

General Description

The MAX5188 is a dual 8-bit, alternate-phase-update, current-output digital-to-analog converter (DAC) designed for superior performance in systems requiring analog signal reconstruction with low distortion and low-power operation. The MAX5191 provides equal specifications, with on-chip output resistors for voltageoutput operation. Both devices are designed for 10pVs glitch operation to reduce distortion and minimize unwanted spurious signal components at the output. An on-board +1.2V bandgap circuit provides a well-regulated, low-noise reference that may be disabled for external reference operation.

The MAX5188/MAX5191 are designed to provide a high level of signal integrity for the least amount of power dissipation. Both DACs operate from a +2.7V to +3.3V single supply. Additionally, these DACs have three modes of operation: normal, low-power standby, and full shutdown. A full shutdown provides the lowest possible power dissipation with a maximum shutdown current of 1µA. A fast wake-up time (0.5µs) from standby mode to full DAC operation allows for power conservation by activating the DACs only when required.

The MAX5188/MAX5191 are available in a 28-pin QSOP package and are specified for the extended (-40°C to +85°C) temperature range. For pin-compatible 10-bit versions, refer to the MAX5182/MAX5185 data sheet.

Applications

Signal Reconstruction Applications Digital Signal Processing Arbitrary Waveform Generators **Imaging Applications**

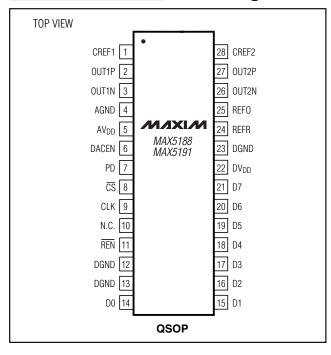
Features

- ♦ +2.7V to +3.3V Single-Supply Operation
- ♦ Wide Spurious-Free Dynamic Range: 70dB at fOUT = 2.2MHz
- **♦ Fully Differential Outputs for Each DAC**
- ♦ ±0.5% FSR Gain Mismatch Between DAC Outputs
- ♦ Low-Current Standby or Full Shutdown Modes
- ♦ Internal +1.2V Low-Noise Bandgap Reference
- ♦ Small 28-Pin QSOP Package

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE		
MAX5188BEEI	-40°C to +85°C	28 QSOP		
MAX5191BEEI	-40°C to +85°C	28 QSOP		

Pin Configuration



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For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642. or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

AV _{DD} , DV _{DD} to AGND, DGND Digital Inputs to DGND	
OUT1P. OUT1N. OUT2P. OUT2N. CREF1.	0.37 10 +07
CREF2 to AGND	0.3V to +6V
V _{REF} to AGND	0.3V to +6V
AV _{DD} to DV _{DD}	±3.3V
AGND to DGND	0.3V to +0.3V
Maximum Current into Any Pin	50mA

Continuous Power Dissipation ($T_A = +70^\circ$	°C)
28-Pin QSOP (derate 9.00mW/°C above	
Operating Temperature Ranges	,
MAX5188/MAX5191BEEI	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(AV_{DD} = DV_{DD} = +3V \pm 10\%, AGND = DGND = 0, f_{CLK} = 40MHz, I_{FS} = 1mA, 400\Omega$ differential output, $C_L = 5pF$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25$ °C.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
STATIC PERFORMANCE								
Resolution	N			8			Bits	
Integral Nonlinearity	INL			-1	±0.25	+1	LSB	
Differential Nonlinearity	DNL	Guaranteed mo	notonic	-1	±0.25	+1	LSB	
		MAX5188		-1		+1	LSB	
Zero-Scale Error		MAX5191		-4		+4	LSB	
Full-Scale Error		(Note 1)		-20	±4	+20	LSB	
DYNAMIC PERFORMANCE								
Output Settling Time		To ±0.5LSB erro	or band		25		ns	
Glitch Impulse					10		pVs	
Spurious-Free Dynamic Range	SFDR	f 40M11-	fout = 500kHz		72		dBc	
to Nyquist	SEDIN	$f_{CLK} = 40MHz$	f _{OUT} = 2.2MHz, T _A = +25°C	57	70			
Total Harmonic Distortion to Nyquist	THD	f _{CLK} = 40MHz	f _{OUT} = 500kHz		-70		dB	
			f _{OUT} = 2.2MHz, T _A = +25°C		-68	-63	1 UD	
Signal-to-Noise Ratio		SNR f _{CLK} = 40MHz	f _{OUT} = 500kHz		52		dB	
to Nyquist	SINH	ICTK = 40IVIUS	$f_{OUT} = 2.2MHz, T_A = +25^{\circ}C$	46	52		7 UB	
DAC-to-DAC Output Isolation		f _{OUT} = 2.2MHz			-60		dB	
Clock and Data Feedthrough		All 0s to all 1s	All 0s to all 1s		50		nVs	
Output Noise					10		pA/√Hz	
Gain Mismatch Between DAC Outputs		f _{OUT} = 2.2MHz, T _A = +25°C			±0.5	±1	LSB	
ANALOG OUTPUT		I						
Full-Scale Output Voltage	V _{FS}				400		mV	
Voltage Compliance of Output				-0.3		0.8	V	
Output Leakage Current		DACEN = 0, MAX5188 only		-1		1	μΑ	
Full-Scale Output Current	IFS	MAX5188 only		0.5	1	1.5	mA	
DAC External Output Resistor Load		MAX5188 only			400		Ω	

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ELECTRICAL CHARACTERISTICS (continued)

 $(AV_{DD} = DV_{DD} = +3V \pm 10\%$, AGND = DGND = 0, $f_{CLK} = 40MHz$, $I_{FS} = 1mA$, 400Ω differential output, $C_L = 5pF$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

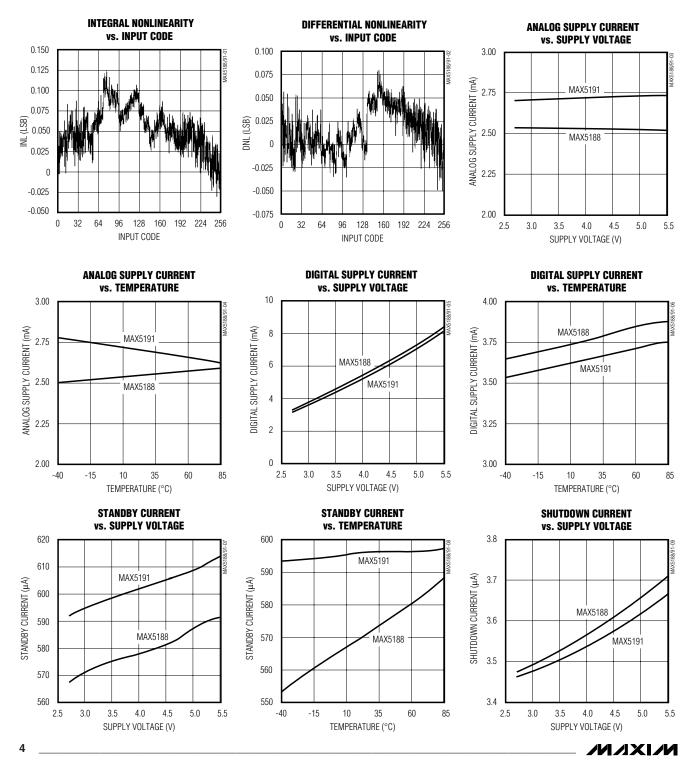
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
REFERENCE						
Output Voltage Range	V _{REF}		1.12	1.2	1.28	V
Output Voltage Temperature Drift	TCV _{REF}			50		ppm/°C
Reference Output Drive Capability	IREFOUT			10		μΑ
Reference Supply Rejection				0.5		mV/V
Current Gain (IFS / IREF)				8		mA/mA
POWER REQUIREMENTS						
Analog Power-Supply Voltage	AV _{DD}		2.7		3.3	V
Analog Supply Current	lavdd	PD = 0, DACEN = 1, digital inputs at 0 or DVDD		2.7	5	mA
Digital Power-Supply Voltage	DV _{DD}		2.7		3.3	V
Digital Supply Current	I _{DVDD}	PD = 0, DACEN = 1, digital inputs at 0 or DV _{DD}		4.2	5	mA
Standby Current	ISTANDBY	PD = 0, DACEN = 0, digital inputs at 0 or DV _{DD}		1	1.5	mA
Shutdown Current	ISHDN	PD = 1, DACEN = X, digital inputs at 0 or DV _{DD} (X = don't care)		0.5	1	μΑ
LOGIC INPUTS AND OUTPUTS						
Digital Input High Voltage	VIH		2			V
Digital Input Low Voltage	VIL				0.8	V
Digital Input Current	I _{IN}	V _{IN} = 0 or DV _{DD}			±1	μΑ
Digital Input Capacitance	CIN			10		рF
TIMING CHARACTERISTICS						
DAC1 DATA to CLK Rise Setup Time	t _{DS1}		10			ns
DAC2 DATA to CLK Fall Setup Time	t _{DS2}		10			ns
DAC1 CLK Rise to DATA Hold Time	t _{DH1}		0			ns
DAC2 CLK Fall to DATA Hold Time	t _{DH2}		0			ns
CS Fall to CLK Rise Time				5		ns
CS Fall to CLK Fall Time				5		ns
DACEN Rise Time to Vout				0.5		μs
PD Fall Time to V _{OUT}				50		μs
Clock Period	tCLK		25			ns
Clock High Time	tch		10			ns
Clock Low Time	tcL		10			ns

Note 1: Excludes reference and reference resistor (MAX5191) tolerance.



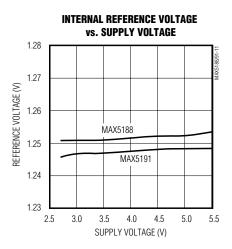
Typical Operating Characteristics

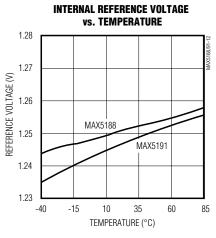
 $(AV_{DD} = DV_{DD} = +3V, AGND = DGND = 0, 400\Omega \text{ differential output, I}_{FS} = 1mA, C_L = 5pF, T_A = +25^{\circ}C, unless otherwise noted.)$

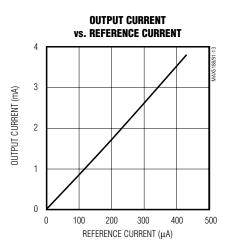


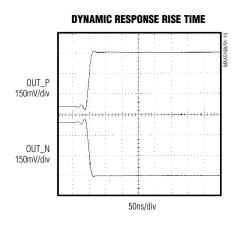
Typical Operating Characteristics (continued)

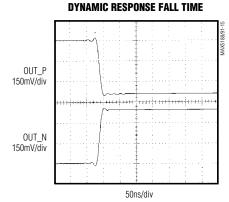
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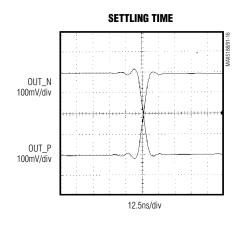


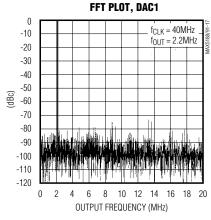


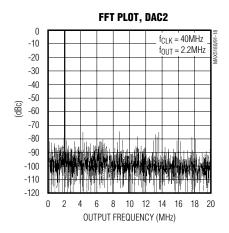










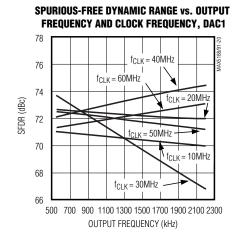


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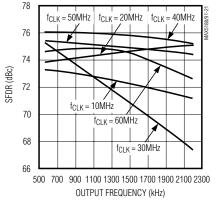
Typical Operating Characteristics (continued)

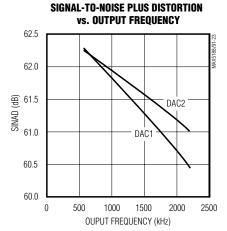
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SPURIOUS-FREE DYNAMIC RANGE vs. CLOCK FREQUENCY 100 90 DAC2 DAC1 60 10 15 20 25 30 35 40 45 50 55 60 CLOCK FREQUENCY (MHz)

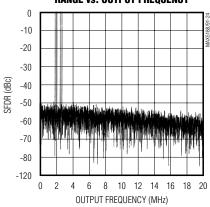




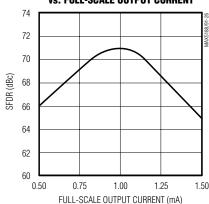




MULTITONE SPURIOUS-FREE DYNAMIC RANGE vs. OUTPUT FREQUENCY







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Pin Description

PIN	NAME	FUNCTION			
1	CREF1	Reference Bias Bypass, DAC1			
2	OUT1P	Positive Analog Output, DAC1. Current output for the MAX5188; voltage output for the MAX5191.			
3	OUT1N	Negative Analog Output, DAC1. Current output for the MAX5188; voltage output for the MAX5191.			
4	AGND	Analog Ground			
5	AV _{DD}	Analog Positive Supply, +2.7V to +3.3V			
6	DACEN	DAC Enable, Digital Input 0: Enter DAC standby mode with PD = DGND 1: Power-up DAC with PD = DGND X: Enter shutdown mode with PD = DVDD (X = don't care)			
7	Power-Down Select PD 0: Enter DAC standby mode (DACEN = DGND) or power-up DAC (DACEN = DV _{DD}) 1: Enter shutdown mode				
8	CS	Active-Low Chip Select			
9	CLK	Clock Input			
10	N.C.	Not Connected. Do not connect to this pin.			
11	REN	Active-Low Reference Enable. Connect to DGND to activate on-chip +1.2V reference.			
12, 13, 23	DGND	Digital Ground			
14	D0	Data Bit D0 (LSB)			
15–20	D1-D6	Data Bits D1-D6			
21	D7	Data Bit D7 (MSB)			
22	DV _{DD}	Digital Supply, +2.7V to +3.3V			
24	REFR	Reference Input			
25	REFO	Reference Output			
26	OUT2N	Negative Analog Output, DAC2. Current output for the MAX5188; voltage output for the MAX5191.			
27	OUT2P	Positive Analog Output, DAC2. Current output for the MAX5188; voltage output for the MAX5191.			
28	CREF2	Reference Bias Bypass, DAC2			



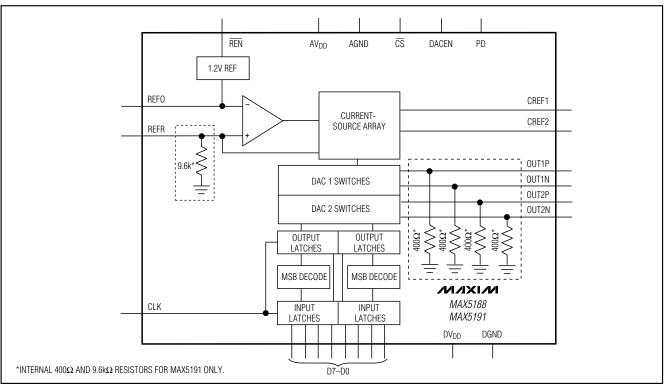


Figure 1. Functional Diagram

Detailed Description

The MAX5188/MAX5191 are dual 8-bit digital-to-analog converters (DACs) capable of operating with clock speeds up to 40MHz. Each of these dual converters consists of separate input and DAC registers, followed by a current-source array capable of generating up to 1.5mA full-scale output current (Figure 1). An integrated +1.2V voltage reference and control amplifier determine the data converters' full-scale output currents/voltages. Careful reference design ensures close gain matching and excellent drift characteristics. The MAX5191's voltage output operation features matched 400Ω on-chip resistors that convert the current from the current array into a voltage.

Internal Reference and Control Amplifier

The MAX5188/MAX5191 provide an integrated 50ppm/°C, +1.2V, low-noise bandgap reference that can be disabled and overridden by an external reference voltage. REFO serves either as an input for an external reference or as an output for the integrated reference. If REN is connected to DGND, the internal reference is selected and REFO provides a +1.2V output.

Due to its limited $10\mu A$ output drive capability, the REFO pin must be buffered with an external amplifier if heavier loading is required.

The MAX5188/MAX5191 also employ a control amplifier, designed to simultaneously regulate the full-scale output current IFS for both MAX5188/MAX5191 outputs. The output current is calculated as follows:

$$IFS = 8 \times IREF$$

where IREF is the reference output current (IREF = V_{REFO} / R_{SET}) and IFS is the full-scale output current. RSET is the reference resistor that determines the amplifier's output current (Figure 2) on the MAX5188. This current is mirrored into the current-source array, where it is equally distributed between matched current segments and summed to valid output current readings for the DACs.

Inside the MAX5191, each output current (DAC1 and DAC2) is converted to an output voltage (V_{OUT1} , V_{OUT2}) with two internal, ground-referenced, 400Ω load resistors. Using the internal +1.2V reference voltage, the integrated reference output current resistor of the MAX5191 (RSET = $9.6k\Omega$) sets IREF to 125µA and IFS to 1mA.

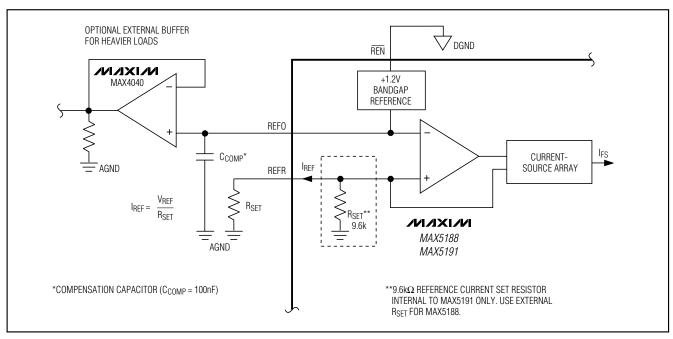


Figure 2. Setting IFS with the Internal +1.2V Reference and Control Amplifier

External Reference

To disable the MAX5188/MAX5191's internal reference, connect REN to DVDD. A temperature-stable external reference may now be applied to drive the REFO pin (Figure 3) to set the full-scale output. Choose a reference that can supply at least 150µA to drive the bias circuit that generates the cascode current for the current array. For improved accuracy and drift performance, choose a fixed output voltage reference such as the +1.2V, 25ppm/°C MAX6520 bandgap reference.

Standby Mode

To enter the lower-power standby mode, connect digital inputs PD and DACEN to DGND. In standby, both the reference and the control amplifier are active with the current array inactive. To exit this condition, DACEN

must be pulled high with PD held at DGND. The MAX5188/MAX5191 typically require 50µs to wake up and allow both the outputs and the reference to settle.

Shutdown Mode

For lowest power consumption, the MAX5188/MAX5191 provide a power-down mode in which the reference, control amplifier, and current array are inactive and the DAC's supply current is reduced to $1\mu A$. To enter this mode, connect PD to DVDD. To return to active mode, connect PD to DGND and DACEN to DVDD. About 50 μ s are required for the devices to leave shutdown mode and settle their outputs to the values prior to shutdown. Table 1 lists the power-down mode selection.

Table 1. Power-Down Mode Selection

PD (POWER-DOWN SELECT)	DACEN (DAC ENABLE)	POWER-DOWN MODE	OUTPUT STATE		
0	0	Standby	MAX5188	High-Z	
0		Stariuby	MAX5191	AGND	
0	1	Wake-Up	Last state prior to standby mode		
1	X		Shutdown	MAX5188	High-Z
		Shutdown	MAX5191	AGND	

X = Don't care

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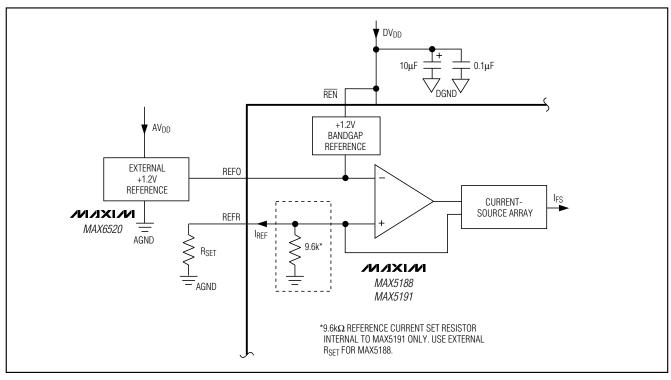


Figure 3. MAX5188/MAX5191 Using an External Reference

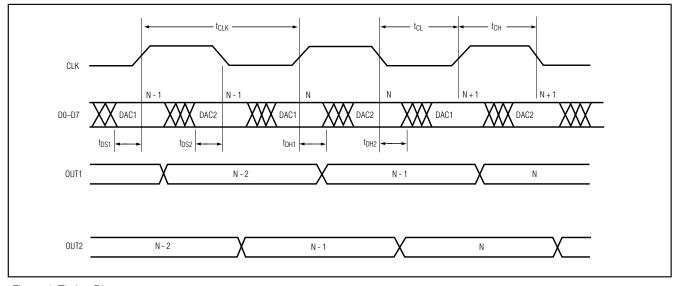


Figure 4. Timing Diagram

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Timing Information

Both internal DAC cells write to their outputs in alternate phase (Figure 4). The input latch of the first DAC (DAC1) is loaded after the clock signal transitions high. When the clock signal transitions low, the input latch of the second DAC (DAC2) is loaded. The contents of the first input latch are shifted into the DAC1 register on the rising edge of the clock; the contents of the second input latch are shifted into the input register of DAC2 on the falling edge of the clock. Both outputs are updated on alternate phases of the clock.

Outputs

The MAX5188 outputs are designed to supply 1mA full-scale output currents into 400Ω loads in parallel with a capacitive load of 5pF. The MAX5191 features integrat-

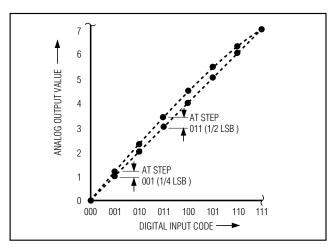


Figure 5a. Integral Nonlinearity

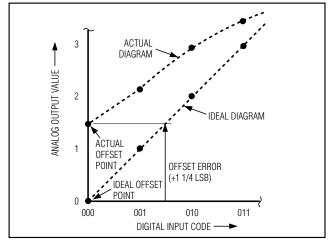


Figure 5c. Offset Error

ed 400Ω resistors that restore the array currents into proportional, differential voltages of 400mV. These differential output voltages can then be used to drive a balun transformer or a low-distortion, high-speed operational amplifier to convert the differential voltage into a single-ended voltage.

Applications Information

Static and Dynamic Performance Definitions

Integral Nonlinearity

Integral nonlinearity (INL) (Figure 5a) is the deviation of the values on an actual transfer function from either a best-straight-line fit (closest approximation to the actual transfer curve) or a line drawn between the endpoints

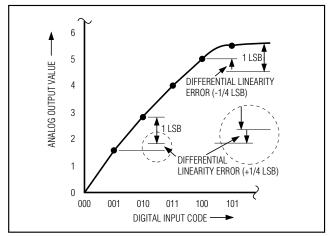


Figure 5b. Differential Nonlinearity

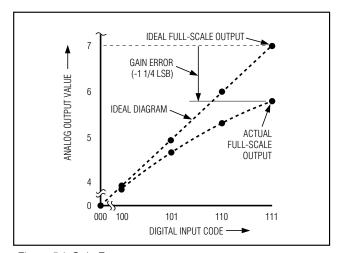


Figure 5d. Gain Error

of the transfer function once offset and gain errors have been nullified. For a DAC, the deviations are measured at every single step.

Differential Nonlinearity

Differential nonlinearity (DNL) (Figure 5b) is the difference between an actual step height and the ideal value of 1LSB. A DNL error specification of less than 1LSB guarantees no missing codes and a monotonic transfer function.

Offset Error

Offset error (Figure 5c) is the difference between the ideal and the actual offset point. For a DAC, the offset point is the step value when the digital input is zero. This error affects all codes by the same amount and can usually be compensated by trimming.

Gain Error

Gain error (Figure 5d) is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

Settling Time

The settling time is the amount of time required from the start of a transition until the DAC output settles its new output value to within the converter's specified accuracy.

Digital Feedthrough

Digital feedthrough is the noise generated on a DAC's output when any digital input transitions. Proper board layout and grounding will significantly reduce this noise, but there will always be some feedthrough caused by the DAC itself.

Total Harmonic Distortion

Total harmonic distortion (THD) is the ratio of the RMS sum of the input signal's first four harmonics to the fundamental itself. This is expressed as:

THD = 20 × log
$$\left(\frac{\sqrt{(V_2^2 + V_3^2 + V_4^2 + V_5^2)}}{V_1} \right)$$

where V_1 is the fundamental amplitude, and V_2 through V_5 are the amplitudes of the 2nd- through 5th-order harmonics.

Spurious-Free Dynamic Range

Spurious-free dynamic range (SFDR) is the ratio of RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest distortion component.

Differential to Single-Ended Conversion

The MAX4108 low-distortion, high input-bandwidth amplifier may be used to generate a voltage from the MAX5188's current-array output. The differential voltage across OUT1P (or OUT2P) and OUT1N (or OUT2N) is converted into a single-ended voltage by designing an appropriate operational amplifier configuration as shown in Figure 6.

Grounding and Power-Supply Decoupling

Grounding and power-supply decoupling strongly influence the performance of the MAX5188/MAX5191. Unwanted digital crosstalk may couple through the input, reference, power-supply, and ground connections, which may affect dynamic specifications like SNR or SFDR. In addition, electromagnetic interference (EMI) can either couple into or be generated by the MAX5188/MAX5191. Therefore, grounding and power-supply decoupling guidelines for high-speed, high-frequency applications should be closely followed.

First, a multilayer PC board with separate ground and power-supply planes is recommended. High-speed signals should run on controlled impedance lines directly above the ground plane. Since the MAX5188/MAX5191 have separate analog and digital ground buses (AGND and DGND, respectively), the PC board should also have separate analog and digital ground sections with only one point connecting the two. Digital signals should run above the digital ground plane, and analog signals should run above the analog ground plane.

Both devices have two power-supply inputs: analog V_{DD} (AV_{DD}) and digital V_{DD} (DV_{DD}). Each AV_{DD} input should be decoupled with parallel $10\mu F$ and $0.1\mu F$ ceramic-chip capacitors as close to the pin as possible. Their opposite ends should have the shortest possible connection to the ground plane. The DV_{DD} pins should also have separate $10\mu F$ and $0.1\mu F$ capacitors, again adjacent to their respective pins. Try to minimize the analog load capacitance for proper operation. For best performance, bypass CREF1 and CREF2 with low-ESR, $0.1\mu F$ capacitors to AV_{DD}.

The power-supply voltages should also be decoupled with large tantalum or electrolytic capacitors at the point they enter the PC board. Ferrite beads with additional decoupling capacitors forming a pi network could also improve performance.

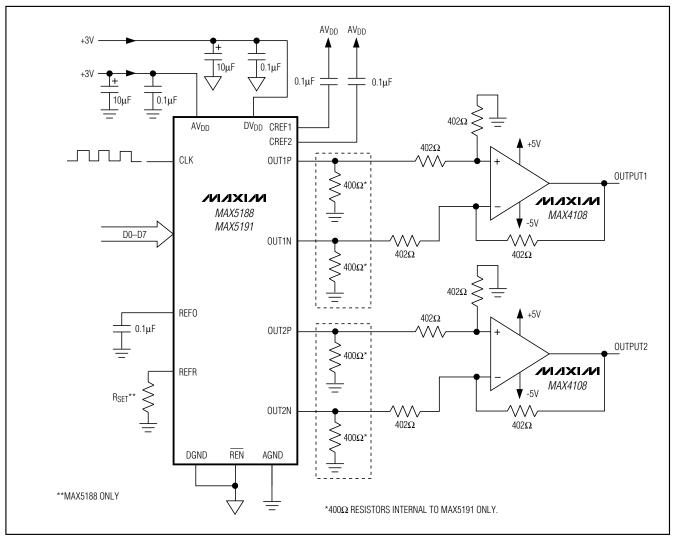


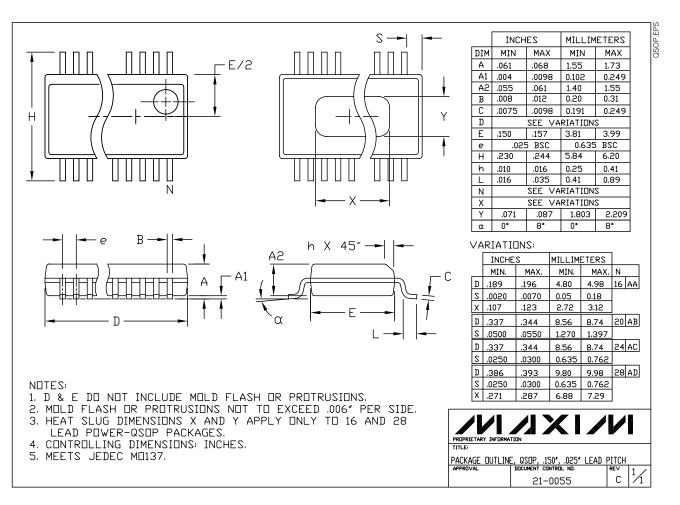
Figure 6. Differential to Single-Ended Conversion Using the MAX4108 Low-Distortion Amplifier

Chip Information

TRANSISTOR COUNT: 9464

SUBSTRATE CONNECTED TO GND

Package Information



Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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