

# MC100EP196A

## 3.3 V ECL Programmable Delay Chip With FTUNE

The MC100EP196A is a Programmable Delay Chip (PDC) designed primarily for clock deskewing and timing adjustment. It provides variable delay of a differential NECL/PECL input transition. It has similar architecture to the EP195 with the added feature of further tunability in delay using the FTUNE pin. The FTUNE input takes an analog voltage from  $V_{CC}$  to  $V_{EE}$  to fine tune the output delay from 0 to 60 ps.

The delay section consists of a programmable matrix of gates and multiplexers as shown in the logic diagram, Figure 2. The delay increment of the EP196A has a digitally selectable resolution of about 10 ps and a net range of up to 10.4 ns. The required delay is selected by the 10 data select inputs D[9:0] values and controlled by the LEN (pin 10). A LOW level on LEN allows a transparent LOAD mode of real time delay values by D[9:0]. A LOW to HIGH transition on LEN will LOCK and HOLD current values present against any subsequent changes in D[10:0]. The approximate delay values for varying tap numbers correlating to D0 (LSB) through D9 (MSB) are shown in Table 6 and Figure 3.

The  $\overline{IN}/\overline{IN}$  inputs can accept LVPECL (SE of Diff), or LVDS level signals. Because the MC100EP196A is designed using a chain of multiplexers it has a fixed minimum delay of 2.2 ns. An additional pin D10 is provided for controlling Pins 14 and 15,  $\overline{CASCAD\bar{E}}$  and  $\overline{CASCAD\bar{E}}$ , also latched by LEN, in cascading multiple PDCs for increased programmable range. The cascade logic allows full control of multiple PDCs. Switching devices from all "1" states on D[0:9] with SETMAX LOW to all "0" states on D[0:9] with SETMAX HIGH will increase the delay equivalent to "D0", the minimum increment.

Select input pins D[10:0] may be threshold controlled by combinations of interconnects between  $V_{EF}$  (pin 7) and  $V_{CF}$  (pin 8) for receiving LVCMOS, ECL, or LVTTTL level signals. For LVCMOS input levels, leave  $V_{CF}$  and  $V_{EF}$  open. For ECL operation, short  $V_{CF}$  and  $V_{EF}$  (Pins 7 and 8). For LVTTTL level operation, connect a 1.5 V supply reference to  $V_{CF}$  and leave open  $V_{EF}$  pin. The 1.5 V reference voltage at the  $V_{CF}$  pin can be accomplished by placing a 2.2 k $\Omega$  resistor between  $V_{CF}$  and  $V_{EE}$  for a 3.3 V power supply.

The  $V_{BB}$  pin, an internally generated voltage supply, is available to this device only. For single-ended input conditions, the unused differential input is connected to  $V_{BB}$  as a switching reference voltage.  $V_{BB}$  may also rebias AC coupled inputs. When used, decouple  $V_{BB}$  and  $V_{CC}$  via a 0.01  $\mu$ F capacitor and limit current sourcing or sinking to 0.5 mA. When not used,  $V_{BB}$  should be left open.

The 100 Series contains temperature compensation.

- Maximum Input Clock Frequency >1.2 GHz Typical
- Programmable Range: 0 ns to 10 ns
- Delay Range: 2.2 ns to 12.4 ns
- 10 ps Increments
- PECL Mode Operating Range:  
 $V_{CC} = 3.0 \text{ V to } 3.6 \text{ V with } V_{EE} = 0 \text{ V}$
- NECL Mode Operating Range:  
 $V_{CC} = 0 \text{ V with } V_{EE} = -3.0 \text{ V to } -3.6 \text{ V}$

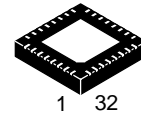
- $\overline{IN}/\overline{IN}$  Inputs Accept LVPECL, LVNECL, LVDS Levels
- A Logic High on the  $\overline{EN}$  Pin Will Force Q to Logic Low
- D[10:0] Can Select Either LVPECL, LVCMOS, or LVTTTL Input Levels
- $V_{BB}$  Output Reference Voltage
- Pb-Free Packages are Available\*

\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.



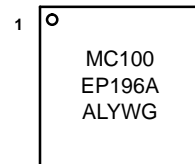
ON Semiconductor®

<http://onsemi.com>



QFN32  
MN SUFFIX  
CASE 488AM

### MARKING DIAGRAM\*



- A = Assembly Location
- L = Wafer Lot
- Y = Year
- W = Work Week
- G = Pb-Free Package

\*For additional marking information, refer to Application Note AND8002/D.

### ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 16 of this data sheet.

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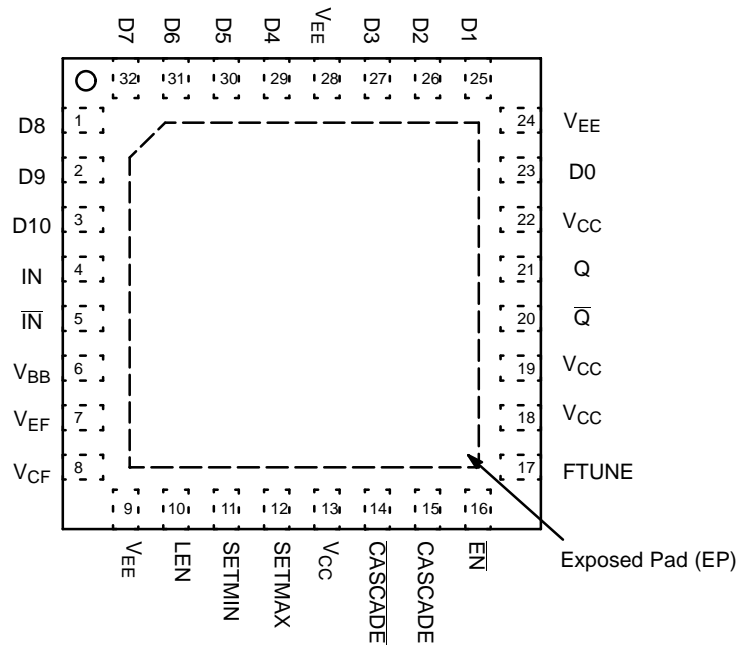


Figure 1. 32-Lead QFN (Top View)

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**Table 1. PIN DESCRIPTION**

Pin	Name	I/O	Default State	Description
23, 25, 26, 27, 29, 30, 31, 32, 1, 2	D[0:9]	LVC MOS, LV TTL, ECL Input	Low	Single-Ended Parallel Data Inputs [0:9]. Internal 75 k $\Omega$ to V <sub>EE</sub> . (Note 1)
3	D[10]	LVC MOS, LV TTL, ECL Input	Low	Single-Ended CASCADE/CASCADE Control Input. Internal 75 k $\Omega$ to V <sub>EE</sub> . (Note 1)
4	IN	LVPECL, LVDS	Low	Noninverted Differential Input. Internal 75 k $\Omega$ to V <sub>EE</sub> .
5	$\overline{\text{IN}}$	LVPECL, LVDS	High	Inverted Differential Input. Internal 75 k $\Omega$ to V <sub>EE</sub> and 36.5 k $\Omega$ to V <sub>CC</sub> .
6	V <sub>BB</sub>	–	–	ECL Reference Voltage Output
7	V <sub>EF</sub>	–	–	Reference Voltage for ECL Mode Connection
8	V <sub>CF</sub>	–	–	LVC MOS, ECL, OR LV TTL Input Mode Select
9, 24, 28	V <sub>EE</sub>	–	–	Negative Supply Voltage. All V <sub>EE</sub> Pins must be Externally Connected to Power Supply to Guarantee Proper Operation. (Note 2)
13, 18, 19, 22	V <sub>CC</sub>	–	–	Positive Supply Voltage. All V <sub>CC</sub> Pins must be externally Connected to Power Supply to Guarantee Proper Operation. (Note 2)
10	LEN	ECL Input	Low	Single-ended D pins LOAD / HOLD input. Internal 75 k $\Omega$ to V <sub>EE</sub> .
11	SETMIN	ECL Input	Low	Single-ended Minimum Delay Set Logic Input. Internal 75 k $\Omega$ to V <sub>EE</sub> . (Note 1)
12	SETMAX	ECL Input	Low	Single-ended Maximum Delay Set Logic Input. Internal 75 k $\Omega$ to V <sub>EE</sub> . (Note 1)
14	$\overline{\text{CASCADE}}$	ECL Output	–	Inverted Differential Cascade Output for D[10]. Typically Terminated with 50 $\Omega$ to V <sub>TT</sub> = V <sub>CC</sub> – 2 V.
15	CASCADE	ECL Output	–	Noninverted Differential Cascade Output. for D[10] Typically Terminated with 50 $\Omega$ to V <sub>TT</sub> = V <sub>CC</sub> – 2 V.
16	$\overline{\text{EN}}$	ECL Input	Low	Single-ended Output Enable Pin. Internal 75 k $\Omega$ to V <sub>EE</sub> .
17	FTUNE	Analog Input	–	Fine Tune Input
21	Q	ECL Output	–	Noninverted Differential Output. Typically Terminated with 50 $\Omega$ to V <sub>TT</sub> = V <sub>CC</sub> – 2 V.
20	$\overline{\text{Q}}$	ECL Output	–	Inverted Differential Output. Typically Terminated with 50 $\Omega$ to V <sub>TT</sub> = V <sub>CC</sub> – 2 V.

1. SETMIN will override SETMAX if both are high. SETMAX and SETMIN will override all D[0:10] inputs.
2. All V<sub>CC</sub> and V<sub>EE</sub> pins must be externally connected to Power Supply to guarantee proper operation.

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**Table 2. CONTROL PIN**

Pin	State	Function
EN	LOW (Note 3)	Input Signal is Propagated to the Output
	HIGH	Output Holds Logic Low State
LEN	LOW (Note 3)	Transparent or LOAD mode for real time delay values present on D[0:10].
	HIGH	LOCK and HOLD mode for delay values on D[0:10]; further changes on D[0:10] are not recognized and do not affect delay.
SETMIN	LOW (Note 3)	Output Delay set by D[0:10]
	HIGH	Set Minimum Output Delay
SETMAX	LOW (Note 3)	Output Delay set by D[0:10]
	HIGH	Set Maximum Output Delay
D10	LOW (Note 3)	CASCADE Output LOW, CASCADE Output HIGH
	HIGH	CASCADE Output LOW, CASCADE Output HIGH

3. Internal pulldown resistor will provide a logic LOW if pin is left unconnected.

**Table 3. CONTROL D[0:10] INTERFACE**

$V_{CF}$	$V_{EF}$ Pin (Note 4)	ECL Mode
$V_{CF}$	No Connect	LVC MOS Mode
$V_{CF}$	1.5 V $\pm$ 100 mV	LVTTL Mode (Note 5)

4. Short  $V_{CF}$  (pin 8) and  $V_{EF}$  (pin 7).

5. When Operating in LVTTL Mode, the reference voltage can be provided by connecting an external resistor,  $R_{CF}$  (suggested resistor value is 2.2 k $\Omega$   $\pm$ 5%), between  $V_{CF}$  and  $V_{EE}$  pins.

**Table 4. DATA INPUT ALLOWED OPERATING VOLTAGE MODE TABLE**

POWER SUPPLY	CONTROL DATA SELECT INPUTS PINS (D [0:10])			
	LVC MOS	LVTTL	LVPECL	LVNECL
PECL Mode Operating Range	YES	YES	YES	N/A
NECL Mode Operating Range	N/A	N/A	N/A	YES

**Table 5. ATTRIBUTES**

Characteristics	Value	
Internal Input Pulldown Resistor (R1)	75 k $\Omega$	
ESD Protection	Human Body Model	> 2 kV
	Machine Model	> 100 V
	Charged Device Model	> 2 kV
Moisture Sensitivity, Indefinite Time Out of Drypack (Note 6)	Pb Pkg	Pb-Free Pkg
	LQFP-32	Level 2
	QFN-32	Level 1
Flammability Rating Oxygen Index: 28 to 34	UL 94 V-0 @ 0.125 in	
Transistor Count	1237 Devices	
Meets or exceeds JEDEC Spec EIA/JESD78 IC Latchup Test		

6. For additional information, see Application Note AND8003/D.

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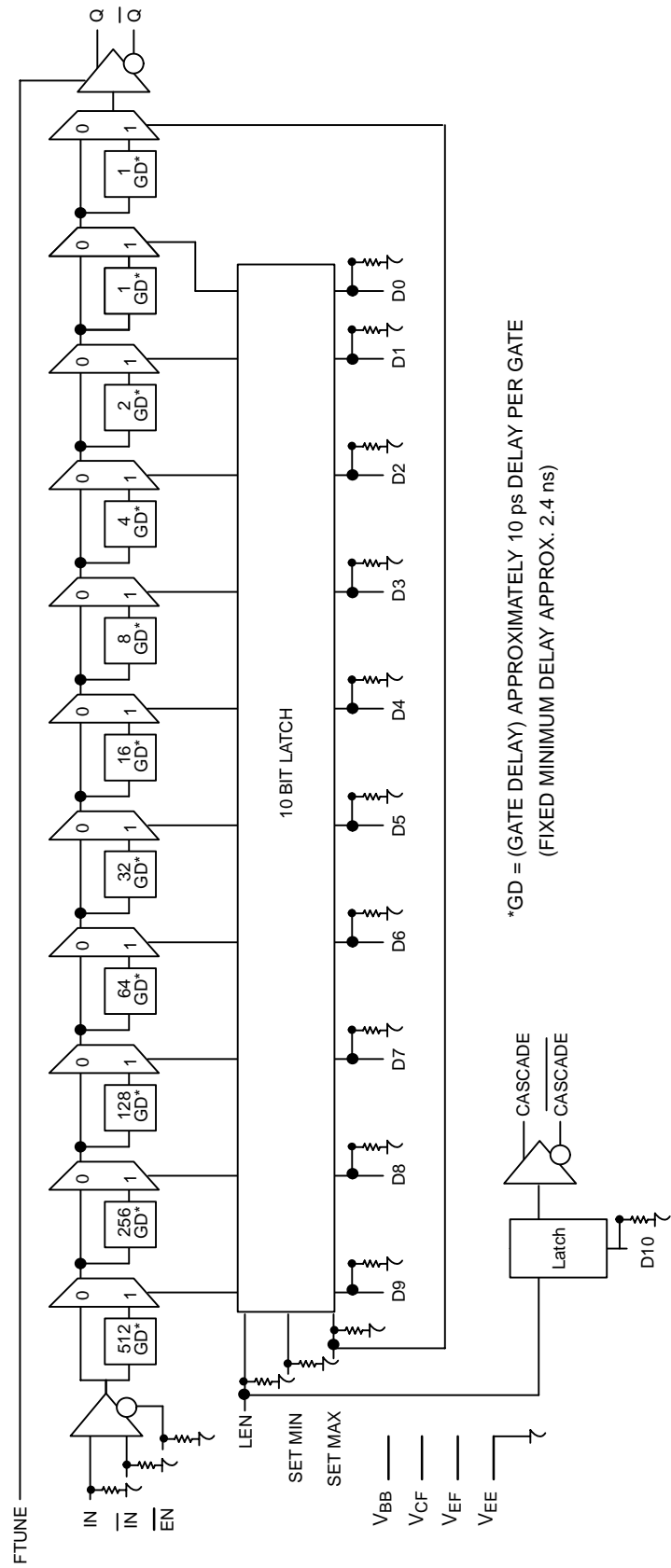


Figure 2. Logic Diagram

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**Table 6. THEORETICAL DELAY VALUES**

D(9:0) Value	SETMIN	SETMAX	Programmable Delay*
XXXXXXXXXX	H	L	0 ps
000000000	L	L	0 ps
000000001	L	L	10 ps
000000010	L	L	20 ps
000000011	L	L	30 ps
000000100	L	L	40 ps
000000101	L	L	50 ps
000000110	L	L	60 ps
000000111	L	L	70 ps
000001000	L	L	80 ps
000010000	L	L	160 ps
000100000	L	L	320 ps
001000000	L	L	640 ps
001000000	L	L	1280 ps
010000000	L	L	2560 ps
100000000	L	L	5120 ps
111111111	L	L	10230 ps
XXXXXXXXXX	L	H	10240 ps

\*Fixed minimum delay not included.

**Table 7. TYPICAL FTUNE DELAY PIN**

Input Range	Output Range
$V_{CC}-V_{EE}$ (V)	0 – 60 (ps)

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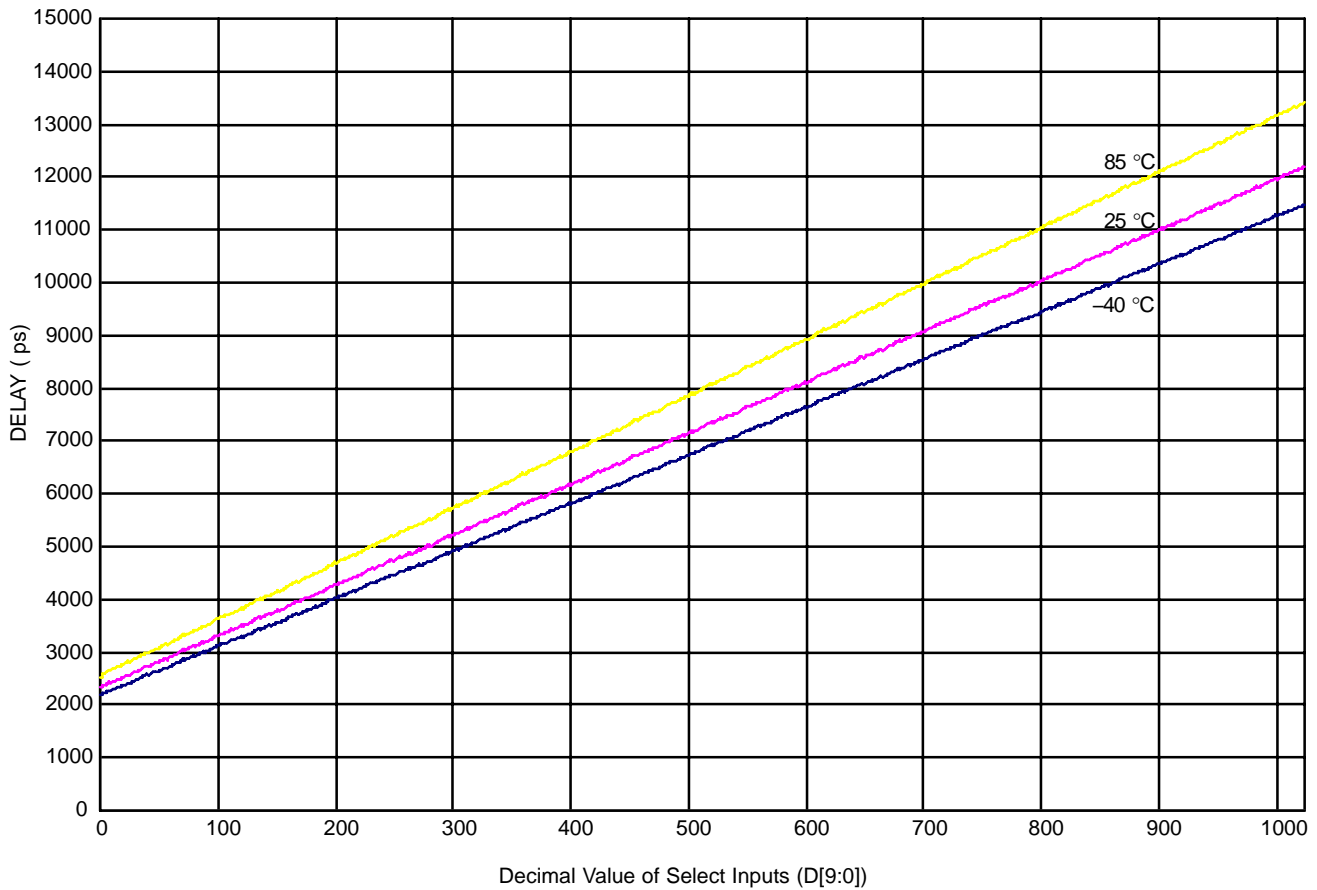


Figure 3. Measured Delay vs. Select Inputs

Table 8. MAXIMUM RATINGS

Symbol	Parameter	Condition 1	Condition 2	Rating	Unit
V <sub>CC</sub>	Positive Mode Power Supply	V <sub>EE</sub> = 0 V		6	V
V <sub>EE</sub>	Negative Mode Power Supply	V <sub>CC</sub> = 0 V		-6	V
V <sub>I</sub>	Positive Mode Input Voltage Negative Mode Input Voltage	V <sub>EE</sub> = 0 V V <sub>CC</sub> = 0 V	V <sub>I</sub> ≤ V <sub>CC</sub> V <sub>I</sub> ≥ V <sub>EE</sub>	6 -6	V V
I <sub>out</sub>	Output Current	Continuous Surge		50 100	mA mA
I <sub>BB</sub>	V <sub>BB</sub> Sink/Source			±0.5	mA
T <sub>A</sub>	Operating Temperature Range			-40 to +85	°C
T <sub>stg</sub>	Storage Temperature Range			-65 to +150	°C
θ <sub>JA</sub>	Thermal Resistance (Junction-to-Ambient)	0 lfpm 500 lfpm	QFN-32 QFN-32	31 27	°C/W °C/W
θ <sub>JC</sub>	Thermal Resistance (Junction-to-Case)	2S2P	QFN-32	12	°C/W
T <sub>sol</sub>	Wave Solder	Pb Pb-Free	<2 to 3 sec @ 248°C <2 to 3 sec @ 260°C	265 265	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

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**Table 9. 100EP DC CHARACTERISTICS, PECL**  $V_{CC} = 3.3\text{ V}$ ,  $V_{EE} = 0\text{ V}$  (Note 7)

Symbol	Characteristic	-40°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$I_{EE}$	Negative Power Supply Current	100	135	160	110	140	170	110	145	175	mA
$V_{OH}$	Output HIGH Voltage (Note 8)	2155	2280	2405	2155	2280	2405	2155	2280	2405	mV
$V_{OL}$	Output LOW Voltage (Note 8)	1355	1480	1605	1355	1480	1605	1355	1480	1605	mV
$V_{IH}$	Input HIGH Voltage (Single-Ended)										mV
	LVPECL	2075		2420	2075		2420	2075		2420	
	CMOS	2000		3300	2000		3300	2000		3300	
	TTL	2000		3300	2000		3300	2000		3300	
$V_{IL}$	Input LOW Voltage (Single-Ended)										mV
	LVPECL	1355		1675	1490		1675	1490		1675	
	CMOS	0		800	0		800	0		800	
	TTL	0		800	0		800	0		800	
$V_{BB}$	ECL Output Voltage Reference	1775	1875	1975	1775	1875	1975	1775	1875	1975	mV
$V_{CF}$	LVTTTL Mode Input Detect Voltage	1.4	1.5	1.6	1.4	1.5	1.6	1.4	1.5	1.6	V
$V_{EF}$	Reference Voltage for ECL Mode Connection	1900	2020	2150	1875	2080	2150	1850	2130	2150	mV
$V_{IHCMR}$	Input HIGH Voltage Common Mode Range (Differential Configuration) (Note 9)	1.2		3.3	1.2		3.3	1.2		3.3	V
$I_{IH}$	Input HIGH Current (@ $V_{IH}$ )			150			150			150	$\mu\text{A}$
$I_{IL}$	Input LOW Current (@ $V_{IL}$ )										$\mu\text{A}$
	IN	0.5			0.5			0.5			
	$\overline{\text{IN}}$	-150			-150			-150			

NOTE: Device will meet the specifications after thermal equilibrium has been established when mounted in a test socket or printed circuit board with maintained transverse airflow greater than 500 lfm. Electrical parameters are guaranteed only over the declared operating temperature range. Functional operation of the device exceeding these conditions is not implied. Device specification limit values are applied individually under normal operating conditions and not valid simultaneously.

7. Input and output parameters vary 1:1 with  $V_{CC}$ .  $V_{EE}$  can vary +0.3 V to -0.3 V.

8. All loading with  $50\ \Omega$  to  $V_{CC} - 2.0\text{ V}$ .

9.  $V_{IHCMR}$  min varies 1:1 with  $V_{EE}$ .  $V_{IHCMR}$  max varies 1:1 with  $V_{CC}$ . The  $V_{IHCMR}$  range is referenced to the most positive side of the differential input signal.



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**Table 10. 100EP DC CHARACTERISTICS, NECL**  $V_{CC} = 0\text{ V}$ ,  $V_{EE} = -3.3\text{ V}$  (Note 10)

Symbol	Characteristic	-40°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$I_{EE}$	Negative Power Supply Current (Note 11)	100	135	160	110	140	170	110	145	175	mA
$V_{OH}$	Output HIGH Voltage (Note 12)	-1145	-1020	-895	-1145	-1020	-895	-1145	-1020	-895	mV
$V_{OL}$	Output LOW Voltage (Note 12)	-1945	-1820	-1695	-1945	-1820	-1695	-1945	-1820	-1695	mV
$V_{IH}$	Input HIGH Voltage (Single-Ended) LVNECL	-1225		-880	-1225		-880	-1225		-880	mV
$V_{IL}$	Input LOW Voltage (Single-Ended) LVNECL	-1945		-1625	-1945		-1625	-1945		-1625	mV
$V_{BB}$	ECL Output Voltage Reference	-1525	-1425	-1325	-1525	-1425	-1325	-1525	-1425	-1325	mV
$V_{EF}$	Reference Voltage for ECL Mode Connection	-1400	-1280	-1250	-1425	-1220	-1250	-1450	-1170	-1250	mV
$V_{IHCMR}$	Input HIGH Voltage Common Mode Range (Differential Configuration) (Note 13)	$V_{EE}+1.2$		0.0	$V_{EE}+1.2$		0.0	$V_{EE}+1.2$		0.0	V
$I_{IH}$	Input HIGH Current (@ $V_{IH}$ )			150			150			150	$\mu\text{A}$
$I_{IL}$	Input LOW Current (@ $V_{IL}$ )	$\overline{IN}$ 0.5 $\overline{IN}$ -150			0.5 -150			0.5 -150			$\mu\text{A}$

NOTE: Device will meet the specifications after thermal equilibrium has been established when mounted in a test socket or printed circuit board with maintained transverse airflow greater than 500 lfm. Electrical parameters are guaranteed only over the declared operating temperature range. Functional operation of the device exceeding these conditions is not implied. Device specification limit values are applied individually under normal operating conditions and not valid simultaneously.

10. Input and output parameters vary 1:1 with  $V_{CC}$ .  $V_{EE}$  can vary +0.3 V to -0.3 V.

11. Required 500 lfm air flow when using +5 V power supply. For  $(V_{CC} - V_{EE}) > 3.3\text{ V}$ ,  $5\ \Omega$  to  $10\ \Omega$  in line with  $V_{EE}$  required for maximum thermal protection at elevated temperatures. Recommend  $V_{CC} - V_{EE}$  operation at  $\leq 3.8\text{ V}$ .

12. All loading with  $50\ \Omega$  to  $V_{CC} - 2.0\text{ V}$ .

13.  $V_{IHCMR}$  min varies 1:1 with  $V_{EE}$ .  $V_{IHCMR}$  max varies 1:1 with  $V_{CC}$ . The  $V_{IHCMR}$  range is referenced to the most positive side of the differential input signal.

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**Table 11. AC CHARACTERISTICS**  $V_{CC} = 0\text{ V}$ ;  $V_{EE} = -3.0\text{ V}$  to  $-3.6\text{ V}$  or  $V_{CC} = 3.0\text{ V}$  to  $3.6\text{ V}$ ;  $V_{EE} = 0\text{ V}$  (Note 14)

Symbol	Characteristic	-40°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$f_{max}$	Maximum Frequency		1.2			1.2			1.2		GHz
$t_{PLH}$ $t_{PHL}$	Propagation Delay IN to Q; D(0-10) = 0 IN to Q; D(0-10) = 1023 $\overline{EN}$ to Q; D(0-10) = 0 D0 to CASCADE	1650 9500 1600 300	2050 11500 2150 420	2450 13500 2600 500	1800 10000 1800 350	2200 12200 2300 450	2600 14000 2800 550	1950 10800 2000 425	2350 13300 2500 525	2750 15800 3000 625	ps
$t_{RANGE}$	Programmable Range $t_{PD}(\text{max}) - t_{PD}(\text{min})$	7850	9450		8200	10000		8850	10950		ps
$\Delta t$	Step Delay (Note 15) D0 High D1 High D2 High D3 High D4 High D5 High D6 High D7 High D8 High D9 High		13 27 44 90 130 312 590 1100 2250 4500			14 30 47 97 140 335 650 1180 2400 4800			41 100 145 360 690 1300 2650 5300		ps
NLIN	Non-Linearity (Note 21)					TBD					ps
$t_{SKEW}$	Duty Cycle Skew (Note 16) $ t_{PHL} - t_{PLH} $		25			25			25		ps
$t_s$	Setup Time D to LEN D to IN (Note 17) $\overline{EN}$ to IN (Note 18)	200 300 300	0 140 150		200 300 300	0 160 170		200 300 300	0 180 180		ps
$t_h$	Hold Time LEN to D IN to $\overline{EN}$ (Note 19)	200 400	60 250		200 400	100 280		200 400	80 300		ps
$t_R$	Release Time $\overline{EN}$ to IN (Note 20) SET MAX to LEN SET MIN to LEN	150 400 350	-25 200 275		150 400 350	-75 250 200		150 400 350	-50 300 225		ps
$t_{jitter}$	RMS Random Clock Jitter @ 1.2 GHz IN to Q; D(0:10) = 0 or SETMIN IN to Q; D(0:10) = 1023 or SETMAX		0.86 0.89			1.16 1.09			1.12 1.02		ps
$V_{PP}$	Input Voltage Swing (Differential Configuration)	150	800	1200	150	800	1200	150	800	1200	mV
$t_r$ $t_f$	Output Rise/Fall Time @ 50 MHz 20-80% (Q) 20-80% (CASCADE)	85 100	100 140	135 200	85 110	110 150	135 200	95 130	125 170	155 220	ps

NOTE: Device will meet the specifications after thermal equilibrium has been established when mounted in a test socket or printed circuit board with maintained transverse airflow greater than 500 lfm. Electrical parameters are guaranteed only over the declared operating temperature range. Functional operation of the device exceeding these conditions is not implied. Device specification limit values are applied individually under normal operating conditions and not valid simultaneously.

14. Measured using a 750 mV source, 50% duty cycle clock source. All loading with  $50\ \Omega$  to  $V_{CC} - 2.0\text{ V}$ .

15. Specification limits represent the amount of delay added with the assertion of each individual delay control pin. The various combinations of asserted delay control inputs will typically realize D0 resolution steps across the specified programmable range.

16. Duty cycle skew guaranteed only for differential operation measured from the cross point of the input to the cross point of the output.

17. This setup time defines the amount of time prior to the input signal the delay tap of the device must be set.

18. This setup time is the minimum time that  $\overline{EN}$  must be asserted prior to the next transition of IN/ $\overline{IN}$  to prevent an output response greater than  $\pm 75\text{ mV}$  to that IN/ $\overline{IN}$  transition.

19. This hold time is the minimum time that  $\overline{EN}$  must remain asserted after a negative going IN or positive going  $\overline{IN}$  to prevent an output response greater than  $\pm 75\text{ mV}$  to that IN/ $\overline{IN}$  transition.

20. This release time is the minimum time that  $\overline{EN}$  must be deasserted prior to the next IN/ $\overline{IN}$  transition to ensure an output response that meets the specified IN to Q propagation delay and transition times.

21. Deviation from a linear delay (actual Min to Max) in the 1024 programmable steps.

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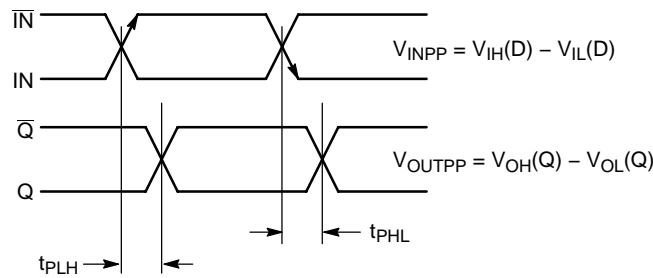


Figure 4. AC Reference Measurement

### Using the FTUNE Analog Input

The analog FTUNE pin on the EP196 device is intended to add more delay in a tunable gate to enhance the 10 ps resolution capabilities of the fully digital EP196. The level of resolution obtained is dependent on the voltage applied to the FTUNE pin.

To provide this further level of resolution, the FTUNE pin must be capable of adjusting the additional delay finer than the 10 ps digital resolution (See Logic Diagram). This requirement is easily achieved because a 60 ps additional delay can be obtained over the entire FTUNE voltage range (See Figure 5). This extra analog range ensures that the

FTUNE pin will be capable even under worst case conditions of covering a digital resolution. Typically, the analog input will be driven by an external DAC to provide a digital control with very fine analog output steps. The final resolution of the device will be dependent on the width of the DAC chosen.

To determine the voltage range necessary for the FTUNE input, Figure 5 should be used. There are numerous voltage ranges which can be used to cover a given delay range; users are given the flexibility to determine which one best fits their designs.

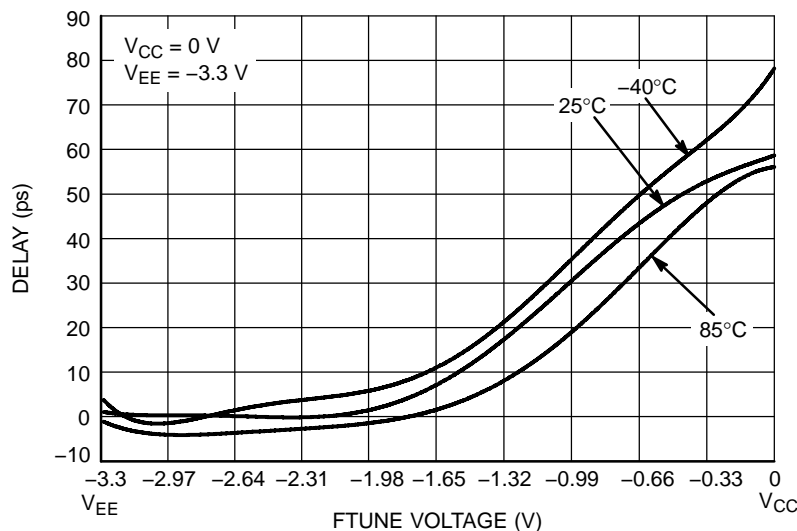


Figure 5. Typical EP196A Delay versus FTUNE Voltage

### Cascading Multiple EP196As

To increase the programmable range of the EP196A, internal cascade circuitry has been included. This circuitry allows for the cascading of multiple EP196As without the need for any external gating. Furthermore, this capability requires only one more address line per added EP196A. Obviously, cascading multiple programmable delay chips will result in a larger programmable range; however, this increase is at the expense of a longer minimum delay.

Figure 6 illustrates the interconnect scheme for cascading two EP196As. As can be seen, this scheme can easily be

expanded for larger EP196A chains. The D10 input of the EP196A is the CASCADE control pin. With the interconnect scheme of Figure 6 when D10 is asserted, it signals the need for a larger programmable range than is achievable with a single device and switches output pin CASCADE HIGH and pin  $\overline{CASCADE}$  LOW. The A11 address can be added to generate a cascade output for the next EP196A. For a 2-device configuration, A11 is not required.



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An expansion of the latch section of the block diagram is pictured in Figure 7. Use of this diagram will simplify the explanation of how the cascade circuitry works. When D10 of chip #1 in Figure 6 is LOW this device's CASCADE output will also be low while the CASCADE output will be high. In this condition the SET MIN pin of chip #2 will be asserted HIGH and thus all of the latches of chip #2 will be reset and the device will be set at its minimum delay.

Chip #1, on the other hand, will have both SET MIN and SET MAX deasserted so that its delay will be controlled entirely by the address bus A0—A9. If the delay needed is greater than can be achieved with 1023 gate delays

(1111111111 on the A0—A9 address bus) D10 will be asserted to signal the need to cascade the delay to the next EP196A device. When D10 is asserted, the SET MIN pin of chip #2 will be deasserted and SET MAX pin asserted resulting in the device delay to be the maximum delay. Table 12 shows the delay time of two EP196A chips in cascade.

To expand this cascading scheme to more devices, one simply needs to connect the D10 pin from the next chip to the address bus and CASCADE outputs to the next chip in the same manner as pictured in Figure 6. The only addition to the logic is the increase of one line to the address bus for cascade control of the second programmable delay chip.

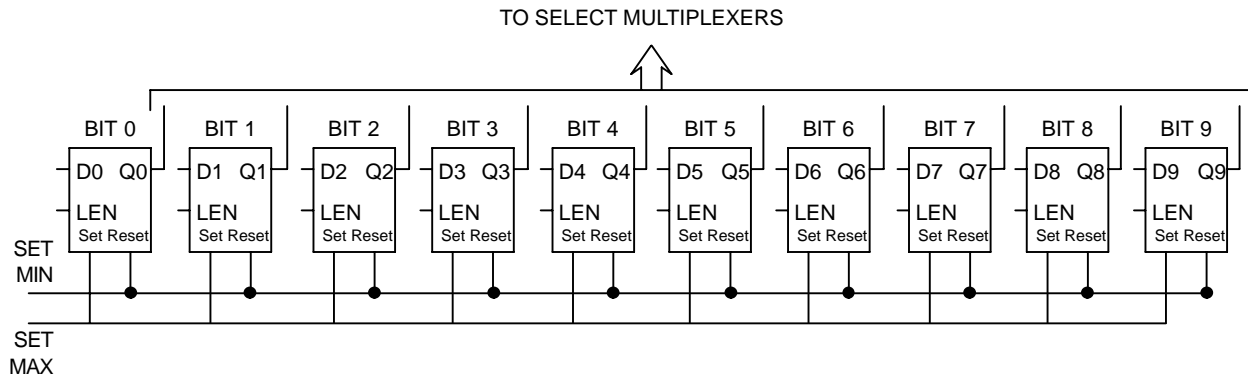


Figure 7. Expansion of the Latch Section of the EP196A Block Diagram

# MC100EP196A

**Table 12. Delay Value of Two EP196A Cascaded**

VARIABLE INPUT TO CHIP #1 AND SETMIN FOR CHIP #2												
INPUT FOR CHIP #1											Delay Value	Total Delay Value
D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0		
0	0	0	0	0	0	0	0	0	0	0	0 ps	4400 ps
0	0	0	0	0	0	0	0	0	0	1	10 ps	4410 ps
0	0	0	0	0	0	0	0	0	1	0	20 ps	4420 ps
0	0	0	0	0	0	0	0	0	1	1	30 ps	4430 ps
0	0	0	0	0	0	0	0	1	0	0	40 ps	4440 ps
0	0	0	0	0	0	0	0	1	0	1	50 ps	4450 ps
0	0	0	0	0	0	0	0	1	1	0	60 ps	4460 ps
0	0	0	0	0	0	0	0	1	1	1	70 ps	4470 ps
0	0	0	0	0	0	0	1	0	0	0	80 ps	4480 ps
0	0	0	0	0	0	1	0	0	0	0	160 ps	4560 ps
0	0	0	0	0	1	0	0	0	0	0	220 ps	4720 ps
0	0	0	0	1	0	0	0	0	0	0	640 ps	5040 ps
0	0	0	1	0	0	0	0	0	0	0	1280 ps	5680 ps
0	0	1	0	0	0	0	0	0	0	0	2560 ps	6960 ps
0	1	0	0	0	0	0	0	0	0	0	5120 ps	9520 ps
0	1	1	1	1	1	1	1	1	1	1	10230 ps	14630 ps

VARIABLE INPUT TO CHIP #1 AND SETMAX FOR CHIP #2												
INPUT FOR CHIP #1											Delay Value	Total Delay Value
D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0		
1	0	0	0	0	0	0	0	0	0	0	10240 ps	14640 ps
1	0	0	0	0	0	0	0	0	0	1	10250 ps	14650 ps
1	0	0	0	0	0	0	0	0	1	0	10260 ps	14660 ps
1	0	0	0	0	0	0	0	0	1	1	10270 ps	14670 ps
1	0	0	0	0	0	0	0	1	0	0	10280 ps	14680 ps
1	0	0	0	0	0	0	0	1	0	1	10290 ps	14690 ps
1	0	0	0	0	0	0	0	1	1	0	10300 ps	14700 ps
1	0	0	0	0	0	0	0	1	1	1	10310 ps	14710 ps
1	0	0	0	0	0	0	1	0	0	0	10320 ps	14720 ps
1	0	0	0	0	0	1	0	0	0	0	10400 ps	14800 ps
1	0	0	0	0	1	0	0	0	0	0	10560 ps	14960 ps
1	0	0	0	1	0	0	0	0	0	0	10880 ps	15280 ps
1	0	0	1	0	0	0	0	0	0	0	11520 ps	15920 ps
1	0	1	0	0	0	0	0	0	0	0	12800 ps	17200 ps
1	1	0	0	0	0	0	0	0	0	0	15360 ps	19760 ps
1	1	1	1	1	1	1	1	1	1	1	20470 ps	24870 ps

# MC100EP196A

## Multi-Channel Deskewing

The most practical application for EP196A is in multiple channel delay matching. Slight differences in impedance and cable length can create large timing skews within a high-speed system. To deskew multiple signal channels, each channel can

be sent through each EP196A as shown in Figure 8. One signal channel can be used as reference and the other EP196As can be used to adjust the delay to eliminate the timing skews. Nearly any high-speed system can be fine-tuned (as small as 10 ps) to reduce the skew to extremely tight tolerances.

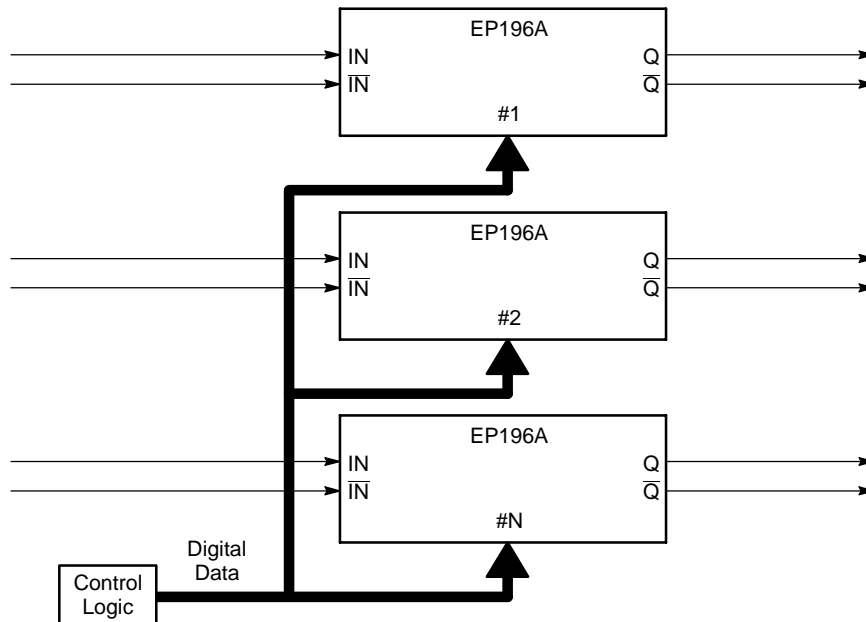


Figure 8. Multiple Channel Deskewing Diagram

## Measure Unknown High Speed Device Delays

EP196As provide a possible solution to measure the unknown delay of a device with a high degree of precision. By combining two EP196As and EP31 as shown in Figure 9, the delay can be measured. The first EP196A can be set to SETMIN and its output is used to drive the unknown delay device, which in turn drives the input of a D flip-flop of EP31. The second EP196A is triggered along with the first EP196A and its output provides a clock signal for EP31. The programmed delay of the second EP196A is varied to detect the output edge from the unknown delay device.

If the programmed delay through the second EP196A is too long, the flip-flop output will be at logic high. On the other hand, if the programmed delay through the second EP196A is too short, the flip-flop output will be at a logic low. If the programmed delay is correctly fine-tuned in the second EP196A, the flip-flop will bounce between logic high and logic low. The digital code in the second EP196A can be directly correlated into an accurate device delay.

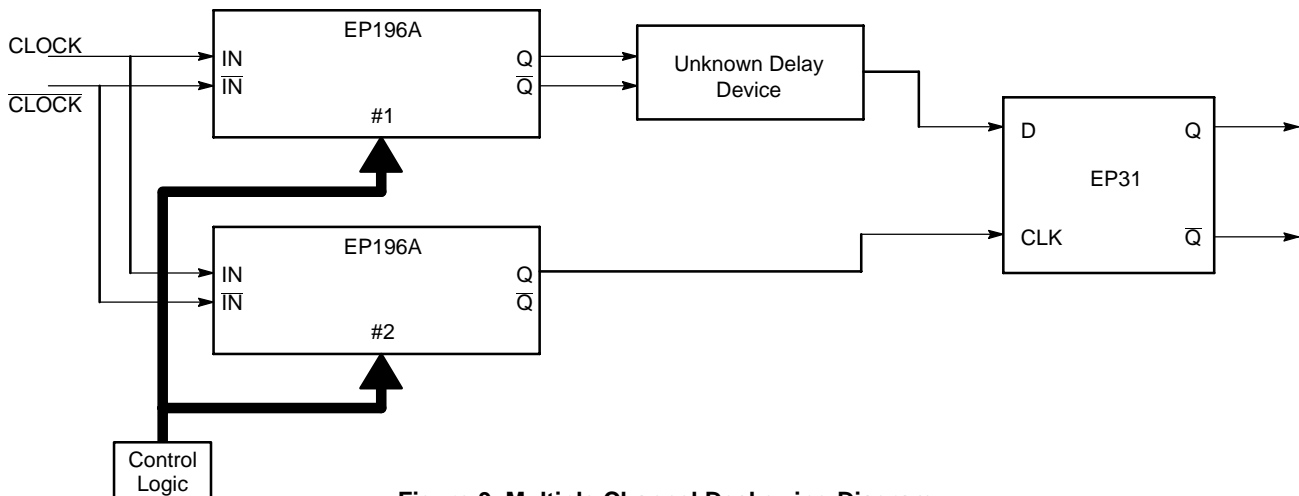
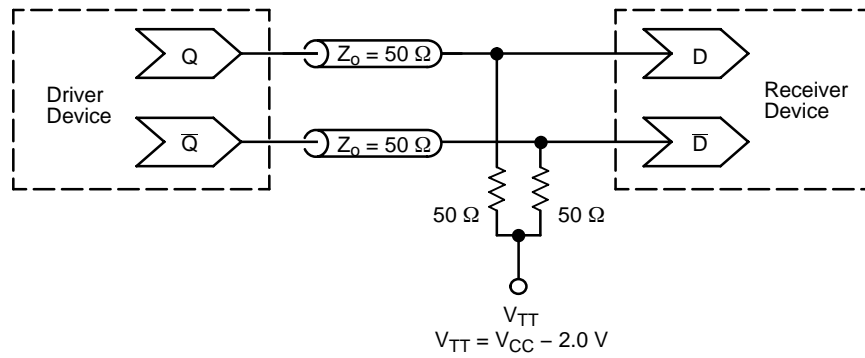


Figure 9. Multiple Channel Deskewing Diagram

## MC100EP196A



**Figure 10. Typical Termination for Output Driver and Device Evaluation  
(See Application Note AND8020/D – Termination of ECL Logic Devices.)**

### ORDERING INFORMATION

Device	Package	Shipping <sup>†</sup>
MC100EP196AMNG	QFN-32 (Pb-Free)	74 Units / Rail
MC100EP196AMNR4G	QFN-32 (Pb-Free)	1000 / Tape & Reel

<sup>†</sup>For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.



# MC100EP196A

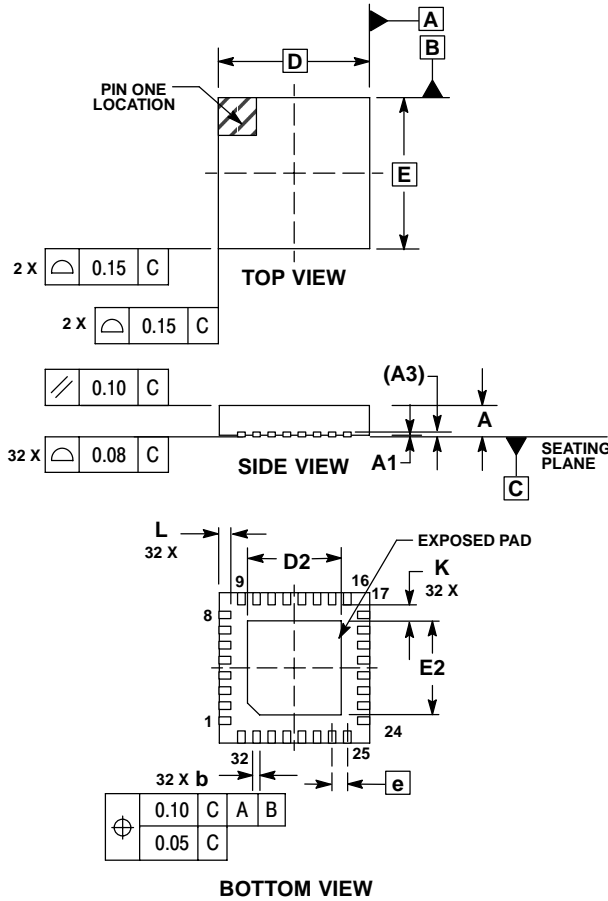
## Resource Reference of Application Notes

- AN1405/D** – ECL Clock Distribution Techniques
- AN1406/D** – Designing with PECL (ECL at +5.0 V)
- AN1503/D** – ECLinPS™ I/O SPiCE Modeling Kit
- AN1504/D** – Metastability and the ECLinPS Family
- AN1568/D** – Interfacing Between LVDS and ECL
- AN1642/D** – The ECL Translator Guide
- AND8001/D** – Odd Number Counters Design
- AND8002/D** – Marking and Date Codes
- AND8020/D** – Termination of ECL Logic Devices
- AND8066/D** – Interfacing with ECLinPS
- AND8090/D** – AC Characteristics of ECL Devices

# MC100EP196A

## PACKAGE DIMENSIONS

QFN32 5\*5\*1 0.5 P  
CASE 488AM-01  
ISSUE O

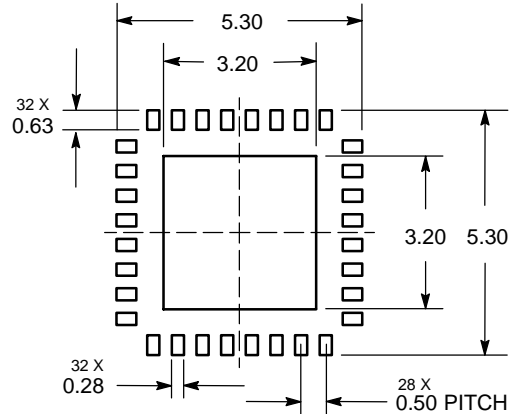


### NOTES:

1. DIMENSIONS AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. DIMENSION b APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN 0.25 AND 0.30 MM TERMINAL
4. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMINALS.

DIM	MILLIMETERS		
	MIN	NOM	MAX
A	0.800	0.900	1.000
A1	0.000	0.025	0.050
A3	0.200 REF		
b	0.180	0.250	0.300
D	5.00 BSC		
D2	2.950	3.100	3.250
E	5.00 BSC		
E2	2.950	3.100	3.250
e	0.500 BSC		
K	0.200	---	---
L	0.300	0.400	0.500

### SOLDERING FOOTPRINT\*



DIMENSIONS: MILLIMETERS

\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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