For Security camera and load Mobile display AIE Adaptive Image Enhancer Series



TV encoder built in Adaptive Image Enhancer BU6520KV

Description

BU6520KV is TV encoder IC with AIE (image treating technology by ROHM's hardware) image correction.

Features

00		
1)	Input/output data format	ITU-R BT.656-4 or YCbCr with synchronization signal
		Data format YCbCr 8bit
		Data range is full range or based on ITU-R BT.601
		Pixel clock
		NTSC 27MHz and 28.63636MHz
		PAL 27MHz, 28.375MHz and 35.46895MHz
2)	Video output data format	NTSC/PAL SD-TV composite video output (CVBS)
3)	Image Correction	Build-in dynamic range correction with Adaptive Image Enhancer (AIE)
		Build-in edge-emphasizing filter and gamma filter
4)	Built-in DAC	10bit DAC 1ch (output load R=75Ω)
5)	Built-in slave function for	2-line serial interface
		The registers in BU6520KV from the outside can be set
6)	Built-in master function for	or SPI BUS
		The registers setting value can be stored in external EEPROM
		When reset is released or the mode is changed, the setting of the registers in BU6520KV
		can be automatically set
7)	Voltage source(Typical)	Compatible with 4 power sources(VDD=1.50V, VDDIO=3.30V, VDDI ² C=3.30V, AVDD=3.30V)
8)	Package	48pin VQFP Package (VQFP48C)

Application

Security camera, Intercom with camera, Drive recorder, and Web camera etc.

Lineup

Parameter	Power source voltage	Input interface	Control interface	Output Interface	TV Encoder	Temperature range of operating	Package
BU6520KV	1.4-1.6V(V _{DD} Core) 2.7-3.6V(V _{DD} I/o,AV _{DD})	8bit YUV=4:2:2 parallel •CCIR601 •CCIR656	l ² C/ Seral EEPROM Interface	8bit YUV=4:2:2 parallel •CCIR601 •CCIR656	NTSC PAL Composite output	-40°C∼+85°C	VQFP48C

I²C BUS is a registered trademark of Philips

•Absolute maximum ratings

Parameter	Symbol	Rating	Unit
Applied power source voltage 1	VDDIO1	-0.3~+4.2	V
Applied power source voltage 2	VDDI ² C	-0.3~+4.2	V
Applied power source voltage 3	AVDD	-0.3~+4.2	V
Applied power source voltage 4	VDD	-0.3~+2.1	V
Input voltage	VIN	-0.3~IO_LVL+0.3*1	V
Storage temperature range	Tstg	-40~+125	°C
Power dissipation	PD	400*2	mW

Recommended	operating range
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Parameter	Symbol	Rating	Unit
Applied power source voltage 1 (IO)	VDDIO	2.70~3.60(Typ:3.3V)	V
Applied power source voltage 2 (IO)	VDDI ² C	2.70~3.60(Typ:3.3V)	V
Applied power source voltage 3 (DAC)	AVDD	2.70~3.60(Typ:3.3V)	V
Applied power source voltage 4 (CORE)	VDD	1.40~1.60(Typ:1.5V)	V
Input voltage range	VIN	0~IO_LVL*1	V
Operating temperature range	Topr	-40~+85	°C

*Please supply power source in order of VDD \rightarrow (VDDIO,VDDI²C,AVDD)

*1 : IO_LVL is a generic name of VDDIO, VDDI²C, and AVDD.

 $^{*}2$: IC only. In the case exceeding 25°C, 4.0mW should be reduced at the rating 1°C.

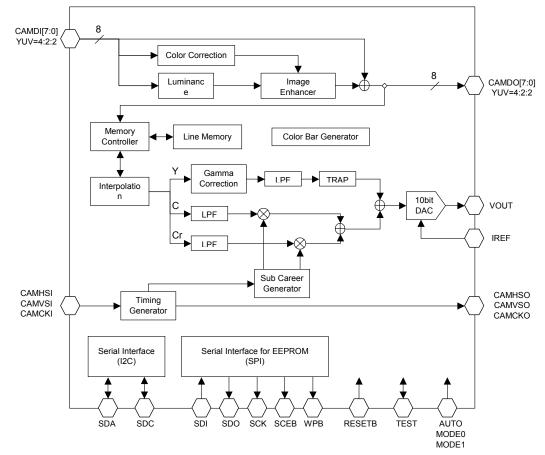
Electric characteristics

(Unless otherwise specified VDD=1.50V, VDDIO=VDDI²C=3.3V, AVDD=3.3V, GND=0.0V, Ta=25 ℃, f_{in}=35.5MHz)

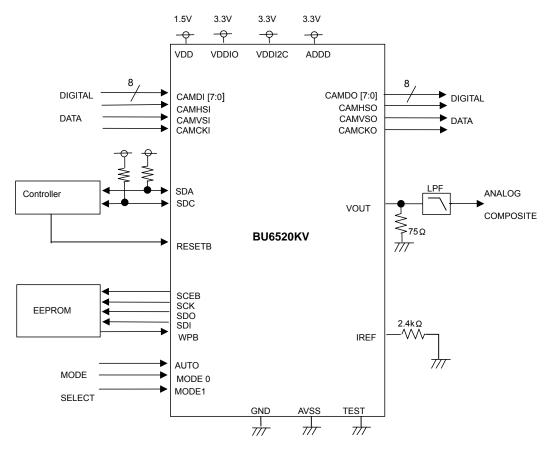
Parameter	Symbol	Limits		Unit	Condition	
Parameter	Symbol	MIN.	TYP.	MAX.	Unit	Condition
Input frequency	F _{IN}	2	-	35.5	MHz	CAMCKI(DUTY45%~55%)
Operational current	IDD1	-	57	-	mA	In the enhance mode (35.5 MHz) (Total value of current of VDD, VDDIO, and VDDI ² C)
Static current	IDDst1	-	-	50	uA	In the sleep mode, input pin: GND
Input "H" current 1	IIH	-10	-	10	uA	VIH=IO_LVL
Input "H" current 2	IL	-10	-	10	uA	VIL=GND
Pull-down current	IPD	25	50	100	uA	VIH=IO_LVL
Input "L" current 1	VIH1	IO_LVL x0.8	-	IO_LVL +0.3	V	Normal input (Including input mode of I/O terminal)
Input "L" current 2	VIL1	-0.3	-	IO_LVL x0.2	V	Normal input (Including input mode of I/O terminal)
Input "H" voltage 1	VIH2	IO_LVL x0.85	-	IO_LVL +0.3	V	Hysteresis input (RESETB, CAMCKI, AUTO, MODE0, MODE1)
Input "L" voltage 1	VIL2	-0.3	-	IO_LVL x0.15	V	Hysteresis input (RESETB, CAMCKI, AUTO, MODE0, MODE1)
Input "H" voltage 2	VOH	IO_LVL -0.4	-	IO_LVL	V	IOH=-1.0mA(DC) (including output mode of I/O terminal)
Input "L" voltage 2	VOL	0.0	-	0.4	V	IOL=1.0mA(DC) (including output mode of I/O terminal)
Resolution (DAC)	RES	-	-	10	Bits	
Operational Current (DAC)	IDD2	-	38	-	mA	R _L =37.5 Ω, R _{IREF} =2.4k Ω (Only the current value of AVDD)
Static consumption current (DAC)	IDDst2	-	-	5	uA	Input terminal =GND setting
Integral Non-linearity	INL	-	±4.0	±8.0	LSB	R _L =37.5Ω, R _{IREF} =2.4kΩ
Differential Non-linearity	DNL	-	±1.0	±2.0	LSB	R _L =37.5 Ω 、R _{IREF} =2.4k Ω
Voltage of Full scale	VFS	1.1	1.25	1.4	V	$R_L=37.5\Omega$, $R_{IREF}=2.4k\Omega$

* IO_LVL is a generic name of VDDIO, VDDI²C, and AVDD.

Block Diagram



Recommended Application Circuit



Terminal functions

					_	
PIN Name	In/Out	Active Level	Init	Function explanation	Power Source System	I/O type
SDI	In	DATA	-	SPI BUS data input	1	А
CAMDI7	In	DATA	-	Data input bit 7	1	С
CAMDI6	In	DATA	-	Data input bit 6	1	С
CAMDI5	In	DATA	-	Data input bit 5	1	С
CAMDI4	In	DATA	-	Data input bit 4	1	С
GND	-	GND	-	Common GROUND	1,2,4	-
VDD	-	PWR	-	CORE P power source	4	-
CAMDI3	In	DATA	-	Data input bit 3	1	С
CAMDI2	In	DATA	-	Data input bit 2	1	С
CAMDI1	In	DATA	-	Data input bit 1	1	С
CAMDI0	In	DATA	-	Data input bit 0	1	С
CAMHSI	In	*	-	Horizontal timing input	1	С
CAMVSI	In	*	-	Vertical timing input	1	С
CAMCKI	In	CLK	-	Clock input	1	E
GND	-	GND	-	Common GROUND	1,2,4	-
VDDIO	-	PWR	-	Digital IO power source	1	-
CAMDO0	Out	DATA	Low	Data output bit 0	1	F
CAMDO1	Out	DATA	Low	Data output bit 1	1	F
CAMDO2	Out	DATA	Low	Data output bit 2	1	F
CAMDO3	Out	DATA	Low	Data output bit 3	1	F
CAMDO4	Out	DATA	Low	Data output bit 4	1	F
CAMDO5	Out	DATA	Low	Data output bit 5	1	F
CAMDO6	Out	DATA	Low	Data output bit 6	1	F
CAMDO7	Out	DATA	Low	Data output bit 7	1	F
	SDI SDI CAMDI7 CAMDI6 CAMDI5 CAMDI4 GND CAMDI3 CAMDO3 CAMDO4 CAMDO5 CAMDO6	SDIInSDIInCAMDI7InCAMDI6InCAMDI5InCAMDI4InCAMDI4InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMDI3InCAMD01InCAMCKIInGND-CAMD03OutCAMD04OutCAMD03OutCAMD05Out	SDIInDATACAMDI7InDATACAMDI6InDATACAMD15InDATACAMD14InDATACAMD14InDATACAMD14InDATACAMD14InDATACAMD14InDATACAMD13InDATACAMD13InDATACAMD14InDATACAMD15InDATACAMD14InDATACAMD15InTACAMD16InATACAMD17InCLKCAMCKIInCLKGND-GNDVDD10-PWRCAMD01OutDATACAMD02OutDATACAMD03OutDATACAMD04OutDATACAMD05OutDATA	SDIInDATACAMDI7InDATA-CAMDI6InDATA-CAMD15InDATA-CAMD14InDATA-CAMD14InDATA-CAMD14InDATA-CAMD14InDATA-CAMD13InDATA-CAMD13InDATA-CAMD12InDATA-CAMD11InDATA-CAMD12InDATA-CAMD13InDATA-CAMD14InDATA-CAMD15In*-CAMD10InATA-CAMD11InCLK-CAMD13In*-CAMD14InCLK-CAMD15In*-CAMCKIInCLK-CAMD01OutDATALowCAMD02OutDATALowCAMD03OutDATALowCAMD04OutDATALowCAMD05OutDATALow	SDIInDATA-SPI BUS data inputCAMDI7InDATA-Data input bit 7CAMDI6InDATA-Data input bit 6CAMDI5InDATA-Data input bit 5CAMDI4InDATA-Data input bit 4CAMDI5InDATA-Data input bit 4GND-GND-Common GROUNDVDD-PWR-CORE P power sourceCAMDI3InDATA-Data input bit 3CAMDI2InDATA-Data input bit 1CAMDI3InDATA-Data input bit 1CAMDI1InDATA-Data input bit 1CAMDI3InDATA-Data input bit 1CAMDI4InDATA-Data input bit 1CAMDI5In*-Horizontal timing inputCAMDI3In*-Clock inputCAMDI4InCLK-Clock inputCAMVSIIn*-Digital IO power sourceCAMVSIInCLK-Digital IO power sourceCAMD00OutDATALowData output bit 1CAMD01OutDATALowData output bit 2CAMD02OutDATALowData output bit 3CAMD03OutDATALowData output bit 3CAMD04OutDATALowData output bit 3CAMD05OutDA	SDIInDATASPI BUS data input1CAMDI7InDATAData input bit 71CAMDI6InDATAData input bit 61CAMDI5InDATAData input bit 51CAMDI4InDATAData input bit 41CAMDI4InDATAData input bit 41CAMDI4InDATAData input bit 41CAMDI4InDATACommon GROUND1,2,4/DDGNDCORE P power source4CAMDI3InDATAData input bit 31CAMDI2InDATAData input bit 11CAMDI3InDATAData input bit 11CAMDI3InDATAData input bit 11CAMDI3InDATAData input bit 11CAMDI3InDATAData input bit 11CAMDI3In*Vertical timing input1CAMDI3In*Vertical timing input1CAMDI4InCLK-Clock input1CAMCKIInCLK-Digital IO power source1CAMCKIInCLK-Digital IO power source1CAMD00OutDATALowData output bit 01CAMD01OutDATALow

* "*" in the Active Level column indicates that it may be changed during set-up of the register.

* Init indicates pin status when released from reset.

* In the power system column, "1" stands for VDDIO, "2" stands for VDDI²C, "3" stands for AVDD, "4" stands for VDD.

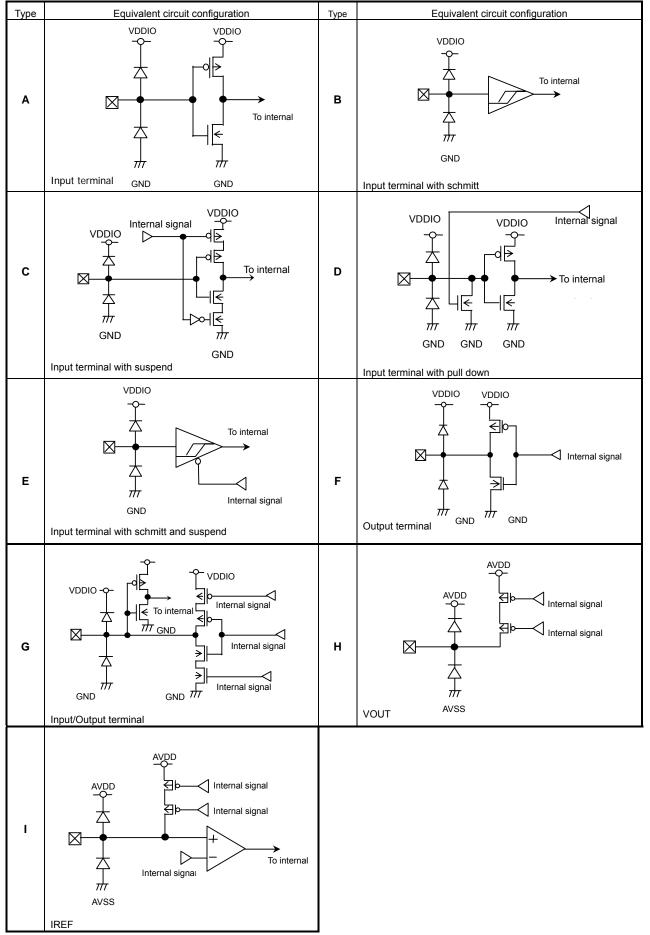
PIN No.	PIN Name	In/Out	Active Level	Init	Function explanation	Power Source System	I/O type
25	CAMHSO	Out	*	Low	Horizontal timing output	1	F
26	CAMVSO	Out	*	Low	Vertical timing output	1	F
27	САМСКО	Out	CLK	Low	Clock output	1	F
28	GND	-	GND	-	Common GROUND	1,2,4	-
29	VDD	-	PWR	-	CORE power source	4	-
30	AUTO	In	High	PD *1	Auto register setting enable signal	1	D
31	MODE0	In	DATA	PD *1	Auto register setting mode select bit 0	1	D
32	MODE1	In	DATA	PD *1	Auto register setting mode select bit 1	1	D
33	VOUT	Out	Analog	-	Analog composite output	3	Н
34	AVSS	-	GND	-	Analog GROUND for DAC	3	-
35	IREF	Out	Analog	-	Reference voltage for DAC	3	I
36	AVDD	-	PWR	-	Analog power source for DAC	3	-
37	GND	-	GND	-	Common GROUND	1,2,4	-
38	VDDI ² C	-	PWR	-	Digital IO power source (For 2-line serial interface input/output)	2	-
39	SDA	In/Out	DATA	In	2-line serial interface data input/output	2	G
40	SDC	In/Out	CLK	In	2-line serial interface clock input	2	G
41	RESETB	In	Low	-	System reset signal	1	В
42	TEST	In	High	PD *1	Test mode terminal (Connect to GND)	1	D
43	GND	-	GND	-	Common GROUND	1,2,4	-
44	VDDIO	-	PWR	-	Digital IO power source	1	-
45	WPB	Out	Low	Low	Write protect signal to EEPROM	1	F
46	SCEB	Out	Low	High	Chip select signal to EEPROM	1	F
47	SCK	Out	CLK	Low	SPI BUS clock	1	F
48	SDO	Out	DATA	Low	SPI BUS data output	1	F

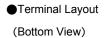
* "*" in the Active Level column indicates that it may be changed during set-up of the register.

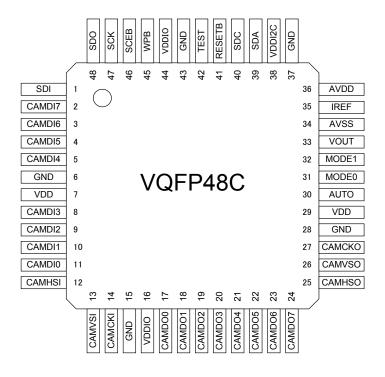
* Init column indicates pin status when released from reset.

* In the power system column, "1" stands for VDDIO, "2" stands for VDDI²C, "3" stands for AVDD, "4" stands for VDD.

*1 : Pull-down status.



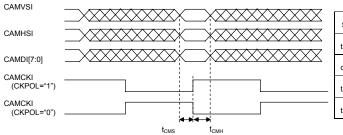




Timing Chart

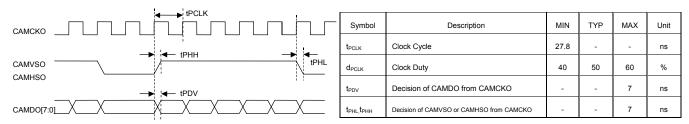
1. Date input / output interface

Data input interface timing



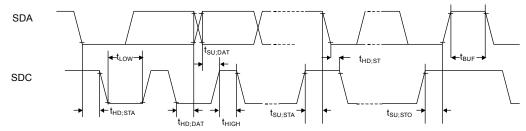
Symbol	Description	MIN	TYP	MAX	Unit
t _{САМСКІ}	Clock Cycle	27.8	-	-	ns
d _{CAMCKI}	Clock Duty	45	50	55	%
t _{CMS}	CAMCKI Rise / Fall Camera set-up Time	8	-	-	ns
t _{смн}	CAMCKI Rise / Fall Camera Hold Time	6	-	-	ns

Data output interface timing



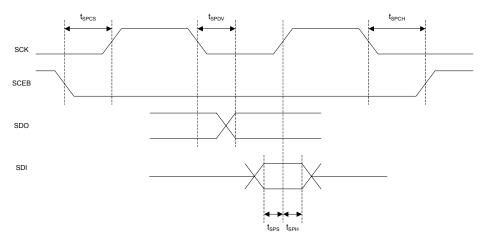
2. I²C BUS interface

I²C BUS interface timing



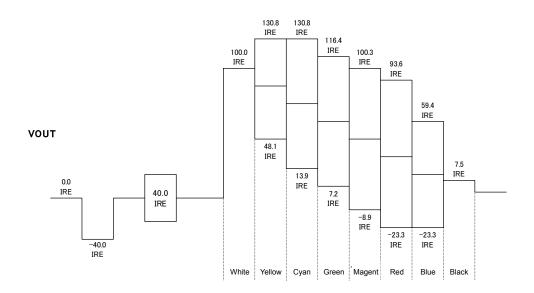
Symbol	Parameter	MIN.	TYP.	MAX.	Unit
fSCL	SDC Clock Frequency	0	-	400	kHz
tHD;STA	Hold-time(repetition) [START] conditions	0.6			110
(HD,31A	The first clock pulse is generated after this period.	0.0	-	-	us
fLOW	The "L" period of SDC clock	1.3	-	-	us
tHIGH	The "H" period of SDC clock	0.6	-	-	us
tSU;STA	Setup time of repetitive 『START』 conditions	0.6	-	-	us
tHD;DAT	Data hold time	0			us
tSU;DAT	Data setup time	100	-	-	ns
tSU;STO	Setup time of the STOP conditions	0.6	-	-	us

SPI BUS interface timing



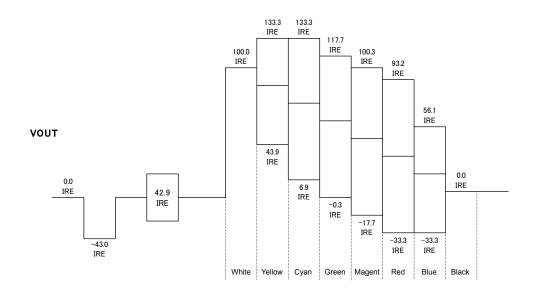
Symbol	Description	MIN	TYP	MAX	Unit
t _{spclk}	Clock Cycle	2	736	8192	t _{самскі}
d _{SPCLK}	Clock Duty	45	50	55	%
t _{SPCS}	SCK Rise SCEB set-up Time	4	738-1105	1102	t _{camcki}
t _{spch}	SCK Fall after SCEB Rise Time	2	751	8319	t _{самскі}
t _{SPDV}	Decision of SDO from SCK Fall	-	-	28	ns
t _{SPS}	SCK Rise SDI set-up Time	-	-	28	ns
t _{SPH}	SCK Rise SDI Hold Time	-	-	28	ns

When the automatic reading function with the AUTO pin is used, it becomes timing of SCEB to SCK as above. It is possible to access from the register of BU6520KV to interface.In that case, SCEB is controlled by the register. After the value is set to the register, the SCEB pin is changed into the logic set at once.



(Note) (*1) The white level and the black level can be changed by the setting.

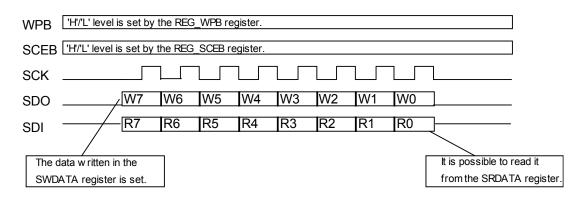
Output waveform in PAL 4.



(Note) (*1) The white level and the black level can be changed by the setting.

Slave address is 70h. The subaddress increment automatically when continuously accessing(read / write) it 2 times or more. SDI SCI K Р S 9 9 START Slave STOP R/W ACK Sub address ACK Data ACK condition condition address Data transmission part Write Slave address w A(S)/ NA(S s Sub address Data Data Data Ρ A(S A(S A(S) A(S (0) sequence (70h) Read Slave address W Slave address R A(M)/ NA(M) Ρ S A(S Sub address A(S S A(S Data A(N Data (0) (70h) (70h) (1) sequence S = START condition A(S) = acknowledge by slave NA(S) = not acknowledge by slave A(M) = acknowledge by master P = STOP condition NA(M) = not acknowledge by master

6. SPI BUS Format



* REG_WPB, REG_SCEB, SWDATA, and SRDATA in figure are the register names, and the each function is as follows.

REG_WPB : Set WPB Terminal logic. Register value output direct.

REG_SCEB : Set SCEB Terminal logic. Register value output direct

SWDATA[7:0] : Write data to EEPROM. It is transfer MSB first.

SRDATA[7:0] : Read data from EEPROM. Convert MSB first.

The SCK clock frequency is as follows.

SCK frequency = CAMCKI frequency ÷ 2^(SPIPREDIV+1) ÷(SPIDIV+1)

Register range : SPIPREDIV = $0 \sim 7$. SPIDIV = $0 \sim 31$ When CAMCKI is 27MHz, SCK becomes 3.3kHz from 13.5MHz.

(1)Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.

(2)Operating conditions

These conditions represent a range within which characteristics can be provided approximately as expected. The electrical characteristics are guaranteed under the conditions of each parameter.

(3)Reverse connection of power supply connector

The reverse connection of power supply connector can break down ICs. Take protective measures against the breakdown due to the reverse connection, such as mounting an external diode between the power supply and the IC's power supply terminal.

(4)Power supply line

Design PCB pattern to provide low impedance for the wiring between the power supply and the GND lines.

In this regard, for the digital block power supply and the analog block power supply, even though these power supplies has the same level of potential, separate the power supply pattern for the digital block from that for the analog block, thus suppressing the diffraction of digital noises to the analog block power supply resulting from impedance common to the wiring patterns. For the GND line, give consideration to design the patterns in a similar manner.

Furthermore, for all power supply terminals to ICs, mount a capacitor between the power supply and the GND terminal. At the same time, in order to use an electrolytic capacitor, thoroughly check to be sure the characteristics of the capacitor to be used present no problem including the occurrence of capacity dropout at a low temperature, thus determining the constant.

(5)GND voltage

Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.

(6)Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.

(7)Operation in strong electromagnetic field

Be noted that using ICs in the strong electromagnetic field can malfunction them.

(8)Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.

(9)Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals, such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the guaranteed value of electrical characteristics.

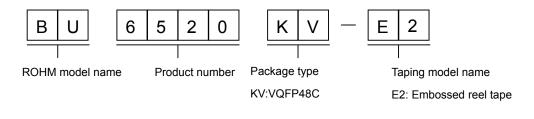
(10)Ground wiring pattern

If small-signal GND and large-current GND are provided, It will be recommended to separate the large-current GND pattern from the small-signal GND pattern and establish a single ground at the reference point of the set PCB so that resistance to the wiring pattern and voltage fluctuations due to a large current will cause no fluctuations in voltages of the small-signal GND. Pay attention not to cause fluctuations in the GND wiring pattern of external parts as well.

(11)External capacitor

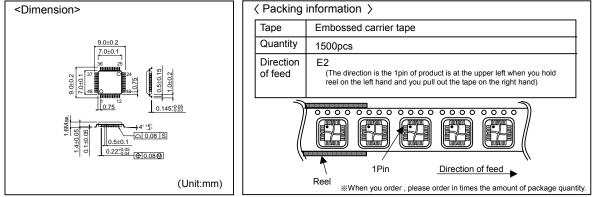
In order to use a ceramic capacitor as the external capacitor, determine the constant with consideration given to a degradation in the nominal capacitance due to DC bias and changes in the capacitance due to temperature, etc.

Order Model Name Selection



Tape and Reel information

VQFP48C



- The contents described herein are correct as of January, 2008
 The contents described herein are subject to change without notice. For updates of the latest information, please contact and confirm with ROHM CO.LTD.
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- The products described herein utilize silicon as the main material.
 The products described herein are not designed to be X ray proof.

The products listed in this catalog are designed to be used with ordinary electronic equipment or devices (such as audio visual equipment, office-automation equipment, communications devices, electrical appliances and electronic toys).

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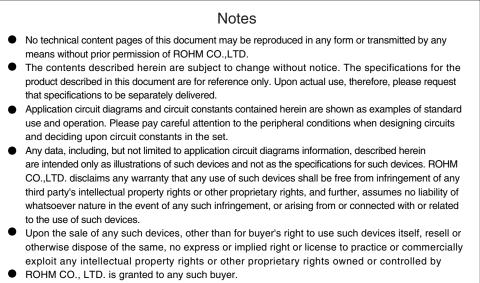
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