideal as the input amplifier in high accuracy (up to 14-bits) A/D systems. Unlike most other high-speed op amps, the CLC402 is free of thermally induced tails in the settling response.

The CLC402 is an upgrade to and pin compatible with the industry standard CLC400. Constructed using a unique, proprietary design and an advanced complementary bipolar process, it offers performance far beyond ordinary monolithic op amps. In addition, unlike many other high-speed op amps, the CLC402 offers both high performance and stability without the need for compensation circuitry – even at a gain of +1.

Supporting the CLC402's excellent pulse performance are improved DC characteristics. The CLC402's input offset voltage is typically 0.5mV and is guaranteed to be less than 1.6mV at +25°C. The input offset voltage drift is typically only 3μ V/°C.

The CLC402 is available in several versions to meet a variety of requirements. A three-letter suffix determines the version:

CLC402AJP -40°C to +85°C CLC402AJE -40°C to +85°C CLC402A8B -55°C to +125°C

8-pin plastic DIP 8-pin plastic SOIC 8-pin hermetic CERDIP,

MIL-STD-833, Level B dice

CLC402ALC -40°C to +85°C CLC402AMC -55°C to +125°C

dice qualified to Method 5008,

MIL-STD-883, Level B

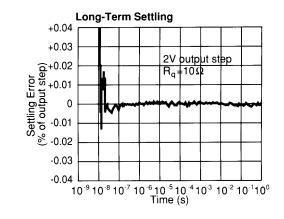
DESC SMD number: 5962-92033

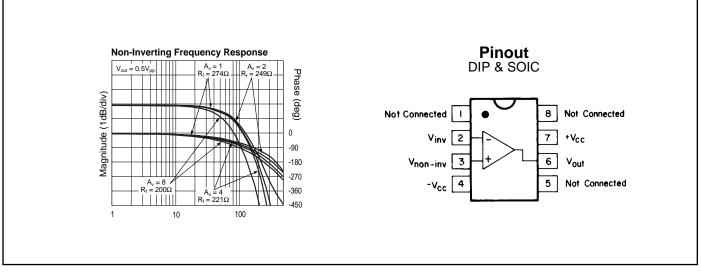
Features

- 0.0025% settling in 25ns (32ns max)
- 0.5mV input offset voltage, 3µV/°C drift
- ±1 to ±8 closed-loop gain range
- Low power, 150mW
- 0.01%/0.05° differential gain/phase

Applications

- High-accuracy A/D systems (12-14 bits)
- High-accuracy D/A converters
- High-speed communications
- IF processors
- Video distribution





CLC402 Electrical Characteristics ($A_v = +2$, $V_{cc} = \pm 5V$, $R_L = 100\Omega$, $R_f = 250\Omega$; unless specified)

PARAMETER	CONDITIONS	TYP	YP MAX & MIN RATINGS		INGS	UNITS	SYMBOL
Ambient Temperature	CLC402AJ	+25℃	−40°C	+25°C	+ 85°C		
FREQUENCY DOMAIN PERFO -3dB bandwidth	$V_{out} < 0.5 V_{op}$	195 80	>120 >50	>130 >50	>120 >50	MHz MHz	SSBW LSBW
gain flatness² peaking peaking	Vout<5Vpp Vout<0.5Vpp DC to 25MHz >25MHz	0 0	<0.4 <0.7	<0.3 <0.5	<0.4 <0.7	dB dB	GFPL GFPH
rolloff linear phase deviation	DC to 50MHz DC to 50MHz	0.5 0.4	<1.0 <1.2	<1.0 <1.0	<1.0 <1.2	dB °	GFR LPD
TIME DOMAIN PERFORMANCE rise and fall time	0.5V step 5V step	2.0 5.0	<2.9 <8	<2.7 <8	<2.9 <8	ns ns	TRS TRL
settling time to ± 0.0025% ± 0.01% ± 0.1%	2Vstep 2V step 2V step	25 18 10	<32 <25 <15	<32 <25 <15	<32 <25 <15	ns ns ns	TS14 TSP TSS
overshoot slew rate	0.5V step	0 800	<10 >500	<10 >500	<10 >500	% V/μs	OS SR
DISTORTION AND NOISE PER 2nd harmonic distortion 3rd harmonic distortion equivalent input noise	FORMANCE 2V _{pp} , 20MHz 2V _{pp} , 20MHz	-50 -60	<-38 <-53	<-43 <-53	<-43 <-50	dBc dBc	HD2 HD3
noise floor integrated noise differential gain¹ differential phase¹	>1MHz 1MHz to 150MHz	-157 40 0.01 0.05	<-155 <49 — —	<-155 <49 — —	<-155 <49 — —	dBm(1Hz) μV %	SNF INV DG DP
*input offset voltage average temperature coefficient *input bias current noninverting average temperature coefficient *input bias current inverting average temperature coefficient		0.5 3 10 100 100	<2.6 <12 <45 <250 <50 <250	<1.6 — <25 — <30	<2.8 <12 <35 <100 <40 <100	mV μV/°C μΑ nA/°C μΑ nA/°C	VIO DVIO IBN DIBN IBI DIBI
power supply rejection ratio common mode rejection ratio *supply current	no load	68 65 15	>55 >55 >55 <20	>60 >60 >60 <20	>60 >60 >60 <20	dB dB mA	PSRR CMRR ICC
MISCELLANEOUS PERFORMAL noninverting input	resistance capacitance	150 3.5	>50 <5.5	>85 <5.5	>85 <5.5	kΩ pF	RIN CIN
output impedance common mode input range output voltage range output current	at DC no load	0.02 ±3.0 ±3.5V ±55	<0.1 >±2.0 >±3.0 >±25	<0.1 >±2.5 >±3.2 >±45	<0.1 >±2.5 >±3.2 >±45	Ω V V mA	RO CMIR VO IO

Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

Absolute Maximum Ratings

Miscellaneous Ratings

 $V_{\rm cc}$ ±7V I_{out} output is short circuit protected to ground, but, maximum reliability will be obtained if Iout does not exceed... 60mA ±V_{cc} +150°C input voltage junction temperature

operating temperature range

- 40°C to +85°C AJ: - 65°C to +150°C storage temperature range 10 sec

lead solder duration (+300°C) ESD rating (human body model) 2000V

F	Reliability Information
Transistor count	

recommended gain range: ± 1 to ± 8

Notes:

100% tested at +25°C.

note 1: Differential gain and phase measured at $A_v = +2V$,

 $R=250\Omega,~R_L=150\Omega,~1V_{pp}$ equivalent video signal 0-100 IRE, 40 IRE $_{pp},~0IRE=0~volts,~75\Omega$ load

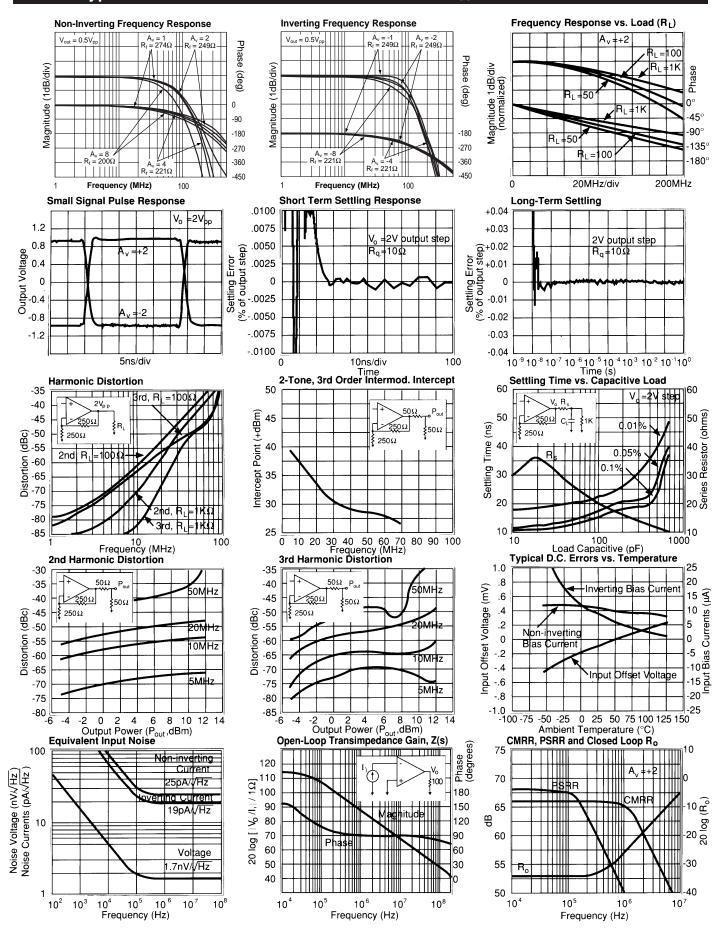
and 3.58 MHz.

Package Thermal Resistance

Package	θ _{JC}	θ_{JA}
AJP	70°C/W	125°C/W
AJE	65°C/W	145°C/W
CERDIP	45°C/W	135°C/W

37

CLC402 Typical Performance Characteristics (T_A = 25°, A_V = +2, V_{CC} = ±5V, R_L = 100Ω, Rf = 250Ω; unless specified)



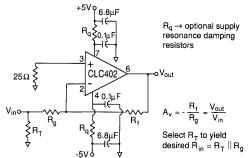


Figure 1: recommended inverting gain circuit

Feedback Resistor

The CLC402 achieves its excellent pulse response by using the current feedback topology pioneered by Comlinear Corporation. The loop gain for a current feedback op amp, and hence the frequency response, is predominantly set by the feedback resistor value. The CLC402 is optimized for use with a 250 Ω feedback resistor. Using lower values can lead to excessive ringing in the pulse response while a higher value will limit the bandwidth. Application Note OA-13 discusses this in detail along with occasions where a different R, might be advantageous.

Optimizing Settling Time

The CLC402 is capable of extremely fast pulse settling times to very fine scale accuracies (.0025% in 25ns typical). It is also virtually free of any measurable thermal tail effects as shown in the long-term settling time plot on the previous page. Careful attention to parasitic effects is critical to achieving this level of performance.

Generally, open any ground and/or power planes around the device while providing an adjacent ground plane for the $0.1\mu f$ ceramic decoupling caps. These caps should be very near the power pins. Connecting the ground return point for the electrolytic capacitors near the load ground point is also very useful. Similarly, for non-inverting applications, connecting R_q to ground near the input terminating resistor ground connection will improve performance. These suggestions become particularly pertinent for fastest settling to lower than 0.1% accuracies.

Using Supply Resistors, $\mathbf{R}_{\mathbf{q}}$ Figures 1 and 2 show a series resistor in the supply leads between the electrolytic and ceramic capacitors. This optional resistor is intended to de-Q any self-resonance between those capacitors and the power supply trace inductance. Any large output voltage step into a significant load, either resistive or capacitive, will necessarily pull a current surge through the supply de-coupling capacitors. This can cause a very low level, high frequency ringing on the power supplies that may not be effectively rejected by the PSRR of the CLC402. This can, in turn, show up at the output as a ringing that will preclude high speed settling to very fine scale accuracies.

Adding R_a will increase the amplitude of this signal at the supplies but will lower the frequency content to where the CLC402's PSRR can effectively reject it. An $R_{\rm q}$ of 5 to 10Ω will yield excellent settling performance with minimal impact on other performance parameters.

Driving Capacitive Loads

Either parasitic or load capacitance directly on the output pin can quickly lead to unacceptable levels of ringing in the pulse response. Adding a series resistor, as shown in the plot of $\rm R_s$ vs. $\rm C_L$ on the previous page, will resolve this problem. Parasitic capacitances less than 2pF can be driven without the series resistor. See Application Note OA-15 for additional discussion.

Distortion Performance

The distortion plots show the harmonic distortions and 3rd order intermodulation intercepts under a variety of load, power, and frequency conditions. Generally, going to higher

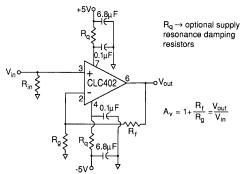
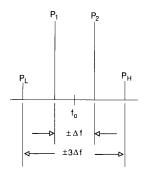


Figure 2: recommended non-inverting gain circuit

frequencies will degrade the distortion performance as the amplifier loop gain decreases. Further distortion improvements at low frequencies are observed when driving higher impedance loads. The 3rd order intermodulation intercept plot may be used to predict the 3rd order spurious levels given the power levels at the load for two closely spaced signal frequencies. Figure 3 shows the signal and spurious level definitions along with equations for predicting the spurious powers from the intercept value and the two signal powers.



P₁, P₂ - test powers at load P_L, P_H – 3rd order spurious powers (all in dBm)

IM3 - 3rd order intercept (from datasheet plot)

$$P_L = P_2 - 2 (IM3 - P_1)$$

$$P_{H} = P_{1} - 2 (IM3 - P_{2})$$

Figure 3: 3rd order spurious calculations

DC Accuracy and Noise

The CLC402 offers an improved offset voltage over the comparable CLC400 low gain amplifier. The offset adjustment available on the CLC400 was therefore not included in this part. Figure 4 shows the output offset computational equation for the non-inverting configuration with an example using the typical bias current and offset specifications for $A_v = +2$.

Output Offset

$$V_o = \left(\pm I_{bn} R_{in} \pm V_{io}\right) \left(1 + \frac{R_f}{R_g}\right) \pm I_{bi} R_f$$

Example computation for $A_v = +2$, $R_f = 250\Omega$

 $V_0 = (\pm 10 \mu A (50\Omega) \pm 0.5 mV) (2) \pm 10 \mu A (250\Omega) = \pm 3.5 mV$

Figure 4: Output DC offset calculation

This low output offset voltage is a marked improvement over earlier very high speed amplifiers. Further improvement in the output offset voltage and drift is possible using the composite amplifiers described in Application Note OA-7.

The equivalent input noise plot shows that the CLC402 offers a low $1.7 \text{nV}/\sqrt{\text{Hz}}$ input noise voltage. A low non-inverting source impedance should be used for lowest noise performance due to the relatively high current noise at that input. See Application Note OA-12 for a full discussion of noise calculations for current feedback amplifiers.

Printed Circuit Layout

Evaluation PC boards (part number 730013 for through-hole and 730027 for SOIC) for the CLC402 are available. This board can be easily modified to include the R_a resistors discussed above. Further layout suggestions may be found in Application Note OA-15.

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National Semiconductor Corporation

1111 West Bardin Road Arlington, TX 76017 Tel: 1(800) 272-9959 Fax: 1(800) 737-7018

National Semiconductor Europe

Fax: (+49) 0-180-530 85 86 E-mail: europe.support.nsc.com Deutsch Tel: (+49) 0-180-530 85 85 English Tel: (+49) 0-180-532 78 32 Francais Tel: (+49) 0-180-532 93 58 Italiano Tel: (+49) 0-180-534 16 80

National Semiconductor Hong Kong Ltd.

2501 Miramar Tower 1-23 Kimberley Road Tsimshatsui, Kowloon Hong Kong Tel: (852) 2737-1600

Fax: (852) 2736-9960

National Semiconductor Japan Ltd.

Tel: 81-043-299-2309 Fax: 81-043-299-2408

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