

# HEF4538B

## Dual precision monostable multivibrator

Rev. 7 — 17 February 2011

Product data sheet

### 1. General description

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The HEF4538B is a dual retriggerable-resettable monostable multivibrator. Each multivibrator has an active LOW trigger/retrigger input ( $\overline{nA}$ ), an active HIGH trigger/retrigger input ( $nB$ ), an overriding active LOW direct reset input ( $\overline{nCD}$ ), an output ( $nQ$ ) and its complement ( $\overline{nQ}$ ), and two pins ( $nREXT/CEXT$ , and  $nCEXT$ , always connected to ground) for connecting the external timing components  $C_{EXT}$  and  $R_{EXT}$ . Typical pulse width variation over the specified temperature range is  $\pm 0.2\%$ .

The multivibrator may be triggered by either the positive or the negative edges of the input pulse and will produce an accurate output pulse with a pulse width range of 10  $\mu\text{s}$  to infinity. The duration and accuracy of the output pulse are determined by the external timing components  $C_{EXT}$  and  $R_{EXT}$ . The output pulse width ( $t_W$ ) is equal to  $R_{EXT} \times C_{EXT}$ . The linear design techniques in LOCMOS (Local Oxide CMOS) guarantee precise control of the output pulse width. A LOW level at  $\overline{nCD}$  terminates the output pulse immediately. The trigger inputs' Schmitt trigger action makes the circuit highly tolerant of slower rise and fall times.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input. It is also suitable for use over the industrial ( $-40\text{ }^\circ\text{C}$  to  $+85\text{ }^\circ\text{C}$ ) and automotive ( $-40\text{ }^\circ\text{C}$  to  $+125\text{ }^\circ\text{C}$ ) temperature ranges.

### 2. Features and benefits

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- Tolerant of slow trigger rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Operates across the automotive temperature range  $-40\text{ }^\circ\text{C}$  to  $+125\text{ }^\circ\text{C}$
- Complies with JEDEC standard JESD 13-B

### 3. Applications

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- Automotive and industrial



### 4. Ordering information

**Table 1. Ordering information**  
 All types operate from  $-40\text{ }^{\circ}\text{C}$  to  $+125\text{ }^{\circ}\text{C}$ .

Type number	Package		Version
	Name	Description	
HEF4538BP	DIP16	plastic dual in-line package; 16 leads (300 mil)	SOT38-4
HEF4538BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

### 5. Functional diagram

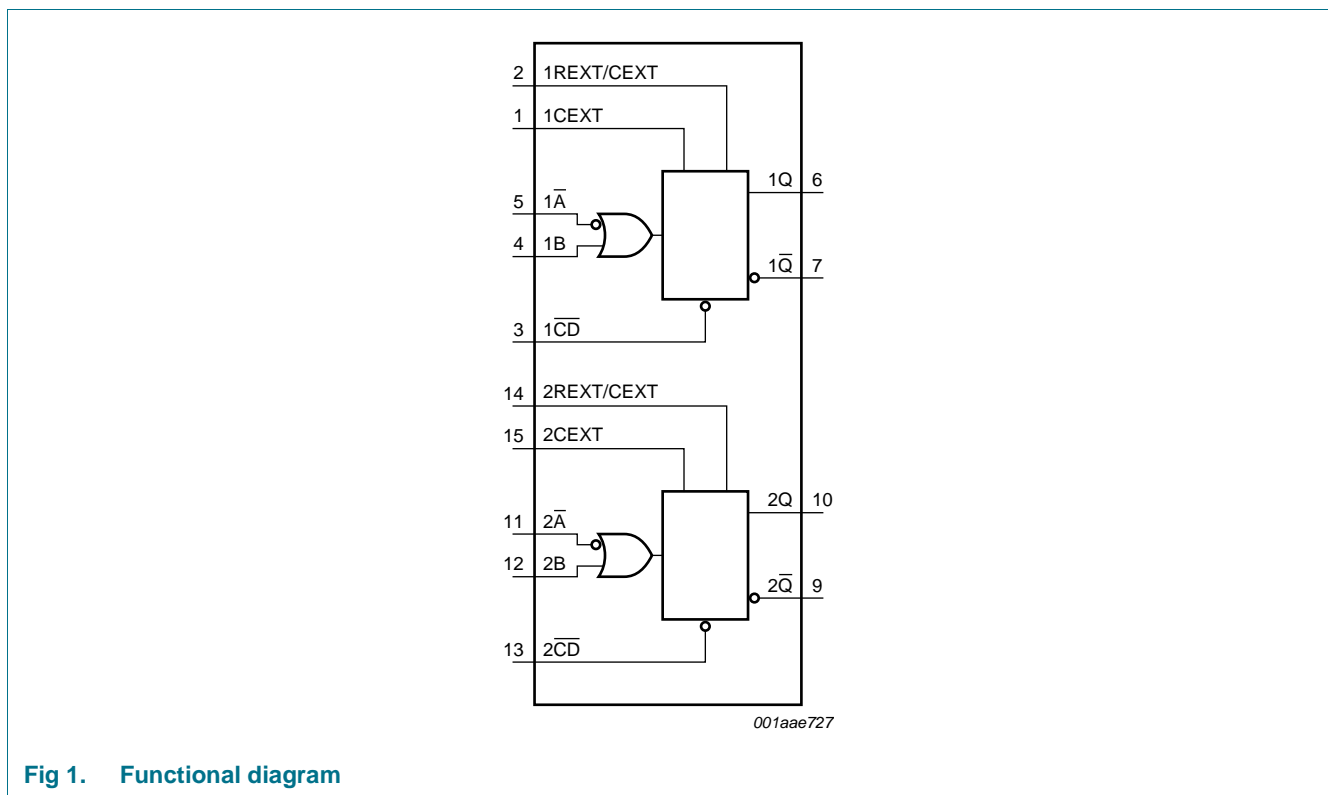


Fig 1. Functional diagram

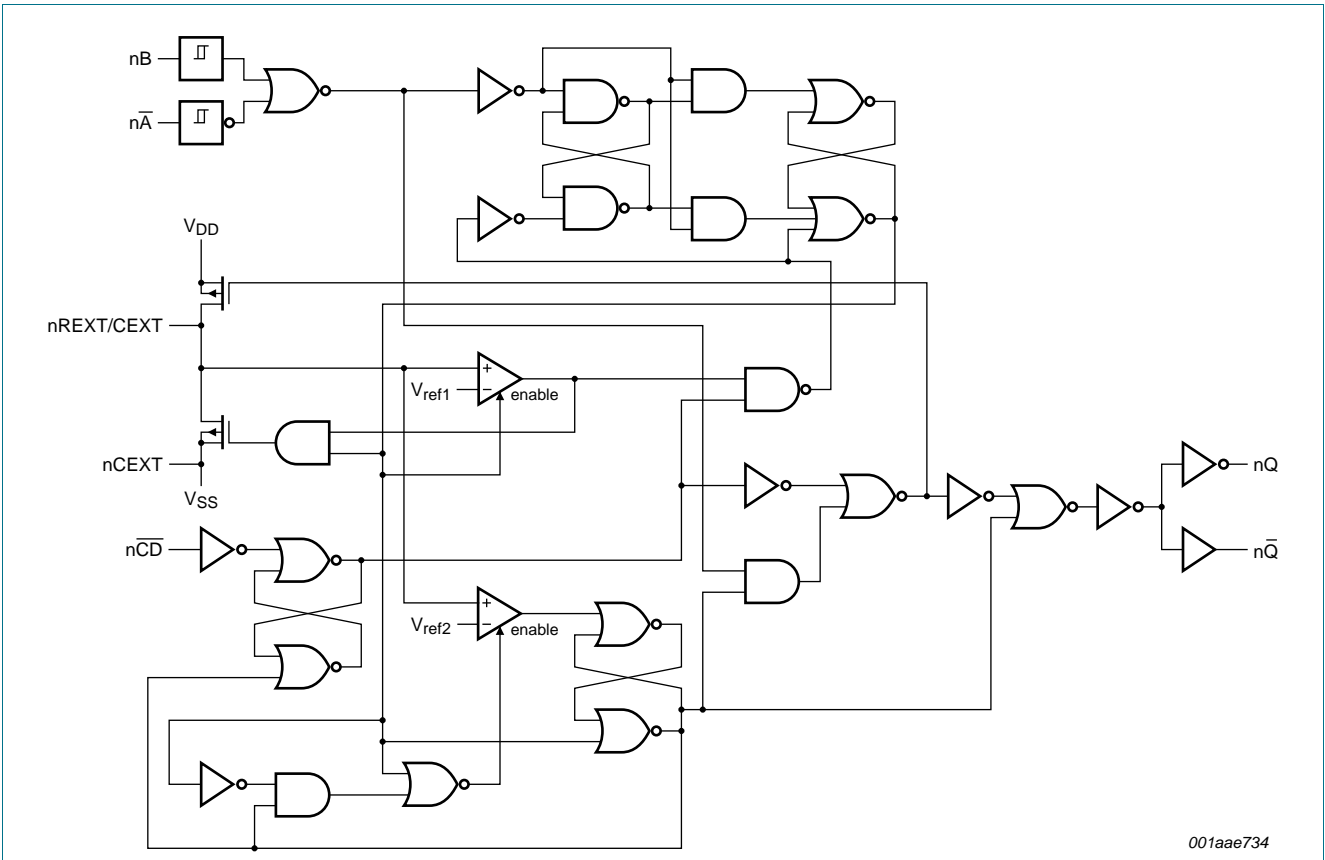


Fig 2. Logic diagram (one multivibrator)

## 6. Pinning information

### 6.1 Pinning

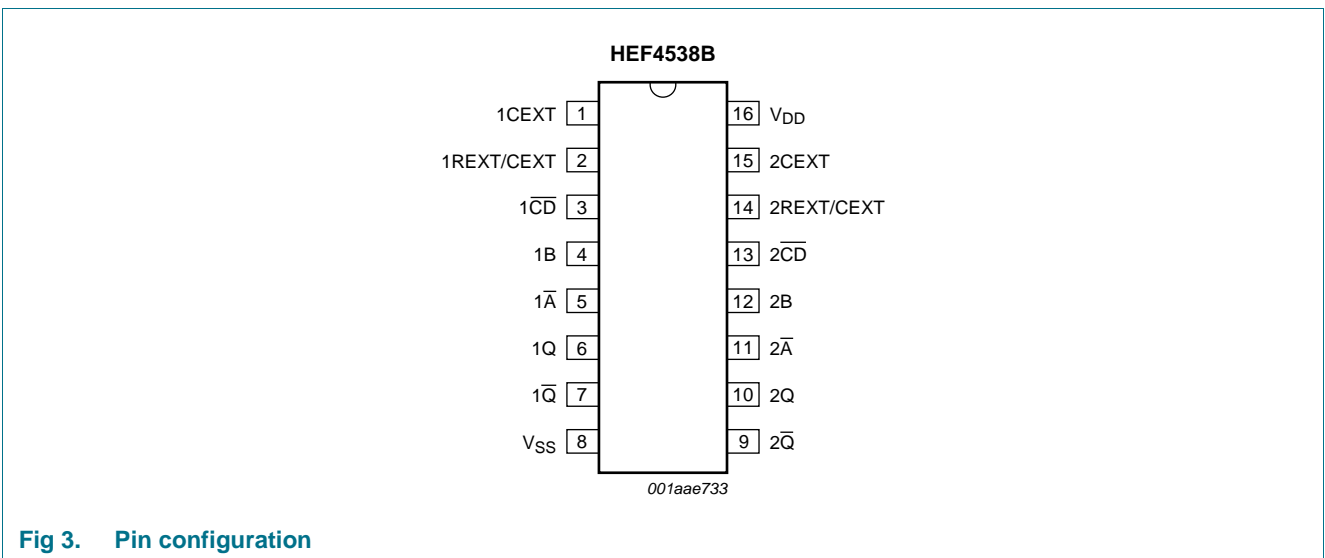


Fig 3. Pin configuration





## 6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
1CEXT, 2CEXT	1, 15	external capacitor connection (always connected to ground)
1REXT/CEXT, 2REXT/CEXT	2, 14	external capacitor/resistor connection
1 $\overline{CD}$ , 2 $\overline{CD}$	3, 13	direct reset input (active LOW)
1B, 2B	4, 12	input (LOW-to-HIGH triggered)
1 $\overline{A}$ , 2 $\overline{A}$	5, 11	input (HIGH-to-LOW triggered)
1Q, 2Q	6, 10	output
1 $\overline{Q}$ , 2 $\overline{Q}$	7, 9	complementary output (active LOW)
V <sub>SS</sub>	8	ground supply voltage
V <sub>DD</sub>	16	supply voltage


## 7. Functional description


Table 3. Function table

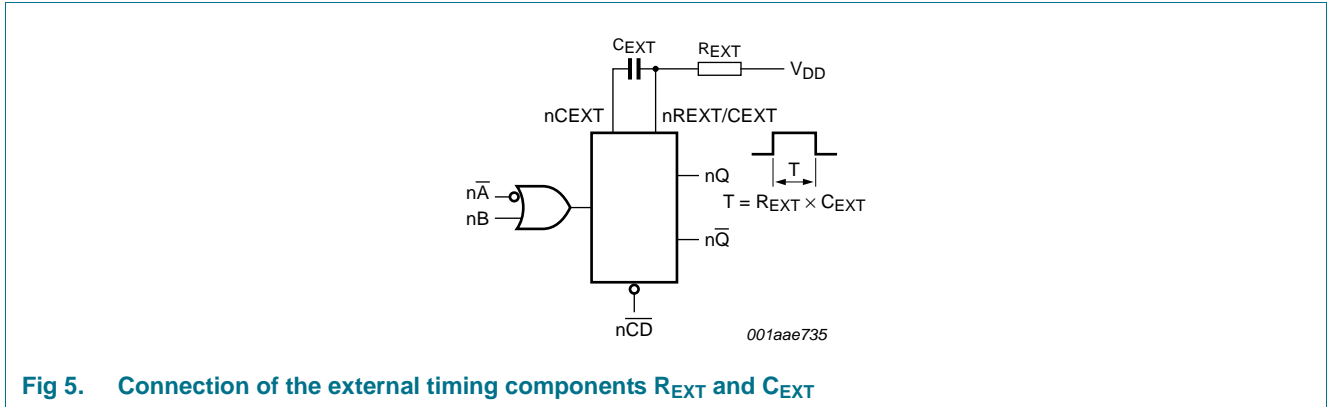
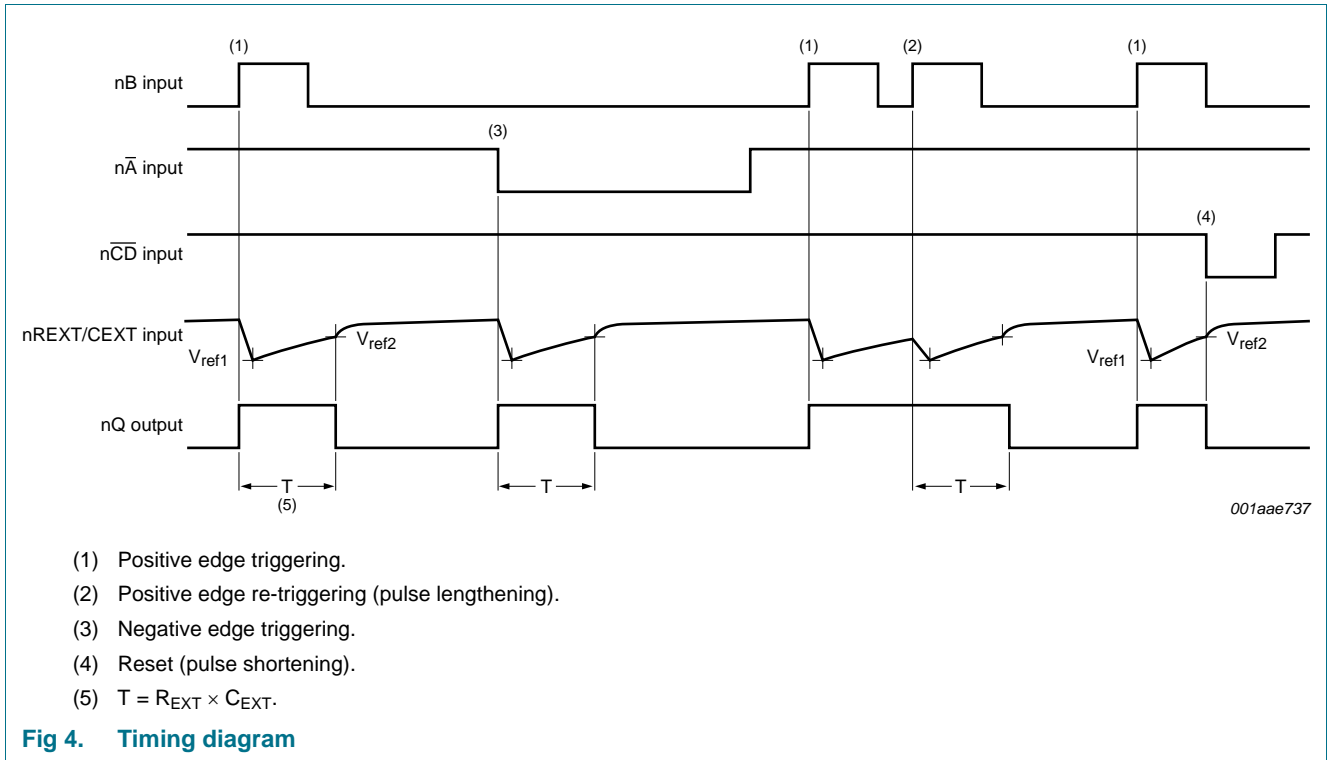
Inputs			Outputs	
n $\overline{A}$	nB	n $\overline{CD}$	nQ	n $\overline{Q}$
↓	L	H		
H	↑	H		
X	X	L	L	H

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care;

↑ = positive-going transition; ↓ = negative-going transition;

 = one HIGH level output pulse, with the pulse width determined by C<sub>EXT</sub> and R<sub>EXT</sub>;

 = one LOW level output pulse, with the pulse width determined by C<sub>EXT</sub> and R<sub>EXT</sub>.



## 8. Limiting values

**Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to V<sub>SS</sub> = 0 V (ground)

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < -0.5 V or V <sub>I</sub> > V <sub>DD</sub> + 0.5 V	-	±10	mA
V <sub>I</sub>	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	V <sub>I</sub> < -0.5 V or V <sub>I</sub> > V <sub>DD</sub> + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C

**Table 4. Limiting values ...continued**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to  $V_{SS} = 0\text{ V}$  (ground)

Symbol	Parameter	Conditions	Min	Max	Unit
$T_{amb}$	ambient temperature		-40	+125	°C
$P_{tot}$	total power dissipation	$T_{amb} = -40\text{ °C}$ to $+125\text{ °C}$			
		DIP16 package	[1] -	750	mW
		SO16 package	[2] -	500	mW
P	power dissipation	per output	-	100	mW

[1] For DIP16 package:  $P_{tot}$  derates linearly with 12 mW/K above 70 °C.

[2] For SO16 package:  $P_{tot}$  derates linearly with 8 mW/K above 70 °C.

## 9. Recommended operating conditions

**Table 5. Recommended operating conditions**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{DD}$	supply voltage		3	-	15	V
$V_I$	input voltage		0	-	$V_{DD}$	V
$T_{amb}$	ambient temperature	in free air	-40	-	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{DD} = 5\text{ V}$	-	-	3.75	µs/V
		$V_{DD} = 10\text{ V}$	-	-	0.5	µs/V
		$V_{DD} = 15\text{ V}$	-	-	0.08	µs/V

## 10. Static characteristics

**Table 6. Static characteristics**

$V_{SS} = 0\text{ V}$ ;  $V_I = V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	$T_{amb} = -40\text{ °C}$		$T_{amb} = 25\text{ °C}$		$T_{amb} = 85\text{ °C}$		$T_{amb} = 125\text{ °C}$		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
$V_{IL}$	LOW-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
$V_{OH}$	HIGH-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
$V_{OL}$	LOW-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V

**Table 6. Static characteristics ...continued**  
 $V_{SS} = 0\text{ V}$ ;  $V_I = V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	$T_{amb} = -40\text{ }^\circ\text{C}$		$T_{amb} = 25\text{ }^\circ\text{C}$		$T_{amb} = 85\text{ }^\circ\text{C}$		$T_{amb} = 125\text{ }^\circ\text{C}$		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
$I_{OH}$	HIGH-level output current	$V_O = 2.5\text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
		$V_O = 4.6\text{ V}$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		$V_O = 9.5\text{ V}$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		$V_O = 13.5\text{ V}$	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
$I_{OL}$	LOW-level output current	$V_O = 0.4\text{ V}$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
		$V_O = 0.5\text{ V}$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		$V_O = 1.5\text{ V}$	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
$I_I$	input leakage current	nREXT/CEXT	15 V	-	$\pm 0.1$	-	$\pm 0.1$	-	$\pm 1.0$	-	$\pm 1.0$	$\mu\text{A}$
$C_I$	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

**Table 7. Typical static characteristics**  
 $V_{SS} = 0\text{ V}$ ;  $V_I = V_{SS}$  or  $V_{DD}$ ;  $T_{amb} = +25\text{ }^\circ\text{C}$ .

Symbol	Parameter	Conditions	$V_{DD}$	Typ	Unit	
$I_{DD}$	supply current	active state	5 V	<a href="#">1</a>	55	$\mu\text{A}$
			10 V		150	$\mu\text{A}$
			15 V		220	$\mu\text{A}$
$C_I$	input capacitance	nREXT/CEXT	-	15	pF	

[1] Only one monostable is switching: for the specified current during the output pulse (output nQ is HIGH).

## 11. Dynamic characteristics

**Table 8. Dynamic characteristics**  
 $V_{SS} = 0\text{ V}$ ;  $T_{amb} = 25\text{ }^\circ\text{C}$ ; for test circuit see [Figure 11](#).

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula <sup>[1]</sup>	Min	Typ	Max	Unit
$t_{PHL}$	HIGH to LOW propagation delay	$n\bar{A}$ , nB to $n\bar{Q}$ ; see <a href="#">Figure 6</a>	5 V	$193\text{ ns} + (0.55\text{ ns/pF}) C_L$	-	220	440	ns
			10 V	$74\text{ ns} + (0.23\text{ ns/pF}) C_L$	-	85	190	ns
			15 V	$52\text{ ns} + (0.16\text{ ns/pF}) C_L$	-	60	120	ns
		$n\bar{CD}$ to nQ; see <a href="#">Figure 6</a>	5 V	$98\text{ ns} + (0.55\text{ ns/pF}) C_L$	-	125	250	ns
			10 V	$44\text{ ns} + (0.23\text{ ns/pF}) C_L$	-	55	110	ns
			15 V	$32\text{ ns} + (0.16\text{ ns/pF}) C_L$	-	40	80	ns
$t_{PLH}$	LOW to HIGH propagation delay	$n\bar{A}$ , nB to nQ; see <a href="#">Figure 6</a>	5 V	$173\text{ ns} + (0.55\text{ ns/pF}) C_L$	-	200	460	ns
			10 V	$79\text{ ns} + (0.23\text{ ns/pF}) C_L$	-	90	180	ns
			15 V	$52\text{ ns} + (0.16\text{ ns/pF}) C_L$	-	60	120	ns
		$n\bar{CD}$ to $n\bar{Q}$ ; see <a href="#">Figure 6</a>	5 V	$98\text{ ns} + (0.55\text{ ns/pF}) C_L$	-	125	250	ns
			10 V	$44\text{ ns} + (0.23\text{ ns/pF}) C_L$	-	55	110	ns
			15 V	$32\text{ ns} + (0.16\text{ ns/pF}) C_L$	-	40	80	ns

**Table 8. Dynamic characteristics ...continued**  
 $V_{SS} = 0\text{ V}$ ;  $T_{amb} = 25\text{ }^{\circ}\text{C}$ ; for test circuit see [Figure 11](#).

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula <sup>[1]</sup>	Min	Typ	Max	Unit
$t_{rec}$	recovery time	$\overline{nCD}$ to $n\overline{A}$ , $nB$ ; see <a href="#">Figure 7</a>	5 V		-	20	40	ns
			10 V		-	10	20	ns
			15 V		-	5	10	ns
$t_{rtrig}$	retrigger time	$nQ$ , $n\overline{Q}$ to $n\overline{A}$ , $nB$ ; see <a href="#">Figure 7</a>	5 V		0	-	-	ns
			10 V		0	-	-	ns
			15 V		0	-	-	ns
$t_W$	pulse width	$n\overline{A}$ LOW; minimum width; see <a href="#">Figure 7</a>	5 V		90	45	-	ns
			10 V		30	15	-	ns
			15 V		24	12	-	ns
		$nB$ HIGH; minimum width; see <a href="#">Figure 7</a>	5 V		50	25	-	ns
			10 V		24	12	-	ns
			15 V		20	10	-	ns
		$n\overline{CD}$ LOW; minimum width; see <a href="#">Figure 7</a>	5 V		55	25	-	ns
			10 V		25	12	-	ns
			15 V		20	10	-	ns
		$nQ$ or $n\overline{Q}$ ; $R_{EXT} = 100\text{ k}\Omega$ ; $C_{EXT} = 2.0\text{ nF}$ ; see <a href="#">Figure 7</a>	5 V		218	230	242	$\mu\text{s}$
			10 V		213	224	235	$\mu\text{s}$
			15 V		211	223	234	$\mu\text{s}$
		$nQ$ or $n\overline{Q}$ ; $R_{EXT} = 100\text{ k}\Omega$ ; $C_{EXT} = 0.1\text{ }\mu\text{F}$ ; see <a href="#">Figure 7</a>	5 V		10.3	10.8	11.3	ms
			10 V		10.2	10.7	11.2	ms
			15 V		10.1	10.6	11.1	ms
$nQ$ or $n\overline{Q}$ ; $R_{EXT} = 100\text{ k}\Omega$ ; $C_{EXT} = 10\text{ }\mu\text{F}$ ; see <a href="#">Figure 7</a>	5 V		1.01	1.09	1.11	s		
	10 V		0.99	1.04	1.09	s		
	15 V		0.99	1.04	1.09	s		
$\Delta t_W$	pulse width variation	$nQ$ or $n\overline{Q}$ variation over temperature range; see <a href="#">Figure 8</a>	5 V		-	$\pm 0.2$	-	%
			10 V		-	$\pm 0.2$	-	%
			15 V		-	$\pm 0.2$	-	%
	$nQ$ or $n\overline{Q}$ variation over $V_{DD}$ voltage range 5 V to 15 V; see <a href="#">Figure 9</a>			-	$\pm 1.5$	-	%	
		$nQ$ or $n\overline{Q}$ variation between monostables in the same device; $R_{EXT} = 100\text{ k}\Omega$ ; $C_{EXT} = 2\text{ nF}$ to $10\text{ }\mu\text{F}$	5 V		-	$\pm 1$	-	%
			10 V		-	$\pm 1$	-	%
$R_{EXT}$	external timing resistor				5	-	<a href="#">[2]</a>	$\text{k}\Omega$
$C_{EXT}$	external timing capacitor				2000	-	no limits	$\text{pF}$

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF).  
 [2] The maximum permissible resistance  $R_{EXT}$ , which holds the specified accuracy of  $t_W$  ( $nQ$ ,  $n\overline{Q}$  output), depends on the leakage current of the capacitor  $C_{EXT}$  and the leakage of the HEF4538B.



12. Waveforms

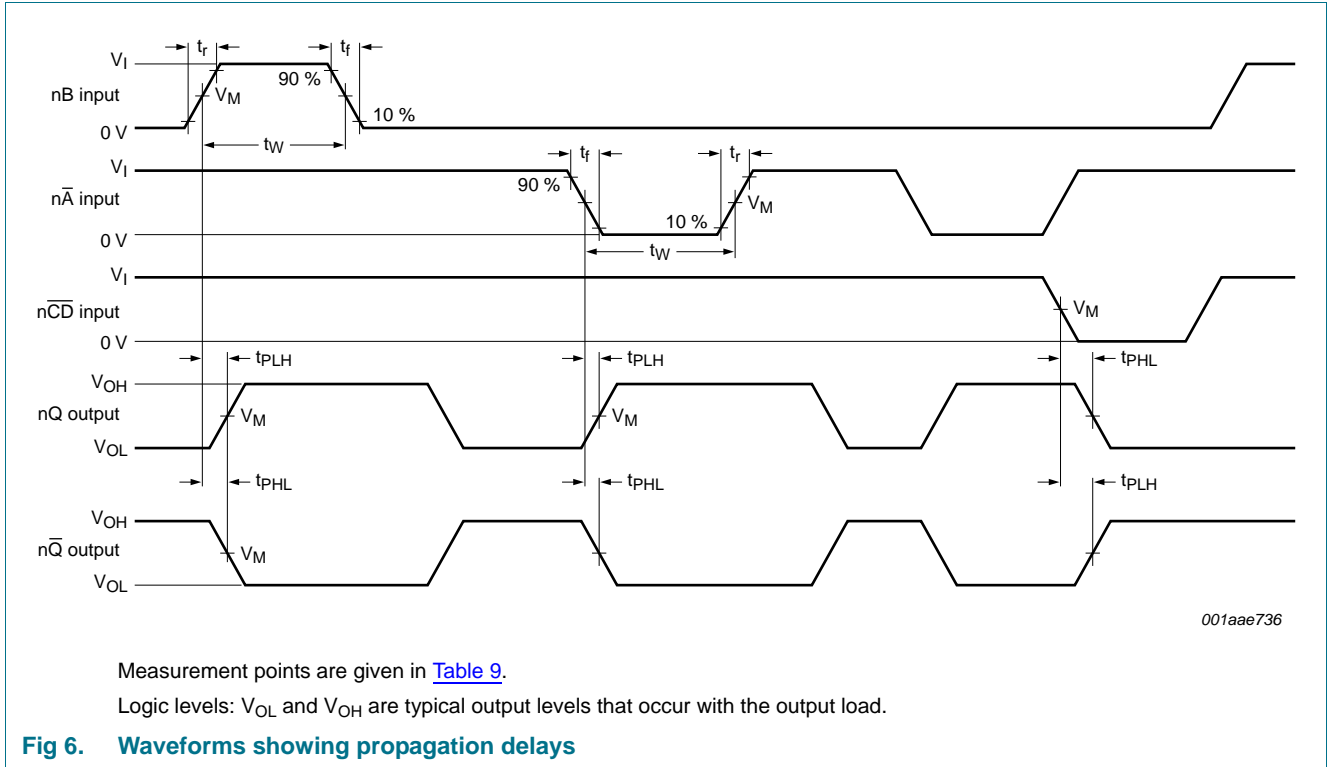
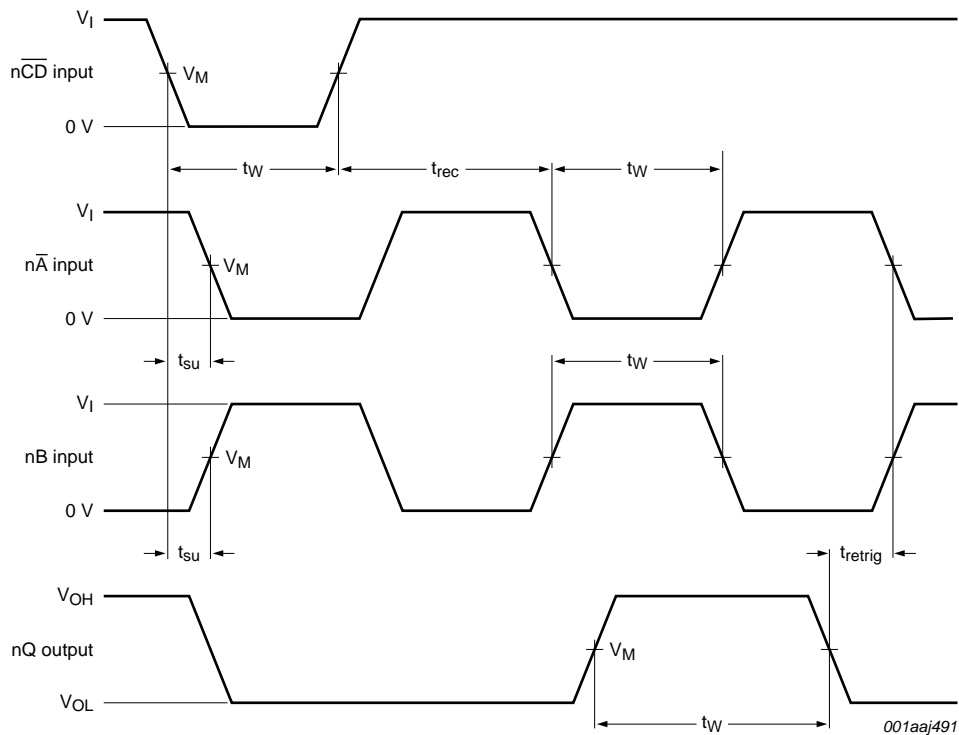


Fig 6. Waveforms showing propagation delays

Table 9. Measurement points

Supply voltage	Input	Output
$V_{DD}$	$V_M$	$V_M$
5 V to 15 V	$0.5V_{DD}$	$0.5V_{DD}$

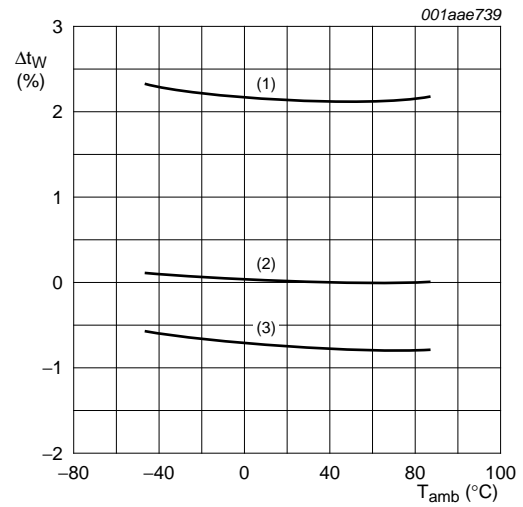
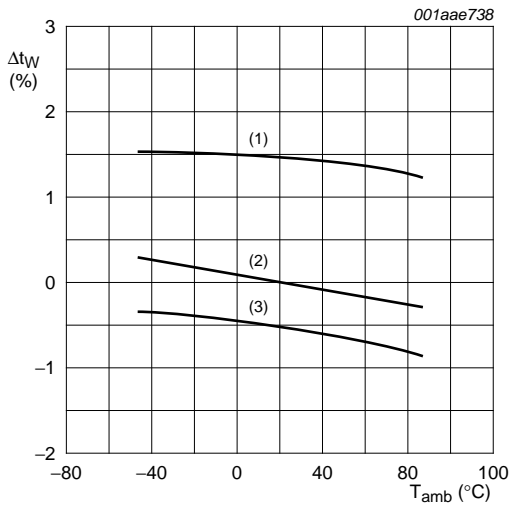


Measurement points are given in [Table 9](#).

Set-up and recovery times are shown as positive values but may be specified as negative values.

Logic levels:  $V_{OL}$  and  $V_{OH}$  are typical output levels that occur with the output load.

**Fig 7. Waveforms showing minimum nA, nB, and nQ pulse widths and set-up, recovery and retrigger times**



a.  $R_{EXT} = 100 \text{ k}\Omega$ ;  $C_{EXT} = 100 \text{ nF}$

b.  $R_{EXT} = 100 \text{ k}\Omega$ ;  $C_{EXT} = 2 \text{ nF}$

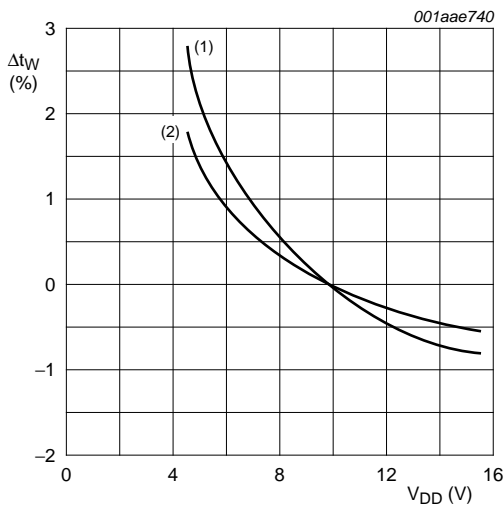
(1)  $V_{DD} = 5 \text{ V}$ .

(2)  $V_{DD} = 10 \text{ V}$ .

(3)  $V_{DD} = 15 \text{ V}$ .

$\Delta t_W = 0 \%$  at  $V_{DD} = 10 \text{ V}$  and  $T_{amb} = 25 \text{ }^\circ\text{C}$

Fig 8. Typical normalized change in output pulse width as a function of ambient temperature

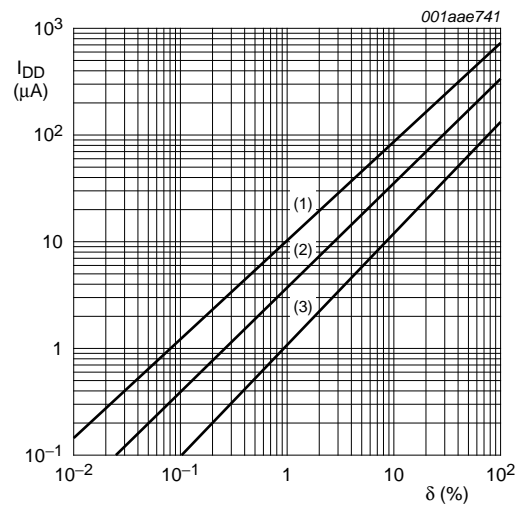


$T_{amb} = 25 \text{ }^\circ\text{C}$ ;  $\Delta t_W = 0 \%$  at  $V_{DD} = 10 \text{ V}$ ;  $R_{EXT} = 100 \text{ k}\Omega$

(1)  $C_{EXT} = 2 \text{ nF}$ .

(2)  $C_{EXT} = 100 \text{ nF}$ .

Fig 9. Typical normalized change in output pulse width as a function of the supply voltage



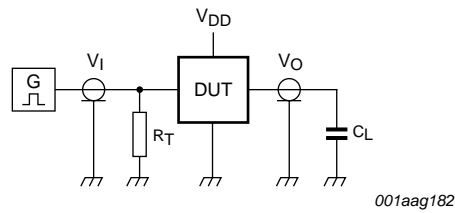
$R_{EXT} = 100 \text{ k}\Omega$ ;  $C_{EXT} = 100 \text{ nF}$ ;  $C_L = 50 \text{ pF}$ ;  
one monostable multivibrator switching only

(1)  $V_{DD} = 15 \text{ V}$ .

(2)  $V_{DD} = 10 \text{ V}$ .

(3)  $V_{DD} = 5 \text{ V}$ .

Fig 10. Total supply current as a function of the output duty factor



Test data is given in [Table 10](#).

Definitions for test circuit:

$C_L$  = load capacitance including jig and probe capacitance.

$R_T$  = termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator.

**Fig 11. Test circuit**

**Table 10. Test data**

Supply voltage	Input		Load
$V_{DD}$	$V_I$	$t_r, t_f$	$C_L$
5 V to 15 V	$V_{SS}$ or $V_{DD}$	$\leq 20$ ns	50 pF

13. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4

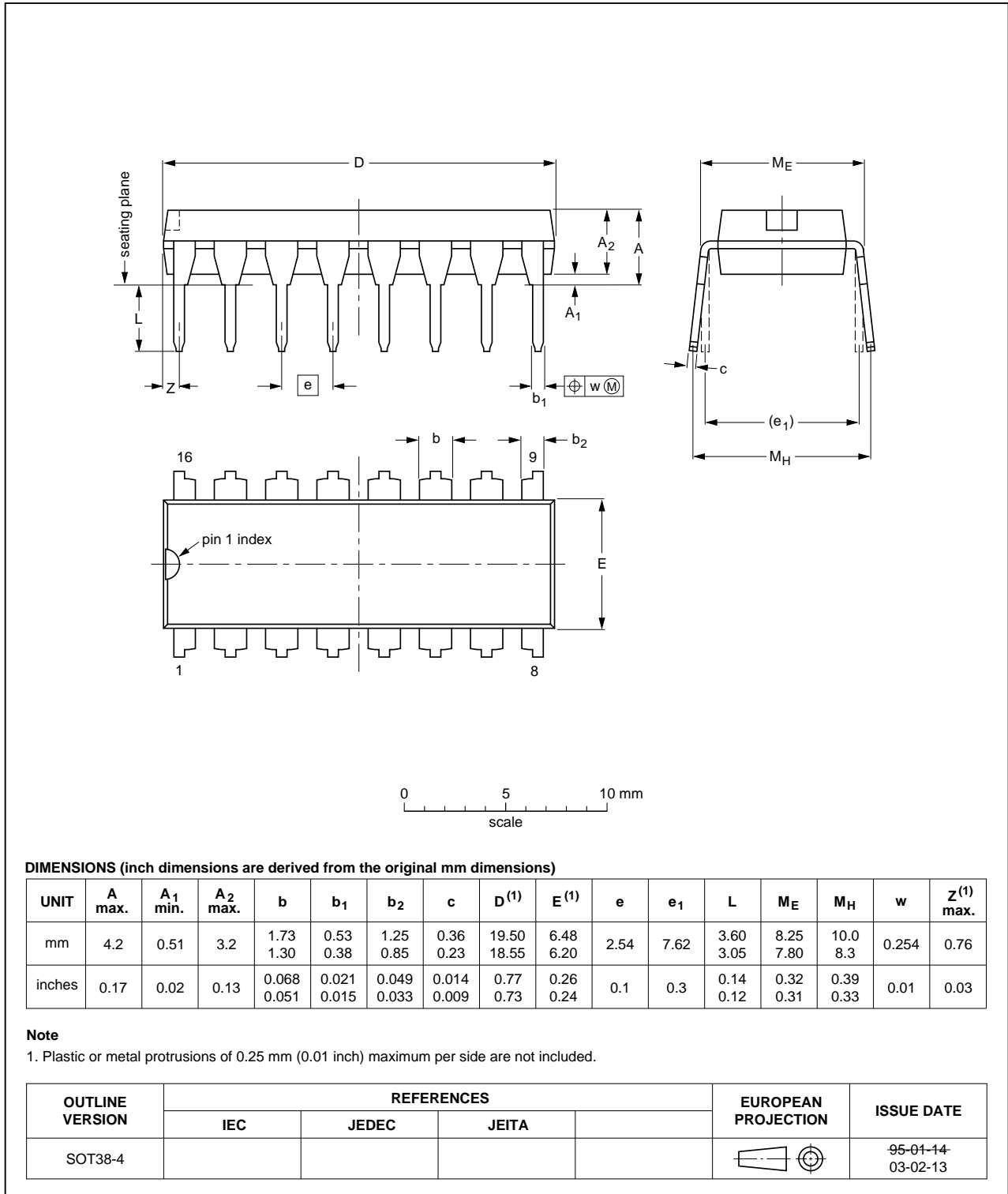


Fig 12. Package outline SOT38-4 (DIP16)

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

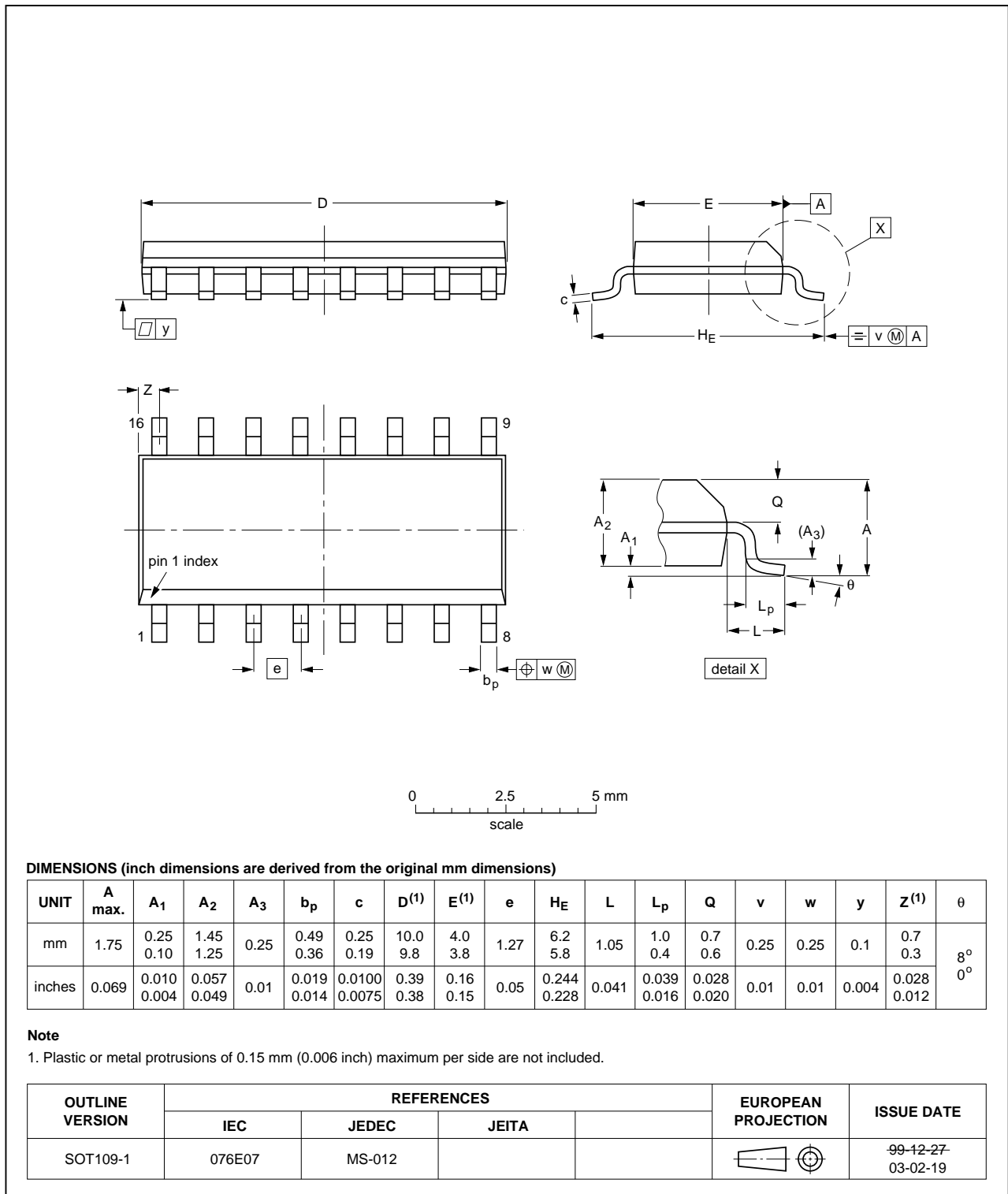


Fig 13. Package outline SOT109-1 (SO16)

## 14. Abbreviations

Table 11. Abbreviations

Acronym	Description
DUT	Device Under Test

## 15. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4538B v.7	20110217	Product data sheet	-	HEF4538B v.6
Modifications:	<ul style="list-style-type: none"> <li>• <a href="#">Table 7</a>: HIGH-level output current values moved from min. column to max. column.</li> <li>• <a href="#">Table 8</a>: Unit for nQ, nQ̄ output pulse width for R<sub>EXT</sub> = 100 kΩ and C<sub>EXT</sub> = 10 μF changed from milliseconds to seconds.</li> </ul>			
HEF4538B v.6	20091102	Product data sheet	-	HEF4538B v.5
HEF4538B v.5	20090304	Product data sheet	-	HEF4538B v.4
HEF4538B v.4	20090206	Product data sheet	-	HEF4538B_CNV v.3
HEF4538B_CNV v.3	19950101	Product specification	-	HEF4538B_CNV v.2
HEF4538B_CNV v.2	19950101	Product specification	-	-

## 16. Legal information

### 16.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

### 16.2 Definitions

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