

## HIGH SPEED 1K X 8 DUAL-PORT STATIC SRAM

## Features

### High-speed access

- Commercial: 20/25/35/55/100ns (max.)
- Industrial: 25/55/100ns (max.)
- Military: 25/35/55/100ns (max.)
- Low-power operation
  - IDT7130/IDT7140SA Active: 550mW (typ.) Standby: 5mW (typ.)
  - IDT7130/IDT7140LA
    Active: 550mW (typ.)
  - Standby: 1mW (typ.)
- MASTER IDT7130 easily expands data bus width to 16-ormore-bits using SLAVE IDT7140

Functional Block Diagram

- On-chip port arbitration logic (IDT7130 Only)
- BUSY output flag on IDT7130; BUSY input on IDT7140
- INT flag for port-to-port communication
- Fully asynchronous operation from either port
- Battery backup operation-2V data retention (LA only)
- TTL-compatible, single 5V ±10% power supply
- Military product compliant to MIL-PRF-38535 QML
- Industrial temperature range (-40°C to +85°C) is available for selected speeds
- Available in 48-pin DIP, LCC and Ceramic Flatpack, 52-pin PLCC, and 64-pin STQFP and TQFP
- Green parts available, see ordering information
- **OE**R OEL CF CER R/W R/WR 1/00L-1/07L I/OOR-I/O7R I/O I/O Control Control BUSYL<sup>(1,2)</sup> BUSYR<sup>(1,2)</sup> A9L A9R Address MEMORY Address : Decoder ARRAY Decoder AOL AOR ARBITRATION CEL Ł ₹ CER and INTERRUPT OEL Y **₹**OER LOGIĆ R/WL Ł -≀R/WR ► INT<sup>(2)</sup> 2689 drw 01

#### NOTES:

- 1. IDT7130 (MASTER): BUSY is open drain output and requires pullup resistor.
- IDT7140 (SLAVE): BUSY is input.
- 2. Open drain output: requires pullup resistor.

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DSC-2689/14

#### Military, Industrial and Commercial Temperature Ranges

## Description

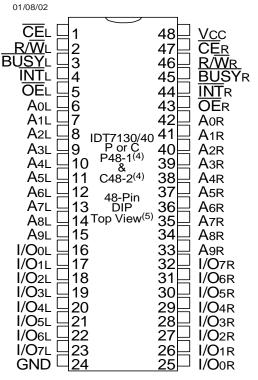
The IDT7130/IDT7140 are high-speed 1K x 8 Dual-Port Static RAMs. The IDT7130 is designed to be used as a stand-alone 8-bit Dual-Port RAM or as a "MASTER" Dual-Port RAM together with the IDT7140 "SLAVE" Dual-Port in 16-bit-or-more word width systems. Using the IDT MASTER/SLAVE Dual-Port RAM approach in 16-or-more-bit memory system applications results in full-speed, error-free operation without the need for additional discrete logic.

Both devices provide two independent ports with separate control, address, and I/O pins that permit independent asynchronous access for reads or writes to any location in memory. An automatic power down feature, controlled by  $\overline{CE}$ , permits the on chip circuitry of each port to enter a very low standby power mode.

Fabricated using IDT's CMOS high-performance tech-nology, these devices typically operate on only 550mW of power. Low-power (LA) versions offer battery backup data retention capability, with each Dual-Port typically consuming 200µW from a 2V battery.

The IDT7130/IDT7140 devices are packaged in 48-pin sidebraze or plastic DIPs, LCCs, flatpacks, 52-pin PLCC, and 64-pin TQFP and STQFP. Military grade products are manufactured in compliance with the latest revision of MIL-PRF-38535 QML, making it ideally suited to military temperature applications demanding the highest level of performance and reliability.

## Pin Configurations<sup>(1,2,3)</sup>

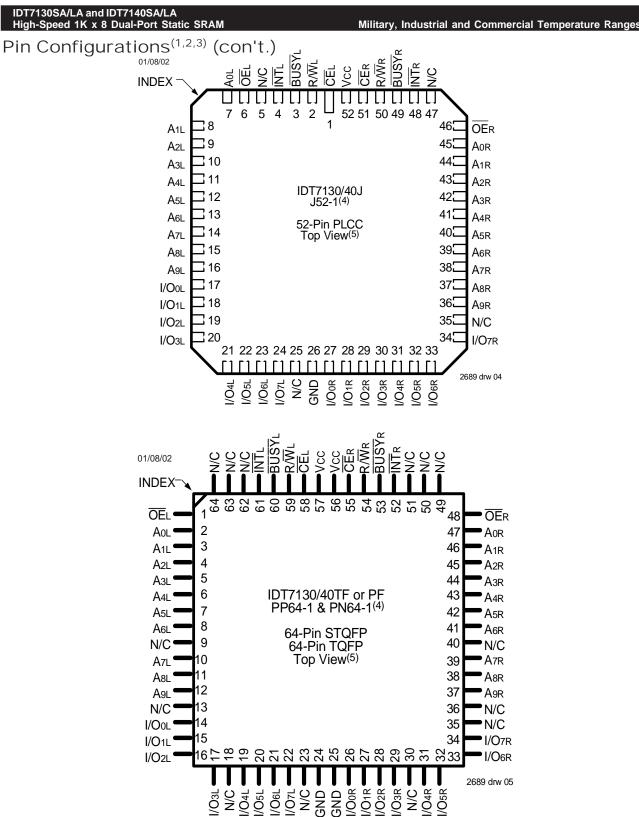


2689 drw 02

#### NOTES:

- 1. All Vcc pins must be connected to power supply.
- 2. All GND pins must be connected to ground supply.
- P48-1 package body is approximately .55 in x .61 in x .19 in. C48-2 package body is approximately .62 in x 2.43 in x .15 in. L48-1 package body is approximately .57 in x .57 in x .68 in. F48-1 package body is approximately .75 in x .75 in x .11 in.
- 4. This package code is used to reference the package diagram.
- 5. This text does not indicate orientation of the actual part-marking.

IN



#### NOTES:

- 1. All Vcc pins must be connected to power supply.
- 2. All GND pins must be connected to ground supply.
- J52-1 package body is approximately .75 in x .75 in x .17 in. PP64-1 package body is approximately 10 mm x 10 mm x 1.4mm. PN64-1 package body is approximately 14mm x 14mm x 1.4mm.
- 4. This package code is used to reference the package diagram.
- 5. This text does not indicate orientation of the actual part-marking.

#### Military, Industrial and Commercial Temperature Ranges

## Absolute Maximum Ratings<sup>(1)</sup>

| Symbol               | Rating                                     | Commercial<br>& Industrial | Military     | Unit |
|----------------------|--|----------------------------|--------------|------|
| VTERM <sup>(2)</sup> | Terminal Voltage<br>with Respect<br>to GND | -0.5 to +7.0               | -0.5 to +7.0 | V    |
| Tbias                | Temperature<br>Under Bias                  | -55 to +125                | -65 to +135  | ٥C   |
| Tstg                 | Storage<br>Temperature                     | -65 to +150                | -65 to +150  | °C   |
| Ιουτ                 | DC Output<br>Current                       | 50                         | 50           | mA   |

#### NOTES:

- Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- 2. VTERM must not exceed Vcc + 10% for more than 25% of the cycle time or 10ns maximum, and is limited to  $\leq$  20mA for the period of VTERM  $\geq$  Vcc + 10%.

## Capacitance (TA = +25°C, f = 1.0MHz) STQFP and TQFP Packages Only

| Symbol | Parameter <sup>(1)</sup> | Conditions | Max. | Unit        |
|--------|--------------------------|------------|------|-------------|
| Cin    | Input Capacitance        | Vin = 3dV  | 9    | pF          |
| Соит   | Output Capacitance       | Vout = 3dV | 10   | pF          |
|        |                          |            |      | 2689 tbl 05 |

NOTES:

 This parameter is determined by device characterization but is not production tested.

3dV references the interpolated capacitance when the input and output signals switch from 0V to 3V or from 3V to 0V.

## Recommended DC Operating Conditions

| Symbol | Parameter          | Min.                | Тур. | Мах.               | Unit |
|--------|--------------------|---------------------|------|--------------------|------|
| Vcc    | Supply Voltage     | 4.5                 | 5.0  | 5.5                | V    |
| GND    | Ground             | 0                   | 0    | 0                  | V    |
| Vih    | Input High Voltage | 2.2                 |      | 6.0 <sup>(2)</sup> | V    |
| VIL    | Input Low Voltage  | -0.5 <sup>(1)</sup> | _    | 0.8                | V    |

#### NOTES:

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1. VIL (min.)  $\geq$  -1.5V for pulse width less than 10ns.

2. VTERM must not exceed Vcc + 10%.

## Recommended Operating Temperature and Supply Voltage<sup>(1)</sup>

| Grade      | Ambient<br>Temperature | GND | Vcc               |
|------------|------------------------|-----|-------------------|
| Military   | -55°C to +125°C        | 0V  | 5.0V <u>+</u> 10% |
| Commercial | 0°C to +70°C           | 0V  | 5.0V <u>+</u> 10% |
| Industrial | -40°C to +85°C         | 0V  | 5.0V <u>+</u> 10% |
| NOTEO      | -                      |     | 2689 tbl 03       |

#### NOTES:

1. This is the parameter TA. This is the "instant on" case temperature.

## DC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range ( $Vcc = 5.0V \pm 10\%$ )

|        |  |   |      | 0SA<br>0SA | -    | 0LA<br>0LA |      |
|--------|--|---|------|------------|------|------------|------|
| Symbol | Parameter  | Test Conditions   | Min. | Max.       | Min. | Max.       | Unit |
| Lu     | Input Leakage Current <sup>(1)</sup>                 | Vcc = 5.5V, VIN = 0V to Vcc                               | _    | 10         | ł    | 5          | μA   |
| llo    | Output Leakage Current <sup>(1)</sup>                | $\frac{V_{CC}}{CE}$ = 5.5V,<br>CE = VIH, VOUT = 0V to VCC | —    | 10         | I    | 5          | μA   |
| Vol    | Output Low Voltage (I/Oo-I/O7)                       | Iol = 4mA   | _    | 0.4        | I    | 0.4        | V    |
| Vol    | Open Drain O <u>utput</u><br>Low Voltage (BUSY, INT) | Iol = 16mA  |      | 0.5        | I    | 0.5        | V    |
| Vон    | Output High Voltage                                  | Юн = -4mA   | 2.4  | _          | 2.4  | _          | V    |

NOTE:

1. At Vcc ≤ 2.0V leakages are undefined.

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DC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(1,5)</sup> (Vcc =  $5.0V \pm 10\%$ )

|        |   |   |              |          | 7130)<br>7140)<br>Com'l |            | 7140       | l, Ind     | 7130<br>7140<br>Co<br>& Mil | )X35<br>m'l |      |
|--------|---|---|--------------|----------|-------------------------|------------|------------|------------|-----------------------------|-------------|------|
| Symbol | Parameter   | Test Condition  | Versio       | on       | Тур.                    | Мах.       | Тур.       | Max.       | Тур.                        | Мах.        | Unit |
| lcc    | Dynamic Operating<br>Current<br>(Both Ports Active)         | CEL and CER = VIL,    Outputs Disabled    f = fMAX <sup>(3)</sup>   | COM'L        | SA<br>LA | 110<br>110              | 250<br>200 | 110<br>110 | 220<br>170 | 110<br>110                  | 165<br>120  | mA   |
|        | (Buill Puils Active)  | T = IMAX <sup>(c)</sup>   | MIL &<br>IND | SA<br>LA | + +                     |            | 110<br>110 | 280<br>220 | 110<br>110                  | 230<br>170  |      |
| ISB1   | Standby Current<br>(Both Ports - TTL<br>Level Inputs)       | $\label{eq:cell} \overline{CE}{L} \mbox{ and } \overline{CE}{R} = V{\rm IH} \\ f = f{M}{A} X^{(3)}$   | COM'L        | SA<br>LA | 30<br>30                | 65<br>45   | 30<br>30   | 65<br>45   | 25<br>25                    | 65<br>45    | mA   |
|        |   |   | MIL &<br>IND | SA<br>LA | -                       | -          | 30<br>30   | 80<br>60   | 25<br>25                    | 80<br>60    |      |
| ISB2   | Standby Current<br>(One Port - TTL<br>Level Inputs)         | $\overline{CE}$ 'A" = VIL and $\overline{CE}$ 'B" = VIH <sup>(6)</sup><br>Active Port OutputsDisabled,<br>f=fmax <sup>(3)</sup>   | COM'L        | SA<br>LA | 65<br>65                | 165<br>125 | 65<br>65   | 150<br>115 | 50<br>50                    | 125<br>90   | mA   |
|        | Level inputs)   | I=IMAX*'  | MIL &<br>IND | SA<br>LA | -                       | -          | 65<br>65   | 160<br>125 | 50<br>50                    | 150<br>115  |      |
| ISB3   | Full Standby Current<br>(Both Ports -<br>CMOS Level Inputs) | CEL and<br>CER ≥ Vcc - 0.2V,<br>Viv ≥ Vcc - 0.2V or   | COM'L        | SA<br>LA | 1.0<br>0.2              | 15<br>5    | 1.0<br>0.2 | 15<br>5    | 1.0<br>0.2                  | 30<br>10    | mA   |
|        |   | $V_{IN} \ge 0.2V, f = 0^{(4)}$  | MIL &<br>IND | SA<br>LA | -                       |            | 1.0<br>0.2 | 30<br>10   | _                           |             |      |
| ISB4   | Full Standby Current<br>(One Port -<br>CMOS Level Inputs)   | $\overline{\underline{CE}}^* A^* \leq 0.2V \text{ and} \\ \overline{CE}^* B^* \geq VCC - 0.2V^{(6)} \\ VW = VCC - 0.2V^{(6)} \\ VW = 0.2V \\$ | COM'L        | SA<br>LA | 60<br>60                | 155<br>115 | 60<br>60   | 145<br>105 | 45<br>45                    | 110<br>85   | mA   |
|        | Givios Level Inputs)  | $V_{IN} \ge \overline{V}_{CC} - 0.2V$ or $V_{IN} \le 0.2V$<br>Active Port Outputs Disabled,<br>$f = f_{MAX}^{(B)}$  | MIL &<br>IND | SA<br>LA |                         |            | 60<br>60   | 155<br>115 | 45<br>45                    | 145<br>105  |      |

|                        |  |  |              |            |            | 0X55<br>0X55<br>'I, Ind<br>litary | 7140<br>Com | 0X100<br>0X100<br>11, Ind<br>ilitary |      |
|------------------------|--|--|--------------|------------|------------|-----------------------------------|-------------|--------------------------------------|------|
| Symbol                 | Parameter  | Test Condition   | Versi        | on         | Тур.       | Мах.                              | Тур.        | Мах.                                 | Unit |
| lcc                    | Dynamic Operating<br>Current<br>(Both Ports Active)  | CEL and CER = VIL,    Outputs Disabled    f = fMAX <sup>(3)</sup>  | COM'L        | SA<br>LA   | 110<br>110 | 155<br>110                        | 110<br>110  | 155<br>110                           | mA   |
|                        | (DUIT POILS ACTIVE)  | T = IMAX*'   | MIL &<br>IND | SA<br>LA   | 110<br>110 | 190<br>140                        | 110<br>110  | 190<br>140                           |      |
| ISB1                   | Standby Current<br>(Both Ports - TTL   | $\overline{CE}L$ and $\overline{CE}R = VIH$<br>f = fMAX <sup>(3)</sup>   | COM'L        | SA<br>LA   | 20<br>20   | 65<br>35                          | 20<br>20    | 55<br>35                             | mA   |
| Level Inputs)          |  | MIL &<br>IND   | SA<br>LA     | 20<br>20   | 65<br>45   | 20<br>20                          | 65<br>45    |                                      |      |
| ISB2                   | Standby Current<br>(One Port - TTL   | $\overline{CE}^{*}A^{*} = V_{IL}$ and $\overline{CE}^{*}B^{*} = V_{IH}^{(6)}$<br>Active Port Outputs Disabled,<br>$f=fmax^{(3)}$ | COM'L        | SA<br>LA   | 40<br>40   | 110<br>75                         | 40<br>40    | 110<br>75                            | mA   |
|                        | Level Inputs)  | T=IMAX*'   | MIL &<br>IND | SA<br>LA   | 40<br>40   | 125<br>90                         | 40<br>40    | 125<br>90                            |      |
| ISB3                   | Full Standby Current<br>(Both Ports -  | CEL and<br>CER ≥ Vcc - 0.2V,   | COM'L        | SA<br>LA   | 1.0<br>0.2 | 15<br>4                           | 1.0<br>0.2  | 15<br>4                              | mA   |
| CMOS Level Inputs) VIN | $ \begin{array}{l} V_{IN} \geq V_{CC} - 0.2V \text{ or} \\ V_{IN} \leq 0.2V, \ f = 0^{(d)} \end{array} $           | MIL &<br>IND   | SA<br>LA     | 1.0<br>0.2 | 30<br>10   | 1.0<br>0.2                        | 30<br>10    |                                      |      |
| ISB4                   | (One Port - $\overline{CE}^{"B"} > VCC - 0.2V^{(6)}$   | $\overline{CE}"B" > VCC - 0.2V^{(6)}$  | COM'L        | SA<br>LA   | 40<br>40   | 100<br>70                         | 40<br>40    | 95<br>70                             | mA   |
|                        | $V_{IN} \ge \overline{V}_{CC} - 0.2V$ or $V_{IN} \le 0.2V$<br>Active Port Outputs Disabled,<br>$f = f_{MAX}^{(3)}$ | MIL &<br>IND   | SA<br>LA     | 40<br>40   | 110<br>85  | 40<br>40                          | 110<br>80   |                                      |      |

NOTES:

1. 'X' in part numbers indicates power rating (SA or LA).

2. PLCC , TQFP and STQFP packages only.

3. At f = fMAX, address and control lines (except Output Enable) are cycling at the maximum frequency read cycle of 1/tcvc, and using "AC TEST CONDITIONS" of input levels of GND to 3V.

4. f = 0 means no address or control lines change. Applies only to inputs at CMOS level standby.

5. Vcc = 5V, TA=+25°C for Typ and is not production tested. Vcc DC = 100 mA (Typ)

6. Port "A" may be either left or right port. Port "B" is opposite from port "A".

Military, Industrial and Commercial Temperature Ranges

Military, Industrial and Commercial Temperature Ranges

## Data Retention Characteristics (LA Version Only)

|                     |                                      |  |             | 7130LA/7140LA      |                     |      |            |
|---------------------|--------------------------------------|--|-------------|--------------------|---------------------|------|------------|
| Symbol              | Parameter                            | Test Condition                             | ı           | Min.               | Typ. <sup>(1)</sup> | Мах. | Unit       |
| Vdr                 | Vcc for Data Retention               |  |             | 2.0                | -                   | _    | V          |
| ICCDR               | Data Retention Current               |  | MIL. & IND. | _                  | 100                 | 4000 | μA         |
|                     |                                      | Vcc = 2.0V, $\overline{CE} \ge Vcc - 0.2V$ | COM'L.      | _                  | 100                 | 1500 |            |
| tcdr <sup>(3)</sup> | Chip Deselect to Data Retention Time | Vin $\geq$ Vcc -0.2V or Vin $\leq$ 0.2V    |             | 0                  | _                   | _    | ns         |
| tR <sup>(3)</sup>   | Operation Recovery Time              |  |             | tRC <sup>(2)</sup> | -                   | _    | ns         |
|                     |                                      |  |             |                    |                     | 2    | 689 tbl 07 |

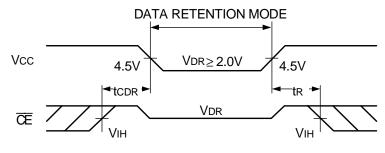
NOTES:

1. Vcc = 2V, TA =  $+25^{\circ}$ C, and is not production tested.

2. tRc = Read Cycle Time

3. This parameter is guaranteed but not production tested.

Data Retention Waveform



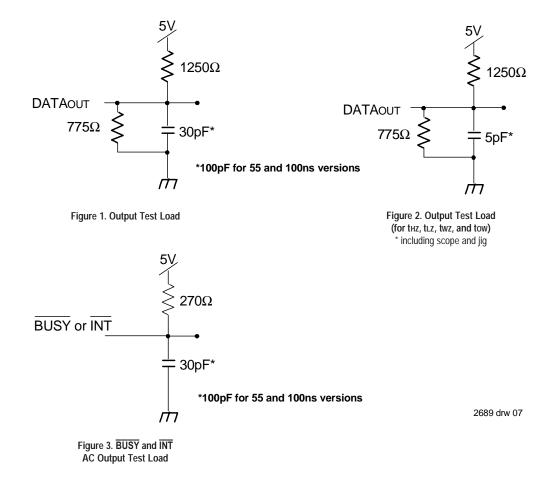
2692 drw 06

## Military, Industrial and Commercial Temperature Ranges

## AC Test Conditions

| Input Pulse Levels            | GND to 3.0V       |
|-------------------------------|-------------------|
| Input Rise/Fall Times         | 5ns               |
| Input Timing Reference Levels | 1.5V              |
| Output Reference Levels       | 1.5V              |
| Output Load                   | Figures 1,2 and 3 |

2689 tbl 08



2689 tbl 09a

2689 tbl 09b

## AC Electrical Characteristics Over the Operating Temperature Supply Voltage Range<sup>(3)</sup>

|             |  | 7130X20 <sup>(2)</sup><br>7140X20 <sup>(2)</sup><br>Com'l Only |      | 7130X25<br>7140X25<br>Com'l, Ind<br>& Military |      |      |      |      |
|-------------|--|--|------|--|------|------|------|------|
| Symbol      | Parameter                                      | Min.   | Мах. | Min.   | Мах. | Min. | Мах. | Unit |
| READ CYCLE  |  |  |      |  |      |      |      |      |
| tRC         | Read Cycle Time                                | 20   | -    | 25   | -    | 35   | _    | ns   |
| taa         | Address Access Time                            |  | 20   |  | 25   |      | 35   | ns   |
| <b>TACE</b> | Chip Enable Access Time                        |  | 20   |  | 25   |      | 35   | ns   |
| taoe        | Output Enable Access Time                      |  | 11   |  | 12   |      | 20   | ns   |
| tон         | Output Hold from Address Change                | 3  | _    | 3  |      | 3    | -    | ns   |
| tLZ         | Output Low-Z Time <sup>(1,4)</sup>             | 0  | -    | 0  |      | 0    |      | ns   |
| tHZ         | Output High-Z Time <sup>(1,4)</sup>            |  | 10   |  | 10   |      | 15   | ns   |
| tPU         | Chip Enable to Power Up Time <sup>(4)</sup>    | 0  |      | 0  | _    | 0    |      | ns   |
| tPD         | Chip Disable to Power Down Time <sup>(4)</sup> |  | 20   | _  | 25   |      | 35   | ns   |

|              |  | 7130X55<br>7140X55<br>Com'l, Ind<br>& Military |      | 7130X100<br>7140X100<br>Com'l, Ind<br>& Military |      |      |
|--------------|--|--|------|--|------|------|
| Symbol       | Parameter                                      | Min.   | Мах. | Min.   | Мах. | Unit |
| READ CYCLE   |  |  |      |  |      |      |
| trc          | Read Cycle Time                                | 55   |      | 100  | _    | ns   |
| taa          | Address Access Time                            | _  | 55   | _  | 100  | ns   |
| <b>T</b> ACE | Chip Enable Access Time                        | -  | 55   | -  | 100  | ns   |
| <b>t</b> AOE | Output Enable Access Time                      | _  | 25   | _  | 40   | ns   |
| tон          | Output Hold from Address Change                | 3  |      | 10   |      | ns   |
| tLZ          | Output Low-Z Time <sup>(1,4)</sup>             | 5  |      | 5  |      | ns   |
| tHZ          | Output High-Z Time <sup>(1,4)</sup>            |  | 25   |  | 40   | ns   |
| tPU          | Chip Enable to Power Up Time <sup>(4)</sup>    | 0  |      | 0  |      | ns   |
| tPD          | Chip Disable to Power Down Time <sup>(4)</sup> |  | 50   |  | 50   | ns   |

NOTES:

1. Transition is measured 0mV from Low or High-impedance voltage Output Test Load (Figure 2).

2. PLCC, TQFP and STQFP packages only.

3. 'X' in part numbers indicates power rating (SA or LA).

4. This parameter is guaranteed by device characterization, but is not production tested.

|         | /LA and IDT7140SA/LA<br>d 1K x 8 Dual-Port Static SRAM | Military, Industrial and Commercial Temperature Ranges |
|---------|--|--|
| Timing  | Waveform of Read Cycle No. 1,                          | Either Side <sup>(1)</sup>                             |
| ADDRESS |  |  |

DATA VALID

2689 drw 08

tPD<sup>(4)</sup>

50%

2689 drw 09

#### NOTES:

DATAOUT

BUSYOUT

1.  $R/\overline{W} = V_{IH}$ ,  $\overline{CE} = V_{IL}$ , and is  $\overline{OE} = V_{IL}$ . Address is valid prior to the coincidental with  $\overline{CE}$  transition LOW.

tBDD delay is required only in the case where the opposite port is completing a write operation to the same the address location. For simultaneous read operations, 2. BUSY has no relationship to valid output data.

tbddh <sup>(2,3)</sup>

3. Start of valid data depends on which timing becomes effective last tAOE, tACE, tAA, and tBDD.

PREVIOUS DATA VALID

## Timing Waveform of Read Cycle No. 2, Either Side<sup>(3)</sup> tACE CE tHZ<sup>(2)</sup> taoe<sup>(4)</sup> ŌĒ tHZ<sup>(2)</sup> tLZ<sup>(1)</sup> DATAOUT VALID DATA

tLZ<sup>(1)</sup>

50%

## NOTES:

Icc CURRENT

Iss

1. Timing depends on which signal is asserted last,  $\overline{OE}$  or  $\overline{CE}$ .

Timing depends on which signal is deserted first, OE or CE.
 R/W = VIH and OE = VIL, and the address is valid prior to or coincidental with CE transition LOW.

- tpu 🔶

Start of valid data depends on which timing becomes effective last tAOE, tACE, tAA, and tBDD. 4.

Military, Industrial and Commercial Temperature Ranges

2689 tbl 10a

2689 tbl 10b

## AC Electrical Characteristics Over the Operating Temperature Supply Voltage Range<sup>(5)</sup>

|            |   | 7130X20 <sup>2)</sup><br>7140X20 <sup>2)</sup><br>Com'l Only |      | 714<br>Com | 0X25<br>0X25<br>'I, Ind<br>litary | 7130X35<br>7140X35<br>Com'l<br>& Military |      |      |  |
|------------|---|--|------|------------|-----------------------------------|---|------|------|--|
| Symbol     | Parameter                                       | Min.   | Мах. | Min.       | Мах.                              | Min.                                      | Мах. | Unit |  |
| WRITE CYCL | E   |  |      |            |                                   |   |      |      |  |
| twc        | Write Cycle Time <sup>(3)</sup>                 | 20   |      | 25         |                                   | 35  |      | ns   |  |
| tew        | Chip Enable to End-of-Write                     | 15   |      | 20         |                                   | 30  | _    | ns   |  |
| taw        | Address Valid to End-of-Write                   | 15   |      | 20         |                                   | 30  | _    | ns   |  |
| tas        | Address Set-up Time                             | 0  |      | 0          |                                   | 0   | _    | ns   |  |
| twp        | Write Pulse Width <sup>(4)</sup>                | 15   |      | 15         | -                                 | 25  | _    | ns   |  |
| twR        | Write Recovery Time                             | 0  |      | 0          |                                   | 0   | _    | ns   |  |
| tow        | Data Valid to End-of-Write                      | 10   |      | 12         |                                   | 15  | _    | ns   |  |
| tHZ        | Output High-Z Time <sup>(1)</sup>               | _  | 10   |            | 10                                | -   | 15   | ns   |  |
| tDH        | Data Hold Time                                  | 0  | -    | 0          |                                   | 0   |      | ns   |  |
| twz        | Write Enable to Output in High-Z <sup>(1)</sup> |  | 10   |            | 10                                |   | 15   | ns   |  |
| tow        | Output Active from End-of-Write <sup>(1)</sup>  | 0  |      | 0          |                                   | 0   |      | ns   |  |

|             |   | 7140<br>Com' | )X55<br>)X55<br>I, Ind<br>litary | 7130<br>7140<br>Com'<br>& Mi |      |      |
|-------------|---|--------------|----------------------------------|------------------------------|------|------|
| Symbol      | Parameter                                       | Min.         | Max.                             | Min.                         | Max. | Unit |
| WRITE CYCLE |   |              |                                  |                              |      |      |
| twc         | Write Cycle Time <sup>(3)</sup>                 | 55           |                                  | 100                          |      | ns   |
| tew         | Chip Enable to End-of-Write                     | 40           |                                  | 90                           |      | ns   |
| taw         | Address Valid to End-of-Write                   | 40           | -                                | 90                           | -    | ns   |
| tas         | Address Set-up Time                             | 0            |                                  | 0                            |      | ns   |
| twp         | Write Pulse Width <sup>(4)</sup>                | 30           |                                  | 55                           |      | ns   |
| twr         | Write Recovery Time                             | 0            |                                  | 0                            |      | ns   |
| tow         | Data Valid to End-of-Write                      | 20           |                                  | 40                           |      | ns   |
| tHZ         | Output High-Z Time <sup>(1)</sup>               |              | 25                               |                              | 40   | ns   |
| tDH         | Data Hold Time                                  | 0            | _                                | 0                            |      | ns   |
| twz         | Write Enable to Output in High-Z <sup>(1)</sup> |              | 25                               |                              | 40   | ns   |
| tow         | Output Active from End-of-Write <sup>(1)</sup>  | 0            |                                  | 0                            |      | ns   |

NOTES:

1. Transition is measured 0mV from Low or High-impedance voltage with Output Test Load (Figure 2). This parameter is guaranteed by device characterization but is not production tested.

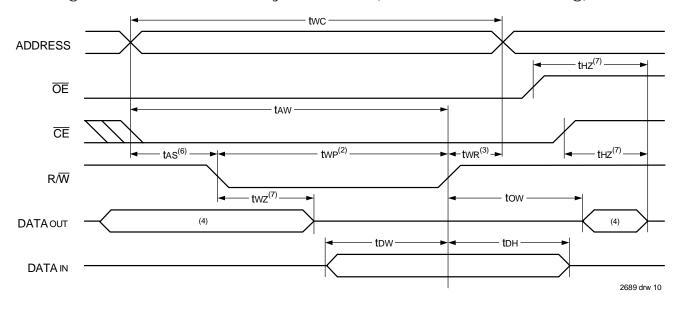
2. PLCC, TQFP and STQFP packages only.

3. For MASTER/SLAVE combination, twc = tBAA + twp, since  $R/\overline{W}$  = VIL must occur after tBAA.

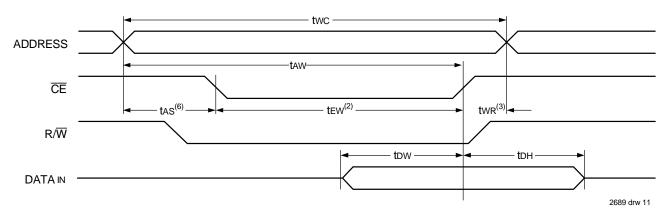
4. If OE is LOW during a RW controlled write cycle, the write pulse width must be the larger of twp or (twz + tow) to allow the I/O drivers to turn off data to be placed on the bus for the required tow. If OE is HIGH during a R/W controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified twp.

5. 'X' in part numbers indicates power rating (SA or LA).

Timing Waveform of Write Cycle No. 1, (R/W Controlled Timing)<sup>(1,5,8)</sup>



Timing Waveform of Write Cycle No. 2, (CE Controlled Timing)<sup>(1,5)</sup>



NOTES:

- 1. R/ $\overline{W}$  or  $\overline{CE}$  must be HIGH during all address transitions.
- 2. A write occurs during the overlap (tew or twp) of  $\overline{CE} = VIL$  and  $R/\overline{W} = VIL$ .
- 3. two is measured from the earlier of  $\overline{CE}$  or R/W going HIGH to the end of the write cycle.
- 4. During this period, the I/O pins are in the output state and input signals must not be applied.
- 5. If the CE LOW transition occurs simultaneously with or after the R/W LOW transition, the outputs remain in the HIGH impedance state.
- 6. Timing depends on which enable signal (CE or R/W) is asserted last.
- 7. This parameter is determined be device characterization, but is not production tested. Transition is measured 0mV from steady state with the Output Test Load (Figure 2).
- 8. If  $\overline{OE}$  is LOW during a R $\overline{W}$  controlled write cycle, the write pulse width must be the larger of twp or (twz + tow) to allow the I/O drivers to turn off data to be placed on the bus for the required tow. If  $\overline{OE}$  is HIGH during a R $\overline{W}$  controlled write cycle, this requirement does not apply and the write pulse can be as short as the specified twp.

## AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(7)</sup>

|                    |  |            | I, Ind<br>litary                  | Com'l<br>& Military |                                     |      |      |               |
|--------------------|--|------------|-----------------------------------|---------------------|-------------------------------------|------|------|---------------|
| Symbol             | Parameter  | Min.       | Мах.                              | Min.                | Max.                                | Min. | Max. | Unit          |
| <b>BUSY</b> TIMING | (For MASTER IDT 7130)                              |            |                                   |                     |                                     |      |      |               |
| tbaa               | BUSY Access Time from Address                      |            | 20                                |                     | 20                                  | -    | 20   | ns            |
| tBDA               | BUSY Disable Time from Address                     |            | 20                                | -                   | 20                                  | _    | 20   | ns            |
| tbac               | BUSY Access Time from Chip Enable                  |            | 20                                | -                   | 20                                  | _    | 20   | ns            |
| tBDC               | BUSY Disable Time from Chip Enable                 | —          | 20                                | _                   | 20                                  | -    | 20   | ns            |
| twн                | Write Hold After BUSY <sup>(6)</sup>               | 12         |                                   | 15                  | _                                   | 20   | -    | ns            |
| twdd               | Write Pulse to Data Delay <sup>(2)</sup>           | _          | 40                                | -                   | 50                                  | _    | 60   | ns            |
| todd               | Write Data Valid to Read Data Delay <sup>(2)</sup> | _          | 30                                | -                   | 35                                  | _    | 35   | ns            |
| taps               | Arbitration Priority Set-up Time <sup>(3)</sup>    | 5          |                                   | 5                   |                                     | 5    | -    | ns            |
| tBDD               | BUSY Disable to Valid Data <sup>(4)</sup>          |            | 25                                |                     | 35                                  | -    | 35   | ns            |
| BUSY INPUT 1       | TIMING (For SLAVE IDT 7140)                        |            |                                   |                     |                                     |      |      |               |
| twв                | Write to BUSY Input <sup>(5)</sup>                 | 0          | —                                 | 0                   | —                                   | 0    | _    | ns            |
| twн                | Write Hold After BUSY <sup>(6)</sup>               | 12         |                                   | 15                  | _                                   | 20   |      | ns            |
| twdd               | Write Pulse to Data Delay <sup>(2)</sup>           | —          | 40                                | _                   | 50                                  | —    | 60   | ns            |
| todd               | Write Data Valid to Read Data Delay <sup>(2)</sup> |            | 30                                |                     | 35                                  | —    | 35   | ns            |
| -                  |  |            |                                   |                     |                                     |      |      | 2689 tbl 11 a |
|                    |  | 714<br>Com | 0X55<br>0X55<br>'I, Ind<br>litary | 7140<br>Com         | 0X100<br>0X100<br>'I, Ind<br>litary |      |      |               |
| Symbol             | Parameter  |            | Min.                              | Мах.                | Min.                                | Max. | Unit |               |
| <b>BUSY</b> TIMING | (For MASTER IDT 7130)                              |            |                                   |                     |                                     |      |      |               |
| <b>t</b> BAA       | BUSY Access Time from Address]                     |            |                                   |                     | 30                                  |      | 50   | ns            |
| tBDA               | BUSY Disable Time from Address                     |            |                                   |                     | 30                                  |      | 50   | ns            |

**BUSY** INPUT TIMING (For SLAVE IDT 7140) Write to BUSY Input<sup>(5)</sup> Write Hold After BUSY<sup>(6)</sup> Write Pulse to Data Delay(2) Write Data Valid to Read Data Delay<sup>(2)</sup>

NOTES:

**t**BAC

tBDC

twн

twdd

todd

taps

tBDD

twв

twн

twdd

todd

1. PLCC, TQFP and STQFP packages only.

Port-to-port delay through RAM cells from the writing port to the reading port, refer to "Timing Waveform of Write with Port -to-Port Read and BUSY." 2.

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To ensure that the earlier of the two ports wins. 3.

tBDD is a calculated parameter and is the greater of 0, twDD - twp (actual) or tDDD - tDw (actual). 4

5. To ensure that a write cycle is inhibited on port 'B' during contention on port 'A'.

**BUSY** Access Time from Chip Enable

BUSY Disable Time from Chip Enable

Write Data Valid to Read Data Delay<sup>(2)</sup>

Arbitration Priority Set-up  $Time^{(3)}$ 

BUSY Disable to Valid Data(4)

Write Hold After BUSY<sup>(6)</sup>

Write Pulse to Data Delay(2)

To ensure that a write cycle is completed on port 'B' after contention on port 'A'. 6.

7. 'X' in part numbers indicates power rating (S or L).

#### ns

50

50

120

100

65

120

100

7130X35

7140X35

ns 2689 tbl 11b

## Military, Industrial and Commercial Temperature Ranges

7130X25

7140X25

30

30

80

55

55

80

55

20

5

0

20

20

5

0

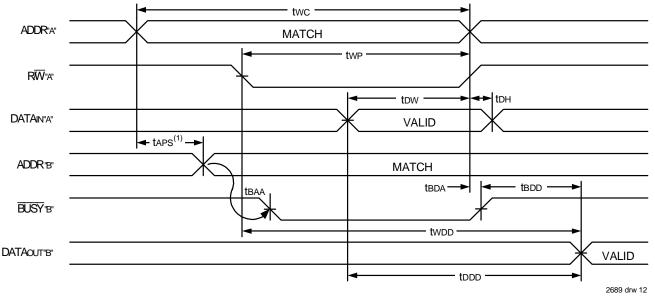
20

\_

7130X 20<sup>(1)</sup>

7140X20<sup>(1)</sup>

Timing Waveform of Write with Port-to-Port Read and **BUSY**<sup>(2,3,4)</sup>



NOTES:

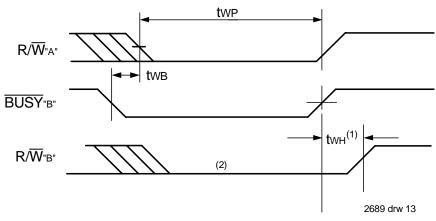
1. To ensure that the earlier of the two ports wins. tBDD is ignored for slave (IDT7140).

 $2. \quad \overline{CE}_L = \overline{CE}_R = VIL$ 

3.  $\overline{OE} = V_{IL}$  for the reading port.

4. All timing is the same for the left and right ports. Port 'A' may be either the left or right port. Port "B" is opposite from port "A".

## Timing Waveform of Write with $\overline{\textbf{BUSY}}^{\scriptscriptstyle{(3)}}$



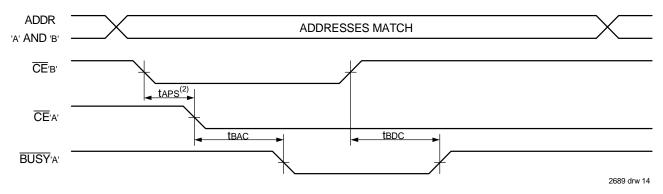
#### NOTES:

1. twH must be met for both BUSY Input (IDT7140, slave) or Output (IDT7130 master).

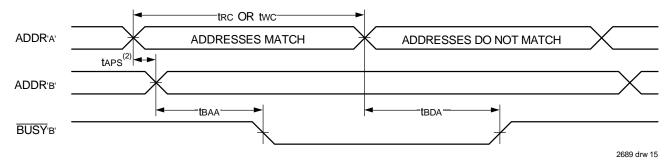
2. BUSY is asserted on port "B" blocking R/W"B", until BUSY"B" goes HIGH.

3. All timing is the same for the left and right ports. Port "A" may be either the left or right port. Port "B" is oppsite from port "A".

Timing Waveform of **BUSY** Arbitration Controlled by **CE** Timing<sup>(1)</sup>



# Timing Waveform by $\overline{\text{BUSY}}$ Arbitration Controlled by Address Match Timing^{(1)}



NOTES:

1. All timing is the same for left and right ports. Port "A" may be either left or right port. Port "B" is the opposite from port "A".

2. If taps is not satisified, the BUSY will be asserted on one side or the other, but there is no guarantee on which side BUSY will be asserted (7130 only).

## AC Electrical Characteristics Over the Operating Temperature and Supply Voltage Range<sup>(2)</sup>

|             |                      | 7130X20 <sup>(1)</sup><br>7140X20 <sup>(1)</sup><br>Com'l Only |      |      | 7130X25<br>7140X25<br>Com'l, Ind<br>& Military |   | 7130X35<br>7140X35<br>Com'l<br>& Military |    |
|-------------|----------------------|--|------|------|--|---|---|----|
| Symbol      | Parameter            | Min.   | Мах. | Unit |  |   |   |    |
| INTERRUPT 1 | ſIMING               |  |      |      |  |   |   |    |
| tas         | Address Set-up Time  | 0  |      | 0    |  | 0 |   | ns |
| twr         | Write Recovery Time  | 0  |      | 0    |  | 0 |   | ns |
| tins        | Interrupt Set Time   |  | 20   |      | 25   |   | 25  | ns |
| tinr        | Interrupt Reset Time |  | 20   |      | 25   |   | 25  | ns |

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NOTES:

1. PLCC, TQFP and STQFP package only.

2. 'X' in part numbers indicates power rating (SA or LA).

Military, Industrial and Commercial Temperature Ranges

Military, Industrial and Commercial Temperature Ranges

2689 tbl 12b

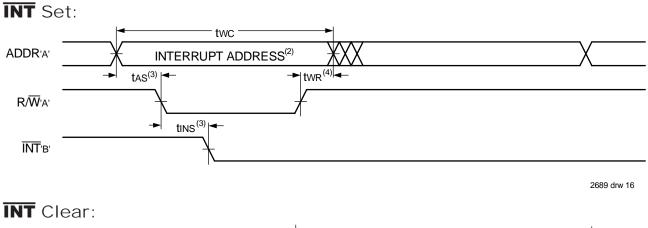
## AC Electrical characteristics Over the Operating Temperature and Supply Voltage Range<sup>(1)</sup>

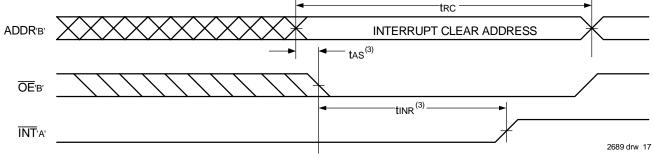
|           |                      | 7140<br>Com | 0X55<br>0X55<br>1, Ind<br>litary | 7130X100<br>7140X100<br>Com'l, Ind<br>& Military |      |      |  |
|-----------|----------------------|-------------|----------------------------------|--|------|------|--|
| Symbol    | Parameter            | Min.        | Мах.                             | Min.   | Мах. | Unit |  |
| INTERRUPT | TIMING               | -           |                                  |  | -    |      |  |
| tas       | Address Set-up Time  | 0           |                                  | 0  |      | ns   |  |
| twr       | Write Recovery Time  | 0           |                                  | 0  |      | ns   |  |
| tiNS      | Interrupt Set Time   |             | 45                               |  | 60   | ns   |  |
| tinr      | Interrupt Reset Time |             | 45                               |  | 60   | ns   |  |

## NOTES:

1. 'X' in part numbers indicates power rating (SA or LA).

## Timing Waveform of Interrupt Mode<sup>(1)</sup>





## NOTES:

- 1. All timing is the same for left and right ports. Port "A" may be either left or right port. Port "B" is the opposite from port "A".
- 2. See Interrupt Truth Table II.
- 3. Timing depends on which enable signal ( $\overline{CE}$  or  $R/\overline{W}$ ) is asserted last.
- 4. Timing depends on which enable signal (CE or R/W) is de-asserted first.

## Truth Tables

## Truth Table I — Non-Contention Read/Write Control<sup>(4)</sup>

|     | Inputs <sup>(1)</sup> |    |         |  |
|-----|-----------------------|----|---------|--|
| R/W | Ē                     | ŌĒ | D0-7    | Function   |
| Х   | Н                     | Х  | Z       | Port Disabled and in Power-Down Mode, ISB2 or ISB4 |
| х   | Н                     | Х  | Z       | CER = CEL = VH, Power-Down Mode, ISB1 or ISB3      |
| L   | L                     | Х  | DATAIN  | Data on Port Written into Memory <sup>(2)</sup>    |
| Н   | L                     | L  | DATAOUT | Data in Memory Output on Port <sup>(3)</sup>       |
| Н   | L                     | Н  | Z       | High Impedance Outputs                             |

NOTES:

1. AOL – A10L • AOR – A10R.

2. If  $\overline{\text{BUSY}}$  = L, data is not written.

3. If  $\overline{\text{BUSY}}$  = L, data may not be valid, see twop and topp timing.

4. 'H' = VIH, 'L' = VIL, 'X' = DON'T CARE, 'Z' = HIGH IMPEDANCE

## Truth Table II — Interrupt Flag<sup>(1,4)</sup>

| Left Port |     |     |         |                  | Right Port |     |             |         |                  |                       |
|-----------|-----|-----|---------|------------------|------------|-----|-------------|---------|------------------|-----------------------|
| R/₩L      | CEL | ŌĒL | A9L-A0L | ĪNTL             | R/WR       | CER | <b>OE</b> R | A9R-A0R | ĪNTR             | Function              |
| L         | L   | Х   | 3FF     | Х                | Х          | Х   | Х           | Х       | L <sup>(2)</sup> | Set Right INTR Flag   |
| Х         | Х   | Х   | Х       | Х                | Х          | L   | L           | 3FF     | H <sup>(3)</sup> | Reset Right INTR Flag |
| Х         | Х   | Х   | Х       | L <sup>(3)</sup> | L          | L   | Х           | 3FE     | Х                | Set Left INTL Flag    |
| Х         | L   | L   | 3FE     | H <sup>(2)</sup> | Х          | Х   | Х           | Х       | Х                | Reset Left INTL Flag  |

#### NOTES:

1. Assumes  $\overline{\text{BUSY}}L = \overline{\text{BUSY}}R = VIH$ 

2. If  $\overline{\text{BUSY}}$ L = VIL, then No Change.

3. If  $\overline{\text{BUSY}}R = \text{VIL}$ , then No Change.

4. 'H' = HIGH,' L' = LOW,' X' = DON'T CARE

## Truth Table III — Address **BUSY** Arbitration

|   | In  | puts   | Out | puts     |                              |
|---|-----|--|-----|----------|------------------------------|
| Ē | ĊĒr | A0L-A9L<br>A0R-A9R BUSYL <sup>(1)</sup> BUSYR <sup>(1)</sup> |     | Function |                              |
| Х | Х   | NO MATCH   | Н   | Н        | Normal                       |
| Н | Х   | MATCH  | Н   | Н        | Normal                       |
| Х | Н   | MATCH  | Н   | Н        | Normal                       |
| L | L   | MATCH  | (2) | (2)      | Write Inhibit <sup>(3)</sup> |

### NOTES:

2689 tbl 15

- Pins BUSY<sub>L</sub> and BUSY<sub>R</sub> are both outputs for IDT7130 (master). Both are inputs for IDT7140 (slave). BUSY<sub>X</sub> outputs on the IDT7130 are open drain, not push-pull outputs. On slaves the BUSY<sub>X</sub> input internally inhibits writes.
- 2. 'L' if the inputs to the opposite port were stable prior to the address and enable inputs of this port. 'H' if the inputs to the opposite port became stable after the address and enable inputs of this port. If tAPS is not met, either  $\overline{BUSY}_L$  or  $\overline{BUSY}_R = LOW$  will result.  $\overline{BUSY}_L$  and  $\overline{BUSY}_R$  outputs can not be LOW simultaneously.
- Writes to the left port are internally ignored when BUSYL outputs are driving LOW regardless of actual logic level on the pin. Writes to the right port are internally ignored when BUSYR outputs are driving LOW regardless of actual logic level on the pin.

2689 tbl 13

2689 tbl 14

## Functional Description

The IDT7130/IDT7140 provides two ports with separate control, address and I/O pins that permit independent access for reads or writes to any location in memory. The IDT7130/IDT7140 has an automatic power down feature controlled by  $\overline{CE}$ . The  $\overline{CE}$  controls onchip power down circuitry that permits the respective port to go into a standby mode when not selected ( $\overline{CE} = VIH$ ). When a port is enabled, access to the entire memory array is permitted.

## Interrupts

If the user chooses the interrupt function, a memory location (mail box or message center) is assigned to each port. The left port interrupt flag ( $\overline{INTL}$ ) is asserted when the right port writes to memory location 3FE (HEX), where a write is defined as the  $\overline{CER} = R/\overline{WR} = VIL per Truth$  Table II. The left port clears the interrupt by access address location 3FE access when  $\overline{CEL} = \overline{OEL} = VIL, R/W$  is a "don't care". Likewise, the right port interrupt flag ( $\overline{INTR}$ ) is asserted when the left port writes to memory location 3FF (HEX) and to clear the interrupt flag ( $\overline{INTR}$ ), the right port must access the memory location 3FF. The message (8 bits) at 3FE or 3FF is user-defined, since it is an addressable SRAM location. If the interrupt function is not used, address locations 3FE and 3FF are not used as mail boxes, but as part of the random access memory. Refer to Truth Table II for the interrupt operation.

## **Busy Logic**

Busy Logic provides a hardware indication that both ports of the RAM have accessed the same location at the same time. It also allows one of the two accesses to proceed and signals the other side that the RAM is "Busy". The BUSY pin can then be used to stall the access until the operation on the other side is completed. If a write operation has been attempted from the side that receives a BUSY indication, the write signal is gated internally to prevent the write from proceeding.

The use of BUSY logic is not required or desirable for all applications. In some cases it may be useful to logically OR the BUSY outputs together and use any BUSY indication as an interrupt source to flag the event of an illegal or illogical operation. In slave mode the BUSY pin operates solely as a write inhibit input pin. Normal operation can be programmed by tying the BUSY pins HIGH. If desired, unintended write operations can be prevented to a port by tying the BUSY pin for that port LOW.

The BUSY outputs on the IDT7130 RAM (Master) are open drain type outputs and require open drain resistors to operate. If these

RAMs are being expanded in depth, then the BUSY indication for the resulting array does not require the use of an external AND gate.

## Width Expansion with Busy Logic Master/Slave Arrays

When expanding an RAM array in width while using busy logic, one master part is used to decide which side of the RAM array will receive a busy indication, and to output that indication. Any number of slaves to be addressed in the same address range as the master, use the busy signal as a write inhibit signal. Thus on the IDT7130/IDT7140 RAMs the BUSY pin is an output if the part is Master (IDT7130), and the BUSY pin is an input if the part is a Slave (IDT7140) as shown in Figure 3.

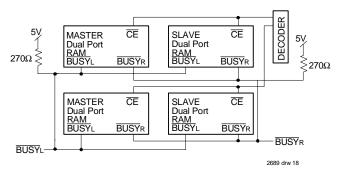
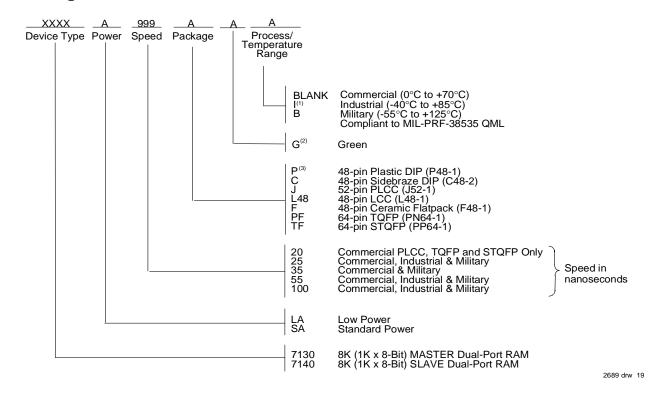


Figure 3. Busy and chip enable routing for both width and depth expansion with IDT7130 (Master) and IDT7140 (Slave)RAMs.

If two or more master parts were used when expanding in width, a split decision could result with one master indicating busy on one side of the array and another master indicating busy on one other side of the array. This would inhibit the write operations from one port for part of a word and inhibit the write operations from the other port for the other part of the word.

The BUSY arbitration, on a Master, is based on the chip enable and address signals only. It ignores whether an access is a read or write. In a master/slave array, both address and chip enable must be valid long enough for a BUSY flag to be output from the master before the actual write pulse can be initiated with either the R/W signal or the byte enables. Failure to observe this timing can result in a glitched internal write inhibit signal and corrupted data in the slave.

## Ordering Information



#### NOTES:

- 1. Contact your local sales office for industrial temp range for other speeds, packages and powers.
- 2. Green parts available. For specific speeds, pacakges and powers contact your local sales office.
- 3. For "P", plastic DIP, when ordering green package the suffix is "PDG".

## Datasheet Document History

| 03/15/99: |                   | Initiated datasheet document history<br>Converted to new format        |
|-----------|-------------------|--|
|           | Dagaa 2 and 2     | Cosmetic and typographical corrections                                 |
| 06/08/99: | Pages 2 and 3     | Added additional notes to pin configurations<br>Changed drawing format |
| 08/02/99: | Page 2            | Corrected package number in note 3                                     |
| 09/29/99: | Page 2            | Fixed pin 1 in DIP pin configuration                                   |
| 11/10/99: | Page 1 & 18       | Replaced IDT logo  |
| 06/23/00: | Page 4            | Increased storage temperature parameters                               |
|           |                   | Clarified TA parameter   |
|           | Page 5            | DC Electrical parameters-changed wording from "open" to "disabled"     |
|           | Page 10           | Changed ±500mV to 0mV in notes   |
| 01/08/02: | Page 1            | Added Ceramic Flatpack to 48-pin package offerings                     |
|           | Page 2 & 3        | Added date revision to pin configurations                              |
|           | Page 4, 5, 8, 10, | Removed industrial temp option footnote from all tables                |
|           | 12,14 & 15        |  |

Continued on page 19

## Datasheet Document History (cont'd)

| 01/08/02: | Page 5, 8, 10, 12, & 14<br>Page 5, 8, 10, 12, & 14<br>Page 18 | Added industrial temp for 25ns to DC & AC Electrical Characteristics<br>Removed industrial temp for 35ns to DC & AC Electrical Characteristics<br>Added industrial temp for 25ns and removed industrial temp for 35ns in ordering information |
|-----------|---|---|
|           | Page 1 & 19   | Updated industrial temp option footnote<br>Replaced IDT ™ logo with IDT ® logo  |
| 01/11/06: | Page 1  | Added green availability to features  |
|           | Page 18   | Added green indicator to ordering information   |
|           | Page 1 & 19   | Replaced old IDT тм with new IDT тм logo  |
| 04/14/06: | Page 18   | Added "PDG" footnote to the ordering information  |
| 10/21/08: | Page 18   | Removed "IDT" from orderable part number  |



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