

Ultra-Low-Power, 12-Bit, Voltage-Output DACs

General Description

The MAX5530/MAX5531 are single, 12-bit, ultra-lowpower, voltage-output, digital-to-analog converters (DACs) offering Rail-to-Rail® buffered voltage outputs. The DACs operate from a 1.8V to 5.5V supply and consume less than 6µA, making them desirable for lowpower and low-voltage applications. A shutdown mode reduces overall current, including the reference input current, to just 0.18µA. The MAX5530/MAX5531 use a 3-wire serial interface that is compatible with SPI™, QSPI™, and MICROWIRE™.

At power-up, the MAX5530/MAX5531 outputs are driven to zero scale, providing additional safety for applications that drive valves or for other transducers that must be off during power-up. The zero-scale outputs enable glitchfree power-up.

The MAX5530 accepts an external reference input. The MAX5531 contains an internal reference and provides an external reference output. Both devices have forcesense-configured output buffers.

The MAX5530/MAX5531 are available in a 4mm x 4mm x 0.8mm, 12-pin, thin QFN package and are guaranteed over the extended -40°C to +85°C temperature range.

For 10-bit compatible devices, refer to the MAX5520/ MAX5521 data sheet. For 8-bit compatible devices, refer to the MAX5510/MAX5511 data sheet.

Applications

Portable Battery-Powered Devices

Instrumentation

Automatic Trimming and Calibration in Factory or Field

Programmable Voltage and Current Sources

Industrial Process Control and Remote Industrial Devices

Remote Data Conversion and Monitoring

Chemical Sensor Cell Bias for Gas Monitors

Programmable Liquid Crystal Display (LCD) Bias

Selector Guide

| PART | REFERENCE | TOP MARK |
|------------|-----------|----------|
| MAX5530ETC | External | AACS |
| MAX5531ETC | Internal | AACT |

Rail-to-Rail is a registered trademark of Nippon Motorola, Inc. SPI and QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp

Features

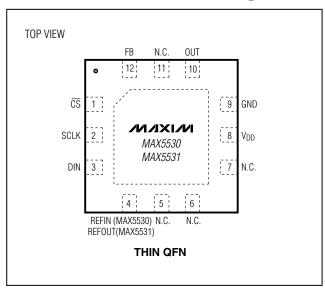
- ♦ Ultra-Low 6µA Supply Current
- ♦ Shutdown Mode Reduces Supply Current to $0.18\mu A (max)$
- ♦ Single +1.8V to +5.5V Supply
- ♦ Small 4mm x 4mm x 0.8mm Thin QFN Package
- ♦ Flexible Force-Sense-Configured Rail-to-Rail **Output Buffers**
- ♦ Internal Reference Sources 8mA of Current (MAX5531)
- ♦ Fast 16MHz 3-Wire SPI-/QSPI-/MICROWIRE-**Compatible Serial Interface**
- ♦ TTL- and CMOS-Compatible Digital Inputs with **Hysteresis**
- ♦ Glitch-Free Outputs During Power-Up

Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
|------------|----------------|-----------------|
| MAX5530ETC | -40°C to +85°C | 12 Thin QFN-EP* |
| MAX5531ETC | -40°C to +85°C | 12 Thin QFN-EP* |

^{*}EP = Exposed paddle (internally connected to GND).

Pin Configuration



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Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

| $\begin{array}{llllllllllllllllllllllllllllllllllll$ | Operating Temperature Range40°C to +85°C Storage Temperature Range65°C to +150°C Junction Temperature+150°C Lead Temperature (soldering, 10s)+300°C |
|--|---|
|--|---|

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = +1.8V \text{ to } +5.5V, \text{ OUT unloaded}, \text{ T}_{A} = \text{T}_{MIN} \text{ to T}_{MAX}, \text{ unless otherwise noted}. \text{ Typical values are at T}_{A} = +25^{\circ}\text{C.})$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---------------------------------------|------------|--|-----|------|-----|--------|
| STATIC ACCURACY (MAX5530 E | XTERNAL R | EFERENCE) | | | | |
| Resolution | N | | 12 | | | Bits |
| Integral Naplinearity (Nate 1) | INL | V _{DD} = 5V, V _{REF} = 4.096V | | ±4 | ±8 | LSB |
| Integral Nonlinearity (Note 1) | IINL | $V_{DD} = 1.8V, V_{REF} = 1.024V$ | | ±4 | ±8 | LSD |
| Differential Nonlinearity (Note 1) | DNL | Guaranteed monotonic, VDD = 5V, VREF = 4.096V | | ±0.2 | ±1 | - LSB |
| Differential Northinearity (Note 1) | DINE | Guaranteed monotonic, VDD = 1.8V, V _{REF} = 1.024V | | ±0.2 | ±1 | LOD |
| Officet Error (Note 2) | Vac | V _{DD} = 5V, V _{REF} = 4.096V | | ±1 | ±20 | m\/ |
| Offset Error (Note 2) | Vos | $V_{DD} = 1.8V, V_{REF} = 1.024V$ | | ±1 | ±20 | mV |
| Offset-Error Temperature Drift | | | | ±2 | | μV/°C |
| Coin Frank (Note 2) | GE | $V_{DD} = 5V, V_{REF} = 4.096V$ | | ±2 | ±4 | LCD |
| Gain Error (Note 3) | GE | V _{DD} = 1.8V, V _{REF} = 1.024V | | ±2 | ±4 | LSB |
| Gain-Error Temperature Coefficient | | | | ±4 | | ppm/°C |
| Power-Supply Rejection Ratio | PSRR | 1.8V ≤ V _{DD} ≤ 5.5V | | 85 | | dB |
| STATIC ACCURACY (MAX5531 I | NTERNAL RI | EFERENCE) | | | | |
| Resolution | N | | 12 | | | Bits |
| Internal New York (Nets 4) | INII | V _{DD} = 5V, V _{REF} = 3.9V | | ±4 | ±8 | 1.00 |
| Integral Nonlinearity (Note 1) | INL | V _{DD} = 1.8V, V _{REF} = 1.2V | | ±4 | ±8 | LSB |
| Differential New York (New 4) | DAII | Guaranteed monotonic, VDD = 5V, VREF = 3.9V | | ±0.2 | ±1 | 1.00 |
| Differential Nonlinearity (Note 1) | DNL | Guaranteed monotonic, VDD = 1.8V, VREF = 1.2V | | ±0.2 | ±1 | - LSB |
| Officet Funey (Nieto O) | \/ | V _{DD} = 5V, V _{REF} = 3.9V | | ±1 | ±20 | \/ |
| Offset Error (Note 2) | Vos | $V_{DD} = 1.8V, V_{REF} = 1.2V$ | | ±1 | ±20 | mV |
| Offset-Error Temperature Drift | | | | ±2 | | μV/°C |
| Gain Error (Note 3) | GE | V _{DD} = 5V, V _{REF} = 3.9V | | ±2 | ±4 | LCD |
| | GE | V _{DD} = 1.8V, V _{REF} = 1.2V | | ±2 | ±4 | LSB |
| Gain-Error Temperature Coefficient | | | | ±4 | | ppm/°C |

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ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = +1.8V \text{ to } +5.5V, \text{ OUT unloaded}, \text{ T}_{A} = \text{T}_{MIN} \text{ to T}_{MAX}, \text{ unless otherwise noted}. \text{ Typical values are at T}_{A} = +25^{\circ}\text{C.})$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | |
|---|--------------------|---|-------|---------|-----------------|-------------------|--|
| Power-Supply Rejection Ratio | PSRR | 1.8V ≤ V _{DD} ≤ 5.5V | | 85 | | dB | |
| REFERENCE INPUT (MAX5530) | • | | | | | • | |
| Reference-Input Voltage Range | V _{REFIN} | | 0 | | V _{DD} | V | |
| Deference Inc. it less adams | D | Normal operation | 4.1 | | | МΩ | |
| Reference-Input Impedance | RREFIN | In shutdown | | 2.5 | | GΩ | |
| REFERENCE OUTPUT (MAX5531 | 1) | | | | | | |
| | | No external load, V _{DD} = 1.8V | 1.197 | 1.214 | 1.231 | | |
| Initial Appropri | \/ | No external load, V _{DD} = 2.5V | 1.913 | 1.940 | 1.967 | | |
| Initial Accuracy | VREFOUT | No external load, V _{DD} = 3V | 2.391 | 2.425 | 2.459 | V | |
| | | No external load, V _{DD} = 5V | 3.828 | 3.885 | 3.941 | | |
| Output-Voltage Temperature Coefficient | VTEMPCO | $T_A = -40^{\circ}C \text{ to } +85^{\circ}C \text{ (Note 4)}$ | | 12 | 30 | ppm/°C | |
| Line Regulation | | VREFOUT < VDD - 200mV (Note 5) | | 2 | 200 | μV/V | |
| | | $0 \le I_{REFOUT} \le 1$ mA, sourcing, $V_{DD} = 1.8$ V, $V_{REF} = 1.2$ V | | 0.3 | 2 | | |
| Load Regulation | | $0 \le I_{REFOUT} \le 8mA$, sourcing, $V_{DD} = 5V$, $V_{REF} = 3.9V$ | | 0.3 | 2 | μV/μΑ | |
| | | -150µA ≤ IREFOUT ≤ 0, sinking | | 0.2 | | | |
| | | 0.1Hz to 10Hz, V _{REFOUT} = 3.9V | | 150 | | | |
| | | 10Hz to 10kHz, V _{REFOUT} = 3.9V | | 600 | | 1 ,, | |
| Output Noise Voltage | | 0.1Hz to 10Hz, V _{REFOUT} = 1.2V | | 50 | | μV _{P-P} | |
| | | 10Hz to 10kHz, V _{REFOUT} = 1.2V | | 450 | | | |
| Chart Circuit Current (Nate C) | | V _{DD} = 5V | | 30 | | Λ | |
| Short-Circuit Current (Note 6) | | V _{DD} = 1.8V | | 14 | | mA | |
| Capacitive Load Stability Range | | (Note 7) | | 0 to 10 | | nF | |
| Thermal Hysteresis | | (Note 8) | | 200 | | ppm | |
| Reference Power-Up Time (from | | REFOUT unloaded, V _{DD} = 5V | | 5.4 | | mo | |
| Shutdown) | | REFOUT unloaded, V _{DD} = 1.8V | | 4.4 | | ms | |
| Long-Term Stability | | | | 200 | | ppm/ 1khrs | |
| DAC OUTPUT (OUT) | | | | | | | |
| Capacitive Driving Capability | CL | | | 1000 | | рF | |
| | | V _{DD} = 5V, V _{OUT} set to full scale, OUT shorted to GND, source current | | | 65 | | |
| Short-Circuit Current (Note 6) | | V _{DD} = 5V, V _{OUT} set to 0V, OUT shorted to V _{DD} , sink current | | | 65 | m ^ | |
| | | V _{DD} = 1.8V, V _{OUT} set to full scale, OUT shorted to GND, source current | | | 14 | mA | |
| | | V _{DD} = 1.8V, V _{OUT} set to 0V, OUT shorted to V _{DD} , sink current | | | 14 | | |



ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = +1.8V \text{ to } +5.5V, \text{ OUT unloaded}, \text{ T}_{A} = \text{T}_{MIN} \text{ to T}_{MAX}, \text{ unless otherwise noted}. \text{ Typical values are at T}_{A} = +25^{\circ}\text{C.})$

| SYMBOL | CONDITIONS | | MIN | TYP | MAX | UNITS | |
|-----------------|--|---|--|----------------------------------|----------------------------------|----------------------------------|--|
| | Coming out of shutdown | $V_{DD} = 5V$ | | 3 | | | |
| | (MAX5530) | $V_{DD} = 1.8V$ | | 3.8 | | ms | |
| | Coming out of standby (MAX5531) | V _{DD} = 1.8V to 5.5V | | 0.4 | | | |
| | C _L = 100pF | | | 10 | | mV | |
| | | | | 10 | | рΑ | |
| 5) | <u> </u> | | | | | | |
| | $4.5V \le V_{DD} \le 5.5V$ | | 2.4 | | | | |
| VIH | 2.7V < V _{DD} ≤ 3.6V | | 2.0 | | | V | |
| | $1.8V \le V_{DD} \le 2.7V$ | | 0.7 x V _{DE} |) | | | |
| | $4.5V \le V_{DD} \le 5.5V$ | | | | 0.8 | | |
| VIL | $2.7V < V_{DD} \le 3.6V$ | | | | 0.6 | V | |
| | $1.8V \le V_{DD} \le 2.7V$ | | (| 0.3 x V _{DD} | | | |
| I _{IN} | (Note 9) | | | ±0.05 | ±0.5 | μΑ | |
| CIN | | | | 10 | | рF | |
| • | | | • | | | • | |
| SR | Positive and negative (Note | 10) | | 10 | | V/ms | |
| | 0.1 to 0.9 of full scale to with (Note 10) | in 0.5 LSB | | 660 | | μs | |
| | | $V_{DD} = 5V$ | | 80 | | | |
| | 0.1Hz to 10Hz | | | 55 | | μV _{P-P} | |
| | 4011 . 40111 | $V_{DD} = 5V$ | | 620 | | | |
| | 10Hz to 10kHz | $V_{DD} = 1.8V$ | | 476 | | | |
| ·! | | _ | | | | I. | |
| V_{DD} | | | 1.8 | | 5.5 | V | |
| | | $V_{DD} = 5V$ | | 2.6 | 4 | | |
| | MAX5530 | | | 2.6 | 4 | | |
| | | $V_{DD} = 1.8V$ | | 3.6 | 5 | | |
| IDD | | $V_{DD} = 5V$ | | 5.3 | 7.0 | μΑ | |
| | MAX5531 | | | 4.8 | 7.0 | 1 | |
| | | | | 5.4 | 7.0 | | |
| | | | | 3.3 | 4.5 | | |
| Ippsp | (Note 9) | | | 2.8 | 4.0 | μA | |
| 5505 | | | | | | 1 . | |
| IDDPD | (Note 9) | 1 22 | | 0.05 | 0.25 | μΑ | |
| | VIH VIL LIN CIN SR VDD LDDSD | Coming out of shutdown (MAX5530) Coming out of standby (MAX5531) CL = 100pF Si) 4.5V ≤ V _{DD} ≤ 5.5V 2.7V < V _{DD} ≤ 3.6V 1.8V ≤ V _{DD} ≤ 5.5V 2.7V < V _{DD} ≤ 3.6V 1.8V ≤ V _{DD} ≤ 2.7V 4.5V ≤ V _{DD} ≤ 3.6V 1.8V ≤ V _{DD} ≤ 2.7V IIN (Note 9) CIN SR Positive and negative (Note 0.1 to 0.9 of full scale to with (Note 10) 0.1Hz to 10Hz 10Hz to 10Hz 10Hz to 10kHz VDD MAX5530 IDD MAX5531 IDDSD (Note 9) | Coming out of shutdown (MAX5530) Coming out of standby (MAX5531) CL = 100pF 4.5V ≤ V _{DD} ≤ 5.5V 2.7V < V _{DD} ≤ 3.6V 1.8V ≤ V _{DD} ≤ 5.5V 2.7V < V _{DD} ≤ 3.6V 1.8V ≤ V _{DD} ≤ 2.7V 4.5V ≤ V _{DD} ≤ 2.7V 4.5V ≤ V _{DD} ≤ 2.7V IN (Note 9) CIN SR Positive and negative (Note 10) 0.1 to 0.9 of full scale to within 0.5 LSB (Note 10) 0.1Hz to 10Hz V _{DD} = 5V V _{DD} = 5V V _{DD} = 5V V _{DD} = 1.8V V _{DD} = 5V V _{DD} = 3V V _{DD} = 1.8V | Coming out of shutdown (MAX5530) | Coming out of shutdown (MAX5530) | Coming out of shutdown (MAX5530) | |

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TIMING CHARACTERISTICS

 $(V_{DD} = +4.5V \text{ to } +5.5V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | | | | | |
|---|-----------------|------------|-----|-----|------|-------|--|--|--|--|--|
| TIMING CHARACTERISTICS (V _{DD} = 4.5V TO 5.5V) | | | | | | | | | | | |
| Serial Clock Frequency | fsclk | | 0 | | 16.7 | MHz | | | | | |
| DIN to SCLK Rise Setup Time | t _{DS} | | 15 | | | ns | | | | | |
| DIN to SCLK Rise Hold Time | tDH | | 0 | | | ns | | | | | |
| SCLK Pulse-Width High | tсн | | 24 | | | ns | | | | | |
| SCLK Pulse-Width Low | t _{CL} | | 24 | | | ns | | | | | |
| CS Pulse-Width High | tcsw | | 100 | | | ns | | | | | |
| SCLK Rise to $\overline{\text{CS}}$ Rise Hold Time | tcsh | | 0 | | | ns | | | | | |
| CS Fall to SCLK Rise Setup Time | tcss | | 20 | | | ns | | | | | |
| SCLK Fall to CS Fall Setup | tcso | | 0 | | | ns | | | | | |
| CS Rise to SCK Rise Hold Time | tcs1 | | 20 | | | ns | | | | | |

TIMING CHARACTERISTICS

 $(V_{DD} = +1.8V \text{ to } +5.5V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | | | | | |
|---|-----------------|------------|-----|-----|-----|-------|--|--|--|--|--|
| TIMING CHARACTERISTICS (V _{DD} = 1.8V TO 5.5V) | | | | | | | | | | | |
| Serial Clock Frequency | fsclk | | 0 | | 10 | MHz | | | | | |
| DIN to SCLK Rise Setup Time | t _{DS} | | 24 | | | ns | | | | | |
| DIN to SCLK Rise Hold Time | tDH | | 0 | | | ns | | | | | |
| SCLK Pulse-Width High | tсн | | 40 | | | ns | | | | | |
| SCLK Pulse-Width Low | tCL | | 40 | | | ns | | | | | |
| CS Pulse-Width High | tcsw | | 150 | | | ns | | | | | |
| SCLK Rise to CS Rise Hold Time | tcsh | | 0 | | | ns | | | | | |
| CS Fall to SCLK Rise Setup Time | tcss | | 30 | | | ns | | | | | |
| SCLK Fall to CS Fall Setup | tcso | | 0 | | | ns | | | | | |
| CS Rise to SCK Rise Hold Time | tcs1 | | 30 | • | • | ns | | | | | |

Note 1: Linearity is tested within codes 96 to 4080.

Note 2: Offset is tested at code 96.

Note 3: Gain is tested at code 4095. FB is connected to OUT.

Note 4: Guaranteed by design. Not production tested.

Note 5: V_{DD} must be a minimum of 1.8V.

Note 6: Outputs can be shorted to V_{DD} or GND indefinitely, provided that the package power dissipation is not exceeded.

Note 7: Optimal noise performance is at 2nF load capacitance.

Note 8: Thermal hysteresis is defined as the change in the initial +25°C output voltage after cycling the device from T_{MAX} to T_{MIN}.

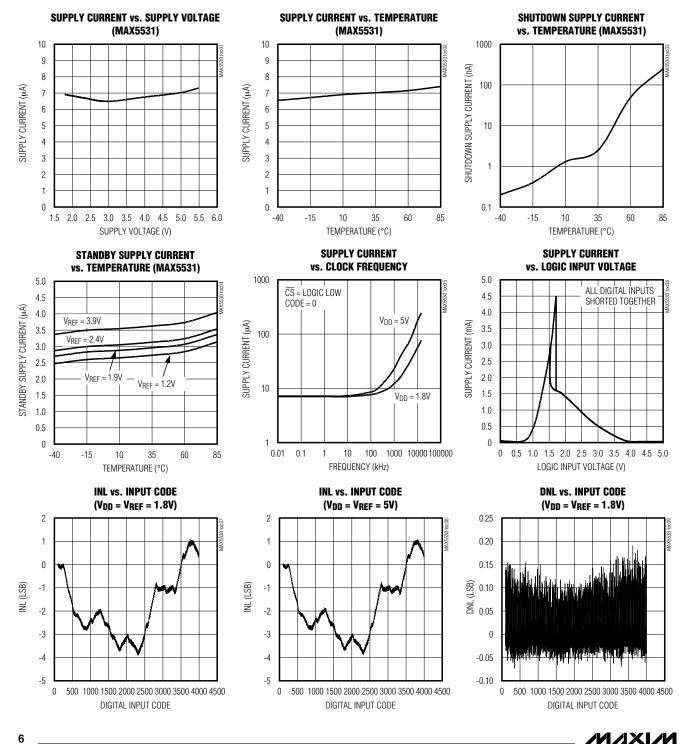
Note 9: All digital inputs at VDD or GND.

Note 10: Load = $10k\Omega$ in parallel with 100pF, $V_{DD} = 5V$, $V_{REF} = 4.096V$ (MAX5530) or $V_{REF} = 3.9V$ (MAX5531).



Typical Operating Characteristics

(VDD = 5.0V, VREF = 4.096V (MAX5530), VREF = 3.9V (MAX5531), TA = +25°C, unless otherwise noted.)

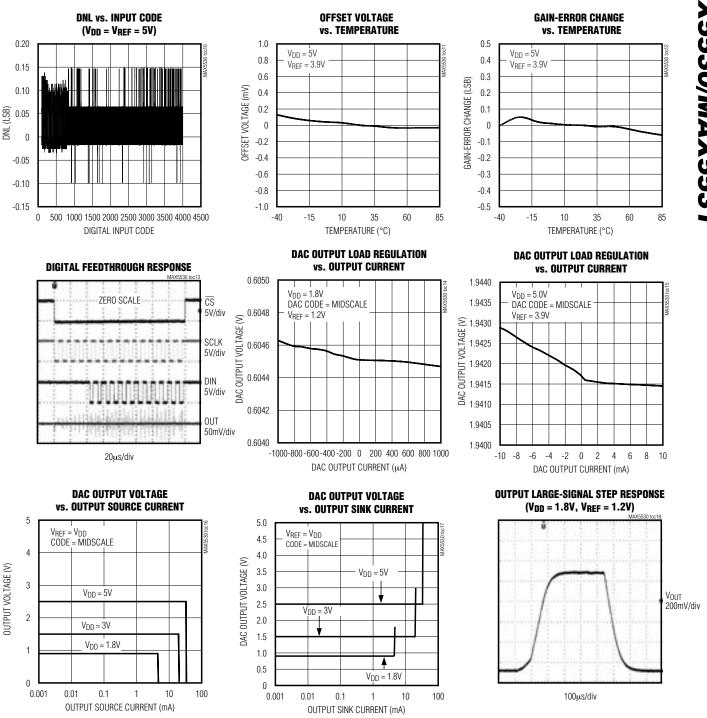


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Ultra-Low-Power, 12-Bit, Voltage-Output DACs

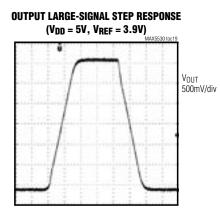
Typical Operating Characteristics (continued)

(V_{DD} = 5.0V, V_{REF} = 4.096V (MAX5530), V_{REF} = 3.9V (MAX5531), T_A = +25°C, unless otherwise noted.)

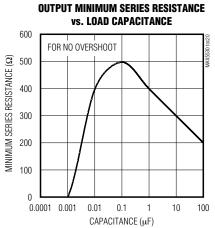


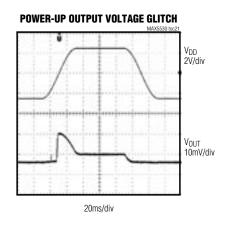
Typical Operating Characteristics (continued)

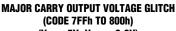
(V_{DD} = 5.0V, V_{REF} = 4.096V (MAX5530), V_{REF} = 3.9V (MAX5531), T_A = +25°C, unless otherwise noted.)

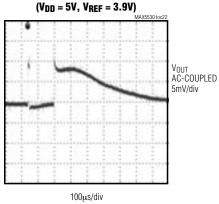


200µs/div

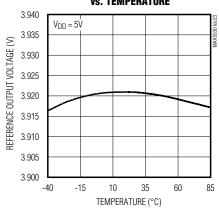




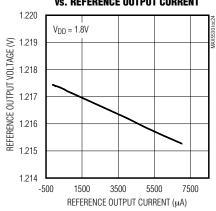




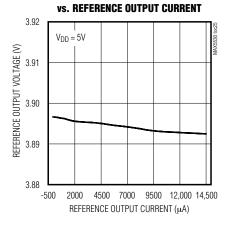




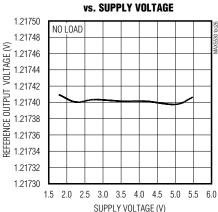




REFERENCE OUTPUT VOLTAGE



REFERENCE OUTPUT VOLTAGE

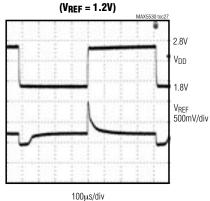


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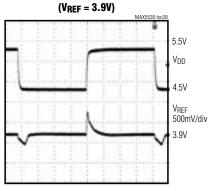
Typical Operating Characteristics (continued)

 $(V_{DD} = 5.0V, V_{REF} = 4.096V (MAX5530), V_{REF} = 3.9V (MAX5531), T_{A} = +25^{\circ}C, unless otherwise noted.)$

REFERENCE LINE-TRANSIENT RESPONSE

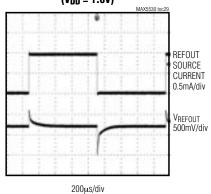


REFERENCE LINE-TRANSIENT RESPONSE (VRFE = 3.9V)

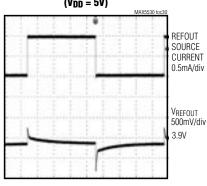


100μs/div

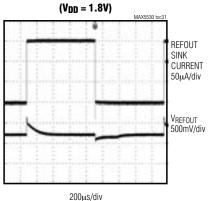
REFERENCE LOAD TRANSIENT (VDD = 1.8V)



REFERENCE LOAD TRANSIENT (VDD = 5V)

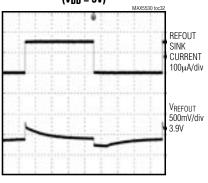


REFERENCE LOAD TRANSIENT



 $\begin{array}{c} \textbf{REFERENCE LOAD TRANSIENT} \\ \textbf{(V}_{DD} = \textbf{5V)} \end{array}$

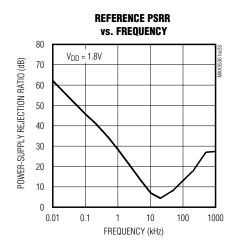
 $200\mu s/div$

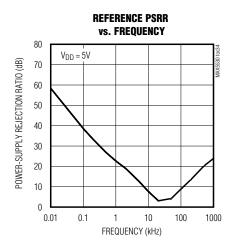


200µs/div

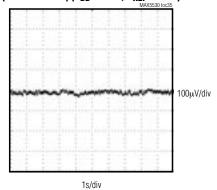
Typical Operating Characteristics (continued)

 $(V_{DD} = 5.0V, V_{REF} = 4.096V (MAX5530), V_{REF} = 3.9V (MAX5531), T_{A} = +25^{\circ}C, unless otherwise noted.)$

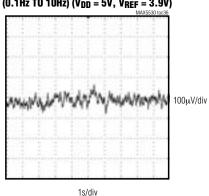




$\label{eq:control_relation} \begin{aligned} & \text{REFERENCE OUTPUT NOISE} \\ & \text{(0.1Hz TO 10Hz) (V}_{DD} = 1.8V, \, V_{REF} = 1.2V) \end{aligned}$



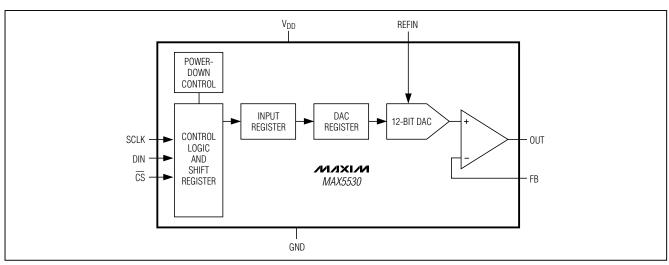
REFERENCE OUTPUT NOISE (0.1Hz TO 10Hz) (VDD = 5V, VREF = 3.9V)



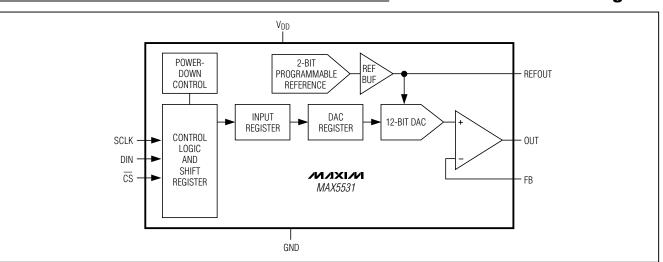
Pin Description

| Р | PIN | | FUNCTION |
|-------------|-------------|-------------------|--|
| MAX5530 | MAX5531 | NAME | FUNCTION |
| 1 | 1 | CS | Active-Low Digital-Input Chip Select |
| 2 | 2 | SCLK | Serial-Interface Clock |
| 3 | 3 | DIN | Serial-Interface Data Input |
| 4 | _ | REFIN | Reference Input |
| _ | 4 | REFOUT | Reference Output |
| 5, 6, 7, 11 | 5, 6, 7, 11 | N.C. | No Connection. Leave N.C. inputs unconnected (floating) or connected to GND. |
| 8 | 8 | V _{DD} | Power Input. Connect V_{DD} to a 1.8V to 5.5V power supply. Bypass V_{DD} to GND with a 0.1 μ F capacitor. |
| 9 | 9 | GND | Ground |
| 10 | 10 | OUT | Analog Voltage Output |
| 12 | 12 | FB | Feedback Input |
| EP | EP | Exposed Paddle | Exposed Paddle. Connect EP to GND. |

MAX5530 Functional Diagram



MAX5531 Functional Diagram



Detailed Description

The MAX5530/MAX5531 single, 12-bit, ultra-low-power, voltage-output DACs offer Rail-to-Rail buffered voltage outputs. The DACs operate from a 1.8V to 5.5V supply and require only 6µA (max) supply current. These devices feature a shutdown mode that reduces overall current, including the reference input current, to just 0.18µA. The MAX5531 includes an internal reference that saves additional board space and can source up to 8mA, making it functional as a system reference. The 16MHz, 3-wire serial interface is compatible with SPI, QSPI, and MICROWIRE protocols. When VDD is applied, all DAC outputs are driven to zero scale with virtually no output glitch. The MAX5530/MAX5531 output buffers are configured in force sense allowing users to externally set voltage gains on the output (an output amplifier inverting input is available). These devices come in a 4mm x 4mm thin QFN package.

Digital Interface

The MAX5530/MAX5531 use a 3-wire serial interface compatible with SPI, QSPI, and MICROWIRE protocols (Figures 1 and 2).

The MAX5530/MAX5531 include a single, 16-bit, input shift register. Data loads into the shift register through the serial interface. \overline{CS} must remain low until all 16 bits are clocked in. Data loads MSB first, D11–D0. The 16 bits consist of 4 control bits (C3–C0) and 12 data bits (D11–D0) (see Table 1). The control bits C3–C0 control the MAX5530/MAX5531, as outlined in Table 2.

Each DAC channel includes two registers: an input register and a DAC register. The input register holds input data. The DAC register contains the data updated to the DAC output.

The double-buffered register configuration allows any of the following:

- Loading the input registers without updating the DAC registers
- Updating the DAC registers from the input registers
- Updating all the input and DAC registers simultaneously

12 _______ /V|/X|/V|

Table 1. Serial Write Data Format

| CONTROL | | | | | DATA BITS | | | | | | | | | | |
|---------|----|----|----|-----|-----------|----|----|----|----|----|-----|----|----|----|----|
| MSB | | | | | | | | | | | LSB | | | | |
| C3 | C2 | C1 | C0 | D11 | D10 | D9 | D8 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |

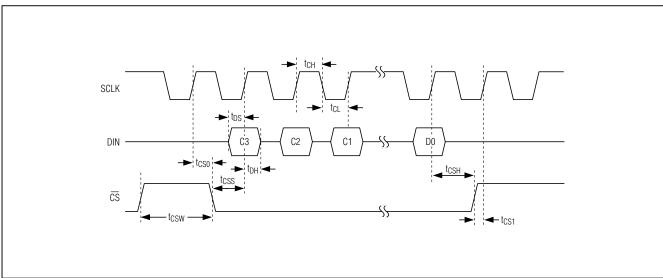


Figure 1. Timing Diagram

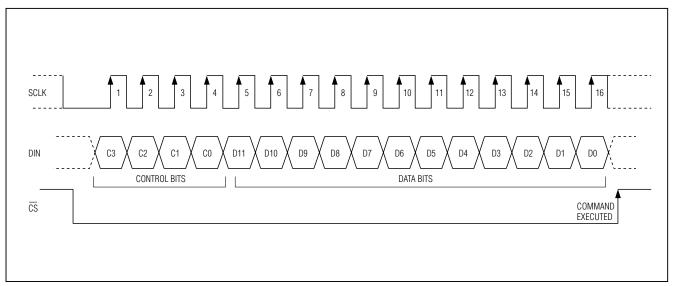


Figure 2. Register Loading Diagram



Table 2. Serial-Interface Programming Commands

| | CONTRO | OL BITS | | INPUT DATA | FUNCTION |
|----|--------|---------|----|-------------------------|--|
| C3 | C2 | C1 | C0 | D11-D0 | FUNCTION |
| 0 | 0 | 0 | 0 | XXXXXXXXXXX | No operation; command is ignored. |
| 0 | 0 | 0 | 1 | 12-bit data | Load input register from shift register; DAC register unchanged; DAC output unchanged. |
| 0 | 0 | 1 | 0 | _ | Command reserved; do not use. |
| 0 | 0 | 1 | 1 | _ | Command reserved; do not use. |
| 0 | 1 | 0 | 0 | _ | Command reserved; do not use. |
| 0 | 1 | 0 | 1 | _ | Command reserved; do not use. |
| 0 | 1 | 1 | 0 | _ | Command reserved; do not use. |
| 0 | 1 | 1 | 1 | _ | Command reserved; do not use. |
| 1 | 0 | 0 | 0 | 12-bit data | Load DAC register from input register; DAC output updated; MAX5530 enters normal operation if in shutdown; MAX5531 enters normal operation if in standby or shutdown. |
| 1 | 0 | 0 | 1 | 12-bit data | Load input register and DAC register from shift register; DAC output updated; MAX5530 enters normal operation if in shutdown; MAX5531 enters normal operation if in standby or shutdown. |
| 1 | 0 | 1 | 0 | _ | Command reserved; do not use. |
| 1 | 0 | 1 | 1 | _ | Command reserved; do not use. |
| 1 | 1 | 0 | 0 | D11, D10, XXXXXXXXXX | MAX5530 enters shutdown; MAX5531 enters standby*. For the MAX5531, D11 and D10 configure the internal reference voltage (Table 3). |
| 1 | 1 | 0 | 1 | D11, D10, XXXXXXXXXX | MAX5530/MAX5531 enter normal operation; DAC output reflects existing contents of DAC register. For the MAX5531, D11 and D10 configure the internal reference voltage (Table 3). |
| 1 | 1 | 1 | 0 | D11, D10, XXXXXXXXXX | MAX5530/MAX5531 enter shutdown; DAC output set to high impedance. For the MAX5531, D11 and D10 configure the internal reference voltage (Table 3). |
| 1 | 1 | 1 | 1 | 12-bit data | Load input register and DAC register from shift register; DAC output updated; MAX5530 enters normal operation if in shutdown; MAX5531 enters normal operation if in standby or shutdown. |

X = Don't care.

^{*}Standby mode can be entered from normal operation only. It is not possible to enter standby mode from shutdown.

Power Modes

The MAX5530/MAX5531 feature two power modes to conserve power during idle periods. In normal operation, the device is fully operational. In shutdown mode, the device is completely powered down, including the internal voltage reference in the MAX5531. The MAX5531 also offers a standby mode where all circuitry is powered down except the internal voltage reference. Standby mode keeps the reference powered up while the remaining circuitry is shut down, allowing it to be used as a system reference. Standby mode also helps reduce the wake-up delay by not requiring the reference to power up when returning to normal operation.

Shutdown Mode

The MAX5530/MAX5531 feature a software-programmable shutdown mode that reduces the typical supply current and the reference input current to 0.18µA (max). Writing an input control word with control bits C[3:0] = 1110 places the device in shutdown mode (Table 2). In shutdown, the MAX5530 reference input and DAC output buffers go high impedance. Placing the MAX5531 into shutdown turns off the internal reference, and the DAC output buffers go high impedance. The serial interface remains active for all devices.

Table 2 shows several commands that bring the MAX5530/MAX5531 back to normal operation. The power-up time from shutdown is required before the DAC outputs are valid.

Note: For the MAX5531, standby mode cannot be entered directly from shutdown mode. The device must be brought into normal operation before entering standby mode.

Table 3. Reference Output Voltage Programming

| D11 | D10 | REFERENCE VOLTAGE (V) |
|-----|-----|-----------------------|
| 0 | 0 | 1.214 |
| 0 | 1 | 1.940 |
| 1 | 0 | 2.425 |
| 1 | 1 | 3.885 |

Standby Mode (MAX5531 Only)

The MAX5531 features a software-programmable standby mode that reduces the typical supply current to $6\mu A$. Standby mode powers down all circuitry except the internal voltage reference. Place the device in standby mode by writing an input control word with control bits C[3:0] = 1100 (Table 2). The internal reference and serial interface remain active while the DAC output buffers go high impedance. If the MAX5531 is coming out of standby, the power-up time from standby is required before the DAC outputs are valid.

For the MAX5531, standby mode cannot be entered directly from shutdown mode. The device must be brought into normal operation before entering standby mode. To enter standby from shutdown, issue the command to return to normal operation, followed immediately by the command to go into standby.

Table 2 shows several commands that bring the MAX5531 back to normal operation. When transitioning from standby mode to normal operation, only the DAC power-up time is required before the DAC outputs are valid.

Reference Input

The MAX5530 accepts a reference with a voltage range extending from 0 to V_{DD}. The output voltage (V_{OUT}) is represented by a digitally programmable voltage source as:

$$VOUT = (VREF \times N / 4096) \times gain$$

where N is the numeric value of the DAC's binary input code (0 to 4095), V_{REF} is the reference voltage and gain is the externally set voltage gain for the MAX5530/MAX5531.

In shutdown mode, the reference input enters a high-impedance state with an input impedance of $2.5G\Omega$ (typ).

Reference Output

The MAX5531 internal voltage reference is software configurable to one of four voltages. Upon power-up, the default reference voltage is 1.214V. Configure the reference voltage using the D11 and D10 data bits (Table 3) when the control bits are as follows C[3:0] = 1100, 1101, or 1110 (Table 2). V_{DD} must be kept at a minimum of 200mV above V_{REF} for proper operation.

Applications Information

1-Cell and 2-Cell Circuit

See Figure 3 for an illustration of how to power the MAX5530/MAX5531 with either one lithium-ion battery or two alkaline batteries. The low current consumption of the devices makes the MAX5530/MAX5531 ideal for battery-powered applications.

Programmable Current Source

See the circuit in Figure 4 for an illustration of how to configure the MAX5530 as a programmable current source for driving an LED. The MAX5530 drives a standard NPN transistor to program the current source. The current source (I_{LED}) is defined in the equation in Figure 4.

Voltage Biasing a Current-Output Transducer

See the circuit in Figure 5 for an illustration of how to configure the MAX5530 to bias a current output transducer. In Figure 5, the output voltage of the MAX5530 is a function of the voltage drop across the transducer added to the voltage drop across the feedback resistor R.

Self-Biased Two-Electrode Potentiostat Application

See the circuit in Figure 6 for an illustration of how to use the MAX5531 to bias a two-electrode potentiostat on the input of an ADC.

Unipolar Output

Figure 7 shows the MAX5530 in a unipolar output configuration with unity gain. Table 4 lists the unipolar output codes.

Bipolar Output

The MAX5530 output can be configured for bipolar operation, as shown in Figure 8. The output voltage is given by the following equation:

$$V_{OUT} = V_{REF} \times [(N_A - 2048) / 2048]$$

where NA represents the numeric value of the DAC's binary input code. Table 5 shows digital codes (offset binary) and the corresponding output voltage for the circuit in Figure 4.

Configurable Output Gain

The MAX5530/MAX5531 have a force-sense output, which provides a connection directly to the inverting terminal of the output op amp, yielding the most flexibility. The advantage of the force-sense output is that specific gains can be set externally for a given application. The gain error for the MAX5530/MAX5531 is specified in a unity-gain configuration (op-amp output and inverting terminals connected), and additional gain error results from external resistor tolerances. Another advantage of the force-sense DAC is that it allows many useful circuits to be created with only a few simple external components.

An example of a custom fixed gain using the force-sense output of the MAX5530/MAX5531 is shown in Figure 9. In this example, R1 and R2 set the gain for Vout.

 $V_{OUT} = [(V_{REFIN} \times N_A) / 4096] \times [1 + (R2 / R1)]$ where NA represents the numeric value of the DAC input code.

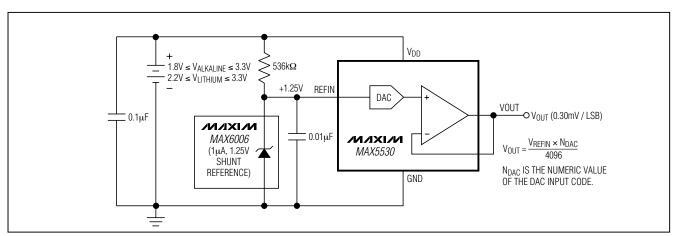


Figure 3. Portable Application Using Two Alkaline Cells or One Lithium Coin Cell

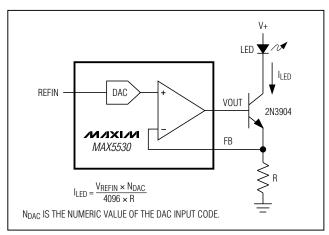


Figure 4. Programmable Current Source Driving an LED

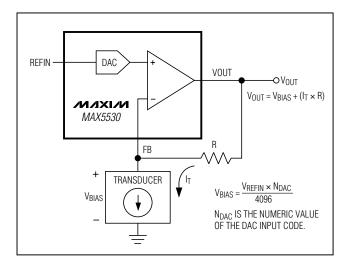


Figure 5. Transimpedance Configuration for a Voltage-Biased Current-Output Transducer

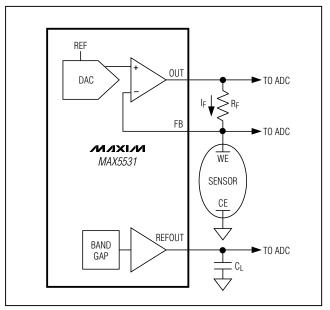


Figure 6. Self-Biased Two-Electrode Potentiostat Application

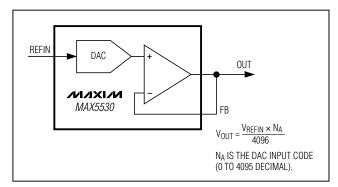


Figure 7. Unipolar Output Circuit

Table 4. Unipolar Code Table (Gain = +1)

| DAC | CONTE | NTS | ANALOG OUTPUT |
|------|-------|------|---|
| MSB | | LSB | ANALOG GOTF OT |
| 1111 | 1111 | 1100 | +V _{REF} (4095/4096) |
| 1000 | 0000 | 0001 | +V _{REF} (2049/4096) |
| 1000 | 0000 | 0000 | +V _{REF} (2048/4096) = +V _{REF} / 2 |
| 0111 | 1111 | 1111 | +V _{REF} (2047/4096) |
| 0000 | 0001 | 0001 | +V _{REF} (1/4096) |
| 0000 | 0000 | 0000 | OV |

Table 5. Bipolar Code Table (Gain = +1)

| DAC CONTENTS | | | ANALOG OUTPUT | | | |
|--------------|------|------|---|--|--|--|
| MSB | | LSB | ANALOG OUTPUT | | | |
| 1111 | 1111 | 1111 | +V _{REF} (2047/2048) | | | |
| 1000 | 0000 | 0001 | +V _{REF} (1/2048) | | | |
| 1000 | 0000 | 0000 | OV | | | |
| 0111 | 1111 | 1111 | -V _{REF} (1/2048) | | | |
| 0000 | 0000 | 0001 | -V _{REF} (2047/2048) | | | |
| 0000 | 0000 | 0000 | -V _{REF} (2048/2048) = -V _{REF} | | | |



Power Supply and Bypassing Considerations

Bypass the power supply with a 0.1µF capacitor to GND. Minimize lengths to reduce lead inductance. If noise becomes an issue, use shielding and/or ferrite beads to increase isolation. For the thin QFN package, connect the exposed paddle to ground.

Figure 8. Bipolar Output Circuit

Layout Considerations

Digital and AC transient signals coupling to GND can create noise at the output. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane. Wire-wrapped boards and sockets are not recommended. For optimum system performance, use printed circuit (PC) boards. Good PC board ground layout minimizes crosstalk between DAC outputs, reference inputs, and digital inputs. Reduce crosstalk by keeping analog lines away from digital lines.

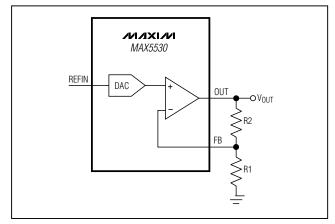


Figure 9. Separate Force-Sense Outputs Create Unity and Greater-than-Unity DAC Gains Using the Same Reference

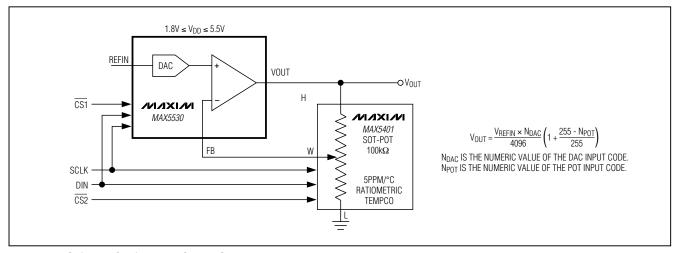


Figure 10. Software-Configurable Output Gain

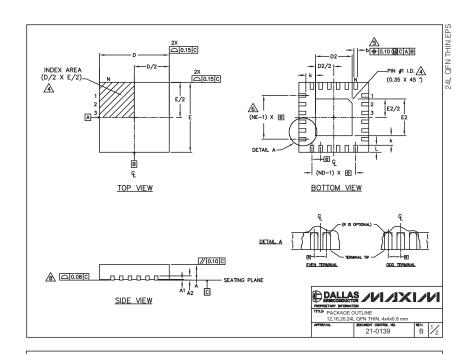
_Chip Information

TRANSISTOR COUNT: 10,688

PROCESS: BICMOS

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)



| | | | | | СПММ | ON DI | MENS | SIONS | | | | |
|---------------|-----------|------|-----------|------|-----------|----------|-----------|-------|----------|------|------|------|
| PKG | 12L 4×4 | | 16L 4×4 | | | 20L 4×4 | | | 24L 4×4 | | | |
| REF. | MIN. | NOM. | MAX. | MIN. | NDM. | MAX. | MIN. | NDM. | MAX. | MIN. | NDM. | MA) |
| Α | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.8 |
| A1 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.0 |
| A2 | 0.20 REF | | 0.20 REF | | | 0.20 REF | | | 0.20 REF | | | |
| b | 0.25 | 0.30 | 0.35 | 0.25 | 0.30 | 0.35 | 0.20 | 0.25 | 0.30 | 0.18 | 0.23 | 0.3 |
| D | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 |
| E | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 |
| e | 0.80 BSC. | | 0.65 BSC. | | 0.50 BSC. | | 0.50 BSC. | | | | | |
| k | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - |
| L | 0.45 | 0.55 | 0.65 | 0.45 | 0.55 | 0.65 | 0.45 | 0.55 | 0.65 | 0.30 | 0.40 | 0.5 |
| N | | 12 | 12 | | 16 | | 20 | | 24 | | | |
| ND | | 3 | | 4 | | 5 | | 6 | | | | |
| NE | | 3 | | | 4 | 4 | | 5 | | 6 | | |
| Jedec Var. | WGGB | | WGGC | | WGGD-1 | | WGGD-2 | | | | | |

| EXPOSED PAD VARIATIONS | | | | | | | | |
|------------------------|------|------|------|------|------|------|--|--|
| PKG. | | DS | | ES. | | | | |
| CODES | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. | | |
| T1244-2 | 1.95 | 2.10 | 2.25 | 1.95 | 2.10 | 2.25 | | |
| T1644-2 | 1.95 | 2.10 | 2.25 | 1.95 | 2.10 | 2.25 | | |
| T2044-1 | 1.95 | 2.10 | 2.25 | 1.95 | 2.10 | 2.25 | | |
| T2444-1 | 2.45 | 2.60 | 2.63 | 2.45 | 2.60 | 2.63 | | |
| T2444-2 | 1.95 | 2.10 | 2.25 | 1.95 | 2.10 | 2.25 | | |

- ILES:

 DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
 ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.

 N IS THE TOTAL NUMBER OF TERMINALS.

- THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO USES 95-1 SPF-012. DETAILS OF TERMINAL #1 IDENTIFIER AND ET OF THE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE ETHER A MOLD OR MARKED FEATURE.
- DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TIP.
- MD AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
 7. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
- COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
 DRAWING CONFORMS TO JEDEC MO220, EXCEPT FOR T2444-1.

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