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AVAILABLE

MAXIM

Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

MAX5134

General Description

The MAX5134 is a low-power, quad 16-bit, buffered voltage-output, high-linearity digital-to-analog converter (DAC). It uses a precision internal reference or a precision external reference for rail-to-rail operation. The MAX5134 accepts a wide +2.7V to +5.25V supply-voltage range to accommodate most low-power and low-voltage applications. The device accepts a 3-wire SPI™-/QSPI™-/MICROWIRE™-/DSP-compatible serial interface to save board space and reduce the complexity of optically isolated and transformer-isolated applications. The digital interface's double-buffered hardware and software LDAC provide simultaneous output update. The serial interface features a READY output for easy daisy-chaining of several MAX5134 devices and/or other compatible devices. The MAX5134 includes a hardware input to power-up or reset the DAC outputs to zero or midscale, providing additional safety for applications that drive valves or other transducers that need to be off during power-up. The high linearity of the DACs makes these devices ideal for precision control and instrumentation applications. The MAX5134 is available in an ultra-small (4mm x 4mm), 24-pin TQFN package and is specified over the -40°C to +105°C extended industrial temperature range.

Applications

- Automatic Test Equipment
- Automatic Tuning
- Communication Systems
- Data Acquisition
- Gain and Offset Adjustment
- Portable Instrumentation
- Power-Amplifier Control
- Process Control and Servo Loops
- Programmable Voltage and Current Sources

Functional Diagram and Typical Operating Circuit appear at end of data sheet.

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MICROWIRE is a trademark of National Semiconductor Corp.

Features

- ◆ 16-Bit Resolution in a 4mm x 4mm, 24-Pin TQFN Package
- ◆ Hardware-Selectable Power-Up or Reset-to-Zero/ Midscale DAC Output
- ◆ Double-Buffered Input Registers
- ◆ LDAC Asynchronously Updates DAC Outputs Simultaneously
- ◆ READY Facilitates Daisy Chaining
- ◆ High-Performance 10ppm/°C Internal Reference
- ◆ Guaranteed Monotonic Over All Operating Conditions
- ◆ Wide +2.7V to +5.25V Supply Range
- ◆ Rail-to-Rail Buffered Output Operation
- ◆ Low Gain Error (Less Than $\pm 0.5\%$ FS) and Offset (Less Than ± 10 mV)
- ◆ 30MHz 3-Wire SPI-/QSPI-/MICROWIRE-/ DSP-Compatible Serial Interface
- ◆ CMOS-Compatible Inputs with Hysteresis
- ◆ Low-Power Consumption (ISHDN = 2 μ A max)

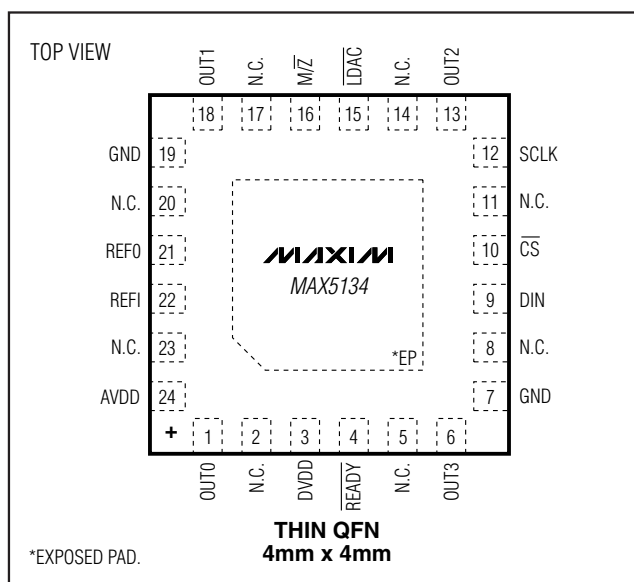
Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX5134AGTG+	-40°C to +105°C	24 TQFN-EP*

+Denotes a lead-free/RoHS-compliant package.

*EP = Exposed pad.

Pin Configuration



MAXIM

Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

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ABSOLUTE MAXIMUM RATINGS

AVDD to GND	-0.3V to +6V
DVDD to GND	-0.3V to +6V
OUT0–OUT3 to GND	-0.3V to the lower of (AVDD + 0.3V) and +6V
REFI, REFO, M/Z to GND	-0.3V to the lower of (AVDD + 0.3V) and +6V
SCLK, DIN, CS to GND	-0.3V to the lower of (DVDD + 0.3V) and +6V
LDAC, READY to GND	-0.3V to the lower of (DVDD + 0.3V) and +6V

Continuous Power Dissipation ($T_A = +70^\circ\text{C}$)	24-Pin TQFN (derate at $17.5\text{mW}/^\circ\text{C}$ above $+70^\circ\text{C}$) 2222.2mW
Maximum Current into Any Input or Output with the Exception of M/Z Pin	$\pm 50\text{mA}$
Maximum Current into M/Z Pin	$\pm 5\text{mA}$
Operating Temperature Range	-40°C to $+105^\circ\text{C}$
Storage Temperature Range	-65°C to $+150^\circ\text{C}$
Lead Temperature (soldering, 10s)	$+300^\circ\text{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

($V_{AVDD} = 2.7\text{V}$ to 5.25V , $V_{DVDD} = 2.7\text{V}$ to 5.25V , $V_{AVDD} \geq V_{DVDD}$, $V_{GND} = 0$, $V_{REFI} = V_{AVDD} - 0.25\text{V}$, $C_{OUT} = 200\text{pF}$, $R_{OUT} = 10\text{k}\Omega$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^\circ\text{C}$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
STATIC ACCURACY (Notes 1, 2)							
Resolution	N		16			Bits	
Integral Nonlinearity	INL	$V_{REFI} = 5\text{V}$, $AVDD = 5.25\text{V}$	(Note 3)	-8	± 2	+10	LSB
						± 6	
Differential Nonlinearity	DNL	Guaranteed monotonic	-1.0		+1.0	LSB	
Offset Error	OE	(Note 4)	-10	± 1	+10	mV	
Offset-Error Drift				± 4		$\mu\text{V}/^\circ\text{C}$	
Gain Error	GE	(Note 4)	-0.5	± 0.2	+0.5	% of FS	
Gain Temperature Coefficient				± 2		ppm FS/ $^\circ\text{C}$	
REFERENCE INPUT							
Reference-Input Voltage Range	V_{REFI}	$AVDD = 3\text{V}$ to 5.25V	2		AVDD	V	
		$AVDD = 2.7\text{V}$ to 3V	2		AVDD - 0.2		
Reference-Input Impedance				113		k Ω	
INTERNAL REFERENCE							
Reference Voltage	V_{REFO}	$T_A = +25^\circ\text{C}$	2.434	2.440	2.443	V	
Reference Temperature Coefficient		(Note 5)		10	25	ppm/ $^\circ\text{C}$	
Reference Output Impedance				1		Ω	
Line Regulation				100		ppm/V	
Maximum Capacitive Load	C_R			0.1		nF	

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ELECTRICAL CHARACTERISTICS (continued)

($V_{AVDD} = 2.7V$ to $5.25V$, $V_{DVDD} = 2.7V$ to $5.25V$, $V_{AVDD} \geq V_{DVDD}$, $V_{GND} = 0$, $V_{REF1} = V_{AVDD} - 0.25V$, $C_{OUT} = 200pF$, $R_{OUT} = 10k\Omega$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^\circ C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DAC OUTPUT VOLTAGE (Note 2)						
Output Voltage Range		No load	0.02		$V_{AVDD} - 0.02$	V
DC Output Impedance				0.1		Ω
Maximum Capacitive Load (Note 5)	C_L	Series resistance = 0		0.2		nF
		Series resistance = 500Ω		15		μF
Resistive Load	R_L		2			$k\Omega$
Short-Circuit Current	I_{SC}	$V_{AVDD} = 5.25V$		± 35		mA
		$V_{AVDD} = 2.7V$	-40	± 20	+40	
Power-Up Time		From power-down mode		25		μs
DIGITAL INPUTS (SCLK, DIN, CS, LDAC) (Note 6)						
Input High Voltage	V_{IH}		0.7 x $DVDD$			V
Input Low Voltage	V_{IL}				0.3 x $DVDD$	V
Input Leakage Current	I_{IN}	$V_{IN} = 0$ or $DVDD$	-1	± 0.1	+1	μA
Input Capacitance	C_{IN}				10	pF
DIGITAL OUTPUTS (READY)						
Output High Voltage	V_{OH}	$I_{SOURCE} = 3mA$	$DVDD - 0.5$			V
Output Low Voltage	V_{OL}	$I_{SINK} = 2mA$			0.4	V
DYNAMIC PERFORMANCE						
Voltage-Output Slew Rate	SR	Positive and negative		1.25		V/ μs
Voltage-Output Settling Time	t_S	1/4 scale to 3/4 scale $V_{REF1} = V_{AVDD} = 5V$ settle to ± 2 LSB (Note 5)		5		μs
Digital Feedthrough		Code 0, all digital inputs from 0 to $DVDD$		0.5		nV•s
Major Code Transition Analog Glitch Impulse				12		nV•s
Output Noise		10kHz		120		nV/ \sqrt{Hz}
Integrated Output Noise		1Hz to 10kHz		18		μV
DAC-to-DAC Crosstalk				25		nV•s

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ELECTRICAL CHARACTERISTICS (continued)

($V_{AVDD} = 2.7V$ to $5.25V$, $V_{DVDD} = 2.7V$ to $5.25V$, $V_{AVDD} \geq V_{DVDD}$, $V_{GND} = 0$, $V_{REF1} = V_{AVDD} - 0.25V$, $C_{OUT} = 200pF$, $R_{OUT} = 10k\Omega$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^\circ C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
POWER REQUIREMENTS (Note 7)						
Analog Supply Voltage Range	AVDD		2.7		5.25	V
Digital Supply Voltage Range	DVDD		2.7		AVDD	V
Supply Current	I_{AVDD}	No load, all digital inputs at 0 or DVDD		2.5	3.6	mA
	I_{DVDD}			1	10	μA
Power-Down Supply Current	I_{AVPD}	No load, all digital inputs at 0 or DVDD		0.2	2	μA
	I_{DVPD}			0.1	2	μA
TIMING CHARACTERISTICS (Note 8) (Figure 1)						
Serial-Clock Frequency	f_{SCLK}		0		30	MHz
SCLK Pulse-Width High	t_{CH}		13			ns
SCLK Pulse-Width Low	t_{CL}		13			ns
\overline{CS} Fall-to-SCLK Fall Setup Time	t_{CSS}		8			ns
SCLK Fall-to \overline{CS} -Rise Hold Time	t_{CSH}		5			ns
DIN-to-SCLK Fall Setup Time	t_{DS}		10			ns
DIN-to-SCLK Fall Hold Time	t_{DH}		2			ns
SCLK Fall to \overline{READY} Transition	t_{SRL}	(Note 9)			30	ns
\overline{CS} Pulse-Width High	t_{CSW}		33			ns
LDAC Pulse Width	$t_{LDACPWL}$		33			ns

Note 1: Static accuracy tested without load.

Note 2: Linearity is tested within 20mV of GND and AVDD, allowing for gain and offset error.

Note 3: Codes above 2047 are guaranteed to be within ± 8 LSB.

Note 4: Gain and offset tested within 100mV of GND and AVDD.

Note 5: Guaranteed by design.

Note 6: Device draws current in excess of the specified supply current when a digital input is driven with a voltage of $V_I < DVDD - 0.6V$ or $V_I > 0.5V$. At $V_I = 2.2V$ with $DVDD = 5.25V$, this current can be as high as 2mA. The SPI inputs are CMOS-input level compatible. The 30MHz clock frequency cannot be guaranteed for a minimum signal swing.

Note 7: Excess current from AVDD is 10mA when powered without DVDD. Excess current from DVDD is 1mA when powered without AVDD.

Note 8: All timing specifications are with respect to the digital input and output thresholds.

Note 9: Maximum daisy-chain clock frequency is limited to 25MHz.

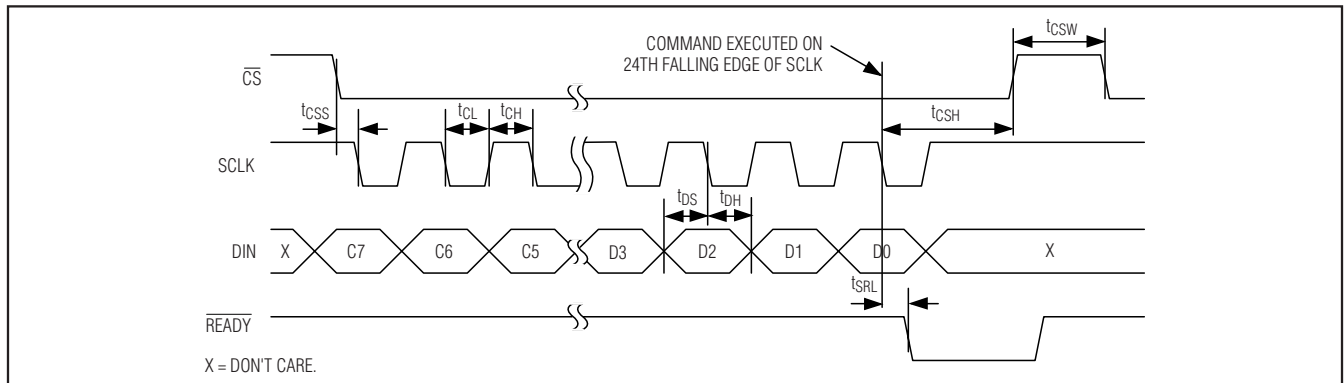


Figure 1. Serial-Interface Timing Diagram

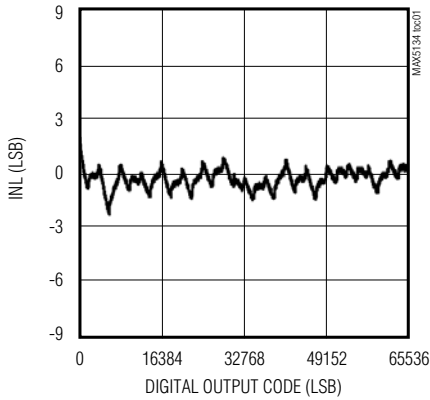
Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

Typical Operating Characteristics

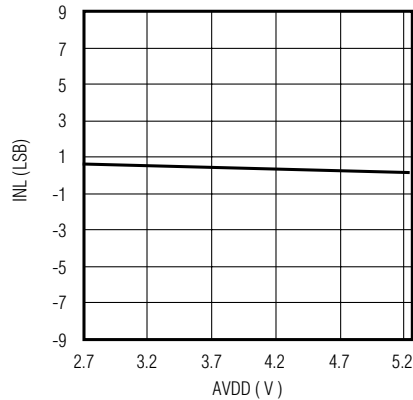
($T_A = +25^\circ\text{C}$, unless otherwise noted.)

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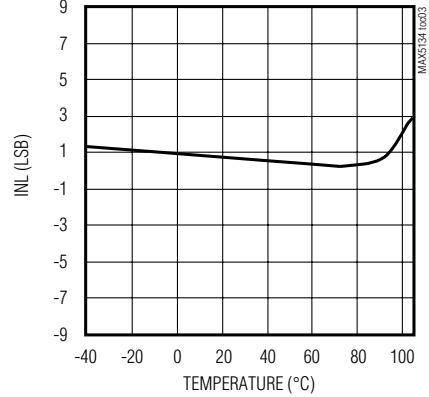
INTEGRAL NONLINEARITY vs. DIGITAL OUTPUT CODE



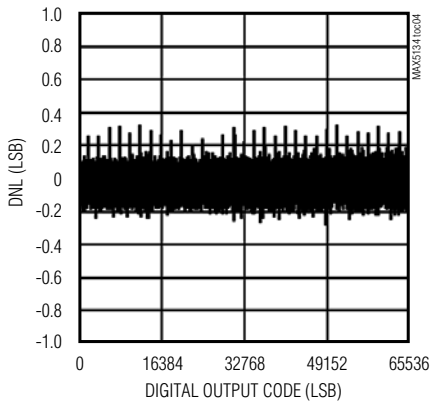
INTEGRAL NONLINEARITY vs. ANALOG SUPPLY VOLTAGE



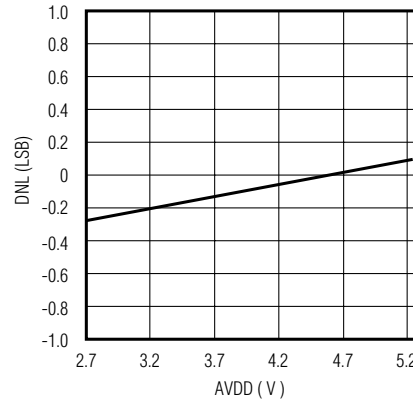
INTEGRAL NONLINEARITY vs. TEMPERATURE



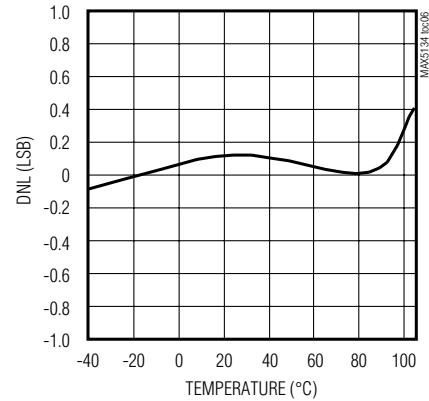
DIFFERENTIAL NONLINEARITY vs. DIGITAL OUTPUT CODE



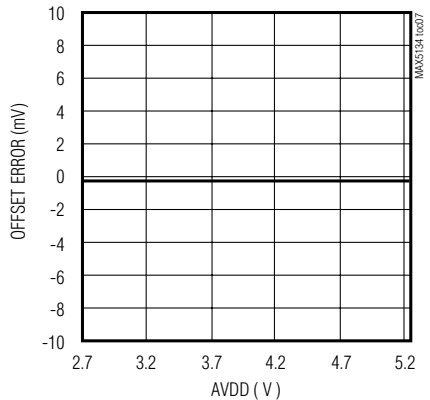
DIFFERENTIAL NONLINEARITY vs. ANALOG SUPPLY VOLTAGE



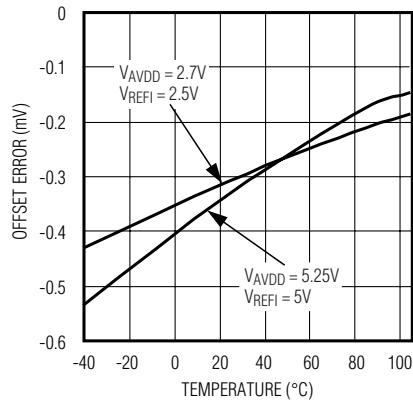
DIFFERENTIAL NONLINEARITY vs. TEMPERATURE



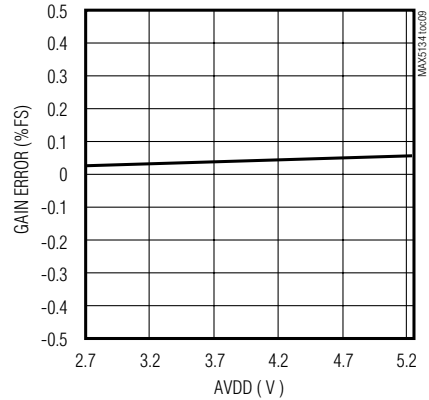
OFFSET ERROR vs. ANALOG SUPPLY VOLTAGE



OFFSET ERROR vs. TEMPERATURE



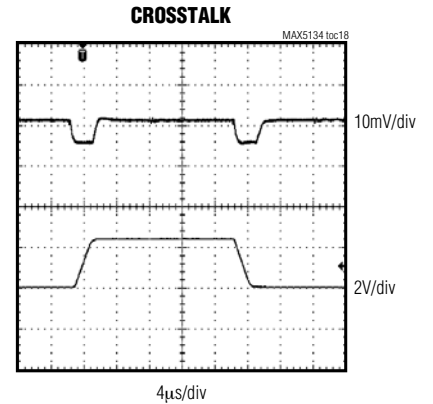
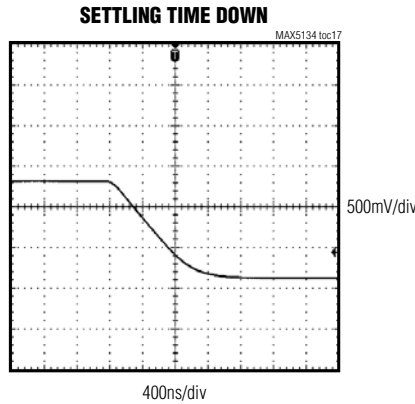
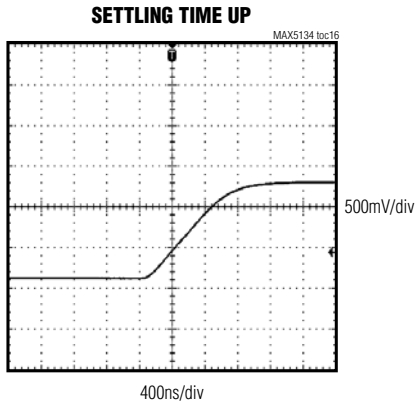
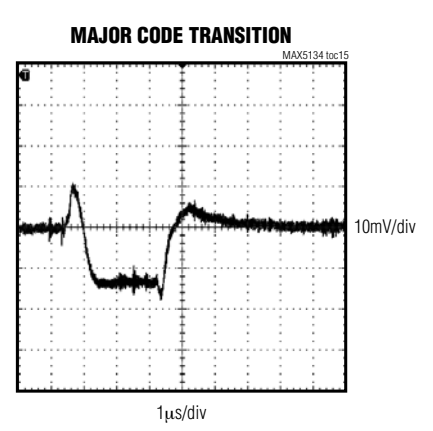
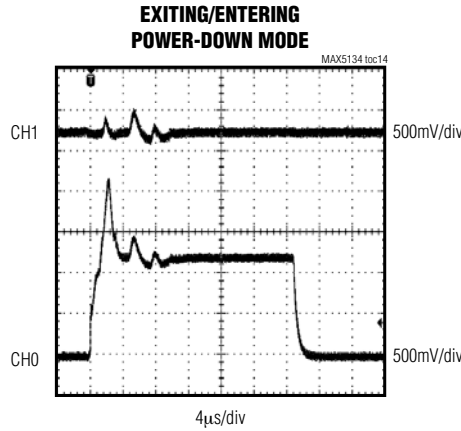
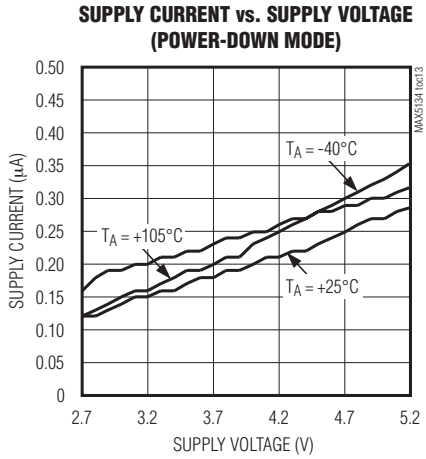
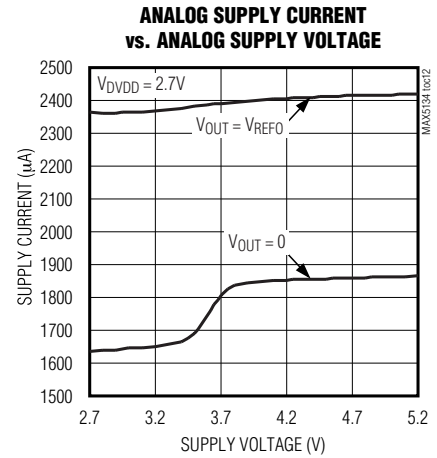
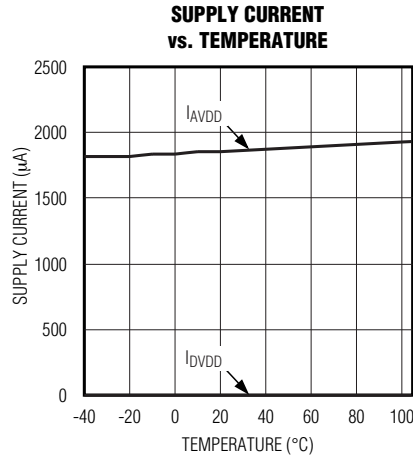
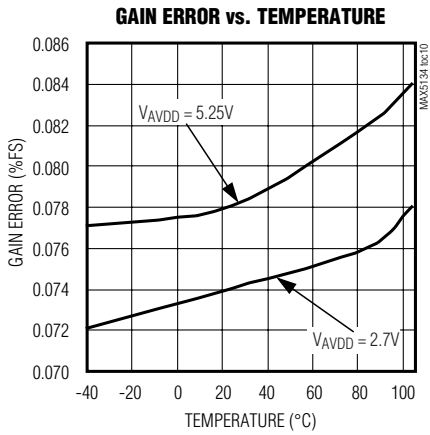
GAIN ERROR vs. ANALOG SUPPLY VOLTAGE



Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

Typical Operating Characteristics (continued)

($T_A = +25^\circ\text{C}$, unless otherwise noted.)



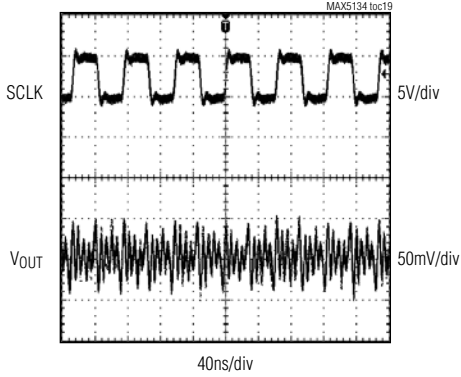
Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

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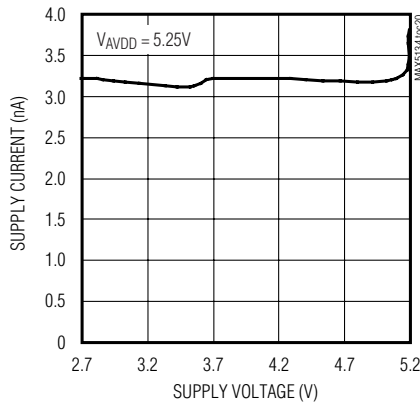
Typical Operating Characteristics (continued)

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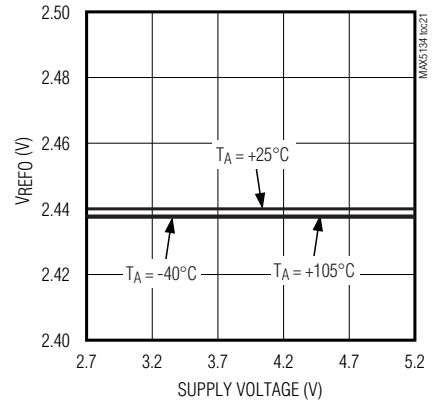
DIGITAL FEEDTHROUGH



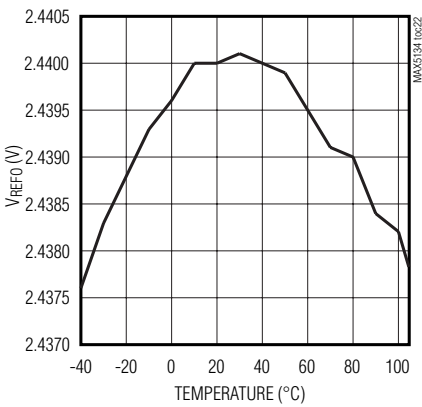
DIGITAL SUPPLY CURRENT vs. DIGITAL SUPPLY VOLTAGE



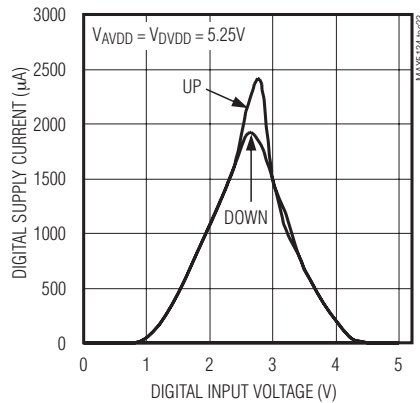
REFERENCE VOLTAGE vs. SUPPLY VOLTAGE



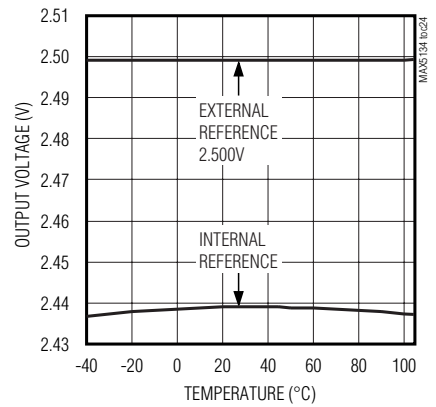
REFERENCE VOLTAGE vs. TEMPERATURE



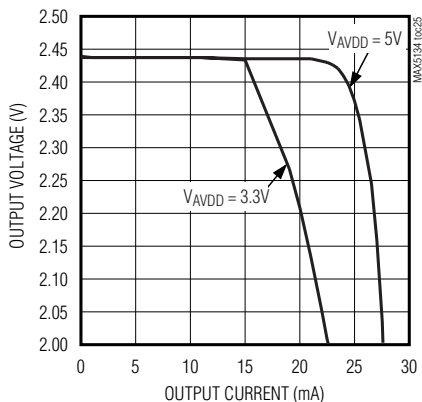
DIGITAL SUPPLY CURRENT vs. DIGITAL INPUT VOLTAGE



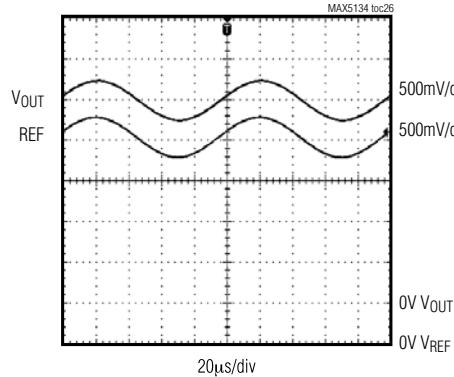
FULL-SCALE OUTPUT vs. TEMPERATURE



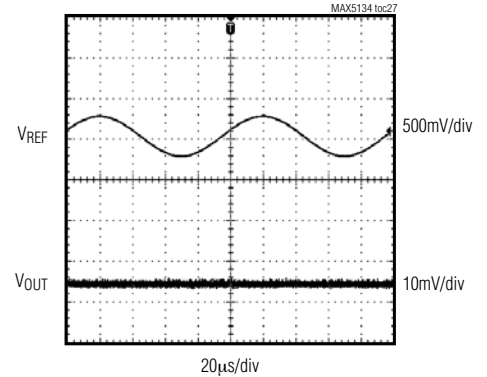
OUTPUT VOLTAGE vs. OUTPUT CURRENT



FULL-SCALE REFERENCE FEEDTHROUGH



ZERO-SCALE REFERENCE FEEDTHROUGH

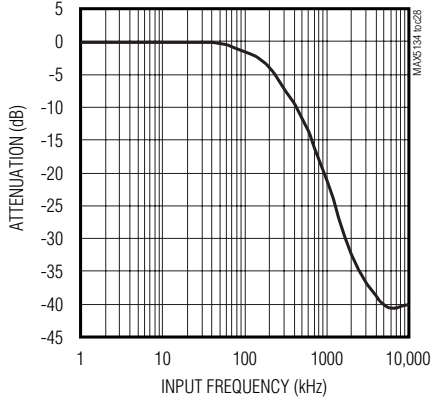


Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

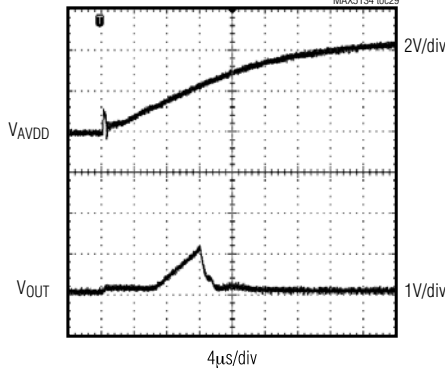
Typical Operating Characteristics (continued)

($T_A = +25^\circ\text{C}$, unless otherwise noted.)

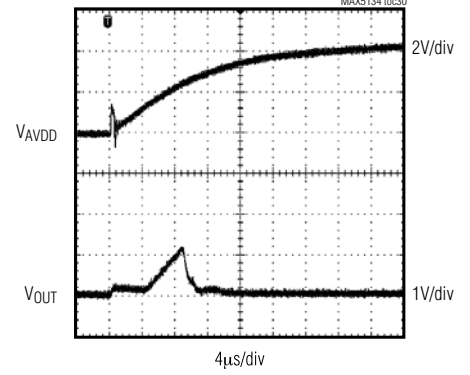
REFERENCE INPUT BANDWIDTH vs. FREQUENCY



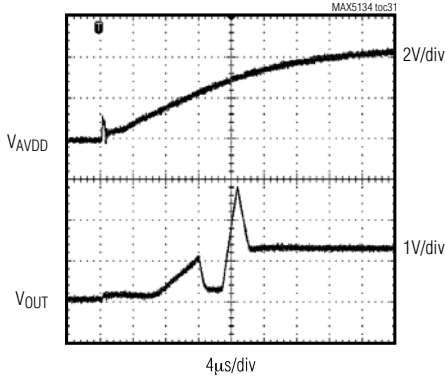
POWER-UP GLITCH, ZERO SCALE, EXTERNAL REFERENCE



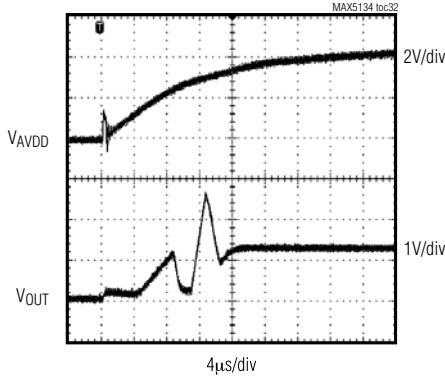
POWER-UP GLITCH, ZERO SCALE, INTERNAL REFERENCE



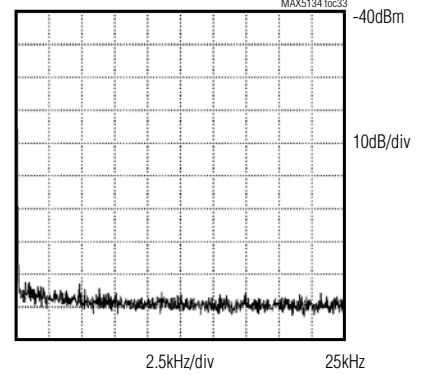
POWER-UP GLITCH, MIDSCALE, EXTERNAL REFERENCE



POWER-UP GLITCH, MIDSCALE, INTERNAL REFERENCE



DC NOISE SPECTRUM, FFT PLOT



Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

MAX5134

Pin Description

PIN	NAME	FUNCTION
1	OUT0	Channel 0 Buffered DAC Output
2, 5, 8, 11, 14, 17, 20, 23	N.C.	No Connection. Not internally connected.
3	DVDD	Digital Power Supply. Bypass DVDD with a 0.1 μ F capacitor to GND.
4	$\overline{\text{READY}}$	Active-Low Ready. Indicated configuration ready. Use $\overline{\text{READY}}$ as $\overline{\text{CS}}$ for consecutive part or as feedback to the μ C.
6	OUT3	Channel 3 Buffered DAC Output
7, 19	GND	Ground
9	DIN	Data In
10	$\overline{\text{CS}}$	Active-Low Chip-Select Input
12	SCLK	Serial-Clock Input
13	OUT2	Channel 2 Buffered DAC Output
15	$\overline{\text{LDAC}}$	Load DAC Input. Active-low hardware load DAC input.
16	$\text{M}/\overline{\text{Z}}$	Power-Up Reset Select. Connect $\text{M}/\overline{\text{Z}}$ to DVDD to power up the DAC outputs to midscale. Connect $\text{M}/\overline{\text{Z}}$ to GND to power up the DAC outputs to zero.
18	OUT1	Channel 1 Buffered DAC Output
21	REFO	Reference Voltage Output
22	REFI	Reference Voltage Input. Bypass REFI with a 0.1 μ F capacitor to GND when using external reference.
24	AVDD	Analog Power Supply. Bypass AVDD with a 0.1 μ F capacitor to GND.
—	EP	Exposed Pad. Internally connected to GND. Connect to a large ground plane to maximize thermal performance. Not intended as an electrical connection point.

Detailed Description

The MAX5134 low-power, quad 16-bit, digital-to-analog converter (DAC) uses a precision internal reference or an external reference for rail-to-rail operation to provide high-linearity buffered voltage outputs. The MAX5134 minimizes the digital noise feedthrough from input to output by powering down the SCLK and DIN input buffers after completion of each 24-bit serial input. On power-up, the MAX5134 resets the DAC outputs to zero or mid-scale, depending on the state of the $\text{M}/\overline{\text{Z}}$ input, providing additional safety for applications that drive valves or other transducers that need to be off on power-up. The MAX5134 contains a segmented resistor string-type DAC, a serial-in parallel-out shift register, a DAC register, power-on reset (POR) circuit, and control logic. On the falling edge of the clock (SCLK) pulse, the serial input (DIN) data is shifted into the device, MSB first. During power-down, an internal 80k Ω resistor pulls DAC outputs to GND.

Output Amplifiers (OUT0–OUT3)

The MAX5134 includes internal buffers for all DAC outputs. The internal buffers provide improved load regulation and transition glitch suppression for the DAC outputs. The output buffers slew at 1.25V/ μ s and drive up to 2k Ω in parallel with 200pF. The analog supply voltage (AVDD) determines the maximum output voltage range of the device as AVDD powers the output buffers.

DAC Reference

Internal Reference

The MAX5134 features an internal reference with a nominal output of +2.44V. Connect REFO to REFI when using the internal reference. Bypass REFO to GND with a 47pF (maximum 100pF) capacitor. Alternatively if heavier decoupling is required, use a 1k Ω series resistor with a 1 μ F capacitor to ground. REFO can deliver up to 100 μ A of current with no degradation in performance. Configure other reference voltages by applying a resistive potential divider with a total resistance greater than 33k Ω from REFO to GND.

Low-Power, Quad 16-Bit, Buffered Voltage-Output DAC

External Reference

The external reference input features a typical input impedance of 113k Ω and accepts an input voltage from +2V to AVDD. Connect an external voltage supply between REF1 and GND to apply an external reference. Leave REFO unconnected. Visit www.maxim-ic.com/products/references for a list of available external voltage-reference devices.

AVDD as Reference

Connect AVDD to REF1 to use AVDD as the reference voltage. Leave REFO unconnected.

Serial Interface

The MAX5134 3-wire serial interface is compatible with MICROWIRE, SPI, QSPI, and DSPs (Figures 2, 3). The interface provides three inputs, SCLK, \overline{CS} , and DIN and one output, \overline{READY} . Use \overline{READY} to verify communication or to daisy-chain multiple devices (see the \overline{READY} section). \overline{READY} is capable of driving a 20pF load with a 30ns (max) delay from the falling edge of SCLK. The chip-select input (\overline{CS}) frames the serial data loading at DIN. Following a chip-select input's high-to-low transi-

tion, the data is shifted synchronously and latched into the input register on each falling edge of the serial-clock input (SCLK). Each serial word is 24 bits. The first 8 bits are the control word followed by 16 data bits (MSB first), as shown in Table 1. The serial input register transfers its contents to the input registers after loading 24 bits of data. To initiate a new data transfer, drive \overline{CS} high, keep \overline{CS} high for a minimum of 33ns before the next write sequence. The SCLK can be either high or low between \overline{CS} write pulses. Figure 1 shows the timing diagram for the complete 3-wire serial-interface transmission.

The MAX5134 digital inputs are double buffered. Depending on the command issued through the serial interface, the input register(s) can be loaded without effecting the DAC register(s) using the write command. To update the DAC registers, either pulse the \overline{LDAC} input low to asynchronously update all DAC outputs, or use the software \overline{LDAC} command. Use the write through commands (see Table 1) to update the DAC outputs immediately after the data is received. Only use the write through command to update the DAC output immediately.

Table 1. Operating Mode Truth Table

24-BIT WORD																		DESC	FUNCTION
CONTROL BITS								DATA BITS											
MSB								LSB											
C7	C6	C5	C4	C3	C2	C1	C0	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6-D0		
0	0	0	0	0	0	0	0	X	X	X	X	X	X	X	X	X	X	NOP	No operation.
0	0	0	0	0	0	0	1	X	X	X	X	DAC 3	DAC 2	DAC 1	DAC 0	X	X	LDAC	Move contents of input to DAC registers indicated by 1's. No effect on registers indicated by 0's.
0	0	0	0	0	0	1	0	X	X	X	X	X	X	X	X	X	X	CLR	Software clear.
0	0	0	0	0	0	1	1	X	X	X	X	DAC 3	DAC 2	DAC 1	DAC 0	READY_EN	X	Power Control	Power down DAC's indicated by 1's. Set READY_EN = 1 to enable \overline{READY} .
0	0	0	0	0	1	0	1	0	0	0	0	0	0	LIN	0	0	0	Linearity	Optimize DAC linearity.
0	0	0	1	DAC 3	DAC 2	DAC 1	DAC 0	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	Write	Write to selected input registers (DAC output not affected).
0	0	1	1	DAC 3	DAC 2	DAC 1	DAC 0	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	Write Through	Write to selected input and DAC registers, DAC outputs updated (write through).
0	0	1	0	0	0	0	0	X	X	X	X	X	X	X	X	X	X	NOP	No operation.

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The 16-bit DAC code is unipolar binary with $V_{OUT} = (\text{code}/65536) \times V_{REF}$. See Table 1 for the serial interface commands

Connect the MAX5134 DVDD supply to the supply of the host DSP or microprocessor. The AVDD supply may be set to any voltage within the operating range of 2.7V to 5.25V, but must be greater than or equal to the DVDD supply.

Writing to the MAX5134

Write to the MAX5134 using the following sequence:

- 1) Drive \overline{CS} low, enabling the shift register.
- 2) Clock 24 bits of data into DIN (C7 first and D0 last), observing the specified setup and hold times. Bits D15–D0 are the data bits that are written to the internal register.

- 3) After clocking in the last data bit, drive \overline{CS} high. \overline{CS} must remain high for 33ns before the next transmission is started.

Figure 1 shows a write operation for the transmission of 24 bits. If \overline{CS} is driven high at any point prior to receiving 24 bits, the transmission is discarded.

READY

Connect \overline{READY} to a microcontroller (μC) input to monitor the serial interface for valid communications. The \overline{READY} pulse appears 24 clock cycles after the negative edge of \overline{CS} (Figure 4). Since the MAX5134 looks at the first 24 bits of the transmission following the falling edge of \overline{CS} , it is possible to daisy chain devices with different command word lengths. \overline{READY} goes high 16ns after \overline{CS} is driven high.

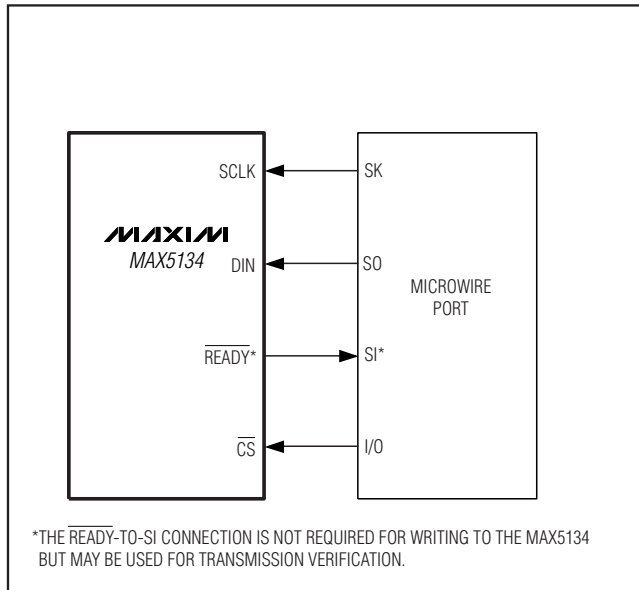


Figure 2. Connections for MICROWIRE

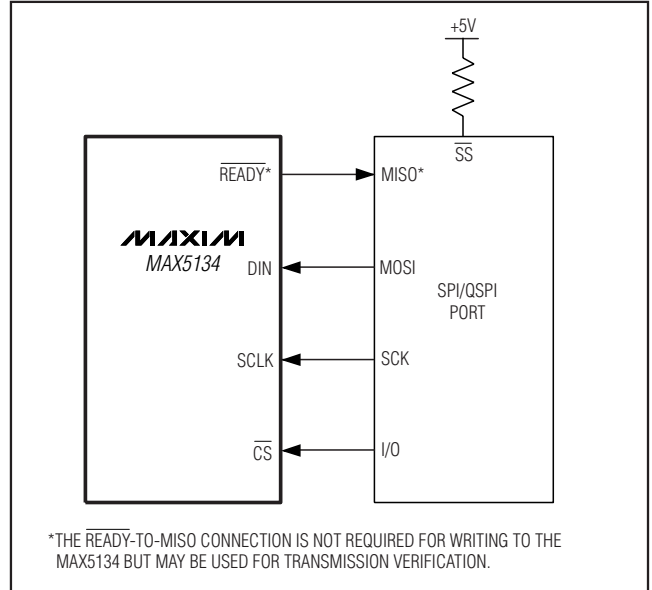


Figure 3. Connections for SPI/QSPI

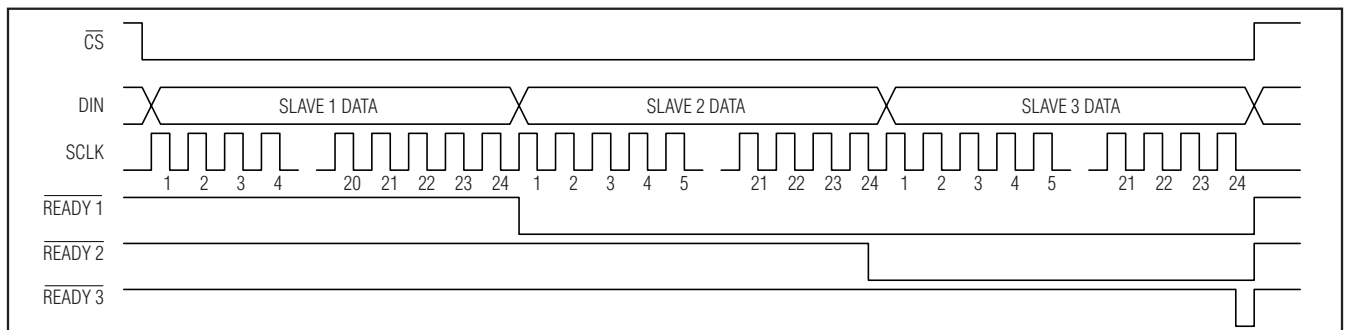


Figure 4. \overline{READY} Timing

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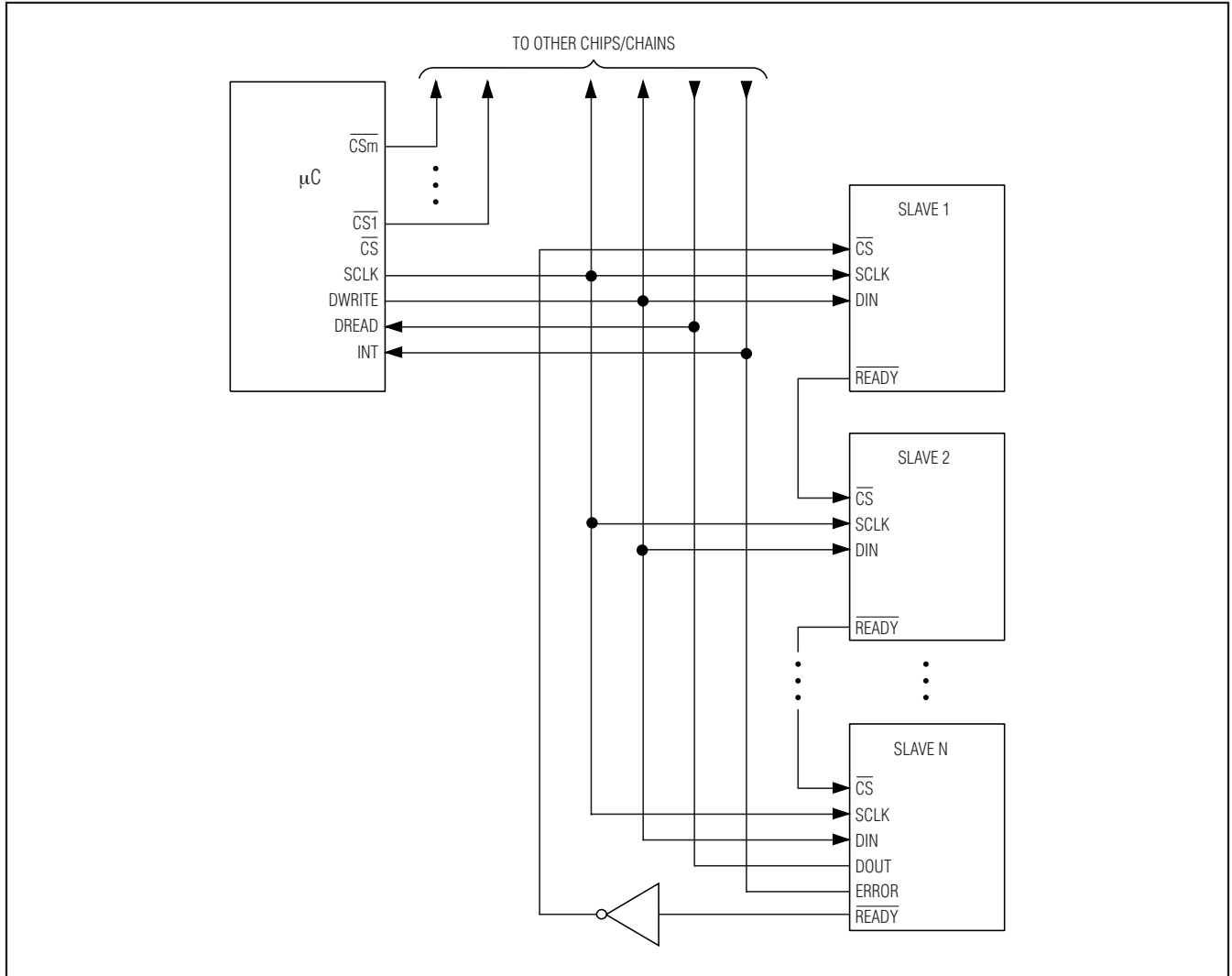


Figure 6. Daisy Chain (\overline{CS} Not Used)

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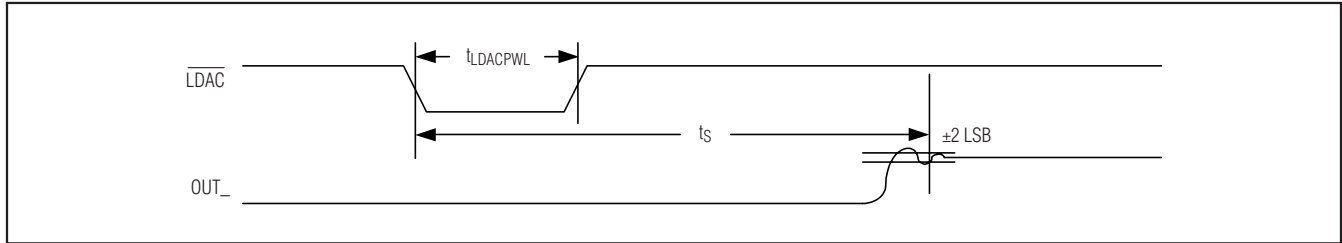


Figure 7. Output Timing

Applications Information

Power-On Reset (POR)

On power-up, the input registers are set to zero, DAC outputs power up to zero or midscale, depending on the configuration of M/\bar{Z} . Connect M/\bar{Z} to GND to power the outputs to GND. Connect M/\bar{Z} to AVDD to power the outputs to midscale.

To optimize DAC linearity, wait until the supplies have settled. Set the LIN bit in the DAC linearity register; wait 10ms, and clear the LIN bit.

Unipolar Output

The MAX5134 unipolar output voltage range is 0 to V_{REF} . The output buffers each drive a load of $2k\Omega$ in parallel with 200pF.

Bipolar Output

Use the MAX5134 in bipolar applications with additional external components (see the *Typical Operating Circuit*).

Power Supplies and Bypassing Considerations

For best performance, use a separate supply for the MAX5134. Bypass both DVDD and AVDD with high-quality ceramic capacitors to a low-impedance ground as close as possible to the device. Minimize lead lengths to reduce lead inductance. Connect both MAX5134 GND inputs to the analog ground plane.

Table 2. Input Code vs. Output Voltage

DAC LATCH CONTENTS		ANALOG OUTPUT, V_{OUT}
MSB	LSB	
1111 1111	1111 1111	$V_{REF} \times (65,535/65,536)$
1000 0000	0000 0000	$V_{REF} \times (32,768/65,536) = 1/2 V_{REF}$
0000 0000	0000 0001	$V_{REF} \times (1/65,536)$
0000 0000	0000 0000	0

Layout Considerations

Digital and AC transient signals on GND inputs can create noise at the outputs. Connect both GND inputs to form the star ground for the DAC system. Refer remote DAC loads to this system ground for the best possible performance. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane, or star connect all ground return paths back to the MAX5134 GND. Carefully lay out the traces between channels to reduce AC crosscoupling and crosstalk. Do not use wire-wrapped boards and sockets. Use shielding to improve noise immunity. Do not run analog and digital signals parallel to one another (especially clock signals) and avoid routing digital lines underneath the MAX5134 package.

Definitions

Integral Nonlinearity (INL)

INL is the deviation of the measured transfer function from a best fit straight line drawn between two codes. This best fit line is a line drawn between codes 3072 and 64,512 of the transfer function, once offset and gain errors have been nullified.

Differential Nonlinearity (DNL)

DNL is the difference between an actual step height and the ideal value of 1 LSB. If the magnitude of the DNL is greater than -1 LSB, the DAC guarantees no missing codes and is monotonic.

Offset Error

Offset error indicates how well the actual transfer function matches the ideal transfer function at a single point. Typically, the point at which the offset error is specified is at or near the zero-scale point of the transfer function.

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Gain Error

Gain error is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

Settling Time

The settling time is the amount of time required from the start of a transition, until the DAC output settles to the new output value within the converter's specified accuracy.

Digital Feedthrough

Digital feedthrough is the amount of noise that appears on the DAC output when the DAC digital control lines are toggled.

Digital-to-Analog Glitch Impulse

A major carry transition occurs at the midscale point where the MSB changes from low to high and all other bits change from high to low, or where the MSB changes from high to low and all other bits change from low to high. The duration of the magnitude of the switching glitch during a major carry transition is referred to as the digital-to-analog glitch impulse.

Digital-to-Analog Power-Up Glitch Impulse

The digital-to-analog power-up glitch is the duration of the magnitude of the switching glitch that occurs as the device exits power-down mode.

DC DAC-to-DAC Crosstalk

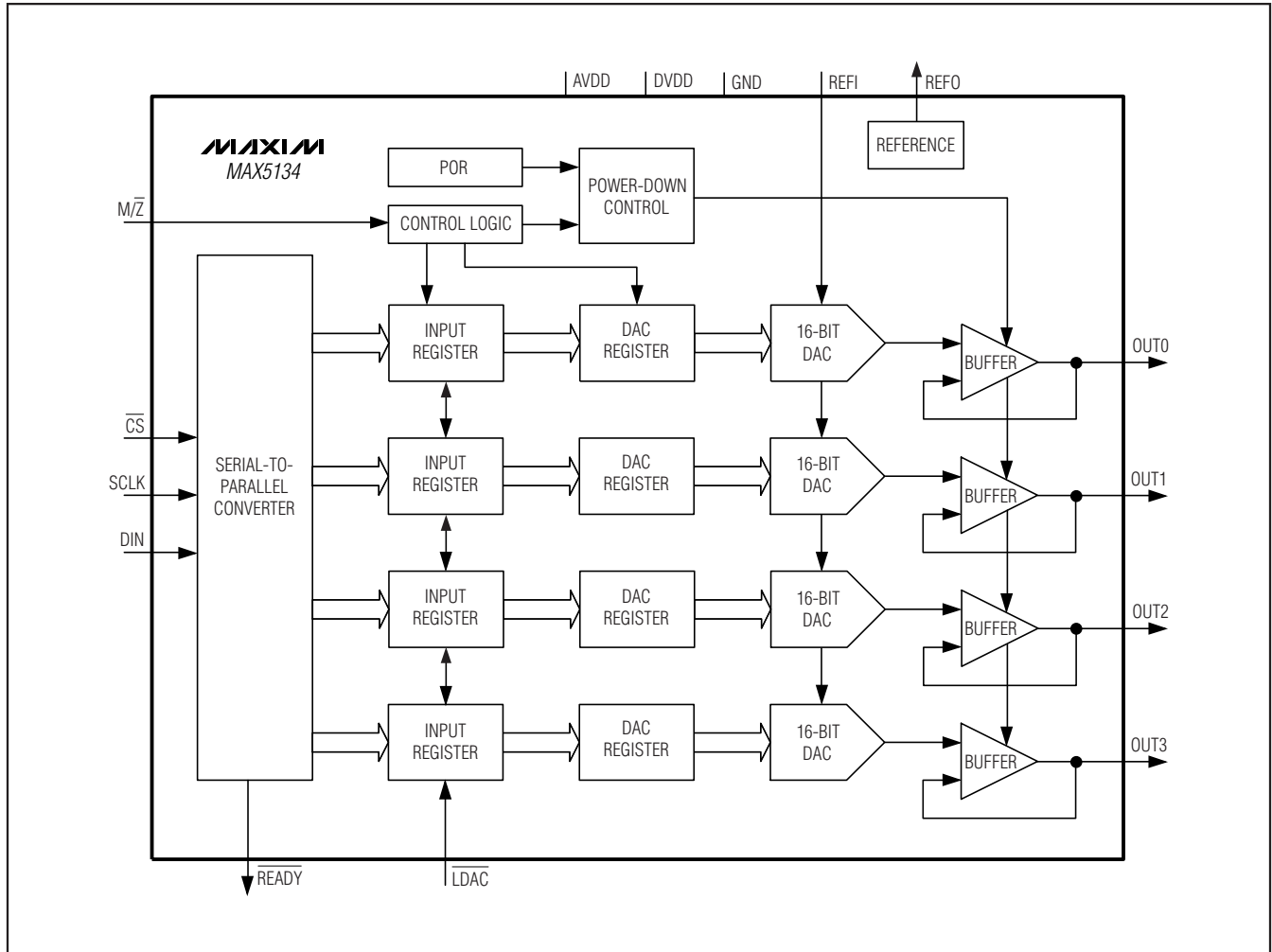
Crosstalk is the amount of noise that appears on a DAC output set to 0 when the other DAC is updated from 0 to AVDD

Chip Information

PROCESS: BiCMOS

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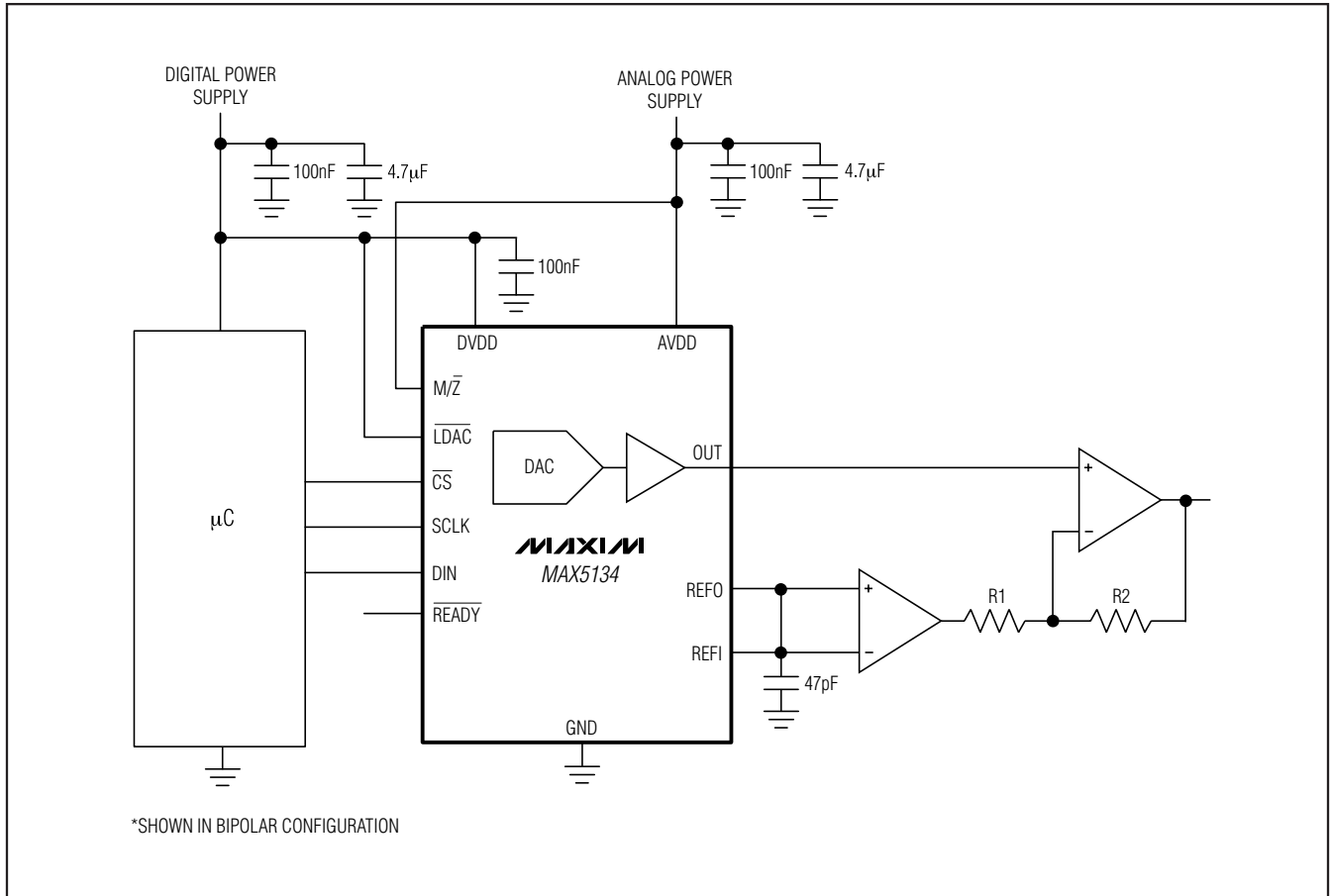
Functional Diagram



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Typical Operating Circuit

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Package Information

For the latest package outline information and land patterns, go to www.maxim-ic.com/packages.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
24 TQFN	T2444-4	21-0139

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