**MAXIM**

# ±80V Fault-Protected Full-Duplex RS-485 Transceiver

## General Description

The MAX13448E full-duplex RS-485 transceiver features inputs and outputs fault protected up to ±80V (with respect to ground). The device operates from a +3.0V to +5.5V supply and features true fail-safe circuitry, guaranteeing a logic-high receiver output when the receiver inputs are open or shorted. This enables all receiver outputs on a terminated bus to output logic-high when all transmitters are disabled.

The MAX13448E features a slew-rate limited driver that minimizes EMI and reduces reflections caused by improperly terminated cables, allowing error-free data transmission at data rates up to 500kbps with a +5V supply, and 250kbps with a +3.3V supply.

The MAX13448E includes a hot-swap capability to eliminate false transitions on the bus during power-up or hot insertion. The driver and receiver feature active-high and active-low enables, respectively, that can be connected together externally to serve as a direction control.

The MAX13448E features an 1/8-unit load receiver input impedance, allowing up to 256 transceivers on the bus. All driver outputs are protected to ±8kV ESD using the Human Body Model. The MAX13448E is available in a 14-pin SO package and operates over the extended -40°C to +85°C temperature range.

## Applications

Industrial Control Systems

HVAC Control systems

Utility Meters

Motor Driver Control Systems

## Features

- ♦ **±80V Fault Protection on the RS-485 I/O Ports**
- ♦ **True Fail-Safe Receiver**
- ♦ **Hot-Swap Input Structure on DE**
- ♦ **ESD Protection on the RS-485 I/O Ports ±8kV Human Body Model**
- ♦ **Slew-Rate Limiting Facilitates Error-Free Data Transmission**
- ♦ **1/8-Unit Load Allows Up to 256 Transceivers on the Bus**
- ♦ **-7V to +12V Common-Mode Input Voltage Range**
- ♦ **+3.0V to +5.5V Operating Supply Voltage**
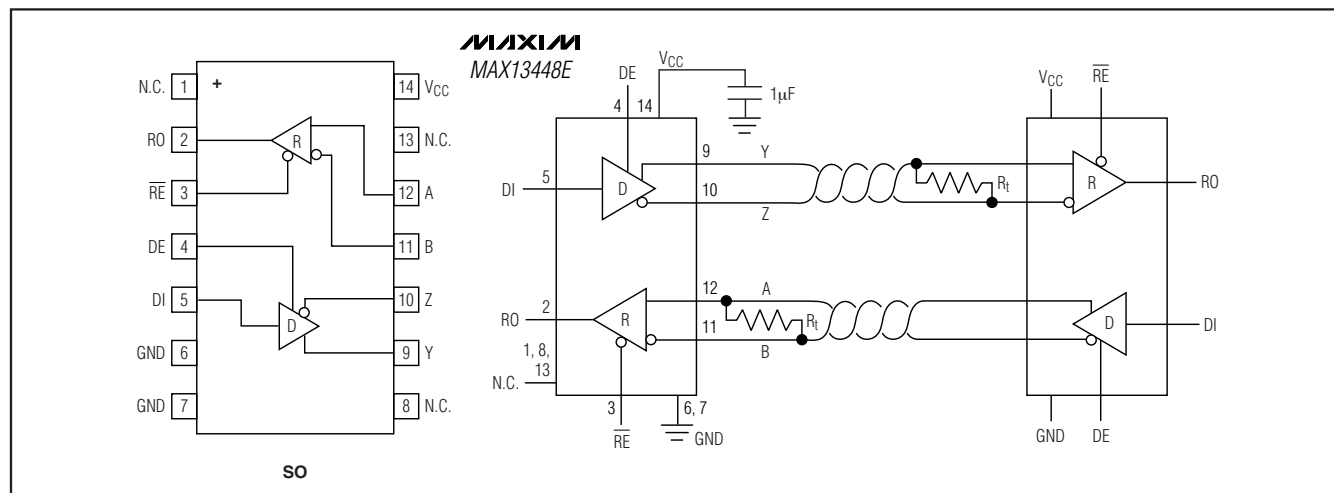- ♦ **Available in 14-Pin SO Package**

## Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
|------|-----------|-------------|
| MAX13448EESD+ | -40°C to +85°C | 14 SO |

*+Denotes a lead-free package.*

*Pin Configuration appears at end of data sheet.*

## Functional Diagram



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***For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.***

# ±80V Fault-Protected Full-Duplex RS-485 Transceiver

MAX13448E

## ABSOLUTE MAXIMUM RATINGS

(All voltages reference to GND.)

Supply Voltage (V$_{CC}$)......................................................+6V
Control Input Voltage ($\overline{RE}$, DE)..................-0.3V to (V$_{CC}$ + 0.3V)
Driver Input Voltage (DI)...........................-0.3V to (V$_{CC}$ + 0.3V)
Receiver Input Voltage (A, B (Note 1)) ...............................±80V
Driver Output Voltage (Y, Z (Note 1)) ................................±80V
Receiver Output Voltage (RO)...................-0.3V to (V$_{CC}$ + 0.3V)
Short-Circuit Duration (RO, A, B) ..............................Continuous

Continuous Power Dissipation (T$_A$ = +70°C)
  14-Pin SO (derate 8.3mW/°C above +70°C)...............667mW
Operating Temperature Range ..........................-40°C to +85°C
Junction Temperature......................................................+150°C
Storage Temperature Range .............................-65°C to +150°C
Lead Temperature (soldering, 10s) ................................+300°C

**Note 1:** If the RS-485 transmission lines are unterminated and a short to a voltage V$_{SHT}$ occurs at a remote point on the line, an active local driver (with DI switching) may see higher voltage than V$_{SHT}$ due to inductive kickback at the driver. Terminating the line with a resistor equal to its characteristic impedance minimizes this kickback effect.

*Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

## ELECTRICAL CHARACTERISTICS

(V$_{CC}$ = +3.0 to +5.5V, T$_A$ = T$_{MIN}$ to T$_{MAX}$, unless otherwise noted. Typical values are at V$_{CC}$ = +3.3V and T$_A$ = +25°C.) (Notes 2, 3)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
|---|---|---|---|---|---|---|
| V$_{CC}$ Supply Voltage Range | V$_{CC}$ | | 3.0 | | 5.5 | V |
| Supply Current | I$_Q$ | No load, DE, DI, $\overline{RE}$ = 0V or V$_{CC}$, V$_{CC}$ = 3.3V | | | 15 | mA |
| | | No load, DE, DI, $\overline{RE}$ = 0V or V$_{CC}$, V$_{CC}$ = 5V | | | 15 | |
| Supply Current in Shutdown Mode | I$_{SHDN}$ | DE = GND, $\overline{RE}$ = V$_{CC}$, V$_{CC}$ = 3.3V | | | 100 | µA |
| | | DE = GND, $\overline{RE}$ = V$_{CC}$, V$_{CC}$ = 5V | | | 100 | |
| Supply Current with Output Shorted to ±60V | I$_{SHRT}$ | DE = GND, $\overline{RE}$ = GND, short to +60V | | | 15 | mA |
| | | DE = GND, $\overline{RE}$ = GND, short to -60V | | | 15 | |
| **DRIVER** | | | | | | |
| Differential Driver Output | V$_{OD}$ | R$_L$ = 100Ω, Figure 1 | 2 | | V$_{CC}$ | V |
| | | R$_L$ = 54Ω, Figure 1 | 1.5 | | V$_{CC}$ | |
| Change in Magnitude of Differential Output Voltage | ΔV$_{OD}$ | R$_L$ = 100Ω or 54Ω, Figure 1 (Note 4) | -0.2 | | 0.2 | V |
| Driver Common-Mode Output Voltage | V$_{OC}$ | RL = 100Ω or 54Ω, Figure 1 | | V$_{CC}$/2 | 3 | V |
| Change in Magnitude of Common-Mode Voltage | ΔV$_{OC}$ | RL = 100Ω or 54Ω, Figure 1 (Note 4) | -0.2 | | +0.2 | V |
| Driver Short-Circuit Output Current | I$_{OSD}$ | DI = low, 0V ≤ V$_Y$ or V$_Z$ ≤ +12V | | | +250 | mA |
| | | DI = high, -7V ≤ V$_Y$ or V$_Z$ ≤ V$_{CC}$ (Note 5) | -250 | | | |
| Driver Short-Circuit Foldback Output Current | I$_{OSDF}$ | DI = low, (V$_{CC}$ - 1V) ≤ V$_Y$ or V$_Z$ ≤ +12V | +10 | | | mA |
| | | DI = high, -7V ≤ V$_Y$ or V$_Z$ ≤ +1V | | | -10 | |
| Driver-Limit Short-Circuit Foldback Output Current | I$_{OSDL}$ | V$_Y$ or V$_Z$ ≥ + 22V, R$_L$ = 100Ω | | | +6 | mA |
| | | V$_Y$ or V$_Z$ ≤ -13V, R$_L$ = 100Ω | -6 | | | |
| Driver Input High Voltage | V$_{DIH}$ | | 2 | | | V |
| Driver Input Low Voltage | V$_{DIL}$ | | | | 0.8 | V |
| Driver Input Current | I$_{DIN}$ | | -1 | | +1 | µA |

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## ELECTRICAL CHARACTERISTICS (continued)

($V_{CC}$ = +3.0 to +5.5V, $T_A$ = $T_{MIN}$ to $T_{MAX}$, unless otherwise noted. Typical values are at $V_{CC}$ = +3.3V and $T_A$ = +25°C.) (Notes 2, 3)

| PARAMETER | SYMBOL | CONDITION | | MIN | TYP | MAX | UNITS |
|---|---|---|---|---|---|---|---|
| **RECEIVER** | | | | | | | |
| Input Current | $I_{A, B}$ | $V_A$, $V_B$ = +12V | $V_{CC}$ = GND or $V_{CC}$ = +3.0V to +5.5V | | | +125 | μA |
| | | $V_A$, $V_B$ = -7V | | -100 | | | μA |
| | | $V_A$, $V_B$ = ±80V | | -6 | | +6 | mA |
| Receiver Differential Threshold Voltage | $V_{TH}$ | -7V ≤ $V_{CM}$ ≤ +12V | | -200 | | -50 | mV |
| Receiver Input Hysteresis | $\Delta V_{TH}$ | | | | 25 | | mV |
| Output High Voltage | $V_{OH}$ | $I_{OH}$ = -1.6mA | | $V_{CC}$ - 0.6 | | | V |
| Output Low Voltage | $V_{OL}$ | $I_{OL}$ = 1mA | | | | 0.4 | V |
| Three-State Output Current at Receiver | $I_{OZR}$ | 0 ≤ $V_A$, $V_B$ ≤ $V_{CC}$ | | -1 | | +1 | μA |
| Receiver Output Short-Circuit Current | $I_{OSR}$ | 0 ≤ $V_{RO}$ ≤ $V_{CC}$ | | -95 | | +95 | mA |
| **ESD PROTECTION** | | | | | | | |
| All Pins | | Human Body Model | | | ±2 | | kV |
| ESD Protection Level (A and B, Y and Z) | | Human Body Model | | | ±8 | | kV |
| **CONTROL** | | | | | | | |
| Control Input High Voltage | $V_{CIH}$ | DE, $\overline{RE}$ | | 2 | | | V |
| Control Input Low Voltage | $V_{CIL}$ | DE, $\overline{RE}$ | | | | 0.8 | V |
| Input Current Latch During First Rising Edge | $I_{IN}$ | DE, $\overline{RE}$ | | | 80 | | μA |
| **PROTECTION SPECIFICATIONS** | | | | | | | |
| Overvoltage Protection | | A, B, Y, Z | | -80 | | +80 | V |

## SWITCHING CHARACTERISTICS ($V_{CC}$ = +3.3V ±10%)

($T_A$ = $T_{MIN}$ to $T_{MAX}$, unless otherwise noted. Typical values are at $V_{CC}$ = +3.3V and $T_A$ = +25°C.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
|---|---|---|---|---|---|---|
| **DRIVER** | | | | | | |
| Driver Differential Propagation Delay | $t_{DPLH}$, $t_{DPHL}$ | $R_L$ = 54Ω, $C_L$ = 50pF, Figures 2 and 3 | | 700 | 1500 | ns |
| Driver Differential Output Transition Time | $t_{LH}$, $t_{HL}$ | $R_L$ = 54Ω, $C_L$ = 50pF, Figures 2 and 3 | 250 | | 1200 | ns |
| Differential Driver Output Skew | $t_{DSKEW}$ | $R_L$ = 54Ω, $C_L$ = 50pF, $t_{DSKEW}$ = [$t_{DPLH}$ - $t_{DPHL}$], Figures 2 and 3 | | 150 | 200 | ns |
| Maximum Data Rate | $f_{MAX}$ | | 250 | | | kbps |
| Driver Enable Time to Output High | $t_{DZH}$ | $R_L$ = 500Ω, $C_L$ = 50pF, Figure 4 | | | 2000 | ns |

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## SWITCHING CHARACTERISTICS ($V_{CC}$ = +3.3V ±10%) (continued)

($T_A$ = $T_{MIN}$ to $T_{MAX}$, unless otherwise noted. Typical values are at $V_{CC}$ = +3.3V and $T_A$ = +25°C.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
|---|---|---|---|---|---|---|
| Driver Disable Time from Output High | $t_{DHZ}$ | $R_L$ = 500Ω, $C_L$ = 50pF, Figure 4 | | | 1000 | ns |
| Driver Enable Time from Shutdown to Output High | $t_{DZH(SHDN)}$ | $R_L$ = 500Ω, $C_L$ = 50pF, Figure 4 | | | 8 | μs |
| Driver Enable Time to Output Low | $t_{DZL}$ | $R_L$ = 500Ω, $C_L$ = 50pF, Figure 5 | | | 1500 | ns |
| Driver Disable Time from Output Low | $t_{DLZ}$ | $R_L$ = 500Ω, $C_L$ = 50pF, Figure 5 | | | 2000 | ns |
| Driver Enable Time from Shutdown to Output Low | $t_{DZL(SHDN)}$ | $R_L$ = 500Ω, $C_L$ = 50pF, Figure 5 | | | 8 | μs |
| Driver Time to Shutdown | $t_{SHDN}$ | $R_L$ = 500Ω, $C_L$ = 50pF | | | 12 | μs |
| **RECEIVER** | | | | | | |
| Receiver Propagation Delay | $t_{RPLH}$, $t_{RPHL}$ | $C_L$ = 20pF, $V_{ID}$ = 2V, $V_{CM}$ = 0V, Figure 6 | | | 2000 | ns |
| Receiver Output Skew | $t_{RSKEW}$ | $C_L$ = 20pF, $t_{RSKEW}$ = [$t_{RPLH}$ - $t_{RPHL}$], Figure 6 | | | 200 | ns |
| Receiver Enable Time to Output High | $t_{RZH}$ | $R_L$ = 1kΩ, $C_L$ = 20pF, Figure 7 | | | 1000 | ns |
| Receiver Disable Time from Output High | $t_{RHZ}$ | $R_L$ = 1kΩ, $C_L$ = 20pF, Figure 7 | | | 150 | ns |
| Receiver Wake Time from Shutdown | $t_{RWAKE}$ | $R_L$ = 1kΩ, $C_L$ = 20pF, Figure 7 | | | 5 | μs |
| Receiver Enable Time to Output Low | $t_{RZL}$ | $R_L$ = 1kΩ, $C_L$ = 20pF, Figure 7 | | | 1000 | ns |
| Receiver Disable Time from Output Low | $t_{RLZ}$ | $R_L$ = 1kΩ, $C_L$ = 20pF, Figure 7 | | | 150 | ns |
| Receiver Time to Shutdown | $t_{SHDN}$ | $R_L$ = 500Ω, $C_L$ = 50pF | | | 200 | ns |

## SWITCHING CHARACTERISTICS ($V_{CC}$ = +5V ±10%)

($T_A$ = $T_{MIN}$ to $T_{MAX}$, unless otherwise noted. Typical values are at $V_{CC}$ = +5V and $T_A$ = +25°C.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
|---|---|---|---|---|---|---|
| **DRIVER** | | | | | | |
| Driver Differential Propagation Delay | $t_{DPLH}$, $t_{DPHL}$ | $R_L$ = 54Ω, $C_L$ = 50pF, Figure 3 | | | 800 | ns |
| Driver Differential Output Transition Time | $t_{LH}$, $t_{HL}$ | $R_L$ = 54Ω, $C_L$ = 50pF, Figure 3 | 100 | | 1200 | ns |
| Differential Driver Output Skew | $t_{DSKEW}$ | $R_L$ = 54Ω, $C_L$ = 50pF, $t_{DSKEW}$ = [$t_{DPLH}$ - $t_{DPHL}$], Figure 3 | | | 200 | ns |
| Maximum Data Rate | $f_{MAX}$ | | 500 | | | kbps |

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## SWITCHING CHARACTERISTICS (V_CC = +5V ±10%) (continued)

(T_A = T_MIN to T_MAX, unless otherwise noted. Typical values are at V_CC = +5V and T_A = +25°C.)

| PARAMETER | SYMBOL | CONDITION | MIN | TYP | MAX | UNITS |
|---|---|---|---|---|---|---|
| Driver Enable Time to Output High | t_DZH | R_L = 500Ω, C_L = 50pF, Figure 4 | | | 1500 | ns |
| Driver Disable Time from Output High | t_DHZ | R_L = 500Ω, C_L = 50pF, Figure 4 | | | 1000 | ns |
| Driver Enable Time from Shutdown to Output High | t_DZH(SHDN) | R_L = 500Ω, C_L = 50pF, Figure 4 | | | 8 | µs |
| Driver Enable Time to Output Low | t_DZL | R_L = 500Ω, C_L = 50pF, Figure 5 | | | 1000 | ns |
| Driver Disable Time from Output Low | t_DLZ | R_L = 500Ω, C_L = 50pF, Figure 5 | | | 2 | µs |
| Driver Enable Time from Shutdown to Output Low | t_DZL(SHDN) | R_L = 500Ω, C_L = 50pF, Figure 5 | | | 8 | µs |
| Driver Time to Shutdown | t_SHDN | R_L = 500Ω, C_L = 50pF | | | 12 | µs |
| **RECEIVER** | | | | | | |
| Receiver Propagation Delay | t_RPLH, t_RPHL | C_L = 20pF, V_ID = 2V, V_CM = 0V, Figure 6 | | | 2000 | ns |
| Receiver Output Skew | t_RSKEW | C_L = 20pF, t_RSKEW = [t_RPLH - t_RPHL], Figure 6 | | | 200 | ns |
| Receiver Enable Time to Output High | t_RZH | R_L = 1kΩ, C_L = 20pF, Figure 7 | | | 1000 | ns |
| Receiver Disable Time from Output High | t_RHZ | R_L = 1kΩ, C_L = 20pF, Figure 7 | | | 150 | ns |
| Receiver Wake Time from Shutdown | t_RWAKE | R_L = 1kΩ, C_L = 20pF, Figure 7 | | | 8 | µs |
| Receiver Enable Time to Output Low | t_RZL | R_L = 1kΩ, C_L = 20pF, Figure 7 | | | 1000 | ns |
| Receiver Disable Time from Output Low | t_RLZ | R_L = 1kΩ, C_L = 20pF, Figure 7 | | | 150 | ns |
| Receiver Time to Shutdown | t_SHDN | R_L = 500Ω, C_L = 50pF | | | 150 | ns |

**Note 2:** Parameters are 100% production tested at T_A = +25°C, unless otherwise noted. Limits over temperature are guaranteed by design.

**Note 3:** All currents into the device are positive. All currents out of the device are negative. All voltages are referenced to device ground, unless otherwise noted.
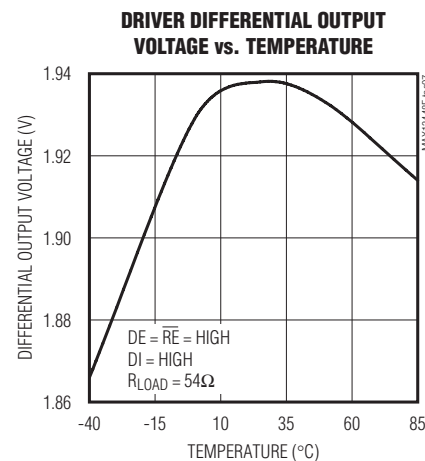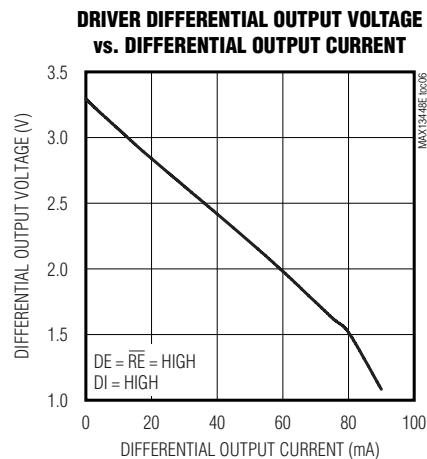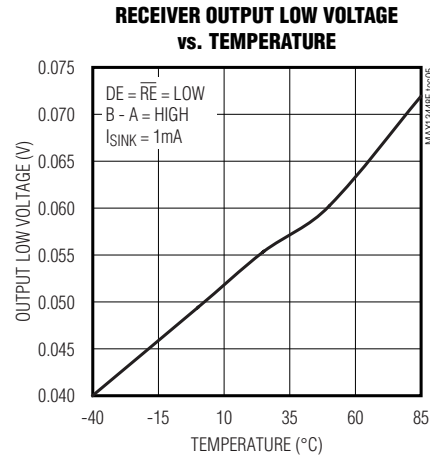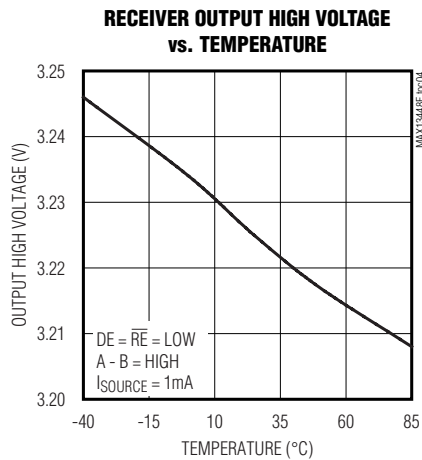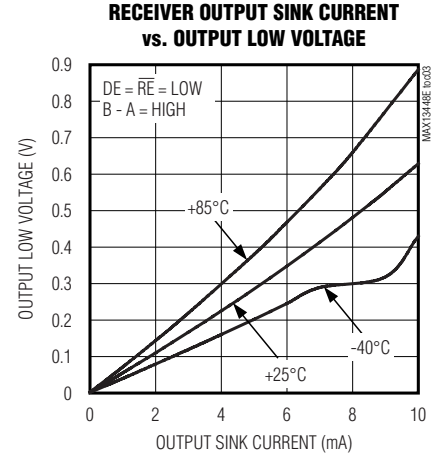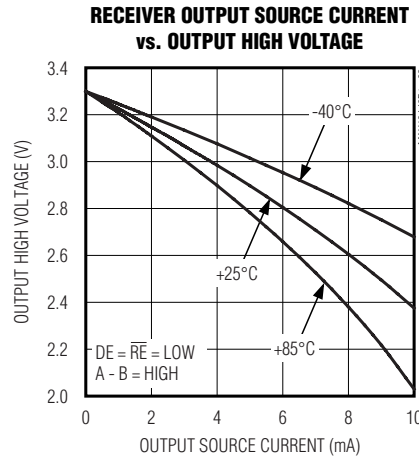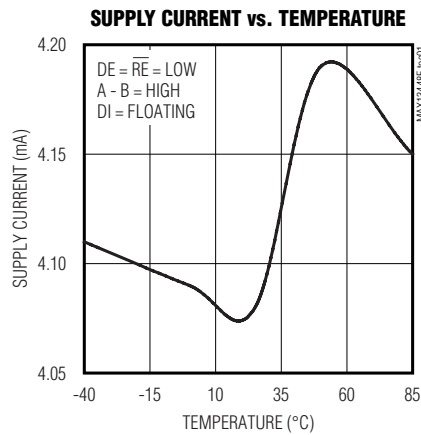
**Note 4:** ΔV_OD and ΔV_OC are the changes in V_OD and V_OC, respectively, when the DI input changes state.

**Note 5:** The short-circuit output current applies to peak current just prior to foldback current limiting. The short-circuit foldback output current applies during current limiting to allow a recover from bus contention.
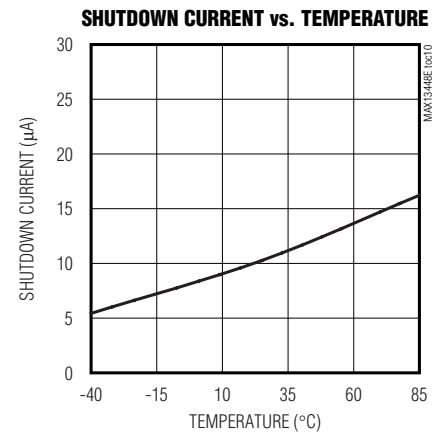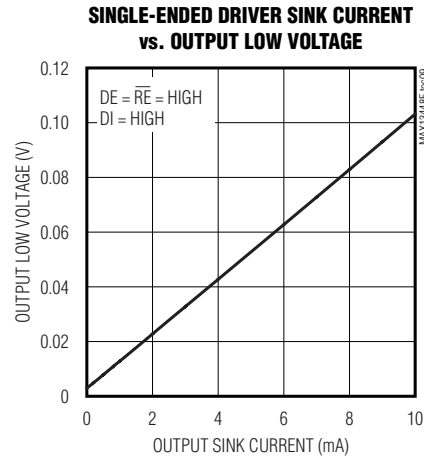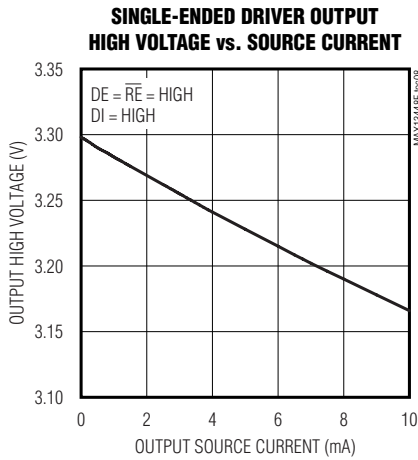
# ±80V Fault-Protected Full-Duplex RS-485 Transceiver

*MAX13448E*

(V_CC = +3.3V, T_A = +25°C, unless otherwise noted.)

**SUPPLY CURRENT vs. TEMPERATURE**

DE = RE̅ = LOW
A - B = HIGH
DI = FLOATING

**RECEIVER OUTPUT SOURCE CURRENT vs. OUTPUT HIGH VOLTAGE**

-40°C
+25°C
+85°C
DE = RE̅ = LOW
A - B = HIGH

**RECEIVER OUTPUT SINK CURRENT vs. OUTPUT LOW VOLTAGE**

DE = RE̅ = LOW
B - A = HIGH
+85°C
-40°C
+25°C

**RECEIVER OUTPUT HIGH VOLTAGE vs. TEMPERATURE**

DE = RE̅ = LOW
A - B = HIGH
I_SOURCE = 1mA

**RECEIVER OUTPUT LOW VOLTAGE vs. TEMPERATURE**

DE = RE̅ = LOW
B - A = HIGH
I_SINK = 1mA

**DRIVER DIFFERENTIAL OUTPUT VOLTAGE vs. DIFFERENTIAL OUTPUT CURRENT**

DE = RE̅ = HIGH
DI = HIGH

**DRIVER DIFFERENTIAL OUTPUT VOLTAGE vs. TEMPERATURE**

DE = RE̅ = HIGH
DI = HIGH
R_LOAD = 54Ω

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**MAX13448E**

($V_{CC}$ = +3.3V, $T_A$ = +25°C, unless otherwise noted.)

**SINGLE-ENDED DRIVER OUTPUT HIGH VOLTAGE vs. SOURCE CURRENT**

DE = $\overline{RE}$ = HIGH
DI = HIGH

**SINGLE-ENDED DRIVER SINK CURRENT vs. OUTPUT LOW VOLTAGE**

DE = $\overline{RE}$ = HIGH
DI = HIGH

**SHUTDOWN CURRENT vs. TEMPERATURE**

**DRIVER PROPAGATION DELAY (500kbsp)**

2V/div

1V/div

400ns

**RECEIVER PROPAGATION DELAY (500kbsp)**

1V/div

2V/div

400ns

**DRIVER PROPAGATION DELAY vs. TEMPERATURE**

$t_{DPLH}$

$t_{DPHL}$

DE = $\overline{RE}$ = HIGH
$R_{LOAD}$ = 54Ω
$C_{LOAD}$ = 50pF

**RECEIVER PROPAGATION DELAY vs. TEMPERATURE**

DE = $\overline{RE}$ = LOW
$C_{LOAD}$ = 20pF

$t_{RPLH}$

$t_{RPHL}$
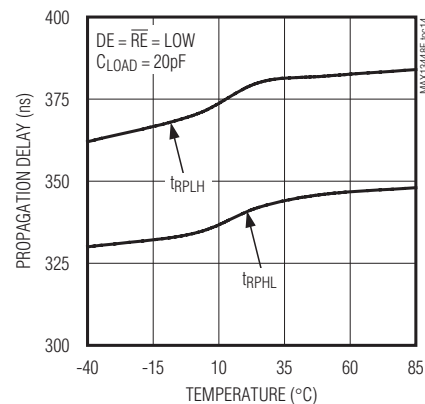
# ±80V Fault-Protected Full-Duplex RS-485 Transceiver

| PIN | NAME | FUNCTION |
|---|---|---|
| 1, 8, 13 | N.C. | No Connection. Not internally connected. Connect N.C. to GND or leave it unconnected. |
| 2 | RO | Receiver Output. If receiver is enabled and (A - B) ≥ -50mV, RO = high; if (A - B) ≥ -200mV, RO = low. |
| 3 | $\overline{RE}$ | Receiver Output Enable. Drive $\overline{RE}$ low to enable RO; RO is high impedance when $\overline{RE}$ is high. Drive $\overline{RE}$ high and DE low to enter low-power shutdown mode. |
| 4 | DE | Driver Output Enable. Drive DE high to enable the driver outputs. Drive DE low to put the outputs in high impedance. Drive $\overline{RE}$ high and DE low to enter low-power shutdown mode. |
| 5 | DI | Driver Input. Drive DI low to force the noninverting output low and the inverting output high. Drive DI high to force the noninverting output high and the inverting output low. |
| 6, 7 | GND | Ground |
| 9 | Y | Noninverting Driver Output |
| 10 | Z | Inverting Driver Output |
| 11 | B | Inverting Receiver Input |
| 12 | A | Noninverting Receiver Input |
| 14 | $V_{CC}$ | Positive Supply. $V_{CC}$ = +3.0V to +5.5V. Bypass $V_{CC}$ to GND with a 1µF ceramic capacitor as close to $V_{CC}$ as possible. Typical $V_{CC}$ values are at $V_{CC}$ = +3.3V and $V_{CC}$ = +5.0V. |
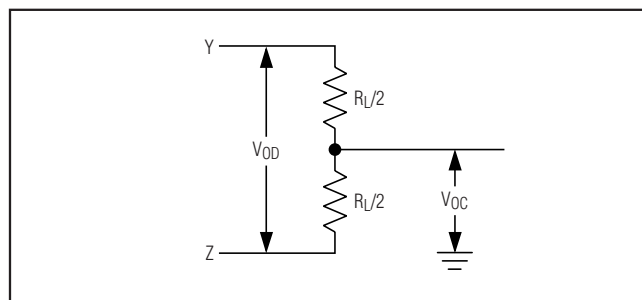


Figure 1. Driver DC Test Load
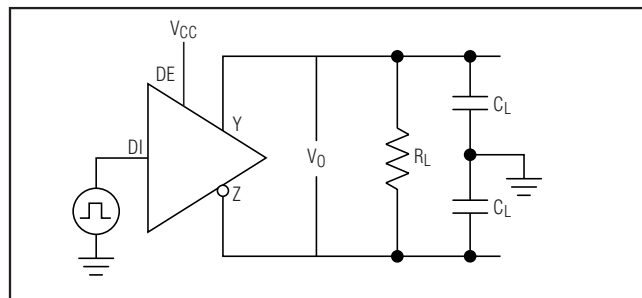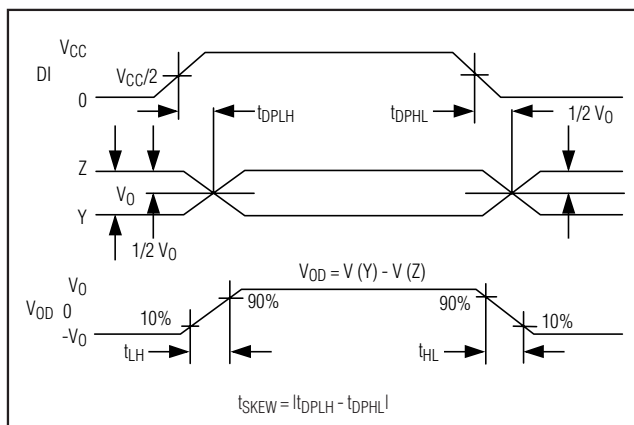


Figure 2. Driver Timing Test Circuit
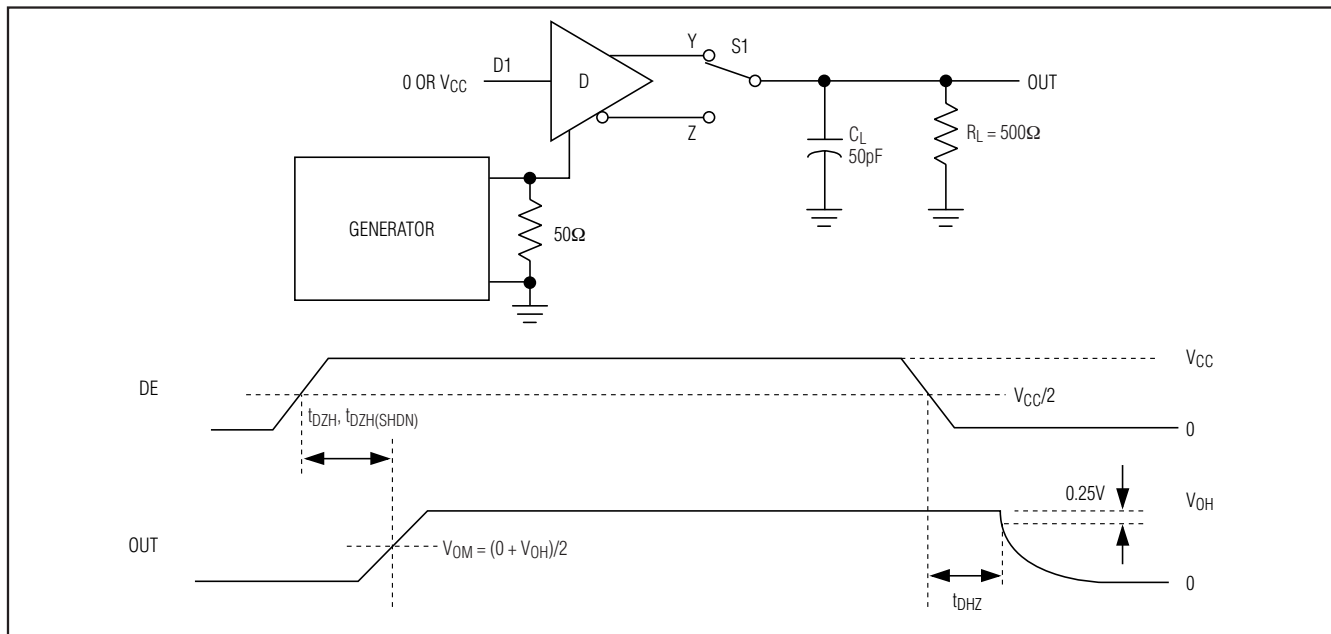


Figure 3. Driver Propagation Delays

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*Figure 4. Driver Enable and Disable Times ($t_{DHZ}$, $t_{DZH}$, $t_{DZH(SHDN)}$)*
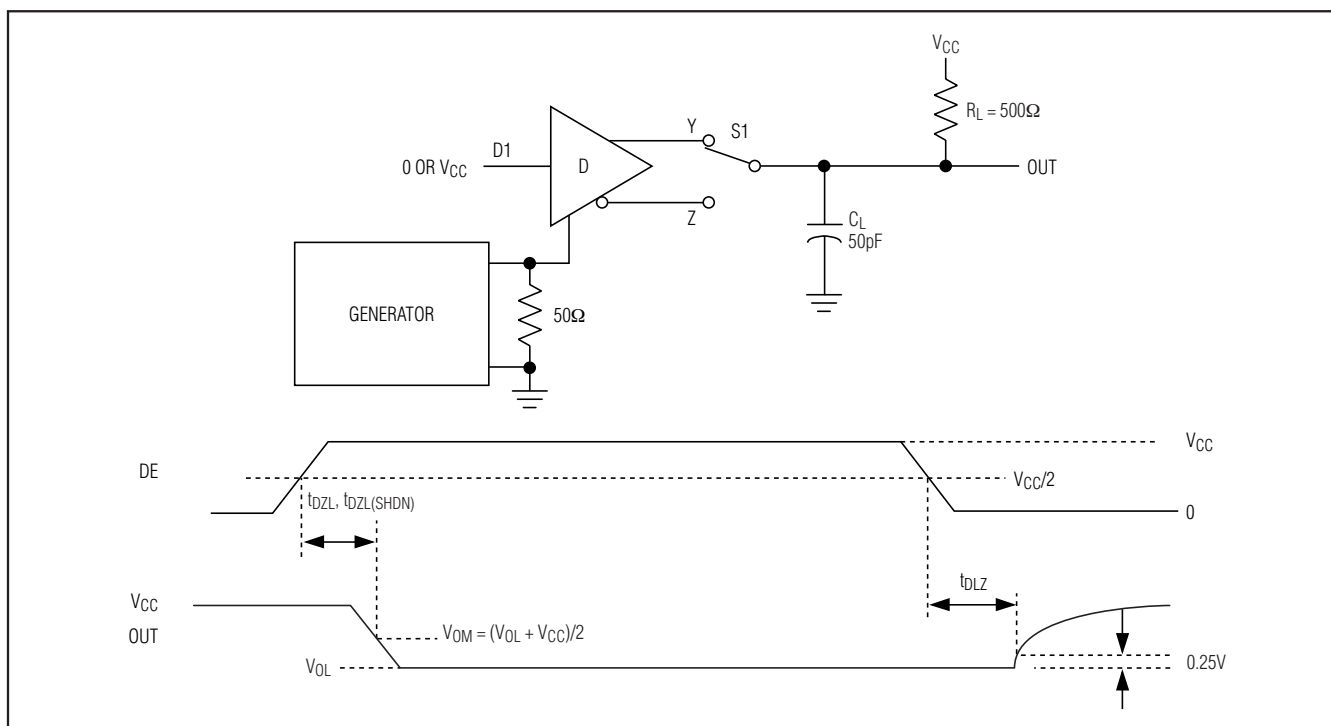


*Figure 5. Driver Enable and Disable Times ($t_{DLZ}$, $t_{DZL}$, $t_{DZL(SHDN)}$)*

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# ±80V Fault-Protected Full-Duplex RS-485 Transceiver
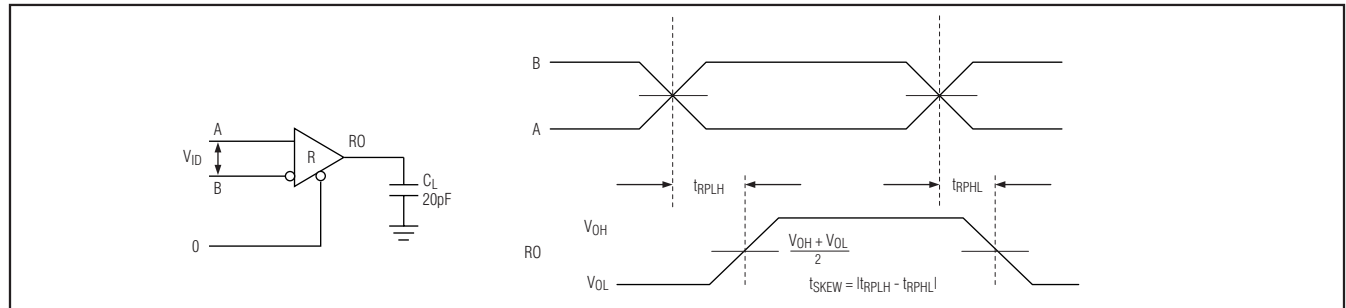


Figure 6. Receiver Propagation Delays
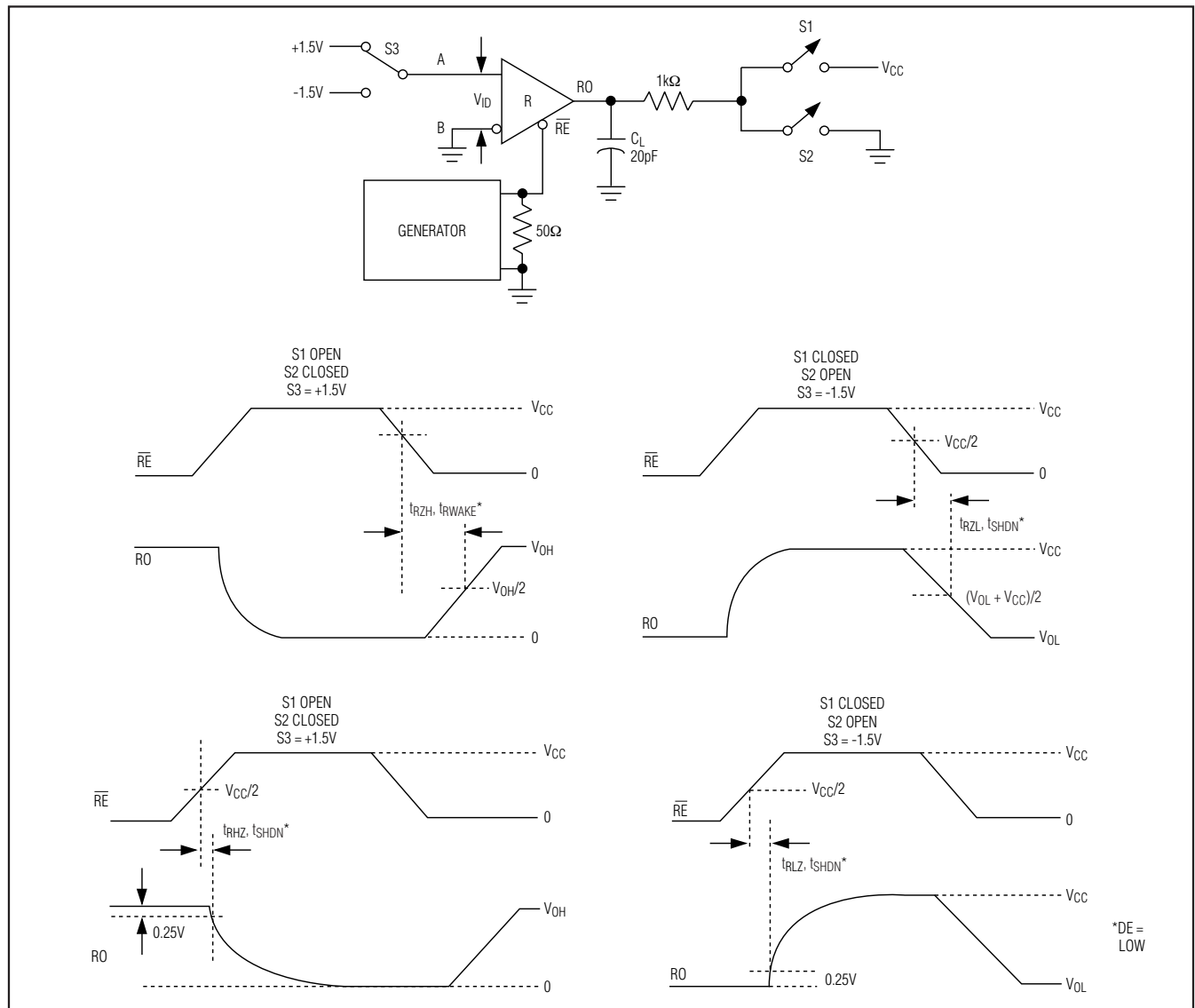


Figure 7. Receiver Enable and Disable Times

## Detailed Description

The MAX13448E ±80V fault-protected RS-485/RS-422 transceiver contains one driver and one receiver. This device features fail-safe circuitry, guaranteeing a logic-high receiver output when the receiver inputs are open or shorted, or when they are connected to a terminated transmission line with all drivers disabled. The device has a hot-swap input structure that prevents disturbances on the differential signal lines when a circuit board is plugged into a hot backplane. All receiver inputs and driver outputs are protected to ±8kV ESD using the Human Body Model. The MAX13448E features a reduced slew-rate driver that minimizes EMI and reduces reflections caused by improperly terminated cables, allowing error-free data transmission up to 500kbps.

### Driver

The driver accepts a single-ended, logic-level input (DI) and converts it to a differential, RS-485/RS-422 level output (A and B). Deasserting the driver enable places the driver outputs (A and B) into a high-impedance state.

### Receiver

The receiver accepts a differential, RS-485/RS-422 level input (A and B), and translates it to a single-ended, logic-level output (RO). Deasserting the receiver enable places the receiver outputs (RO) into a high-impedance state (see Table 1).

### Low-Power Shutdown

Low-power shutdown is initiated by bringing DE low and RE high. In shutdown, the device draws a maximum of 100µA of supply current.

The device is guaranteed to not enter shutdown if DE is low and RE is high for 1µs. If the inputs are in this state for at least 1ms, the device is guaranteed to enter shutdown. In the shutdown state, the driver outputs (A and B) as well as the receiver output (RO) are in a high-impedance state.

### ±80V Fault Protection

In certain applications, such as industrial control, driver outputs and receiver inputs of an RS-485 device sometimes experience common-mode voltages in excess of the -7V to +12V range specified in the EIA/TIA-485 standard. In these applications, ordinary RS-485 devices (typical absolute maximum ratings of -8V to +12.5V) may experience damage without the addition of external protection devices.

### Table 1. Function Table

| TRANSMITTING | | | | |
|---|---|---|---|---|
| INPUT | | | OUTPUT | |
| $\overline{RE}$ | DE | DI | Z | Y |
| X | 1 | 0 | 1 | 0 |
| X | 1 | 1 | 0 | 1 |
| 0 | 0 | X | High Impedance | High Impedance |
| 1 | 0 | X | High Impedance (Shutdown) | |
| RECEIVING | | | | |
| INPUT | | | OUTPUT | |
| $\overline{RE}$ | DE | A - B | RO | |
| 0 | X | -50mV | 1 | |
| 0 | X | -200mV | 0 | |
| 1 | 1 | X | Disabled | |
| 1 | 0 | X | High Impedance (Shutdown) | |

*X = Don't care; shutdown mode, driver, and receiver outputs are high impedance.*

To reduce system complexity and the need for external protection, the driver outputs and receiver inputs of the MAX13448E withstand voltage faults of up to ±80V with respect to ground without damage (see the *Absolute Maximum Ratings* section, Note 1). Protection is guaranteed regardless of whether the device is active, in shutdown, or without power. Certain parasitic effects present while driving an unterminated cable may cause the voltage seen at driver outputs to exceed the absolute maximum limit, while the DI input is switched during a ±80V fault on the A or B input. Therefore, a termination resistor is recommend in order to maximize the overvoltage fault protection while the DI input is being switched. If the DI input does not change state while the fault voltage is present, the MAX13448E will withstand up the ±80V on the RS-485 inputs, regardless of the presence of a termination resistor. While the MAX13448E is not damaged by up to ±80V common-mode voltages, the RO, Y, and Z outputs will be in an indeterminate state if the common-mode voltage exceeds -7V to +12V.

### True Fail-Safe

The MAX13448E guarantees a logic-high receiver output when the receiver inputs are shorted or open, or when they are connected to a terminated transmission line with all drivers disabled. This is done by setting the
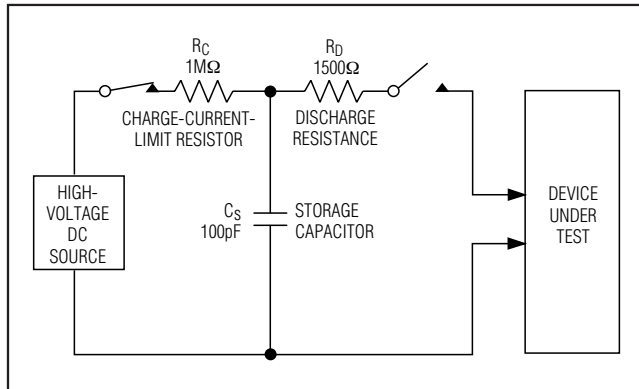
**MAX13448E**



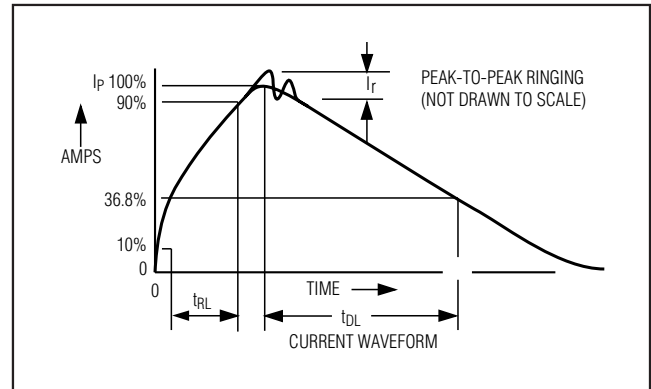Figure 8a. Human Body ESD Test Model



Figure 8b. Human Body Current Waveform

receiver threshold between -50mV and -200mV. If the differential receiver input voltage (A - B) is greater than or equal to -50mV, RO is logic-high. If A - B is less than or equal to -200mV, RO is logic-low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to 0V by the termination. With the receiver thresholds of the MAX13448E, this results in a logic-high with a 50mV minimum noise margin. The -50mV to -200mV threshold complies with the ±200mV EIA/TIA-485 standard.

## ±8kV ESD Protection
As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs of the MAX13448E have extra protection against static electricity. Maxim's engineers have developed state-of-the-art structures to protect these pins against ESD of ±8kV without damage. The ESD structures withstand high ESD in all states: normal operation, shutdown, and powered down. After an ESD event, the MAX13448E keeps working without latchup or damage. ESD protection can be tested in various ways. The transmitter outputs and receiver inputs of the MAX13448E are characterized for protection to the following limits:

• ±8kV using the Human Body Model

### ESD Test Conditions
ESD performance depends on a variety of conditions. Contact Maxim for a reliability report that documents test setup, test methodology, and test results.

### Human Body Model
Figure 8a shows the Human Body Model, and Figure 8b shows the current waveform it generates when discharged into a low impedance. This model consists of a

100pF capacitor charged to the ESD voltage of interest, which is then discharged into the test device through a 1.5kΩ resistor.

## Driver Output Protection
Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. The first, a foldback current limit on the output stage, provides immediate protection against short circuits over the whole common-mode voltage range (see the *Typical Operating Characteristics*). The second, a thermal-shutdown circuit, forces the driver outputs into a high-impedance state if the die temperature exceeds +160°C (typ).

## Hot-Swap Capability

### Hot-Swap Inputs
When circuit boards are inserted into a powered backplane, disturbances to the data bus can lead to data errors. Upon initial circuit-board insertion, the data communication processor undergoes its own power-up sequence. During this period, the processor's logic-output drivers are high impedance and are unable to drive the DE input of the device to a defined logic level. Leakage currents up to ±10µA from the high-impedance state of the processor's logic drivers could cause standard CMOS enable inputs of a transceiver to drift to an incorrect logic level. Additionally, parasitic circuit-board capacitance could cause coupling of $V_{CC}$ or GND to the enable inputs. Without the hot-swap capability, these factors could improperly enable the transceiver's driver or receiver.

When $V_{CC}$ rises, an internal pulldown circuit holds DE low. After the initial power-up sequence, the pulldown circuit becomes transparent, resetting the hot-swap tolerable input.
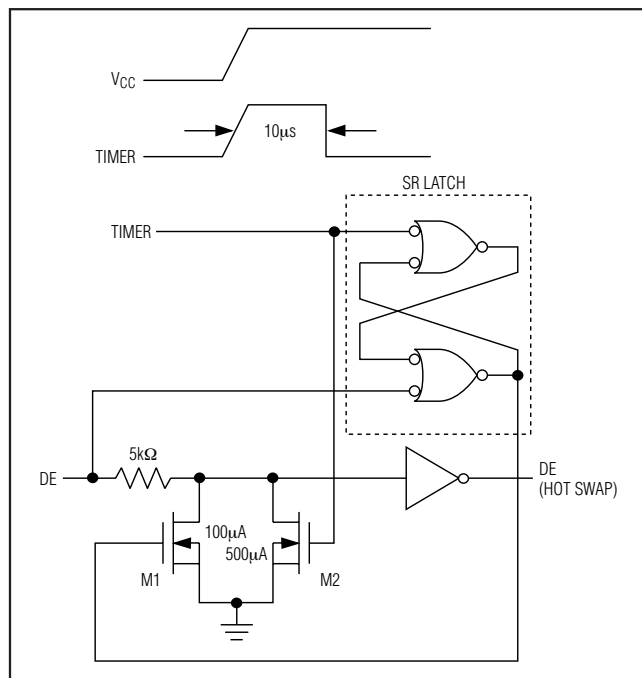
***MAXIM***

Figure 9. Simplified Structure of the Driver Enable Pin (DE)

### Hot-Swap Input Circuitry

The enable inputs feature hot-swap capability. At the input there are two NMOS devices, M1 and M2 (Figure 9). When $V_{CC}$ ramps from zero, an internal 7μs timer turns on M2 and sets the SR latch that also turns on M1. Transistor M2, a 1.5mA current sink, and M1, a 100μA current sink, pull DE to GND through a 5kΩ resistor. M2 is designed to pull DE to the disabled state against an external parasitic capacitance up to 100pF that can drive DE high. After 7μs, the timer deactivates M2 while M1 remains on, holding DE low against three-state leakages that can drive DE high. M1 remains on until an external source overcomes the required input current. At this time, the SR latch resets and M1 turns off. When M1 turns off, DE reverts to a standard, high-impedance CMOS input.

## Applications Information

### 256 Transceivers on the Bus

The RS-485 standard specifies the load each receiver places on the bus in terms of unit loads. An RS-485 compliant transmitter can drive 32 one-unit loads when used with a 120Ω cable that is terminated on both ends over a common-mode range of -7V to +12V. The

MAX13448E is specified as 1/8 unit loads. This means a compliant transmitter can drive up to 256 MAX13448E devices. Reducing the common mode and/or changing the characteristic impedance of the cable changes the maximum number of receivers that can be used. Refer to the TIA/EIA-485 specification for further details.

### Proper Termination and Cabling/Wiring Configurations

When the data rates for RS-485 are high relative to its cable lengths, the system is subject to proper transmission line design. In most cases, a single, controlled-impedance cable or trace should be used and should be properly terminated on both ends with the characteristic impedance of the cable/trace. RS-485 transceivers should be connected to the cable/traces with minimum length wires to prevent stubs. Star configurations and improperly terminated cables can cause data loss. Refer to the *Applications* section of the Maxim website or to TIA/EIA publication TSB89 for further information.

### Reduced EMI and Reflections

The MAX13448E features reduced slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free data transmission up to 500kbps.

### Line Length

The Telecommunications Industry Association (TIA) publishes the document TSB-89: *Application Guidelines for TIA/EIA-485-A* that is a good reference for determining maximum data rate vs. line length.

### Typical Applications

The MAX13448E transceivers are designed for bidirectional data communications on multipoint bus transmission lines. Figure 10 shows a typical network application circuit. To minimize reflections, terminate the line at both ends in its characteristic impedance, and keep stub lengths off the main line as short as possible.

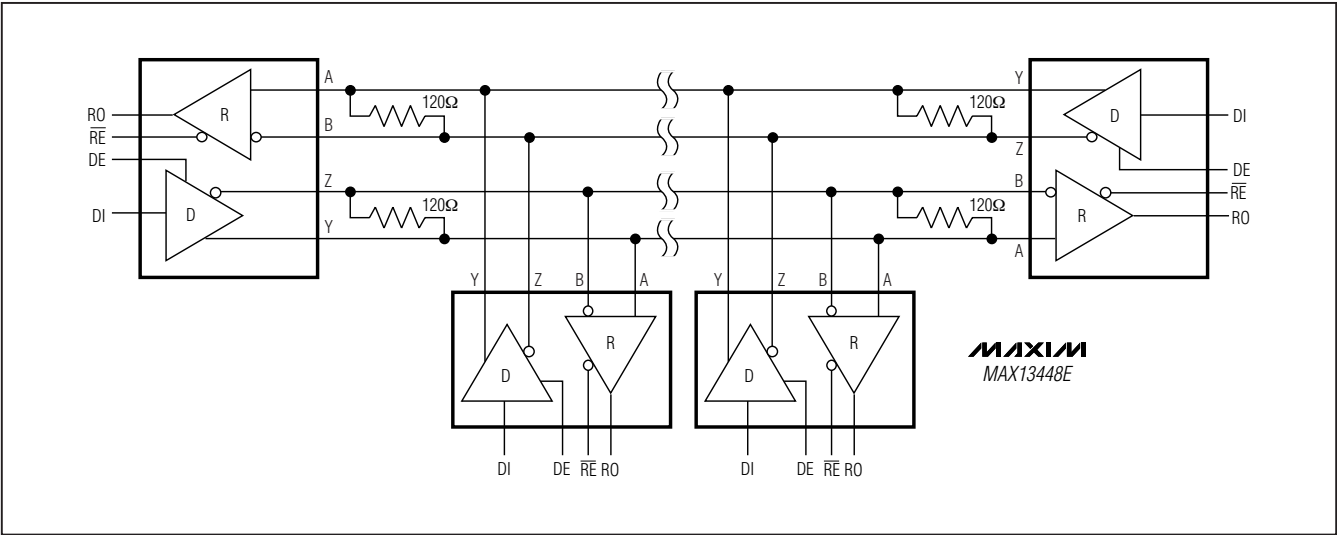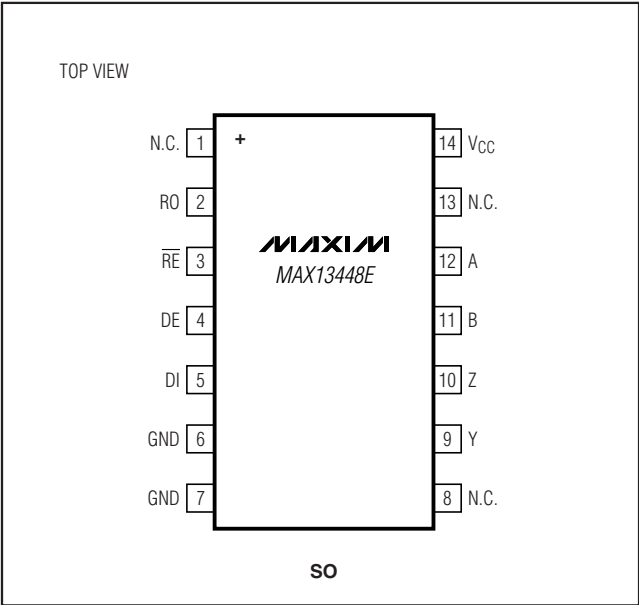# ±80V Fault-Protected Full-Duplex RS-485 Transceiver

Figure 10. Typical Full-Duplex RS-485 Network

## Pin Configuration



## Chip Information

PROCESS: BiCMOS

## Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**.

| PACKAGE TYPE | PACKAGE CODE | DOCUMENT NO. |
|---|---|---|
| 14 SO | S14-5 | **21-0041** |

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