

Single-phase DC Brushless Motor Driver IC

■ GENERAL DESCRIPTION

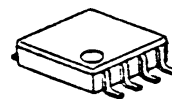
The NJU7356 is single-phase DC brushless motor driver IC. And It features MOS-FET driver circuit for better output characteristics.

NJU7356 features Lock Detect, Frequency Generator Output, Thermal Shutdown Circuit and Hall Bias Terminal.

Maximum output current is 1000mA and Continuance output current is 400mA.

It is suitable for variable speed FAN required Low Noise & Good Efficiency characteristics.

■ PACKAGE OUTLINE

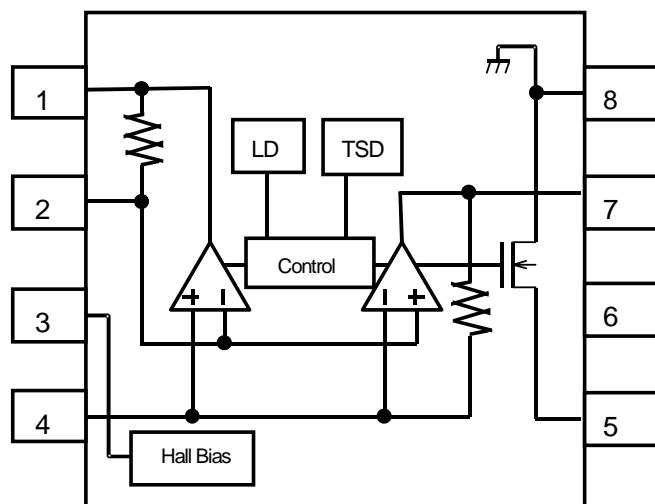


NJU7356RB1

■ FEATURES

- Operating Voltage 2.2 to 5.5V
- Low Operating Current $I_{DD}=2\text{mA}$
- Low Saturation Output Voltage
 $V_{sat}= \pm 0.2\text{V} @ I_o=\pm 400\text{mA}$
- Lock Detect / Auto Release Circuit
- Thermal Shutdown Circuit
- Frequency Generator Output
- Hall Bias Terminal
- CMOS Technology
- Package Outline TVSP8

■ BLOCK DIAGRAM



■ PIN FUNCTION

- 1: OUTB
- 2: IN +
- 3: HB
- 4: IN -
- 5: FG
- 6: V_{DD}
- 7: OUT A
- 8: V_{SS}

NJU7356

■ ABSOLUTE MAXIMUM RATINGS

(Ta=25°C)

PARAMETER	RATINGS	SYMBOL (unit)	NOTE
Supply Voltage	+7.0	V _{DD} (V)	
Input Voltage	-0.3 ~ V _{DD}	V _{ID} (V)	
Output Current (Continuance)	400	I _O (mA)	Note1
Output Current (Peak)	1000	I _{OPEAK} (mA)	Note2
Operating Temperature Range	-40 ~ +85	Topr (°C)	
Storage Temperature Range	-50 ~ +150	Tstg (°C)	
Power Dissipation	400	P _D (mW)	Device itself
Junction Temperature	150	Tjmax(°C)	

Note1 : This value is not to be over Pd.

Note2 : Input voltage is not to be over supply voltage to really use.

■ RECOMMENDED OPERATING CONDITIONS

(Ta=25°C)

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
Supply Voltage	V _{DD}	Ct=0	2.2	5.0	5.5	V

■ ELECTRICAL CHARACTERISTICS

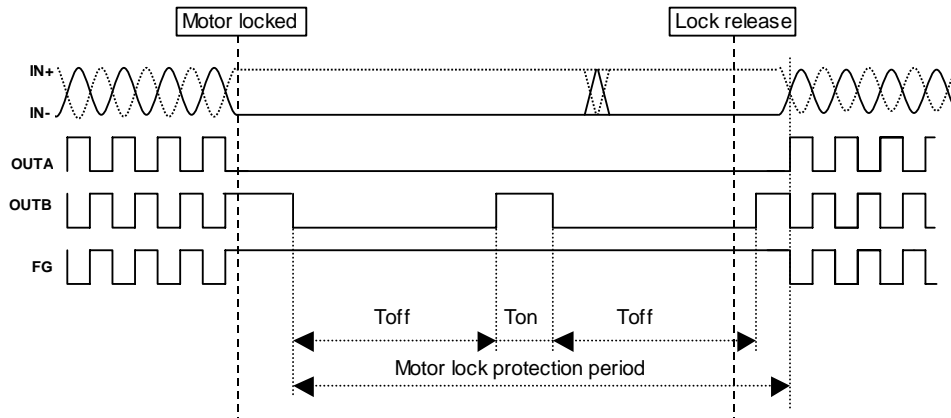
(V_{DD} =5V, Ta=25°C)

PARAMETER	SYMBOL	CONDITION	MIN.	TYP.	MAX.	UNIT
General						
Operating Current	I _{DD}	-	-	2.0	5.0	mA
Thermal Shutdown Temperature	T _{TSD}	-	-	180	-	°C
Thermal Shutdown Hysteresis	T _{HYS}	-	-	50	-	°C
Hall Amplifier						
Input Offset Voltage	V _{IO}	-	-10	-	10	mV
Feedback Resistance	R _F	-	-	27.5	-	kΩ
Open Loop Gain	A _V	-	-	70	-	dB
Input Common Mode Voltage Range	V _{ICM}	-	0.4	-	4.0	V
Output						
Maximum Output Voltage Range	V _{OH}	I _o =+400mA	4.65	4.80	-	V
	V _{OL}	I _o =-400mA	-	0.20	0.35	
Output Resistance	R _{ONH}	I _o =+400mA	-	0.5	-	Ω
	R _{ONL}	I _o =-400mA	-	0.5	-	
FG L Output Voltage	V _{FG}	IN+=5V, IN-=0V, R _L =10kΩ	-	-	0.3	V
FG H Leak Current	I _{FG-LEAK}	IN+=0V, IN-=5V, FG=5V	-	-	1.0	μA
Lock Detect Circuit*						
Lock Protect ON Time	T _{ON}	-	-	0.5	-	sec
Lock Protect OFF Time	T _{OFF}	-	-	3.5	-	sec
Detect Protection ON/OFF Ratio	T _{RATIO}	-	-	1:7	-	-
Hall Bias						
Hall Bias Voltage	V _{HB}	-	1.1	1.3	1.5	V

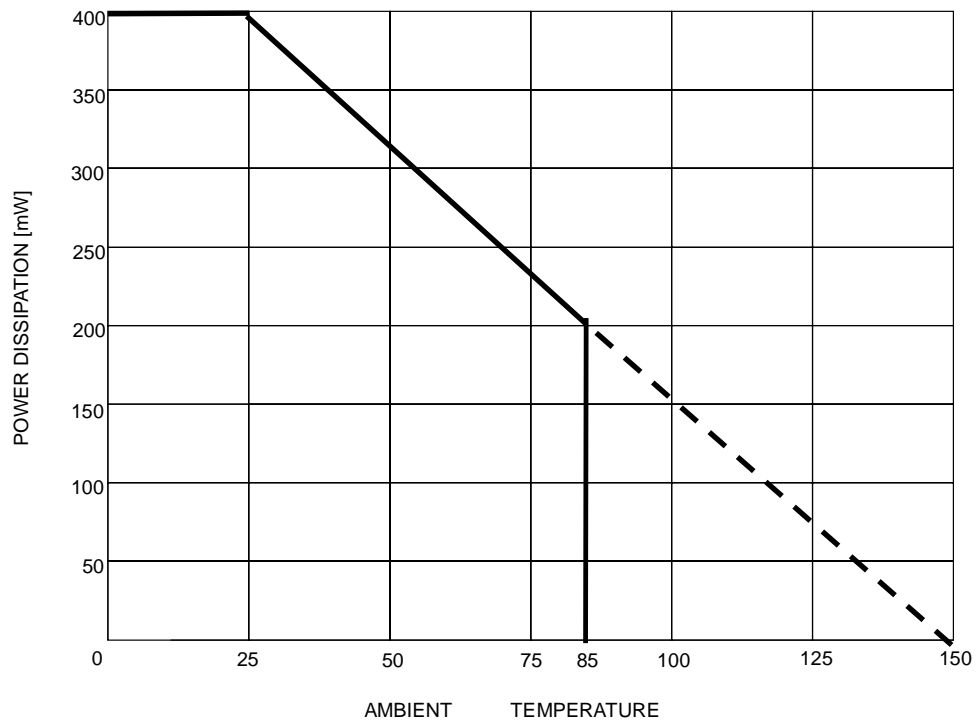
INPUT-OUTPUT TRUTH TABLE

IN+	IN -	OUTA	OUTB	FG
H	L	H	L	L (Output Transistor ON)
L	H	L	H	Z (Output Transistor OFF)

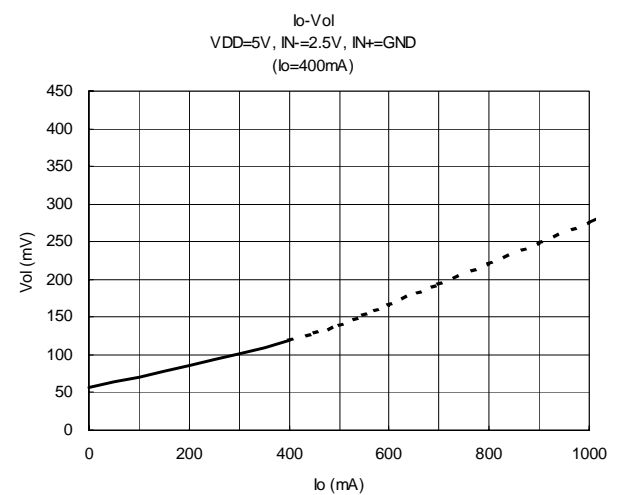
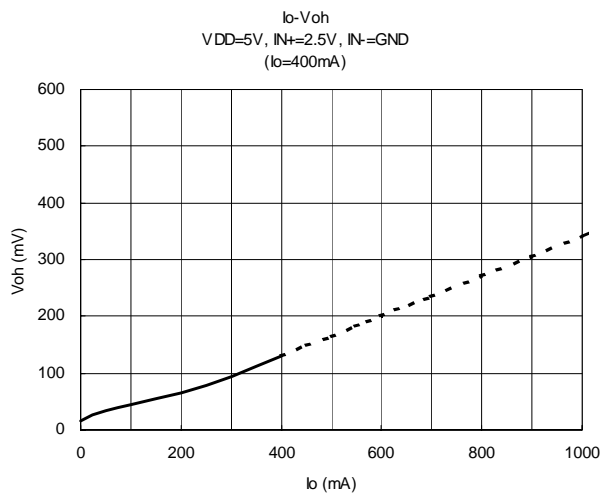
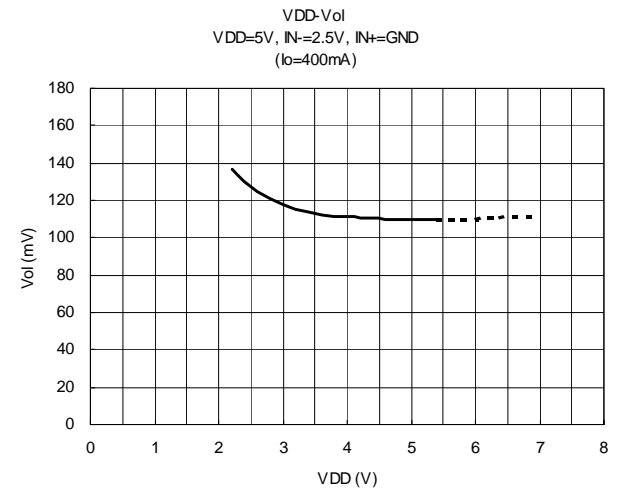
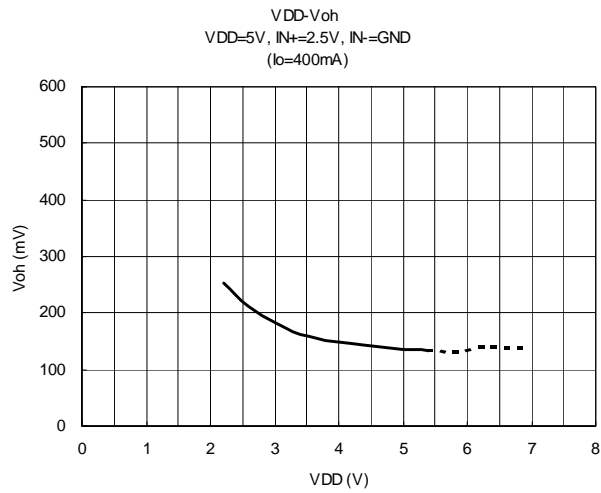
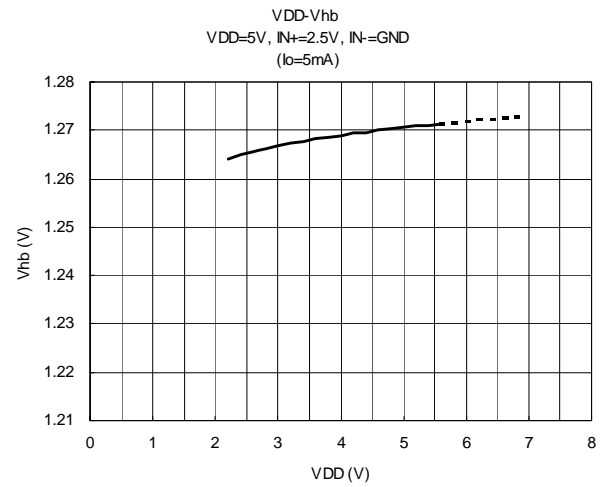
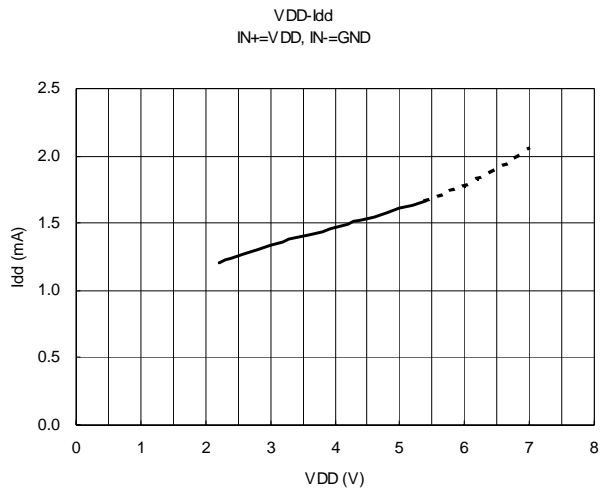
TIMING CHART



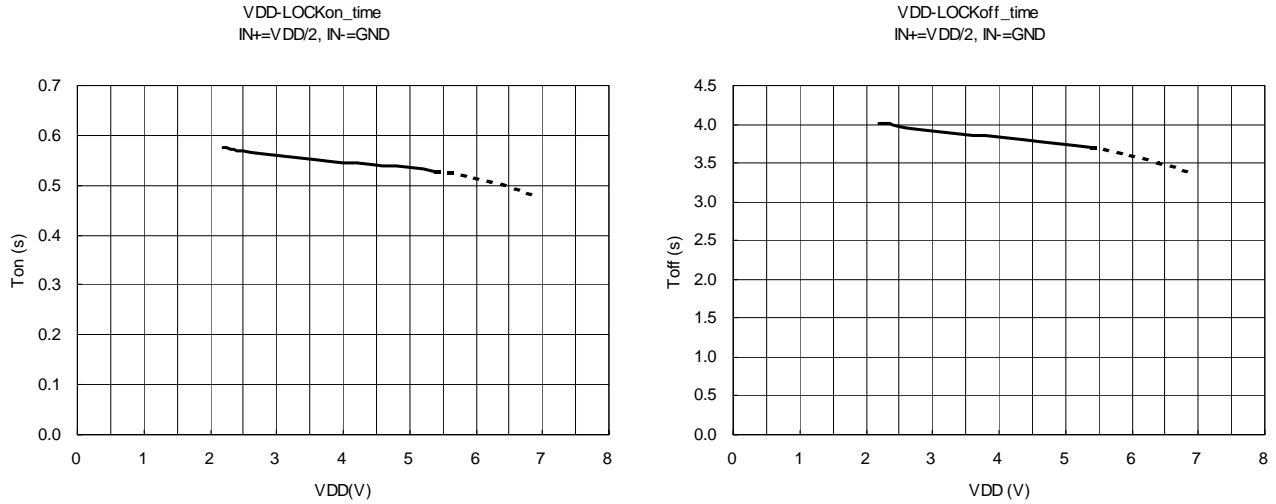
POWER DISSIPATION



TYPICAL CHARACTERISTICS



■ TYPICAL CHARACTERISTICS

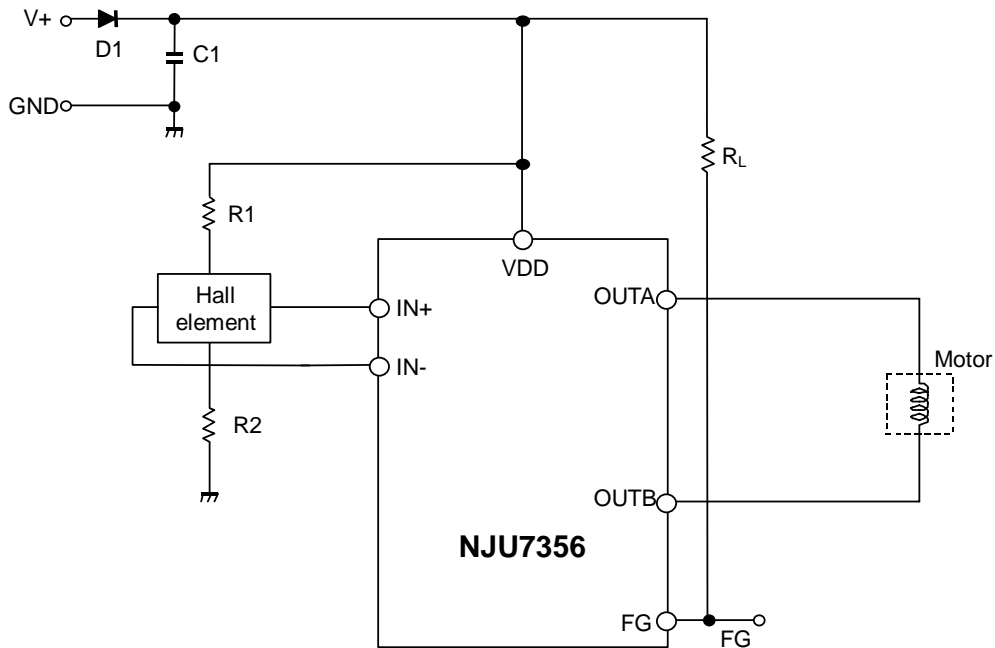


■ APPLICATION NOTE

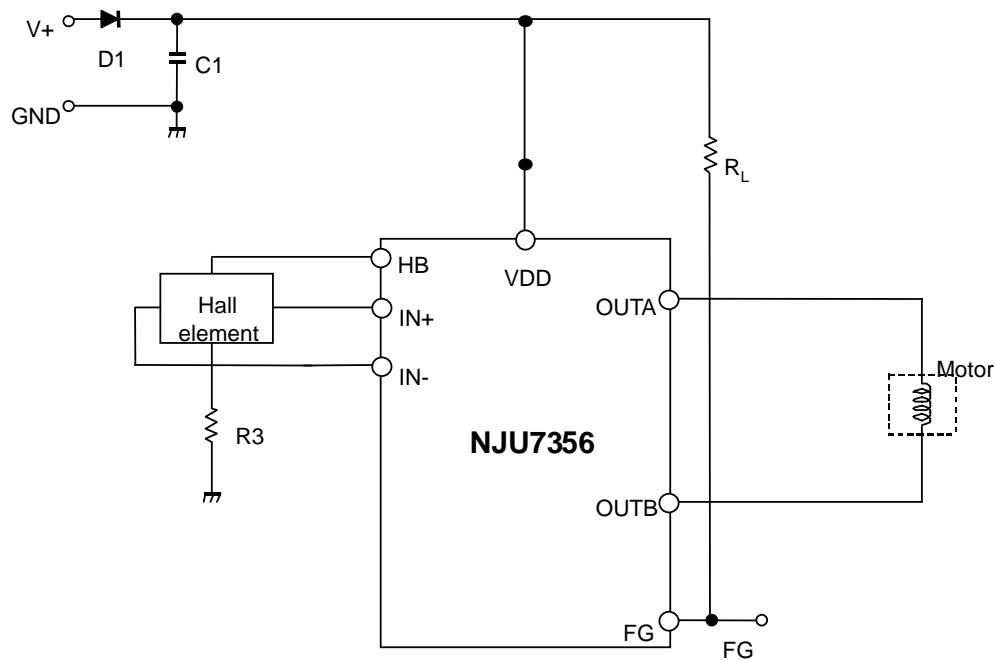
The NJU7356 are single-phase DC brushless motor driver IC in small TVSP8 package. With minimal external components, that can drive up to 400mA of motor current for small fan application.

[Application Circuit Example]

1) Hall Bias unused application circuit



2) Hall bias used application circuit



[Design Notes]

Above application example is designed for 5V operation with motor current of 400mA. It uses the following components:

Hall elements: HW101A (AKE)

1. Selection of C1 and D1:

C1 is used for a noise reduction purpose. A typical value is 0.1uF.

Optimize the value in actual operating conditions if necessary. D1 is a diode for protection against reverse voltage supply. Silicon rectifier diode (WO3C, 10D1 and equivalent) is appropriate.

2. Position Detection Circuit Hall Device

2-1. When using V_{DD} (R1 and R2)

Hall amplifier is a differential amplifier.

The common-mode input voltage is between 0.4V and $V_{DD}-1V$ and the input signal must be within the range.

Non-excitation hall bias voltage is to be set at a half of V_{DD} for effective use of common-mode input voltage range.

Therefore the same value of hall bias resistors is selected for R1 and R2.

Given that the bias current is set to be 5mA by HW101A datasheet, R1 and R2 can be determined as follows:

$$R1 + R2 + R_{in} = \frac{V_{DD}}{I_{bias}} = \frac{5}{5 \times 10^{-3}} = 1.0k\Omega$$

$$R1 = R2 = 300\Omega$$

The output voltage of hall elements is influenced by the bias current and magnetic flux density of hall elements.
The optimum input voltage of NJU7356 are 100mVp-p and higher. With such input voltage, the highest efficiency can be obtained.

2-2. When using HB (R3 design)

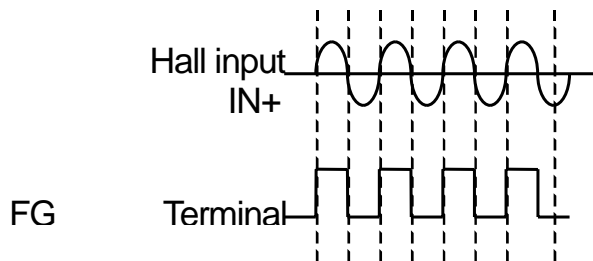
By connecting a Hall device to the Hall bias terminal (HB), a constant Hall output amplitude that has good temperature characteristics is obtained, resulting in stable linear drive. If it is necessary to adjust the Hall output amplitude, perform adjustment with R3.

3. Design of FG output resistance (R_L)

FG Out (FG: Pin5) is an open drain output and R_L is a pull up register. A typical value of R_L is 10k Ω .

The timing chart of FG Out is as follows.

Note that the pull up resistance shall be connected to below supply voltage.



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