## SCAN18245T Non-Inverting Transceiver with 3-STATE Outputs

## **General Description**

FAIRCHILD

SEMICONDUCTOR

The SCAN18245T is a high speed, low-power bidirectional line driver featuring separate data inputs organized into dual 9-bit bytes with byte-oriented output enable and direction control signals. This device is compliant with IEEE 1149.1 Standard Test Access Port and Boundary Scan Architecture with the incorporation of the defined boundary-scan test logic and test access port consisting of Test Data Input (TDI), Test Data Out (TDO), Test Mode Select (TMS), and Test Clock (TCK).

#### Features

- IEEE 1149.1 (JTAG) Compliant
- Dual output enable control signals
- 3-STATE outputs for bus-oriented applications
- 9-bit data busses for parity applications
- Reduced-swing outputs source 32 mA/sink 64 mA
- Guaranteed to drive 50Ω transmission line to TTL input levels of 0.8V and 2.0V
- TTL compatible inputs
- 25 mil pitch SSOP (Shrink Small Outline Package)
- Includes CLAMP and HIGHZ instructions
- Member of Fairchild's SCAN Products

## **Ordering Code:**

$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	onnectio	n Diagram		Pin Desc	riptions
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$\begin{array}{c c c c c c c c c c c c c c c c c c c $				A1 <sub>(0-8)</sub>	Side A1 Inputs or 3-STATE Outputs
$\begin{array}{c c c c c c c c c c c c c c c c c c c $				B1 <sub>(0-8)</sub>	Side B1 Inputs or 3-STATE Outputs
$CND = 6$ $51 - CNC$ $B1_3 - 7$ $50 - A1_3$ Side B2 Inputs or 3-STATE Output $B1_3 - 7$ $50 - A1_3$ $G1, G2$ Output Enable Pins $V_{CC} = 9$ $48 - V_{CC}$ $DIR1, DIR2$ Direction of Data Flow Pins $B1_5 - 10$ $47 - A1_5$ $DIR1, DIR2$ Direction of Data Flow Pins $B1_5 - 11$ $46 - A1_6$ $DIR1, DIR2$ Direction of Data Flow Pins $B1_7 - 13$ $44 - A1_7$ $B1_8 - 14$ $43 - A1_8$ $B2_0 - 15$ $42 - A2_0$ $B2_1 - 16$ $41 - A2_1$ $OND - 17$ $40 - GAR$ $6A2_2$ $B2_3 - 19$ $38 - A2_3$ $V_{CC} - 20$ $37 - V_{CC}$ $B2_4 - 21$ $36 - A2_4$ $B2_5 - 22$ $B2_4 - 21$ $36 - A2_4$ $B2_5 - 22$ $35 - A2_5$ $OND - 23$ $34 - ONE$ $B2_6 - 24$ $33 - A2_6$ $B2_7 - 25$ $32 - A2_7$ $A2_7$			•	A2 <sub>(0-8)</sub>	Side A2 Inputs or 3-STATE Outputs
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$			GND		Side B2 Inputs or 3-STATE Outputs
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$				()	Output Enable Pins
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$B2_{3} = \begin{vmatrix} 19 & 38 \\ 23 \\ 19 & 37 \end{vmatrix} + \begin{vmatrix} 20 & 37 \\ 10 \\ 20 & 37 \end{vmatrix} + \begin{vmatrix} 20 \\ 10 \\ 10 \\ 10 \\ 10 \\ 10 \\ 10 \\ 10 \\$					
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$\begin{array}{c c c c c c c c c c c c c c c c c c c $			- A24		
$\begin{array}{cccc} B2_6 & 24 & 33 \\ B2_7 & 25 & 32 \\ \end{array}  A2_7 \end{array}$		·			
$B_{2_7} - 25$ $32 - A_{2_7}$					
		*	•		
$B_{2_8} \rightarrow 27 \qquad 30 \rightarrow A_{2_8}$			-		
		100 - 28 29	- ICK		

## Truth Table

Inp	uts	A1 (	0 0)	B1 (0–8)		
G1	DIR1	A1 (	0-0)	ы(	0-0)	
L	L	Н	~	_	Н	
L	L	L ←		-	L	
L	Н	H →		÷	Н	
L	н	L	-	÷	L	
Н	Х	Z			Z	

Inp	outs	A 2 (0	٥)	B2 (0 9)
G2	DIR2	A2 (0–	0)	B2 (0–8)
L	L	Н	<del>(</del>	– H
L	L	L	<i>\</i>	- L
L	Н	Н	-	→ H
L	Н	L	-	→ L
Н	Х	Z		Z

X= Immaterial

Z= High Impedance

H= HIGH Voltage Level

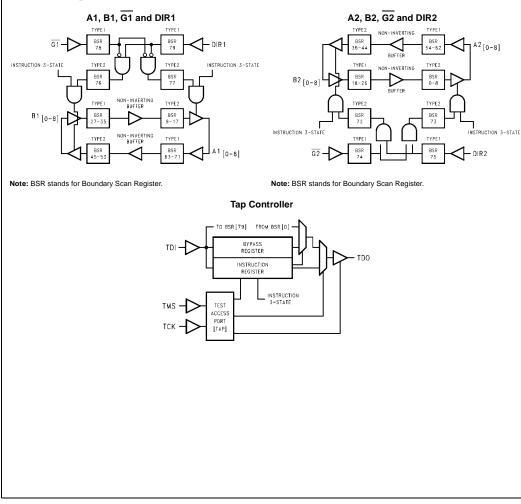
L= LOW Voltage Level

## **Functional Description**

**Block Diagrams** 

The SCAN18245 consists of two sets of nine non-inverting bidirectional buffers with 3-STATE outputs and is intended for bus-oriented applications. Direction pins (DIR1 and DIR2) LOW enables data from B Ports to A Ports, when

HIGH enables data from A Ports to B Ports. The Output Enable pins  $(\overline{G1} \text{ and } \overline{G2})$  when HIGH disables both A and B Ports by placing them in a high impedance condition.



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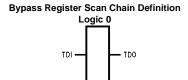
Downloaded from **Elcodis.com** electronic components distributor

## **Description of Boundary-Scan Circuitry**

The scan cells used in the BOUNDARY-SCAN register are one of the following two types depending upon their location. Scan cell TYPE1 is intended to solely observe system data, while TYPE2 has the additional ability to control system data. (See IEEE Standard 1149.1 Figure 10-11 for a further description of scan cell TYPE1 and Figure 10-12 for a further description of scan cell TYPE2.)

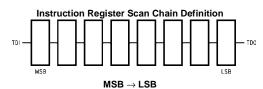
Scan cell TYPE1 is located on each system input pin while scan cell TYPE2 is located at each system output pin as well as at each of the two internal active-high output enable signals. AOE controls the activity of the A-outputs while BOE controls the activity of the B-outputs. Each will activate their respective outputs by loading a logic high.

The BYPASS register is a single bit shift register stage identical to scan cell TYPE1. It captures a fixed logic low.

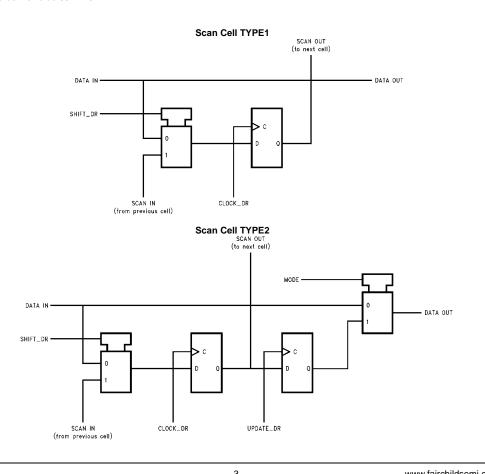


The INSTRUCTION register is an eight-bit register which captures the value 00111101.

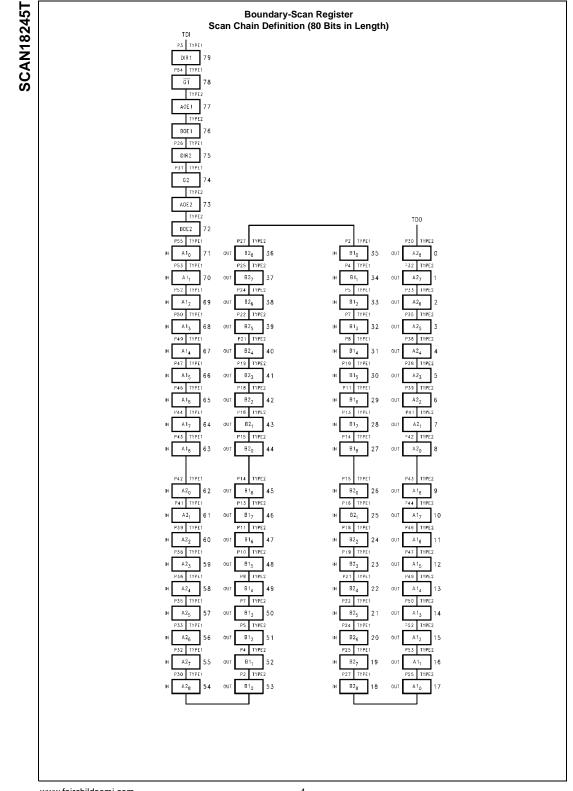
The two least significant bits of this captured value (01) are required by IEEE Std 1149.1. The upper six bits are unique to the SCAN18245T device. SCAN CMOS Test Access Logic devices do not include the IEEE 1149.1 optional identification register. Therefore, this unique captured value can be used as a "pseudo ID" code to confirm that the correct device is placed in the appropriate location in the boundary scan chain.



Instruction Code	Instruction
0000000	EXTEST
1000001	SAMPLE/PRELOAD
10000010	CLAMP
00000011	HIGHZ
All Others	BYPASS



## **SCAN18245T**



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Bit No.	Pin Name	Pin No.	Pin Type	Scan C	ell Type	Bit No.	Pin Name	Pin No.	Pin Type	Scan Co	ell Typ
79	DIR1	3	Input	TYPE1		35	B1 <sub>0</sub>	2	Input	TYPE1	
78	G1	54	Input	TYPE1		34	B1 <sub>1</sub>	4	Input	TYPE1	
77	AOE <sub>1</sub>		Internal	TYPE2		33	B1 <sub>2</sub>	5	Input	TYPE1	
76	BOE <sub>1</sub>		Internal	TYPE2	00	32	B1 <sub>3</sub>	7	Input	TYPE1	
75	DIR2	26	Input	TYPE1	Signals	31	B1 <sub>4</sub>	8	Input	TYPE1	B1–
74	G2	31	Input	TYPE1		30	B1 <sub>5</sub>	10	Input	TYPE1	
73	AOE <sub>2</sub>		Internal	TYPE2		29	В1 <sub>6</sub>	11	Input	TYPE1	
72	BOE <sub>2</sub>		Internal	TYPE2		28	B1 <sub>7</sub>	13	Input	TYPE1	
71	A1 <sub>0</sub>	55	Input	TYPE1		27	B1 <sub>8</sub>	14	Input	TYPE1	
70	A1 <sub>1</sub>	53	Input	TYPE1		26	B2 <sub>0</sub>	15	Input	TYPE1	
69	A1 <sub>2</sub>	52	Input	TYPE1		25	B2 <sub>1</sub>	16	Input	TYPE1	
68	A1 <sub>3</sub>	50	Input	TYPE1		24	B2 <sub>2</sub>	18	Input	TYPE1	
67	A1 <sub>4</sub>	49	Input	TYPE1	A1–in	23	B2 <sub>3</sub>	19	Input	TYPE1	_
66	A1 <sub>5</sub>	47	Input	TYPE1		22	B2 <sub>4</sub>	21	Input	TYPE1	B2–
65	A1 <sub>6</sub>	46	Input	TYPE1		21	B2 <sub>5</sub>	22	Input	TYPE1	
64	A1 <sub>7</sub>	44	Input	TYPE1		20	B2 <sub>6</sub>	24	Input	TYPE1	
63	A1 <sub>8</sub>	43	Input	TYPE1		19	B2 <sub>7</sub>	25	Input	TYPE1	
62	A2 <sub>0</sub>	42	Input	TYPE1		18	B2 <sub>8</sub>	27	Input	TYPE1	
61	A2 <sub>1</sub>	41	Input	TYPE1		17	A1 <sub>0</sub>	55	Output	TYPE2	
60	A2 <sub>2</sub>	39	Input	TYPE1		16	A1 <sub>1</sub>	53	Output	TYPE2	
59	A2 <sub>3</sub>	38	Input	TYPE1		15	A1 <sub>2</sub>	52	Output	TYPE2	
58	A2 <sub>4</sub>	36	Input	TYPE1	A2–in	14	A1 <sub>3</sub>	50	Output	TYPE2	• •
57	A2 <sub>5</sub>	35	Input	TYPE1		13	A1 <sub>4</sub>	49	Output	TYPE2	A1–0
56	A2 <sub>6</sub>	33	Input	TYPE1		12	A1 <sub>5</sub>	47	Output	TYPE2	
55	A2 <sub>7</sub>	32	Input	TYPE1		11	A1 <sub>6</sub>	46	Output	TYPE2	
54	A2 <sub>8</sub>	30	Input	TYPE1 TYPE2		10	A1 <sub>7</sub>	44	Output	TYPE2 TYPE2	
53 52	B1 <sub>0</sub>	2 4	Output	TYPE2		9	A1 <sub>8</sub>	43 42	Output Output	TYPE2	
52 51	B1 <sub>1</sub>	4 5	Output Output	TYPE2		о 7	A2 <sub>0</sub> A2 <sub>1</sub>	42 41	Output	TYPE2	
50	B1 <sub>2</sub>	7	Output	TYPE2		6	A21 A22	39	Output	TYPE2	
50 49	B1 <sub>3</sub> B1₄	8	Output	TYPE2	B1–out	5	A22 A23	38	Output	TYPE2	
49 48		。 10	Output	TYPE2	BI-Oul	5 4	A2 <sub>3</sub> A2 <sub>4</sub>	36	Output	TYPE2	12
40 47	B1 <sub>5</sub> B1 <sub>6</sub>	10	Output	TYPE2		4	A24 A25	35	Output	TYPE2	A2-0
46	B1 <sub>6</sub> B1 <sub>7</sub>	13	Output	TYPE2		2	A25 A26	33	Output	TYPE2	
40 45	B1 <sub>7</sub> B1 <sub>8</sub>	14	Output	TYPE2		1	A2 <sub>6</sub> A2 <sub>7</sub>	32	Output	TYPE2	
44	B18 B20	15	Output	TYPE2		0	A27 A28	30	Output	TYPE2	
43	B2 <sub>0</sub> B2 <sub>1</sub>	16	Output	TYPE2		0	728	50	Output		
42	B2 <sub>1</sub> B2 <sub>2</sub>	18	Output	TYPE2							
41	B2 <sub>2</sub> B2 <sub>3</sub>	19	Output	TYPE2							
40	B2 <sub>4</sub>	21	Output		B2-out						
39	B2 <sub>5</sub>	22	Output	TYPE2	22 000						
38	B2 <sub>6</sub>	24	Output	TYPE2							
37	B2 <sub>6</sub> B2 <sub>7</sub>	25	Output	TYPE2							
36	B2 <sub>8</sub>	27	Output	TYPE2							

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## Absolute Maximum Ratings(Note 1)

Supply Voltage (V <sub>CC</sub> )	-0.5V to +7.0V
DC Input Diode Current (I <sub>IK</sub> )	
$V_{I} = -0.5V$	-20 mA
$V_I = V_{CC} + 0.5V$	+20 mA
DC Output Diode Current (I <sub>OK</sub> )	
$V_0 = -0.5V$	-20 mA
$V_O = V_{CC} + 0.5V$	+20 mA
DC Output Voltage (V <sub>O</sub> )	–0.5V to V <sub>CC</sub> +0.5V
DC Output Source/Sink Current (I <sub>O</sub> )	±70 mA
DC V <sub>CC</sub> or Ground Current	
Per Output Pin	±70 mA
Junction Temperature	
SSOP	+140°C
Storage Temperature	-65°C to +150°C
ESD (Min)	2000V

## Recommended Operating Conditions

Supply Voltage (V <sub>CC</sub> )	
SCAN Products	4.5V to 5.5V
Input Voltage (V <sub>I</sub> )	0V to $V_{CC}$
Output Voltage (V <sub>O</sub> )	0V to V <sub>CC</sub>
Operating Temperature (T <sub>A</sub> )	$-40^{\circ}C$ to $+85^{\circ}C$
Minimum Input Edge Rate $\Delta V/\Delta t$	125 mV/ns
V <sub>IN</sub> from 0.8V to 2.0V	
V <sub>CC</sub> @ 4.5V, 5.5V	
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Note 1: Absolute maximum ratings are those values beyond which damage to the device may occur. The databook specifications should be met, without exception, to ensure that the system design is reliable over its power supply, temperature, and output/input loading variables. Fairchild does not recommend operation of SCAN circuits outside databook specifications.

## **DC Electrical Characteristics**

Symbol	Parameter	V <sub>cc</sub>	<b>T</b> <sub>A</sub> =	+25°C	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	Units	Conditions
Symbol	Farameter	(V)	Тур	Gua	aranteed Limits	Units	Conditions
VIH	Minimum HIGH	4.5	1.5	2.0	2.0	V	$V_{OUT} = 0.1V$
	Input Voltage	5.5	1.5	2.0	2.0	v	or V <sub>CC</sub> –0.1V
V <sub>IL</sub>	Maximum LOW	4.5	1.5	0.8	0.8	V	$V_{OUT} = 0.1V$
	Input Voltage	5.5	1.5	0.8	0.8	v	or V <sub>CC</sub> –0.1V
V <sub>OH</sub>	Minimum HIGH	4.5		3.15	3.15	V	
	Output Voltage	5.5		4.15	4.15	v	$I_{OUT} = -50 \ \mu A$
	(Note 2)	4.5		2.4	2.4	V	$V_{IN} = V_{IL} \text{ or } V_{IH}$
		5.5		2.4	2.4	v	$I_{OH} = -32 \text{ mA}$
		4.5		2.4		V	$V_{IN} = V_{IL} \text{ or } V_{IH}$
		5.5		2.4		v	$I_{OH} = -24 \text{ mA}$
V <sub>OL</sub>	Maximum LOW	4.5		0.1	0.1	V	. 50 4
	Output Voltage	5.5		0.1	0.1	v	$I_{OUT} = 50 \ \mu A$
	(Note 2)	4.5		0.55	0.55	V	$V_{IN} = V_{IL} \text{ or } V_{IH}$
		5.5		0.55	0.55	v	I <sub>OL</sub> = 64 mA
		4.5		0.55		V	$V_{IN} = V_{IL} \text{ or } V_{IH}$
		5.5		0.55		v	I <sub>OL</sub> = 48 mA
IN	Maximum Input Leakage Current	5.5		±0.1	±1.0	μA	$V_I = V_{CC}, GND$
IN	Maximum Input Leakage	5.5		2.8	3.6	μA	$V_I = V_{CC}$
TDI, TMS				-385	-385	μA	$V_I = GND$
	Minimum Input Leakage	5.5		-160	-160	μA	$V_I = GND$
OLD	Minimum Dynamic	5.5		94	94	mA	$V_{OLD} = 0.8V$ Max
онр	Output Current (Note 3)			-40	-40	mA	$V_{OHD} = 2.0V$ Min
OZT	Maximum I/O						$V_{I}$ (OE) = $V_{IL}$ ,
	Leakage Current	5.5		±0.6	±6.0	μA	$V_{IH}V_I = V_{CC}, GND$
							$V_{O} = V_{CC}, GND$
l <sub>os</sub>	Output Short Circuit Current	5.5		-100	-100	mA (min)	$V_0 = 0V$
I <sub>CC</sub>	Maximum Quiescent	5.5		16.0	88	μA	V <sub>O</sub> = HIGH
	Supply Current	5.5		10.0	00	μΑ	TDI, TMS = $V_{CC}$
		E E		750	820		V <sub>O</sub> = HIGH
		5.5		750	820	μA	TDI, TMS = GND

## DC Electrical Characteristics (Continued)

Symbol	Parameter	v <sub>cc</sub>	T <sub>A</sub> = +25°C		$T_A=-40^\circ C$ to $+85^\circ C$	Units	Conditions
Symbol Parameter		(V)	Тур	Gua	ranteed Limits	onita	Conditions
I <sub>CCt</sub>	Maximum I <sub>CC</sub> Per Input	5.5		2.0	2.0	mA	$V_{I} = V_{CC} - 2.1V$
							$V_{I} = V_{CC} - 2.1V$
		5.5		2.15	2.15	mA	TDI/TMS Pin,
							test one with the
							other floating

Note 2: All outputs loaded; thresholds associated with output under test. Note 3: Maximum test duration 2.0 ms, one output loaded at a time.

## **Noise Specifications**

Symbol	Parameter	V <sub>cc</sub>	<b>T<sub>A</sub></b> = -	+25°C	$T_A = -40^{\circ}C$ to $+85^{\circ}C$	Units
Symbol	Falance	(V)	Тур	Guaran	teed Limits	Units
V <sub>OLP</sub>	Maximum HIGH Output Noise (Note 5)(Note 6)	5.0	1.0	1.5		V
V <sub>OLV</sub>	Minimum LOW Output Noise (Note 5)(Note 6)	5.0	-0.6	-1.2		V
V <sub>OHP</sub>	Maximum Overshoot (Note 4)(Note 6)	5.0	V <sub>OH</sub> +1.0	V <sub>OH</sub> +1.5		V
V <sub>OHV</sub>	Minimum V <sub>CC</sub> Droop (Note 4)(Note 6)	5.0	V <sub>OH</sub> -1.0	V <sub>OH</sub> -1.8		V
V <sub>IHD</sub>	Minimum HIGH Dynamic Input Voltage Level (Note 4)(Note 7)	5.5	1.6	2.0	2.0	V
V <sub>ILD</sub>	Maximum LOW Dynamic Input Voltage Level (Note 4)(Note 7)	5.5	1.4	0.8	0.8	V

Note 4: Worst case package.

Note 5: Maximum number of outputs that can switch simultaneously is n. (n-1) outputs are switched LOW and one output held LOW.

Note 6: Maximum number of outputs that can switch simultaneously is n. (n-1) outputs are switched HIGH and one output held HIGH.

Note 7: Maximum number of data inputs (n) switching. (n-1) input switching 0V to 3V. Input under test switching 3V to threshold (VILD).

## **AC Electrical Characteristics**

		V <sub>cc</sub>		$T_A = +25^{\circ}C$		T <sub>A</sub> =-40°C	C to +85°C	
Symbol	Parameter	(V)		$C_L = 50 \ pF$		<b>C</b> <sub>L</sub> =	50 pF	Units
		(Note 8)	Min	Тур	Max	Min	Max	
t <sub>PLH</sub> ,	Propagation Delay	5.0	1.6		7.9	1.6	8.5	ns
t <sub>PHL</sub>	A to B, B to A		1.6		7.9	1.6	8.8	115
t <sub>PLZ</sub> ,	Disable Time	5.0	1.2		8.6	1.2	9.5	ns
t <sub>PHZ</sub>			1.2		8.5	1.2	9.0	115
t <sub>PZL</sub> ,	Enable Time	5.0	1.6		11.0	1.6	12.0	
t <sub>PZH</sub>			1.6		8.5	1.6	9.5	ns

Note 8: Voltage Range 5.0 is 5.0V  $\pm$  0.5V.

Note: All Input Timing Delays involving TCK are measured from the rising edge of TCK.

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## **AC Electrical Characteristics**

		V <sub>CC</sub>		$T_A = +25^{\circ}C$		T <sub>A</sub> =-40°C	C to +85°C	
Symbol	Parameter	(V)		C <sub>L</sub> = 50 pF		<b>C</b> <sub>L</sub> =	50 pF	Units
		(Note 9)	Min	Тур	Мах	Min	Max	
t <sub>PLH</sub> ,	Propagation Delay	5.0	2.8		13.2	2.8	14.5	
t <sub>PHL</sub>	TCK to TDO		2.8		13.2	2.8	14.5	ns
t <sub>PLZ</sub> ,	Disable Time	5.0	2.0		11.5	2.0	11.9	
t <sub>PHZ</sub>	TCK to TDO		2.0		11.5	2.0	11.9	ns
t <sub>PZL</sub> ,	Enable Time	5.0	2.4		14.5	2.4	15.8	
t <sub>PZH</sub>	TCK to TDO		2.4		14.5	2.4	15.8	ns
t <sub>PLH</sub> ,	Propagation Delay	5.0	4.0		18.0	4.0	19.8	
t <sub>PHL</sub>	TCK to Data Out		4.0		18.0	4.0	19.8	ns
	During Update-DR State							
t <sub>PLH</sub> ,	Propagation Delay		4.0		18.6	4.0	20.2	
t <sub>PHL</sub>	TCK to Data Out	5.0	4.0		18.6	4.0	20.2	ns
	During Update-IR State							
t <sub>PLH</sub> ,	Propagation Delay	5.0	4.4		19.9	4.4	21.5	
t <sub>PHL</sub>	TCK to Data Out		4.4		19.9	4.4	21.5	ns
	During Test Logic							
	Reset State							
t <sub>PLZ</sub> ,	Propagation Delay	5.0	3.2		16.4	3.2	18.2	
t <sub>PHZ</sub>	TCK to Data Out		3.2		16.4	3.2	18.2	ns
	During Update-DR State							
t <sub>PLZ</sub> ,	Propagation Delay	5.0	2.8		18.0	2.8	19.3	
t <sub>PHZ</sub>	TCK to Data Out		2.8		18.0	2.8	19.3	ns
	During Update-IR State							
t <sub>PLZ</sub> ,	Propagation Delay	5.0	2.8		18.4	2.8	20.0	
t <sub>PHZ</sub>	TCK to Data Out		2.8		18.4	2.8	20.0	ns
	During Test Logic							
	Reset State							
t <sub>PZL</sub> ,	Propagation Delay	5.0	4.0		18.9	4.0	20.9	-
t <sub>PZH</sub>	TCK to Data Out		4.0		18.9	4.0	20.9	ns
	During Update-DR State							
t <sub>PZL</sub> ,	Propagation Delay	5.0	3.2		19.9	3.2	21.7	nc
t <sub>PZH</sub>	TCK to Data Out		3.2		19.9	3.2	21.7	ns
	During Update-IR State							
t <sub>PZL</sub> ,	Propagation Delay	5.0	3.6		21.3	3.6	23.3	-
t <sub>PZH</sub>	TCK to Data Out		3.6		21.3	3.6	23.3	ns
	During Test Logic							
	Reset State							

Note 9: Voltage Range 5.0 is  $5.0V \pm 0.5V$ .

Note: All Input Timing Delays involving TCK are measured from the rising edge of TCK.

Note: All Propagation Delays involving TCK are measured from the falling edge of TCK.

	Operation Parameter	V <sub>cc</sub>	$T_A = +25^{\circ}C$	$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	C Units
Symbol		(V) (Note 10)	$C_L = 50 \ pF$	$C_L = 50 \ pF$	
			Guaran	l	
t <sub>s</sub>	Setup Time, H or L	5.0	0.0	0.0	
	Data to TCK (Note 11)	5.0	0.0	0.0	ns
t <sub>H</sub>	Hold Time, H or L	5.0	6.5	6.5	ns
	TCK to Data (Note 11)	0.0	0.5	0.0	113
t <sub>S</sub>	Setup Time, H or L	5.0	0.0	0.0	ns
	G1, G2 to TCK (Note 12)	0.0	0.0	0.0	10
t <sub>H</sub>	Hold Time, H or L	5.0	4.0	4.0	ns
	TCK to $\overline{G1}$ , $\overline{G2}$ (Note 12)	0.0	-1.0	v	10
t <sub>S</sub>	Setup Time, H or L	5.0	0.0	0.0	ns
	DIR1, DIR2 to TCK (Note 13)				
t <sub>H</sub> t <sub>S</sub>	Hold Time, H or L	5.0	4.0	4.0	ns
	TCK to DIR1, DIR2 (Note 13)			-	-
	Setup Time, H or L				
	Internal AOE <sub>n</sub> , BOE <sub>n</sub>	5.0	1.0	1.0	ns
	to TCK (Note 14)				
t <sub>H</sub>	Hold Time, H or L				
	TCK to Internal AOE <sub>n</sub> ,	5.0	4.0	4.0	ns
	BOE <sub>n</sub> (Note 14)				
t <sub>S</sub>	Setup Time, H or L	5.0	7.0	7.0	ns
	TMS to TCK				
t <sub>H</sub>	Hold Time, H or L	5.0	2.0	2.0	ns
	TCK to TMS				
t <sub>S</sub>	Setup Time, H or L	5.0	1.0	1.0	ns
	TDI to TCK				
t <sub>H</sub>	Hold Time, H or L	5.0	3.5	3.5	ns
	TCK to TDI				
	Pulse Width	5.0			
	н		15.0	15.0	ns
	L		5.0	5.0	L
f <sub>MAX</sub>	Maximum TCK	5.0	25	25	MHz
	Clock Frequency				
T <sub>PU</sub>	Wait Time,	5.0	100	100	ns
-	Power Up to TCK				
T <sub>DN</sub>	Power Down	0.0	100	100	ms

Note 10: Voltage Range 5.0 is  $5.0V \pm 0.5V$ .

Note 11: Timing pertains to the TYPE1 BSR and TYPE2 BSR after the buffer (BSR 0-8, 9-17, 18-26, 27-35, 36-44, 45-53, 54-62, 63-71).

Note 12: Timing pertains to BSR 74 and 78 only.

Note 13: Timing pertains to BSR 75 and 79 only.

Note 14: Timing pertains to BSR 72, 73, 76 and 77 only.

Note: All Input Timing Delays involving TCK are measured from the rising edge of TCK.

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## **Extended AC Electrical Characteristics**

Symbol	Parameter		$T_A = +25^{\circ}C, V_{CC} = 5.0V$ $C_L = 50 \text{ pF}$ 18 Outputs Switching (Note 15)			$T_{A} = -40^{\circ}C \text{ to } +85^{\circ}C$ $V_{CC} = 5.0V \pm 0.5V$ $C_{L} = 250 \text{ pF}$ (Note 16)	
		Min	Тур	Max	Min	Max	
t <sub>PLH,</sub>	Propagation Delay	2.5		10.5	3.5	3.5 12.0	
t <sub>PHL</sub>	Data to Output	2.5		10.5	3.5 13.5		ns
t <sub>PZH</sub> ,	Output Enable Time	2.5		10.5	(Note 17)		ns
t <sub>PZL</sub>		2.5		13.5			
t <sub>PHZ,</sub>	Output Disable Time	2.0		9.5	(Note 18)		ns
t <sub>PLZ</sub>		2.0		10.0			
t <sub>OSHL</sub>	Pin to Pin Skew		0.5	1.0		1.0	
(Note 19)	HL Data to Output		0.5 1.0		1.0		ns
toslh	Pin to Pin Skew		0.5 1.0			1.0	ns
(Note 19)	LH data to Output				1.0		115

Note 15: This specification is guaranteed but not tested. The limits apply to propagation delays for all paths described switching in phase (i.e., all LOW-to-HIGH, HIGH-to-LOW, etc.)

Note 16: This specification is guaranteed but not tested. The limits represent propagation delays with 250 pF load capacitors in place of the 50 pF load capacitors in the standard AC load. This specification pertains to single output switching only.

Note 17: 3-STATE delays are load dominated and have been excluded from the datasheet.

Note 18: The Output Disable Time is dominated by the RC network ( $500\Omega$ , 250 pF) on the output and has been excluded from the datasheet.

Note 19: Skew is defined as the absolute value of the difference between the actual propagation delays for any two separate outputs of the same device. The specification applies to any outputs switching HIGH-to-LOW (t<sub>OSHL</sub>), LOW-to-HIGH (t<sub>OSLH</sub>), or any combination switching LOW-to-HIGH and/or HIGH-to-LOW.

## Capacitance

Symbol	Parameter	Тур	Units	Conditions
CIN	Input Pin Capacitance	4	pF	V <sub>CC</sub> = 5.0V
C <sub>I/O</sub>	Input/Output Capacitance	20	pF	$V_{CC} = 5.0V$
C <sub>PD</sub>	Power Dissipation Capacitance	41	pF	V <sub>CC</sub> = 5.0V

