19-2983; Rev 1; 11/04

EVALUATION KIT AVAILABLE

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

General Description

The MAX5590–MAX5595 octal, 12/10/8-bit, voltage-output digital-to-analog converters (DACs) offer buffered outputs and a 3µs maximum settling time at the 12-bit level. The DACs operate from a +2.7V to +5.25V analog supply and a separate +1.8V to +5.25V digital supply. The 20MHz 3-wire serial interface is compatible with SPI™, QSPI™, MICROWIRE™, and digital signal processor (DSP) protocol applications. Multiple devices can share a common serial interface in direct-access or daisy-chained configuration. The MAX5590–MAX5595 provide two multifunction, user-programmable, digital I/O ports. The externally selectable power-up states of the DAC outputs are either zero scale, midscale, or full scale. Software-selectable FAST and SLOW settling modes decrease settling time in FAST mode, or reduce supply current in SLOW mode.

The MAX5590/MAX5591 are 12-bit DACs, the MAX5592/MAX5593 are 10-bit DACs, and the MAX5594/MAX5595 are 8-bit DACs. The MAX5590/MAX5592/MAX5594 provide unity-gain-configured output buffers, while the MAX5591/MAX5593/MAX5595 provide force-sense-configured output buffers. The MAX5590–MAX5595 are specified over the extended -40°C to +85°C temperature range, and are available in space-saving 24-pin and 28-pin TSSOP packages.

Applications

Portable Instrumentation
Automatic Test Equipment (ATE)
Digital Offset and Gain Adjustment
Automatic Tuning
Programmable Voltage and Current Sources
Programmable Attenuators
Industrial Process Controls
Motion Control
Microprocessor (µP)-Controlled Systems
Power Amplifier Control
Fast Parallel-DAC to Serial-DAC Upgrades

Features

- **Octal, 12/10/8-Bit Serial DACs in TSSOP Packages**
- **3µs (max) 12-Bit Settling Time to 1/2 LSB**
- **Integral Nonlinearity:**
  - **1 LSB (max) MAX5590/MAX5591 A-Grade (12-Bit)**
  - **1 LSB (max) MAX5592/MAX5593 (10-Bit)**
  - **1/2 LSB (max) MAX5594/MAX5595 (8-Bit)**
- **Guaranteed Monotonic, ±1 LSB (max) DNL**
- **Two User-Programmable Digital I/O Ports**
- **Single +2.7V to +5.25V Analog Supply**
- **+1.8V to AV_{DD} Digital Supply**
- **20MHz, 3-Wire, SPI-/QSPI-/MICROWIRE-/DSP-Compatible Serial Interface**
- **Glitch-Free Outputs Power Up to Zero Scale, Midscale, or Full Scale Controlled by PU Pin**
- **Unity-Gain or Force-Sense-Configured Output Buffers**

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX5590AEUG*	-40°C to +85°C	24 TSSOP
MAX5590BEUG	-40°C to +85°C	24 TSSOP
MAX5591AEUI*	-40°C to +85°C	28 TSSOP
MAX5591BEUI	-40°C to +85°C	28 TSSOP
MAX5592EUG	-40°C to +85°C	24 TSSOP
MAX5593EUI	-40°C to +85°C	28 TSSOP
MAX5594EUG	-40°C to +85°C	24 TSSOP
MAX5595EUI	-40°C to +85°C	28 TSSOP

**Future product—contact factory for availability. Specifications are preliminary.*

Selector Guide and Pin Configurations appear at end of data sheet.

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MICROWIRE is a trademark of National Semiconductor Corp.

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ABSOLUTE MAXIMUM RATINGS

AV_{DD} to DV_{DD} .....±6V
AGND to DGND .....±0.3V
AV_{DD} to AGND, DGND.....-0.3V to +6V
DV_{DD} to AGND, DGND .....-0.3V to +6V
FB_, OUT_,
REF to AGND .....-0.3V to the lower of (AV_{DD} + 0.3V) or +6V
SCLK, DIN, $\overline{CS}$, PU,
$\overline{DSP}$ to DGND .....-0.3V to the lower of (DV_{DD} + 0.3V) or +6V
UPIO1, UPIO2
to DGND .....-0.3V to the lower of (DV_{DD} + 0.3V) or +6V
Maximum Current into Any Pin .....±50mA
Continuous Power Dissipation (T_A = +70°C)
24-Pin TSSOP (derate 12.2mW/°C above +70°C) 976mW
28-Pin TSSOP (derate 12.8mW/°C above +70°C) 1026mW
Operating Temperature Range .....-40°C to +85°C
Storage Temperature Range .....-65°C to +150°C
Maximum Junction Temperature .....+150°C
Lead Temperature (soldering, 10s) .....+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(AV_{DD} = 2.7V to 5.25V, DV_{DD} = 1.8V to AV_{DD}, AGND = 0, DGND = 0, V_{REF} = 2.5V (for AV_{DD} = 2.7V to 5.25V), V_{REF} = 4.096V (for AV_{DD} = 4.5V to 5.25V), R_L = 10kΩ, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
STATIC ACCURACY							
Resolution	N	MAX5590/MAX5591		12			Bits
		MAX5592/MAX5593		10			
		MAX5594/MAX5595		8			
Integral Nonlinearity	INL	V_{REF} = 2.5V at AV_{DD} = 2.7V and V_{REF} = 4.096V at AV_{DD} = 5.25V (Note 2)	MAX5590A/MAX5591A (12-bit)			±1	LSB
			MAX5590B/MAX5591B (12-bit)		±2	±4	
			MAX5592/MAX5593 (10-bit)		±0.5	±1	
			MAX5594/MAX5595 (8-bit)		±0.125	±0.5	
Differential Nonlinearity	DNL	Guaranteed monotonic (Note 2)				±1	LSB
Offset Error	V_{OS}	MAX5590A/MAX5591A (12-bit), decimal code = 40				±5	mV
		MAX5590B/MAX5591B (12-bit), decimal code = 40			±5	±25	
		MAX5592/MAX5593 (10-bit), decimal code = 10			±5	±25	
		MAX5594/MAX5595 (8-bit), decimal code = 3			±5	±25	
Offset-Error Drift					5		ppm of FS/°C
Gain Error	GE	Full-scale output	MAX5590A/MAX5591A (12-bit)			±4	LSB
			MAX5590B/MAX5590B (12-bit)		±20	±40	
			MAX5592/MAX5593 (10-bit)		±5	±10	
			MAX5594/MAX5595 (8-bit)		±2	±3	
Gain-Error Drift					1		ppm of FS/°C

ELECTRICAL CHARACTERISTICS (continued)

(AV_{DD} = 2.7V to 5.25V, DV_{DD} = 1.8V to AV_{DD}, AGND = 0, DGND = 0, V_{REF} = 2.5V (for AV_{DD} = 2.7V to 5.25V), V_{REF} = 4.096V (for AV_{DD} = 4.5V to 5.25V), R_L = 10kΩ, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Power-Supply Rejection Ratio	PSRR	Full-scale output, AV_{DD} = 2.7V to 5.25V			200		µV/V
REFERENCE INPUT							
Reference Input Range	V_{REF}			0.25		AV_{DD}	V
Reference Input Resistance	R_{REF}	Normal operation (no code dependence)		145	200		kΩ
Reference Leakage Current		Shutdown mode			0.5	1	µA
DAC OUTPUT CHARACTERISTICS							
Output Voltage Noise		SLOW mode, full scale	Unity gain		85		$µV_{RMS}$
			Force sense		67		
		FAST mode, full scale	Unity gain		140		
			Force sense		110		
Output Voltage Range (Note 3)		Unity-gain output		0		AV_{DD}	V
		Force-sense output		0		AV_{DD} / 2	
DC Output Impedance					38		Ω
Short-Circuit Current		AV_{DD} = 5V, OUT_ to AGND, full scale, FAST mode			57		mA
		AV_{DD} = 3V, OUT_ to AGND, full scale, FAST mode			45		
Power-Up Time		From V_{DD} applied until interface is functional			30	60	µs
Wake-Up Time		Coming out of shutdown, outputs settled			40		µs
Output OUT_ and FB_ Open-Circuit Leakage Current		Programmed in shutdown mode, force-sense outputs only			0.01		µA
DIGITAL OUTPUTS (UPIO_)							
Output High Voltage	V_{OH}	I_{SOURCE} = 2mA		DV_{DD} - 0.5			V
Output Low Voltage	V_{OL}	I_{SINK} = 2mA				0.4	V
DIGITAL INPUTS (SCLK, $\overline{CS}$, DIN, $\overline{DSP}$, UPIO_)							
Input High Voltage	V_{IH}	DV_{DD} ≥ 2.7V		2.4			V
		DV_{DD} < 2.7V		0.7 x DV_{DD}			
Input Low Voltage	V_{IL}	DV_{DD} > 3.6V				0.8	V
		2.7V ≤ DV_{DD} ≤ 3.6V				0.6	
		DV_{DD} < 2.7V				0.2	
Input Leakage Current	I_{IN}				±0.1	±1	µA
Input Capacitance	C_{IN}				10		pF

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ELECTRICAL CHARACTERISTICS (continued)

(AV_{DD} = 2.7V to 5.25V, DV_{DD} = 1.8V to AV_{DD}, AGND = 0, DGND = 0, V_{REF} = 2.5V (for AV_{DD} = 2.7V to 5.25V), V_{REF} = 4.096V (for AV_{DD} = 4.5V to 5.25V), R_L = 10kΩ, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
PU INPUT							
Input High Voltage	V_{IH-PU}			DV_{DD} - 200mV			V
Input Low Voltage	V_{IL-PU}					200	mV
Input Leakage Current	I_{IN-PU}	PU still considered floating when connected to a tri-state bus				±200	nA
DYNAMIC PERFORMANCE							
Voltage-Output Slew Rate	SR	FAST mode			3.6		V/µs
		SLOW mode			1.6		
Voltage-Output Settling Time (Note 5)		FAST mode	MAX5590/MAX5591 from code 322 to code 4095 to 1/2 LSB		2	3	µs
			MAX5592/MAX5593 from code 10 to code 1023 to 1/2 LSB		1.5	3	
			MAX5594/MAX5595 from code 3 to code 255 to 1/2 LSB		1	2	
		SLOW mode	MAX5590/MAX5591 from code 322 to code 4095 to 1/2 LSB		3	6	
			MAX5592/MAX5593 from code 10 to code 1023 1/2 LSB		2.5	6	
			MAX5594/MAX5595 from code 3 to code 255 to 1/2 LSB		2	4	
FB_ Input Voltage				0		V_{REF} / 2	V
FB_ Input Current						0.1	µA
Reference -3dB Bandwidth (Note 6)		Unity gain			200		kHz
		Force sense			150		
Digital Feedthrough		$\overline{CS}$ = DV_{DD}, code = zero scale, any digital input from 0 to DV_{DD} and DV_{DD} to 0, f = 100kHz			0.1		nV-s
Digital-to-Analog Glitch Impulse		Major carry transition			2		nV-s
DAC-to-DAC Crosstalk		(Note 4)			15		nV-s

ELECTRICAL CHARACTERISTICS (continued)

(AV_{DD} = 2.7V to 5.25V, DV_{DD} = 1.8V to AV_{DD}, AGND = 0, DGND = 0, V_{REF} = 2.5V (for AV_{DD} = 2.7V to 5.25V), V_{REF} = 4.096V (for AV_{DD} = 4.5V to 5.25V), R_L = 10kΩ, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
POWER REQUIREMENTS							
Analog Supply Voltage Range	AV_{DD}			2.70		5.25	V
Digital Supply Voltage Range	DV_{DD}			1.8		AV_{DD}	V
Operating Supply Current	I_{AVDD} + I_{DVDD}	SLOW mode, all digital inputs at DGND or DV_{DD}, no load, V_{REF} = 4.096V	Unity gain		1.5	3.2	mA
			Force sense		2.4	4.8	
		FAST mode, all digital inputs at DGND or DV_{DD}, no load, V_{REF} = 4.096V	Unity gain		2.5	8	
			Force sense		3.4	8	
Shutdown Supply Current	$I_{AVDD(SHDN)}$ + $I_{DVDD(SHDN)}$	No clocks, all digital inputs at DGND or DV_{DD}, all DACs in shutdown mode			0.5	1	µA

Note 1: For the force-sense versions, FB_ is connected to its respective OUT_. V_{OUT} (max) = V_{REF} / 2, unless otherwise noted.

Note 2: Linearity guaranteed from decimal code 40 to code 4095 for the MAX5590B/MAX5591B (12-bit, B-grade), code 10 to code 1023 for the MAX5592/MAX5593 (10-bit), and code 3 to code 255 for the MAX5594/MAX5595 (8-bit).

Note 3: Represents the functional range. The linearity is guaranteed at V_{REF} = 2.5V (for AV_{DD} from 2.7V to 5.25V), and V_{REF} = 4.096V (for AV_{DD} = 4.5V to 5.25V). See the *Typical Operating Characteristics* section for linearity at other voltages.

Note 4: DC crosstalk is measured as follows: outputs of DACA–DACH are set to full scale and the output of DACH is measured. While keeping DACH unchanged, the outputs of DACA–DACG are transitioned to zero scale and the ΔV_{OUT} of DACH is measured.

Note 5: Guaranteed by design.

Note 6: The reference -3dB bandwidth is measured with a $0.1V_{P-P}$ sine wave on V_{REF} and with full-scale input code.

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

TIMING CHARACTERISTICS—DSP Mode Disabled (3V, 3.3V, 5V Logic) (Figure 1)

(DV_{DD} = 2.7V to 5.25V, GND = 0, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Frequency	f_{SCLK}	2.7V < DV_{DD} < 5.25V			20	MHz
SCLK Pulse-Width High	t_{CH}	(Note 7)	20			ns
SCLK Pulse-Width Low	t_{CL}	(Note 7)	20			ns
$\overline{CS}$ Fall to SCLK Rise Setup Time	t_{CSS}		10			ns
SCLK Rise to $\overline{CS}$ Rise Hold Time	t_{CSH}		5			ns
SCLK Rise to $\overline{CS}$ Fall Setup	t_{CS0}		10			ns
DIN to SCLK Rise Setup Time	t_{DS}		12			ns
DIN to SCLK Rise Hold Time	t_{DH}		5			ns
SCLK Rise to DOUTDC1 Valid Propagation Delay	t_{DO1}	C_L = 20pF, UPIO_ = DOUTDC1 mode			30	ns
SCLK Fall to DOUT_ Valid Propagation Delay	t_{DO2}	C_L = 20pF, UPIO_ = DOUTDC0 or DOUTRB mode			30	ns
$\overline{CS}$ Rise to SCLK Rise Hold Time	t_{CS1}	MICROWIRE and SPI modes 0 and 3	10			ns
$\overline{CS}$ Pulse-Width High	t_{CSW}		45			ns
UPIO_ TIMING CHARACTERISTICS						
DOUT Tri-State Time when Exiting DOUTDC0, DOUTDC1, and UPIO Modes	t_{DOZ}	C_L = 20pF, from end of write cycle to UPIO_ in high impedance			100	ns
DOUTRB Tri-State Time from $\overline{CS}$ Rise	t_{DRBZ}	C_L = 20pF, from rising edge of $\overline{CS}$ to UPIO_ in high impedance			20	ns
DOUTRB Tri-State Enable Time from 8th SCLK Rise	t_{ZEN}	C_L = 20pF, from 8th rising edge of SCLK to UPIO_ driven out of tri-state			20	ns
$\overline{LDAC}$ Pulse-Width Low	t_{LDL}	Figure 5	20			ns
$\overline{LDAC}$ Effective Delay	t_{LDS}	Figure 6	100			ns
$\overline{CLR}$, $\overline{MID}$, $\overline{SET}$ Pulse-Width Low	t_{CMS}	Figure 5	20			ns
GPO Output Settling Time	t_{GP}	Figure 6			100	ns
GPO Output High-Impedance Time	t_{GPZ}				100	ns

TIMING CHARACTERISTICS—DSP Mode Disabled (1.8V Logic) (Figure 1)

(DV_{DD} = 1.8V to 5.25V, GND = 0, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Frequency	f_{SCLK}	1.8V < DV_{DD} < 5.25V			10	MHz
SCLK Pulse-Width High	t_{CH}	(Note 7)	40			ns
SCLK Pulse-Width Low	t_{CL}	(Note 7)	40			ns
$\overline{CS}$ Fall to SCLK Rise Setup Time	t_{CSS}		20			ns
SCLK Rise to $\overline{CS}$ Rise Hold Time	t_{CSH}		0			ns
SCLK Rise to $\overline{CS}$ Fall Setup	t_{CS0}		10			ns
DIN to SCLK Rise Setup Time	t_{DS}		20			ns
DIN to SCLK Rise Hold Time	t_{DH}		5			ns
SCLK Rise to DOUTDC1 Valid Propagation Delay	t_{DO1}	C_L = 20pF, UPIO_ = DOUTDC1 mode			60	ns
SCLK Fall to DOUT_ Valid Propagation Delay	t_{DO2}	C_L = 20pF, UPIO_ = DOUTDC0 or DOUTRB mode			60	ns
$\overline{CS}$ Rise to SCLK Rise Hold Time	t_{CS1}	MICROWIRE and SPI modes 0 and 3	20			ns
$\overline{CS}$ Pulse-Width High	t_{CSW}		90			ns
UPIO_ TIMING CHARACTERISTICS						
DOUT Tri-State Time when Exiting DOUTDC0, DOUTDC1, and UPIO Modes	t_{DOZ}	C_L = 20pF, from end of write cycle to UPIO_ in high impedance			200	ns
DOUTRB Tri-State Time from $\overline{CS}$ Rise	t_{DRBZ}	C_L = 20pF, from rising edge of $\overline{CS}$ to UPIO_ in high impedance			40	ns
DOUTRB Tri-State Enable Time from 8th SCLK Rise	t_{ZEN}	C_L = 20pF, from 8th rising edge of SCLK to UPIO_ driven out of tri-state			40	ns
$\overline{LDAC}$ Pulse-Width Low	t_{LDL}	Figure 5	40			ns
$\overline{LDAC}$ Effective Delay	t_{LDS}	Figure 6	200			ns
$\overline{CLR}$, $\overline{MID}$, $\overline{SET}$ Pulse-Width Low	t_{CMS}	Figure 5	40			ns
GPO Output Settling Time	t_{GP}	Figure 6			200	ns
GPO Output High-Impedance Time	t_{GPZ}				200	ns

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

TIMING CHARACTERISTICS—DSP Mode Enabled (3V, 3.3V, 5V Logic) (Figure 2)

(DV_{DD} = 2.7V to 5.25V, GND = 0, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Frequency	f_{SCLK}	2.7V < DV_{DD} < 5.25V			20	MHz
SCLK Pulse-Width High	t_{CH}	(Note 7)	20			ns
SCLK Pulse-Width Low	t_{CL}	(Note 7)	20			ns
$\overline{CS}$ Fall to SCLK Fall Setup Time	t_{CSS}		10			ns
$\overline{DSP}$ Fall to SCLK Fall Setup Time	t_{DSS}		10			ns
SCLK Fall to $\overline{CS}$ Rise Hold Time	t_{CSH}		5			ns
SCLK Fall to $\overline{CS}$ Fall Delay	t_{CS0}		10			ns
SCLK Fall to $\overline{DSP}$ Fall Delay	t_{DS0}		10			ns
DIN to SCLK Fall Setup Time	t_{DS}		12			ns
DIN to SCLK Fall Hold Time	t_{DH}		5			ns
SCLK Rise to DOUT_ Valid Propagation Delay	t_{DO1}	C_L = 20pF, UPIO_ = DOUTDC1 or DOUTRB mode			30	ns
SCLK Fall to DOUT_ Valid Propagation Delay	t_{DO2}	C_L = 20pF, UPIO_ = DOUTDC0 mode			30	ns
$\overline{CS}$ Rise to SCLK Fall Hold Time	t_{CS1}	MICROWIRE and SPI modes 0 and 3	10			ns
$\overline{CS}$ Pulse-Width High	t_{CSW}		45			ns
$\overline{DSP}$ Pulse-Width High	t_{DSW}		20			ns
$\overline{DSP}$ Pulse-Width Low	t_{DSPWL}	(Note 8)	20			ns
UPIO_ TIMING CHARACTERISTICS						
DOUT Tri-State Time when Exiting DOUTDC0, DOUTDC1, and UPIO Modes	t_{DOZ}	C_L = 20pF, from end of write cycle to UPIO_ in high impedance			100	ns
DOUTRB Tri-State Time from $\overline{CS}$ Rise	t_{DRBZ}	C_L = 20pF, from rising edge of $\overline{CS}$ to UPIO_ in high impedance			20	ns
DOUTRB Tri-State Enable Time from 8th SCLK Fall	t_{ZEN}	C_L = 20pF, from 8th falling edge of SCLK to UPIO_ driven out of tri-state			20	ns
$\overline{LDAC}$ Pulse-Width Low	t_{LDL}	Figure 5	20			ns
$\overline{LDAC}$ Effective Delay	t_{LDS}	Figure 6	100			ns
$\overline{CLR}$, $\overline{MID}$, $\overline{SET}$ Pulse-Width Low	t_{CMS}	Figure 5	20			ns
GPO Output Settling Time	t_{GP}	Figure 6			100	ns
GPO Output High-Impedance Time	t_{GPZ}				100	ns

TIMING CHARACTERISTICS—DSP Mode Enabled (1.8V Logic) (Figure 2)

(DV_{DD} = 1.8V to 5.25V, GND = 0, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Frequency	f_{SCLK}	1.8V < DV_{DD} < 5.25V			10	MHz
SCLK Pulse-Width High	t_{CH}	(Note 7)	40			ns
SCLK Pulse-Width Low	t_{CL}	(Note 7)	40			ns
$\overline{CS}$ Fall to SCLK Fall Setup Time	t_{CSS}		20			ns
$\overline{DSP}$ Fall to SCLK Fall Setup Time	t_{DSS}		20			ns
SCLK Fall to $\overline{CS}$ Rise Hold Time	t_{CSH}		0			ns
SCLK Fall to $\overline{CS}$ Fall Delay	t_{CS0}		10			ns
SCLK Fall to $\overline{DSP}$ Fall Delay	t_{DS0}		15			ns
DIN to SCLK Fall Setup Time	t_{DS}		20			ns
DIN to SCLK Fall Hold Time	t_{DH}		5			ns
SCLK Rise to DOUT_ Valid Propagation Delay	t_{DO1}	C_L = 20pF, UPIO_ = DOUTDC1 or DOUTRB mode			60	ns
SCLK Fall to DOUT_ Valid Propagation Delay	t_{DO2}	C_L = 20pF, UPIO_ = DOUTDC0 mode			60	ns
$\overline{CS}$ Rise to SCLK Fall Hold Time	t_{CS1}	MICROWIRE and SPI modes 0 and 3	20			ns
$\overline{CS}$ Pulse-Width High	t_{CSW}		90			ns
$\overline{DSP}$ Pulse-Width High	t_{DSW}		40			ns
$\overline{DSP}$ Pulse-Width Low	t_{DSPWL}	(Note 8)	40			ns
UPIO_ TIMING CHARACTERISTICS						
DOUT Tri-State Time when Exiting DOUTDC0, DOUTDC1, and UPIO Modes	t_{DOZ}	C_L = 20pF, from end of write cycle to UPIO_ in high impedance			200	ns
DOUTRB Tri-State Time from $\overline{CS}$ Rise	t_{DRBZ}	C_L = 20pF, from rising edge of $\overline{CS}$ to UPIO_ in high impedance			40	ns
DOUTRB Tri-State Enable Time from 8th SCLK Fall	t_{ZEN}	C_L = 20pF, from 8th falling edge of SCLK to UPIO_ driven out of tri-state			40	ns
$\overline{LDAC}$ Pulse-Width Low	t_{LDL}	Figure 5	40			ns
$\overline{LDAC}$ Effective Delay	t_{LDS}	Figure 6	200			ns
$\overline{CLR}$, $\overline{MID}$, $\overline{SET}$ Pulse-Width Low	t_{CMS}	Figure 5	40			ns
GPO Output Settling Time	t_{GP}	Figure 6			200	ns
GPO Output High-Impedance Time	t_{GPZ}				200	ns

Note 7: In some daisy-chain modes, data is required to be clocked in on one clock edge and the shifted data clocked out on the following edge. In the case of a 1/2 clock-period delay, it is necessary to increase the minimum high/low clock times to 25ns (2.7V) or 50ns (1.8V).

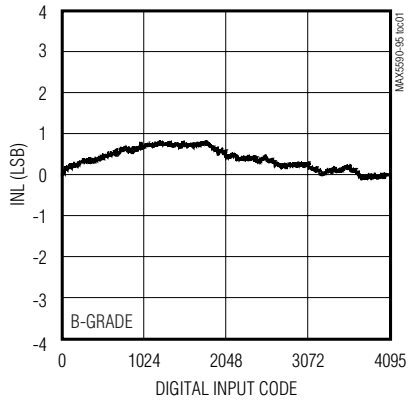
Note 8: The falling edge of $\overline{DSP}$ starts a DSP-type bus cycle, provided that $\overline{CS}$ is also active low to select the device. $\overline{DSP}$ active low and $\overline{CS}$ active low must overlap by a minimum of 10ns (2.7V) or 20ns (1.8V). $\overline{CS}$ can be permanently low in this mode of operation.

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

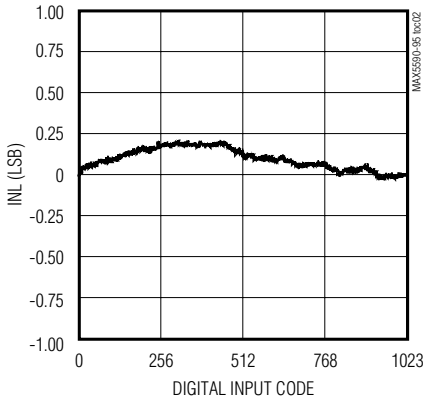
Typical Operating Characteristics

(AV_{DD} = DV_{DD} = 5V, V_{REF} = 4.096V, R_L = 10kΩ, C_L = 100pF, speed mode = FAST, PU = floating, T_A = +25°C, unless otherwise noted.)

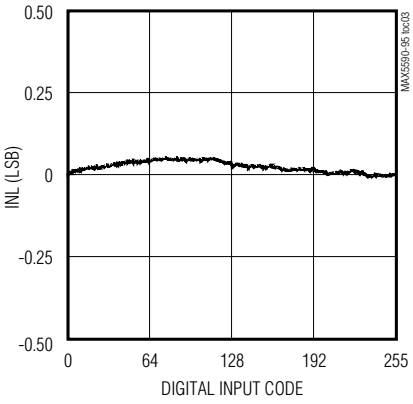
INTEGRAL NONLINEARITY vs. DIGITAL INPUT CODE (12-BIT)



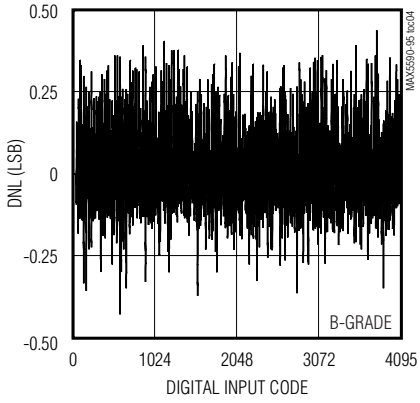
INTEGRAL NONLINEARITY vs. DIGITAL INPUT CODE (10-BIT)



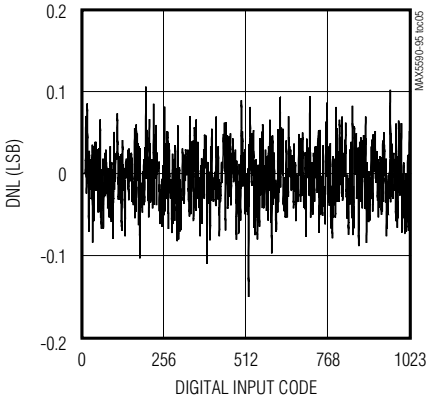
INTEGRAL NONLINEARITY vs. DIGITAL INPUT CODE (8-BIT)



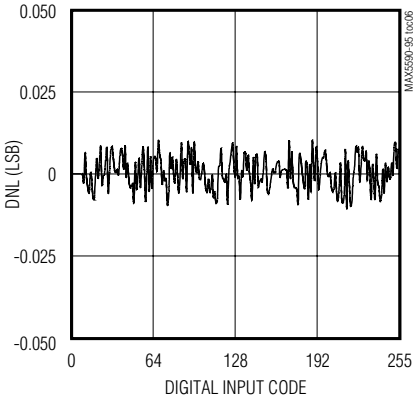
DIFFERENTIAL NONLINEARITY vs. DIGITAL INPUT CODE (12-BIT)



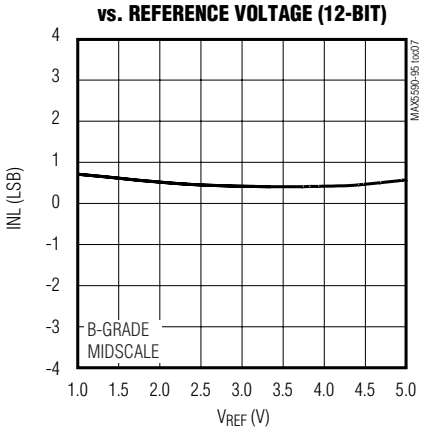
DIFFERENTIAL NONLINEARITY vs. DIGITAL INPUT CODE (10-BIT)



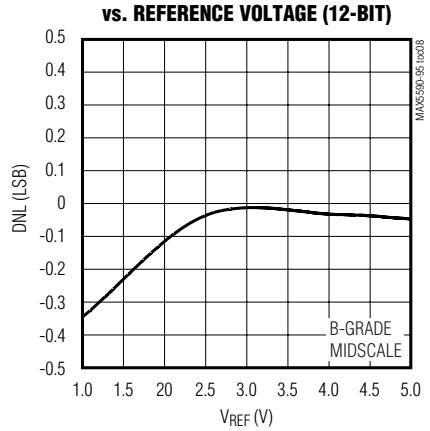
DIFFERENTIAL NONLINEARITY vs. DIGITAL INPUT CODE (8-BIT)



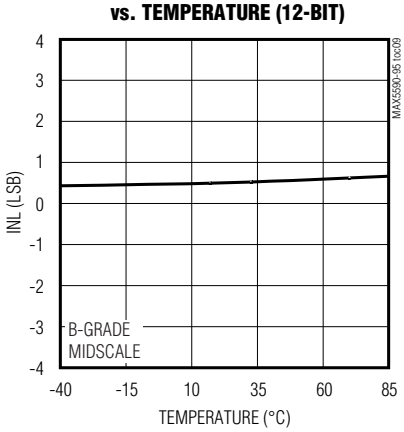
INTEGRAL NONLINEARITY vs. REFERENCE VOLTAGE (12-BIT)



DIFFERENTIAL NONLINEARITY vs. REFERENCE VOLTAGE (12-BIT)



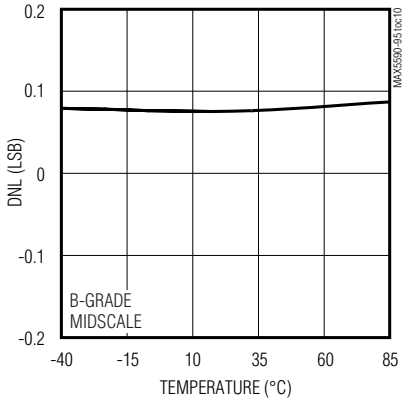
INTEGRAL NONLINEARITY vs. TEMPERATURE (12-BIT)



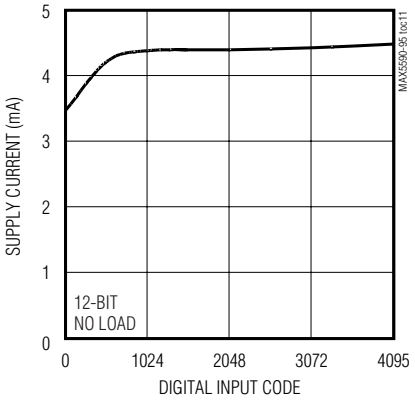
Typical Operating Characteristics (continued)

(AV_{DD} = DV_{DD} = 5V, V_{REF} = 4.096V, R_L = 10kΩ, C_L = 100pF, speed mode = FAST, PU = floating, T_A = +25°C, unless otherwise noted.)

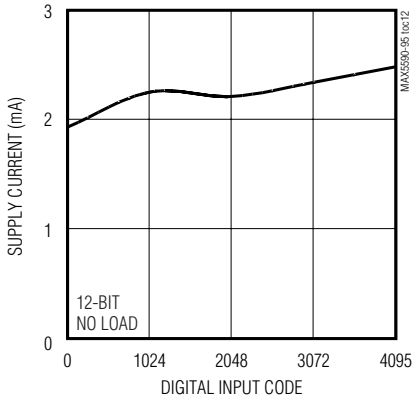
DIFFERENTIAL NONLINEARITY vs. TEMPERATURE (12-BIT)



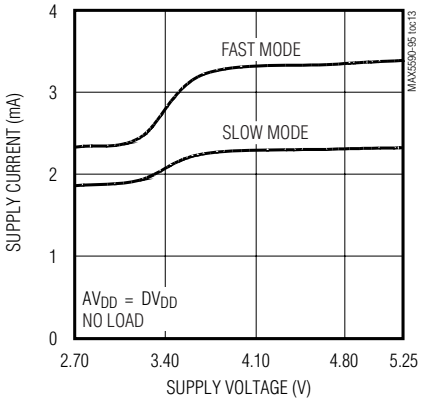
SUPPLY CURRENT vs. DIGITAL INPUT CODE (FORCE-SENSE)



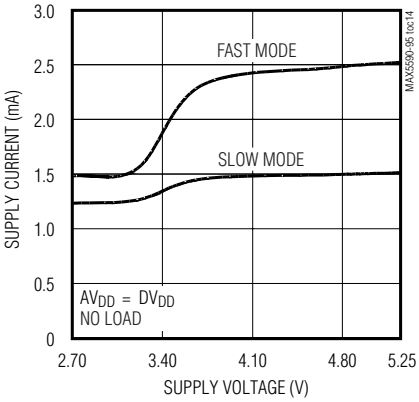
SUPPLY CURRENT vs. DIGITAL INPUT CODE (UNITY GAIN)



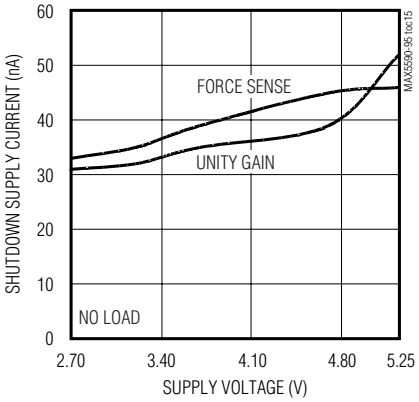
SUPPLY CURRENT vs. SUPPLY VOLTAGE (FORCE-SENSE)



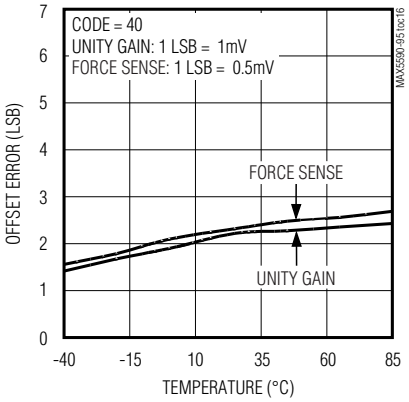
SUPPLY CURRENT vs. SUPPLY VOLTAGE (UNITY GAIN)



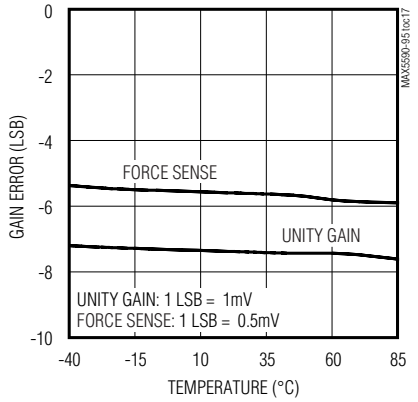
SHUTDOWN SUPPLY CURRENT vs. SUPPLY VOLTAGE



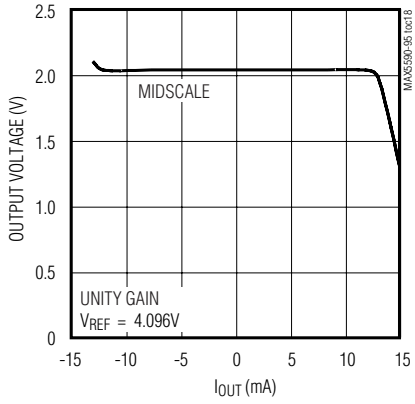
OFFSET ERROR vs. TEMPERATURE



GAIN ERROR vs. TEMPERATURE



OUTPUT VOLTAGE vs. OUTPUT SOURCE/SINK CURRENT

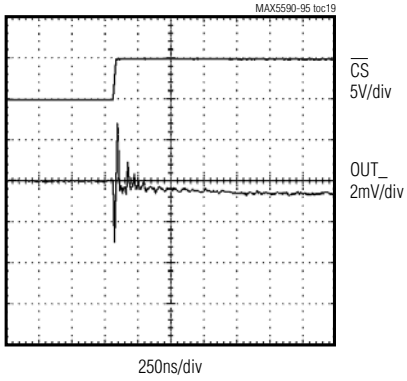


Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

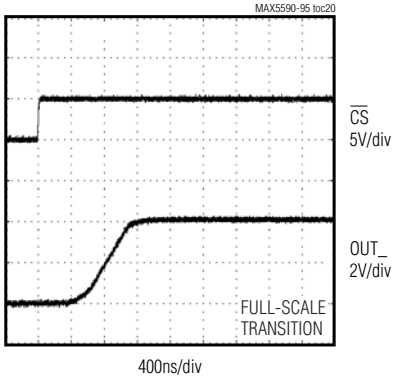
Typical Operating Characteristics (continued)

(AV_{DD} = DV_{DD} = 5V, V_{REF} = 4.096V, R_L = 10kΩ, C_L = 100pF, speed mode = FAST, PU = floating, T_A = +25°C, unless otherwise noted.)

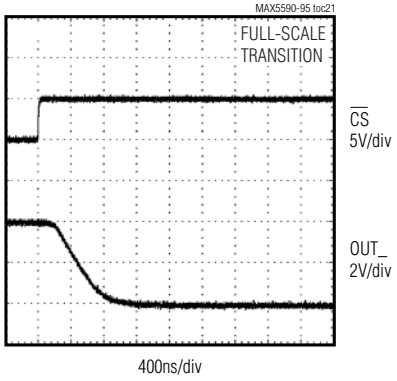
MAJOR-CARRY TRANSITION GLITCH



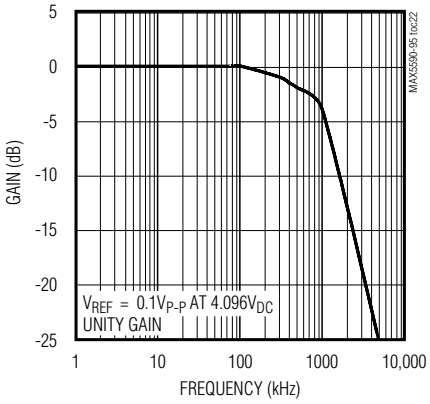
SETTLING TIME POSITIVE



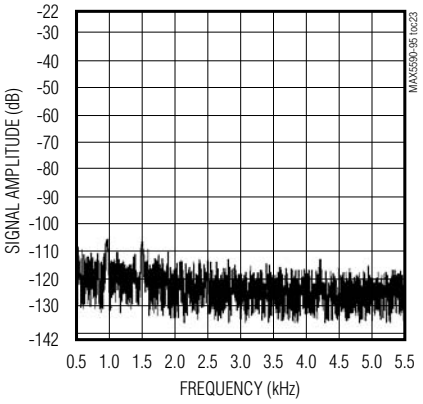
SETTLING TIME NEGATIVE



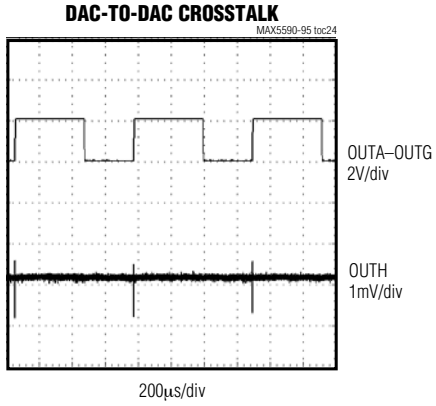
REFERENCE INPUT BANDWIDTH



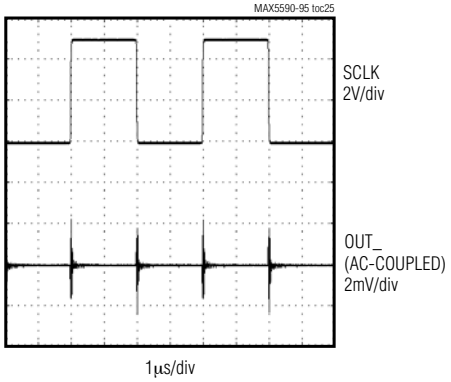
REFERENCE FEEDTHROUGH AT 1kHz



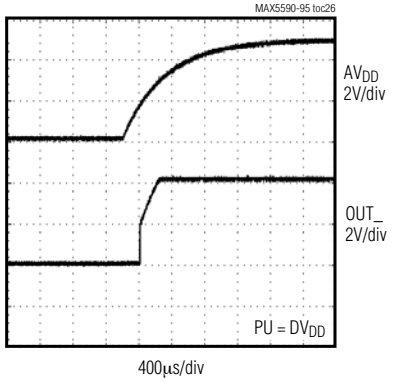
DAC-TO-DAC CROSSTALK



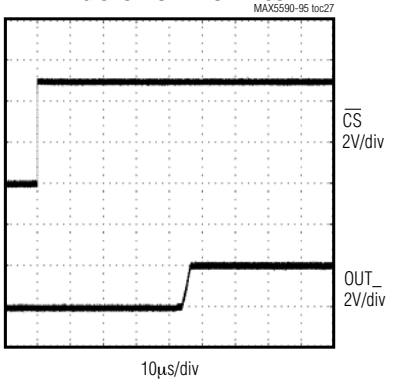
DIGITAL FEEDTHROUGH



POWER-UP GLITCH



EXITING SHUTDOWN TO MIDSCALE

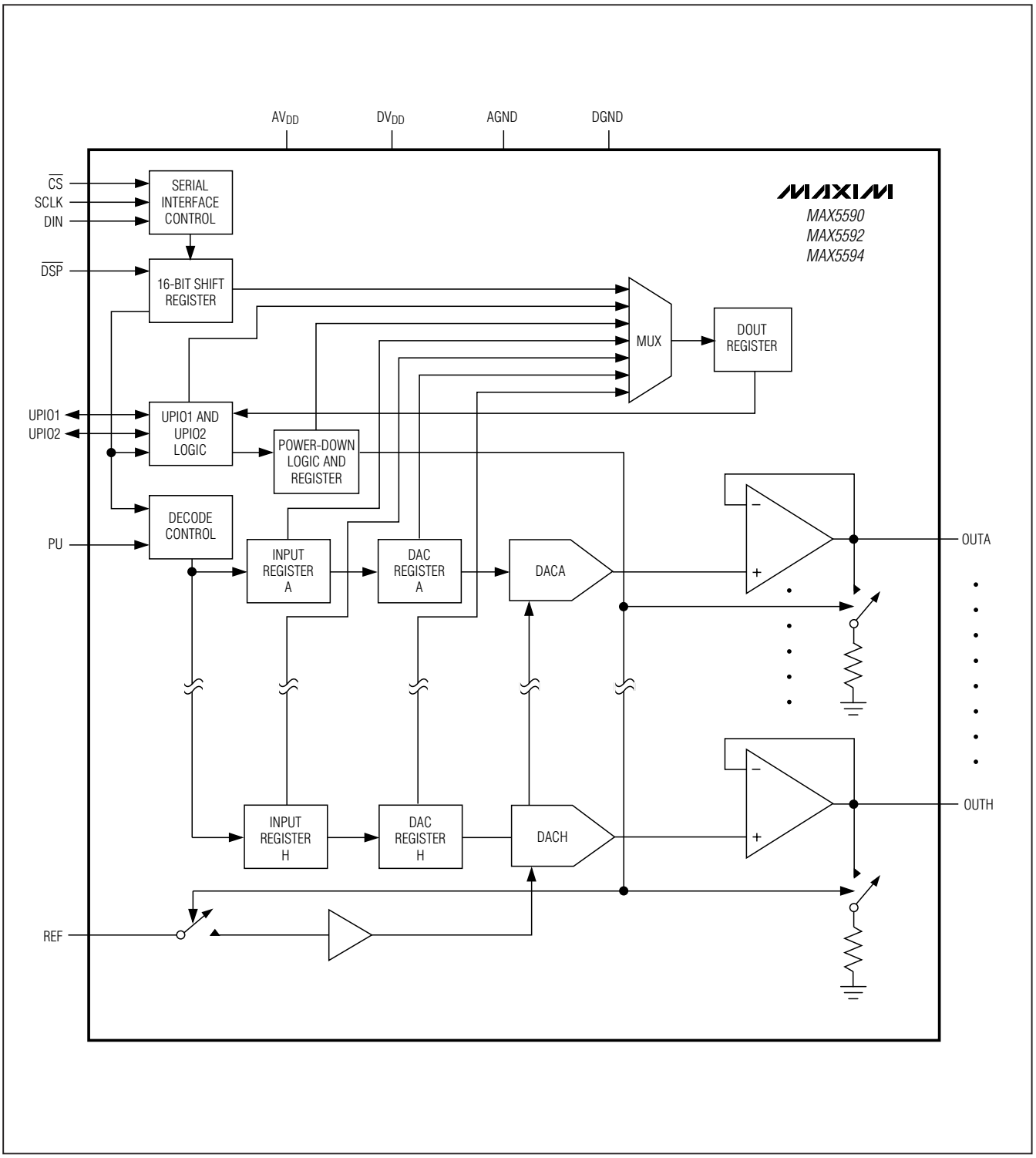


Pin Description

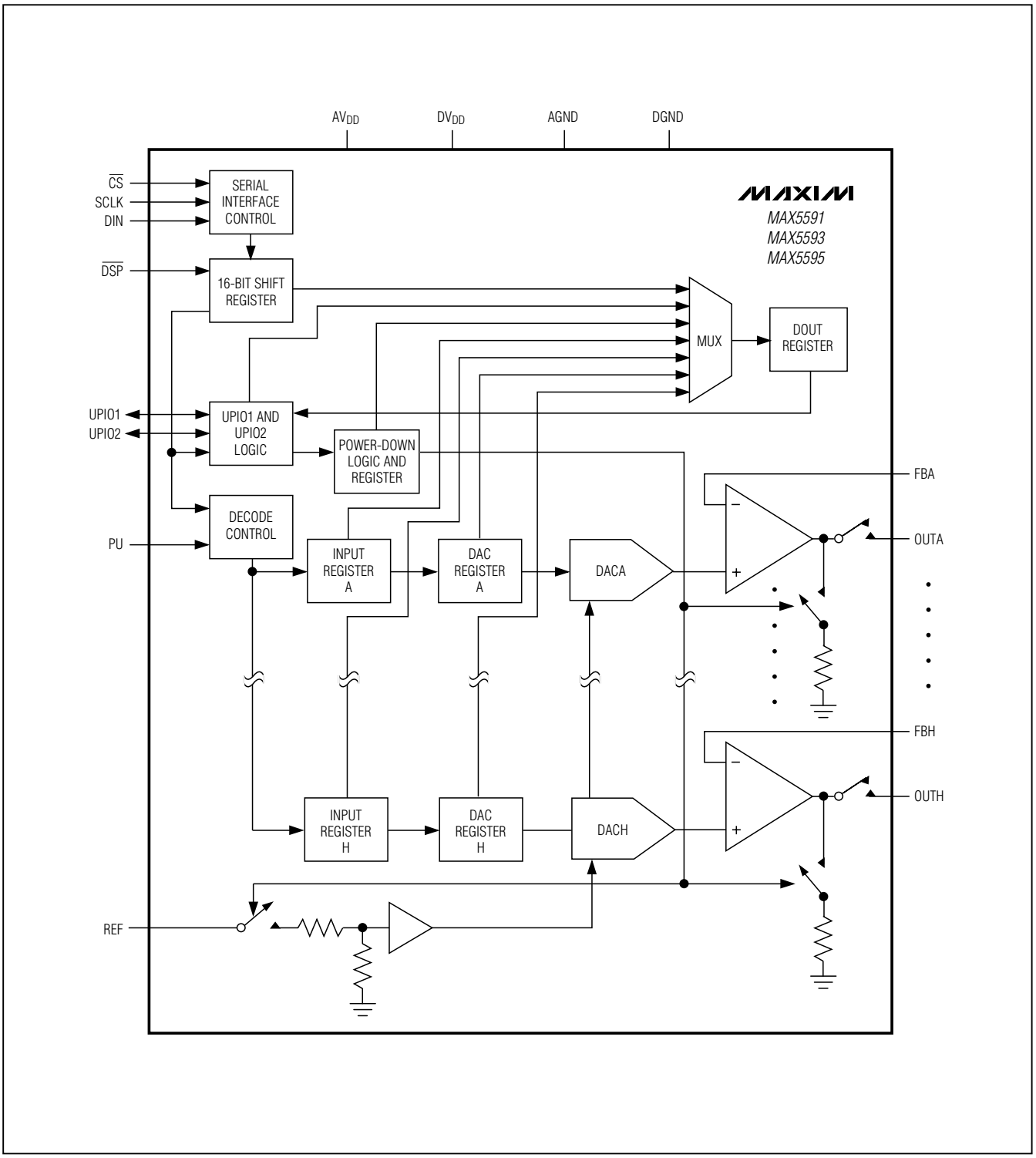
PIN		NAME	FUNCTION
MAX5590 MAX5592 MAX5594	MAX5591 MAX5593 MAX5595		
1	1	AV_{DD}	Analog Supply
2	2	AGND	Analog Ground
3	3	OUTA	DACA Output
4, 8, 17, 21	—	N.C.	No Connection. Not internally connected.
5	6	OUTB	DACB Output
6	7	OUTC	DACC Output
7	10	OUTD	DACD Output
9	11	$\overline{CS}$	Active-Low Chip-Select Input
10	12	SCLK	Serial Clock Input
11	13	DIN	Serial Data Input
12	14	$\overline{DSP}$	Clock Enable. Connect $\overline{DSP}$ to DV_{DD} at power-up to transfer data on the rising edge of SCLK. Connect $\overline{DSP}$ to GND to transfer data on the falling edge of SCLK. Connect $\overline{DSP}$ to DGND at power-up to transfer data on the falling edge of SCLK.
13	15	DV_{DD}	Digital Supply
14	16	DGND	Digital Ground
15	17	UPIO1	User-Programmable Input/Output 1
16	18	UPIO2	User-Programmable Input/Output 2
18	19	OUTE	DACE Output
19	22	OUTF	DACF Output
20	23	OUTG	DACG Output
22	26	OUTH	DACH Output
23	27	PU	Power-Up State Select Input. Connect PU to DV_{DD} to set OUTA–OUTH to full scale upon power-up. Connect PU to DGND to set OUTA–OUTH to zero upon power-up. Leave PU floating at power-up to set OUTA–OUTH to midscale.
24	28	REF	Reference Input
—	4	FBA	Feedback for DACA
—	5	FBB	Feedback for DACB
—	8	FBC	Feedback for DACC
—	9	FBD	Feedback for DACD
—	20	FBE	Feedback for DACE
—	21	FBF	Feedback for DACF
—	24	FBG	Feedback for DACG
—	25	FBH	Feedback for DACH

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

Functional Diagrams



Functional Diagrams (continued)



Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

Detailed Description

The MAX5590–MAX5595 octal, 12/10/8-bit, voltage-output DACs offer buffered outputs and a 3µs maximum settling time at the 12-bit level. The DACs operate from a single 2.7V to 5.25V analog supply and a separate 1.8V to AV_{DD} digital supply. The MAX5590–MAX5595 include an input register and DAC register for each channel and a 16-bit data-in/data-out shift register. The 3-wire serial interface is compatible with SPI, QSPI, MICROWIRE, and DSP applications. The MAX5590– MAX5595 provide two user-programmable digital I/O ports, which are programmed through the serial interface. The externally selectable power-up states of the DAC outputs are either zero scale, midscale, or full scale.

Reference Input

The reference input, REF, accepts both AC and DC values with a voltage range extending from analog ground (AGND) to AV_{DD}. The voltage at REF sets the full-scale output of the DACs. Determine the output voltage using the following equations:

Unity-gain versions:

$$V_{OUT\_} = (V_{REF} \times CODE) / 2^N$$

Force-sense versions (FB_ connected to OUT_):

$$V_{OUT} = 0.5 \times (V_{REF} \times CODE) / 2^N$$

where CODE is the numeric value of the DAC's binary input code and N is the bits of resolution. For the MAX5590/MAX5591, N = 12 and CODE ranges from 0 to 4095. For the MAX5592/MAX5593, N = 10 and CODE ranges from 0 to 1023. For the MAX5594/MAX5595, N = 8 and CODE ranges from 0 to 255.

Output Buffers

The DACA and DACH output-buffer amplifiers of the MAX5590–MAX5595 are unity-gain stable with rail-to-rail output voltage swings and a typical slew rate of 3.6V/µs (FAST mode). The MAX5590/MAX5592/MAX5594 provide unity-gain outputs, while the MAX5591/MAX5593/MAX5595 provide force-sense outputs. For the MAX5591/MAX5593/MAX5595, access to the output amplifier's inverting input provides flexibility in output gain setting and signal conditioning (see the *Applications Information* section).

The MAX5590–MAX5595 offer FAST and SLOW settling-time modes. In the SLOW mode, the settling time is 6µs (max), and the supply current is 3.2mA (max). In the FAST mode, the settling time is 3µs (max), and the supply current is 8mA (max). See the *Digital Interface* section for settling-time mode programming details.

Use the serial interface to set the shutdown output impedance of the amplifiers to 1kΩ or 100kΩ for the MAX5590/MAX5592/MAX5594 and 1kΩ or high impedance for the MAX5591/MAX5593/MAX5595. The DAC outputs can drive a 10kΩ (typ) load and are stable with up to 500pF (typ) of capacitive load.

Power-On Reset

At power-up, all DAC outputs power up to full scale, midscale, or zero scale, depending on the configuration of the PU input. Connect PU to DV_{DD} to set OUT_ to full scale upon power-up. Connect PU to digital ground (DGND) at power-up to set OUT_ to zero scale. Leave PU floating to set OUT_ to midscale.

Digital Interface

The MAX5590–MAX5595 use a 3-wire serial interface that is compatible with SPI, QSPI, MICROWIRE, and DSP protocol applications (Figures 1 and 2). Connect $\overline{DSP}$ to DV_{DD} before power-up to clock data in on the rising edge of SCLK. Connect $\overline{DSP}$ to DGND before power-up to clock data in on the falling edge of SCLK. After power-up, the device enters DSP frame-sync mode on the first rising edge of $\overline{DSP}$. Refer to the *MAX5590–MAX5595 Programmer's Handbook* for details.

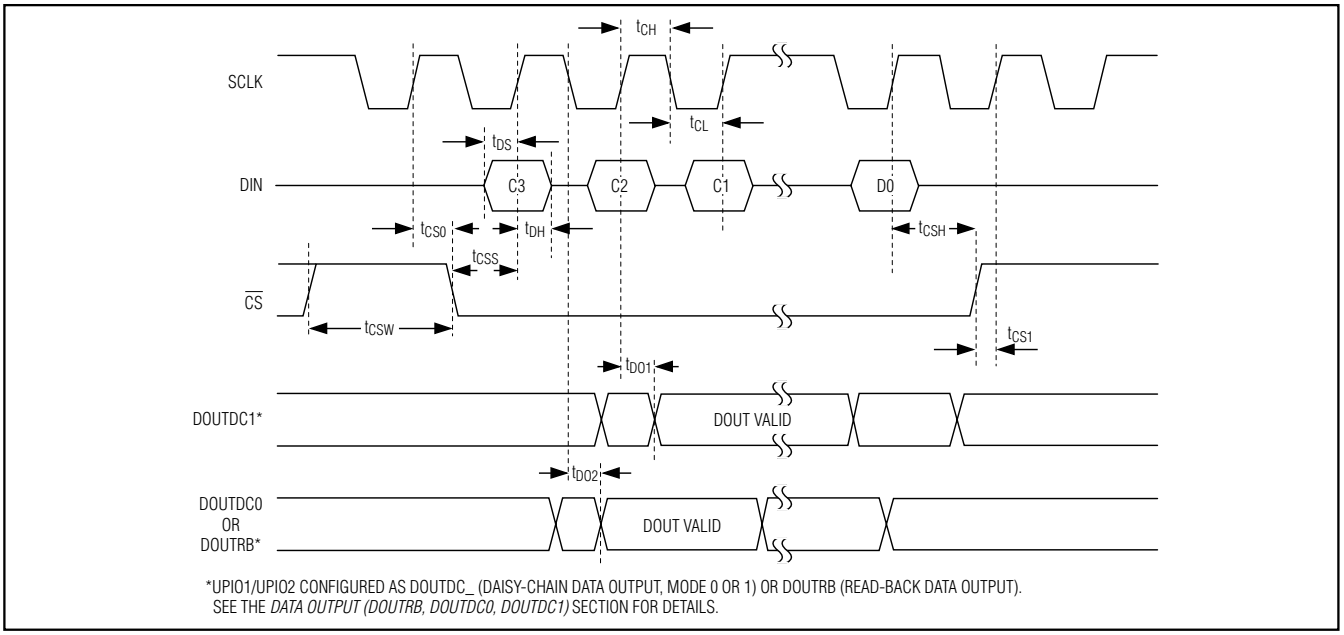
The MAX5590–MAX5595 include a 16-bit input shift register. The data is loaded into the input shift register through the serial interface. The 16 bits can be sent in two serial 8-bit packets or one 16-bit word ($\overline{CS}$ must remain low until all 16 bits are transferred). The data is loaded MSB first. For the MAX5590/MAX5591, the 16 bits consist of 4 control bits (C3–C0) and 12 data bits (D11–D0) (see Table 1). For the 10-bit MAX5592/MAX5593 devices, D11–D2 are the data bits and D1 and D0 are sub-bits. For the 8-bit MAX5594/MAX5595 devices, D11–D4 are the data bits and D3–D0 are sub-bits. Set all sub-bits to zero for optimum performance.

Each DAC channel includes two registers: an input register and the DAC register. At power-up, the DAC output is set according to the state of PU. The DACs are double-buffered, which allows any of the following for each channel:

- Loading the input register without updating the DAC register
- Updating the DAC register from the input register
- Updating the input and DAC registers simultaneously

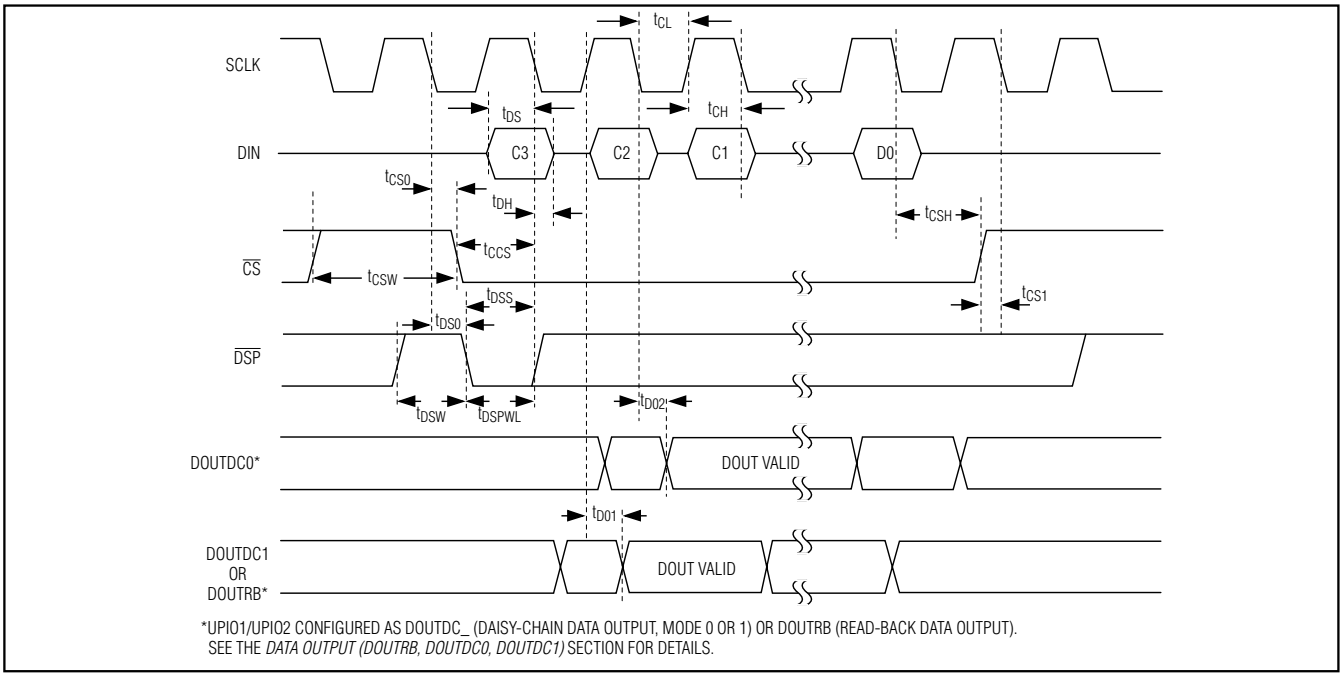
Table 1. Serial Write Data Format

MSB				16 BITS OF SERIAL DATA											LSB
CONTROL BITS				DATA BITS											
C3	C2	C1	C0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0



*UPIO1/UPIO2 CONFIGURED AS DOUTDC_ (DAISY-CHAIN DATA OUTPUT, MODE 0 OR 1) OR DOUTRB (READ-BACK DATA OUTPUT). SEE THE *DATA OUTPUT (DOUTRB, DOUTDC0, DOUTDC1)* SECTION FOR DETAILS.

Figure 1. Serial-Interface Timing Diagram (DSP Mode Disabled)



*UPIO1/UPIO2 CONFIGURED AS DOUTDC_ (DAISY-CHAIN DATA OUTPUT, MODE 0 OR 1) OR DOUTRB (READ-BACK DATA OUTPUT). SEE THE *DATA OUTPUT (DOUTRB, DOUTDC0, DOUTDC1)* SECTION FOR DETAILS.

Figure 2. Serial-Interface Timing Diagram (DSP Mode Enabled)

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

Serial-Interface Programming Commands

Tables 2a, 2b, and 2c provide all of the serial-interface programming commands for the MAX5590–MAX5595. Table 2a shows the basic DAC programming commands, Table 2b gives the advanced-feature programming commands, and Table 2c provides the 24-bit read commands. Figures 3 and 4 provide the serial-interface diagrams for read and write operations.

Loading Input and DAC Registers

The MAX5590–MAX5595 contain a 16-bit shift register that is followed by a 12-bit input register and a 12-bit DAC register for each channel (see the *Functional Diagrams*). Tables 3, 4, and 5 highlight a few of the commands that handle the loading of the input and DAC registers. See Table 2a for all DAC programming commands.

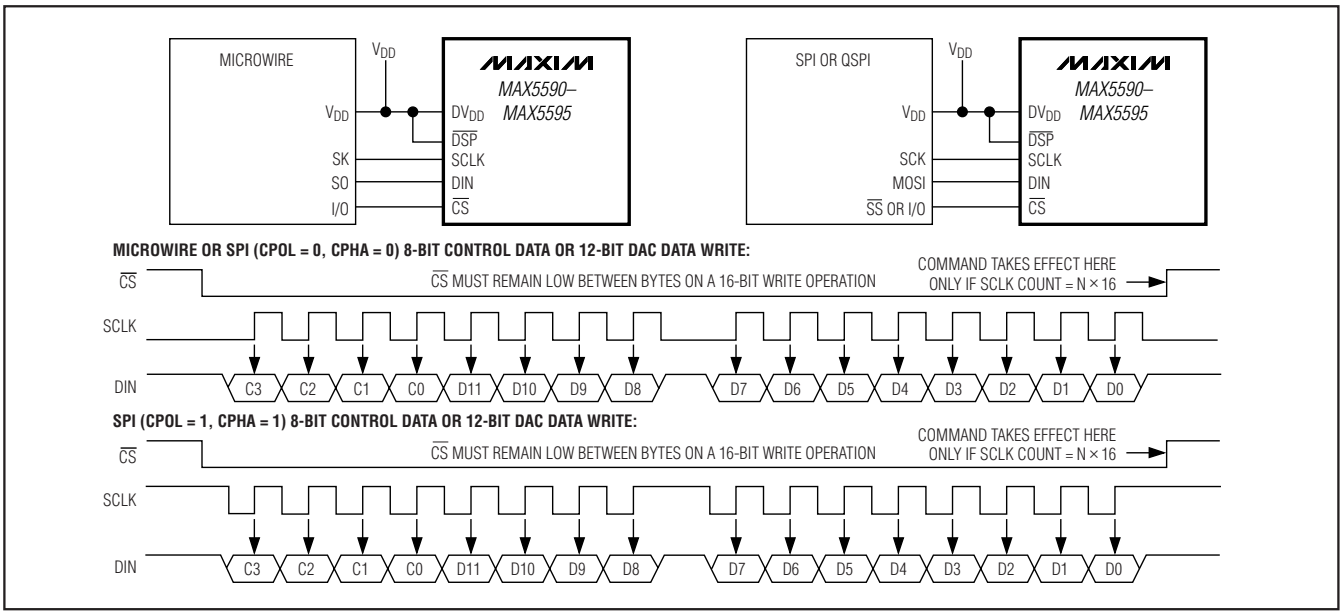


Figure 3. MICROWIRE and SPI Single DAC Writes (CPOL = 0, CPHA = 0 or CPOL = 1, CPHA = 1)

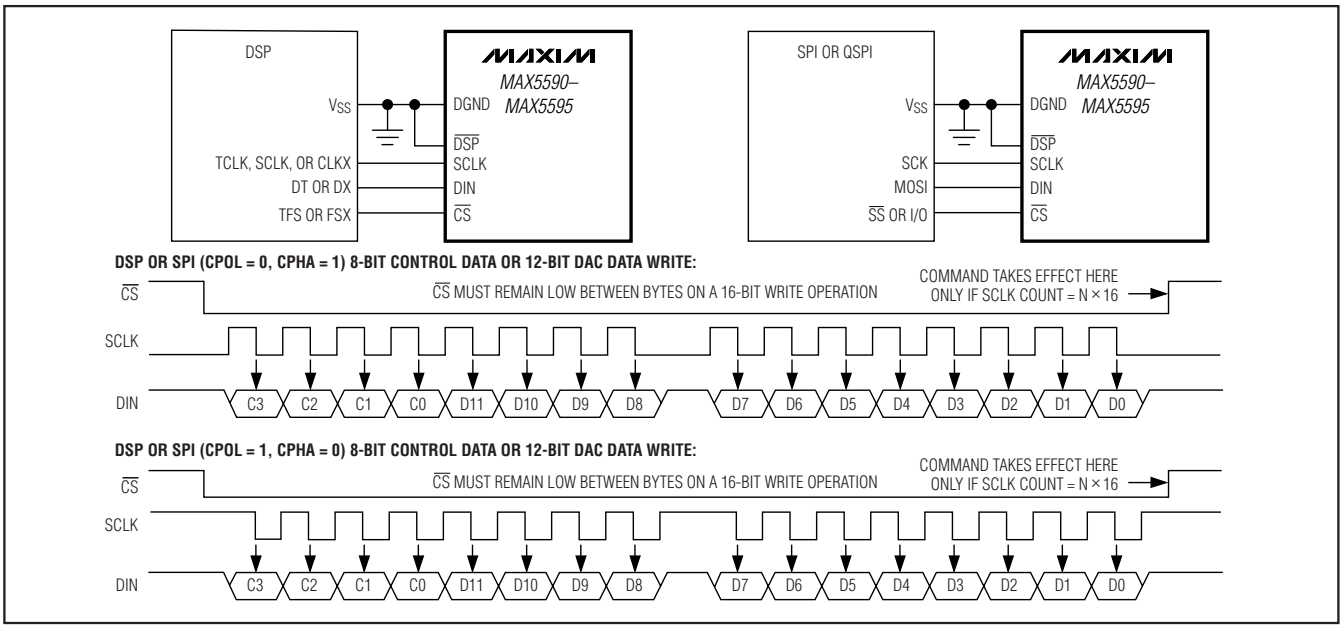


Figure 4. DSP and SPI Single DAC Writes (CPOL = 0, CPHA = 1 or CPOL = 1, CPHA = 0)

Table 2a. DAC Programming Commands

DATA	CONTROL BITS				DATA BITS												FUNCTION
	C3	C2	C1	C0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
INPUT REGISTERS (A–H)																	
DIN	0	0	0	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register A from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	0	0	1	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register B from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	0	1	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register C from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	0	1	1	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register D from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	1	0	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register E from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	1	0	1	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register F from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	1	1	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register G from shift register; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	0	1	1	1	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load input register H from shift register; DAC registers are unchanged. DAC outputs are unchanged.*

**For the MAX5592/MAX5593 (10-bit version), D11–D2 are the significant bits and D1 and D0 are sub-bits. For the MAX5594/MAX5595 (8-bit version), D11–D4 are the significant bits and D3–D0 are sub-bits. Set all sub-bits to zero during the write commands.*

Table 2b. Advanced-Feature Programming Commands

DATA	CONTROL BITS				DATA BITS												FUNCTION
	C3	C2	C1	C0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
SELECT BITS																	
DIN	1	0	0	0	X	X	X	X	MH	MG	MF	ME	MD	MC	MB	MA	Load DAC register "_" from input register "_" when M_ = 1. DAC register "_" is unchanged if M_ = 0.
LOADING INPUT AND DAC REGISTERS (A–H)																	
DIN	1	0	0	1	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load all input registers A–H from their respective shift registers; DAC registers are unchanged. DAC outputs are unchanged.*
DIN	1	0	1	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0	Load all input and DAC registers A–H from their respective shift registers. DAC outputs updated.
SHUTDOWN BITS																	
DIN	1	0	1	1	0	0	0	0	PDD1	PDD0	PDC1	PDC0	PDB1	PDB0	PDA1	PDA0	Write DACA–DACD shutdown-mode bits. See Table 8.
DIN	1	0	1	1	0	0	0	1	X	X	X	X	X	X	X	X	Read-back DACA–DACD shutdown-mode bits.
DOUTRB	X	X	X	X	X	X	X	X	PDD1	PDD0	PDC1	PDC0	PDB1	PDB0	PDA1	PDA0	
DIN	1	0	1	1	0	0	1	0	PDH1	PDH0	PDG1	PDG0	PDF1	PDF0	PDE1	PDE0	Write DACE–DACH shutdown-mode bits. See Table 8.
DIN	1	0	1	1	0	0	1	1	X	X	X	X	X	X	X	X	Read-back DACE–DACH shutdown-mode bits.
DOUTRB	X	X	X	X	X	X	X	X	PDH1	PDH0	PDG1	PDG0	PDF1	PDF0	PDE1	PDE0	
DIN	1	0	1	1	0	1	0	0	PDCH	PDCG	PDCF	PDCE	PDCD	PDCC	PDCB	PDCA	Write DAC shutdown-control bits.
DIN	1	0	1	1	0	1	0	1	X	X	X	X	X	X	X	X	Read-back DAC shutdown-control settings.
DOUTRB	X	X	X	X	X	X	X	X	PDCH	PDCG	PDCF	PDCE	PDCD	PDCC	PDCB	PDCA	

X = Don't care.

**For the MAX5592/MAX5593 (10-bit version), D11–D2 are the significant bits and D1 and D0 are sub-bits. For the MAX5594/MAX5595 (8-bit version), D11–D4 are the significant bits and D3–D0 are sub-bits. Set all sub-bits to zero during the write commands.*

Table 2b. Advanced-Feature Programming Commands (continued)

DATA	CONTROL BITS				DATA BITS												FUNCTION
	C3	C2	C1	C0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
UPIO CONFIGURATION BITS																	
DIN	1	0	1	1	0	1	1	0	UPSL2	UPSL1	UP3	UP2	UP1	UP0	X	X	Write UPIO configuration bits. See Tables 19 and 22.
DIN	1	0	1	1	0	1	1	1	X	X	X	X	X	X	X	X	Read-back UPIO configuration bits function.
DOUTRB	X	X	X	X	X	X	X	X	UP3-2	UP2-2	UP1-2	UP0-2	UP3-1	UP2-1	UP1-1	UP0-1	
SETTLING-TIME-MODE BITS																	
DIN	1	0	1	1	1	0	0	0	SPDH	SPDG	SPDF	SPDE	SPDD	SPDC	SPDB	SPDA	Write settling-time bits for DACA–DACH (0 = SLOW [default, 6µs], 1 = FAST [3µs]).
DIN	1	0	1	1	1	0	0	1	X	X	X	X	X	X	X	X	Read-back DAC settling-time bits.
DOUTRB	X	X	X	X	X	X	X	X	SPDH	SPDG	SPDF	SPDE	SPDD	SPDC	SPDB	SPDA	
UPIO_ AS GPI (GENERAL-PURPOSE INPUT)																	
DIN	1	0	1	1	1	0	1	X	X	X	X	X	X	X	X	X	Read UPIO_ inputs (valid only when UPIO1 or UPIO2 is configured as a general-purpose input.) See the GPI, GPOL, GPOH section.
DOUTRB	X	X	X	X	X	X	X	X	X	X	RTP2	LF2	LR2	RTP1	LF1	LR1	
CPOL AND CPHA CONTROL BITS																	
DIN	1	1	0	0	0	0	0	0	X	X	X	X	X	X	CPOL	CPHA	Write CPOL, CPHA control bits. See Table 15.
DIN	1	1	0	0	0	0	0	1	X	X	X	X	X	X	X	X	Read CPOL, CPHA control bits.
DOUTRB	X	X	X	X	X	X	X	X	X	X	X	X	X	X	CPOL	CPHA	

X = Don't care.

Table 2c. 24-Bit Read Commands

DATA	CONTROL BITS				DATA BITS																												FUNCTION
	C3	C2	C1	C0	D27	D26	D25	D24	D23	D22	D21	D20	D19	D18	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
READ INPUT AND DAC REGISTERS A–H																																	
DIN	1	1	0	1	0	0	0	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDA_11	DDA_10	DDA_9	DDA_8	DDA_7	DDA_6	DDA_5	DDA_4	DDA_3	DDA_2	DDA_1	DDA_0	IDA_11	IDA_10	IDA_9	IDA_8	IDA_7	IDA_6	IDA_5	IDA_4	IDA_3	IDA_2	IDA_1	IDA_0	Read input register A and DAC register A (all 24 bits).**†
DIN	1	1	0	1	0	0	1	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDB_11	DDB_10	DDB_9	DDB_8	DDB_7	DDB_6	DDB_5	DDB_4	DDB_3	DDB_2	DDB_1	DDB_0	IDB_11	IDB_10	IDB_9	IDB_8	IDB_7	IDB_6	IDB_5	IDB_4	IDB_3	IDB_2	IDB_1	IDB_0	Read input register B and DAC register B (all 24 bits).**†
DIN	1	1	0	1	0	1	0	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDC_11	DDC_10	DDC_9	DDC_8	DDC_7	DDC_6	DDC_5	DDC_4	DDC_3	DDC_2	DDC_1	DDC_0	IDC_11	IDC_10	IDC_9	IDC_8	IDC_7	IDC_6	IDC_5	IDC_4	IDC_3	IDC_2	IDC_1	IDC_0	Read input register C and DAC register C (all 24 bits).**†
DIN	1	1	0	1	0	1	1	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDD_11	DDD_10	DDD_9	DDD_8	DDD_7	DDD_6	DDD_5	DDD_4	DDD_3	DDD_2	DDD_1	DDD_0	IDD_11	IDD_10	IDD_9	IDD_8	IDD_7	IDD_6	IDD_5	IDD_4	IDD_3	IDD_2	IDD_1	IDD_0	Read input register D and DAC register D (all 24 bits).**†
DIN	1	1	0	1	1	0	0	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDE_11	DDE_10	DDE_9	DDE_8	DDE_7	DDE_6	DDE_5	DDE_4	DDE_3	DDE_2	DDE_1	DDE_0	IDE_11	IDE_10	IDE_9	IDE_8	IDE_7	IDE_6	IDE_5	IDE_4	IDE_3	IDE_2	IDE_1	IDE_0	Read input register E and DAC register E (all 24 bits).**†
DIN	1	1	0	1	1	0	1	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDF_11	DDF_10	DDF_9	DDF_8	DDF_7	DDF_6	DDF_5	DDF_4	DDF_3	DDF_2	DDF_1	DDF_0	IDF_11	IDF_10	IDF_9	IDF_8	IDF_7	IDF_6	IDF_5	IDF_4	IDF_3	IDF_2	IDF_1	IDF_0	Read input register F and DAC register F (all 24 bits).**†
DIN	1	1	0	1	1	1	0	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDG_11	DDG_10	DDG_9	DDG_8	DDG_7	DDG_6	DDG_5	DDG_4	DDG_3	DDG_2	DDG_1	DDG_0	IDG_11	IDG_10	IDG_9	IDG_8	IDG_7	IDG_6	IDG_5	IDG_4	IDG_3	IDG_2	IDG_1	IDG_0	Read input register G and DAC register G (all 24 bits).**†
DIN	1	1	0	1	1	1	1	X	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	X	X	X	X	X	X	X	X	
DOUTRB	X	X	X	X	X	X	X	X	DDH_11	DDH_10	DDH_9	DDH_8	DDH_7	DDH_6	DDH_5	DDH_4	DDH_3	DDH_2	DDH_1	DDH_0	IDH_11	IDH_10	IDH_9	IDH_8	IDH_7	IDH_6	IDH_5	IDH_4	IDH_3	IDH_2	IDH_1	IDH_0	Read input register H and DAC register H (all 24 bits).**†

X = Don't care.

***D23–D12 represent the 12-bit data from the corresponding DAC register. D11–D0 represent the 12-bit data from the corresponding input register. For the MAX5592/MAX5593, bits D13, D12, D1, and D0 are zero bits. For the MAX5594/MAX5595, bits D15–D12 and D3–D0 are zero bits.*

†During readback, all ones (code FF) must be clocked into DIN for all 24 bits. No command can be issued before all 24 bits have been clocked out. $\overline{CS}$ must be kept low while all 24 bits are being clocked out.

DAC Programming Examples:
To load input register A from the shift register, leaving DAC register A unchanged (DAC output unchanged), use the command in Table 3.

The MAX5590–MAX5595 can load all of the input registers (A–H) simultaneously from the shift register, leaving the DAC registers unchanged (DAC output unchanged), by using the command in Table 4.

To load all of the input registers (A–H) and all of the DAC registers (A–H) simultaneously, use the command in Table 5.

For the 10-bit and 8-bit versions, set sub-bits = 0 for best performance.

Advanced-Feature Programming Commands

Select Bits (M_)

The select bits allow synchronous updating of any combination of channels. The select bits command the loading of the DAC register from the input register of each channel. Set the select bit M_ = 1 to load the DAC register "_" with data from the input register "_", where "_" is replaced with A, B, or C and so on through H, depending on the selected channel. Setting the select bit M_ = 0 results in no action for that channel (Table 6).

Select Bits Programming Example:
To load DAC register B from input register B while keeping other channels (A, C–H) unchanged, set MB = 1 and M_ = 0 (Table 7).

Table 3. Load Input Register A from Shift Register

DATA	CONTROL BITS				DATA BITS											
DIN	0	0	0	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0

Table 4. Load Input Registers (A–H) from Shift Register

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	0	1	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0

Table 5. Load Input Registers (A–H) and DAC Registers (A–H) from Shift Register

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	0	D11	D10	D9	D8	D7	D6	D5	D4	D3/0	D2/0	D1/0	D0/0

Table 6. Select Bits (M_)

DATA	CONTROL BITS								DATA BITS							
DIN	1	0	0	0	X	X	X	X	MH	MG	MF	ME	MD	MC	MB	MA

X = Don't care.

Table 7. Select Bits Programming Example

DATA	CONTROL BITS								DATA BITS							
DIN	1	0	0	0	X	X	0	0	0	0	0	0	0	0	1	0

X = Don't care.

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

Shutdown-Mode Bits (PD_0, PD_1)

Use the shutdown-mode bits and control bits to shut down each DAC independently. The shutdown-mode bits determine the output state of the selected channels. The shutdown-control bits put the selected channels into shutdown-mode. To select the shutdown mode for DACA–DACH, set PD_0 and PD_1 according to Table 8 (where "_" is replaced with one of the selected channels (A–H)). The three possible states for unity-gain versions are 1) normal operation, 2) shutdown with 1kΩ output impedance, and 3) shutdown with 100kΩ output impedance. The three possible states for force-sense versions are 1) normal operation, 2) shutdown with 1kΩ output impedance, and 3) shutdown with the output in a high-impedance state. Tables 9 and 10 show the commands for writing to the shutdown-mode bits. Table 11 shows the commands for writing the shutdown-control bits. This command is required to put the selected channels into shutdown.

Always write the shutdown-mode-bits command first and then write the shutdown-control-bits command to properly shut down the selected channels. The shutdown-control-bits command can be written at any time after the shutdown-mode-bits command. It does not have to immediately follow the shutdown-mode-bits command.

Settling-Time-Mode Bits (SPD_)

The settling-time-mode bits select the settling time (FAST mode or SLOW mode) of the MAX5590–MAX5595. Set SPD_ = 1 to select FAST mode or set SPD_ = 0 to select SLOW mode, where "_" is replaced by A, B, or C and so on through H, depending on the selected channel (Table 12). FAST mode provides a 3µs maximum settling time, and SLOW mode provides a 6µs maximum settling time.

Table 8. Shutdown-Mode Bits

PD_1	PD_0	DESCRIPTIONS
0	0	Shutdown with 1kΩ termination to ground on DAC_ output.
0	1	Shutdown with 100kΩ termination to ground on DAC_ output for unity-gain versions. Shutdown with high-impedance output for force-sense versions.
1	0	Ignored.
1	1	DAC_ is powered up in its normal operating mode.

Table 9. Shutdown-Mode Write Command (DACA–DACD)

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	0	0	0	0	PDD1	PDD0	PDC1	PDC0	PDB1	PDB0	PDA1	PDA0

X = Don't care.

Table 10. Shutdown-Mode Write Command (DACE–DACH)

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	0	0	1	0	PDH1	PDH0	PDG1	PDG0	PDF1	PDF0	PDE1	PDE0

X = Don't care.

Table 11. Shutdown-Control-Bits Write Command

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	0	1	0	0	PDCH	PDCG	PDCF	PDCE	PDCD	PDCC	PDCB	PDCA

X = Don't care.

Table 12. Settling-Time-Mode Write Command

DATA	CONTROL BITS								DATA BITS							
DIN	1	0	1	1	1	0	0	0	SPDH	SPDG	SPDF	SPDE	SPDD	SPDC	SPDB	SPDA

Settling-Time-Mode Write Example:
To configure DACA and DACD into FAST mode and DACB and DACC into SLOW mode, use the command in Table 13.

To read back the settling-time-mode bits, use the command in Table 14.

CPOL and CPHA Control Bits

The CPOL and CPHA control bits of the MAX5590–MAX5595 are defined the same as the CPOL and CPHA bits in the SPI standard. Set the DAC's CPOL and CPHA bits to CPOL = 0 and CPHA = 0 or CPOL = 1 and CPHA = 1 for MICROWIRE and SPI applications requiring the clocking of data in on the rising edge of SCLK. Set the DAC's CPOL and CPHA bits to CPOL = 0 and CPHA = 1 or CPOL = 1 and CPHA = 0 for DSP and SPI applications, requiring the clocking of data in on the falling edge of SCLK (refer to the *Programmer's Handbook* and see Table 15 for details). At power-up, if $\overline{DSP}$ = DV_{DD}, the default value of CPHA is zero and if $\overline{DSP}$ = DGND, the default value of CPHA is one. The default value of CPOL is zero at power-up.

To write to the CPOL and CPHA bits, use the command in Table 16.

To read back the device's CPOL and CPHA bits, use the command in Table 17.

Table 13. Settling-Time-Mode Write Example

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	1	0	0	0	X	X	X	X	1	0	0	1

X = Don't care.

Table 14. Settling-Time-Mode Read Command

DATA	CONTROL BITS								DATA BITS							
DIN	1	0	1	1	1	0	0	1	X	X	X	X	X	X	X	X
DOUTRB	X	X	X	X	X	X	X	X	SPDH	SPDG	SPDF	SPDE	SPDD	SPDC	SPDB	SPDA

X = Don't care.

Table 15. CPOL and CPHA Bits

CPOL	CPHA	DESCRIPTION
0	0	Default values at power-up when $\overline{DSP}$ is connected to DV_{DD}. Data is clocked in on the rising edge of SCLK.
0	1	Default values at power-up when $\overline{DSP}$ is connected to DGND. Data is clocked in on the falling edge of SCLK.
1	0	Data is clocked in on the falling edge of SCLK.
1	1	Data is clocked in on the rising edge of SCLK.

Table 16. CPOL and CPHA Write Command

DATA	CONTROL BITS				DATA BITS											
DIN	1	1	0	0	0	0	0	0	X	X	X	X	X	X	CPOL	CPHA

X = Don't care.

Table 17. CPOL and CPHA Read Command

DATA	CONTROL BITS				DATA BITS											
DIN	1	1	0	0	0	0	0	1	X	X	X	X	X	X	X	X
DOUTRB	X	X	X	X	X	X	X	X	X	X	X	X	X	X	CPOL	CPHA

X = Don't care.

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

UPIO Bits (UPSL1, UPSL2, UP0–UP3)

The MAX5590–MAX5595 provide two user-programmable input/output (UPIO) ports: UPIO1 and UPIO2. These ports have 15 possible configurations, as shown in Table 22. UPIO1 and UPIO2 can be programmed independently or simultaneously by writing to the UPSL1, UPSL2, and UP0–UP3 bits (Table 18).

Table 19 shows how UPIO1 and UPIO2 are selected for configuration. The UP0–UP3 bits select the desired functions for UPIO1 and/or UPIO2 (Table 22).

UPIO Programming Example:

To set only UPIO1 as $\overline{LDAC}$ and leave UPIO2 unchanged, use the command in Table 20.

The UPIO selection and configuration bits can be read back from the MAX5590–MAX5595 when UPIO1 or UPIO2 is configured as a DOUTRB output. Table 21 shows the read-back data format for the UPIO bits. Writing the command in Table 21 initiates a read operation of the UPIO bits. The data is clocked out starting on the ninth clock cycle of the sequence. Bits UP3-2 through UP0-2 provide the UP3–UP0 configuration bits for UPIO2 (Table 22), and bits UP3-1 through UP0-1 provide the UP3–UP0 configuration bits for UPIO1.

Table 18. UPIO Write Command

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	0	1	1	0	UPSL2	UPSL1	UP3	UP2	UP1	UP0	X	X

X = Don't care.

Table 19. UPIO Selection Bits (UPSL1 and UPSL2)

UPSL2	UPSL1	UPIO PORT SELECTED
0	0	None selected
0	1	UPIO1 selected
1	0	UPIO2 selected
1	1	Both UPIO1 and UPIO2 selected

Table 20. UPIO Programming Example

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	0	1	1	0	0	1	0	0	0	0	X	X

X = Don't care.

Table 21. UPIO Read Command

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	0	1	1	1	X	X	X	X	X	X	X	X
DOUTRB	X	X	X	X	X	X	X	X	UP3-2	UP2-2	UP1-2	UP0-2	UP3-1	UP2-1	UP1-1	UP0-1

X = Don't care.

UPIO Configuration

Table 22 lists the possible configurations for UPIO1 and UPIO2. UPIO1 and UPIO2 use the selected function when configured by the UP3–UP0 configuration bits.

LDAC

LDAC controls the loading of the DAC registers. When LDAC is high, the DAC registers are latched, and any change in the input registers does not affect the contents of the DAC registers or the DAC outputs. When LDAC is low, the DAC registers are transparent, and the values stored in the input registers are fed directly to the DAC registers, and the DAC outputs are updated.

Drive LDAC low to asynchronously load the DAC registers from their corresponding input registers (DACs that are in shutdown remain shut down). The LDAC input does not require any activity on CS, SCLK, or DIN to take effect. If LDAC is brought low coincident with a rising edge of CS (which executes a serial command modifying the value of either DAC input register), then LDAC must remain asserted for at least 120ns following the CS rising edge. This requirement applies only for serial commands that modify the value of the DAC input registers. See Figures 5 and 6 for timing details.

Table 22. UPIO Configuration Register Bits (UP3–UP0)

UPIO CONFIGURATION BITS				FUNCTION	DESCRIPTION
UP3	UP2	UP1	UP0		
0	0	0	0	LDAC	Active-Low Load DAC Input. Drive low to asynchronously load all DAC registers with data from input registers.
0	0	0	1	SET	Active-Low Input. Drive low to set all input and DAC registers to full scale.
0	0	1	0	MID	Active-Low Input. Drive low to set all input and DAC registers to midscale.
0	0	1	1	CLR	Active-Low Input. Drive low to set all input and DAC registers to zero scale.
0	1	0	0	PDL	Active-Low Power-Down Lockout Input. Drive low to disable software shutdown.
0	1	0	1	Reserved	This mode is reserved. Do not use.
0	1	1	0	SHDN1K	Active-Low 1kΩ Shutdown Input. Overrides PD_1 and PD_0 settings. For the MAX5590/MAX5592/MAX5594, drive SHDN1K low to pull OUTA–OUTH to AGND with 1kΩ. For the MAX5591/MAX5593/MAX5595, drive SHDN1K low to leave OUTA–OUTH high impedance.
0	1	1	1	SHDN100K	Active-Low 100kΩ Shutdown Input. Overrides PD_1 and PD_0 settings. For the MAX5590/MAX5592/MAX5594, drive SHDN100K low to pull OUTA–OUTH to AGND with 100kΩ. For the MAX5591/MAX5593/MAX5595, drive low to leave OUTA–OUTH high impedance.
1	0	0	0	DOUTRB	Data Read-Back Output
1	0	0	1	DOUTDC0	Mode 0 Daisy-Chain Data Output. Data is clocked out on the falling edge of
1	0	1	0	DOUTDC1	Mode 1 Daisy-Chain Data Output. Data is clocked out on the rising edge of SCLK.
1	0	1	1	GPI	General-Purpose Logic Input
1	1	0	0	GPOL	General-Purpose Logic-Low Output
1	1	0	1	GPOH	General-Purpose Logic-High Output
1	1	1	0	TOGG	Toggle Input. Toggles DAC outputs between data in input registers and data in DAC registers. Drive low to set all DAC outputs to values stored in input registers. Drive high to set all DAC outputs to values stored in DAC registers.
1	1	1	1	FAST	Fast/Slow Settling-Time-Mode Input. Drive low to select FAST (3µs) mode or drive high to select SLOW (6µs) settling mode. Overrides the SPDA–SPDH settings.

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

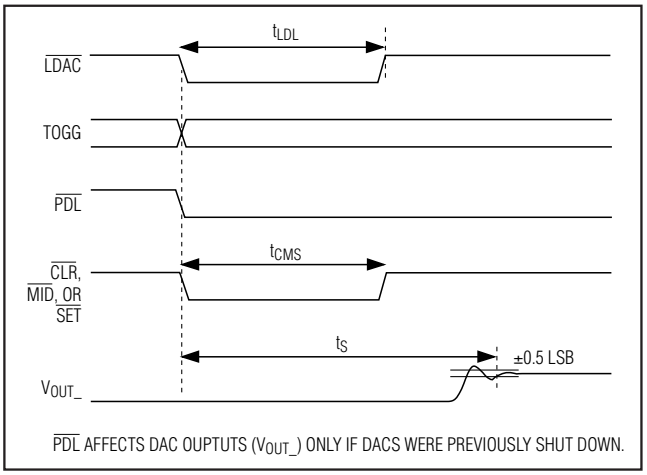


Figure 5. Asynchronous Signal Timing

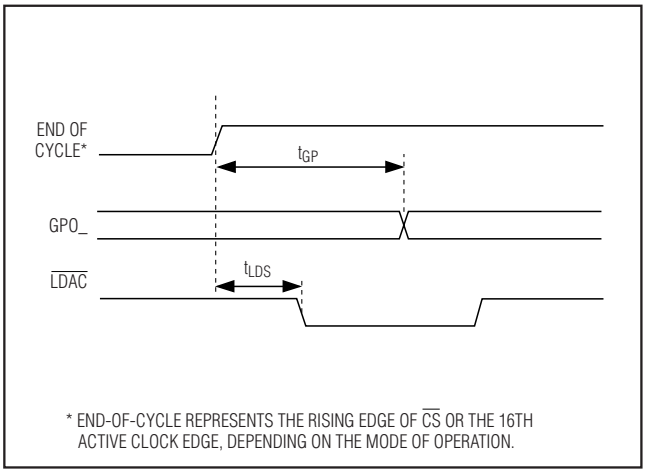


Figure 6. GPO_ and LDAC Signal Timing

SET, MID, CLR

The SET, MID, and CLR signals force the DAC outputs to full scale, midscale, or zero scale (Figure 5). These signals cannot be active at the same time.

The active-low SET input forces the DAC outputs to full scale when SET is low. When SET is high, the DAC outputs follow the data in the DAC registers.

The active-low MID input forces the DAC outputs to midscale when MID is low. When MID is high, the DAC outputs follow the data in the DAC registers.

The active-low CLR input forces the DAC outputs to zero scale when CLR is low. When CLR is high, the DAC outputs follow the data in the DAC registers.

If CLR, MID, or SET signals go low during a write command, reload the data to ensure accurate results.

Power-Down Lockout (PDL)

The PDL active-low, software-shutdown lockout input overrides (not overwrites) the PD_0 and PD_1 shutdown-mode bits. PDL cannot be active at the same time as SHDN1K or SHDN100K (see the *Shutdown Mode (SHDN1K, SHDN100K)* section).

If the PD_0 and PD_1 bits command the DAC to shut down prior to PDL going low, the DAC returns to shutdown mode immediately after PDL goes high, unless the PD_0 and PD_1 bits were modified through the serial interface in the meantime.

Shutdown Mode (SHDN1K, SHDN100K)

The SHDN1K and SHDN100K are active-low signals that override (not overwrite) the PD_1 and PD_0 bit settings. For the MAX5590/MAX5592/MAX5594, drive SHDN1K low to select shutdown mode with OUTA–OUTH internally terminated with 1kΩ to ground, or drive SHDN100K low to select shutdown with an internal 100kΩ termination. For the MAX5591/MAX5593/MAX5595, drive SHDN1K low for shutdown with 1kΩ output termination, or drive SHDN100K low for shutdown with high-impedance outputs.

For proper shutdown, first select a shutdown mode (Table 8), then use the shutdown-control bits as listed in Table 2b.

Data Output (DOUTRB, DOUTDC0, DOUTDC1)

UPIO1 and UPIO2 can be configured as serial data outputs, DOUTRB (data out for read back), DOUTDC0 (data out for daisy-chaining, mode 0), and DOUTDC1 (data out for daisy-chaining, mode 1). The differences between DOUTRB and DOUTDC0 (or DOUTDC1) are as follows:

- The source of read-back data on DOUTRB is the DOUT register. Daisy-chain DOUTDC_ data comes directly from the shift register.
- Read-back data on DOUTRB is only present after a DAC read command. Daisy-chain data is present on DOUTDC_ for any DAC write after the first 16 bits are written.
- The DOUTRB idle state (CS = high) for read back is high impedance. Daisy-chain DOUTDC_ idles high when inactive to avoid floating the data input in the next device in the daisy-chain.

See Figures 1 and 2 for timing details.

GPI, GPOL, GPOH

UPIO1 and UPIO2 can each be configured as a general-purpose input (GPI), a general-purpose output low (GPOL), or a general-purpose output high (GPOH).

The GPI can serve to detect interrupts from µPs or microcontrollers. The GPI has three functions:

1) Sample the signal at GPI at the time of the read (RTP1 and RTP2).
2) Detect whether or not a falling edge has occurred since the last read or reset (LF1 and LF2).
3) Detect whether or not a rising edge has occurred since the last read or reset (LR1 and LR2).

RTP1, LF1, and LR1 represent the data read from UPIO1; RTP2, LF2, and LR2 represent the data read from UPIO2.

To issue a read command for the UPIO configured as GPI, use the command in Table 23.

Once the command is issued, RTP1 and RTP2 provide the real-time status (0 or 1) of the inputs at UPIO1 or UPIO2, respectively, at the time of the read. If LF2 or LF1 is one, then a falling edge has occurred on the respective UPIO1 or UPIO2 input since the last read or reset. If LR2 or LR1 is one, then a rising edge has occurred since the last read or reset.

GPOL outputs a constant low, and GPOH outputs a constant high. See Figure 6.

TOGG

Use the TOGG input to toggle the DAC outputs between the values in the input registers and DAC registers. A delay of greater than 100ns from the end of the previous write command is required before the TOGG signal can be correctly switched between the new value and the previously stored value. When TOGG = 0, the output follows the information in the input registers. When TOGG = 1, the output follows the information in the DAC register (Figure 5).

$\overline{FAST}$

The MAX5590–MAX5595 have two settling-time-mode options: FAST (3µs max) and SLOW (6µs max). To select the FAST mode, drive $\overline{FAST}$ low, and to select SLOW mode, drive $\overline{FAST}$ high. This overrides (not overwrites) the SPDA–SPDH bit settings.

Table 23. GPI Read Command

DATA	CONTROL BITS				DATA BITS											
DIN	1	0	1	1	1	0	1	X	X	X	X	X	X	X	X	X
DOUTRB	X	X	X	X	X	X	X	X	X	X	RTP2	LF2	LR2	RTP1	LF1	LR1

X = Don't care.

Table 24. Unipolar Code Table (Gain = +1)

DAC CONTENTS MSB		LSB	ANALOG OUTPUT
1111	1111	1111	$+V_{REF}$ (4095 / 4096)
1000	0000	0001	$+V_{REF}$ (2049 / 4096)
1000	0000	0000	$+V_{REF}$ (2048 / 4096) = V_{REF} / 2
0111	1111	1111	$+V_{REF}$ (2047 / 4096)
0000	0000	0001	$+V_{REF}$ (1 / 4096)
0000	0000	0000	0

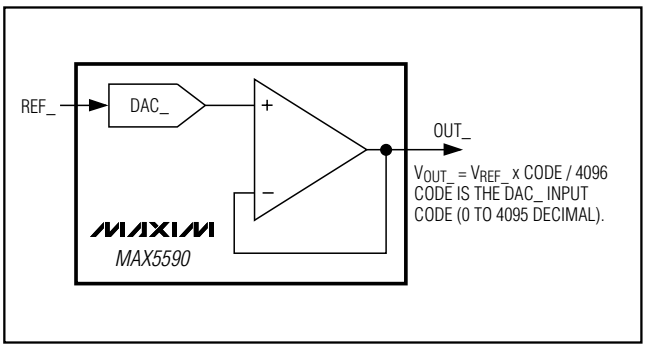


Figure 7. Unipolar Output Circuit

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

Applications Information

Unipolar Output

Figure 7 shows the unity-gain MAX5590 in a unipolar output configuration. Table 24 lists the unipolar output codes.

Bipolar Output

The MAX5590 outputs can be configured for bipolar operation, as shown in Figure 8. The output voltage is given by the following equation:

$$V_{OUT\_} = V_{REF} \times (CODE - 2048) / 2048$$

where CODE represents the numeric value of the DAC's binary input code (0 to 4095 decimal). Table 25 shows digital codes and the corresponding output voltage for the Figure 8 circuit.

Configurable Output Gain

The MAX5591/MAX5593/MAX5595 have force-sense outputs, which provide a direct connection to the inverting terminal of the output op amp, yielding the most flexibility. The force-sense output has the advantage that specific gains can be set externally for a given application. The gain error for the MAX5591/MAX5593/MAX5595 is specified in a unity-gain configuration (op-amp output and inverting terminals connected), and additional gain error results from external resistor tolerances. The force-sense DACs allow many useful circuits to be created with only a few simple external components.

An example of a custom, fixed gain using the MAX5591's force-sense output is shown in Figure 9. In this example, the external reference is set to 1.25V, and the gain is set to +1.1V/V with external discrete resistors to provide an approximate 0 to 1.375V DAC output voltage range.

$$V_{OUT} = [(0.5 \times V_{REF\_} \times CODE) / 4096] \times [1 + (R2 / R1)]$$

where CODE represents the numeric value of the DAC's binary input code (0 to 4095 decimal).

In this example, R2 = 12kΩ and R1 = 10kΩ to set the gain = 1.1V/V.

$$V_{OUT} = [(0.5 \times 1.25V \times CODE) / 4096] \times 2.2$$

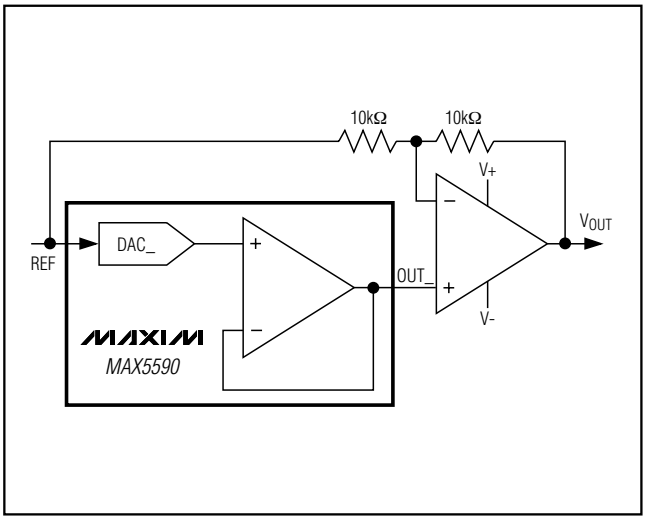


Figure 8. Bipolar Output Circuit

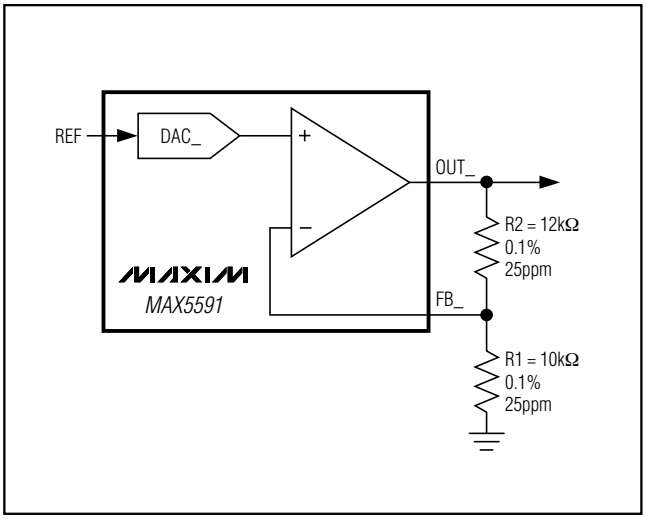


Figure 9. Configurable Output Gain

Table 25. Bipolar Code Table (Gain = +1)

DAC CONTENTS MSB		LSB	ANALOG OUTPUT
1111	1111	1111	$+V_{REF}$ (2047 / 2048)
1000	0000	0001	$+V_{REF}$ (1 / 2048)
1000	0000	0000	0
0111	1111	1111	$-V_{REF}$ (1 / 2048)
0000	0000	0001	$-V_{REF}$ (2047 / 2048)
0000	0000	0000	$-V_{REF}$ (2048 / 2048) = $-V_{REF}$

Power-Supply and Layout Considerations

Bypass the analog and digital power supplies by using a 10µF capacitor in parallel with a 0.1µF capacitor to AGND and DGND (Figure 10). Minimize lead lengths to reduce lead inductance. Use shielding and/or ferrite beads to further increase isolation.

Digital and AC transient signals coupling to AGND can create noise at the output. Connect AGND to the highest quality ground available. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane. Wire-wrapped boards and sockets are not recommended. For optimum system performance, use PC boards with separate analog and digital ground planes. Connect the two ground planes together at the low-impedance power-supply source.

Using separate power supplies for AV_{DD} and DV_{DD} improves noise immunity. Connect AGND and DGND at the low-impedance power-supply sources (Figure 11).

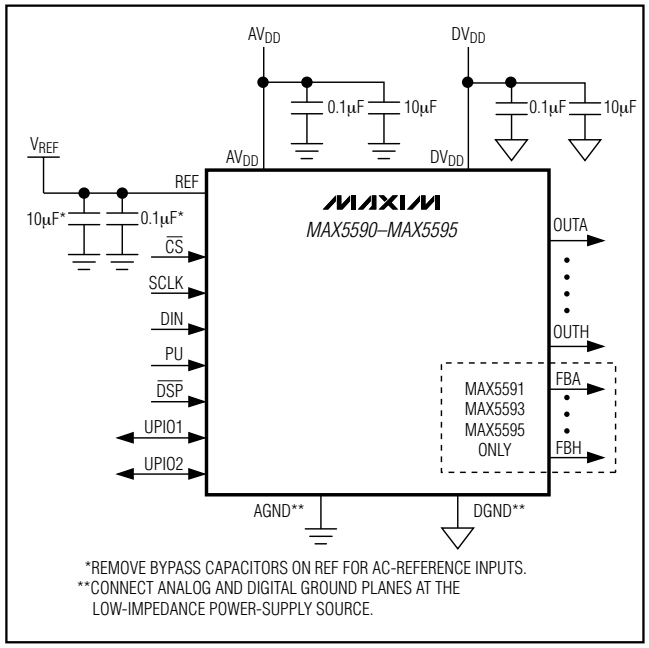


Figure 10. Bypassing Power Supplies AV_{DD}, DV_{DD}, and REF

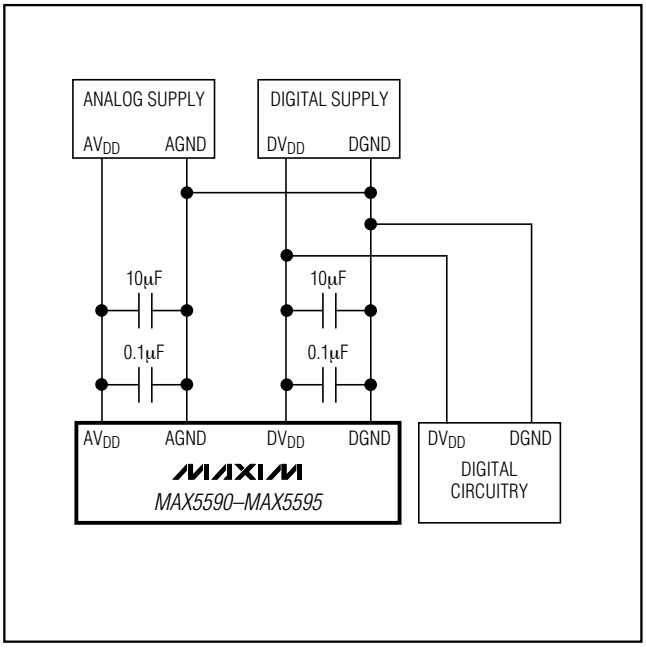
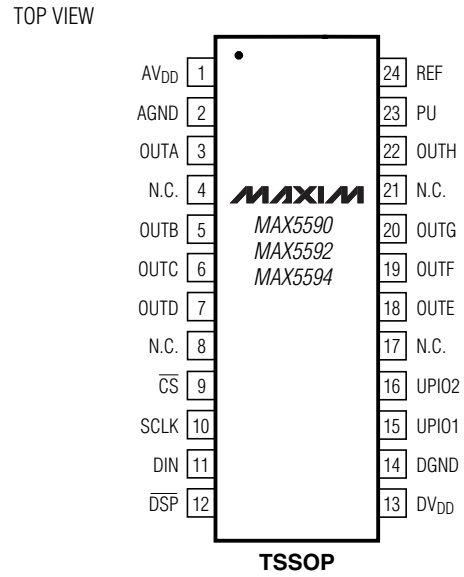
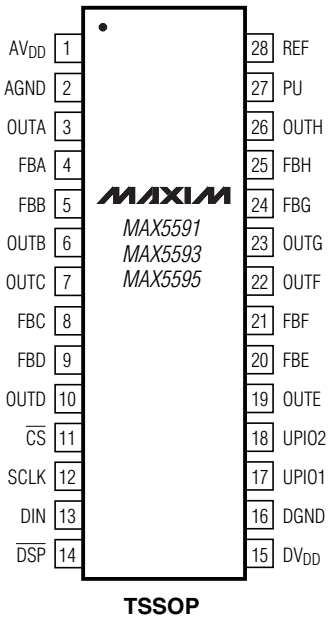


Figure 11. Separate Analog and Digital Power Supplies

Buffered, Fast-Settling, Octal, 12/10/8-Bit, Voltage-Output DACs

Pin Configurations





Selector Guide

PART	OUTPUT BUFFER CONFIGURATION	RESOLUTION (BITS)	INL (LSBs MAX)
MAX5590AEUG*	Unity Gain	12	±1
MAX5590BEUG	Unity Gain	12	±4
MAX5591AEUI*	Force Sense	12	±1
MAX5591BEUI	Force Sense	12	±4
MAX5592EUG	Unity Gain	10	±1
MAX5593EUI	Force Sense	10	±1
MAX5594EUG	Unity Gain	8	±0.5
MAX5595EUI	Force Sense	8	±0.5

**Future product. Contact factory for availability. Specifications are preliminary.*

Chip Information

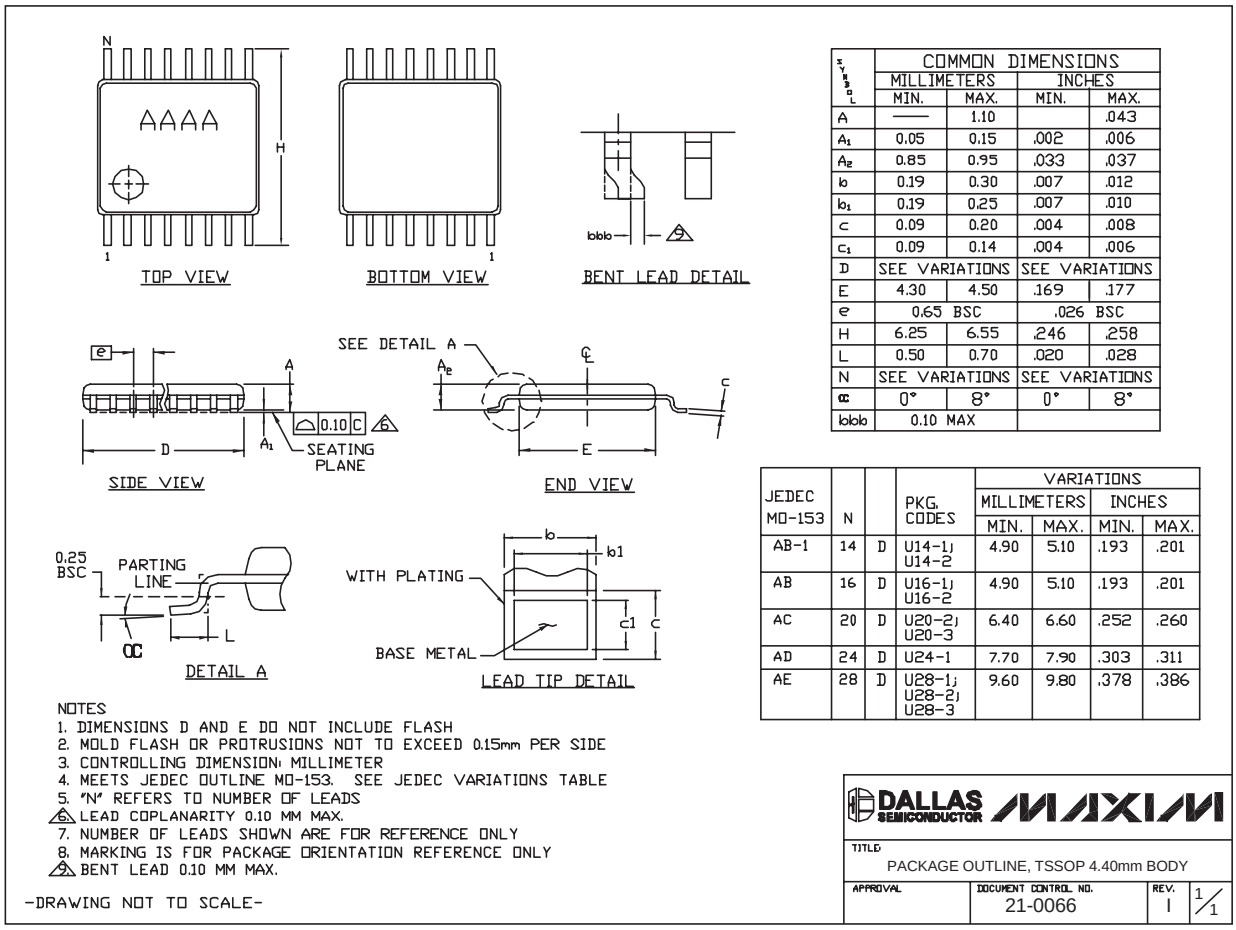
TRANSISTOR COUNT: 38,513

PROCESS: BiCMOS

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to **www.maxim-ic.com/packages**.)

TSSOP4.40mm.EPS



SYMBOL	COMMON DIMENSIONS			
	MILLIMETERS		INCHES	
	MIN.	MAX.	MIN.	MAX.
A	———	1.10		.043
A_1	0.05	0.15	.002	.006
A_2	0.85	0.95	.033	.037
b	0.19	0.30	.007	.012
b_1	0.19	0.25	.007	.010
c	0.09	0.20	.004	.008
c_1	0.09	0.14	.004	.006
D	SEE VARIATIONS		SEE VARIATIONS	
E	4.30	4.50	.169	.177
e	0.65 BSC		.026 BSC	
H	6.25	6.55	.246	.258
L	0.50	0.70	.020	.028
N	SEE VARIATIONS		SEE VARIATIONS	
α	0°	8°	0°	8°
bbb	0.10 MAX			

JEDEC MO-153	N		PKG. CODES	VARIATIONS			
				MILLIMETERS		INCHES	
				MIN.	MAX.	MIN.	MAX.
AB-1	14	D	U14-1, U14-2	4.90	5.10	.193	.201
AB	16	D	U16-1, U16-2	4.90	5.10	.193	.201
AC	20	D	U20-2, U20-3	6.40	6.60	.252	.260
AD	24	D	U24-1	7.70	7.90	.303	.311
AE	28	D	U28-1, U28-2, U28-3	9.60	9.80	.378	.386

NOTES
1. DIMENSIONS D AND E DO NOT INCLUDE FLASH
2. MOLD FLASH OR PROTRUSIONS NOT TO EXCEED 0.15mm PER SIDE
3. CONTROLLING DIMENSION: MILLIMETER
4. MEETS JEDEC OUTLINE MO-153. SEE JEDEC VARIATIONS TABLE
5. "N" REFERS TO NUMBER OF LEADS
6. LEAD COPLANARITY 0.10 MM MAX.
7. NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY
8. MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY
9. BENT LEAD 0.10 MM MAX.

-DRAWING NOT TO SCALE-

DALLAS SEMICONDUCTOR MAXIM

TITLE: PACKAGE OUTLINE, TSSOP 4.40mm BODY

APPROVAL	DOCUMENT CONTROL NO.	REV.	
	21-0066	I	1/1