

LMH6622

Dual Wideband, Low Noise, 160MHz, Operational Amplifiers

General Description

The LMH6622 is a dual high speed voltage feedback operational amplifier specifically optimized for low noise. A voltage noise specification of 1.6nV/ $\sqrt{\text{Hz}}$, a current noise specification 1.5pA/ $\sqrt{\text{Hz}}$, a bandwidth of 160MHz, and a harmonic distortion specification that exceeds 90dBc combine to make the LMH6622 an ideal choice for the receive channel amplifier in ADSL, VDSL, or other xDSL designs. The LMH6622 operates from $\pm 2.5 \text{V}$ to $\pm 6 \text{V}$ in dual supply mode and from $\pm 5 \text{V}$ to $\pm 12 \text{V}$ in single supply configuration. The LMH6622 is stable for $A_{\text{V}} \geq 2$ or $A_{\text{V}} \leq -1$. The fabrication of the LMH6622 on National Semiconductor's advanced VIP10 process enables excellent (160MHz) bandwidth at a current consumption of only 4.3mA/amplifier. Packages for this dual amplifier are the 8-lead SOIC and the 8-lead MSOP.

Features

 $V_S = \pm 6V$, $T_A = 25$ °C, Typical values unless specified

■ Bandwidth $(A_V = +2)$ 160MHz

■ Supply Voltage Range ±2.5V to ±6V +5V to +12
■ Slew rate \$5V/us

■ Slew rate 85V/µs
■ Supply current 4.3mA/amp

■ Input common mode voltage —4.75V to +5.7V

■ Imput common mode voltage —4.75v to +5.7v
■ Output Voltage Swing (R_L = 100Ω) ±4.6v

■ Input voltage noise 1.6nV/ √Hz

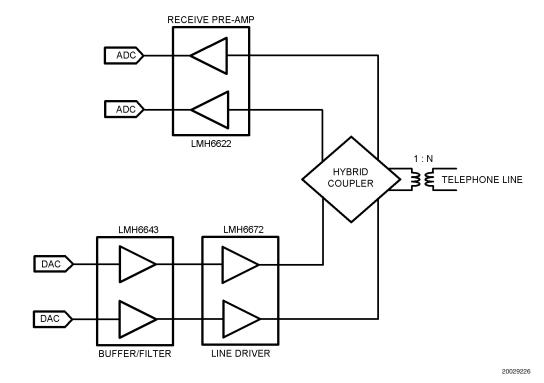
■ Input current noise 1.5pA/√Hz ■ Linear output current 90mA

■ Linear output current 90mA ■ Excellent harmonic distortion 90dBc

Applications

- xDSL receiver
- Low noise instrumentation front end
- Ultrasound preamp
- Active filters
- Cellphone basestation

xDSL Analog Front End



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DS200292

Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

ESD Tolerance

Soldering Information

Infrared or Convection (20 sec) 235°C

Wave Soldering (10 sec) 260°C Storage Temperature Range -65°C to $+150^{\circ}\text{C}$ Junction Temperature (Note 4) $+150^{\circ}\text{C}$

Operating Ratings (Note 1)

Supply Voltage (V⁺– V⁻) ± 2.25 V to ± 6 V Junction Temperature Range -40° C to $+85^{\circ}$ C

(Note 3), (Note 4)

Package Thermal Resistance (Note 4) (θ_{JA})

8-pin SOIC 166°C/W 8-pin MSOP 211°C/W

±6V Electrical Characteristics

Unless otherwise specified, $T_J = 25^{\circ}C$, $V^+ = 6V$, $V^- = -6V$, $V_{CM} = 0V$, $A_V = +2$, $R_F = 500\Omega$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units | |
|---------------------|-------------------------------------|---|-------------------|----------|-------------------|---------|--|
| | | | (Note 6) | (Note 5) | (Note 6) | | |
| Dynamic I | Performance | | | | | | |
| f _{CL} | -3dB BW | $V_O = 200 \text{mV}_{PP}$ | | 160 | | MHz | |
| BW _{0.1dB} | 0.1dB Gain Flatness | $V_O = 200 \text{mV}_{PP}$ | | 30 | | MHz | |
| SR | Slew Rate (Note 8) | $V_O = 2V_{PP}$ | | 85 | | V/µs | |
| TS | Settling Time | $V_{\rm O} = 2V_{\rm PP} \text{ to } \pm 0.1\%$ | | 40 | | | |
| | | $V_{\rm O} = 2V_{\rm PP}$ to ±1.0% | | 35 | | ns | |
| Tr | Rise Time | V _O = 0.2V Step, 10% to 90% | | 2.3 | | ns | |
| Tf | Fall Time | V _O = 0.2V Step, 10% to 90% | | 2.3 | | ns | |
| Distortion | and Noise Response | • | | • | • | | |
| e _n | Input Referred Voltage Noise | f = 100kHz | | 1.6 | | nV/ √Hz | |
| i _n | Input Referred Current Noise | f = 100kHz | | 1.5 | | pA/ √Hz | |
| DG | Differential Gain | $R_L = 150\Omega$, $R_F = 470\Omega$, NTSC | | 0.03 | | % | |
| DP | Differential Phase | $R_L = 150\Omega$, $R_F = 470\Omega$, NTSC | | 0.03 | | deg | |
| HD2 | 2 nd Harmonic Distortion | $f_c = 1MHz, V_O = 2V_{PP}, R_L = 100\Omega$ | | -90 | | dBc | |
| | | $f_c = 1MHz$, $V_O = 2V_{PP}$, $R_L = 500\Omega$ | | -100 | | abc | |
| HD3 | 3 rd Harmonic Distortion | $f_c = 1MHz, V_O = 2V_{PP}, R_L = 100\Omega$ | | -94 | | - dBc | |
| | | $f_c = 1MHz, V_O = 2V_{PP}, R_L = 500\Omega$ | | -100 | | | |
| MTPR | Upstream | $V_O = 0.6 V_{RMS}$, 26kHz to 132kHz (see test circuit 5) | | -78 | | | |
| | Downstream | $V_O = 0.6 V_{RMS}$, 144kHz to 1.1MHz (see test circuit 5) | | -70 | | dBc | |
| Input Cha | racteristics | | | | | | |
| V _{OS} | Input Offset Voltage | V _{CM} = 0V | -1.2 -2 | +0.2 | +1.2 +2 | mV | |
| TC V _{os} | Input Offset Average Drift | V _{CM} = 0V (Note 7) | | -2.5 | | μV/°C | |
| I _{os} | Input Offset Current | $V_{CM} = 0V$ | -1 | -0.04 | 1 | μA | |
| | | | -1.5 | | 1.5 | | |
| I _B | Input Bias Current | V _{CM} = 0V | | 4.7 | 10 15 | μΑ | |
| R _{IN} | Input Resistance | Common Mode | | 17 | | MΩ | |
| 55 E | | Differential Mode | | 12 | | kΩ | |
| C _{IN} | Input Capacitance | Common Mode | | 0.9 | | pF | |
| | | Differential Mode | | 1.0 | | pF | |

±6V Electrical Characteristics (Continued)

Unless otherwise specified, $T_J = 25^{\circ}C$, $V^+ = 6V$, $V^- = -6V$, $V_{CM} = 0V$, $A_V = +2$, $R_F = 500\Omega$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|------------------|--------------------------------|---|-------------------|-----------------|-----------------|-------|
| CMVR | Input Common Mode Voltage | CMRR ≥ 60dB | | -4.75 | -4.5 | |
| | Range | | 5.5 | +5.7 | | V |
| CMRR | Common-Mode Rejection Ratio | Input Referred, | 80 | 100 | | dB |
| | | $V_{CM} = -4.2 \text{ to } +5.2 \text{V}$ | 75 | | | |
| Transfer C | Characteristics | | | | | |
| A _{VOL} | Large Signal Voltage Gain | $V_O = 4V_{PP}$ | 74 70 | 83 | | dB |
| X _t | Crosstalk | f = 1MHz | | -75 | | dB |
| Output Ch | naracteristics | 1 | | | l l | |
| V _O | Output Swing | No Load, Positive Swing | 4.8 4.6 | 5.2 | | |
| | | No Load, Negative Swing | | -5.0 | -4.6 | |
| | | | | | -4.4 | V |
| | | $R_L = 100\Omega$, Positive Swing | 4.0 3.8 | 4.6 | | V |
| | | $R_L = 100\Omega$, Negative Swing | | -4.6 | -4 | |
| | | | | | -3.8 | |
| Ro | Output Impedance | f = 1MHz | | 0.08 | | Ω |
| I _{sc} | Output Short Circuit Current | Sourcing to Ground $\Delta V_{IN} = 200 \text{mV}$ (Note 3), (Note 9) | 100 | 135 | | |
| | | Sinking to Ground $\Delta V_{IN} = -200 \text{mV}$ (Note 3), (Note 9) | 100 | 130 | | mA |
| I _{OUT} | Output Current | Sourcing, $V_O = +4.3V$ Sinking, $V_O = -4.3V$ | | 90 | | mA |
| Power Su | pply | | • | | | |
| +PSRR | Positive Power Supply | Input Referred, | 80 | 95 | | |
| | Rejection Ratio | $V_S = +5V \text{ to } +6V$ | 74 | | | dB |
| -PSRR | Negative Power Supply | Input Referred, | 75 | 90 | | uБ |
| | Rejection Ratio | $V_S = -5V$ to $-6V$ | 69 | | | |
| I _S | Supply Current (per amplifier) | No Load | | 4.3 | 6 6.5 | mA |

±2.5V Electrical Characteristics

Unless otherwise specified, all limits guaranteed for T_J = 25°C, V^+ = 2.5V, V^- = -2.5V, V_{CM} = 0V, A_V = +2, R_F = 500 Ω , R_L = 100 Ω . **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|---------------------|------------------------------|---|----------|----------|----------|---------|
| | | | (Note 6) | (Note 5) | (Note 6) | |
| Dynamic F | Performance | | • | | • | |
| f _{CL} | -3dB BW | $V_O = 200 \text{mV}_{PP}$ | | 150 | | MHz |
| BW _{0.1dB} | 0.1dB Gain Flatness | $V_O = 200 \text{mV}_{PP}$ | | 20 | | MHz |
| SR | Slew Rate (Note 8) | $V_O = 2V_{PP}$ | | 80 | | V/µs |
| T _S | Settling Time | $V_{\rm O} = 2V_{\rm PP}$ to ±0.1% | | 45 | | 20 |
| | | $V_{\rm O} = 2V_{\rm PP} \text{ to } \pm 1.0\%$ | | 40 | | ns |
| T _r | Rise Time | V _O = 0.2V Step, 10% to 90% | | 2.5 | | ns |
| T _f | Fall Time | V _O = 0.2V Step, 10% to 90% | | 2.5 | | ns |
| Distortion | and Noise Response | | | | | |
| e _n | Input Referred Voltage Noise | f = 100kHz | | 1.7 | | nV/ √Hz |
| i _n | Input Referred Current Noise | f = 100kHz | | 1.5 | | pA/ √Hz |

±2.5V Electrical Characteristics (Continued)

Unless otherwise specified, all limits guaranteed for $T_J=25^{\circ}C$, $V^+=2.5V$, $V^-=-2.5V$, $V_{CM}=0V$, $A_V=+2$, $R_F=500\Omega$, $R_L=100\Omega$. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|--------------------|-------------------------------------|--|---------------------|-----------------|---------------------|-------|
| HD2 | 2 nd Harmonic Distortion | $fc = 1MHz$, $V_O = 2V_{PP}$, $R_L = 100\Omega$ | | -88 | | T |
| | | $fc = 1MHz$, $V_O = 2V_{PP}$, $R_L = 500\Omega$ | | -98 | | dBc |
| HD3 | 3 rd Harmonic Distortion | $fc = 1MHz$, $V_O = 2V_{PP}$, $R_L = 100\Omega$ | | -92 | | |
| | | $fc = 1MHz$, $V_O = 2V_{PP}$, $R_L = 500\Omega$ | | -100 | | dBc |
| MTPR | Upstream | $V_O = 0.4V_{RMS}$,26kHz to 132kHz | | -76 | | |
| | | (see test circuit 5) | | | | dBc |
| | Downstream | $V_O = 0.4V_{RMS}$,144kHz to 1.1MHz (see test circuit 5) | | -68 | | |
| nput Cha | racteristics | | | • | | |
| Vos | Input Offset Voltage | V _{CM} = 0V | -1.5 -2.3 | +0.3 | +1.5 +2.3 | mV |
| TC V _{os} | Input Offset Average Drift | V = 0V (Noto 7) | -2.5 | -2.5 | 72.0 | μV/°C |
| l _{os} | Input Offset Current | $V_{CM} = 0V \text{ (Note 7)}$ $V_{CM} = 0V$ | -1.5 | +0.01 | 1.5 | μΑ |
| los | Input Onset Current | VCM - OV | -1.5 -2.5 | +0.01 | 2.5 | μΑ |
| I _B | Input Bias Current | V _{CM} = 0V | -2.5 | 4.6 | 10 | μA |
| .R | pat bido odiforit | · GM — GV | | 7.0 | 15 | 47 |
| R _{IN} | Input Resistance | Common Mode | | 17 | | MΩ |
| -IIN | | Differential Mode | | 12 | | kΩ |
| C _{IN} | Input Capacitance | Common Mode | | 0.9 | | pF |
| OIN | Impat Sapasitarios | Differential Mode | | 1.0 | | pF |
| CMVR | Input Common Mode Voltage | CMRR ≥ 60dB | | -1.25 | -1 | Pi |
| OWIVIT | Range | OWITH 2 GOOD | 2 | +2.2 | | V |
| CMRR | Common Mode Rejection Ratio | Input Referred, | 80 | 100 | | dB |
| OWNTH | Common wode riejection riatio | $V_{CM} = -0.7 \text{ to } +1.7 \text{V}$ | 75 | 100 | | 45 |
| Transfor (| L Characteristics | VCM = -0.7 to +1.7 V | 7.5 | | | |
| A _{VOL} | Large Signal Voltage Gain | $V_O = 1V_{PP}$ | 74 | 82 | | dB |
| X_t | Crosstalk | f = 1MHz | 7-7 | -75 | | dB |
| | paracteristics | 1 - 1141112 | | _73 | | |
| V _O | Output Swing | No Load, Positive Swing | 1.4 | 1.7 | | |
| v O | Output Swing | No Load, I ositive Swing | 1.2 | 1.7 | | |
| | | No Load, Negative Swing | 1 | -1.5 | -1.2 | 1 |
| | | The Edda, Hegalive Swing | | 1.0 | -1 | |
| | | $R_L = 100\Omega$, Positive Swing | 1.2 | 1.5 | • | V |
| | | l l l l l l l l l l l l l l l l l l l | 1 | | | |
| | | $R_L = 100\Omega$, Negative Swing | | -1.4 | -1.1 | 1 |
| | | | | | -0.9 | |
| R _o | Output Impedance | f = 1MHz | | 0.1 | | Ω |
| I _{sc} | Output Short Circuit Current | Sourcing to Ground | 100 | 137 | | |
| - = | | $\Delta V_{IN} = 200 \text{mV} \text{ (Note 3), (Note 9)}$ | | | | |
| | | Sinking to Ground | 100 | 134 | | mA |
| | | $\Delta V_{IN} = -200 \text{mV}$ (Note 3), (Note 9) | | | | |
| I _{OUT} | Output Current | Sourcing, $V_O = +0.8V$ | | 90 | | mA |
| | | Sinking, $V_O = -0.8V$ | | | | |
| Power Su | pply | | | | | |
| +PSRR | Positive Power Supply Rejection | Input Referred, | 78 | 93 | | 70 |
| | Ratio | $V_{S} = +2.5V \text{ to } +3V$ | 72 | | | dB |
| | Magativa Dawar Cupply | Input Referred, | 75 | 88 | | dB |
| -PSRR | Negative Power Supply | input rieleneu, | / / / | 00 | | l ab |

±2.5V Electrical Characteristics (Continued)

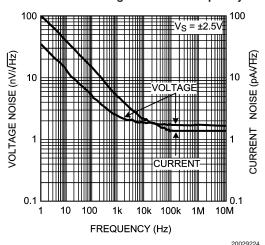
Unless otherwise specified, all limits guaranteed for $T_J = 25^{\circ}C$, $V^+ = 2.5V$, $V^- = -2.5V$, $V_{CM} = 0V$, $A_V = +2$, $R_F = 500\Omega$, $R_L = 100\Omega$. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|----------------|--------------------------------|------------|----------|----------|----------|-------|
| | | | (Note 6) | (Note 5) | (Note 6) | |
| I _s | Supply Current (per amplifier) | No Load | | 4.1 | 5.8 | mA |
| | | | | | 6.4 | |

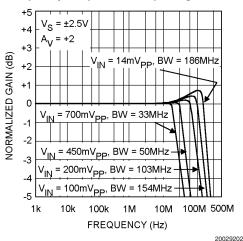
- Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics.
- **Note 2:** Human body model, $1.5k\Omega$ in series with 100pF. Machine model, 0Ω in series with 200pF.
- Note 3: Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C.
- Note 4: The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} T_A)/\theta_{JA}$. All numbers apply for packages soldered directly onto a PC board.
- Note 5: Typical values represent the most likely parametric norm.
- Note 6: All limits are guaranteed by testing or statistical analysis.
- Note 7: Offset voltage average drift is determined by dividing the change in V_{OS} at temperature extremes into the total temperature change.
- Note 8: Slew rate is the slowest of the rising and falling slew rates.
- Note 9: Short circuit test is a momentary test. Output short circuit duration is infinite for $V_S \le \pm 2.5V$, at room temperature and below. For $V_S > \pm 2.5V$, allowable short circuit duration is 1.5ms.

Typical Performance Characteristics

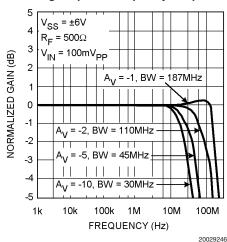
Current and Voltage Noise vs. Frequency



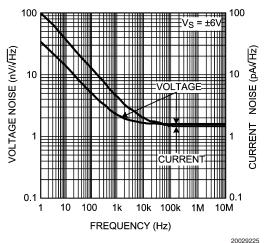
Frequency Response vs. Input Signal Level



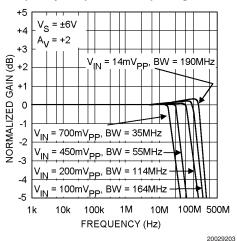
Inverting Amplifier Frequency Response



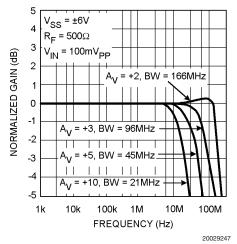
Current and Voltage Noise vs. Frequency



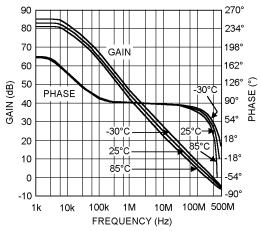
Frequency Response vs. Input Signal Level



Non-Inverting Amplifier Frequency Response

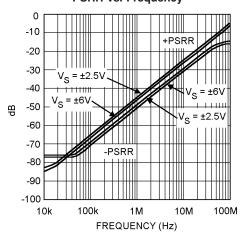


Open Loop Gain and Phase Response



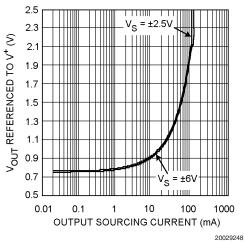
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PSRR vs. Frequency

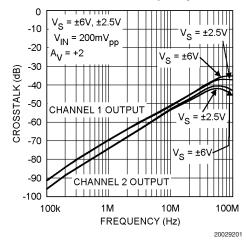


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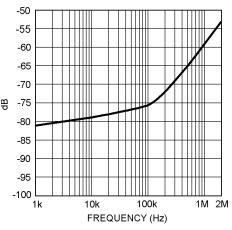
Positive Output Swing vs. Source Current



Crosstalk vs. Frequency

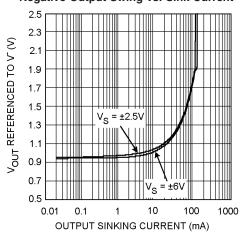


CMRR vs. Frequency



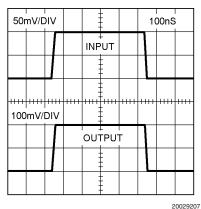
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Negative Output Swing vs. Sink Current

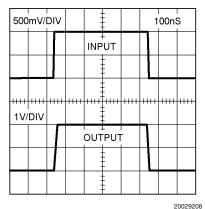


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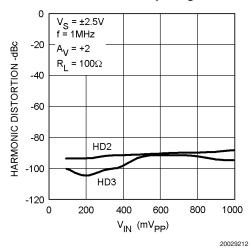
Non-Inverting Small Signal Pulse Response V_S = ±2.5V, R_L = 100 Ω , A_V = +2, R_F = 500 Ω



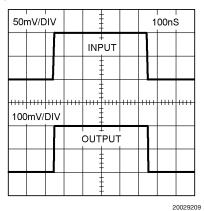
Non-Inverting Large Signal Pulse Response $V_S = \pm 2.5V$, $R_L = 100\Omega$, $A_V = +2$, $R_F = 500\Omega$



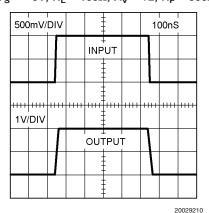
Harmonic Distortion vs. Input Signal Level



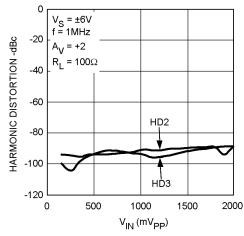
Non-Inverting Small Signal Pulse Response $V_S=\pm 6V,\,R_L=100\Omega,\,A_V=+2,\,R_F=500\Omega$



Non-Inverting Large Signal Pulse Response $V_S = \pm 6V$, $R_L = 100\Omega$, $A_V = +2$, $R_F = 500\Omega$

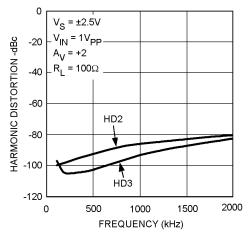


Harmonic Distortion vs. Input Signal Level



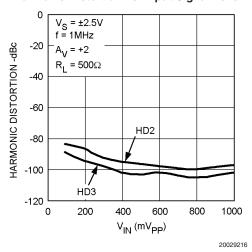
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Harmonic Distortion vs. Frequency

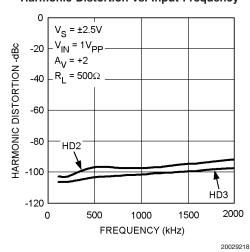


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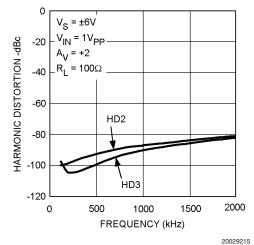
Harmonic Distortion vs. Input Signal Level



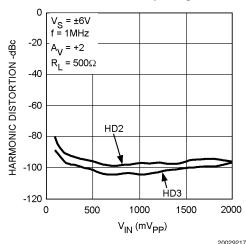
Harmonic Distortion vs. Input Frequency



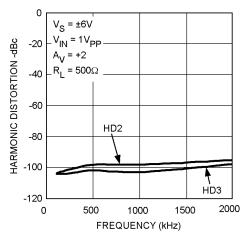
Harmonic Distortion vs. Frequency



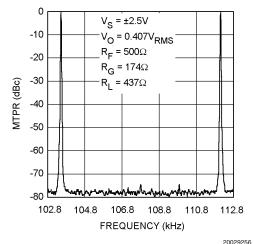
Harmonic Distortion vs. input Signal Level



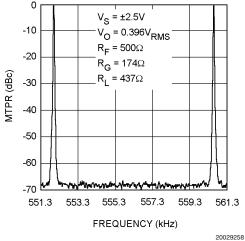
Harmonic Distortion vs. Input Frequency



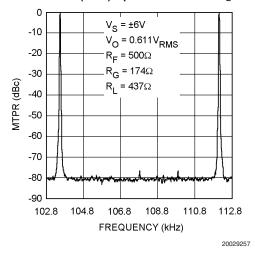
Full Rate ADSL (DMT) Upstream MTPR @ $V_S = \pm 2.5V$



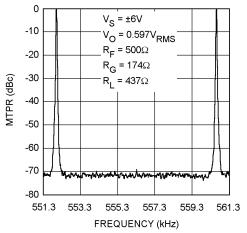
Full Rate ADSL (DMT) Downstream MTPR @ $V_S = \pm 2.5V$



Full Rate ADSL (DMT) Upstream MTPR @ $V_S = \pm 6V$

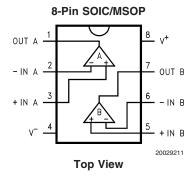


Full Rate ADSL (DMT) Downstream MTPR @ $V_S = \pm 6V$



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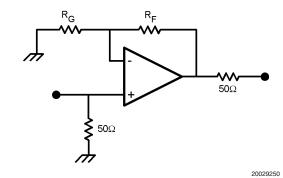
Connection Diagram



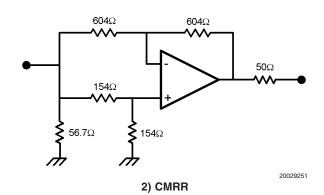
Ordering Information

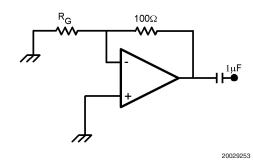
| Package | Part Number | Package Marking | Transport Media | NSC Drawing |
|------------|-------------|-----------------|--------------------------|-------------|
| 8-Pin SOIC | LMH6622MA | LMH6622MA | 95 Units per Rail | M08A |
| | LMH6622MAX | | 2.5k Units Tape and Reel | |
| 8-Pin MSOP | LMH6622MM | A80A | 1k Units Tape and Reel | MUA08A |
| | LMH6622MMX | | 3.5k Units Tape and Reel | |

Test Circuits

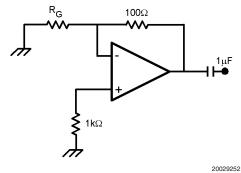


1) Non-Inverting Amplifier



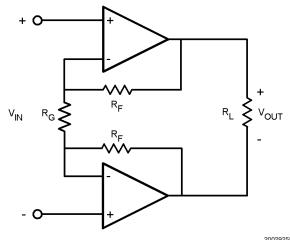


3) Voltage Noise $\label{eq:RG} \textbf{R}_{\textbf{G}} = \mathbf{1}\Omega \text{ for } \textbf{f} \leq \mathbf{100kHz}, \ \textbf{R}_{\textbf{G}} = \mathbf{20}\Omega \text{ for } \textbf{f} > \mathbf{100kHz}$



4) Current Noise $\rm R_G$ = 1Ω for f $\leq 100 kHz, \, R_G$ = 20Ω for f > 100 kHz

Test Circuits (Continued)



5) Multitone Power Ratio, $R_F = 500\Omega$, $R_G = 174\Omega$, $R_L = 437\Omega$

DSL Receive Channel Applications

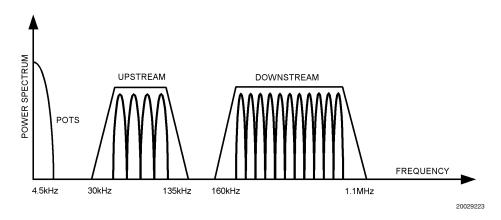


FIGURE 1. ADSL Signal Description

The LMH6622 is a dual, wideband operational amplifier designed for use as a DSL line receiver. In the receive band of a Customer Premises Equipment (CPE) ADSL modem it is possible that as many as 255 Discrete Multi-Tone (DMT) QAM signals will be present, each with its own carrier frequency, modulation, and signal level. The ADSL standard requires a line referred noise power density of -140dBm/Hz within the CPE receive band of 100KHz to 1.1MHz. The CPE driver output signal will leak into the receive path because of full duplex operation and the imperfections of the hybrid coupler circuit. The DSL analog front end must incorporate a

receiver pre-amp which is both low noise and highly linear for ADSL-standard operation. The LMH6622 is designed for the twin performance parameters of low noise and high linearity.

Applications ranging from +5V to +12V or $\pm 2.5V$ to $\pm 6V$ are fully supported by the LMH6622. In *Figure 2*, the LMH6622 is used as an inverting summing amplifier to provide both received pre-amp channel gain and driver output signal cancellation, i.e., the function of a hybrid coupler.

DSL Receive Channel Applications (Continued)

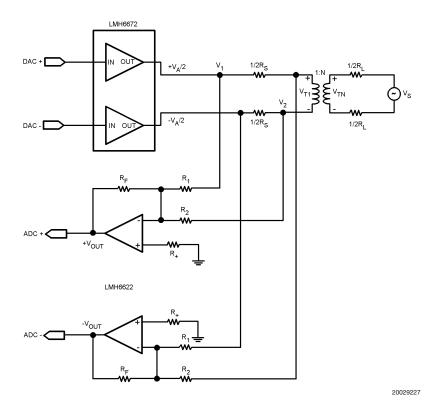


FIGURE 2. ADSL Receive Applications Circuit

DSL Receive Channel Applications

(Continued)

The two $R_{\rm S}$ resistors are used to provide impedance matching through the 1:N transformer.

$$R_S = \frac{R_L}{N^2}$$

Where R_I is the impedance of the twisted pair line.

N is the turns ratio of the transformer.

The resistors R_2 and R_F are used to set the receive gain of the pre-amp. The receive gain is selected to meet the ADC full-scale requirement of a DSL chipset.

Resistor $\rm R_1$ and $\rm R_2$ along with $\rm R_F$ are used to achieve cancellation of the output driver signal at the output of the receiver.

Since the LMH6622 is configured as an inverting summing amplifier, V_{OUT} is found to be,

$$V_{OUT} = -R_F \left[\frac{V_1}{R_1} + \frac{V_2}{R_2} \right]$$

The expression for V_1 and V_2 can be found by using superposition principle.

When $V_S = 0$,

$$V_1 = \frac{1}{2}V_A$$
 and $V_2 = -\frac{1}{4}V_A$

When $V_A = 0$,

$$V_1 = 0$$
 and $V_2 = -\frac{1}{2}V_{T1}$

Therefore.

$$V_1 = \frac{1}{2}V_A$$
 and $V_2 = -\frac{1}{4}V_A - \frac{1}{2}V_{T1}$

And then,

$$V_{OUT} = -R_F \left[\frac{V_A}{2R_1} - \frac{V_A}{4R_2} - \frac{V_{T1}}{2R_2} \right]$$

Setting $R_1 = 2*R_2$ to cancel unwanted driver signal in the receive path, then we have

$$V_{OUT} = \frac{R_F}{2R_2} V_{T1}$$

We can also find that,

$$V_{TN} = \frac{1}{2}V_{S}$$
 and $V_{T1} = \frac{1}{N}V_{TN} = \frac{1}{2N}V_{S}$

And then

$$V_{OUT} = \frac{R_F}{4NR_2}V_S$$

In conclusion, the peak-to-peak voltage to the ADC would be,

$$2 V_{OUT} = \frac{R_F}{2NR_2} V_S$$

RECEIVE CHANNEL NOISE CALCULATION

The circuit of *Figure 2* also has the characteristic that it cancels noise power from the drive channel.

The noise gain of the receive pre-amp is found to be:

$$A_N = 1 + \frac{R_F}{R_1 / / R_2}$$

Noise power at each of the output of LMH6622:

$$e_{o}^{2} = A_{n}^{2} [V_{n}^{2} + i_{non-inv}^{2} R_{+}^{2} + 4kT R_{+}] + i_{inv}^{2} R_{F}^{2} + 4kT R_{F} A_{n}$$

where

 V_n Input referred voltage noise i_n Input referred current noise

 $i_{\text{non-inv}}$ Input referred non-inverting current noise i_{inv} Input referred inverting current noise k Boltzmann's constant, K = 1.38 x 10⁻²³

T Resistor temperature in k

R₊ Source resistance at the non-inverting input to balance offset voltage, typically very small for this inverting summing applications

For a voltage feedback amplifier,

$$i_{inv} = i_{non-inv} = i_{n}$$

Therefore, total output noise from the differential pre-amp is:

$$e^2_{TotalOutput} = 2 e^2_{o}$$

The factor '2' appears here because of differential output.

DIFFERENTIAL ANALOG-TO-DIGITAL DRIVER

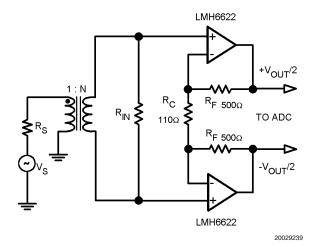


FIGURE 3. Circuit for Differential A/D Driver

DSL Receive Channel Applications

(Continued)

The LMH6622 is a low noise, low distortion high speed operational amplifier. The LMH6622 comes in either SOIC-8 or MSOP-8 packages. Because two channels are available in each package the LMH6622 can be used as a high dynamic range differential amplifier for the purpose of driving a high speed analog-to-digital converter. Driving a 1k Ω load, the differential amplifier of Figure 3 provides 20dB gain, a flat frequency response up to 6MHz, and harmonic distortion that is lower than 80dBc. This circuit makes use of a transformer to convert a single-ended signal to a differential signal. The input resistor $R_{\rm IN}$ is chosen by the following equation,

$$R_{IN} = \frac{1}{N^2} R_S$$

The gain of this differential amplifier can be adjusted by $R_{\text{\scriptsize C}}$ and $R_{\text{\scriptsize F}},$

$$A_V = 2 \frac{R_F}{R_C}$$

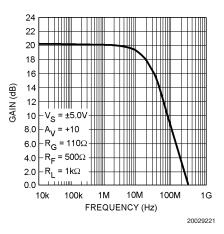


FIGURE 4. Frequency Response

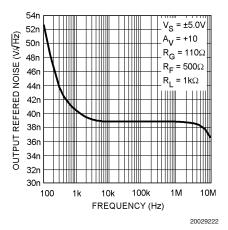


FIGURE 5. Total Output Referred Noise Density

CIRCUIT LAYOUT CONSIDERATIONS

National Semiconductor suggests the copper patterns on the evaluation boards listed below as a guide for high frequency layout. These boards are also useful as an aid in device testing and characterization. As is the case with all highspeed amplifiers, accepted-practice R_E design technique on the PCB layout is mandatory. Generally, a good high frequency layout exhibits a separation of power supply and ground traces from the inverting input and output pins. Parasitic capacitances between these nodes and ground will cause frequency response peaking and possible circuit oscillations (see Application Note OA-15 for more information). High quality chip capacitors with values in the range of 1000pF to 0.1µF should be used for power supply bypassing. One terminal of each chip capacitor is connected to the ground plane and the other terminal is connected to a point that is as close as possible to each supply pin as allowed by the manufacturer's design rules. In addition, a tantalum capacitor with a value between 4.7µF and 10µF should be connected in parallel with the chip capacitor. Signal lines connecting the feedback and gain resistors should be as short as possible to minimize inductance and microstrip line effect. Input and output termination resistors should be placed as close as possible to the input/output pins. Traces greater than 1 inch in length should be impedance matched to the corresponding load termination.

Symmetry between the positive and negative paths in the layout of differential circuitry should be maintained so as to minimize the imbalance of amplitude and phase of the differential signal.

| Device | Package | Evaluation Board P/N |
|-----------|---------|----------------------|
| LMH6622MA | SOIC-8 | CLC730036 |
| LMH6622MM | MSOP-8 | CLC730123 |

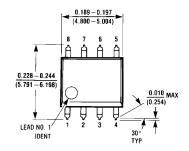
These free evaluation boards are shipped when a device sample request is placed with National Semiconductor.

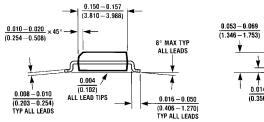
Component value selection is another important parameter in working with high speed/high performance amplifiers. Choosing external resistors that are large in value compared to the value of other critical components will affect the closed loop behavior of the stage because of the interaction of these resistors with parasitic capacitances. These parasitic capacitors could either be inherent to the device or be a by-product of the board layout and component placement. Moreover, a large resistor will also add more thermal noise to the signal path. Either way, keeping the resistor values low will diminish this interaction. On the other hand, choosing very low value resistors could load down nodes and will contribute to higher overall power dissipation and worse distortion.

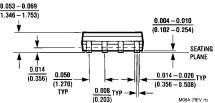
DRIVING CAPACITIVE LOAD

Capacitive Loads decrease the phase margin of all op amps. The output impedance of a feedback amplifier becomes inductive at high frequencies, creating a resonant circuit when the load is capacitive. This can lead to overshoot, ringing and oscillation. To eliminate oscillation or reduce ringing, an isolation resistor can be placed between the load and the output. In general, the bigger the isolation resistor, the more damped the pulse response becomes. For initial evaluation, a 50Ω isolation resistor is recommended.

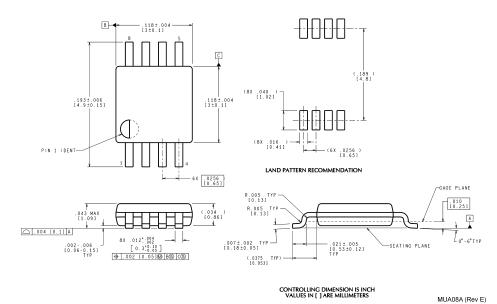
Physical Dimensions inches (millimeters) unless otherwise noted







8-Pin SOIC NS Package Number M08A



8-Pin MSOP NS Package Number MUA08A

Notes

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