

### **DS92LV010A** Bus LVDS 3.3/5.0V Single Transceiver

### **General Description**

The DS92LV010A is one in a series of transceivers designed specifically for the high speed, low power proprietary bus backplane interfaces. The device operates from a single 3.3V or 5.0V power supply and includes one differential line driver and one receiver. To minimize bus loading the driver outputs and receiver inputs are internally connected. The logic interface provides maximum flexibility as 4 separate lines are provided (DIN, DE, RE, and ROUT). The device also features flow through which allows easy PCB routing for short stubs between the bus pins and the connector. The driver has 10 mA drive capability, allowing it to drive heavily loaded backplanes, with impedance as low as 27 Ohms.

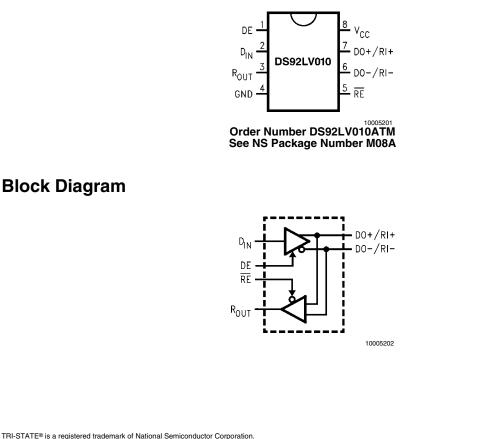
The driver translates between TTL levels (single-ended) to Low Voltage Differential Signaling levels. This allows for high speed operation, while consuming minimal power with reduced EMI. In addition the differential signaling provides common mode noise rejection of ±1V.

The receiver threshold is ±100mV over a ±1V common mode range and translates the low voltage differential levels to standard (CMOS/TTL) levels.

### Features

- Bus LVDS Signaling (BLVDS)
- **Designed for Double Termination Applications**
- **Balanced Output Impedance**
- Lite Bus Loading 5pF typical
- Glitch free power up/down (Driver disabled)
- 3.3V or 5.0V Operation
- ±1V Common Mode Range
- ±100mV Receiver Sensitivity
- High Signaling Rate Capability (above 100 Mbps)
- Low Power CMOS design
- Product offered in 8 lead SOIC package
- Industrial Temperature Range Operation





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### Absolute Maximum Ratings (Notes 1, 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (V <sub>CC</sub> )	6.0V
Enable Input Voltage (DE, RE)	–0.3V to (V <sub>CC</sub> + 0.3V)
Driver Input Voltage (DIN)	–0.3V to (V <sub>CC</sub> + 0.3V)
Receiver Output Voltage (R <sub>OUT</sub> ) Bus Pin Voltage (DO/RI±) Driver Short Circuit Current ESD (HBM 1.5 kΩ, 100 pF)	-0.3V to (V <sub>CC</sub> + 0.3V) -0.3V to + 3.9V Continuous >2.0 kV
Maximum Package Power D	issipation at 25°C
SOIC	1025 mW

Derate SOIC Package	8.2 mW/°C
Junction Temperature	+150°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature	
(Soldering, 4 sec.)	260°C

# Recommended Operating Conditions

	Min	Max	Units
Supply Voltage (V <sub>CC</sub> ), or	3.0	3.6	V
Supply Voltage (V <sub>CC</sub> )	4.5	5.5	V
Receiver Input Voltage	0.0	2.9	V
Operating Free Air	-40	+85	°C
Temperature			

### 3.3V DC Electrical Characteristics (Notes 2, 3)

 $T_{A}$  =  $-40^{\circ}C$  to  $+85^{\circ}C$  unless otherwise noted,  $V_{CC}$  = 3.3V  $\pm$  0.3V

Symbol	Parameter	Conditions		Pin	Min	Тур	Max	Units
V <sub>OD</sub>	Output Differential Voltage	R <sub>L</sub> = 27Ω, <i>Figure 1</i>		DO+/RI+,	140	250	360	mV
ΔV <sub>OD</sub>	V <sub>OD</sub> Magnitude Change					3	30	mV
V <sub>os</sub>	Offset Voltage	_			1	1.25	1.65	V
ΔV <sub>OS</sub>	Offset Magnitude Change	7				5	50	mV
I <sub>OSD</sub>	Output Short Circuit Current	$V_0 = 0V, DE = V_{CC}$		1		-12	-20	mA
V <sub>OH</sub>	Voltage Output High	V <sub>ID</sub> = +100 mV	Ι <sub>OH</sub> = -400 μA	R <sub>OUT</sub>	2.8	3		V
		Inputs Open			2.8	3		V
		Inputs Shorted	1		2.8	3		V
		Inputs Terminated, $R_L = 27\Omega$			2.8	3		V
V <sub>OL</sub>	Voltage Output Low	I <sub>OL</sub> = 2.0 mA, V <sub>ID</sub> = -100 mV				0.1	0.4	V
I <sub>os</sub>	Output Short Circuit Current	$V_{OUT} = 0V, V_{ID} = +100 \text{ mV}$		1	-5	-35	-85	mA
V <sub>TH</sub>	Input Threshold High	DE = 0V		DO+/RI+,			+100	mV
V <sub>TL</sub>	Input Threshold Low			DO-/RI-	-100			mV
I <sub>IN</sub>	Input Current	$DE = 0V, V_{IN} = +2.4V, \text{ or } 0V$		1	-20	±1	+20	μA
		$V_{CC} = 0V, V_{IN} = +2.4V, \text{ or } 0V$		1	-20	±1	+20	μA
V <sub>IH</sub>	Minimum Input High Voltage			DIN, DE,	2.0		V <sub>cc</sub>	V
V <sub>IL</sub>	Maximum Input Low Voltage			RE	GND		0.8	V
I <sub>IH</sub>	Input High Current	$V_{IN} = V_{CC}$ or 2.4V				±1	±10	μA
I <sub>IL</sub>	Input Low Current	V <sub>IN</sub> = GND or 0.4V		1		±1	±10	μA
V <sub>CL</sub>	Input Diode Clamp Voltage	I <sub>CLAMP</sub> = -18 mA		1	-1.5	-0.8		V
I <sub>CCD</sub>	Power Supply Current	$DE = \overline{RE} = V_{CC}, R_L = 27\Omega$		V <sub>cc</sub>		13	20	mA
I <sub>CCR</sub>		$DE = \overline{RE} = 0V$		-		5	8	mA
I <sub>CCZ</sub>	1	$\overline{DE} = 0V, \overline{RE} = V_{CC}$		1		3	7.5	mA
I <sub>CC</sub>	1	$\overline{DE} = V_{CC},  \overline{RE} = 0V,  R_{L} = 27\Omega$		1		16	22	mA
C <sub>output</sub>	Capacitance @ BUS Pins			DO+/RI+, DO-/RI-		5		pF

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### **5V DC Electrical Characteristics** (Notes 2, 3) $T_{A} = -40^{\circ}$ C to +85°C unless otherwise noted, $V_{CC} = 5.0V \pm 0.5V$

Symbol	Parameter	Conditions		Pin	Min	Тур	Max	Units
V <sub>OD</sub>	Output Differential Voltage	$R_{L} = 27\Omega$ , Figure 1		DO+/RI+,	145	270	390	mV
ΔV <sub>OD</sub>	V <sub>OD</sub> Magnitude Change			DO-/RI-		3	30	mV
V <sub>os</sub>	Offset Voltage	1			1	1.35	1.65	V
ΔV <sub>OS</sub>	Offset Magnitude Change					5	50	mV
I <sub>OSD</sub>	Output Short Circuit Current	$V_0 = 0V, DE = V_{CC}$				-12	-20	mA
V <sub>OH</sub>	Voltage Output High	V <sub>ID</sub> = +100 mV	I <sub>OH</sub> = -400 μA	R <sub>OUT</sub>	4.3	5.0		V
		Inputs Open			4.3	5.0		V
		Inputs Shorted	-		4.3	5.0		V
		Inputs Terminated, $R_L = 27\Omega$	_		4.3	5.0		V
V <sub>OL</sub>	Voltage Output Low	$I_{OL} = 2.0 \text{ mA}, V_{ID} = -100 \text{ mV}$	•			0.1	0.4	V
I <sub>OS</sub>	Output Short Circuit Current	$V_{OUT} = 0V, V_{ID} = +100 \text{ mV}$		7	-35	-90	-130	mA
V <sub>TH</sub>	Input Threshold High	DE = 0V		DO+/RI+,			+100	mV
V <sub>TL</sub>	Input Threshold Low			DO-/RI-	-100			mV
I <sub>IN</sub>	Input Current	$DE = 0V, V_{IN} = +2.4V, \text{ or } 0V$			-20	±1	+20	μA
		$V_{\rm CC} = 0V, V_{\rm IN} = +2.4V, \text{ or } 0V$			-20	±1	+20	μA
V <sub>IH</sub>	Minimum Input High Voltage			DIN, DE,	2.0		V <sub>CC</sub>	V
V <sub>IL</sub>	Maximum Input Low Voltage			RE	GND		0.8	V
I <sub>IH</sub>	Input High Current	$V_{IN} = V_{CC} \text{ or } 2.4 \text{V}$				±1	±10	μA
I <sub>IL</sub>	Input Low Current	V <sub>IN</sub> = GND or 0.4V				±1	±10	μA
V <sub>CL</sub>	Input Diode Clamp Voltage	$I_{CLAMP} = -18 \text{ mA}$			-1.5	-0.8		V
I <sub>CCD</sub>	Power Supply Current	$DE = \overline{RE} = V_{CC}, R_L = 27\Omega$		V <sub>cc</sub>		17	25	mA
I <sub>CCR</sub>		$DE = \overline{RE} = 0V$				6	10	mA
I <sub>CCZ</sub>		$DE = 0V, \overline{RE} = V_{CC}$		1		3	8	mA
I <sub>CC</sub>	1	$DE = V_{CC}, \overline{RE} = 0V, R_L = 27\Omega$				20	25	mA
Coutput	Capacitance @ BUS Pins			DO+/RI+, DO-/RI-		5		pF

Note 1: "Absolute Maximum Ratings" are these beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the device should be operated at these limits. The table of "Electrical Characteristics" provides conditions for actual device operation.

Note 2: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground except  $V_{OD}$ ,  $V_{ID}$ ,  $V_{TH}$  and  $V_{TL}$  unless otherwise specified.

Note 3: All typicals are given for V\_{CC} = +3.3V or 5.0 V and T\_A = +25 °C, unless otherwise stated.

**Note 4:** ESD Rating: HBM (1.5 k $\Omega$ , 100 pF) > 2.0 kV EAT (0 $\Omega$ , 200 pF) > 300V.

Note 5:  $C_L$  includes probe and fixture capacitance.

**Note 6:** Generator waveforms for all tests unless otherwise specified: f = 1MHz,  $ZO = 50\Omega$ , tr,  $tf \le 6.0ns (0\%-100\%)$  on control pins and  $\le 1.0ns$  for RI inputs. **Note 7:** The DS92LV010A is a current mode device and only function with datasheet specification when a resistive load is applied between the driver outputs. **Note 8:** For receiver TRI-STATE® delays, the switch is set to V<sub>CC</sub> for t<sub>PZL</sub>, and t<sub>PLZ</sub> and to GND for t<sub>PZL</sub>, and t<sub>PLZ</sub>.

### 3.3V AC Electrical Characteristics (Note 6)

<b>T</b> (000)			
$T_A = -40^{\circ}C$ to	+85°C, V	/ <sub>CC</sub> = 3.3V	± 0.3V

Symbol	Parameter	Conditions	Min	Тур	Max	Units	
DIFFEREN	DIFFERENTIAL DRIVER TIMING REQUIREMENTS						
t <sub>PHLD</sub>	Differential Prop. Delay High to Low	R <sub>L</sub> = 27Ω, <i>Figures 2</i> , <i>3</i>	1.0	3.0	5.0	ns	
t <sub>PLHD</sub>	Differential Prop. Delay Low to High	C <sub>L</sub> = 10 pF	1.0	2.8	5.0	ns	
t <sub>SKD</sub>	Differential SKEW It <sub>PHLD</sub> - t <sub>PLHD</sub> I			0.2	1.0	ns	
t <sub>TLH</sub>	Transition Time Low to High			0.3	2.0	ns	
t <sub>THL</sub>	Transition Time High to Low			0.3	2.0	ns	

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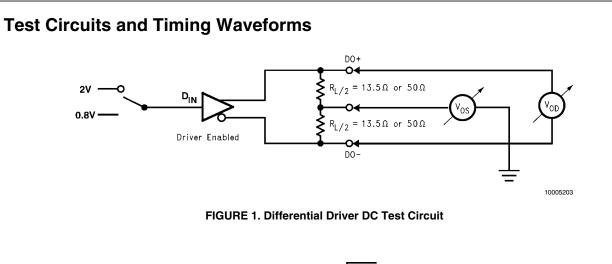
Symbol	Parameter	Conditions	Min	Тур	Max	Units
t <sub>PHZ</sub>	Disable Time High to Z	R <sub>L</sub> = 27Ω, <i>Figures 4</i> , <i>5</i>	0.5	4.5	9.0	ns
t <sub>PLZ</sub>	Disable Time Low to Z	C <sub>L</sub> = 10 pF	0.5	5.0	10.0	ns
t <sub>PZH</sub>	Enable Time Z to High		2.0	5.0	7.0	ns
t <sub>PZL</sub>	Enable Time Z to Low		1.0	4.5	9.0	ns
DIFFEREN	TIAL RECEIVER TIMING REQUIREME	NTS	<u>.</u>	•	•	•
t <sub>PHLD</sub>	Differential Prop. Delay High to Low	Figures 6, 7	2.5	5.0	12.0	ns
t <sub>PLHD</sub>	Differential Prop. Delay Low to High	C <sub>L</sub> = 10 pF	2.5	5.5	10.0	ns
t <sub>SKD</sub>	Differential SKEW It PHLD - tPLHD			0.5	2.0	ns
t <sub>r</sub>	Rise Time			1.5	4.0	ns
t <sub>f</sub>	Fall Time			1.5	4.0	ns
t <sub>PHZ</sub>	Disable Time High to Z	$R_{L}$ = 500 $\Omega$ , Figures 8, 9	2.0	4.0	6.0	ns
t <sub>PLZ</sub>	Disable Time Low to Z	$C_{L} = 10 \text{ pF}$	2.0	5.0	7.0	ns
t <sub>PZH</sub>	Enable Time Z to High	(Note 8)	2.0	7.0	13.0	ns
t <sub>PZL</sub>	Enable Time Z to Low		2.0	6.0	10.0	ns

### 5V AC Electrical Characteristics (Note 6)

 $T_{A}=-40^{\circ}C$  to +85°C,  $V_{CC}=5.0V\pm0.5V$ 

Symbol	Parameter	Conditions	Min	Тур	Max	Units
DIFFERE	ITIAL DRIVER TIMING REQUIREMENT	S				
t <sub>PHLD</sub>	Differential Prop. Delay High to Low	R <sub>L</sub> = 27Ω, <i>Figures 2, 3</i>	0.5	2.7	4.5	ns
t <sub>PLHD</sub>	Differential Prop. Delay Low to High	C <sub>L</sub> = 10 pF	0.5	2.5	4.5	ns
t <sub>SKD</sub>	Differential SKEW It PHLD - tPLHD			0.2	1.0	ns
t <sub>TLH</sub>	Transition Time Low to High			0.3	2.0	ns
t <sub>THL</sub>	Transition Time High to Low			0.3	2.0	ns
t <sub>PHZ</sub>	Disable Time High to Z	R <sub>L</sub> = 27Ω, <i>Figures 4, 5</i>	0.5	3.0	7.0	ns
t <sub>PLZ</sub>	Disable Time Low to Z	C <sub>L</sub> = 10 pF	0.5	5.0	10.0	ns
t <sub>PZH</sub>	Enable Time Z to High		2.0	4.0	7.0	ns
t <sub>PZL</sub>	Enable Time Z to Low		1.0	4.0	9.0	ns
DIFFERE	ITIAL RECEIVER TIMING REQUIREME	NTS	•		•	•
t <sub>PHLD</sub>	Differential Prop. Delay High to Low	Figures 6, 7	2.5	5.0	12.0	ns
t <sub>PLHD</sub>	Differential Prop. Delay Low to High	C <sub>L</sub> = 10 pF	2.5	4.6	10.0	ns
t <sub>SKD</sub>	Differential SKEW It PHLD - tPLHD			0.4	2.0	ns
t <sub>r</sub>	Rise Time			1.2	2.5	ns
t <sub>f</sub>	Fall Time			1.2	2.5	ns
t <sub>PHZ</sub>	Disable Time High to Z	R <sub>L</sub> = 500Ω, <i>Figures 8</i> , <i>9</i>	2.0	4.0	6.0	ns
t <sub>PLZ</sub>	Disable Time Low to Z	$C_{L} = 10 \text{ pF}$	2.0	4.0	6.0	ns
t <sub>PZH</sub>	Enable Time Z to High	(Note 8)	2.0	5.0	9.0	ns
t <sub>PZL</sub>	Enable Time Z to Low		2.0	5.0	7.0	ns

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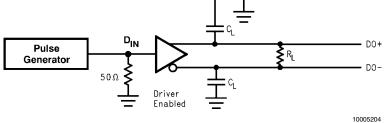


FIGURE 2. Differential Driver Propagation Delay and Transition Time Test Circuit

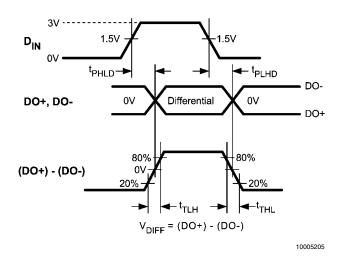
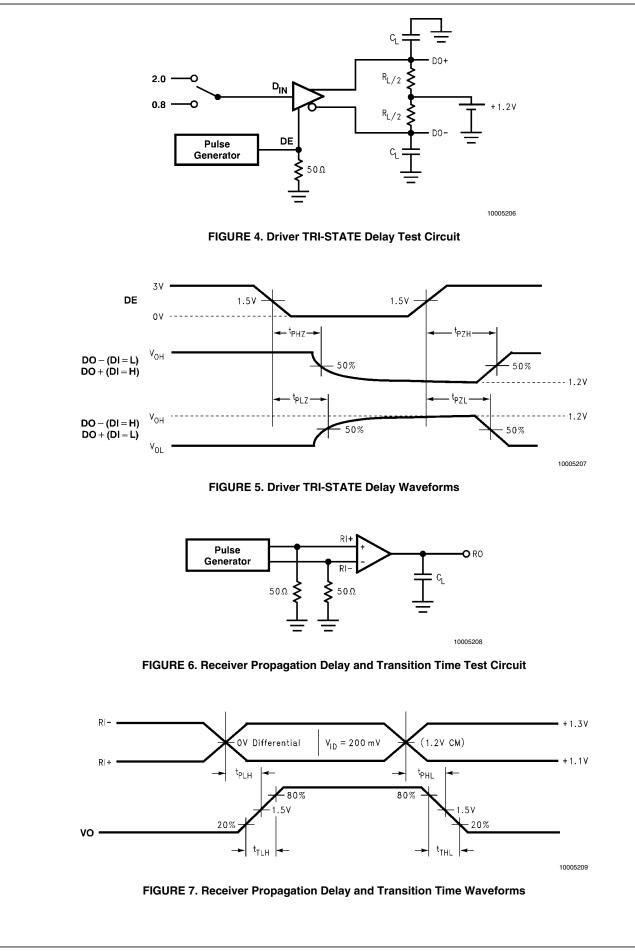
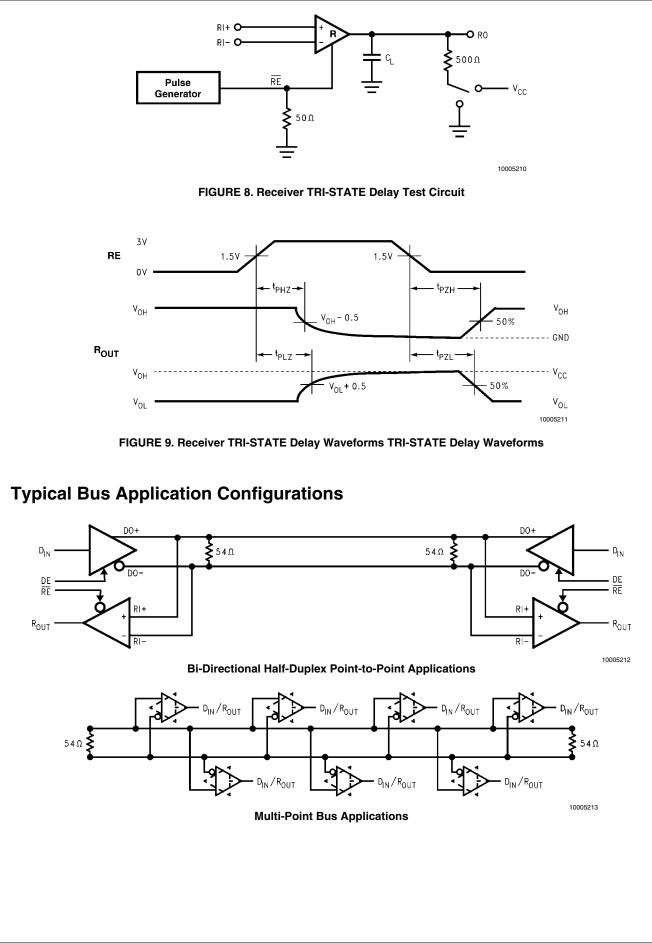


FIGURE 3. Differential Driver Propagation Delay and Transition Time Waveforms





### **Application Information**

There are a few common practices which should be implied when designing PCB for BLVDS signaling. Recommended practices are:

- Use at least 4 layer PCB board (BLVDS signals, ground, power and TTL signals).
- Keep drivers and receivers as close to the (BLVDS port side) connector as possible.
- Bypass each BLVDS device and also use distributed bulk capacitance. Surface mount capacitors placed close to power and ground pins work best. Two or three multi-layer ceramic (MLC) surface mount capacitors (0.1  $\mu F$ , and 0.01  $\mu F$  in parallel should be used between each  $V_{CC}$  and ground. The capacitors should be as close as possible to the  $V_{CC}$  pin.
- Use the termination resistor which best matches the differential impedance of your transmission line.
- Leave unused LVDS receiver inputs open (floating)

#### **TABLE 1. Functional Table**

MODE SELECTED	DE	RE
DRIVER MODE	Н	Н
RECEIVER MODE	L	L
TRI-STATE MODE	L	Н
LOOP BACK MODE	Н	L

#### **TABLE 2. Transmitter Mode**

	INPUTS	OUTI	PUTS
DE	DI	DO+	DO-
Н	L	L	Н
н	Н	Н	L
н	2 > & > 0.8	Х	Х
L	Х	Z	Z

L = Low state

H = High state

#### TABLE 3. Receiver Mode

	INPUTS	
RE	(RI+)-(RI–)	
L	L (< –100 mV)	L
L	H (> +100 mV)	н
L	100 mV > & > –100 mV	Х
Н	Х	Z

X = High or Low logic state

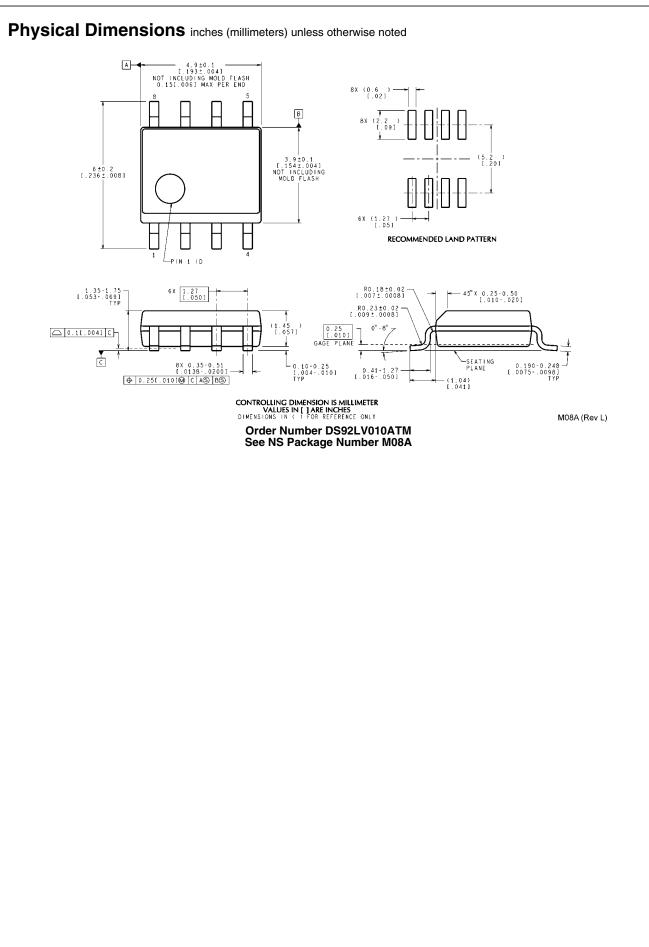
Z = High impedance state

L = Low state

H = High state

#### **TABLE 4. Device Pin Descriptions**

Pin Name	Pin #	Input/Output	Description	
DIN	2	I	TTL Driver Input	
DO±/RI±	6, 7	I/O	LVDS Driver Outputs/LVDS Receiver Inputs	
R <sub>OUT</sub>	3	0	TTL Receiver Output	
RE	5	I	Receiver Enable TTL Input (Active Low)	
DE	1	I	Driver Enable TTL Input (Active High)	
GND	4	NA	Ground	
V <sub>CC</sub>	8	NA	Power Supply	



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## Notes

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